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Machine Learning with Python-From Linear Models to Deep Learning

<u>Help</u>



<u>sandipan_dey</u>

Unit 2 Nonlinear Classification,

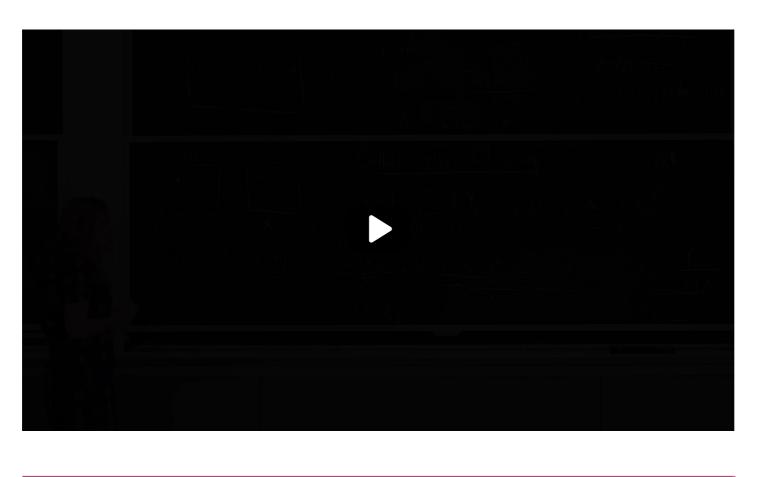
Linear regression, Collaborative

4. Collaborative Filtering: the Naive

Course > Filtering (2 weeks)

> <u>Lecture 7. Recommender Systems</u> > Approach

4. Collaborative Filtering: the Naive Approach Collaborative Filtering: the Naive Approach



entries.

There is no dependence whatsoever between different assignment that we are making.

We're treating every choice independently.

And it is not surprising that since we're not modeling dependency in any way, we're really losing important connection, which was the first reason why we decided to look at this problem

differently in order to find the connection-the hidden connection between different users and between different products.

10:18 / 10:18

▶ Speed **1.50**x

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Compute the Derivative of the Regression Objective

2/2 points (graded)

Recall that each user a has a set of movies that (s)he has already rated. Let Y be a matrix with n row and m columns whose $(a,i)^{\text{th}}$ entry Y_{ai} is the rating by user a of movie i if this rating has already been given, and blank if not. Our goal is to come up with a matrix X that has no blank entries and whose $(a,i)^{\text{th}}$ entry X_{ai} is the prediction of the rating user a will give to movie i.

Let D be the set of all (a,i)'s for which a user rating Y_{ai} exists, i.e. $(a,i)\in D$ if and only if the rating of user a to movie i exists.

A naive approach to solve this problem would be to minimize the following objective:

$$J\left(X
ight) = \sum_{a,i \in D} rac{\left(Y_{ai} - X_{ai}
ight)^2}{2} + rac{\lambda}{2} \sum_{(a,i)} X_{ai}^2$$

where the first term is the sum of the squared errors for entries with observed rating, and the second term is a regularization term roughly to prevent the predictions to become extremely large, and the parameter λ controls the balance between theses two terms.

Compute the derivative $\frac{\partial J}{\partial X_{ai}}$ of the objective function $J\left(X\right)$. (Note that $J\left(X\right)$ can be viewed as a function of the variables X_{ai} .)

(Type x_{ai} for matrix entries X_{ai} , Y_{ai} for matrix entries Y_{ai} and "lambda" for λ .)

For (any fixed) $(a,i) \in D$,

For (any fixed) $(a, i) \notin D$:

$$rac{\partial J}{\partial X_{ai}} = egin{bmatrix} ext{lambda* X_{ai}} \ ext{ } & ext$$

STANDARD NOTATION

Solution:

Derive the objective and remember to treat any entry in the matrix that is not the one that we are deriving by as a constant. Hence, the derivative of all components of the sum that are not (a, i) will be zero.

Submit

You have used 1 of 2 attempts

1 Answers are displayed within the problem

Performance of the Naive Approach

2/2 points (graded)

Let us now check the quality of the solution when using this wrong approach. Recall the naive approach assumes independence between all entries of the matrix.

What value of the matrix X will minimize the loss $J(X) = \sum_{a,i \in D} \frac{(Y_{ai} - X_{ai})^2}{2} + \frac{\lambda}{2} \sum_{(a,i)} X_{ai}^2$? That is, for each (a,i), solve the following equation for X_{ai} :

$$rac{\partial J}{\partial X_{ai}} = 0.$$

We will denote the argmin as \widehat{X} and its components as \widehat{X}_{ai} .

For
$$(a,i) \in D$$
:

$$\widehat{X}_{ai} = { extstyle extstyle$$

For
$$(a,i) \notin D$$
:

$$\widehat{X}_{ai} = egin{bmatrix} \mathtt{0} \end{bmatrix}$$

STANDARD NOTATION

Submit

You have used 1 of 3 attempts

✓ Correct (2/2 points)

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	2
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Meaningful symbols continuation	3

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