

Lego.

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This page is dedicated to my works on the new [LEGO\(R\) Mindstorms](#) the new way to play LEGO, using some lego technic pieces, motors, sensors and some fantasy touch you can build a new robot.

I have noted that in the web space there aren't complete packages to build your projects on Microsoft(r) platform that can be done simply & fast (legOS is so complex and UNIX dependent), so I created [Quite C](#), a C compiler (EGCS 1.1.2) with a complete (ROM based) lib that you can use to build very complex programs with your RCX (all 32K memory is yours!).

If you want to use a more standard way, use NQC and BrixCC with at least:

- Standard RCX2.0 firmware [firm0328.lgo](#)
This is the last original firmware that work ok for NQC
- Dick Swan 10x firmware [fast0103.lgo](#)
Old & slow, but extremely compatible
- Dick Swan 100x Firmware [fast0612.lgo](#)
Only few discrepancies with NQC 3.1r5
- Dick Swan Firmware [fast0722.lgo](#)
???
- Dick Swan Firmware [fast0753.lgo](#)
Work only with RobotC software (exception 11 Invalid Opcode if using NQC)

This is the reference documentation about Dick Swan Firmware:

[New Opcodes](#)

[Quick Start Guide](#)

[Firmware Features](#)

[Performance Testing](#)

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RCX the CPU of
your Robot