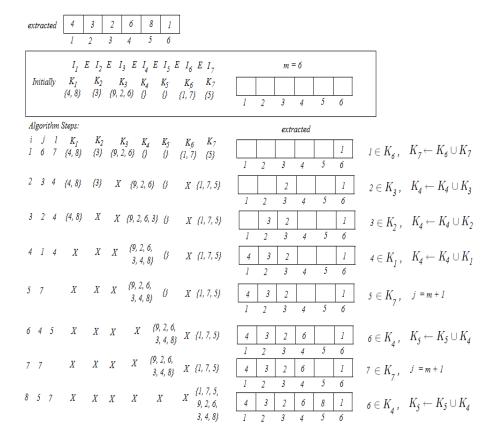
CMSC 641, Design and Analysis of Algorithms, Spring 2010

Sandipan Dey, Homework Assignment - 3

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Problem 1 (Offline minimum) Solution

Part (a)



Part (b)

Proof

The OFF-LINE-MINIMUM algorithm deals with n INSERT (I) operations $(\bigcup_{k=1}^{m} I_k)$ and m EXTRACT-MIN (E) operations. To prove that the algorithm is correct, we need to prove that $\forall j \in \{1, 2, \dots m\}$, extract[j] contains the key returned by j^{th} E.

For i=1, the algorithm considers the entire sequence $I_1, E, I_2, E, \dots I_m, E, I_{m+1}$. It first finds a $j|i \in K_j$. There can be couple of cases:

- 1. j=m+1, which means that the element 1 is inserted after the last EXTRACT-MIN, in which case it will NOT be part of the *extracted* array, since it will never get a chance to be extracted. The algorithm also does nothing $(j \neq m+1$ check on line 3 ensures it), simply proceeds to the next larger element. Since the elements $\{1, 2, \dots n\}$ are considered in the increasing order (ensured by the for loop in line 1), this element will never be considered again. Hence, this behavior is correct.
- 2. $j \neq m+1$, which means that some EXRACT-MIN operation has taken place after this INSERT operation I_j . 1 being the smallest element in the set S, the immediate E operation $(j^{th} E)$ must extract this element. The algorithm also correctly assigns $extracted[j] \leftarrow i$ at line 4, where i=1 here.

For the 2nd case, after the INSERT operation of the element 1 and the immediate (j^{th}) EXTRACT-MIN is evaluated correctly by the algorithm, the algorithm tries to consider the remaining sequence of operations again, but this time without the particular I and E. This is done by the line 6, which performs $K_l \leftarrow K_l \cup K_j$ (since the keys in K_j other than the element i can only be considered for extraction by the following EXTRACT-MINS) and destroys K_j , since it already found extract[j], namely the key returned by the j^{th} EXTRACT-MIN.

Therefore, for iterations $i=2\ldots n$ it considers only the sequence of operations $I_1, E, I_2, E, \ldots I_{j-1}, E, I_{j+1}, E, \ldots I_m, E, I_{m+1}$, where l=j+1 in this case (it can be > j+1 in other cases when j+1 is already destroyed). Hence after removing the INSERT operation for the element 1 (it's not physically removed, but will never be considered, since i is strictly increasing) and the corresponding extracted[j], the sequence of n INSERT and m EXTRACT-MIN operations get reduced to a different (smaller) sequence of n-1 INSERT and m-1 EXTRACT-MIN operations, hence a smaller subproblem that is exactly similar and on it the algorithm will work for the iterations i=2 to n.

By applying the same logic for the smaller subproblem with n-1 INSERT an m-1 EXTRACT-MIN operations (consdered by the algorithm steps $\forall i = 1$)

2...n), we can divide it into 2 parts again, one for i=2 and the other for still smaller subproblem i=3...n and argue that the algorithm works correctly for i=2. Continuing in this manner, $\forall i=k...n$, each time we can divide the current problem into another subproblem with strictly non-increasing size in the sequence of operations (handled by the algorithm in iterations i=k+1...n) and prove the correctness of the k^{th} iteration. But i is increasing, hence we are done when we have i=n.

Part (c)

Implementation

- Start with each element as a singleton set in a disjoint set forest, with total n elements.
- In order to form sets K_j , $j = 1 \dots m + 1$ (in the worst case last n 1 of them possibly empty), n 1 UNIONs in the worst case.
- Line 2 basically then reduces to $j \leftarrow FIND SET(i)$ and we have n such operations.
- Line 5 reduces to $l \leftarrow next(j)$, operation which is executed for n times in the worst case.
- Line 6 reduces to $l \leftarrow LINK(j, l)$ operation which is also executed for n times in the worst case.

Hence, total number of operations = m' = O(n)

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\Rightarrow amortized time = O(m' \log^* n) = O(n \log^*(n))
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or to provide a tighter bound, the amortized time = $O(n\alpha(n))$, where α is the inverse of the Ackerman function.

Problem 2 Solution

As it can be seen from the figure 1, starting with $2^n + 1$ INSERT operations, followed by an EXTRACT-MIN (with CONSOLIDATE) operations, followed by $2^n - 1$ DELETE operations can create a Fibonacci Heap of height n, with n nodes (a chain).

Note that DELETE operation uses DECREASE-KEY + EXTRACT-MIN, where none of the DECREASE-KEY operation here can have cascade-cut, since every non-root node will have its child deleted only once.

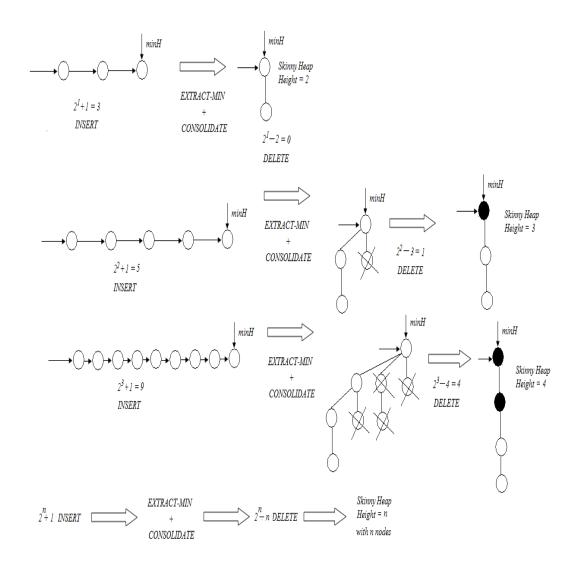


Figure 1: Skinny Fibonacci Heaps with height O(n)

Problem 3 Solution

Part (a)

Algorithm 1 Algorithm FIB-HEAP-CHANGE-KEY

```
FIB - HEAP - CHANGE - KEY(H, x, k)
 1: if k < key[x] then
     call FIB - HEAP - DECREASE - KEY(H, x, k).
 3: else if k == key[x] then
     return {do nothing}.
 5: else {increase key}
     for each child y of x do
 6:
       call CUT(H, y, x).
 7:
     end for
 8:
 9:
     key[x] \leftarrow k.
     call CASCADING - CUT(H, x).
10:
11: end if
```

- Lines 1-2 have an amortized cost of O(1), so have lines 3-4 (comparison cost).
- Let's analyze the amortized cost for lines 5-10, i.e., for the increase-key operation.

By the potential method, potential before increase-key = t(H) + 2m(H).

Line 7 can increase the number of trees t(H) by at most D(n) (maximum degree of a node in the n-node Fibonacci heap $= O(\lg n)$).

Also, if we assume that the number of cascading cut recursive calls line 10 is c, then total decrease in number of marked nodes = O(c), where the same call produces O(c) additional trees, where c is a constant. Hence the potential after increase-key = (t(H) + D(n) + O(c)) + 2(m(H) - O(c)).

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Hence, the change in potential is at most = (t(H) + D(n) + O(c)) + 2(m(H) - O(c))) - (t(H) + 2m(H))
= D(n) - O(c) = O(lg n).
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• Total amortized time for FIB-HEAP-CHANGE-KEY = O(lg n).

Part (b)

Deleting a node \Rightarrow Decrease the corresponding key to $-\infty$, followed by Extract-Min, hence has an amortized cost of $O(1) + O(\lg n) = O(\lg n)$.

If we were to delete min(r, n[H]) particular nodes the amortized cost would be = O(min(r, n[H]).lg n).

But, since we could delete arbitrary nodes, we hope to do better. Deleting singleton trees and leaf nodes is easy. So, by maintaining a pointer to leaf nodes in each tree, the amortized cost of pruning min(r, n[H]) nodes is O(min(r, n[H])).