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JC

Jacky C.K. Chow · a day ago (/learn/robotics-learning/discussions/weeks/2/threads/kbhJ2xvQEea_TAo4ODIo0w)
 (</learn/robotics-learning/profiles/cccb93c3a545f8f3542bcf9d9d03c09e>)
 Hi Lea,

You're absolutely right, thanks for clarifying that. I'm not doing a totally separate prediction at 0.33s at every time step but with my position and velocity computed at every time step. Now I get 3/15 instead of 2/15, so I'm getting closer to what I want. My filter has a lower error than the reference and case6 datasets, just not sure why I'm not passing

0 Upvote



Lea Kantor · a day ago (/learn/robotics-learning/discussions/weeks/2/threads/kbhJ2xvQEea_TAo4ODIo0w)
 (</learn/robotics-learning/profiles/501850438a2ea1bebd2991bf0214fa33>)
 Hi Jacky,

I have the same problem. Maybe this is the result of what McGill had warned us about. Good luck and please let me know if you reach 15/15.

Help Center

