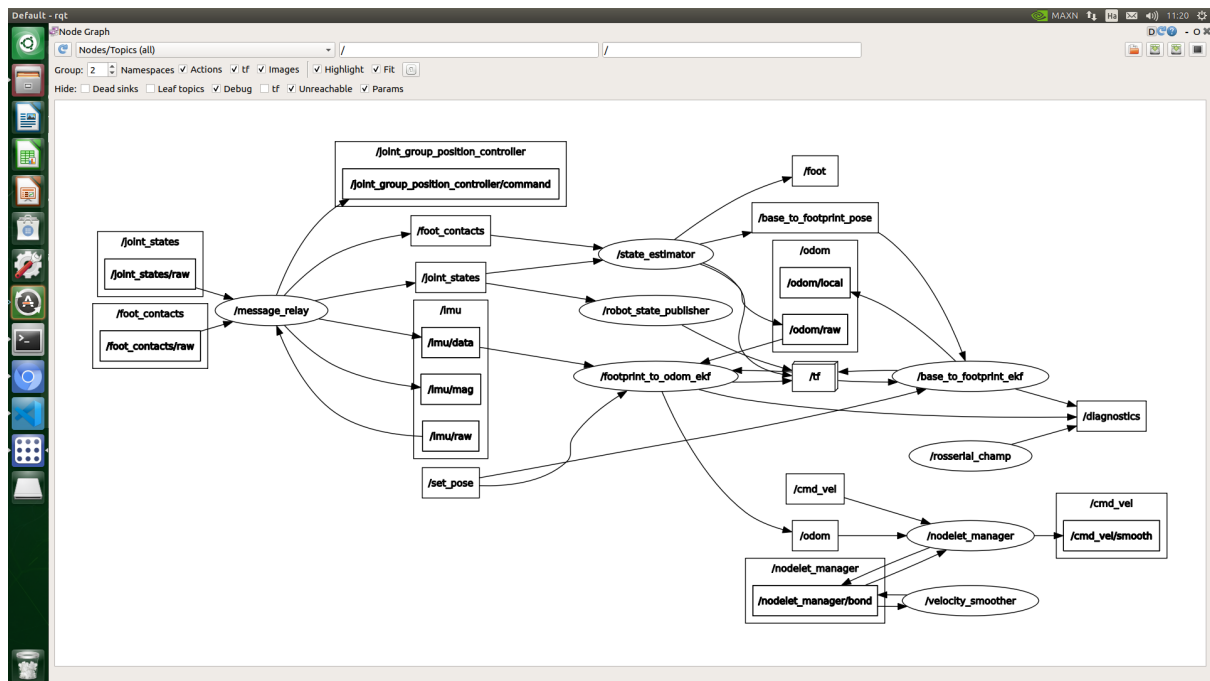
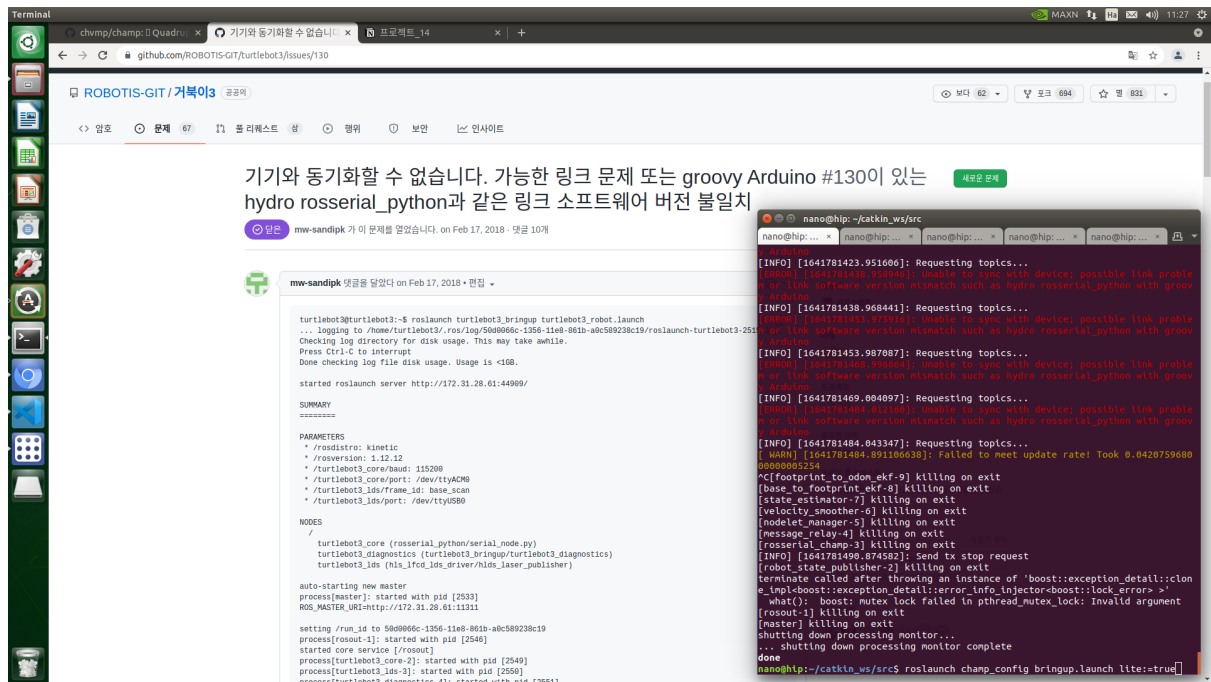


프로젝트_14

roslaunch champ_config bringup.launch lite:=true

rqt node map





catkin_make 에러 : i2cpwm config

<https://s3-us-west-2.amazonaws.com/secure.notion-static.com/af5c004d-ea45-41a1-9c0a-a56e19861044/ros-i2cpwmboard-master.zip>