

Linear Regression

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MACHINE LEARNING DEPARTMENT



So far ...

- Learning distributions
 - Maximum Likelihood Estimation (MLE)
 - Maximum A Posteriori (MAP)
- Learning classifiers
 - Naïve Bayes

Discrete to Continuous Labels

Classification

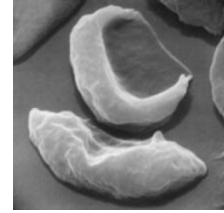


X = Document



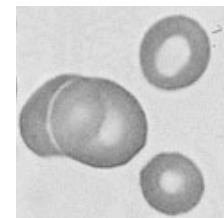
Sports
Science
News

Y = Topic



Anemic cell
Healthy cell

Y = Diagnosis

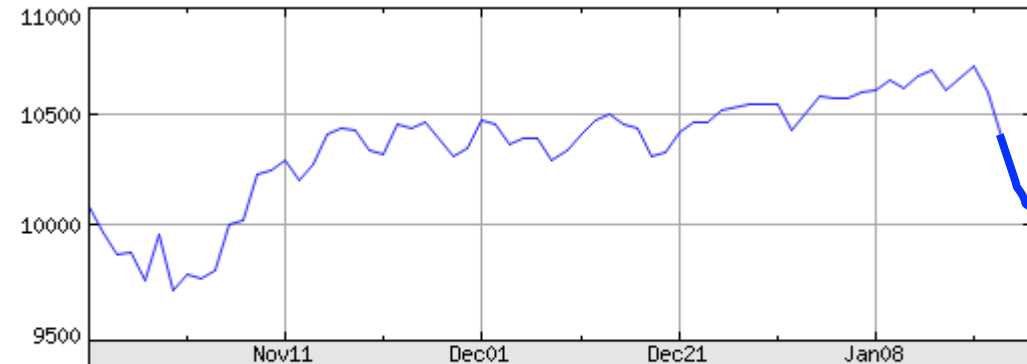


X = Cell Image

Regression

Stock Market
Prediction

DJ INDU AVERAGE (DOW JONES & CO
as of 22-Jan-2010



Y = ?

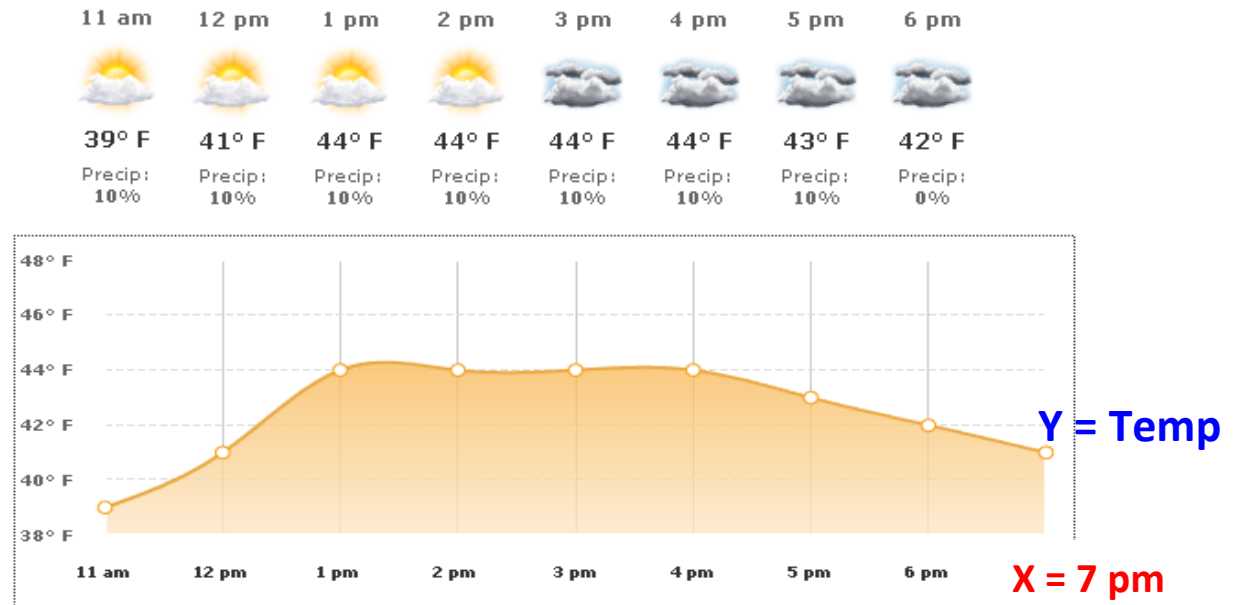
X = Feb01

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Regression Tasks

Weather Prediction



Estimating Contamination

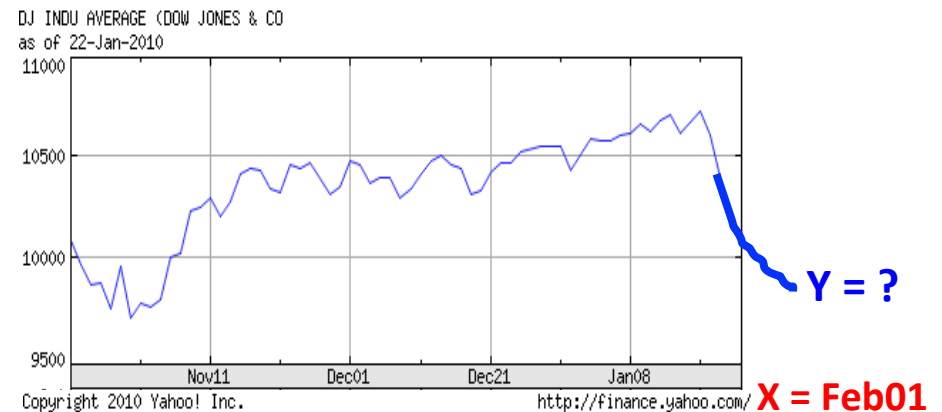


Supervised Learning

Goal: Construct a **predictor** $f : X \rightarrow Y$ to minimize loss function (performance measure)



Sports
Science
News



Classification:

$$P(f(X) \neq Y)$$

Probability of Error

Regression:

$$\mathbb{E}[(f(X) - Y)^2]$$

Mean Squared Error

Regression algorithms



Linear Regression

Regularized Linear Regression – Ridge regression, Lasso

Polynomial Regression

Kernel Regression

Regression Trees, Splines, Wavelet estimators, ...

Replace Expectation with Empirical Mean

Optimal predictor:

$$f^* = \arg \min_f \mathbb{E}[(f(X) - Y)^2]$$

Empirical Minimizer:

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \underbrace{\left(\frac{1}{n} \sum_{i=1}^n (f(X_i) - Y_i)^2 \right)}_{\text{Empirical mean}}$$

Empirical mean

Law of Large Numbers:

$$\frac{1}{n} \sum_{i=1}^n [\text{loss}(Y_i, f(X_i))] \xrightarrow{n \rightarrow \infty} \mathbb{E}_{XY} [\text{loss}(Y, f(X))]$$

Restrict class of predictors

Optimal predictor:

$$f^* = \arg \min_f \mathbb{E}[(f(X) - Y)^2]$$

Empirical Minimizer:

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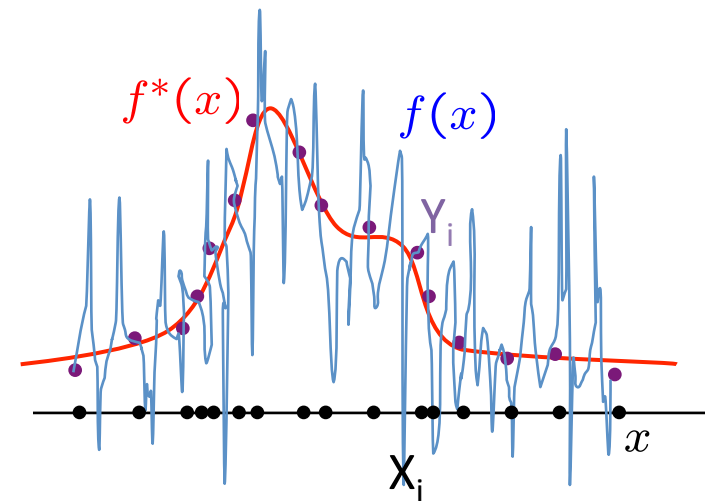
Class of predictors

Why?

Overfitting!

Empirical loss minimized by any function of the form

$$f(x) = \begin{cases} Y_i, & x = X_i \text{ for } i = 1, \dots, n \\ \text{any value,} & \text{otherwise} \end{cases}$$



Restrict class of predictors

Optimal predictor:

$$f^* = \arg \min_f \mathbb{E}[(f(X) - Y)^2]$$

Empirical Minimizer:

$$\hat{f}_n = \arg \min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^n (f(X_i) - Y_i)^2$$

Class of predictors

- \mathcal{F} - Class of Linear functions
- Class of Polynomial functions
- Class of nonlinear functions

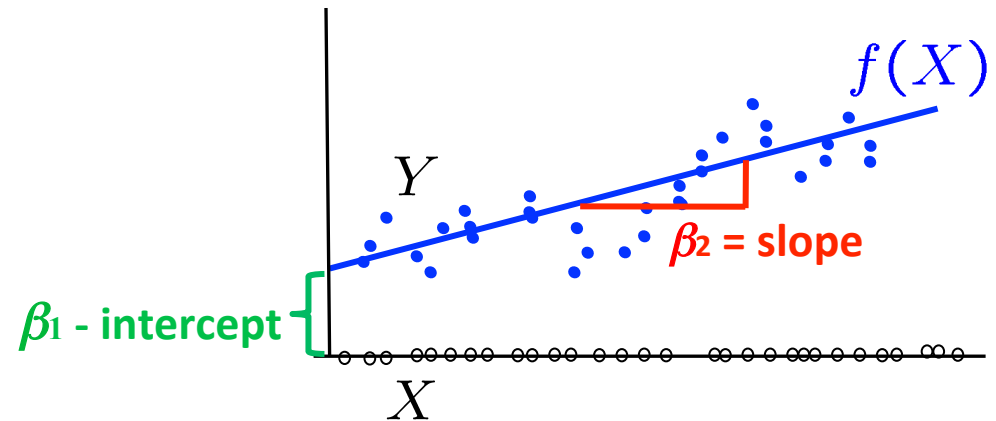
Linear Regression

$$\hat{f}_n^L = \arg \min_{f \in \mathcal{F}_L} \frac{1}{n} \sum_{i=1}^n (f(X_i) - Y_i)^2 \quad \text{Least Squares Estimator}$$

\mathcal{F}_L - Class of Linear functions

Uni-variate case:

$$f(X) = \beta_1 + \beta_2 X$$



Multi-variate case:

$$f(X) = f(X^{(1)}, \dots, X^{(p)}) = \beta_1 X^{(1)} + \beta_2 X^{(2)} + \dots + \beta_p X^{(p)}$$

$$= X\beta \quad \text{where} \quad X = [X^{(1)} \dots X^{(p)}], \quad \beta = [\beta_1 \dots \beta_p]^T$$

Least Squares Estimator

$$\hat{f}_n^L = \arg \min_{f \in \mathcal{F}_L} \frac{1}{n} \sum_{i=1}^n (f(X_i) - Y_i)^2 \quad f(X_i) = X_i \beta$$



$$\hat{\beta} = \arg \min_{\beta} \frac{1}{n} \sum_{i=1}^n (X_i \beta - Y_i)^2 \quad \hat{f}_n^L(X) = X \hat{\beta}$$

$$= \arg \min_{\beta} \frac{1}{n} (\mathbf{A} \beta - \mathbf{Y})^T (\mathbf{A} \beta - \mathbf{Y})$$

$$\mathbf{A} = \begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} X_1^{(1)} & \dots & X_1^{(p)} \\ \vdots & \ddots & \vdots \\ X_n^{(1)} & \dots & X_n^{(p)} \end{bmatrix} \quad \mathbf{Y} = \begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix}$$

Least Squares Estimator

$$\hat{\beta} = \arg \min_{\beta} \frac{1}{n} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) = \arg \min_{\beta} J(\beta)$$

$$J(\beta) = (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y})$$

$$\left. \frac{\partial J(\beta)}{\partial \beta} \right|_{\hat{\beta}} = 0$$

Normal Equations

$$\underbrace{(\mathbf{A}^T \mathbf{A})}_{p \times p} \underbrace{\hat{\beta}}_{p \times 1} = \underbrace{\mathbf{A}^T \mathbf{Y}}_{p \times 1}$$

If $(\mathbf{A}^T \mathbf{A})$ is invertible,

$$\hat{\beta} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{Y} \qquad \hat{f}_n^L(X) = X \hat{\beta}$$

When is $(\mathbf{A}^T \mathbf{A})$ invertible ?

Recall: Full rank matrices are invertible. What is rank of $(\mathbf{A}^T \mathbf{A})$?

What if $(\mathbf{A}^T \mathbf{A})$ is not invertible ?

Regularization (later)

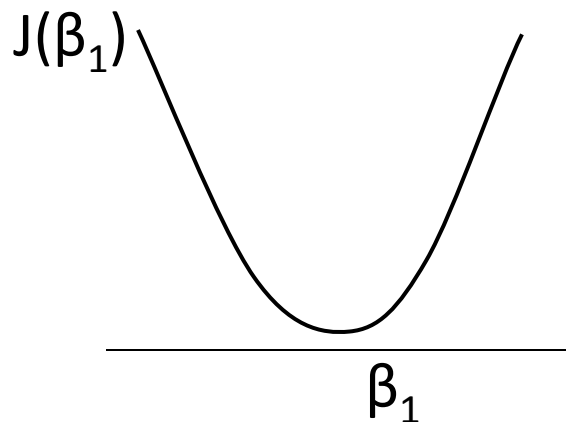
Gradient Descent

Even when $(\mathbf{A}^T \mathbf{A})$ is invertible, might be computationally expensive if \mathbf{A} is huge.

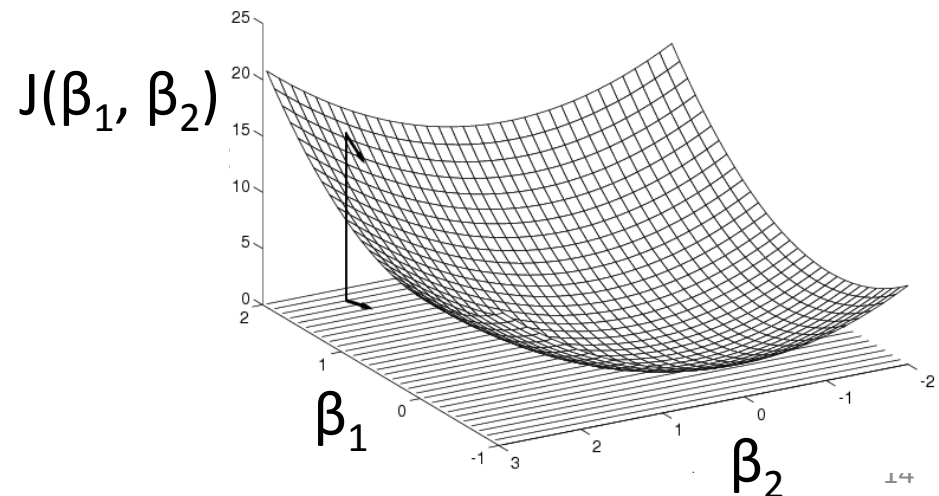
$$\hat{\beta} = \arg \min_{\beta} \frac{1}{n} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) = \arg \min_{\beta} J(\beta)$$

Treat as optimization problem

Observation: $J(\beta)$ is convex in β .



How to find the minimizer?



Gradient Descent

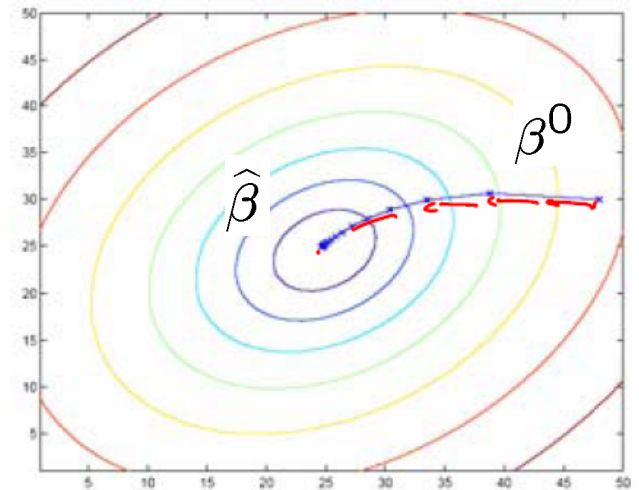
Even when $(\mathbf{A}^T \mathbf{A})$ is invertible, might be computationally expensive if \mathbf{A} is huge.

$$\hat{\beta} = \arg \min_{\beta} \frac{1}{n} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) = \arg \min_{\beta} J(\beta)$$

Since $J(\beta)$ is convex, move along negative of gradient

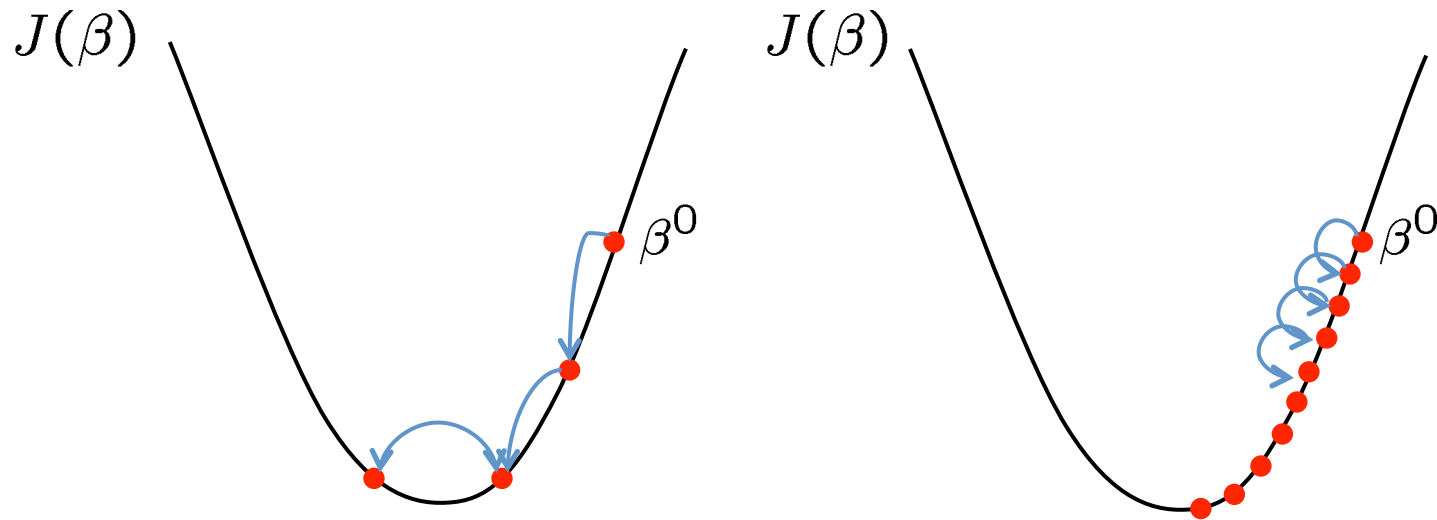
Initialize: β^0

$$\begin{aligned} \text{Update: } \beta^{t+1} &= \beta^t - \overset{\text{step size}}{\frac{\alpha}{2} \frac{\partial J(\beta)}{\partial \beta}} \bigg|_t \\ &= \beta^t - \alpha \underbrace{\mathbf{A}^T (\mathbf{A}\beta^t - \mathbf{Y})}_{0 \text{ if } \hat{\beta} = \beta^t} \end{aligned}$$



Stop: when some criterion met e.g. fixed # iterations, or $\left. \frac{\partial J(\beta)}{\partial \beta} \right|_{\beta^t} < \epsilon$.

Effect of step-size α



Large $\alpha \Rightarrow$ Fast convergence but larger residual error
Also possible oscillations

Small $\alpha \Rightarrow$ Slow convergence but small residual error

Least Squares and MLE

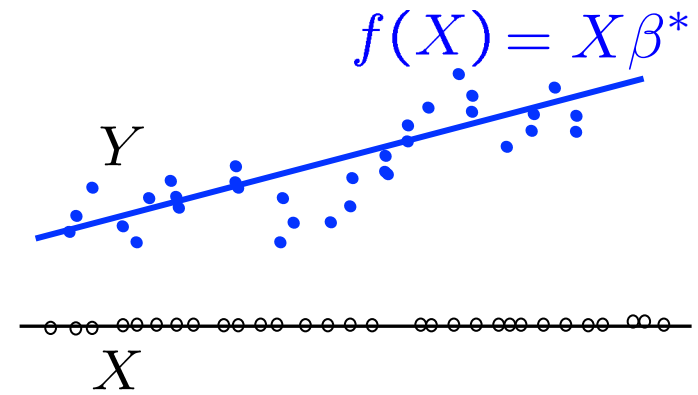
Intuition: Signal plus (zero-mean) Noise model

$$Y = f^*(X) + \epsilon = X\beta^* + \epsilon$$

$$\epsilon \sim \mathcal{N}(0, \sigma^2 \mathbf{I}) \quad Y \sim \mathcal{N}(X\beta^*, \sigma^2 \mathbf{I})$$

$$\hat{\beta}_{\text{MLE}} = \arg \max_{\beta} \underbrace{\log p(\{(X_i, Y_i)\}_{i=1}^n | \beta, \sigma^2)}_{\text{log likelihood}}$$

$$= \arg \min_{\beta} \sum_{i=1}^n (X_i \beta - Y_i)^2 = \hat{\beta}$$



Least Square Estimate is same as Maximum Likelihood Estimate under a Gaussian model !

Regularized Least Squares and MAP

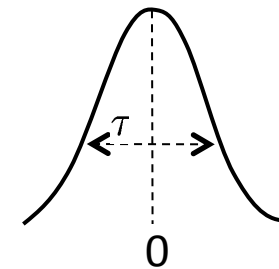
What if $(\mathbf{A}^T \mathbf{A})$ is not invertible ?

$$\hat{\beta}_{\text{MAP}} = \arg \max_{\beta} \underbrace{\log p(\{(X_i, Y_i)\}_{i=1}^n | \beta, \sigma^2)}_{\text{log likelihood}} + \underbrace{\log p(\beta)}_{\text{log prior}}$$

I) Gaussian Prior

$$\beta \sim \mathcal{N}(0, \tau^2 \mathbf{I})$$

$$p(\beta) \propto e^{-\beta^T \beta / 2\tau^2}$$



$$\hat{\beta}_{\text{MAP}} = \arg \min_{\beta} \sum_{i=1}^n (Y_i - X_i \beta)^2 + \lambda \|\beta\|_2^2$$

constant(σ^2, τ^2)

Ridge Regression

$$\hat{\beta}_{\text{MAP}} = (\mathbf{A}^T \mathbf{A} + \lambda \mathbf{I})^{-1} \mathbf{A}^T \mathbf{Y}$$

Regularized Least Squares and MAP

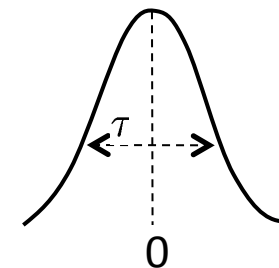
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constant(σ^2, τ^2)

Ridge Regression

Prior belief that β is Gaussian with zero-mean biases solution to “small” β

Regularized Least Squares and MAP

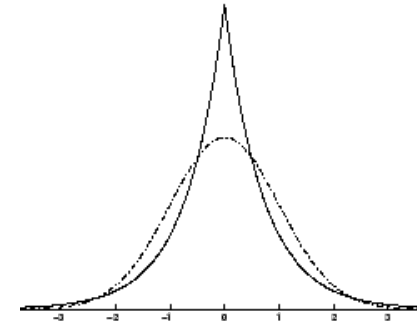
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II) Laplace Prior

$$\beta_i \stackrel{iid}{\sim} \text{Laplace}(0, t)$$

$$p(\beta_i) \propto e^{-|\beta_i|/t}$$



$$\hat{\beta}_{\text{MAP}} = \arg \min_{\beta} \sum_{i=1}^n (Y_i - X_i \beta)^2 + \underbrace{\lambda \|\beta\|_1}_{\text{constant}(\sigma^2, t)} \quad \text{Lasso}$$

Prior belief that β is Laplace with zero-mean biases solution to “small” β

Ridge Regression vs Lasso

$$\min_{\beta} (\mathbf{A}\beta - \mathbf{Y})^T (\mathbf{A}\beta - \mathbf{Y}) + \lambda \text{pen}(\beta) = \min_{\beta} J(\beta) + \lambda \text{pen}(\beta)$$

Ridge Regression:

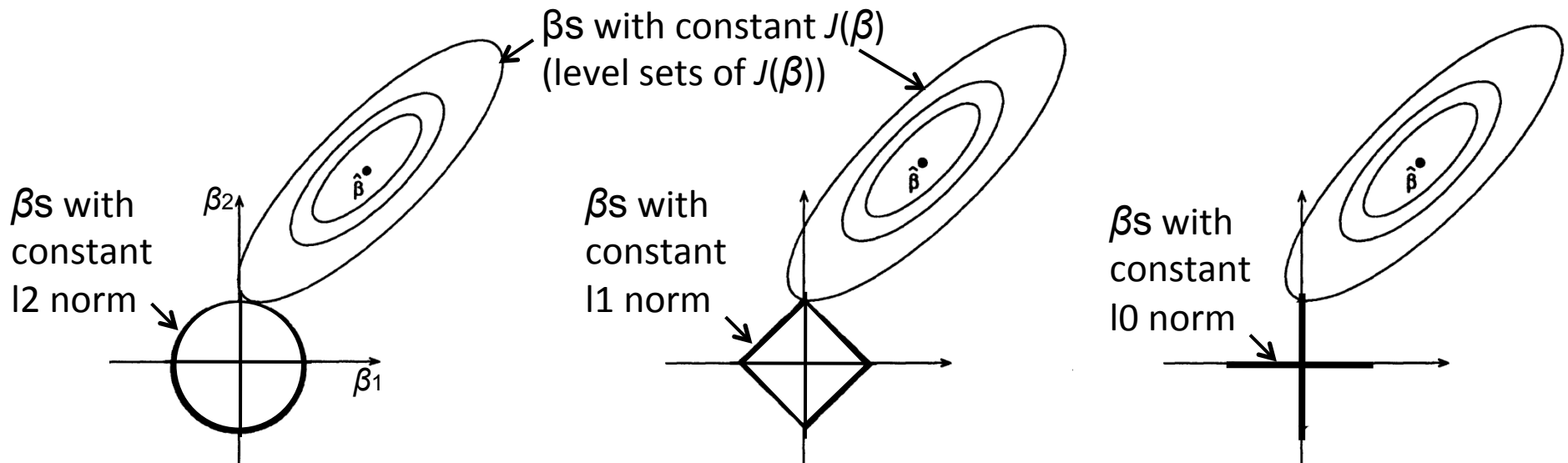
$$\text{pen}(\beta) = \|\beta\|_2^2$$

Lasso:

$$\text{pen}(\beta) = \|\beta\|_1$$

HOT!

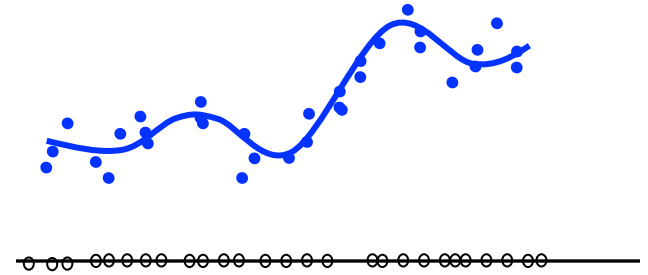
Ideally l0 penalty,
but optimization
becomes non-convex



Lasso (l1 penalty) results in sparse solutions – vector with more zero coordinates
Good for high-dimensional problems – don't have to store all coordinates!

Beyond Linear Regression

Polynomial regression



Regression with nonlinear features

Later ...

Kernel regression - Local/Weighted regression

Polynomial Regression

degree m
↙

Univariate (1-dim) $f(X) = \beta_0 + \beta_1 X + \beta_2 X^2 + \dots + \beta_m X^m = \mathbf{X}\beta$
case:

where $\mathbf{X} = [1 \ X \ X^2 \ \dots \ X^m]$, $\beta = [\beta_1 \ \dots \ \beta_m]^T$

$$\hat{\beta} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{Y}$$

$$\hat{f}_n(X) = \mathbf{X}\hat{\beta}$$

$$\mathbf{A} = \begin{bmatrix} 1 & X_1 & X_1^2 & \dots & X_1^m \\ \vdots & & & \ddots & \vdots \\ 1 & X_n & X_n^2 & \dots & X_n^m \end{bmatrix}$$

Multivariate (p-dim) $f(X) = \beta_0 + \beta_1 X^{(1)} + \beta_2 X^{(2)} + \dots + \beta_p X^{(p)}$

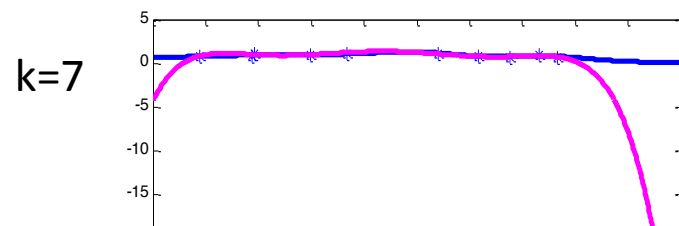
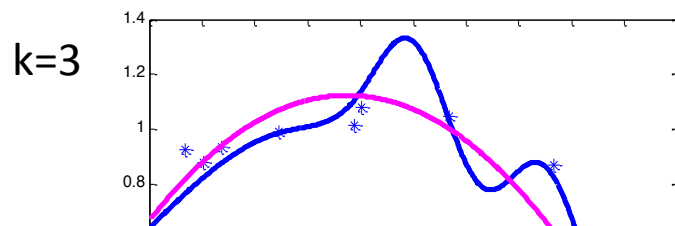
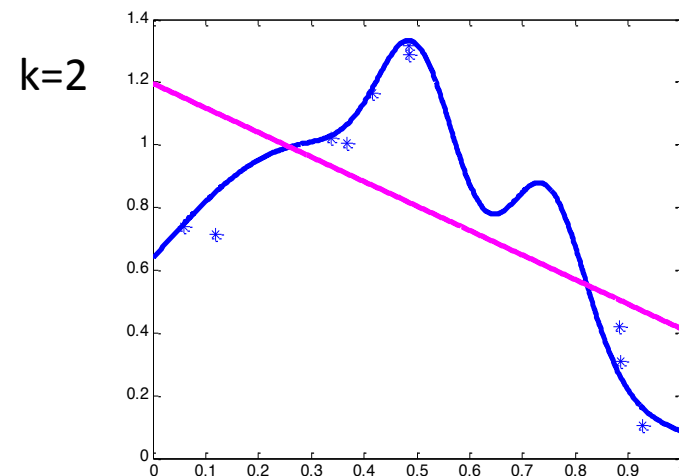
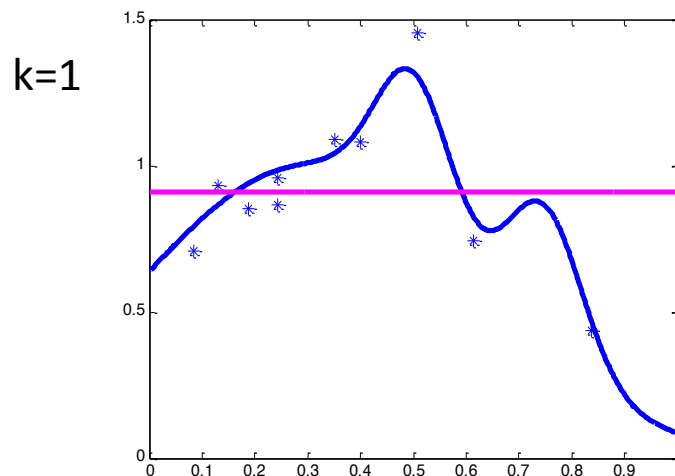
case:

$$+ \sum_{i=1}^p \sum_{j=1}^p \beta_{ij} X^{(i)} X^{(j)} + \sum_{i=1}^p \sum_{j=1}^p \sum_{k=1}^p \beta_{ijk} X^{(i)} X^{(j)} X^{(k)}$$

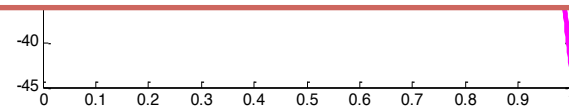
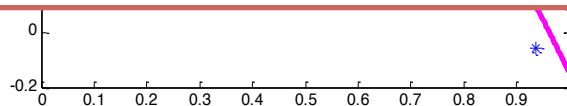
+ ... terms up to degree m

Polynomial Regression

Polynomial of order k , equivalently of degree up to $k-1$



What is the right order? Recall overfitting! More later ...

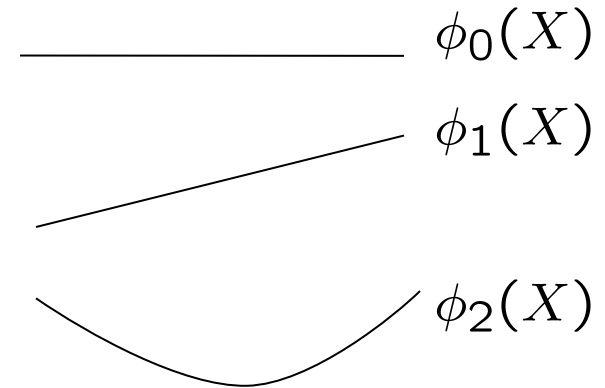


Regression with nonlinear features

$$f(X) = \sum_{j=0}^m \beta_j X^j = \sum_{j=0}^m \beta_j \phi_j(X)$$

Weight of
each feature

Nonlinear
features



In general, use any nonlinear features

e.g. e^X , $\log X$, $1/X$, $\sin(X)$, ...

What you should know

Linear Regression

- Least Squares Estimator

- Normal Equations

- Gradient Descent

- Probabilistic Interpretation (connection to MLE)

Regularized Linear Regression (connection to MAP)

- Ridge Regression, Lasso

Polynomial Regression, Regression with Non-linear features