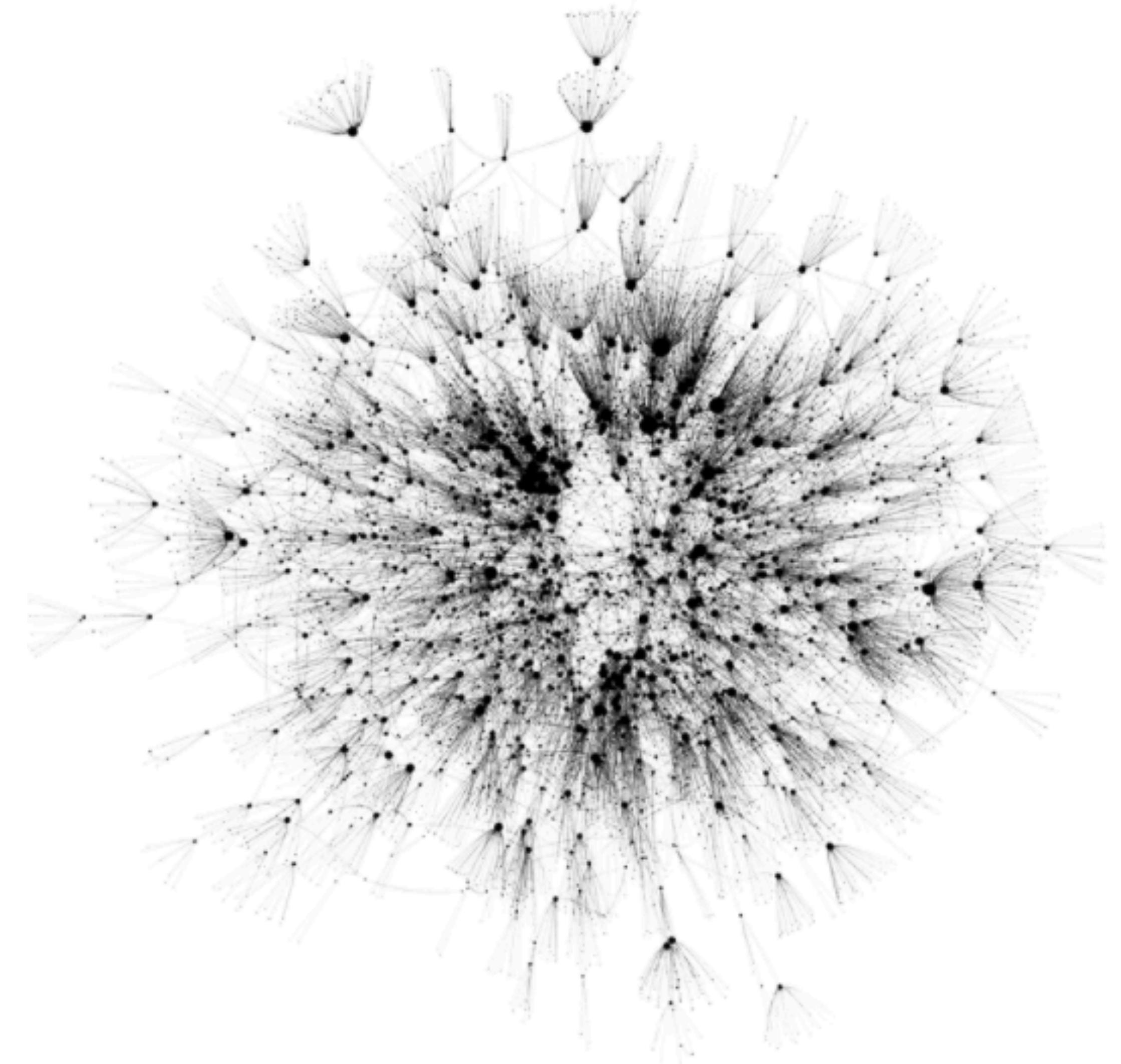


Social Network Analysis - Lecture 11

2162-F23

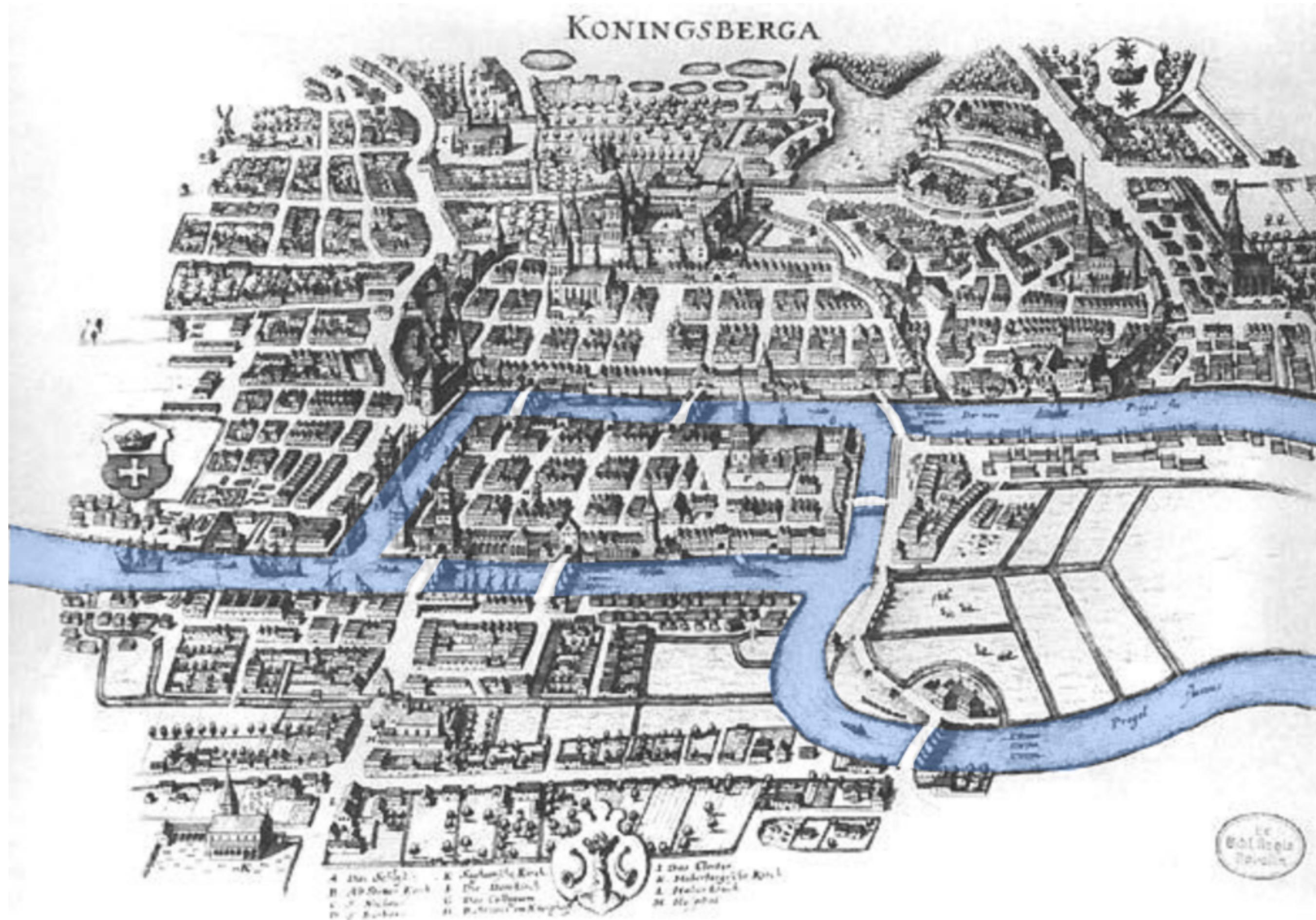
2023-03-13



Today's plan!

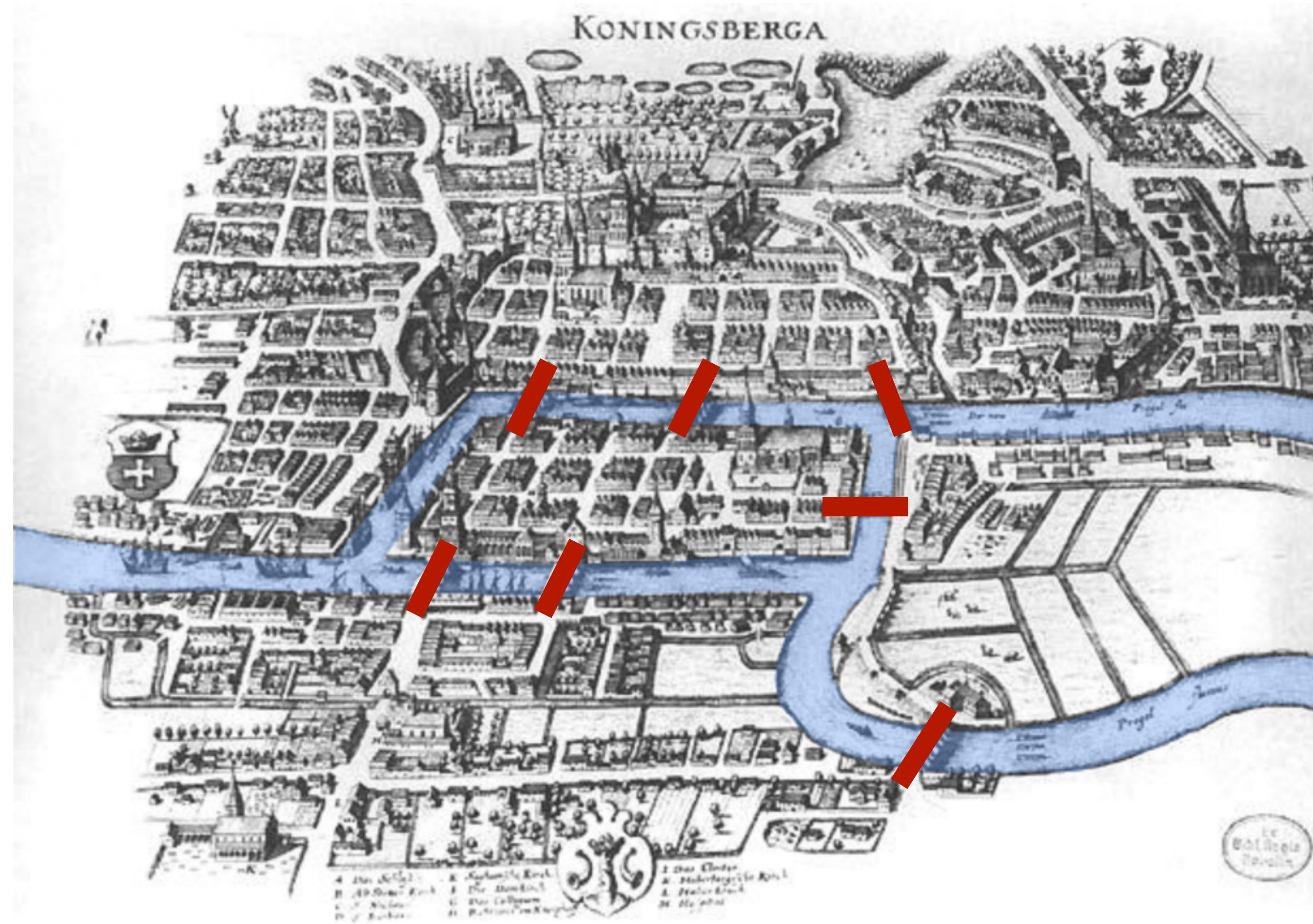
1. Introduction to the course: why networks?
2. Key concepts: Nodes, links, paths
3. Network representation: edge list, matrix
4. Linear Algebra quick recap

Königsberg bridges

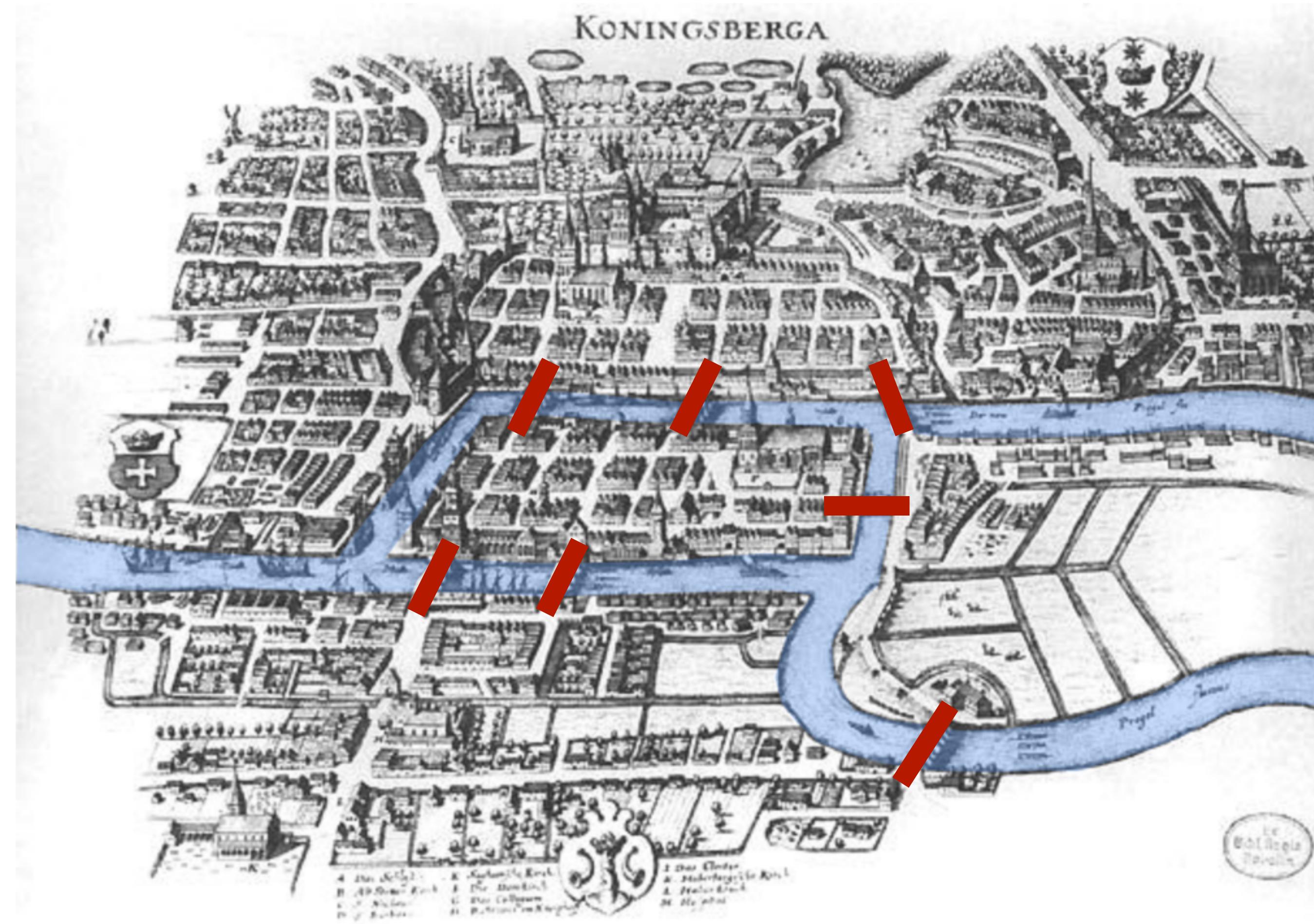


1735

Königsberg bridges

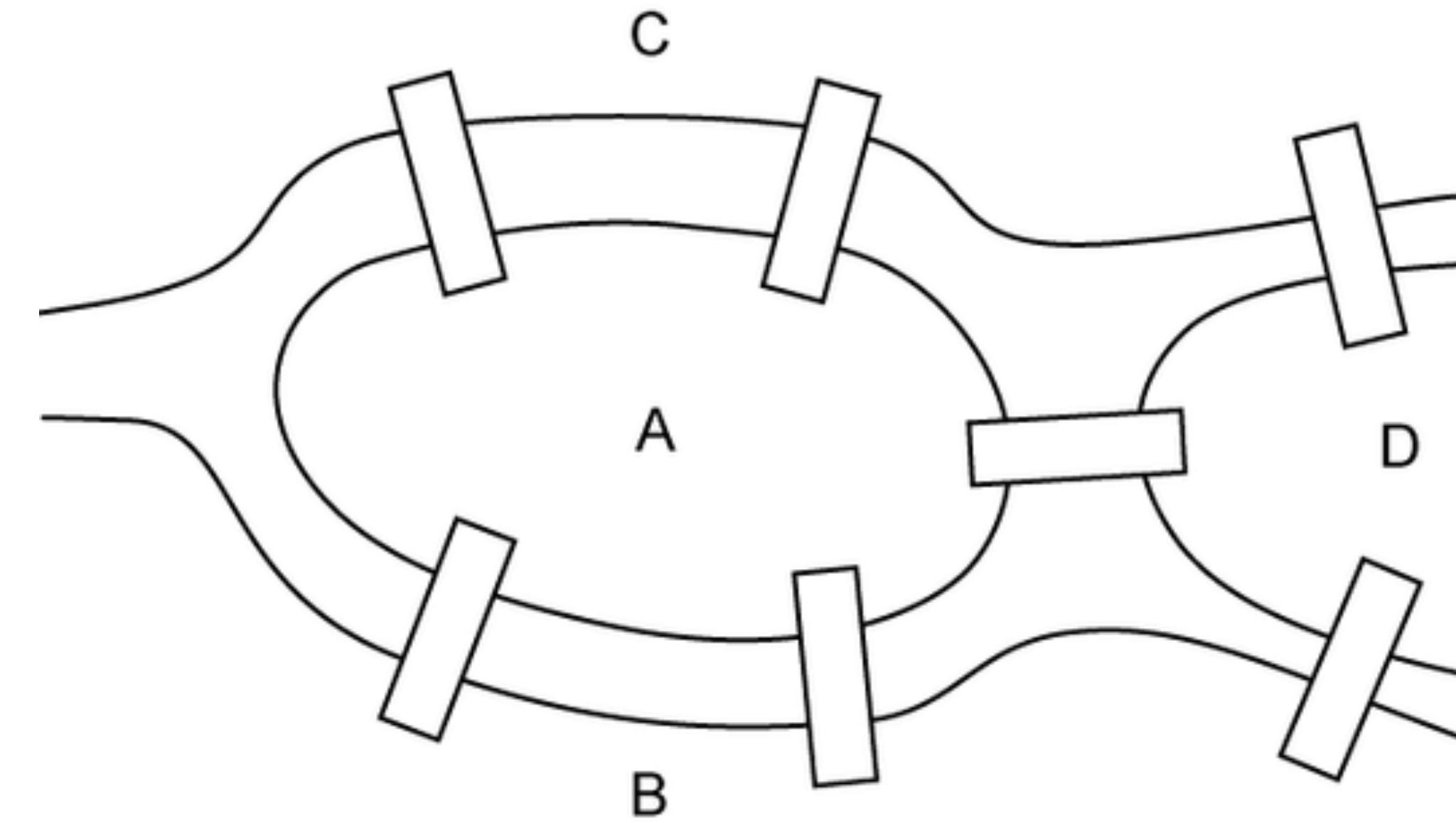
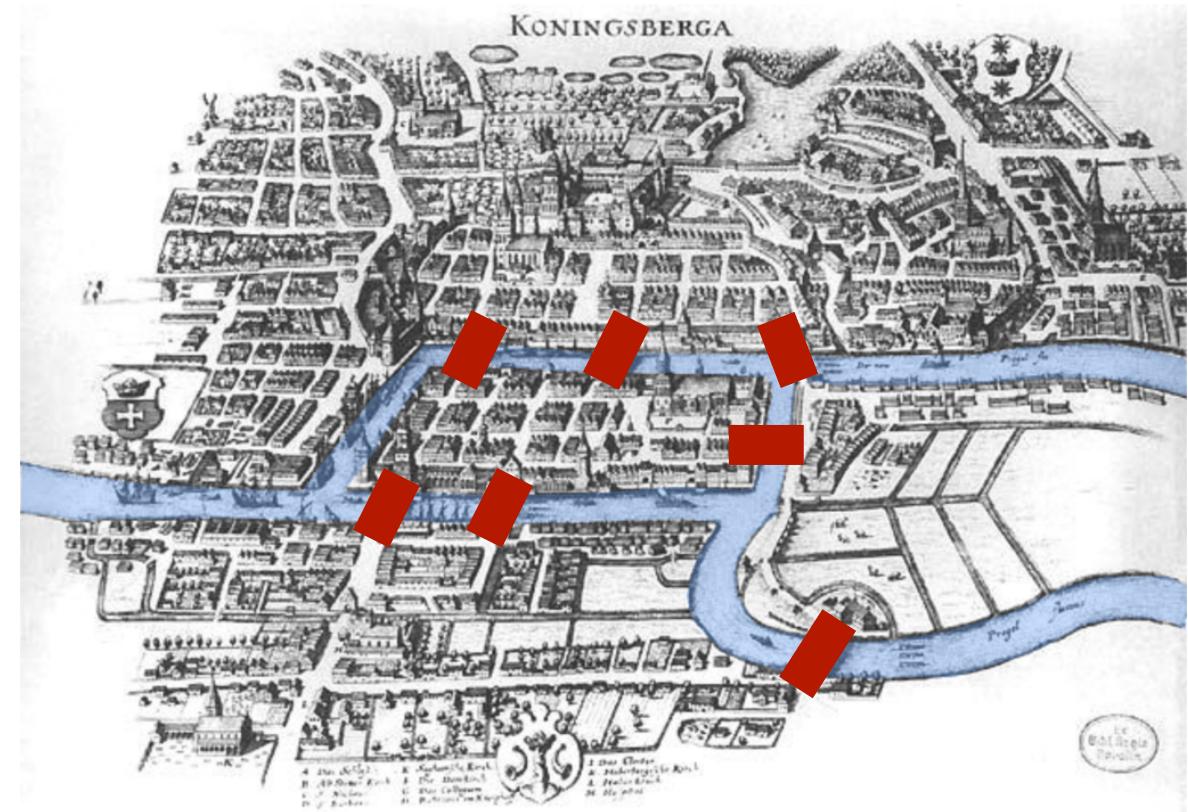


Königsberg bridges



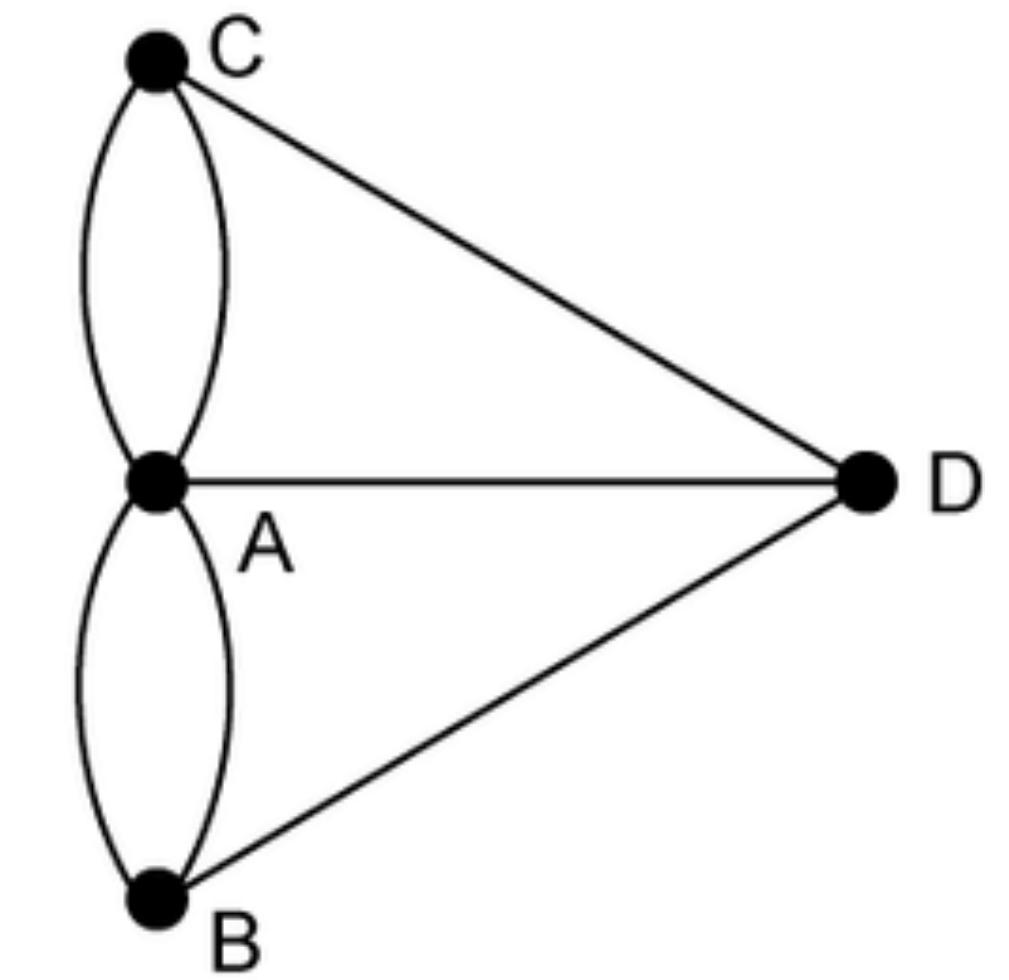
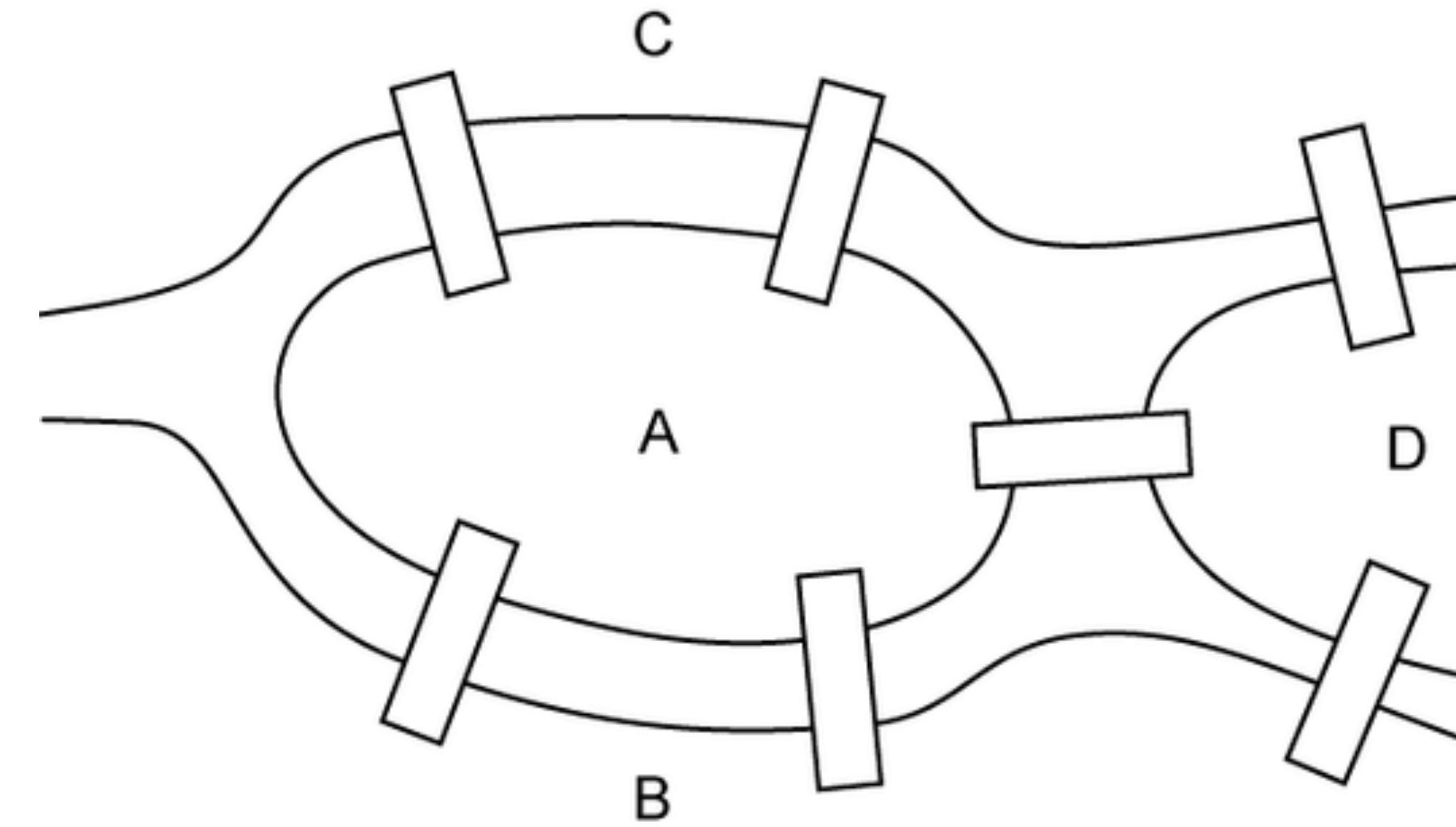
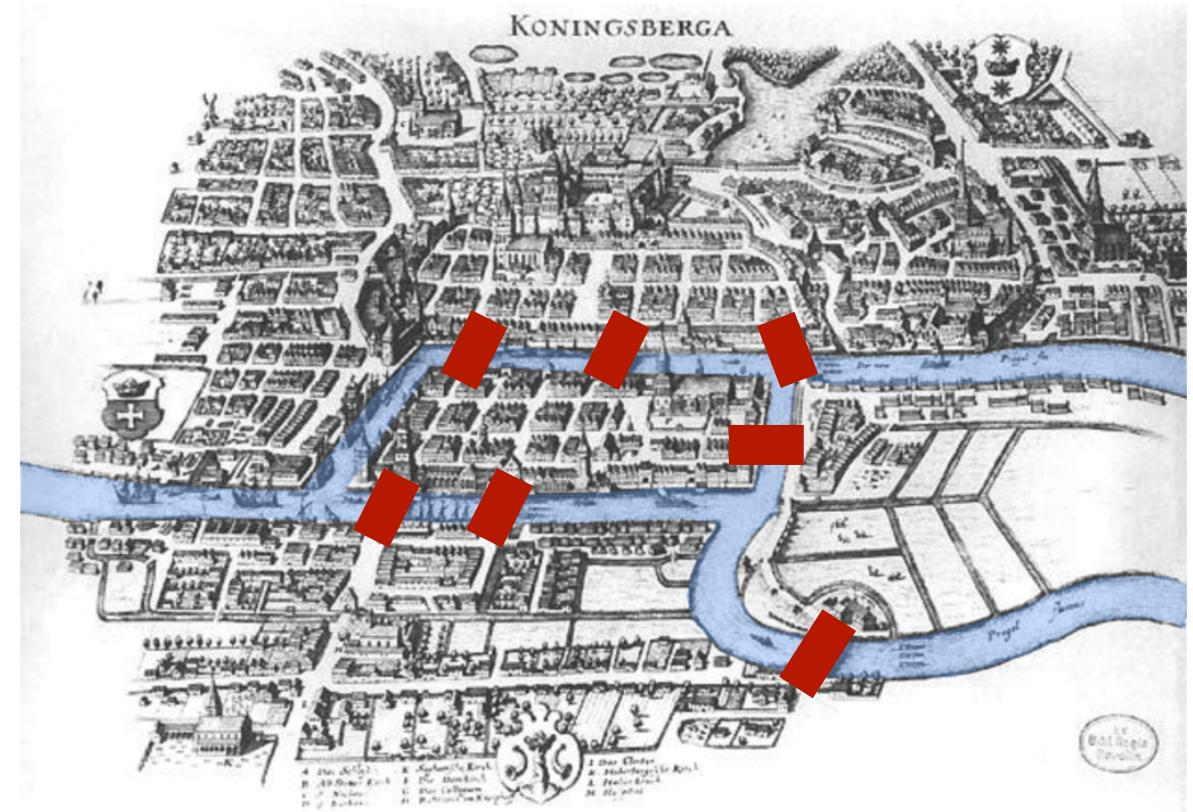
Q: Is it possible to devise a walk through the city that would cross each of those bridges once and only once?

Königsberg bridges



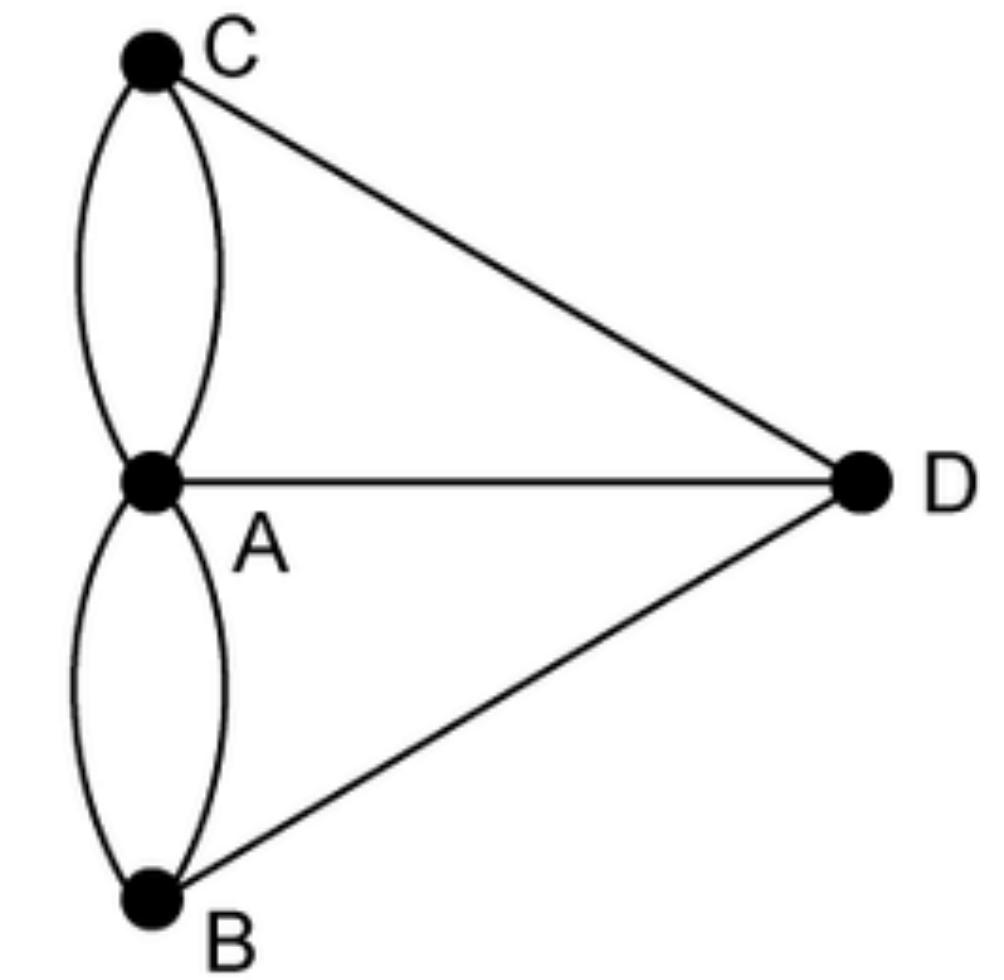
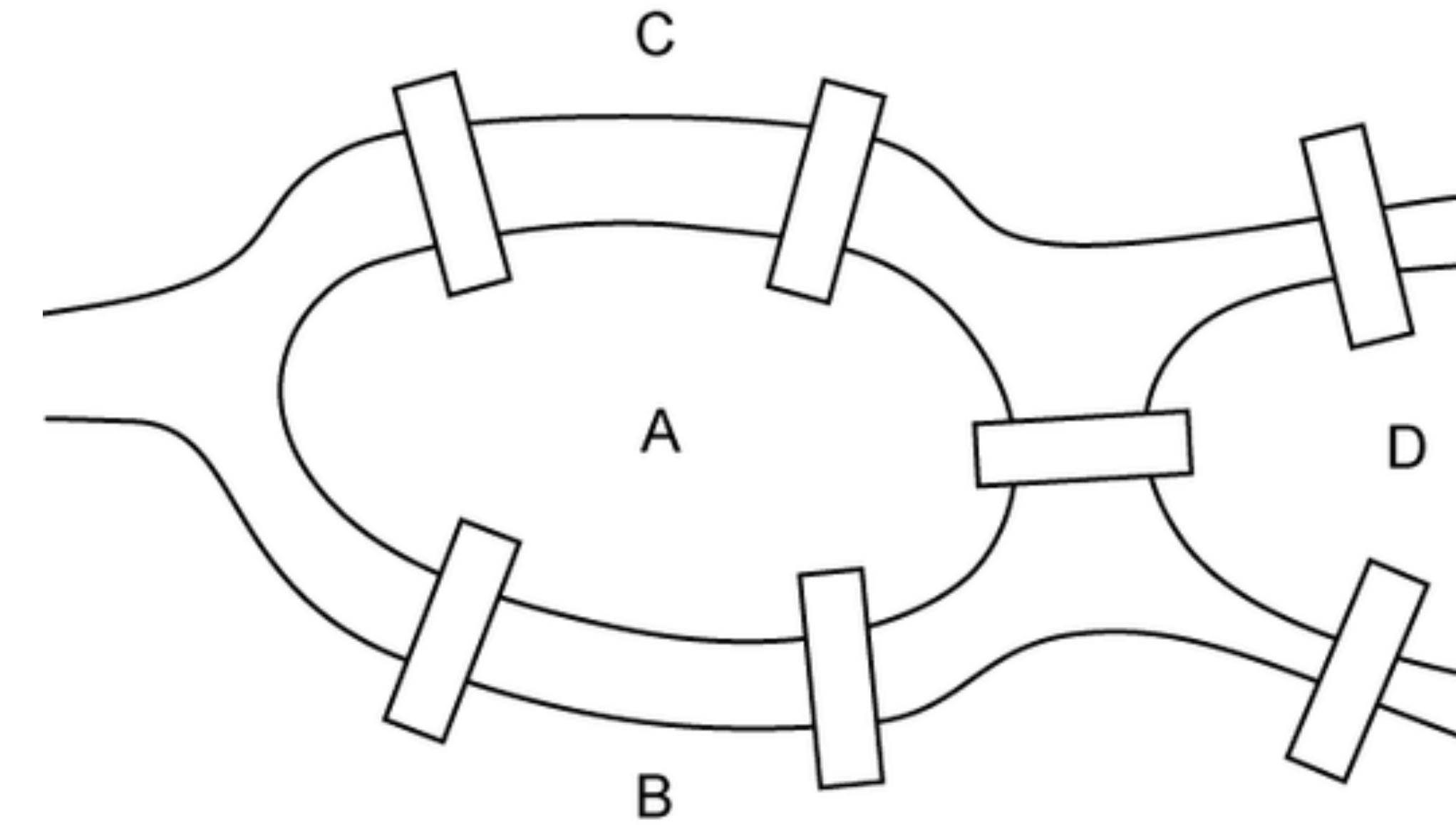
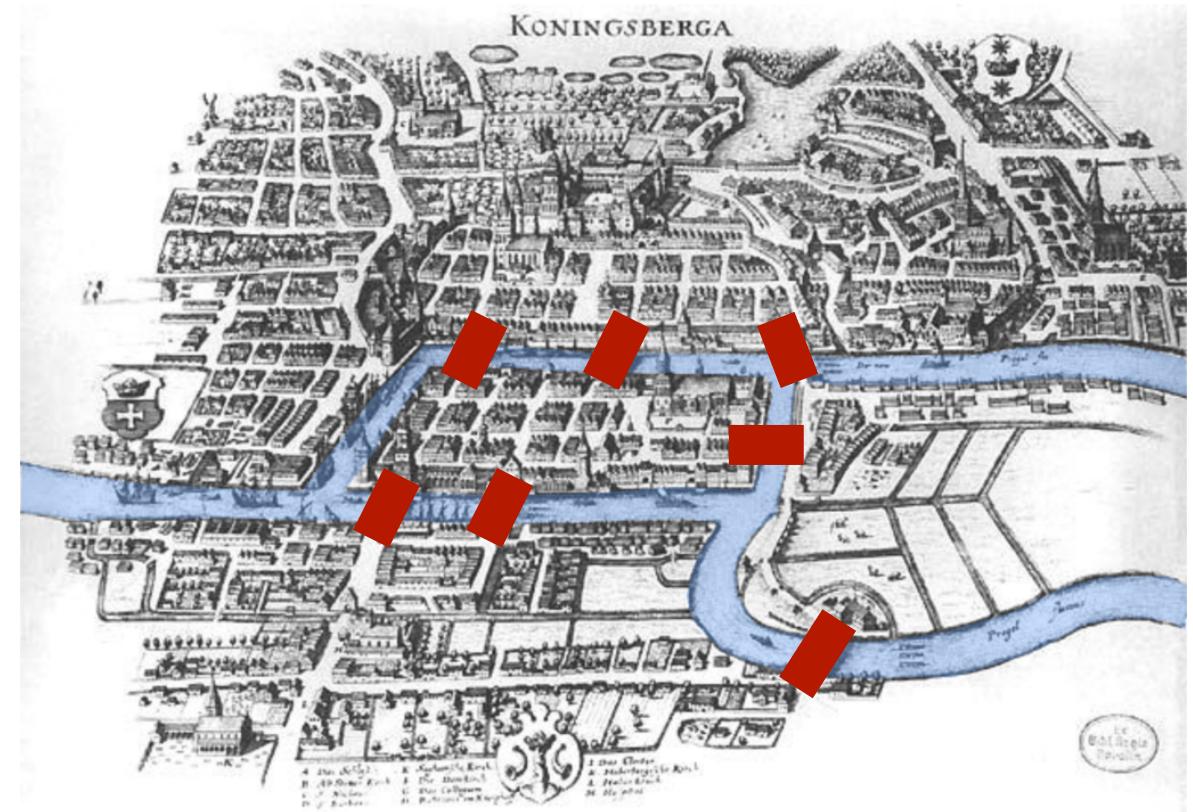
Q: Is it possible to devise a walk through the city that would cross each of those bridges once and only once?

Königsberg bridges



Q: Is it possible to devise a walk through the city that would cross each of those bridges once and only once?

Königsberg bridges



Q: Is it possible to devise a walk through the city that would cross each of those bridges once and only once?

A: No. At most two nodes (start, end) may have odd # of links

The history of Network Analysis

Graph theory: 1735, Euler

The history of Network Analysis

Graph theory: 1735, Euler

Social Network Research: 1930s, Moreno

Communication networks/internet: 1960s

Ecological Networks: 1979, May

The history of Network Analysis

Graph theory: 1735, Euler

Social Network Research: 1930s, Moreno

Communication networks/internet: 1960s

Ecological Networks: 1979, May

Today?

The Emergence of Network Data

The Emergence of Network Data

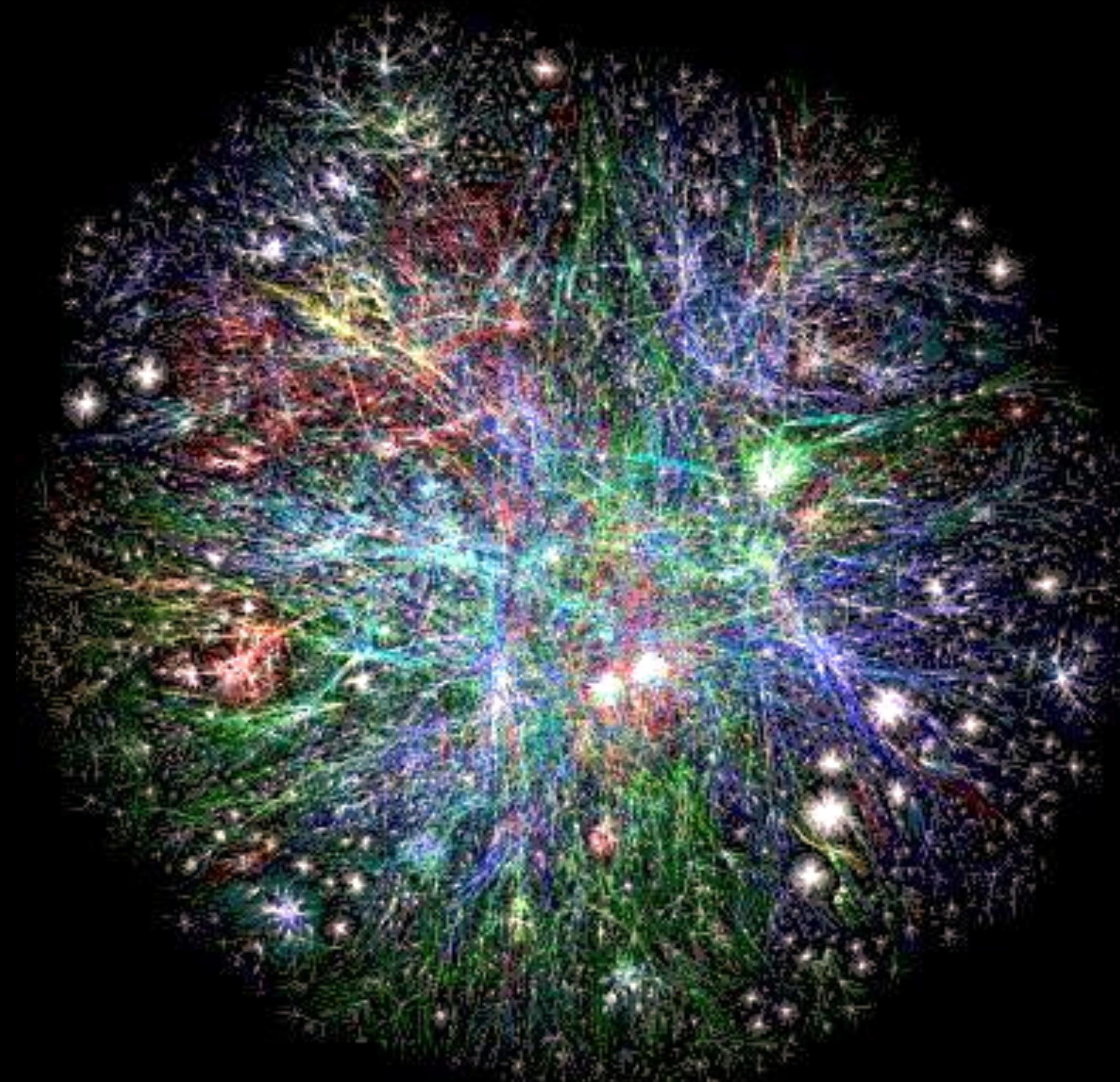


Facebook

The Emergence of Network Data

Brain

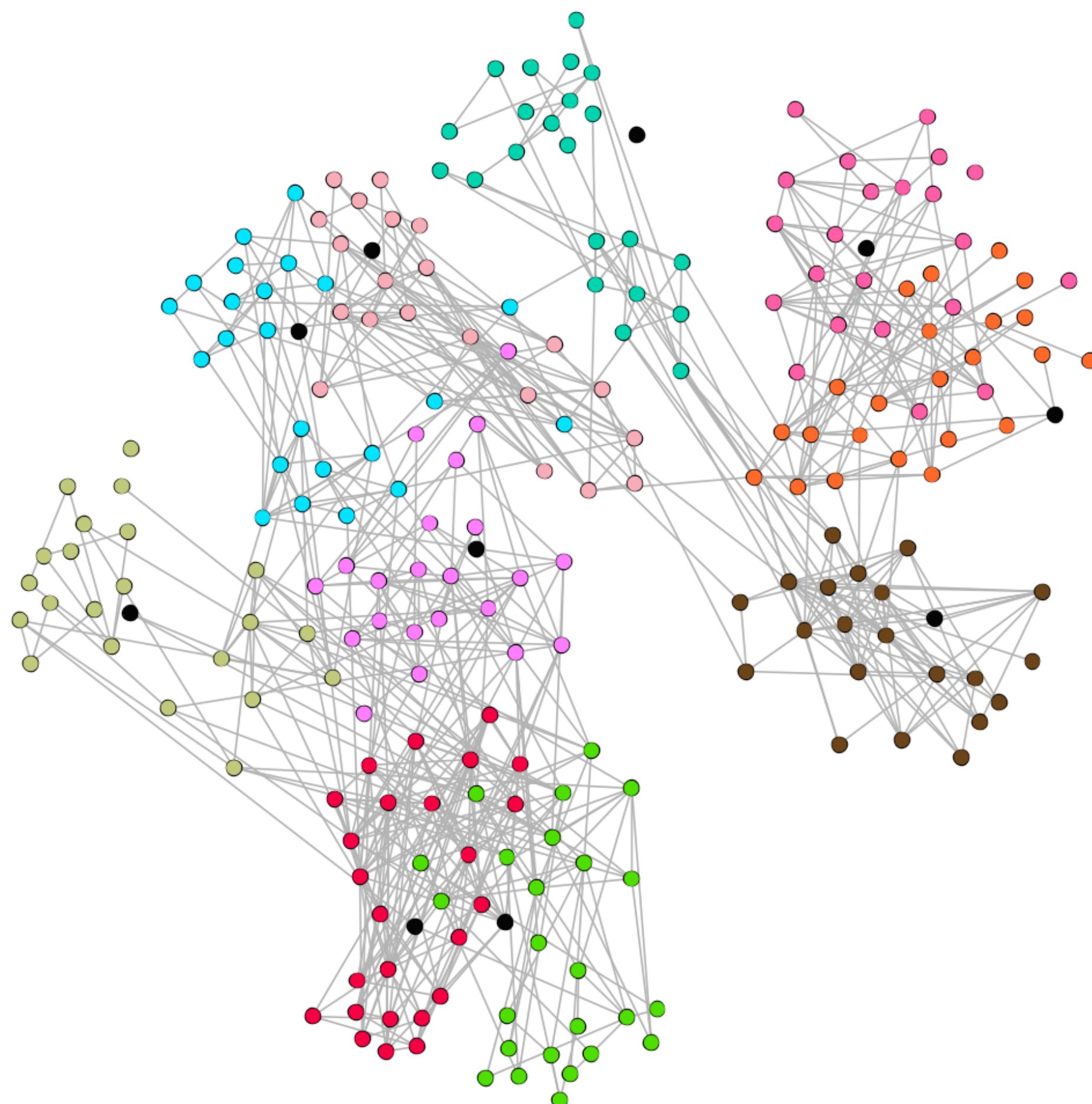
The Emergence of Network Data



www

The emergence of network maps

A network made of kids...



Nodes: Students at a primary school (1 day) + Teachers
Edges: Physical proximity (more than 60 secs)

Legends: color represent the class, teachers are represented as black nodes.

Source: High-Resolution Measurements of Face-to-Face Contact Patterns in a Primary School.

Juliette Stehlé, Nicolas Voirin, Alain Barrat, Ciro Cattuto, Lorenzo Isella, Jean-François Pinton, Marco Quaggiotto, Wouter Van den Broeck, Corinne Régis, Bruno Lina and Philippe Vanhems. PLOS ONE 6(8): e23176 (2011). doi:10.1371/journal.pone.0023176

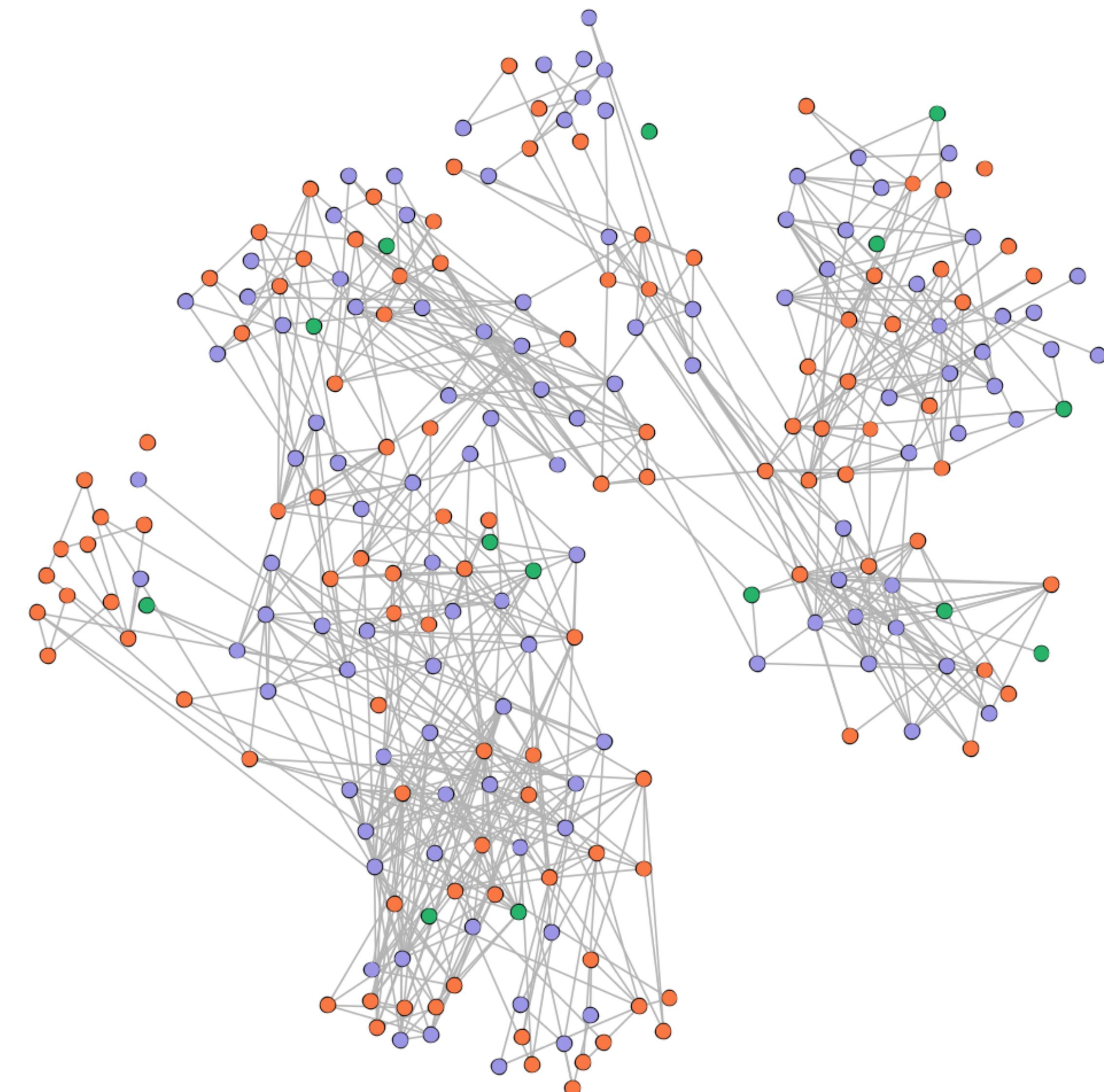
The emergence of network maps

What could we ask?

Nodes: Students at a primary school (1 day) + Teachers

Edges: Physical proximity (more than 60 secs)

Legends: color represent the gender (green = unknown)

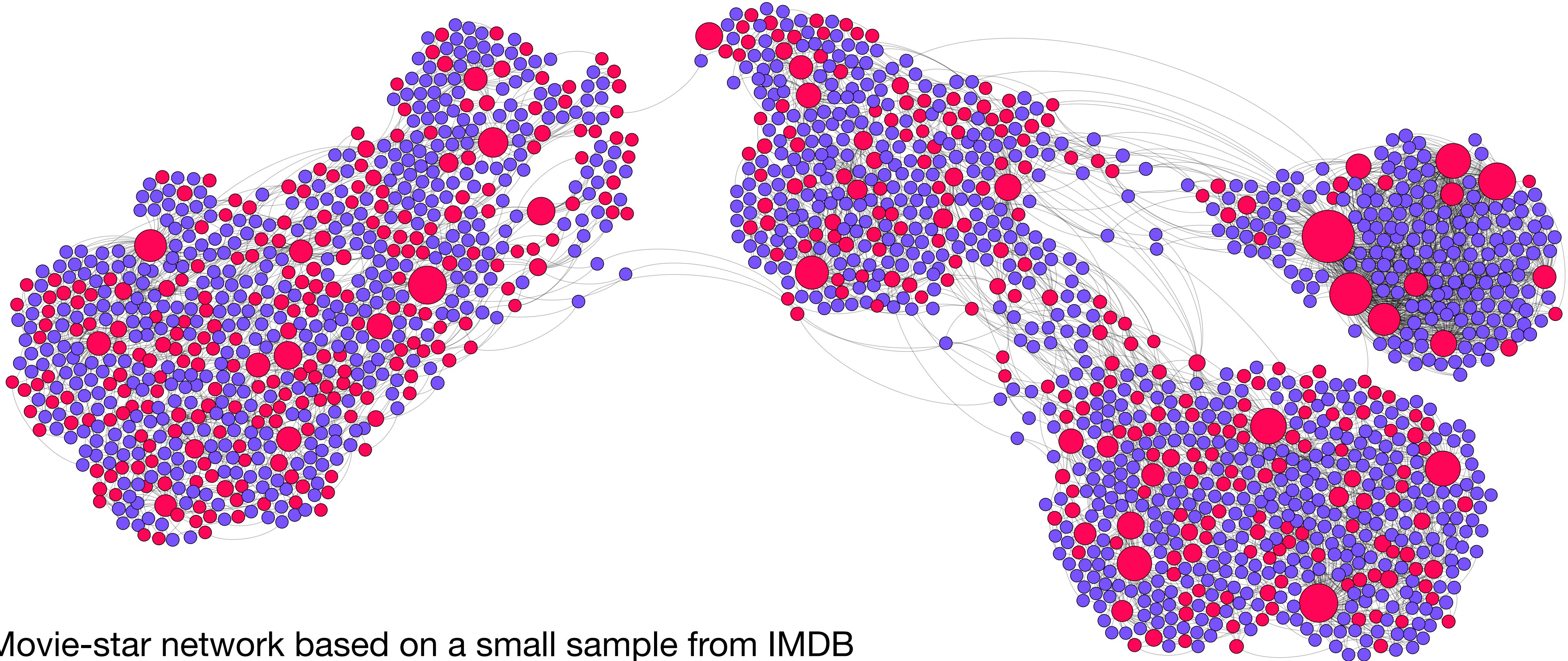


Source: High-Resolution Measurements of Face-to-Face Contact Patterns in a Primary School.

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doi:10.1371/journal.pone.0023176

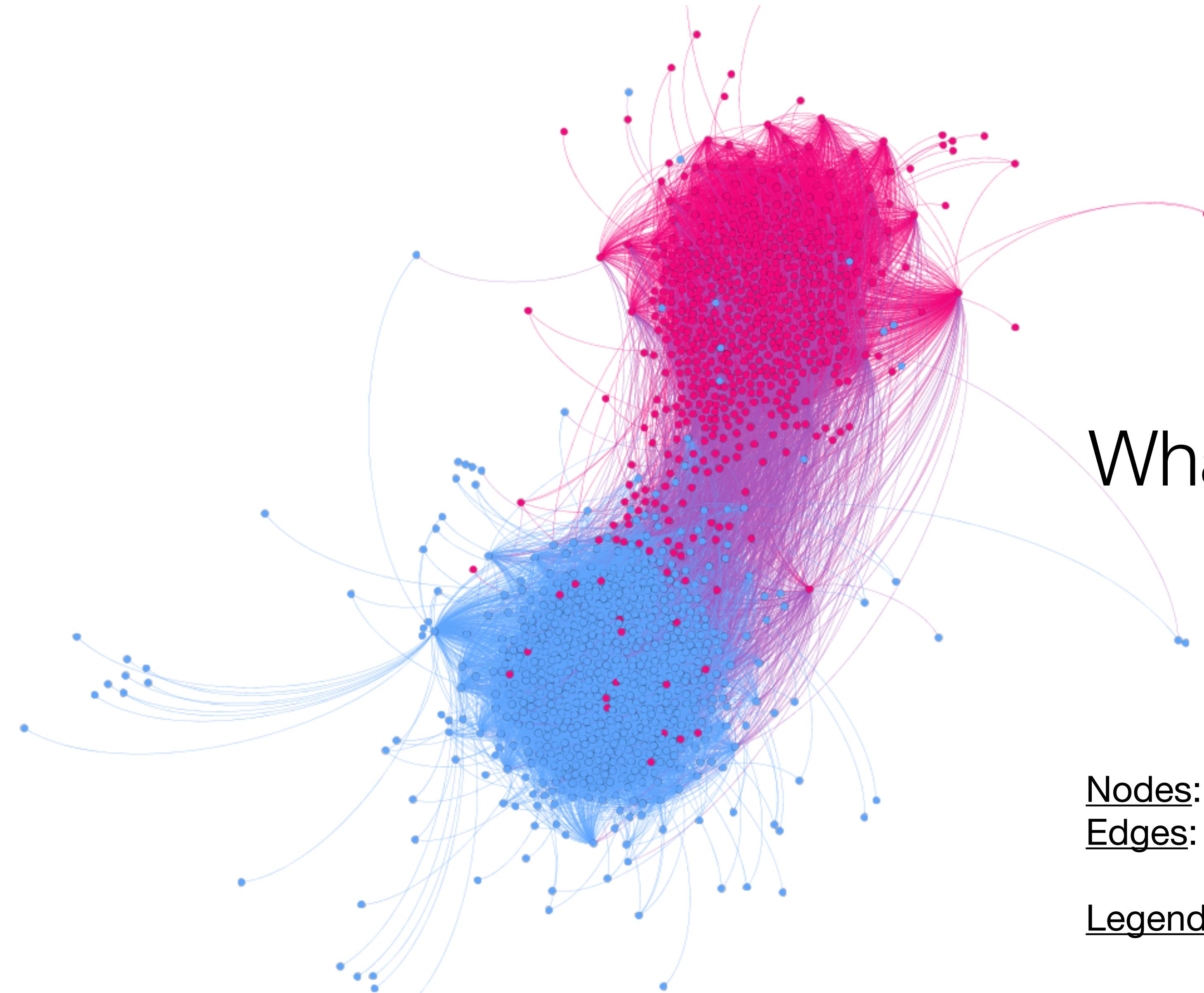
Give me a network!



Movie-star network based on a small sample from IMDB
Blue nodes represent movies
Red nodes represent actors

What's the difference?
What could we ask?

More networks



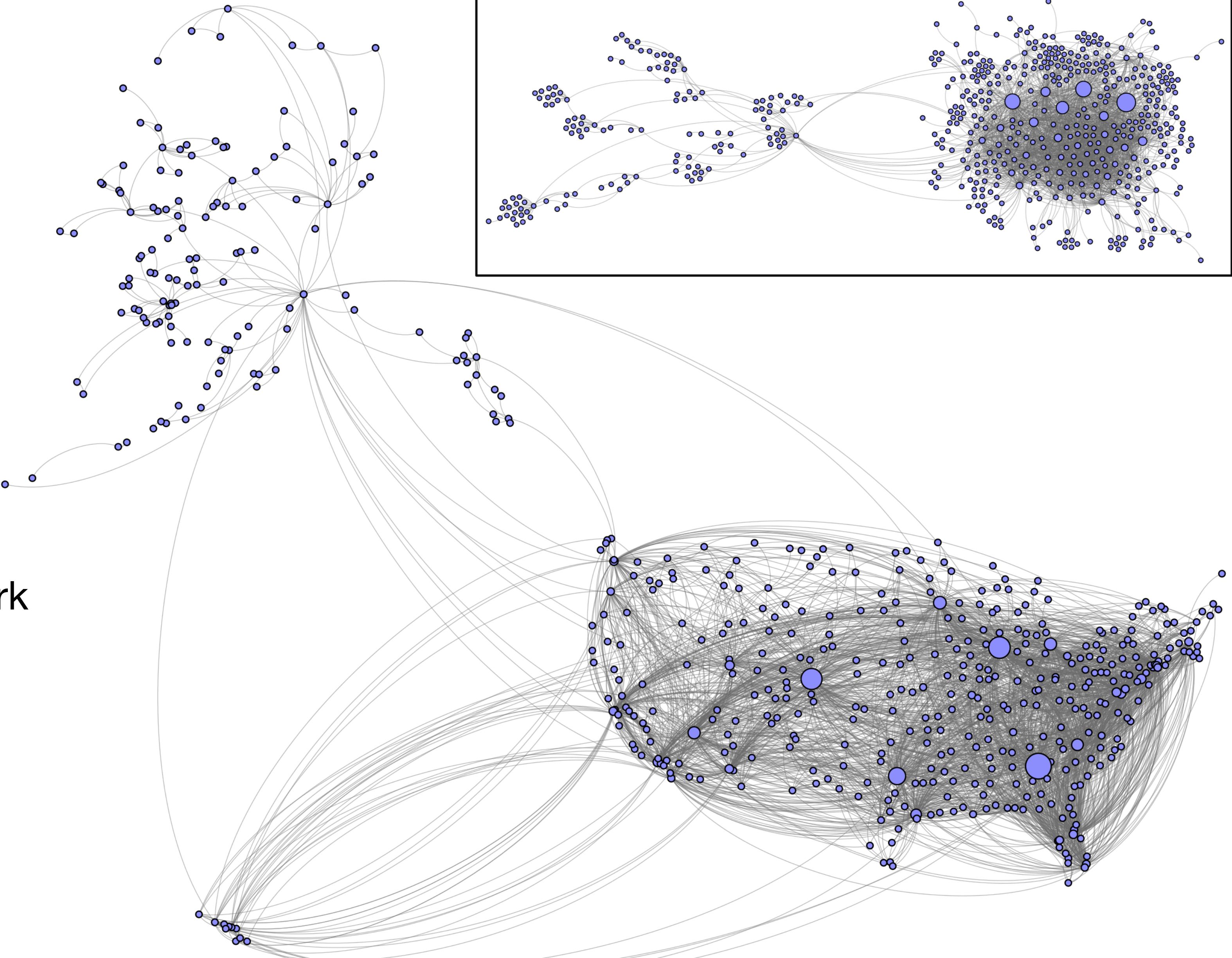
What could we ask?

Nodes: Political Blogs (US 2004)
Edges: Co-link

Legends: color represent the political leaning (Rep / Dem)

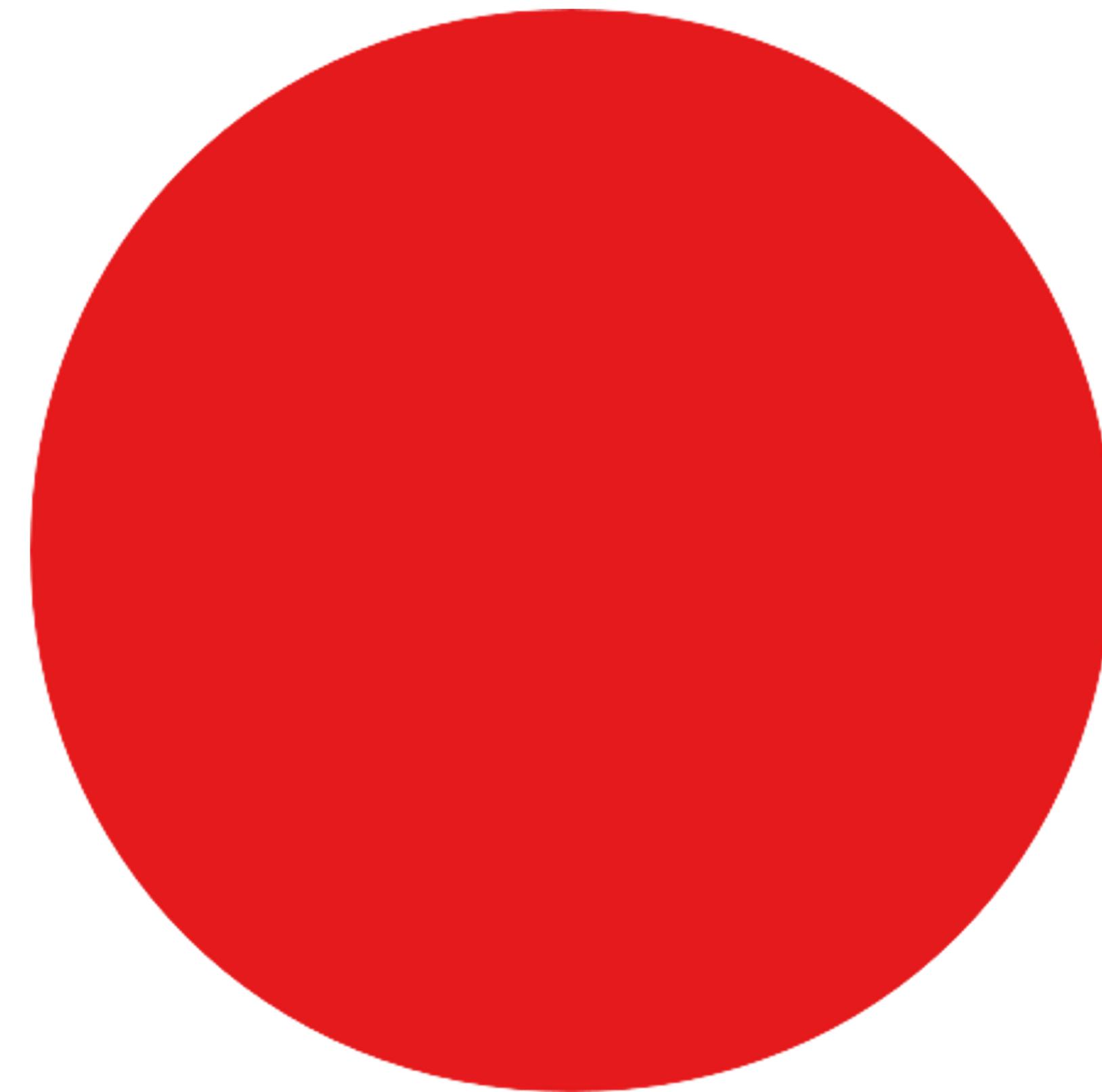
More networks

US air transportation network
What do nodes represent?
What do links represent?
What can we ask?



Definitions

Node



Vertex

Actor

Entity

Notation

G = graph

V = set of vertices

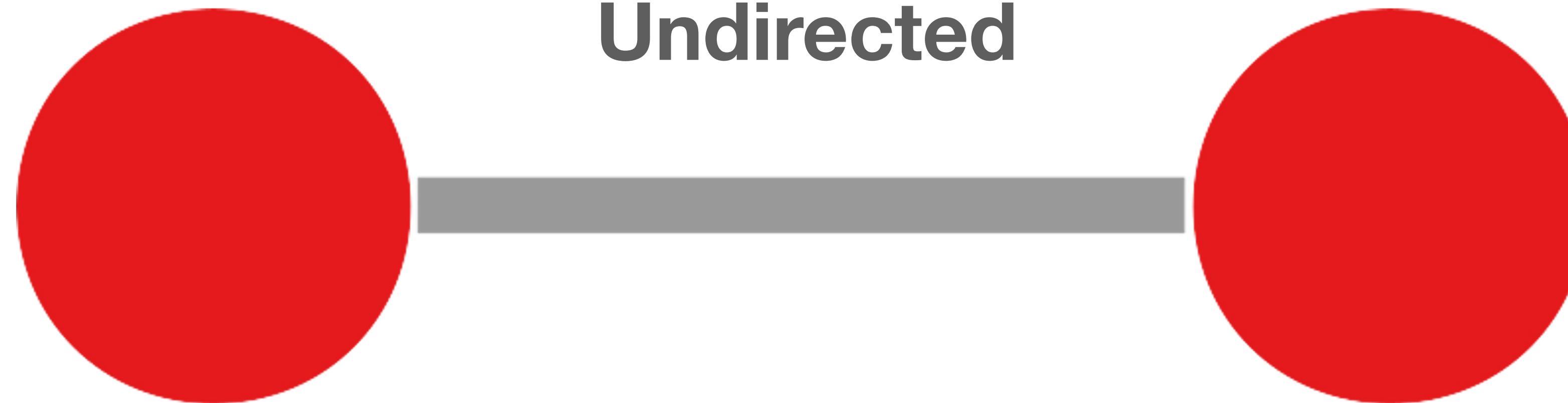
v, u = single vertices

N or $|V|$ = number of vertices

Definitions

Edge

Link



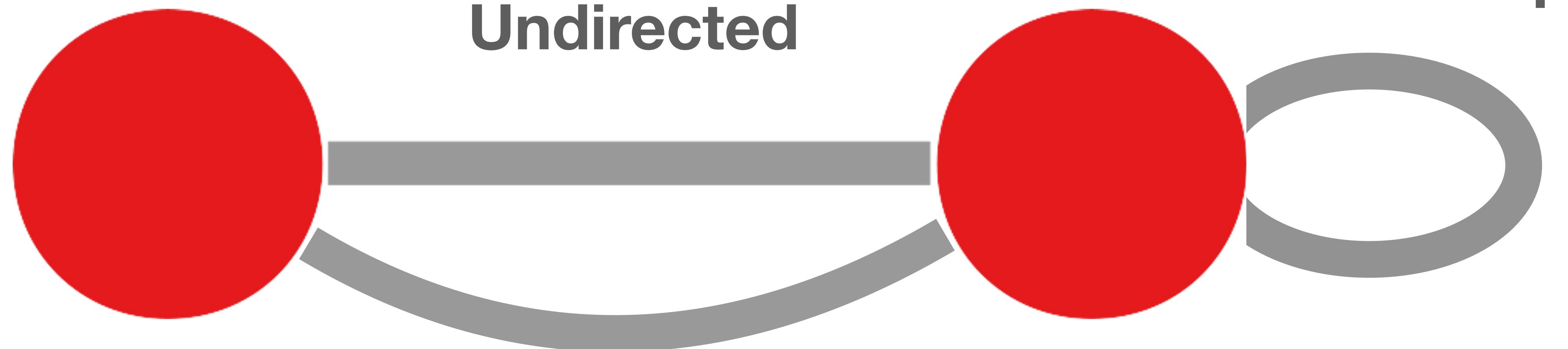
Connection

Arc

Definitions

Edge

Link



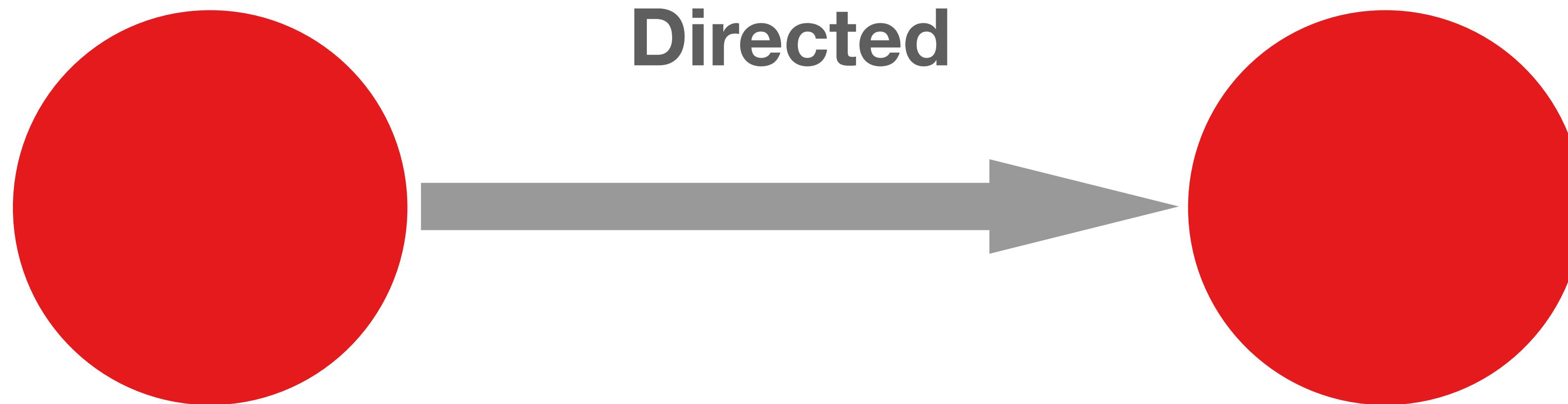
Connection

Arc

Definitions

Edge

Link



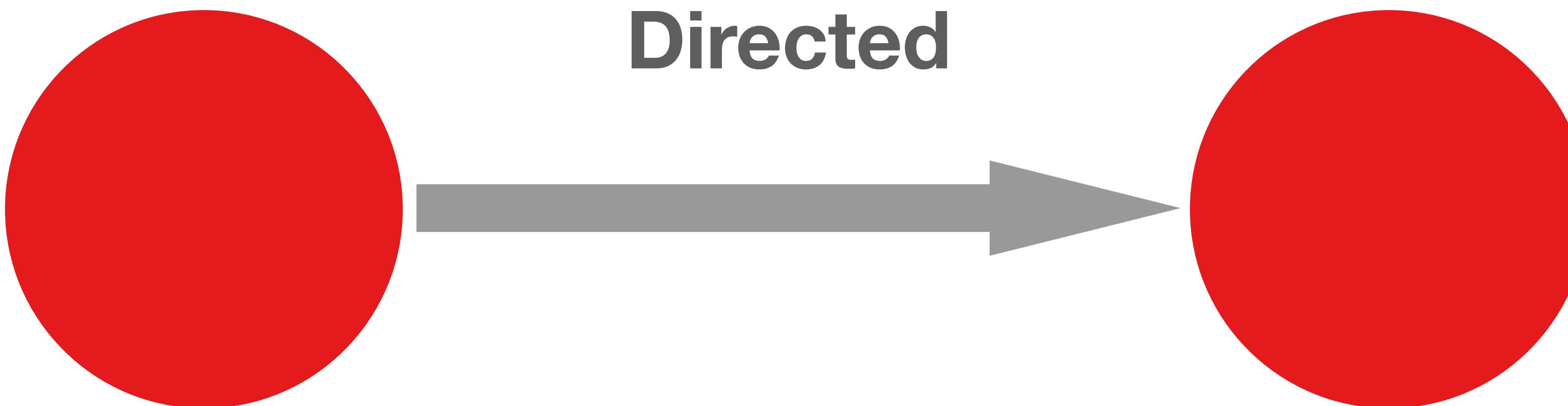
Connection

Arc

Definitions

Edge

Link



Complicating everything since 1735!
Only use if needed!

Connection

Arc

Notation

E = set of edges

(u, v) = single edge: a pair of vertices

L or $(|E|)$ = number of edges

So: $G = (V, E)$

A **Graph** is a set of nodes and a set of edges

Digraph if edges are directed

Network Graph

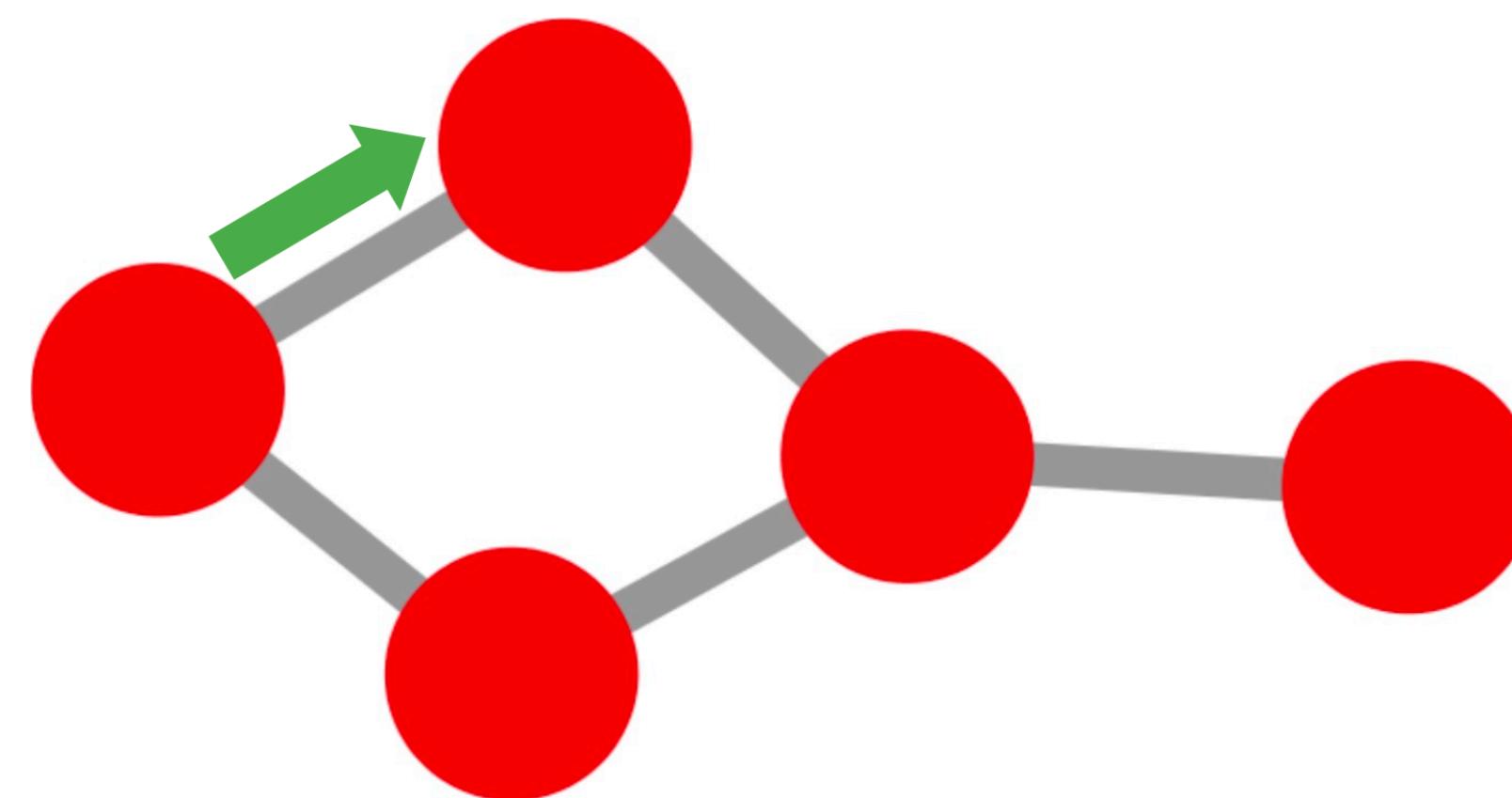
Node
Link

Vertex
Edge

I will mostly use i, j to
refer to nodes

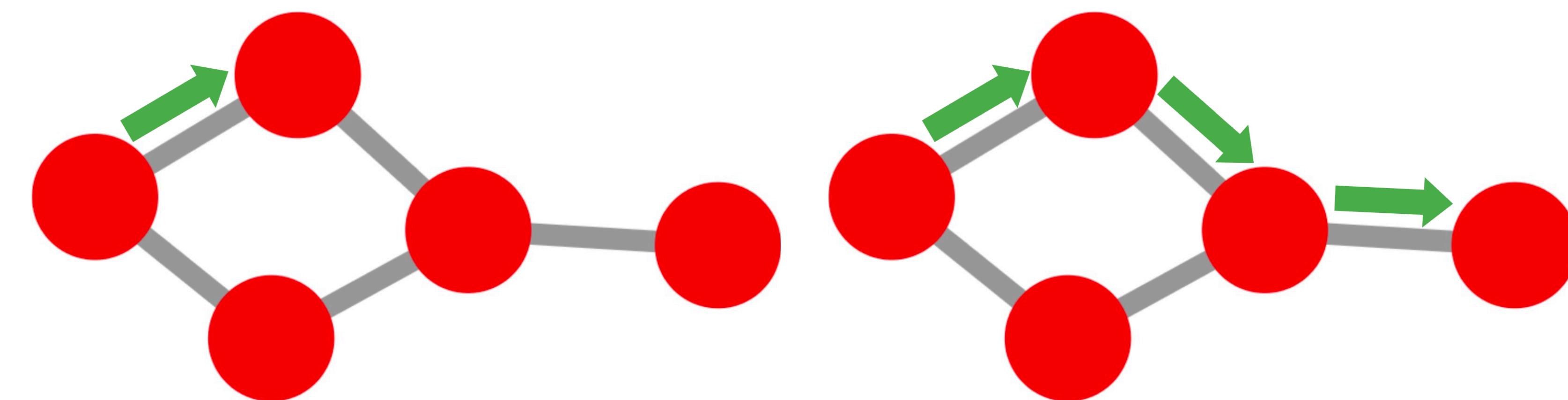
Definitions

Path: (walk, trail, ...)



Definitions

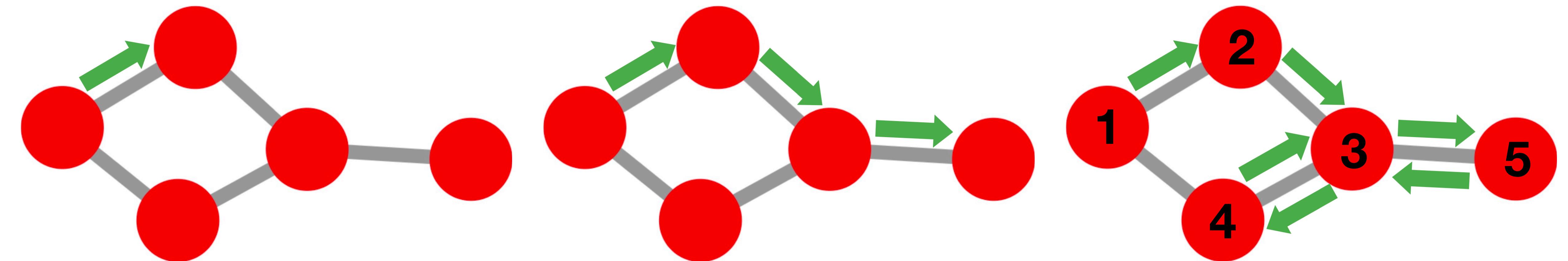
Path: (walk, trail, ...)



Definitions

How many edges visited? Path length 6

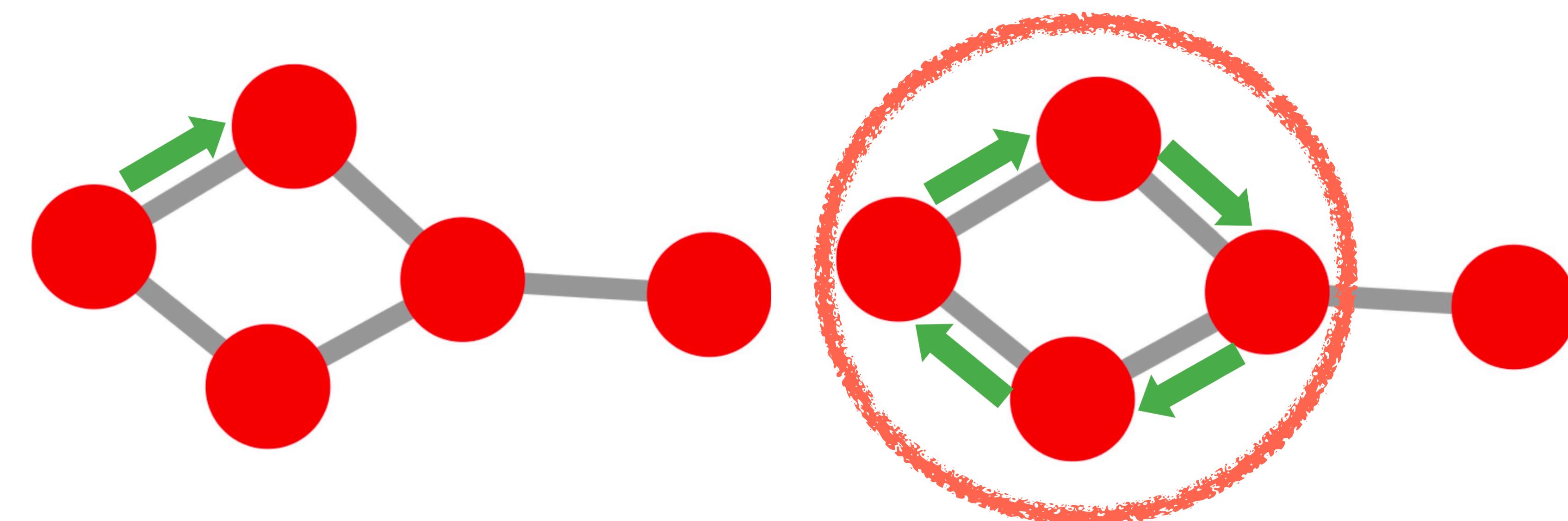
Shortest path from 1 to 5? 3 edges
 $\{(1,2),(2,3),(3,4)\}$



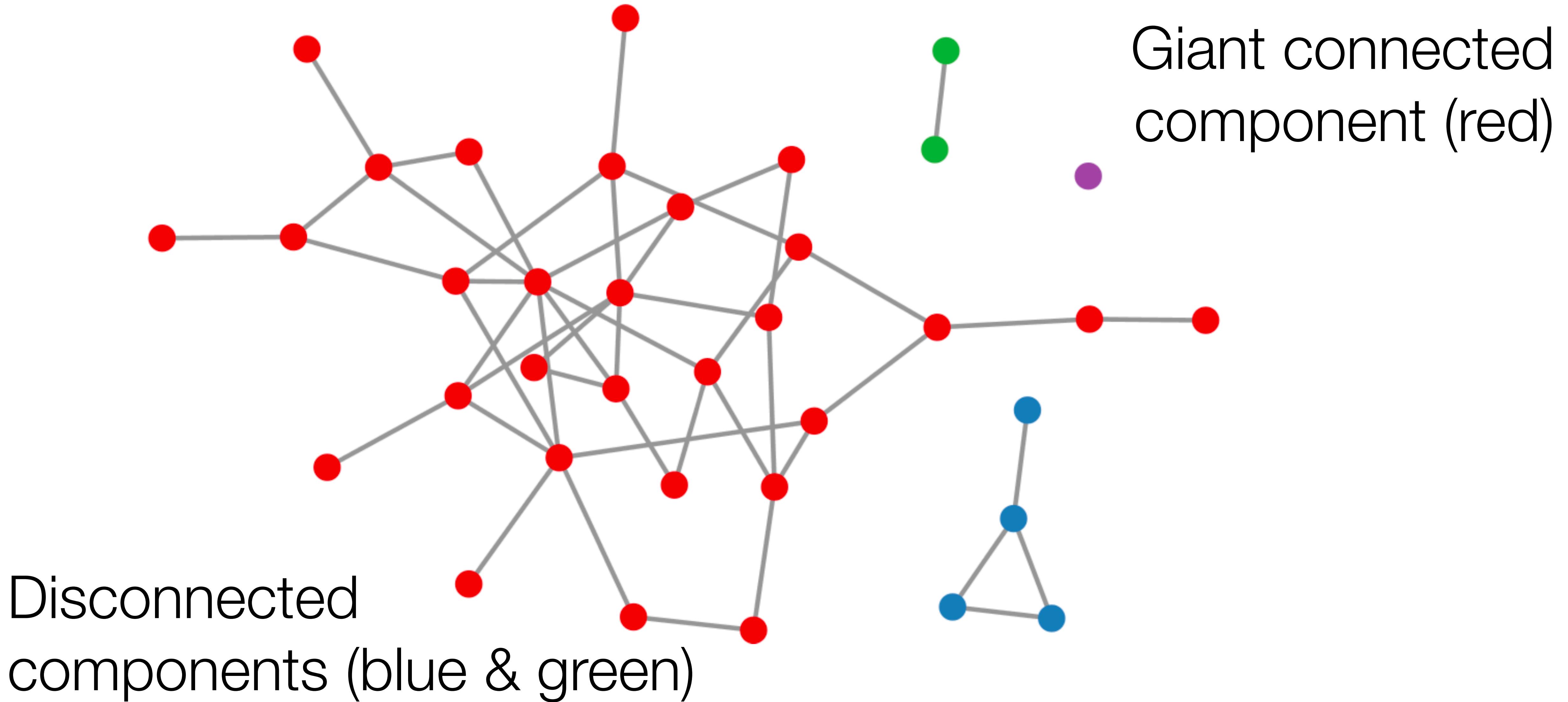
Other definitions with different constraints: Eulerian Path, Hamiltonian Path

Definitions

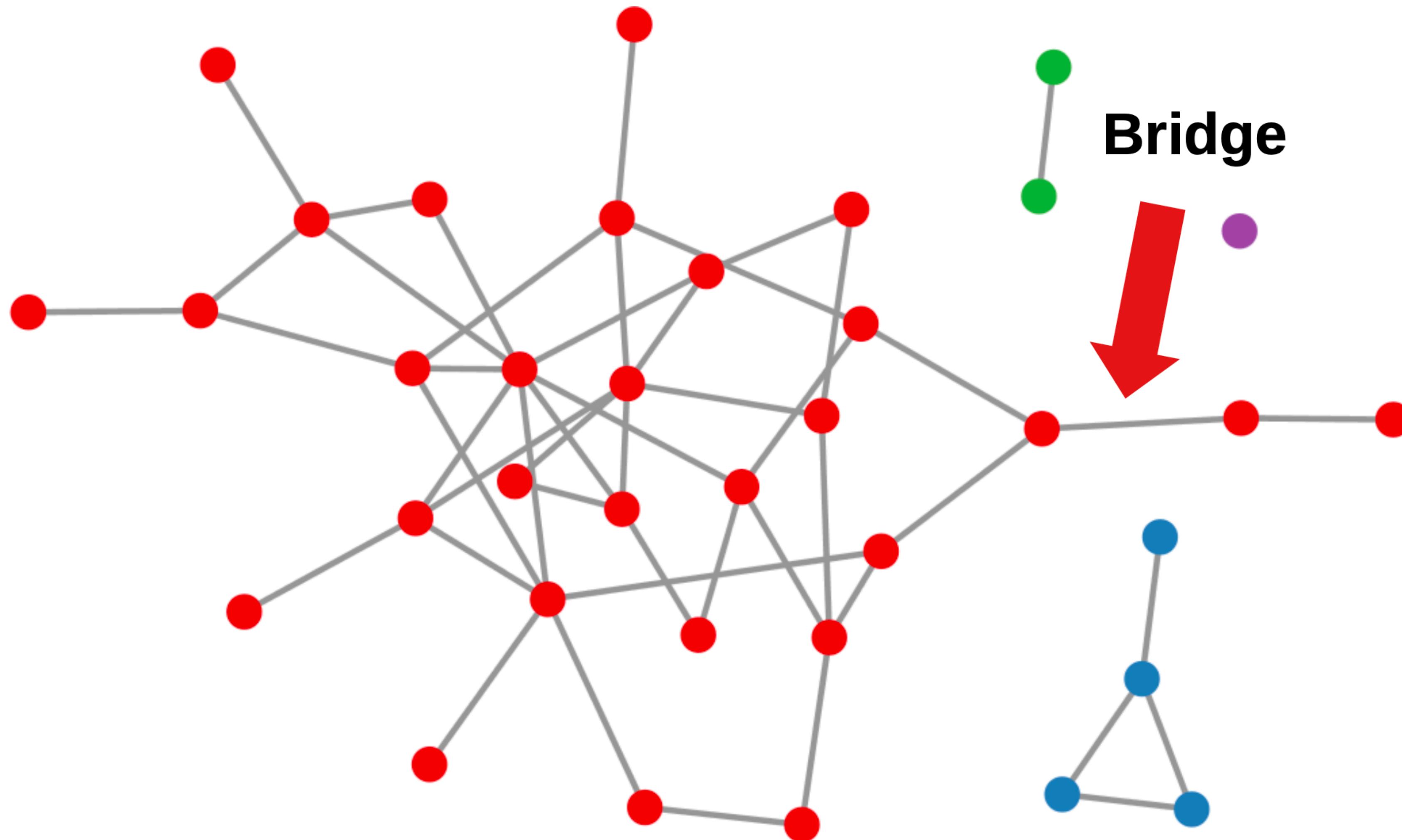
Cycle: (Special path!)



Definitions



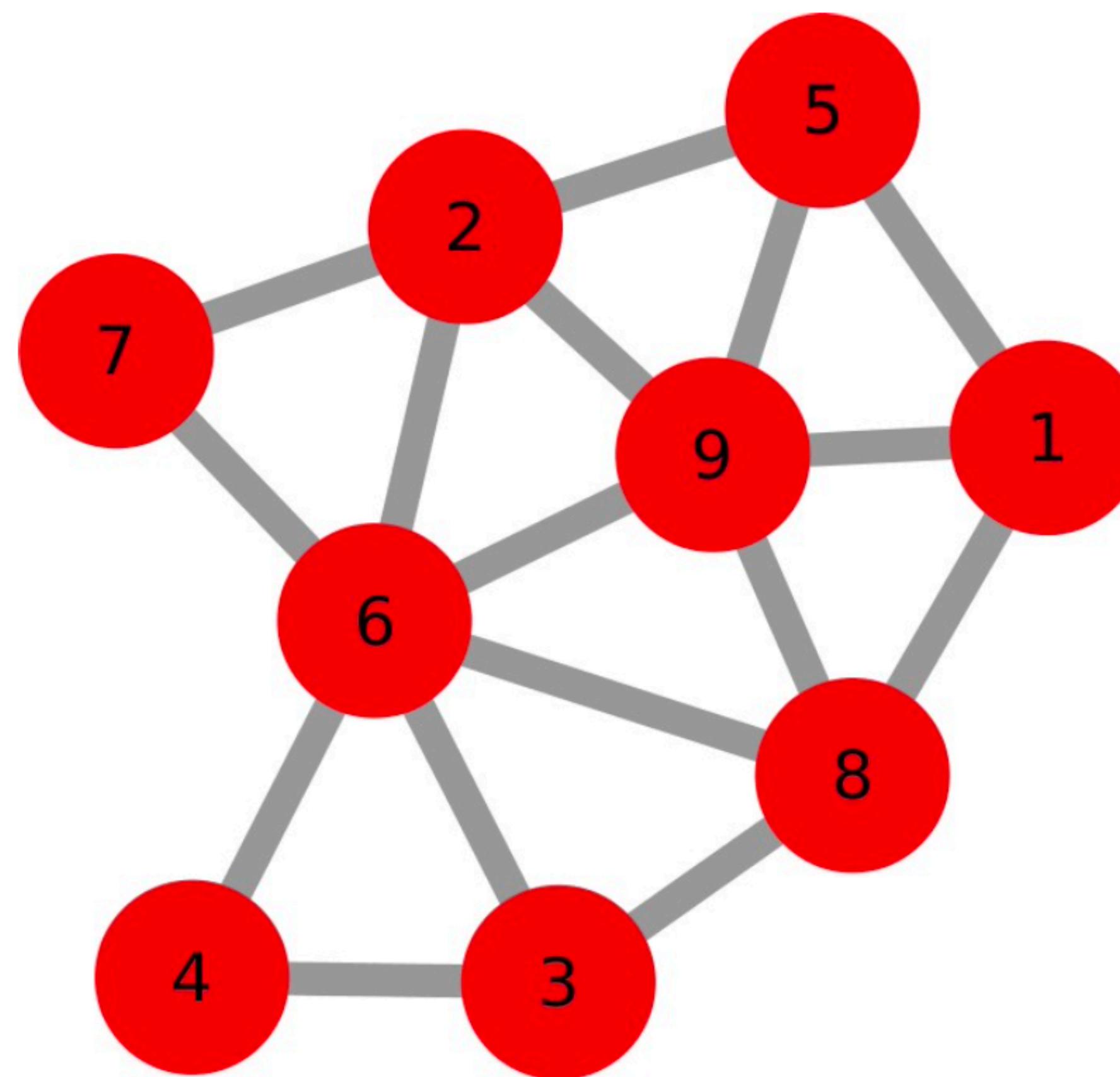
Definitions



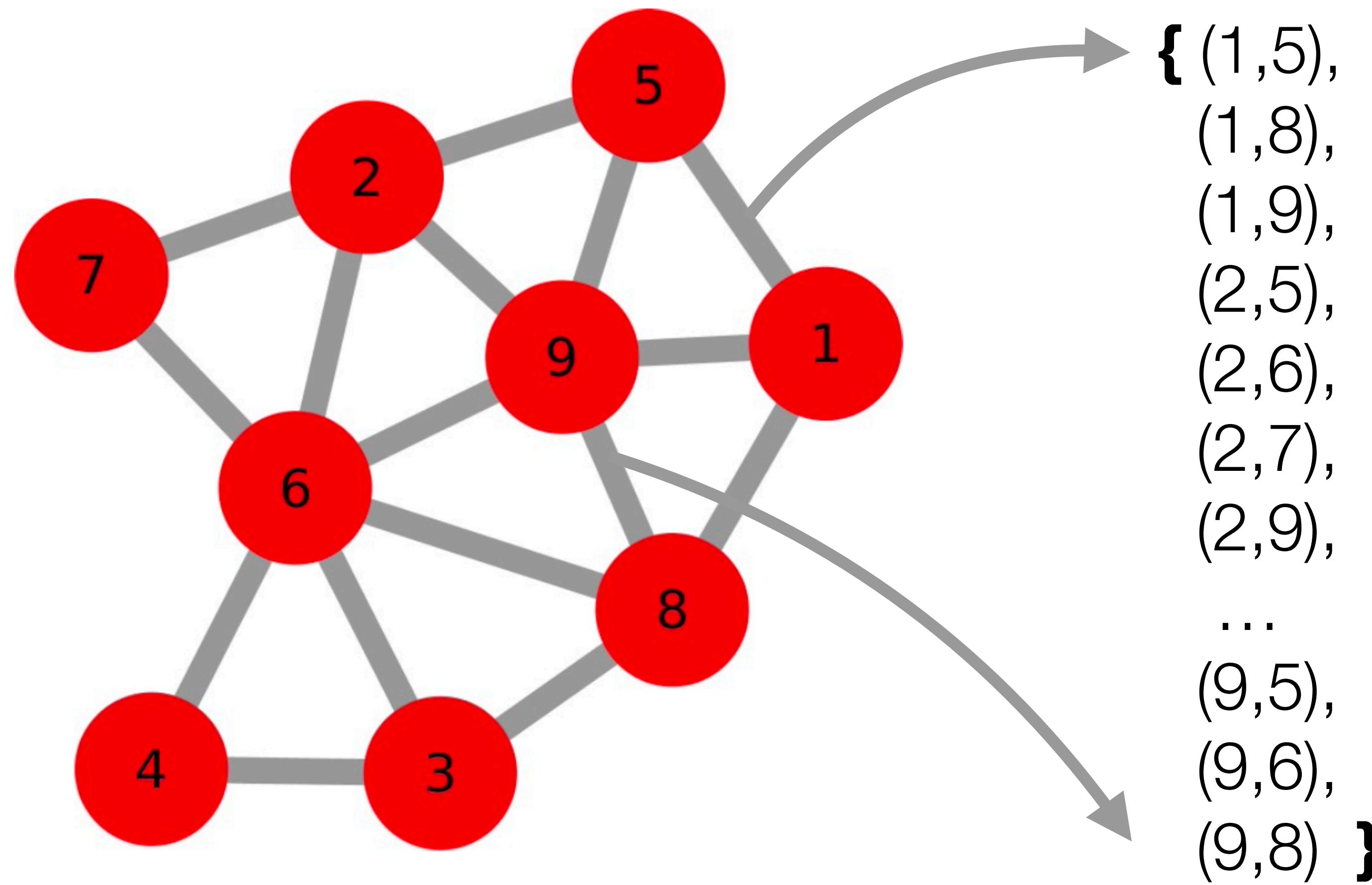


Break?

Network representation

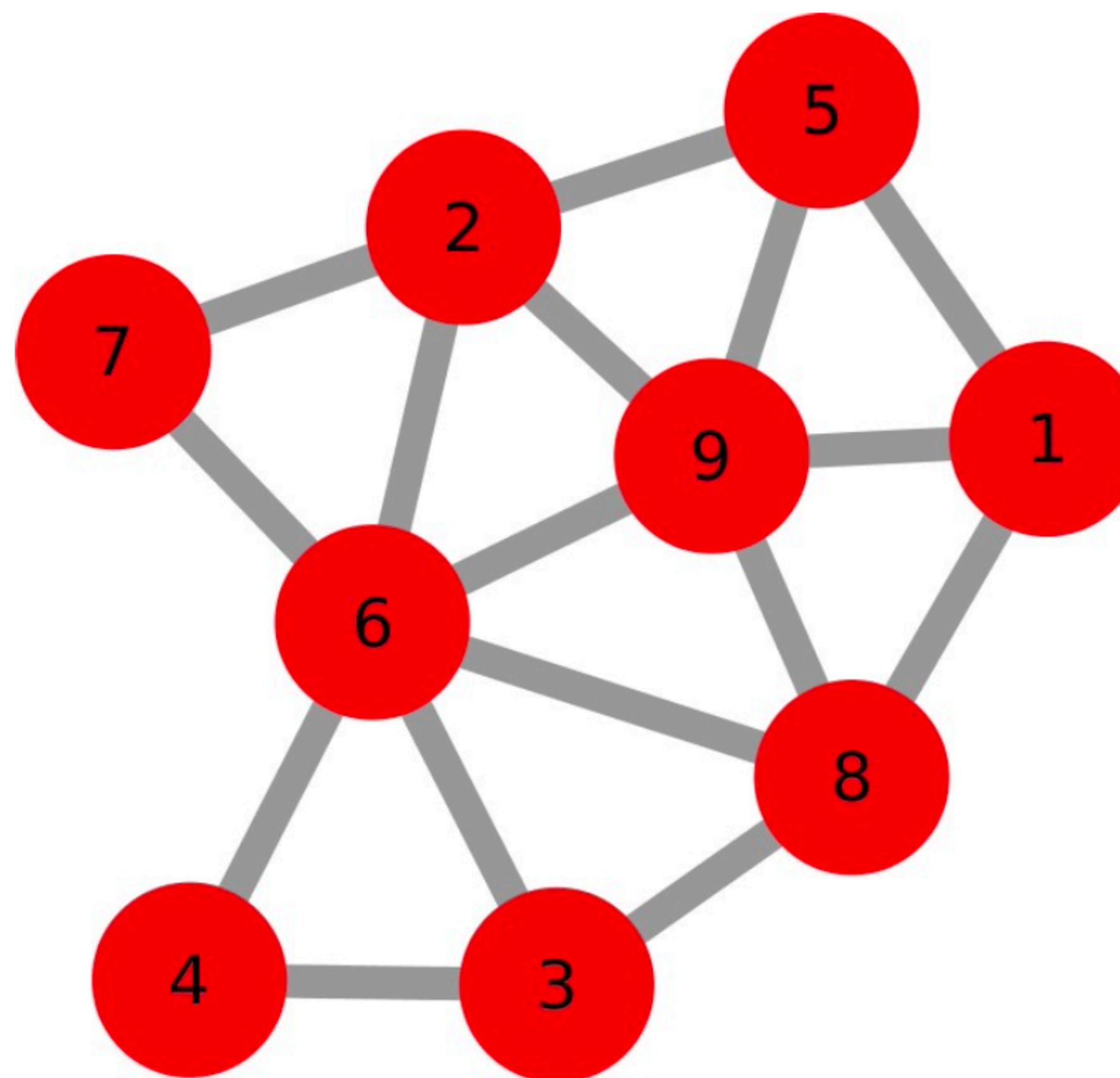


Network representation



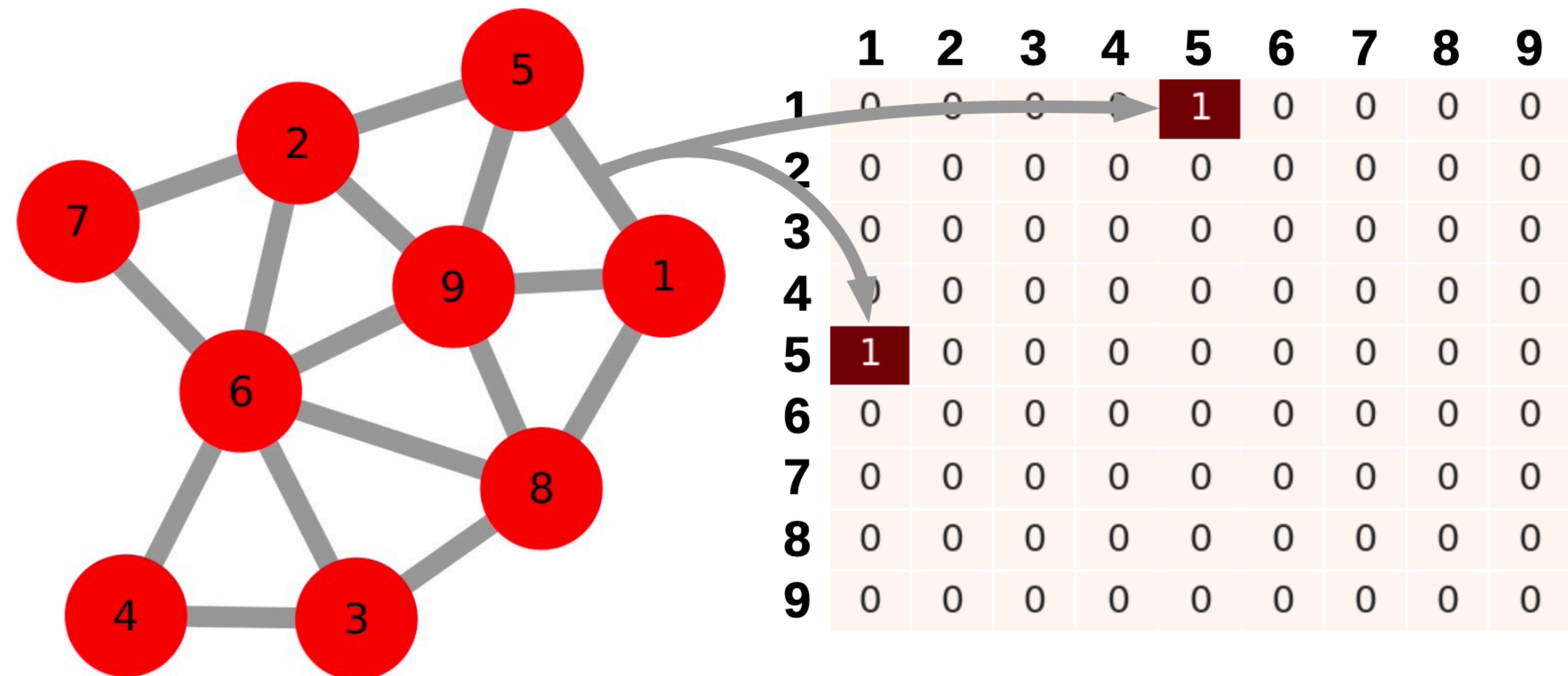
Edge list
(undirected)
pairs (i,j)

Network representation



0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0

Network representation



Undirected adjacency matrix \mathbf{A}

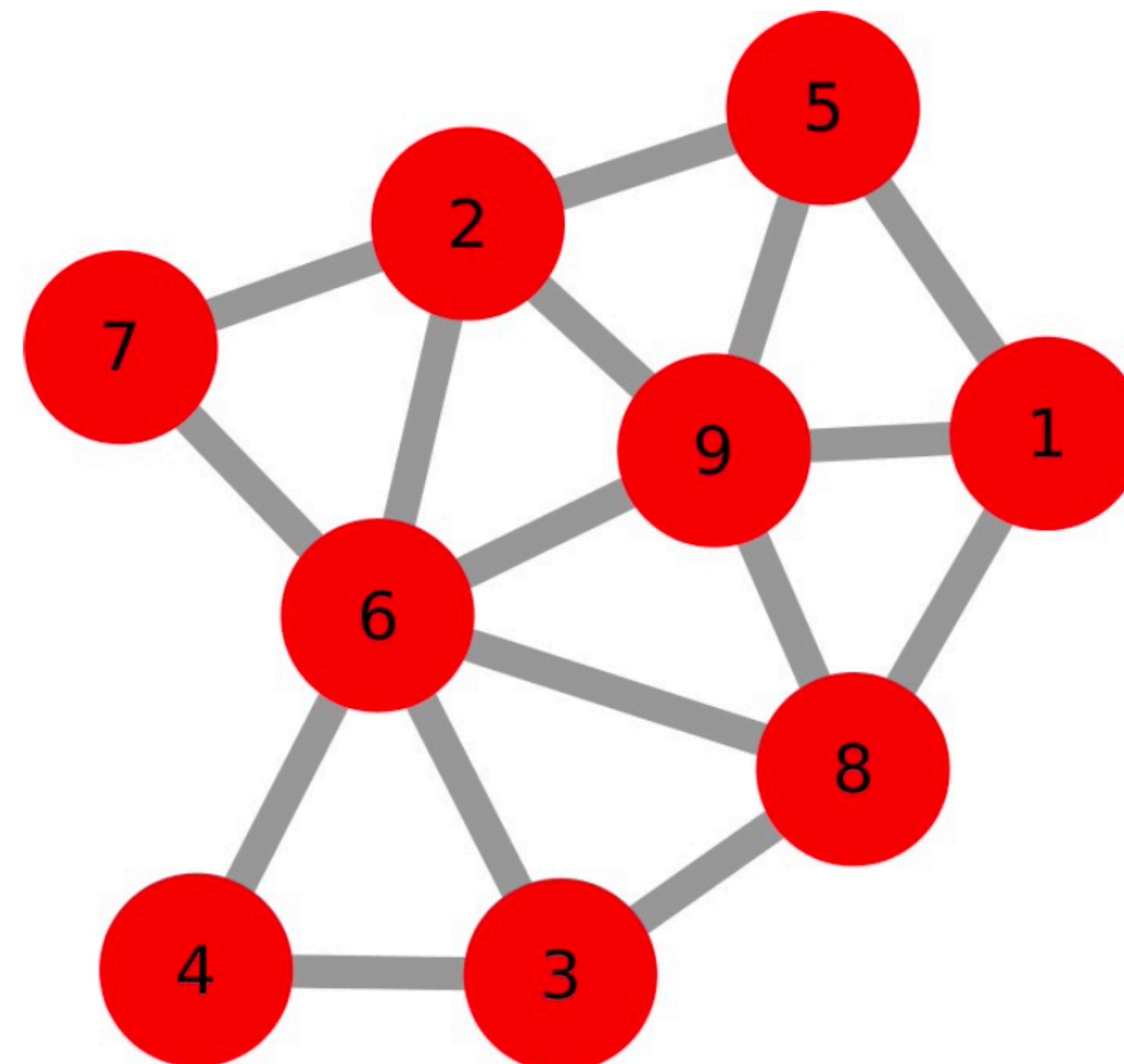
$A_{ij}, A_{ji} = 1$
if (5,1) are
connected

0

otherwise

Network representation

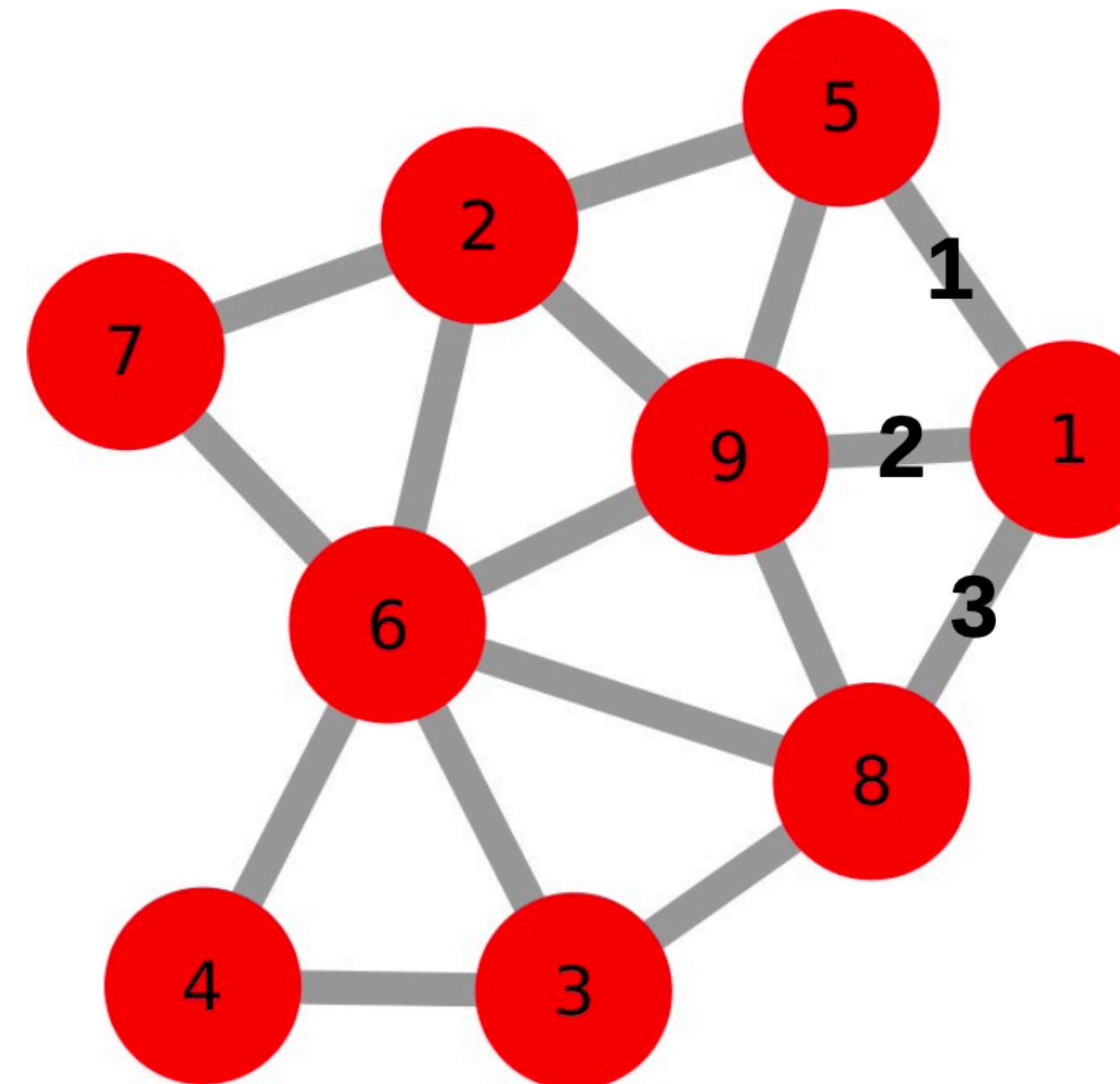
A is symmetric & has diagonal = 0



1	2	3	4	5	6	7	8	9
1	0	0	0	0	1	0	0	1
2	0	0	0	0	1	1	1	0
3	0	0	0	1	0	1	0	1
4	0	0	1	0	0	1	0	0
5	1	1	0	0	0	0	0	1
6	0	1	1	1	0	0	1	1
7	0	1	0	0	0	1	0	0
8	1	0	1	0	0	1	0	1
9	1	1	0	0	1	1	0	0

Undirected adjacency matrix A

Network representation

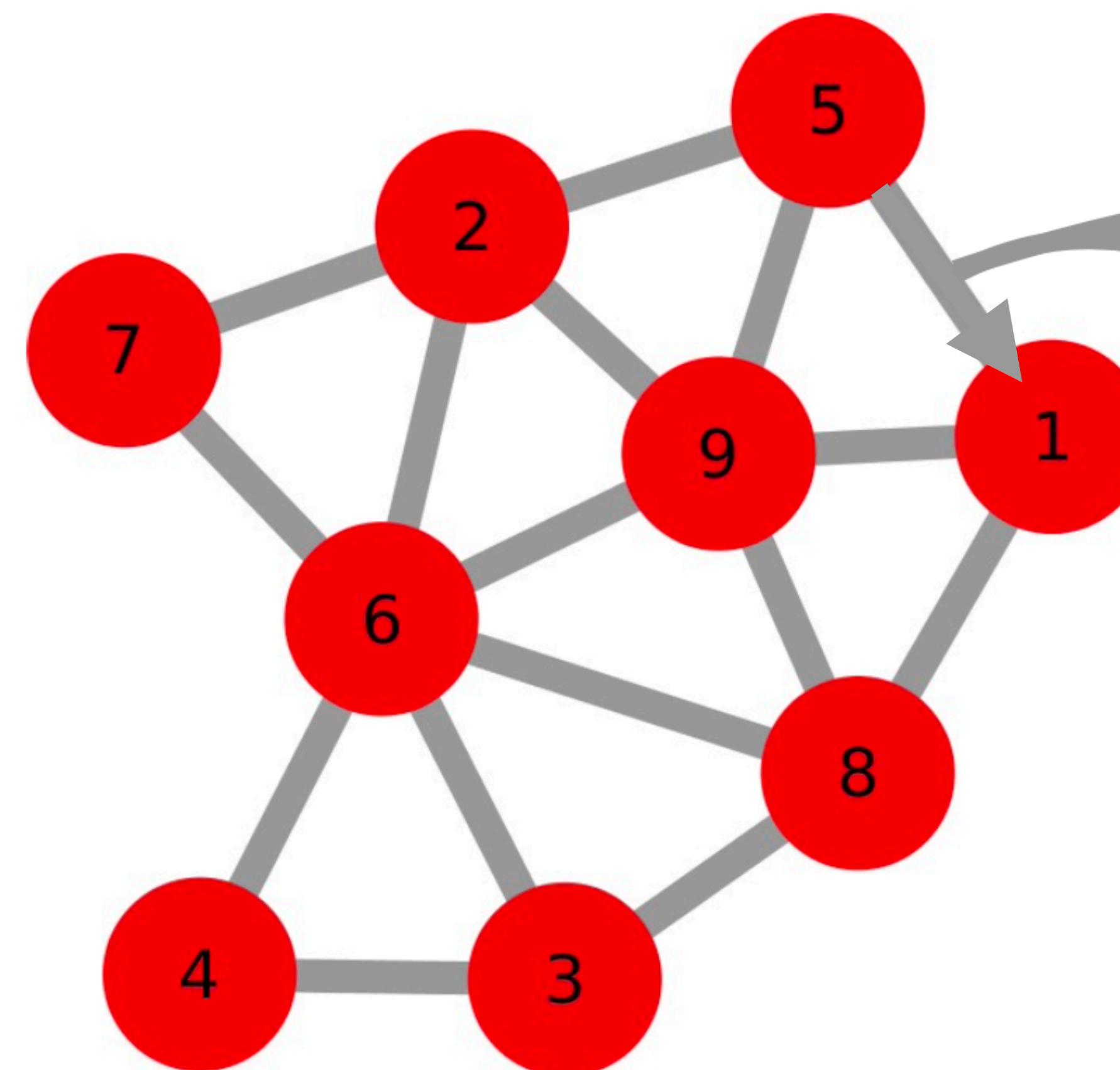


A is squared: $N \times N$

Links of node i									
0	0	0	0	1	0	0	1	1	3
0	0	0	0	1	1	1	0	1	
0	0	0	1	0	1	0	1	0	
0	0	1	0	0	1	0	0	0	
1	1	0	0	0	0	0	0	1	
0	1	1	1	0	0	0	1	1	
0	1	0	0	0	0	1	0	0	
1	0	1	0	0	0	1	0	1	
1	1	0	0	1	1	0	1	0	

Undirected adjacency matrix A

Network representation



1	2	3	4	5	6	7	8	9
1	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0
5	1	0	0	0	0	0	0	0
6	0	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0
8	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0

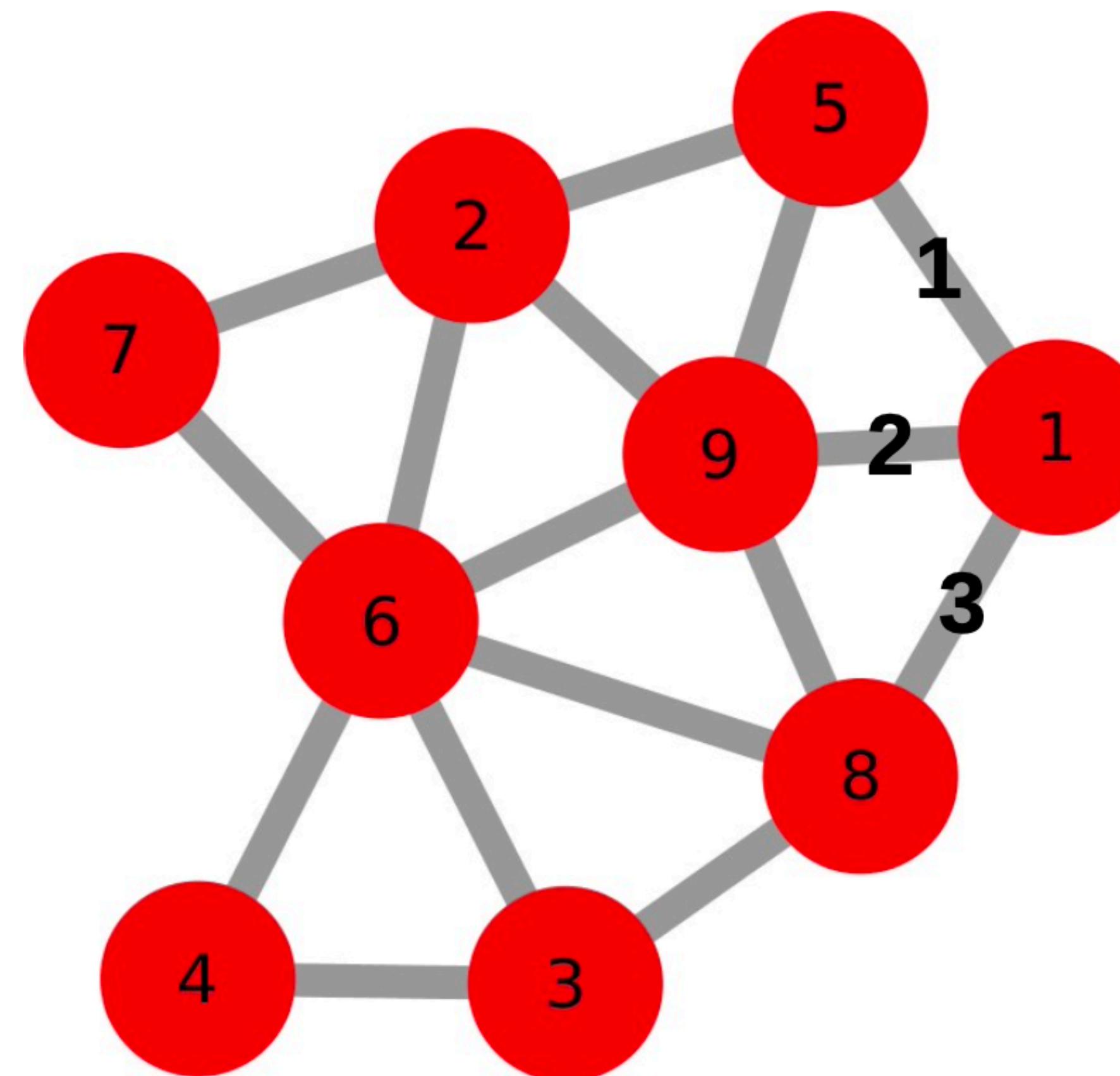
$A_{51} = 1$
there's a
link from
5 to 1

$A_{15} = 0$
no link
from 1 to 5

Directed adjacency matrix \mathbf{A}

Network representation

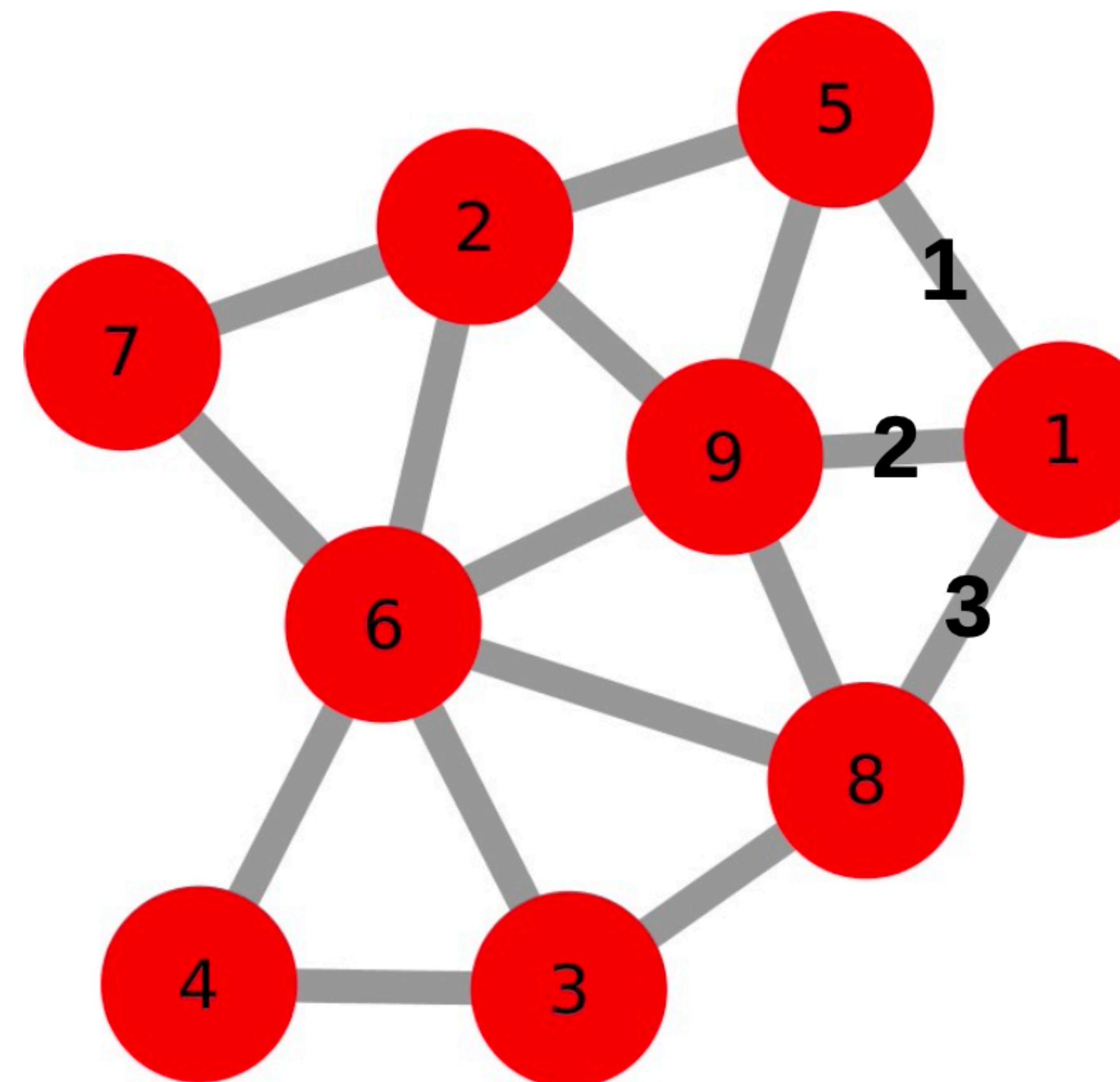
Adding weights



0	0	0	0	0.33	0	0	0.33	0.33
0	0	0	0	0.25	0.25	0.25	0	0.25
0	0	0	0.33	0	0.33	0	0.33	0
0	0	0.5	0	0	0.5	0	0	0
0.33	0.33	0	0	0	0	0	0	0.33
0	0.17	0.17	0.17	0	0	0.17	0.17	0.17
0	0.5	0	0	0	0.5	0	0	0
0.25	0	0.25	0	0	0.25	0	0	0.25
0.2	0.2	0	0	0.2	0.2	0	0.2	0

Network representation

If you normalise the A_i entries to 1,
they become probabilities.



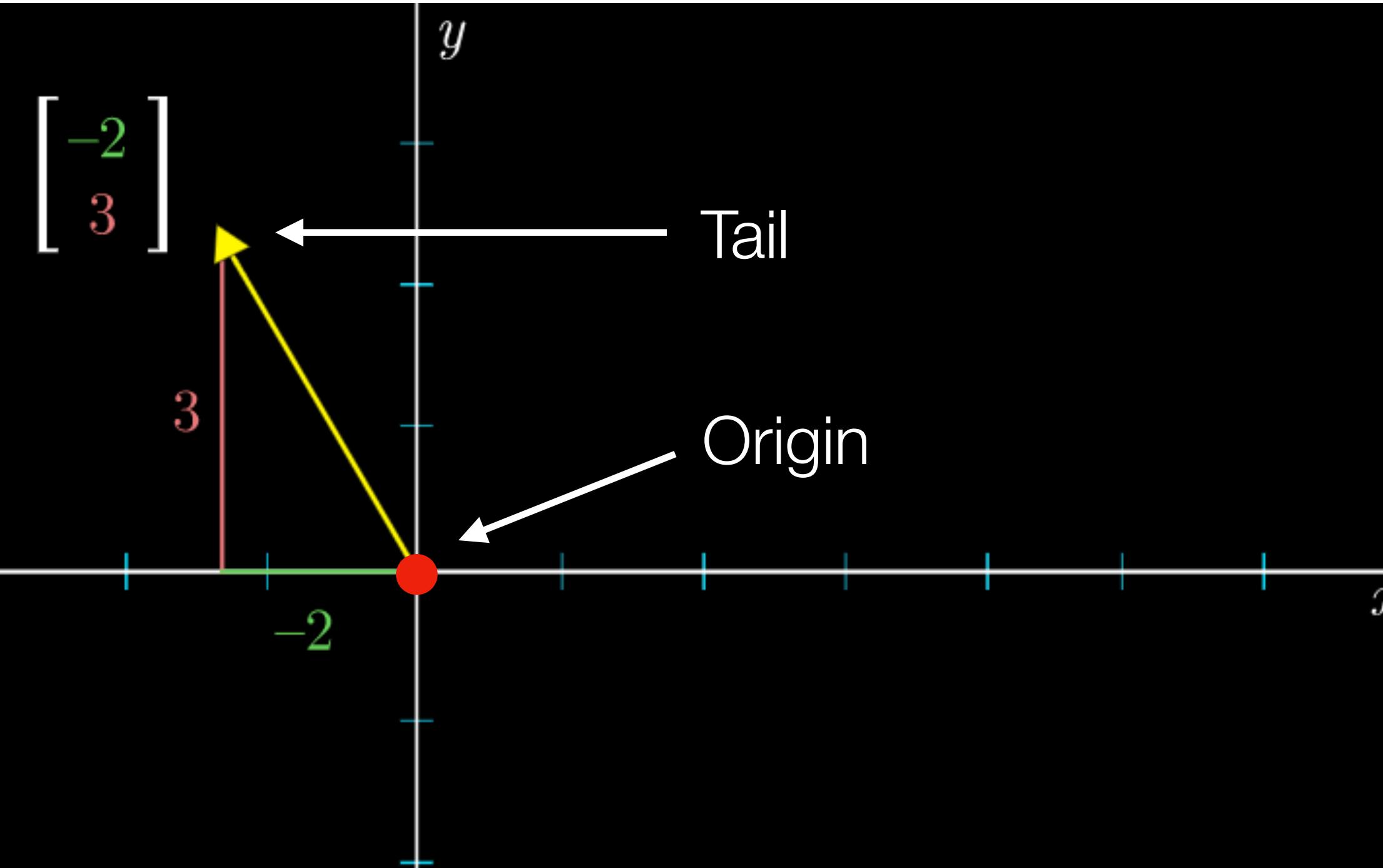
0	0	0	0	0.33	0	0	0.33	0.33	1
0	0	0	0	0.25	0.25	0.25	0	0.25	
0	0	0	0.33	0	0.33	0	0.33	0	
0	0	0.5	0	0	0.5	0	0	0	
0.33	0.33	0	0	0	0	0	0	0.33	
0	0.17	0.17	0.17	0	0	0	0.17	0.17	0.17
0	0.5	0	0	0	0	0.5	0	0	0
0.25	0	0.25	0	0	0.25	0	0	0.25	
0.2	0.2	0	0	0.2	0.2	0	0.2	0	

Stochastic matrix (not covered)

Linear Algebra recap

One step back

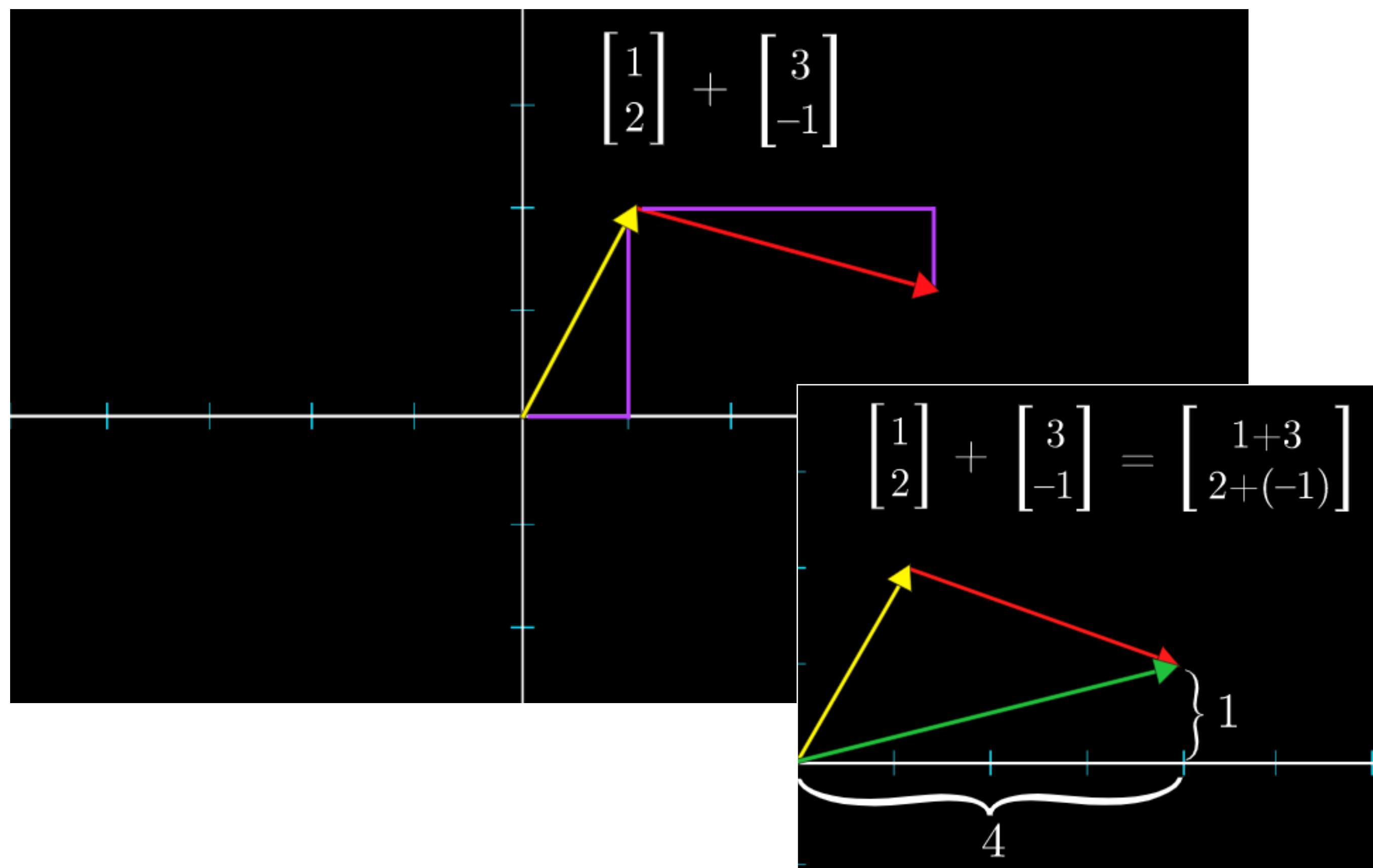
Vectors



Vector: coordinates of the tail and origin in a space

$$\vec{v} \leftarrow = \begin{bmatrix} -2 \\ 3 \end{bmatrix} \neq (2, 3)$$

Vectors

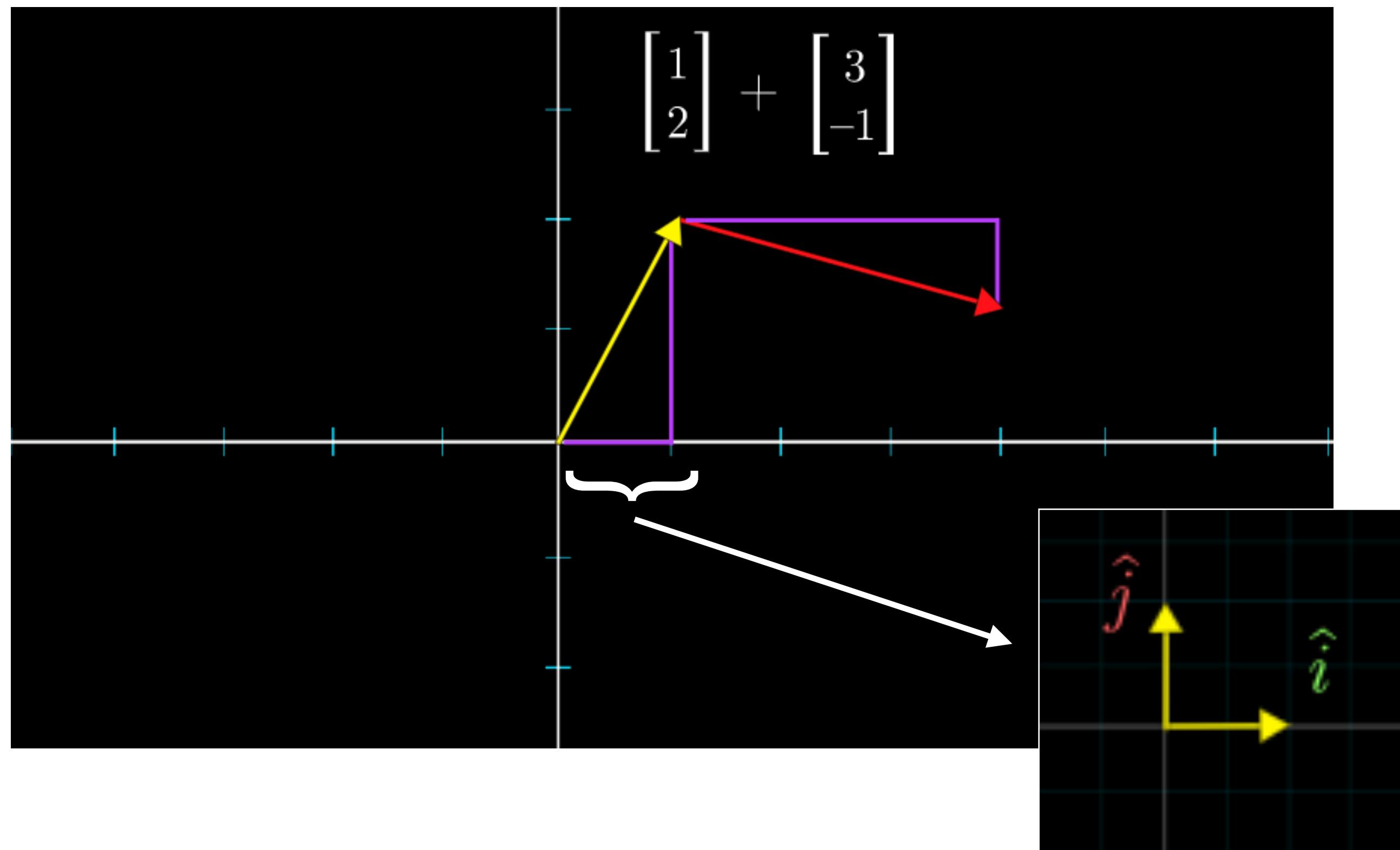


$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 \end{bmatrix} \text{ add}$$

$$2\vec{v} = 2 \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x \\ 2y \end{bmatrix} \text{ Multiply}$$

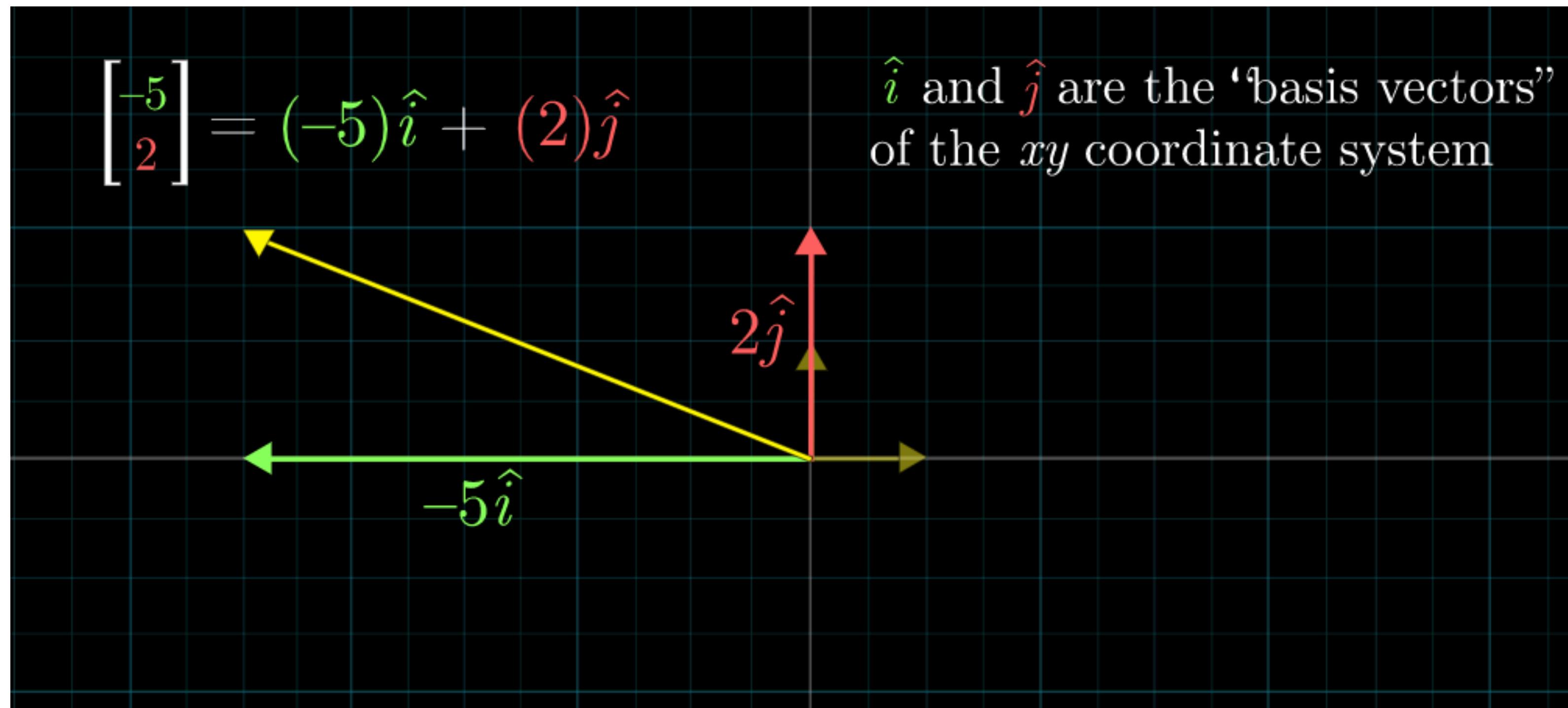
↓
Stretch and squish
vectors: **scaling**

Vectors



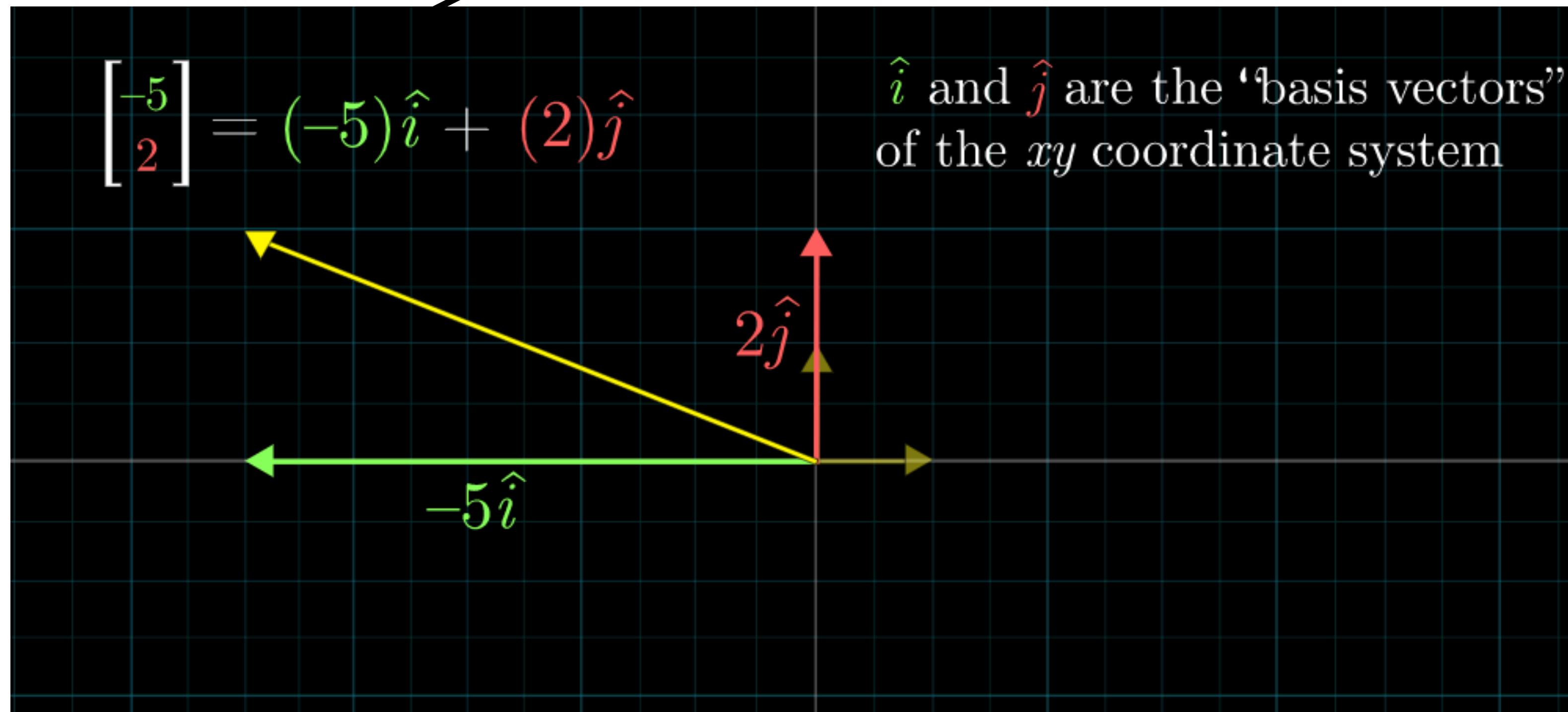
Basis vector = unit length

Linear Algebra recap



Flipping x + scaling by 5, scaling y by 2

Linear transformation



Linear
transformation

Flipping x + scaling by 5, scaling y by 2

Linear transformation

Linear transformation
function

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} \xrightarrow{L(\vec{\mathbf{v}})} \begin{bmatrix} ? \\ ? \end{bmatrix}$$

Vector input Vector output

L preserves sums: $L(\vec{\mathbf{v}} + \vec{\mathbf{w}}) = L(\vec{\mathbf{v}}) + L(\vec{\mathbf{w}})$

L preserves scaling: $L(s\vec{\mathbf{v}}) = sL(\vec{\mathbf{v}})$

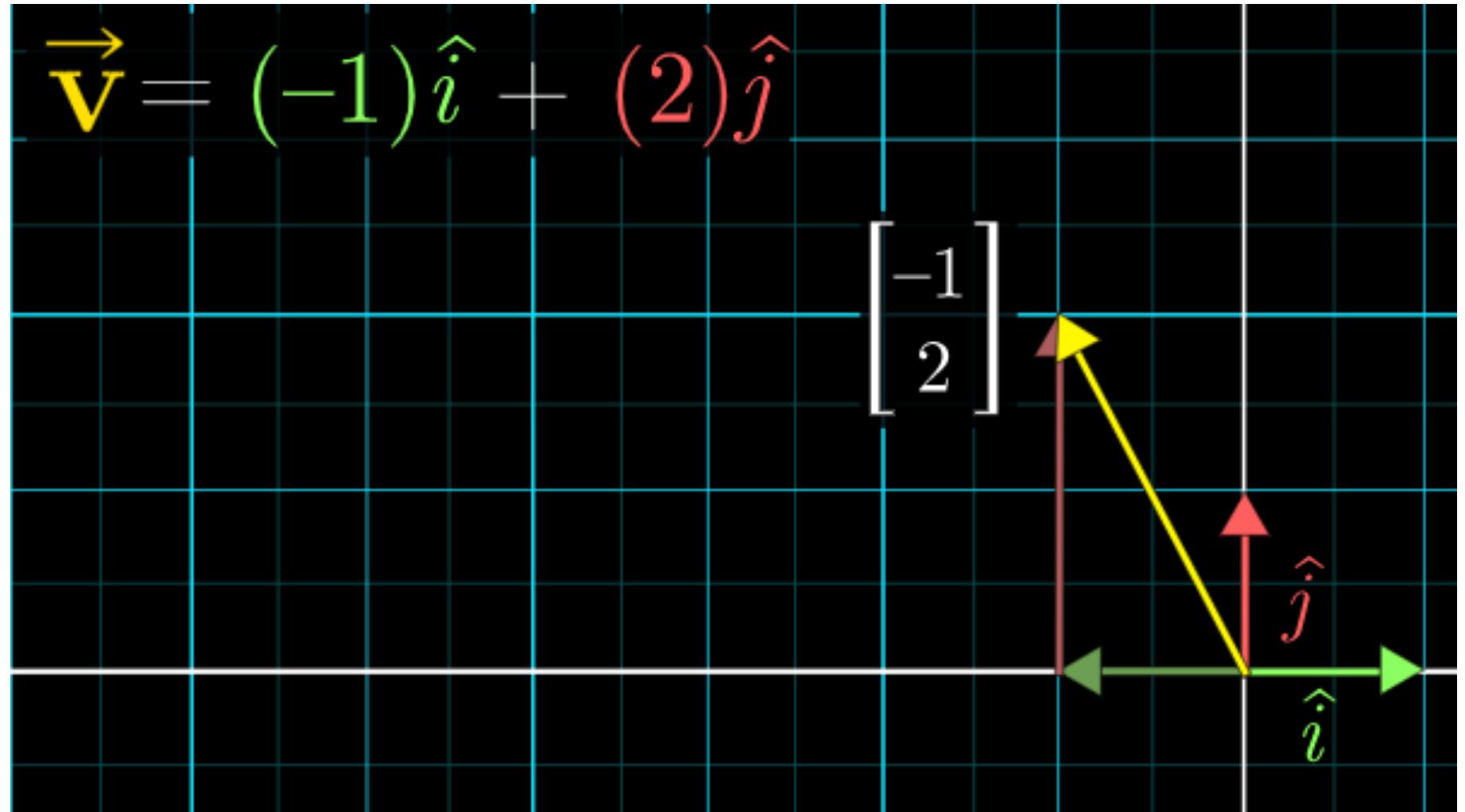
$$\vec{\mathbf{v}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \vec{\mathbf{v}} = -1\hat{\mathbf{i}} + 2\hat{\mathbf{j}}.$$

Linear transformation

Linear transformation
function

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} \rightarrow L(\vec{\mathbf{v}}) \rightarrow \begin{bmatrix} ? \\ ? \end{bmatrix}$$

Vector input Vector output



L preserves sums: $L(\vec{\mathbf{v}} + \vec{\mathbf{w}}) = L(\vec{\mathbf{v}}) + L(\vec{\mathbf{w}})$

L preserves scaling: $L(s\vec{\mathbf{v}}) = sL(\vec{\mathbf{v}})$

$$\vec{\mathbf{v}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \vec{\mathbf{v}} = -1\hat{i} + 2\hat{j}.$$

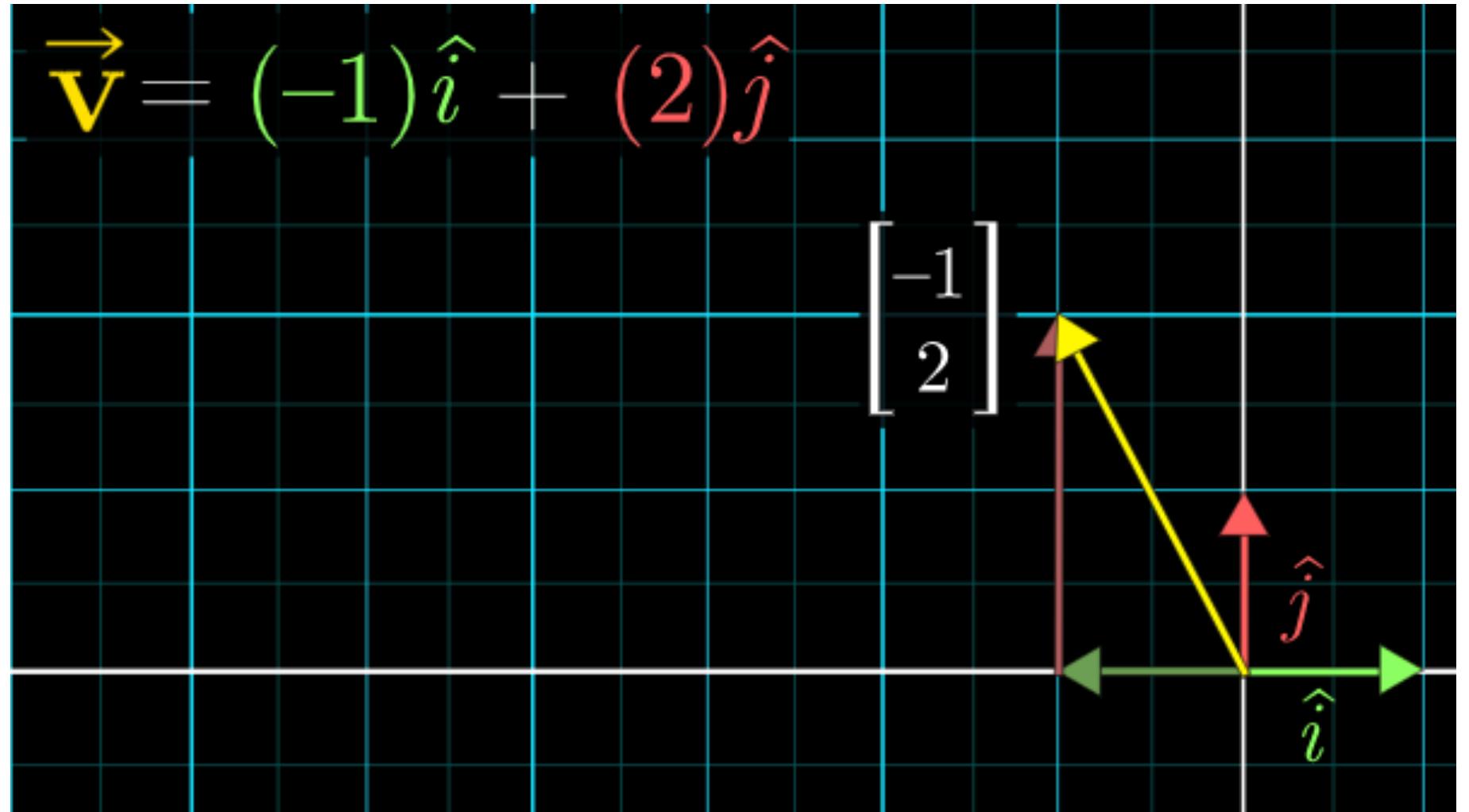
$$L(\hat{i}) = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad L(\hat{j}) = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

Linear transformation

Linear transformation
function

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} \rightarrow L(\vec{\mathbf{v}}) \rightarrow \begin{bmatrix} ? \\ ? \end{bmatrix}$$

Vector input Vector output



L preserves sums: $L(\vec{\mathbf{v}} + \vec{\mathbf{w}}) = L(\vec{\mathbf{v}}) + L(\vec{\mathbf{w}})$

L preserves scaling: $L(s\vec{\mathbf{v}}) = sL(\vec{\mathbf{v}})$

$$\vec{\mathbf{v}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \vec{\mathbf{v}} = -1\hat{i} + 2\hat{j}.$$

$$L(\vec{\mathbf{v}}) = L(-1\hat{i} + 2\hat{j})$$

$$L(\hat{i}) = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad L(\hat{j}) = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$
$$= -1 \cdot L(\hat{i}) + 2 \cdot L(\hat{j})$$

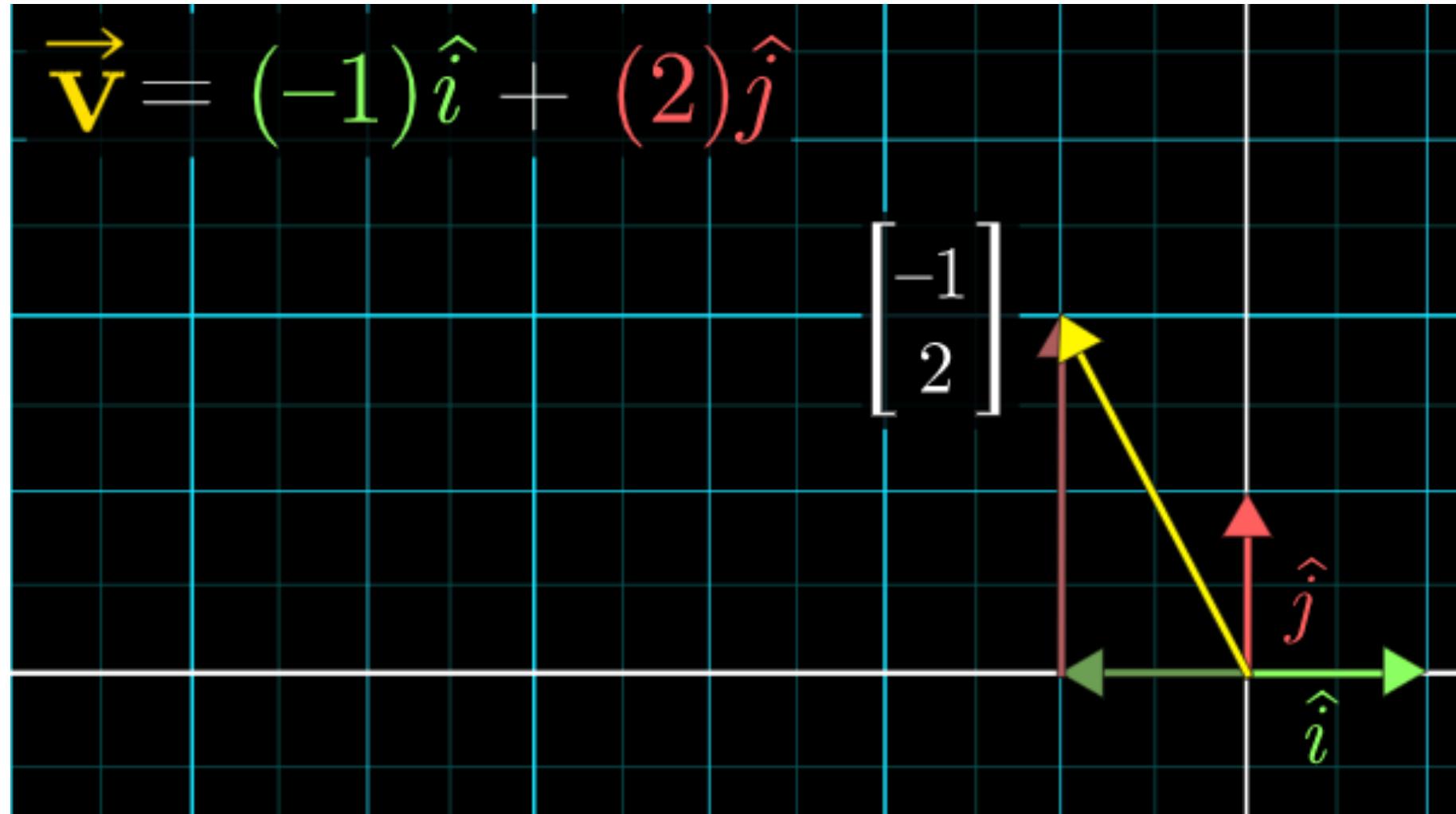
$$= -1 \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix} + 2 \cdot \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

Linear transformation

Linear transformation
function

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} \rightarrow L(\vec{\mathbf{v}}) \rightarrow \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

Vector input Vector output



L preserves sums: $L(\vec{\mathbf{v}} + \vec{\mathbf{w}}) = L(\vec{\mathbf{v}}) + L(\vec{\mathbf{w}})$

L preserves scaling: $L(s\vec{\mathbf{v}}) = sL(\vec{\mathbf{v}})$

$$\vec{\mathbf{v}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \vec{\mathbf{v}} = -1\hat{i} + 2\hat{j}.$$

$$L(\vec{\mathbf{v}}) = L(-1\hat{i} + 2\hat{j})$$

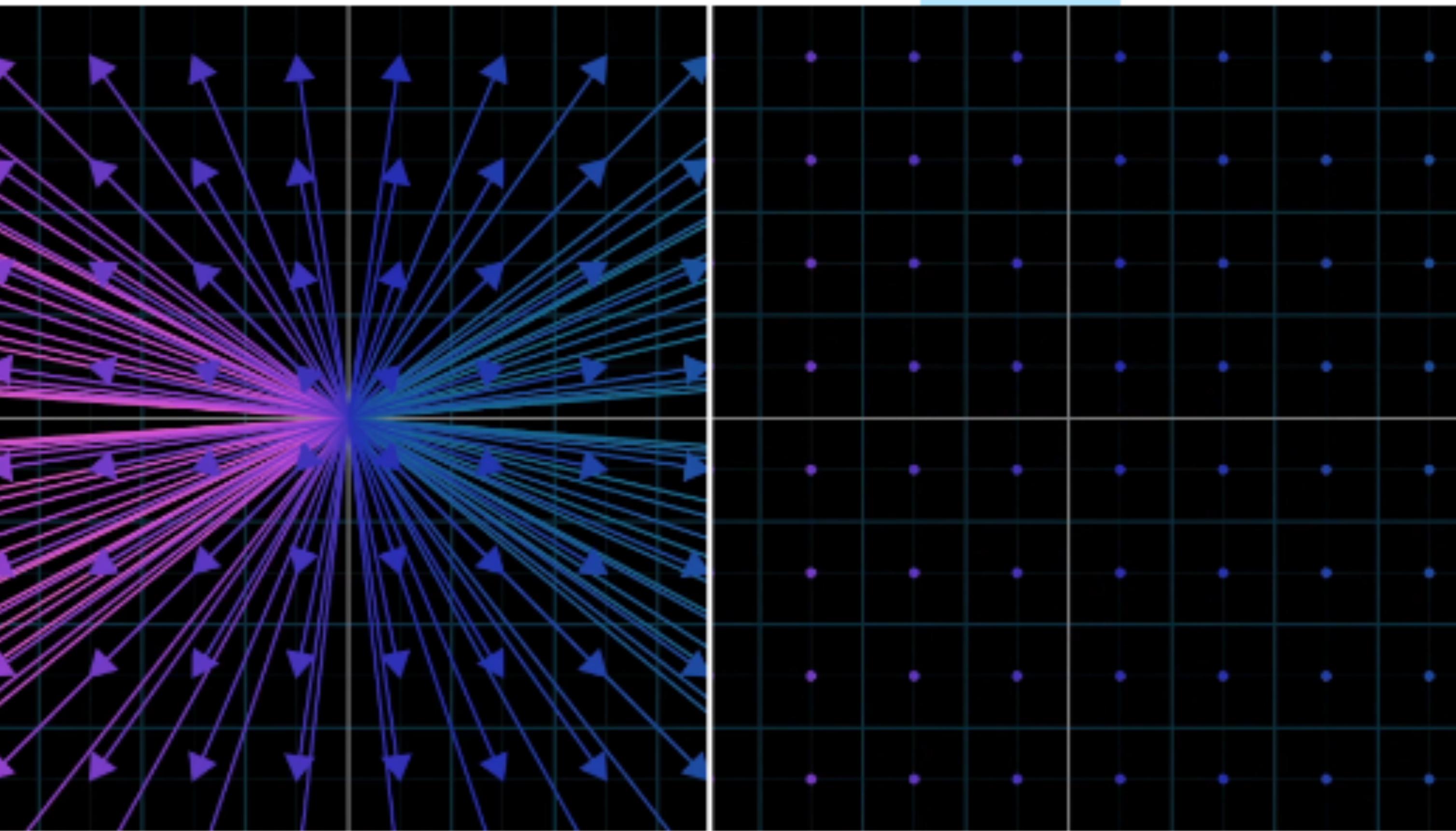
$$L(\hat{i}) = \underbrace{\begin{bmatrix} 1 \\ -2 \end{bmatrix}}_{\text{"2} \times 2 \text{ Matrix"}}, \quad L(\hat{j}) = \underbrace{\begin{bmatrix} 3 \\ 0 \end{bmatrix}}_{\begin{bmatrix} 1 & 3 \\ -2 & 0 \end{bmatrix}}$$

$$= -1 \cdot L(\hat{i}) + 2 \cdot L(\hat{j})$$

$$= -1 \cdot \begin{bmatrix} 1 \\ -2 \end{bmatrix} + 2 \cdot \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$$

Many known matrices encoding common transformations

Linear transformation



Intuition: Vectors as points in a coordinate space.
We can store only the tip of the vector as **points** —> 2D space (matrix).
Linear transformations manipulate this space.

Matrix operations

$$\begin{bmatrix} 3 & 2 \\ -2 & 1 \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 7 \end{bmatrix} = 5 \begin{bmatrix} 3 \\ -2 \end{bmatrix} + 7 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 29 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} a \\ c \end{bmatrix} + y \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$

Matrix multiplication by a vector

Matrix operations

$$\underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_{M_2} \underbrace{\begin{bmatrix} e & f \\ g & h \end{bmatrix}}_{M_1} = \begin{bmatrix} 0 & 2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ 1 & 0 \end{bmatrix}$$

$$= 1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$= -2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

Matrix multiplication by a matrix

Matrix operations

$$\underbrace{\begin{bmatrix} a & b \\ c & d \end{bmatrix}}_{M_2} \underbrace{\begin{bmatrix} e & f \\ g & h \end{bmatrix}}_{M_1} =$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e \\ g \end{bmatrix} = e \begin{bmatrix} a \\ c \end{bmatrix} + g \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} ae + bg \\ ce + dg \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} f \\ h \end{bmatrix} = f \begin{bmatrix} a \\ c \end{bmatrix} + h \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} af + bh \\ cf + dh \end{bmatrix} = \underbrace{\begin{bmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{bmatrix}}_{M_2 M_1}$$

Matrix multiplication by a matrix

Matrix operations

Rules

$$(A+B)+C = A+(B+C) \quad (\text{associativity})$$

$$A + B = B + A \quad (\text{commutativity})$$

$$d \cdot (c \cdot A) = (d \cdot c) \cdot A$$

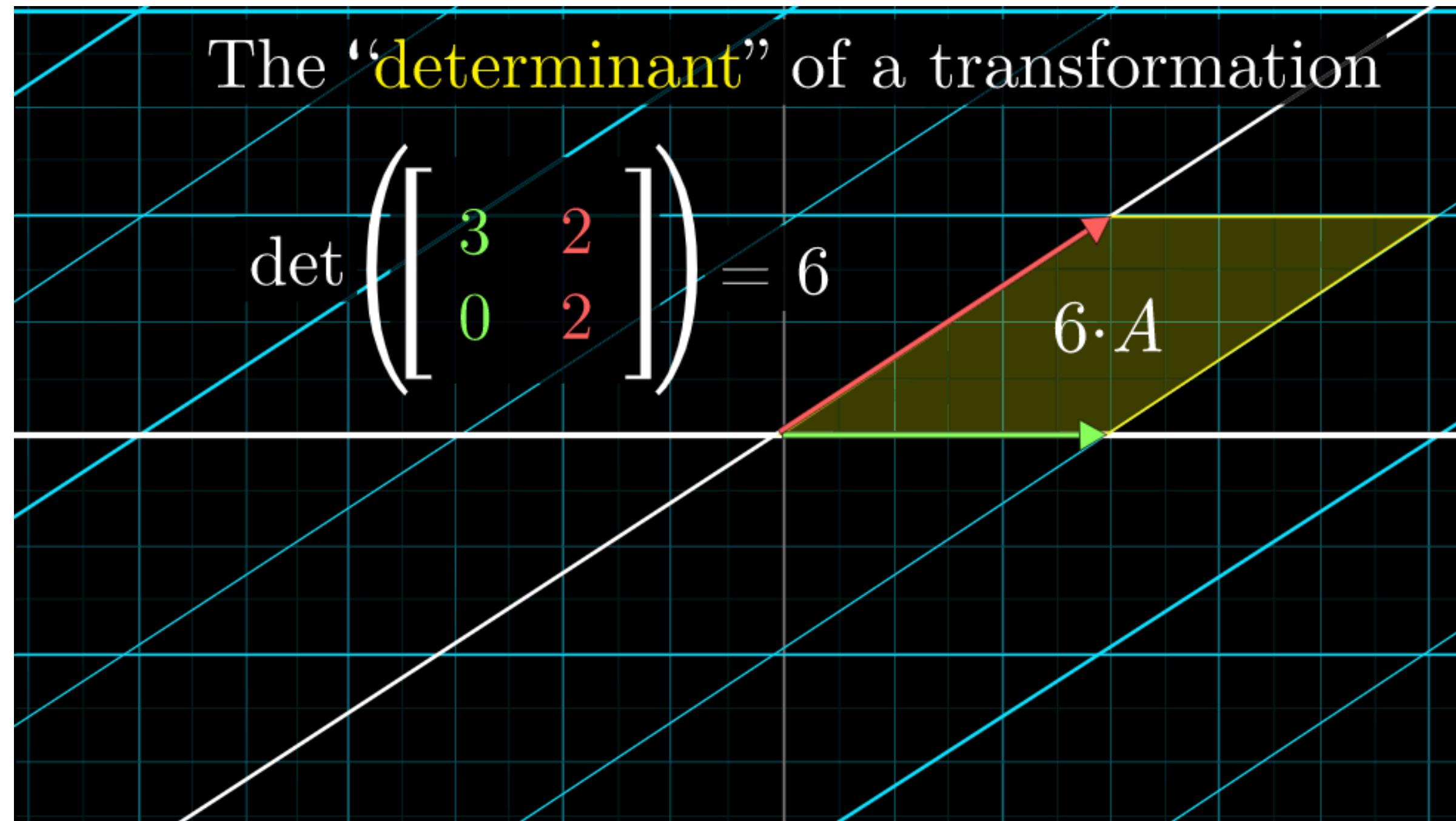
$$1 \cdot A = A$$

$$c \cdot (A+B) = c \cdot A + c \cdot B \quad (\text{distributive law})$$

$$(c+d) \cdot A = c \cdot A + d \cdot A \quad \underline{\hspace{2cm}} \parallel \underline{\hspace{2cm}}$$

Matrix properties

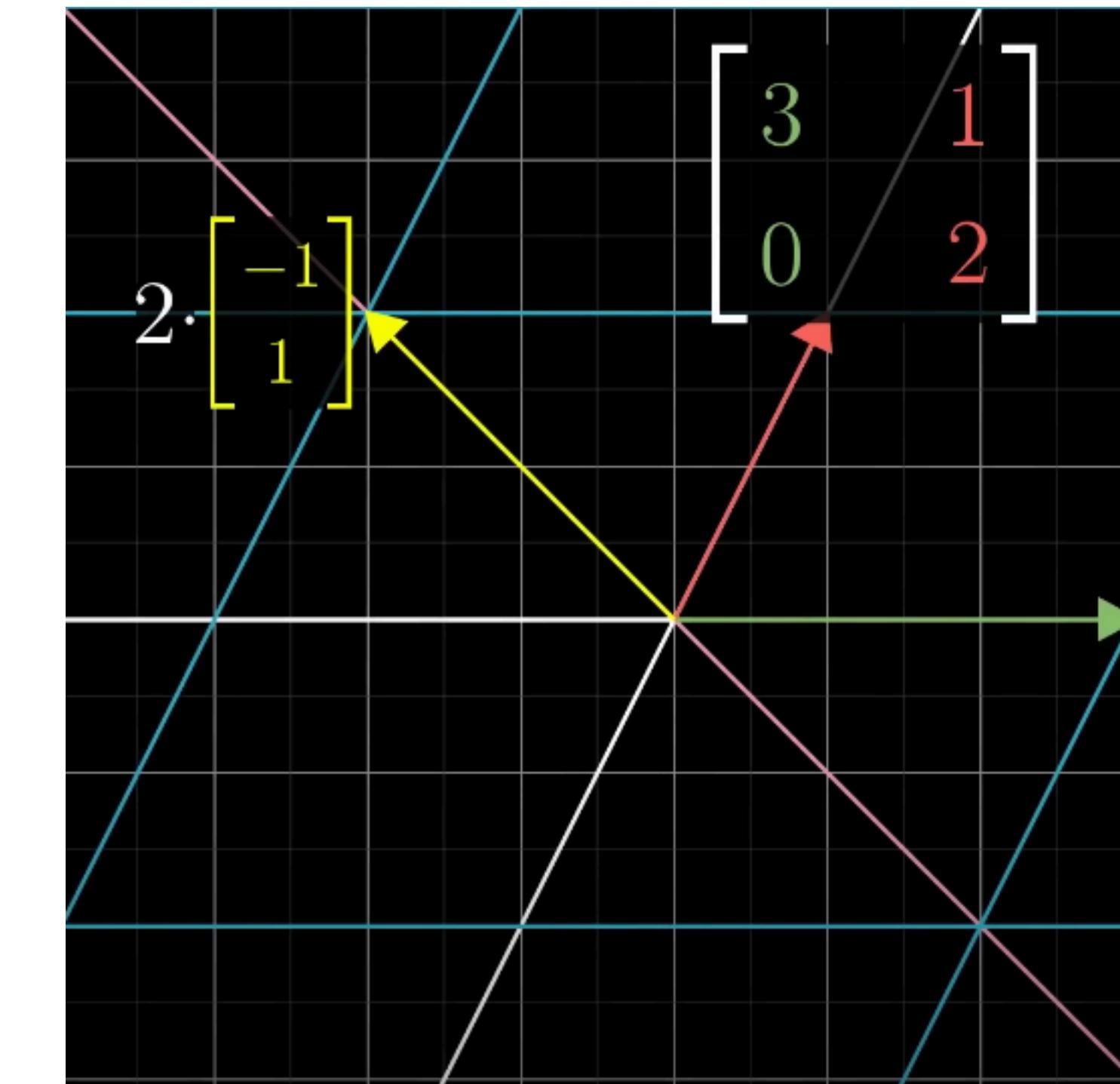
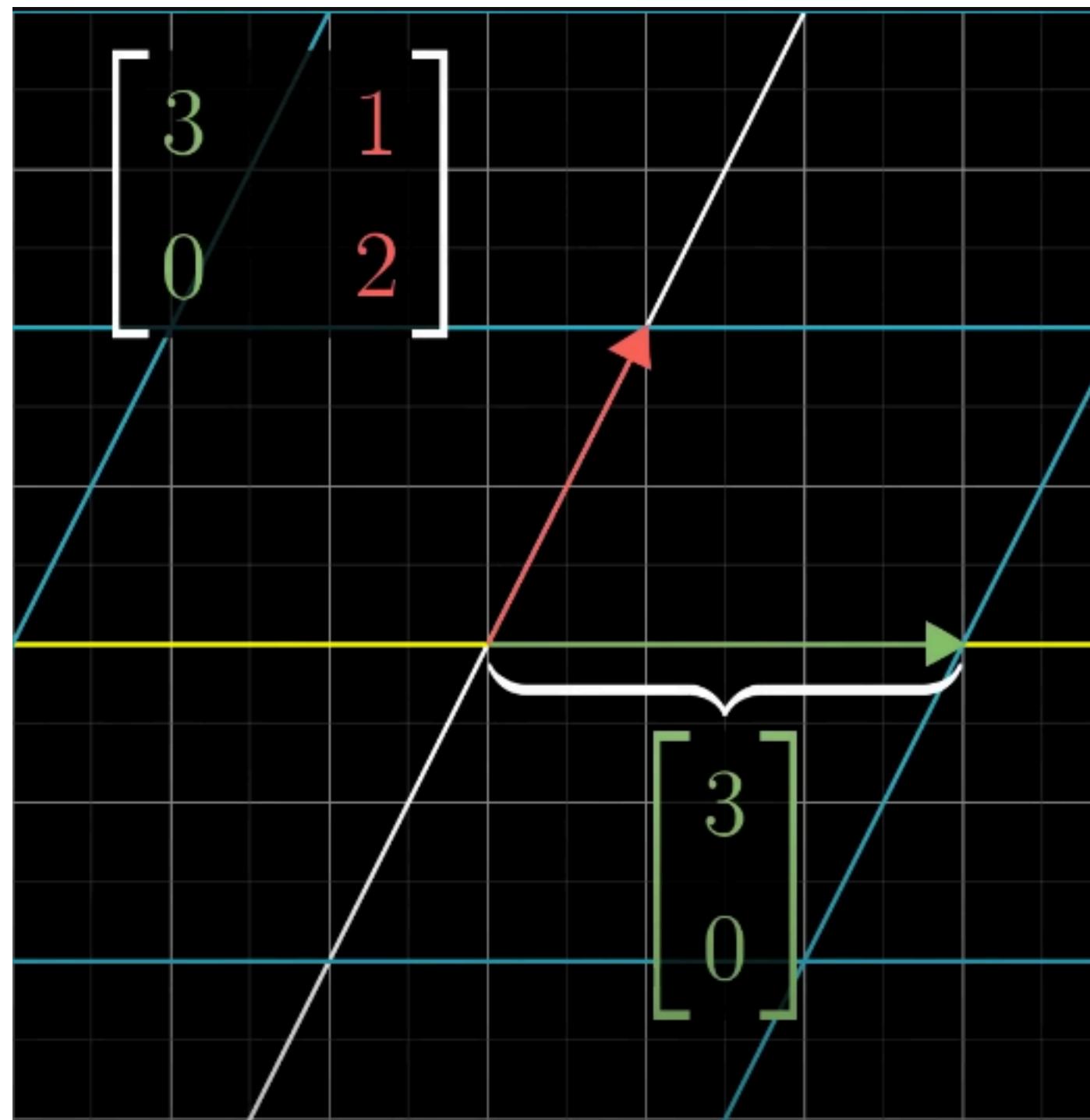
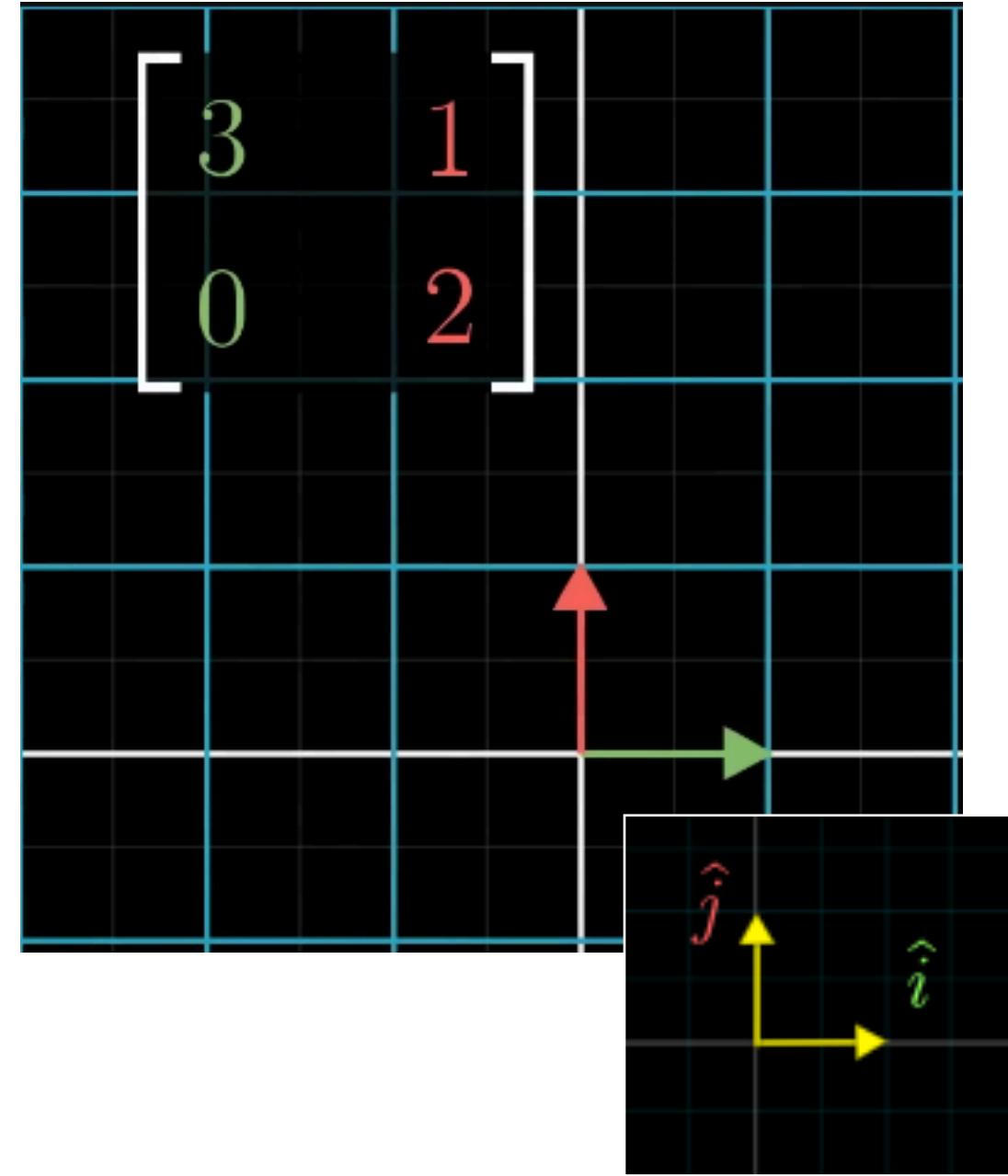
Matrix operations



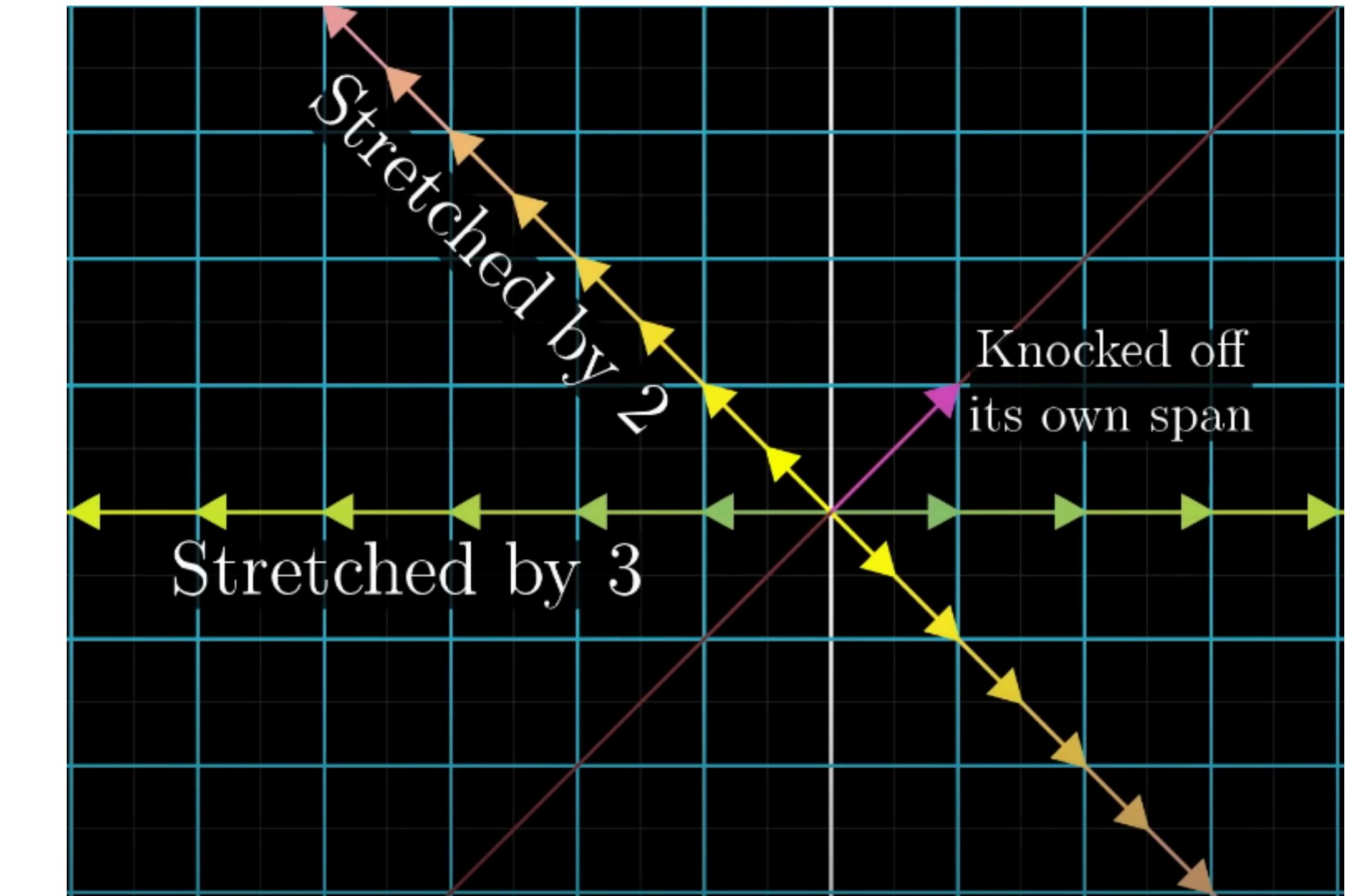
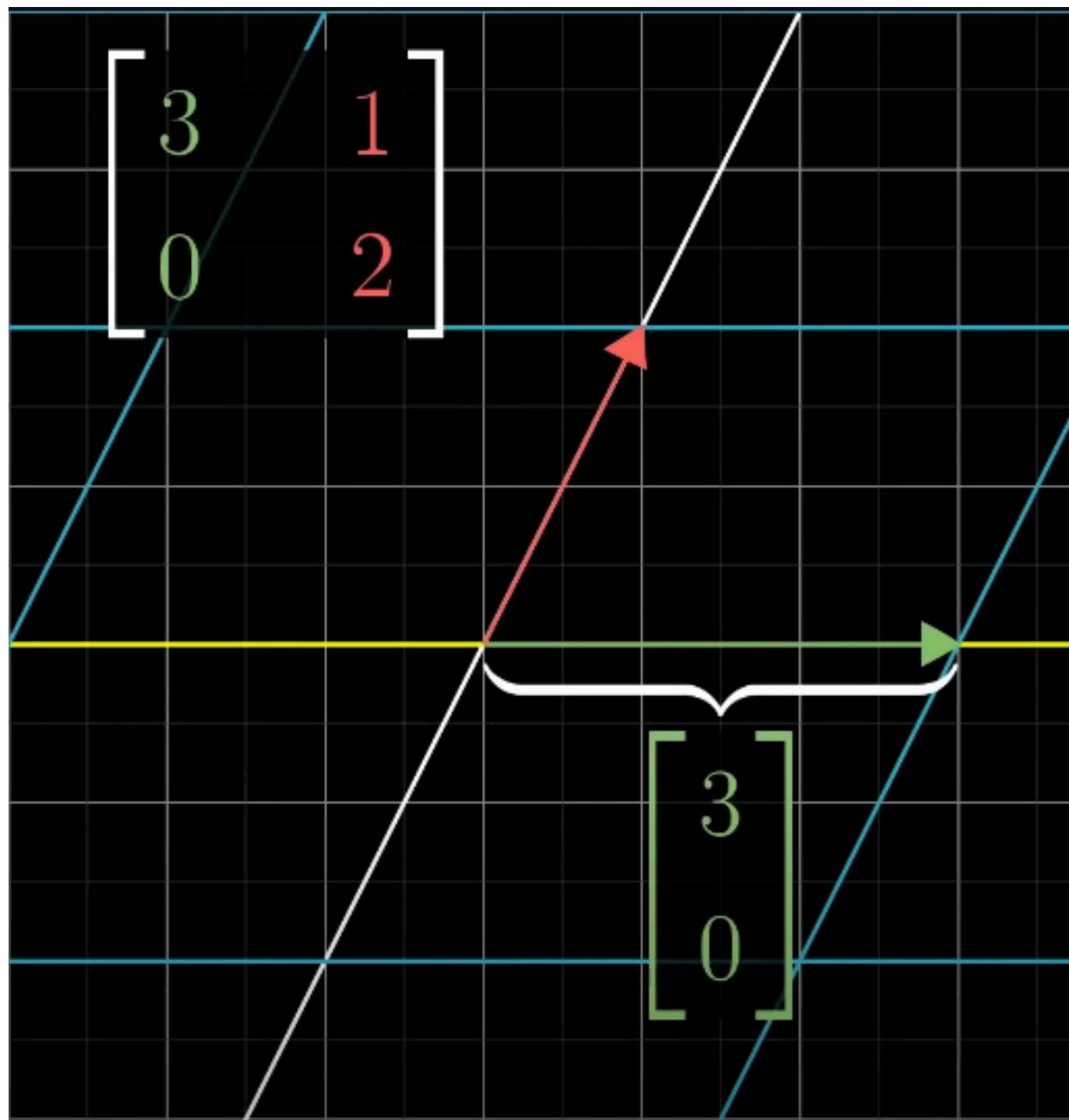
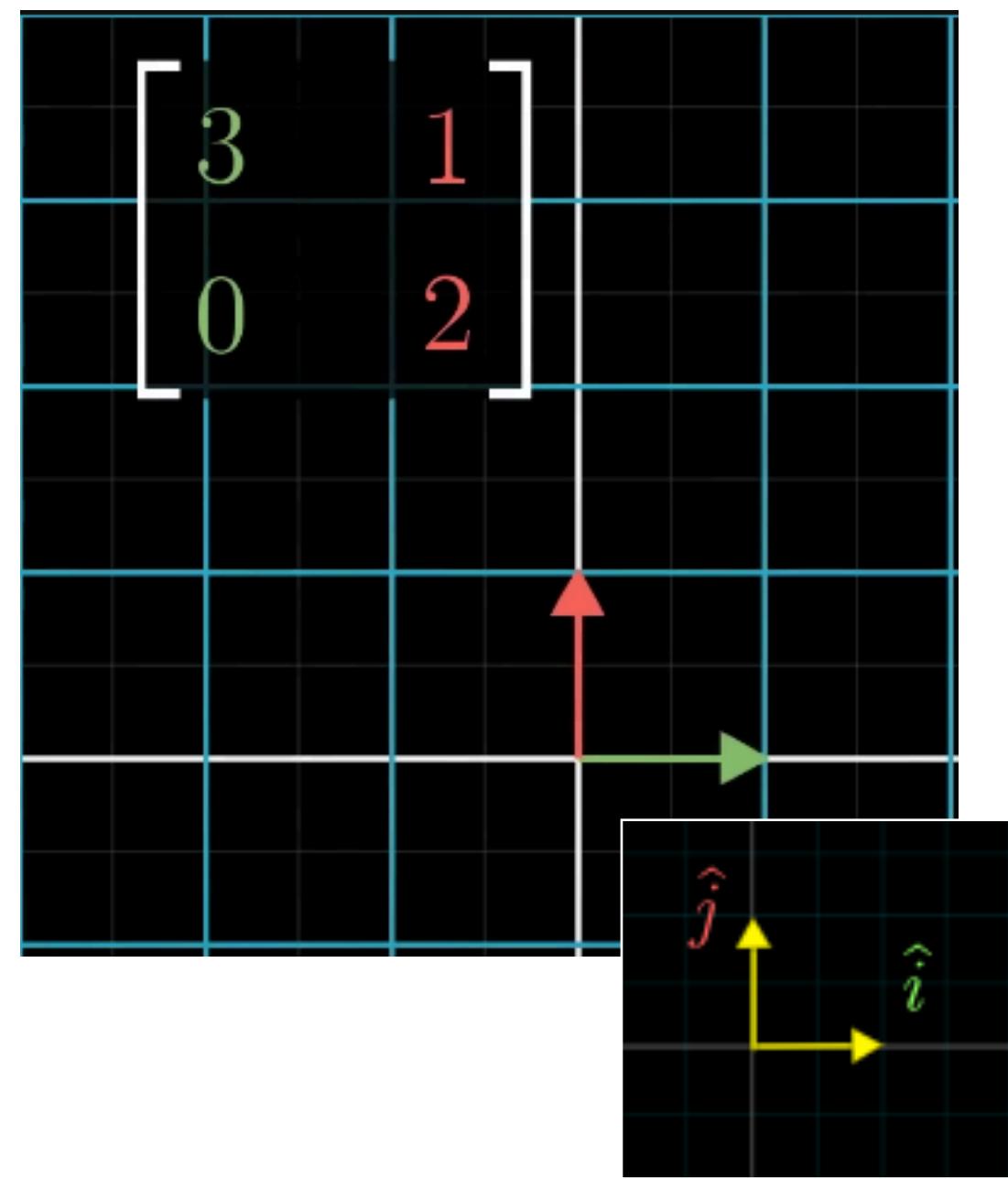
If $\det(L(A)) = 0$,
it squishes all of
space onto a lower
dimension, here a
(line).

How much an area scaled?

Eigenvalues & Eigenvectors

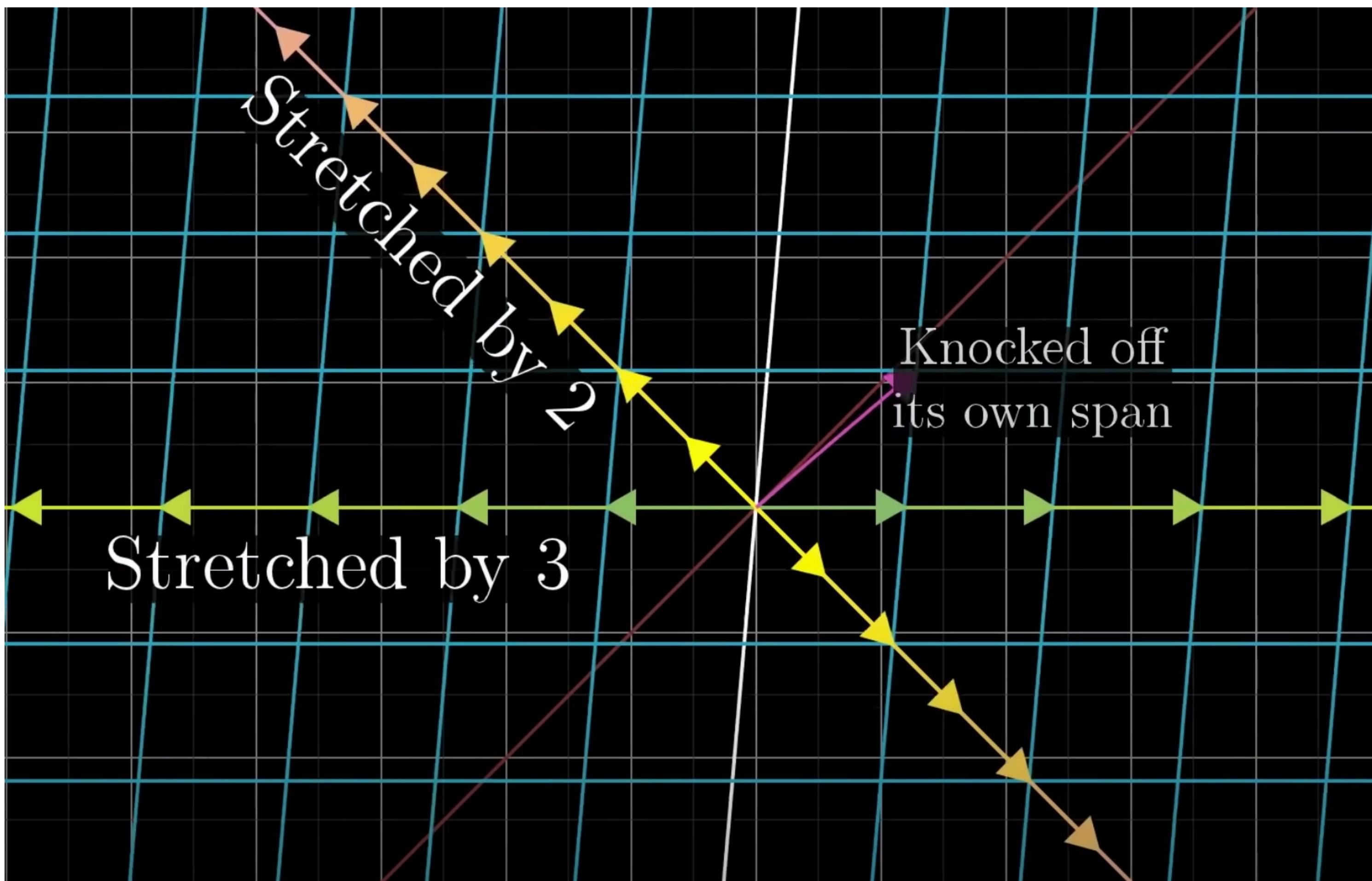


Eigenvalues & Eigenvectors



Eigenvalues & Eigenvectors

Eigenvectors
with
eigenvalues
 λ_2 and λ_3



Gives us an orientation point

No change,
Axis of
rotation

Eigenvalues & Eigenvectors

Matrix
multiplication

Transformation

matrix

$$\hat{A}\vec{v} = \lambda\vec{v}$$

Eigenvector

equivalent to
scaling \vec{v} by λ

Solve: Find \vec{v} and λ where this is true

Rewrite the right-hand side as
matrix vector multiplication

Scaling by λ \leftrightarrow Matrix
multiplication by

$$\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}$$

Eigenvalues & Eigenvectors

Matrix multiplication

Transformation

matrix

$$\hat{A}\vec{v} = \hat{\lambda}\vec{v}$$

Eigenvector

equivalent to scaling \vec{v} by λ

Solve: Find \vec{v} and λ where this is true

Rewrite the right-hand side as matrix vector multiplication

Scaling by λ \Leftrightarrow Matrix multiplication by

$$\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}$$

$$\lambda \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_I$$

Factor out λ
Identity matrix I

Eigenvalues & Eigenvectors

Matrix multiplication

Transformation matrix

$$\hat{A}\vec{v} = \lambda\vec{v}$$

Eigenvector

equivalent to scaling \vec{v} by λ

Solve: Find \vec{v} and λ where this is true

Rewrite the right-hand side as matrix vector multiplication

Scaling by λ \leftrightarrow Matrix multiplication by

$$\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix} \underbrace{\lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_I \vec{v} = \vec{0}$$

Factor out λ
Identity matrix I

Both sides as matrix vector multiplication

$$A\vec{v} = (\lambda I)\vec{v}$$

$$A\vec{v} - (\lambda I)\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$

Eigenvalues & Eigenvectors

Matrix multiplication

Transformation matrix

$$\hat{A}\vec{v} = \lambda\vec{v}$$

Eigenvector

equivalent to scaling \vec{v} by λ

Solve: Find \vec{v} and λ where this is true

Rewrite the right-hand side as matrix vector multiplication

Scaling by λ \leftrightarrow Matrix multiplication by

$$\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix}$$

$$\underbrace{\lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_I$$

Factor out λ
Identity matrix I

Both sides as matrix vector multiplication

$$A\vec{v} = (\lambda I)\vec{v}$$

$$A\vec{v} - (\lambda I)\vec{v} = \vec{0}$$

$$(A - \lambda I)\vec{v} = \vec{0}$$



$$\det(A - \lambda I) = 0$$

Eigenvalues & Eigenvectors

Tweaking values until the $\det(\text{area}) = 0 >$ compressing to a vector.

$$\begin{aligned} A\vec{v} &= \lambda\vec{v} \\ A\vec{v} - \lambda I\vec{v} &= 0 \\ (A - \lambda I)\vec{v} &= 0 \\ \det(A - \lambda I) &= 0 \end{aligned}$$

$$\det \left(\begin{bmatrix} 3-\lambda & 1 \\ 0 & 2-\lambda \end{bmatrix} \right) = (3-\lambda)(2-\lambda) = 0$$

Seeking eigenvalue λ

$\lambda = 2$ or $\lambda = 3$

$$\begin{bmatrix} 3-2 & 1 \\ 0 & 2-2 \\ \lambda = 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Plugin the eigenvalue and solve to get the eigenvectors

Finding these eigen-things

Linear Algebra recap

If none of that makes sense:
remember this



Useful for:

Change coordinate systems,
Computer vision, finding
centrality and components in a
network...

and for Google making loads of
money (PageRank)

Course logistics

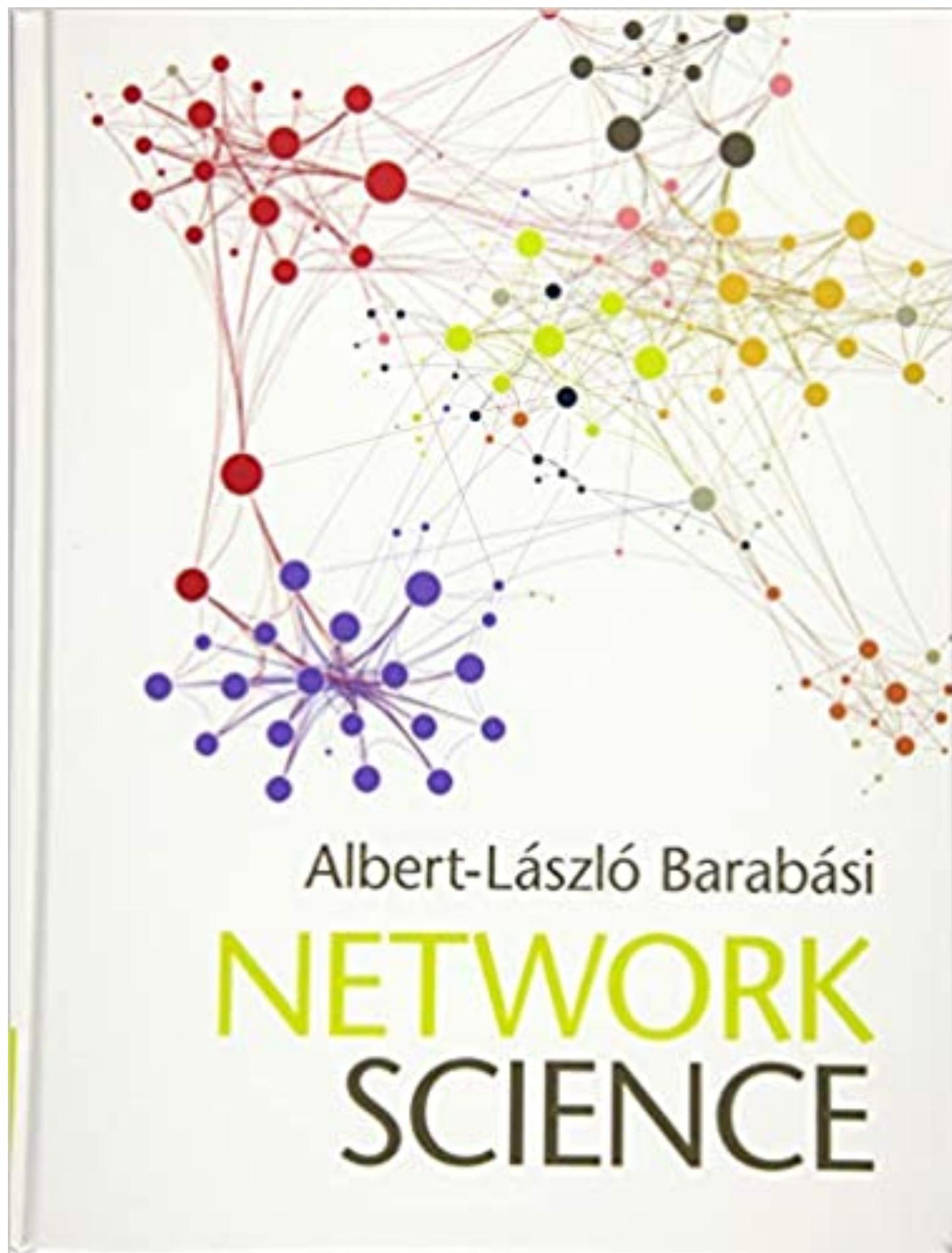
Syllabus

- 1. 2023/03/13 Mon - Basic Graph Theory [Sandro]**
 1. Motivation: What is Network Science, why is it relevant, and what examples?
 2. Key concepts: Nodes & Links
 3. Origins: Leonhard Euler - Seven Bridges of Königsberg (Path, Link directions, Connected components)
 4. Network representation: Edge list, Adjacency matrix, Adding weights
 5. Linear Algebra short recap: Vectors, Matrix, Matrix operations, Eigenvectors & eigenvalues
- 2. 2023/03/15 Wed - Network identity card & Centrality [Sandro]**
 1. Identity card Part 1: Nodes and edges, Unipartite/bipartite, Clustering coefficient, Shortest paths, Average path length, Diameter, Density
 2. Identity card Part 2: Node degree, In-degree/ Out-degree, Weights
 3. Network centrality: Degree centrality, Betweenness centrality, Eigenvector centrality
- 3. 2023/03/20 Mon - Network statistical distributions [Sandro]**
 1. Statistical distribution: Definition, Calculation, Interpretation, Degree distribution
 2. Random network model: Parameters, Degree distribution
 3. Stanley Milgram (Small-world experiment): Shortest path in real-world
- 4. 2023/03/22 Wed - Network mesoscale structure [Roberta]**
Ego network, Homophily, Assortativity, Communities

Exercises

- Work on the ipynb files provided.
- Writing tasks: Be reflexive; it's about understanding the concepts instead of getting the right answer.
- Coding tasks: there are many ways to operationalise an idea; use what you are comfortable with.

Book



Available for free at:

<http://networksciencebook.com/>

Or you can purchase a printed copy.