

We're updating the default styles for Matplotlib 2.0

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api example code:  
radar\_chart.py

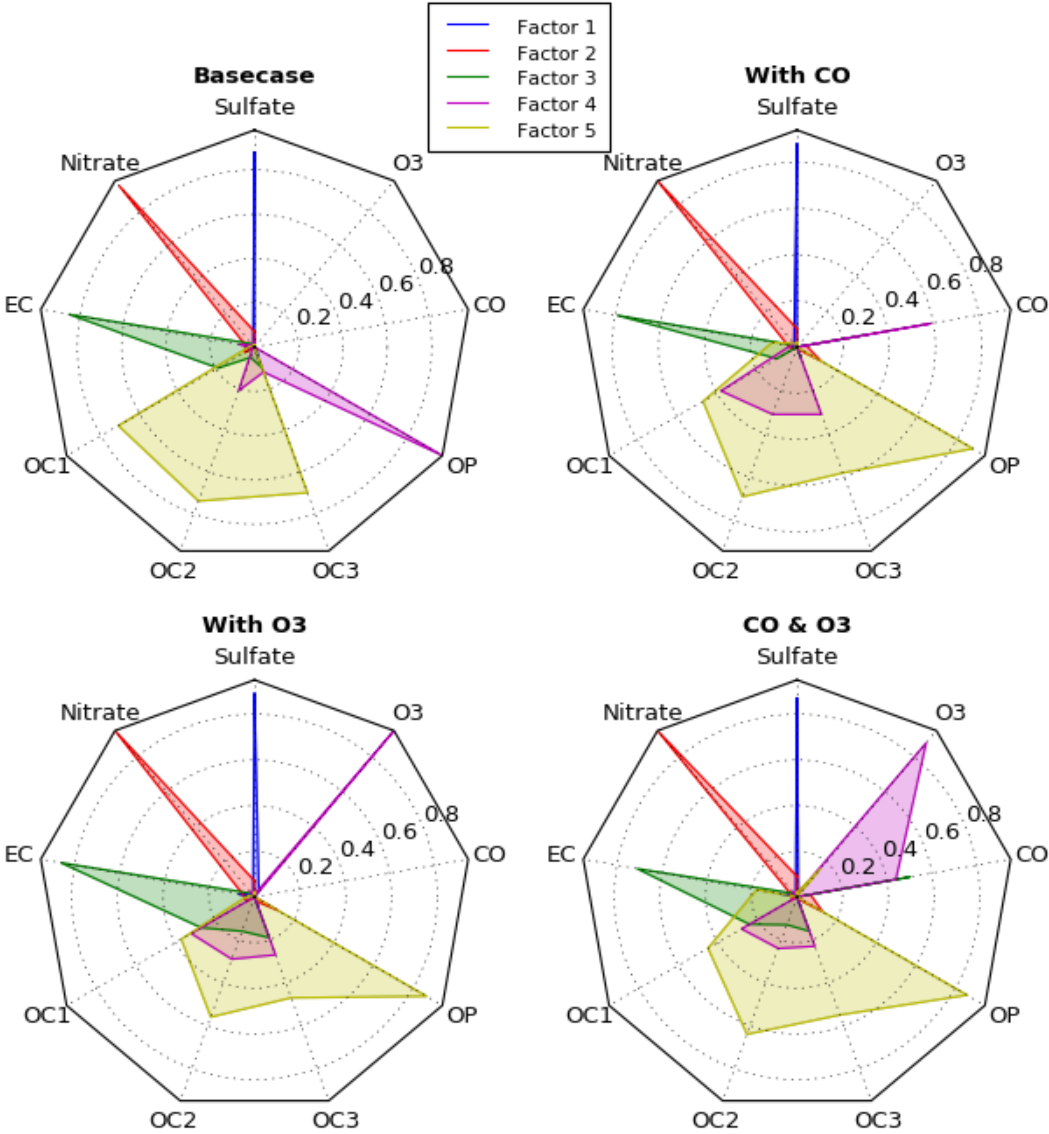
([Source code](#), [png](#), [hires.png](#), [pdf](#))

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```
"""  
Example of creating a radar chart (a.k.a. a spider or star chart) [1]_.  
[1]_
```

Although this example allows a frame of either 'circle' or 'polygon', polygon frames don't have proper gridlines (the lines are circles instead of polygons). It's possible to get a polygon grid by setting `GRIDLINE_INTERPOLATION_STEPS` in `matplotlib.axis` to the desired number of vertices, but the orientation of the polygon is not aligned with the radial axes.

```
.. [1] http://en.wikipedia.org/wiki/Radar\_chart
"""
import numpy as np

import matplotlib.pyplot as plt
from matplotlib.path import Path
from matplotlib.spines import Spine
from matplotlib.projections.polar import PolarAxes
from matplotlib.projections import register_projection

def radar_factory(num_vars, frame='circle'):
    """Create a radar chart with `num_vars` axes.

    This function creates a RadarAxes projection and registers it.

    Parameters
    -----
    num_vars : int
        Number of variables for radar chart.
    frame : {'circle' | 'polygon'}
        Shape of frame surrounding axes.

    """
    # calculate evenly-spaced axis angles
    theta = np.linspace(0, 2*np.pi, num_vars, endpoint=False)
    # rotate theta such that the first axis is at the top
    theta += np.pi/2

    def draw_poly_patch(self):
        verts = unit_poly_verts(theta)
        return plt.Polygon(verts, closed=True, edgecolor='k')

    def draw_circle_patch(self):
        # unit circle centered on (0.5, 0.5)
        return plt.Circle((0.5, 0.5), 0.5)

    patch_dict = {'polygon': draw_poly_patch, 'circle': draw_circle_patch}
    if frame not in patch_dict:
        raise ValueError('unknown value for `frame`: %s' % frame)

    class RadarAxes(PolarAxes):

        name = 'radar'
        # use 1 line segment to connect specified points
        RESOLUTION = 1
        # define draw_frame method
        draw_patch = patch_dict[frame]

        def fill(self, *args, **kwargs):
            """Override fill so that line is closed by default"""
            closed = kwargs.pop('closed', True)
            return super(RadarAxes, self).fill(closed=closed, *args, **kwargs)

        def plot(self, *args, **kwargs):
            """Override plot so that line is closed by default"""
            lines = super(RadarAxes, self).plot(*args, **kwargs)
            for line in lines:
                self._close_line(line)

        def _close_line(self, line):
            x, y = line.get_data()
            # FIXME: markers at x[0], y[0] get doubled-up
```

```

        if x[0] != x[-1]:
            x = np.concatenate((x, [x[0]]))
            y = np.concatenate((y, [y[0]]))
            line.set_data(x, y)

    def set_varlabels(self, labels):
        self.set_thetagrids(np.degrees(theta), labels)

    def _gen_axes_patch(self):
        return self.draw_patch()

    def _gen_axes_spines(self):
        if frame == 'circle':
            return PolarAxes._gen_axes_spines(self)
        # The following is a hack to get the spines (i.e. the axes frame)
        # to draw correctly for a polygon frame.

        # spine_type must be 'left', 'right', 'top', 'bottom', or 'circle'.
        spine_type = 'circle'
        verts = unit_poly_verts(theta)
        # close off polygon by repeating first vertex
        verts.append(verts[0])
        path = Path(verts)

        spine = Spine(self, spine_type, path)
        spine.set_transform(self.transAxes)
        return {'polar': spine}

register_projection(RadarAxes)
return theta

def unit_poly_verts(theta):
    """Return vertices of polygon for subplot axes.

    This polygon is circumscribed by a unit circle centered at (0.5, 0.5)
    """
    x0, y0, r = [0.5] * 3
    verts = [(r*np.cos(t) + x0, r*np.sin(t) + y0) for t in theta]
    return verts

def example_data():
    # The following data is from the Denver Aerosol Sources and Health study.
    # See doi:10.1016/j.atmosenv.2008.12.017
    #
    # The data are pollution source profile estimates for five modeled
    # pollution sources (e.g., cars, wood-burning, etc) that emit 7-9 chemical
    # species. The radar charts are experimented with here to see if we can
    # nicely visualize how the modeled source profiles change across four
    # scenarios:
    # 1) No gas-phase species present, just seven particulate counts on
    # Sulfate
    # Nitrate
    # Elemental Carbon (EC)
    # Organic Carbon fraction 1 (OC)
    # Organic Carbon fraction 2 (OC2)
    # Organic Carbon fraction 3 (OC3)
    # Pyrolyzed Organic Carbon (OP)
    # 2) Inclusion of gas-phase specie carbon monoxide (CO)
    # 3) Inclusion of gas-phase specie ozone (O3).
    # 4) Inclusion of both gas-phase species present...
    data = [
        ['Sulfate', 'Nitrate', 'EC', 'OC1', 'OC2', 'OC3', 'OP', 'CO', 'O3'],
        ('Basecase', [
            [0.88, 0.01, 0.03, 0.03, 0.00, 0.06, 0.01, 0.00, 0.00],
            [0.07, 0.95, 0.04, 0.05, 0.00, 0.02, 0.01, 0.00, 0.00],
            [0.01, 0.02, 0.85, 0.19, 0.05, 0.10, 0.00, 0.00, 0.00],
            [0.02, 0.01, 0.07, 0.01, 0.21, 0.12, 0.98, 0.00, 0.00],
            [0.01, 0.01, 0.02, 0.71, 0.74, 0.70, 0.00, 0.00, 0.00]]),
    ]

```

```

    ('With CO', [
        [0.88, 0.02, 0.02, 0.02, 0.00, 0.05, 0.00, 0.05, 0.00],
        [0.08, 0.94, 0.04, 0.02, 0.00, 0.01, 0.12, 0.04, 0.00],
        [0.01, 0.01, 0.79, 0.10, 0.00, 0.05, 0.00, 0.31, 0.00],
        [0.00, 0.02, 0.03, 0.38, 0.31, 0.31, 0.00, 0.59, 0.00],
        [0.02, 0.02, 0.11, 0.47, 0.69, 0.58, 0.88, 0.00, 0.00]]),
    ('With O3', [
        [0.89, 0.01, 0.07, 0.00, 0.00, 0.05, 0.00, 0.00, 0.03],
        [0.07, 0.95, 0.05, 0.04, 0.00, 0.02, 0.12, 0.00, 0.00],
        [0.01, 0.02, 0.86, 0.27, 0.16, 0.19, 0.00, 0.00, 0.00],
        [0.01, 0.03, 0.00, 0.32, 0.29, 0.27, 0.00, 0.00, 0.95],
        [0.02, 0.00, 0.03, 0.37, 0.56, 0.47, 0.87, 0.00, 0.00]]),
    ('CO & O3', [
        [0.87, 0.01, 0.08, 0.00, 0.00, 0.04, 0.00, 0.00, 0.01],
        [0.09, 0.95, 0.02, 0.03, 0.00, 0.01, 0.13, 0.06, 0.00],
        [0.01, 0.02, 0.71, 0.24, 0.13, 0.16, 0.00, 0.50, 0.00],
        [0.01, 0.03, 0.00, 0.28, 0.24, 0.23, 0.00, 0.44, 0.88],
        [0.02, 0.00, 0.18, 0.45, 0.64, 0.55, 0.86, 0.00, 0.16]])
]
return data

if __name__ == '__main__':
    N = 9
    theta = radar_factory(N, frame='polygon')

    data = example_data()
    spoke_labels = data.pop(0)

    fig = plt.figure(figsize=(9, 9))
    fig.subplots_adjust(wspace=0.25, hspace=0.20, top=0.85, bottom=0.05)

    colors = ['b', 'r', 'g', 'm', 'y']
    # Plot the four cases from the example data on separate axes
    for n, (title, case_data) in enumerate(data):
        ax = fig.add_subplot(2, 2, n + 1, projection='radar')
        plt.rgrids([0.2, 0.4, 0.6, 0.8])
        ax.set_title(title, weight='bold', size='medium', position=(0.5, 1.1),
                     horizontalalignment='center', verticalalignment='center')
        for d, color in zip(case_data, colors):
            ax.plot(theta, d, color=color)
            ax.fill(theta, d, facecolor=color, alpha=0.25)
        ax.set_varlabels(spoke_labels)

    # add legend relative to top-left plot
    plt.subplot(2, 2, 1)
    labels = ('Factor 1', 'Factor 2', 'Factor 3', 'Factor 4', 'Factor 5')
    legend = plt.legend(labels, loc=(0.9, .95), labelspace=0.1)
    plt.setp(legend.get_texts(), fontsize='small')

    plt.figtext(0.5, 0.965, '5-Factor Solution Profiles Across Four Scenarios',
               ha='center', color='black', weight='bold', size='large')
    plt.show()

```

Keywords: python, matplotlib, pylab, example, codex (see [Search examples](#))