

Problem 1d

The eigenvalues of A are given by

$$\lambda_k = 4/h^2 * \sin^2(k * \pi / (2m)) \text{ for } k = 1, 2, 3 \dots m - 1$$

To get an eigenvalue of 0, we need to substitute $k = 0$ or m . But this corresponds to the boundary condition, which is already known ($u_0 = u_m = 0$).

Further, if 0 were an eigenvalue for A, then A would not be invertible, which is not the case for A
=> contradiction! Hence, 0 cannot be an eigenvalue for A.

Problem 1e

The residual norms for the different values of h are:

$h = 0.001$, $\text{res} = 2.5870416919815398\text{e-}12$

$h = 0.0005$, $\text{res} = 1.2190581877291606\text{e-}11$

$h = 0.00025$, $\text{res} = 4.2633674368630636\text{e-}11$

The convergence rate = 4.0006112759774055 (~ 4)

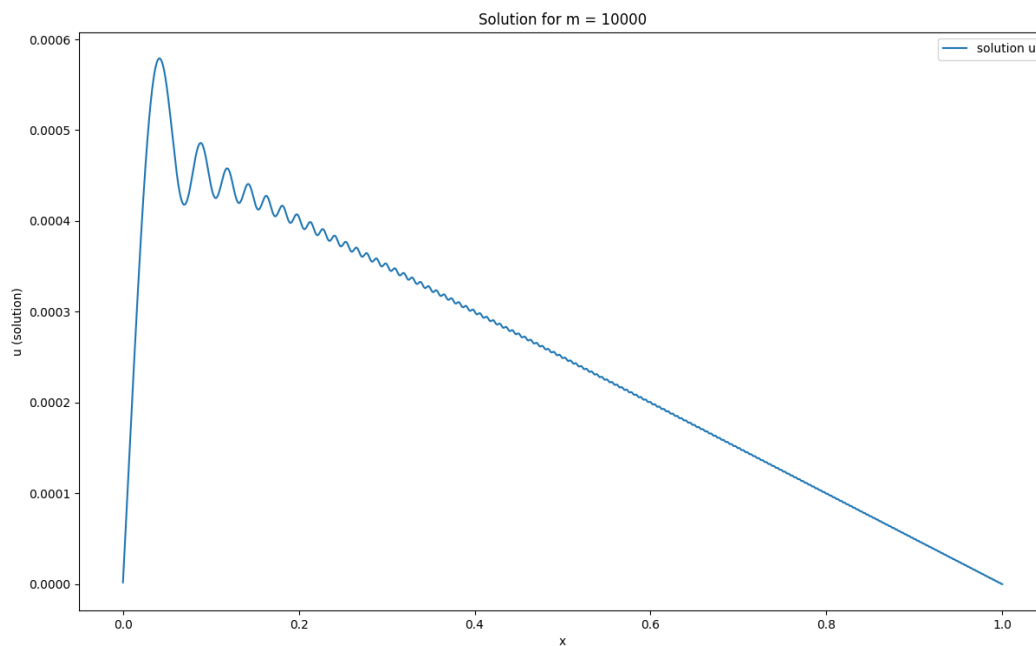
Problem 1f

$f = \sin(10000 * x * x)$

$m = 10000$

Time taken for solve = 4.859262943267822 s

The plot of the solution is:



Problem 1g

Thomas algorithm

Thomas algorithm is a simplified form of Gaussian elimination that can be used to solve tridiagonal systems of equations. For a tridiagonal system with n equations, the solution can be obtained in $O(n)$ time using the Thomas algorithm as opposed to the $O(n^3)$ time complexity required by Gaussian elimination. In this algorithm, the values below the diagonal are first eliminated, followed by a back substitution using the resulting upper triangular matrix to solve the system.

Problem 1h

$f = \sin(1000 \cdot x)$

$m = 100000$

Residual norm for sparse solve = $2.718582026162153e-09$

Time taken for sparse solve = 0.04828000068664551 s

The 1D laplace matrix A has eigenvectors where each element is a sin function. And the eigenvalues are multiples of the \sin^2 function.

$$\lambda_k = 4/h^2 * \sin^2(k * \pi / (2m)) \text{ for } k = 1, 2, 3 \dots m$$

When m increases, the m eigenvalues and eigenvectors are not estimated with high accuracy for the higher modes.

In this problem, since f is a sin function. So solving $Au=f$ can be interpreted as estimating the eigenvalues of A for the eigenvector f . But since the value of m is very high, the frequency of f is very high. So estimating eigenvalues for higher modes (ie, higher values of k) is not very accurate. So, since the accuracy suffers, the value of R is not very informative with large values in this case.

Code for Problem1:

```
import numpy as np
from scipy.sparse import csc_matrix, csr_matrix, diags
from scipy.sparse.linalg import spsolve
import time
import matplotlib.pyplot as plt

def construct_1D_laplace(m):
    h = 1./m
    diagonal = 2. * np.ones(m-1)
    off_diag = -1. * np.ones(m-2)
    return (1./(h*h)) * (np.diag(diagonal, 0) + np.diag(off_diag, 1) +
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np.diag(off_diag, -1))

def sample_points_1D(m):
    h = 1./m
    x = np.linspace(h, 1-h, num=m-1)
    return x, np.zeros_like(x)

def get_rhs(x, const):
    return np.sin(const*x*x)

def compute_residual_norm(A, u, f):
    return np.linalg.norm(f - np.dot(A, u), np.inf)

def direct_solve(A, f):
    return np.linalg.solve(A, f)

def build_sparse_A(m):
    h = 1./m
    A_sparse = csc_matrix(diags([-1, 2, -1], [-1, 0, 1], shape=(m-1, m-1)))/(h**2)
    return A_sparse

def sparse_solve(A_sparse, f):
    return spsolve(A_sparse, f)

def verify_eigen_values(A):
    n = A.shape[0]
    h = 1./(n+1)
    v_num, _ = np.linalg.eig(A)
    v_num = np.sort(v_num)
    k = np.arange(1, n+1)
    v_an = (4/(h*h)) * np.sin((k*np.pi)/(2*n+2)) * np.sin((k*np.pi)/(2*n+2))
    print("Inf Norm of diff in eigenvalues for m = {} is {}".format(n+1,
np.linalg.norm(v_an-v_num, np.inf)))

m = 8
A = construct_1D_laplace(m)
verify_eigen_values(A)

ms = [1000, 2000, 4000]
rn = []
for m in ms:

```

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const = 100
A = construct_1D_laplace(m)
x, u = sample_points_1D(m)
f = get_rhs(x, const)
u_ds = direct_solve(A, f)
rn.append(np.linalg.norm(u_ds, np.inf))
print("\t h = {}, res = {}".format( 1./m, compute_residual_norm(A, u_ds, f)))

print("Convergence rate = {}".format((rn[0]-rn[1])/(rn[1]-rn[2])))

m = 10000
const = 1000
A = construct_1D_laplace(m)
x, u = sample_points_1D(m)
f = get_rhs(x, const)
start = time.time()
u_ds = direct_solve(A, f)
end = time.time() - start
print("Time taken for solve = {}".format(end))

plt.plot(x, u_ds, label='solution u')
plt.title("Solution for m = {}".format(m))
plt.ylabel("u (solution)")
plt.xlabel("x")
plt.legend()
plt.show()

m = 100000
const = 1000

A_sparse = build_sparse_A(m)
x, u = sample_points_1D(m)
f = get_rhs(x, const)

start = time.time()
u_ss = sparse_solve(A_sparse, f)
end = time.time() - start
print("Residual norm for sparse solve = {} for m = {}".format(np.linalg.norm(f-A_sparse.dot(u_ss), np.inf), m))
print("Time taken for sparse solve = {} for m = {}".format(end, m))

```