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5. Application: finding a basis for the span of any collection of vectors

Given vectors $\mathbf{v}_1, \dots, \mathbf{v}_n \in \mathbb{R}^m$, how can one compute a basis of $\mathrm{Span}(\mathbf{v}_1, \dots, \mathbf{v}_n)$?

Algorithm for computing a basis for $\mathrm{Span}(\mathbf{v}_1,\ldots,\mathbf{v}_n)$

- 1. Form the matrix **A** whose columns are $\mathbf{v}_1, \dots, \mathbf{v}_n$.
- 2. Find a basis for CS(A) (by using a row echelon form as discussed earlier).

Example 5.1 Find a basis for the span of the following vectors:

$$egin{pmatrix} 1 \ -1 \ 1 \ 0 \end{pmatrix}, egin{pmatrix} 2 \ -2 \ 2 \ 0 \end{pmatrix}, egin{pmatrix} 3 \ -3 \ 3 \ 1 \end{pmatrix}, egin{pmatrix} 0 \ 0 \ 0 \ 1 \end{pmatrix}.$$

Start by forming the matrix ${f A}=egin{pmatrix}1&2&3&0\\-1&-2&-3&0\\1&2&3&0\\0&0&1&1\end{pmatrix}$. Find the row echelon form of ${f A}$

using Gaussian elimination:

The pivot columns are the first and third columns, therefore a basis is given by

$$\begin{pmatrix} 1 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ -3 \\ 3 \\ 1 \end{pmatrix}.$$

Finding a basis for a span

1/1 point (graded)

At least one of the following sets of vectors is a basis for the span of the following three vectors

$$\mathbf{v}_1 = egin{pmatrix} 1 \ 2 \ 3 \end{pmatrix}, \mathbf{v}_2 = egin{pmatrix} 4 \ 5 \ 6 \end{pmatrix}, \mathbf{v}_3 = egin{pmatrix} 7 \ 8 \ 9 \end{pmatrix}$$

Find one basis.

\bullet $\mathbf{v}_1, \mathbf{v}_2. \checkmark$		
- 11/12.		

$$\mathbf{v}_1$$
, \mathbf{v}_2 , \mathbf{v}_3 .

$$\mathbf{v}_1, \mathbf{v}_3. \checkmark$$

$$\circ$$
 $\mathbf{v_1}$.

$$\circ$$
 \mathbf{v}_2 .

$$\mathbf{v}_1$$
, $\begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$. \checkmark

Solution:

We first put ${f A}=\left(f v_1 \quad {f v_2} \quad {f v_3} \right)$ into row echelon form:

$$\mathbf{A} = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{pmatrix}$$
$$\longrightarrow \begin{pmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}.$$

Hence $\mathbf{v_1}$ and $\mathbf{v_2}$ form a basis for the column space.

Observe that

$$egin{array}{lll} \mathbf{v}_2 &=& \mathbf{v}_1 + egin{pmatrix} 3 \ 3 \ 3 \end{pmatrix} \ \mathbf{v}_3 &=& \mathbf{v}_1 + 2 egin{pmatrix} 3 \ 3 \ 3 \end{pmatrix} \end{array}$$

In particular, $\mathbf{v_2} = \frac{1}{2}(\mathbf{v_3} + \mathbf{v_1})$. Thus since $\mathbf{v_2}$ can be described in terms of $\mathbf{v_1}$ and $\mathbf{v_3}$, an equally valid basis is $\mathbf{v_1}$ and $\mathbf{v_3}$.

These linear relationships say even more. For example all vectors in the space can be

described as a span of
$$\mathbf{v_1}$$
 and $\begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix}$. Thus $\mathbf{v_1}$ and $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ is also a basis, and in particular, so is $\mathbf{v_1}$ and $\mathbf{v_1} - \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$.

None of the other options serve as bases because they assume dimensions different from ${f 2}.$

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