

## Case Study 4: Collaborative Filtering

### Graph-Parallel Problems

### Synchronous v. Asynchronous Computation

Machine Learning/Statistics for Big Data  
CSE599C1/STAT592, University of Washington

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## Needless to Say, We Need Machine Learning for Big Data



6 Billion  
Flickr Photos



28 Million  
Wikipedia Pages



1 Billion  
Facebook Users



72 Hours a Minute  
YouTube

The New York Times  
**Sunday Review**  
WORLD U.S. N.Y./REGION BUSINESS TEC

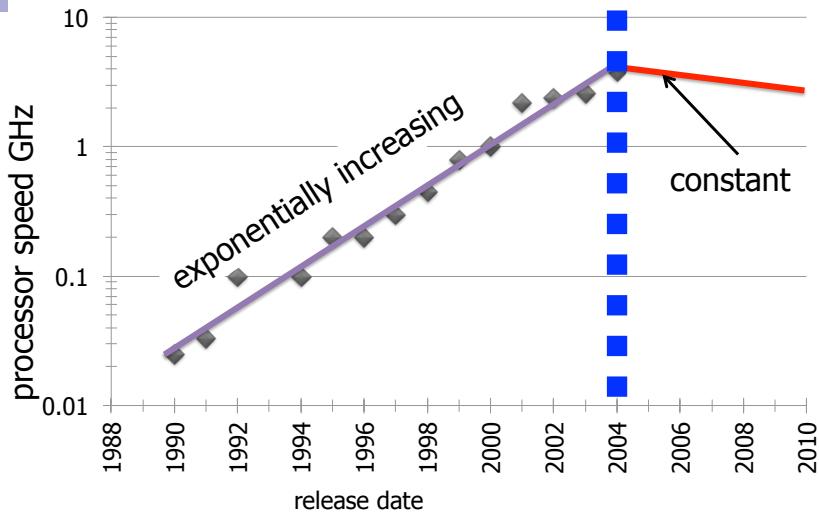
NEWS ANALYSIS  
**The Age of Big Data**  
By STEVE LOHR  
Published: February 11, 2012

“... data a new class of economic asset, like currency or gold.”

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## CPUs Stopped Getting Faster...



## ML in the Context of Parallel Architectures



- But scalable ML in these systems is hard, especially in terms of:

1. Programmability
2. Data distribution
3. Failures

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## Move Towards Higher-Level Abstraction

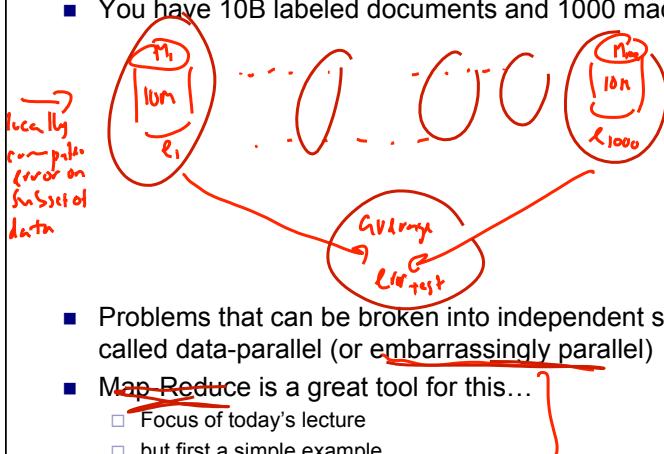
- Distributed computing challenges are hard and annoying!
  1. Programmability ↑
  2. Data distribution
  3. Failures
- High-level abstractions try to simplify distributed programming by hiding challenges:
  - Provide different levels of robustness to failures, optimizing data movement and communication, protect against race conditions...
  - Generally, you are still on your own WRT designing parallel algorithms
- Some common parallel abstractions:
  - Lower-level:
    - Pthreads: abstraction for distributed threads on single machine
    - MPI: abstraction for distributed communication in a cluster of computers
  - Higher-level:
    - Map-Reduce (Hadoop: open-source version): mostly data-parallel problems ✓
    - GraphLab: for graph-structured distributed problems ✓

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## Simplest Type of Parallelism: Data Parallel Problems

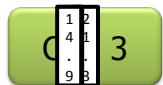
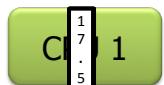
- You have already learned a classifier
  - What's the test error?  $\text{err} = \frac{w^T}{N_{\text{test}}} \sum_i |y^{(i)} - \text{sign}(w^T x^{(i)})|$
- You have 10B labeled documents and 1000 machines



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## Data Parallelism (MapReduce)



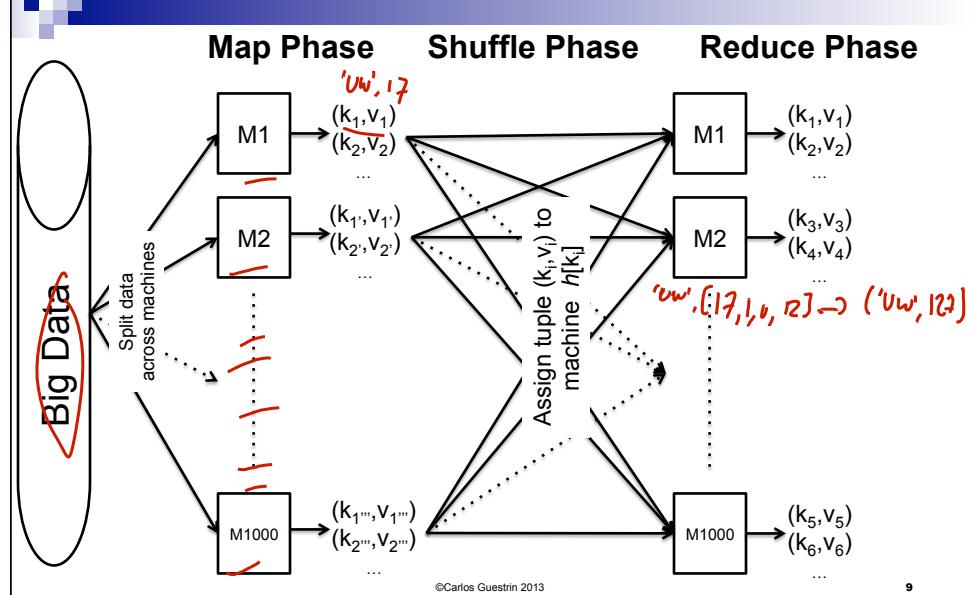
Solve a huge number of **independent** subproblems,  
e.g., extract features in images

## Map-Reduce Abstraction

- Map: *Transforms a data element*
    - Data-parallel over elements, e.g., documents
    - Generate (key,value) pairs
      - “value” can be any data type
  - Reduce: *Take all values associated with a key and aggregate*
    - Aggregate values for each key *and aggregate*
    - Must be commutative-associate operation
    - Data-parallel over keys
    - Generate (key,value) pairs
  - Map-Reduce has long history in functional programming
    - But popularized by Google, and subsequently by open-source Hadoop implementation from Yahoo!
- word count  
map (document)  
for word in doc  
emit (word, 1)

reduce (word, count: list(int))  
c = 0  
for i in count  
c += count[i]  
emit (word, c)
- ('Uw', 17)  
in this example: ('Uw', 1) —  
                          ('Mary', 1) —  
                          ('Uw', 1) —  
                          ('Mary', 1) —
- map reduce ('Uw', [1, 17, 0, 0, 12])  
emit ('Uw', 30)
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## Map-Reduce – Execution Overview



## Issues with Map-Reduce Abstraction

- Often all data gets moved around cluster
  - Very bad for iterative settings
- Definition of Map & Reduce functions can be unintuitive in many apps
  - Graphs are challenging
- Computation is synchronous

## SGD for Matrix Factorization in Map-Reduce?

$$\epsilon_t = L_u^{(t)} \cdot R_v^{(t)} - r_{uv}$$

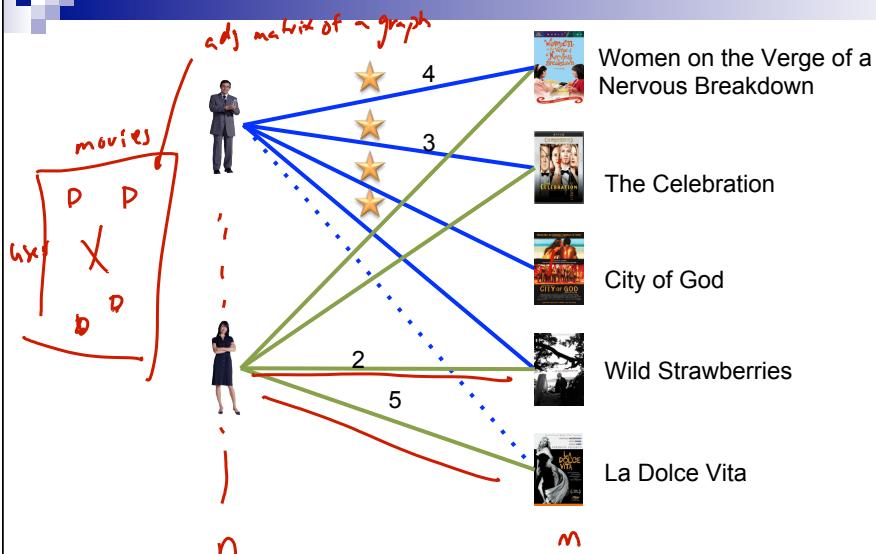
$$\begin{bmatrix} L_u^{(t+1)} \\ R_v^{(t+1)} \end{bmatrix} \leftarrow \begin{bmatrix} (1 - \eta_t \lambda_u) L_u^{(t)} - \eta_t \epsilon_t R_v^{(t)} \\ (1 - \eta_t \lambda_v) R_v^{(t)} - \eta_t \epsilon_t L_u^{(t)} \end{bmatrix}$$

- Map and Reduce functions???
- Map-Reduce:
  - Data-parallel over all mappers
  - Data-parallel over reducers with same key
- Here, one update at a time!

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## Matrix Factorization as a Graph



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# Flashback to 1998

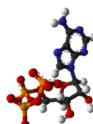


First Google advantage:  
a **Graph Algorithm & a System to Support it!**

## Social Media



## Science



## Advertising



## Web



- **Graphs** encode the **relationships** between:

## People

### Facts

## Products

### Interests

## Ideas

- **Big: 100 billions of vertices and edges** and rich metadata

- Facebook (10/2012): 1B users, 144B friendships
- Twitter (2011): 15B follower edges

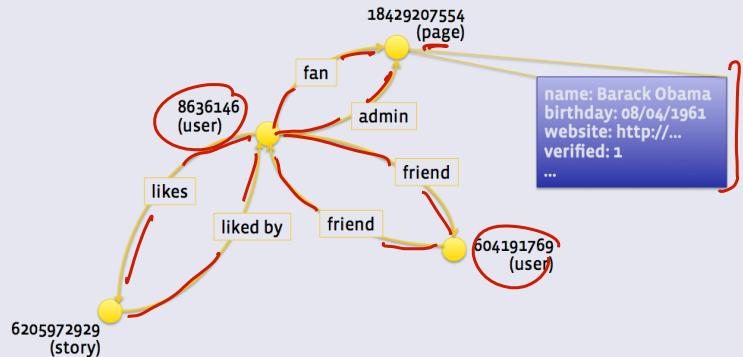
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# Facebook Graph

## Data model

### Objects & Associations



Slide from Facebook Engineering presentation 15

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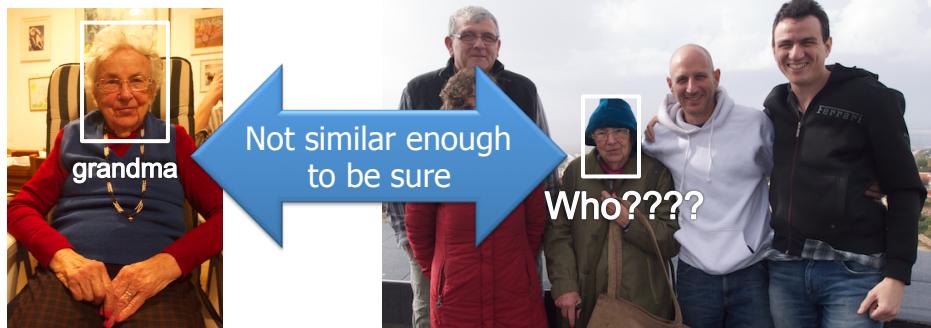
# Label a Face and Propagate



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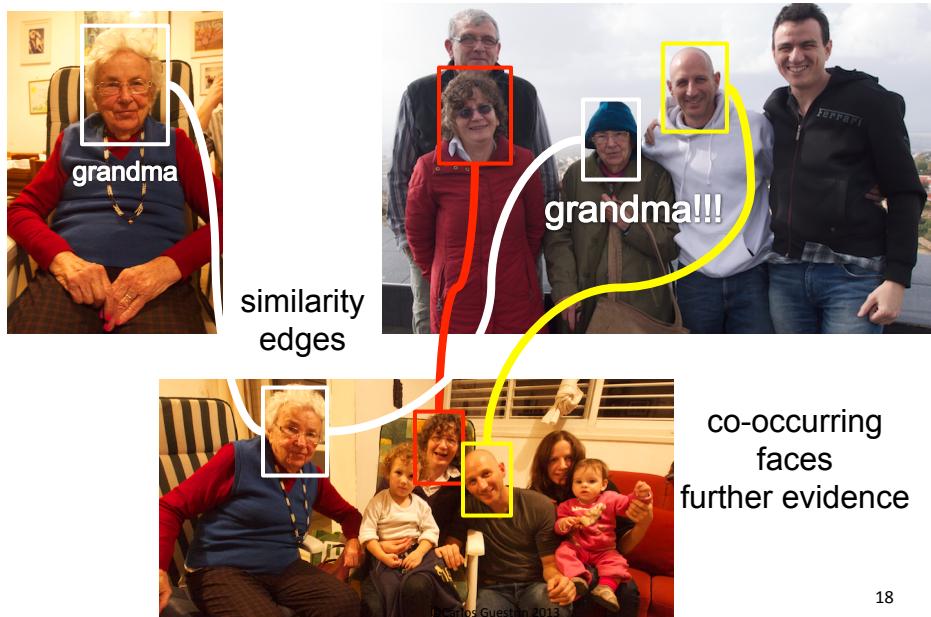
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## Pairwise similarity not enough...



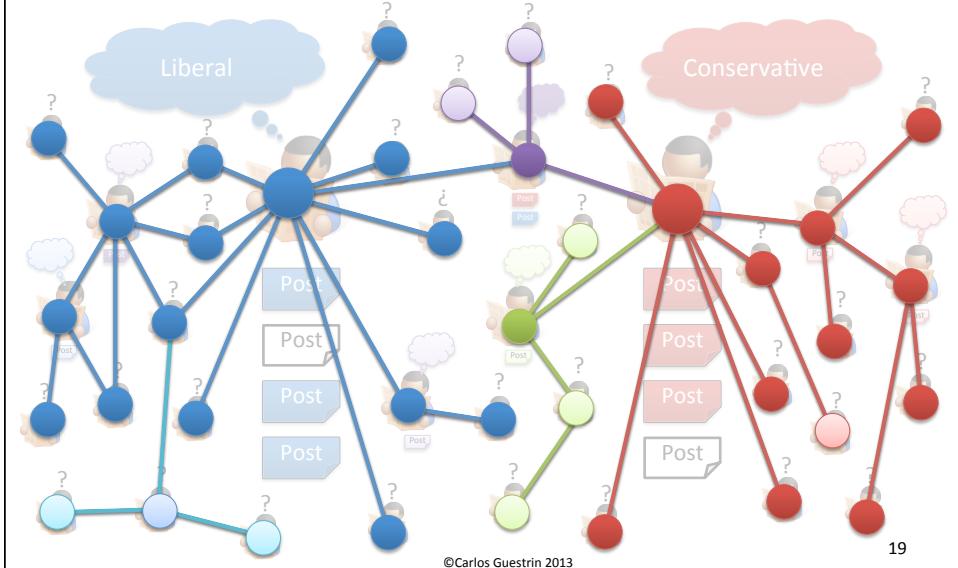
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## Propagate Similarities & Co-occurrences for Accurate Predictions

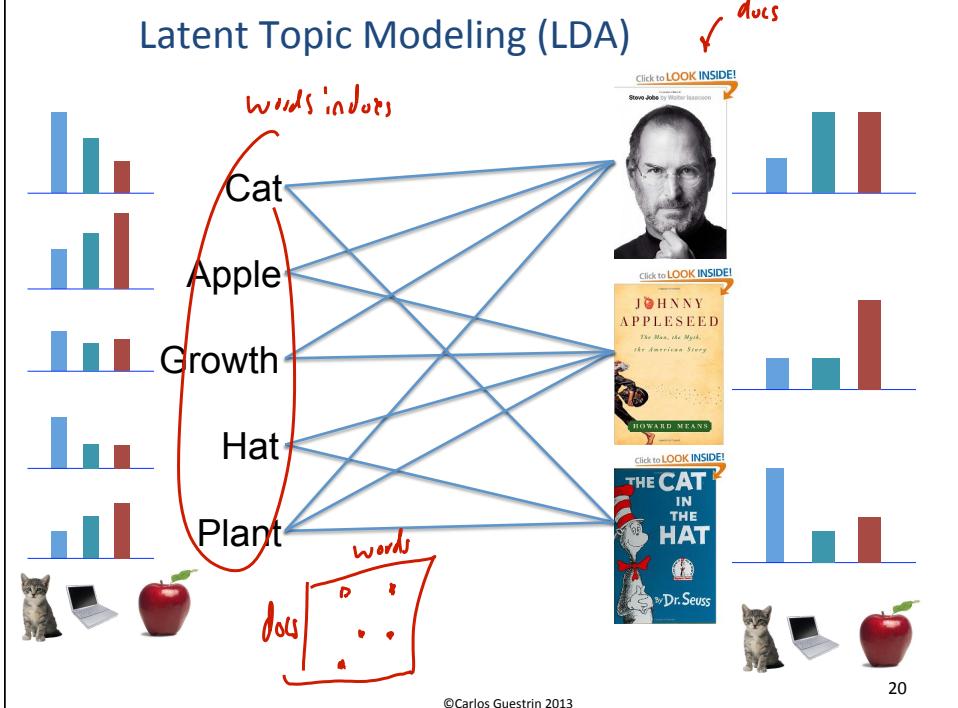


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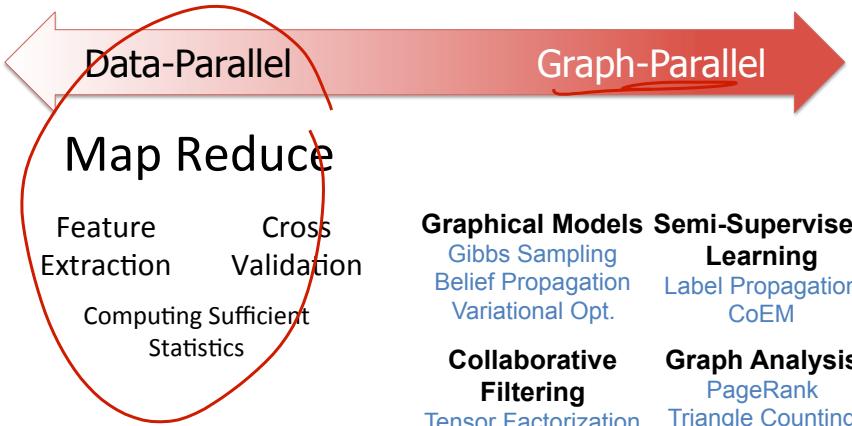
## Example: Estimate Political Bias



## Latent Topic Modeling (LDA)



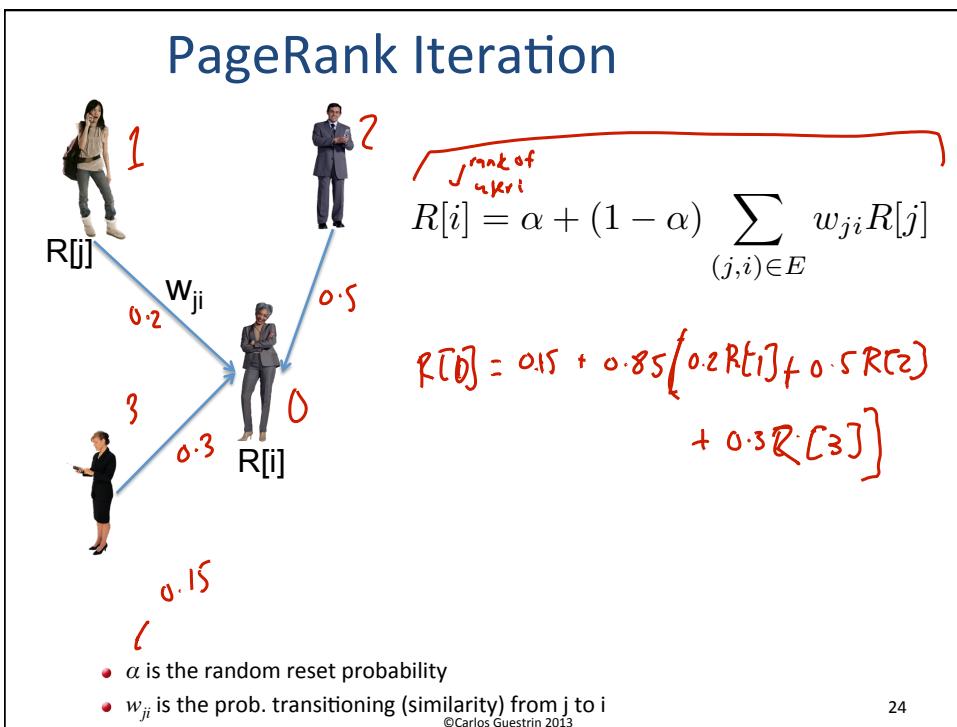
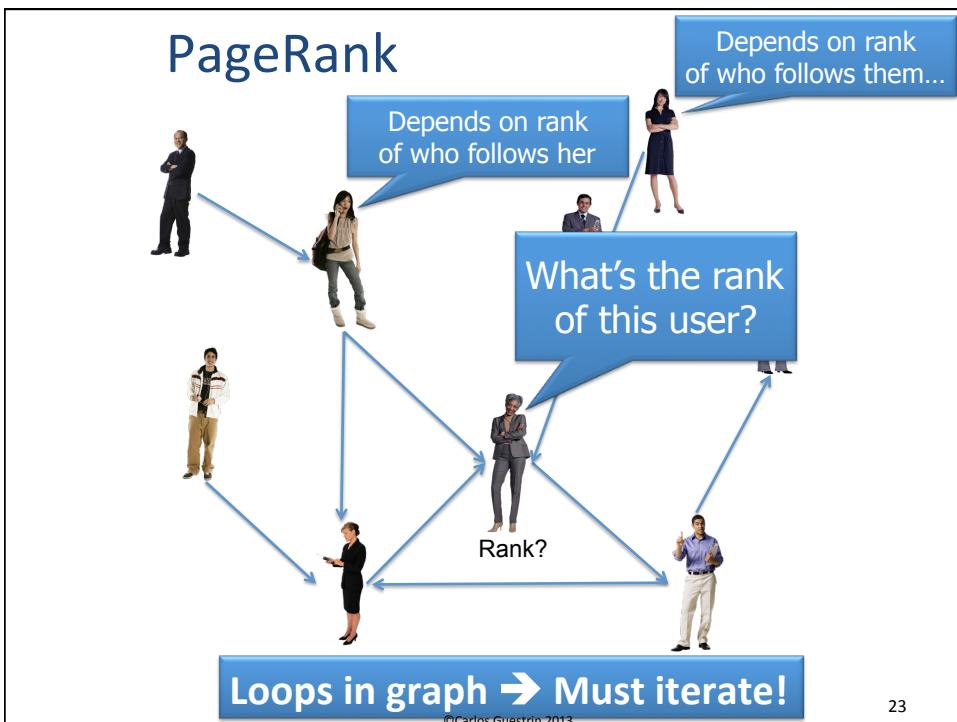
## ML Tasks Beyond Data-Parallelism



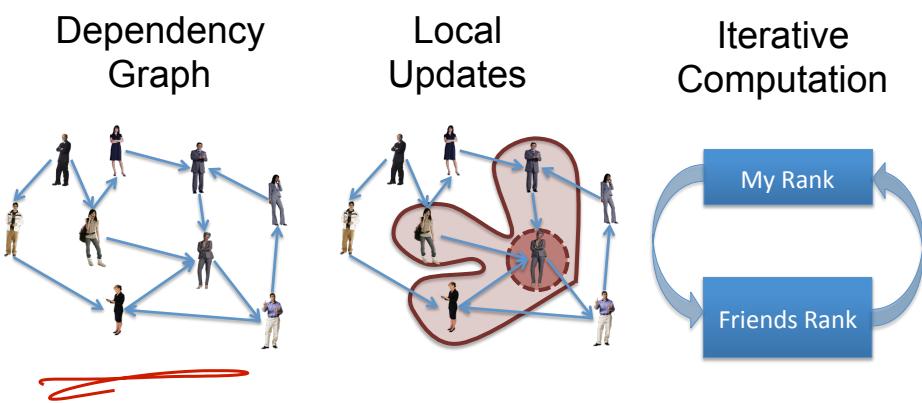
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## Example of a Graph-Parallel Algorithm



## Properties of Graph Parallel Algorithms



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## Addressing Graph-Parallel ML



### Map Reduce

Feature Extraction  
Cross Validation  
Computing Sufficient Statistics

### Graph-Parallel Abstraction

**Graphical Models**      **Semi-Supervised Learning**  
Gibbs Sampling      Label Propagation  
Belief Propagation      CoEM  
Variational Opt.  
  
**Collaborative Filtering**      **Data-Mining**  
Tensor Factorization      PageRank  
Triangle Counting

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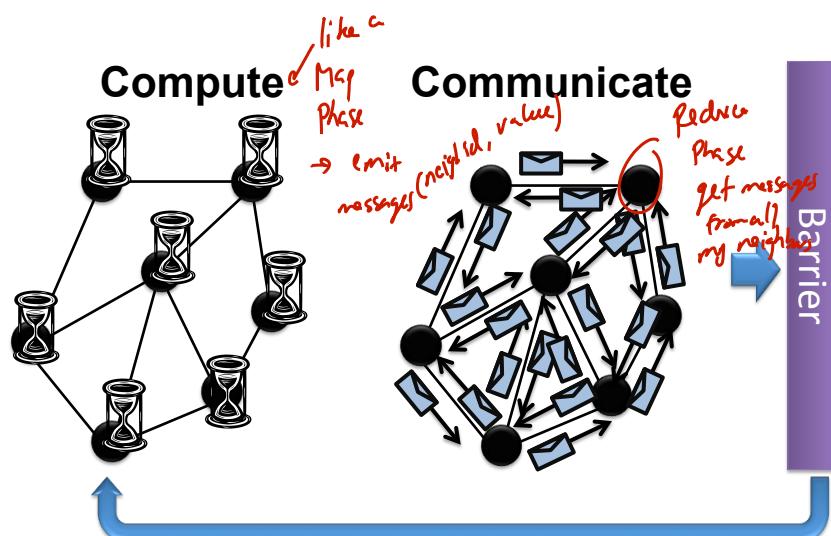
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Graph Computation:

*Synchronous*  
v.  
*Asynchronous*

Bulk Synchronous Parallel Model:  
Pregel (Giraph)

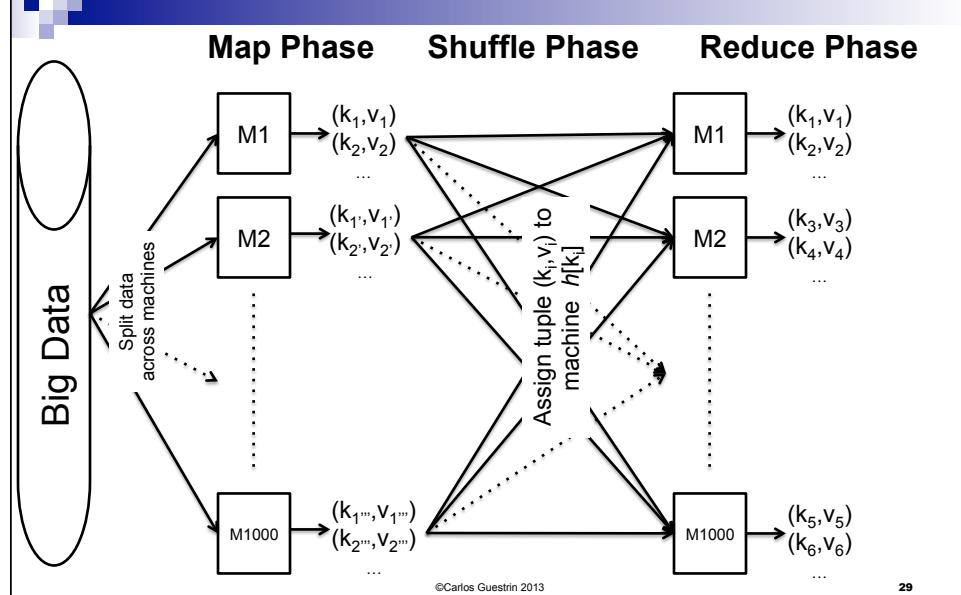
[Valiant '90]



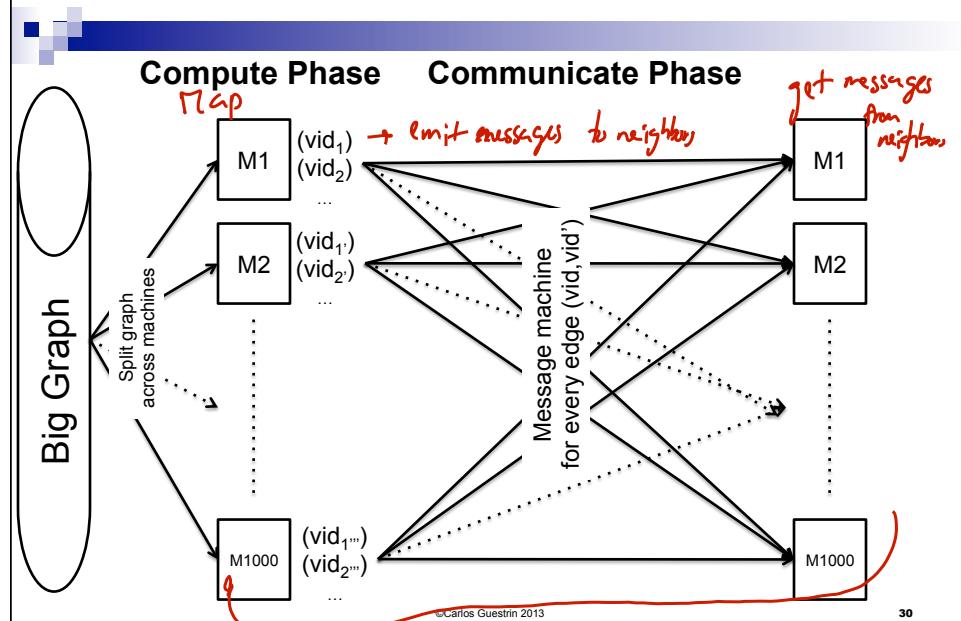
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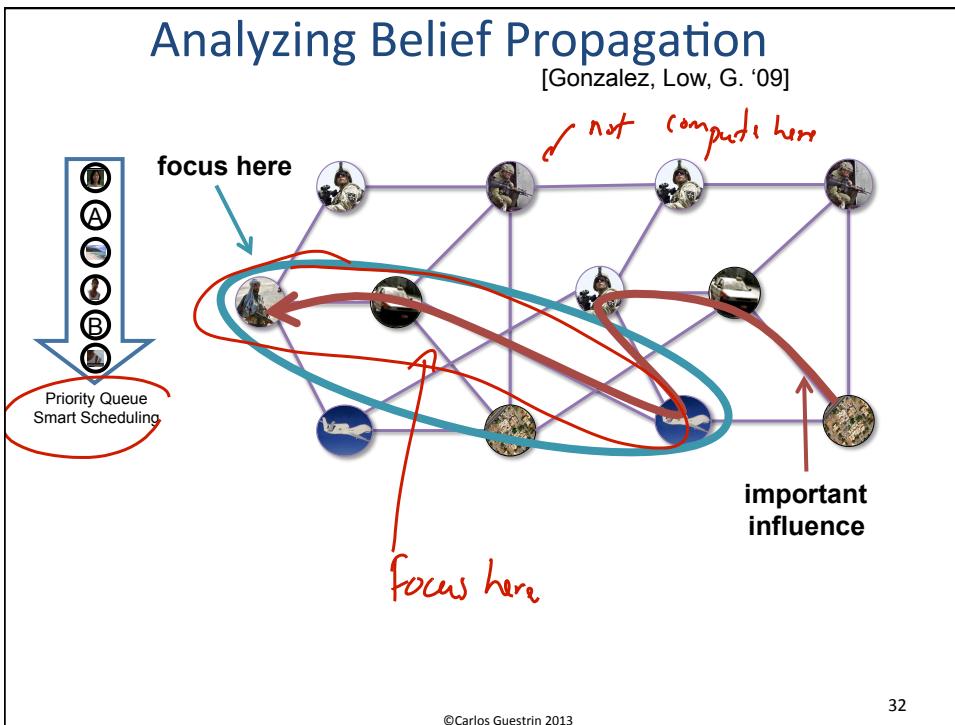
## Map-Reduce – Execution Overview



## BSP – Execution Overview

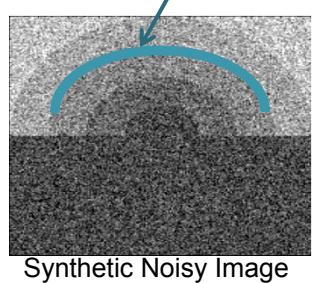


*Bulk synchronous  
parallel model  
**provably inefficient**  
for some ML tasks*



## Asynchronous Belief Propagation

**Challenge = Boundaries**



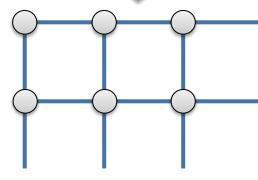
Synthetic Noisy Image



Many Updates

Few Updates

Cumulative Vertex Updates



Graphical Model

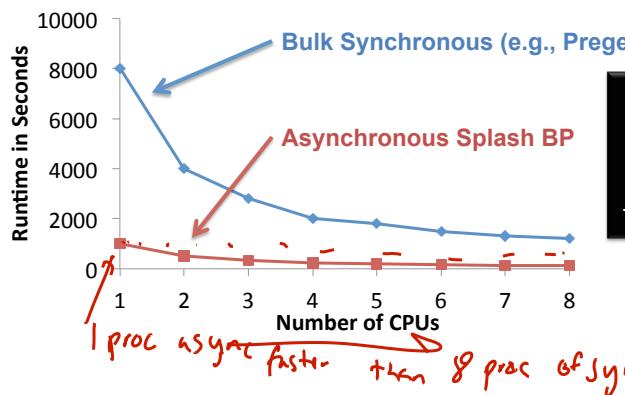
Algorithm identifies and focuses  
on hidden sequential structure

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BSP ML Problem: *BP on real data*

Synchronous Algorithms can be Inefficient



Theorem:

Bulk Synchronous BP  
O(#vertices) slower  
than Asynchronous BP

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# Synchronous v. Asynchronous

- Bulk synchronous processing:
  - Computation in phases
    - All vertices participate in a phase
      - Though OK to say no-op
    - All messages are sent
  - Simpler to build, like Map-Reduce
    - No worries about race conditions, barrier guarantees data consistency
    - Simpler to make fault-tolerant, save data on barrier
  - Slower convergence for many ML problems
  - In matrix-land, called Jacobi Iteration
  - Implemented by Google Pregel 2010
- Asynchronous processing:
  - Vertices see latest information from neighbors
    - Most closely related to sequential execution
  - Harder to build:
    - Race conditions can happen all the time
      - Must protect against this issue
    - More complex fault tolerance
    - When are you done?
    - Must implement scheduler over vertices
  - Faster convergence for many ML problems
  - In matrix-land, called Gauss-Seidel Iteration
  - Implemented by GraphLab 2010, 2012

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