

Law of total expectation

The proposition in [probability theory](#) known as the **law of total expectation**,^[1] the **law of iterated expectations**^[2] (**LIE**), the **tower rule**,^[3] **Adam's law**, and the **smoothing theorem**,^[4] among other names, states that if ***X*** is a [random variable](#) whose expected value **E(*X*)** is defined, and ***Y*** is any random variable on the same [probability space](#), then

$$\mathbf{E}(X) = \mathbf{E}(\mathbf{E}(X \mid Y)),$$

i.e., the [expected value](#) of the [conditional expected value](#) of ***X*** given ***Y*** is the same as the expected value of ***X***.

One special case states that if $\{A_i\}_i$ is a finite or [countable partition](#) of the [sample space](#), then

$$\mathbf{E}(X) = \sum_i \mathbf{E}(X \mid A_i) \mathbf{P}(A_i).$$

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Example

Suppose that two factories supply [light bulbs](#) to the market. Factory ***X***'s bulbs work for an average of 5000 hours, whereas factory ***Y***'s bulbs work for an average of 4000 hours. It is known that factory ***X*** supplies 60% of the total bulbs available. What is the expected length of time that a purchased bulb will work for?

Applying the law of total expectation, we have:

$$\mathbf{E}(L) = \mathbf{E}(L \mid X) \mathbf{P}(X) + \mathbf{E}(L \mid Y) \mathbf{P}(Y) = 5000(0.6) + 4000(0.4) = 4600$$

where

- $\mathbf{E}(L)$ is the expected life of the bulb;
- $\mathbf{P}(X) = \frac{6}{10}$ is the probability that the purchased bulb was manufactured by factory ***X***;
- $\mathbf{P}(Y) = \frac{4}{10}$ is the probability that the purchased bulb was manufactured by factory ***Y***;
- $\mathbf{E}(L \mid X) = 5000$ is the expected lifetime of a bulb manufactured by ***X***;

- $\mathbf{E}(L \mid Y) = 4000$ is the expected lifetime of a bulb manufactured by Y .

Thus each purchased light bulb has an expected lifetime of 4600 hours.

Proof in the finite and countable cases

Let the random variables \mathbf{X} and \mathbf{Y} , defined on the same probability space, assume a finite or countably infinite set of finite values. Assume that $\mathbf{E}[\mathbf{X}]$ is defined, i.e. $\min(\mathbf{E}[\mathbf{X}_+], \mathbf{E}[\mathbf{X}_-]) < \infty$. If $\{A_i\}$ is a partition of the probability space Ω , then

$$\mathbf{E}(\mathbf{X}) = \sum_i \mathbf{E}(\mathbf{X} \mid A_i) \mathbf{P}(A_i).$$

Proof.

$$\begin{aligned} \mathbf{E}(\mathbf{E}(\mathbf{X} \mid \mathbf{Y})) &= \mathbf{E} \left[\sum_x x \cdot \mathbf{P}(\mathbf{X} = x \mid \mathbf{Y}) \right] \\ &= \sum_y \left[\sum_x x \cdot \mathbf{P}(\mathbf{X} = x \mid \mathbf{Y} = y) \right] \cdot \mathbf{P}(\mathbf{Y} = y) \\ &= \sum_y \sum_x x \cdot \mathbf{P}(\mathbf{X} = x, \mathbf{Y} = y). \end{aligned}$$

If the series is finite, then we can switch the summations around, and the previous expression will become

$$\begin{aligned} \sum_x \sum_y x \cdot \mathbf{P}(\mathbf{X} = x, \mathbf{Y} = y) &= \sum_x x \sum_y \mathbf{P}(\mathbf{X} = x, \mathbf{Y} = y) \\ &= \sum_x x \cdot \mathbf{P}(\mathbf{X} = x) \\ &= \mathbf{E}(\mathbf{X}). \end{aligned}$$

If, on the other hand, the series is infinite, then its convergence cannot be conditional, due to the assumption that $\min(\mathbf{E}[\mathbf{X}_+], \mathbf{E}[\mathbf{X}_-]) < \infty$. The series converges absolutely if both $\sum_x x \cdot \mathbf{P}(\mathbf{X} = x)$ and $\sum_y \mathbf{P}(\mathbf{Y} = y)$ are finite, and diverges to an infinity when either $\sum_x x \cdot \mathbf{P}(\mathbf{X} = x)$ or $\sum_y \mathbf{P}(\mathbf{Y} = y)$ is infinite. In both scenarios, the above summations may be exchanged without affecting the sum.

Proof in the general case

Let Ω be a probability space on which two sub σ -algebras \mathcal{F} and \mathcal{G} are defined. For a random variable \mathbf{X} on such a space, the smoothing law states that if $\mathbf{E}[\mathbf{X}]$ is defined, i.e. $\min(\mathbf{E}[\mathbf{X}_+], \mathbf{E}[\mathbf{X}_-]) < \infty$, then

Proof. Since a conditional expectation is a Radon–Nikodym derivative, verifying the following two properties establishes the smoothing law:

- X is \mathcal{G} -measurable
- $E[X|\mathcal{G}] = X$ for all $\omega \in \Omega$

The first of these properties holds by definition of the conditional expectation. To prove the second one,

so the integral $\int X dP$ is defined (not equal to 0).

The second property thus holds since $E[X|\mathcal{G}] = X$ implies

Corollary. In the special case when $\mathcal{G} = \mathcal{F}$ and $X = 1_A$, the smoothing law reduces to

Proof of partition formula

where 1_A is the indicator function of the set A .

If the partition \mathcal{A} is finite, then, by linearity, the previous expression becomes

and we are done.

If, however, the partition \mathcal{P} is infinite, then we use the dominated convergence theorem to show that

Indeed, for every n , $\mathbb{E}[X] = \sum_{i=1}^n \mathbb{E}[X \mathbf{1}_{A_i}] + \mathbb{E}[X \mathbf{1}_{A_{n+1}^c}]$,

Since every element of the set Ω falls into a specific partition A_i , it is straightforward to verify that the sequence $\mathbb{E}[X \mathbf{1}_{A_i}]$ converges pointwise to X . By initial assumption, $\mathbb{E}[X] < \infty$. Applying the dominated convergence theorem yields the desired.

See also

- The fundamental theorem of poker for one practical application.
- Law of total probability
- Law of total variance
- Law of total covariance
- Law of total cumulance
- Product distribution#expectation (application of the Law for proving that the product expectation is the product of expectations)

References

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2. "Law of Iterated Expectation | Brilliant Math & Science Wiki" (<https://brilliant.org/wiki/law-of-iterated-expectation/>). *brilliant.org*. Retrieved 2018-03-28.

3. Rhee, Chang-han (Sep 20, 2011). "Probability and Statistics" (<https://web.stanford.edu/class/cme001/handouts/changhan/Refresher2.pdf>) (PDF).

4. Wolpert, Robert (November 18, 2010). "Conditional Expectation" (<https://www2.stat.duke.edu/courses/Fall10/sta205/lec/topics/rn.pdf>) (PDF).

- Billingsley, Patrick (1995). *Probability and measure*. New York: John Wiley & Sons. ISBN 0-471-00710-2. (Theorem 34.4)
- Christopher Sims, "Notes on Random Variables, Expectations, Probability Densities, and Martingales" (<http://sims.princeton.edu/yftp/Bubbles2007/ProbNotes.pdf>), especially equations (16) through (18)

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