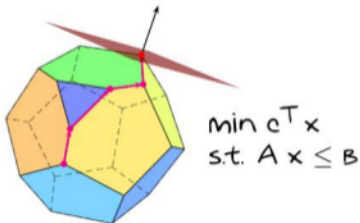


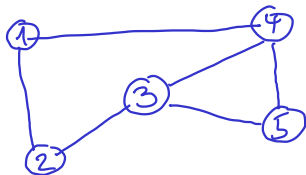
How efficient is the simplex method?

- ▶ Graphs of polyhedra
- ▶ and their diameter



Graphs

An *undirected graph* $G = (V, E)$ consists of a finite set V of *nodes* or *vertices* and a set E of *edges*, where each edge $e \in E$ is a two-element subset of vertices, $e = \{u, v\}$, $u \neq v \in V$. We also write $e = uv$.

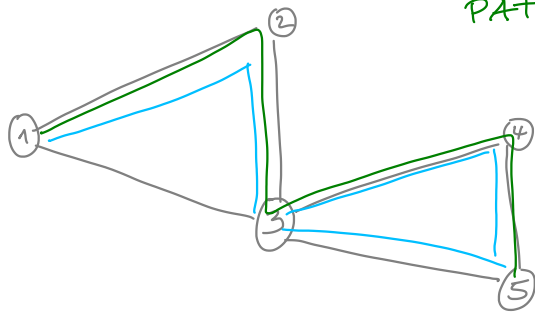


$$V = \{1, 2, 3, 4, 5\}$$

$$E = \{\{1, 2\}, \{1, 4\}, \{2, 3\}, \{3, 4\}, \{3, 5\}, \{4, 5\}\}$$

Walks and paths

A **walk** from node $i_1 \in V$ to $i_t \in V$ is a sequence i_1, i_2, \dots, i_t of nodes such that $i_k i_{k+1} \in E$, $k = 1, \dots, t-1$. A walk is called a **path** if it has no repeated nodes.



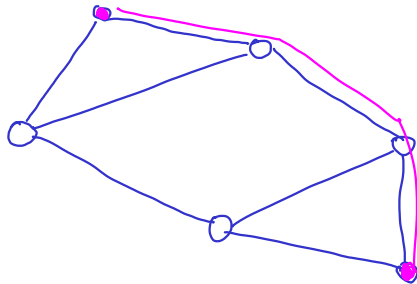
PATH: 1, 2, 3, 4, 5

WALK: 1, 2, 3, 5, 4, 3

Distance and diameter

The *distance* of $u, v \in V$ is the smallest t such that there exists a path i_0, \dots, i_t in G with $i_0 = u$ and $i_t = v$.

The *diameter* of G is the largest distance of two nodes of G .

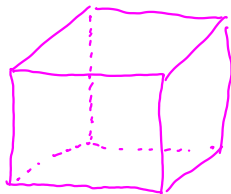


What is the diameter of
this graph?

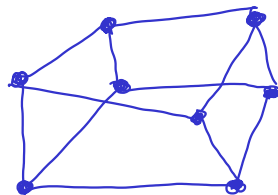
3

Graphs of polyhedra

A polyhedron $P = \{x \in \mathbb{R}^n : Ax \leq b\}$ with vertices defines a graph $G_P = (V, E)$ as follows. The set of nodes V is the set of vertices of P and $v_1 v_2 \in E$ iff v_1 and v_2 are adjacent.



The diameter of
 G_P is the
diameter of P



Diameter and simplex algorithm

If a version of the simplex algorithm requires only a polynomial number of iterations (in n and m), then the diameter of each polyhedral graph is polynomial.

Linear programming, simplex algorithm and diameter

Linear Program

$$\max\{c^T x : x \in \mathbb{R}^n, Ax \leq b\}$$

- ▶ Simplex algorithm walks along edges of graph G_P of $P = \{x \in \mathbb{R}^n : Ax \leq b\}$.
- ▶ *Big mystery*: Is there a version of Simplex requiring a polynomial number of iterations?
- ▶ Necessary condition: The *diameter* of the graph G_P must be polynomial.
- ▶ We define $\Delta(n, m)$: *Largest diameter* of a graph G_P of a polyhedron $P \subseteq \mathbb{R}^n$ described by m inequalities.

Theorem (Kalai and Kleitman 1992)

$$\Delta(n, m) \leq m^{1+\log n}$$

An important property of G_P

$$\underbrace{\pi^T \cdot A_B \cdot g^*}_{\leq b_B} + \underbrace{\pi \cdot \pi^T \cdot A_C \cdot g^*}_{= b_C} < \pi^T \cdot b_B + \pi \cdot \pi^T \cdot b_C$$

\uparrow some are strict !!!

$A_B x \leq b_B$

Theorem

Let $P = \{x \in \mathbb{R}^n : Ax \leq b\}$ be a polyhedron with vertices. Then G_P is connected.

Furthermore, for each pair of vertices u, v there exists a path connecting u and v such that each inequality of $Ax \leq b$ active at both u and v is also active at each vertex of that path.

Proof:

$B \subseteq \{1, \dots, m\}$

$C \subseteq \{1, \dots, m\}$

basis associated with v

ineq. active at both u and v .

$$\underline{C^T = \pi^T \cdot A_B + \pi \cdot \pi^T \cdot A_C}$$

large number!
> 0

$$C^T \cdot x \leq \pi^T \cdot b_B + \pi \cdot \pi^T \cdot b_C$$

Valid for P and active at v

and inactive at any other $y^* \neq v \in P$.

Simplex: $u \rightsquigarrow v \leftarrow$ unique opt. sol.



An important property of G_P

$\exists \varepsilon > 0$ s.t. for each vertex w with $A_c \cdot w \leq b_c$
 \uparrow
some strict.

One has $\pi^T \cdot A_c \cdot w \leq \pi^T \cdot b_c - \varepsilon$

$$\pi^T \cdot A_c \cdot w < \pi^T \cdot b_c$$

π large enough s.t. for each such vertex w :

$$C^T \cdot w = \pi^T \cdot A_B \cdot w + \pi \cdot \pi^T \cdot A_c \cdot w \leq \pi^T \cdot A_B \cdot w + \cancel{\pi \cdot \pi^T \cdot b_c - \pi \cdot \varepsilon}$$

$$< C^T \cdot u = \pi^T \cdot A_B \cdot u + \underbrace{\cancel{\pi \cdot \pi^T \cdot A_c \cdot u}}_{= \pi^T \cdot b_c}$$

\xrightarrow{u}

Simpler does not visit such a w



Degeneracy

Theorem

$\Delta(n, m)$ is attained at a non-degenerate polyhedron.

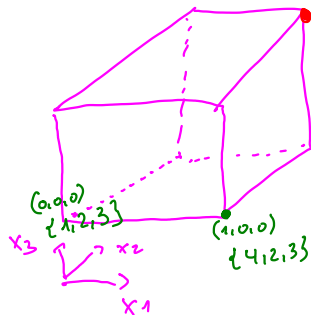
Vertices \leftrightarrow feasible bases

Identify vertices with their feasible basis

$G_P = (V, E)$ is graph with $V \subseteq \binom{[m]}{n}$.

$$[m] = \{1, \dots, m\}$$

$$\{4, 5, 6\}$$



$$1 \quad x_1 \geq 0$$

$$2 \quad x_2 \geq 0$$

$$3 \quad x_3 \geq 0$$

$$4 \quad x_1 \leq 1$$

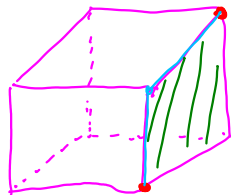
$$5 \quad x_2 \leq 1$$

$$6 \quad x_3 \leq 1$$

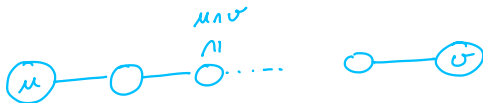
The connectivity condition

$G_P = (V, E)$ with $V \subseteq \binom{[m]}{n}$ is a graph such that for each $u, v \in V$, there exists a path i_0, i_1, \dots, i_t in G such that $u = i_0$ and $v = i_t$ and

$$i_j \supseteq u \cap v, \quad j = 1, \dots, t-1$$



$$x_1 \leq 1$$



P non-degenerate.