Instructions

- This is a closed-book, closed-notes exam.
- You have 75 minutes for the exam.

Problem 1 (20 pts). What, if any, is the relationship between each of the following pairs of complexity classes? Make sure that you distinguish between $C_1 \subseteq C_2$ and $C_1 \subsetneq C_2$. Briefly justify your answer using the Time and Space Hierarchy Theorems.

- a. DSPACE[n^2] and DSPACE[f(n)], where f(n) = n for odd n and $f(n) = n^3$ for even n.
- b. DTIME[2ⁿ] and DTIME[3ⁿ].
- c. $NSPACE[2^n]$ and $DSPACE[5^n]$.
- d. DSPACE[n] and DTIME[$(\log n)^n$].

Problem 2 (20 pts). Consider 1-tape Turing machines that are "ink bounded" — that is, Turing machines that are limited by the number of times that they can change a symbol on the tape. We think of each change (including erasing a symbol) as taking 1 unit of "ink". Let $INK^1[n]$, $TIME^1[n]$ and $SPACE^1[n]$ be the class of languages recognized by 1-tape Turing machines that on inputs of length n use at most n units of ink, take at most n steps and use at most n tape cells, respectively.

Discuss how $INK^1[n]$, $TIME^1[n]$ and $SPACE^1[n]$ are related. Justify your remarks as fully as you can,

Problem 3 (20 pts). Consider the PATH language defined in the textbook:

PATH = { (G, s, t) | G is a directed graph that has a path from s to t }.

For this problem, we will work with a variation:

 $\mathsf{DAG_Path} = \{ \ (G, s, t) \mid G \text{ is a directed acyclic graph and } G \text{ has a path from } s \text{ to } t \ \}.$

We want to show that DAG_PATH is complete for NLOG (nondeterministic logspace) using logspace transducers. For both PATH and DAG_PATH, the graph G is given as an adjacency matrix.

- a. Show that DAG_PATH is in NLOG by giving a high-level description of a nondeterministic logspace Turing machine for DAG_PATH. Note that your machine must reject when G
- b. Describe a logspace transducer that reduces PATH to DAG_PATH. Give a high-level description, then argue that your machine uses no more than logarithmic space on the work tape.

Short Exam 2 / Math 650 / Spring 2010 / Dr. Güler (Thursday, March 25, 2010)

Name Sandipan Dey

- [10 pts.] Let C be a convex set in Rⁿ, and let f be a Gateaux differentiable function on an open set
 - (a) If $x^* \in C$ is a local minimizer of f on C, then

$$\langle \nabla f(x^*), x - x^* \rangle \ge 0$$
 for all $x \in C$.

- (b) If f is convex and (1) is satisfied at $x^* \in C$, then x^* is a global minimizer of f on C.
- 2. [10 pts.] Prove one the following:
- a. Prove that

$$\left(\frac{x}{2} + \frac{y}{3} + \frac{z}{12} + \frac{w}{12}\right)^4 \leq \frac{1}{2}x^4 + \frac{1}{3}y^4 + \frac{1}{12}z^4 + \frac{1}{12}w^4$$

with equality holding if and only if x = y = z = w.

b. Consider the optimization problem

$$\min\{||x-d||^2:||x||^2\leq 1\},$$

where ||d|| > 1. Use the variational inequality to find the optimal solution solution.

3. (Extra credit) [4 pts.] Let C be a convex set in \mathbb{R}^n , and let f be a Gateaux differentiable function on an open set containing C. Prove that f is convex on C if and only if the tangent plane at any point $x \in C$ lies below the graph of f, that is,

$$f(y) \ge f(x) + \langle \nabla f(x), y - x \rangle$$
 for all $x, y \in C$.

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- 1. [10 pts.] Let C be a convex set in \mathbb{R}^n , and let f be a Gateaux differentiable function on an open set
 - (a) If $x^* \in C$ is a local minimizer of f on C, then

$$\langle \nabla f(x^*), x - x^* \rangle \ge 0$$
 for all $x \in C$. (1)

- (b) If f is convex and (1) is satisfied at $x^* \in C$, then x^* is a global minimizer of f on C.
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- a. Prove that

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(a) First order necessary condition

fin a convex function and & x"EC is a local minimizer. Since Choose any xEC. Since x is convex all the points in the interval x-x* EC.

Now, let's consider f(x'+t(x-x')), where $t \in \mathbb{R}$. For arbitrary small t (t >0), since x is a look minima,

Also, of is hatneaux differentiable, and

ief(x,x-x)=lim + (x-x)) + : f(x,x-x)=lim + (x-x*))

Also, fis convex=> f(x)-f(x)= (x), y-x), +x, y2C.

Rulling y= z+++(x-x*) and x=x*, we have, $f(x^*+t(x-x^*))-f(x^*) \times \langle vf(x^*), x-x^* \rangle$. @

from (1) & (2), we have,

0= (\rangle f(x*), x-x*) ≥0, but x was arbitrarily chosen => <\\f(x*), x-x*>≥0 \x \cap C

tisage fis convex and we have < \ \ f(x+), x-x+ > ≥0, 4x € C. Also, $f(x) - f(x^*) \ge \langle \nabla f(x^*), x - x^* \rangle \ge 0$, since f is convex => f(x) ≥ f(x*), + x & C./ =) 2" is a global minimizer. 2 a) choose Harris 2 4 + 3 Let f (x, y, z, w) = 300 y 2. a) Let f(x)=x4, now, f"(x)=12x2 ≥0, 4x ER, =) f(a) is convex. By Jensen's inequality, we have, 医面 f(至入;xi)≤至身入;f(xi), with 2; 20, \ \(\lambda i = 1. det, $\lambda_1 = \frac{1}{2}$, $\lambda_2 = \frac{1}{3}$, $\lambda_3 = \lambda_4 = \frac{1}{12}$, no possible. 1. By Jensen's inequality on f (4:) = 2:4, we have, (= xixi) 4 & Exi(xi)4 三)(当+当+三十三)とシュンナラッサートランナーシルケ equely one? (-4)

By Torplor's Theorem. $f(x+t(y-x)) = f(x) + t \langle vf(x), y-x \rangle + o(t)$ $\Rightarrow (j-t) f(x) + t f(y) \quad (since f is convex)$ $\Rightarrow t (f(y) - f(x)) \ge t \langle vf(y), y-x \rangle + o(t)$ $\Rightarrow f(y) - f(x) \ge \langle vf(y), y-x \rangle + o(t)$ At, t \to 0, \quad \text{20} \quad \frac{o(t)}{t} \to 0

\tag{\tag{\tag{t}}} \quad \frac{o(t)}{t} \to 0

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