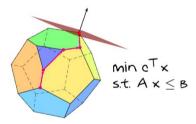


## Linear and Discrete Optimization

### Paths, Cycles and Flows

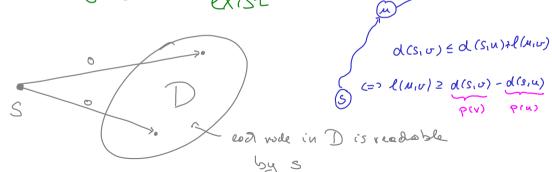
Shortest paths and linear programming



#### **Potentials**

Let D=(V,A) be a directed graph with arc-lengths  $\ell:A\to\mathbb{R}$ . A function  $p:V\to\mathbb{R}$  is a *potential* if

$$\forall a=(u,v)\in A:\quad \ell(a)\geqslant p(v)-p(u).$$

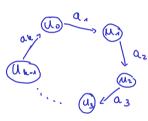


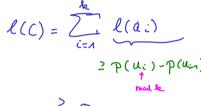
### Existence of potentials

#### **Theorem**

D=(V,A) with  $\ell:A\to\mathbb{R}$  has a potential p if and only if each directed cycle is of non-negative length.









# Computing distances with linear programming

#### **Theorem**

Let D=(V,A) be a directed graph with arc-lengths  $\ell:A\to\mathbb{R},\,s\in V$  such that each vertex in V is reachable from s and suppose that each directed cycle is non-negative. Let p be a potential with p(s)=0 and  $\sum_{v\in V}p(v)$  maximal. Then

$$\forall t \in V : p(t) = \operatorname{dist}_{\ell}(s, t).$$

broot:

Shortest path distances are a potential

$$S \longrightarrow \mathcal{M}_{2} \longrightarrow \mathcal{M}_{2} \longrightarrow \mathcal{M}_{2}$$

$$P(\mathcal{M}_{1}) \leq l(S_{1}\mathcal{M}_{1})$$

$$P(\mathcal{M}_{2}) \leq l(\mathcal{M}_{1}\mathcal{M}_{2}) + P(\mathcal{M}_{1}) \leq l(\mathcal{M}_{1}\mathcal{M}_{2}) + l(S_{1}\mathcal{M}_{1})$$

$$P(\mathcal{M}_{2}) \leq lm_{2}\mathcal{M}_{1} \text{ of } PATH.$$

$$P(\mathcal{M}) \leq d(S_{1}\mathcal{M}_{1})$$

