

20.10.05

Rectangle Sticking Problem:

$$\min \sum_{h \in H} x_h + \sum_{v \in V} x_v$$

$$\sum_{h \in H(r)} x_h + \sum_{v \in V(r)} x_v \geq 1 \quad \forall r$$

$$x_v, x_h \in \{0, 1\}$$

based on LP optimal soln, $x^* = (x_h^*, x_v^*)$

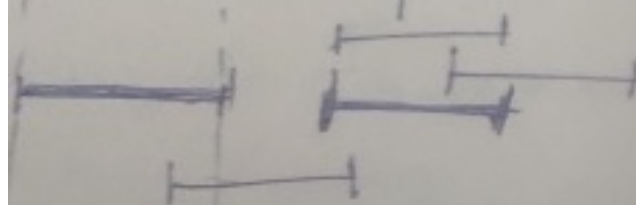
$$\min ()$$

$$A[x_h, 0] \geq 1 \text{ if } A[r] \cdot \langle x_h^*, 0 \rangle \geq 1/2$$

$$A[0, x_v] \geq 1 \text{ if } A[r] \cdot \langle 0, x_v^* \rangle \geq 1/2$$

$$x_h, x_v \in \{0, 1\}.$$

$$A' \begin{bmatrix} x_h & x_v \\ 0 & 0 \end{bmatrix} \geq 1$$



$$\min x$$

$$A'x \geq 1$$

Number of independent intervals are same as number of lines

$$\begin{bmatrix} \geq 1 \\ - & | & - \end{bmatrix}$$

Integer optimal to P' can be constructed in $O(n \lg n)$ [If not sorted, we have to sort]

Fact :

$2x^*$ = it is feasible in P'

OPT' be the optimal solⁿ to P'

$$OPT' \leq 2x^*$$

Performance Ratio is $\frac{OPT'}{x^*} \leq 2$

Value associated with optimal solⁿ

provided the solⁿ that is constructed over there is indeed optimal solⁿ.

Prop Problem above the line & below the line is independent

If Matrix A' is TUM (totally unimodular)

$$P: \min cx$$

$$A'x \geq 1$$

$$x \in \{0,1\}^n$$

$$A''x \geq 1$$

$$x \geq A''^{-1} 1$$

then ~~shows only~~ all the optimal solutions to P are integral (0/1).

Reading Assignment
Proof of the statement.

Question (Research)

$$\min cx$$

$$Ax \geq 1$$

$$x \in \{0,1\}$$

x^* is fractional

$$\begin{bmatrix} A_1 & A_2 & \dots & A_K \end{bmatrix} x^* \geq 1$$

R_1, R_2, \dots, R_K recorder A into K parts

~~Each R_i~~ If each submatrix $(A_i, R_i) \forall i$ is TUM then

$$\phi r = K$$

~~at~~ Given such matrix A what is the smallest K ?

Generalize ~~to~~ balanced matrices.

we can compute ~~do~~ in polynomial time

does not have any odd cycles $\frac{2K+1}{\underline{\underline{\quad}}}$ for any K

3-odd cycle

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

5-odd cycle

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

single element performance ratio $\underline{\underline{\quad}}$

$$x^* = \begin{bmatrix} x_{A_1}^* & \dots & x_{A_n}^* \end{bmatrix}$$

$$\geq \frac{1}{K}$$

Q: How to solve point separation problem using rectangle stabbing?

consider rectangles ~~defined~~ defined by every pair of points

Greene, Calinescu, Karloff

CCCC 04

~~TC~~ TJCA?

LP is expensive $\underline{n^5}$ for coefficient matrix and matrix

E. Tardos, 1985

$A[0,1] \in$ strongly Polynomial.

$O(n^5)$

Facility Location

~~$x_{ij} \in \mathbb{R}$~~ $i \in F$ $j \in C$

$$(P) \min \sum_{i \in F} y_i f_i + \sum_{i \in F, j \in C} x_{ij} \cdot c_{ij}$$

$$d_j \quad \sum_{i \in F} x_{ij} \geq 1 \quad \forall j \in C$$

$$b_{ij} \quad y_i \geq x_{ij} \quad \forall i \in F, j \in C$$

$$(D) \max \sum_{j \in C} x_j \quad \text{s.t.} \quad \begin{aligned} d_j - b_j &\leq c_{ij} \quad \forall i \in F, j \in C \\ \sum_{j \in C} b_{ij} &\leq f_i \quad \forall i \in F \end{aligned}$$

- (1) $x_{ij} > 0 \Rightarrow \alpha_i - \beta_{ij} = c_{ij}$
 (2) $y_i > 0 \Rightarrow \sum_{j \in C} \beta_{ij} = f_i$
 (3) $\alpha_j > 0 \Rightarrow \sum_{i \in F} x_{ij} = 1$
 (4) $\beta_{ij} > 0 \Rightarrow y_i = x_{ij}$
- } Primal complementary slackness condition
 } Dual complementary slackness condition

Relaxed conditions are

$$\frac{1}{3} c_{\phi(j), j} \leq \alpha_j - \beta_{\phi(j), j} \leq c_{\phi(j), j}$$

$$\frac{1}{3} f_i \leq \sum_{j: \phi(j)=i} \beta_{ij} = f_i$$

$\phi(j)$: Cities which are connected to facility i .
~~facility~~

Directly connected.

$$\alpha_j - \beta_{\phi(j), j} = c_{\phi(j), j} \quad (A)$$

~~definition~~

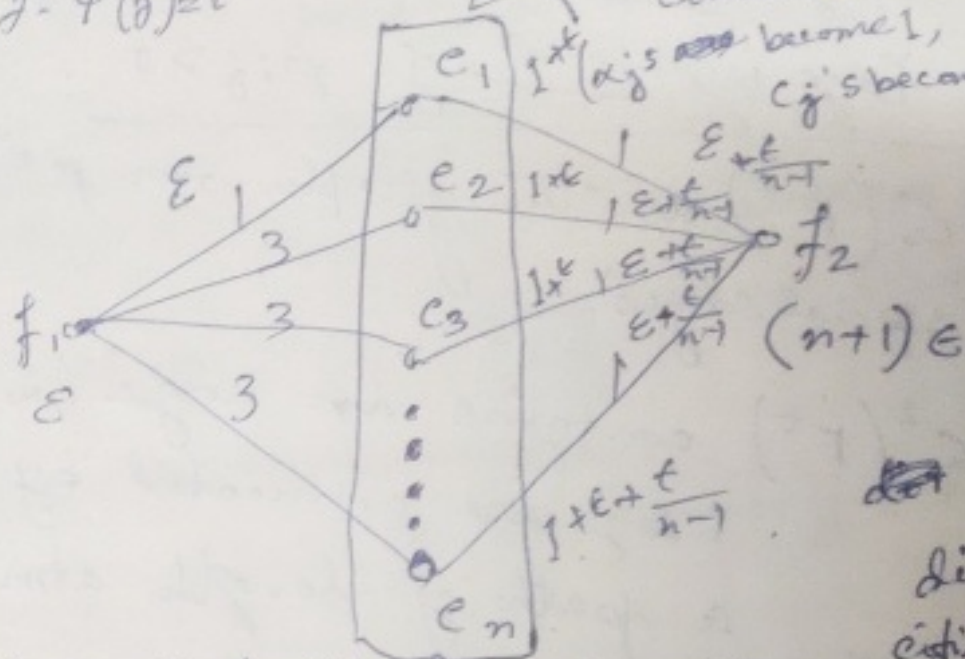
Indirectly connected.

$$\beta_{ij} = 0 \quad (\text{by definition})$$

~~$\alpha_j - \beta_{\phi(j), j} = c_{\phi(j), j}$~~ (we want this in our complementary slackness condition)

$$\frac{1}{3} c_{\phi(i)j} \leq \alpha_j \leq c_{\phi(i)j} \quad (B)$$

$\sum_{j: \phi(i)=i} \beta_{ij} = f_i(c)$ [summation over all the cities that are connected to city i]
 $j: \phi(i)=i$



Edge is tight if $\alpha_j = c_{ij}$

Directly connected cities correspond to tight edges.

Facilities will be declared connecting witness.

only on the tight edges raise β until some facility is paid for or some new edge becomes tight

every city becomes connected to opened facility.

raising dual variables.

synchronized. ~~variable~~ ~~is~~

Phase 2

F^t is the set of temporarily open facilities. We want to ^{close} some of ~~close~~ open facilities, because cost is too much.

Edge is tight if $d_i = c_{ij}$.

Edge is special if $\beta_{ij} > 0$

$G(F^t)$ as the graph over F^t & the "special edges".

$G^2(F^t)$ contains an edge (i, j) if i & j are connected by a path of length at most 2 in $G(F^t)$.

Take any maximal independent set I in $G^2(F^t)$ and declare all facilities in I as open. Close everything in $F^t \setminus I$.

10 City j F_j is the set of facilities s.t.
 $\beta_{ij} > 0 \Rightarrow c_j$

1. If $I \cap F_j \neq \emptyset$ then
 connect j to $I \cap F_j$

2. $I \cap F_j = \emptyset$

facilities directly connected { j has connecting witness i
 (if no connecting witness, algorithm would
 go on)
 if $i \in I$ then connect j to i

else (~~by G^2 construction~~)

facilities indirectly connected { ~~$i \in I$~~ there exists a nbr i' of i
 in I (by G^2 construction).
 connect j to i'