

4.3.1 Transpose Matrix-Vector Multiplication

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Week 4 due Oct 24, 2023 19:42 IST

4.3.1 Transpose Matrix-Vector Multiplication

Summary

▶ Algorithms for $y := Ax + y$ can be easily changed into algorithms for $y := A^T x + y$.

▶ THERE IS NO NEED TO EXPLICITLY TRANSPOSE!!!!

29 / 29

▶ 5:55 / 5:55

▶ 2.0x 🔊 🗑️ 🗑️

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Reading Assignment

0 points possible (ungraded)
Read Unit 4.3.1 of the notes. [LINK]

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Calculator

- ☒ Does not a matrix-vector multiplication require memops?
In the reading (p. 133) and the video is said: "A matrix-vector multiplication requires $2mn$ flops. Transposing a matrix requires $2mn$ memops (mn ..."
 - ☒ what's the point of transposing if you could do the dot product?
why did we ever transpose if we could just take the dot product and be more efficient in our memory processing? i'm don't understand what it m...

Homework 4.3.1.1

1/1 point (graded)

<p>Algorithm: $y := \text{MVMULT_T_UNB_VAR1}(A, x, y)$</p> <p>Partition $A \rightarrow \left(A_L \middle A_R \right), y \rightarrow \left(\frac{y_T}{y_B} \right)$</p> <p>where A_L is $m \times 0$ and y_T is 0×1</p> <p>while $m(y_T) < m(y)$ do</p> <p>Repartition</p> $\left(A_L \middle A_R \right) \rightarrow \left(A_0 \middle a_1 \middle A_2 \right), \left(\frac{y_T}{y_B} \right) \rightarrow \left(\frac{y_0}{\psi_1} \right)$ <hr/> $\psi_1 := a_1^T x + \psi_1$ <hr/> <p>Continue with</p> $\left(A_L \middle A_R \right) \leftarrow \left(A_0 \middle a_1 \middle A_2 \right), \left(\frac{y_T}{y_B} \right) \leftarrow \left(\frac{y_0}{\psi_1} \right)$ <p>endwhile</p>	<p>Algorithm: $y := \text{MVMULT_T_UNB_VAR2}(A, x, y)$</p> <p>Partition $A \rightarrow \left(\frac{A_T}{A_B} \right), x \rightarrow \left(\frac{x_T}{x_B} \right)$</p> <p>where A_T is $0 \times n$ and x_T is 0×1</p> <p>while $m(A_T) < m(A)$ do</p> <p>Repartition</p> $\left(\frac{A_T}{A_B} \right) \rightarrow \left(\frac{A_0}{a_1^T} \right), \left(\frac{x_T}{x_B} \right) \rightarrow \left(\frac{x_0}{\chi_1} \right)$ <hr/> $y := \chi_1 a_1 + y$ <hr/> <p>Continue with</p> $\left(\frac{A_T}{A_B} \right) \leftarrow \left(\frac{A_0}{a_1^T} \right), \left(\frac{x_T}{x_B} \right) \leftarrow \left(\frac{x_0}{\chi_1} \right)$ <p>endwhile</p>
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Write routines

- `[y_out] = Mvmult_t_unb_var1(A, x, y)`
- `[y_out] = Mvmult_t_unb_var2(A, x, y)`

that compute $\mathbf{y} := \mathbf{A}^T \mathbf{x} + \mathbf{y}$ using the algorithms in this unit.

Some links that will come in handy:

- Spark (alternatively, open the file LAFF-2.0xM/Spark/index.html)
- PictureFLAME (alternatively, open the file LAFF-2.0xM/PictureFLAME/PictureFLAME.html)

You may want to use the following scripts to test your implementations (these should be in your directory `LAFF-2.0xM/Programming/Week04/`):


- test_Mvmult_t_unb_var1.m
- test_Mvmult_t_unb_var2.m

 Done/Skip



[View document with most algorithms and implementations for this week.](#)

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 Answers are displayed within the problem

Homework 4.3.1.2

2/2 points (graded)

Implementations achieve better performance (finish faster) if one accesses data consecutively in memory. Now, most scientific computing codes store matrices in "column-major order" which means that the first column of a matrix is stored consecutively in memory, then the second column and so forth. Now, this means that an algorithm that accesses a matrix by columns tends to be faster than an algorithm that accesses a matrix by rows. That, in turn, means that when one is presented with more than one algorithm, one should pick the algorithm that accesses the matrix by columns.

Our FLAME notation makes it easy to recognize algorithms that access the matrix by columns.

- For the matrix-vector multiplication of $Ax + y$, would you recommend the algorithm that uses dot products or the algorithm that uses axpy operations?

axpy

✓ Answer: axpy

- For the matrix-vector multiplication of $A^T x + y$, would you recommend the algorithm that uses dot products or the algorithm that uses axpy operations?

dot

✓ Answer: dot

Explanation

Answer: When computing $Ax + y$, it is when you view Ax as taking linear combinations of the *columns* of A that you end up accessing the matrix by columns. Hence, the **axpy**-based algorithm will access the matrix by columns.

When computing $A^T x + y$, it is when you view $A^T x$ as taking dot products of *columns* of A with vector x that you end up accessing the matrix by columns. Hence, the **dot**-based algorithm will access the matrix by columns.

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