

# 18.650 – Fundamentals of Statistics

## 6. Linear Regression

# Goals

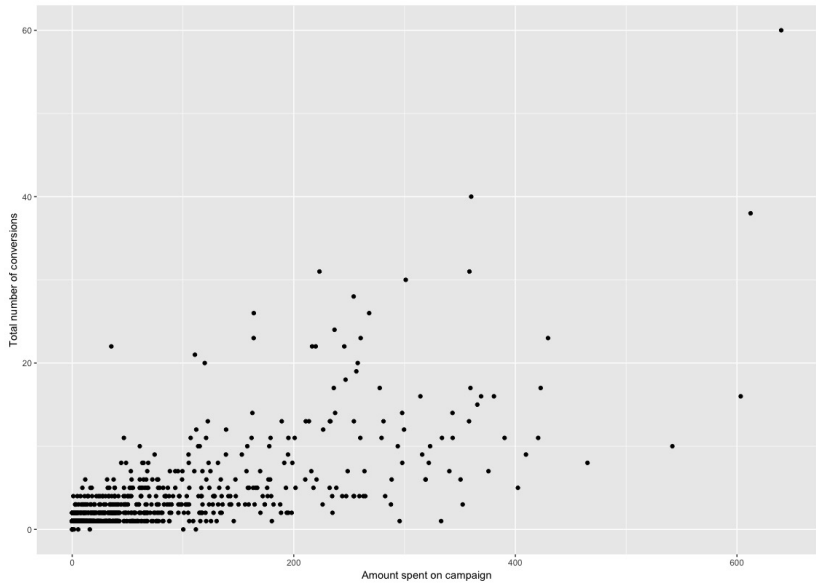
Consider two random variables  $X$  and  $Y$ . For example,

1.  $X$  is the amount of \$ spent on Facebook ads and  $Y$  is the total conversion rate
2.  $X$  is the age of the person and  $Y$  is the number of clicks

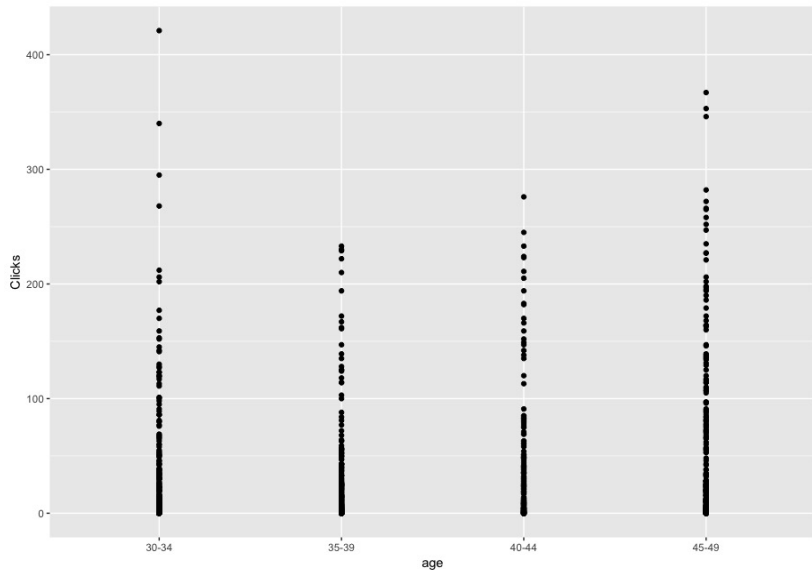
Given two random variables  $(X, Y)$ , we can ask the following questions:

- ▶ How to predict  $Y$  from  $X$ ?
- ▶ Error bars around this prediction?
- ▶ How much more conversions  $Y$  for an additional dollar?
- ▶ Does the number of clicks even depend on age?
- ▶ What if  $X$  is a random vector? For example,  $X = (X_1, X_2)$  where  $X_1$  is the amount of \$ spent on Facebook ads and  $X_2$  is the duration in days of the campaign.

# Conversions vs. amount spent



# Clicks vs. age



# Modeling assumptions

$(X_i, Y_i), i = 1, \dots, n$  are i.i.d from some **unknown joint distribution**  $\mathbb{P}$ .

$\mathbb{P}$  can be described by (assuming all exist)

- ▶ Either a joint PDF  $h(x, y)$
- ▶ The marginal density of  $X$   $h(x) =$  **and the**

$$h(y|x) =$$

$h(y|x)$  answers all our questions. It contains all the information about  $Y$  given  $X$

## Partial modeling

We can also describe the distribution only ,e.g., using

- ▶ The expectation of  $Y$ :
- ▶ The conditional expectation of  $Y$  given  $X = x$ :  
The function

$$x \mapsto f(x) := \mathbb{E}[Y|X = x] = \int$$

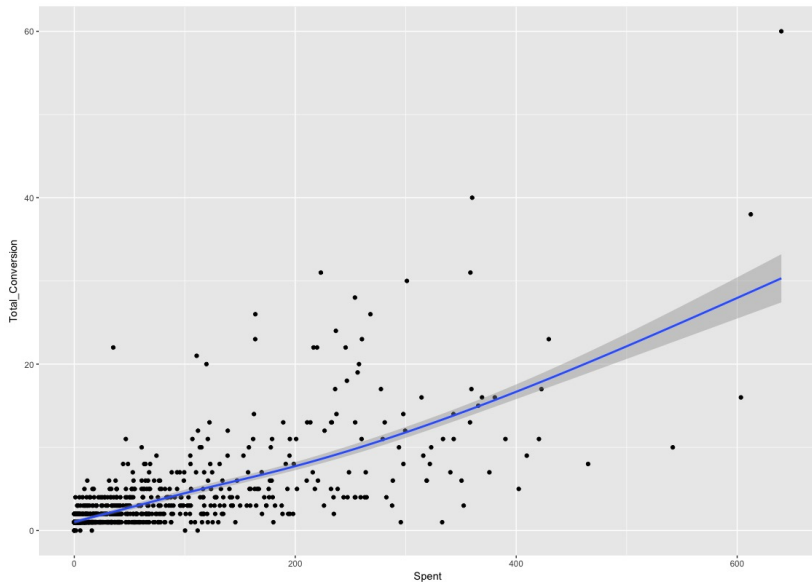
is called

- ▶ Other possibilities:
  - ▶ The conditional median: such that

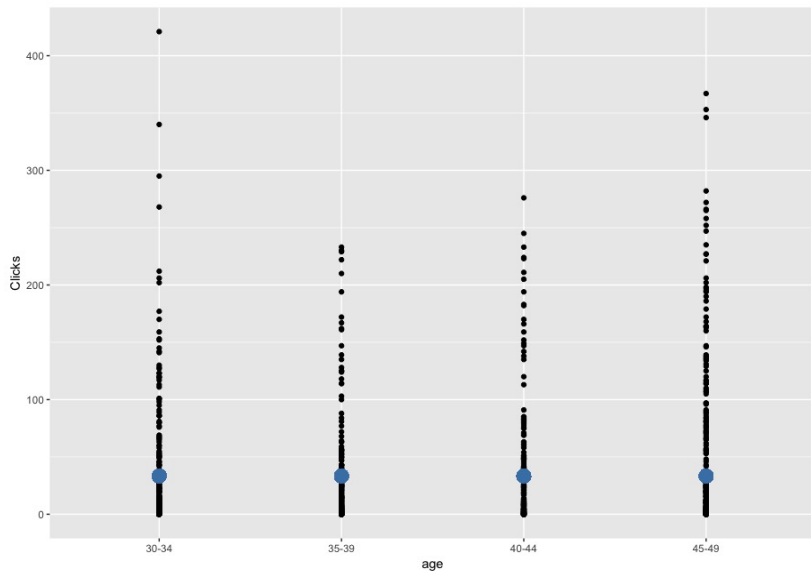
$$\int_{-\infty}^m h(y|x)dy =$$

- ▶ Conditional
- ▶ Conditional variance (not informative about location)

# Conditional expectation and standard deviation

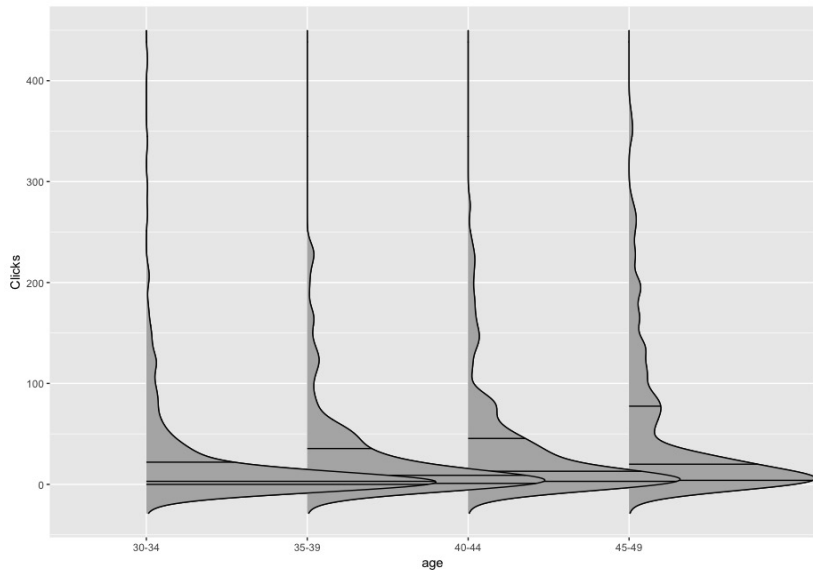


# Conditional expectation

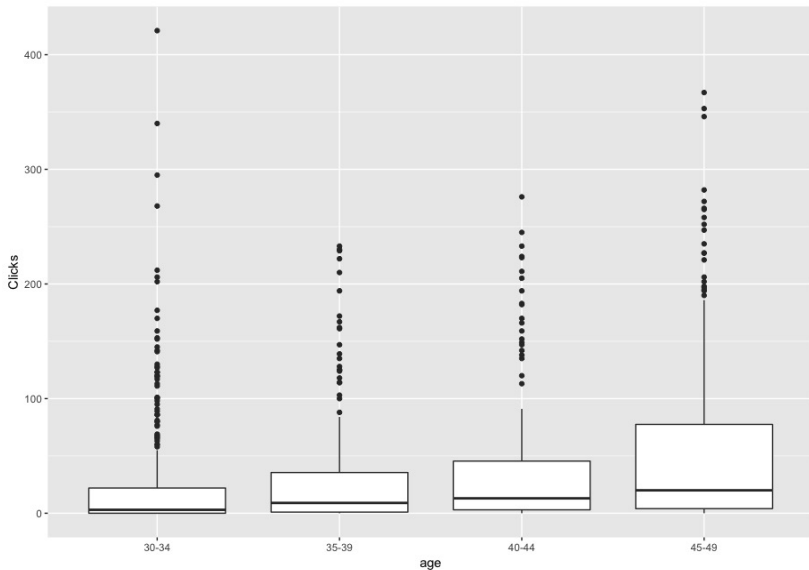




# Conditional density and conditional quantiles



## Conditional distribution: boxplots



# Linear regression

We first focus on modeling the regression function

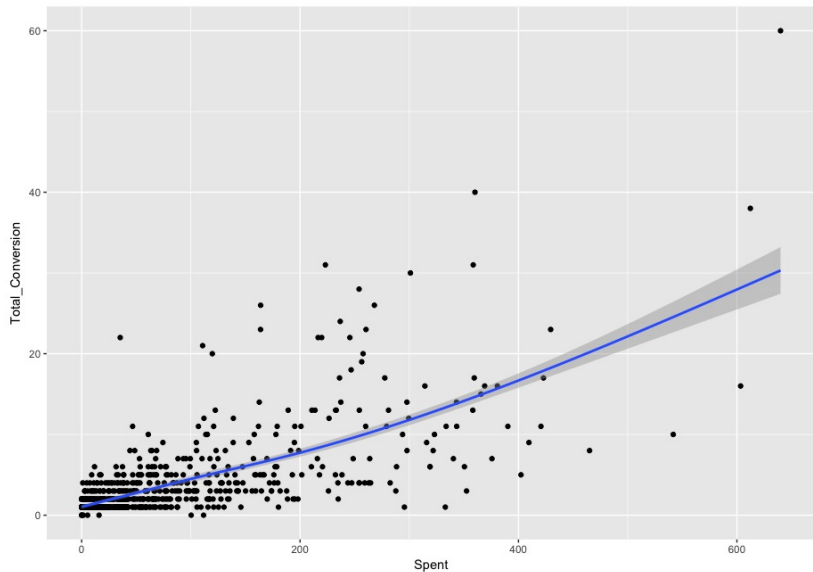
$$f(x) =$$

- ▶ Too many possible regression functions  $f$  (nonparametric)
- ▶ Useful to restrict to **simple** functions that are described by a few parameters
- ▶ Simplest:

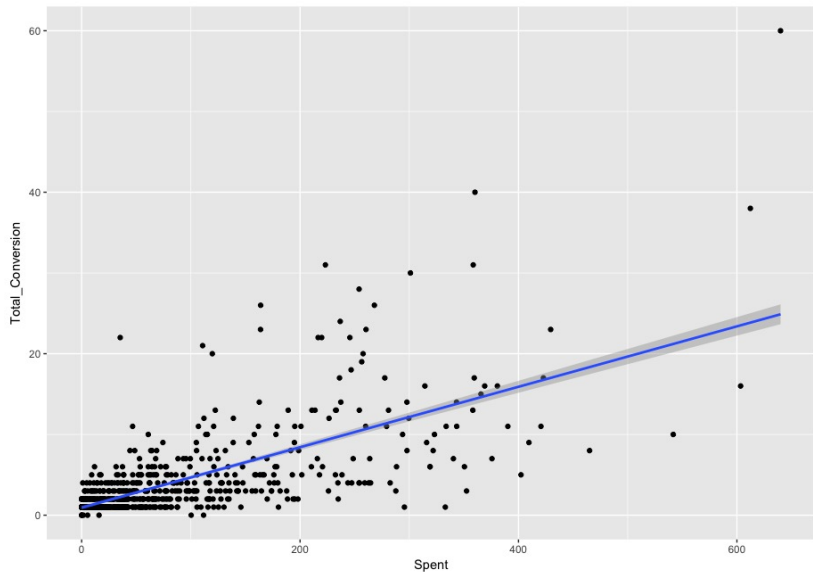
$$f(x) = a + bx$$

Under this assumption, we talk about

# Nonparametric regression



# Linear regression



# Probabilistic analysis

- ▶ Let  $X$  and  $Y$  be two real r.v. (not necessarily independent) with two moments and such that  $\text{var}(X) > 0$ .
- ▶ The **theoretical linear regression** of  $Y$  on  $X$  is the line  $x \mapsto a^* + b^*x$  where

$$(a^*, b^*) = \underset{(a,b) \in \mathbb{R}^2}{\operatorname{argmin}} \mathbb{E} \left[ (Y - a - bX)^2 \right]$$

- ▶ Setting partial derivatives to zero gives

- ▶  $b^* = \frac{\text{cov}(X, Y)}{\text{var}(X)},$

- ▶  $a^* = \mathbb{E}[Y] - b^* \mathbb{E}[X] = \mathbb{E}[Y] - \mathbb{E}[X].$

# Noise

Clearly the points are not exactly on the line  $x \mapsto a^* + b^*x$  if  $\text{var}(Y|X = x) > 0$ . The random variable  $\varepsilon = Y - (a^* + b^*X)$  is called *noise* and satisfies

$$Y = a^* + b^*X + \varepsilon,$$

with

- ▶  $\mathbb{E}[\varepsilon] = 0$  and
- ▶  $\text{cov}(X, \varepsilon) = 0$ .

# Statistical problem

In practice  $a^*, b^*$  need to be estimated from data.

- ▶ Assume that we observe  $n$  i.i.d. random pairs  $(X_1, Y_1), \dots, (X_n, Y_n)$  with same distribution as  $(X, Y)$ :

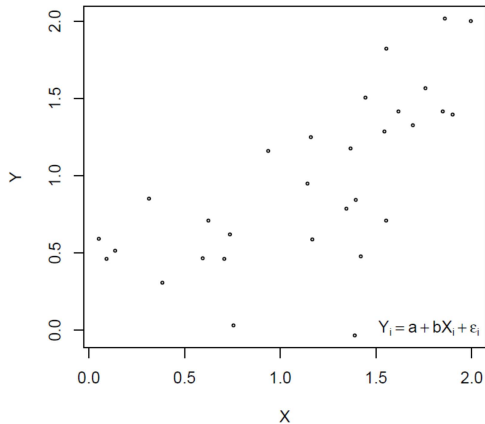
$$Y_i = \quad + \varepsilon_i$$

- ▶ We want to estimate  $a^*$  and  $b^*$ .



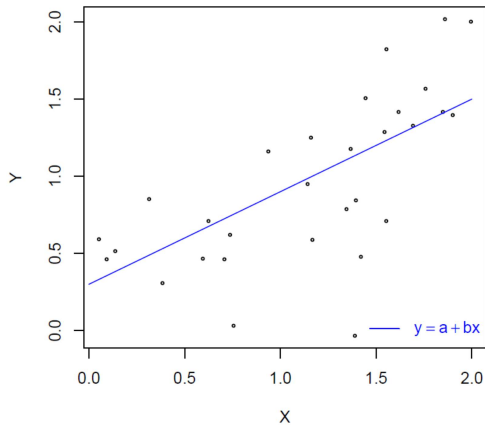
# Statistical problem

$$Y_i = a^* + b^* X_i + \varepsilon_i$$



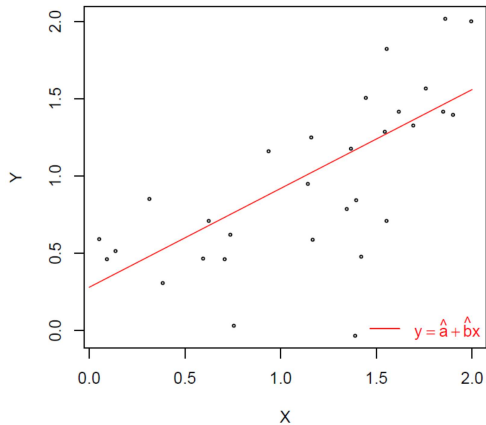
# Statistical problem

$$Y_i = a^* + b^*X_i + \varepsilon_i$$



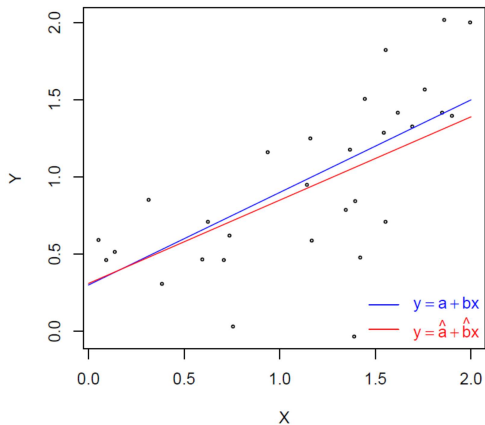
# Statistical problem

$$Y_i = a^* + b^*X_i + \varepsilon_i$$



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# Least squares

## Definition

The **least squares estimator (LSE)** of  $(a^*, b^*)$  is the minimizer of the sum of squared errors:

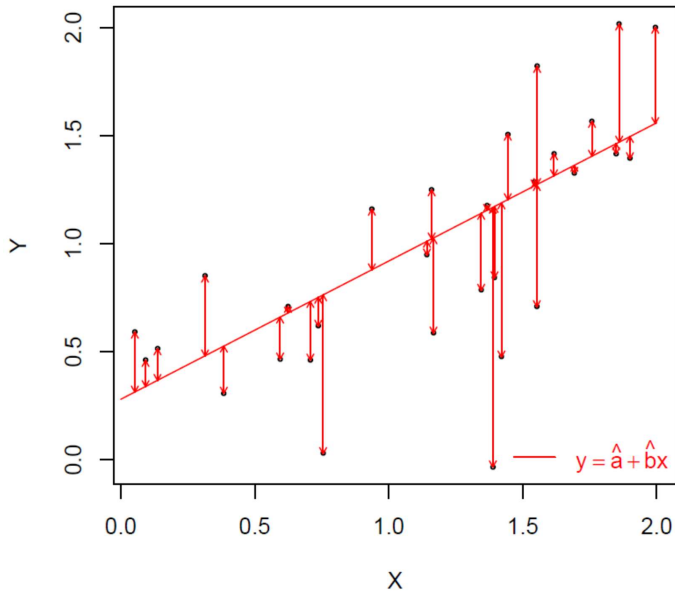
$$\sum_{i=1}^n (Y_i - a - bX_i)^2.$$

$(\hat{a}, \hat{b})$  is given by

$$\hat{b} = \frac{\overline{XY} - \bar{X}\bar{Y}}{\overline{X^2} - \bar{X}^2}$$

$$\hat{a} = \bar{Y} - \hat{b}\bar{X}.$$

# Residuals



# Multivariate regression

$$Y_i = \mathbf{X}_i^\top \boldsymbol{\beta}^* + \varepsilon_i, \quad i = 1, \dots, n.$$

- ▶ Vector of **explanatory variables** or **covariates**:  $\mathbf{X}_i \in \mathbb{R}^p$  (wlog, assume its first coordinate is 1).
- ▶ **Response / Dependent variable**:  $Y_i$ .
- ▶  $\boldsymbol{\beta}^* = (a^*, \mathbf{b}^{*\top})^\top$ ;  $\beta_1^* (= a^*)$  is called the **intercept**.
- ▶  $\{\varepsilon_i\}_{i=1, \dots, n}$ : noise terms satisfying  $\text{cov}(\mathbf{X}_i, \varepsilon_i) = \mathbf{0}$ .

## Definition

The **least squares estimator (LSE)** of  $\boldsymbol{\beta}^*$  is the minimizer of the sum of square errors:

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta} \in \mathbb{R}^p}{\operatorname{argmin}} \sum_{i=1}^n$$

# LSE in matrix form

- ▶ Let  $\mathbf{Y} = (Y_1, \dots, Y_n)^\top \in \mathbb{R}^n$ .
- ▶ Let  $\mathbb{X}$  be the  $n \times p$  matrix whose rows are  $\mathbf{X}_1^\top, \dots, \mathbf{X}_n^\top$  ( $\mathbb{X}$  is called the **design matrix**).
- ▶ Let  $\boldsymbol{\varepsilon} = (\varepsilon_1, \dots, \varepsilon_n)^\top \in \mathbb{R}^n$  (unobserved noise)
- ▶  $\mathbf{Y} = \mathbb{X}\boldsymbol{\beta}^* + \boldsymbol{\varepsilon}$ ,  $\boldsymbol{\beta}^*$  unknown.
- ▶ The LSE  $\hat{\boldsymbol{\beta}}$  satisfies:

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta} \in \mathbb{R}^p}{\operatorname{argmin}} \|\mathbf{Y} - \mathbb{X}\boldsymbol{\beta}\|_2^2.$$



## Closed form solution

- ▶ Assume that  $\text{rank}(\mathbb{X}) = p$ .
- ▶ Analytic computation of the LSE:

$$\hat{\boldsymbol{\beta}} = (\mathbb{X}^\top \mathbb{X})^{-1} \mathbb{X}^\top \mathbf{Y}.$$

- ▶ Geometric interpretation of the LSE:  $\mathbb{X}\hat{\boldsymbol{\beta}}$  is the orthogonal projection of  $\mathbf{Y}$  onto the subspace spanned by the columns of  $\mathbb{X}$ :

$$\mathbb{X}\hat{\boldsymbol{\beta}} = P\mathbf{Y},$$

where  $P = \mathbb{X}(\mathbb{X}^\top \mathbb{X})^{-1} \mathbb{X}^\top$ .

# Statistical inference

To make inference (confidence regions, tests) we need more assumptions.

## Assumptions:

- ▶ The design matrix  $\mathbb{X}$  is deterministic and  $\text{rank}(\mathbb{X}) = p$ .
- ▶ The model is **homoscedastic**:  $\varepsilon_1, \dots, \varepsilon_n$  are i.i.d.
- ▶ The noise vector  $\varepsilon$  is Gaussian:

$$\varepsilon \sim$$

for some known or unknown  $\sigma^2 > 0$ .

# Properties of LSE

- ▶ LSE = MLE
- ▶ Distribution of  $\hat{\beta}$ :  $\hat{\beta} \sim$  .
- ▶ Quadratic risk of  $\hat{\beta}$ :  $\mathbb{E} \left[ \|\hat{\beta} - \beta^*\|_2^2 \right] = \sigma^2 \text{tr} \left( (\mathbb{X}^\top \mathbb{X})^{-1} \right)$ .
- ▶ Prediction error:  $\mathbb{E} \left[ \|\mathbf{Y} - \mathbb{X}\hat{\beta}\|_2^2 \right] = \sigma^2(n - p)$ .
- ▶ Unbiased estimator of  $\sigma^2$ :  $\hat{\sigma}^2 =$  .

## Theorem

- ▶  $(n - p) \frac{\hat{\sigma}^2}{\sigma^2} \sim$  .
- ▶  $\hat{\beta} \perp\!\!\!\perp \hat{\sigma}^2$ .

## Significance tests

- ▶ Test whether the  $j$ -th explanatory variable is significant in the linear regression ( $1 \leq j \leq p$ ).
- ▶  $H_0 : \beta_j^* = 0$  v.s.  $H_1 : \beta_j^* \neq 0$ .
- ▶ If  $\gamma_j$  is the  $j$ -th diagonal coefficient of  $(\mathbb{X}^\top \mathbb{X})^{-1}$  ( $\gamma_j > 0$ ):

$$\frac{\hat{\beta}_j - \beta_j^*}{\sqrt{\hat{\sigma}^2 \gamma_j}} \sim$$

- ▶ Let  $T_n^{(j)} = \frac{\hat{\beta}_j}{\sqrt{\hat{\sigma}^2 \gamma_j}}$ .
- ▶ Test with non asymptotic level  $\alpha \in (0, 1)$ :

$$R_{j,\alpha} =$$

where  $q_{\frac{\alpha}{2}}(t_{n-p})$  is the  $(1 - \alpha/2)$ -quantile of  $t_{n-p}$ .

- ▶ We can also compute p-values.

# Bonferroni's test

- ▶ Test whether a **group** of explanatory variables is significant in the linear regression.
- ▶  $H_0 : \beta_j^* = 0, \forall j \in S$  v.s.  $H_1 : \exists j \in S, \beta_j^* \neq 0$ , where  $S \subseteq \{1, \dots, p\}$ .
- ▶ *Bonferroni's test*:  $R_{S,\alpha} =$  , where  $k = |S|$ .
- ▶ This test has nonasymptotic level at most  $\alpha$ .

## Remarks

- ▶ Linear regression exhibits correlations, **NOT** causality
- ▶ Normality of the noise: One can use goodness of fit tests to test whether the residuals  $\hat{\varepsilon}_i = Y_i - \mathbb{X}_i^\top \hat{\beta}$  are Gaussian.
- ▶ Deterministic design: If  $\mathbb{X}$  is not deterministic, all the above can be understood conditionally on  $\mathbb{X}$ , if the noise is assumed to be Gaussian, conditionally on  $X$ .