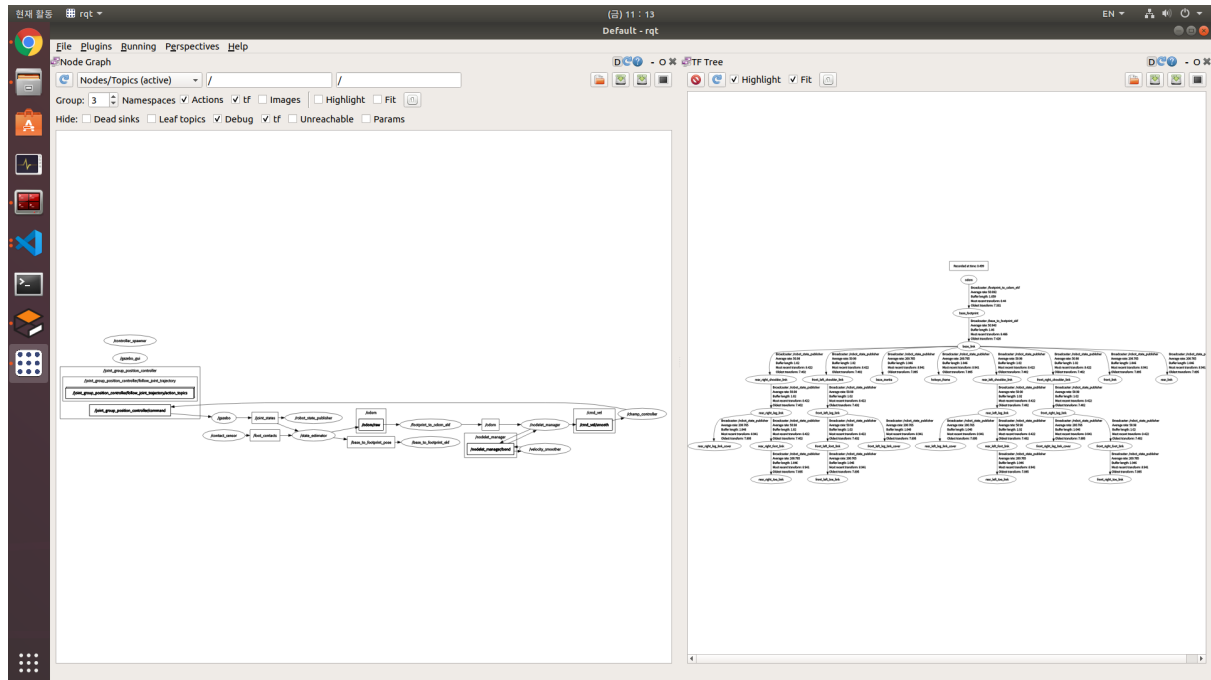
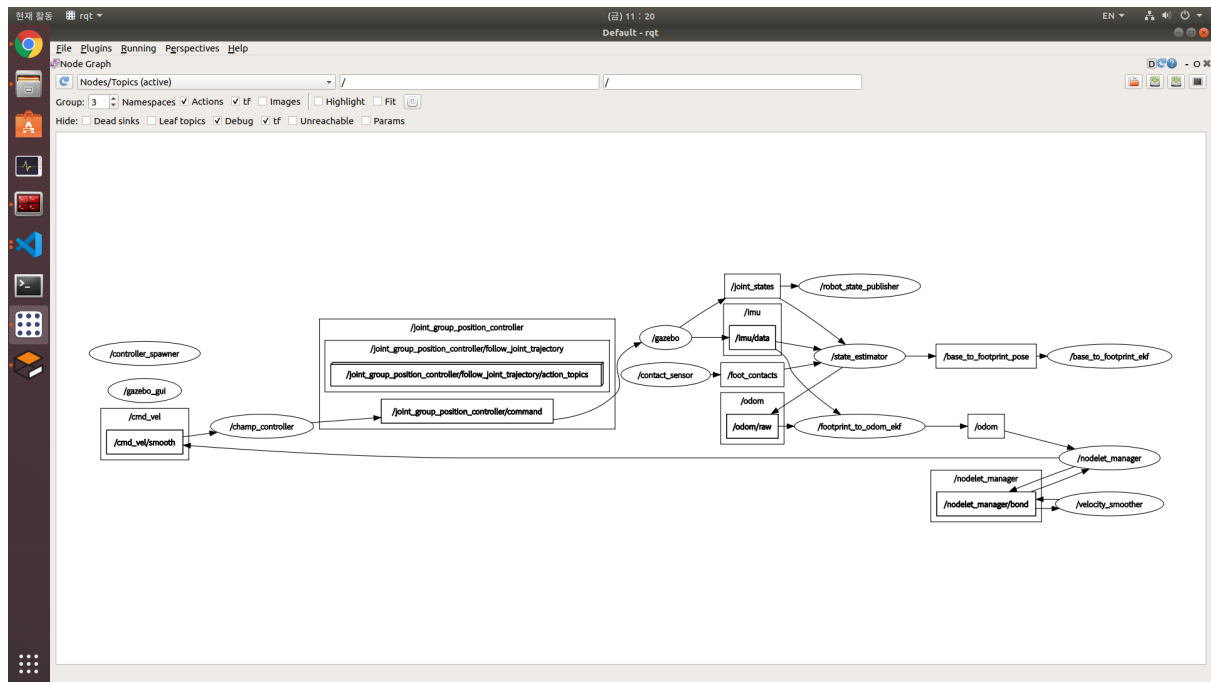


프로젝트_18

joint_group_controller 적용 추가

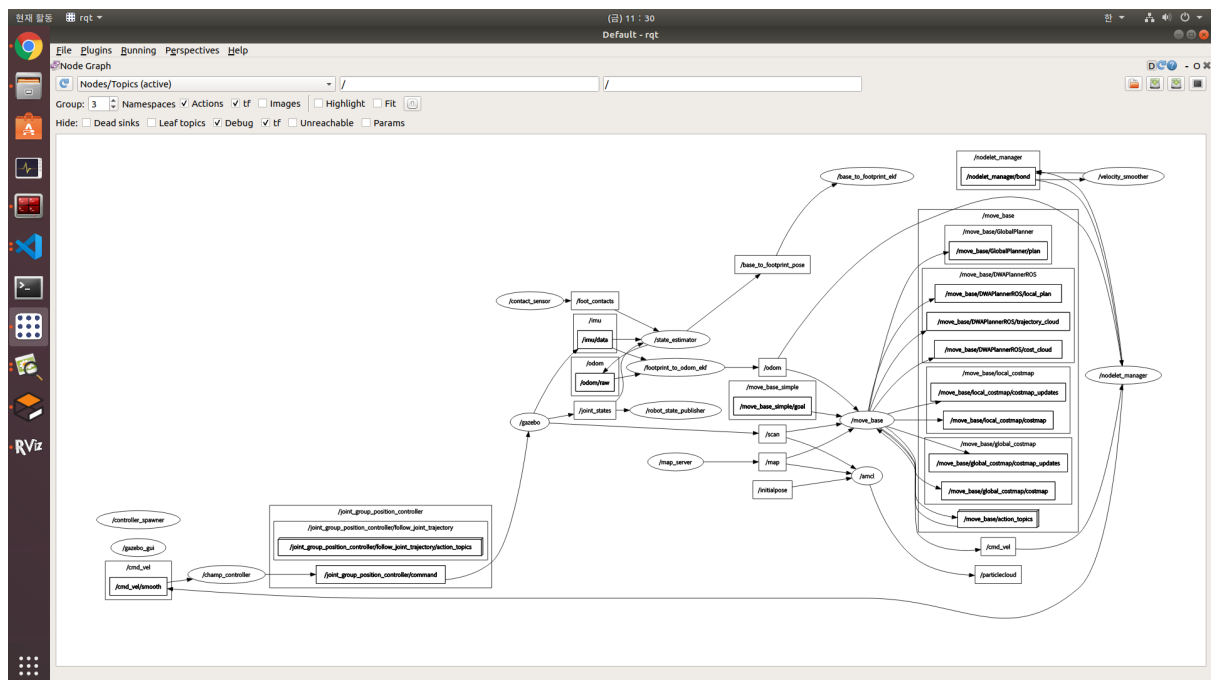


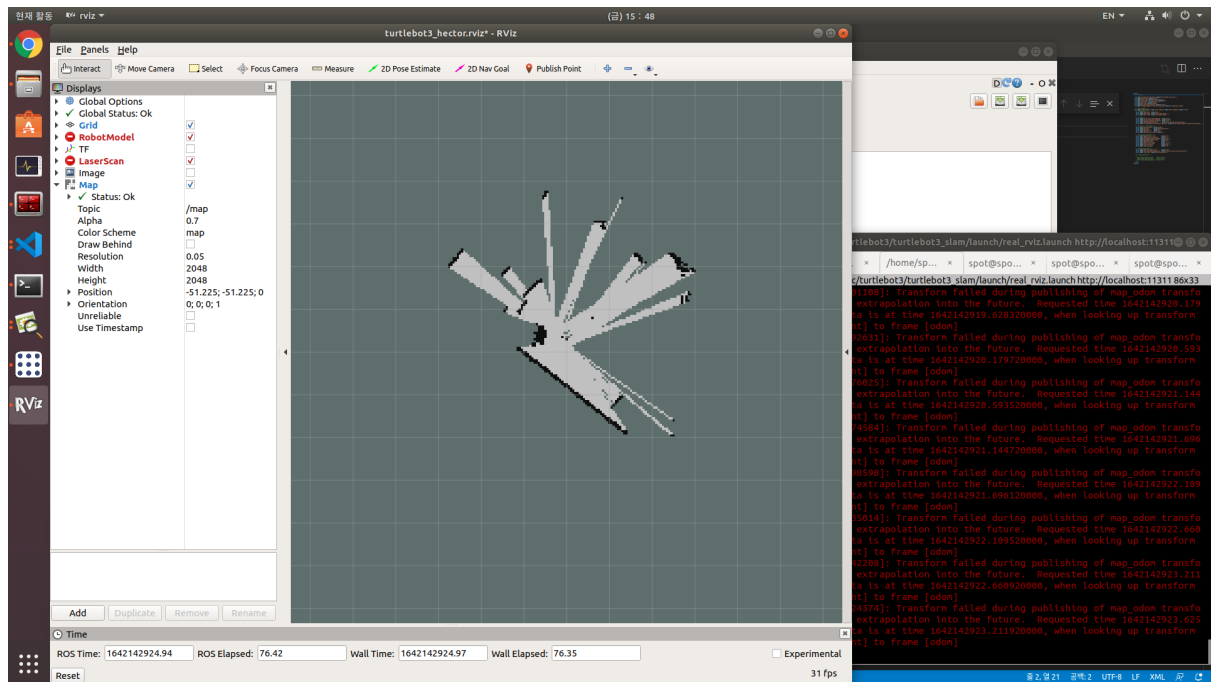
imu 적용 추가



champ와 spotmicro

rqt map





실제 4족보행로봇으로 정확하게 매핑하는것은 오래걸리고 투자해야할 시간이 많을거 같아
다른 팀과 협업으로 가상환경에서 매핑논의

https://github.com/zlingkang/hd_servo