

Computational Photography



Dr. Irfan Essa

Professor

School of Interactive Computing

Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.

Digital Images: Merging and Blending Images using Image Pyramids



Dr. Irfan Essa

Professor

School of Interactive Computing

Different methods for Combing Multiple
Images to Generate a Novel Image: Use of
Image Pyramids



Lesson Objectives

- ★ Explain in your own words the Gaussian and the Laplacian Pyramids
- ★ Explain in your own words, how these Pyramids encode the Frequency domain
- ★ Write the equation for computing a Laplacian Pyramid form a Gaussian Pyramid
- ★ Describe in your own words the specific process to blend two images using Pyramids

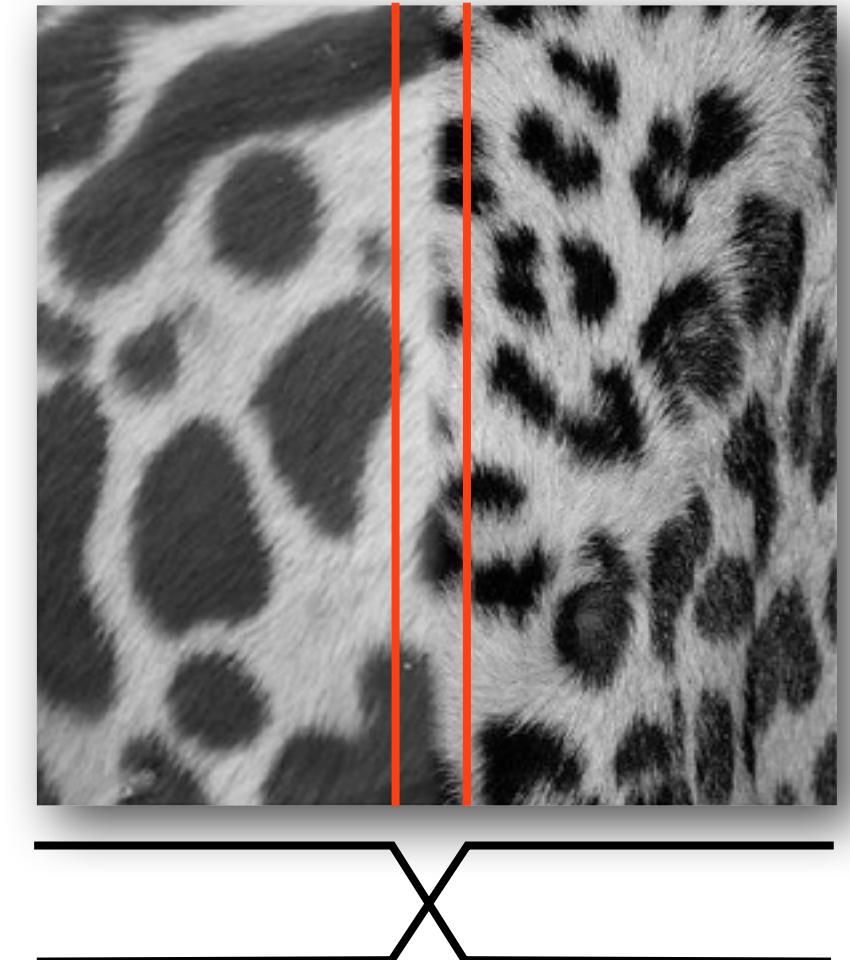


REVIEW: Optimal Window Size



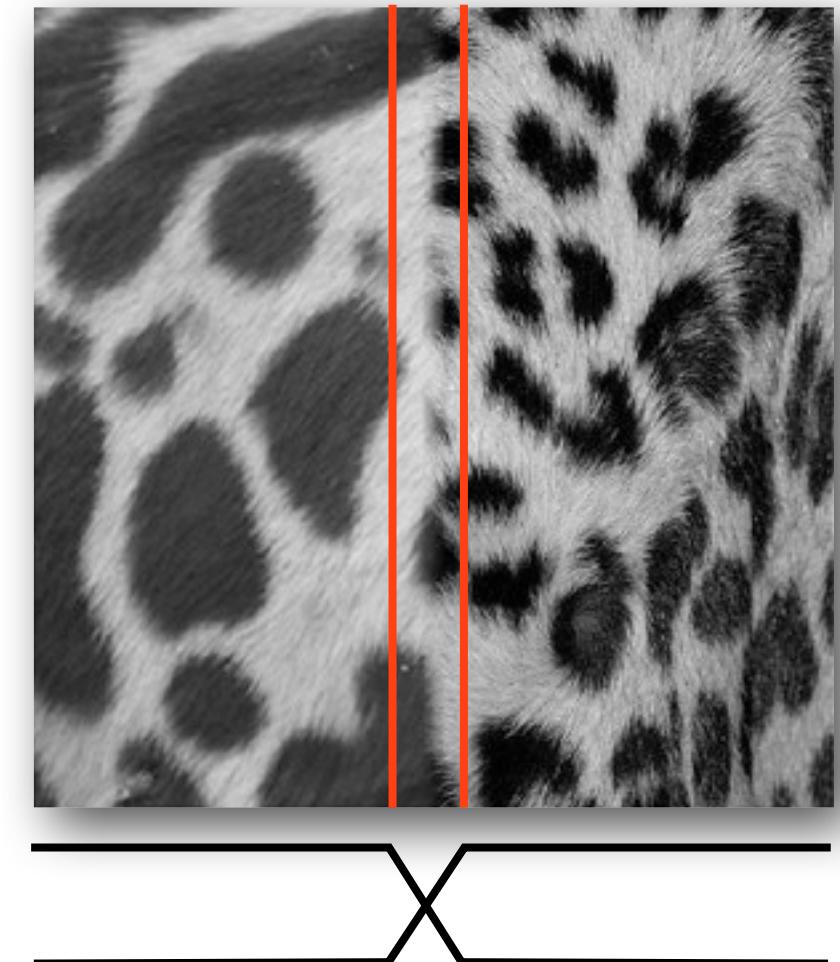
REVIEW: Optimal Window Size

- ★ To avoid seams: Window = size of largest prominent “feature”

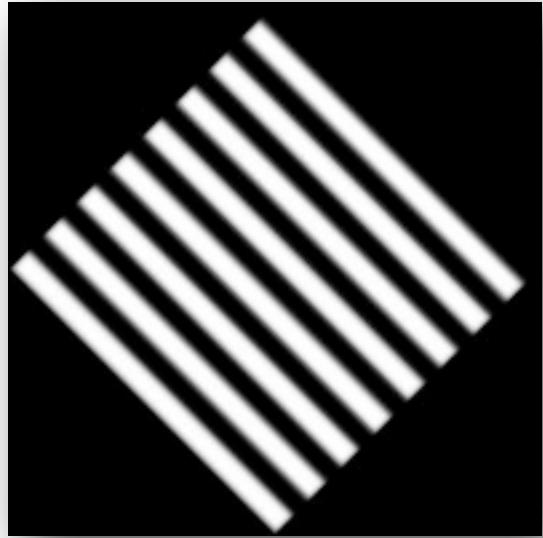


REVIEW: Optimal Window Size

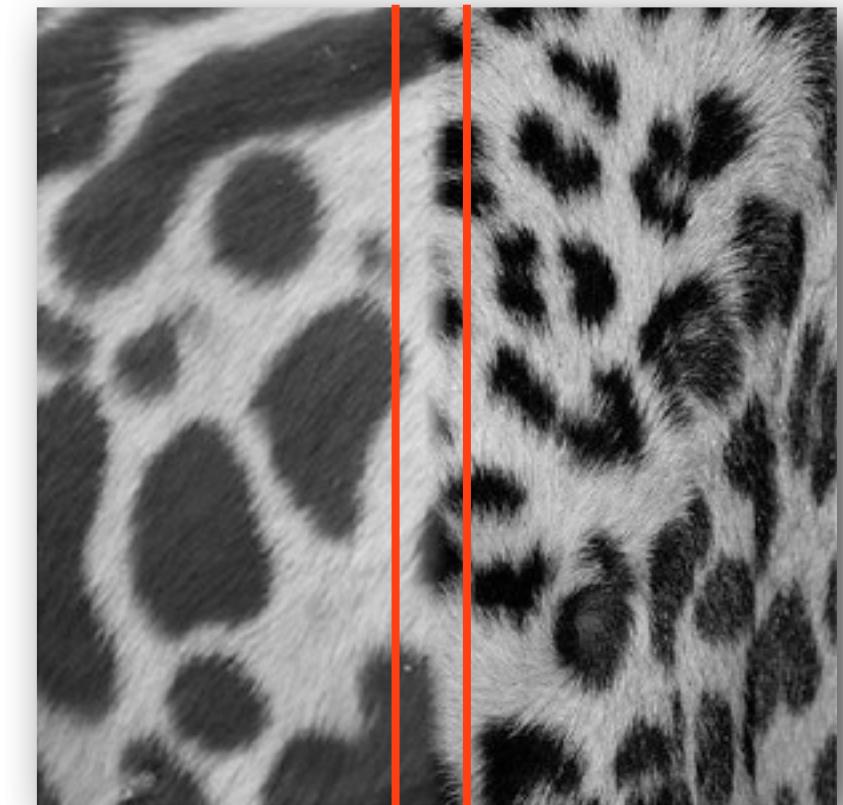
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”



REVIEW: Optimal Window Size



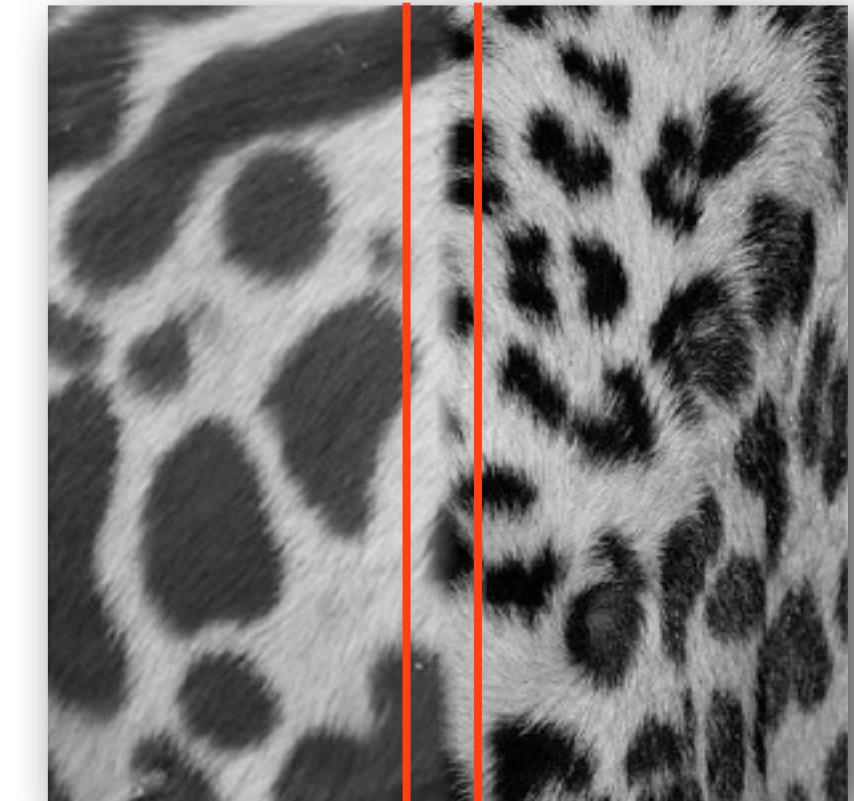
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”



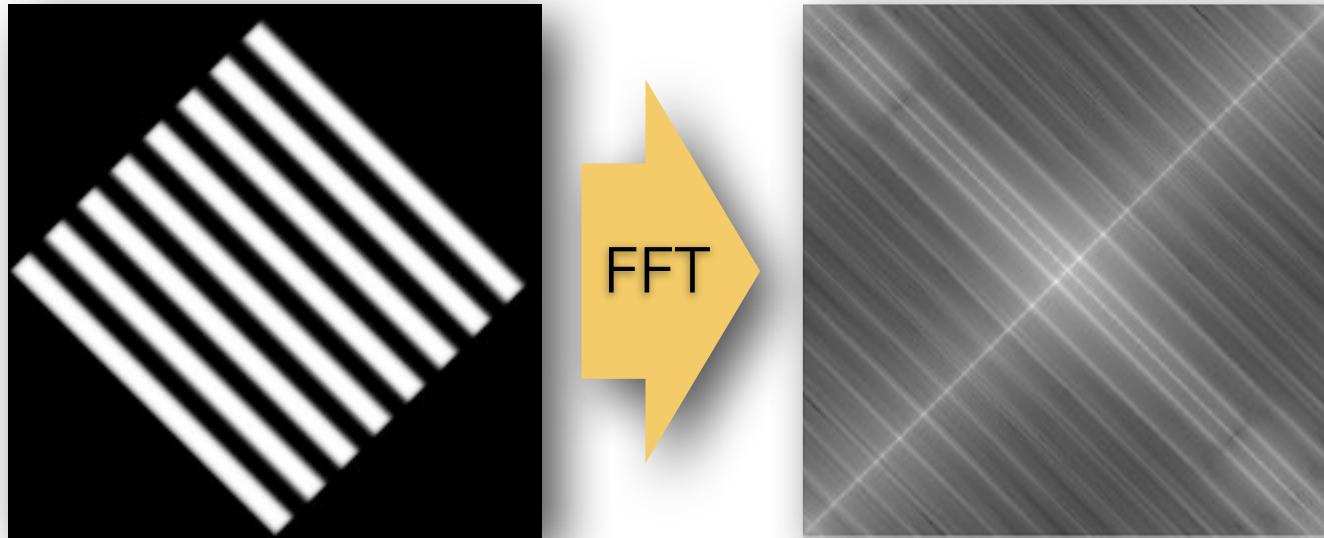
REVIEW: Optimal Window Size



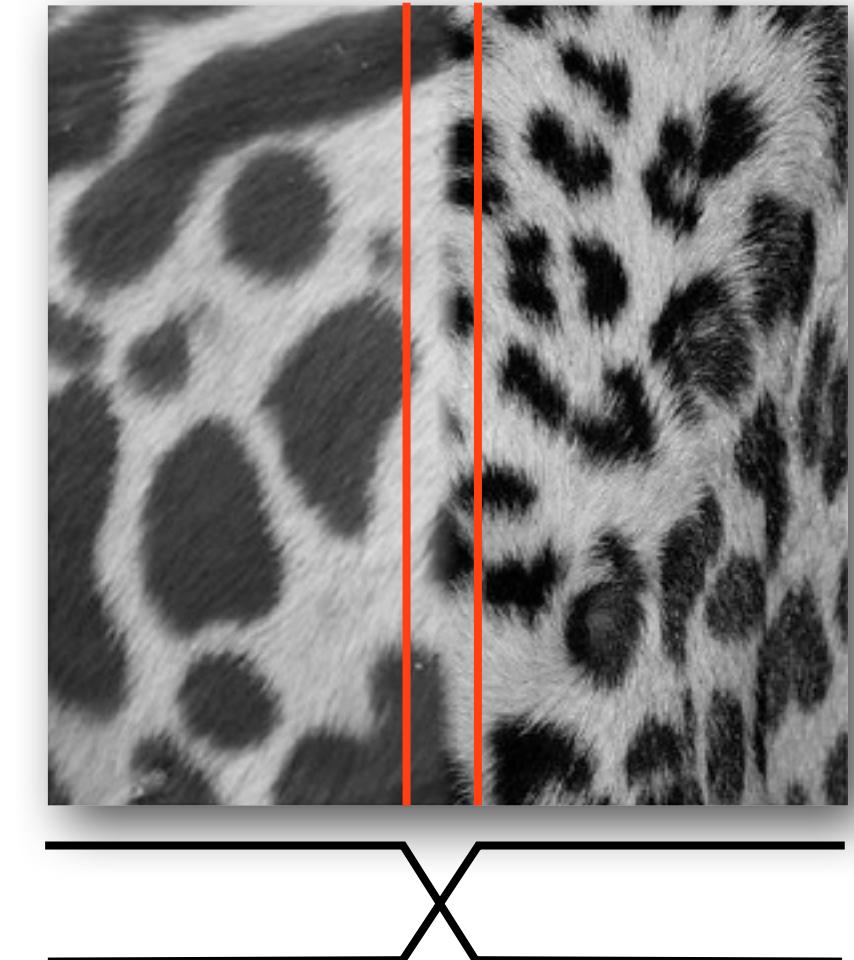
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”



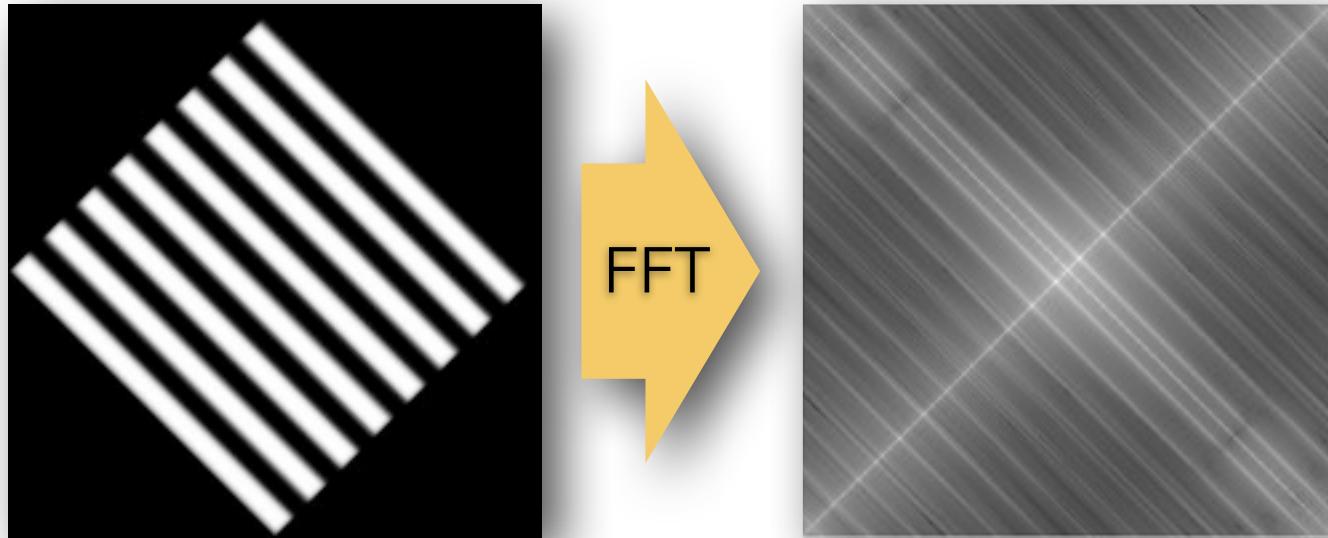
REVIEW: Optimal Window Size



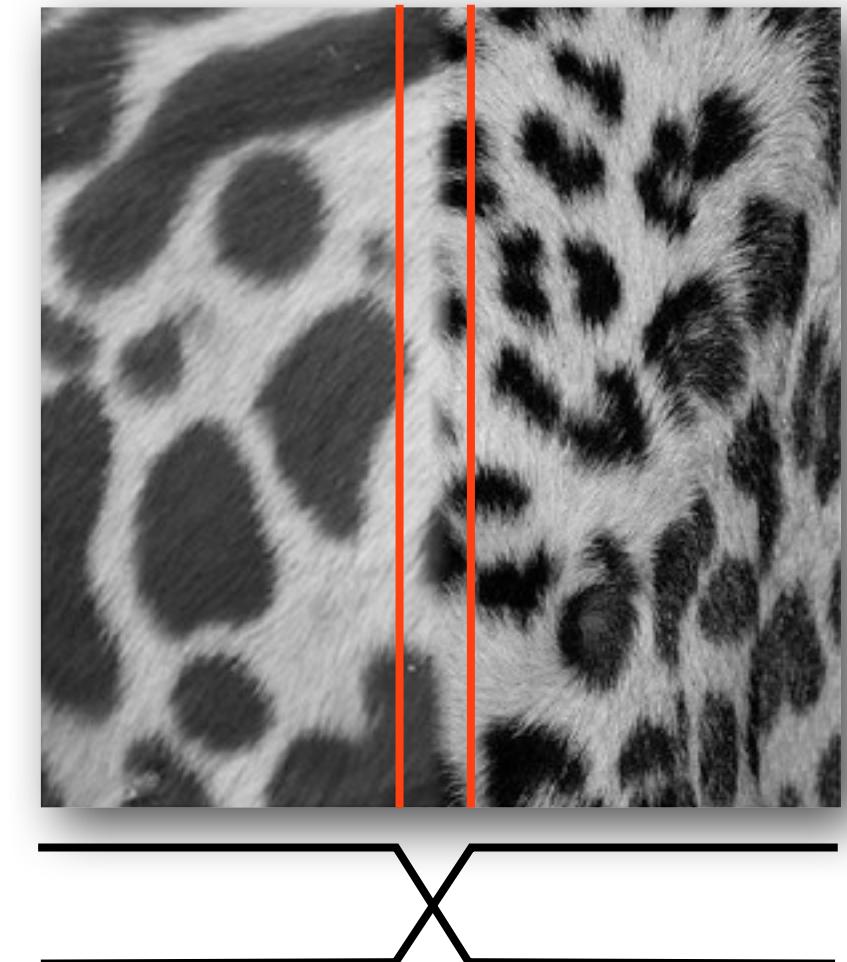
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”



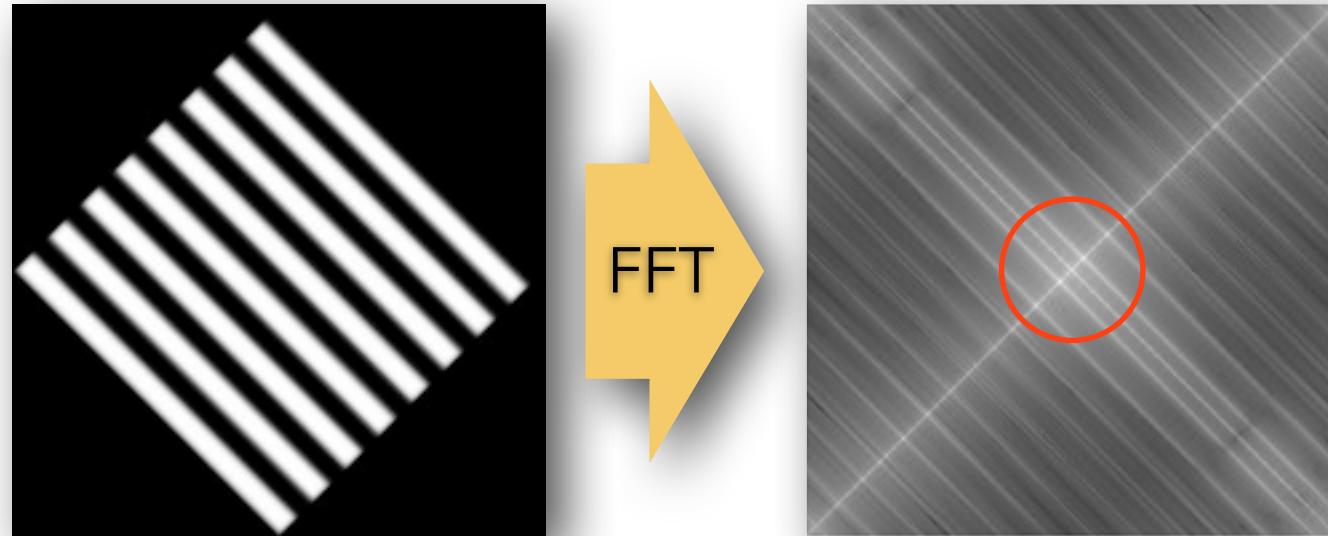
REVIEW: Optimal Window Size



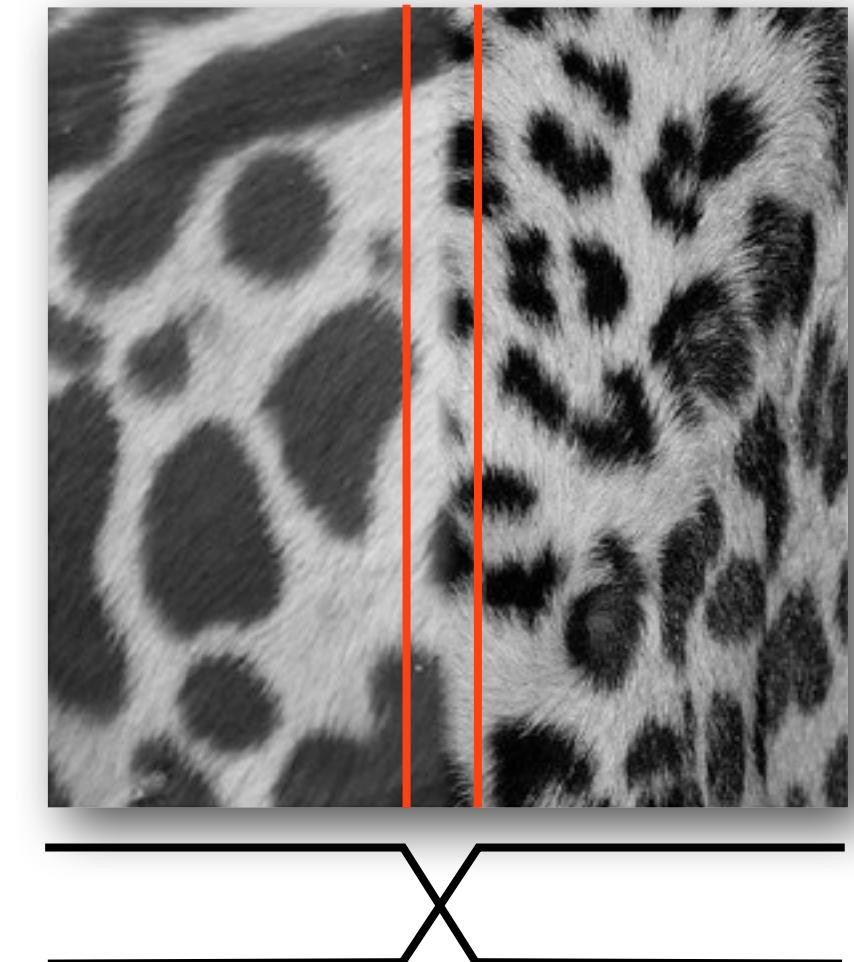
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”
- ★ Use Fourier domain
 - Largest frequency $\leq 2 \times$ size of smallest frequency
 - Image frequency content should occupy one “octave” (power of two)



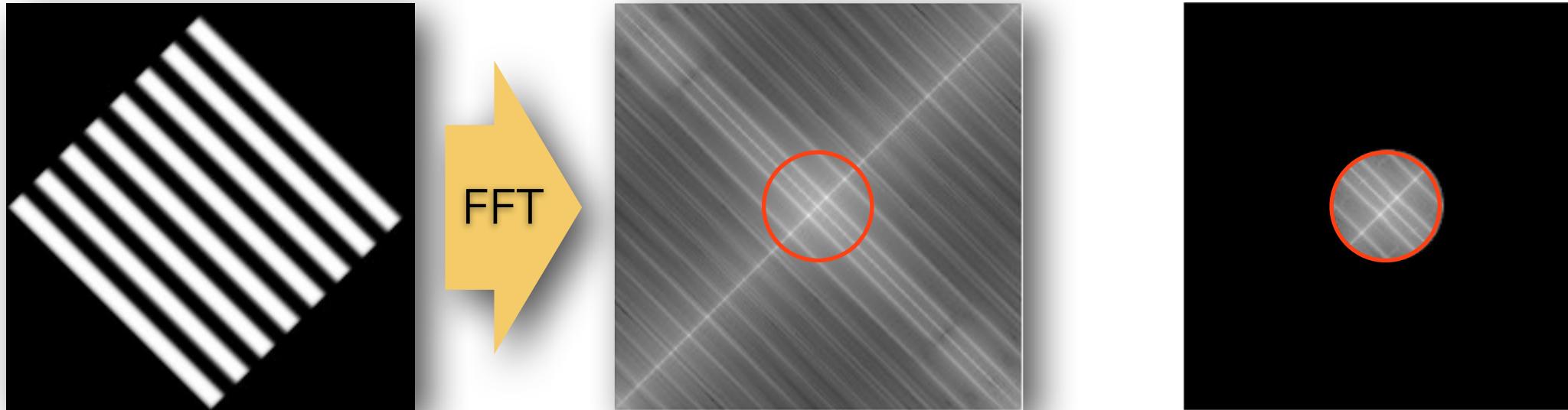
REVIEW: Optimal Window Size



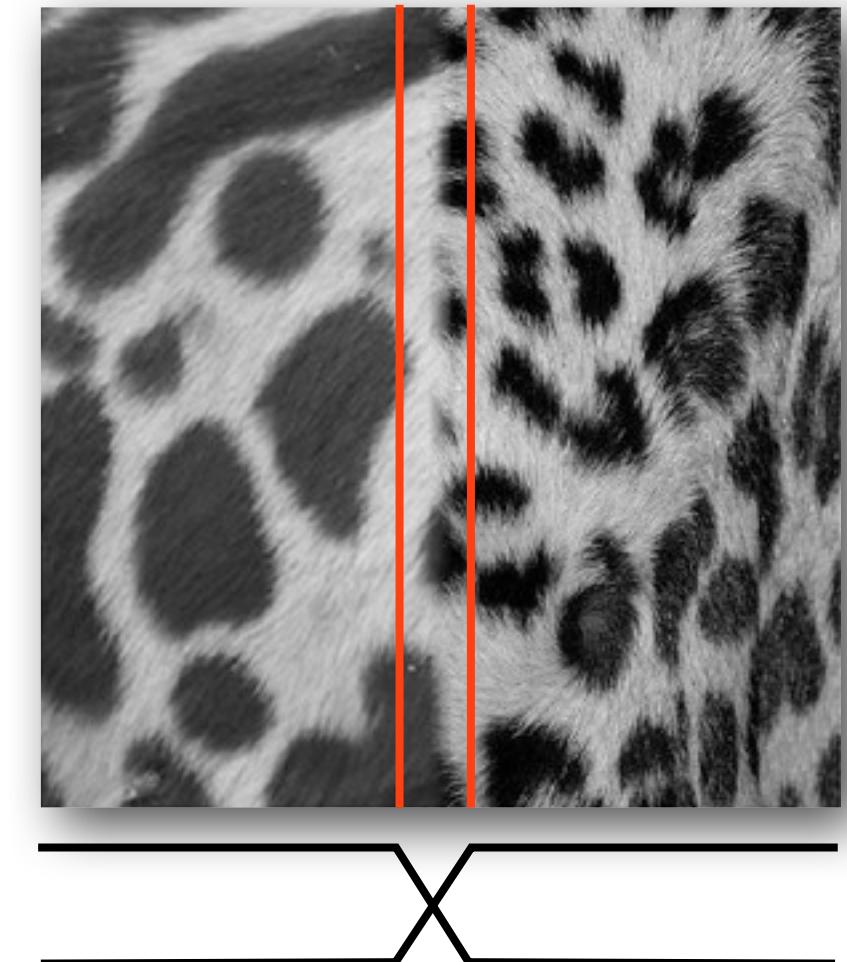
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”
- ★ Use Fourier domain
 - Largest frequency $\leq 2 \times$ size of smallest frequency
 - Image frequency content should occupy one “octave” (power of two)



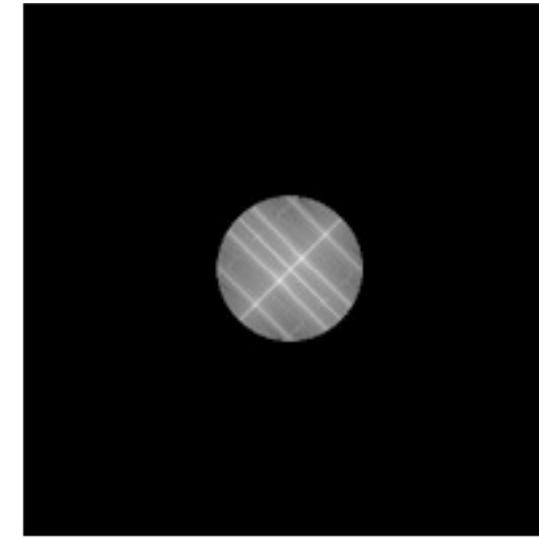
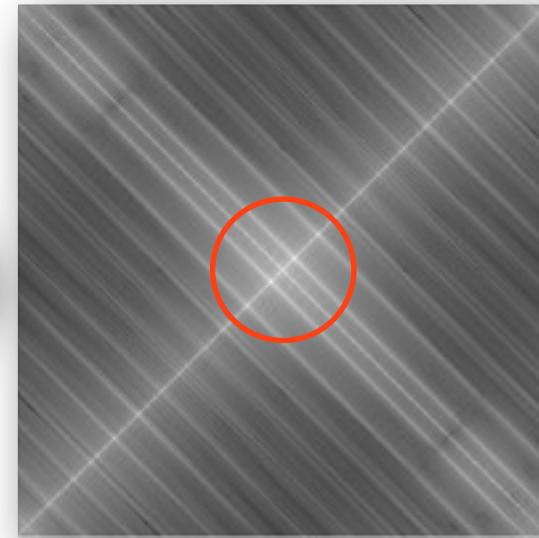
REVIEW: Optimal Window Size



- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”
- ★ Use Fourier domain
 - Largest frequency $\leq 2 \times$ size of smallest frequency
 - Image frequency content should occupy one “octave” (power of two)



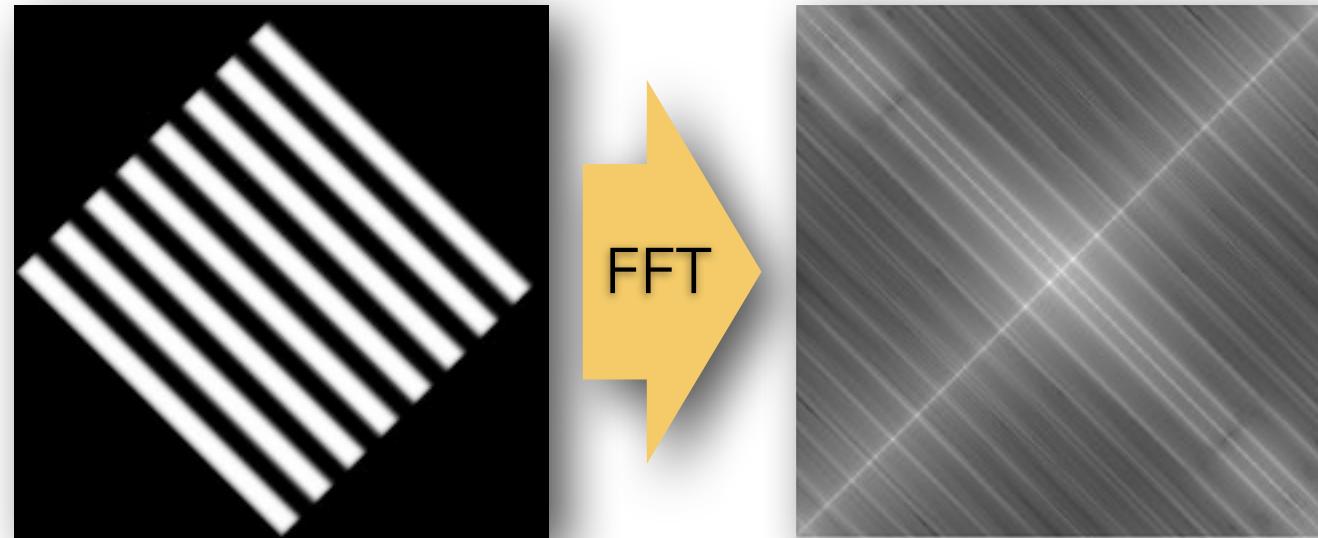
REVIEW: Optimal Window Size



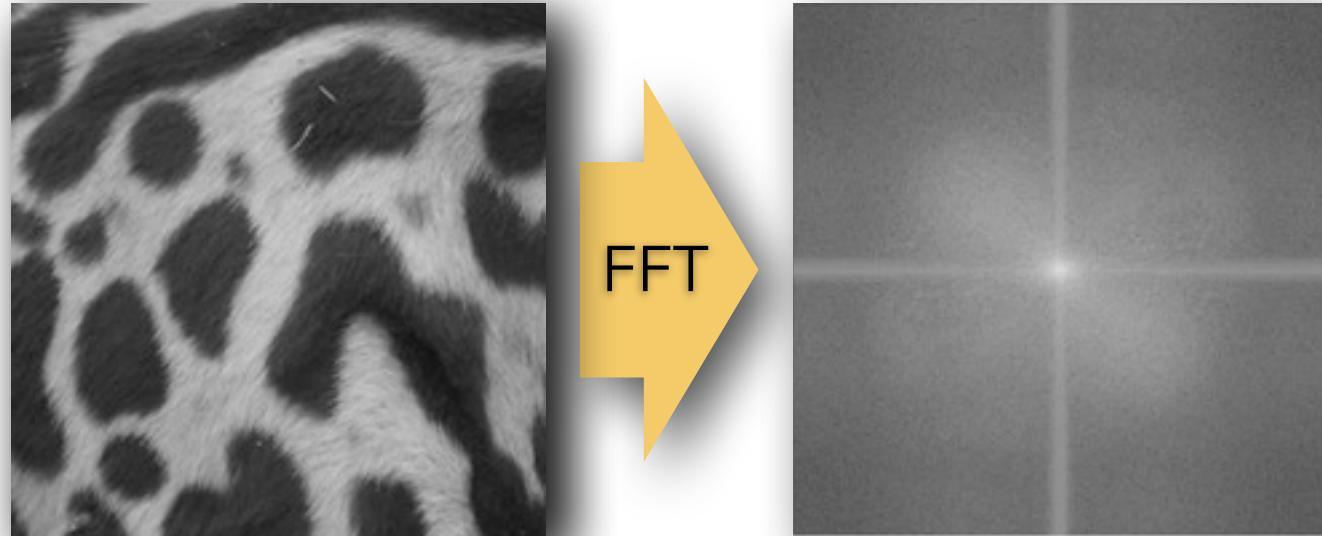
- ★ To avoid seams: Window = size of largest prominent “feature”
- ★ To avoid ghosting: Window $\leq 2 \times$ size of smallest prominent “feature”
- ★ Use Fourier domain
 - Largest frequency $\leq 2 \times$ size of smallest frequency
 - Image frequency content should occupy one “octave” (power of two)



Frequency Spread needs to be Modeled



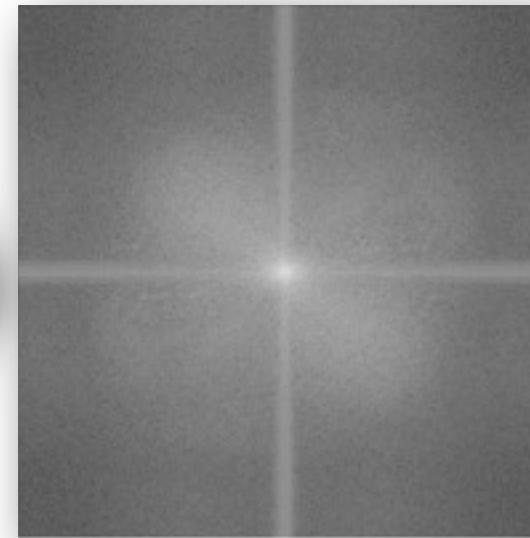
Frequency Spread needs to be Modeled



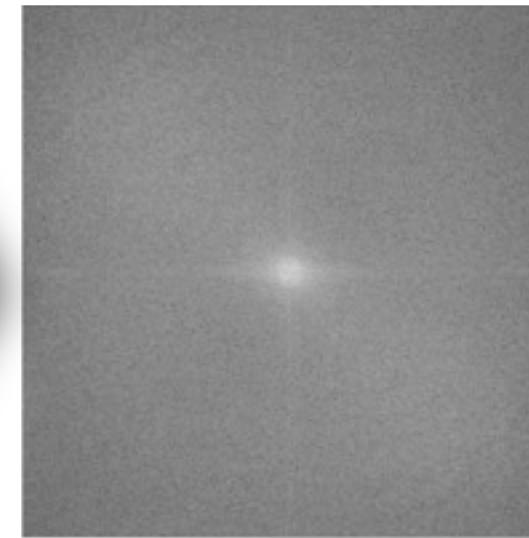
Frequency Spread needs to be Modeled



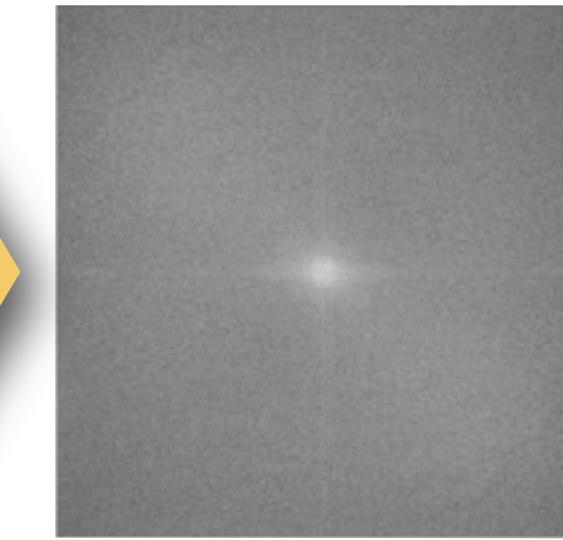
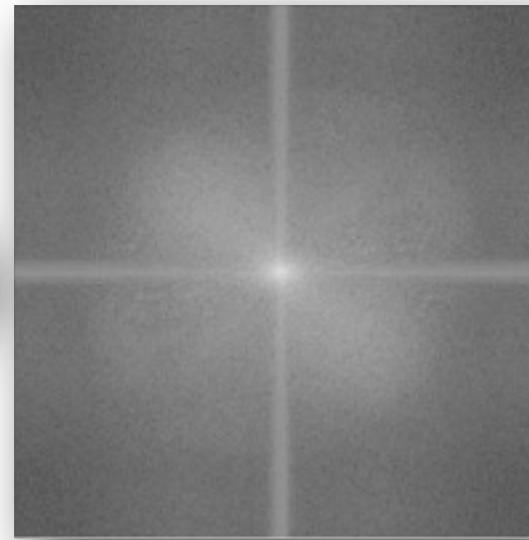
FFT



FFT

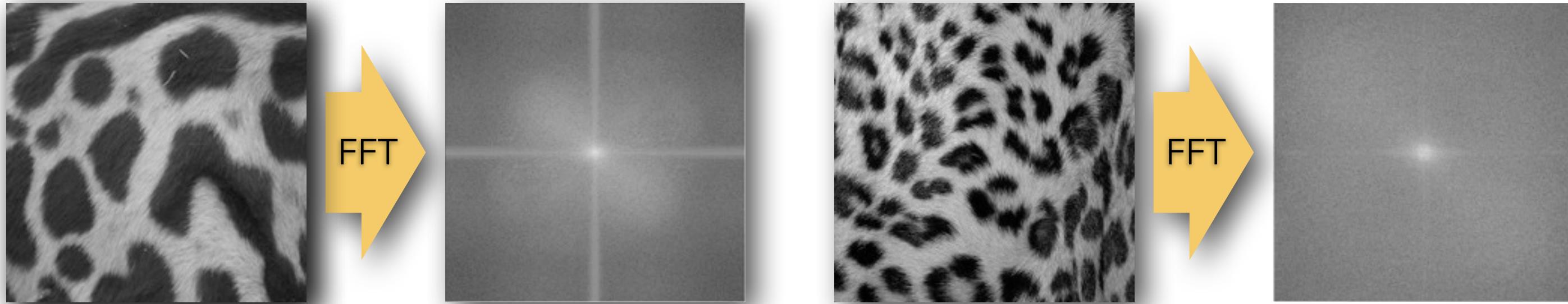


Frequency Spread needs to be Modeled



- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$

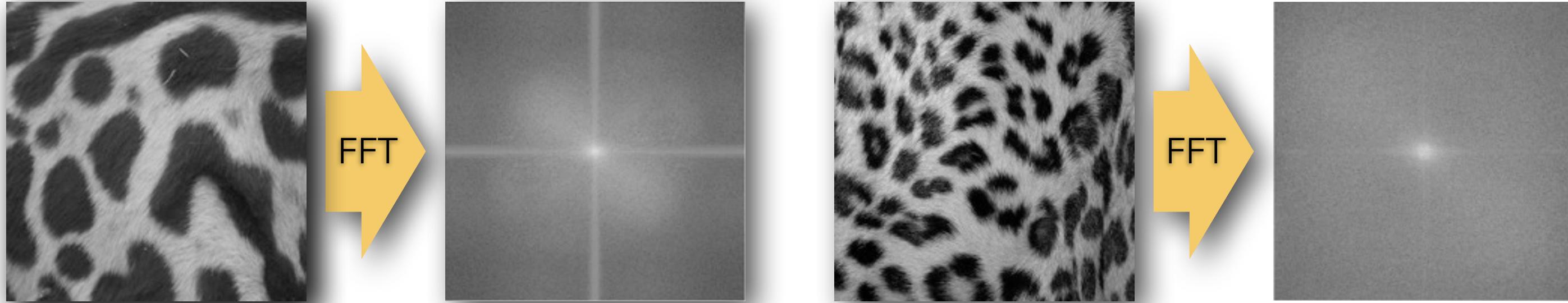
Frequency Spread needs to be Modeled



- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$
- ★ Decompose Fourier image into octaves (bands)

$$F_l = F_l^1 + F_l^2 + F_l^3 + \dots, \quad F_r = F_r^1 + F_r^2 + F_r^3 + \dots$$

Frequency Spread needs to be Modeled



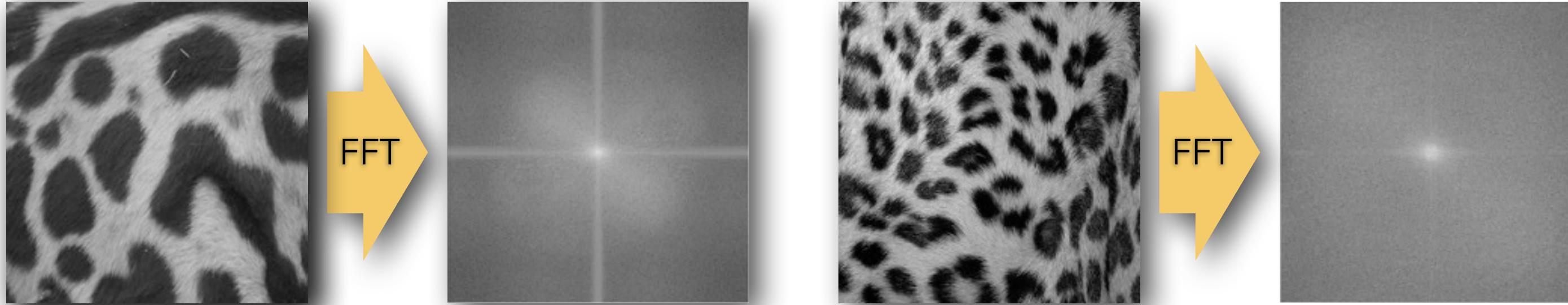
- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$

- ★ Decompose Fourier image into octaves (bands)

$$F_l = F_l^1 + F_l^2 + F_l^3 + \dots, \quad F_r = F_r^1 + F_r^2 + F_r^3 + \dots$$

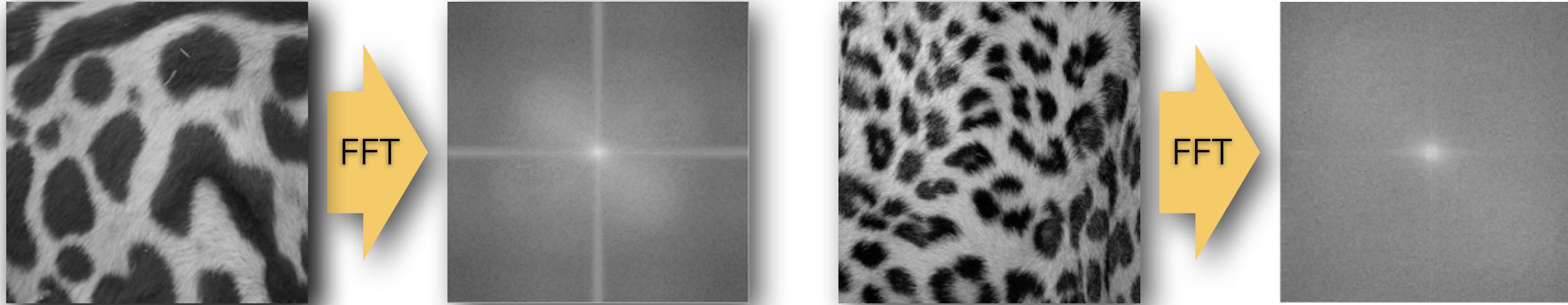
- ★ “Feather” corresponding octaves of: $F_l \quad F_r$

Frequency Spread needs to be Modeled



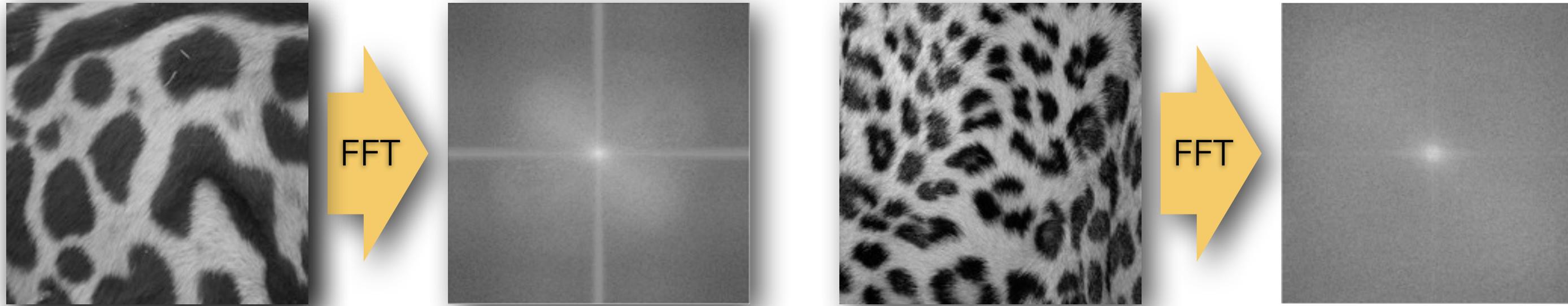
- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$
- ★ Decompose Fourier image into octaves (bands)
$$F_l = F_l^1 + F_l^2 + F_l^3 + \dots, \quad F_r = F_r^1 + F_r^2 + F_r^3 + \dots$$
- ★ “Feather” corresponding octaves of: $F_l \quad F_r$
- ★ Compute inverse FFT and feather in spatial domain

Frequency Spread needs to be Modeled



- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$
- ★ Decompose Fourier image into octaves (bands)
$$F_l = F_l^1 + F_l^2 + F_l^3 + \dots, \quad F_r = F_r^1 + F_r^2 + F_r^3 + \dots$$
- ★ “Feather” corresponding octaves of: $F_l \quad F_r$
- ★ Compute inverse FFT and feather in spatial domain
- ★ Sum feathered octave images in frequency domain

Frequency Spread needs to be Modeled



- ★ Compute: $FFT(I_l) \Rightarrow F_l, \quad FFT(I_r) \Rightarrow F_r$
- ★ Decompose Fourier image into octaves (bands)
$$F_l = F_l^1 + F_l^2 + F_l^3 + \dots, \quad F_r = F_r^1 + F_r^2 + F_r^3 + \dots$$
- ★ “Feather” corresponding octaves of: $F_l \quad F_r$
- ★ Compute inverse FFT and feather in spatial domain
- ★ Sum feathered octave images in frequency domain
- ★ Burt and Adelson (1983)



Pyramid Representation of Images (A Gaussian Pyramid)



g_0



g_1

Pyramid Representation of Images (A Gaussian Pyramid)



g_0

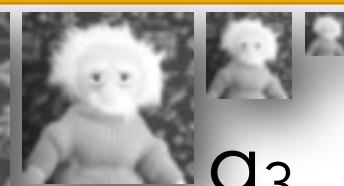


g_1

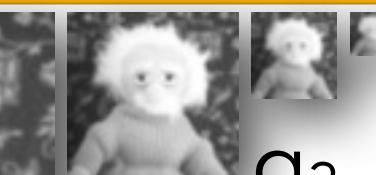


g_2

Pyramid Representation of Images (A Gaussian Pyramid)



Pyramid Representation of Images (A Gaussian Pyramid)


 $\omega_v =$
 $1/4 - a/2$
 $1/4$
 a
 $1/4$
 $1/4 - a/2$
 $\omega_h =$
 $1/4 - a/2$
 $1/4$
 a
 $1/4$
 $1/4 - a/2$
 g_0
 g_1
 g_2
 g_3

Pyramid Representation of Images

(A Gaussian Pyramid)



$$\omega_v =$$

$$h = \omega_h \star \omega_v$$

$$\omega_h =$$



$\frac{1}{4} - \frac{a}{2}$

$\frac{1}{4}$

a

$\frac{1}{4}$

$\frac{1}{4} - \frac{a}{2}$

Pyramid Representation of Images

(A Gaussian Pyramid)



$$\omega_v =$$

$$h = \omega_h \star \omega_v$$

$$a = 0.3 - .6 (.38)$$

$$\omega_h =$$



$\frac{1}{4} - a/2$

$1/4$

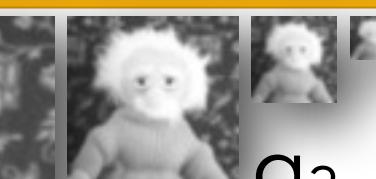
a

$1/4$

$\frac{1}{4} - a/2$

Pyramid Representation of Images

(A Gaussian Pyramid)



$$\omega_v =$$

$$h = \omega_h \star \omega_v$$

$$a = 0.3 - .6 (.38)$$

$$\omega_h =$$

$\frac{1}{4} - \frac{a}{2}$	$\frac{1}{4}$	a	$\frac{1}{4}$	$\frac{1}{4} - \frac{a}{2}$
-----------------------------	---------------	-----	---------------	-----------------------------

$$g_k = h \star g_{k-1}$$

g_0

$\frac{1}{4} - \frac{a}{2}$

$\frac{1}{4}$

a

$\frac{1}{4}$

$\frac{1}{4} - \frac{a}{2}$

Pyramid Representation of Images

(A Gaussian Pyramid)



$$\omega_v =$$

$$h = \omega_h \star \omega_v$$

$$a = 0.3 - .6 (.38)$$

$$\omega_h =$$

1/4 - a/2	1/4	a	1/4	1/4 - a/2

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

g_0

1/4 -
a/2

1/4

a

1/4

1/4 -
a/2

Pyramid Representation of Images

(A Gaussian Pyramid)

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)



g_1

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)

 g_1 g_2

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)



g₁

g₂

g₃

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)



g_1

g_2

g_3

g_4

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)



g_1

g_2

g_3

g_4

g_5

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)



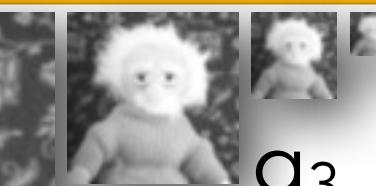
g_0



g_1



g_2



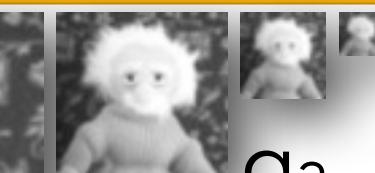
g_3

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images

(A Gaussian Pyramid)



g_3

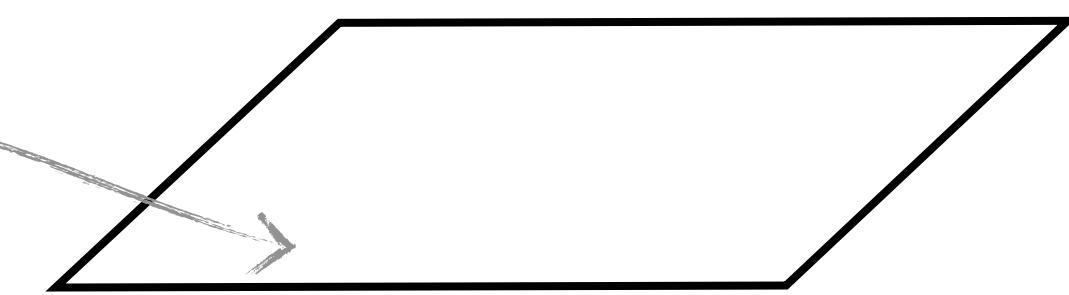
g_2

g_1

g_0

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$



Pyramid Representation of Images

(A Gaussian Pyramid)



g_3

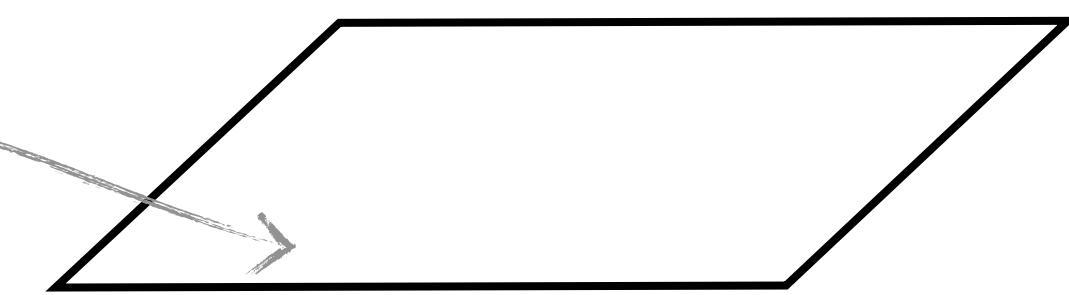
g_2

g_1

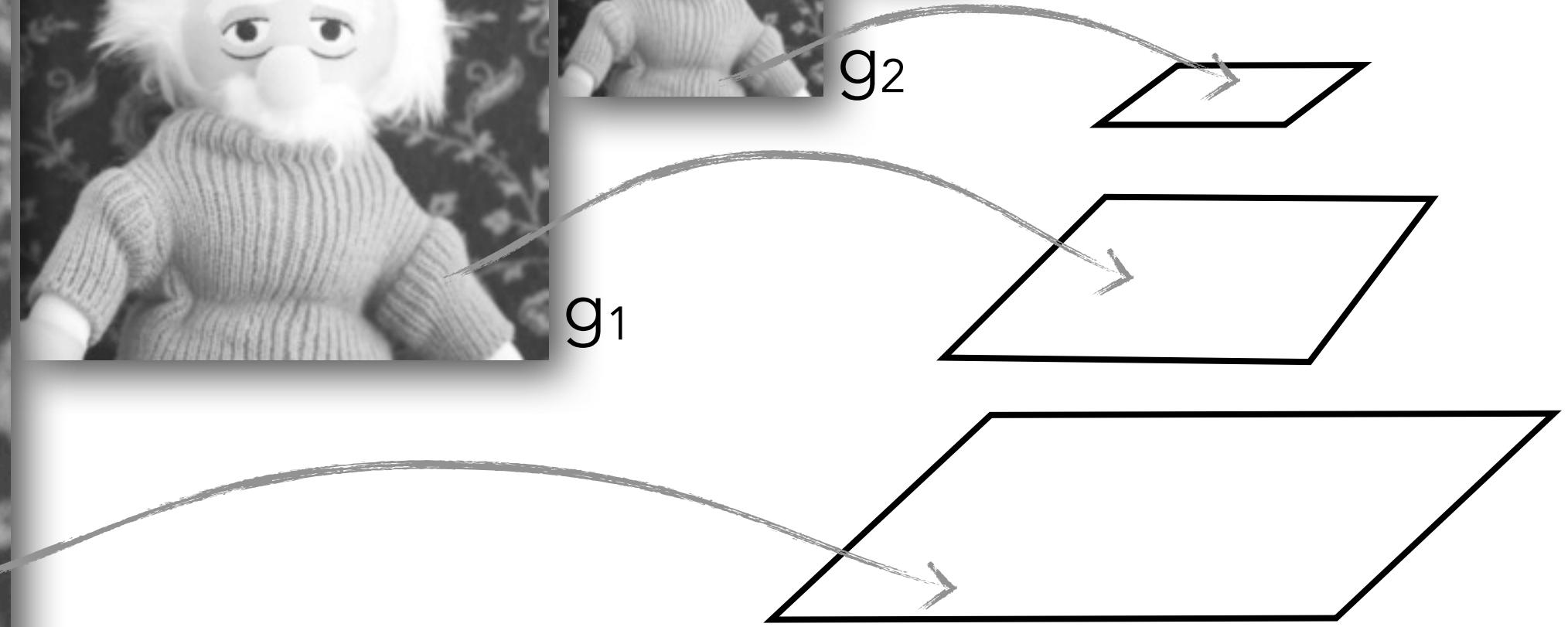
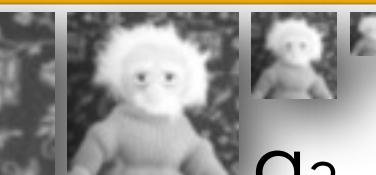
g_0

$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$



Pyramid Representation of Images (A Gaussian Pyramid)

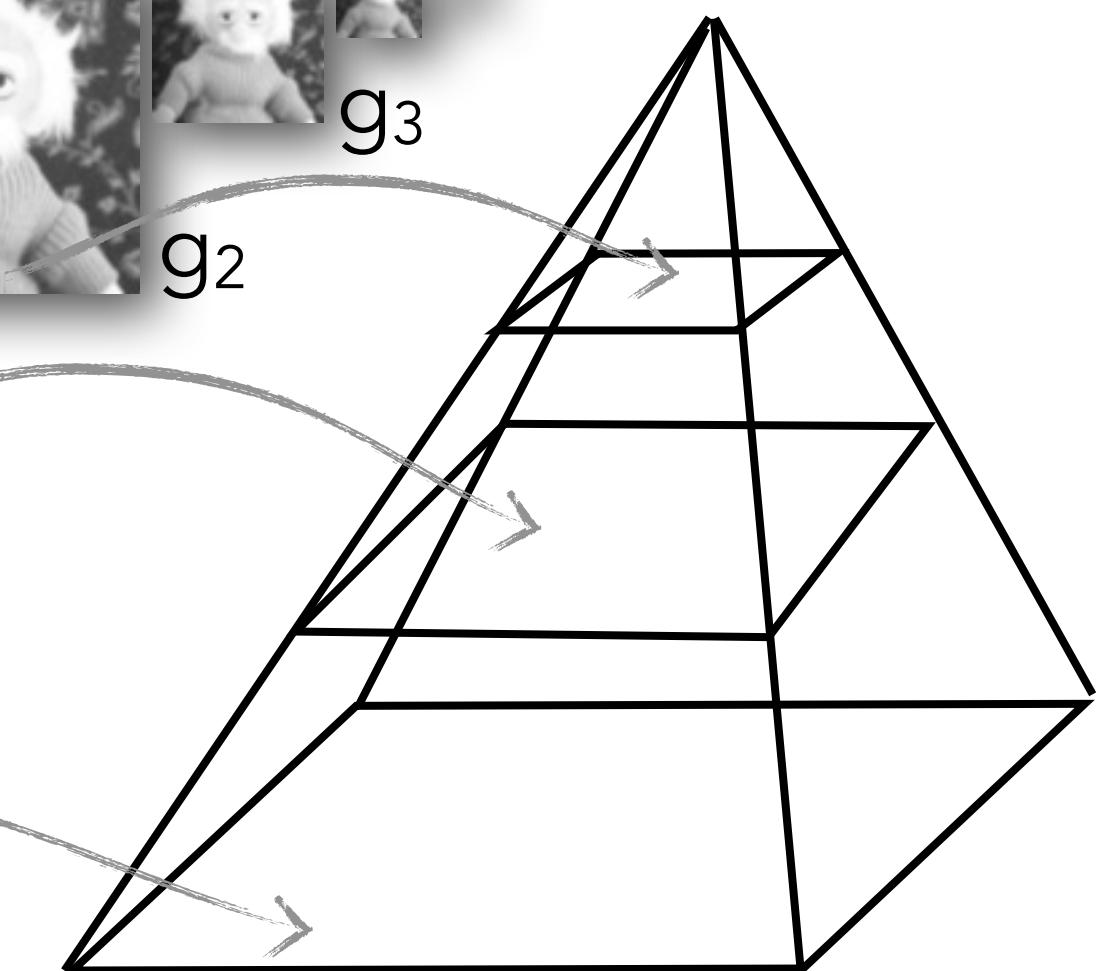
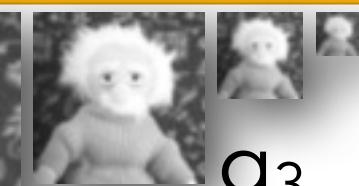


$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images

(A Gaussian Pyramid)

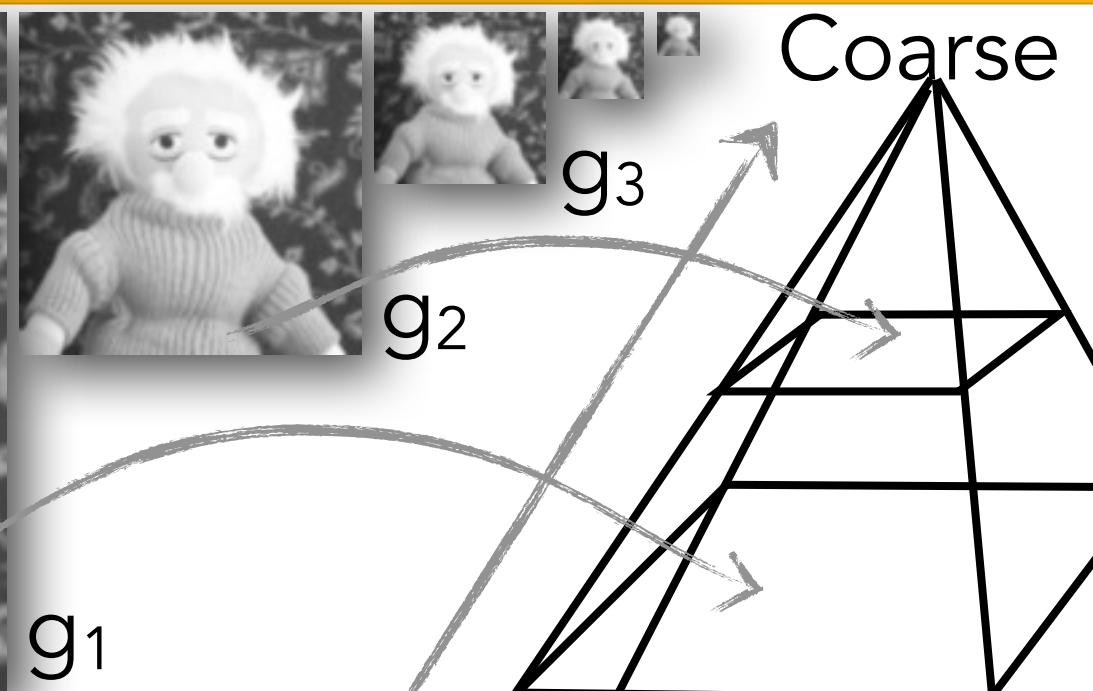
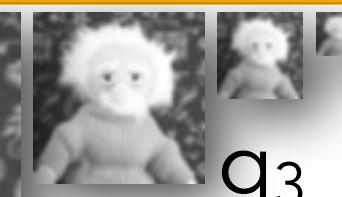


$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images

(A Gaussian Pyramid)



$$g_k = h \star g_{k-1}$$

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images (A Gaussian Pyramid)

 g_0 g_1

$$g_k = \text{REDUCE}(g_{k-1})$$

Pyramid Representation of Images

(A Gaussian Pyramid)



g_0

g_1

$$g_k = \text{REDUCE}(g_{k-1})$$
$$g_{l,n} = \text{EXPAND}(g_l, n-1)$$

Pyramid Representation of Images (A Gaussian Pyramid)

 g_0

Pyramid Representation of Images (A Gaussian Pyramid)

$$g_k = \text{REDUCE}(g_{k-1})$$

$$g_{l,n} = \text{EXPAND}(g_l, n-1)$$

EXPAND is inverse of REVERSE, as it seeks to add new values in between knowns ones. $g_{l,n}$ is g_l expanded n times



$g_{0,1}$
 g_0

$g_k = \text{REDUCE}(g_{k-1})$
 $g_{l,n} = \text{EXPAND}(g_l, n-1)$

EXPAND is inverse of REVERSE, as it seeks to add new values in between knowns ones. $g_{l,n}$ is g_l expanded n times

Pyramid Representation of Images (A Gaussian Pyramid)

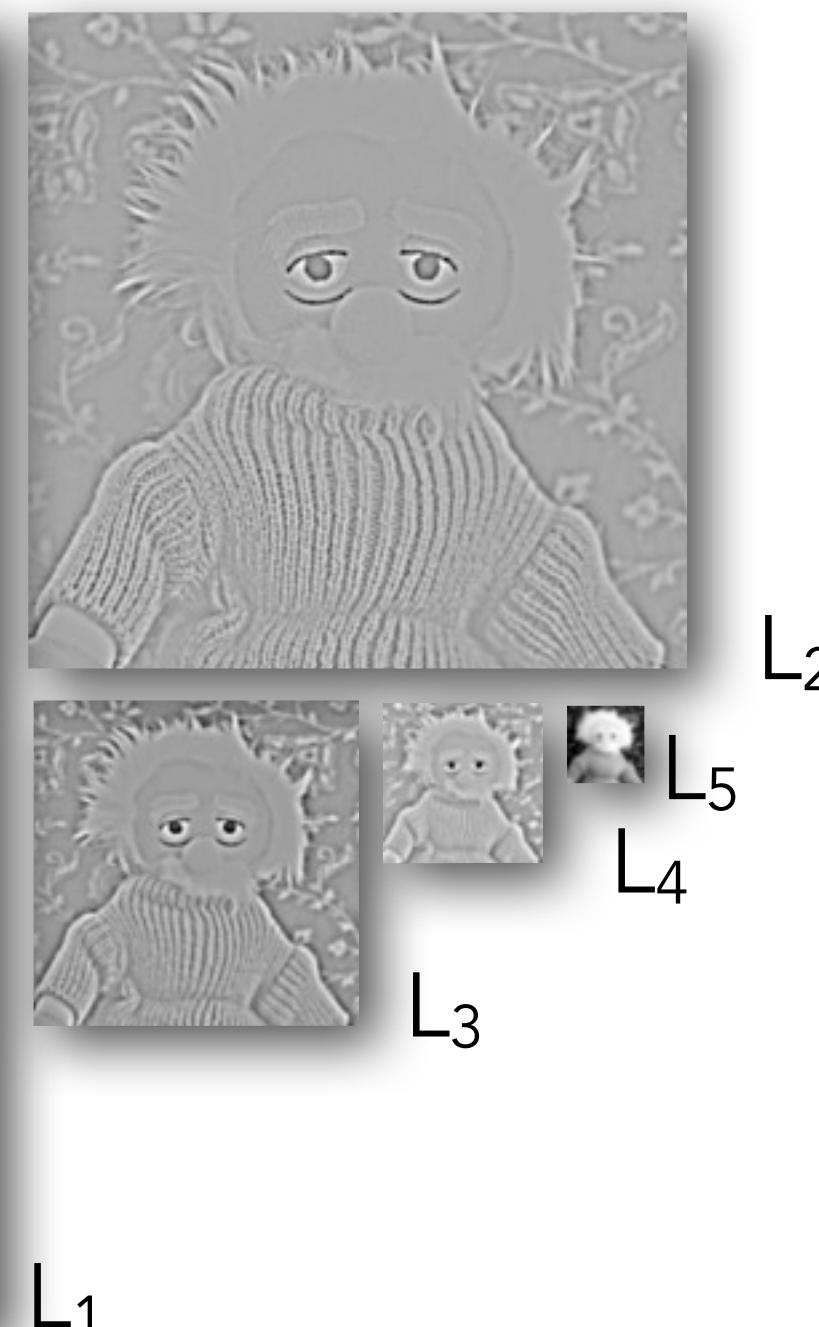


$g_0 - g_{0,1}$
 $g_{0,1}$
 g_0

$g_k = \text{REDUCE}(g_{k-1})$
 $g_{l,n} = \text{EXPAND}(g_l, n-1)$

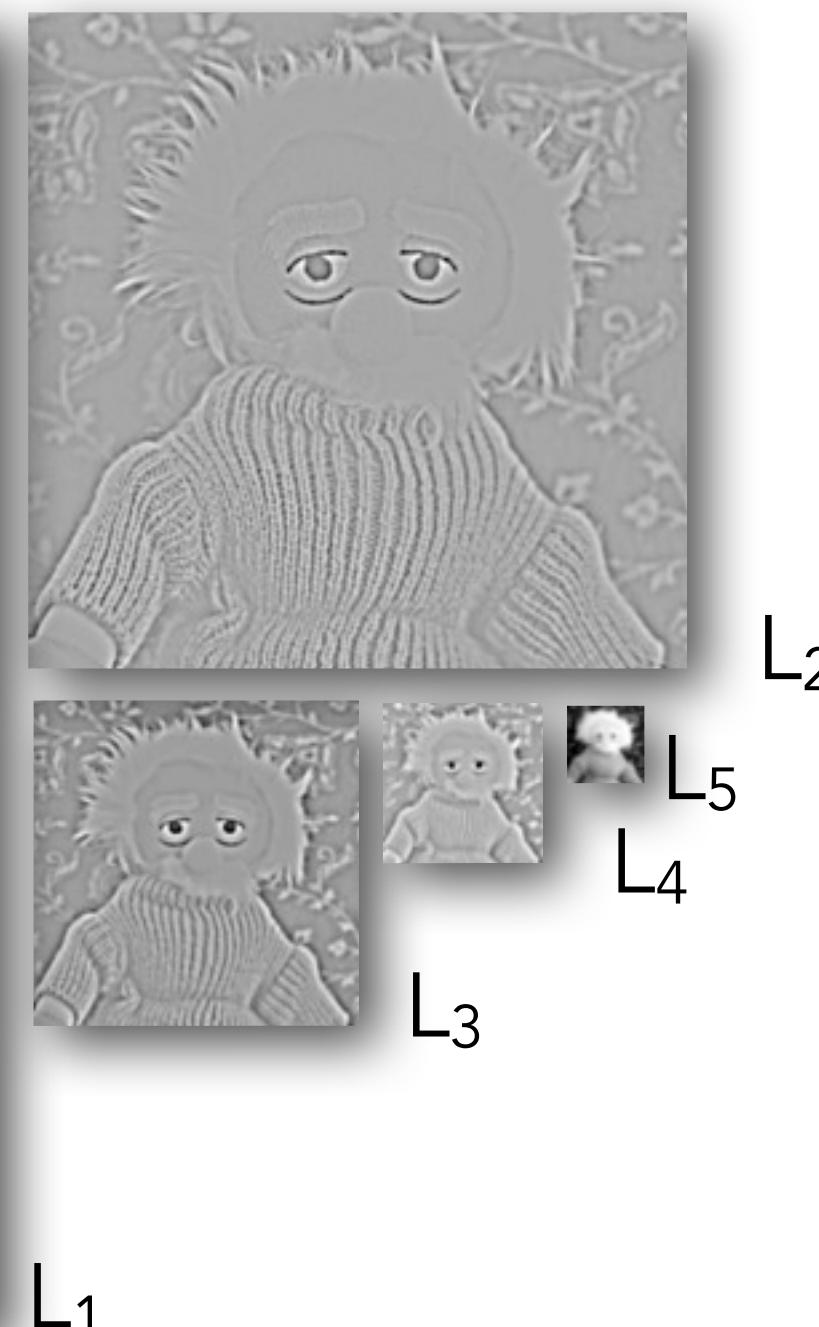
g_1 EXPAND is inverse of REVERSE, as it seeks to add new values in between knowns ones. $g_{l,n}$ is g_l expanded n times

Pyramid Representation of Images (A Gaussian Pyramid)



- ★ A Laplacian Pyramid is a series of “error” images, L_0, L_1, L_2, \dots
- ★ Each is a difference between two levels of a Gaussian Pyramid

Pyramid Representation of Images (A Laplacian Pyramid)



- ★ A Laplacian Pyramid is a series of “error” images, L_0, L_1, L_2, \dots
- ★ Each is a difference between two levels of a Gaussian Pyramid

$$L_I = g_I - \text{EXPAND}(g_{I+1})$$

Pyramid Representation of Images (A Laplacian Pyramid)

g_1

$g_{1,1}$

L_1

Computing Gaussian and Laplacian Pyramids



g_1

$g_{1,1}$

L_1

Computing Gaussian and Laplacian Pyramids



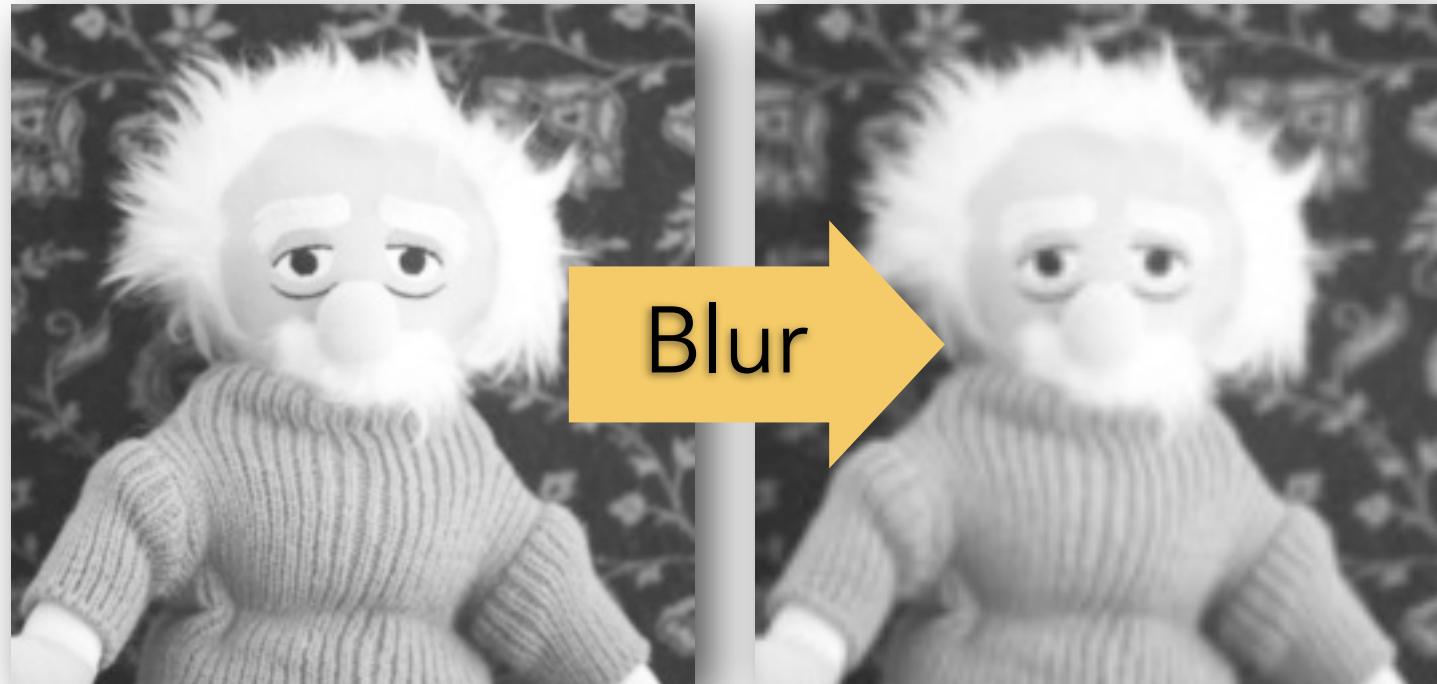
g_1



$g_{1,1}$

L_1

Computing Gaussian and Laplacian Pyramids

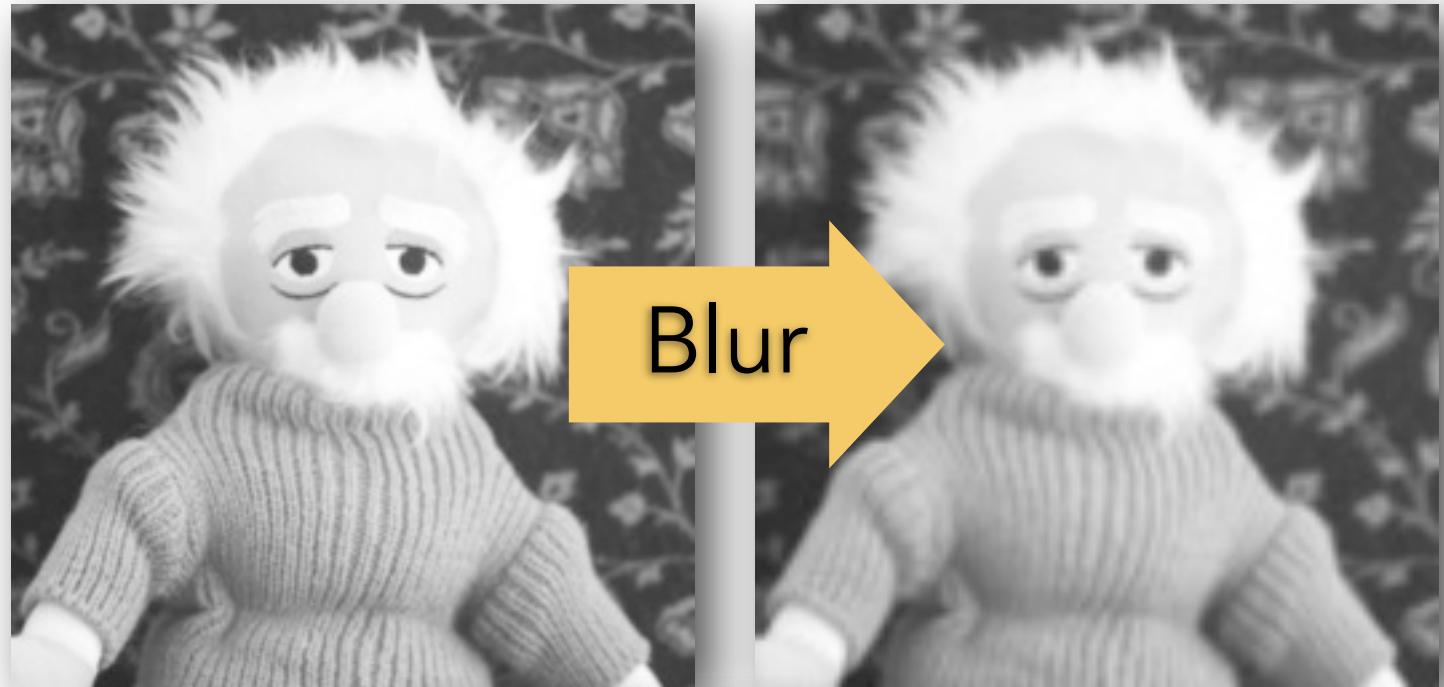


g_1

$g_{1,1}$

L_1

Computing Gaussian and Laplacian Pyramids



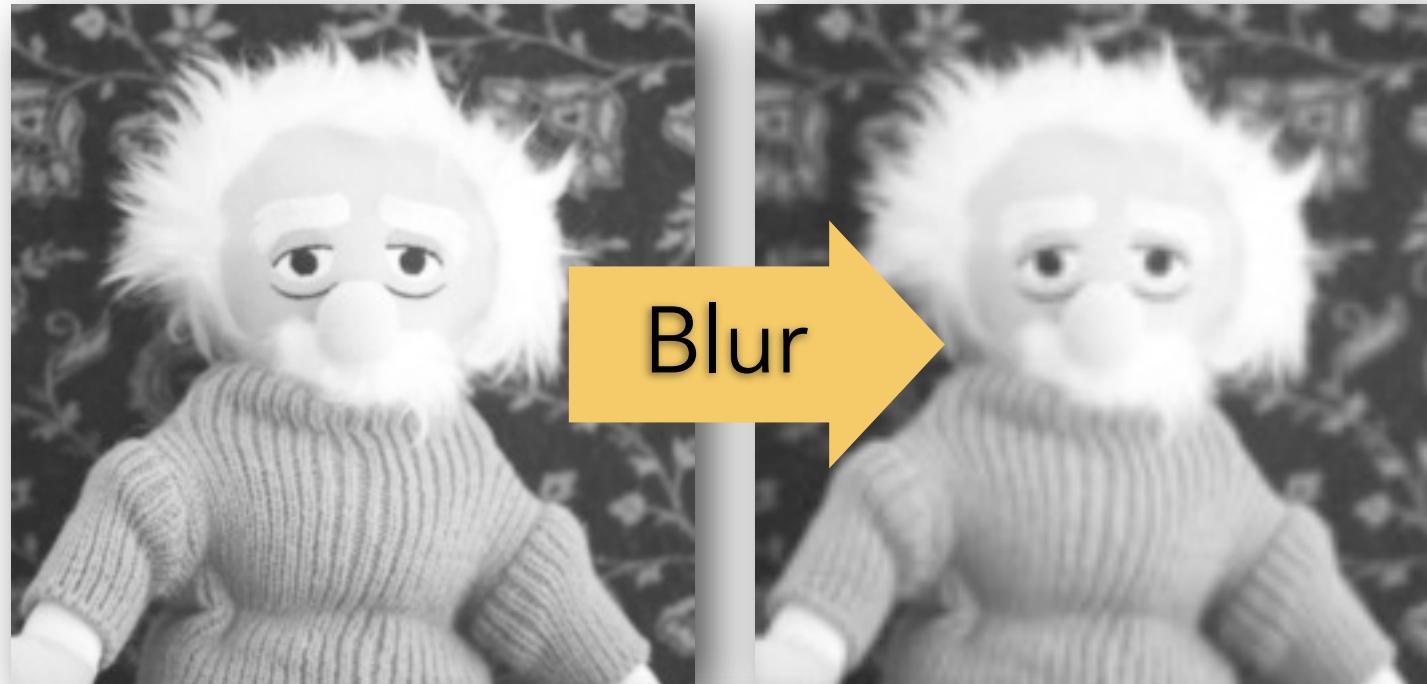
g_1

$g_{1,1}$



L_1

Computing Gaussian and Laplacian Pyramids



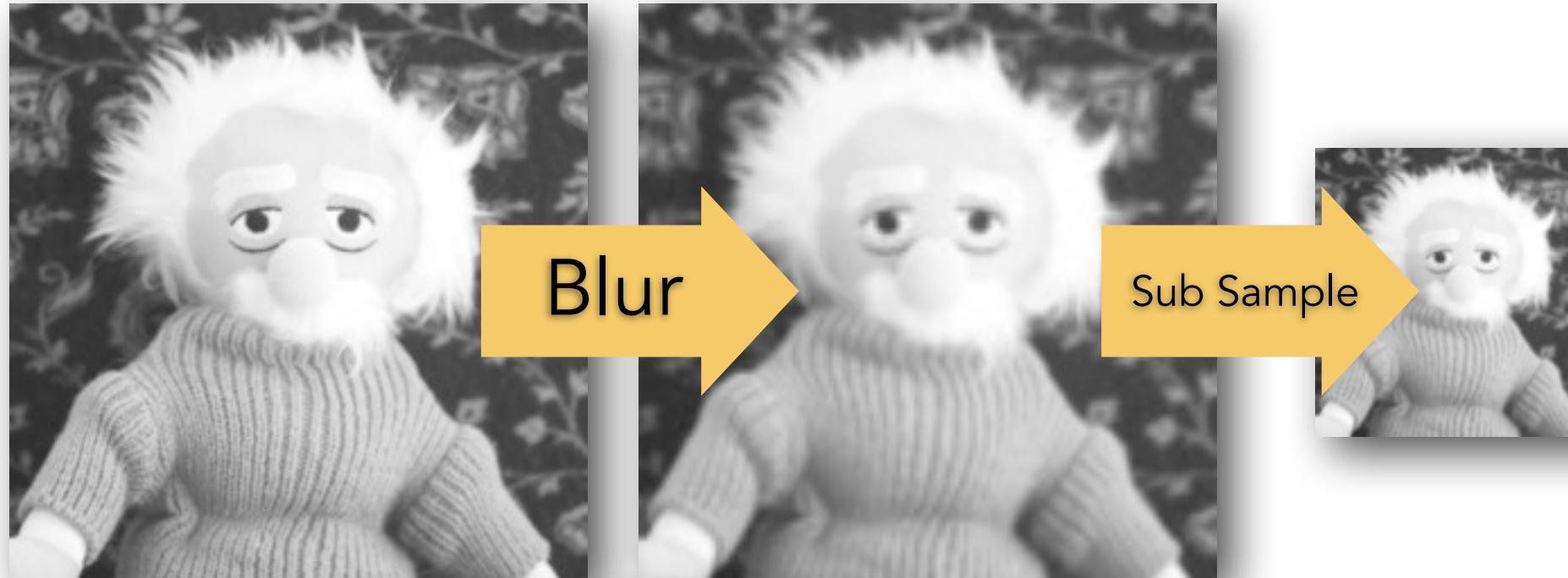
g_1

$g_{1,1}$



L_1

Computing Gaussian and Laplacian Pyramids

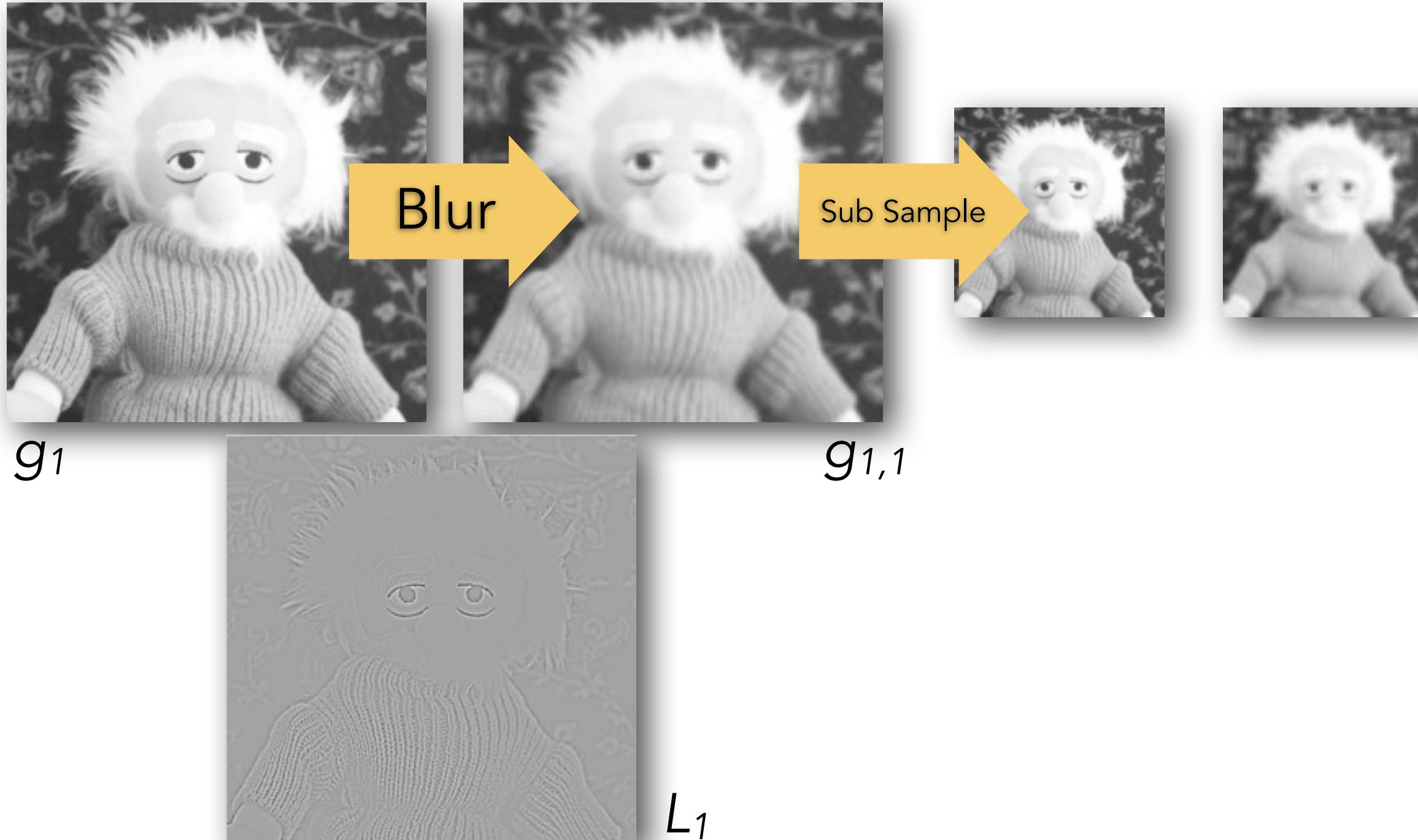


g_1

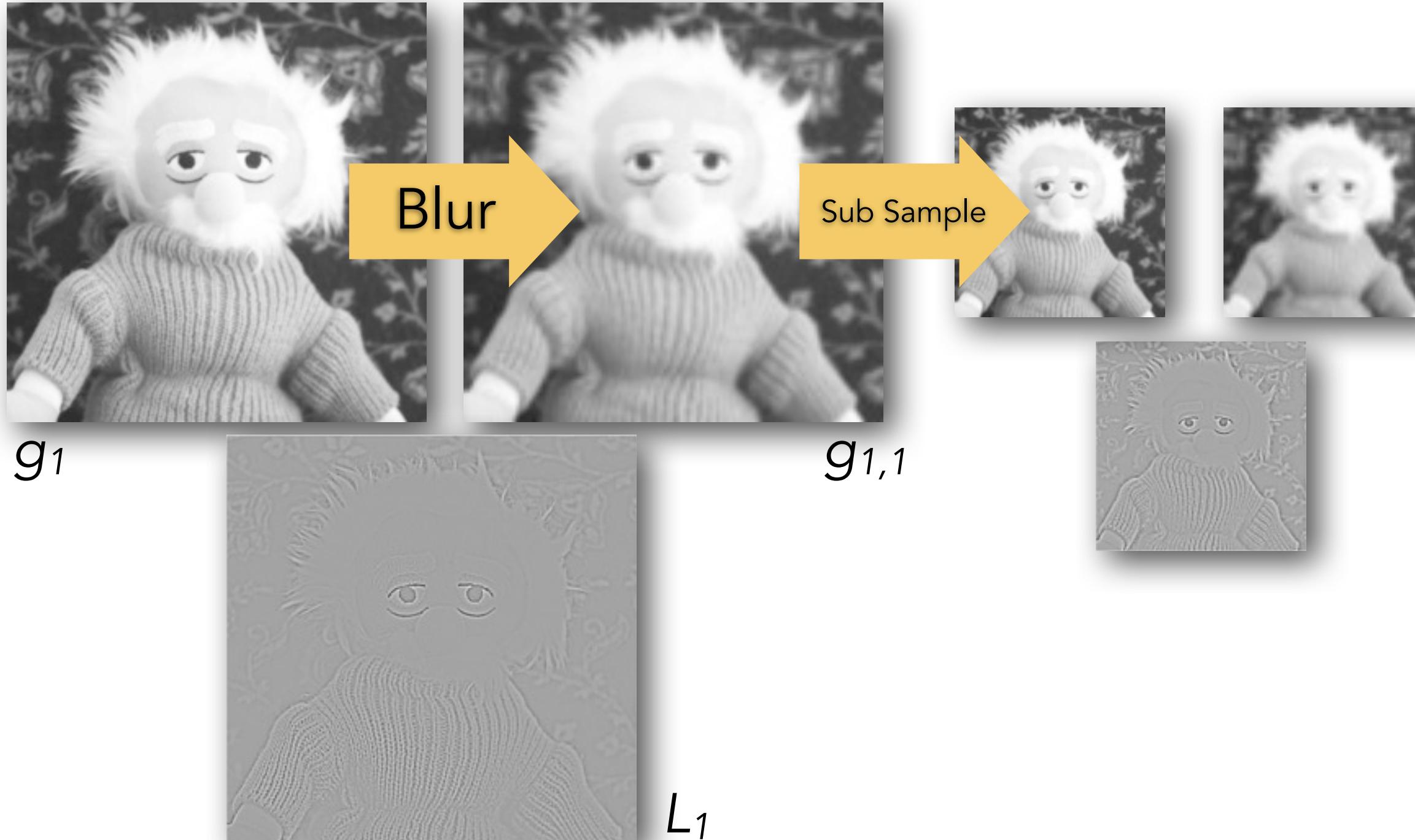
$g_{1,1}$

L_1

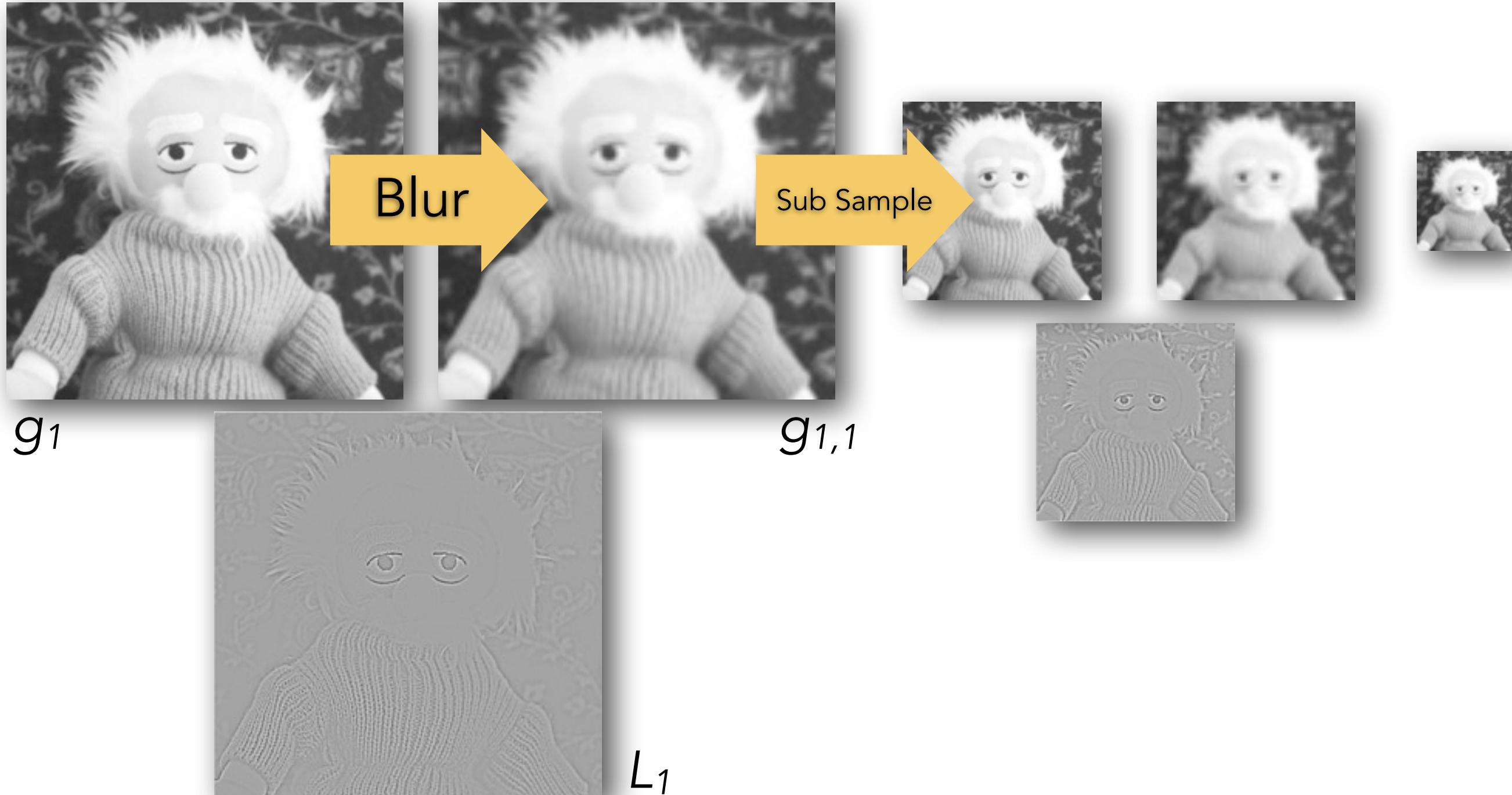
Computing Gaussian and Laplacian Pyramids



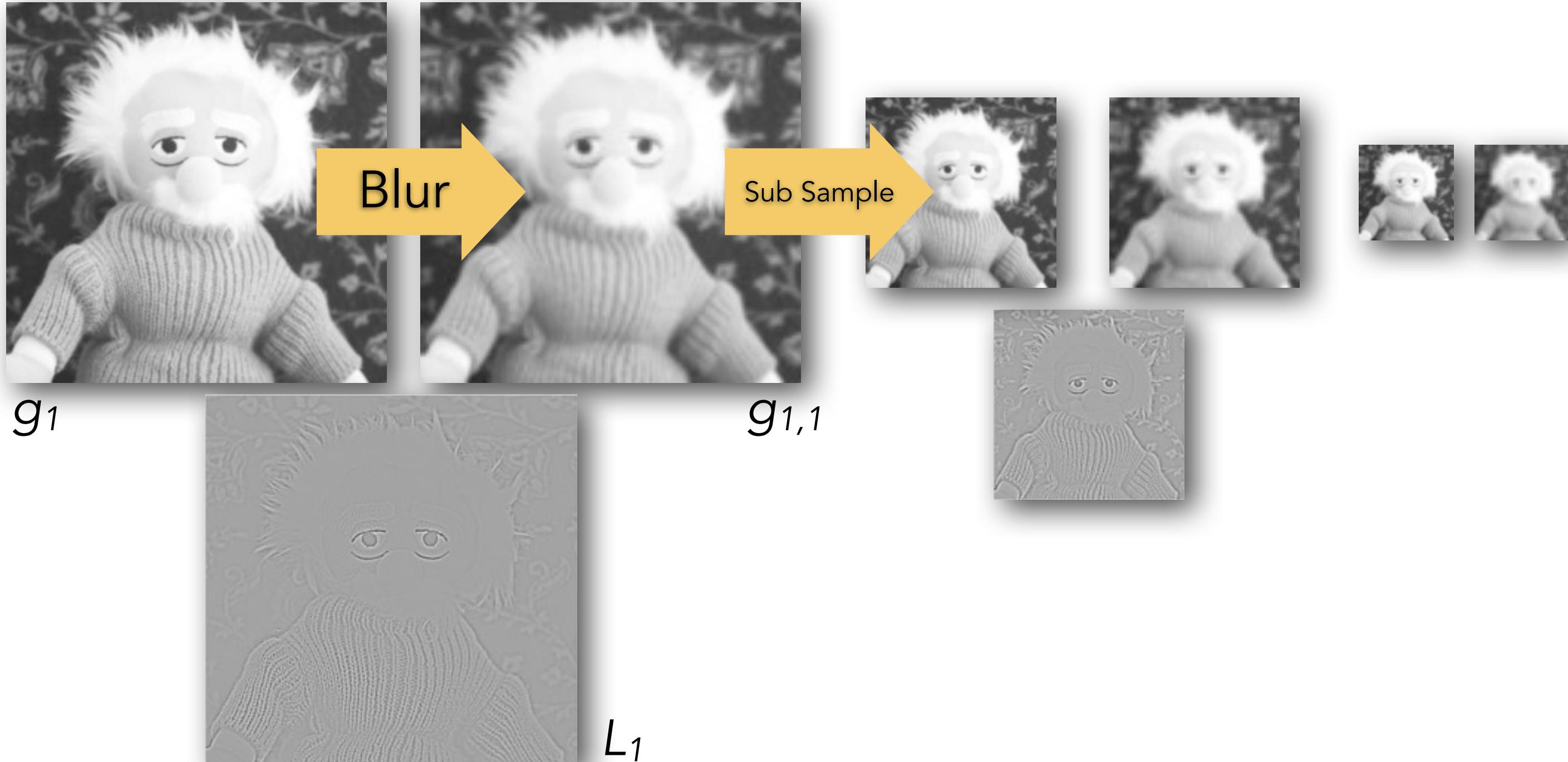
Computing Gaussian and Laplacian Pyramids



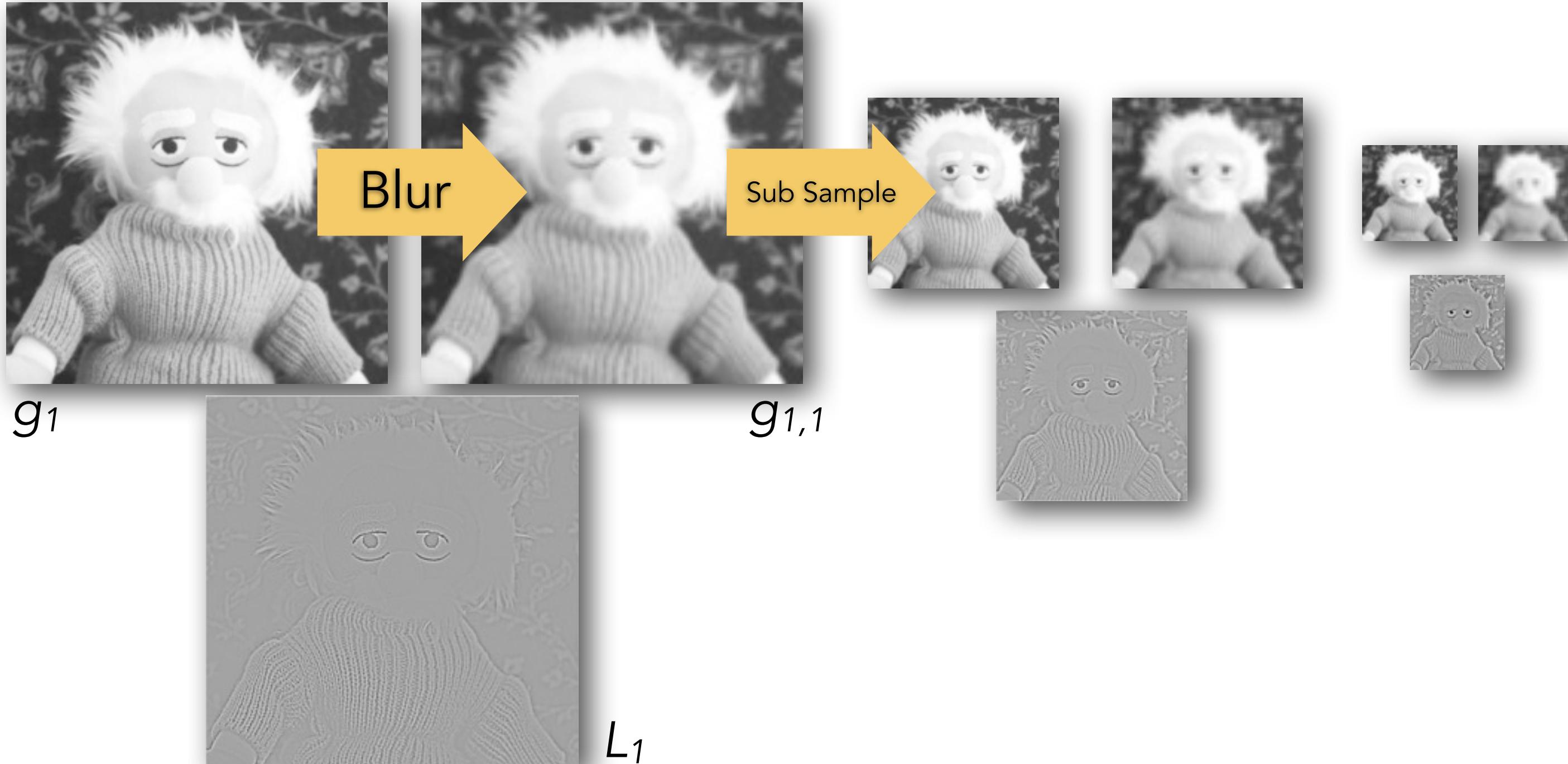
Computing Gaussian and Laplacian Pyramids



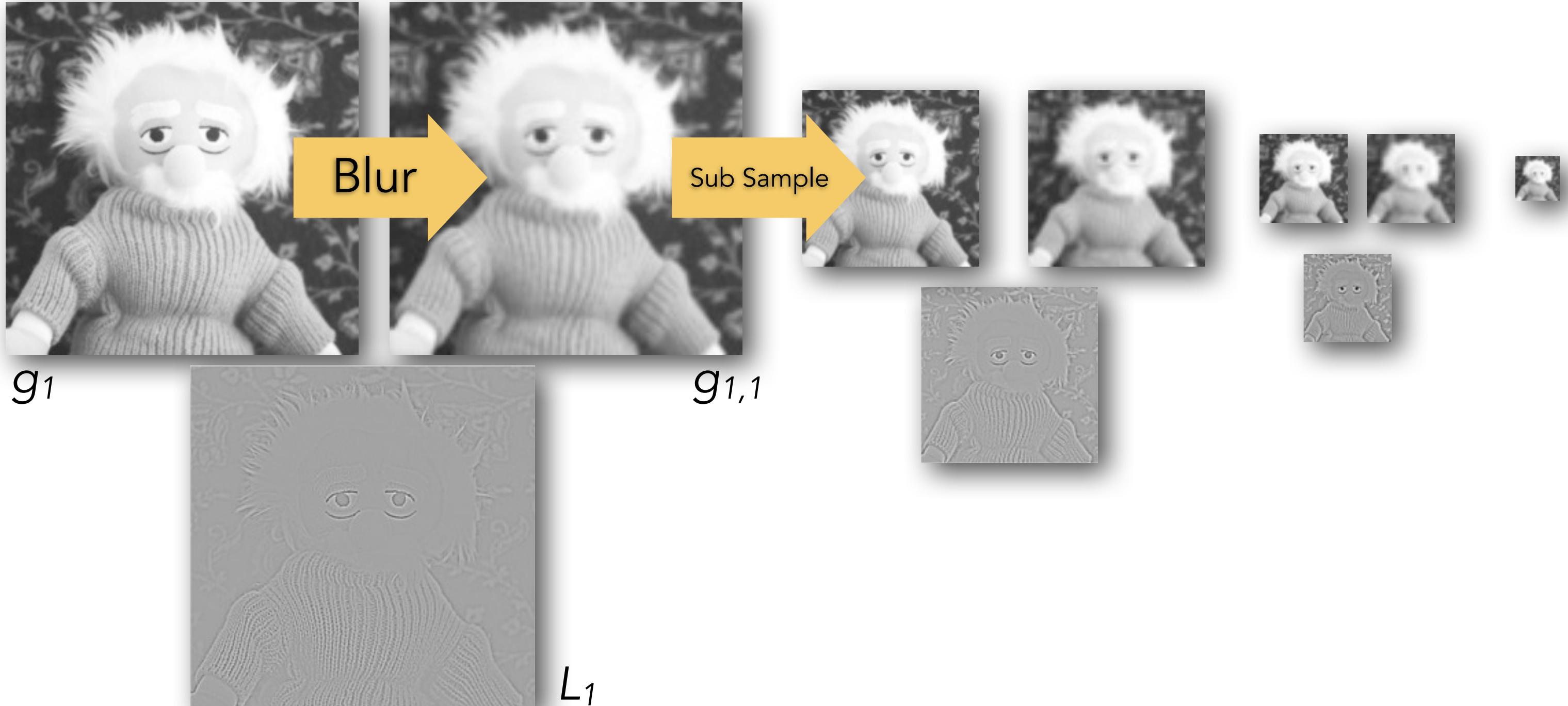
Computing Gaussian and Laplacian Pyramids



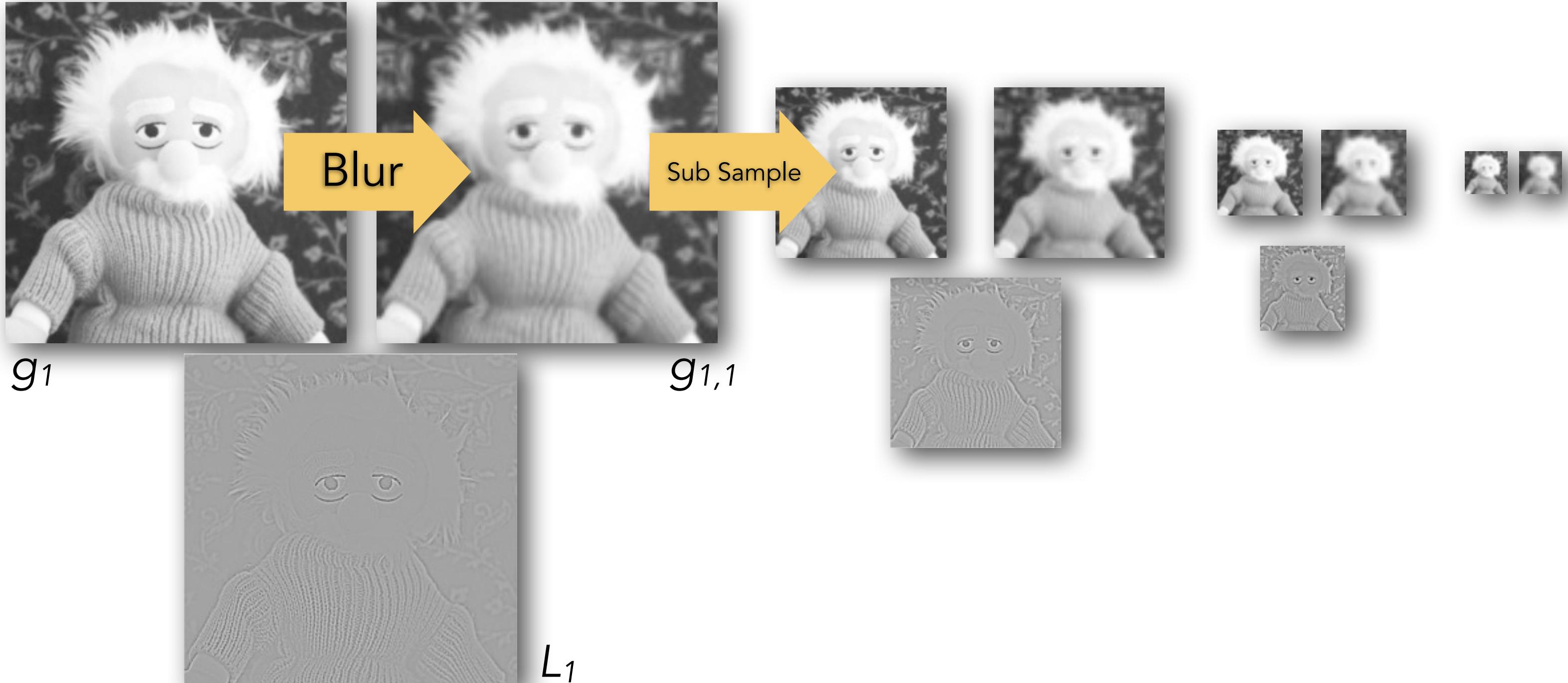
Computing Gaussian and Laplacian Pyramids



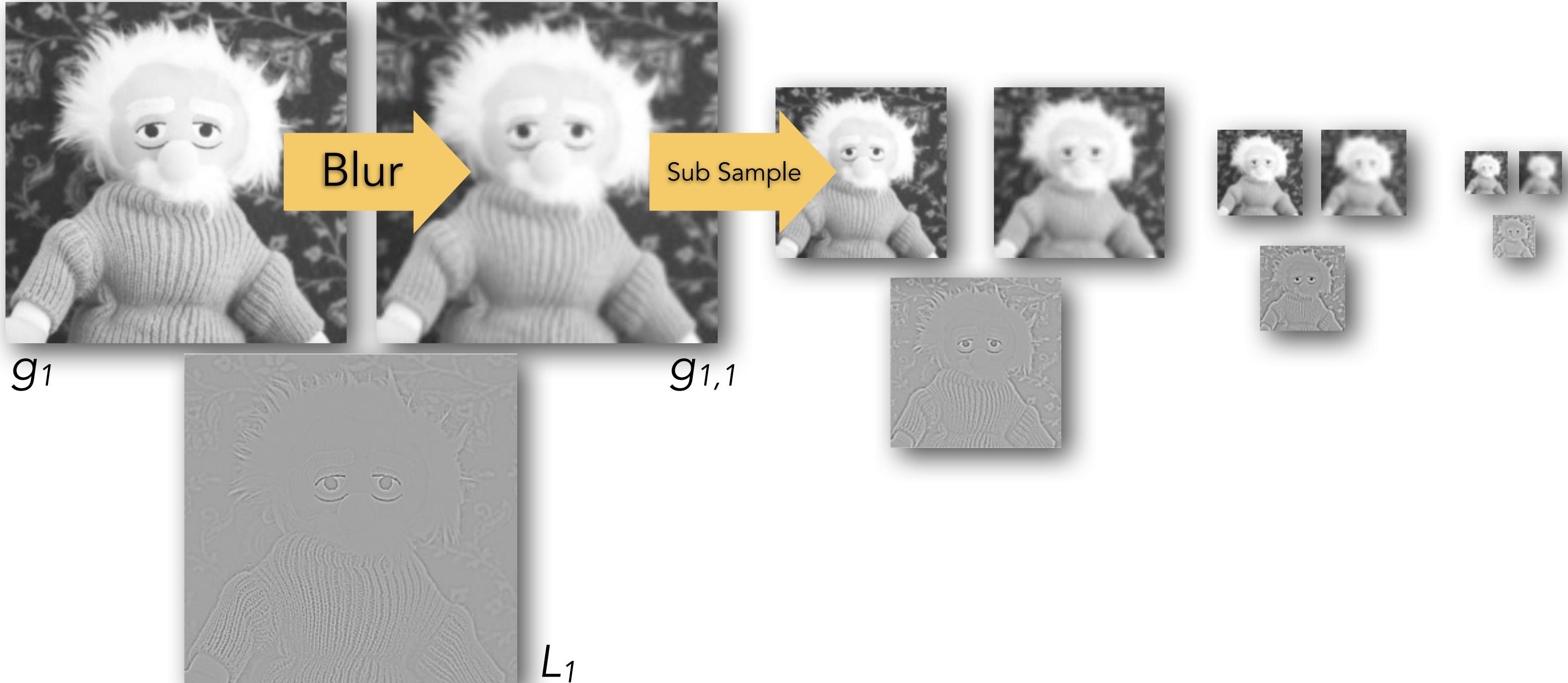
Computing Gaussian and Laplacian Pyramids



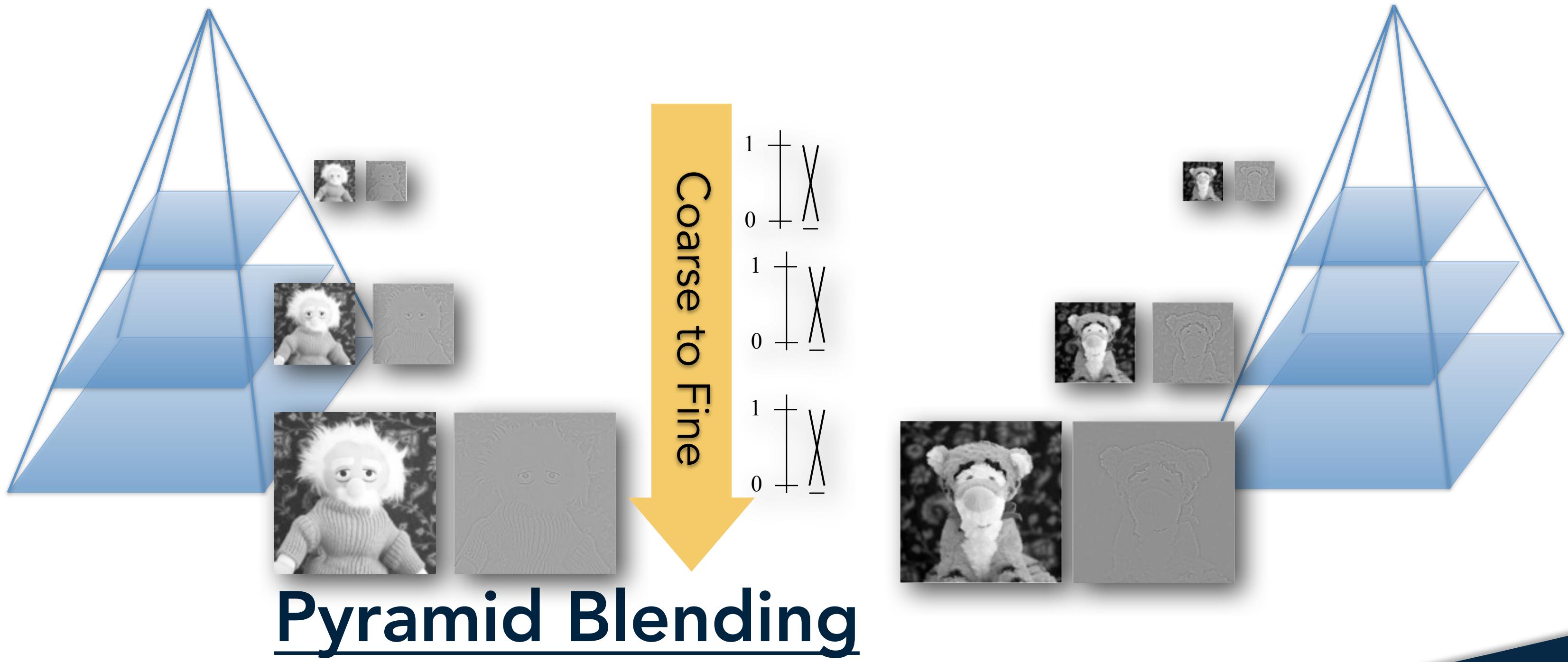
Computing Gaussian and Laplacian Pyramids



Computing Gaussian and Laplacian Pyramids



Computing Gaussian and Laplacian Pyramids





Blend 1

Pyramid Blending Process

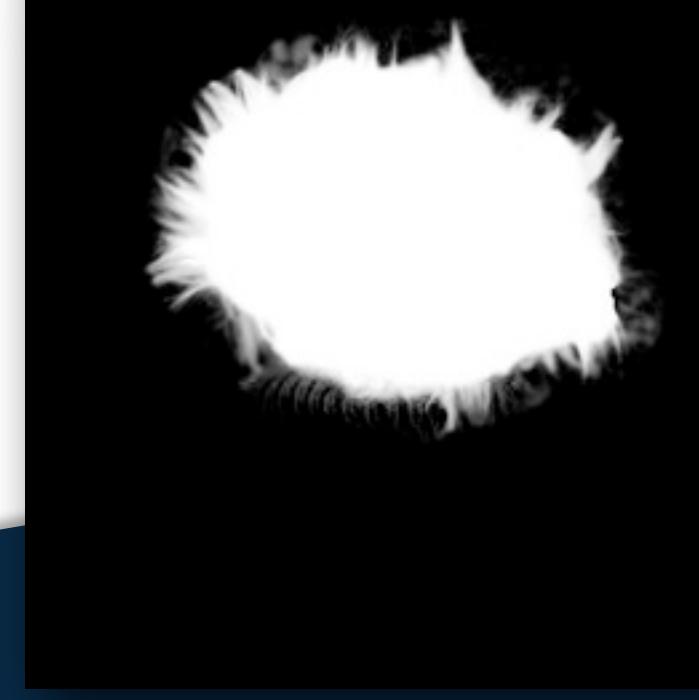
A



B



R



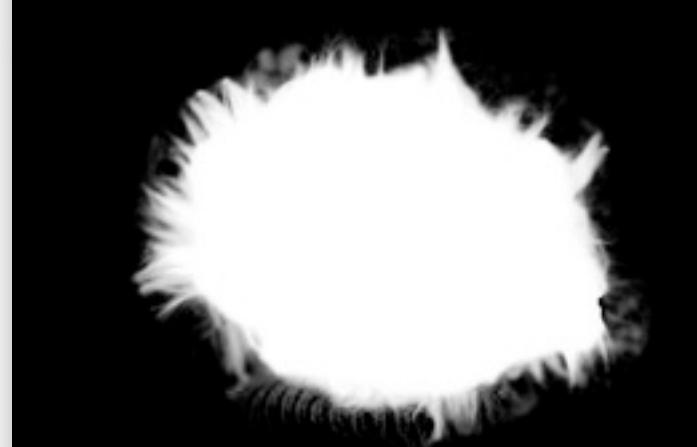
Pyramid Blending Process

- ★ Build Laplacian pyramids L_A and L_B from images A and B

A

B

R



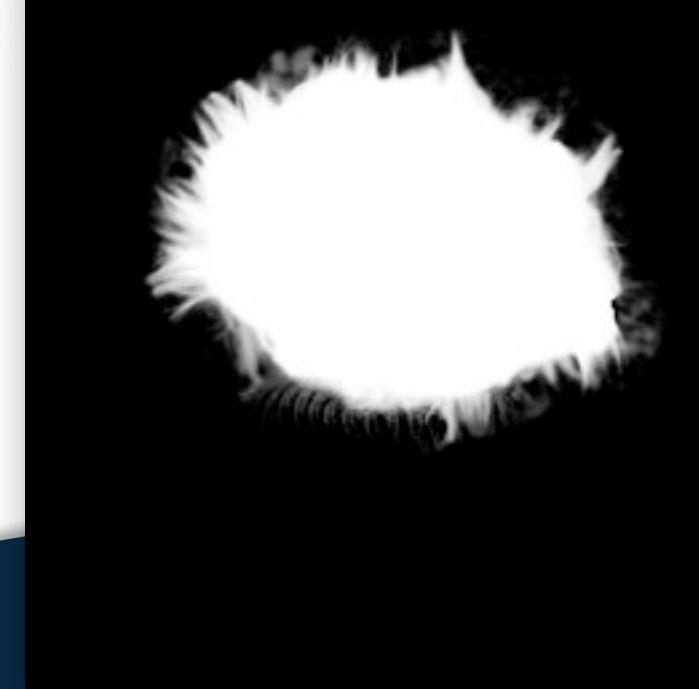
Pyramid Blending Process

- ★ Build Laplacian pyramids L_A and L_B from images A and B
- ★ Build a Gaussian pyramid G_R from selected region R (aka. the Mask Image!).

A

B

R



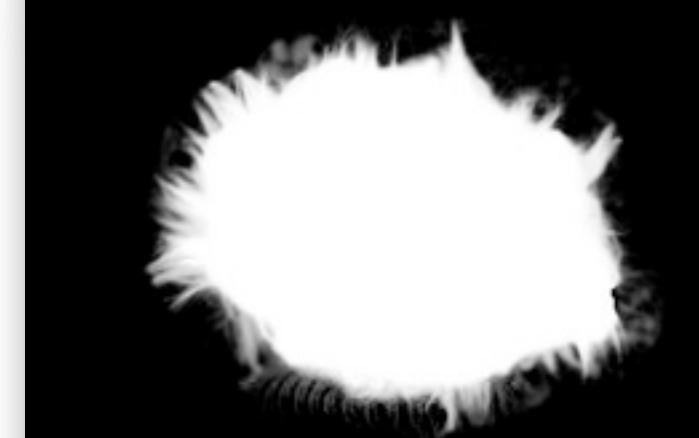
Pyramid Blending Process

- ★ Build Laplacian pyramids L_A and L_B from images A and B
- ★ Build a Gaussian pyramid G_R from selected region R (aka. the Mask Image!).
- ★ Form a combined pyramid L_S from L_A and L_B using nodes of G_R as weights:
 - $$L_S(i,j) = G_R(i,j) * L_A(i,j) + (1-G_R(i,j)) * L_B(i,j)$$

A

B

R



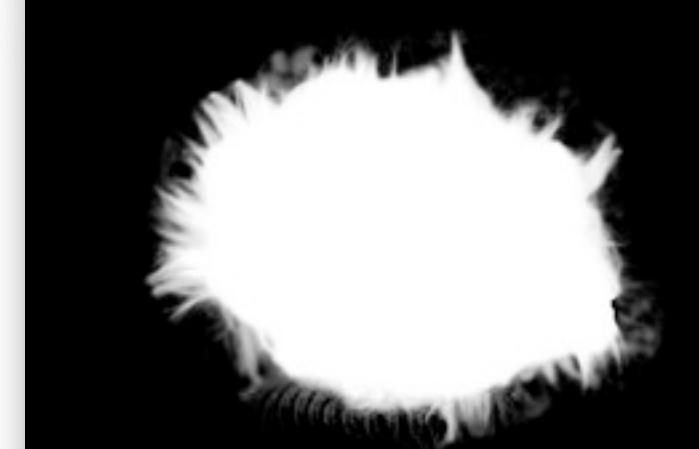
Pyramid Blending Process

- ★ Build Laplacian pyramids L_A and L_B from images A and B
- ★ Build a Gaussian pyramid G_R from selected region R (aka. the Mask Image!).
- ★ Form a combined pyramid L_S from L_A and L_B using nodes of G_R as weights:
 - $$L_S(i,j) = G_R(i,j) * L_A(i,j) + (1-G_R(i,j)) * L_B(i,j)$$
- ★ Collapse the L_S pyramid to get the final blended image

A

B

R



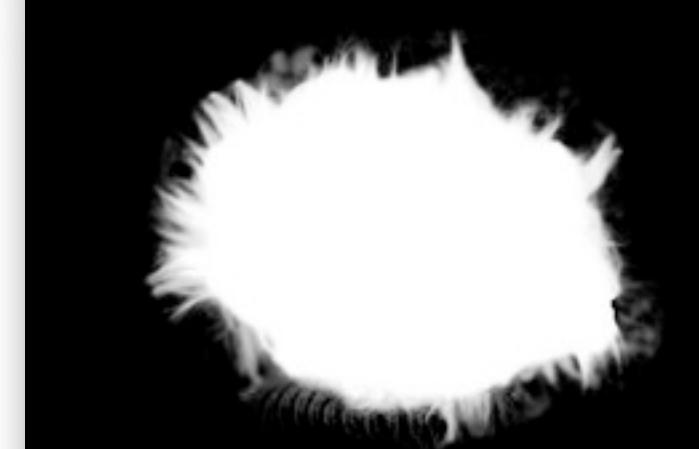
Pyramid Blending Process

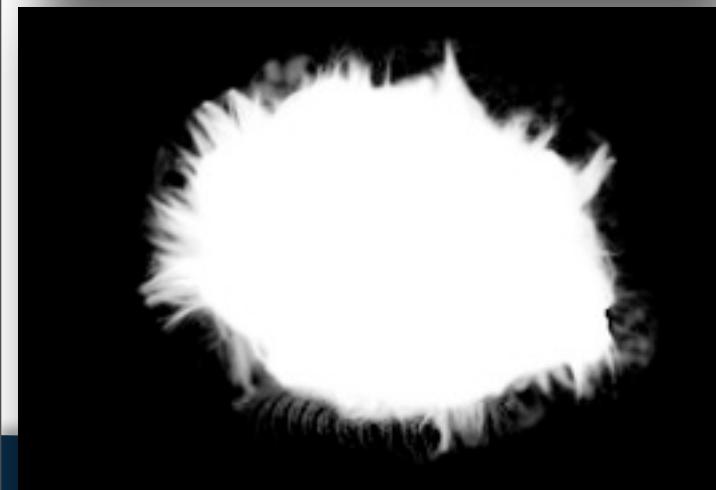
- ★ Build Laplacian pyramids L_A and L_B from images A and B
- ★ Build a Gaussian pyramid G_R from selected region R (aka. the Mask Image!).
- ★ Form a combined pyramid L_S from L_A and L_B using nodes of G_R as weights:
 - $$L_S(i,j) = G_R(i,j) * L_A(i,j) + (1-G_R(i,j)) * L_B(i,j)$$
- ★ Collapse the L_S pyramid to get the final blended image

A

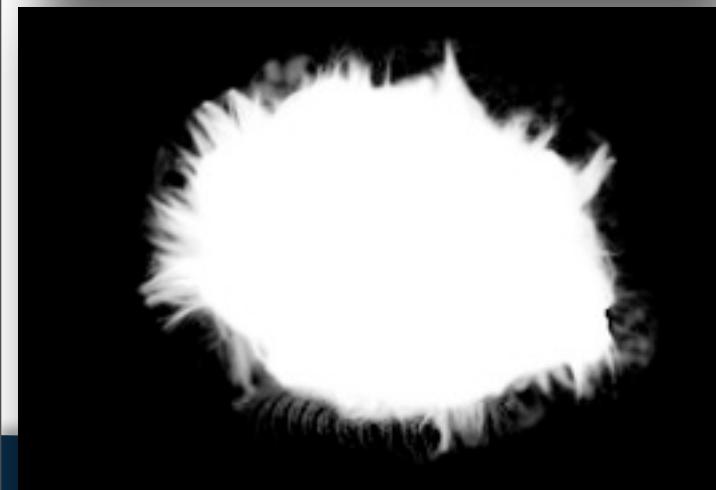
B

R





Blend 2



Blend 2

Summary

- ★ Introduced the concept of merging two images leveraging the Frequency Domain.
- ★ Introduced the Gaussian and the Laplacian Pyramids.
- ★ Discussed the Mathematical formulation to compute a Laplacian.
- ★ Outlined the specific process to blend two images using Pyramids.



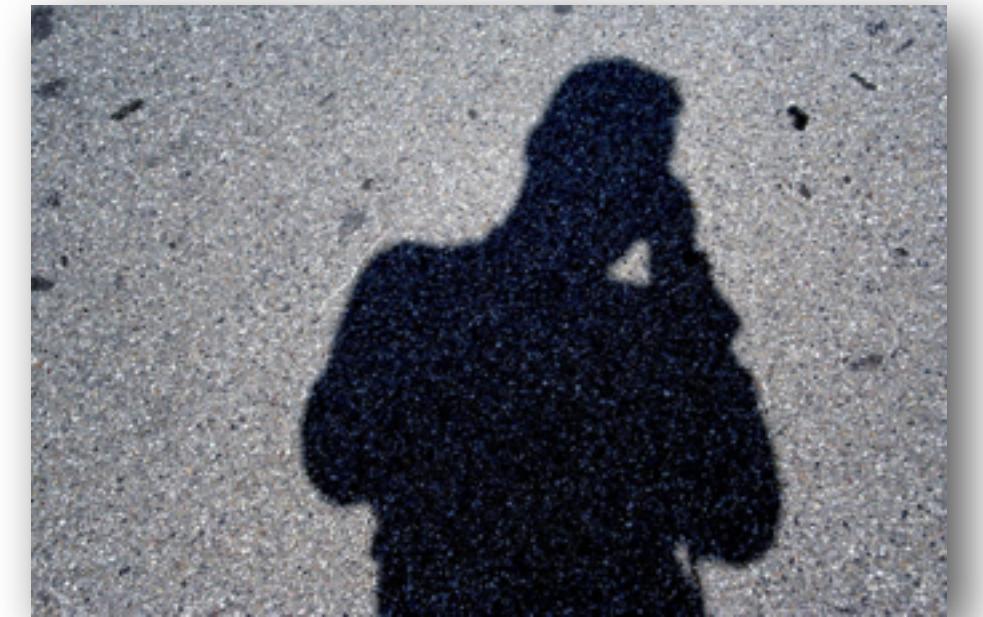
Next Class

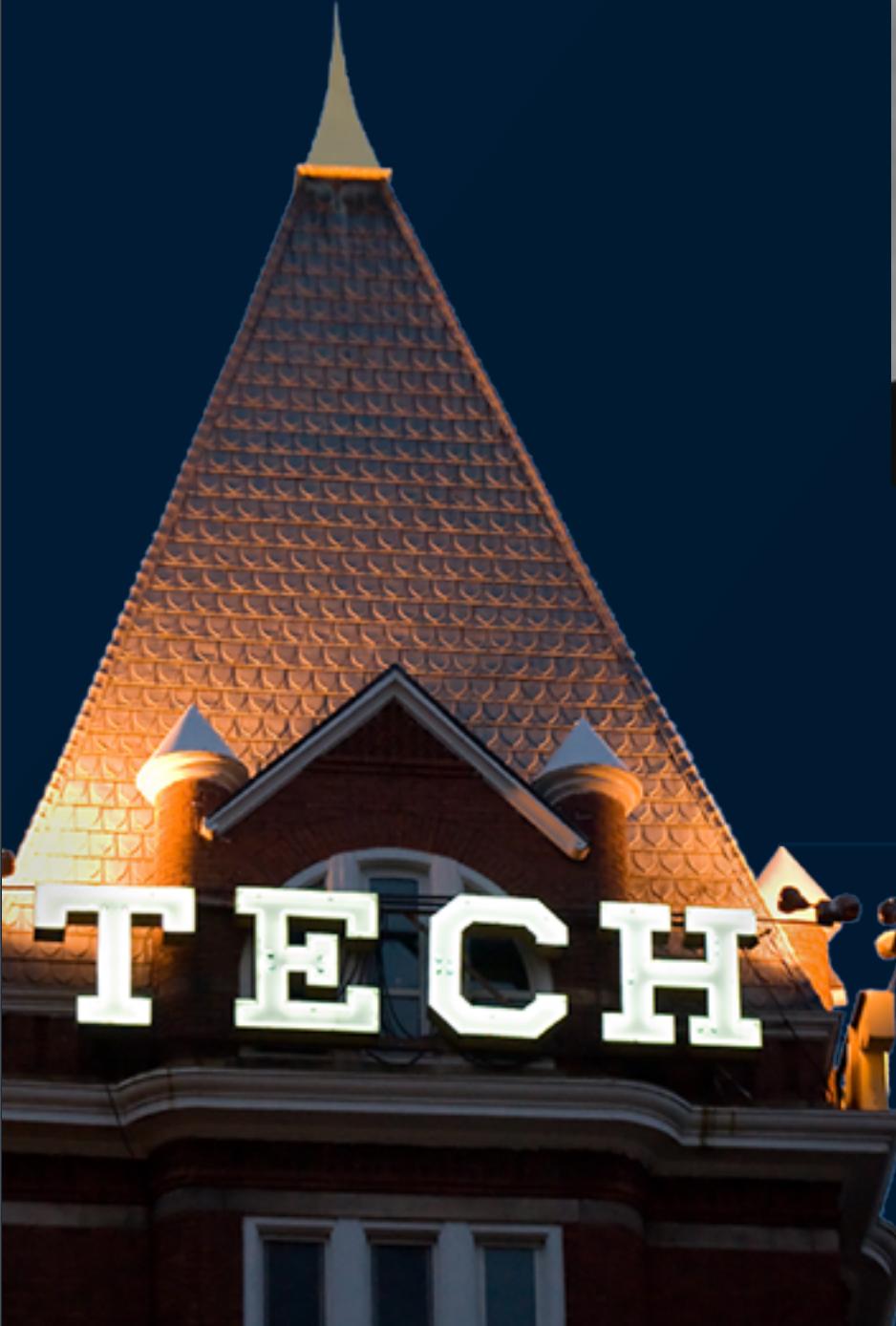
★ Merging and Blending of
Images: Cutting Images



Credits

- ★ For more information, see
 - Richard Szeliski (2010) Computer Vision: Algorithms and Applications, Springer.
 - Burt and Adelson (1983) "The Laplacian Pyramid as a Compact Image Code", In IEEE Transactions on Communications, 31 (4). p 532-540. 1983 (DOI)
 - Burt and Adelson (1983) "A multiresolution spline with application to image mosaics". In ACM Transactions on Graphics, 2 (4). 1983 (DOI)
- ★ Some concepts in slides motivated by similar slides by A. Efros and J. Hays.
- ★ Some images retrieved from
 - <http://commons.wikimedia.org/>.
 - List will be available on website.
 - by Irfan Essa





Computational Photography



Dr. Irfan Essa

Professor

School of Interactive Computing

Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.