1. Use ACF to Determine Order of AR Process?

Calculate the ACF of AR(1) process:

$$y(k) + a_1 y(k-1) = \xi(k)$$

Multiplying by y(k-1), y(k-2), ..., y(k-l) and take expectation:

$$\gamma_{yy}(1) + a_1 \gamma_{yy}(0) = 0$$

$$\gamma_{yy}(2) + a_1 \gamma_{yy}(1) = 0$$

$$\vdots$$

$$\gamma_{yy}(l) + a_1 \gamma_{yy}(l-1) = 0$$

$$\gamma_{yy}(l) = -a_1 \gamma_{yy}(l-1) = -a_1(-a_1 \gamma_{yy}(l-2)) = \dots = (-1)^l a_1^l \gamma_{yy}(0)$$

- ullet Therefore, $ho_{yy}(l)=(-1)^la_1^l.$ Thus, ACF never dies out for an AR process and hence cannot be used for detecting the order of an AR process.
- ullet Although there is no direct correlation between y(k) and y(k-l) for l>1, it appears to exist due to auto-regression.

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2. PACF Approach

To determine the order of AR(p) process:

$$y(n) + a_1 y(n-1) + \dots + a_p y(n-p) = \xi(n)$$

- 1. Let j = 1
- 2. Assume that the system is an AR(j) model:

$$y(n) + a_{1j}y(n-1) + \cdots + a_{jj}y(n-j) = \xi(n)$$

3. Multiplying this equation by y(n-k) and taking expectation, we obtain

$$\gamma_{yy}(k) + a_{1j}\gamma_{yy}(k-1) + \dots + a_{jj}\gamma_{yy}(k-j) = 0, \quad \forall k \ge 1$$

- 4. Write this for k = 1 to j, arrive at j equations. Solve them for a_{ij} .
- 5. If $j < j_{max}$, increment j by 1 and go to step 2 above.

Note that j_{max} should be chosen to be greater than the expected p. A plot of a_{jj} vs. j will have a cut off from j = p + 1 onwards.

Recall the basic equation:

$$y(n) + a_{1j}y(n-1) + \dots + a_{jj}y(n-j) = \xi(n)$$
 (1)

Determine the order of

$$y(n) - y(n-1) + 0.5y(n-2) = \xi(n)$$
(2)

For j = 1, Eq. 1 becomes

$$\gamma_{yy}(k) + a_{11}\gamma_{yy}(k-1) = 0, \ \forall k \ge 1.$$

For k = 1, the above equation becomes

$$\gamma_{yy}(1) + a_{11}\gamma_{yy}(0) = 0$$

$$a_{11} = -\frac{\gamma_{yy}(1)}{\gamma_{yy}(0)}$$
(3)

For j = 2, Eq. 1 becomes

$$\gamma_{yy}(k) + a_{12}\gamma_{yy}(k-1) + a_{22}\gamma_{yy}(k-2) = 0$$

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4. Determination of AR(2) by PACF Approach - Ctd - 1

$$\gamma_{yy}(k) + a_{12}\gamma_{yy}(k-1) + a_{22}\gamma_{yy}(k-2) = 0$$

 $k \ge 1$. For k = 1, 2, this equation becomes,

$$\begin{bmatrix} \gamma_{yy}(0) & \gamma_{yy}(1) \\ \gamma_{yy}(1) & \gamma_{yy}(0) \end{bmatrix} \begin{bmatrix} a_{12} \\ a_{22} \end{bmatrix} = - \begin{bmatrix} \gamma_{yy}(1) \\ \gamma_{yy}(2) \end{bmatrix}. \tag{4}$$

For j = 3, Eq. 1 becomes

$$\gamma_{yy}(k) + a_{13}\gamma_{yy}(k-1) + a_{23}\gamma_{yy}(k-2) + a_{33}\gamma_{yy}(k-3) = 0$$

 $\forall k \geq 1$. For k = 1, 2, 3, it becomes,

$$\begin{bmatrix} \gamma_{yy}(0) & \gamma_{yy}(1) & \gamma_{yy}(2) \\ \gamma_{yy}(1) & \gamma_{yy}(0) & \gamma_{yy}(1) \\ \gamma_{yy}(2) & \gamma_{yy}(1) & \gamma_{yy}(0) \end{bmatrix} \begin{bmatrix} a_{13} \\ a_{23} \\ a_{33} \end{bmatrix} = - \begin{bmatrix} \gamma_{yy}(1) \\ \gamma_{yy}(2) \\ \gamma_{yy}(3) \end{bmatrix}$$
 (5)

To solve these equations for a_{jj} , we need to calculate $\gamma_{yy}(k)$, k=0 to 3.

Determine the order of

$$y(n) - y(n-1) + 0.5y(n-2) = \xi(n)$$
(6)

Multiply by $\xi(n)$, take expectation:

$$\gamma_{y\xi}(0) = \gamma_{ee}(0) = \sigma_{\xi}^2$$

Multiply Eq. 6 by y(n), y(n-1) and y(n-2), one at a time, take expectation:

$$\begin{bmatrix} 1 & -1 & 0.5 \\ -1 & 1.5 & 0 \\ 0.5 & -1 & 1 \end{bmatrix} \begin{bmatrix} \gamma_{yy}(0) \\ \gamma_{yy}(1) \\ \gamma_{yy}(2) \end{bmatrix} = \sigma_{\xi}^{2} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Solving it, we obtain

$$\begin{bmatrix} \gamma_{yy}(0) \\ \gamma_{yy}(1) \\ \gamma_{yy}(2) \end{bmatrix} = \begin{bmatrix} 2.4 \\ 1.6 \\ 0.4 \end{bmatrix} \sigma_{\xi}^{2} \tag{7}$$

Multiply Eq. 6 by y(n-3) and take expectation

$$\gamma_{yy}(3) - \gamma_{yy}(2) + 0.5\gamma_{yy}(1) = 0$$

solving which, we obtain

$$\gamma_{yy}(3) = -0.4\sigma_{\varepsilon}^2 \tag{8}$$

Substitute 7 to 8 in 3 - 5 and determine a_{ij} . We obtain

$$a_{11} = -0.67$$
 $a_{22} = 0.5$
 $a_{33} = 0$

As expected for the AR(2) process, $a_{ij} = 0$ for j > 2.

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6. pacf_ex.m

```
% Define model and generate
    m = idpoly([1, -1, 0.5], [], 1);
    e = 0.1*randn(100000,1);
    y = sim(m, e);
    Plot noise and plant output
    subplot (2,1,1), plot (y(1:500))
    title ('Plant_output_and_noise_input_vs._time',...
           'FontSize',14)
    ylabel('Plant_output_y', 'FontSize',14)
10
    subplot (2,1,2), plot (e(1:500))
11
    ylabel('Noise_input_e', 'FontSize',14)
12
    xlabel('Sampling_instant, _k', 'FontSize', 14)
13
14
    Generate PACF and plot
15
    figure, pacf(y,10);
16
```

5

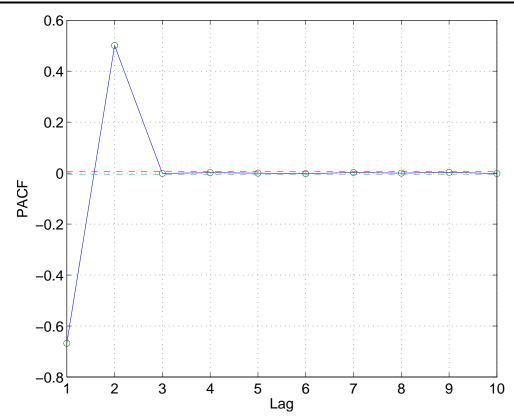
7. pacf.m

```
function [ajj] = pacf(y,M)
  ryy = xcorr(y,'coeff');
 len = length(ryy);
_{4} \text{ zero} = (len + 1)/2;
  ryy0 = ryy(zero);
  ryy_one_side = ryy(zero+1:len);
  ajj = [];
  for j = 1:M,
     ajj = [ajj pacf_mat(ryy0,ryy_one_side,j,1)];
  p = 1: length(ajj);
  N = length(p);
  \lim = 2/\operatorname{sqrt}(\operatorname{length}(y));
  % Plot the
15
  A = axes('FontSize', 14);
  set(get(A, 'Xlabel'), 'FontSize',14);
  plot(p, ajj, p, ajj, 'o', p, lim*ones(N,1),
                    p,-lim * ones (N,1), '---')
  ylabel('PACF'), xlabel('Lag'), grid
```

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8. Partial Auto Correlation Function



9. Determination of MA(q) and AR(p) Processes

MA(q) process:

$$y(n) = \xi(n) + c_1 \xi(n-1) + \dots + c_q \xi(n-q)$$

• A plot of $\{\gamma_{yy}(k)\}$ vs. k becomes zero for all k>q.

Known as ACF plot

AR(p) process:

$$y(k) + a_1 y(k-1) + \dots + a_p y(k-p) = \xi(k)$$

- Assume p=1, calculate a_1 , call it a_{11}
- ullet Assume p=2, calculate a_2 , call it a_{22}
- Repeat this enough number of times
- Plot a_{11} , a_{22} , ..., a_{jj} vs. j
- From j = p + 1 onwards, $a_{ij} = 0$

Known as PACF plot

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10. Determination of ARMA(p,q) Process by Trial and Error

9

$$y(n) + a_1 y(n-1) + \dots + a_p y(n-p) = \xi(n) + c_1 \xi(n-1) + \dots + c_q \xi(n-q)$$

- 1. Plot the ACF and PACF to check if it is a pure AR, MA or a mixed process.
- 2. For mixed process, start with an AR(1) model (use the arma function in MATLAB).
- 3. Compute the residuals of this model (use the pe function in MATLAB).
- 4. Examine the ACF and PACF of the residuals.
- 5. If a mixed process is observed, estimate an ARMA(1,1) model.
- 6. Implement steps 3 and 4. Increase the AR and MA order alternately until convergence.

In practice, commonly occurring stochastic processes can be adequately represented by an arma(2,2) or by a lower order process

11. Determination of ARMA(p,q) Process by Trial and Error

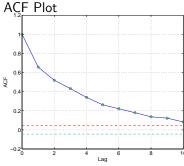
$$y(n) = \frac{1 - 0.3z^{-1}}{1 - 0.8z^{-1}}\xi(n)$$

```
model for simulation
     Set up the
    arma_mod = idpoly(1,0,[1 -0.3],[1 -0.8],1,1);
     Generate the
     Deterministic Input
                            can
                               be anything
    u = zeros(2048,1);
    e = randn(2048, 1);
    Simulate the model
    y = idsim(arma_mod,[u e]);
10
11
    Plot ACF and PACF for 10 lags
    figure, plotacf(y,1e-03,11,1);
13
    figure, pacf(y,10);
14
15
    Estimate AR(1) model and present it
16
    mod_{est1} = armax(y,[1 \ 0]); present(mod_{est1})
17
18
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                                     11
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```

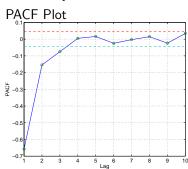
```
err_mod1 = pe(mod_est1,y);
```

```
21
    Plot ACF and PACF for 10 lags
22
    figure
23
    plotacf(err_mod1, 1e-03, 11, 1);
    figure, pacf(err_mod1,10);
26
    Check ACF and PACF of residuals
    mod_{est2} = armax(y,[1 1]); present(mod_{est2})
    err_mod2 = pe(mod_est2, y);
    Plot ACF and PACF for 10 lags
    figure
32
    plotacf (err_mod2, 1e-03, 11, 1);
    figure, pacf(err_mod2,10);
```

Original Process:

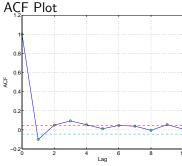


Slow decay \Rightarrow AR Process

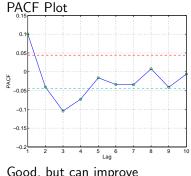


Many nonzero coefficients \Rightarrow Mixed Process

Residual of AR(1) Process (24):

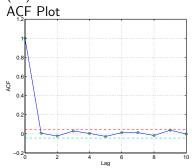


Good, but can improve

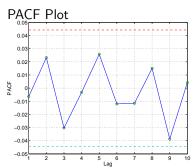


13

Good, but can improve Try ARMA(1,1) process Residual of ARMA(1,1) Process (33):



Behaves like white noise



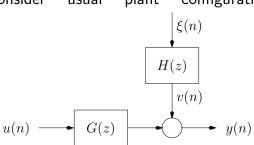
White noise is confirmed

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13. Estimation of Impulse Response

Consider usual plant configuration:



$$y(m) = g(m) * u(m) + h(m) * \xi(m)$$

Convolve with u(-m). As u and e are uncorrelated $(r_{ue}(n) = 0)$,

$$r_{yu}(m) = g(m) * r_{uu}(m),$$

where, r denotes correlation. Taking Z-transform,

$$\Phi_{yu}(z) = G(z)\Phi_{uu}(z)$$

Taking Fourier Transform,

$$\Phi_{yu}\left(e^{j\omega}\right) = G\left(e^{j\omega}\right)\Phi_{uu}\left(e^{j\omega}\right)$$

As $r_{uu}(n)$ is real and even, Φ_{uu} real. If $\Phi_{uu}\left(e^{j\omega}\right)=K$, a constant,

$$G\left(e^{j\omega}\right) = \frac{1}{K}\Phi_{yu}\left(e^{j\omega}\right).$$

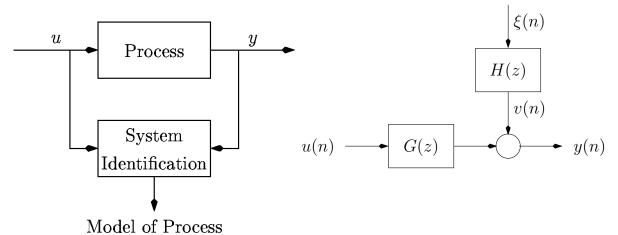
On inverting this, we obtain

$$\{g(n)\} = \frac{1}{K} \{r_{yu}(n)\}.$$

- This method of estimating impulse response reduces noise: summation is a smoothing operation.
- ullet If input were white, $\Phi_{uu}\left(e^{j\omega}\right)=K$, a constant

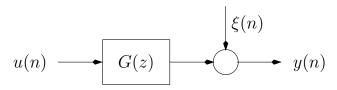
System Identification Problem:

Want to find G(z) and H(z):



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First find G only, assuming white noise:



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