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The solution to a (nondegenerate) linear programming problem must occur at a vertex of the feasible set. In our unperturbed problem there are three vertices: $[0,1]$, $[1,0]$, and $[0,0]$. Since the gradient of cTx is almost parallel to the constraint $Ax \leq b$, we sometimes find the solution at the first vertex and sometimes at the second.

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Thus, Chapters 7, 8, 12, and 13 could be covered much earlier, and Chapters 3, 4 and 6 much later, than their appearance in the book. For example, Chapters 3, 7, and 12 all involve some type of data fitting, so it might be desirable to cover them as a unit.

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