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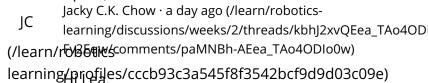
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You're absolutely right, thanks for clarifying that. I no doing a totally separate prediction at 0.33s at every t equations but with my position and velocity compute inputs. Now I get 3/15 instead of 2/15, so I'm getting wants. My filter has a lower error than the reference and case6 datasets, just not sure why I'm not passing

🖒 0 Upvote



Lea Kantor · a day ago (/learn/robotics-learning/discussions/weeks/2/threads/kbhJ2xvQEea_TAo4OD

(/learn/rtv/gក្សាស្ត្រcomments/emwNiR-CEeaVDxK4na7kAw) learning/អ្នក្រឡូវ៉ូស្ត្រ/501850438a2ea1bebd2991bf0214fa33)

I have the same problem. Maybe this is the result of McGill had warned us about. Good luck and please le reach 15/15.

