

# FP5

image index	id	# pts	xmin lidar	xmin difference	past mean xmin	TTC Lidar (cm)	past mean TTC
0		5	312	7,9740			
1		5	328	7,9130	0,0610	12,9722	
2		3	295	7,8490	0,0640	12,2640	12,9722
3		5	307	7,7930	0,0560	13,9161	12,6181
4		6	307	7,7410	0,0520	14,8865	13,0508
5		5	333	7,6380	0,1030	7,4155	13,5097
6		6	334	7,5770	0,0610	12,4213	12,2909
7		4	307	7,5550	0,0220	34,3404	12,3126
8		5	286	7,4750	0,0800	9,3438	15,4594
9		4	287	7,4340	0,0410	18,1318	14,6950
10		4	266	7,3930	0,0410	18,0318	15,0768
11		4	283	7,3440	0,0490	14,9877	15,3723
12		4	292	7,2720	0,0720	10,1000	15,3374
13		1	307	7,1940	0,0780	9,2231	14,9009
14		1	299	7,1290	0,0650	10,9678	14,4642
15		1	284	7,0420	0,0870	8,0942	14,2144
16		1	279	6,9630	0,0790	8,3139	13,8064
17		1	271	6,8960	0,0670	10,2926	13,4631
18		1	280	6,8160	0,0800	8,5200	13,2766

Outliers are filter out using the interquartile range (IRQ)

TTC Lidar estimation over frame

