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Maps. A discrete-time, affine dynamical system has the form of a matrix difference equation: $x_{n+1} = Ax_n + b$, with A a matrix and b a vector. As in the continuous case, the change of coordinates $x \rightarrow x + (I - A)^{-1}b$ removes the term b from the equation. In the new coordinate system, the origin is a fixed point of the map and the solutions are of the linear system $A^n x_0$.

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