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2 1. Smooth Manifolds. want to call a curve \smooth" if it has a tangent line that varies continu-ously from point to point, and similarly a \smooth surface" should be one that has a tangent plane that varies continuously from point to point.

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Fig. 1.4: Both occurrences of xi should be xnC1.

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As for the rest of the book – skip (or skim through) it and go straight to a smooth manifolds book after learning some general topology. Places that need extra concentration: Section 8 (The Inverse Function Theorem) – read Rudin's proof instead, Section 19 (Proof of the Change of Variables Theorem), Section 32 (The Action of a Differentiable Map).

Mathematics – wj32
Introduction to Smooth Manifolds from John Lee is one of the best introduction books I ever read. I read most of this book, except for the appendices at the end and proofs of some corollaries.

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Introduction to Smooth Manifolds | John Lee | Springer
This is without a doubt one of the absolute best mathematics books I've ever read. The book covers a lot of smooth manifold theory. Of course, it can't cover everything, so things on Lie groups, curvature, connections are being left out. But Lee really shows a lot of love and passion for the subject ...

Introduction to Smooth Manifolds by Lee | Physics Forums
Introduction to differentiable manifolds Lecture notes version 2.1, November 5, 2012 This is a self contained set of lecture notes. The notes were written by Rob van der Vorst. The solution manual is written by Guit-Jan Ridderbos. We follow the book 'Introduction to Smooth Manifolds' by John M. Lee as a reference text [1].

INTRODUCTION TO DIFFERENTIABLE MANIFOLDS - VU
Chapter 1. Smooth Manifolds Theorem 1. [Exercise 1.18] Let M be a topological manifold. Then any two smooth atlases for Mdetermine the same smooth structure if and only if their union is a smooth

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