

2017 17:30 IST

## **DelftX:** OT.1x Observation theory: Estimating the Unknown

Help

4. Best Linear Unbiased Estimation (BLUE) > 4.1. Estimates vs Estimators > Exercises: Estimate vs. Estimator **Bookmarks** Exercises: Estimate vs. Estimator ☐ Bookmark this page 0. Getting Started Understanding random/stochastic variables ▶ 1. Introduction to 1/1 point (ungraded) **Observation Theory** In module 4.1, new terminology was introduced. ▶ 2. Mathematical model Of the names of the variables below, please indicate which ones are used to indicate a random/stochastic variable. ▶ 3. Least Squares Estimation (LSE) estimator ▼ 4. Best Linear estimate **Unbiased Estimation** (BLUE) observation Warming up observable 4.1. Estimates vs **Estimators** 4.2. Best Linear Unbiased **Estimation (BLUE)** Assessment Graded Assignment due Feb 8,

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**Q&A Forum** 

4. Non-linear Least Squares (optional topic)

Feedback

- ► 5. How precise is the estimate?
- Pre-knowledgeMathematics
- MATLAB Learning Content

✓ Correct (1/1 point)

## Stochastic vs. deterministic variables

1/1 point (ungraded)

## Theory:

It is proven in statistics that a linear function of a normally distributed variable/vector is again normally distributed. That is, if  $\underline{y}$  is normally distributed and  $\underline{z}$  is a linear function of  $\underline{y}$  (such as  $\underline{z} = L\underline{y}$ ), then  $\underline{z}$  is also normally distributed.

Based on this theory answer the following question.

Assume we observe the width of a canal five times and we want to estimate the width of the canal. The observables are  $\underline{y}_1$ ,  $\underline{y}_2$ ,  $\underline{y}_3$ ,  $\underline{y}_4$ , and  $\underline{y}_5$ , and all are normally distributed. For this estimation problem, the observable vector  $\underline{y}$ , and the design matrix  $\underline{A}$  can be written as

$$\underline{y} = egin{bmatrix} ar{y}_1 \ ar{y}_2 \ ar{y}_3 \ ar{y}_4 \ ar{y}_5 \end{bmatrix}, \ \ A = egin{bmatrix} 1 \ 1 \ 1 \ 1 \ 1 \end{bmatrix}.$$

Applying least squares estimation on this model provides us the estimator for the canal width as:

$$\underline{\hat{x}} = (A^T A)^{-1} A^T y.$$

Which of the following statements is correct?

- ullet  $\hat{oldsymbol{x}}$  is a stochastic variable, and it is normally distributed. ullet
- igcirc is a stochastic variable, but it is not necessarily normally distributed.
- igcirc  $\hat{m{x}}$  is deterministic, and so it does not have any distribution

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✓ Correct (1/1 point)

## Stochastic vs. deterministic variables (continued)

1/1 point (ungraded)

Now for the above question assume the observations are given as:  $y_1=10.1$ m,  $y_2=10.15$ m,  $y_3=9.9$ m,  $y_4=10.2$ m, and  $y_5=10.1$ m. Application of LS estimation gives the estimate  $\hat{x}$  as

$$\hat{x} = (A^TA)^{-1}A^T egin{bmatrix} 10.1\ 10.15\ 9.9\ 10.2\ 10.1 \end{bmatrix} = 10.09$$

Which of the following statements is correct?

- ullet  $\hat{x}=10.09$  is stochastic, and it is normally distributed.
- ullet  $\hat{m{x}}={f 10.09}$  is deterministic, but it is a realization of the estimator  ${f \hat{x}}$ .  $m{\checkmark}$

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Correct (1/1 point)

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