<u>Posting Date</u>: Tuesday Nov. 12<sup>th</sup>. Due Date: Tuesday Nov. 19<sup>th</sup>.

1. Complete the MATLAB template file script\_simaircraft05\_temp.m by completing the parts of the code where ???? appears. The result will be the MATLAB script script\_simaircraft05.m. This script re-does the simulation in the Assignment 5 script script\_simaircraft04.m that uses ffunctaircraft03.m in order to simulate aircraft 3-dimensional motion with the Coriolis and centrifugal forces that are caused by the Earth's rotation. It performs the simulation in two ways. One uses ode45.m. The other method uses Euler numerical integration. It performs Euler integration using 3 different numbers of integration steps, N = 1,000, 10,000, 10,000. It compares the results to those produced by ode45.m when using a very tight error tolerance in 'RelTol'.

Run your code and hand in your code and the first two plots that it makes, the one that plots the ground track and the one that plots the altitude, airspeed, flight-path-angle, and heading-angle time histories. Also hand in the values of the final state errors of the Euler integration method, errorxfinal\_10000 and errorxfinal\_10000, given to 15 significant digits, i.e., using MATLAB'S format long command. As a way of checking your code, the correct value for the final state error of the coarsest Euler integration is:

```
errorxfinal_1000 = 1.0e+03 * -2.249895893562921 0.251280598994137 0.152175509991668 0.003678205103694 0.000056219544104 -0.000066881571850
```

Also hand in your computation times for the numerical integrations. They are contained in timetoode45 and in timetoeuler\_vec. How does Euler integration compare to ode45.m in terms of execution speed?

Compute the vector of error ratios errorxfinal\_10000./errorxfinal\_100000 and hand it in. The theory of Euler's method predicts that these ratios should be about 10. Is that true?

2. Complete the MATLAB template file script\_simaircraft06\_temp.m by completing the parts of the code where ???? appears. The result will be the MATLAB script script\_simaircraft06.m. This script re-does the simulation in the Assignment 5 script script\_simaircraft04.m that uses ffunctaircraft03.m in order to simulate aircraft 3-dimensional motion with the Coriolis and centrifugal forces that are caused by the Earth's rotation. It performs the simulation in two ways. One uses ode45.m. The other method uses trapezoidal numerical integration. It performs trapezoidal integration using 3 different numbers of integration steps, N = 500, 2,000, and 8,000. It compares the results to those produced by ode45.m when using a very tight error tolerance in 'RelTol'.

Run your code and hand in your code and the first two plots that it makes, the one that plots the ground track and the one that plots the altitude, airspeed, flight-path-angle, and heading-angle time histories. Also hand in the values of the final state errors of the trapezoidal integration method, errorxfinal\_2000 and errorxfinal\_8000, given to 15 significant digits, i.e., using MATLAB's format long command. As a way of checking your code, the correct value for the final state error of the coarsest trapezoidal integration is:

```
errorxfinal_500 = 1.0e+02 * 2.470874422823008 0.312781372675090 -0.020091213827387 -0.001686689529057 0.000002200901484 0.000076213593823
```

How do errorxfinal\_2000 and errorxfinal\_8000 for this run compare errorxfinal\_10000 and errorxfinal\_100000 for the Euler integration run?

Also hand in your computation times for the numerical integrations. They are contained in timetoode45 and in timetotrapez\_vec. How does trapezoidal integration compare to ode45.m in terms of execution speed?

Compute the vector of error ratios errorxfinal\_2000./errorxfinal\_8000 and hand it in. The theory of Euler's method predicts that these ratios should be about 16. Is that true?

3. Complete the MATLAB template file script\_simaircraft07\_temp.m by completing the parts of the code where ???? appears. The result will be the MATLAB script script\_simaircraft07.m. This script re-does the simulation in the Assignment 5 script script\_simaircraft04.m that uses ffunctaircraft03.m in order to simulate aircraft 3-dimensional motion with the Coriolis and centrifugal forces that are caused by the Earth's rotation. It performs the simulation in two ways. One uses ode45.m. The other approach uses the following 4<sup>th</sup>-order Runge-Kutta numerical integration method:

$$t_{ak} = t_{k}, x_{ak} = x_{k}, f_{ak} = f(t_{ak}, x_{ak})$$

$$t_{bk} = t_{k} + \frac{1}{2} \Delta t, x_{bk} = x_{k} + \frac{1}{2} \Delta t f_{ak}, f_{bk} = f(t_{bk}, x_{bk})$$

$$t_{ck} = t_{k} + \frac{1}{2} \Delta t, x_{ck} = x_{k} + \frac{1}{2} \Delta t f_{bk}, f_{ck} = f(t_{ck}, x_{ck})$$

$$t_{dk} = t_{k} + \Delta t, x_{dk} = x_{k} + \Delta t f_{ck}, f_{dk} = f(t_{dk}, x_{dk})$$

$$t_{k+1} = t_{k} + \Delta t$$

$$x_{k+1} = x_{k} + \frac{\Delta t}{6} (f_{ak} + 2f_{bk} + 2f_{ck} + f_{dk})$$

The script performs  $4^{th}$ -order Runge-Kutta numerical integration using 3 different numbers of integration steps, N = 100, 400, and 1,600. It compares the results to those produced by ode 45.m when using a very tight error tolerance in 'RelTol'.

Run your code and hand in your code and the first two plots that it makes, the one that plots the ground track and the one that plots the altitude, airspeed, flight-path-angle, and heading-angle time histories. Also hand in the values of the final state errors of the 4<sup>th</sup>-order Runge-Kutta numerical integration method, errorxfinal\_400 and errorxfinal\_1600, given to 15 significant digits, i.e., using MATLAB'S format long command. As a way of checking your code, the correct value for the final state error of the coarsest 4<sup>th</sup>-order Runge-Kutta integration is:

```
errorxfinal_100 = 1.0e+02 * -7.127606248392213 -0.264484908926461 -0.035371532136971 -0.002812622432203 0.000014204895534 -0.000218345320909
```

How do errorxfinal\_400 and errorxfinal\_1600 for this run compare errorxfinal\_2000 and errorxfinal\_8000 for the trapezoidal integration run?

Also hand in your computation times for the numerical integrations. They are contained in timetoode45 and in timeto4thOrdRK\_vec. How does the 4<sup>th</sup>-order Runge-Kutta integration method compare to ode45.m in terms of execution speed?

Compute the vector of error ratios errorxfinal\_400./errorxfinal\_1600 and hand it in. The theory of Euler's method predicts that these ratios should be about 256. Is that true?

4. Someone has proposed the following Runge-Kutta numerical integration scheme as an alternative to trapezoidal integration:

$$t_{ak} = t_k, x_{ak} = x_k, f_{ak} = f(t_{ak}, x_{ak})$$

$$t_{bk} = t_k + \frac{1}{2} \Delta t, x_{bk} = x_k + \frac{1}{2} \Delta t f_{ak}, f_{bk} = f(t_{bk}, x_{bk})$$

$$t_{k+1} = t_k + \Delta t$$

$$x_{k+1} = x_k + \Delta t (b_1 f_{ak} + b_2 f_{bk})$$

Determine the values of  $b_1$  and  $b_2$  that will make this method  $2^{nd}$ -order and prove that the resulting method is  $2^{nd}$ -order.

<u>Hints</u>: Develop an analysis of the order of this method that is similar to the analysis that was developed in lecture for the trapezoidal numerical integration method. This analysis will

involve developing a Taylor series approximation of  $f_{bk}$ . Find the  $b_1$  and  $b_2$  values which cause the resulting series to have  $\Delta t$  and  $\Delta t^2$  terms that match the true Taylor series for x(t) expanded about  $t_k$ .