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CF

Triangle intersection: clarification

Carlos Gálvez del Postigo Fernández Configuration Space (/learn/robotics-motion-planning/module/EDk8Q/discussions) · 4 days ago (/learn/robotics-motion-planning/discussions/L3VSFNfSEeWsaAqtPzxiow)

I only manage to get 11/15 points in my triangle intersection code, so I guess there are some extreme cases I have not considered.

I would like to ask:

- If one vertex of the triangle lies exactly on the edge of the other triangle, is that considered to be intersecting?
- If two triangles share 2 points (for example, when a square is splitted into two triangles), are those considered to be intersecting?
- Do we need to consider degenerate triangles, which are in fact lines or points?

Thanks.

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一敏 葛 · 4 days ago (/learn/robotics-motion-planning/replies/uEg-gtfbEeW01g7o8S6alw)

1. yes  
2. yes  
3. if you consider above 2 cases, this one is included. however It was no bother , just ignore this situation.

Besides, you can check this link [https://www.coursera.org/learn/robotics-motion-planning/module/EDk8Q/discussions/iLbv5de5EeW9ug73QL\\_FVQ](https://www.coursera.org/learn/robotics-motion-planning/module/EDk8Q/discussions/iLbv5de5EeW9ug73QL_FVQ) ([https://www.coursera.org/learn/robotics-motion-planning/module/EDk8Q/discussions/iLbv5de5EeW9ug73QL\\_FVQ](https://www.coursera.org/learn/robotics-motion-planning/module/EDk8Q/discussions/iLbv5de5EeW9ug73QL_FVQ)). It may help.


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SS

Selvaraj S · 3 days ago (/learn/robotics-motion-planning/discussions/L3VSFNfSEeWsaAqtPzxiow/replies/4PSCS9hyEeWwoQrblHhKaQ)

area of triangle we can find out wheather a point is inside the triange or outside by equatiing area of traingle and sum motion-of 3 triangles formed by point as vertex. if areas equal point is inside otherwise outside. for this we require new fuction that planning/profiles/28cfaf212e937fa37629c3d9930805d3a)

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Yuan Gao · 8 hours ago (/learn/robotics-motion-planning/discussions/L3VSFNfSEeWsaAqtPzxiow/replies/4PSCS9hyEeWwoQrblHhKaQ/comments/kWZ7mNqEeWckg6uCoXykQ)

I did this problem using this method, however I only get 11/15..... Do you get 15/15?

planning/profiles/8be9bdce65e955ab836b713c97290f9)

SD

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1/2

SD

(/learn/robotics-motion-planning/profiles/f34069ce8df6de7dbebfedfb7e760d9f)

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