



Lab: Discrete Fourier Transform and

<u>Course</u> > <u>Unit 1: Fourier Series</u> > <u>Signal Processing</u>

> 3. The Discrete Fourier Transform

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3. The Discrete Fourier Transform

Review

We can think of the Fourier Series as a method that takes "any" periodic function, and replaces it with a discrete set of coefficients (infinitely many, but countably infinite).

The Fourier Transform takes "any" function, and replaces it with a continuous function.

$$f\left(t
ight) \;\;\;=\;\;\;\int_{-\infty}^{\infty}\widehat{f}\left(k
ight) e^{ikt}\,dk,$$

$$egin{array}{lcl} f\left(t
ight) &=& \int_{-\infty}^{\infty} \widehat{f}\left(k
ight) e^{ikt} \, dk, \ & \ \widehat{f}\left(k
ight) &=& rac{1}{2\pi} \int_{-\infty}^{\infty} f\left(t
ight) e^{-ikt} \, dt \end{array}$$

A new problem

Suppose we have a discrete set of N data points $y_0, y_1, ..., y_{N-1}$ sampled over equal time increments Δt . Define

$$t_n = \ \Delta t \ n.$$

ب fixed

Figure 13: N data points sampled over equal time intervals Δt

Goal: Fit the data with a sum of sines and cosines (or really with complex exponentials using a complex Fourier series). That is, determine all of the "frequencies" in this discrete set of data points.

First step: Make it periodic. Add another point t_N and define $y_N = y_0$.

Example 3.1 Let f(t) and g(t) be two functions that fit all of the data $y_0, ..., y_{N-1}$, and satisfying

$$f(t_N) = f(t_0)$$

$$g(t_N) = g(t_0)$$

We can extend f(t) and g(t) to functions that are periodic of period $\Delta t N$.

This implies that we can write

$$f(t) = \sum_{k=-\infty}^{\infty} c_k e^{ik\pi t/(t_N/2)} = \sum_{k=-\infty}^{\infty} c_k e^{i2\pi kt/N\Delta t},$$

for some set of complex coefficients c_k .

And

$$g(t) = \sum_{k=-\infty}^{\infty} c'_{k} e^{i2\pi kt/N\Delta t},$$

for a set of coefficients $c_{k}^{'} \neq c_{k}$.

The problem Any way of filling in the space between the points leads to a new function, with a new set of coefficients. Thus there are infinitely many ways to fit the data with sines and cosines (or equivalently, with complex exponentials as we are actually doing here).

Modified goal Represent the data as simply as possible with a continuous function obtained as a sum of complex exponentials.

Observe that when we compare complex exponentials only at the the discrete times where we sampled our data,

$$e^{i2\pi k t_n/N\Delta t} = e^{i2\pi k (n\Delta t)/N\Delta t} = e^{i2\pi k n/N}$$

we cannot distinguish the difference between the kth and the k + Nth frequency

$$e^{i2\pi(k+N)t_n/N\Delta t} = e^{i2\pi kn/N}e^{i2\pi n} = e^{i2\pi kn/N}$$

Thus $e^{i2\pi kt/N\Delta t} = e^{i2\pi(k+N)t/N\Delta t}$ whenever $t = t_n = n\Delta t$.

Example 3.2 Consider the set of data that are all equal to 1.

Figure 15: Sampled data all equal to 1. Both the constant function 1 (dashed line) and $\cos(2\pi t/\Delta t)$ (solid line) pass through all data. Represented as the real parts of complex exponentials, the dashed line is e^{i0} , and the solid line is $e^{i2\pi t/\Delta t}$.

There are multiple frequencies that fit the data. Any frequencies higher than the sampling frequency cannot be detected in the data.

Because the kth and the (k + N)th modes are equal when evaluated on the discrete times $t_{k'}$ we can represent the data uniquely by the discrete time Fourier series

$$y(t) = \sum_{k=0}^{N-1} c_k e^{\frac{i2\pi kt}{N\Delta t}},$$

for some complex coefficients c_0 , c_1 , , c_{N-1} .

So, how do we actually compute these coefficients?

Define $\omega = e^{i2\pi/N}$, which is the *N*th root of unity, where we have *N* data points.

Let's look at how our data points are represented in terms of ω .

$$y_0 = y(0) = c_0 + c_1 + c_2 + \dots + c_{N-1}$$

$$y_1 = y(\Delta t) = c_0 + c_1 \omega^1 + c_2 \omega^2 + \dots + c_{N-1} \omega^{N-1}$$

$$\begin{array}{rcl} y_2 & = & y(2\Delta t) = c_0 + c_1\omega^2 + c_2\omega^4 + \dots + c_{N-1}\omega^{2(N-1)} \\ & \vdots \\ & \\ y_{N-1} & = & c_0 + c_1\omega^{N-1} + c_2\omega^{2(N-1)} + \dots + c_{N-1}\omega^{(N-1)(N-1)} \end{array}$$

Therefore we can write this data as a matrix equation

$$\begin{pmatrix} y_0 \\ \vdots \\ y_{N-1} \end{pmatrix} = \mathbf{W}_N \begin{pmatrix} c_0 \\ \vdots \\ c_{N-1} \end{pmatrix},$$

where

$$\mathbf{W}_{N} = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega & \omega^{2} & \cdots & \omega^{N-1} \\ 1 & \omega^{2} & \omega^{4} & \cdots & \omega^{2(N-1)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & \omega^{N-1} & \omega^{2(N-1)} & \cdots & \omega^{(N-1)(N-1)} \end{pmatrix}$$

Note that we can describe this as the coefficient in the *i*th row and *j*th column is $(\mathbf{W}_N)_{ij} = \omega^{(i-1)(j-1)}$.

Definition 3.3 The inverse of this matrix is the *N* point Fourier Matrix.

$$\mathbf{W}_{N}^{-1} = \mathbf{F}_{N} = \frac{1}{N} \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ & - & -_{2} & & -_{N-1} \\ 1 & \omega & \omega & \cdots & \omega \\ & -_{2} & -_{4} & & -_{2(N-1)} \\ 1 & \omega & \omega & \cdots & \omega \\ \vdots & \vdots & \vdots & & \vdots \\ & -_{N-1} & -_{2(N-1)} & & -_{(N-1)(N-1)} \\ 1 & \omega & \omega & \cdots & \omega \end{pmatrix}$$

Definition 3.4 We say that the vector

$$\begin{pmatrix} c_0 \\ \vdots \\ c_{N-1} \end{pmatrix} = \mathbf{F}_N \begin{pmatrix} y_0 \\ \vdots \\ y_{N-1} \end{pmatrix}$$

is the **Finite Discrete Fourier Transform (FDFT)** of $\begin{pmatrix} y_0 \\ \vdots \\ y_{N-1} \end{pmatrix}.$

(Note that the Discrete Fourier Transform is the periodic, continuous function obtained by imagining that we take these coefficients and sum the continuous functions, allowing it to be defined for all times *t*.)

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✓ Typo in eq	uation? ion that is just above the section "A new problem", in the exponent of e, two consecutive i's appear. I think the first 'i' should be a negative sign for e^(-ikt). Please	5
☑ Modified g	goal k+Nth frequency?	5
•	sible errors on page: The Discrete Fourier Transform ors. second eqn. perhaps c k should have a factor of 1/2L and the exponent be negative. fourth eqn, for f-tilda(k), the exponent should perhaps be -i instead of ii	1
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