

Probability and Statistics: To p, or not to p?

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2.5 Parameters

Probability distributions may differ from each other in a broader or narrower sense. In the broader sense, we have different **families** of distributions which may have quite different characteristics, for example:

- discrete distributions versus continuous distributions
- among discrete distributions: a finite versus an infinite number of possible values
- among continuous distributions: different sets of possible values (for example, all real numbers x, x > 0, or $x \in [0, 1]$); symmetric versus skewed distributions.

These 'distributions' are really families of distributions in this sense.

In the narrower sense, individual distributions within a family differ in having different values of the **parameters** of the distribution. The parameters determine the mean and variance of the distribution, values of probabilities from it etc.

In the statistical analysis of a random variable X we typically:

- select a family of distributions based on the basic characteristics of X
- use observed data to choose (estimate) values for the parameters of that distribution, and perform statistical inference on them.

Example

An opinion poll on a referendum, where each X_i is an answer to the question 'Will you vote 'Yes' or 'No' to joining/leaving¹ the European Union?' has answers recorded as $X_i = 0$ if 'No' and $X_i = 1$ if 'Yes'. In a poll of 950 people, 513 answered 'Yes'.

¹In light of Brexit, you can choose which you prefer!

How do we choose a distribution to represent X_i ?

- Here we need a family of discrete distributions with only two possible values (0 and 1). The Bernoulli distribution (discussed below), which has one parameter π (the probability that $X_i = 1$) is appropriate.
- Within the family of Bernoulli distributions, we use the one where the value of π is our best estimate based on the observed data. This is $\hat{\pi} = 513/950 = 0.54$ (where $\hat{\pi}$ denotes an estimate of the parameter π).

A Bernoulli trial is an experiment with only *two* possible outcomes. We will number these outcomes 1 and 0, and refer to them as 'success' and 'failure', respectively. Note these are notional successes and failures – the success does not necessarily have to be a 'good' outcome, nor a failure a 'bad' outcome!

Example

Examples of outcomes of Bernoulli trials are:

- agree / disagree
- pass a test / fail a test
- employed / unemployed
- owns a car / does not own a car
- business goes bankrupt / business continues trading.

The Bernoulli distribution is the distribution of the outcome of a single Bernoulli trial, named after Jacob Bernoulli (1654–1705). This is the distribution of a random variable X with the following probability function:²

$$P(X = x) = \begin{cases} \pi^x (1 - \pi)^{1-x} & \text{for } x = 0, 1\\ 0 & \text{otherwise.} \end{cases}$$

Therefore:

$$P(X=1) = \pi^1 (1-\pi)^{1-1} = \pi$$

and:

$$P(X = 0) = \pi^0 (1 - \pi)^{1-0} = 1 - \pi$$

and no other values are possible. We could express this family of Bernoulli distributions in tabular form as follows:

$$\begin{array}{c|c|c} X = x & 0 & 1 \\ \hline P(X = x) & 1 - \pi & \pi \end{array}$$

 $^{^{2}}$ A probability function is simply a function which returns the probability of a particular value of X.

where $0 \le \pi \le 1$ is the probability of 'success'. Note that just as a **sample space** represents all possible values of a random variable, a **parameter space** represents all possible values of a parameter. Clearly, as a probability, we must have that $0 \le \pi \le 1$.

Such a random variable X has a Bernoulli distribution with (probability) parameter π . This is often written as:

$$X \sim \text{Bernoulli}(\pi)$$
.

If $X \sim \text{Bernoulli}(\pi)$, then we can determine its expected value, i.e. its mean, as the usual probability-weighted average:

$$E(X) = 0 \times (1 - \pi) + 1 \times \pi = \pi.$$

Hence we can view π as the long-run average (proportion) of successes if we were to draw a large random sample from this distribution.

Different members of this family of distributions differ in terms of the value of π .

Example

Consider the toss of a fair coin, where X=1 denotes 'heads' and X=0 denotes 'tails'. As this is a fair coin, heads and tails are equally likely and hence $\pi=0.5$ leading to the specific Bernoulli distribution:

$$\begin{array}{c|c|c} X = x & 0 & 1 \\ \hline P(X = x) & 0.5 & 0.5 \end{array}$$

Hence:

$$E(X) = 0 \times 0.5 + 1 \times 0.5 = 0.5$$

such that if we tossed a fair coin a large number of times, we would expect the proportion of heads to be 0.5 (and in practice the long-run proportion of heads would be approximately 0.5)³.

³Get a fair coin, and test this!