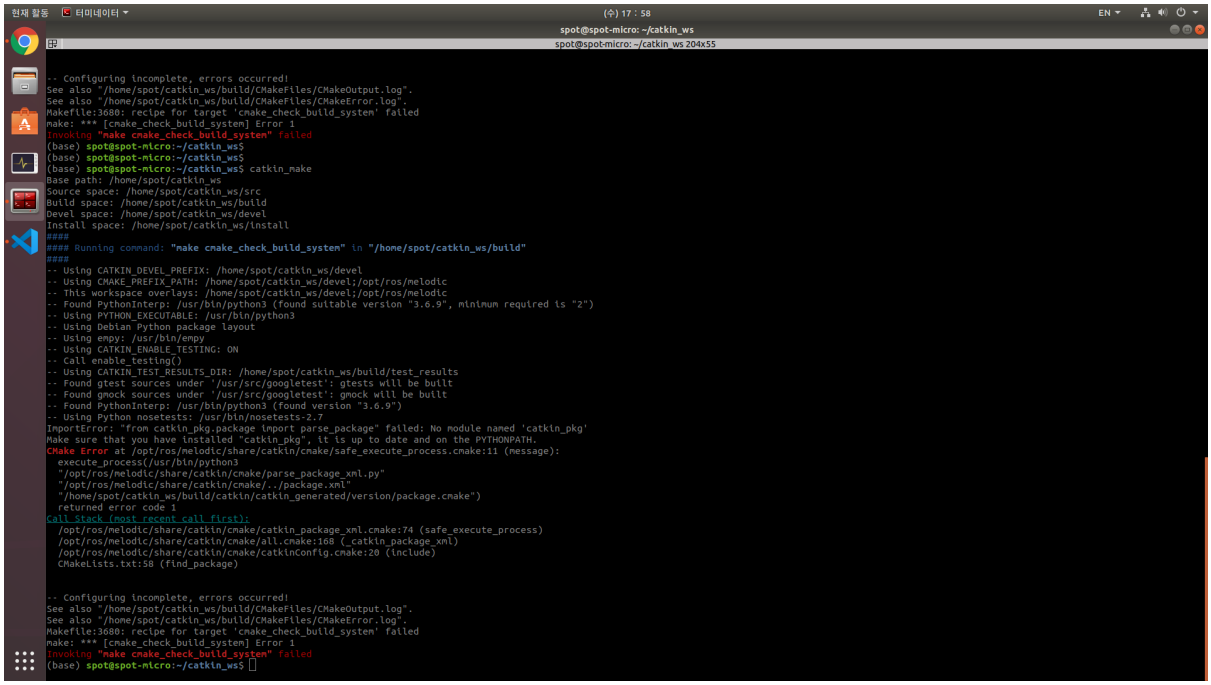
프로젝트_8



오류 해결 : 작업폴더 재생성

로봇 구조 파악진행중

https://s3-us-west-2.amazonaws.com/secure.notion-static.com/b1b5f951-4b59-4ee3-8022-521fe4dbc227/spotmicro.xacro

https://s3-us-west-2.amazonaws.com/secure.notion-static.com/13641f5a-58ea-46e5-b423-64acab6e5897/spotmicro2.xacro

---

조립 과정중 jetson nano보드 자체 문제발생(40pin 입력X)

※jetson nano에 ros-melodic 설치하기

과정중 문제

“sudo apt --fix-broken install” 에러

apt사용 X

cd /var/lib/dpkg/info/ 이동

sudo rm -r [해당 패키지].* 삭제

sudo apt clean

sudo apt update

“sudo apt --fix-broken install” 로 수정

ros 설치 다시 시작

※jetson nano에 netplan 사용하여 고정ip설정

sudo apt-get install netplan.io

sudo vi /etc/netplan/config.yaml 만들기

(gateway 확인 : route)

(gateway 확인 : netstat -nr)

(주소 확인 : hostname - I)

유선

```
network:
  version: 2
  renderer: networkd
  ethernets:
    enp6s0:
    addresses:
      - ???.???.???.???/24
    gateway4: ???.???.???.???
```

```
    nameservers:
        addresses: [8.8.8.8.1,8.8.4.4]
```

와이파이

```
network:
  version: 2
  renderer: networkd
  wifis:
    wlp2s0:
      dhcp4: yes
      access-points:
        "network_ssid_name":
        password: "**********"
```

dhcp 방식

```
network:
  version: 2
  renderer: networkd
    ethernets:
      enp6s0:
        dhcp4: yes
        dhcp6: yes
```

```
sudo netplan apply
```
