# DESIGNAND ANALYSIS OF ALGORITHMS

CS 4120/5120 P, NP, AND FINAL REVIEW

### **AGENDA**

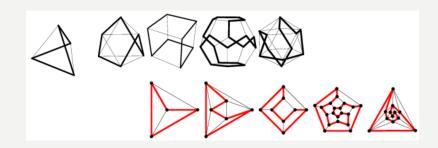
- Polynomial (P), P stands for polynomial
- Non-polynomial (NP)
- Non-polynomial complete (NP-Complete or NPC)
- Final Exam Review

## CASE 1 SHORTEST VS LONGEST PATHS

- Given a directed weighted graph G = (V, E) and its weight function  $w: E \to \mathbb{R}$ .
  - $-\mathbb{R}$  is the set of real numbers.
- Problem I
  - Find the shortest **simple** paths from a source vertex.
  - Can be solved in  $O(|V| \cdot |E|)$  time when the graph contains no negative-weighted cycle.
- Problem 2
  - Find the longest **simple** paths from a source vertex.
  - **-** ?

## CASE 2 EULER TOUR VS HAMILTONIAN CYCLE

- Given a connected directed graph G = (V, E).
  - Connect means there exist a simple path from any pair of vertices (u, v).
- Problem I Euler tour.
  - Find a cycle that traverses each edge exactly once, although it is allowed to visit each vertex more than once.
  - Solvable in O(E) time
- Problem 2 Hamiltonian cycle
  - Find a simple cycle that contains each vertex in V.
  - \_ ?



- The class P consists of those problems that are solvable in  $O(n^k)$  time for some constant k.
  - All the problems we learned in this semester belong in the class *P*.
    - Divide and conquer: Maximum-subarray  $(O(n \log n))$ , Strassen's algorithm  $(\Theta(n^{\log 7}))$
    - Prune and search: SELECT (O(n))
    - Sorting algorithms  $O(n \log n)$
    - DP: Rod-cutting  $(O(n^2))$ , matrix-chain multiplication  $(O(n^3))$ , LCS (O(n+m))
    - Greedy: Activity selection algorithm  $(\Theta(n))$ , HUFFMAN  $(O(n \lg n))$ , or depending the implementation),
    - Graph: Graph searching algorithm (O(|V| + |E|)), etc...
  - The problem I of the previous two cases.

- The class P consists of those problems that are solvable in  $O(n^k)$  time for some constant k.
  - Such algorithms are called **polynomial-time algorithm**.
- Tractable
- Easy

- The class NP consists of those problems that are "verifiable" in polynomial time.
  - If we were somehow given a "certificate" of a solution, then we could verify that the certificate is correct in time polynomial in the size of the input to the problem.
- Consider the Hamiltonian cycle problem (problem #2 in case 2).
  - Given a directed graph G = (V, E), a certificate would be a sequence  $\langle v_1, v_2, ..., v_{|v|} \rangle$  of |V| vertices.
  - We can easily check in polynomial time that  $(v_i, v_{i+1}) \in E$  for i = 1, 2, ..., |V| 1 and that  $(v_{|v|}, v_1) \in E$  as well.

### THE FAMOUS $P \neq NP$ QUESTION

- Any problem in P is also in NP.
  - If a problem is in P, then we can solve it in polynomial time without the need of a certificate.
  - $-P \subseteq NP$
- However, whether a P problem is a proper subset of NP is the open problem.
  - Given a set S, a proper subset S' of S means that S' is strictly contained in S and necessarily excludes at least one member of S.

- A problem is in the class NPC if it is in NP and is as "hard" as any problem in NP.
  - The status of NPC class is unknown.
- What does as "hard" as mean?

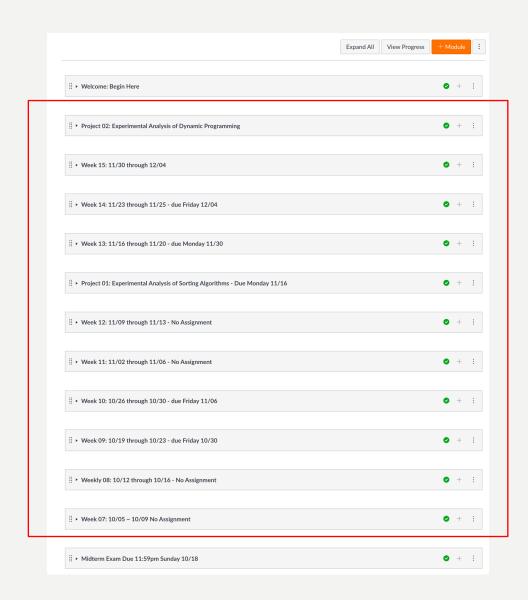
- NPC is the grey area in  $P \neq NP$ .
  - If we can discover a polynomial-time algorithm for an NP-complete problem, then the problem becomes P.
  - If we can prove that there exist no polynomial-time algorithm for an NP-complete problem, then we
    might be able to find a certificate to verify that the problem is NP.
  - No polynomial-time algorithm has yet been discovered for an NP-complete problem, nor has
    anyone yet been able to prove that no polynomial-time algorithm can exist for any one of them.
    - This is why we have a class NPC that describe such problems.

## NEXT UP FINAL REVIEW

- Available at 10 am on Monday, December 7
- Close at 11:59 pm on Friday, December 11
- Two attempts with each being limited by 2.5 hours.
- Scores of the two attempts will be averaged out.
- INDIVIDUAL WORK
- You may use notes. Manage your time wisely.

### **TOPICS**

- Week 07 till TODAY.
- Review tips
  - Assignments in the weekly module.



#### SELECTION PROBLEM

- RANDOMIZED-SELECT
  - PARTITION, RANDOMIZED-PARTITION
  - Best, worst-case scenario running time
- SELECT in linear time in the worst-case scenario
  - Five steps
  - Divide into groups of five elements, ...
  - Think about dividing into groups of 7 elements

### SORTING

- Quicksort
  - PATITION
  - RANDOMIZED-PARTITION
  - Best-case, worst-case scenario running time
- Heapsort
  - Data structure: heap, max-heap properties, min-heap properties
  - BUILD-MAX-HEAP
  - MAX-HEAPIFY
  - HEAPSORT

### DYNAMIC PROGRAMMING

- Key ingredients
- Elements
- The optimal substructure (notation, proof), the recursive formula of computing the optimal value, and the running time of the following
  - Rod-cutting
  - Matrix-chain
  - Longest-common subsequence

#### **GREEDY STRATEGY**

- Key ingredients
- Activity selection problem
  - Optimal substructure (notation, proof)
  - The greedy property (notation, proof)
  - Running time
- HUFFMAN algorithm
  - Variable-length codeword
  - Prefix codes
  - Data structure
  - Running time

### **GRAPH ALGORITHMS**

- Graph representation
- Graph searching algorithms
  - BFS
    - Strategy, data structure, object, result, running time
  - DFS
    - Strategy, object, result, running time

### **GRAPH ALGORITHMS**

- Shortest-paths problem
  - **Single-source** shortest-paths problem
    - Can be used to solve many variants of shortest-paths problem
  - Dijkstra's algorithm
    - Directed, weighted graph, with no negative edge
    - Strategy, data structure, object, running time
  - Bellman-ford
    - Directed, weighted graph with negative edge.
    - Strategy, result, running time

### REFERENCE