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Source code for torchvision.transforms

```
from __future__ import division
import torch
import math
import random
from PIL import Image, ImageOps
try:
   import accimage
except ImportError:
   accimage = None
import numpy as np
import numbers
import types
import collections
                                                                                                 [docs]
class Compose(object):
    """Composes several transforms together.
   Args:
        transforms (list of ``Transform`` objects): list of transforms to compose.
        >>> transforms.Compose([
              transforms.CenterCrop(10),
        >>>
        >>>
               transforms.ToTensor(),
        >>> ])
   def __init__(self, transforms):
        self.transforms = transforms
   def __call__(self, img):
        for t in self.transforms:
           img = t(img)
        return img
class ToTensor(object):
                                                                                                 [docs]
   """Convert a ``PIL.Image`` or ``numpy.ndarray`` to tensor.
   Converts a PIL.Image or numpy.ndarray (H x W x C) in the range
   [0, 255] to a torch.FloatTensor of shape (C x H x W) in the range [0.0, 1.0].
                                                                                                 [docs]
   def __call__(self, pic):
        Args:
           pic (PIL.Image or numpy.ndarray): Image to be converted to tensor.
        Returns:
           Tensor: Converted image.
        if isinstance(pic, np.ndarray):
            # handle numpy array
            img = torch.from_numpy(pic.transpose((2, 0, 1)))
            # backward compatibility
           return img.float().div(255)
        if accimage is not None and isinstance(pic, accimage.Image):
            nppic = np.zeros([pic.channels, pic.height, pic.width], dtype=np.float32)
            pic.copyto(nppic)
           return torch.from numpy(nppic)
        # handle PIL Image
        if pic.mode == 'I':
```

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img = torch.from numpy(np.array(pic, np.int32, copy=False))
        elif pic.mode == 'I;16':
            img = torch.from_numpy(np.array(pic, np.int16, copy=False))
        else:
            img = torch.ByteTensor(torch.ByteStorage.from buffer(pic.tobytes()))
        # PIL image mode: 1, L, P, I, F, RGB, YCbCr, RGBA, CMYK
        if pic.mode == 'YCbCr':
           nchannel = 3
        elif pic.mode == 'I;16':
           nchannel = 1
        else:
           nchannel = len(pic.mode)
        img = img.view(pic.size[1], pic.size[0], nchannel)
        # put it from HWC to CHW format
        # yikes, this transpose takes 80% of the Loading time/CPU
        img = img.transpose(0, 1).transpose(0, 2).contiguous()
        if isinstance(img, torch.ByteTensor):
           return img.float().div(255)
       else:
           return img
                                                                                                 [docs]
class ToPILImage(object):
   """Convert a tensor to PIL Image.
   Converts a torch.*Tensor of shape C x H x W or a numpy ndarray of shape
   H x W x C to a PIL. Image while preserving the value range.
                                                                                                  [docs]
   def __call__(self, pic):
        Args:
           pic (Tensor or numpy.ndarray): Image to be converted to PIL.Image.
        Returns:
           PIL.Image: Image converted to PIL.Image.
       npimg = pic
       mode = None
        if isinstance(pic, torch.FloatTensor):
           pic = pic.mul(255).byte()
        if torch.is tensor(pic):
           npimg = np.transpose(pic.numpy(), (1, 2, 0))
        assert isinstance(npimg, np.ndarray), 'pic should be Tensor or ndarray'
        if npimg.shape[2] == 1:
           npimg = npimg[:, :, 0]
           if npimg.dtype == np.uint8:
               mode = 'L'
           if npimg.dtype == np.int16:
               mode = 'I;16'
           if npimg.dtype == np.int32:
               mode = 'I'
            elif npimg.dtype == np.float32:
               mode = 'F
        else:
           if npimg.dtype == np.uint8:
        assert mode is not None, '{} is not supported'.format(npimg.dtype)
        return Image.fromarray(npimg, mode=mode)
                                                                                                  [docs]
class Normalize(object):
    """Normalize an tensor image with mean and standard deviation.
```

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Given mean: (R, G, B) and std: (R, G, B),
   will normalize each channel of the torch.*Tensor, i.e.
   channel = (channel - mean) / std
   Args:
        mean (sequence): Sequence of means for R, G, B channels respecitvely.
        std (sequence): Sequence of standard deviations for R, G, B channels
           respecitively.
   def __init__(self, mean, std):
        self.mean = mean
       self.std = std
   def __call__(self, tensor):
                                                                                                 [docs]
        Args:
           tensor (Tensor): Tensor image of size (C, H, W) to be normalized.
        Returns:
           Tensor: Normalized image.
       # TODO: make efficient
        for t, m, s in zip(tensor, self.mean, self.std):
           t.sub (m).div (s)
        return tensor
                                                                                                 [docs]
class Scale(object):
   """Rescale the input PIL.Image to the given size.
        size (sequence or int): Desired output size. If size is a sequence like
            (w, h), output size will be matched to this. If size is an int,
            smaller edge of the image will be matched to this number.
           i.e, if height > width, then image will be rescaled to
            (size * height / width, size)
        interpolation (int, optional): Desired interpolation. Default is
             `PIL.Image.BILINEAR`
   def init (self, size, interpolation=Image.BILINEAR):
       assert isinstance(size, int) or (isinstance(size, collections.Iterable) and len(size) == 2)
        self.size = size
        self.interpolation = interpolation
   def __call__(self, img):
           img (PIL.Image): Image to be scaled.
       Returns:
           PIL.Image: Rescaled image.
       if isinstance(self.size, int):
           w, h = img.size
           if (w <= h and w == self.size) or (h <= w and h == self.size):</pre>
               return img
           if w < h:
               ow = self.size
               oh = int(self.size * h / w)
               return img.resize((ow, oh), self.interpolation)
           else:
               oh = self.size
               ow = int(self.size * w / h)
```

```
return img.resize((ow, oh), self.interpolation)
       else:
            return img.resize(self.size, self.interpolation)
class CenterCrop(object):
                                                                                                 [docs]
   """Crops the given PIL.Image at the center.
        size (sequence or int): Desired output size of the crop. If size is an
           int instead of sequence like (h, w), a square crop (size, size) is
   def __init__(self, size):
       if isinstance(size, numbers.Number):
           self.size = (int(size), int(size))
       else:
           self.size = size
   def __call__(self, img):
       Args:
           img (PIL.Image): Image to be cropped.
        Returns:
           PIL.Image: Cropped image.
       w, h = img.size
       th, tw = self.size
       x1 = int(round((w - tw) / 2.))
       y1 = int(round((h - th) / 2.))
        return img.crop((x1, y1, x1 + tw, y1 + th))
                                                                                                 [docs]
class Pad(object):
   """Pad the given PIL. Image on all sides with the given "pad" value.
   Args:
        padding (int or sequence): Padding on each border. If a sequence of
           length 4, it is used to pad left, top, right and bottom borders respectively.
       fill: Pixel fill value. Default is 0.
   def __init__(self, padding, fill=0):
        assert isinstance(padding, numbers.Number)
       assert isinstance(fill, numbers.Number) or isinstance(fill, str) or isinstance(fill, tuple)
       self.padding = padding
        self.fill = fill
   def __call__(self, img):
           img (PIL.Image): Image to be padded.
       Returns:
           PIL.Image: Padded image.
        return ImageOps.expand(img, border=self.padding, fill=self.fill)
class Lambda(object):
                                                                                                 [docs]
   """Apply a user-defined lambda as a transform.
```

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lambd (function): Lambda/function to be used for transform.
   def init (self, lambd):
        assert isinstance(lambd, types.LambdaType)
       self.lambd = lambd
   def call (self, img):
       return self.lambd(img)
                                                                                                 [docs]
class RandomCrop(object):
   """Crop the given PIL.Image at a random location.
   Args:
        size (sequence or int): Desired output size of the crop. If size is an
           int instead of sequence like (h, w), a square crop (size, size) is
       padding (int or sequence, optional): Optional padding on each border
           of the image. Default is 0, i.e no padding. If a sequence of length
           4 is provided, it is used to pad left, top, right, bottom borders
           respectively.
   def __init__(self, size, padding=0):
       if isinstance(size, numbers.Number):
           self.size = (int(size), int(size))
       else:
           self.size = size
       self.padding = padding
   def __call__(self, img):
       Args:
           img (PIL.Image): Image to be cropped.
       Returns:
           PIL.Image: Cropped image.
        if self.padding > 0:
           img = ImageOps.expand(img, border=self.padding, fill=0)
       w, h = img.size
        th, tw = self.size
       if w == tw and h == th:
           return img
       x1 = random.randint(0, w - tw)
       y1 = random.randint(0, h - th)
       return img.crop((x1, y1, x1 + tw, y1 + th))
class RandomHorizontalFlip(object):
                                                                                                 [docs]
   """Horizontally flip the given PIL.Image randomly with a probability of 0.5."""
   def __call__(self, img):
           img (PIL.Image): Image to be flipped.
       Returns:
           PIL.Image: Randomly flipped image.
       if random.random() < 0.5:</pre>
```

```
return img.transpose(Image.FLIP LEFT RIGHT)
        return img
class RandomSizedCrop(object):
                                                                                                 [docs]
   """Crop the given PIL.Image to random size and aspect ratio.
   A crop of random size of (0.08 to 1.0) of the original size and a random
   aspect ratio of 3/4 to 4/3 of the original aspect ratio is made. This crop
   is finally resized to given size.
   This is popularly used to train the Inception networks.
   Args:
       size: size of the smaller edge
       interpolation: Default: PIL.Image.BILINEAR
   def init (self, size, interpolation=Image.BILINEAR):
       self.size = size
       self.interpolation = interpolation
   def __call__(self, img):
        for attempt in range(10):
           area = img.size[0] * img.size[1]
           target area = random.uniform(0.08, 1.0) * area
            aspect_ratio = random.uniform(3. / 4, 4. / 3)
           w = int(round(math.sqrt(target area * aspect ratio)))
           h = int(round(math.sqrt(target area / aspect ratio)))
           if random.random() < 0.5:</pre>
               w, h = h, w
           if w <= img.size[0] and h <= img.size[1]:</pre>
               x1 = random.randint(0, img.size[0] - w)
               y1 = random.randint(0, img.size[1] - h)
               img = img.crop((x1, y1, x1 + w, y1 + h))
               assert(img.size == (w, h))
               return img.resize((self.size, self.size), self.interpolation)
       # Fallback
       scale = Scale(self.size, interpolation=self.interpolation)
        crop = CenterCrop(self.size)
        return crop(scale(img))
```