# Structural Causal Bandits with non-manipulable variables

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   A: a generalized identifiability algorithm (z²ID)
- Faster convergence: smaller arms to play; more accurate estimation.

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- Conclusions

# Motivation

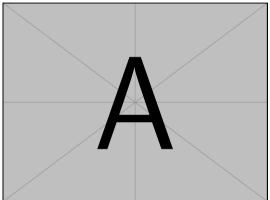
## Multi-armed bandit (MAB)

A classic, sequential decision-making problem

- Given: a set of arms (actions), A
- How: at round t, pull an arm  $A_t$ , and get a **reward**  $Y_{A_t}$
- Goal: to minimize cumulative regret (or maximize cumulative reward)
- a trade-off between exploitation vs. exploration
- Examples: ad. placement, medical treatment, packet routing ...
- Key **assumption**: arms are *independent* (in a traditional MAB setting).

# Multi-armed bandit (MAB)

The action & reward can be understood as,



#### Why?

• environments can be modeled explicitly with causal graphs decision = passive? (observation) active? (intervention, where? how?) not every variable is intervenable (figure, intervention, causal mechanism, graphs, outcome) ((what's causal about MAB?))

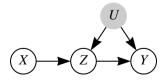
#### Structural Causal Model (SCM) $\mathcal{M} = \langle \mathbf{U}, \mathbf{V}, \mathbf{F}, P(\mathbf{U}) \rangle$ :

- U: unobserved variables
- V: observed variables
- F: a set of functions for V
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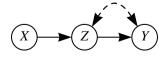


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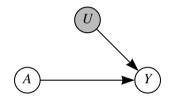
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An example with a traditional MAB problem



- a bandit algorithm plays an arm a by doing do(a),
- get a reward, e.g.,

$$Y = f(a, u) = \mu_a + u,$$

where, e.g.,  $U \sim \mathcal{N}(0, 1)$ . (with time step t implicit)

## A SCM-MAB is $\langle M, Y, \mathbf{N} \rangle$ :

- a SCM  $\mathcal{M} = \langle \mathbf{U}, \mathbf{V}, \mathbf{F}, P(\mathbf{U}) \rangle$ ,
- a reward variable  $Y \in \mathbf{V}$ ,
- non-manipulable variables  $N \subseteq V \setminus \{Y\}$

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#### Therefore,

- Actions:  $A = \{x \in \mathfrak{X}_X | X \subseteq V \setminus N \setminus \{Y\}\}\$  (including observation)
- Reward distribution:  $P(Y|do(\mathbf{X} = \mathbf{x}))$  (or  $P_{\mathbf{x}}(Y)$ )  $(\forall_{\mathbf{x} \in \mathbf{A}})$
- Expected reward:  $\mu_{\mathbf{x}} = \mathbb{E}[Y|do(\mathbf{x})]$

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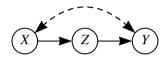
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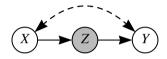
Assumption: we access to the causal graph  ${\mathcal G}$  without knowing  ${\mathbf F}$  nor  $P({\mathbf U})$ .

# **SCM-MAB** examples



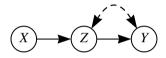
- Intervention sets:  $\emptyset$ ,  $\{X\}$ ,  $\{Z\}$ ,  $\{X,Z\}$
- Arms:  $do(\emptyset)$ , do(X = 0), do(X = 1), ..., do(X = 1, Z = 1)

# SCM-MAB examples



- Intervention sets:  $\emptyset$ ,  $\{X\}$
- Arms:  $do(\emptyset)$ , do(X = 0), do(X = 1)
- $\bullet \ \, \text{e.g., diet} \rightarrow \text{cholesterol} \rightarrow \text{health}$

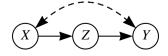
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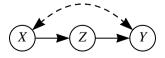
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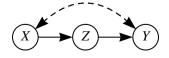


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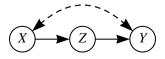
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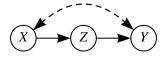
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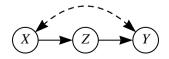
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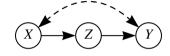
3. **Expressions**: infer one arm's reward distr. from other arms' samples.

$$P_x(y) = \sum_z P(z|x) \sum_{x'} P(y|z, x') P(x')$$



# Structural Property 1: Equivalence

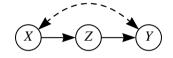
#### Consider a graph:



 $\mu_{x,z} = \mu_z$  based on Rule 3 of *do*-calculus (Pearl, 2000),  $(Y \perp \!\!\! \perp X | Z)_{\Im_{\overline{X},\overline{Z}}}$ 

# Structural Property 1: Equivalence

#### Consider a graph:



 $\mu_{x,z} = \mu_z$  based on Rule 3 of *do*-calculus (Pearl, 2000),  $(Y \perp \!\!\! \perp X | Z)_{\Im_{\overline{X,Z}}}$  Implication: play do(z) instead of do(x,z).

## Definition (Minimal Intervention Set (MIS))

Given  $\langle \mathfrak{G}, Y, \mathbf{N} \rangle$ , a set of variables  $\mathbf{X} \subseteq \mathbf{V} \setminus \{Y\} \setminus \mathbf{N}$  is said to be a *minimal* intervention set if there is no  $\mathbf{X}' \subset \mathbf{X}$  such that  $\mu_{\mathbf{x}'} = \mu_{\mathbf{x}}$  for every SCM conforming to  $\mathfrak{G}$  where  $\mathbf{x}' \in \mathfrak{X}_{\mathbf{X}'}$  that is consistent with  $\mathbf{x}$ .

\* We devised an algorithm to efficiently enumerate all MISs.

Possibly-Optimal Minimal Intervention Set Key theorem without non-manipulability constraints (soundness-and-completeness theorem goes here)  $^*$  We provided an algorithm to efficiently enumerate all POMISs given  $\mathfrak{G}, Y, \mathbf{N}$  (+ theorems).

Definition (Possibly-Optimal Minimal Intervention Set (POMIS))

Given  $\langle \mathfrak{G}, Y, \mathbf{N} \rangle$ , let  $\mathbf{X} \in \mathbb{M}_{\mathfrak{G},Y}^{\mathbf{N}}$ . If there exists a SCM conforming to  $\mathfrak{G}$  such that  $\mu_{\mathbf{x}^*} > \forall_{\mathbf{W} \in \mathbb{M}_{\mathfrak{G},Y}^{\mathbf{N}} \setminus \{\mathbf{X}\}} \mu_{\mathbf{w}^*}$ , then  $\mathbf{X}$  is a *possibly-optimal minimal intervention set* with respect to  $\langle \mathfrak{G}, Y, \mathbf{N} \rangle$ .

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Key theorem with non-manipulability constraints Latent projection here?

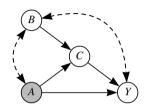
## Structural Property 3: Relating (POMISs) Arms

• Q: how are samples from  $\{do(\mathbf{z})\}_{\mathbf{Z} \in POMIS}$  related to  $do(\mathbf{x})$ ?

### Structural Property 3: Relating (POMISs) Arms

- Q: how can we express  $P_{\mathbf{x}}(\mathbf{v}')$  with  $\{P_{\mathbf{z}}\}_{\mathbf{Z} \in \mathsf{POMIS}}$ ?
- ID:  $P_{\mathbf{x}}(\mathbf{v}')$  from  $P(\mathbf{v})$  (SP, 2006)
- zID:  $P_{\mathbf{x}}(\mathbf{v}')$  from  $P_{\mathbf{z}'}(\mathbf{v})$  for  $\mathbf{Z}' \subseteq \mathbf{Z}$  (BP, 2012)
- $z^2ID$ :  $P_x(v')$  from a set of experiments (this paper)

### Structural Property 3: Relating POMISs — an example



POMISs are  $\emptyset$ ,  $\{B\}$ , and  $\{C\}$ .

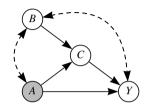
$$P(y) = \sum_{a,b,c} P_b(c|a) P_c(a,b,y)$$

$$P_b(y) = \sum_{a,c} P(c|a,b) \sum_{b'} P(y|a,b',c) P(a,b')$$

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# **SCM-MAB** algorithms

### Incorporating Structural Properties into MAB algos.

What we know,

- **POMIS**: all arms vs. possibly-optimal arms
- expressions: utilize samples from other arms

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#### What we know,

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#### Two algorithms we considered:

- Thompson sampling: posterior sample for expected reward
  - ightarrow approximate 'posterior distribution' w/ all available data.
- kI-UCB: upper bounds computed for expected reward
  - $\rightarrow$  adjust 'upper bound' by taking account samples from other arms.

### SCM-MAB algorithm: modified TS

taking advantage of **POMIS** and **z<sup>2</sup>ID**.

```
function Z^2-TS(\mathcal{G}, Y, \mathbf{N}, T)
               \mathbf{x} \leftarrow \{\mathbf{x} \in \mathfrak{X}_{\mathbf{X}} \mid \mathbf{X} \in \mathbb{Z}\}
        \hat{\boldsymbol{\theta}}_{\mathbf{x}} \leftarrow \{P_{\mathbf{x}}(y)\} \cup \{\mathsf{z}^{\mathsf{2}}\mathsf{ID}(\mathfrak{G},y,\mathbf{x},\mathbb{Z}')\}_{\mathbb{Z}'\subset\mathbb{Z}\setminus\{\mathbf{X}\}} \text{ for } \mathbf{x}\in\mathbf{A}
       \mathbf{D} \leftarrow \{D_{\mathbf{x}} = \emptyset\}_{\mathbf{x} \in \mathbf{A}}
      for t in 1, \ldots, T do
             for x \in A do
                      \hat{\theta}_{\mathbf{x}}, \hat{s}_{\mathbf{x}}^2 \leftarrow \mathsf{bMVWA}(\mathbf{D}, \hat{\boldsymbol{\theta}}_{\mathbf{x}})
                      Find \hat{\alpha}_{\mathbf{x}}, \hat{\beta}_{\mathbf{x}} such that Beta(\hat{\alpha}_{\mathbf{x}}, \hat{\beta}_{\mathbf{x}}) matching \hat{\theta}_{\mathbf{x}}, \hat{s}_{\mathbf{x}}^2
                    \theta_{\mathbf{x}} \sim \text{Beta}(\hat{\alpha}_{\mathbf{x}}, \hat{\beta}_{\mathbf{x}})
              \mathbf{x}' \leftarrow \operatorname{arg\,max}_{\mathbf{x} \in \mathbf{\Delta}} \theta_{\mathbf{x}}
              Sample v by do(\mathbf{x}') and append v to D_{\mathbf{x}'}
```

### SCM-MAB algorithm: modified kl-UCB

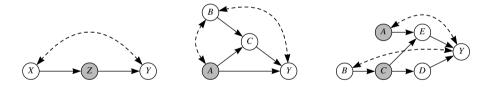
taking advantage of **POMIS** and **z<sup>2</sup>ID**.

```
function Z^2-KL-UCB(\mathcal{G}, Y, \mathbf{N}, T, f \leftarrow \ln(t) + 3\ln(\ln(t)))
      Initialize \mathbb{Z}, \mathbf{A}, \{\hat{\boldsymbol{\theta}}_{\mathbf{x}}\}_{\mathbf{x} \in \mathbf{A}}, \mathbf{D}
       (\forall_{\mathbf{x} \in \mathbf{A}}) Sample v by do(\mathbf{x}), and append v to D_{\mathbf{x}}
      for t in |\mathbf{A}|, \ldots, T do
             \hat{\theta}_{\mathbf{x}}, \hat{s}_{\mathbf{x}}^2 \leftarrow \mathsf{bMVWA}(\mathbf{D}, \hat{\boldsymbol{\theta}}_{\mathbf{x}}) \text{ for } \mathbf{x} \in \mathbf{A}
              \hat{N}_{\mathbf{x}} \leftarrow \hat{\theta}_{\mathbf{x}} (1 - \hat{\theta}_{\mathbf{x}}) / \hat{s}_{\mathbf{x}}^2; \quad \hat{t} \leftarrow \sum_{\mathbf{x}} \hat{N}_{\mathbf{x}}
           \boldsymbol{\mu} = \left\{ \sup \left\{ \mu \in [0, 1] : KL(\hat{\theta}_{\mathbf{x}}, \mu) \leq \frac{f(\hat{t})}{\hat{N}_{-}} \right\} \right\}
            \mathbf{x}' \leftarrow \operatorname{arg\,max}_{\mathbf{x} \in \mathbf{A}} \mu_{\mathbf{x}}
            Sample v by do(\mathbf{x}'), and append v to D_{\mathbf{x}'}
```

# **Empirical Evaluation**

### Experimental settings

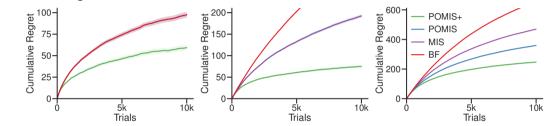
- 4 strategies: Brute-force, MIS, POMIS, POMIS+
- 2 base MAB algorithms: Thompson sampling (TS), kl-UCB
- ullet 3 SCM-MAB problems, binary  ${f V}$



1000 simulations

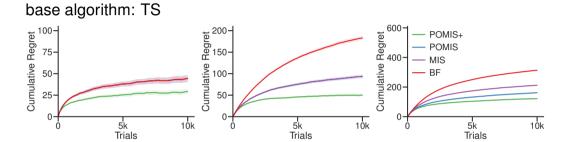
### Experimental results (average cumulative regret)





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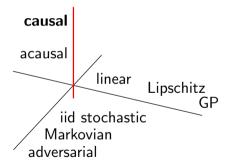


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## Conclusions

### Bandit Landscape

**Dimensions**: functional assumptions, bandit type, reward type, etc. We generalized MABs into a *causal* dimension.



**SCM-MAB**: stochastic iid reward, nonparametric, bandit feedback

### Conclusions

We studied how to take advantage of a known causal graph in bandit setting:

- introduced: SCM-MAB w/ non-manipulability constraints
- characterized: Possibly-Optimal Minimal Intervention Set (POMIS)
- devised: z<sup>2</sup>ID for connecting arms
- provided: SCM-MAB algorithms: z²-TS, z²-kl-UCB