Robot

readThread
m_readThreadStatus
ios
readTimer
m_toggleListening
m_listeners
m_status
TERMINATE_THREAD
RUN_THREAD

+ Robot()
+ ~Robot()
+ registerListener()
+ deregisterListener()
+ listen()
+ stopListening()
+ close()
+ twitch()
+ processKeys()
+ parse()
# warnEvent()
# sendCommand()
# threadLoop()

OmniRobot

+ OmniRobot()
+ ~OmniRobot()
+ twitch()
+ processKeys()
+ drive()
+ drive()
+ emergencyStop()
+ getServoPosition()
+ getServoSpeed()
+ getBatteryVoltage()
and 7 more...