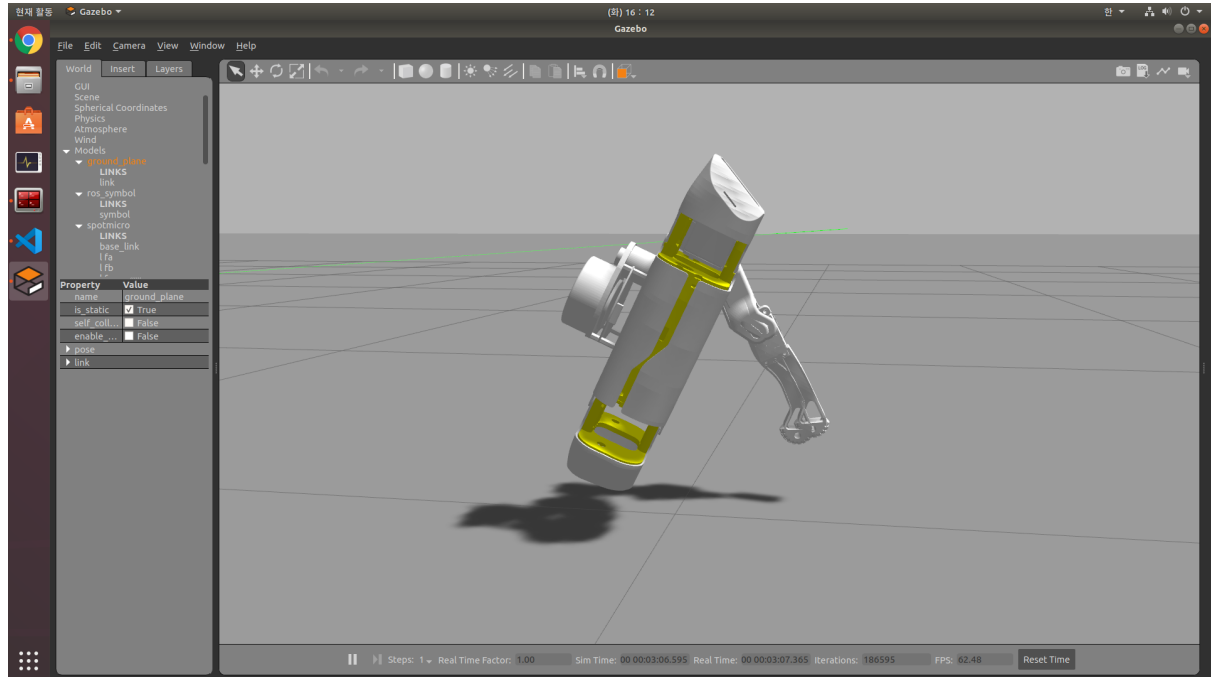
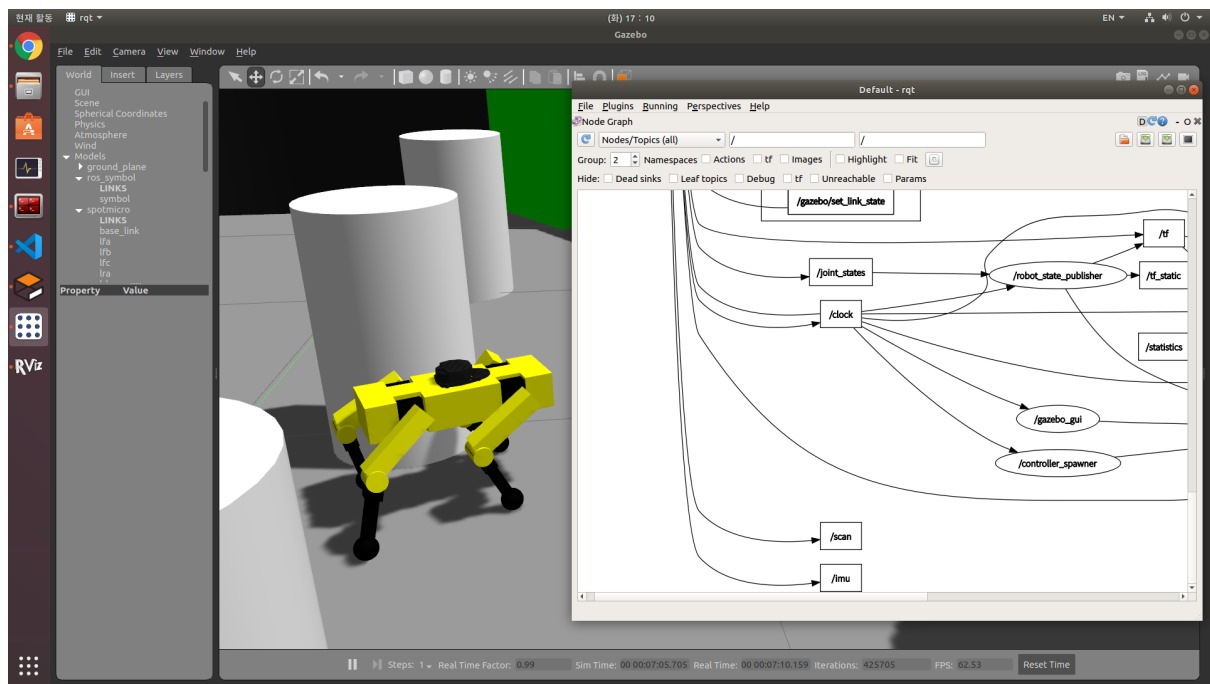


프로젝트_10

퀄리티 높은 모델 중지



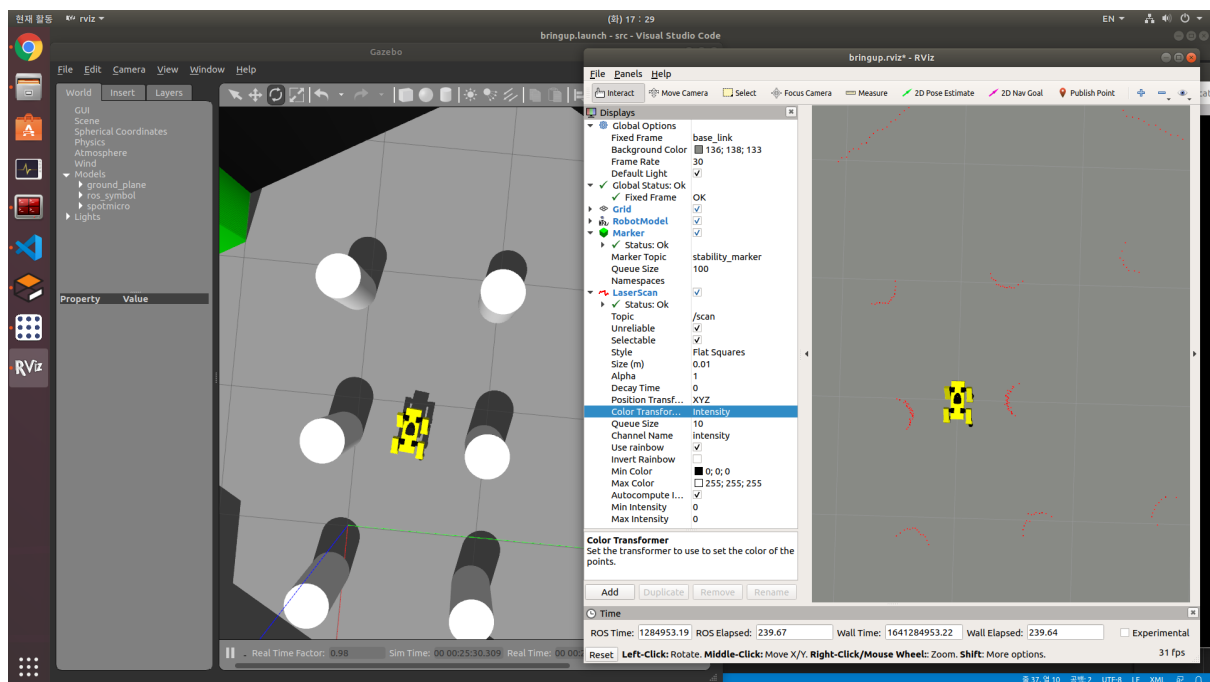
controller 가능한 모델에 라이다센서 장착



정상작동

roslaunch spotmicro bringup.launch mode:=sim gait:=walk (gazebo 가상환경)

roslaunch spotmicro bringup.launch mode:=rviz gait:=walk (rviz)



약간의 parameter 조정, imu센서

https://s3-us-west-2.amazonaws.com/secure.notion-static.com/b34812bc-d09d-415b-98ac-3f37469d22f6/스크린샷_2022년_01월_04일_17시_55분_26초.webm