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Lecture 8: Distance measures

15. Likelihood of a Poisson Statistical

<u>Course</u> > <u>Unit 3 Methods of Estimation</u> > <u>between distributions</u>

> Model

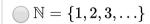
Currently enrolled in Audit Track (expires December 25, 2019) Upgrade (\$300)

## 15. Likelihood of a Poisson Statistical Model

Review: Statistical Model for a Poisson Distribution

2/2 points (graded)

Let  $X_1, \ldots, X_n \overset{iid}{\sim} \operatorname{Poiss}(\lambda^*)$  for some unknown  $\lambda^* \in (0, \infty)$ . Let  $(E, {\{\operatorname{Poiss}(\lambda)\}_{\lambda \in \Theta}})$  denote the corresponding statistical model. What is the smallest possible set that could be E?











The parameter space  $\Theta$  can be written as an interval  $(a, \infty)$ . What is the smallest value of a so that  $\{\operatorname{Poiss}(\lambda)\}_{\lambda \in (a, \infty)}$  represents all possible Poisson distributions?

 $a= \boxed{ ext{0}}$  Answer: 0.0

### Solution:

A Poisson random variable takes values on all non-negative integers  $\{0,1,2,\ldots\}$ . Hence, the smallest possible sample space is  $\mathbb{N} \cup \{0\}$ .

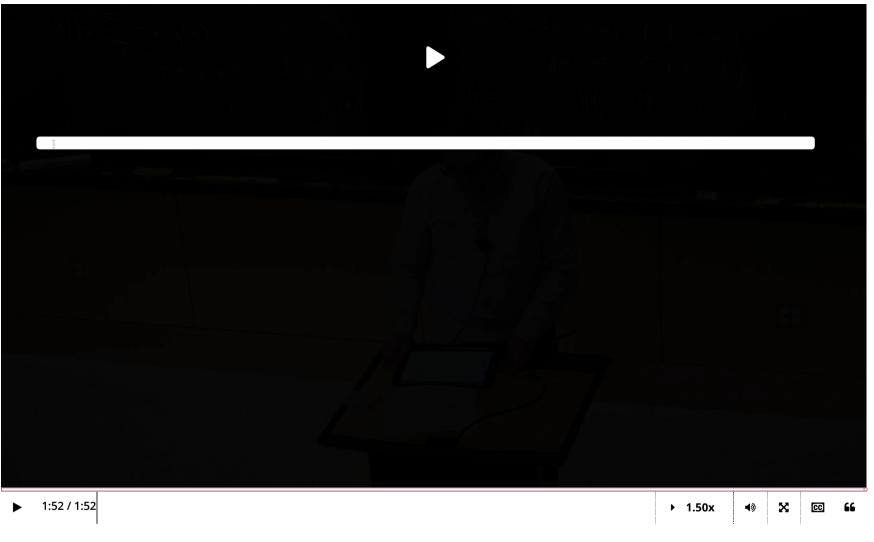
A Poisson random variable is specified by its mean  $\lambda$ , which is allowed to be any positive real number. Hence, a=0 is the correct choice.

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## Likelihood of a Poisson Statistical Model



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Practice: Compute Likelihood of a Poisson Statistical Model

3/3 points (graded)

Let  $X_1, \ldots, X_n \overset{iid}{\sim} \operatorname{Poiss}(\lambda^*)$  for some unknown  $\lambda^* \in (0, \infty)$ . You construct the associated statistical model  $(E, {\{\operatorname{Poiss}(\lambda)\}_{\lambda \in \Theta}})$  where E and  $\Theta$  are defined as in the answers to the previous question.

Suppose you observe two samples  $X_1=1, X_2=2$ . What is  $L_2(1,2,\lambda)$ ? Express your answer in terms of  $\lambda$ .

Next, you observe a third sample  $X_3=3$  that follows  $X_1=1$  and  $X_2=2$ . What is  $L_3$   $(1,2,3,\lambda)$ ?

$$L_3\left(1,2,3,\lambda
ight)= egin{array}{c} {
m e^{-3\cdot\lambda}\cdot\lambda^6} \\ \hline rac{e^{-3\cdot\lambda\cdot\lambda^6}}{12} \end{array}$$

Suppose your data arrives in a different order:  $X_1=2, X_2=3, X_3=1$ . What is  $L_3(2,3,1,\lambda)$ ?

STANDARD NOTATION

#### **Solution:**

The probability mass function of  $\mathrm{Poiss}\,(\lambda)$  is  $x\mapsto e^{-\lambda} rac{\lambda^x}{x!}$  where  $x\in\mathbb{N}\cup\{0\}.$  Hence by definition

$$L_n\left(x_1,\ldots,x_n,\lambda
ight)=\prod_{i=1}^n e^{-\lambda}rac{\lambda^{x_i}}{x_i!}=e^{-n\lambda}rac{\lambda^{\sum_{i=1}^n x_i}}{x_1!\cdots x_n!}.$$

Hence, first we plug in n=2,  $x_1=1$ , and  $x_2=2$ :

$$L_{2}\left(1,2,\lambda
ight)=e^{-2\lambda}rac{\lambda^{1+2}}{2!1!}=e^{-2\lambda}rac{\lambda^{3}}{2}.$$

When the next sample arrives, we can simply evaluate the density of a Poisson at the observation:

$$P(X_3=3)=e^{-\lambda}rac{\lambda^3}{3!}, \quad X\sim ext{Poiss}\left(\lambda
ight)$$

and multiply this by the previous response:

$$L_{3}\left(1,2,3,\lambda
ight)=e^{-\lambda}rac{\lambda^{3}}{3!}L_{2}\left(1,2,\lambda
ight)=e^{-3\lambda}rac{\lambda^{6}}{12}.$$

**Remark 1:** Observe that we can compute the likelihood sequentially as the data arrives, updating it in the previous fashion after each new observation.

Similarly, we see that

$$L_{3}\left( 2,3,1,\lambda 
ight) =e^{-3\lambda }rac{\lambda ^{6}}{12}.$$

**Remark 2**: Observe that the likelihood of observations  $X_1 = x_1, \dots, X_n = x_n$  is independent of the *order* in which these observations arrive.

You have used 1 of 3 attempts

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# Properties of the Likelihood

1/1 point (graded)

Let  $(E, \{P_{\theta}\}_{\theta \in \Theta})$  denote a discrete statistical model. Let  $p_{\theta}$  denote the pmf of  $P_{\theta}$ . Let  $X_1, \ldots, X_n \overset{iid}{\sim} P_{\theta^*}$  where the parameter  $\theta^*$  is unknown. Then the **likelihood** is the function

$$L_{n}:E^{n} imes\Theta\;
ightarrow\mathbb{R} \ (x_{1},\ldots,x_{n}, heta)\mapsto\prod_{i=1}^{n}p_{ heta}\left(x_{i}
ight).$$

For our purposes, we think of  $x_1, \ldots, x_n$  as observations of the random variables  $X_1, \ldots, X_n$ .

Which of the following are properties of the likelihood  $L_n$ ? (Choose all that apply.)

**Hint**: It may be useful to consider your responses from the previous question.

- The likelihood does not change with the parameter  $\theta$ .
- $lap{lacksquare}$  The likelihood can be updated sequentially as new samples are observed. For example,  $L_3\left(x_1,x_2,x_3, heta
  ight)=L_1\left(x_3, heta
  ight)L_2\left(x_1,x_2, heta
  ight)$
- The likelihood is symmetric: it doesn't matter the order in which we plug in the observations. For example,  $L_4(x_1, x_2, x_3, x_4, \theta) = L_4(x_2, x_3, x_1, x_4, \theta)$  and this is true for any rearrangement of  $x_1, x_2, x_3, x_4$ .
- lacksquare If we eliminate a single observation, then the likelihood remains unchanged. For example,  $L_3\left(x_1,x_2,x_3, heta
  ight)=L_2\left(x_1,x_2, heta
  ight)$

#### Solution:

We examine the choices in order.

- "The likelihood does not change with the parameter  $\theta$ ." is incorrect. Rather, it is crucial that we interpret the likelihood  $L_n$  as a function of  $\theta$ . That is,  $L_n$  varies as  $\theta$  ranges over the parameter space  $\Theta$ . This is evident in the likelihoods for the Bernoulli and Poisson models in the previous problems.
- "The likelihood can be updated sequentially as new samples are observed. For example,  $L_3\left(x_1,x_2,x_3,\theta\right)=L_1\left(x_3,\theta\right)L_2\left(x_1,x_2,\theta\right)$ ." is also correct. In the previous problem, we saw that to compute the likelihood after observing  $X_3=3$ , we simply took the old likelihood  $L_2\left(1,2,\lambda\right)$  and multiplied it by  $L_1\left(3,\lambda\right)$ . Note that  $L_1\left(x_3,\theta\right)=p_\theta\left(x_3\right)$ , the density of  $P_\theta$  evaluated at the new observation. Inspection of the defining formula

$$L_{n}\left(x_{1},\ldots,x_{n}, heta
ight)=\prod_{i=1}^{n}p_{ heta}\left(x_{i}
ight)$$

implies that the likelihood can be updated sequentially in this fashion.

• "The likelihood is symmetric..." is correct. We observed in the previous problem that observing the samples in a different order does not affect the likelihood. This is also evident from the definition of the likelihood: we can take the product

$$\prod_{i=1}^{n}p_{ heta}\left(x_{i}
ight)$$

in any order, and the result will still be the same.

• "If we eliminate a single observation, then the likelihood remains unchanged..." is incorrect. In the previous question, we saw that for a Poisson statistical model,  $L_2$   $(1,2,\lambda)$  and  $L_3$   $(1,2,3,\lambda)$  do not have the same formula. Hence, deleting an observation from the sample will change the likelihood.

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