



Course > Final A... > 6.3 Su... > 6.3 Su...

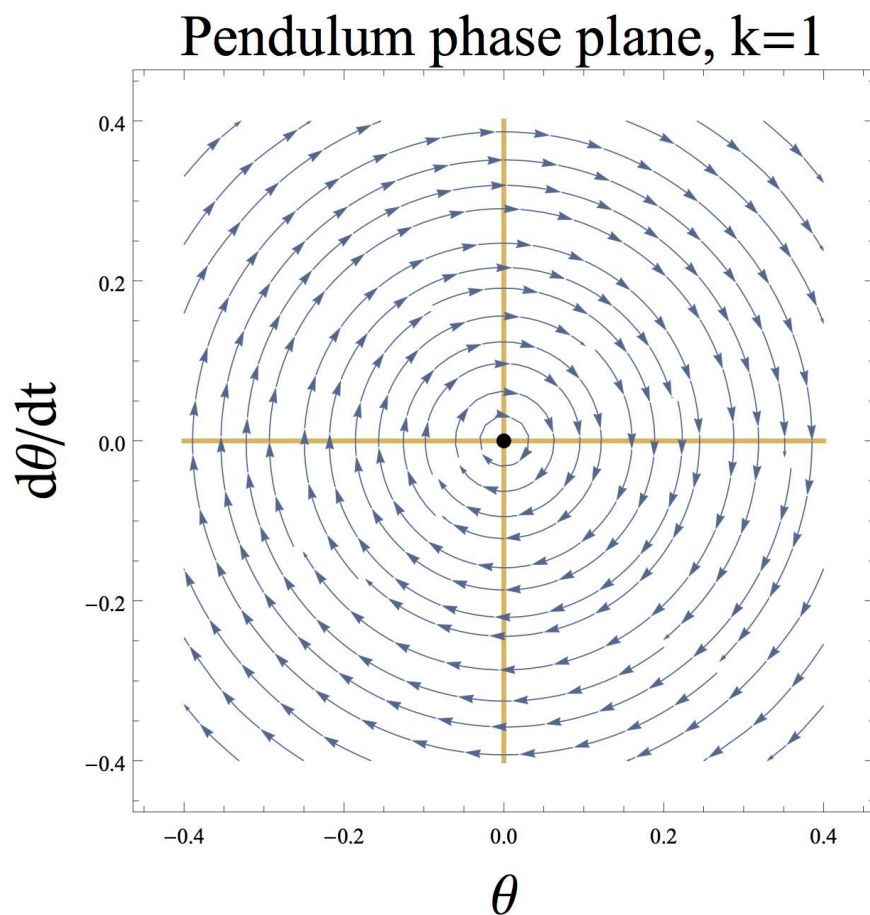
## 6.3 Summary Quiz Part III: What Happens in the Original System for the Pendulum?

🔖 Bookmark this page

Given that we can find exact solutions of the differential equation

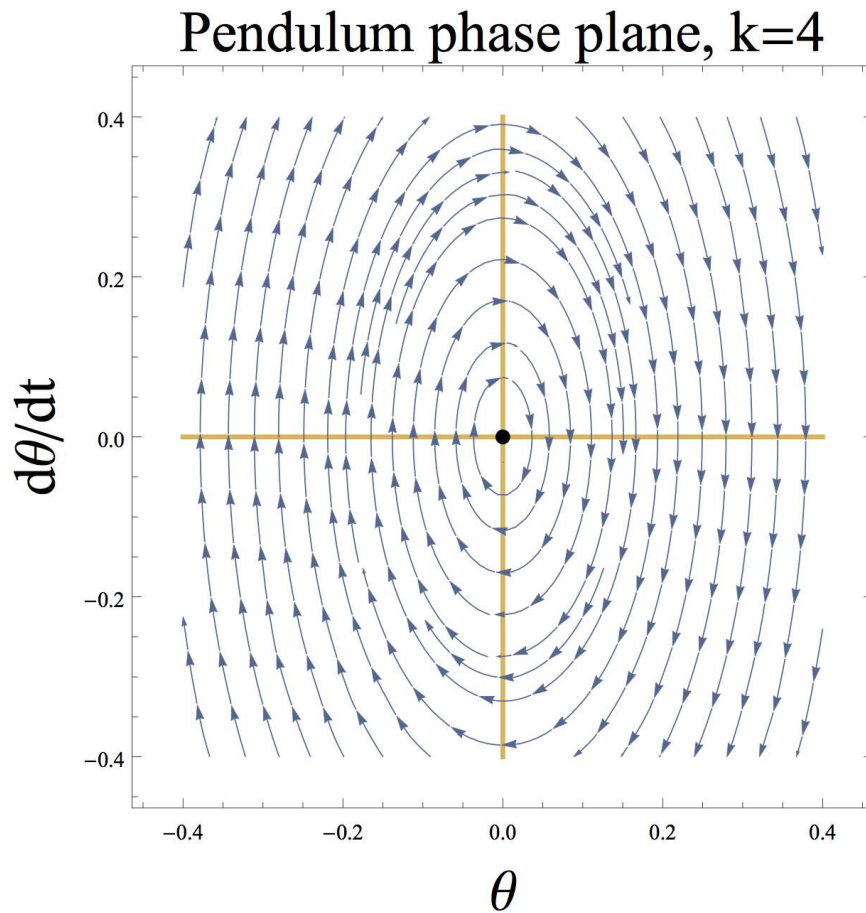
$$\frac{d^2\theta}{dt^2} = -k\theta$$

we might wonder whether phase plane analysis is helpful. One nice feature of the phase plane is that it allows us to see how the position and velocity of the pendulum influence each other.



[View Larger Image](#)

[Image Description](#)




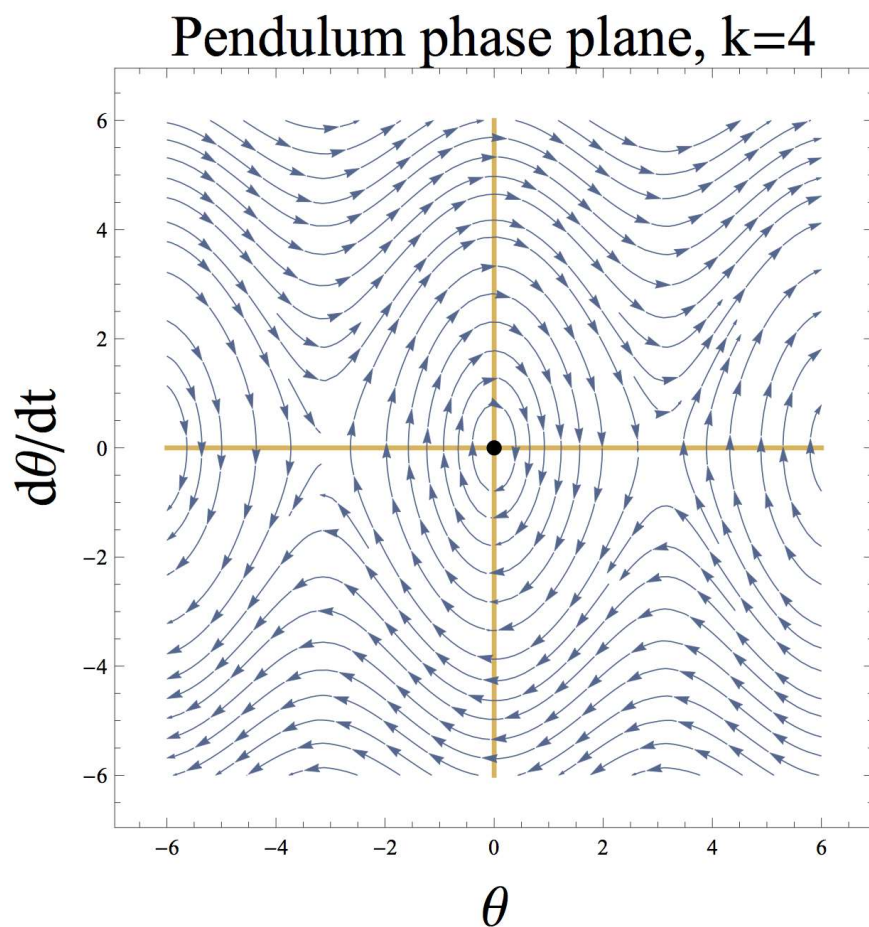
[View Larger Image](#)

Image Description

It is also useful to contrast this phase plane with the phase plane for the original system

$$\frac{d^2\theta}{dt^2} = -k \sin(\theta).$$

Here phase plane analysis is very useful as we can't find exact solutions. Here is the phase plane for  $k =$   with trajectories shown.



[View Larger Image](#)

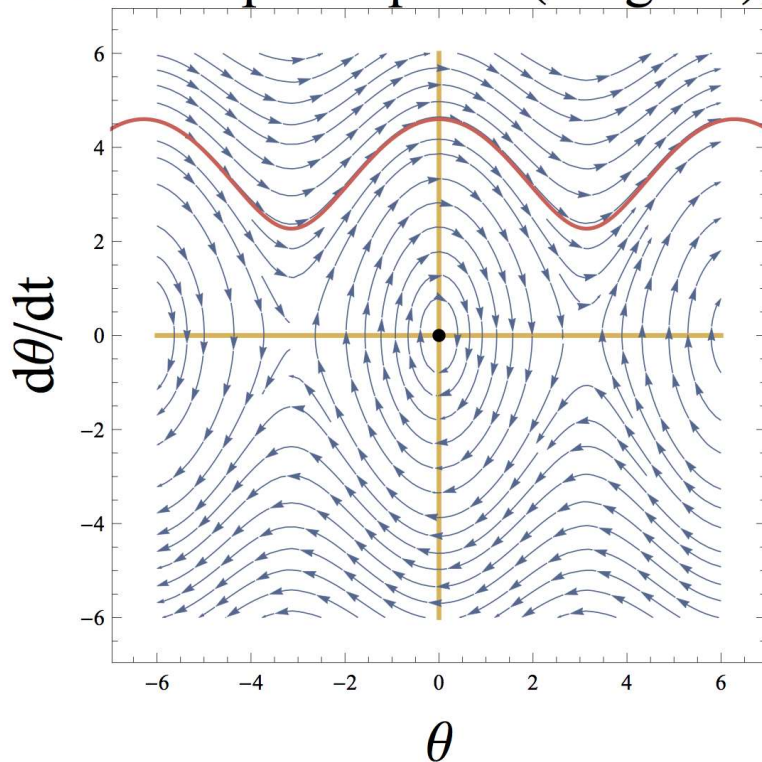
[Image Description](#)

### Question 1: Think About It...

1/1 point (graded)

What is the physical interpretation of the highlighted trajectory?

## Pendulum phase plane (Original), $k=4$



View Larger Image  
Image Description

Changes from one equilibrium state to another.



Thank you for your response.

### Explanation

In this case, we see the trajectory is not a closed loop but an oscillating curve oriented to the right. The angular velocity is always positive, meaning the angle is always increasing, from 0 to  $\pi$  to  $2\pi$  and so on. Physically, this means the pendulum had initial velocity great enough that it could swing over the top of the pivot point and because there is no friction, it will continue to rotate completely around the pivot indefinitely. For more, see the Examples at [https://en.wikipedia.org/wiki/Pendulum\\_\(mathematics\)](https://en.wikipedia.org/wiki/Pendulum_(mathematics)) which show an animated pendulum.

Submit

You have used 1 of 2 attempts

**i** Answers are displayed within the problem

[Learn About Verified Certificates](#)

© All Rights Reserved



© 2012–2018 edX Inc. All rights reserved except where noted. EdX, Open edX and the edX and Open edX logos are registered trademarks or trademarks of edX Inc. | 粤ICP备17044299号-2

POWERED BY  
**OPEN**edX

