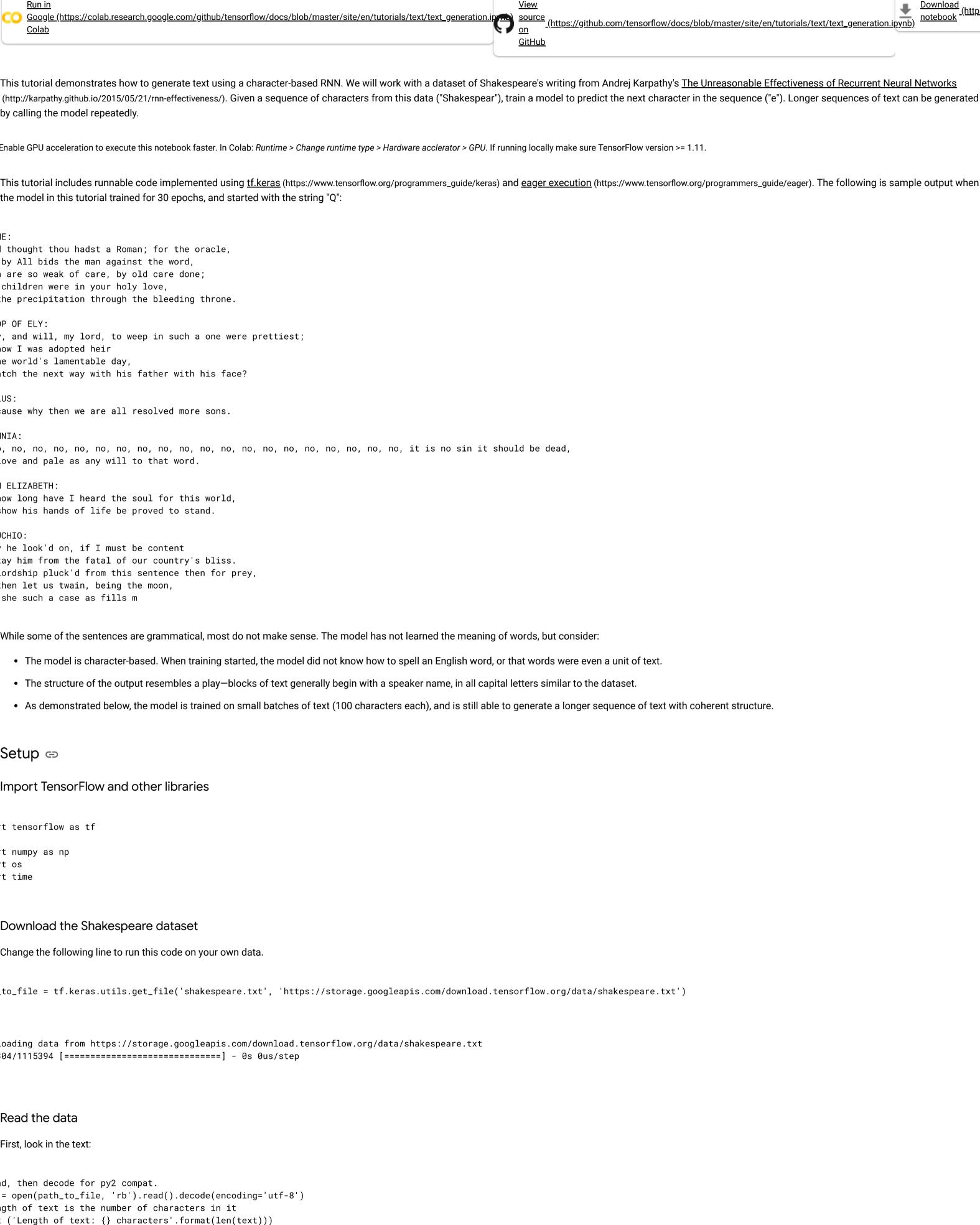
Text generation with an RNN

Run in

h of text: 1115394 characters



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```
Citizen:

de we proceed any further, hear me speak.

de speak.

Citizen:

de all resolved rather to die than to famish?

Aved. resolved.

Citizen:

de you know Caius Marcius is chief enemy to the people.

de unique characters in the file

de sorted(set(text))

de ('{} unique characters'.format(len(vocab)))
```

Process the text

ique characters

e a look at the first 250 characters in text

(text[:250])

Vectorize the text

eating a mapping from unique characters to indices

idx = {u:i for i, u in enumerate(vocab)}

Before training, we need to map strings to a numerical representation. Create two lookup tables: one mapping characters to numbers, and another for numbers to characters.

```
: 12,

www how the first 13 characters from the text are mapped to integers

converged ('{} ---- characters mapped to int ---- > {}'.format(repr(text[:13]), text_as_int[:13]))

converged to the text are mapped to int ---- > [18 47 56 57 58 1 15 47 58 47 64 43 52]
```

The prediction task

: 10, : 11,

Given a character, or a sequence of characters, what is the most probable next character? This is the task we're training the model to perform. The input to the model will be a sequence of characters, and we train the model to predict the output—the following character at each time step.

Since RNNs maintain an internal state that depends on the previously seen elements, given all the characters computed until this moment, what is the next character?

Create training examples and targets

Next divide the text into example sequences. Each input sequence will contain <code>seq_length</code> characters from the text.

For each input sequence, the corresponding targets contain the same length of text, except shifted one character to the right.

So break the text into chunks of seq_length+1. For example, say seq_length is 4 and our text is "Hello". The input sequence would be "Hell", and the target sequence "ello".

To do this first use the tf.data.Dataset.from_tensor_slices (https://www.tensorflow.org/api_docs/python/tf/data/Dataset#from_tensor_slices) function to convert the text vector into a stream of character indices.

```
e maximum length sentence we want for a single input in characters
length = 100
eles_per_epoch = len(text)//(seq_length+1)
eate training examples / targets
ldataset = tf.data.Dataset.from_tensor_slices(text_as_int)
```

```
The batch method lets us easily convert these individual characters to sequences of the desired size.
ences = char_dataset.batch(seq_length+1, drop_remainder=True)
tem in sequences.take(5):
.nt(repr(''.join(idx2char[item.numpy()])))
t Citizen:\nBefore we proceed any further, hear me speak.\n\nAll:\nSpeak, speak.\n\nFirst Citizen:\nYou
all resolved rather to die than to famish?\n\n (n) resolved.\n\n Citizen:\n First, you k'
Caius Marcius is chief enemy to the people.\n\nAll:\nWe know't, we know't.\n\nFirst Citizen:\nLet us ki"
im, and we'll have corn at our own price.\nIs't a verdict?\n\nAll:\nNo more talking on't; let it be d"
away, away!\n\nSecond Citizen:\nOne word, good citizens.\n\nFirst Citizen:\nWe are accounted poor citi'
For each sequence, duplicate and shift it to form the input and target text by using the map method to apply a simple function to each batch:
split_input_target(chunk):
ut_text = chunk[:-1]
get_text = chunk[1:]
urn input_text, target_text
set = sequences.map(split_input_target)
Print the first examples input and target values:
.nput_example, target_example in dataset.take(1):
.nt ('Input data: ', repr(''.join(idx2char[input_example.numpy()])))
.nt ('Target data:', repr(''.join(idx2char[target_example.numpy()])))
data: 'First Citizen:\nBefore we proceed any further, hear me speak.\n\nAll:\nSpeak, speak.\n\nFirst Citizen:\nYou'
t data: 'irst Citizen:\nBefore we proceed any further, hear me speak.\n\nAll:\nSpeak, speak.\n\nFirst Citizen:\nYou '
Each index of these vectors are processed as one time step. For the input at time step 0, the model receives the index for "F" and trys to predict the index for "i" as the next character. At the next timestep, it does the same
thing but the RNN considers the previous step context in addition to the current input character.
., (input_idx, target_idx) in enumerate(zip(input_example[:5], target_example[:5])):
.nt("Step {:4d}".format(i))
.nt(" input: {} ({:s})".format(input_idx, repr(idx2char[input_idx])))
.nt(" expected output: {} ({:s})".format(target_idx, repr(idx2char[target_idx])))
  0
ut: 18 ('F')
ected output: 47 ('i')
out: 47 ('i')
ected output: 56 ('r')
out: 56 ('r')
ected output: 57 ('s')
ut: 57 ('s')
ected output: 58 ('t')
ut: 58 ('t')
Create training batches
We used tf.data (https://www.tensorflow.org/api_docs/python/tf/data) to split the text into manageable sequences. But before feeding this data into the model, we need to shuffle the data and pack it into batches.
ch size
I_SIZE = 64
fer size to shuffle the dataset
data is designed to work with possibly infinite sequences,
it doesn't attempt to shuffle the entire sequence in memory. Instead,
maintains a buffer in which it shuffles elements).
R_SIZE = 10000
et = dataset.shuffle(BUFFER_SIZE).batch(BATCH_SIZE, drop_remainder=True)
hDataset shapes: ((64, 100), (64, 100)), types: (tf.int64, tf.int64)>
```

.in char_dataset.take(5): .nt(idx2char[i.numpy()])

Build The Model

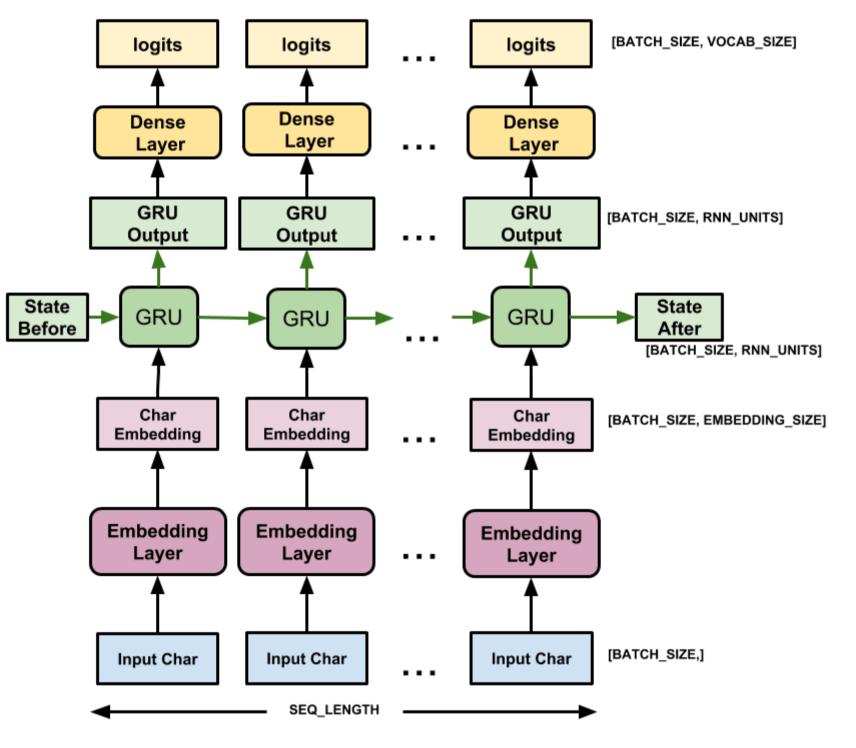
Use tf.keras.Sequential (https://www.tensorflow.org/api_docs/python/tf/keras/Sequential) to define the model. For this simple example three layers are used to define our model:

- <u>tf.keras.layers.Embedding</u> (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Embedding): The input layer. A trainable lookup table that will map the numbers of each character to a vector with embedding_dim dimensions;
- <u>tf.keras.layers.GRU</u> (https://www.tensorflow.org/api_docs/python/tf/keras/layers/GRU): A type of RNN with size units=rnn_units (You can also use a LSTM layer here.)
- <u>tf.keras.layers.Dense</u> (https://www.tensorflow.org/api_docs/python/tf/keras/layers/Dense): The output layer, with vocab_size outputs.

```
_size = len(vocab)
embedding dimension
|ding_dim| = 256
ber of RNN units
nits = 1024
uild_model(vocab_size, embedding_dim, rnn_units, batch_size):
lel = tf.keras.Sequential([
f.keras.layers.Embedding(vocab_size, embedding_dim,
                         batch_input_shape=[batch_size, None]),
f.keras.layers.GRU(rnn_units,
                   return_sequences=True,
                   stateful=True,
                   recurrent_initializer='glorot_uniform'),
f.keras.layers.Dense(vocab_size)
urn model
= build_model(
ocab_size = len(vocab),
mbedding_dim=embedding_dim,
nn_units=rnn_units,
atch_size=BATCH_SIZE)
```

gth of the vocabulary in chars

For each character the model looks up the embedding, runs the GRU one timestep with the embedding as input, and applies the dense layer to generate logits predicting the log-likelihood of the next character:



Please note that we choose to Keras sequential model here since all the layers in the model only have single input and produce single output. In case you want to retrieve and reuse the states from stateful RNN layer, you might want to build your model with Keras functional API or model subclassing. Please check Keras RNN guide (https://www.tensorflow.org/guide/keras/rnn#rnn_state_reuse) for more details.

Try the model

Now run the model to see that it behaves as expected.

First check the shape of the output:

```
.nput_example_batch, target_example_batch in dataset.take(1):
.mple_batch_predictions = model(input_example_batch)
.nt(example_batch_predictions.shape, "# (batch_size, sequence_length, vocab_size)")

100, 65) # (batch_size, sequence_length, vocab_size)
```

In the above example the sequence length of the input is 100 but the model can be run on inputs of any length:

.summary()

```
      (type)
      Output Shape
      Param #

      ding (Embedding)
      (64, None, 256)
      16640

      GRU)
      (64, None, 1024)
      3938304

      (Dense)
      (64, None, 65)
      66625
```

rainable params: 0 -----

To get actual predictions from the model we need to sample from the output distribution, to get actual character indices. This distribution is defined by the logits over the character vocabulary.

t is important to s*ample* from this distribution as taking the *argmax* of the distribution can easily get the model stuck in a loop.

Try it for the first example in the batch:

params: 4,021,569 able params: 4,021,569

```
.ed_indices = tf.random.categorical(example_batch_predictions[0], num_samples=1)
.ed_indices = tf.squeeze(sampled_indices,axis=-1).numpy()
```

This gives us, at each timestep, a prediction of the next character index:

.ed_indices

```
      7([11, 10, 6, 52, 46, 56, 43, 19, 34, 36, 7, 55, 6, 34, 43, 4, 37, 10, 10, 10, 20, 24, 48, 45, 22, 57, 46, 27, 45, 10, 20, 17, 30, 45, 21, 19, 7, 5, 59, 64, 45, 18, 17, 15, 20, 3, 16, 39, 32, 27, 26, 10, 34, 21, 46, 45, 22, 58, 50, 32, 18, 26, 9, 23, 49, 42, 56, 7, 28, 25, 42, 37, 8, 13, 21, 59, 17, 56, 30, 42, 0, 11, 62, 22, 35, 40, 56, 42, 34, 12, 57, 24, 53, 26, 38, 24, 56, 33, 24, 8])
```

Decode these to see the text predicted by this untrained model:

```
("Input: \n", repr("".join(idx2char[input_example_batch[0]])))
(()
(()
(()Next Char Predictions: \n", repr("".join(idx2char[sampled_indices ])))

::
too late, I fear me, noble lord, \nHath clouded all thy happy days on earth:\nO, call back yesterday, '
Char Predictions:
nhreGVX-q, Ve&Y:::HLjgJshOg:HERgIG-'uzgFECH$DaTON:VIhgJtlTFN3Kkdr-PMdY.AIuErRd\n; xJWbrdV?sLoNZLrUL."
```

Train the model

.oss(labels, logits):

At this point the problem can be treated as a standard classification problem. Given the previous RNN state, and the input this time step, predict the class of the next character.

Attach an optimizer, and a loss function

The standard tf.keras.losses.sparse_categorical_crossentropy (https://www.tensorflow.org/api_docs/python/tf/keras/losses/sparse_categorical_crossentropy) loss function works in this case because it is applied across the last dimension of the predictions.

Because our model returns logits, we need to set the from_logits flag.

```
curn tf.keras.losses.sparse_categorical_crossentropy(labels, logits, from_logits=True)

cle_batch_loss = loss(target_example_batch, example_batch_predictions)

c("Prediction shape: ", example_batch_predictions.shape, " # (batch_size, sequence_length, vocab_size)")

c("scalar_loss: ", example_batch_loss.numpy().mean())

cction shape: (64, 100, 65) # (batch_size, sequence_length, vocab_size)

cction shape: (4.176197
```

Configure the training procedure using the tf.keras.Model.compile (https://www.tensorflow.org/api_docs/python/tf/keras/Model#compile) method. We'll use tf.keras.optimizers.Adam (https://www.tensorflow.org/api_docs/python/tf/keras/optimizers/Adam) with default arguments and the loss function.

```
..compile(optimizer='adam', loss=loss)
```

Configure checkpoints

Use a tf.keras.callbacks.ModelCheckpoint (https://www.tensorflow.org/api_docs/python/tf/keras/callbacks/ModelCheckpoint) to ensure that checkpoints are saved during training:

```
rectory where the checkpoints will be saved 
point_dir = './training_checkpoints'

pe of the checkpoint files

point_prefix = os.path.join(checkpoint_dir, "ckpt_{epoch}")
```

point_callback=tf.keras.callbacks.ModelCheckpoint(

ilepath=checkpoint_prefix, ave_weights_only=True)

Execute the training

To keep training time reasonable, use 10 epochs to train the model. In Colab, set the runtime to GPU for faster training.

IS=10

1/10

```
ry = model.fit(dataset, epochs=EPOCHS, callbacks=[checkpoint_callback])
```

Generate text

Restore the latest checkpoint

To keep this prediction step simple, use a batch size of 1.

Because of the way the RNN state is passed from timestep to timestep, the model only accepts a fixed batch size once built.

To run the model with a different batch_size, we need to rebuild the model and restore the weights from the checkpoint.

```
ain.latest_checkpoint(checkpoint_dir)
```

```
aining_checkpoints/ckpt_10'
```

```
= build_model(vocab_size, embedding_dim, rnn_units, batch_size=1)
```

```
..load_weights(tf.train.latest_checkpoint(checkpoint_dir))
```

..build(tf.TensorShape([1, None]))

.summary()

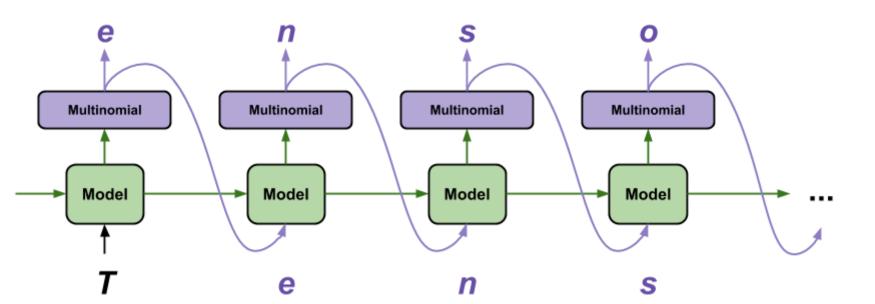
: "sequential_1"

(type)	Output Shape	 Param #
ding_1 (Embedding)	(1, None, 256)	16640
(GRU)	(1, None, 1024)	3938304
_1 (Dense)	(1, None, 65)	66625
params: 4,021,569 able params: 4,021,569 rainable params: 0		

The prediction loop

The following code block generates the text:

- It Starts by choosing a start string, initializing the RNN state and setting the number of characters to generate.
- Get the prediction distribution of the next character using the start string and the RNN state.
- Then, use a categorical distribution to calculate the index of the predicted character. Use this predicted character as our next input to the model.
- The RNN state returned by the model is fed back into the model so that it now has more context, instead than only one character. After predicting the next character, the modified RNN states are again fed back into the model, which is how it learns as it gets more context from the previously predicted characters.



Looking at the generated text, you'll see the model knows when to capitalize, make paragraphs and imitates a Shakespeare-like writing vocabulary. With the small number of training epochs, it has not yet learned to form coherent sentences.

```
_generate = 1000
converting our start string to numbers (vectorizing)
ut_eval = [char2idx[s] for s in start_string]
out_eval = tf.expand_dims(input_eval, 0)
impty string to store our results
t_generated = []
ow temperatures results in more predictable text.
ligher temperatures results in more surprising text.
experiment to find the best setting.
perature = 1.0
lere batch size == 1
lel.reset_states()
i in range(num_generate):
redictions = model(input_eval)
remove the batch dimension
redictions = tf.squeeze(predictions, 0)
using a categorical distribution to predict the character returned by the model
redictions = predictions / temperature
redicted_id = tf.random.categorical(predictions, num_samples=1)[-1,0].numpy()
We pass the predicted character as the next input to the model
along with the previous hidden state
.nput_eval = tf.expand_dims([predicted_id], 0)
ext_generated.append(idx2char[predicted_id])
urn (start_string + ''.join(text_generated))
(generate_text(model, start_string=u"ROMEO: "))
: Jesuehousady, having
is, let's we move, and be
d that love I passing him!
BOLINGBROKE:
r little I have in arms.
ive love; stand fortent, he thanks?
did stop me none; and prayed was' not to gue applain
ill it once. perour will Nature understand'st.
```

The easiest thing you can do to improve the results it to train it for longer (try EP0CHS=30).

You can also experiment with a different start string, or try adding another RNN layer to improve the model's accuracy, or adjusting the temperature parameter to generate more or less random predictions.

Advanced: Customized Training

HENRY VI:

|enerate_text(model, start_string):

lumber of characters to generate

valuation step (generating text using the learned model)

The above training procedure is simple, but does not give you much control.

So now that you've seen how to run the model manually let's unpack the training loop, and implement it ourselves. This gives a starting point if, for example, to implement curriculum learning to help stabilize the model's open-loop output.

We will use tf.GradientTape (https://www.tensorflow.org/api_docs/python/tf/GradientTape) to track the gradients. You can learn more about this approach by reading the eager execution guide (https://www.tensorflow.org/guide/eager)

The procedure works as follows:

- First, reset the RNN state. We do this by calling the tf.keras.Model.reset_states (https://www.tensorflow.org/api_docs/python/tf/keras/Model#reset_states) method.
- Next, iterate over the dataset (batch by batch) and calculate the *predictions* associated with each.
- Open a tf.GradientTape (https://www.tensorflow.org/api_docs/python/tf/GradientTape), and calculate the predictions and loss in that context.
- Calculate the gradients of the loss with respect to the model variables using the tf.GradientTape.grads method.
- Finally, take a step downwards by using the optimizer's tf.train.Optimizer.apply_gradients method.

```
. = build_model(
rocab_size = len(vocab),
embedding_dim=embedding_dim,
```

```
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer.iter
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer.beta_1
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer.beta_2
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer.decay
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer.learning_rate
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-0.embeddings
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-2.kernel
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-2.bias
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-1.cell.kernel
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-1.cell.recurrent_kernel
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'm' for (root).layer_with_weights-1.cell.bias
NG:tensorflow:Unresolved object in checkpoint: (root).optimizer's state 'v' for (root).layer_with_weights-0.embeddings
nizer = tf.keras.optimizers.Adam()
unction
rain_step(inp, target):
h tf.GradientTape() as tape:
redictions = model(inp)
.oss = tf.reduce_mean(
  tf.keras.losses.sparse_categorical_crossentropy(
      target, predictions, from_logits=True))
ids = tape.gradient(loss, model.trainable_variables)
imizer.apply_gradients(zip(grads, model.trainable_variables))
urn loss
ining step
IS = 10
poch in range(EPOCHS):
rt = time.time()
esetting the hidden state at the start of every epoch
lel.reset_states()
(batch_n, (inp, target)) in enumerate(dataset):
.oss = train_step(inp, target)
.f batch_n % 100 == 0:
template = 'Epoch {} Batch {} Loss {}'
print(template.format(epoch+1, batch_n, loss))
eaving (checkpoint) the model every 5 epochs
(epoch + 1) \% 5 == 0:
iodel.save_weights(checkpoint_prefix.format(epoch=epoch))
.nt ('Epoch {} Loss {:.4f}'.format(epoch+1, loss))
.nt ('Time taken for 1 epoch {} sec\n'.format(time.time() - start))
..save_weights(checkpoint_prefix.format(epoch=epoch))
1 Batch 0 Loss 4.174383640289307
1 Batch 100 Loss 2.3455469608306885
1 Loss 2.1354
taken for 1 epoch 6.386500358581543 sec
2 Batch 0 Loss 2.143766403198242
2 Batch 100 Loss 1.9540011882781982
2 Loss 1.7758
taken for 1 epoch 5.211035490036011 sec
3 Batch 0 Loss 1.7939282655715942
3 Batch 100 Loss 1.697733759880066
```

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taken for 1 epoch 5.233696222305298 sec

3 Loss 1.6339

nn_units=rnn_units, atch_size=BATCH_SIZE)

NG:tensorflow:Unresolved object in checkpoint: (root).optimizer