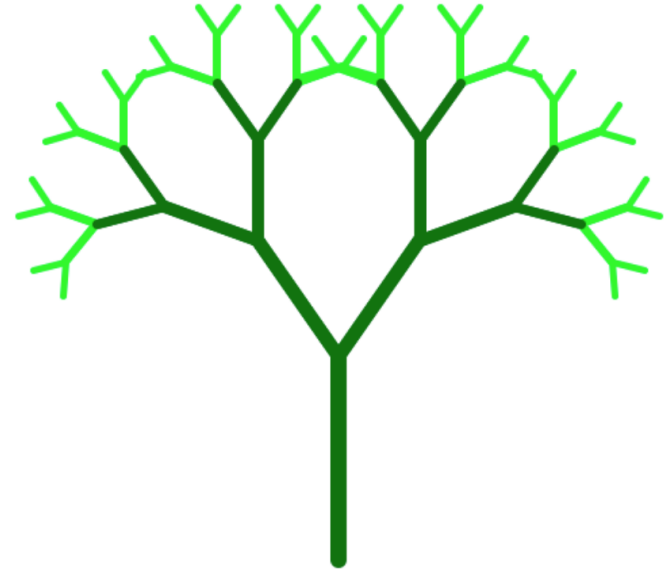
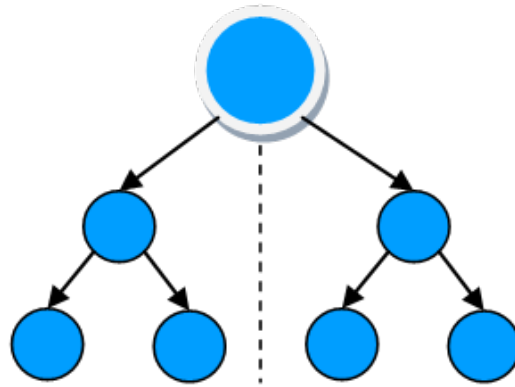


Lecture 4: Binary Trees



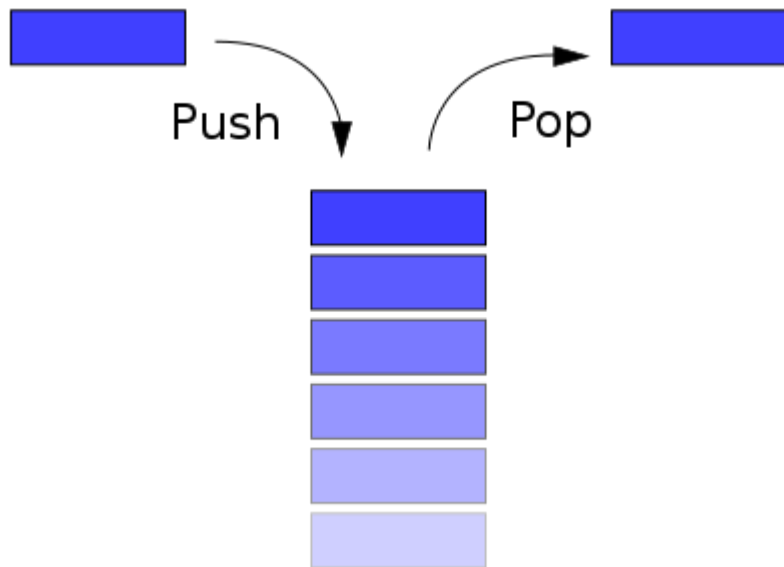
Objectives

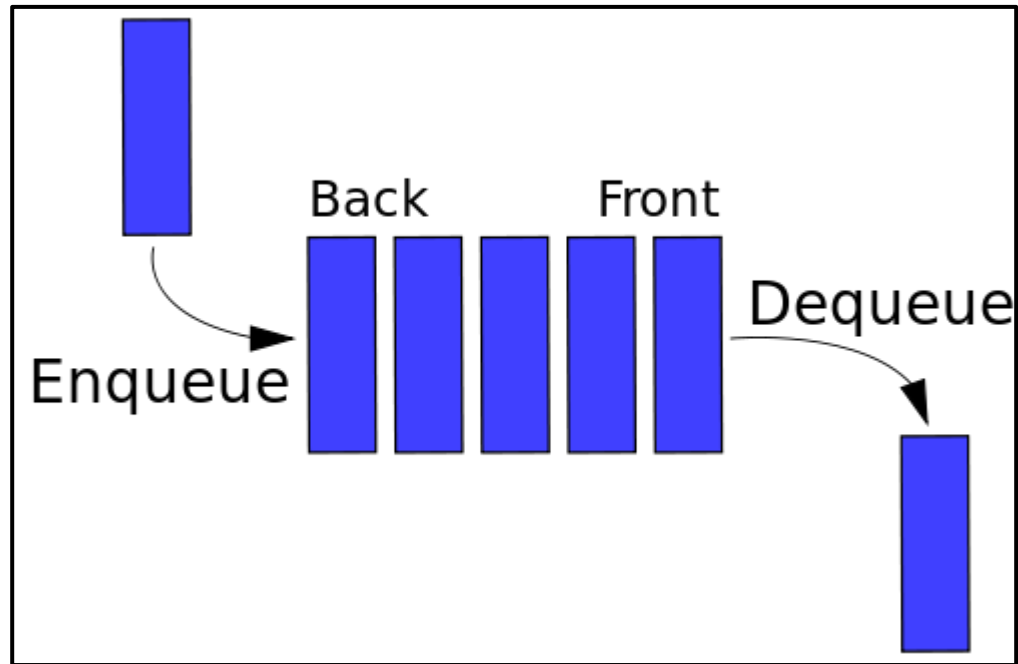
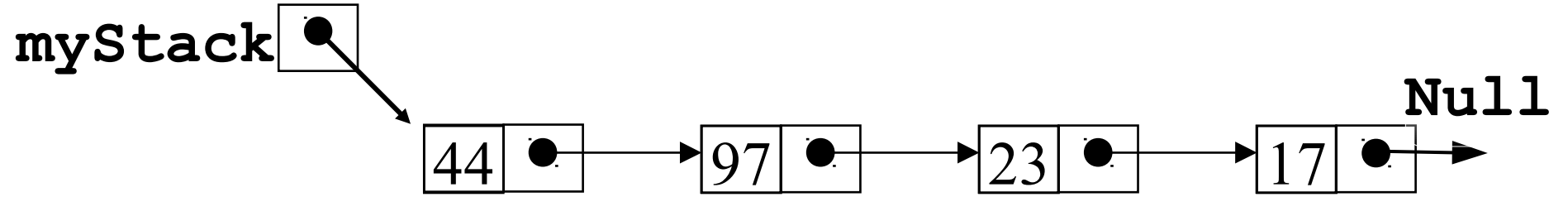
- Linear VS Non-linear Data Structures
- Binary Trees
- Binary Search Trees
- Operations
- Applications

Agenda

- Binary Trees
- Binary Search Trees
- Traversal, Search
- Operations
- Depth First Search
- Breadth First Search
- Application

0	1	2	3	4	5	6	7	8	9
91	92	99	93	94	95	44	97	23	17





Linear DS

Every item is related to its previous & next item

Data is arranged in linear sequence

Data items can be traversed in a single run

Array, Stack, Queue
Linked List

Implementation is easy

Non-Linear DS

Every item is attached with many other items

Data is not arranged in sequence

Data items cannot be traversed in a single run

Trees, Graphs

Implementation is difficult

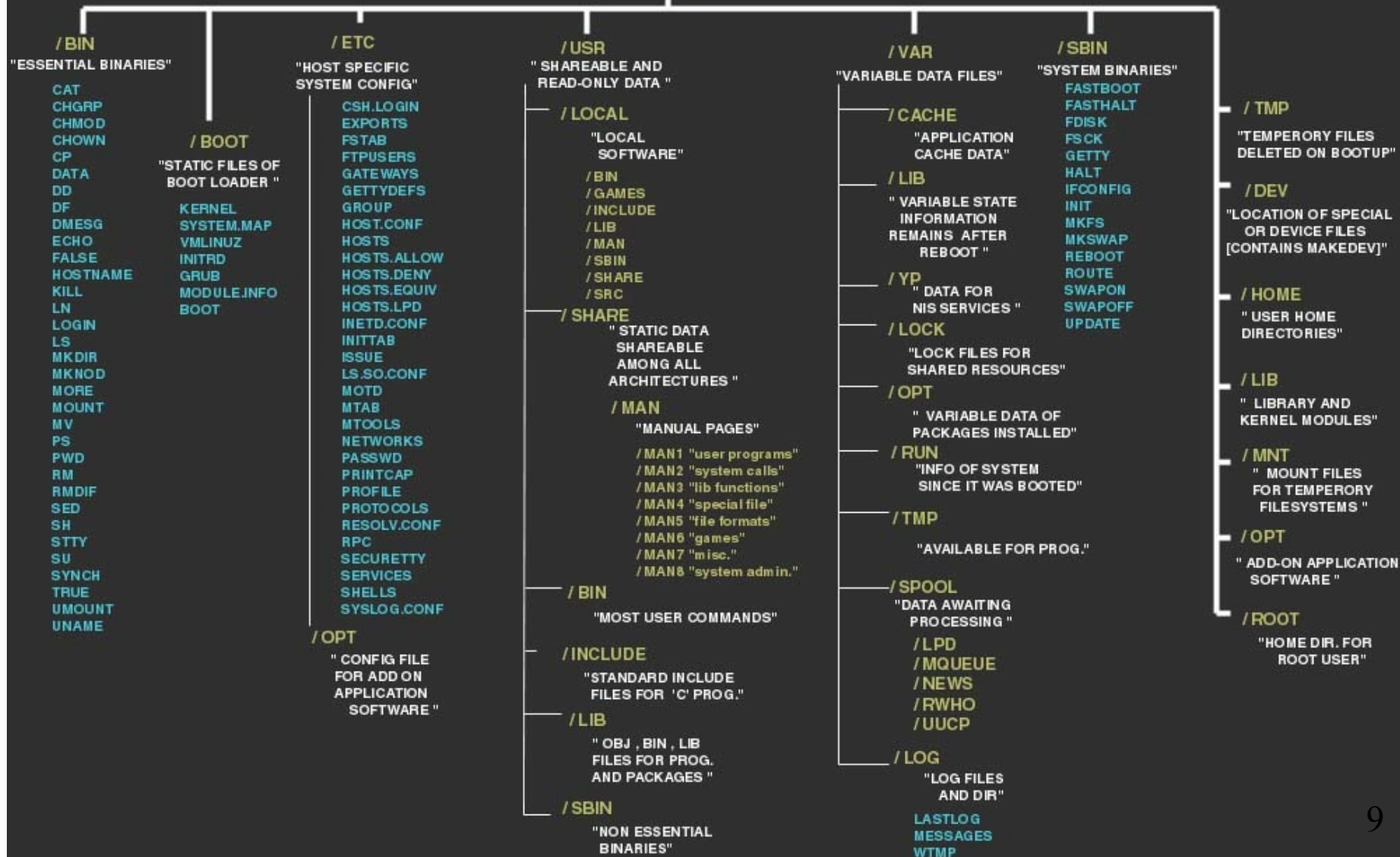
Data Structure Selection

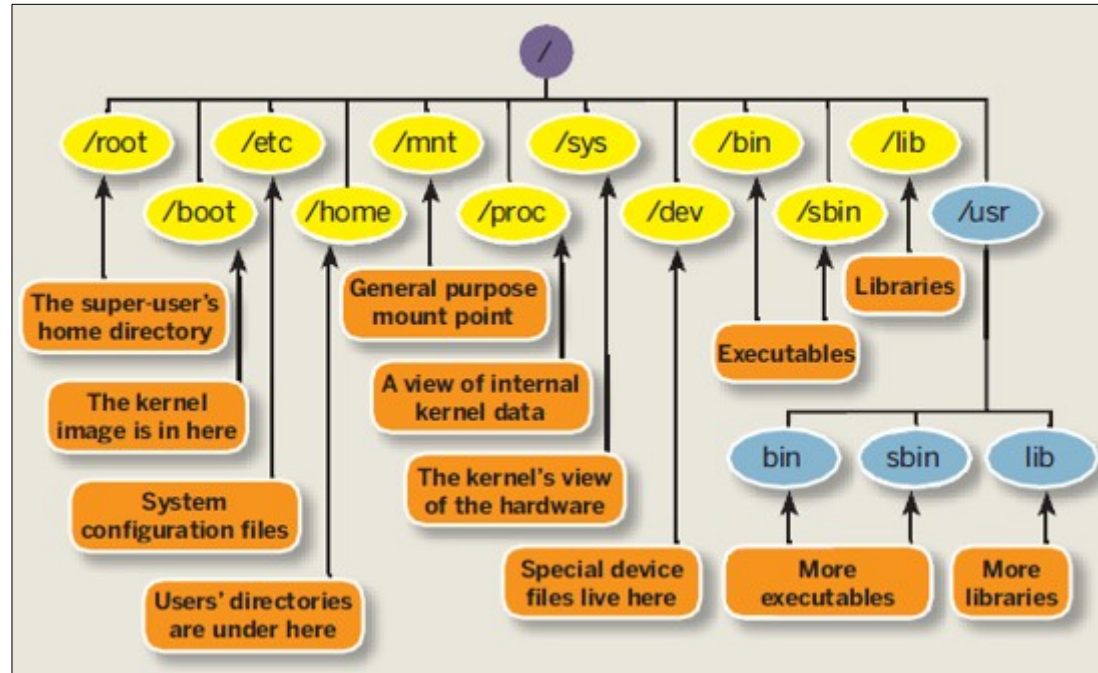
- What needs to be stored?
- Cost of operation
- Memory Usage
- Ease of Implementation

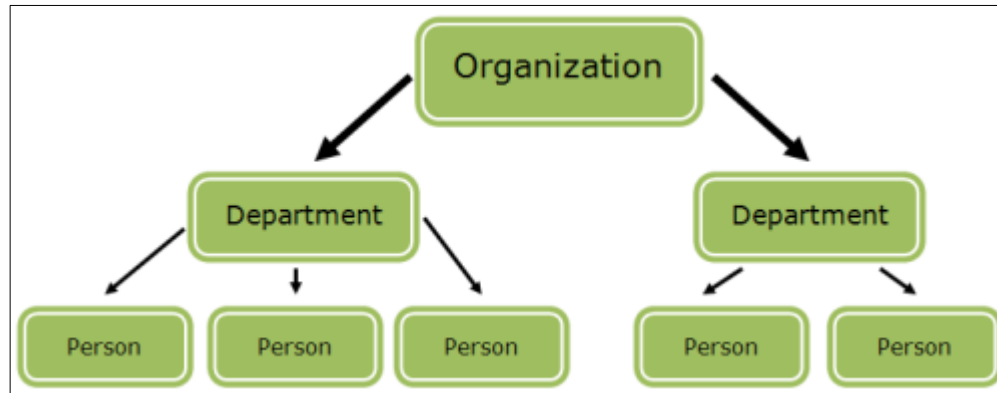
Trees

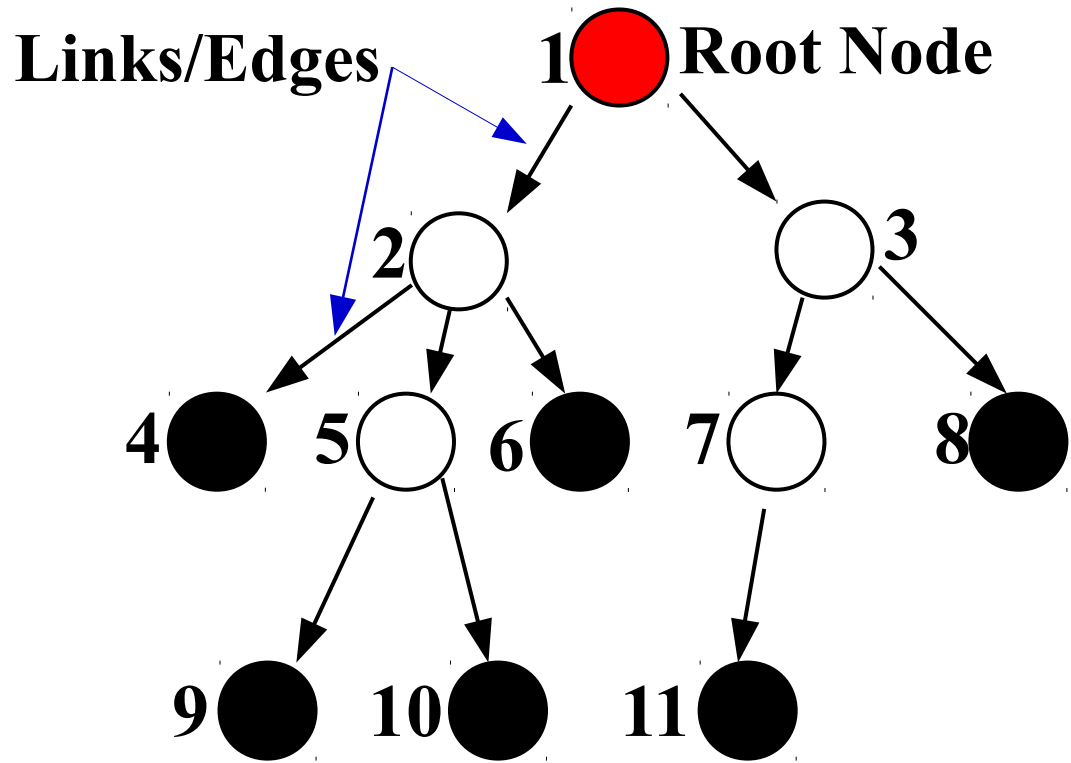
- Trees are useful for hierarchical data
 - ✓ A way to organize data if they are naturally hierarchical
 - ✓ A collection of entities called nodes linked together to simulate a hierarchy

/ "ROOT"







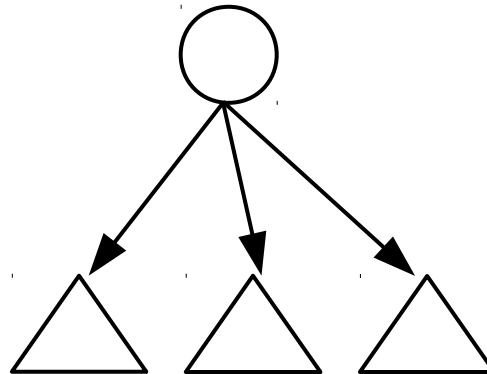


Except Leaf nodes: **Internal Nodes**

- a) Root Node: 1
- b) Children of 1: 2,3
- c) Sibling: {4,5,6} {7,8}...
- d) Leaf Node: 4,6,8,9,10,11
- e) 1 is grandparent of 4,5,6
- f) 4 is grandchild of 1
- g) Ancestors of 10: 1,2,5
- h) 10 is descendant of 5,2,1
- i) **Are 6,7 Siblings?** (Cousins)
- j) 3 is uncle of 6
- k) **Common ancestors of 4 & 9**
??

Properties of Trees

- Recursive data structure
 - ✓ A tree is composed of smaller trees (**subtrees**) & leaf nodes
- If there are **n** nodes, there will be exactly **n-1** edges
- There will be one incoming link for each node except root



Sub-Trees

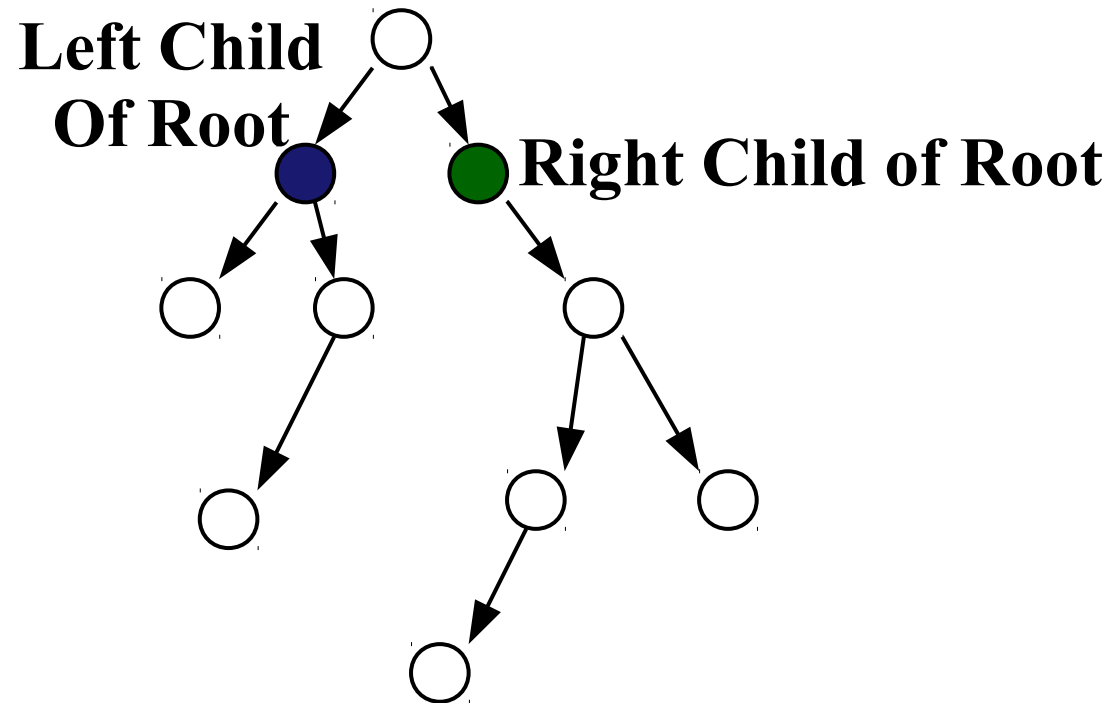
- Depth & Height
 - ✓ **Depth of n^{th} node = no. of edges in path from Root to n**
 - ✓ **Height of n^{th} node = no. of edges in longest path from n to Leaf**
 - ✓ **Depth of Root Node = 0**
 - ✓ **Height of tree = Height of Root Node**

Applications

- Storing naturally hierarchical data
 - ✓ File system on your disk drive
 - ✓ File & Folder hierarchy is naturally hierarchical data
- Organizing data, collection
- Dictionary
- Network Routing Algorithms

Binary Trees

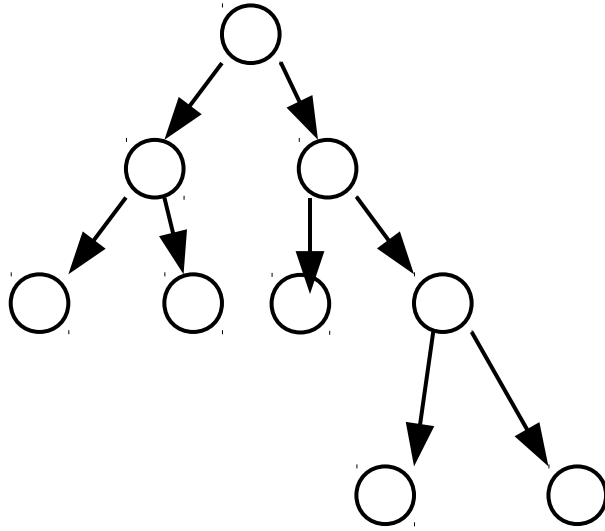
- A tree in which each node can have at most 2 children



- If a tree has just a single node, then also its called a **BT**
- **Types of BT**
 - ✓ **Proper BT (Strict, Full, 2-Tree)**
 - ✓ **Complete BT**
 - ✓ **Perfect BT**
 - ✓ **A degenerate(Pathological) BT**
 - ✓ **Balanced BT**

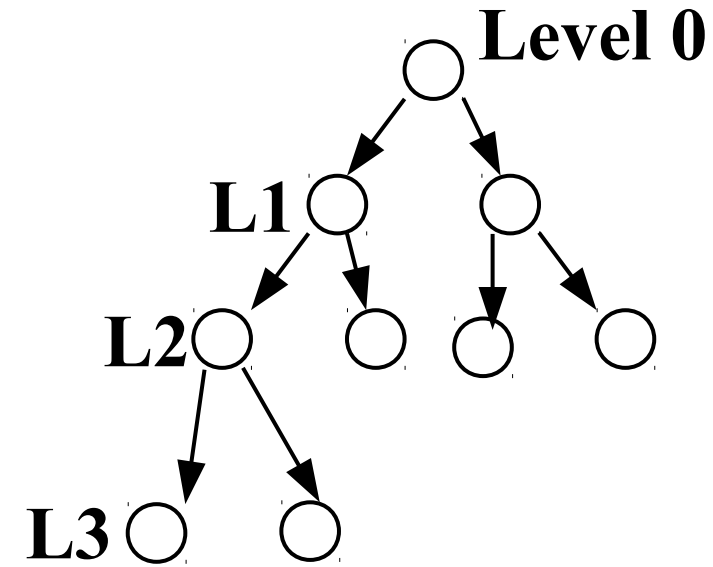
- **Proper BT**

- ✓ Each node can have either 2 or 0 children
- ✓ Number of leaf nodes = no. of internal nodes + 1



- **Complete BT**

- ✓ All levels, except possibly last, is completely filled & all nodes are as far left as possible
- ✓ Height of root node = Maximum depth of tree = height of the tree
- ✓ Maximum no. of nodes at level $L = 2^L$

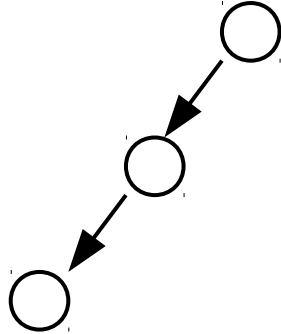


- **Perfect BT**

- ✓ All internal nodes have two children & all leaves are at same level
- ✓ **Are all proper BT are perfect?**
- ✓ Maximum no. of nodes(**n**) with height **h** = **$2^0 + 2^1 + \dots + 2^h$**
- ✓ **$n = 2^{h+1} - 1 = 2^{\text{no. of levels}} - 1$**
- ✓ What will be the height of Perfect BT with n-nodes?

$$\mathbf{h = \log(n+1)-1}$$

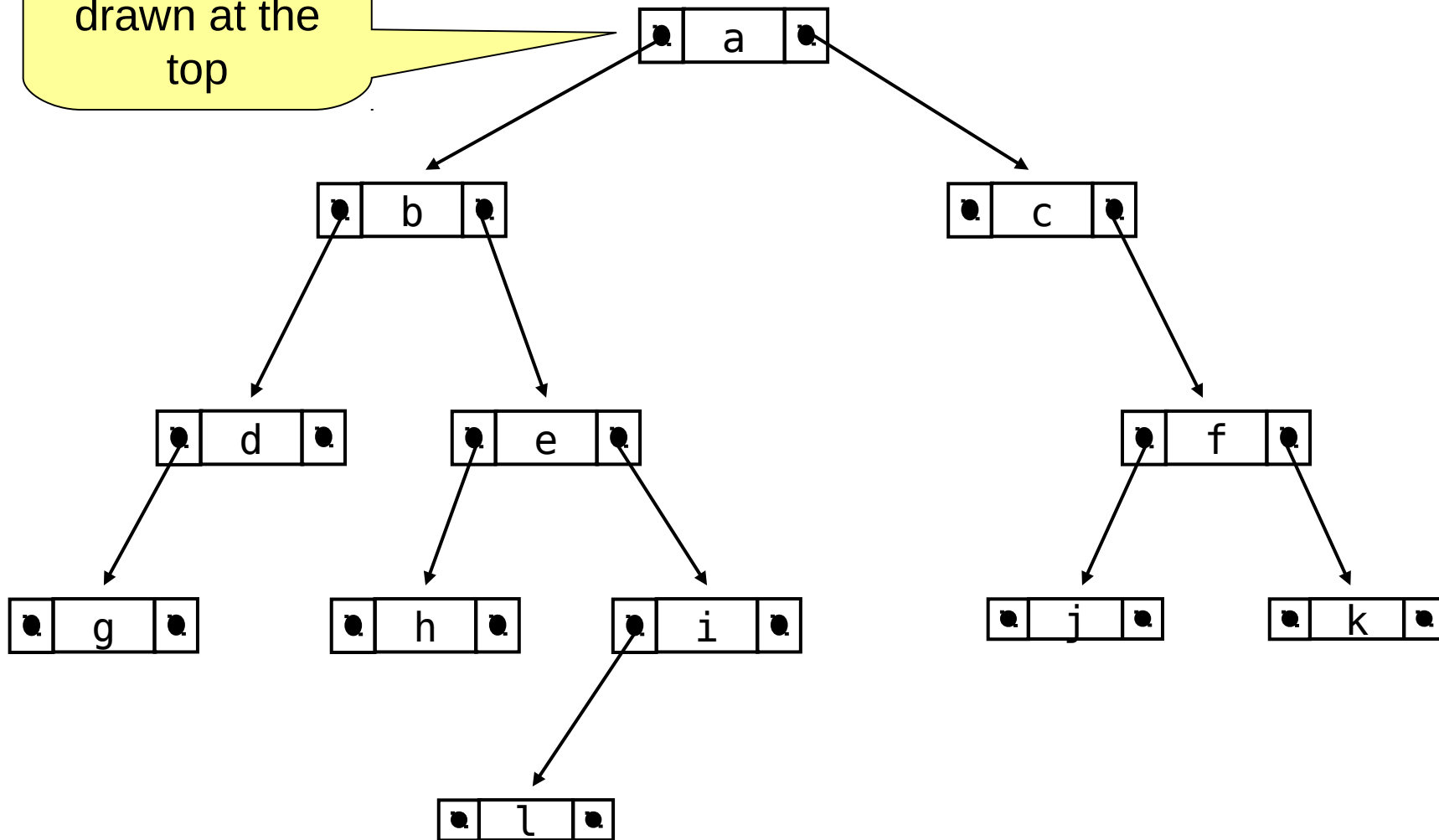
- **A degenerate(or Pathological) BT**
 - ✓ A tree where every internal node has one child. These type of trees are performance wise same as linked-list.
 - ✓ **Maximum height = $n-1$**



- **Balanced BT**
 - ✓ A binary tree in which difference between height of left & right subtree for every node is not more than k (mostly 1)
 - ✓ **Difference = $|\text{Height}_{\text{left}} - \text{Height}_{\text{right}}|$**
 - ✓ **Height of an empty tree = -1**
 - ✓ **Height of a tree with just one node = 0**

- **Implementation of BT**
 - ✓ Dynamically created nodes (Linked List)
 - ✓ Arrays(In case of Complete BT)
 - **For node at index i**
 - Left-child-index = $2i+1$
 - Right-child-index = $2i+2$

The root is
drawn at the
top

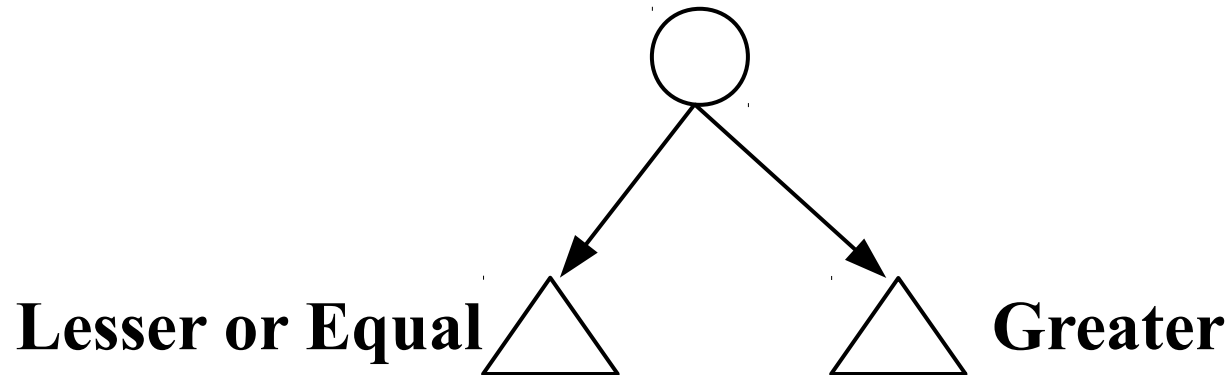


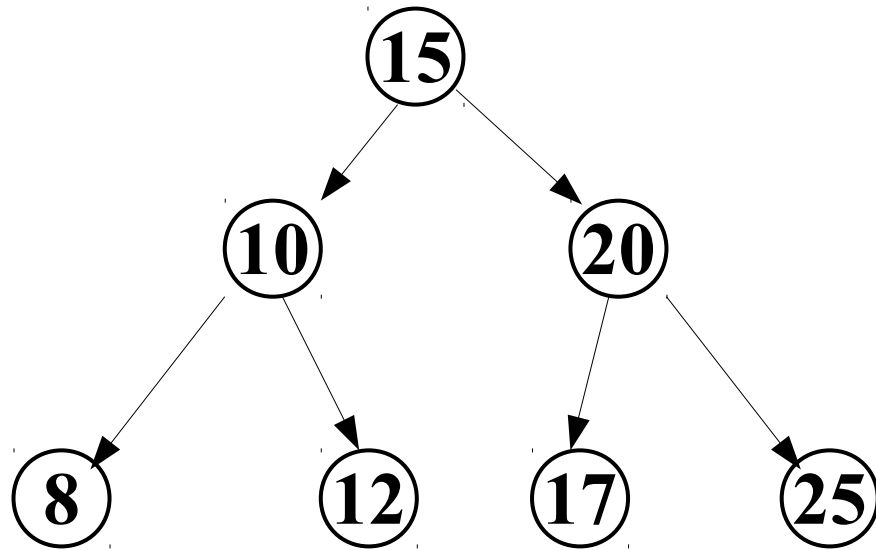
- **Binary Search Tree**

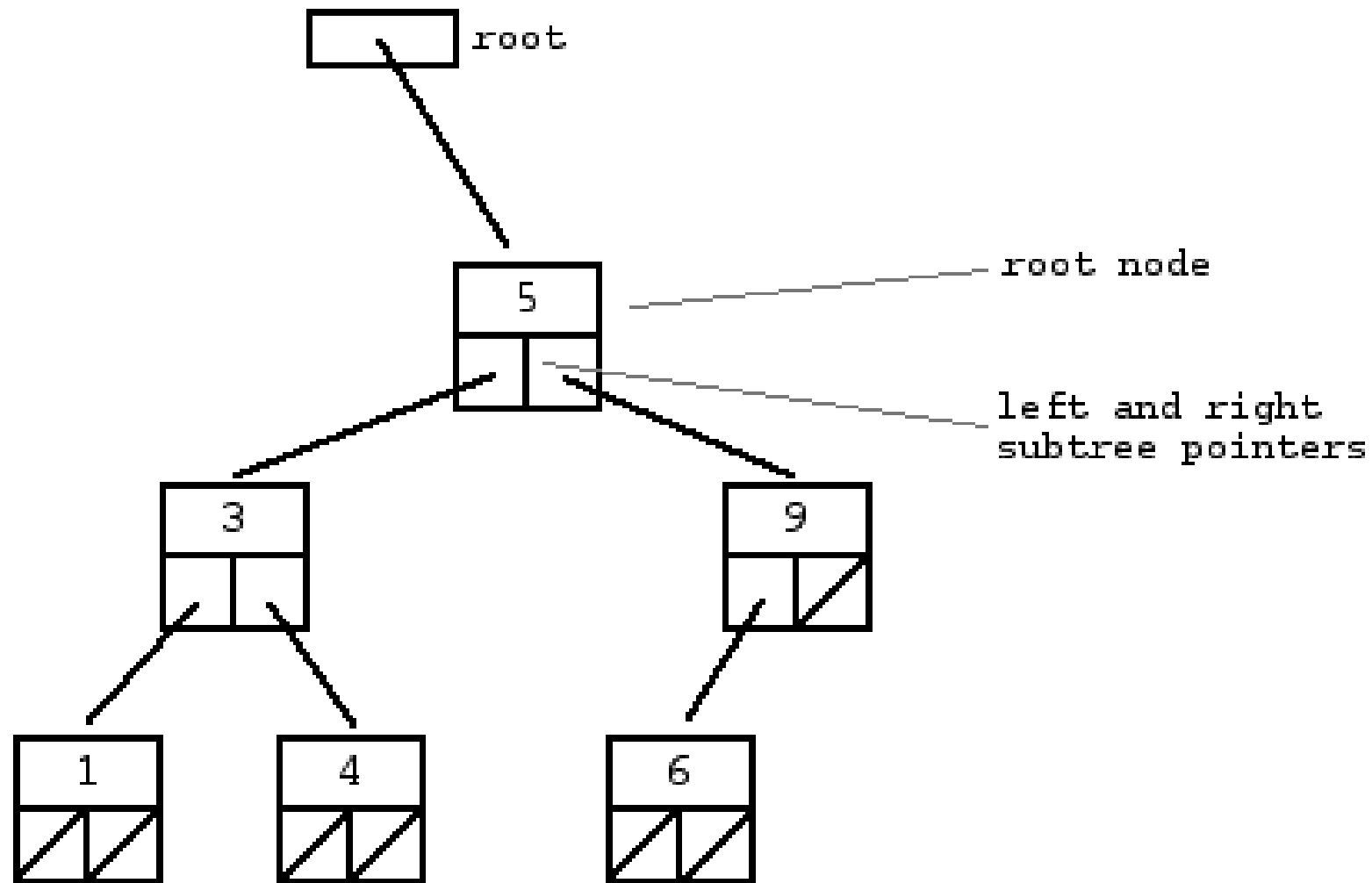
Operations	Array Unsorted	Linked List	Array Sorted	BST Balanced
Search(x)	$O(n)$	$O(n)$	$O(\log n)$	$O(\log n)$
Insert(x)	$O(1)$	$O(1)$	$O(n)$	$O(\log n)$
Remove(x)	$O(n)$	$O(n)$	$O(n)$	$O(\log n)$

- **Binary Search Tree**

- ✓ Binary search tree or Ordered binary tree where the nodes are arranged in order
- ✓ For each node, all elements in its left subtree are less-or-equal to the node (\leq), and all the elements in its right subtree are greater than the node ($>$).

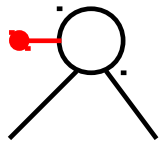




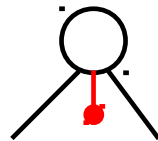


• Tree Traversal

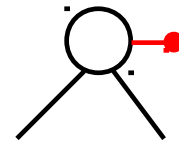
- ✓ Binary Tree consists of a root, a left subtree, and a right subtree
- ✓ To traverse (or walk) the binary tree is to visit each node in the binary tree exactly once (Depth First Search)
- ✓ **<Root><Left><Right> : Pre-Order**
- ✓ **<Left><Root><Right> : In-Order**
- ✓ **<Left><Right><Root>: Post-Order**



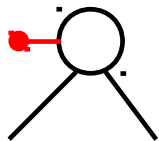
preorder



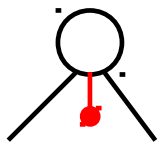
inorder



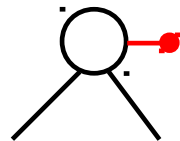
postorder



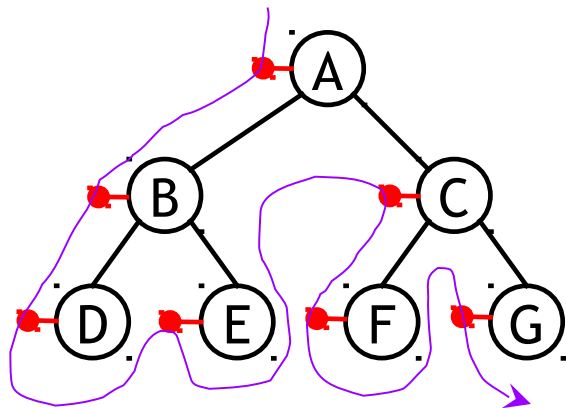
preorder



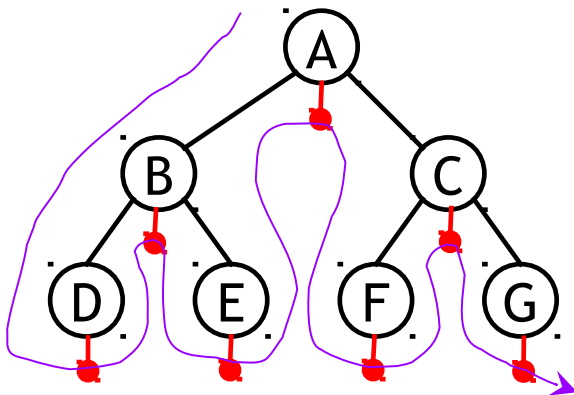
inorder



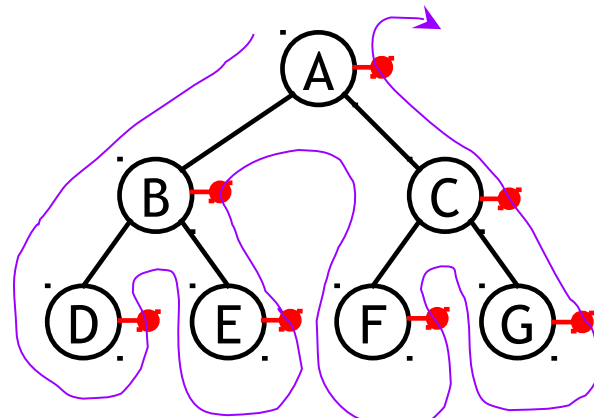
postorder



A B D E C F G



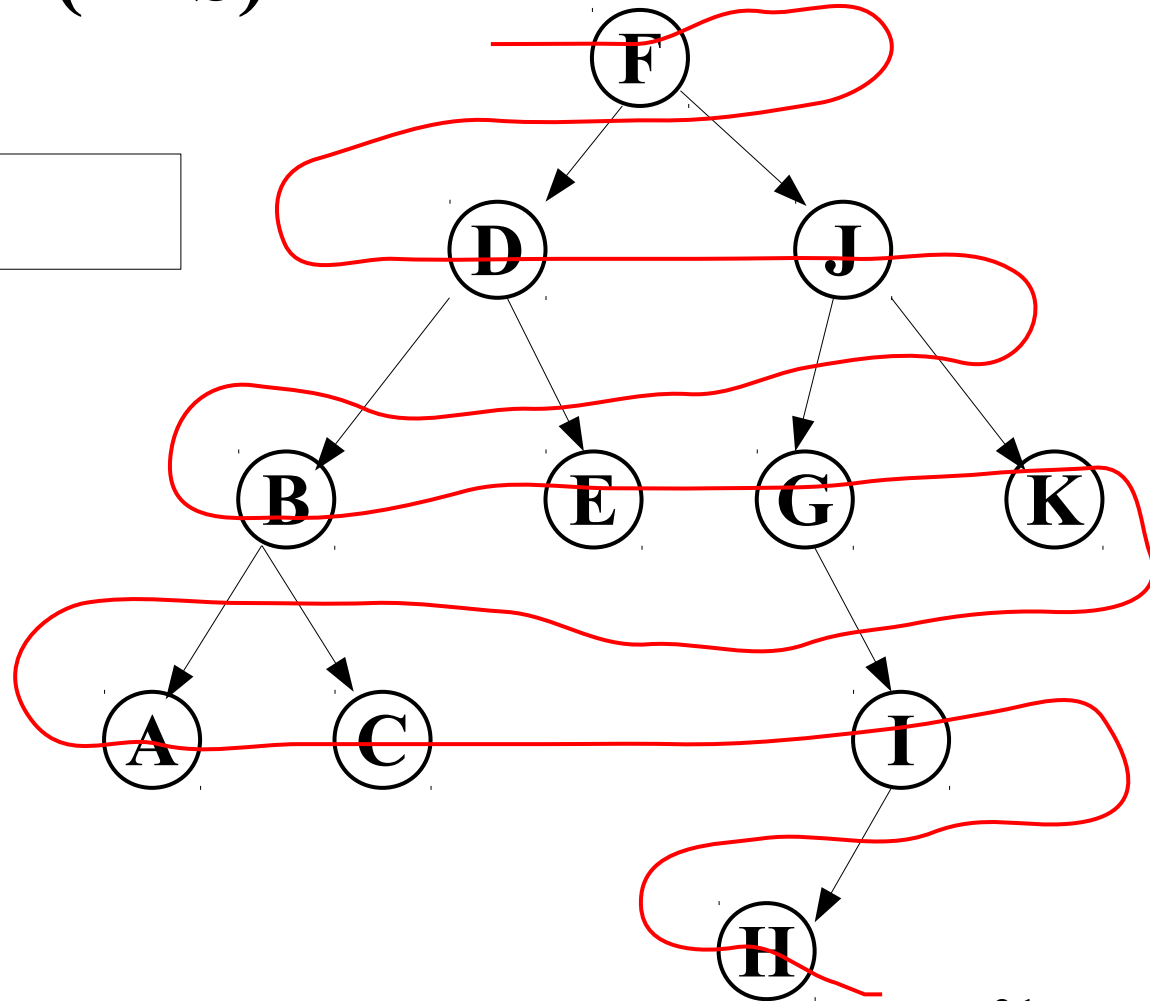
D B E A F C G



D E B F G C A

- **Level Order Traversal (BFS)**

FDJBEGKACIH



Full Binary Tree Theorem

- The number of leaves in a non-empty full binary tree is one more than the number of internal nodes
 - ✓ No. of leaf nodes = No. of internal nodes + 1
 - ✓ Relevant since it helps us calculate space requirements
- **Proof** by Mathematical Induction
 - ✓ **Base Case:** A full binary tree with **0** internal node has **1** leaf node

- **Proof by Mathematical Induction**
 - ✓ **Base Case:** A full binary tree with **0** internal node has **1** leaf node
 - ✓ **Induction Hypothesis:** Assume any full binary tree **T** containing **$n - 1$** internal nodes has **n** leaves
 - ✓ **Induction Step:** Given a full tree **T** with **$n - 1$** internal nodes (\Rightarrow **n leaves**), add two leaf nodes as children of one of its leaves \Rightarrow obtain a tree **T'** having **n** internal nodes and **$n + 1$** leaves

Full Binary Tree Theorem Corollary

- The number of empty subtrees in a non-empty binary tree is **one more than** the number of nodes in the tree
- **Proof**
 - ✓ Replace all empty subtrees with a leaf node. This is a full binary tree, having
leaves = empty subtrees of original tree

Binary Tree Node ADT

```
interface BinNode { // ADT for binary tree nodes
// Return and set the element value
public Object element();
public Object setElement(Object v);
// Return and set the left child
public BinNode left();
public BinNode setLeft(BinNode p);
// Return and set the right child
public BinNode right();
public BinNode setRight(BinNode p);
// Return true if this is a leaf node
public boolean isLeaf(); }
```

Traversals

- Any process for visiting the nodes in some order is called a **traversal**
- Depth First Search

- Depth First Search
 - ✓ Pre-Order (Root, Left, Right)
 - ✓ In-Order (Left, Root, Right)
 - ✓ Post-Order (Left, Right, Root)
- ✓ Reverse Pre-Order (Root, Right, Left)
 - ✓ Reverse In-Order (Right, Root, Left)
 - ✓ Reverse Post-Order (Right, Left, Root)

DFS(Basic Pseudocode)

$O(n)$

- Initialize an empty stack for storage of nodes, S .
 - For each node n , define $n.visited$ to be false.
 - Push the root (first node to be visited) onto S .
 - While S is not empty:
 - Pop the first element in S , n .
 - If $n.visited = \text{false}$, then:
 - $n.visited = \text{true}$
 - for each unvisited neighbor p of n :
 - Push p into S .
- End process when all nodes have been visited.

DFS(Pre-Order)

$O(n)$

- Create an empty stack S & push root node to S
- while S is not empty.

Pop an item from stack and print it

Push right child of popped item to stack

Push left child of popped item to stack

// Right child is pushed before left child to make sure that left subtree is processed first.

BFS

$O(n)$

- **BFS (T, s)**

//Where T is the Tree & s is the root node

- **let Q be queue.**

//Inserting s in queue until all nodes marked

Q.enqueue(s)

- **mark s as visited**

- **while (Q is not empty)**

//Removing node from queue, whose neighbor will be

//visited now

p = Q.dequeue()

- **for all neighbours R of P in T, if R: not visited**

- **Q.enqueue(R) & mark R as visited**

- Just before starting to explore level **n**, the queue holds all the nodes at level **n-1**
- In a typical tree, the number of nodes at each level increases *exponentially* with the depth
- Memory requirements may be infeasible
- There is *no* “recursive” breadth-first search equivalent to recursive depth-first search

Heaps

A *(binary) heap* data structure is an array object that can be viewed as a complete binary tree

- Each node of the tree corresponds to an element of the array that stores the value in the node
- Max Heap: $A[\text{parent}(i)] \geq A[i]$
 - ✓ *The root of any sub-tree holds the **greatest** value in the sub-tree*
- Min Heap: $A[\text{parent}(i)] \leq A[i]$
 - ✓ *The root of any sub-tree holds the least value in that sub-tree*

- **Operations**

- ✓ **getMini():** It returns the root element of Min Heap. **$O(1)$**
- ✓ **extractMin():** Removes the minimum element from Min Heap. **$O(\text{Log}n)$**
- ✓ **insert():** Inserting a new key takes **$O(\text{Log}n)$** time. We add a new key at the end of the tree. If new key is greater than its parent, then we don't need to do anything. Otherwise...!
- ✓ **decreaseKey():** Decreases value of key. **$O(\text{Log}n)$** If the decreases key value of a node is greater than parent of the node, then we don't need to do anything. Otherwise...!

- **Max-Heapify**

- ✓ Given a tree that is a heap except for node **i**,
- ✓ Max-Heapify function arranges node **i** and its subtrees to satisfy the heap property

MAX-HEAPIFY(A, i)

$O(h)$

l = LEFT(i)

r = RIGHT(i)

if l ≤ A.heapsize and A[l] > A[i]

largest = l

else

largest = i

if r ≤ A.heapsize and A[r] > A[largest]

largest = r

if largest ≠ i

exchange A[i] with A[largest]

~~else~~ MAX-HEAPIFY(A, largest)

Priority Queue

- Extension of Queue with following properties:
 - ✓ Every item has a priority associated with it
 - ✓ An element with high priority is dequeued before an element with low priority
 - ✓ If two elements have the same priority, they are served according to their order in the queue
- Using a heap to implement a priority queue, we will always have the element of highest priority in the root node of the heap

- **Operations**

- ✓ **getHighestPriority()**: $O(1)$

- ✓ **insert()**: $O(\log n)$

- ✓ **deleteHighestPriority()**: $O(\log n)$

...?

Thank You