

Exercise of Supervised Learning: Gaussian Processes Part 2

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Exercise 1: Gaussian Posterior Process

Assume your data follows the following law:

$$\mathbf{y} = \mathbf{f} + \boldsymbol{\epsilon}, \quad \boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I}),$$

with $\mathbf{f} = f(\mathbf{x}) \in \mathbb{R}^n$ being a realization of a Gaussian process (GP), for which we a priori assume

$$f(\mathbf{x}) \sim \mathcal{GP}(m(\mathbf{x}), k(\mathbf{x}, \mathbf{x}')).$$

\mathbf{x} here only consists of 1 feature that is observed for n data points.

(a) Derive / define the prior distribution of \mathbf{f} .

1 (a): Prior Distribution of \mathbf{f}

- ▶ $\mathbf{f} \sim \mathcal{N}(\mathbf{m}, \mathbf{K})$.
- ▶ $\mathbf{m} = m(\mathbf{x})$.
- ▶ $\mathbf{K}_{ij} = k(x^{(i)}, x^{(j)})$.
- ▶ NB: Note the (in-)finite Gaussian property of a GP: no matter which finite collection of points you choose from the domain of the process, the corresponding values of the processes are jointly Gaussian.

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Exercise 1 (b)

(b) Derive the posterior distribution of $\mathbf{f}|\mathbf{y}$.

1 (b): Likelihood and Prior

The posterior can be derived from the likelihood and prior using Bayes rule:

$$\mathbf{y} = \mathbf{f} + \boldsymbol{\epsilon}, \quad \boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \sigma^2 \mathbf{I})$$

The likelihood is:

$$p(\mathbf{y}|\mathbf{f}) \propto \exp \left(-\frac{1}{2}(\mathbf{y} - \mathbf{f})^\top (\sigma^2 \mathbf{I})^{-1} (\mathbf{y} - \mathbf{f}) \right).$$

The prior is:

$$p(\mathbf{f}) \propto \exp \left(-\frac{1}{2}(\mathbf{f} - \mathbf{m})^\top \mathbf{K}^{-1} (\mathbf{f} - \mathbf{m}) \right).$$

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So the posterior is:

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1 (b): Complete the Square

$$p(\mathbf{f}|\mathbf{y}) \propto \exp\left(-\frac{1}{2}\mathbf{f}^\top \mathbf{K}_{\text{post}}^{-1}\mathbf{f} + \mathbf{f}^\top \tilde{\mathbf{f}}\right)$$

Recall the technique of **completing the square**:

- Scalar: $ax^2 + bx + c = a(x + \frac{b}{2a})^2 + (c - \frac{b^2}{4a})$
- Matrix / vector: $\mathbf{x}^\top \mathbf{A} \mathbf{x} + \mathbf{x}^\top \mathbf{b} + c = (\mathbf{x} + \frac{1}{2}\mathbf{A}^{-1}\mathbf{b})^\top \mathbf{A}(\mathbf{x} + \frac{1}{2}\mathbf{A}^{-1}\mathbf{b}) + (c - \frac{1}{4}\mathbf{b}^\top \mathbf{A}^{-1}\mathbf{b})$ for a **symmetric** matrix \mathbf{A} .

In our case: $\mathbf{A} = -\frac{1}{2}\mathbf{K}_{\text{post}}^{-1}$, and $\mathbf{b} = \tilde{\mathbf{f}}$, and $c = 0$ or an arbitrary const. So,

$$\mathbf{x} + \frac{1}{2}\mathbf{A}^{-1}\mathbf{b} = \mathbf{f} + \frac{1}{2}\left(-\frac{1}{2}\mathbf{K}_{\text{post}}^{-1}\right)^{-1}\tilde{\mathbf{f}} = \mathbf{f} - \mathbf{K}_{\text{post}}\tilde{\mathbf{f}}$$

and we omit $c - \frac{1}{4}\mathbf{b}^\top \mathbf{A}^{-1}\mathbf{A}\mathbf{b}$ because

- It is a constant w.r.t. \mathbf{f} .
- the exp and \propto operators.

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1 (b): Complete the Square

$$\begin{aligned} p(\mathbf{f}|\mathbf{y}) &\propto \exp \left((\mathbf{f} - \mathbf{K}_{\text{post}} \tilde{\mathbf{f}})^\top \left(-\frac{1}{2} \mathbf{K}_{\text{post}}^{-1} \right)^{-1} (\mathbf{f} - \underbrace{\mathbf{K}_{\text{post}} \tilde{\mathbf{f}}}_{:=\mathbf{f}_{\text{post}}}) \right) \\ &\propto \exp \left((\mathbf{f} - \mathbf{f}_{\text{post}})^\top \left(-\frac{1}{2} \mathbf{K}_{\text{post}}^{-1} \right)^{-1} (\mathbf{f} - \mathbf{f}_{\text{post}}) \right) \end{aligned}$$

Hence,

$$\mathbf{f}|\mathbf{y} \sim \mathcal{N}(\mathbf{f}_{\text{post}}, \mathbf{K}_{\text{post}}).$$

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Hence,

$$\mathbf{f}|\mathbf{y} \sim \mathcal{N}(\mathbf{f}_{\text{post}}, \mathbf{K}_{\text{post}}).$$

Exercise 1 (c)

(c) Derive the posterior predictive distribution $y_* | x_*, \mathbf{x}, \mathbf{y}$ for a new sample x_* from the sample data-generating process.

1 (c): Derive Predictive Posterior from Joint Distribution

Naïvely, we can compute

$$p(y_*|x_*, \mathbf{x}, \mathbf{y}) = \int p(y_*|x_*, \mathbf{x}, \mathbf{y}, \mathbf{f}) \cdot p(\mathbf{f}|\mathbf{y}, \mathbf{x}) d\mathbf{f}.$$

This is cumbersome. Alternative, we can use the fact that

$$\text{if } \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} \boldsymbol{\mu}_a \\ \boldsymbol{\mu}_b \end{pmatrix}, \begin{pmatrix} \Sigma_{aa} & \Sigma_{ab} \\ \Sigma_{ab}^\top & \Sigma_{bb} \end{pmatrix} \right), \text{ then } \mathbf{a}|\mathbf{b} \sim \mathcal{N}(\boldsymbol{\mu}_{a|b}, \Sigma_{a|b})$$

where

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1 (c) Derive Predictive Posterior from Joint Distribution

The joint distribution of (\mathbf{y}, y_*) : **Note: here is \mathbf{y} instead of \mathbf{f} , and $\mathbf{y} = \mathbf{f} + \epsilon$. So we have σ^2 in the in the cov. matrix.**

$$\begin{pmatrix} \mathbf{y} \\ y_* \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} \mathbf{m} \\ m_* \end{pmatrix}, \begin{pmatrix} \mathbf{K} + \sigma^2 \mathbf{I} & \mathbf{K}_* \\ \mathbf{K}_*^\top & \mathbf{K}_{**} + \sigma^2 \end{pmatrix} \right),$$

Therefore, the conditional distribution $y_* | x_*, \mathbf{x}, \mathbf{y}$ is also a Gaussian:

$$y_* | x_*, \mathbf{x}, \mathbf{y} \sim \mathcal{N}(m_* + \mathbf{K}_*^\top (\mathbf{K} + \sigma^2 \mathbf{I})^{-1} (\mathbf{y} - \mathbf{m}), \mathbf{K}_{**} + \sigma^2 - \mathbf{K}_*^\top (\mathbf{K} + \sigma^2 \mathbf{I})^{-1} \mathbf{K}_*).$$

1 (c) Derive Predictive Posterior from Joint Distribution

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Exercise 1 (d)

Implement the GP with squared exponential kernel, zero mean function and $\ell = 1$ from scratch for $n = 2$ observations (\mathbf{y}, \mathbf{x}) . Do this as efficiently as possible by explicitly calculating all expensive computations by hand. Do the same for the posterior predictive distribution of y_* . Test your implementation using simulated data.

Show the standard solution.