

# MSCV6 Software Engineering Project

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16/01/2015

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# Background

- Triangular mesh
- Applications: Gaming, animation, 3D scanning, etc
- Our project: Laplacian Mesh study, Spectral Analysis
- Making use of OpenGL and Eigen library



# Mesh Laplacian

- To generate a Laplacian matrix by A matrix and D matrix

$$A_{ij} = \begin{cases} 1 & i \in N(j) \\ 0 & \text{otherwise} \end{cases} \quad (1)$$

$$D_{ij} = \begin{cases} d_i & i = j \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

$$L_s = DL = D - A \quad (3)$$

- With Laplacian matrix we have:

$$Lx = \delta \quad (4)$$

where  $x$  is global coordinate and  $\delta$  is the differential coordinate. This equation is useful for mesh editing and curvature analysis.

# Mesh Laplacian-Cotangent weights

- Cotangent weights can be expressed as:

$$w_{ij} = \frac{1}{2}(\cot \alpha_{ij} + \cot \beta_{ij}) \quad (5)$$

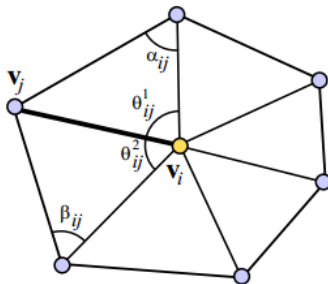


Figure : Taken from reference [1]

- With cotangent weights Harmonic Laplacian matrix can be calculated, which is useful for curvature analysis.

# Spectral Analysis

- Eigenvectors and eigenvalues
- Using Eigen library to solve Eigen: SelfAdjointEigenSolver...
- Eigen sorting
- Colors as functions of eigenvectors

$$y = (b - a) \times (x - m) / (M - m) + a \quad (6)$$

- Mesh Compression: eigen space and frequency

$$[x_1, x_2, \dots, x_n]^T = c_1 e_1 + c_2 e_2 + \dots + c_{n-1} e_{n-1} + c_n e_n \quad (7)$$

- Projection in eigen space

$$P = x_1 e_1 + x_2 e_2 + x_3 e_3 + \dots \quad (8)$$

# Spectral Analysis - Colors as functions of eigenvectors

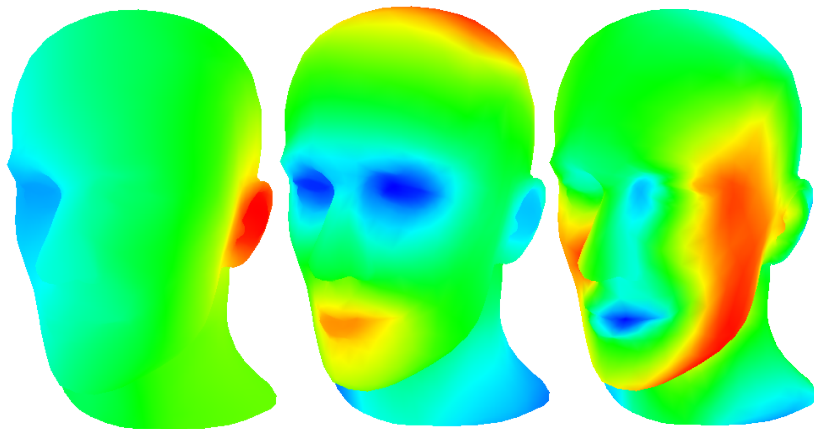
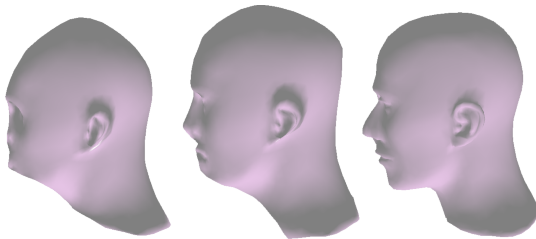


Figure : Results of the low, mid-level and high eigen vectors respectively

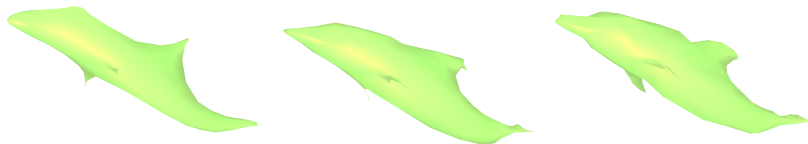
# Spectral Analysis - Compression 1



**Figure :** Results of high compression, mid-level compression and low-level compression



# Spectral Analysis - Compression 2



**Figure :** Results of high compression, mid-level compression and low-level compression

- OpenGL to visualise 3D meshes and various processing done on it.
- OpenGL functions of lighting and materials.
- Previliges of signals and slots

# Signal and Slots

- A way to communicate between GLWidgets and QWidgets
- SIGNALS and SLOTS of different classes
- Qt Designer forms and windows

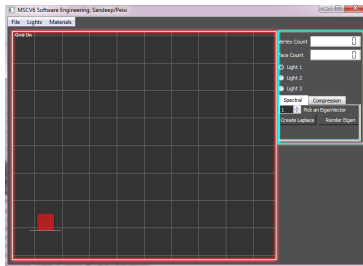


Figure : user interface

- Someway to interact with 3D world
- Dragging with mouse
- Rotation and Zoom

# Mapping Mouse Motion to Rotation

- Rotation axis and Rotation Angle
- Two vectors; Initial click, and every final Drag location

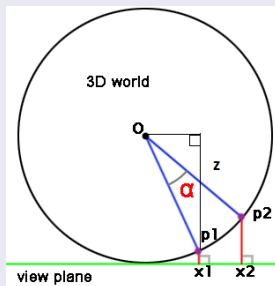


Figure : Arcball: looking the World from Top view

$x_1$  and  $x_2$ : initial and final mouse location,

$\alpha$ : rotation angle

$p_1$  and  $p_2$ : projections on sphere

$$z = \sqrt{1 - x_1^2}$$

# Lighting in OpenGL

- Overall appearance of 3D object
- Ambient, Diffuse, Specular

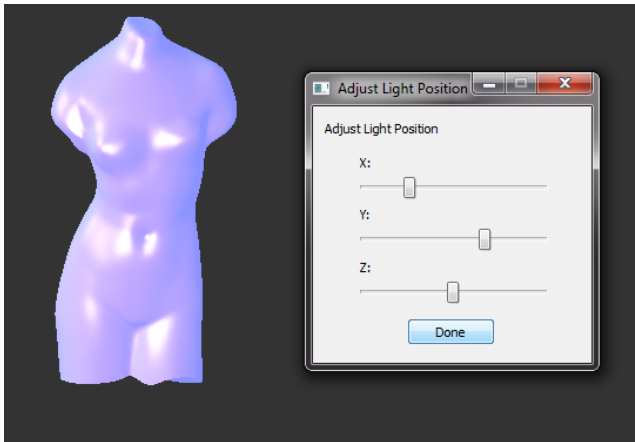


Figure :

# Shading

- Basic OpenGL Shading Modes
- GL\_FLAT and GL\_SMOOTH
- GL\_FLAT: low cost to compute
- GL\_SMOOTH: Interpolate along the vertices

## Shading in OpenGL

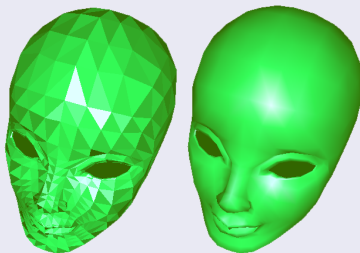


Figure : Results of Flat and Smooth shading

# GUI Implementation

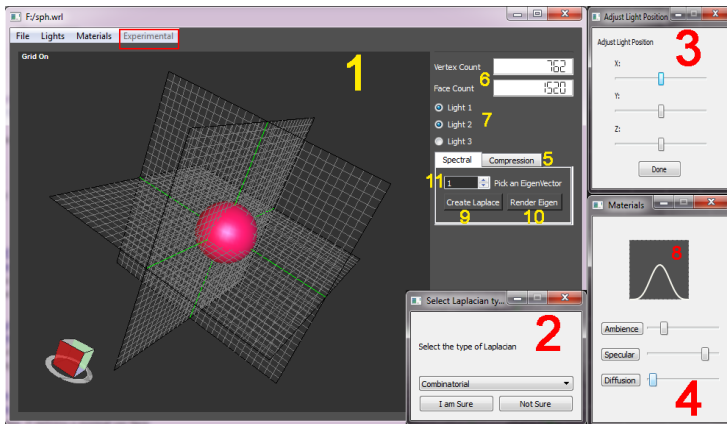


Figure : GUI



- Usable GUI
- Glut Abandoned
- Code refactored
- Mobile Light and Basic Material Editor
- Mesh operations
- Experimental Watermarking(Needs mesh saving)
- OpenGL selection and picking
- Nystrom Method to extract few leading Eigen components

# Watermark

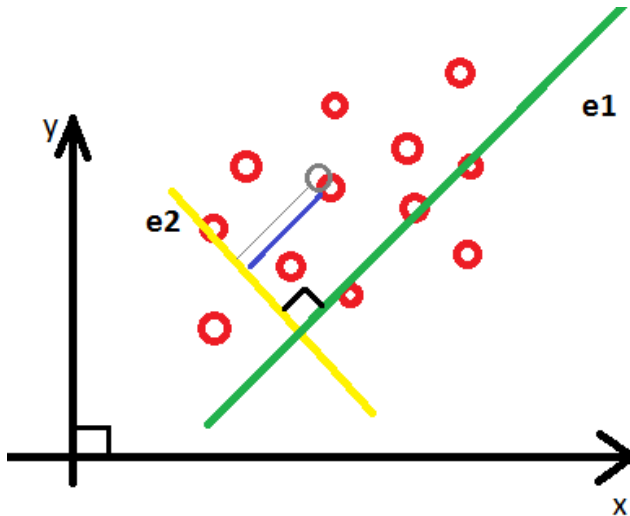
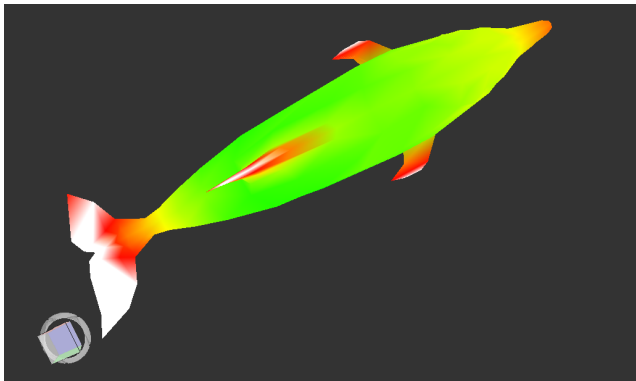


Figure : Watermark

# Experimental Curvature Analysis

With cotangent Laplacian matrix and differential coordinate, the curvature image was calculated:



**Figure :** Curvature image with cotangent Laplacian matrix and differential coordinate



SORKINE O., Laplacian mesh processing. In Eurographics State-of-the-Art Report (2005)



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ARCBALL: A User Interface for Specifying Three-Dimensional Orientation Using a Mouse, Shoemake, k., Computer Graphics Laboratory, University of Pennsylvania



Traile. C., , <http://www.ctr.alie.com/index.html>



Eigen 3.2.3 documentation,[http://eigen.tuxfamily.org/dox/classEigen\\_1\\_1SelfAdjointEigenSolver.html](http://eigen.tuxfamily.org/dox/classEigen_1_1SelfAdjointEigenSolver.html)



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# The End