



# **Session 2. Spatiotemporal and Trajectory Pattern Mining**

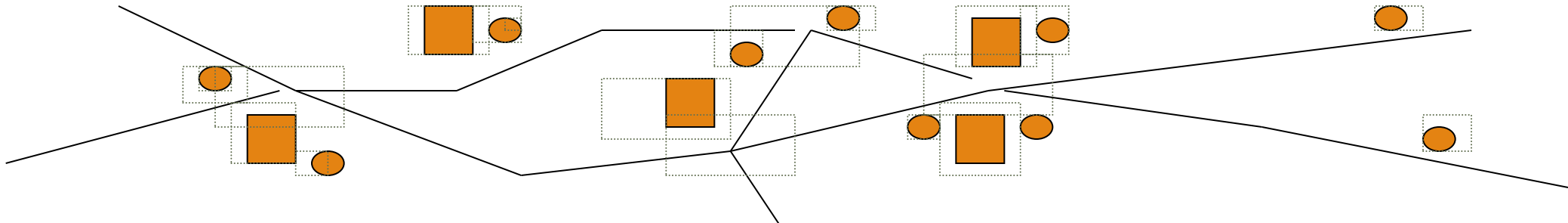
# Spatial Patterns and Associations

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- Spatial frequent patterns and association rule:  $A \Rightarrow B [s\%, c\%]$ 
  - A and B are sets of spatial or non-spatial predicates, e.g.,
    - Topological relations: *intersects*, *overlaps*, *disjoint*, etc.
    - Spatial orientations: *left\_of*, *west\_of*, *under*, etc.
    - Distance information: *close\_to*, *within\_distance*, etc.
  - $s\%$ : support, and  $c\%$ : confidence of the rule
- Example: Rules likely to be found
  - $is\_a(x, large\_town) \wedge intersect(x, highway) \rightarrow adjacent\_to(x, water)$   
 $[7\%, 85\%]$
- Explore *spatial autocorrelation*: Spatial data tends to be highly self-correlated (*nearby things are more related than distant ones*)
  - E.g., neighborhood, temperature

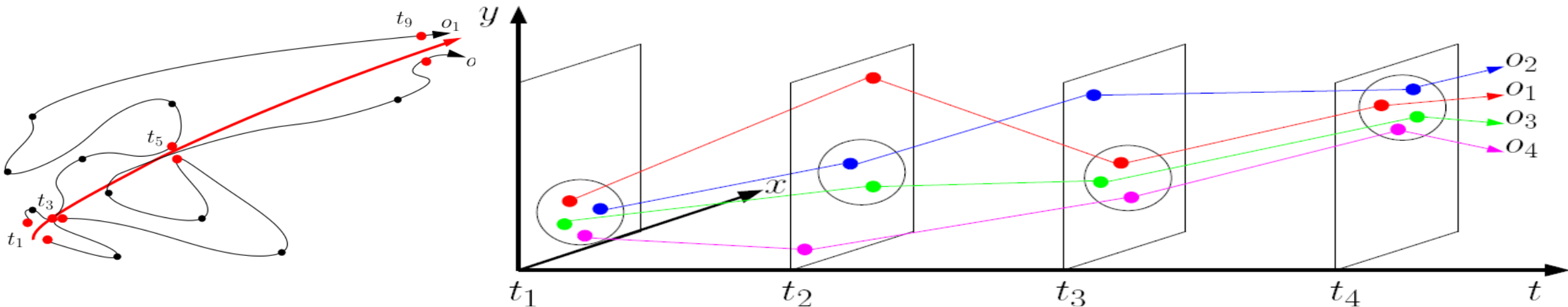
# Mining Spatial Associations: Progressive Refinement

- Hierarchy of spatial relationship:
  - *g\_close\_to: near\_by, touch, intersect, contain, etc.*
  - **Progressive refinement:** First search for rough relationship and then refine it
- Two-step mining of spatial association:
  - Step 1: Rough spatial computation (as a filter)
    - Using MBR (Minimum Bounding Rectangle) or R-tree for rough estimation
  - Step2: Detailed spatial algorithm (as refinement)
    - Apply only to those objects which have passed the rough spatial association test (no less than *min\_support*)



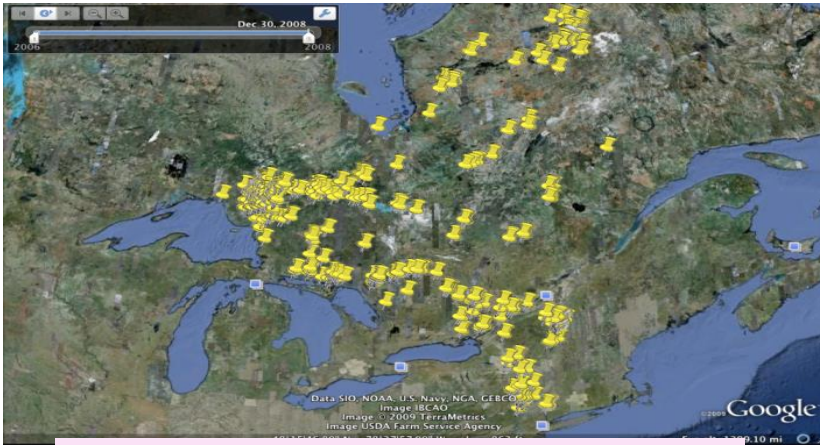
# Mining Relative Movement Patterns

- ❑ **Flock:** At least  $m$  entities are within a circular region of *radius*  $r$  and move in the same direction
- ❑ **Convoy:** Uses *density-based clustering* at each timestamp; no need to be a rigid circle
- ❑ Flock and convoy: Both require  $k$  **consecutive** time stamps
- ❑ **Swarm:** Moving objects may not be close to each other for all the consecutive time stamps
- ❑ Efficient pattern mining algorithms for uncovering such swarm patterns

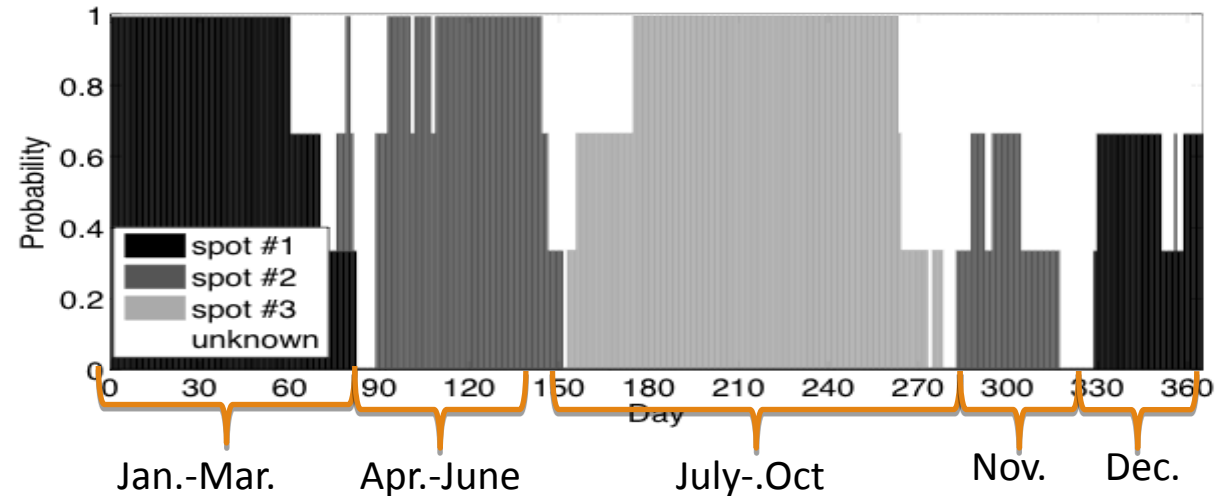
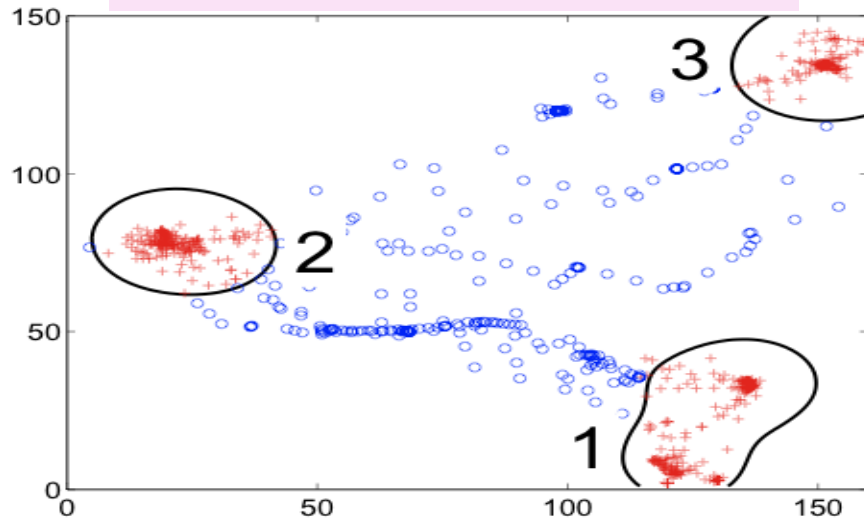




# Mining Periodic Patterns with Sparse Data



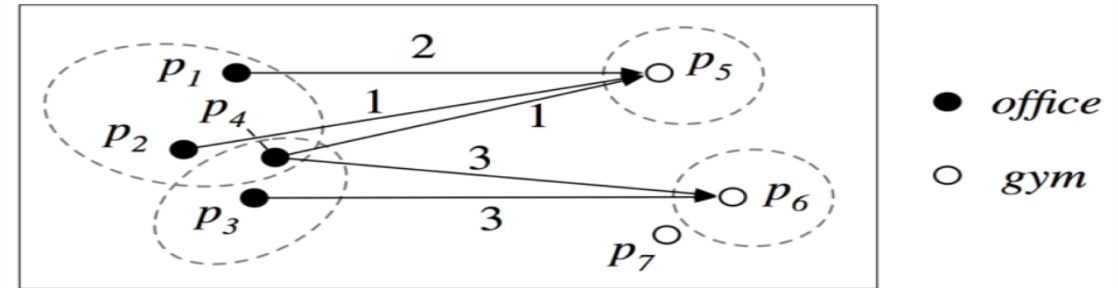
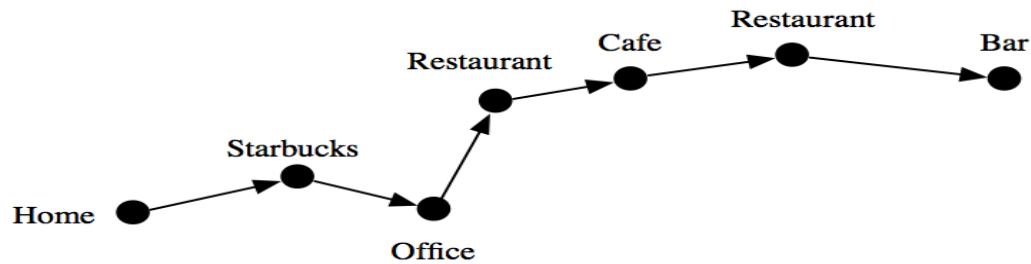
3-yr Bird migration data: very sparse



- **Detecting periods:** Cluster to find reference “points” and then detect multiple interleaved periods by Fourier Transform and auto-correlation
- **Summarizing periodic patterns:** By clustering and pattern discovery

# Semantic Trajectory Pattern Mining

- Semantic trajectory: Trajectory carries semantics (e.g., category)



- Meaningful sequential patterns: 3 constraints: (i) semantic consistency; (ii) spatial compactness; and (iii) temporal continuity
- Method: A two-step approach
  - 1: Mining coarse patterns that satisfy the semantic and temporal constraints (e.g., office  $\rightarrow$  gym)
    - First, mine semantically meaningful patterns (e.g., categories)
    - Then, detect dense and compact clusters in the high-dimensional space
  - 2: Splitting coarse patterns into fine-grained ones to meet the spatial constraint (e.g., people working in which office tend to go to which gym)

# Recommended Readings on Spatiotemporal and Trajectory Pattern Mining

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- ❑ Y. Huang, S. Shekhar, H. Xiong, Discovering colocation patterns from spatial data sets: A general approach, IEEE Trans. on Knowledge and Data Engineering, 16(12), 2004
- ❑ K. Koperski, J. Han, “Discovery of Spatial Association Rules in Geographic Information Databases”, SSD’95
- ❑ Z. Li, B. Ding, J. Han, R. Kays, “Swarm: Mining Relaxed Temporal Moving Object Clusters”, VLDB’10
- ❑ Z. Li, B. Ding, J. Han, Roland Kays, Peter Nye, “Mining Periodic Behaviors for Moving Objects”, KDD’10
- ❑ C. Zhang, J. Han, L. Shou, J. Lu, T. La Porta, “Splitter: Mining Fine-Grained Sequential Patterns in Semantic Trajectories”, VLDB’14
- ❑ Y. Zheng and X. Zhou, Computing with Spatial Trajectories, Springer, 2011