SANDEEP N MENON

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EXPERIENCE

Deep Learning Intern, Perception | Kodiak Robotics | Mountain View, California

May - Sept 2023

• Engineered a multi-modal deep learning architecture integrating Camera, Lidar, and Radar sensory data for ground height, lane, and obstacle estimation

Deep Learning Research Engineer | Deepen AI | Hyderabad, India

Sept 2020 - Jul 2022

- Developed a 3D PointNet model for temporal smoothing of segmentation predictions over point cloud sequences, achieving a 20% mIoU improvement
- Built a Sparse Point-Voxel CNN model for semantic segmentation of 3D point cloud sequences, boosting data annotation speed by 30% and obtaining a 76% mIoU score
- Implemented 2D object-aware anchor-free tracking in auto-labeling pipeline, increasing labeling speed by 50%
- Devised a targetless Camera-IMU and stereo camera calibration algorithm, reducing calibration time by 90% and achieving a 1-degree error margin
- Created an on-demand GPU Virtual Machine allocation system saving up to 4000 USD/month for the company

Software Development Engineer II | Microsoft | Hyderabad, India

Jun 2018 – Sept 2020

- Co-authored new Machine Learning method inspired by Random Forests to identify similar won customer deals and opportunities for sales executives in Relationship Analytics in Dynamics 365; **received patent award**
- Shipped Dynamics 365 sales insights connector in Power platforms managing 9 million monthly requests

PROJECTS

Video frame prediction and collision modeling using Deep Learning | PyTorch, WandB

Mar - May 2023

- Leveraged self-supervision techniques with the SimVP model for future segmentation prediction in videos, winning 1^{st} place in Prof. Yann LeCun's and Prof. Alfredo Canziani's Deep Learning class at NYU
- Innovated a New Object Suppression (NOS) decision tree-based technique to rectify prediction errors

Federated Training System for Generative Adversarial Networks | PyTorch, Flower

Oct - Dec 2022

• Designed a federated learning system to train Generative Adversarial Networks(GAN). GANs can be trained across dozens of devices without sharing their data

Point Cloud Oversegmentation using Superpoint Graphs | PyTorch, Boost

May - Jun 2021

• Optimized Superpoint Graph implementation to Argoverse point cloud dataset to achieve over-segmentation results of overall accuracy of 96% and Boundary Recall of 92%

Asymmetric 3D Convolutions in Torchsparse | PyTorch

Feb 2021

• Contributed Asymmetric 3D Convolutions implementation to TorchSparse library, managed by MIT HAN Lab

Removing noise from Optical Coherence Tomography (OCT) Images [CVIP 2020]

Aug 2017 - May 2018

• Achieved Structural Similarity Index (SSIM) value of 96.7% for low noise images and 91.2% for high noise images, surpassing the state-of-the-art results

TECHNICAL SKILLS

Deep Learning (PyTorch, Tensorflow, TensorRT, Onnx, Keras, MMDet, PointNet, CNN, VAE, GAN),

Convex Optimization (CVXPY, Ceres, SciPy, NumPy),

Computer Vision (OpenCV, LiDAR, SLAM, Multi-Sensor Calibration and Fusion),

Languages/Platforms: C++, C#, Python, JavaScript, TypeScript, CUDA, OCamL, React, Redux, Django, LangChain, Flower, Bazel, Docker, Azure, ROS, ClearML, WandB, Google Cloud, MongoDB, RocksDB, MySQL, Git

EDUCATION

New York University (NYU) Courant Institute of Mathematical Sciences

2022 - 2024

Master of Science in Computer Science

National Institute of Technology Karnataka, Surathkal, India (NITK)

2014 - 2018

Bachelor of Technology in Computer Science