

Computational Photography



Dr. Irfan Essa

Professor

School of Interactive Computing

Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.

Digital Images: Into the Frequency Domain

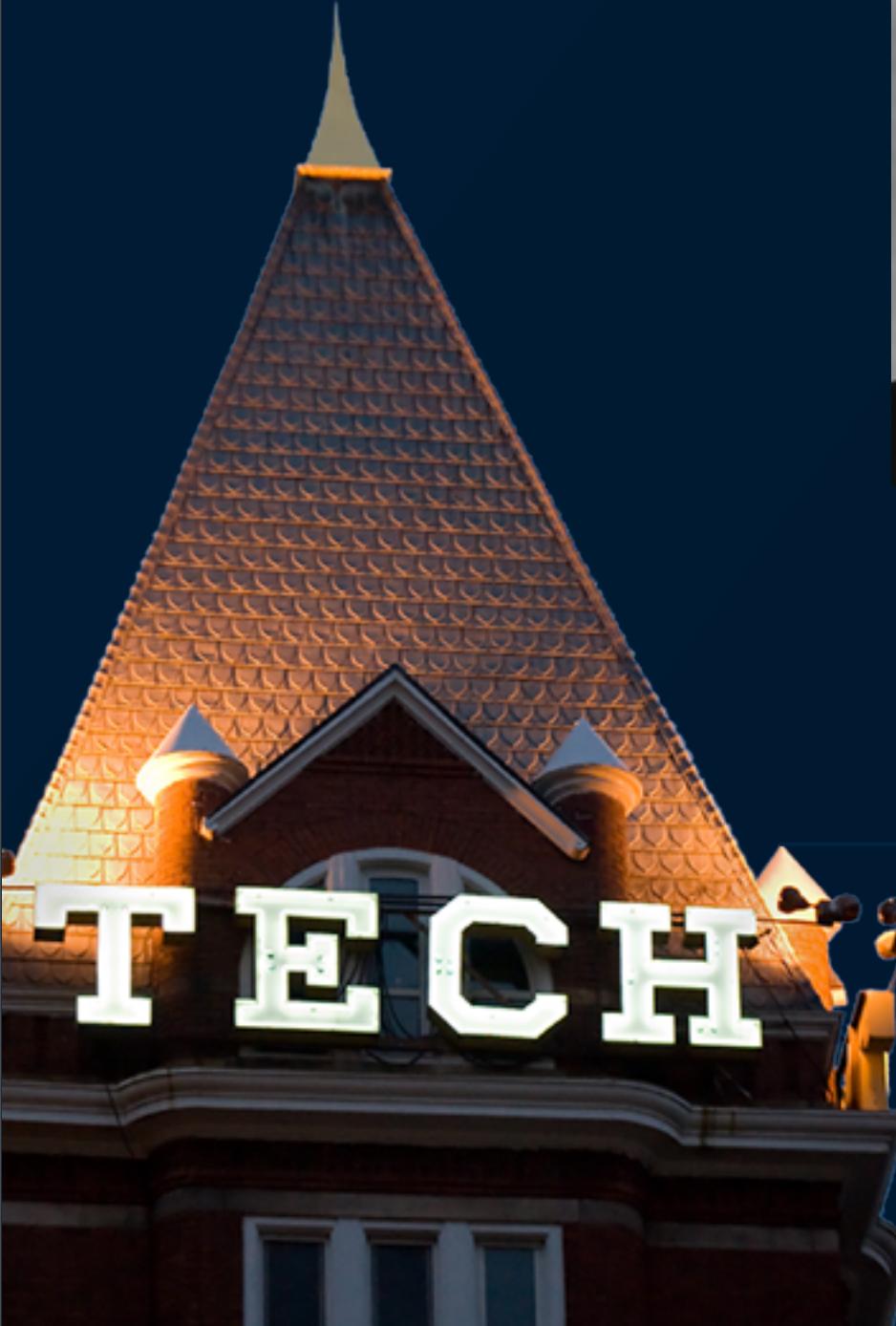


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Images are samples of light information stored in array of pixels.

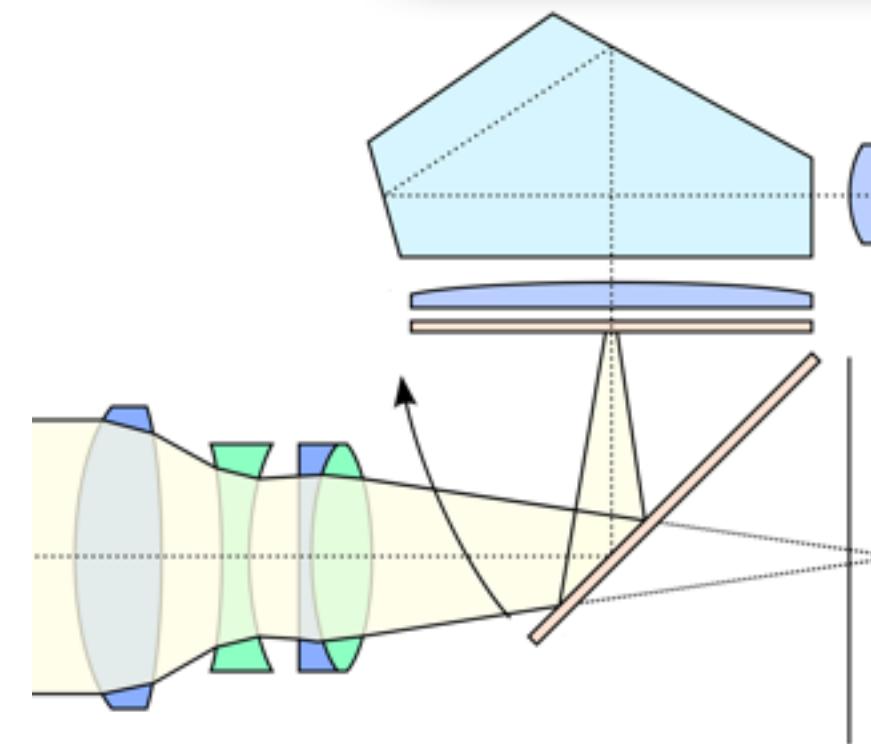


Lesson Objectives

- ★ Describe in your own words how sines and cosines can be used to reconstruct a signal.
- ★ Describe in your own words the Fourier Transform using terms like Frequency, Amplitude and Phase.
- ★ Explain in your own words the value of using Frequency Domains for a Signal.
- ★ Recall the three (3) properties of Convolution as it is associated with the Fourier Transform.

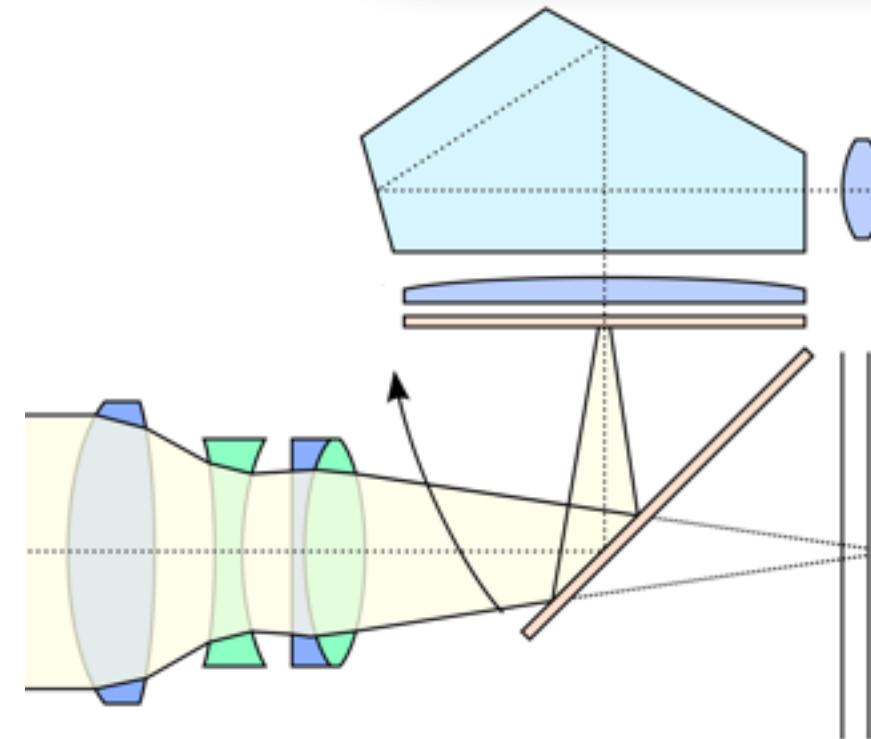


REVIEW: Images and Camera



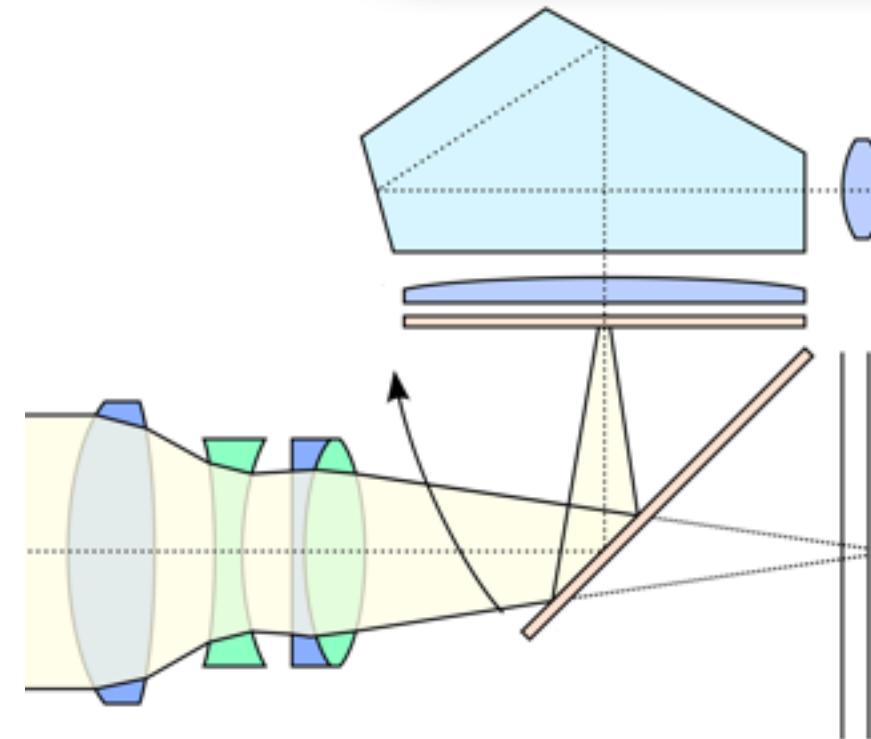
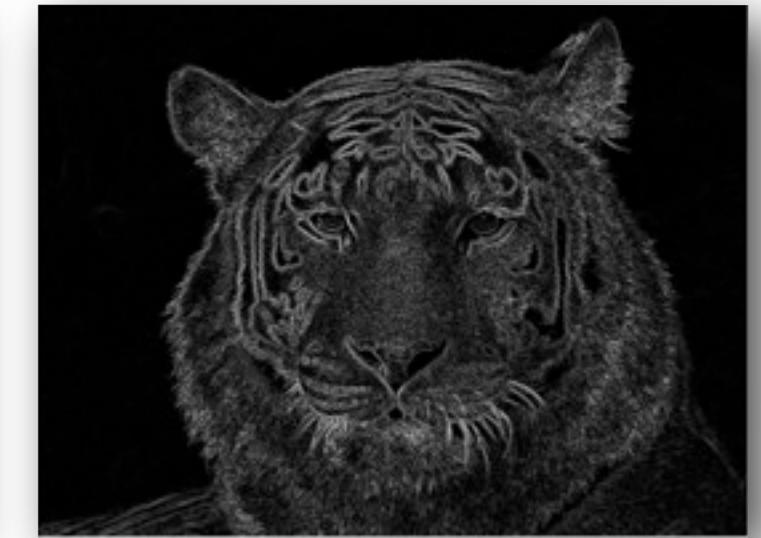
REVIEW: Images and Camera

- ★ Rays of Light go through
 - a Camera
 - Optics/Lens



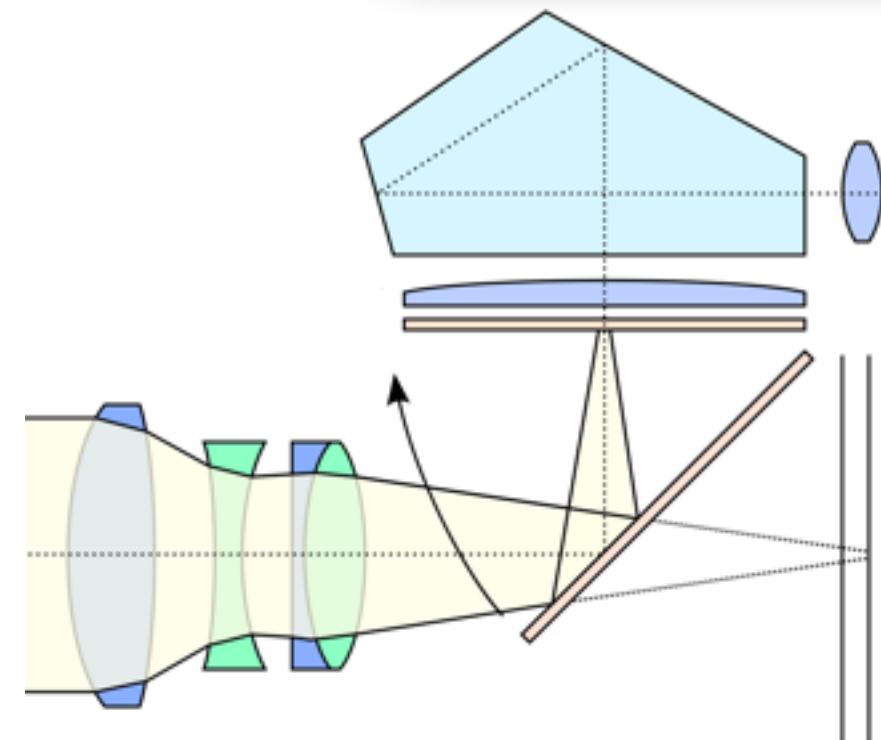
REVIEW: Images and Camera

- ★ Rays of Light go through
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- ★ Controlled by Aperture, Shutter, and Film Sensitivity



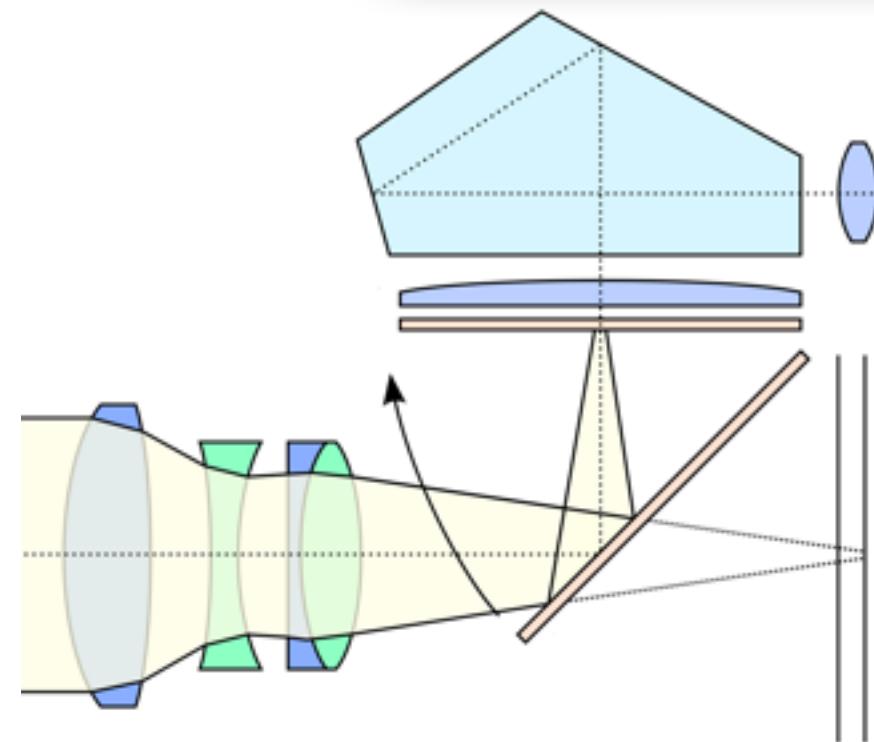
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- ★ Sensor to Convert Light to Digital Information



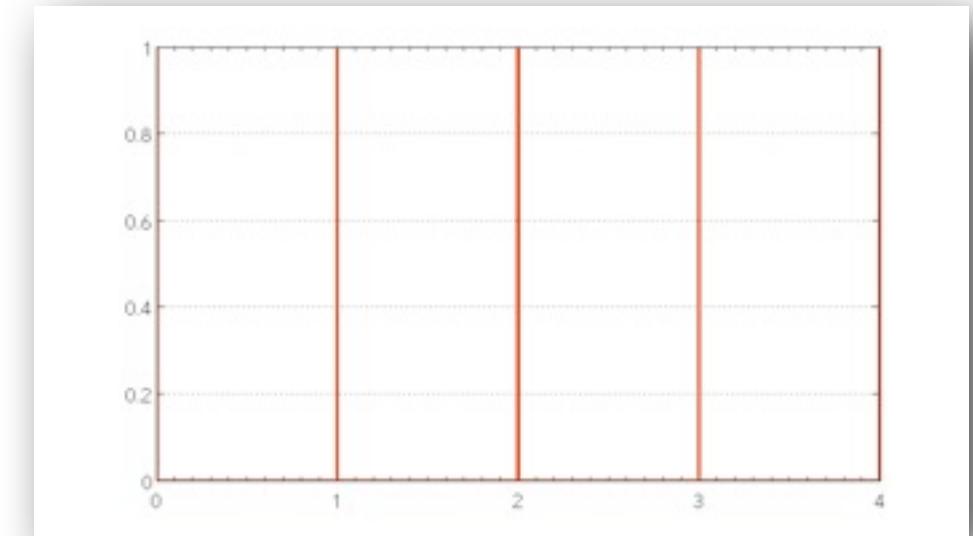
REVIEW: Images and Camera

- ★ Rays of Light go through
 - a Camera
 - Optics/Lens
- ★ Controlled by Aperture, Shutter, and Film Sensitivity
- ★ Sensor to Convert Light to Digital Information
- ★ Process the Image
 - Improve Quality
 - Find Relevant and Useful Information



Sum of Cosines

$f^T(t)$ Target Signal

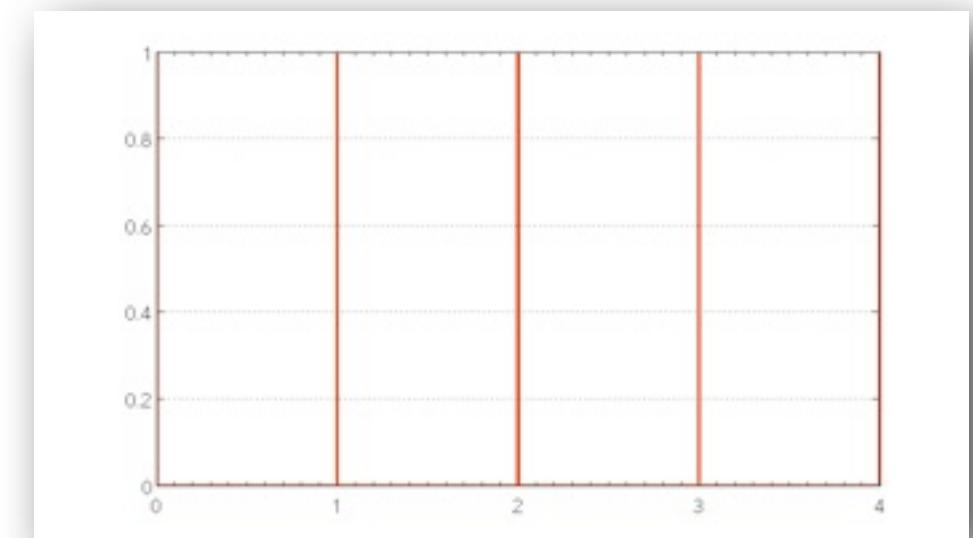


Repeating Impulse Function

Sum of Cosines

- ★ Using this as our basic building block
 - $f(t) = A \cos(n\omega t)$

$f^T(t)$ Target Signal

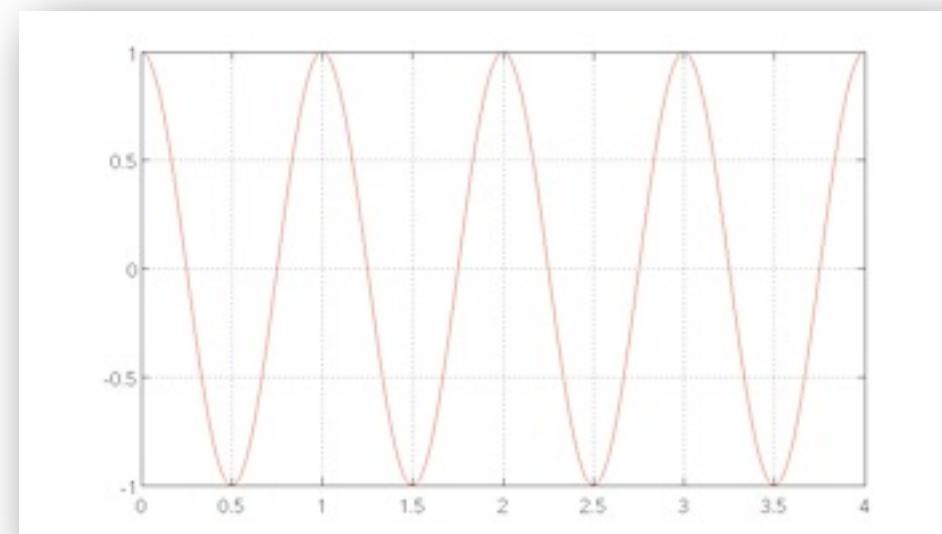


Repeating Impulse Function

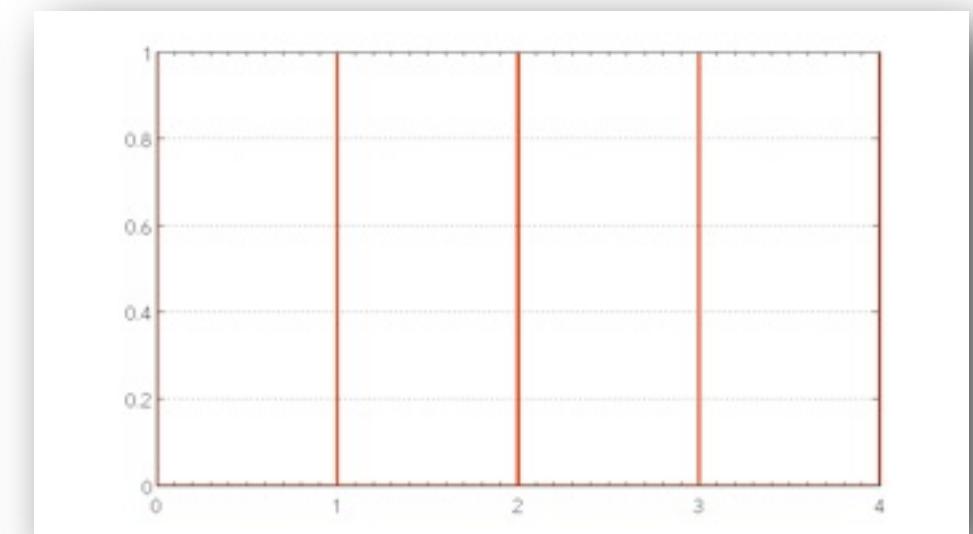
Sum of Cosines

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f_1



$f^T(t)$ Target Signal

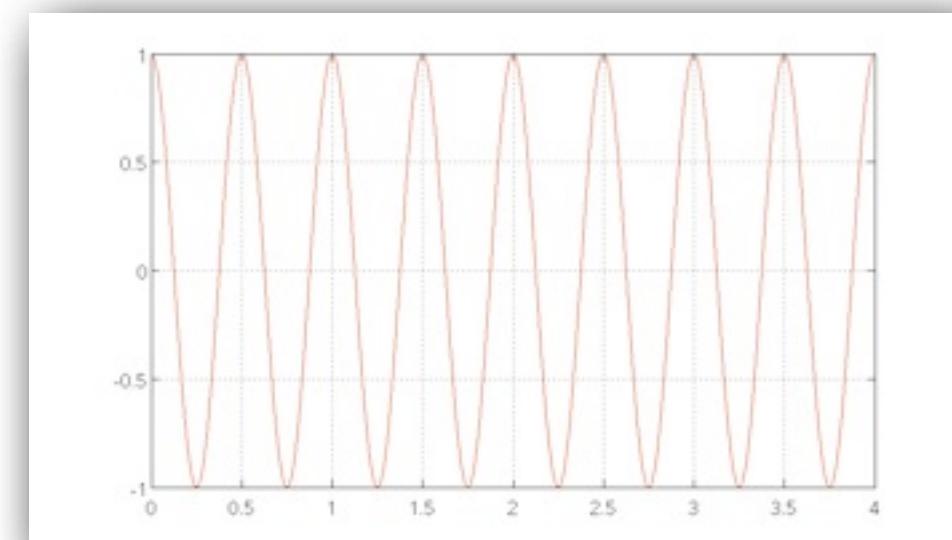


Repeating Impulse Function

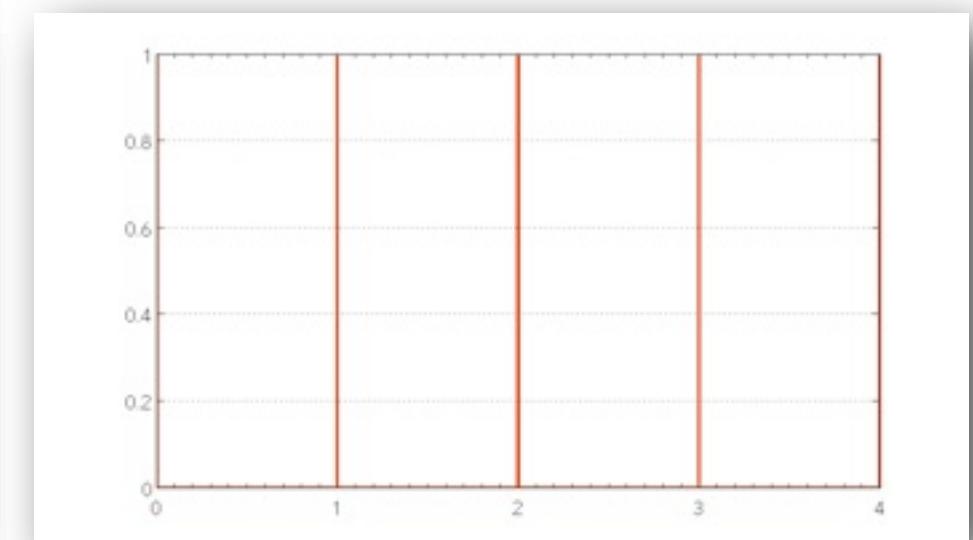
Sum of Cosines

- ★ Using this as our basic building block
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f_1 f_2



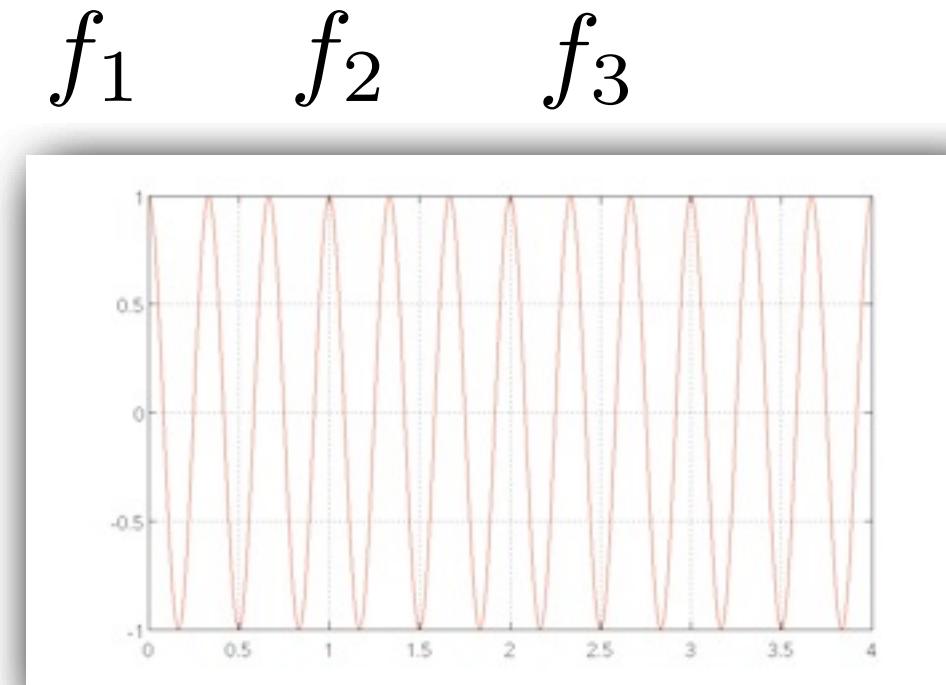
$f^T(t)$ Target Signal



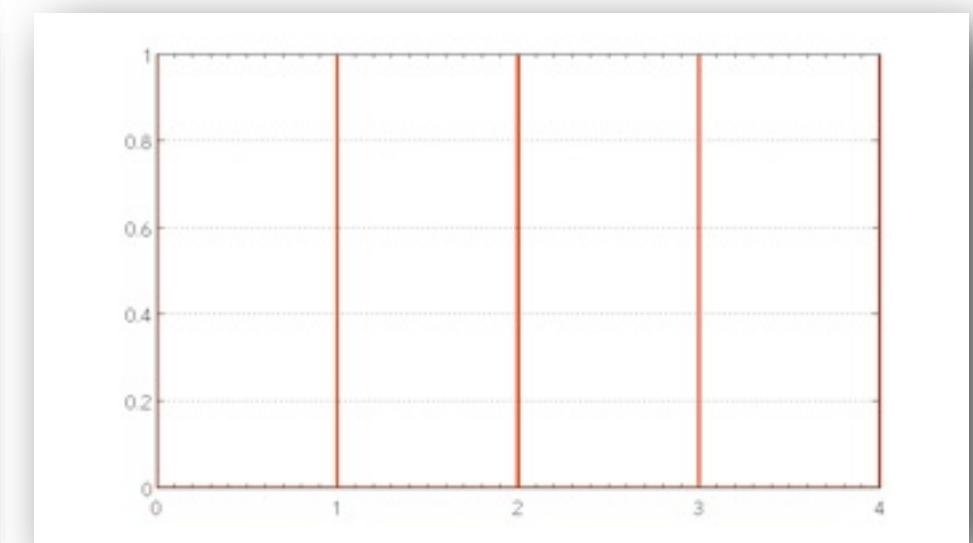
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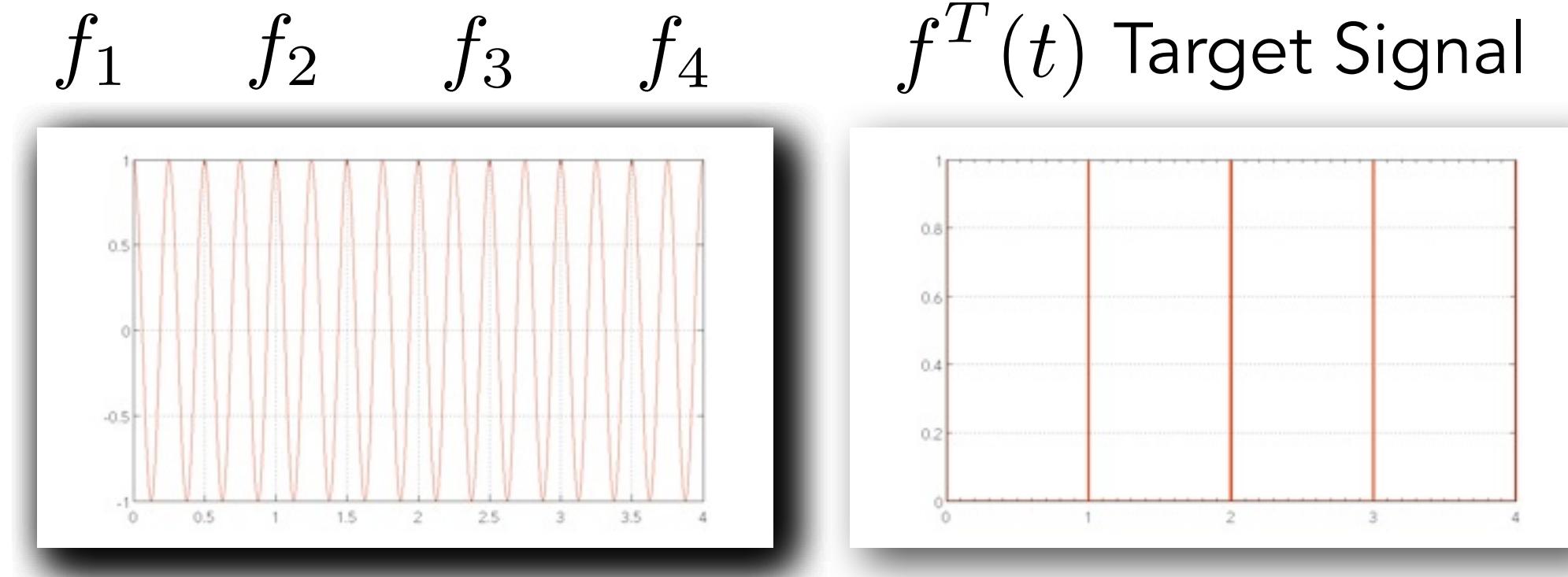
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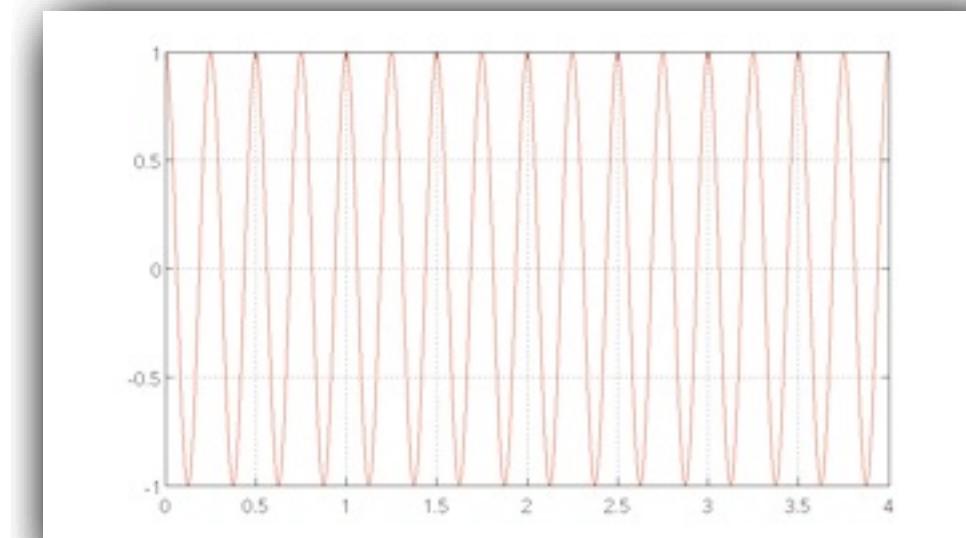


Repeating Impulse Function

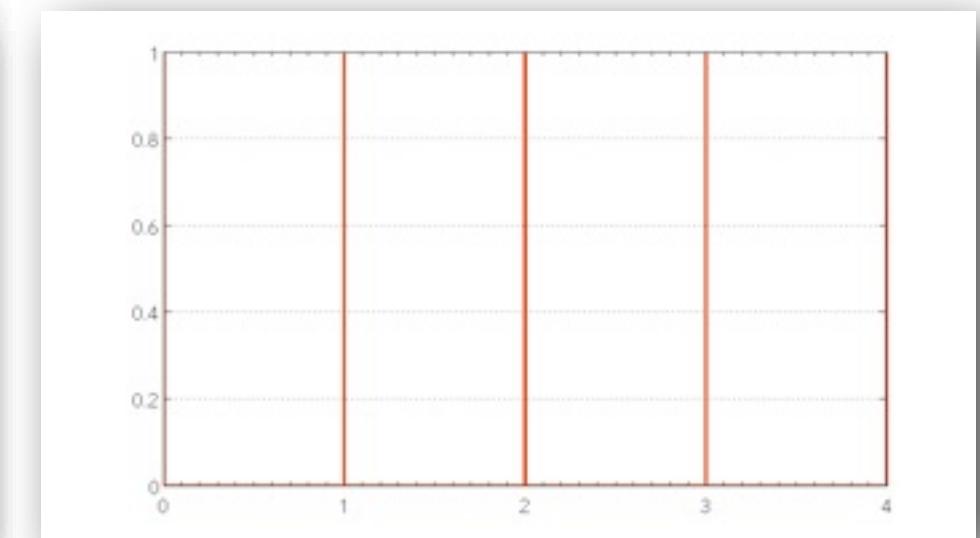
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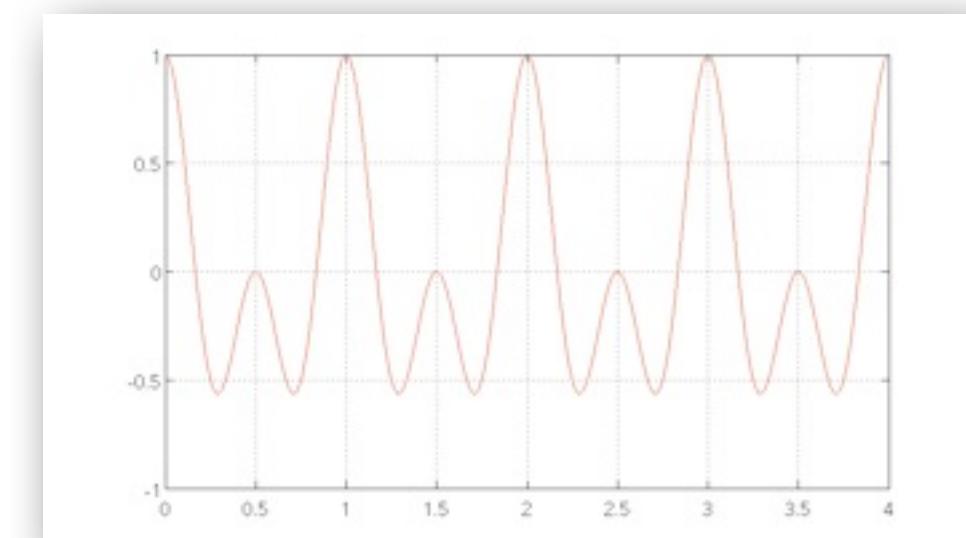
$$f_1 \quad f_2 \quad f_3 \quad f_4$$



$f^T(t)$ Target Signal



Repeating Impulse Function

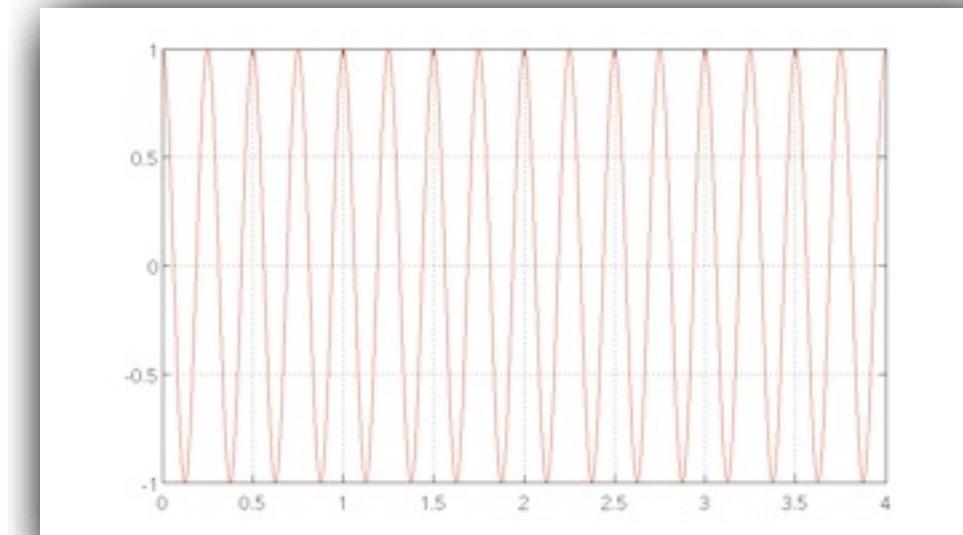


$$f_1 + f_2$$

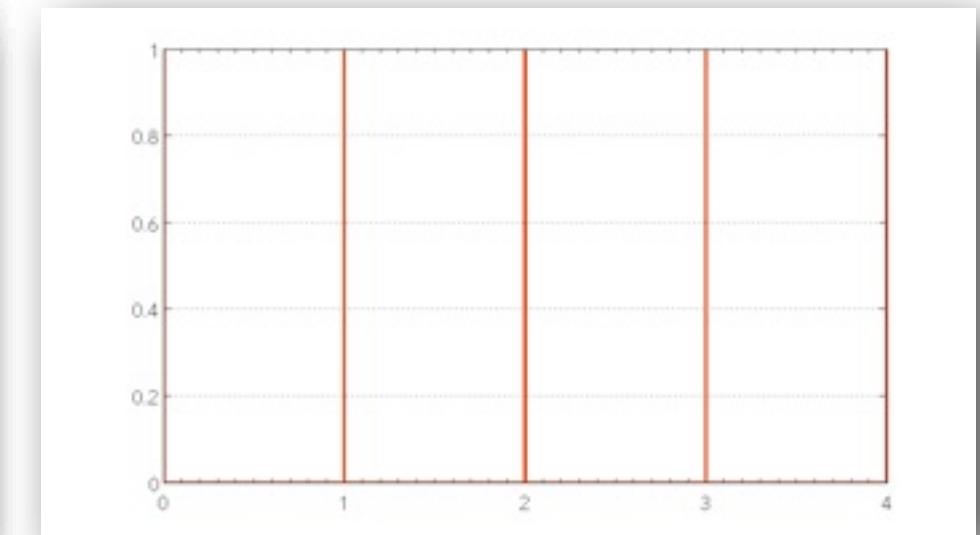
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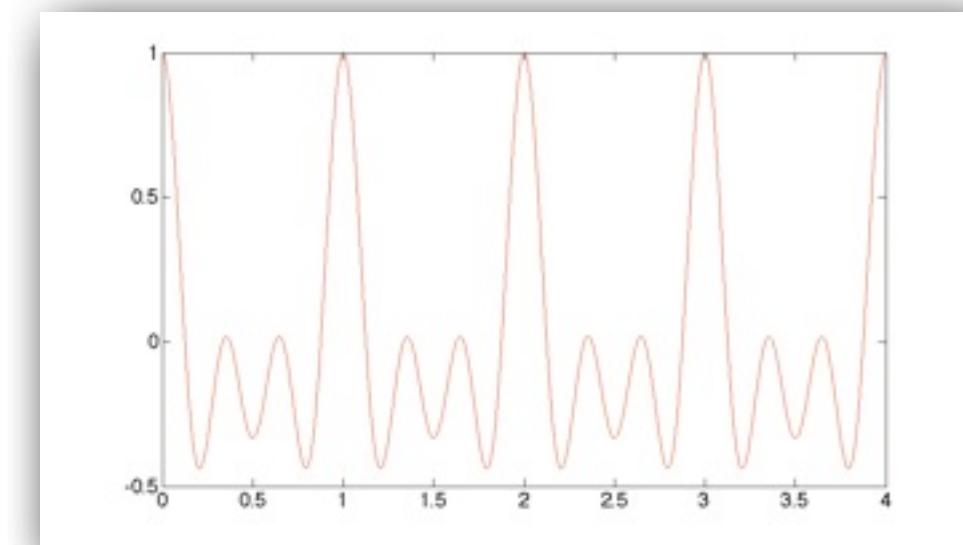
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$f^T(t)$ Target Signal



Repeating Impulse Function



$$f_1 + f_2 + f_3$$

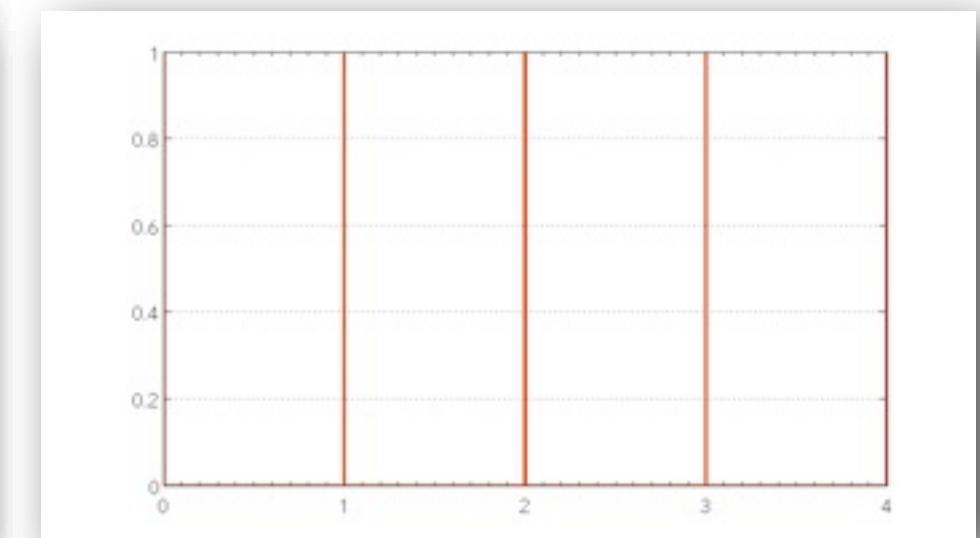
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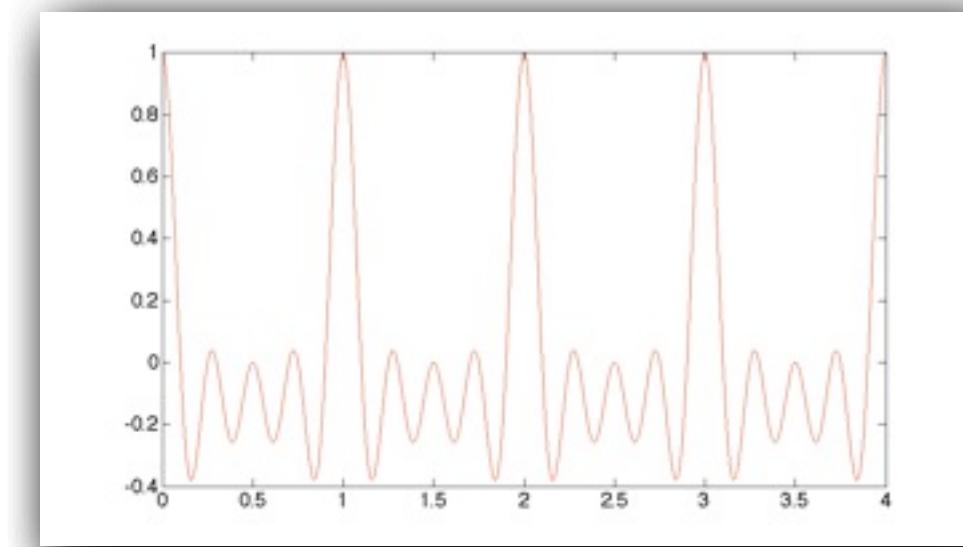
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$f^T(t)$ Target Signal



Repeating Impulse Function



$$f_1 + f_2 + f_3 + f_4$$

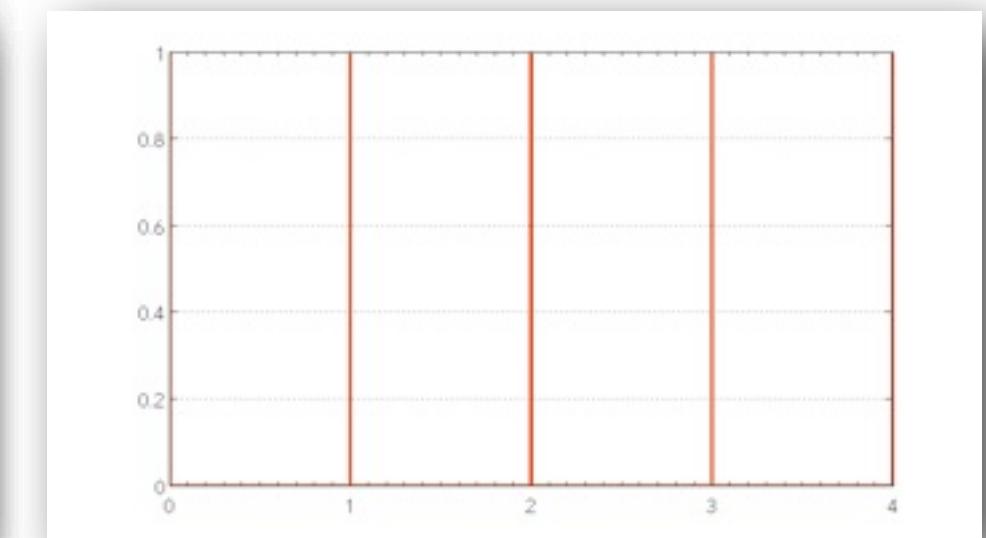
Sum of Cosines

- ★ Using this as our basic building block
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- ★ We want to get the target signal by adding enough of them
 - $f^T(t) = \sum_{n=1}^N A \cos(n\omega t)$

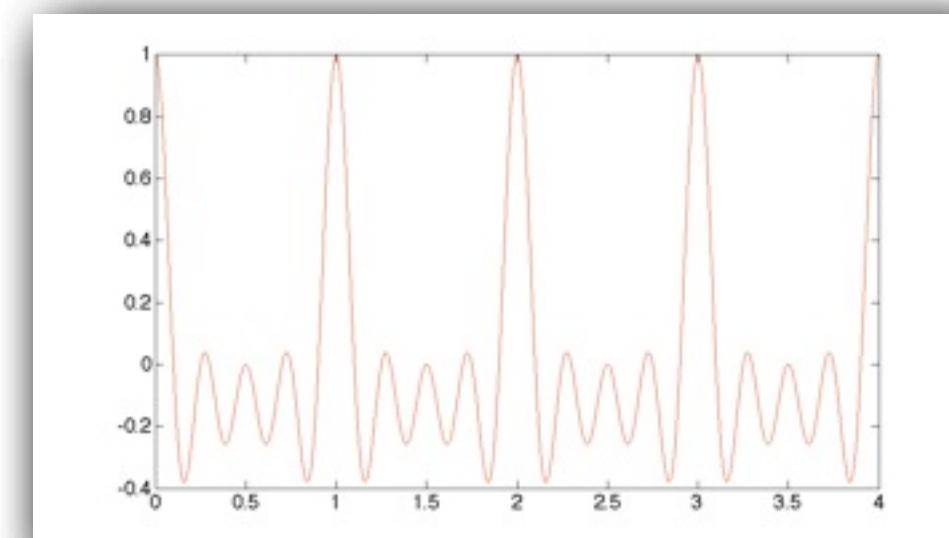
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$f^T(t)$ Target Signal



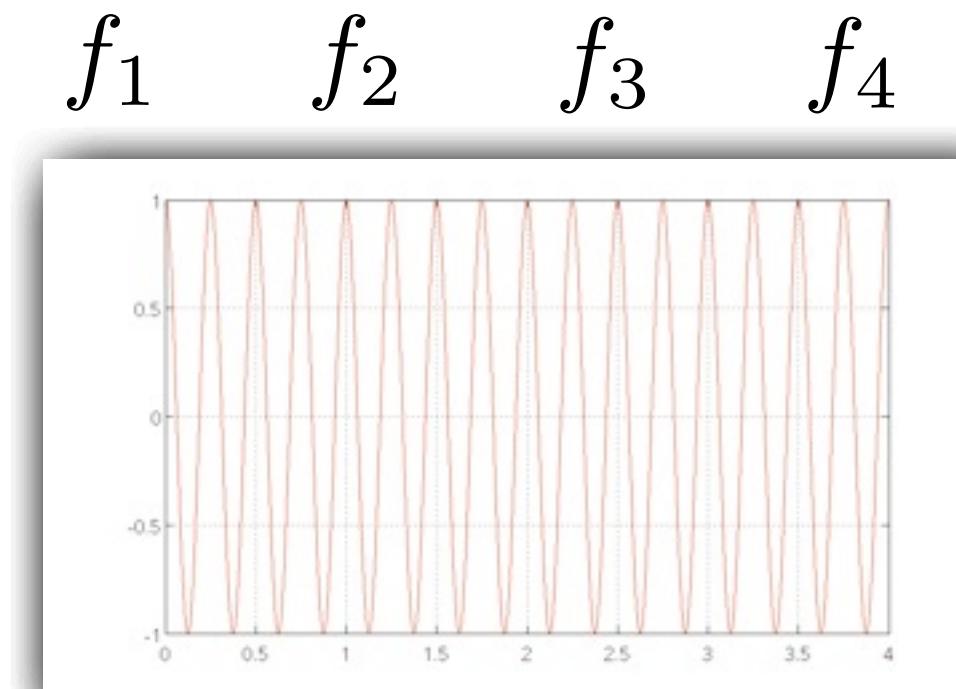
Repeating Impulse Function



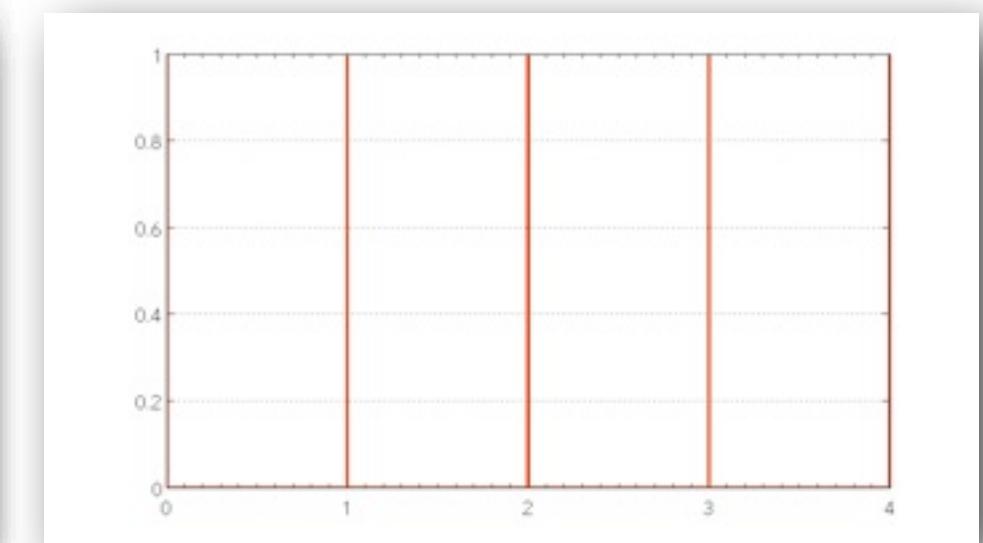
$$f_1 + f_2 + f_3 + f_4$$

Sum of Cosines

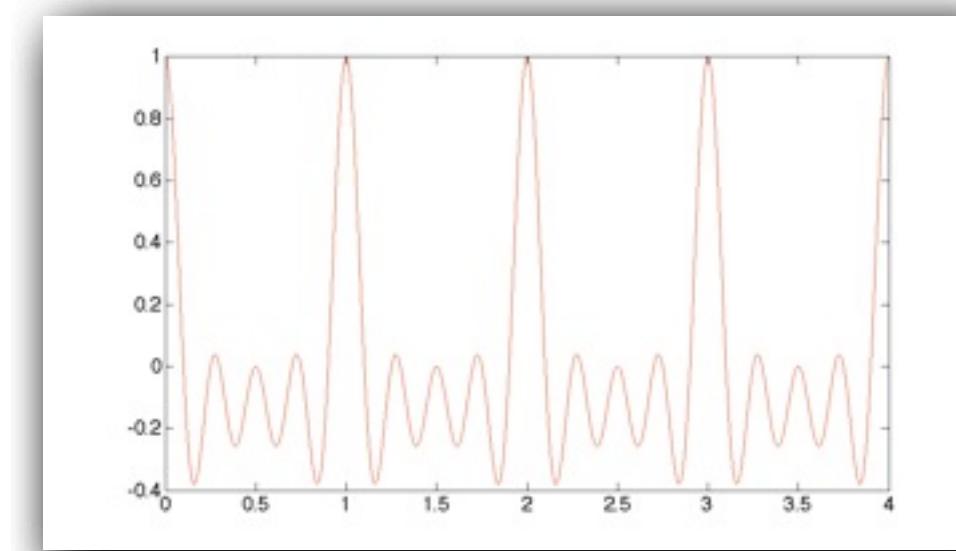
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- ★ N is Max number of blocks needed, A is amplitude and n is frequency



$f^T(t)$ Target Signal



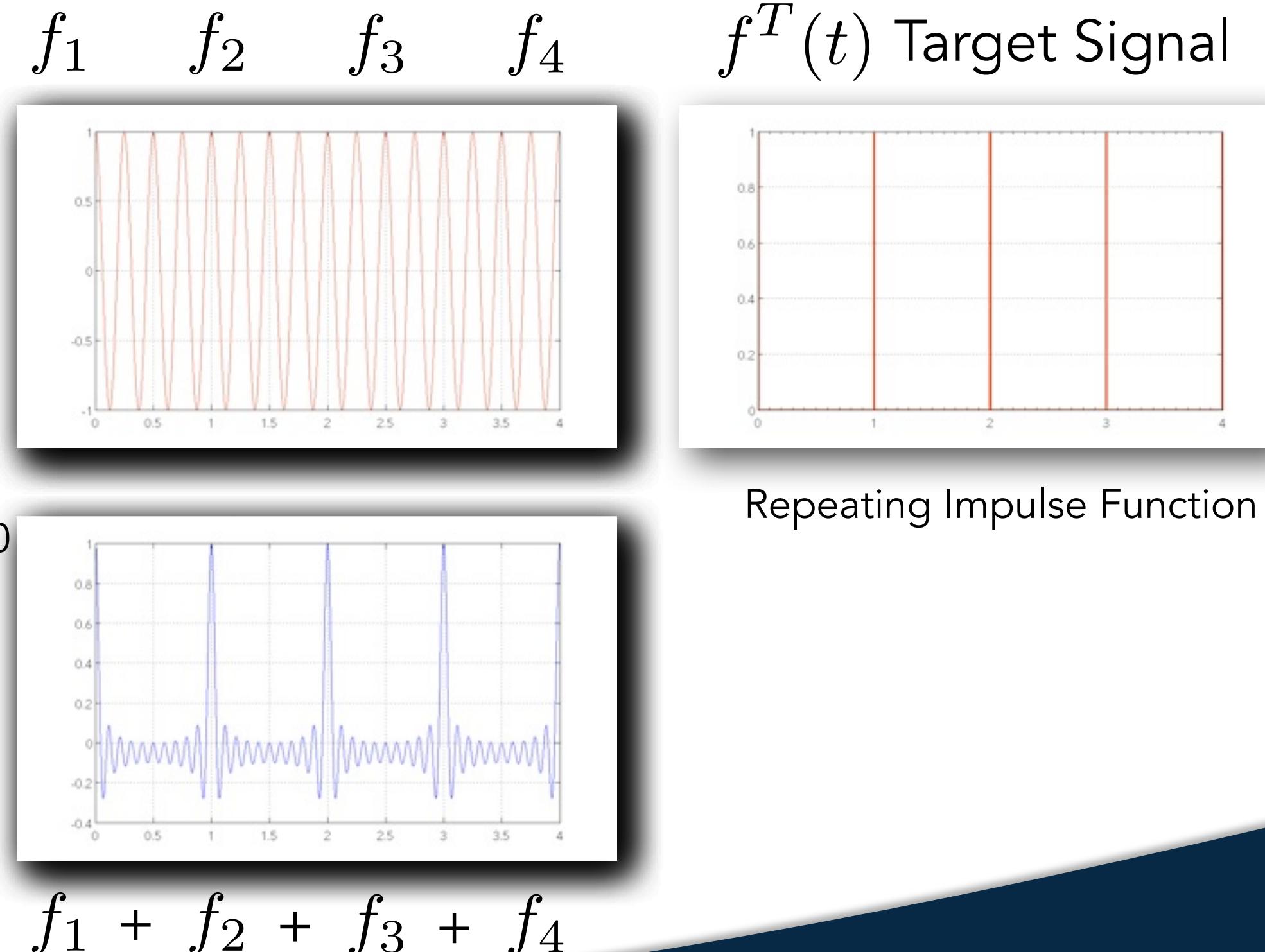
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$$f_1 + f_2 + f_3 + f_4$$

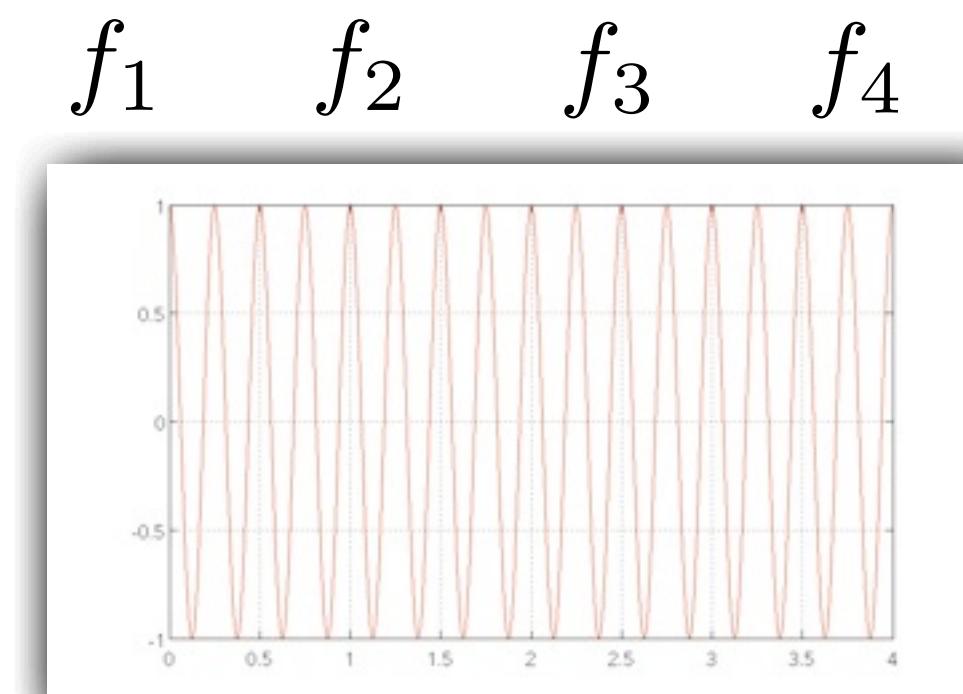
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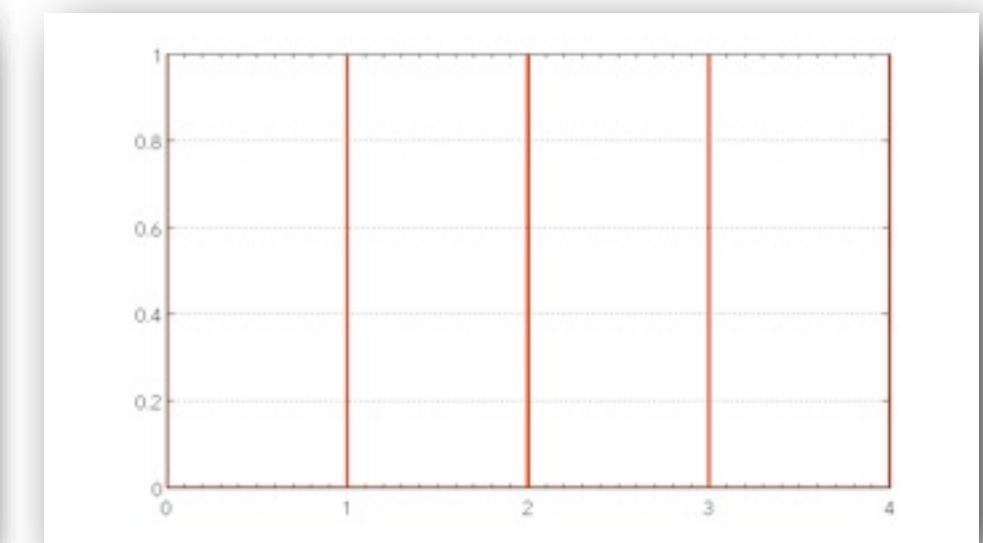


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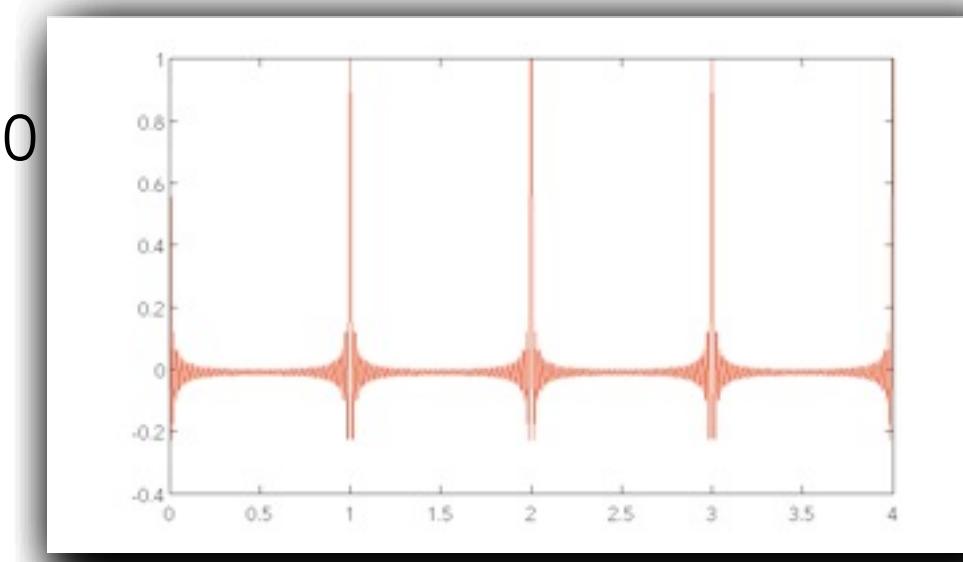
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$f^T(t)$ Target Signal



Repeating Impulse Function



$$f_1 + f_2 + f_3 + f_4$$

A Fourier Transform



Jean Baptiste Joseph Fourier
(1768-1830)

<http://en.wikipedia.org/wiki/File:Fourier2.jpg>

A Fourier Transform

- ★ Any periodic function can be rewritten as a weighted sum of sines and cosines of different frequencies.



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$$F(\omega) = A \cos(\omega t + \phi)$$

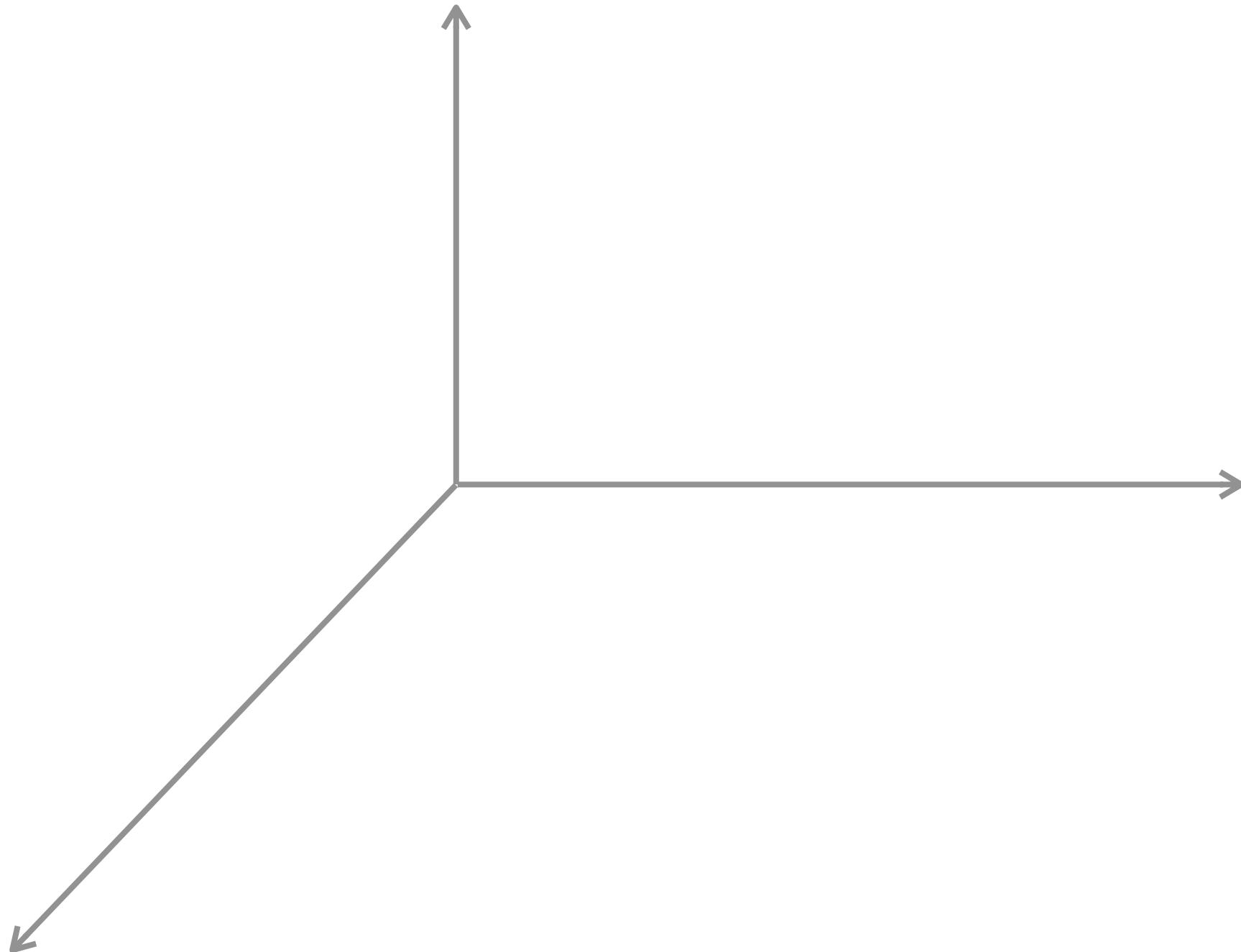


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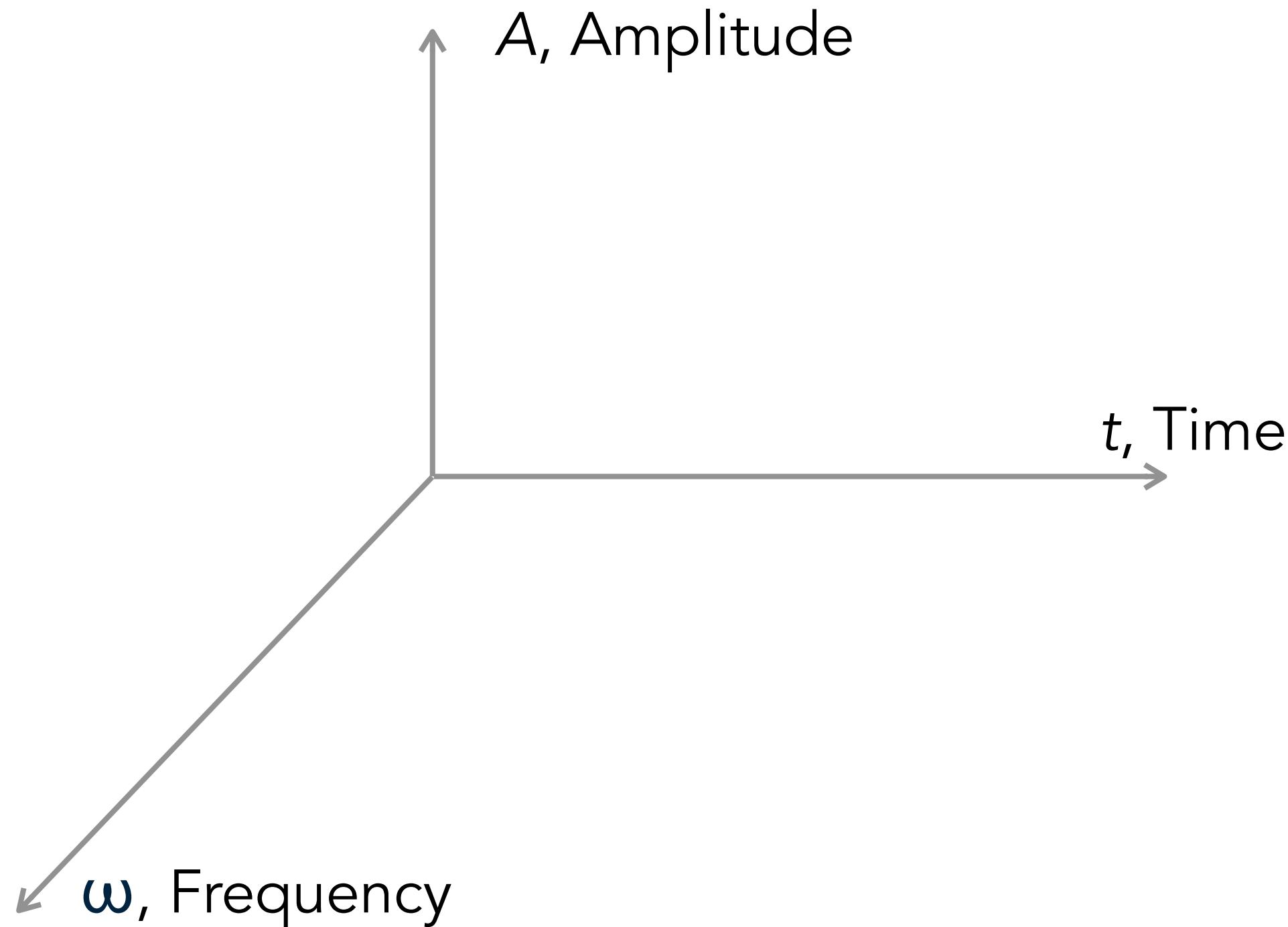
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Frequency Domain of a Signal

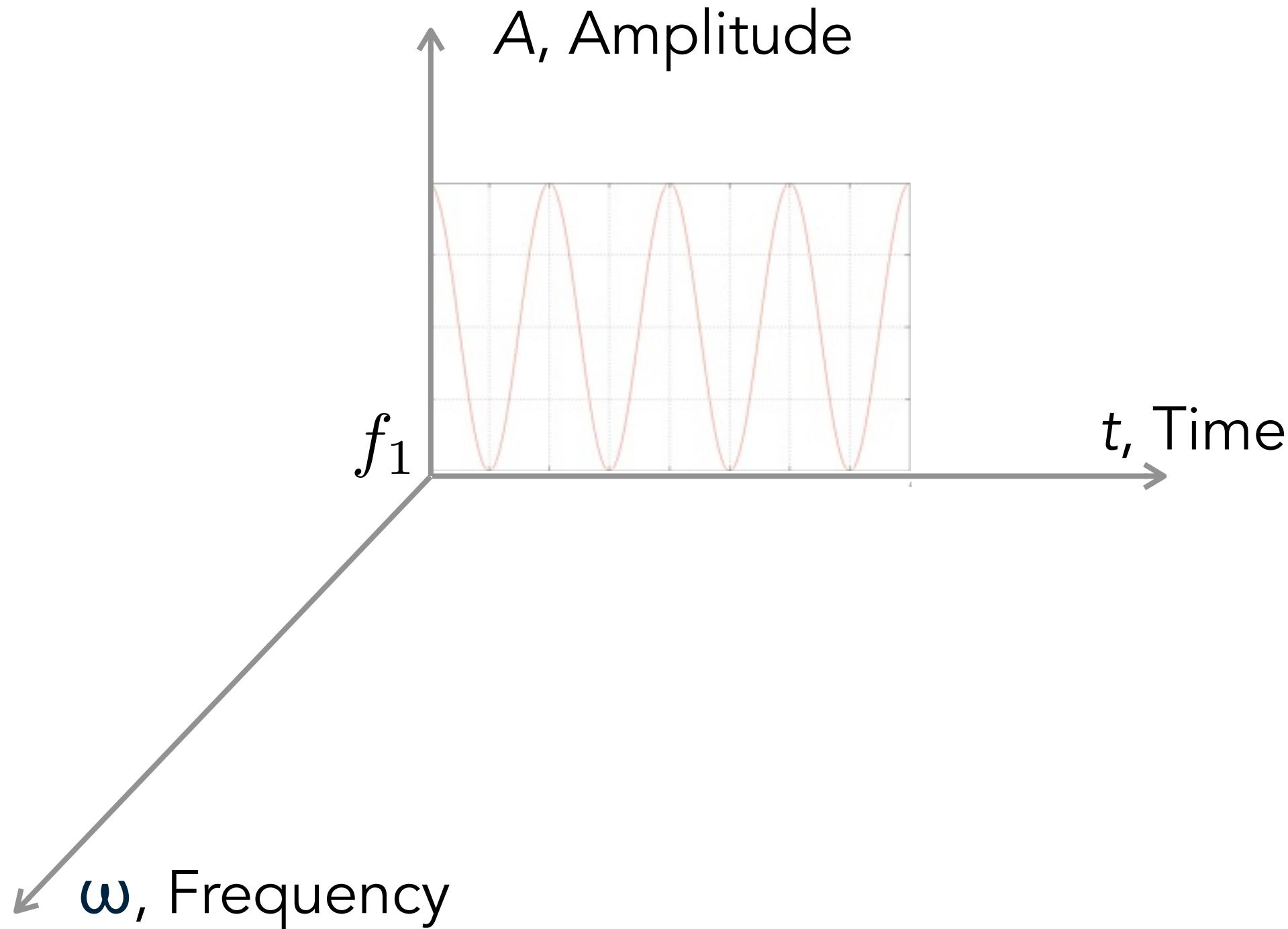
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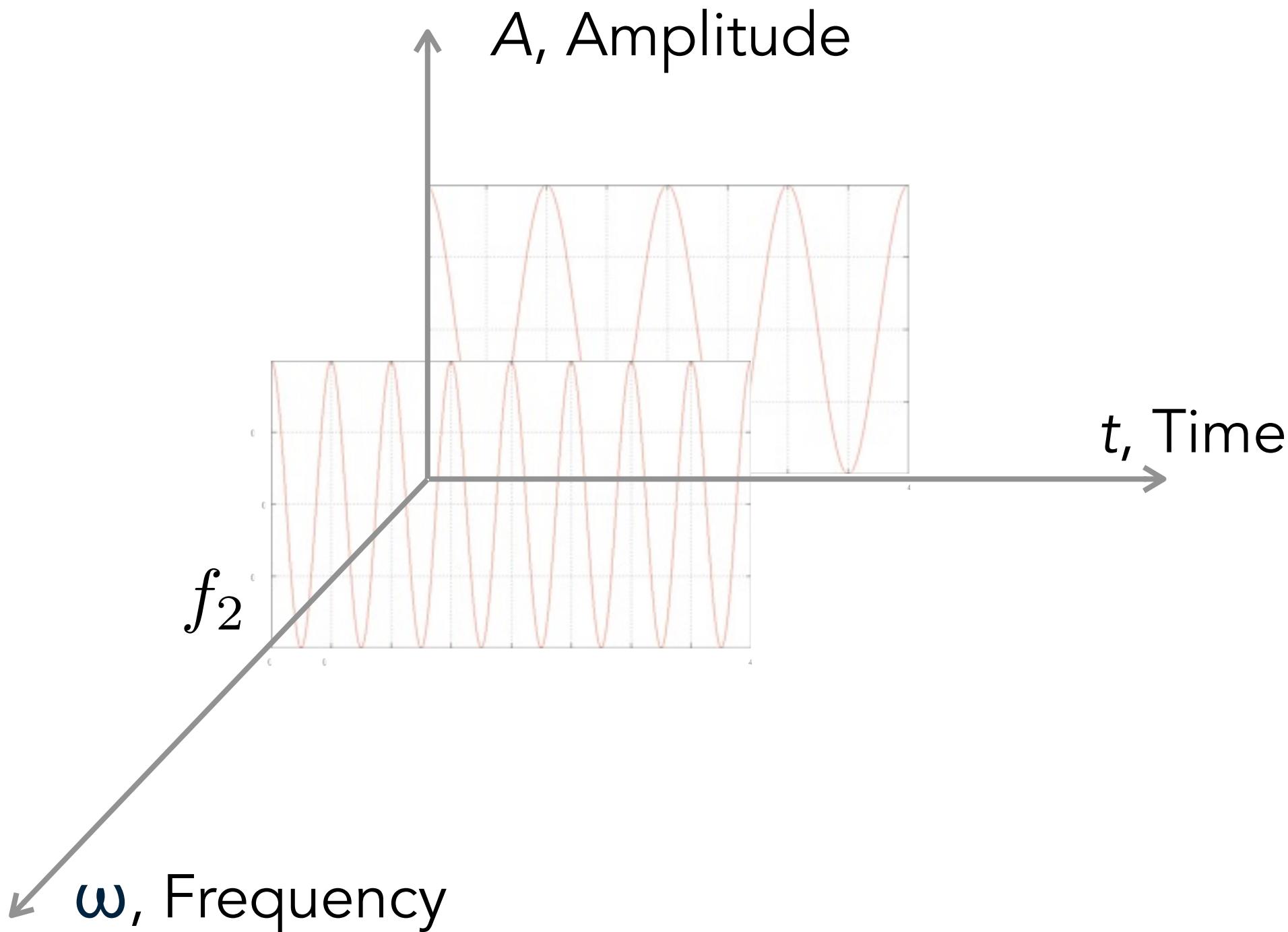
Frequency Domain of a Signal



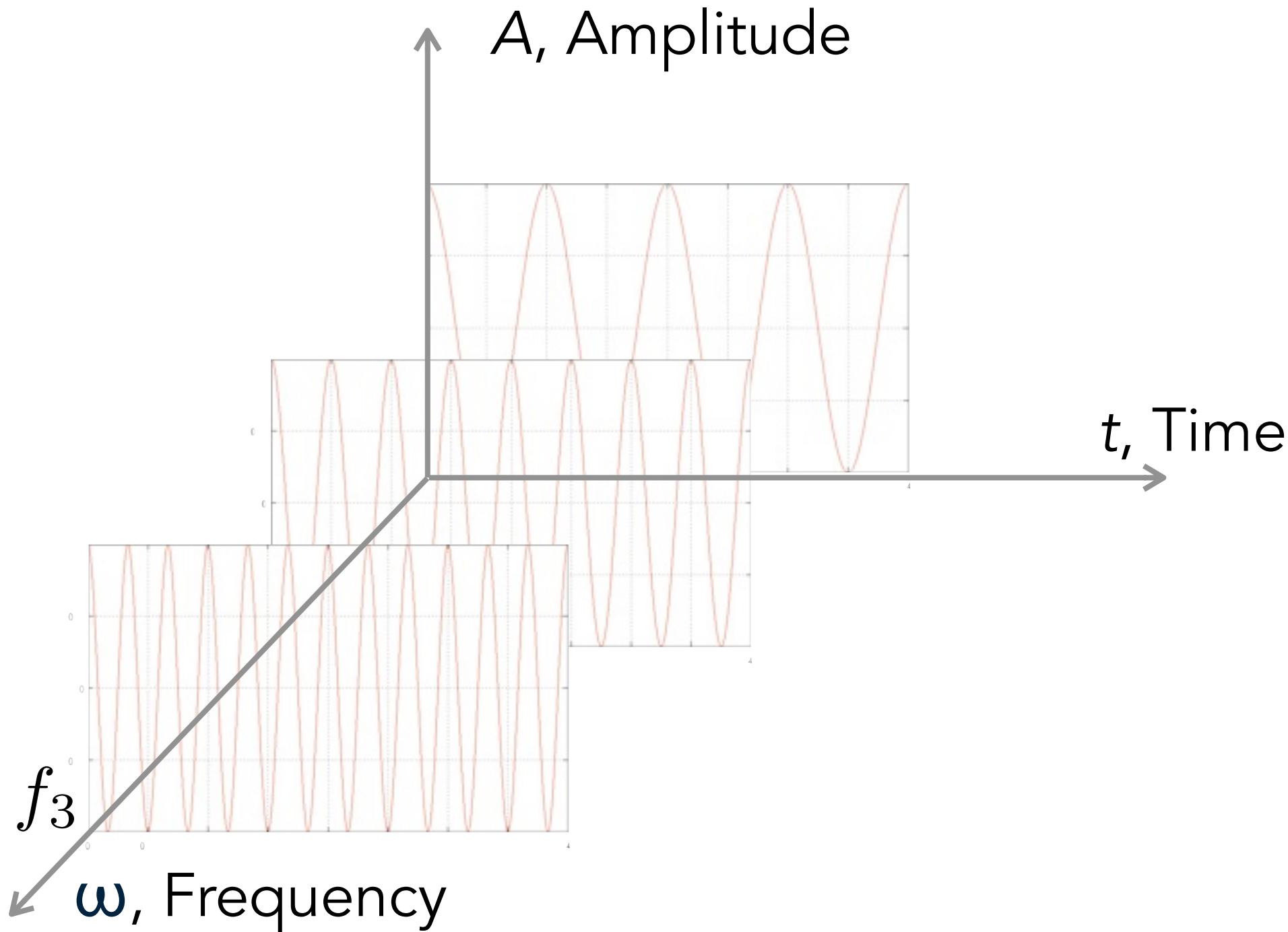
Frequency Domain of a Signal



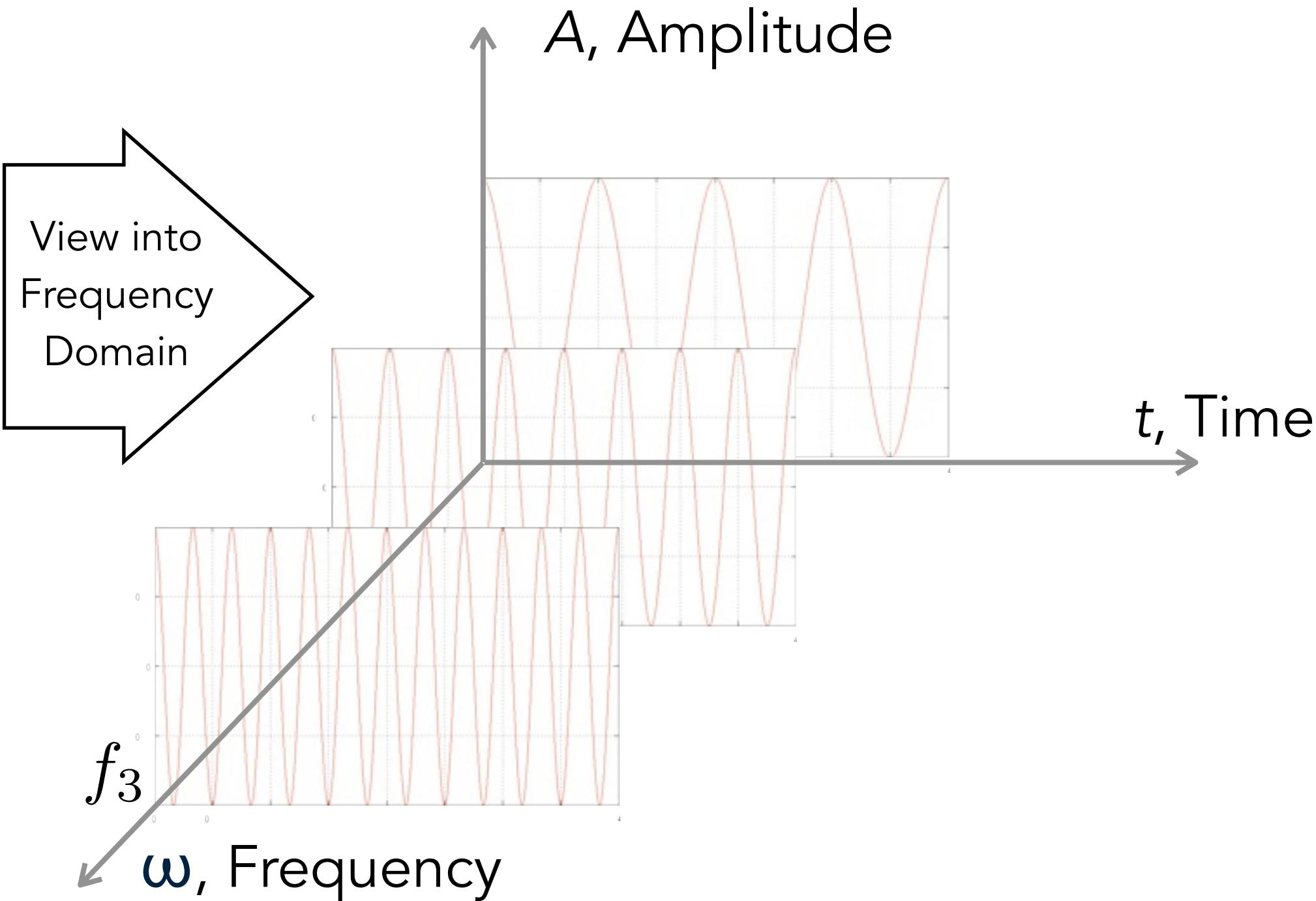
Frequency Domain of a Signal



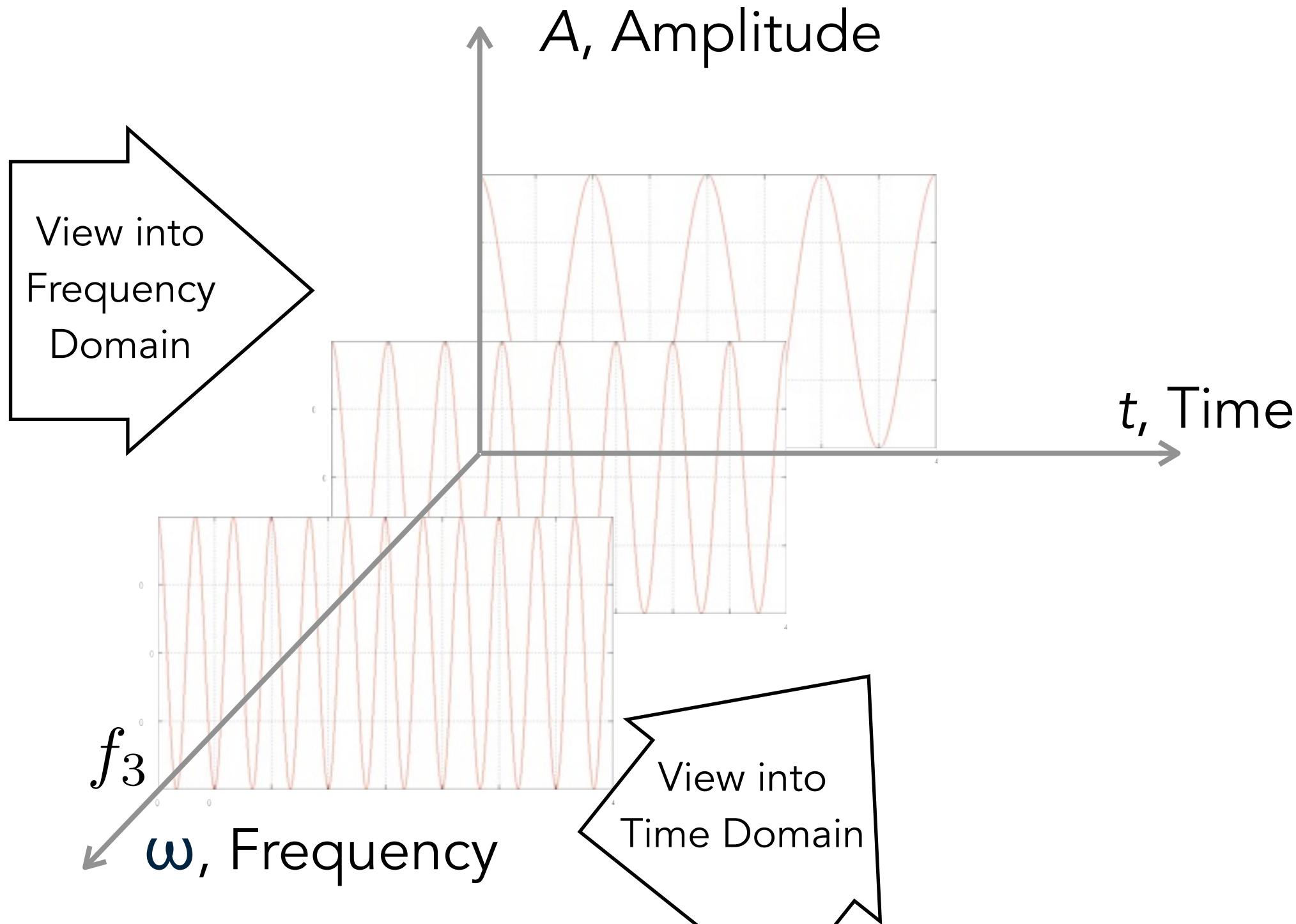
Frequency Domain of a Signal



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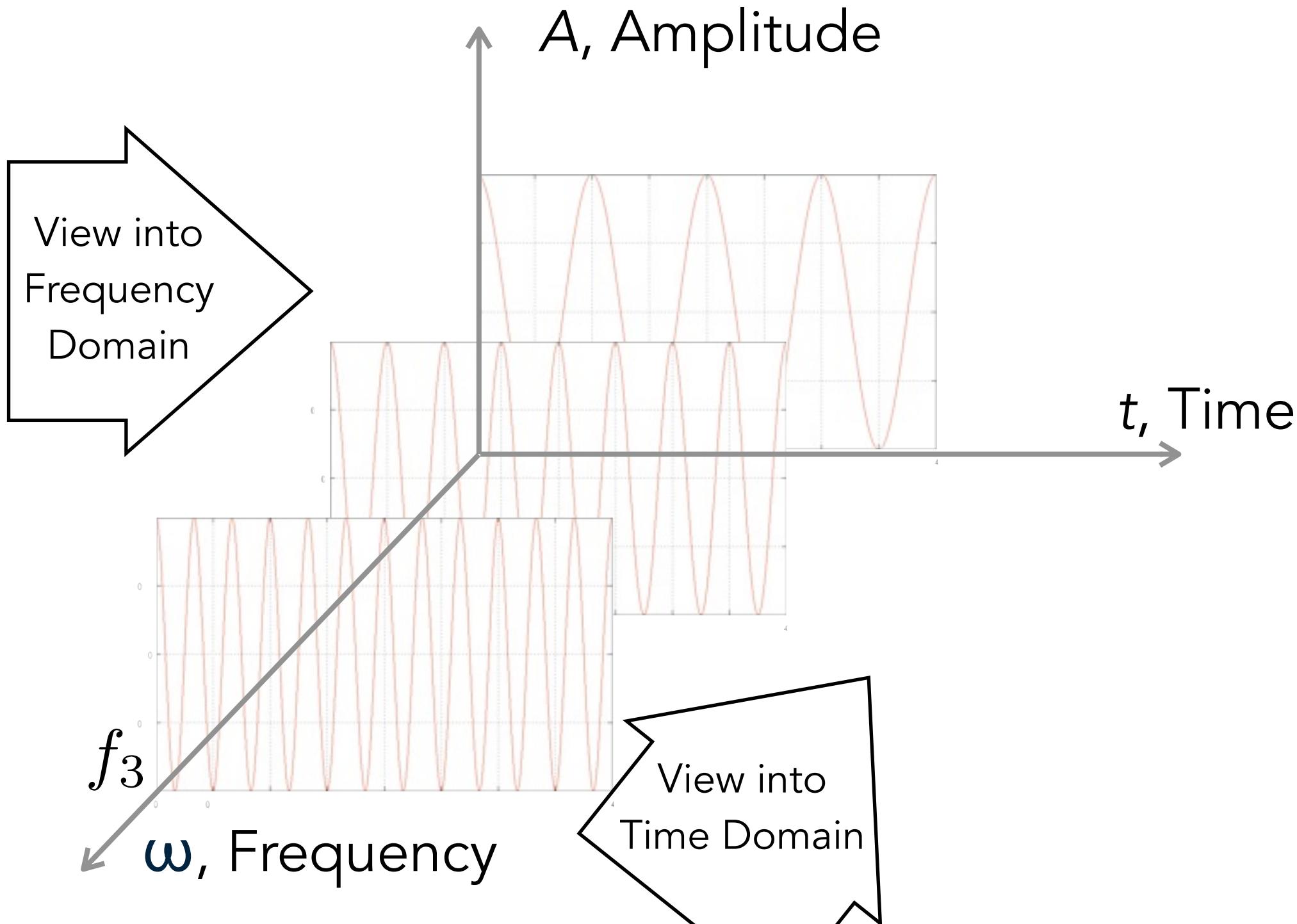


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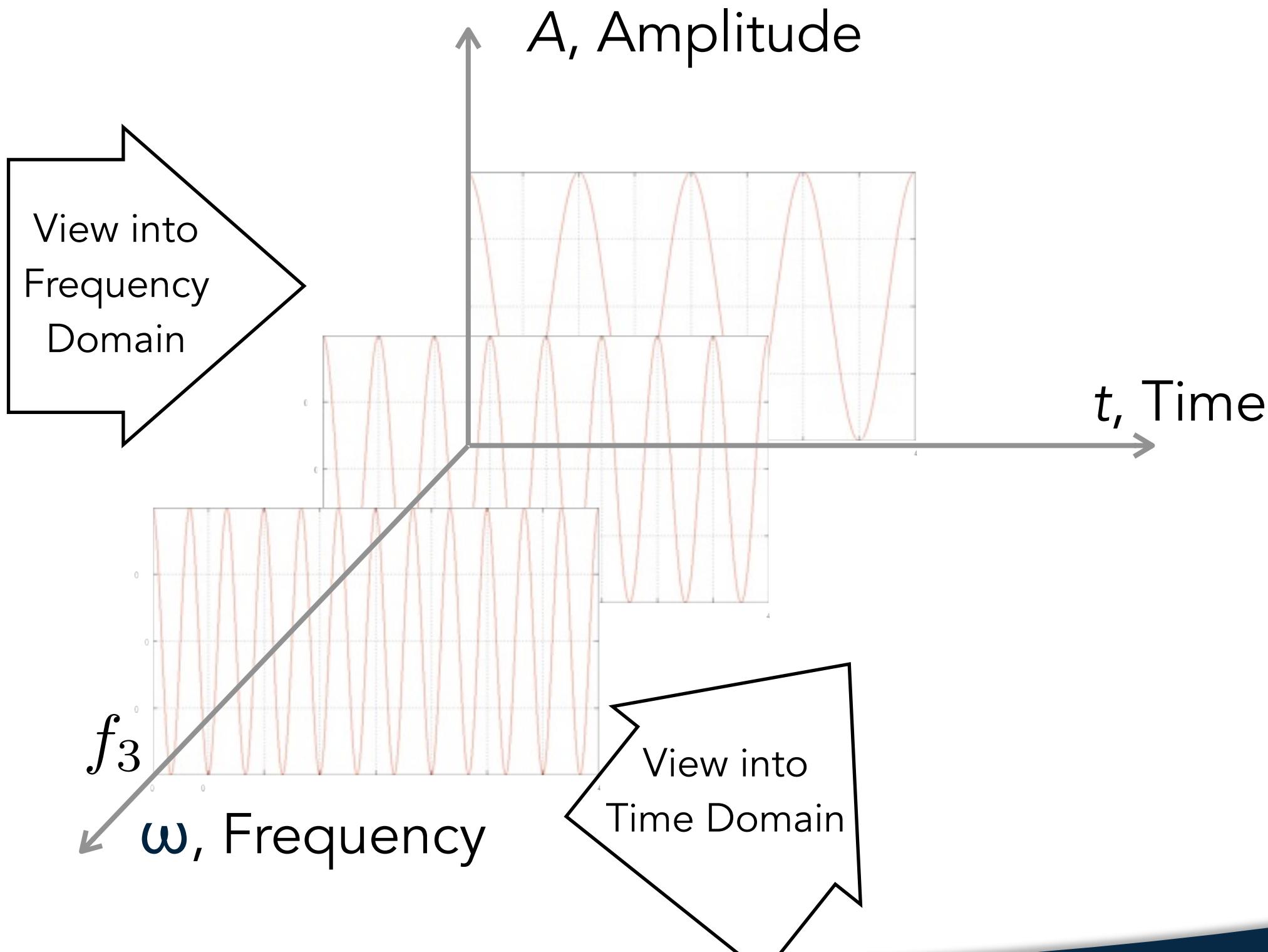
Frequency Domain of a Signal

1. How many N?

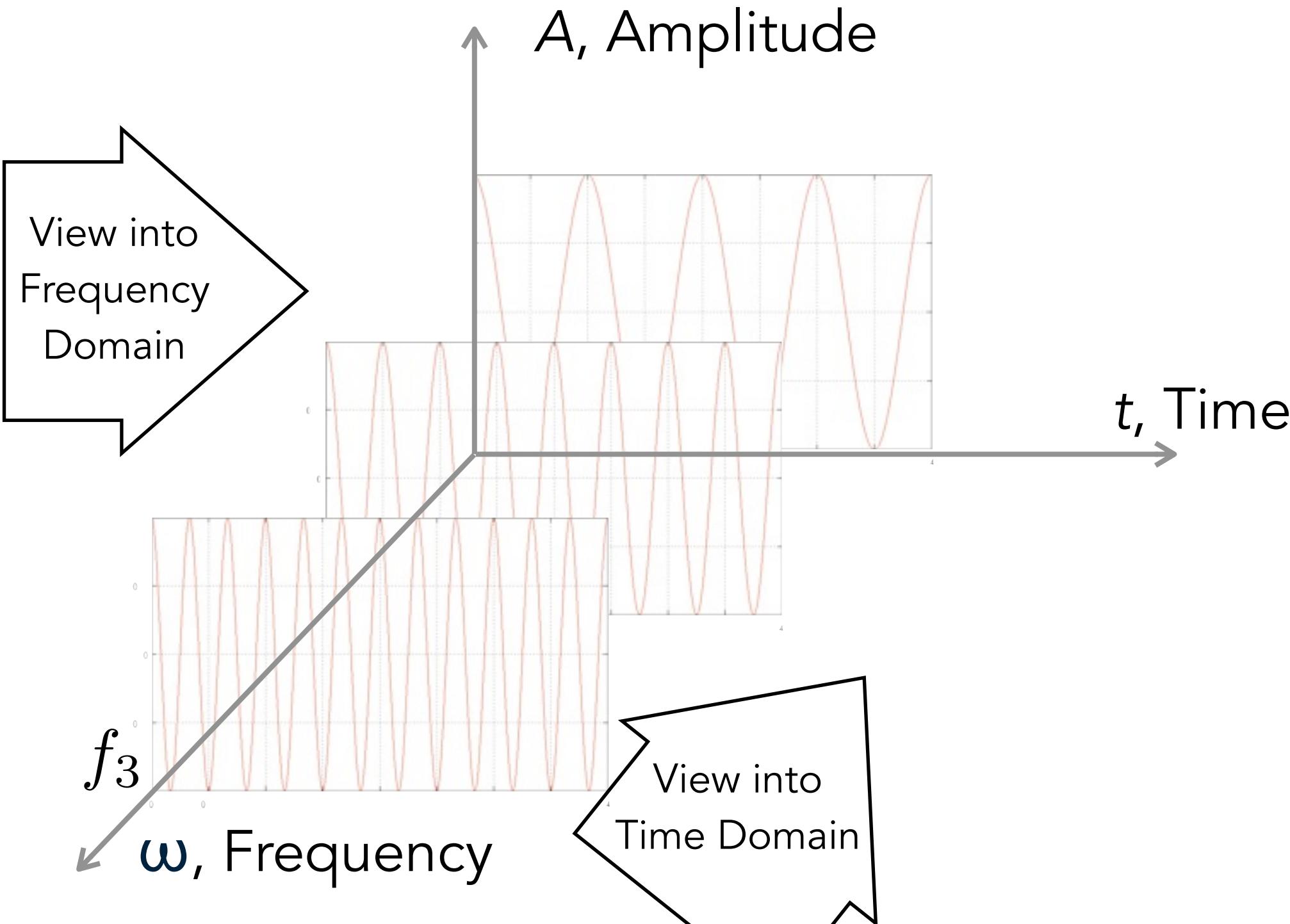


Frequency Domain of a Signal

1. How many N?
2. What does each control?

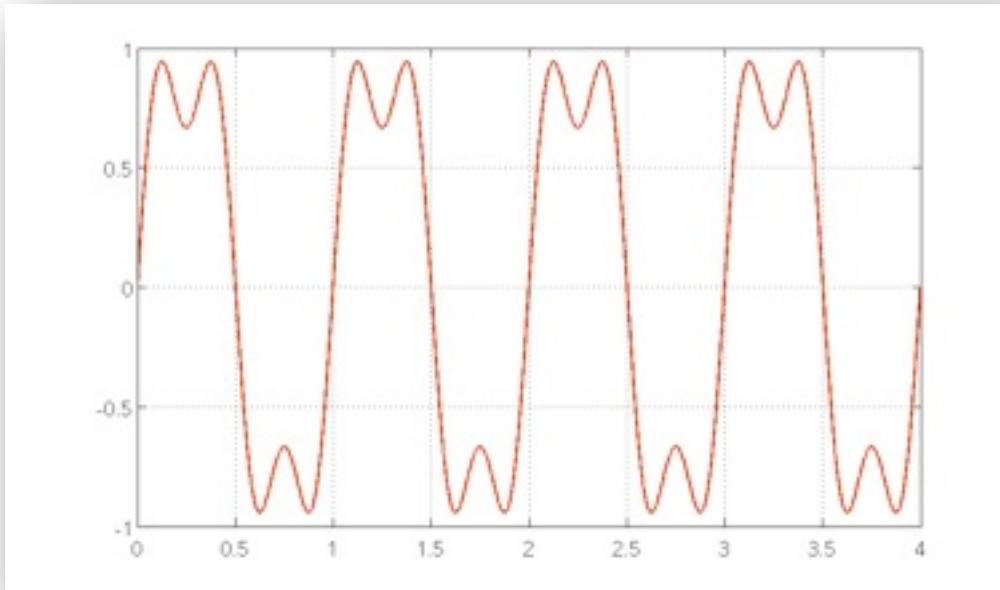


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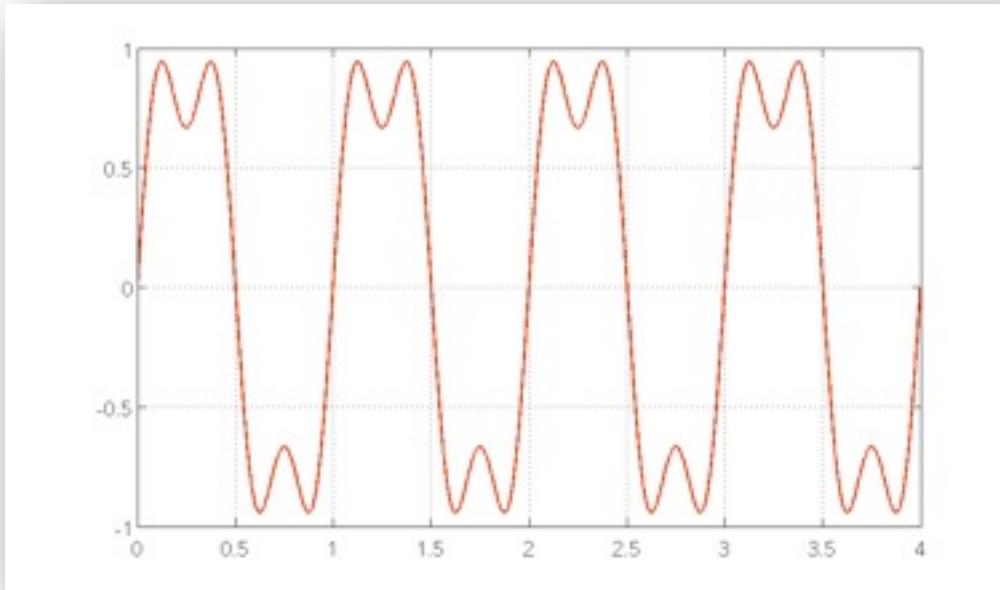


1. How many N?
2. What does each control?
3. Which one encodes the coarse vs. fine structure of the signal?

Time, Frequency, and Frequency Spectra

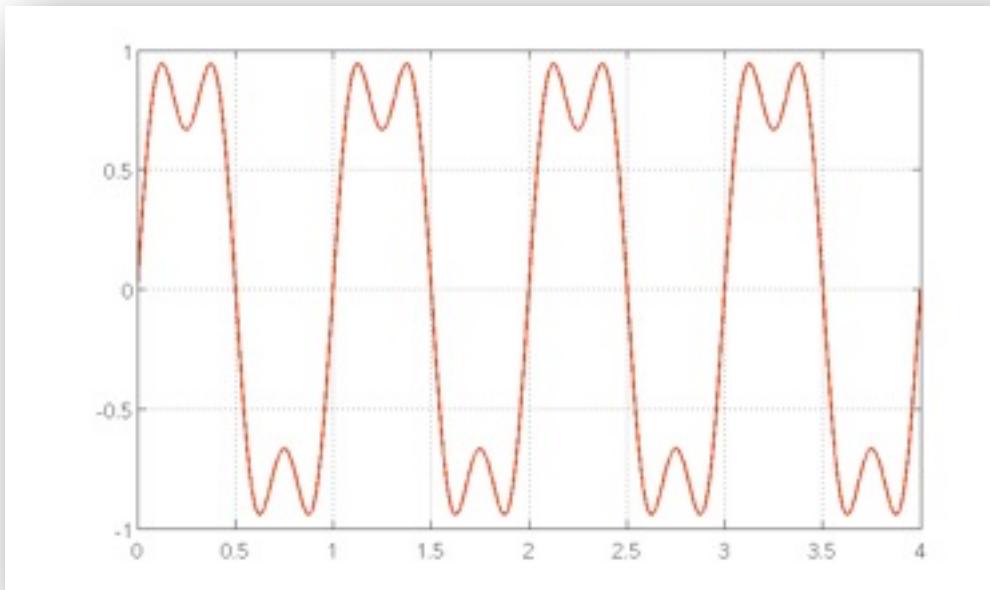


Time, Frequency, and Frequency Spectra

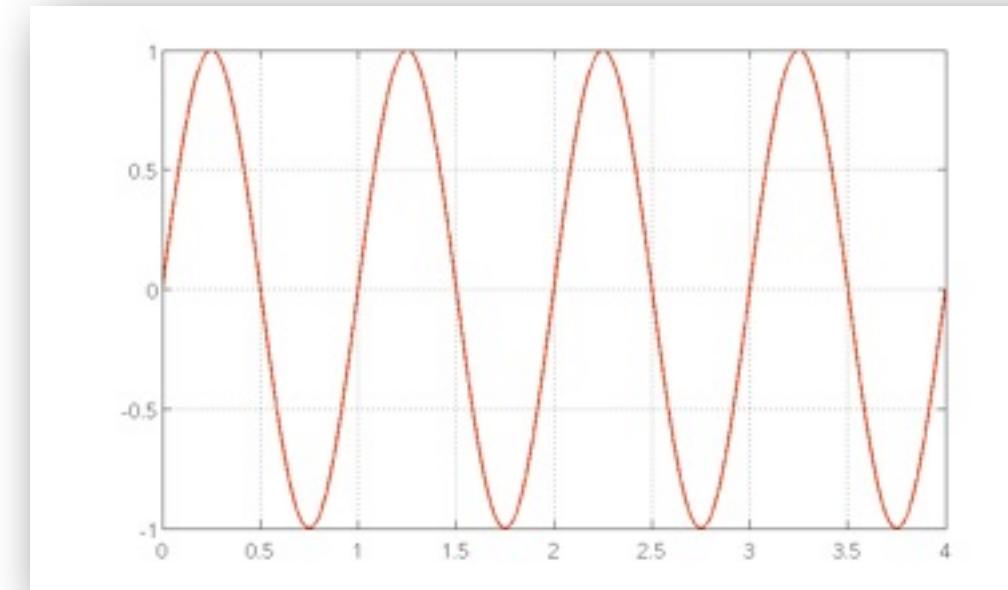


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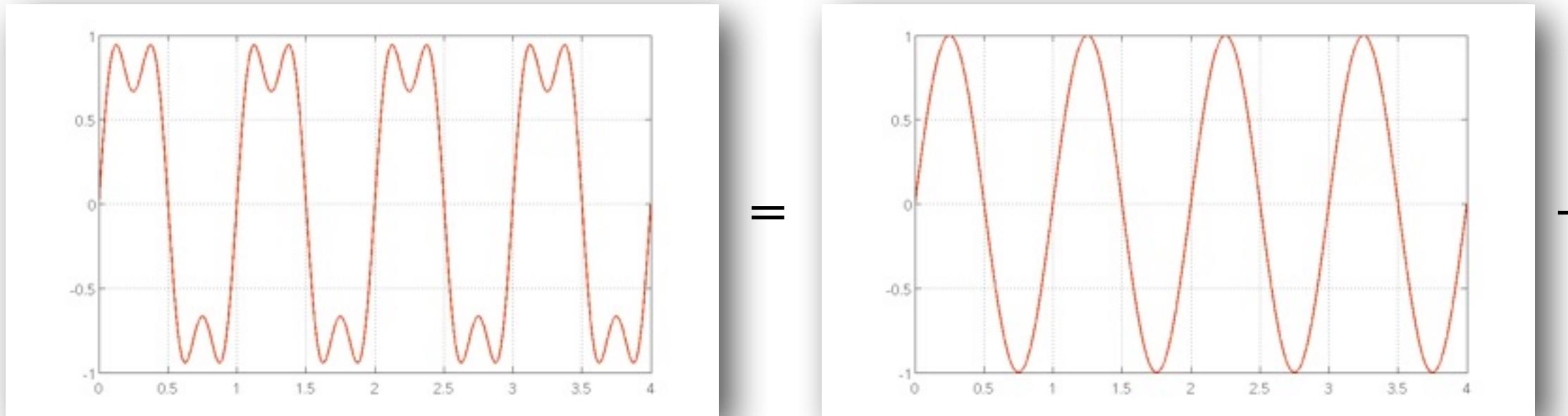
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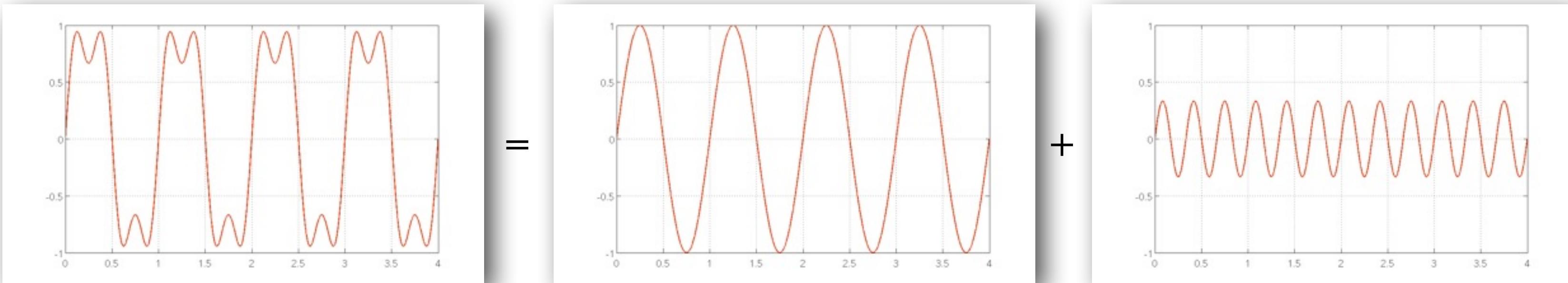
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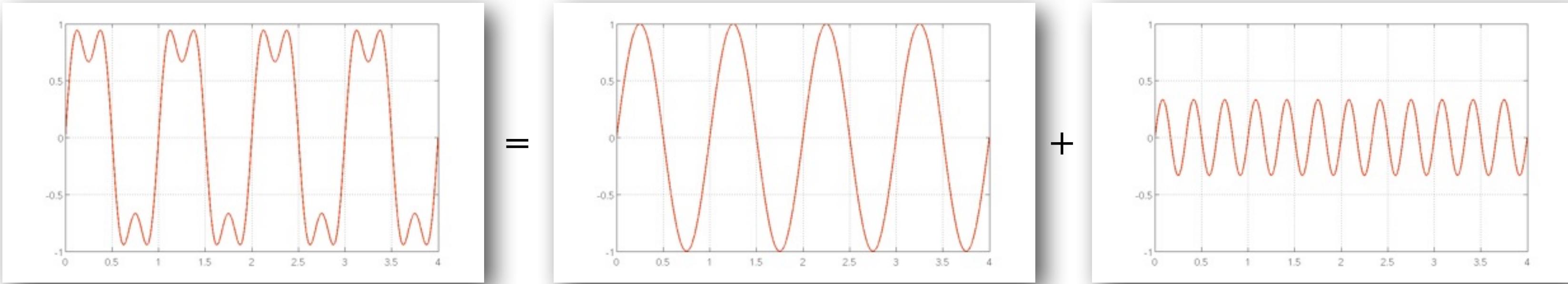
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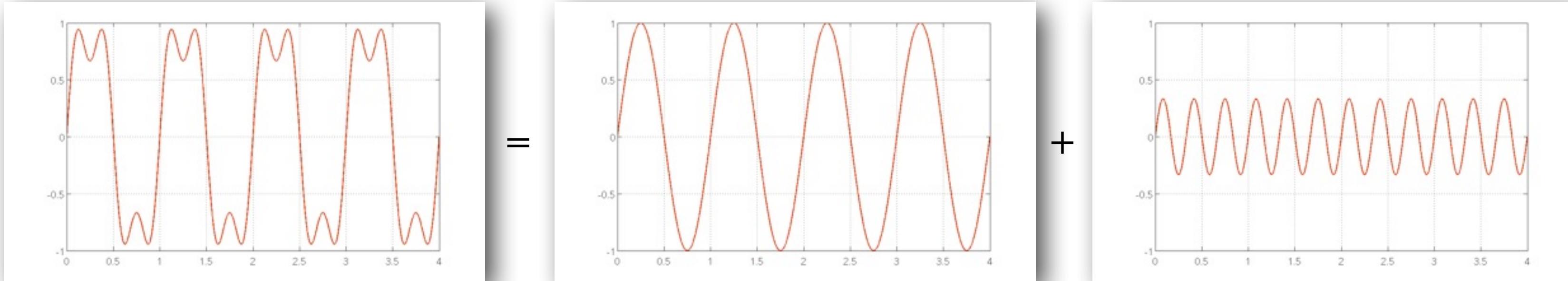


Time, Frequency, and Frequency Spectra



$$g(t) = \sin(2p\omega t) + \frac{1}{3} \sin(2p(3\omega)t)$$

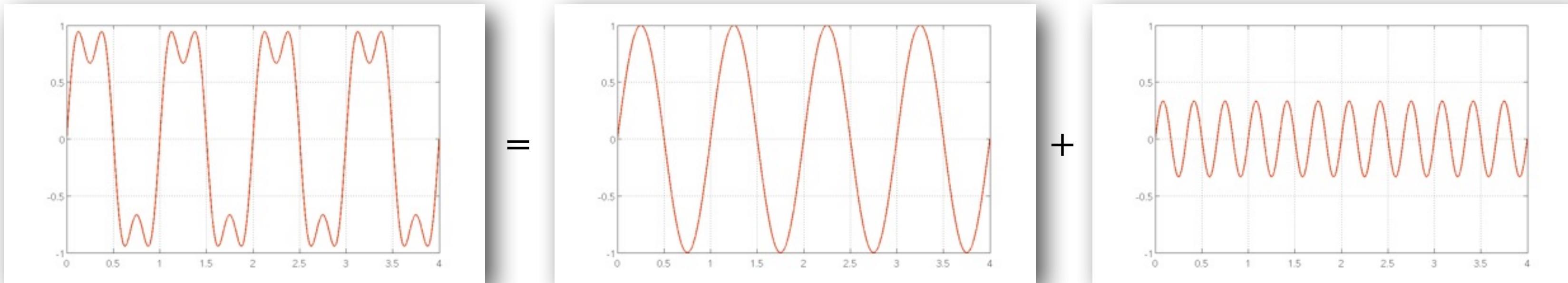
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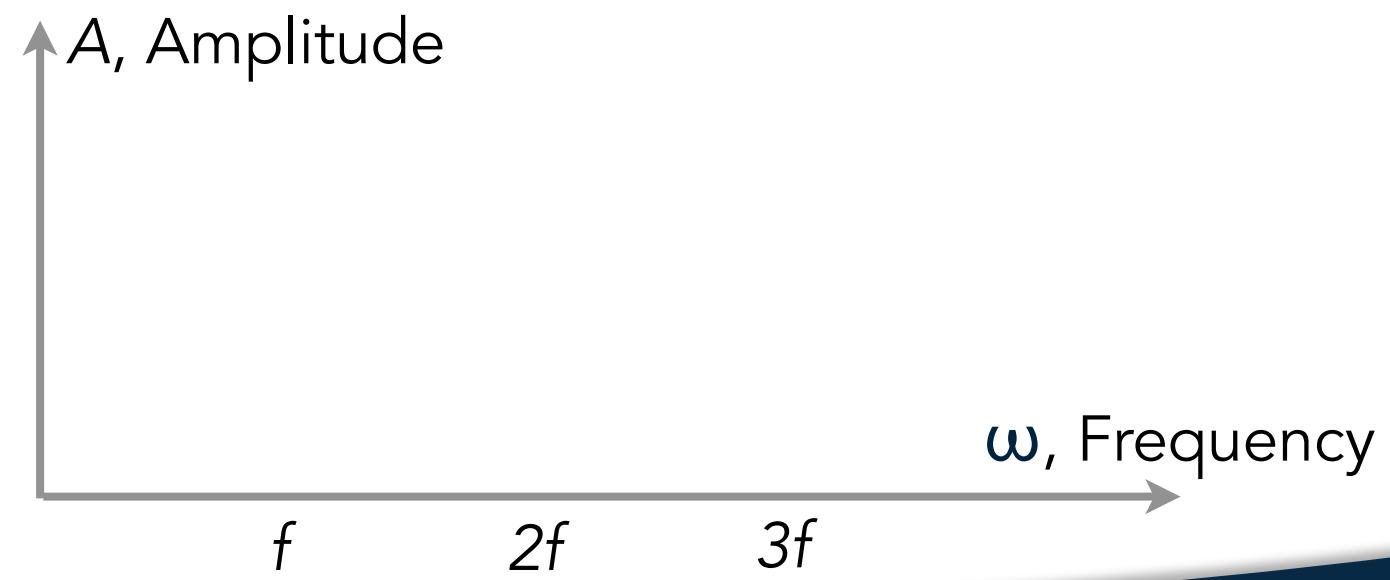
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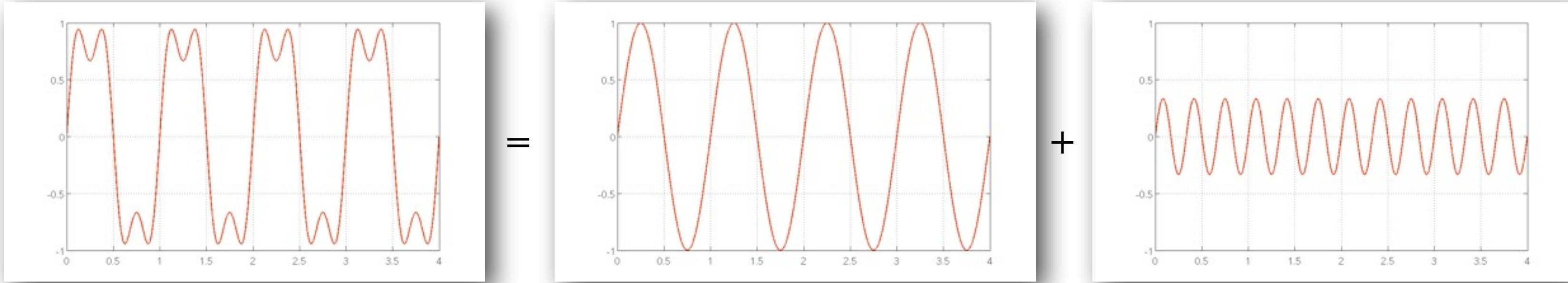
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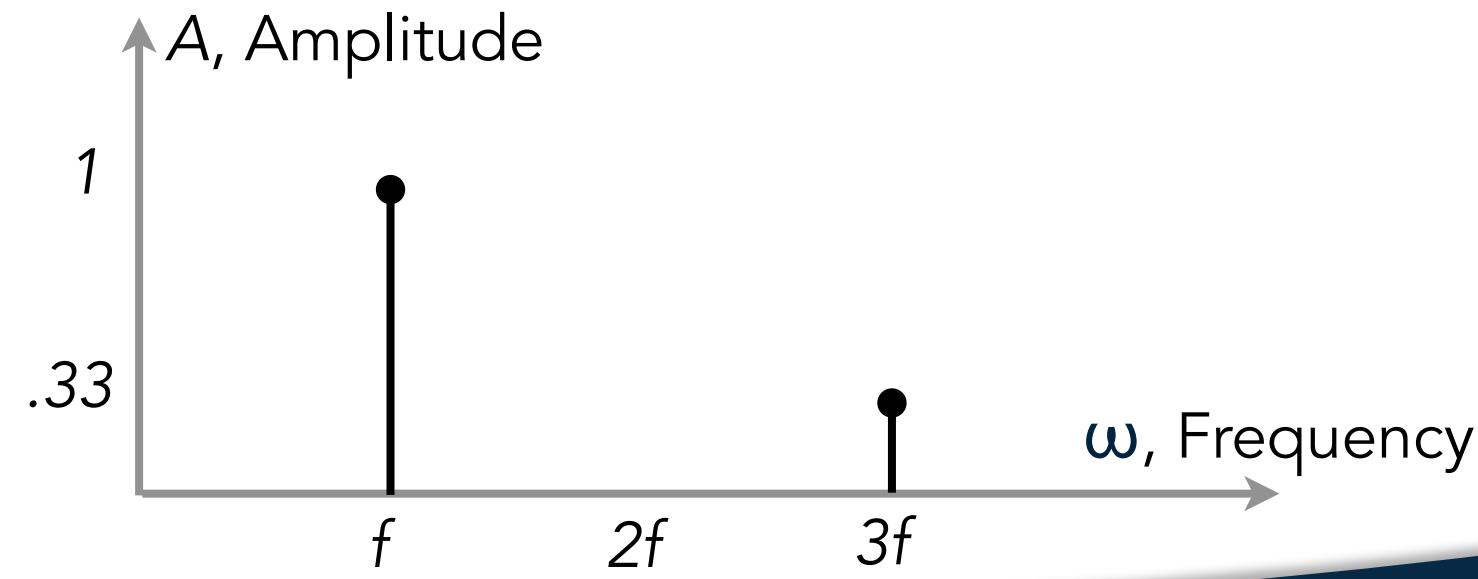
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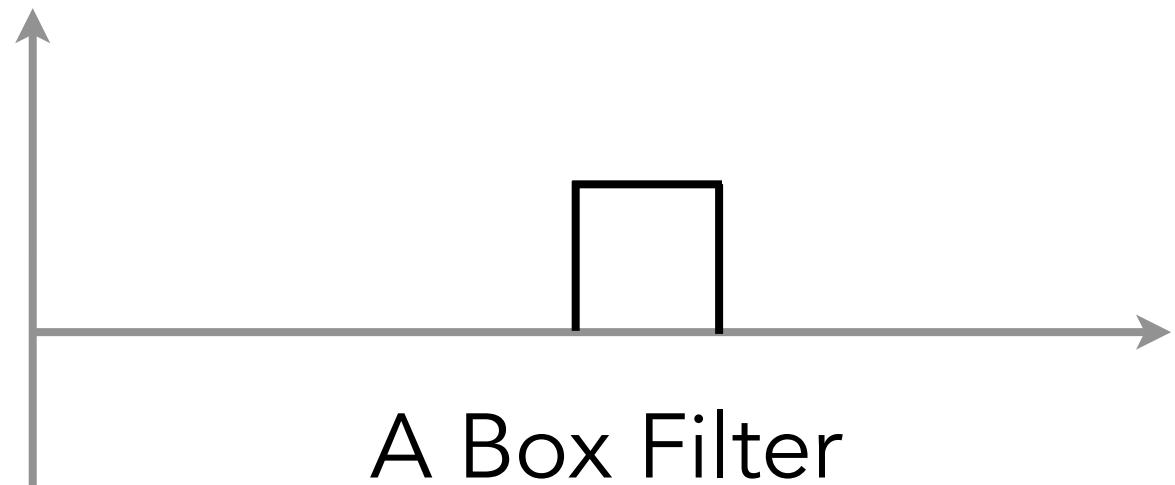
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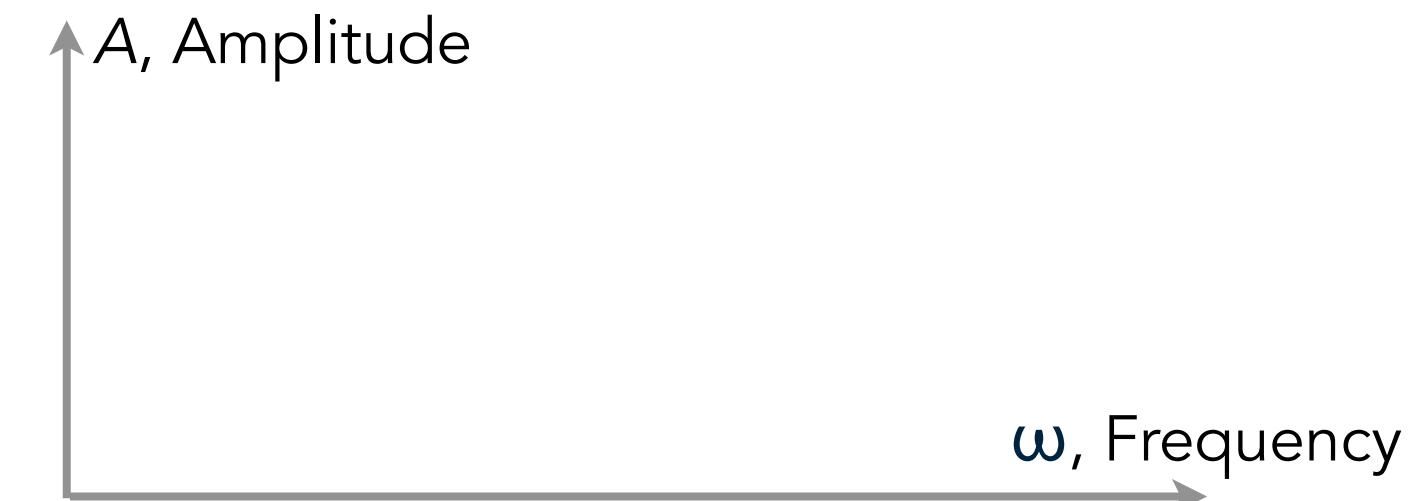
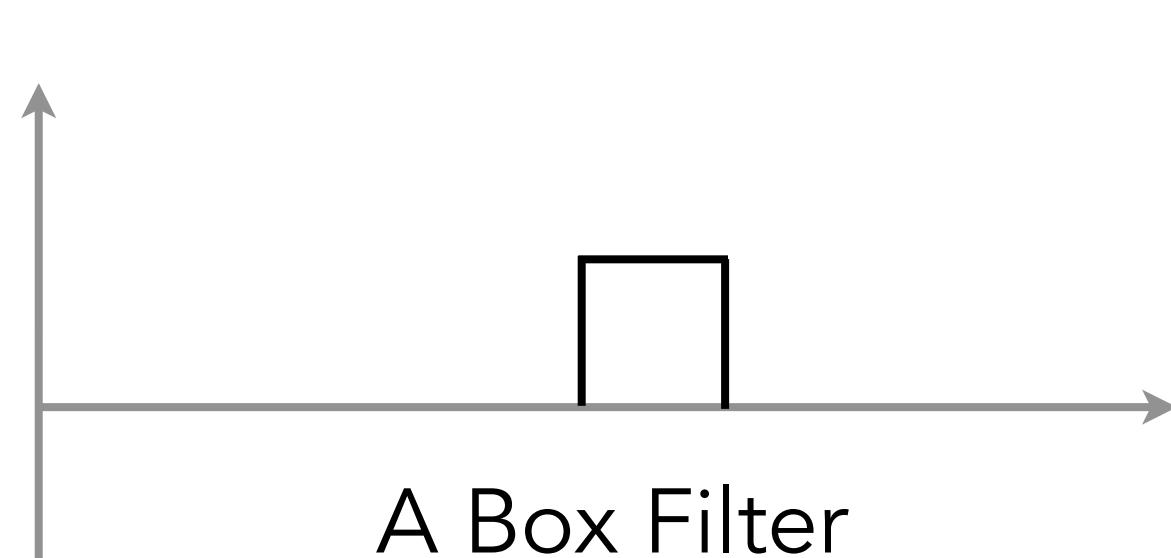


Frequency Spectra



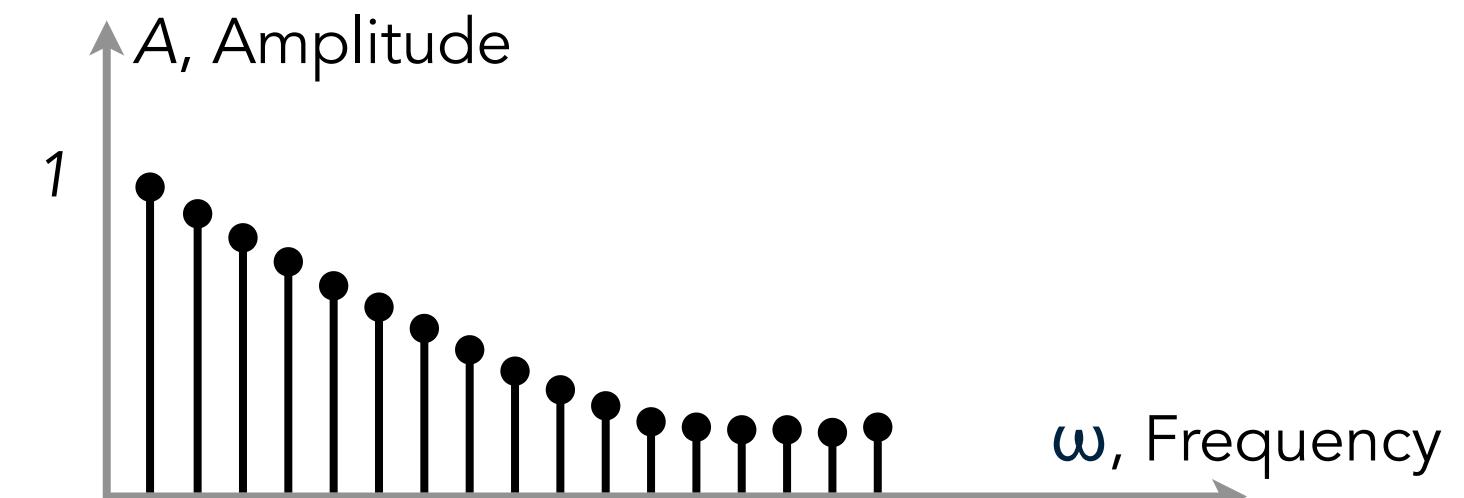
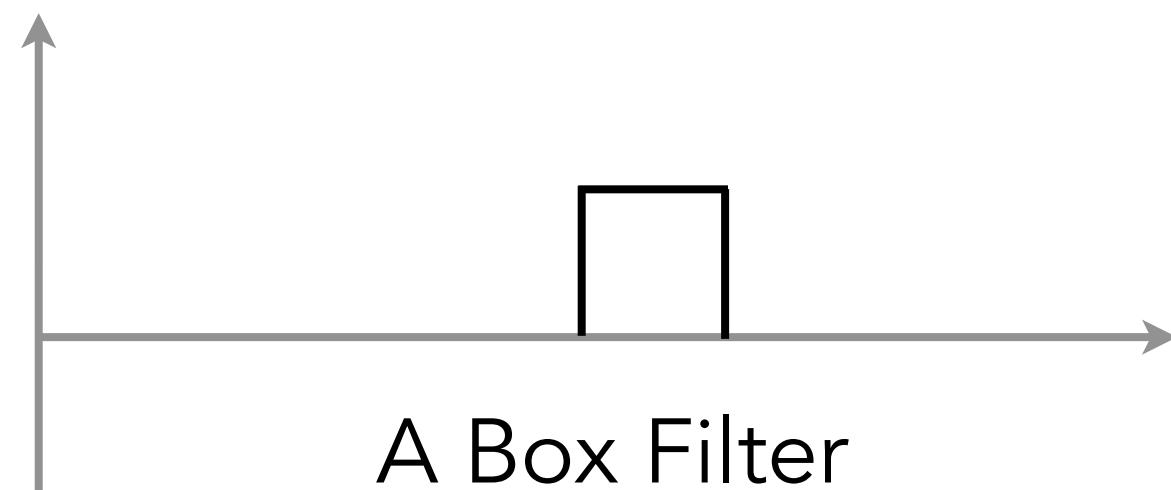
$$A \sum_{k=1}^{\infty} \frac{1}{k} \sin(2\pi kt)$$

Frequency Spectra



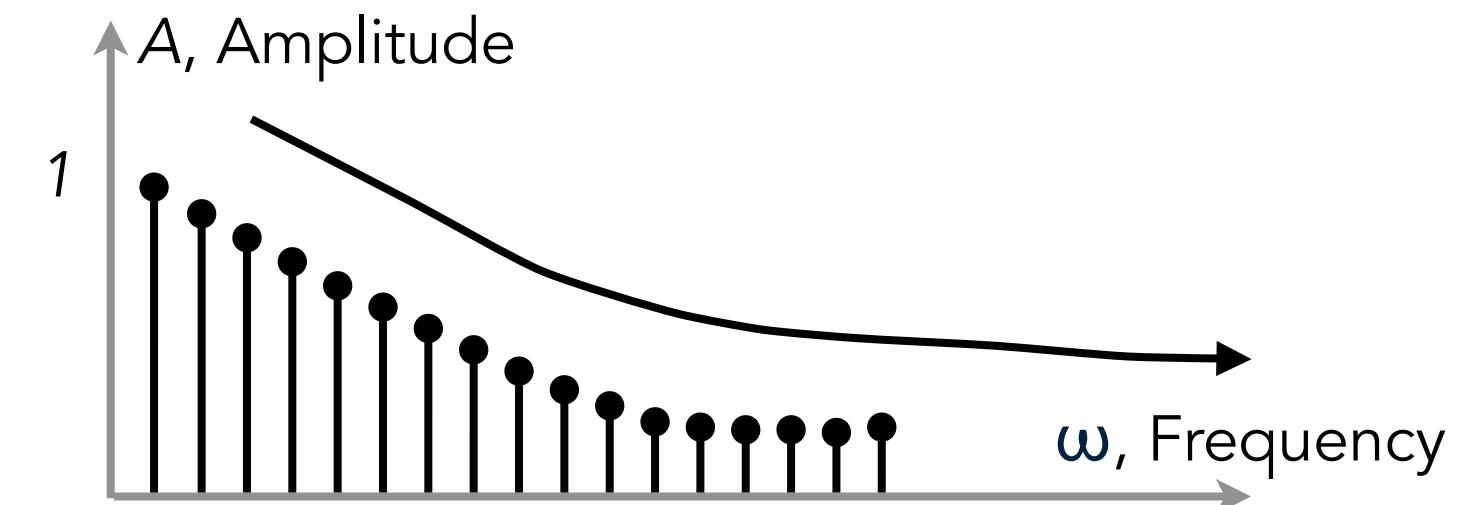
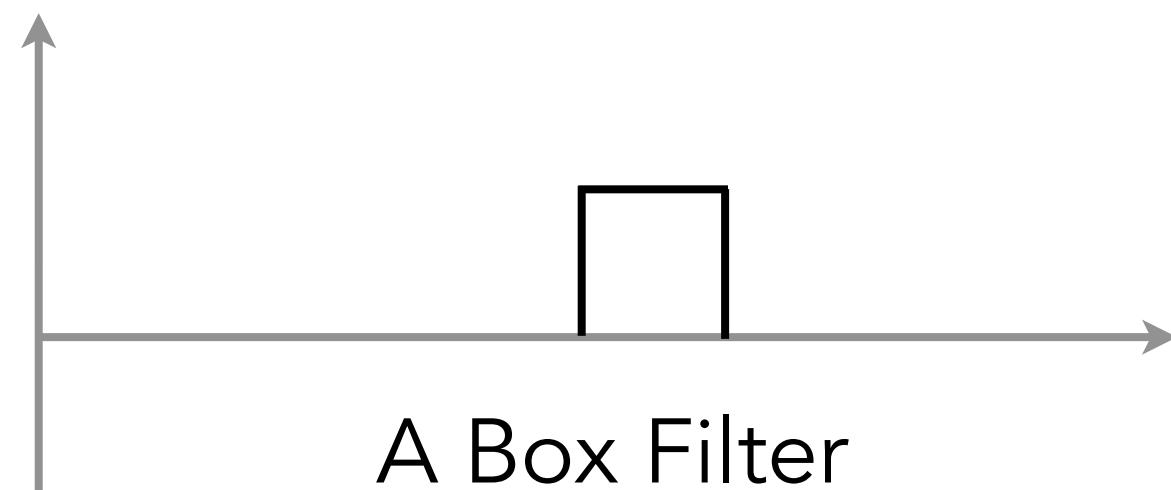
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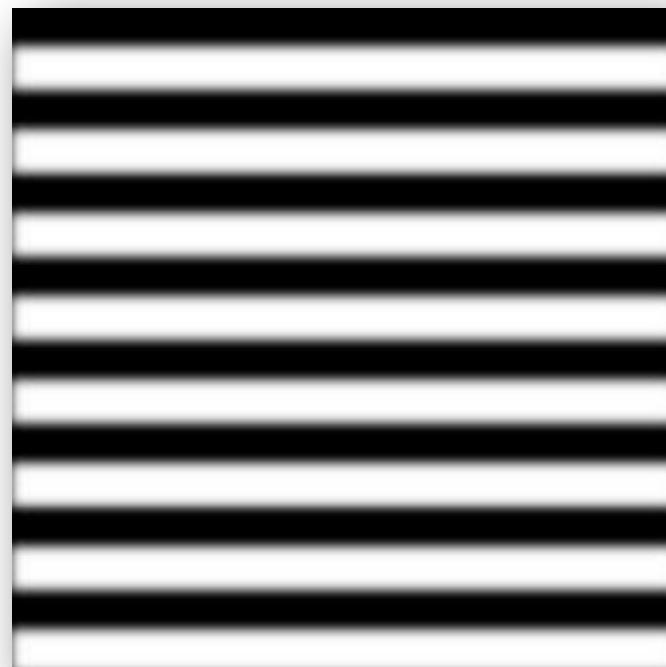
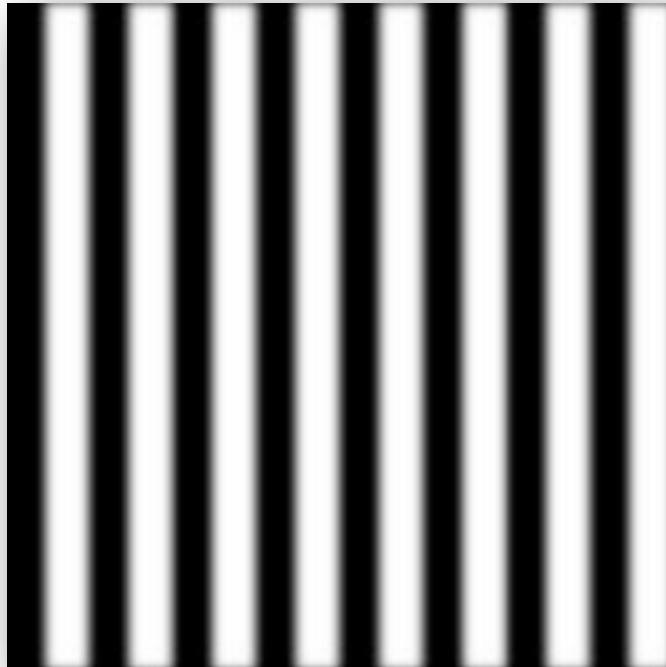
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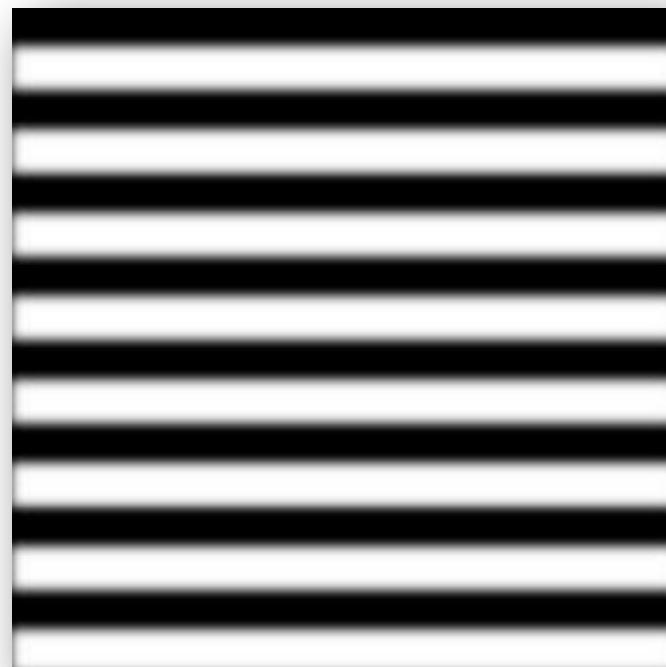
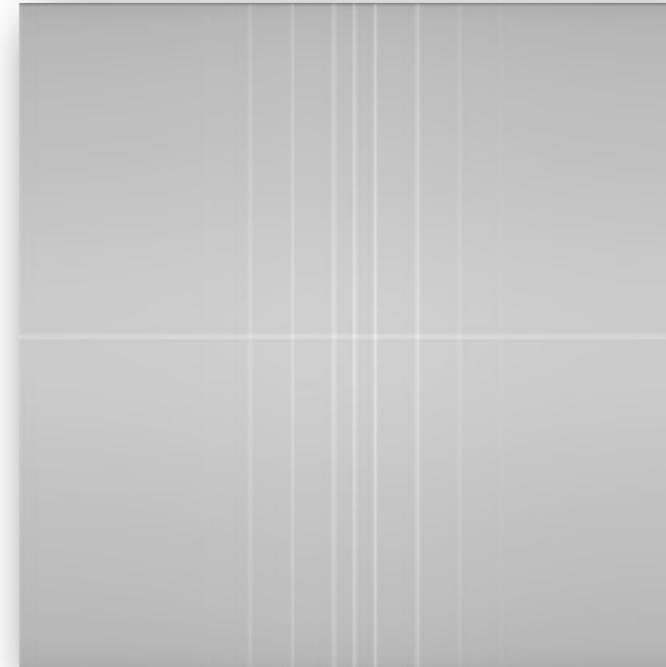
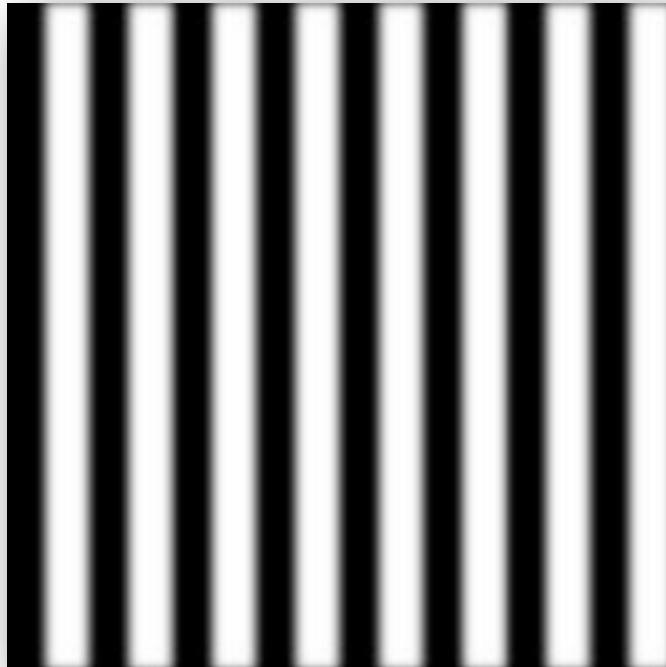
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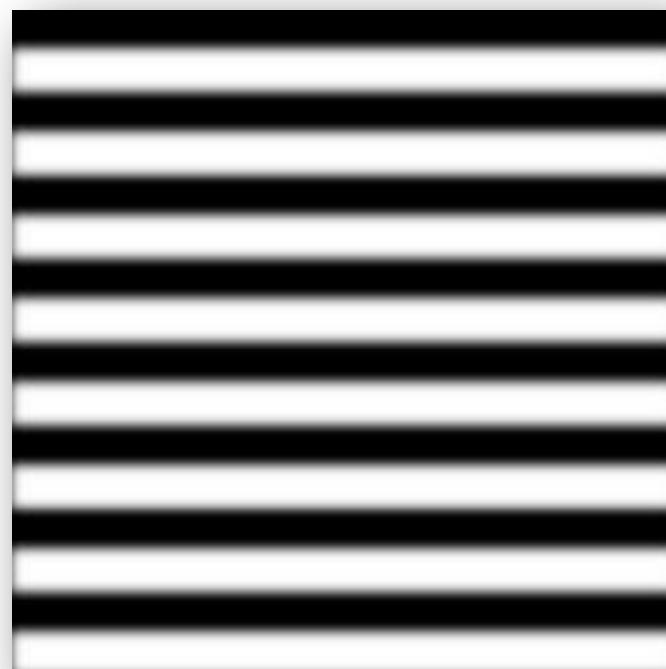
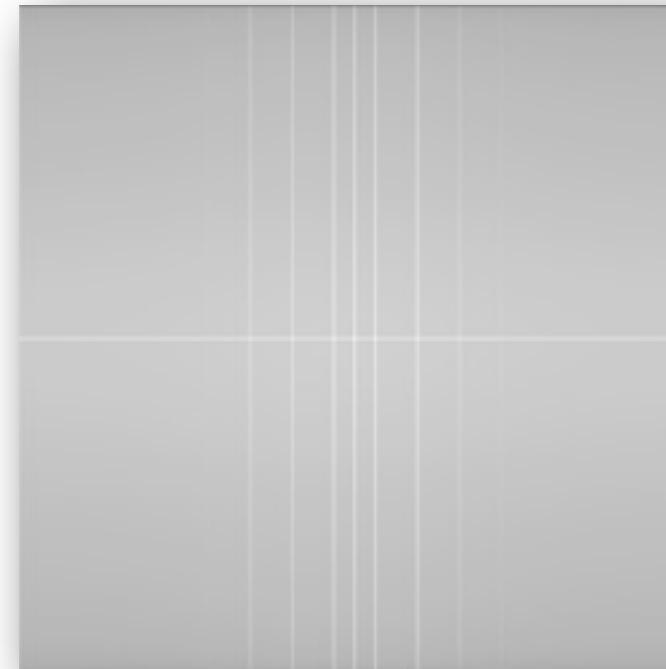
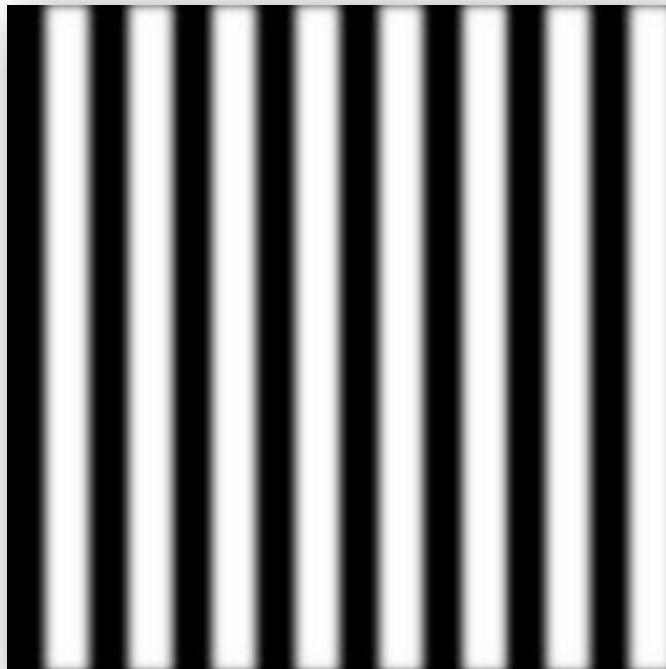
Now, Frequency Spectra for Images



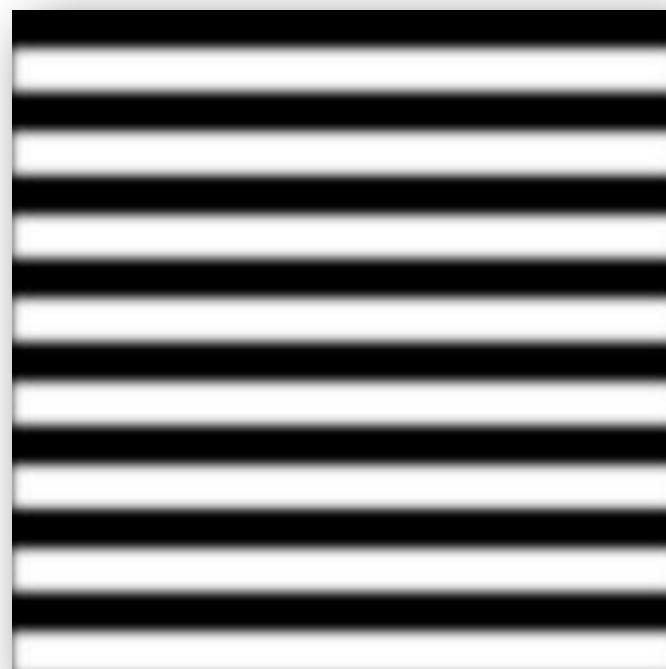
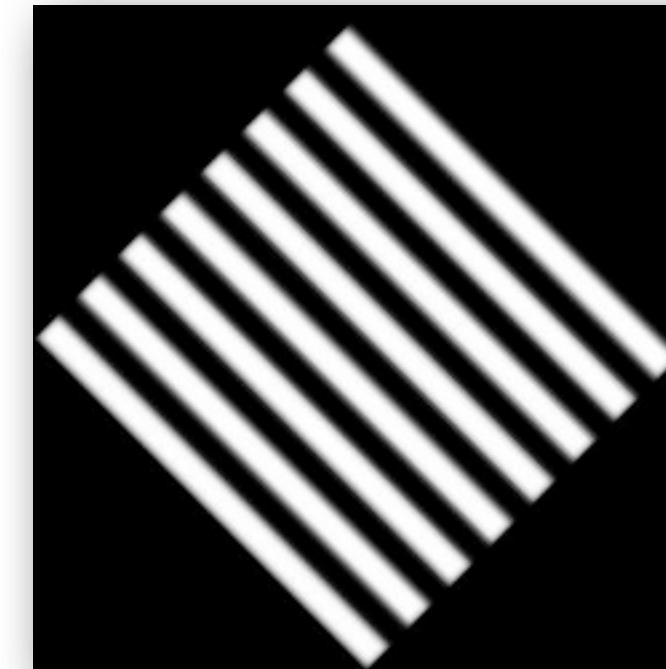
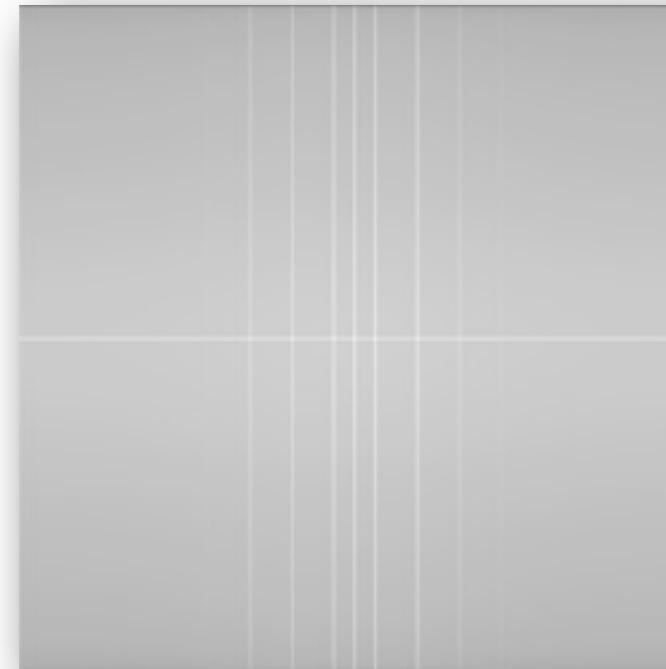
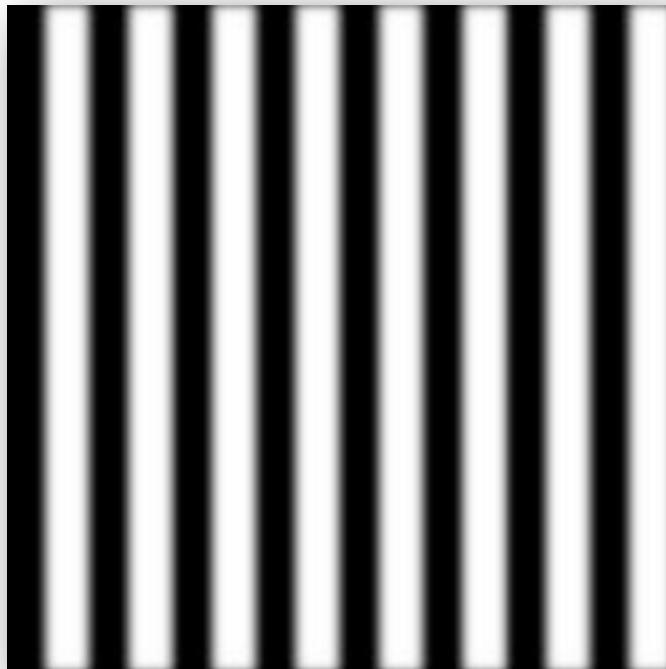
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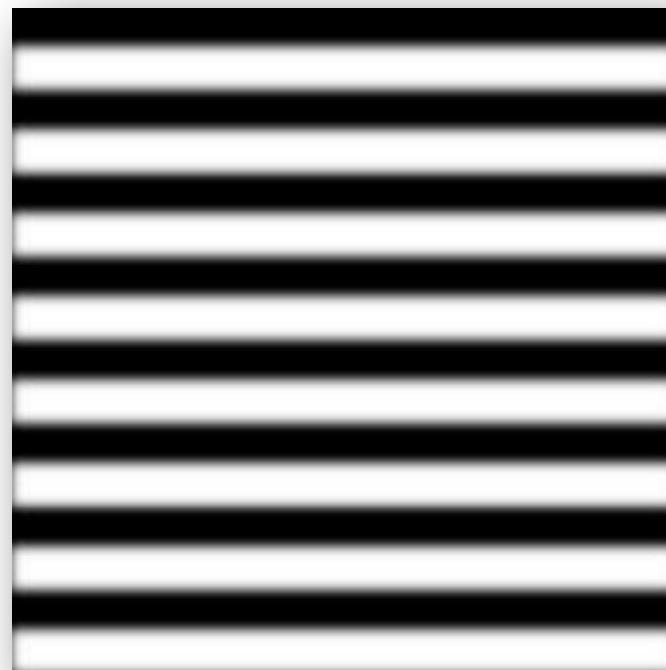
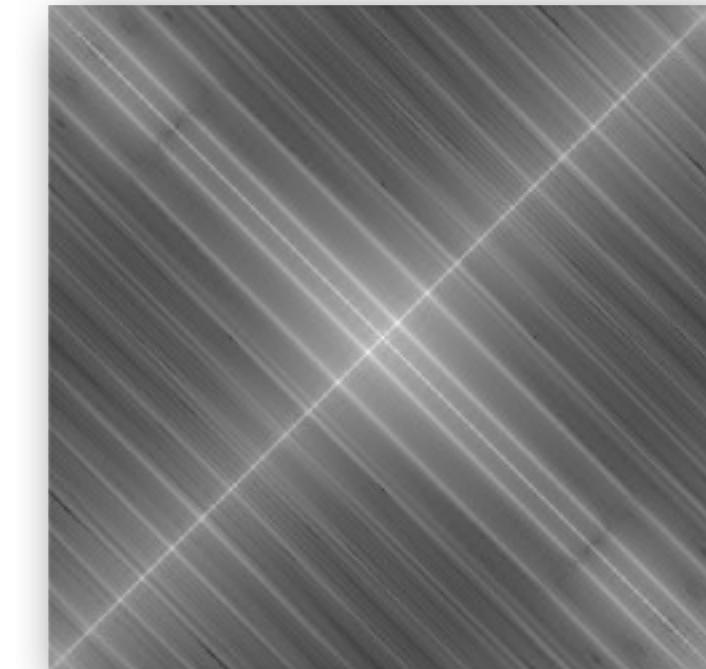
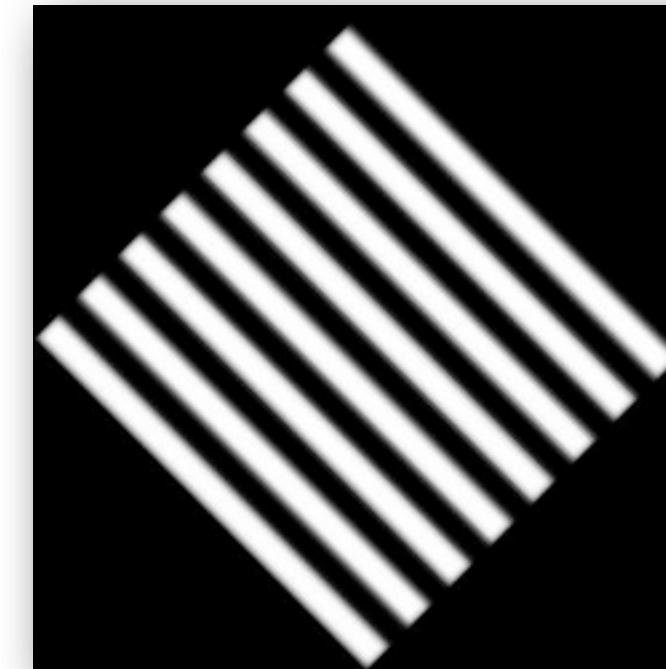
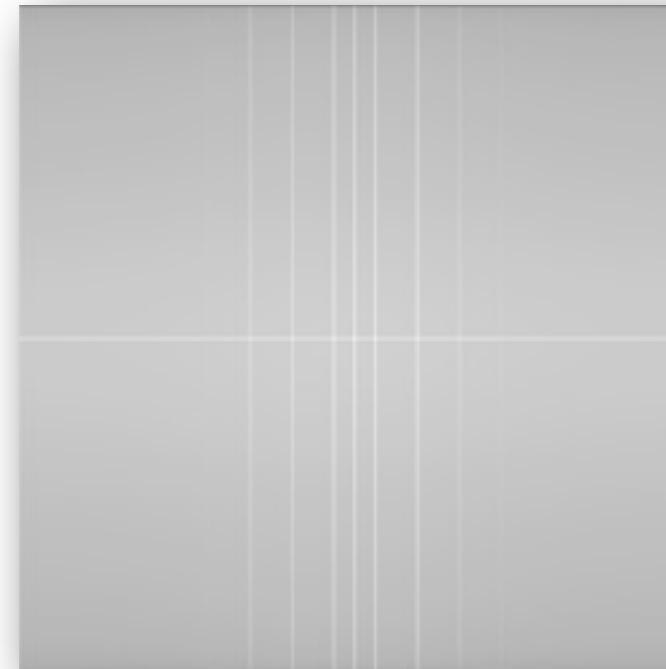
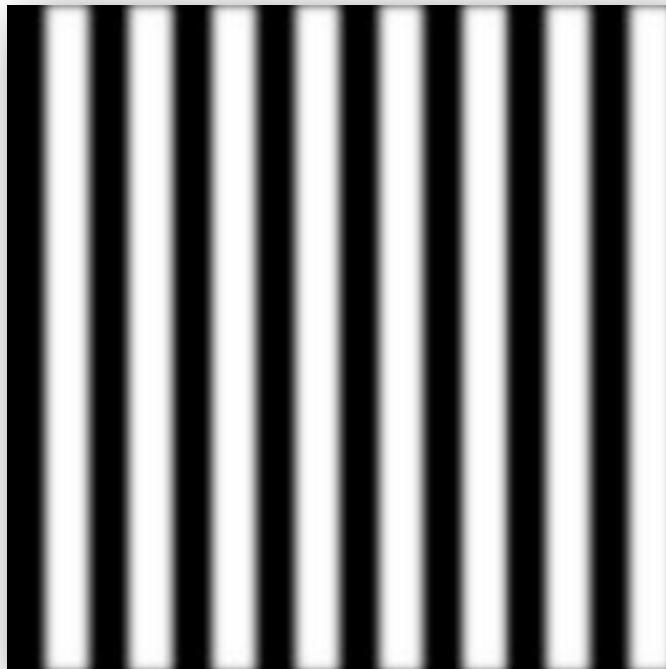
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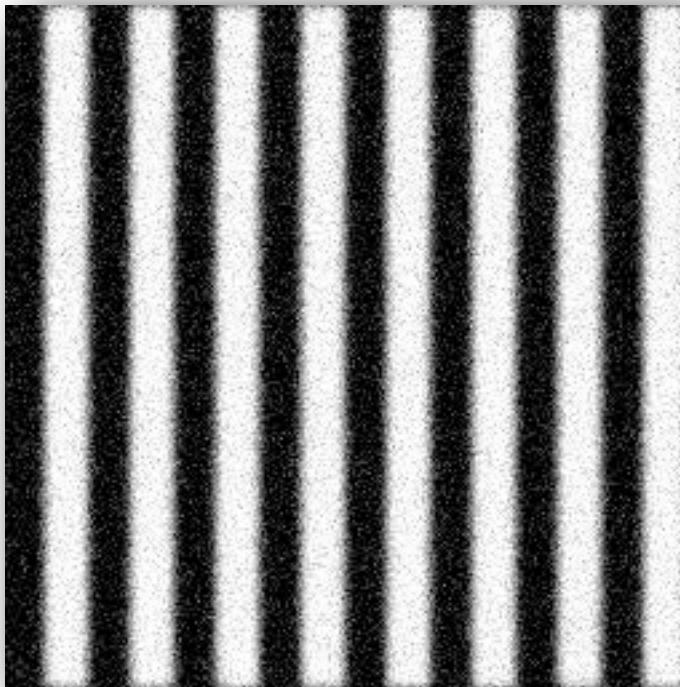
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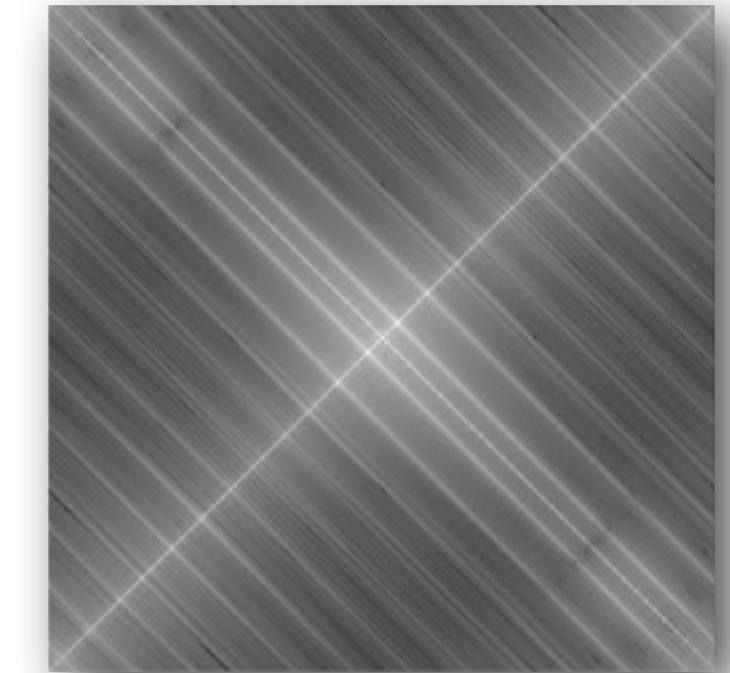
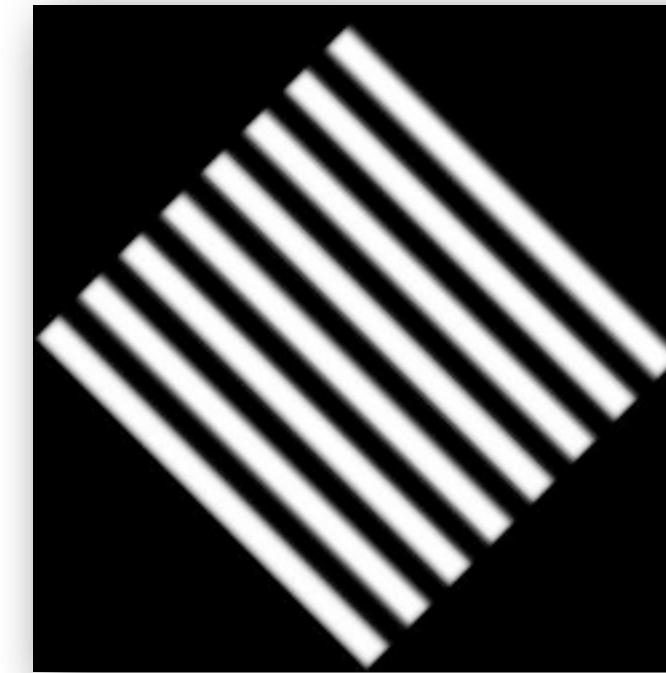
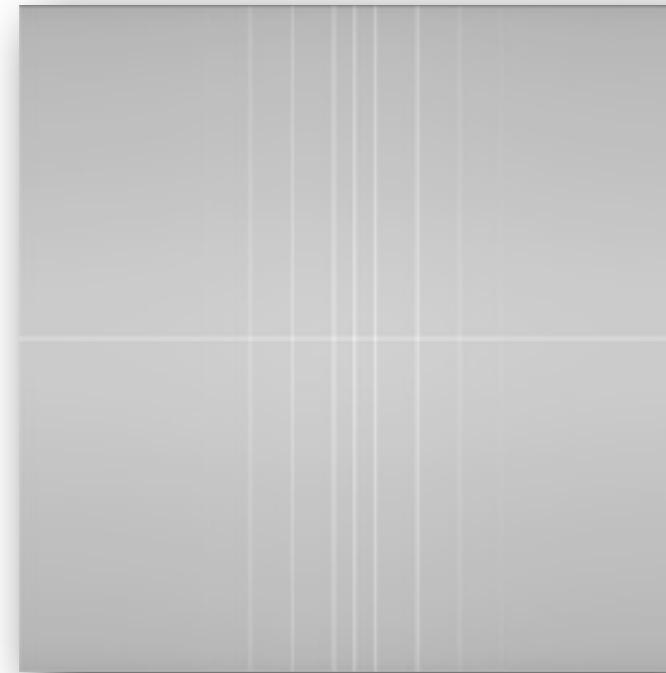
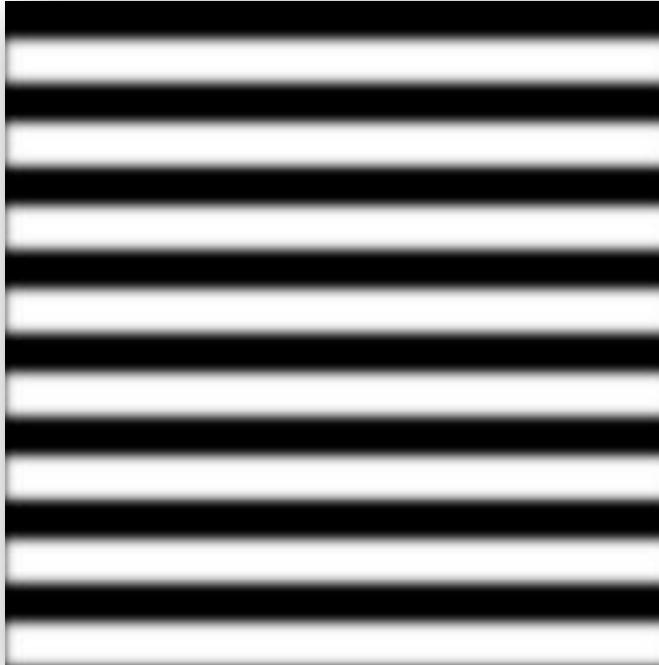
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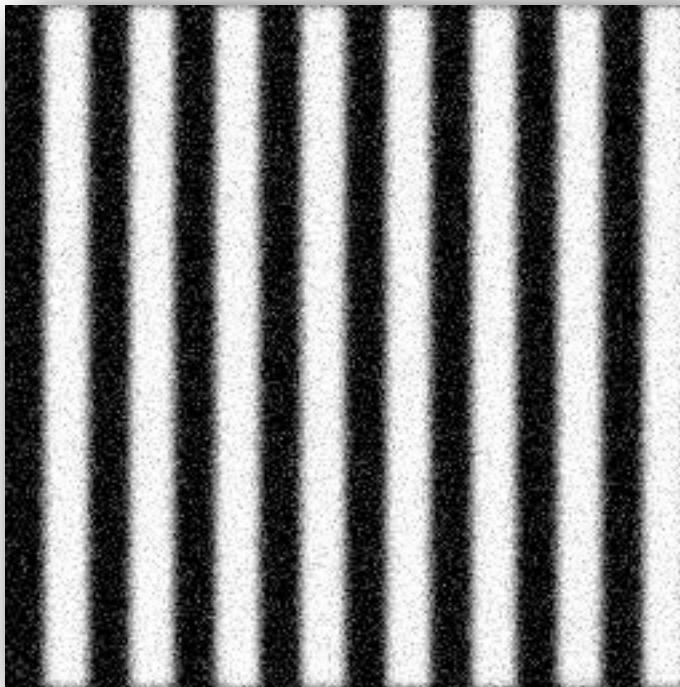
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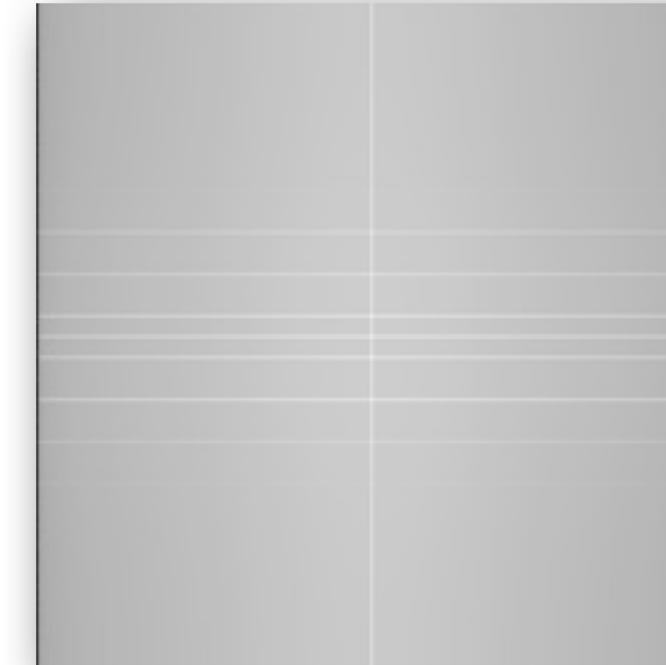
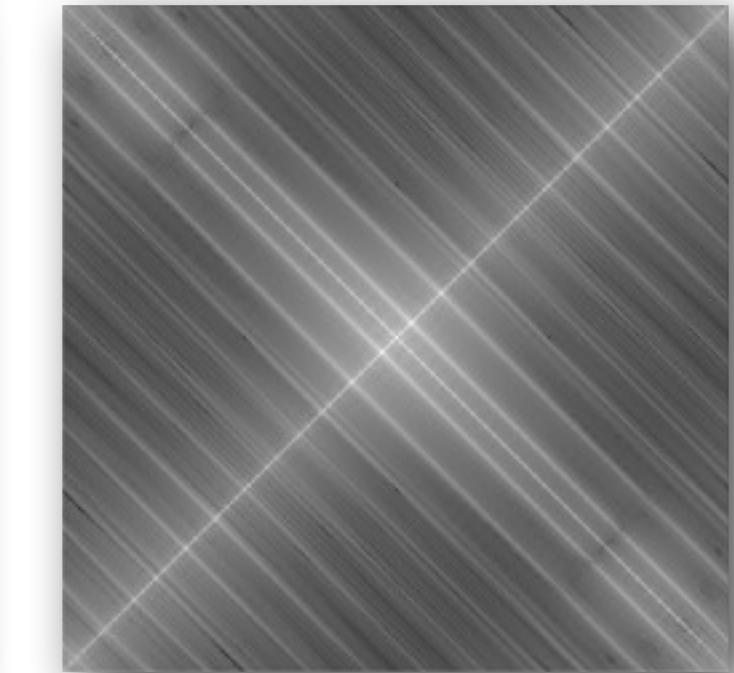
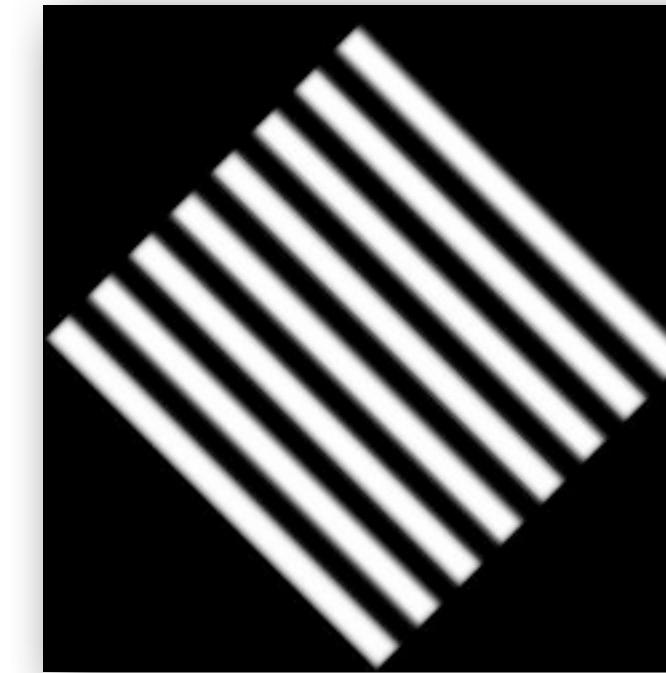
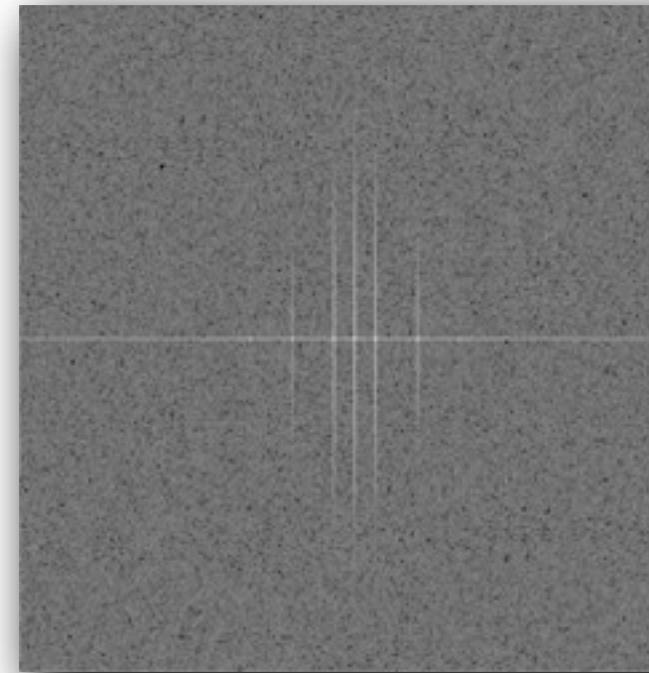
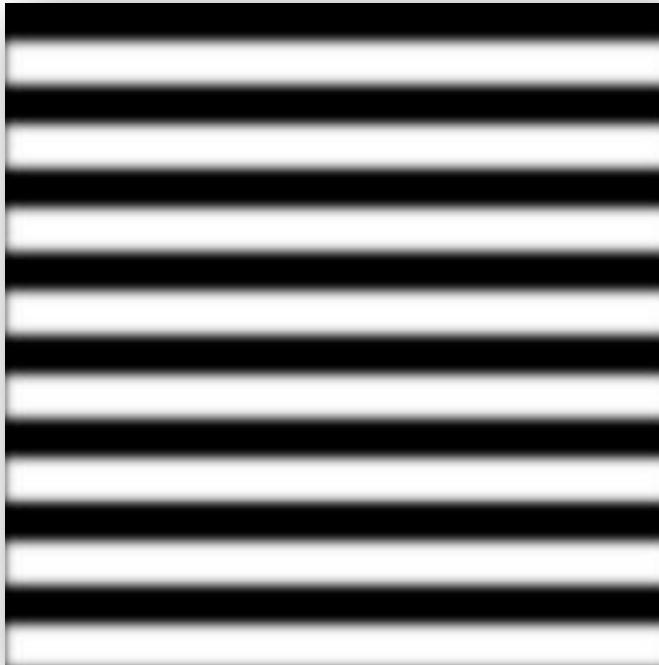
Noise Added



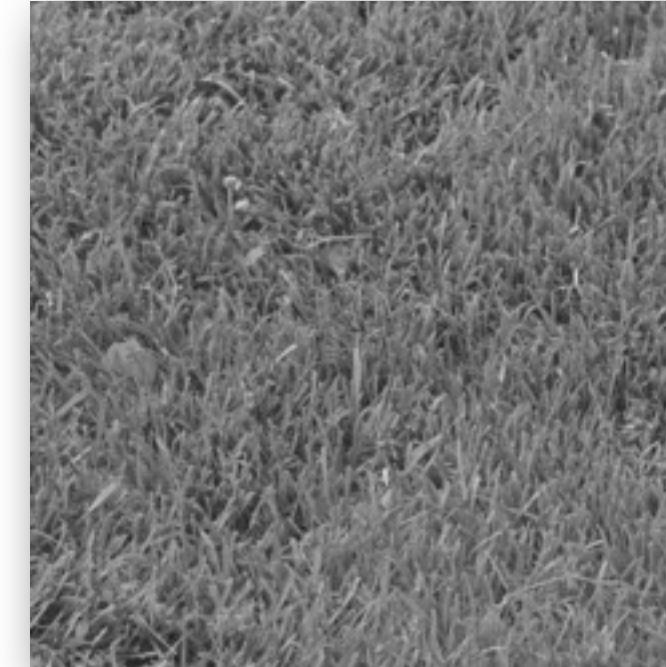
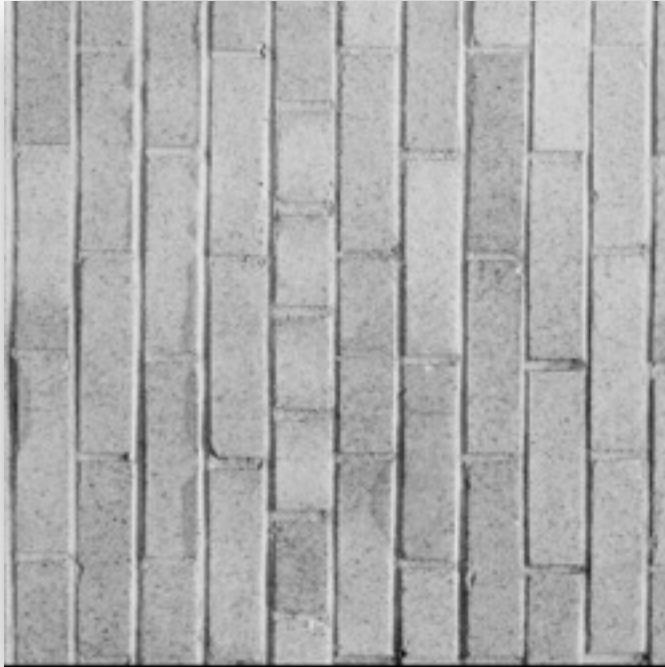
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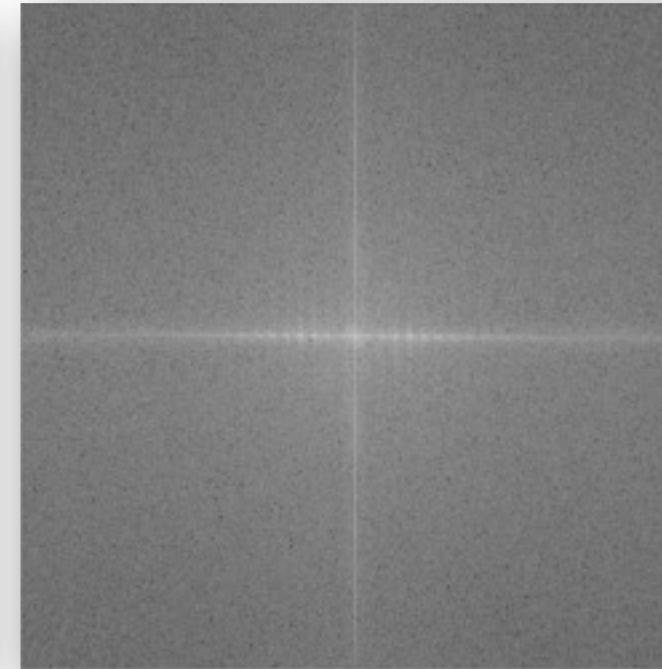
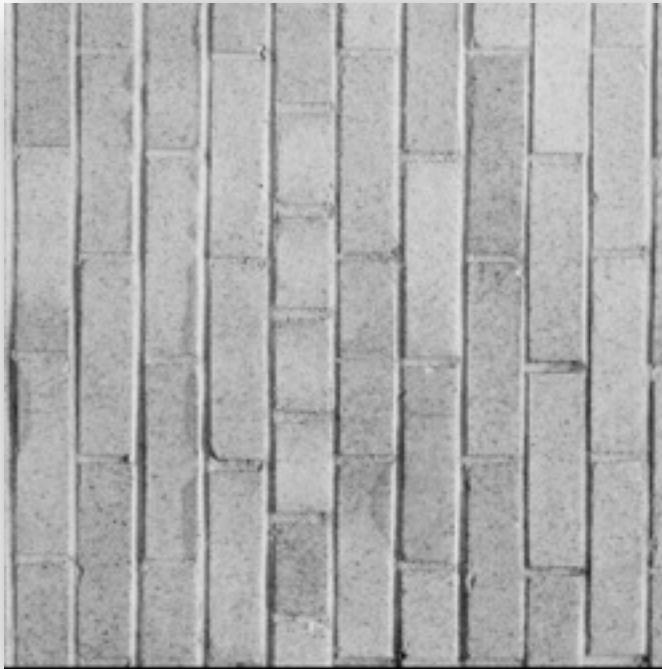
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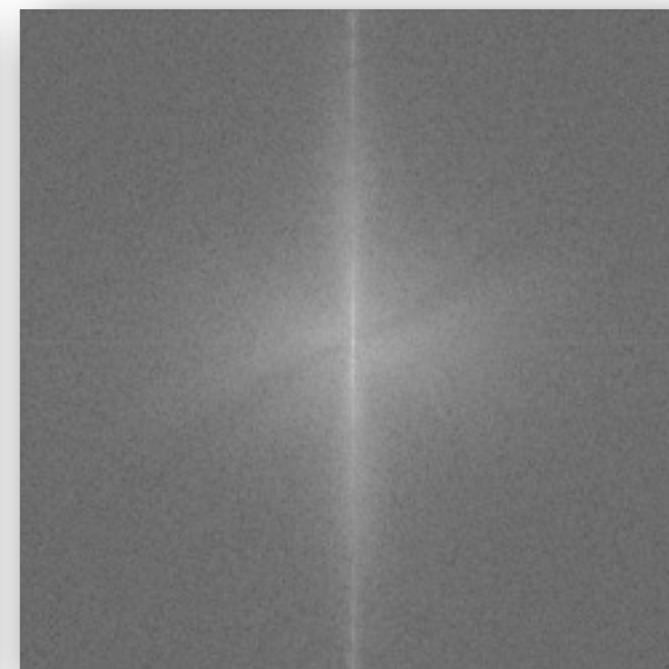
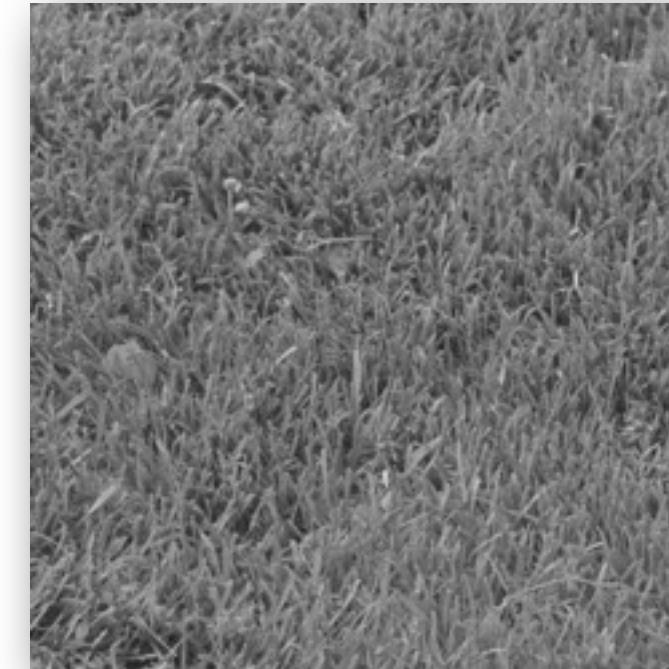
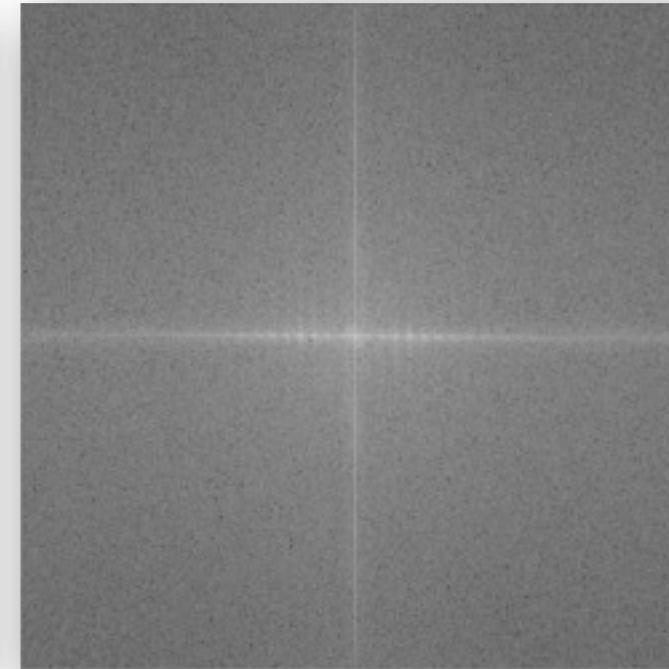
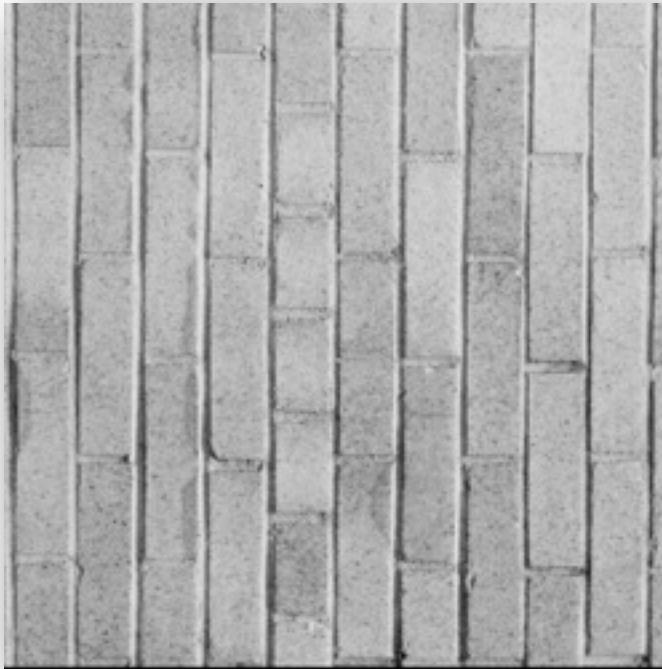
Frequency Spectra for Real Images



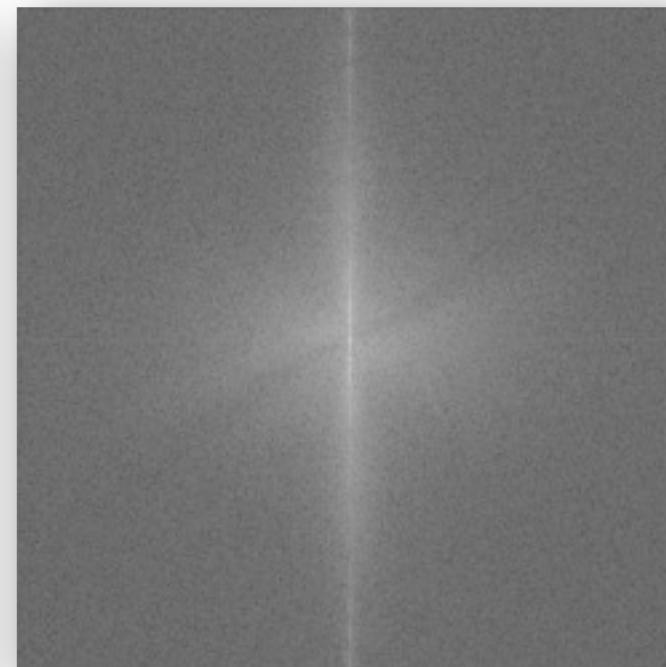
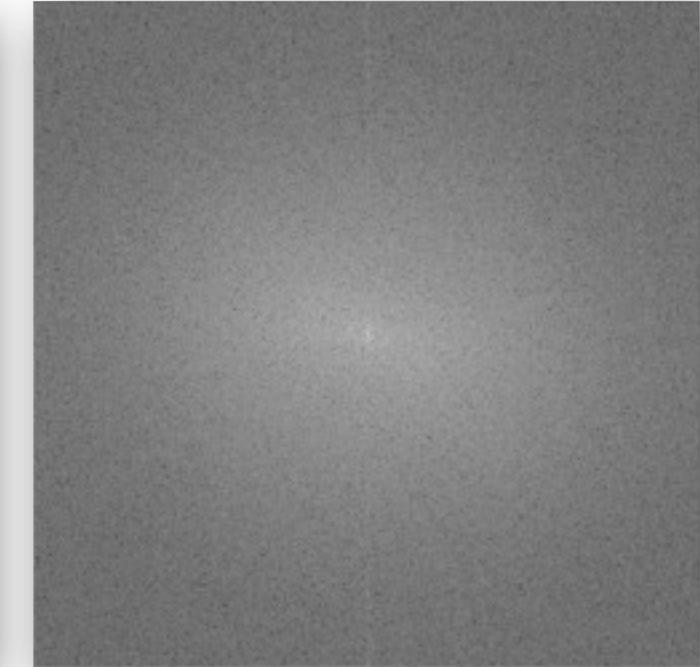
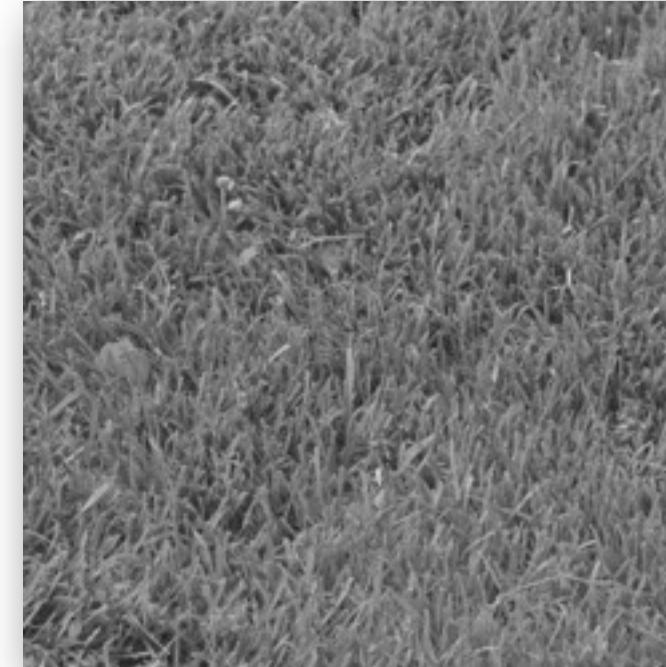
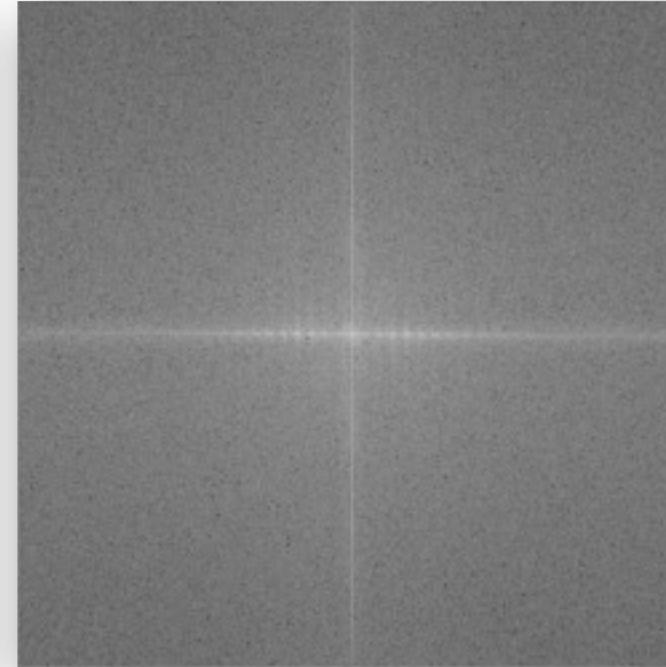
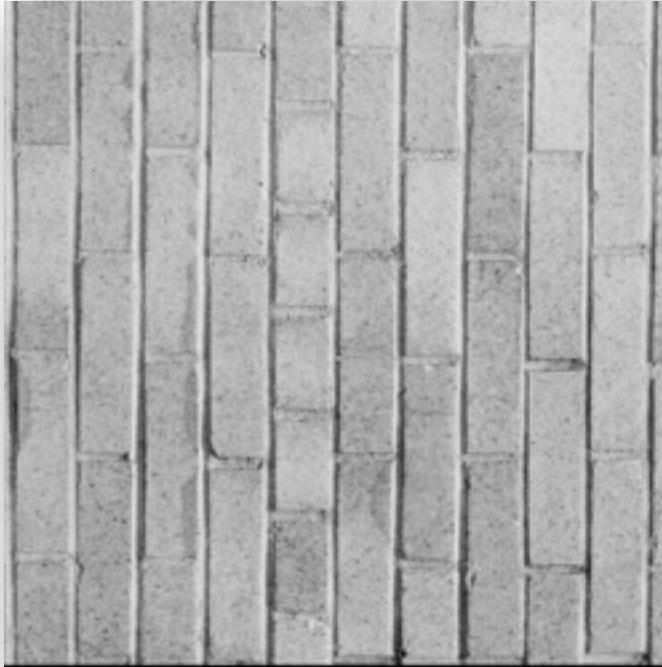
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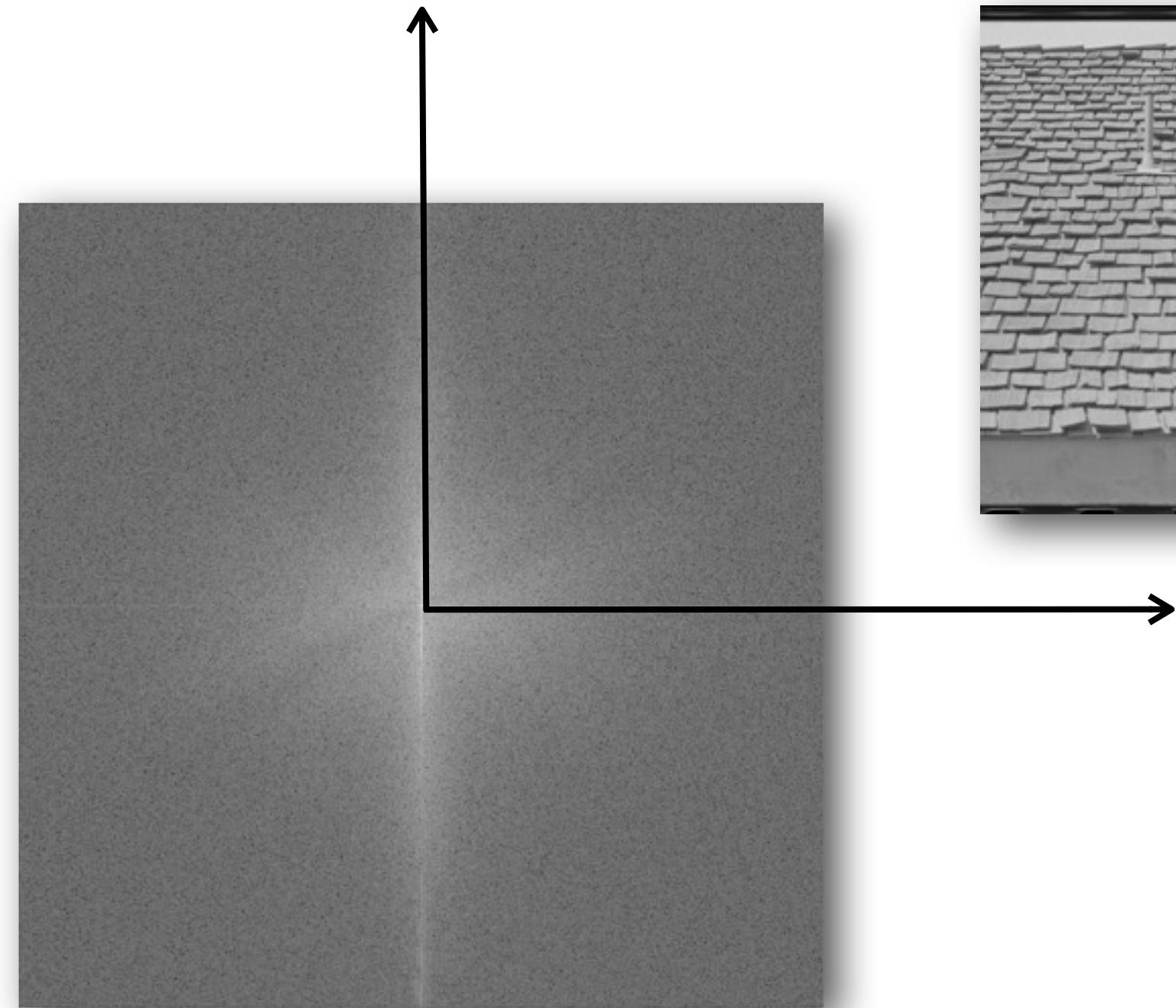
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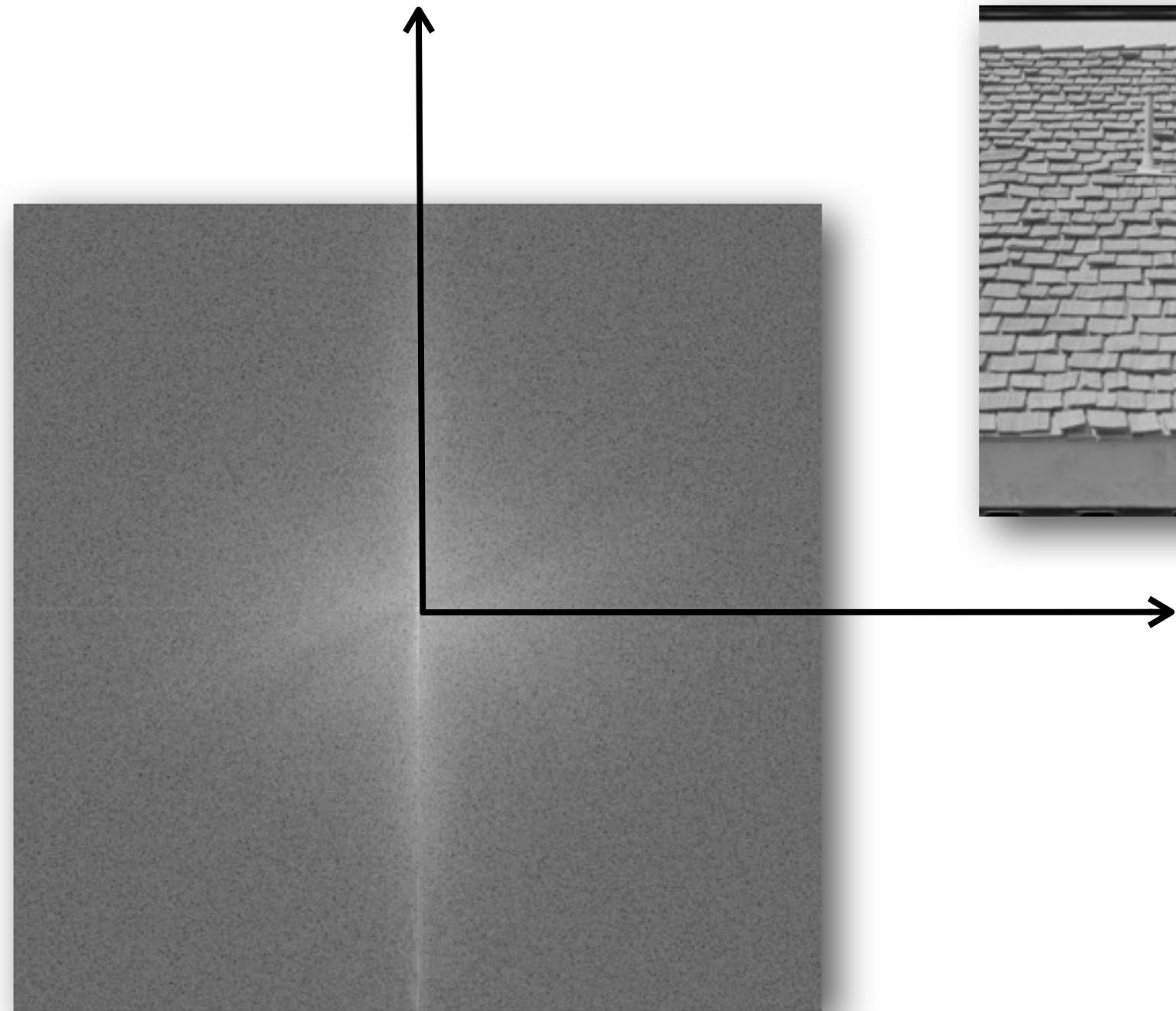


Fourier Transform: Some Observations



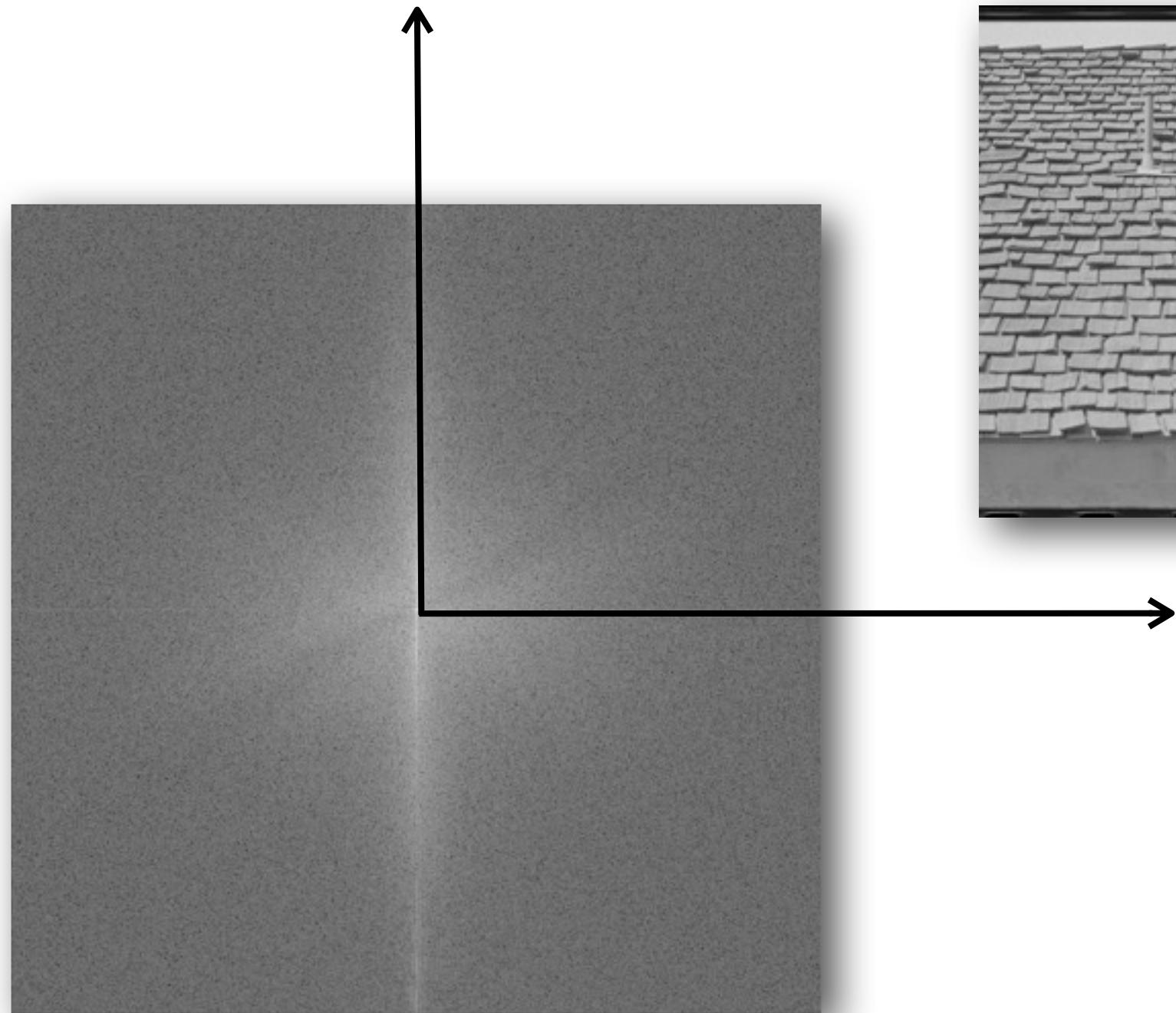
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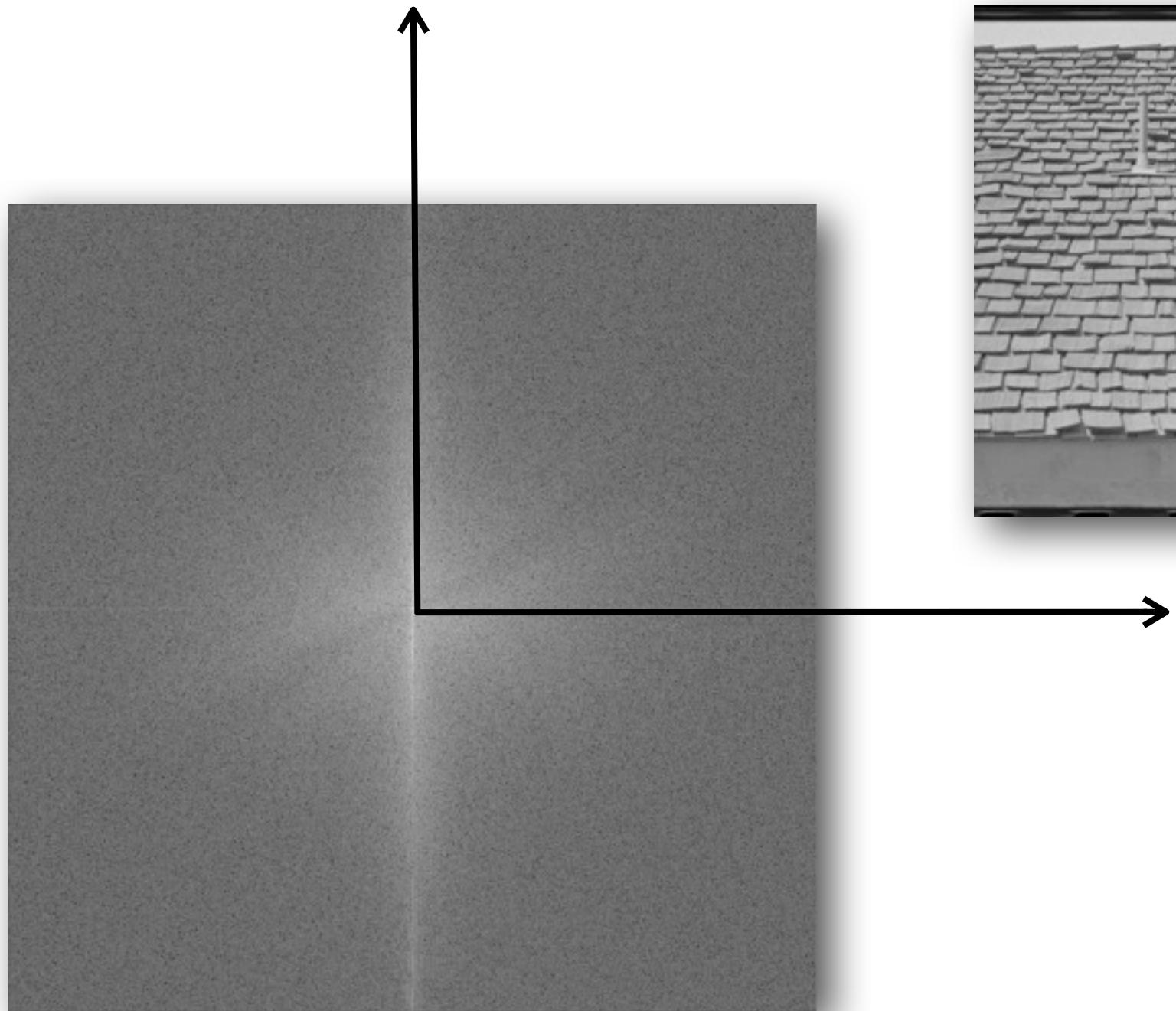
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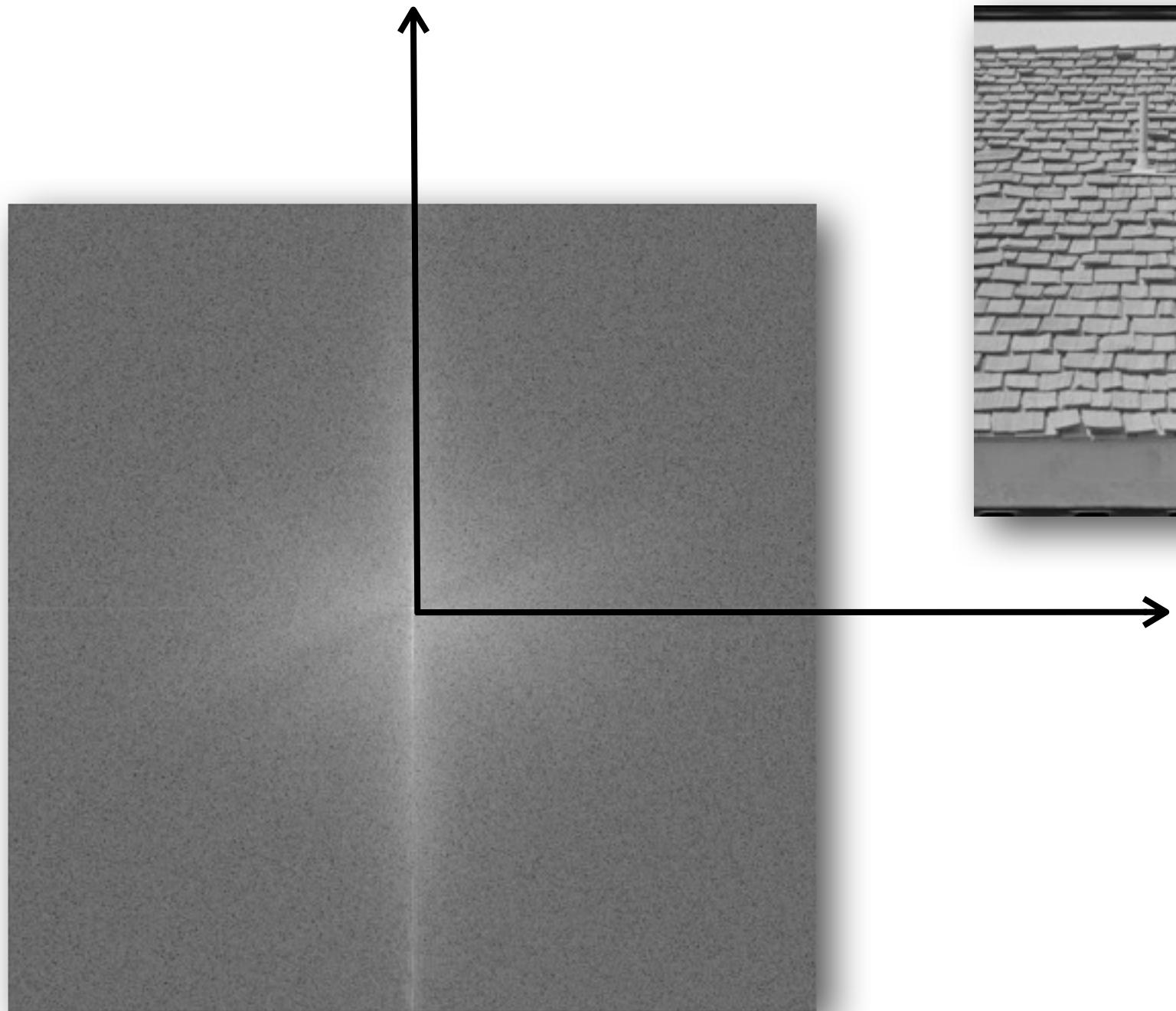


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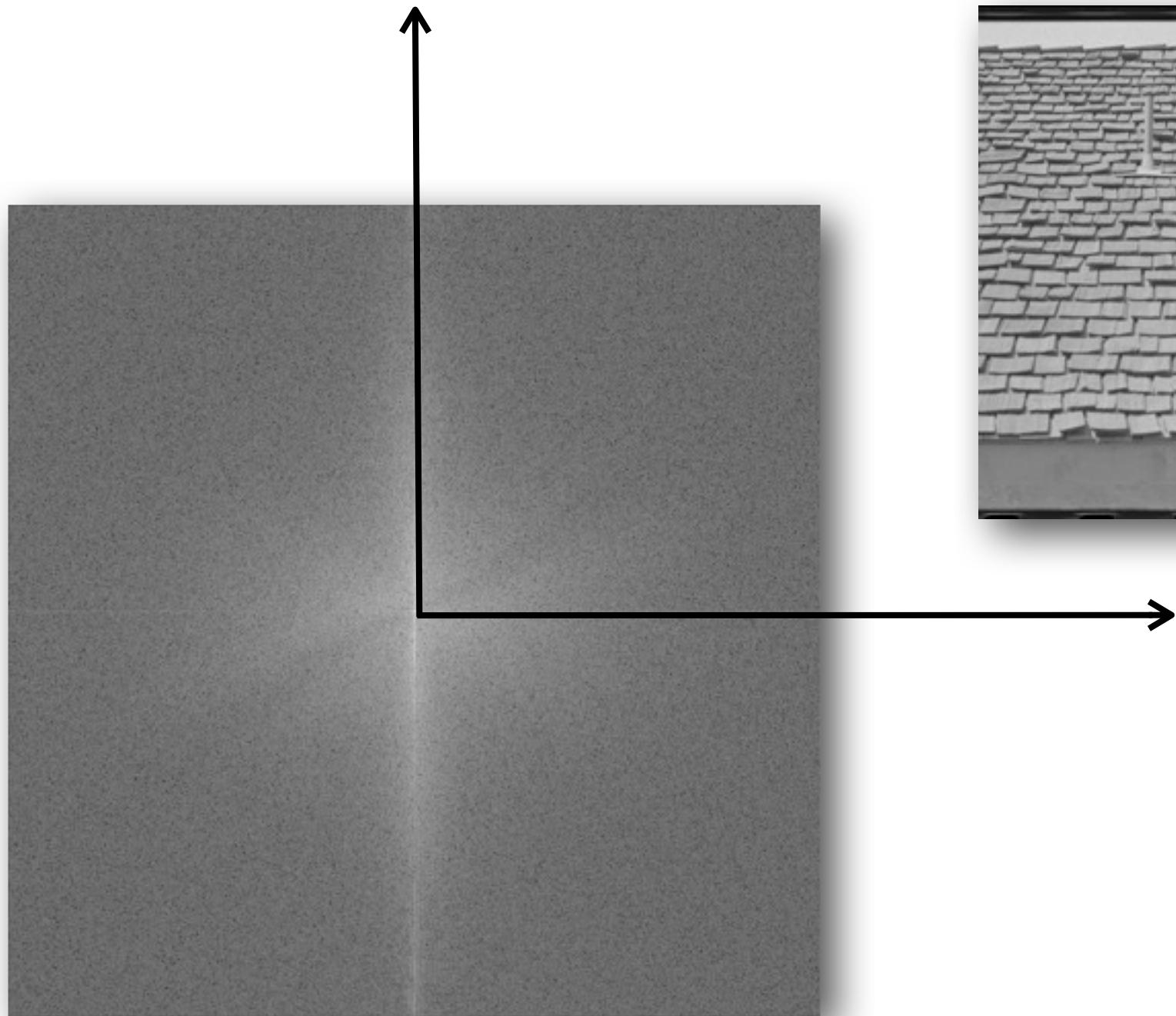
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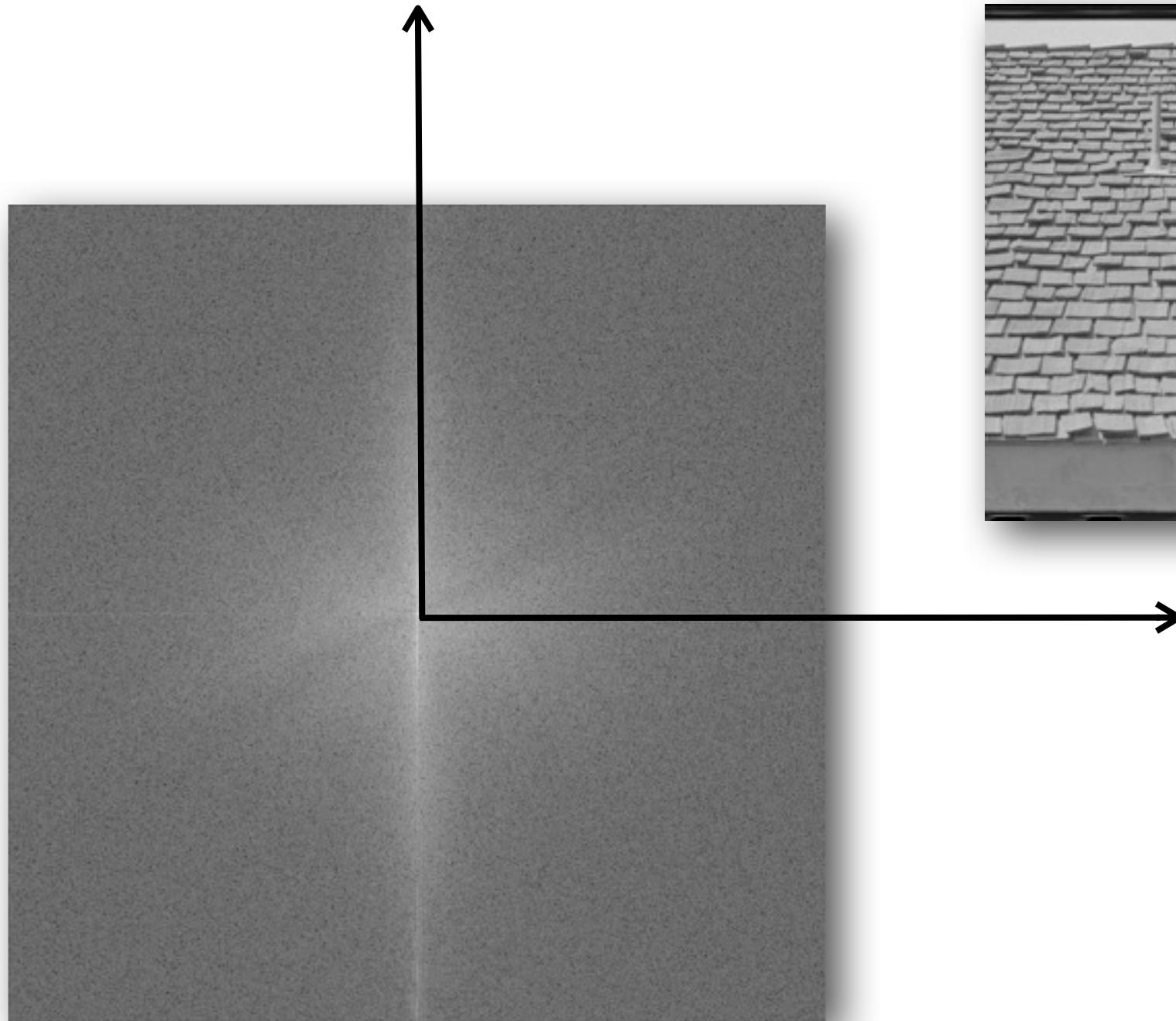
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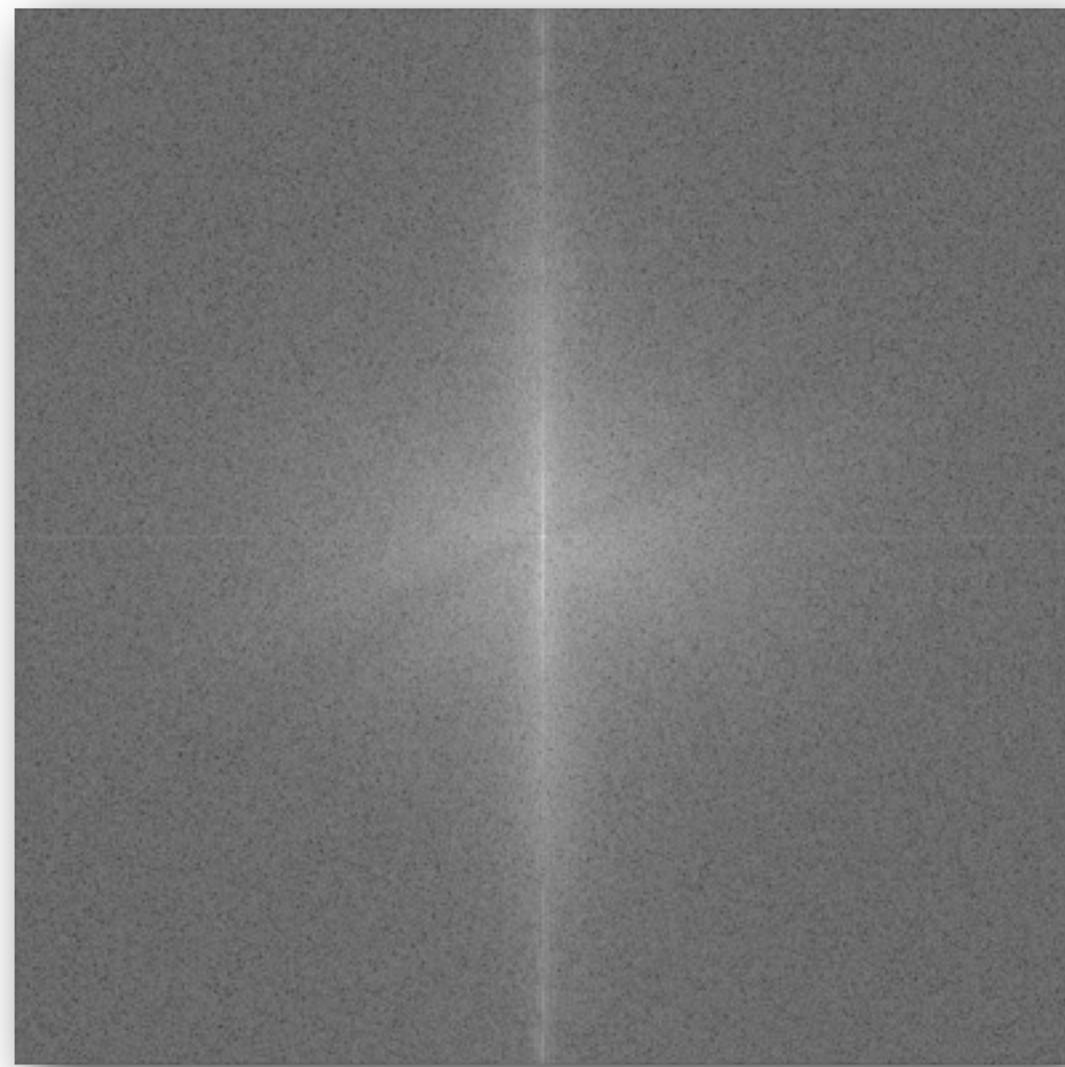
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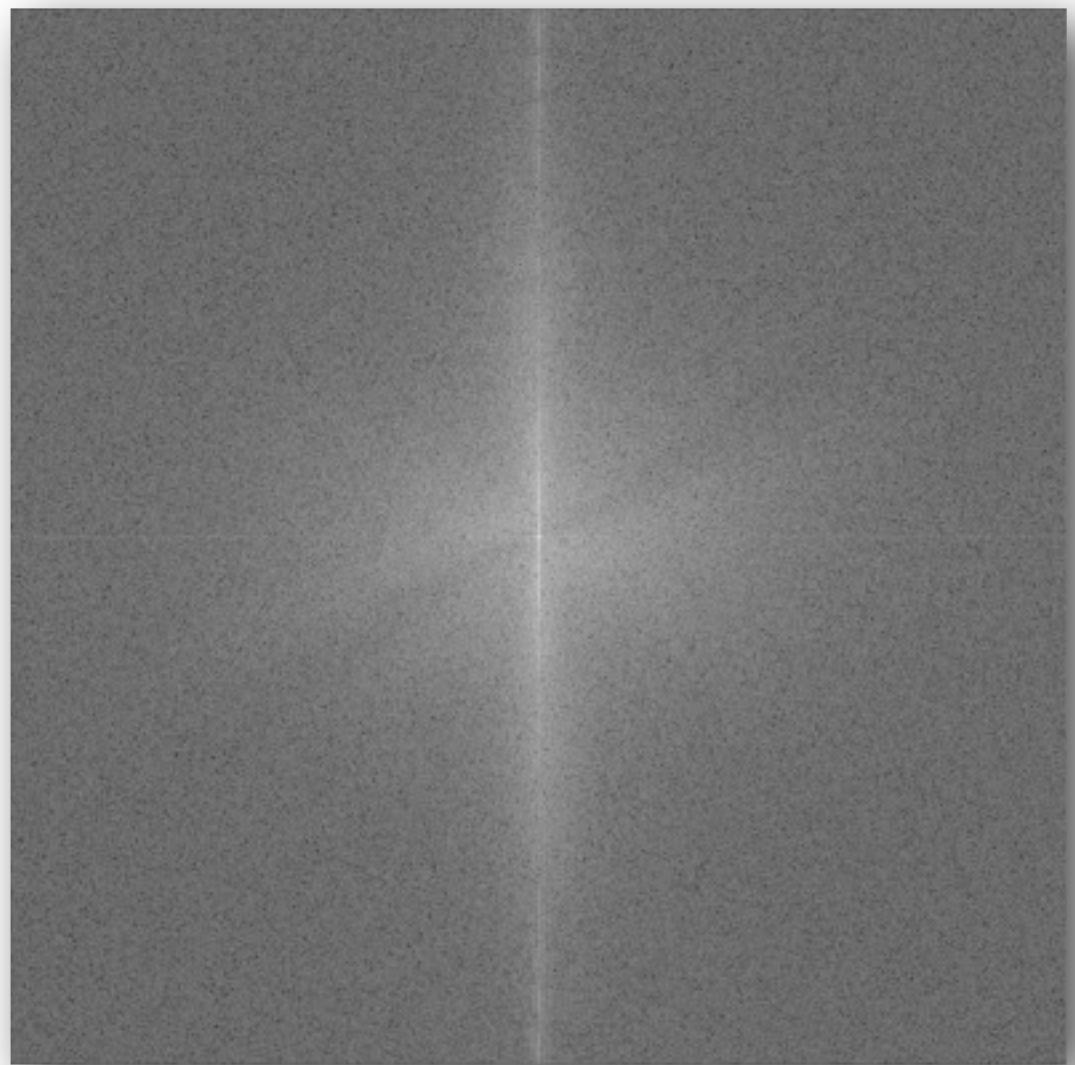


Using the Frequency Spectra



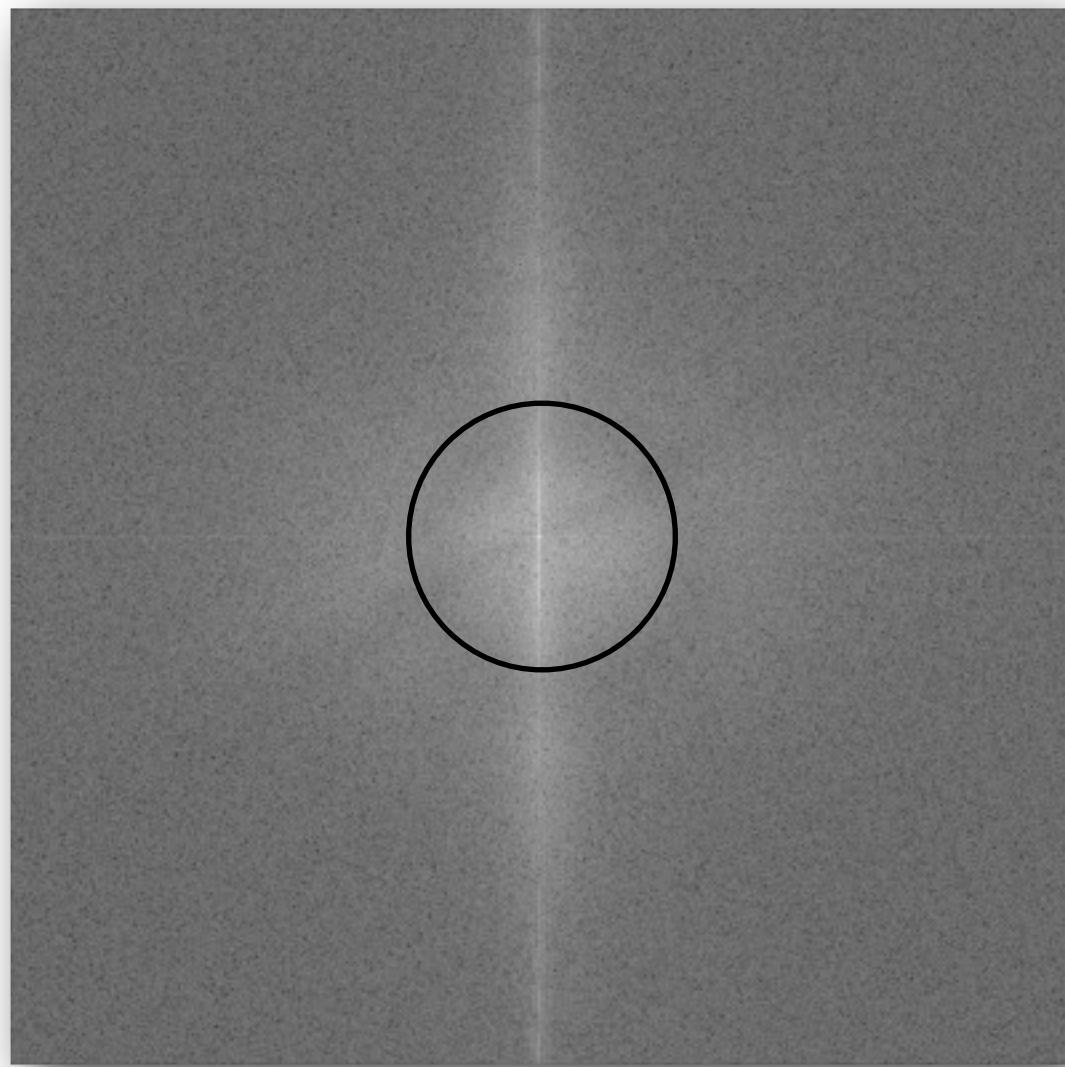
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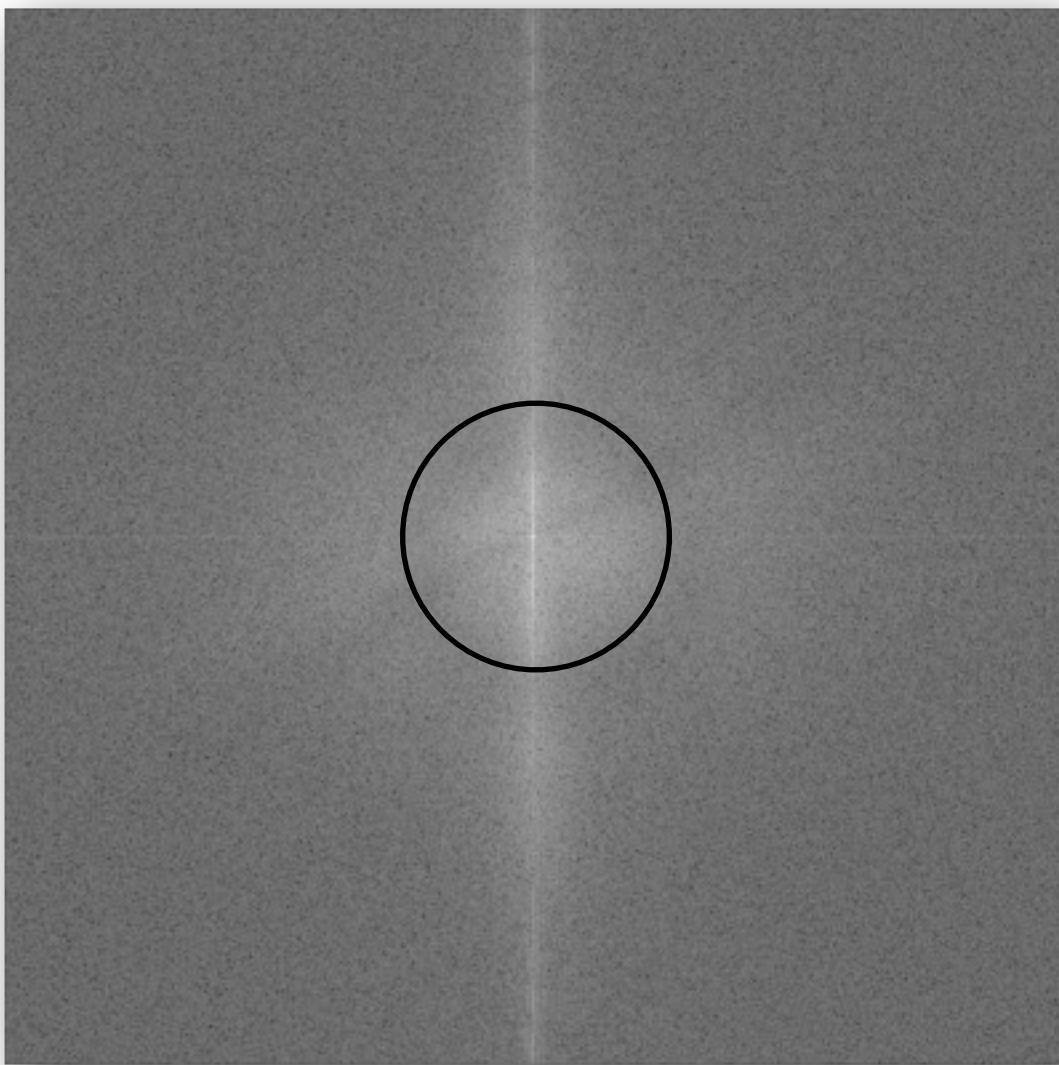
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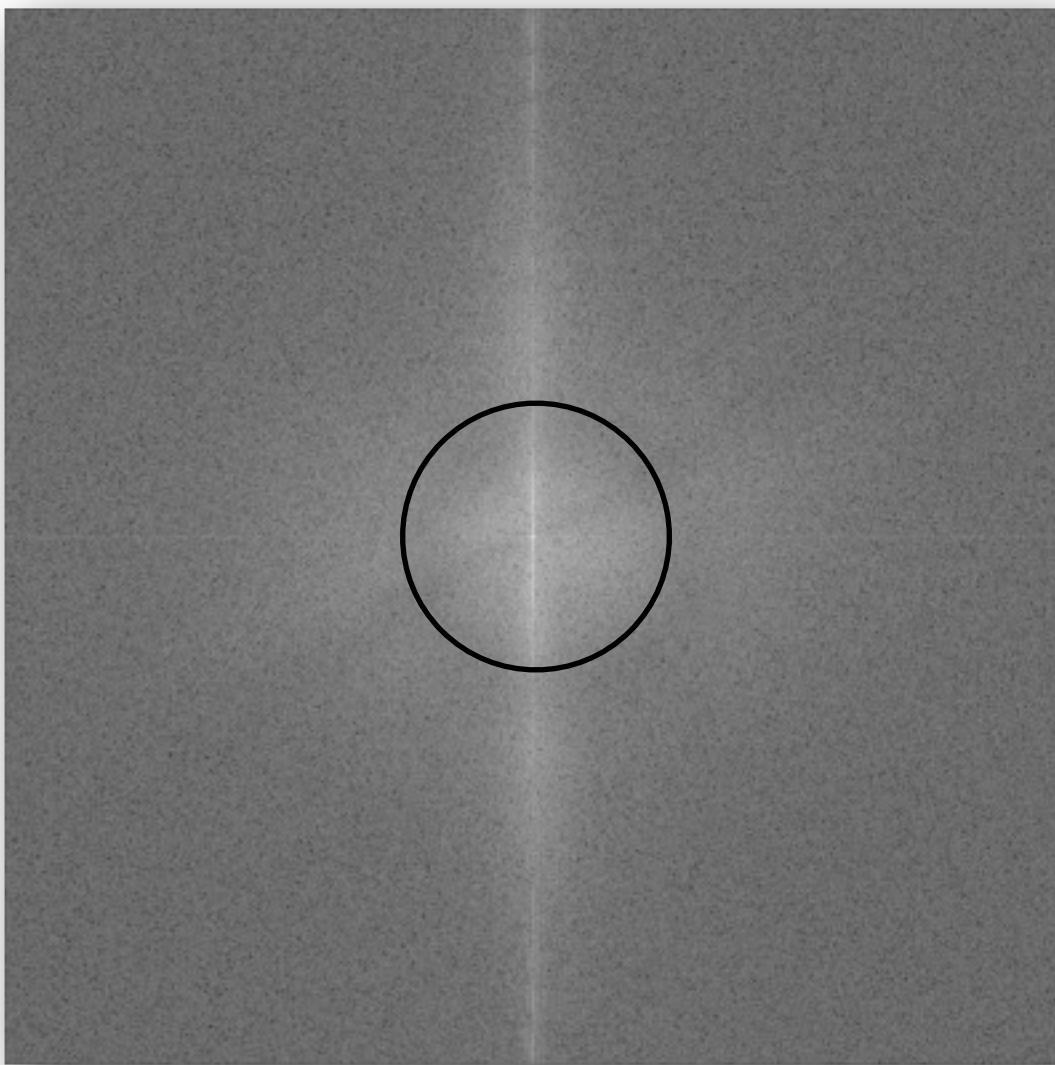
Using the Frequency Spectra

- ★ Low-pass,
- ★ High-Pass,



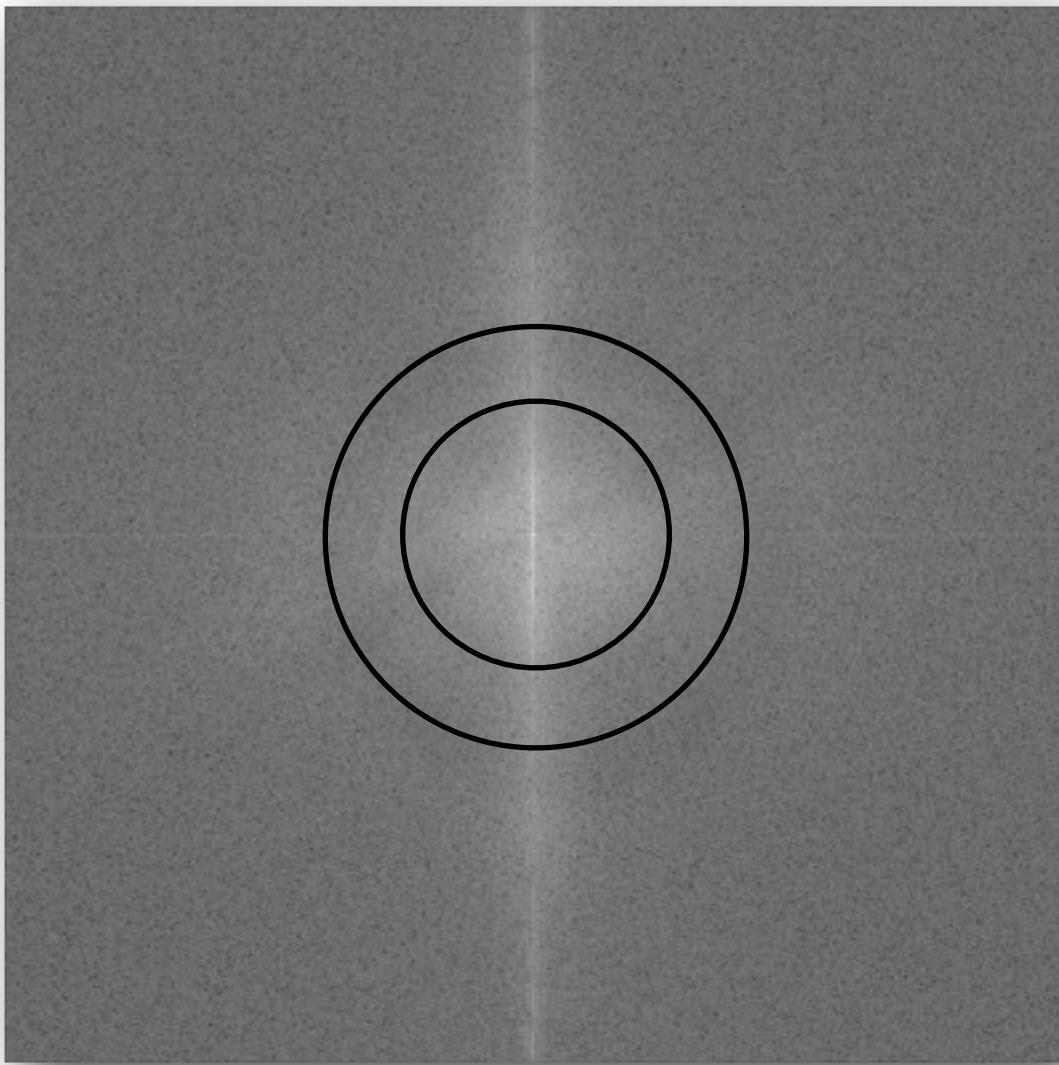
Using the Frequency Spectra

- ★ Low-pass,
- ★ High-Pass,
- ★ Band-pass Filtering



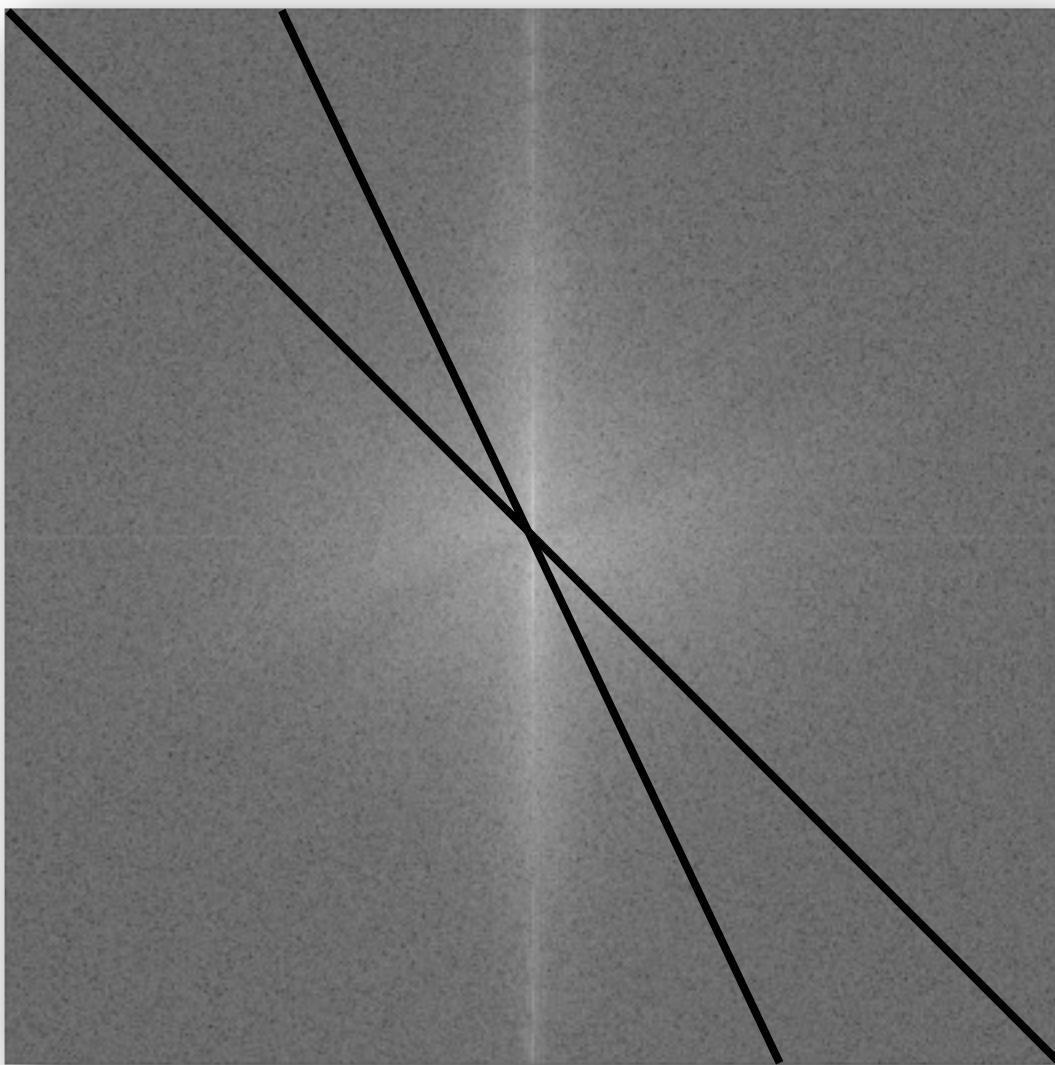
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Using the Frequency Spectra

- ★ Low-pass,
- ★ High-Pass,
- ★ Band-pass Filtering
- ★ Change the spectrum and reconstruct



Blurring and Frequencies



Original Image



Gaussian 5x5 Blur



Smooth - Original

Summary

- ★ Introduced how sines and cosines can be used to reconstruct a signal.
- ★ Characterized the Fourier Transform using terms like Frequency, Amplitude and Phase.
- ★ Introduced the Frequency Domains for a Signal.
- ★ Identified the three (3) properties of Convolution as it is associated with the Fourier Transform.



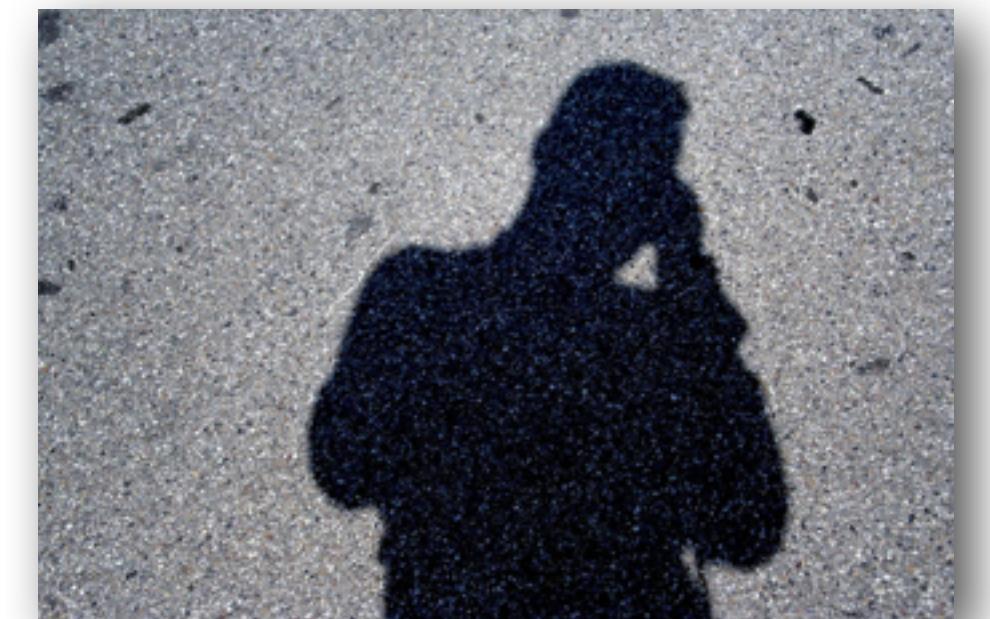
Next Class

★ Merging and Blending of Images



Credits

- ★ For more information, see
 - Richard Szeliski (2010) Computer Vision: Algorithms and Applications, Springer.
 - Forsyth & Ponce (2012), Computer Vision: A Modern Approach, Pearson.
- ★ Some concepts in slides motivated by similar slides by A. Efros and J. Hays.
- ★ Some images retrieved from
 - <http://commons.wikimedia.org/>.
 - List will be available on website.



www.flickr.com/photos/neneonline/231886965/



Computational Photography



Dr. Irfan Essa

Professor

School of Interactive Computing

Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.