

1. To prove: $A \leq_L B \wedge B \leq_L C \Rightarrow A \leq_L C$.

Proof: $A \leq_L B \Rightarrow \exists$ logspace computable $f: \Sigma^* \rightarrow \Sigma^* \mid \forall w, w \in A \Leftrightarrow f(w) \in B$
 $B \leq_L C \Rightarrow \dots \dots \dots g: \Sigma^* \rightarrow \Sigma^* \mid \forall w, w \in B \Leftrightarrow g(w) \in C$
 (By definition)

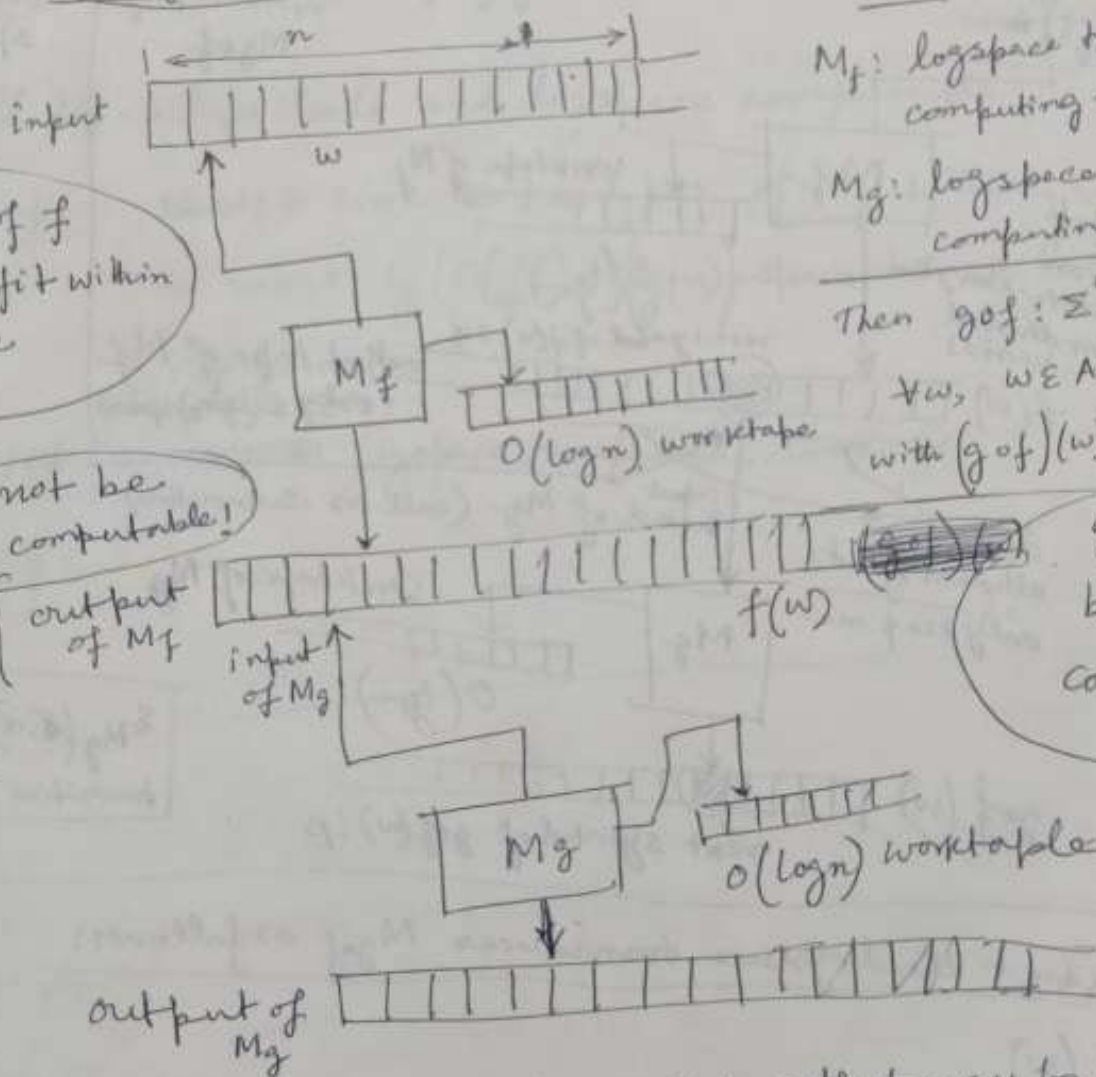
Wrong proof:

Why

Output of f may not fit within logspace

$g \circ f$ may not be logspace computable!

intermediate output of $f(w)$ may be large



Let

M_f : logspace transducer computing f

M_g : logspace transducer computing g .

Then $g \circ f: \Sigma^* \rightarrow \Sigma^* \mid \forall w, w \in A \Leftrightarrow (g \circ f)(w) \in C$
 with $(g \circ f)(w) = g(f(w))$

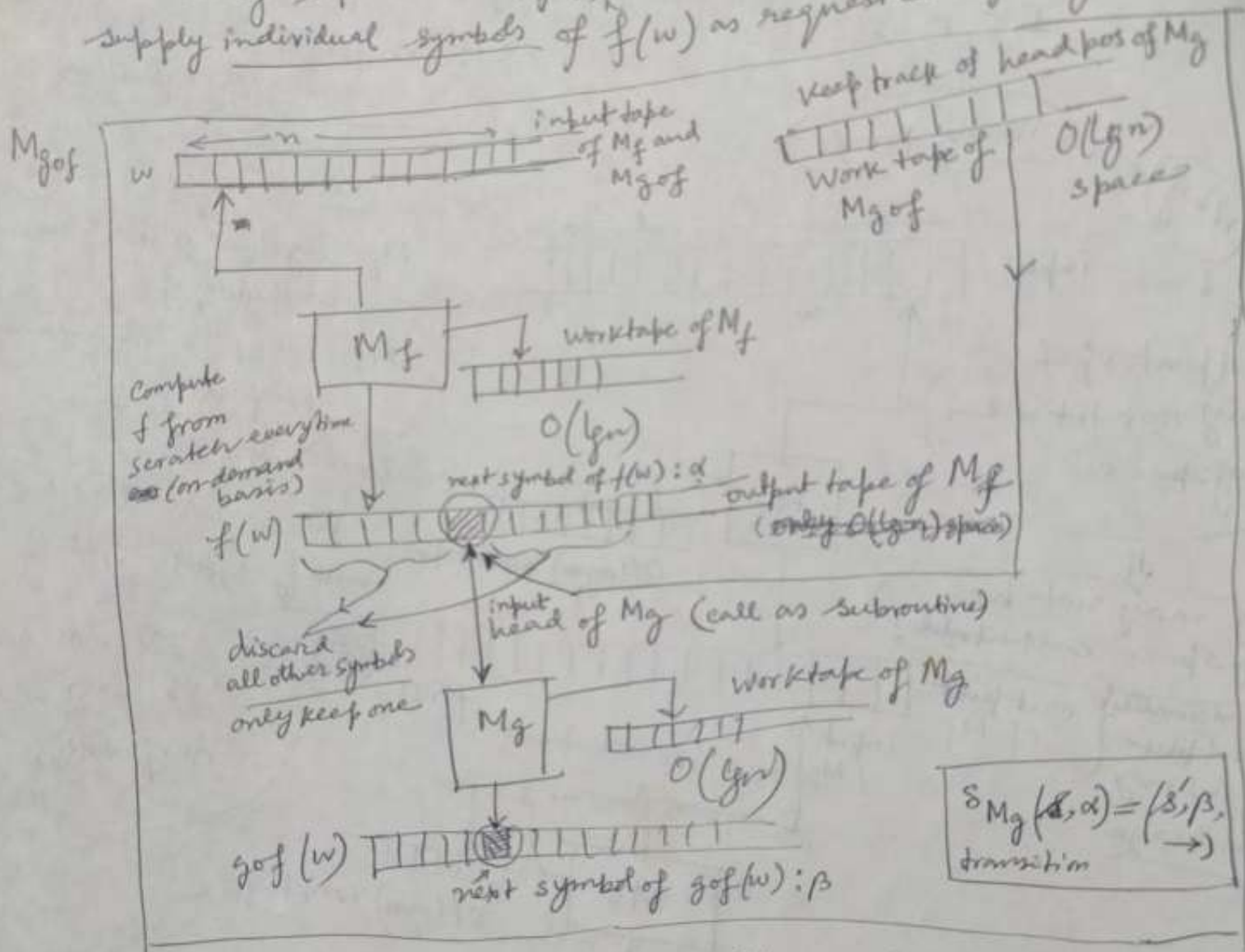
$g \circ f$ may not be logspace computable!

The problem is: $f(w)$, the intermediate output may be too large to fit with logspace bound. Since M_f runs in $O(\log n)$ space on input w of length n , number of configurations of M_f of w is $O(n^{O(\log n)}) = O(n^{2 \log n})$ which is an upper bound on the running time of M_f on w and also on the length of $f(w)$, which is not logspace. Hence $g \circ f$ is no longer logspace computable!

$n^{2 \log n}$ input
 $\frac{1}{\log n}$ time
 $\frac{1}{\log n}$ space
 $\frac{1}{\log n}$ configurations

Correct Proof:

Instead of storing the entire $f(w)$ (which may need much larger space than $\log n$), M_f recomputes $f(w)$ everytime to supply individual symbols of $f(w)$ as requested by M_g .



Construct the logspace transducer M_{gof} as follows:

$M_{gof}(w)$

1. Keep track of where M_g 's input head would be on $f(w)$.
/ e.g., initialize with the start pos. of $f(w)$ / If the input head is on the right of $f(w)$, exit.
2. (Re-) compute $f(w)$ by running M_f on w from the beginning and ignore all the output except the desired location (where M_g 's input head is). / e.g.,

need to store all of $f(w)$, only a single symbol is needed everytime the head of M_g is moved \star

3. Run M_g , only ~~by~~ by a single step (e.g. step execution mode, a single transition each time of on the input symbol $f(w)$ obtained from M_f and compute the next symbol for $g(f(w))$. Go to Step 1. $\delta_{M_g}(\beta, \alpha) = (\beta', \beta'', R)$ \star
- \uparrow next symbol of $f(w)$ \uparrow next symbol of $g(f(w))$

All the 3 steps halt and logspace computable.

Step 1: Needs to store the head pos. of M_g , which needs at most $\lg(O(n^2)) = O(\lg(n))$ space hence logspace computable.

Step 2: ~~Needs~~ logspace computable, since f is.

Step 3: " " " " g ✓

2. Let's assume that the ^{input} adjacency list is represented as ~~ordered~~ pairs of 2-tuples, i.e., if the list looks like $(u_1, v_1), (u_2, v_2), (u_3, v_3)$ then we have $(u_1, v_1) < (u_2, v_2) < (u_3, v_3) < \dots$ where the relation $<$ is defined as: $(u_1, v_1) < (u_2, v_2) \iff (u_1 < u_2) \vee (u_1 = u_2 \wedge v_1 < v_2)$ (Standard representation of adjacency matrix). According to the assumption $(1, 2), (2, 1256798), (2, 3)$ is not a valid representation instead it should be $(1, 2), (2, 3), (2, 1256798)$. Similarly $(1, 2), (2, 3)$ is a valid

should be able to fix the adjacency list if it doesn't have this format

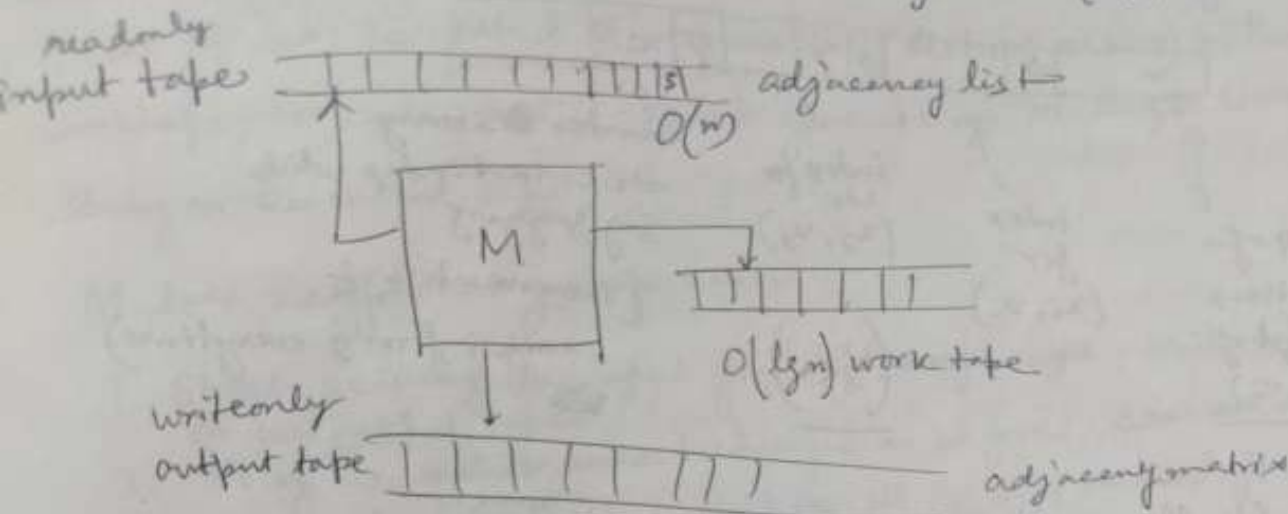
Also let's assume the output adjacency ~~list~~ ^{matrix} format is going to be like the following: if the graph has m nodes it will be $s_{11} s_{12} \dots s_{1m} s_{21} s_{22} \dots s_{2m} \dots s_{m1} s_{m2} \dots s_{mm}$ with $s_{ij} = \begin{cases} 1, & \text{iff } (i, j) \in \text{adj} \\ 0, & \text{otherwise} \end{cases}$ length m^2 binary string. There exists no isolated vertices (given).

Obviously, we need to compute the following things in logarithmic space

1. Number of vertices of the graph, m
2. ~~$s_{ij}, \forall i, j$~~
3. If the graph is sparse change the vertex numbers accordingly
3. Compute $s_{ij}, \forall (i, j) = 1, \dots, m$

For the sparse matrix we note that output will not have any redundant rows, i.e., $(\forall i)(\exists j)(s_{ij} \neq 0)$. Also since we are concerned about space here we shall not be efficient w.r.t. time. With all that in mind let's describe the algorithm for the logspace transducer that is going to convert the adjacency list representation to an adjacency matrix representation.

let's concentrate on computing the count of vertices (m).



M does the following:

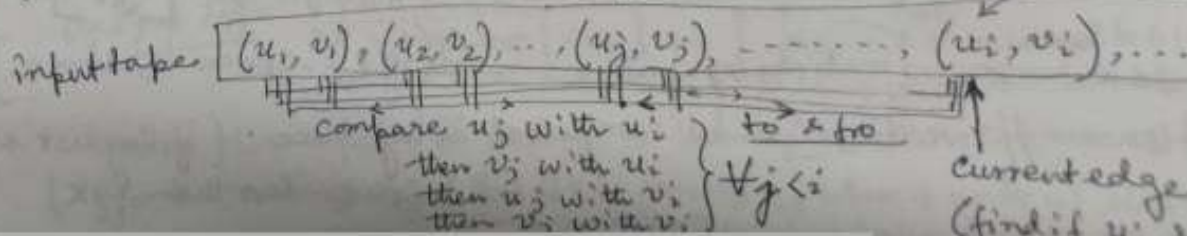
1. Initialize m with 0 and store it on the worktape. $/\ast m \leftarrow 0 \ast/$
2. ~~Scan the input~~ Store the ~~next~~ ⁽ⁱ⁾ index of the edge to be scanned ~~next~~ on the worktape as well, initialize it with 1. ~~per~~
 $/\ast$ e.g., if $(u_1, v_1), (u_2, v_2), (u_3, v_3), \dots$ in the adjacency list
 (u_1, v_1) and (u_2, v_2) are already scanned, $i \leftarrow 3$. Before start of
 Scanning the input, $i \leftarrow 1$, whenever $'i'$ is encountered, increment $i \ast/$
 eg. $i \leftarrow 1$ when $'1'$ is encountered, increment $i \ast/$
3. Repeatedly do the following until the end of input $'\$'$ is reached:

3.1. ~~(Restart scanning the input from the beginning. Initialize a counter~~
~~on the worktape by 1. While $(c < i)$ { move head to right and~~
~~if $'i'$ is encountered increment c by 1. Now extract the~~
~~next edge (u_i, v_i) from the input~~

$(\forall j < i)$ compare u_j and v_j with u_i in a zigzag manner, if all are different from u_i (which means a new vertex),
 $m \leftarrow m + 1$;

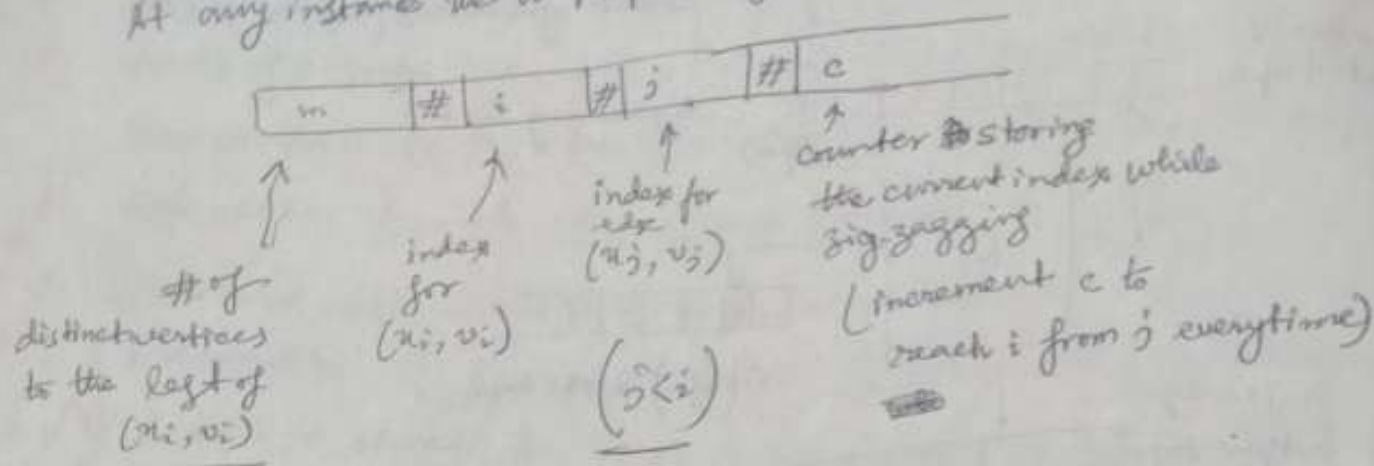
do the similar comparison to check if v_i is a new symbol.

3.2. $i \leftarrow i + 1$; goto 3.



(find if u_i & v_i are new)

At any instance the workspace may look like:



Typically m, i, j, c all will be ~~much~~ ^{much} less than $O(\log n)$, since i, j, c stores the index ^{of the edge} only.

e.g. for if $(1, 2), (2, 123576798), (3, 2)$ ^{be} the adj-list.

i is going to store ~~3~~ 3 (since 3rd edge)

j - - - - 2 (2nd)

m - - - - 4 (4 different vertices)

~~also in the worst case, if we have adj-list as $(1, 2), (2, 3), (3, 4), \dots, (k, k+1)$~~
~~input len $n = \lfloor \log_{10} 1 \rfloor + 1 + 2(\lfloor \log_{10} 2 \rfloor + 1) + 2(\lfloor \log_{10} 3 \rfloor + 1) + \dots + 2(\lfloor \log_{10} (k-1) \rfloor + 1) + \log_{10} k + 3k + k - 1$~~

Now the next step

[Also, in the worst case if we have adj-list as $(1, 2), (2, 3), (3, 4), \dots, (k-1, k)$,
 input length $n = \lfloor \log_{10} 1 \rfloor + 1 + 2(\lfloor \log_{10} 2 \rfloor + 1) + 2(\lfloor \log_{10} 3 \rfloor + 1) + \dots + 2(\lfloor \log_{10} (k-1) \rfloor + 1)$

$$\begin{aligned}
 &+ \lfloor \log_{10} k \rfloor + 1 + 3 \cdot k + k - 1 \\
 &\approx 2 \cdot \log_{10} 2 \cdot 3 \cdot (k-1) + 4k + \log_{10} k \\
 &= 2 \log_{10} (k-1)! + 4k + \log_{10} k \\
 &\geq 2 \log_{10} 10^{k-1} + 4k + \log_{10} k, \quad \forall k \geq 11 \\
 &= 2(k-1) + 4k + \log_{10} k = O(k).
 \end{aligned}$$

while, # vertices $m = K$, which needs ~~$O(\log_{10} K)$~~ $\lfloor \log_{10} K \rfloor + 1$

for same reason i, j needs also log space $= O(\lg k)$ space to store

Hence # vertices can be computed in log space. (if the list sparse it will be even less than $\lg k$)

Now the next step:

Once M has computed m (number of distinct vertices) on the worktape, it knows that it needs to generate an m^2 -length binary string on the output tape.

M does the following steps next.

1. Start scanning the input from left to right. Write m^2 zeros on the output tape.
2. Using the ~~same~~ same technique as before, scan an edge (u_i, v_i) . Again $\forall i < m$ compare all (u_j, v_j) 's on the left with

current edge to find the ~~last~~ new vertex number (in case of sparse matrix it will be different) of u_i and v_i . ~~Write~~ (let's say u_i' and v_i')

The renaming of vertices is explained in the example below. ~~Start from the beginning of the output tape and move the head towards right for identity transition $\delta(a, a) = (a, a)$~~

In between two consecutive (u_i, v_i) and (u_i, w_i) if v_i' and w_i' are not consecutive integers (obviously $v_i' < w_i'$), write the intermediate bits as 0's on the tape. But write 1 at the position

$(m-1) \times u_i + v_i$ (then write 0's) and write 1 at

$(m-1) \times u_i + w_i$ on the output tape

3. Go to step 2 and repeat until $i > m$.

Not sure about the details of your renaming scheme, but something like this will work

Vertex renaming

Let's see an example

input tape

$(1, 2) (2, 3) (3, 10100) (5, 1) (5, 12345678910)$

Count # vertices ~~with~~ having less number than the current one = 4 hence rename to 5

↑ rename to 5 ↑ rename to 4 ↑ rename to 6

M finds $m=6$

M extracts $(1, 2)$ first and finds that ~~both are~~ it does not need to change vertex numbers. So it ~~writes~~ writes 0's until it reaches δ_{12} , where it writes a 1

output tape $0100000000000000101000001$ $\delta_{11} \delta_{12} \dots \delta_{41} \delta_{21} \delta_{23} \delta_{31} \delta_{35} \delta_{51}$ $\delta_{54} \delta_{56}$ 15345678910 renamed

Then M scans $(2, 3)$ and sees that $u_2 = 2$, hence it goes on writing 0's for the remaining δ_{ij} 's and till it reaches δ_{23} where it writes a 1. Next scan $(3, 10100)$ and scanning the input tape find there are 4 vertices with less numbers. Hence,

3. To prove: Immerman-Szelepcsenyi Theorem extends to non-deterministic space bounds, i.e., $\forall S(n) \geq \lg n$, $NSPACE(S(n)) = co-NSPACE(S(n))$ is not space constructible.

Proof ~~of the theorem~~

1. M be a NTM which is $S(n)$ -space bounded $\Rightarrow \overline{L(M)} \in co-NSPACE(S(n))$. We have to construct another NTM N accepting $\overline{L(M)}$. If M has finite alphabet set Δ , with $|\Delta| = d$, every configuration can be represented as a string in $\Delta^{S(n)}$, where n is length of input.

2. Assume M has unique accepting configuration w.l.o.g., $accept \in \Delta^{S(n)}$ on inputs of length n . Let $start \in \Delta^{S(n)}$ represent start configuration on input x , $|x| = n$.

Define $A_m = \{ \alpha \in \Delta^{S(n)} \mid start \xrightarrow{\leq m} \alpha \}$
Set of configuration. configuration reachable within at most m steps from start

if x is accepted by M , the length of accepting config can be at most $d \cdot S(n)$

Obviously $A_0 = \{ start \}$, $|A_0| = 1$. Since $|A_m| \leq d^{S(n)}$, $\forall m$ to compute any $|A_m|$ only $O(S(n))$ space is needed.

Now, since $S(n)$ is NOT space constructible, we can't start by marking of $S(n)$ space (note: this much space is required in computing any $|A_m|$ and N uses the concept of census function to nondeterministically test the nonmembership of $accept$ in $A_{d \cdot S(n)}$) on N 's workspace.

6. Instead ~~do~~ do the following steps⁽⁵⁻⁶⁾ for successive values of $S = 1, 2, 3, \dots$ approximating the true space bound $S(n)$ (in order to get rid of space constructibility). For each S , if we ever encounter a configuration reachable from the start configuration that wants to use more than S space, set $S \leftarrow S+1$ and restart. We shall eventually hit $S(n)$, at which point no reachable configuration will try to use more space.

5.

5. Last off S space from on N 's workspace. ~~Compute~~ $|A_0| = 1$, compute $|A_{m+1}|$ from $|A_m|$: successively write down $\beta \in \Delta^{S(n)}$ in lexicographic order and for each one determine if $\beta \in A_{m+1}$, if so, increment a counter by one.

To test whether $\beta \in A_{m+1}$, nondeterministically guess $|A_m|$ elements of A_m in lexicographic order, verify that each $\alpha \in A_m$ by guessing the computation path $\text{start} \xrightarrow{\leq m} \alpha$ and for each α check whether $\alpha \xrightarrow{\leq 1} \beta$. If true then $\beta \in A_{m+1}$ or $\beta \notin A_{m+1}$ (using census function concept \xrightarrow{N} nondeterministically decided the non-reducibility problem)

6. After $|A_d^s|$ has been computed test accept $\notin A_d^s$ non-membership again in the similar manner by guessing $|A_d^s|$ elements α of A_d^s and verifying $\alpha \in A_d^s$ by guessing computation path $\text{start} \xrightarrow{\leq d^s} \alpha$, also verifying each α is different from accept .

/ Repeat steps 5, 6 for $s=1, 2, 3, \dots$ since the function is not space constructible, can't mark $S(n)$ space initially on N's tape +/

N runs in $S(n)$ space and decides $L(\bar{M}) \in \text{co-NSPACE}(S(n))$

$\Rightarrow \text{NSPACE}(S(n)) = \text{co-NSPACE}(S(n))$ (Proved) ✓

Extra-credit

8. To prove: $\text{UCYCLE} \in L$

8+2=10
Proof

We have to find whether the graph G is a forest or not. We assume that the vertices of G are arbitrarily labeled 1 through n . First let's define a cyclic ordering of the edges incident on a vertex u in the following manner: if $(u, v_1), (u, v_2), \dots, (u, v_k) \in E[G]$ with $d(u) = k$, the cyclic ordering is defined by $(u, v_{i_1}) < (u, v_{i_2}) < \dots < (u, v_{i_k})$

where i_1, i_2, \dots, i_k is a proper permutation of $1, 2, \dots, k$ and $i_1 < i_2 < \dots < i_k$.
If $d(u) = 0$, no ordering. $d(u) = 1, (u, v) \in E$: the ordering is $(u, v) < (u, v)$

Next, let's define a traversal algorithm starting from any vertex u . The algorithm starts with a vertex-edge pair (u, e) , where e is incident on u . At each step, the algorithm enters a vertex on an

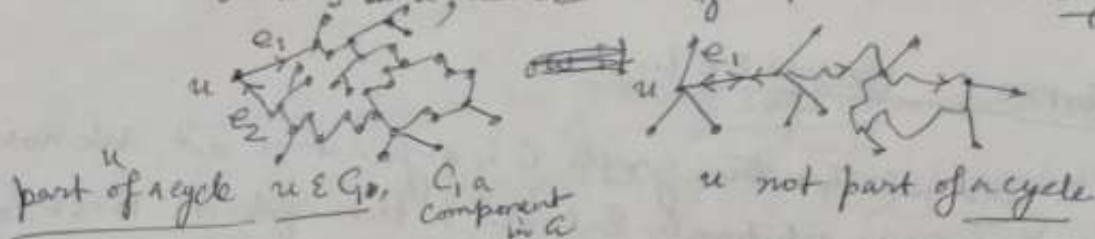


edge e_1 and leaves the vertex on the edge e_2 that comes after e_1 in the circular order.

Claim 1: The algorithm starting from u eventually returns to u .

Proof: Since the traversal algorithm starting from u can only reach the nodes v that are reachable (by a path) from u and reachability is symmetric (u will also be reachable from v) and since the circular ordering guarantees that all the ~~paths~~ edges ~~from~~ incident on every node must be traversed eventually, it must reach u . [If it reaches to a vertex $v \neq u$ from u via path P_1 , it will return ~~to~~ back to u via the path P_1 ~~on a different path~~ if \exists only one path $P_1: u \rightarrow v$, otherwise it will return ~~to~~ via a different path P_2 , if $d(v) \geq 2$ and \exists a different path $u \xrightarrow{P_2} v$]

Claim 2: If a vertex $u \in C_1$ is part of a cycle, $\iff \exists$ such a traversal starting from u and traversing ~~all the~~ ^{$K=1, 2, \dots, |C_1|$} reachable vertices ~~at~~ ^{from} u , ~~must~~ coming back to u via a different edge.



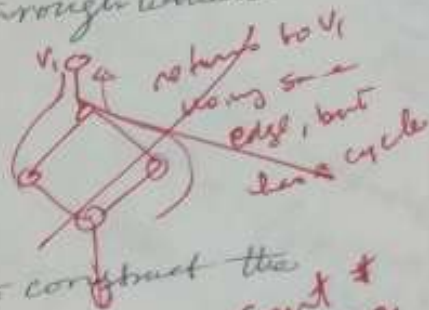
Here $1 \leq K \leq |C_1|$, where C_1 is the component where u belongs to.

Proof: It's easy to see that if ~~there is~~ ^{u} is not part of a cycle, $\forall v \in V(G)$ that are reachable from u , \exists exactly one path from u to v . Hence ~~the~~ ^{any} traversal starting from u and exiting u with edge e_1 must return to u ~~via~~ via edge e_1 only.

If u is part of a cycle, \exists at least one more vertex $v \neq u$ on the same cycle \odot hence \exists at least 2 paths from u to v and ~~since~~ by circular ordering, \exists at least one traversal starting

from u will come back to u in a different edge (and path).

Claim 3: G is a forest (does not contain a cycle) iff all possible such traversals starting from any vertex of G returns to the same vertex via the same edge through which it left that vertex.



Proof: Obvious from Claim 1 & 2

With all the above claims, we are now ready to construct the logspace transducer M that decides $UCYCLE$:

$M(G(V, E))$

/* Decides whether G contains $CYCLE$ */

1. $\forall v \in V(G)$ do the following:

1.1. Store the start vertex v , and current vertex c only on the worktape. Initialize $c \leftarrow v$, $p \leftarrow v$. /* only $(\log(n))$ space */

1.2. if $(c == v)$ /* first vertex of cycle or doing from v by choosing the by finding the corresponding vertex $v_1 \in adj(c)$ /* read the input tape to find such v_1 's from $E[G]$ */

else choose the next edge e_2 incident on c such that it's next to $e_1 = (p, c)$ in the cyclic ordering

/* scan each $e = (c, v) \in E[G]$ from input tape */

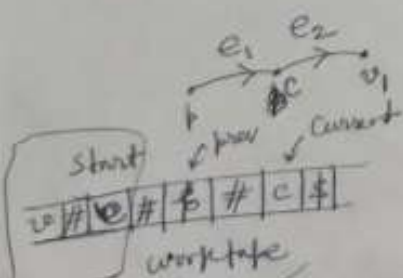
~~if $(v_1 == v)$ goto 1.1~~

1.3. if $(v_1 == v)$ /* returned to start */

if $(c, v_1) \neq e$ /* Not same return edge */

output 'yes'; else goto 1;

else goto 1.1; /* if $v_1 = v$ */



only uses logspace

Always terminates

Forest: \rightarrow

output 'No'