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Congratulations!

Start Week 3

You have completed Week 2.

(/learn/roboticsmotionplanning/home/week/3)

## **Configuration Space**



CJ Taylor

Welcome to Week 2! In this module, we begin by introducing the concept of configuration space which is a

✓ More

## Configuration Space Applications



2.1: Introduction toConfiguration Space 4 min

(/learn/robotics-motionplanning/lecture/0auld/2-1-introduction-toconfiguration-space)



2.2: RR arm 2 min

(/learn/robotics-motion-

planning/lecture/mNhWs/2-2-rr-arm)



2.3: Piano Mover's Problem 3 min

(/learn/robotics-motionplanning/lecture/Yh5fc/2-3-piano-moversproblem)



Setting Up your MATLAB Environment

(/learn/robotics-motionplanning/supplement/E7Hk2/setting-up-yourmatlab-environment)

Path Planning in Configuration Space



2.4: Visibility Graph 3 min

(/learn/robotics-motionplanning/lecture/e1iaQ/2-4-visibility-graph)



2.5: Trapezoidal

Decomposition 1 min

(/learn/robotics-motionplanning/lecture/KQQGu/2-5-trapezoidaldecomposition)



2.6: Collision Detection and



Freespace Sampling Methods 5 min

(/learn/robotics-motionplanning/lecture/v8M8j/2-6-collision-detectionand-freespace-sampling-methods)



**Quiz:** Configuration Space 4 questions

(/learn/robotics-motionplanning/exam/dYQsq/configuration-space)



Assignment: Configuration
Space 3h 00m

(/learn/robotics-motionplanning/programming/BBYLi/configurationspace)