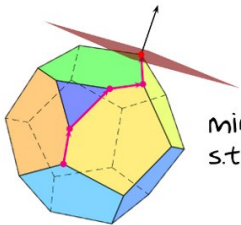


Paths, Cycles and Flows

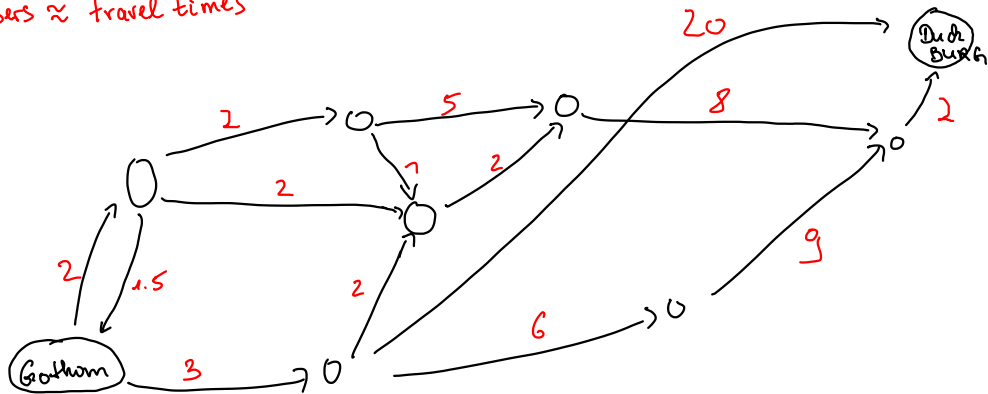
- ▶ Directed graphs
- ▶ Shortest (unweighted) paths
- ▶ Breadth-First-Search



$$\begin{aligned} \min c^T x \\ \text{s.t. } Ax \leq b \end{aligned}$$

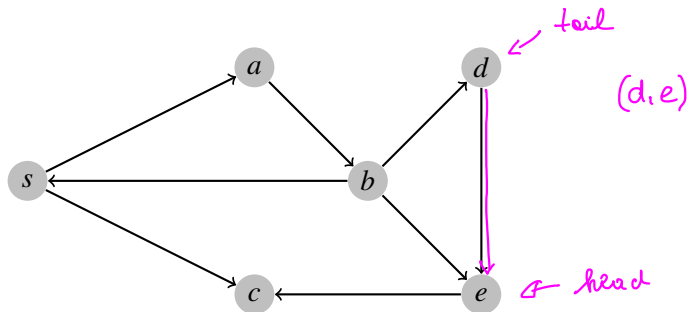
Motivation

Numbers \approx travel times



Directed graphs

A *directed graph* is a tuple $D = (V, A)$, where V is a finite set of *vertices* or *nodes* and $A \subseteq (V \times V)$ is the set of *arcs* or *directed edges* of G .

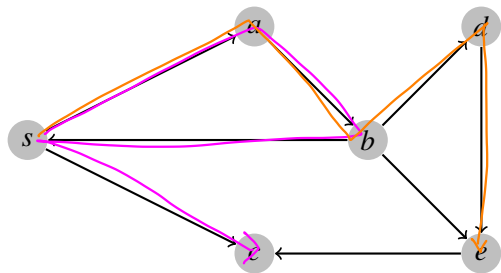


We denote a directed edge by its defining tuple $(u, v) \in A$. The nodes u and v are called *tail* and *head* of (u, v) respectively.

Walks and paths

A **walk** in a directed graph $D = (V, A)$ is a sequence v_0, \dots, v_k , where $(v_i, v_{i+1}) \in A$ for each $i = 0, \dots, k - 1$.

A walk is a **path** if the v_0, \dots, v_k are distinct. The **length** of the path v_0, \dots, v_k is k .



s, a, b, s, c
↑ ↑

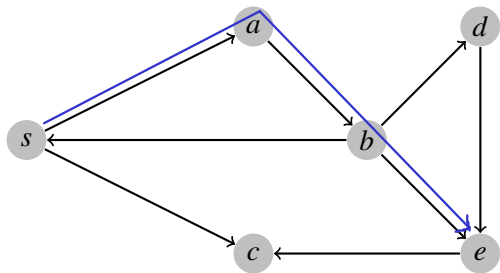
s, a, b, d, e : PATH

length = 4

Unweighted distance

The *distance* $d(s, t)$ between two nodes $s, t \in V$ is the smallest $k \in \mathbb{N}_0$ such that there exists a path $s = v_0, \dots, v_k = t$. (Possibly ∞).

$d(s, t)$ is the length of the *shortest path* connecting s and t .



Quiz:

$$d(s, e) =$$

3

Quiz

What is the largest possible length of a path a directed graph $D = (V, A)$ with $|V| = n$?

▶ n

▶ $n - 1$

▶ $n^2 - 1$



Which of the following are upper bounds for the number of directed paths of length $n - 1$ in directed graph with n nodes?

▶ $n!$

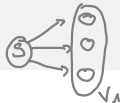
▶ 2^n

▶ n

PATH SPECIFIED BY Sequence v_1, v_2, \dots, v_n $n!$



Distance labels



For $i \in \mathbb{N}_0$, $V_i \subseteq V$ denotes the set of vertices that have distance i from s . Notice that $V_0 = \{s\}$.

Proposition

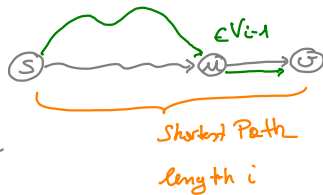
For $i = 1, \dots, n-1$, the set V_i is equal to the set of vertices $v \in V \setminus (V_0 \cup \dots \cup V_{i-1})$ such that there exists an arc $(u, v) \in A$ with $u \in V_{i-1}$.

Proof:

" \subseteq " $v \in V_i$

" \supseteq " $v \in V_j, j \geq i$

$j \leq i \Rightarrow j = i$



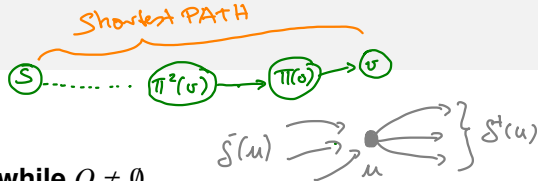
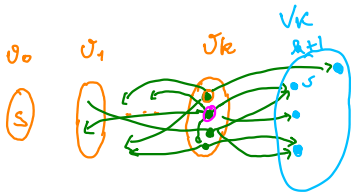
Breadth-First-Search

Alg. maintains two arrays

$$D[v_1 = \overset{\circ}{s} v_2, \dots, v_n]$$

$$\pi[v_1 = \overset{\circ}{s}, v_2, \dots, v_n]$$

and a **queue** $Q = [s]$



while $Q \neq \emptyset$

$u := \text{head}(Q)$

for each $(u, v) \in \delta^+(u)$

if $(D[v] = \infty)$

$\pi[v] := u$

$D[v] := D[u] + 1$

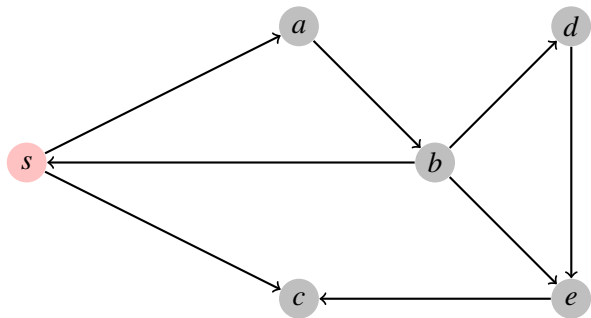
$\text{enqueue}(Q, v)$

$\text{dequeue}(Q)$



Example

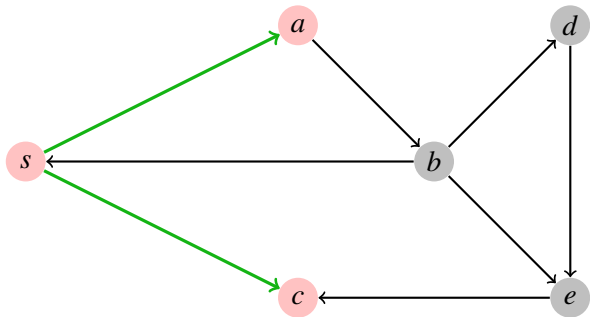
```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



$Q = [s]$

Example

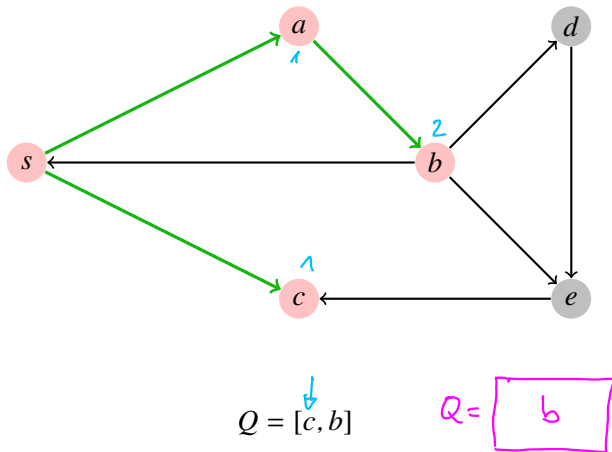
```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



$Q = [a, c]$

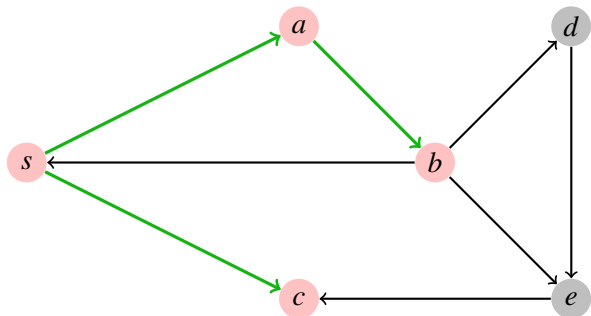
Example

```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



Example

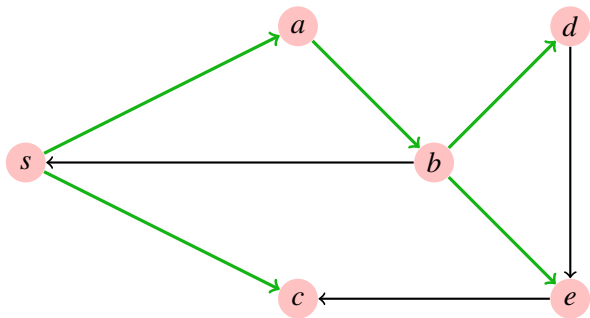
```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



$Q = [b]$

Example

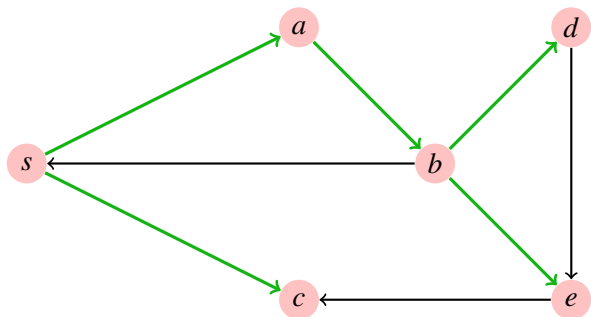
```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



$Q = [d, e]$

Example

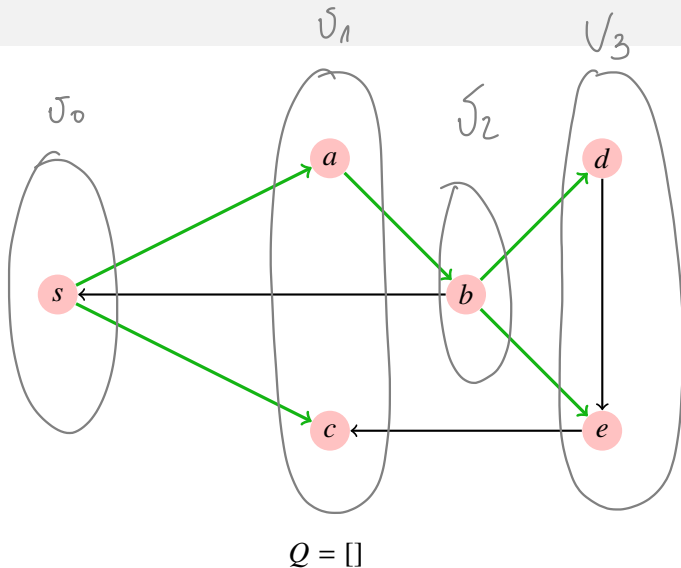
```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



$Q = [e]$

Example

```
while  $Q \neq \emptyset$   
   $u := \text{head}(Q)$   
  for each  $(u, v) \in \delta^+(u)$   
    if  $(D[v] = \infty)$   
       $\pi[v] := u$   
       $D[v] := D[u] + 1$   
       $\text{enqueue}(Q, v)$   
   $\text{dequeue}(Q)$ 
```



Analysis

Cheat: Ignore init. of ARRAYS.



With this initialization $O(|V| + |A|)$

Theorem

The Breadth-First-Search algorithm runs in time $O(|A|)$, algorithm.

It is thus a *linear time*

while $Q \neq \emptyset$

$u := \text{head}(Q)$

for each $v \in \delta^+(u)$

if $(D[v] = \infty)$

$\pi[v] := u$

$D[v] := D[u] + 1$

$\text{enqueue}(Q, v)$

$\text{dequeue}(Q)$

Iteration u : At most $c_1 \cdot |\delta^+(u)| + c_2$ elementary operations.

$$|\delta^+(u)| \quad C_1 \cdot |\delta^+(u)| + C_2$$

$$\sum_{\substack{u \in V \\ \text{unreachable from } s}} C_1 \cdot |\delta^+(u)| + C_2 \leq C_1 \cdot |A| + |\bigvee_{\text{from } s}^{\text{reach.}}|$$

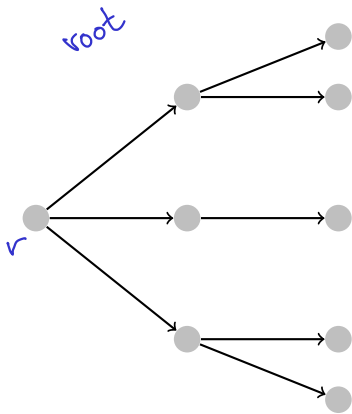
$$= O(|A|)$$

elementary op.

□

Directed trees

A *directed tree* is a directed graph $T = (V, A)$ with $|A| = |V| - 1$ and there exists a node $r \in T$ such that there exists a path from r to all other nodes of T .



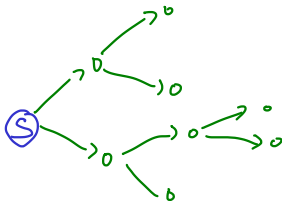
A shortest path tree

Lemma

Consider the arrays D and π after the termination of the breadth-first-search algorithm. The graph $T = (V', A')$ with $V' = \{v \in V: D[v] < \infty\}$ and $A' = \{(\pi(v), v): 1 \leq D[v] < \infty\}$ is a tree.

Proof.

- ▶ Clearly, $|A'| = |V'| - 1$.
- ▶ For any $i \in \{1, \dots, n-1\}$, by backtracking the π -labels from any $v \in V_i$, we will eventually reach s .



Shortest
path tree

