

8 Structures

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Bundle Information in a `struct`

- Sometimes a number of variables belong logically together. For instance two doubles can be the x , y components of a point.
- The `struct` construct bundles one or more data types together.
- The elements of a structure are usually called members.

```
struct vector {  
    double x;  
    double y;  
};
```

Structure syntax

Definition:

```
struct Struct_name {  
    datatype struct_var1  
    datatype struct_var2};
```

Declaration:

```
Struct_name mystruct;
```

Initialize:

```
mystruct.struct_var1 = somevalue;  
mystruct.struct_var2 = anothervalue;
```



use dot "." syntax to access struct members

Using Structures

- Define the structure itself at the top of the program, before functions.

```
struct StructName {int num; double val;}
```

- Declare and initialize variables of type StructName in your main program, as usual:

```
int main() {  
    StructName mystruct1,mystruct2;  
    mystruct1.val=2.5; mystruct.num=10;  
    myfunc(mystruct) ;  
}
```

Initializing Structures

```
struct Point {  
    int x;  
    int y;  
};  
  
void printpoint(Point p) {  
    cout << "(" << p.x << "," << "\n"  
        << p.y << ")" << endl;}  
  
int main() {  
    Point p1,p2;  
  
    p1.x=3; p1.y=5;  
    printpoint(p1);  
  
    p2={18,10};  
    printpoint(p2);  
}
```

```
$ ./a.out  
  
(3,5)  
  
(18,10)
```

Review Quiz

True or false?

- The members of a `struct` must be of the same type.
- The following definition:

```
struct numbered { int n; double x; };
```

creates an object with an integer and a double as members.

- Given this declaration:

```
struct numbered xn;
```

are these statements correct?

- `cout << xn << endl;`
- `xn.x = xn.n+1;`
- `xn = {5, 3.5};`

Passing Structures to Functions

Just like any other data type, you can *pass* structures to functions.

```
double distance(Vector v1, Vector v2 ) {  
    double d1 = v1.x-v2.x;  
    double d2 = v1.y-v2.y;  
    return sqrt( d1*d1 + d2*d2 );  
}  
  
main {  
    Vector vectorA, vectorB;  
    vectordistance = distance (vectorA, vectorB);  
}
```

Returning Structures from Functions

And, just like any other data type, you can *return* structures from functions.

```
// structure definition
struct vector { double x; double y; } ;

// function definition
struct vector vector_add (vector v1, vector v2 ) {
    vector sum = {v1.x+v2.x,v1.y+v2.y};
    return sum;
};

// in main...
vector v1 = {2., 2.}; //declare & initialize v1
vector v2 = {3., 6.};
vector vectorsum = vector_add (v1, v2);
```


Exercise 1

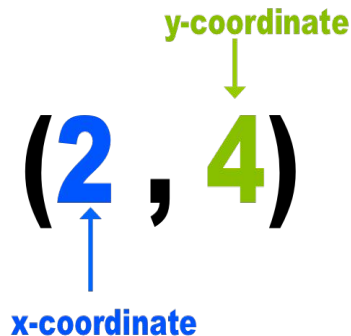
Write a void function, `flip`, that has a struct `Point` parameter, and exchanges its `x` and `y` member coordinates:

```
struct Point a = {3.,2.};  
cout << "Flip (" << a.x << ", " << a.y << ")";  
flip(a);  
cout << " to   (" << a.x << ", " << a.y << ")";  
cout << endl;
```

Struct allows you to create your own datatypes with int, float, double, string, and/or bool

Current Code:

```
int x=2;  
int y=4;
```


(2, 4)
x-coordinate y-coordinate

In Structure Code:

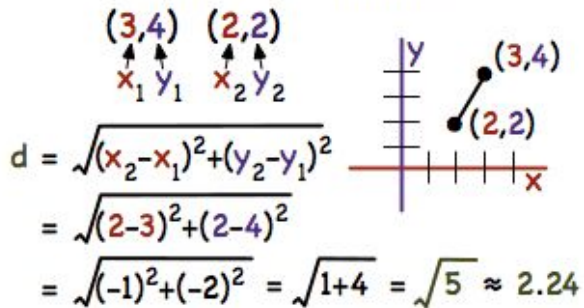
```
struct coord {int x;  
int y; };  
coord point_1;  
point_1.x = 2;  
point_1.y = 4;
```

```
coord point_2;  
point_2.x = 0;  
point_2.y = 4;
```

Example

Distance between two points

Find the Distance


$$\begin{aligned}d &= \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2} \\&= \sqrt{(2 - 3)^2 + (2 - 4)^2} \\&= \sqrt{(-1)^2 + (-2)^2} = \sqrt{1 + 4} = \sqrt{5} \approx 2.24\end{aligned}$$

```
#include<iostream>
#include<math.h>
using std::cout;
using std::endl;
int main() {
    float x1 = 3.0;
    float y1 = 4.0;
    float x2 = 2.0;
    float y2 = 2.0;
    float dist =
    sqrt(pow(x2-x1,2)+pow(y2-y1
    ,2));
    cout << dist << endl;
}
```

Example with Struct

```
...
struct coords {
    float x;
    float y;
};
int main() {
    coords c1,c2;
    c1.x = 3.;
    c1.y = 4.;
    c2.x = 2.;
    c2.y = 2.;
    float dist = sqrt(pow(c2.x-c1.x,2)+pow(c2.y-c1.y,2));
    cout << dist << endl;
}
```

Exercise 2

Write a 2×2 `matrix` class (that is, a structure storing 4 real numbers), and write a function `multiply` that multiplies a `matrix` times another `matrix`.

Remember, exercise 2 from the HW04.

Exercise 3

Create a new structure, `Point3d`, that contains `x`, `y`, and `z` real coordinates, then write a function, `distance3d`, that calculates the distance between those two `Point3d`'s using the distance formula in 3 dimensions:

$$AB = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} ;$$

```
float distance = distance3d(P1, P2)
```