```
Robot
# readThread
# m_readThreadStatus
# ins
# readTimer
# m togaleListening
# m listeners
# m status
# TERMINATE THREAD
# RUN THREAD
+ Robot()
+ ~Robot()
+ registerListener()
+ deregisterListener()
+ listen()
+ stopListening()
+ close()
+ twitch()
+ processKeys()
+ parse()
# warnEvent()
# sendCommand()
# threadLoop()
```