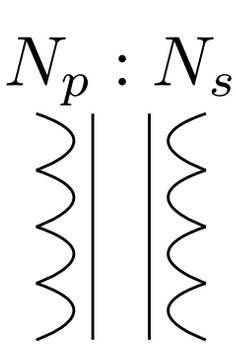
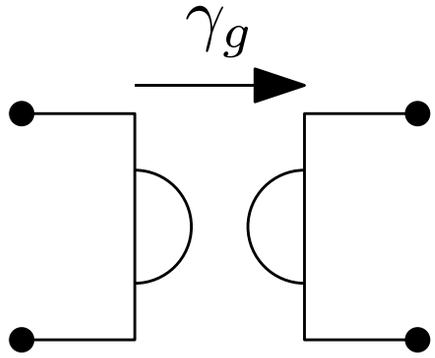
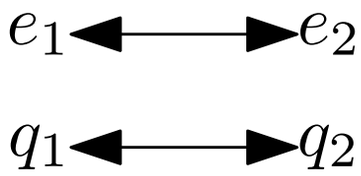
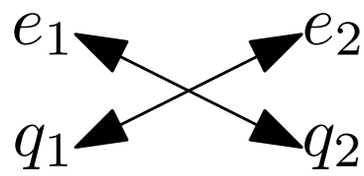
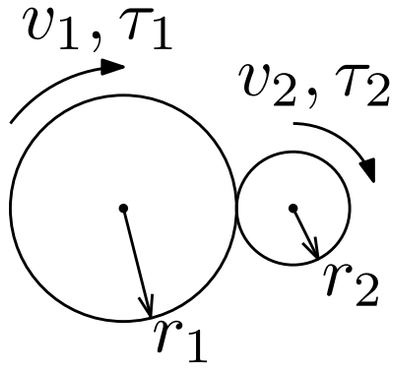
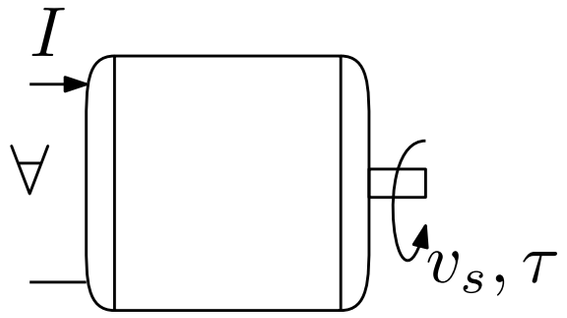
	Transformer	Gyrator
Network diagram symbols		
	$e_1 = \gamma_t e_2$	$e_2 = \gamma_g q_1$
	$q_1 = \frac{1}{\gamma_t} q_2$	$e_1 = -\gamma_g q_2$
Variable relationships		
Examples		
	$N = \frac{r_1}{r_2}$	$\tau = -k_\tau I$
	$v_1 = -\frac{1}{N} v_2$	$\forall = k_\tau v_s$
	$\tau_1 = N \tau_2$	