## **Table of Contents**

Question 2	1
Question 3	
Ouestion 4	

## **Question 2**

```
clear;clc;
close all;
format long
load rotmateuler123_data01
R01 = rotmateuler123(psi,theta,phi);
disp('Checking Result for Euler angles data set 01')
disp('Error is:')
disp(norm(R01-R_true));
clear
load rotmateuler123_data02
R_true = rotmateuler123(psi,theta,phi);
disp('R_true from Euler angles for data set 02 is:')
disp(R_true);
Checking Result for Euler angles data set 01
Error is:
     0
R_true from Euler angles for data set 02 is:
   0.053726755769759 -0.968751794569192 -0.242143338197493
   0.296835946406159 -0.216037226294276
                                           0.930170058524911
  -0.953415888600361 -0.121851866518510
                                           0.275953376479323
```

## **Question 3**

```
clear;
load rotmatquaternion_data05

R01 = rotmatquaternion(q);
disp('Checking Result for quaternion data set 01')
disp('Error is:')
disp(norm(R01-R_true));
clear
```

## **Question 4**

Rb is:		
0.0000	0	-1.0000
0	1.0000	0
1.0000	0	0.0000
Ra*Rb is:		
0.0000	1.0000	-0.0000
-0.0000	0.0000	1.0000
1.0000	0	0.0000
Rb*Ra is:		
0.0000	0.0000	-1.0000
-1.0000	0.0000	0
0.0000	1.0000	0.0000

These examples of Ra and Rb show that Ra\*Rb is not always equal to Rb\*Ra

Published with MATLAB® R2017a