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Part (b)

Proof

The OFF-LINE-MINIMUM algorithm deals with n INSERT (I) operations ($\bigcup_{k=1}^m I_k$) and m EXTRACT-MIN (E) operations. To prove that the algorithm is correct, we need to prove that $\forall j \in \{1, 2, \dots, m\}$, $extract[j]$ contains the key returned by j^{th} E.

For $i = 1$, the algorithm considers the entire sequence $I_1, E, I_2, E, \dots, I_m, E, I_{m+1}$. It first finds a $j | i \in K_j$. There can be couple of cases:

1. $j = m + 1$, which means that the element 1 is inserted after the last EXTRACT-MIN, in which case it will NOT be part of the *extracted* array, since it will never get a chance to be extracted. The algorithm also does nothing ($j \neq m + 1$ check on line 3 ensures it), simply proceeds to the next larger element. Since the elements $\{1, 2, \dots, n\}$ are considered in the increasing order (ensured by the for loop in line 1), this element will never be considered again. Hence, this behavior is correct.
2. $j \neq m + 1$, which means that some EXTRACT-MIN operation has taken place after this INSERT operation I_j . 1 being the smallest element in the set S , the immediate E operation (j^{th} E) must extract this element. The algorithm also correctly assigns $extracted[j] \leftarrow i$ at line 4, where $i = 1$ here.

For the 2nd case, after the INSERT operation of the element 1 and the immediate (j^{th}) EXTRACT-MIN is evaluated correctly by the algorithm, the algorithm tries to consider the remaining sequence of operations again, but this time without the particular I and E . This is done by the line 6, which performs $K_l \leftarrow K_l \cup K_j$ (since the keys in K_j other than the element i can only be considered for extraction by the following EXTRACT-MINS) and destroys K_j , since it already found $extract[j]$, namely the key returned by the j^{th} EXTRACT-MIN. ✓

Therefore, for iterations $i = 2 \dots n$ it considers only the sequence of operations $I_1, E, I_2, E, \dots, I_{j-1}, E, I_{j+1}, E, \dots, I_m, E, I_{m+1}$, where $l = j + 1$ in this case (it can be $> j + 1$ in other cases when $j + 1$ is already destroyed). Hence after removing the INSERT operation for the element 1 (it's not physically removed, but will never be considered, since i is strictly increasing) and the corresponding $extracted[j]$, the sequence of n INSERT and m EXTRACT-MIN operations get reduced to a different (smaller) sequence of $n - 1$ INSERT and $m - 1$ EXTRACT-MIN operations, hence a smaller subproblem that is exactly similar and on it the algorithm will work for the iterations $i = 2$ to n .

By applying the same logic for the smaller subproblem with $n - 1$ INSERT and $m - 1$ EXTRACT-MIN operations (considered by the algorithm steps $\forall i =$

$2 \dots n$), we can divide it into 2 parts again, one for $i = 2$ and the other for still smaller subproblem $i = 3 \dots n$ and argue that the algorithm works correctly for $i = 2$. Continuing in this manner, $\forall i = k \dots n$, each time we can divide the current problem into another subproblem with strictly non-increasing size in the sequence of operations (handled by the algorithm in iterations $i = k + 1 \dots n$) and prove the correctness of the k^{th} iteration. But i is increasing, hence we are done when we have $i = n$.

Part (c)

Implementation

- Start with each element as a singleton set in a disjoint set forest, with total n elements.
- In order to form sets K_j , $j = 1 \dots m + 1$ (in the worst case last $n - 1$ of them possibly empty), $n - 1$ UNIONS in the worst case.
- Line 2 basically then reduces to $j \leftarrow \text{FIND-SET}(i)$ and we have n such operations.
- Line 5 reduces to $l \leftarrow \text{next}(j)$, operation which is executed for n times in the worst case.
- Line 6 reduces to $l \leftarrow \text{LINK}(j, l)$ operation which is also executed for n times in the worst case.

Hence, total number of operations = $m! = O(n)$

\Rightarrow amortized time = $O(m! \log^* n) = O(n \log^*(n))$

or to provide a tighter bound, the amortized time = $O(n\alpha(n))$, where α is the inverse of the Ackerman function.

Problem 2 Solution

As it can be seen from the figure 1, starting with $2^n + 1$ INSERT operations, followed by an EXTRACT-MIN (with CONSOLIDATE) operations, followed by $2^n - 1$ DELETE operations can create a Fibonacci Heap of height n , with n nodes (a chain).

Note that DELETE operation uses DECREASE-KEY + EXTRACT-MIN, where none of the DECREASE-KEY operation here can have cascade-cut, since every non-root node will have its child deleted only once.

Problem 3 Solution

Part (a)

Algorithm 1 Algorithm FIB-HEAP-CHANGE-KEY
FIB-HEAP-CHANGE-KEY(H, x, k)

```
1: if  $k < \text{key}[x]$  then
2:   call FIB-HEAP-DECREASE-KEY( $H, x, k$ ).
3: else if  $k == \text{key}[x]$  then
4:   return {do nothing}.
5: else {increase key}
6:   for each child  $y$  of  $x$  do
7:     call CUT( $H, y, x$ ).
8:   end for
9:    $\text{key}[x] \leftarrow k$ .
10:  call CASCADING-CUT( $H, x$ ).
11: end if
```

- Lines 1 – 2 have an amortized cost of $O(1)$, so have lines 3 – 4 (comparison cost).
- Let's analyze the amortized cost for lines 5 – 10, i.e., for the increase-key operation.

By the potential method, potential before increase-key = $t(H) + 2m(H)$.

Line 7 can increase the number of trees $t(H)$ by at most $D(n)$ (maximum degree of a node in the n -node Fibonacci heap = $O(\lg n)$).

Also, if we assume that the number of cascading cut recursive calls line 10 is c , then total decrease in number of marked nodes = $O(c)$, where the same call produces $O(c)$ additional trees, where c is a constant. Hence the potential after increase-key = $(t(H) + D(n) + O(c)) + 2(m(H) - O(c))$.

Hence, the change in potential is at most

$$\begin{aligned} &= (t(H) + D(n) + O(c)) + 2(m(H) - O(c)) - (t(H) + 2m(H)) \\ &= D(n) - O(c) = O(\lg n). \end{aligned}$$

- Total amortized time for FIB-HEAP-CHANGE-KEY = $O(\lg n)$.

Part (b) ?

Deleting a node \Rightarrow Decrease the corresponding key to $-\infty$, followed by Extract-Min, hence has an amortized cost of $O(1) + O(\lg n) = O(\lg n)$.



$$\cos \frac{\pi}{2} = \frac{1}{2}$$

$$1 + \cos \theta = 2 \cos^2 \frac{\theta}{2}$$

$$a^2 + b^2 = 1 \Rightarrow b^2 = 1 - a^2$$

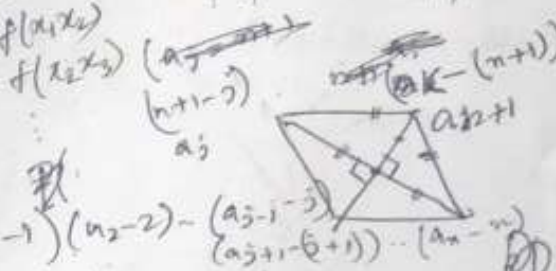
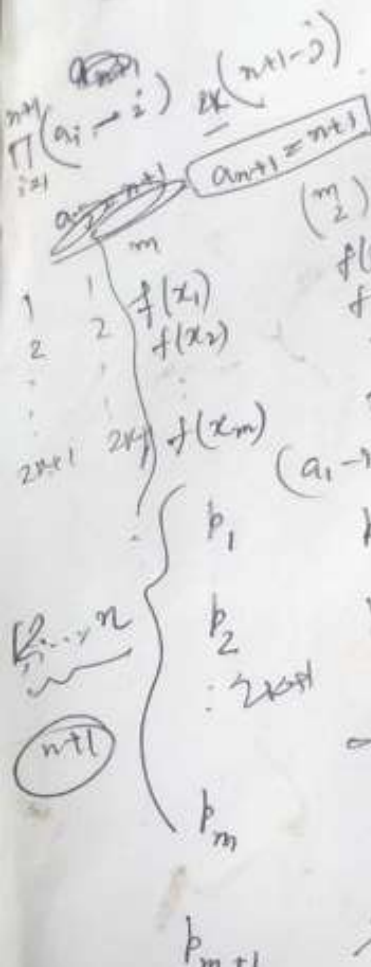
$$\frac{1 - \cos \theta}{\sin \theta} = \frac{1 - a + \sqrt{1 - a^2}}{a + \sqrt{1 - a^2}}$$

$$1 - (a + \sqrt{1 - a^2})^2 = (1 - a^2 - b^2) - 2a\sqrt{1 - a^2} = c + d$$



If we were to delete $\min(r, n[H])$ particular nodes the amortized cost would be $= O(\min(r, n[H]) \lg n)$.

But, since we could delete arbitrary nodes, we hope to do better. Deleting singleton trees and leaf nodes is easy. So, by maintaining a pointer to leaf nodes in each tree, the amortized cost of pruning $\min(r, n[H])$ nodes is $O(\min(r, n[H]))$.



$$c^2 + d = 1 - a^2 - b$$

$$c^2 + a^2 b = 1 - a^2 - b$$

$$\Rightarrow c^4 + (1 - a^2 - b)c^2 + a^2 b = 0$$

$$f(x) = (a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n) \equiv 0 \pmod{p_1}$$

$$f(x) \equiv 0 \pmod{p_m}$$

$$\Rightarrow (f_{m+1}, f(x_i)) = 1, \forall x_i \in \mathbb{Z}$$

$$(a_1 - 1)(a_2 - 2) \dots (a_n - n)(a_{n+1} - (n+1))$$

$$f(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n$$

$$f(x_1) + f(x_2) - f(x_m) \equiv 0 \pmod{p_m}$$