

DelftX: OT.1x Observation theory: Estimating the Unknown

Help



- 0. Getting Started
- 1. Introduction to Observation Theory

Warming up

- 1.1 What is the Problem?
- 1.2 Quality and Types of Errors part 1
- 1.2 Quality and Types of Errors part 2
- 1.3 Elements of the Estimation Problem

Assessment

Graded Assignment due Feb 8, 2017 17:30 IST

Q&A Forum

Feedback

▶ 2. Mathematical model

1. Introduction to Observation Theory > 1.2 Quality and Types of Errors - part 1 > Exercises: Quality of measurements

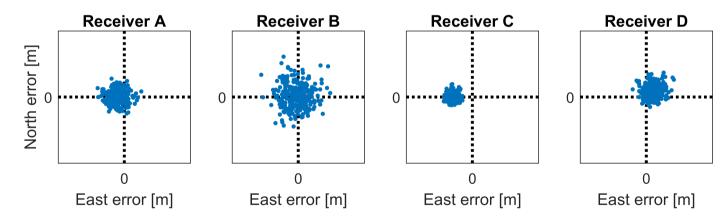
Exercises: Quality of measurements

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GPS positions

7/7 points (ungraded)

GPS was used to estimate the position of 4 different static receivers (i.e., the receivers were not moving). The measurements were repeated 200 times, and the errors in the horizontal positions are shown in the figures below.



Which receiver performs best in terms of precision?

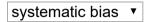
C ▼ Answer: C

- 3. Least Squares Estimation (LSE)
- 4. Best Linear Unbiased Estimation (BLUE)
- Pre-knowledgeMathematics
- MATLAB Learning Content

Which receiver performs best in terms of accuracy?

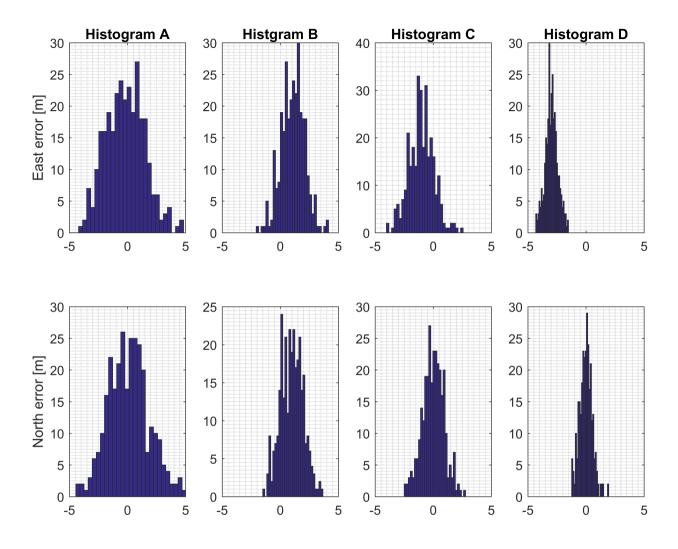


Which type of error caused the lower accuracy in the case of the lowest accuracy?



✓ Answer: systematic bias

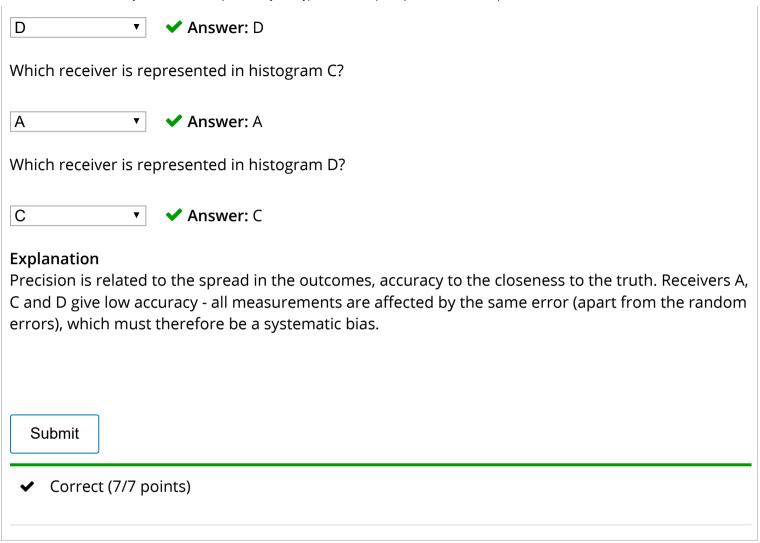
Histograms of all four receivers have been made. Which histogram belongs to each of the receivers?



Which receiver is represented in histogram A?

B ▼ Answer: B

Which receiver is represented in histogram B?



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