

### exercise 1.1.1.

Consider the initial value problem for the equation

$$u_t + a u_x = f(t, x)$$

with  $u(0, x) = 0$  and

$$f(t, x) = \begin{cases} 1 & x \geq 0 \\ 0 & \text{otherwise.} \end{cases}$$

Assume that  $a$  is positive. Show that the solution is

$$u(t, x) = \begin{cases} 0 & x \leq 0 \\ x/a & x \geq 0 \text{ \& } x - at \leq 0 \\ t & x \geq 0 \text{ \& } x - at \geq 0 \end{cases}$$

*proof*) Change of variables that

$$\begin{cases} t = \tau \\ \xi = x - at \end{cases} \Rightarrow \begin{cases} u(t, x) = \tilde{u}(\tau, \xi) \\ u(0, x) = \tilde{u}(0, \xi) = 0 \end{cases}$$

$$\frac{\partial \tilde{u}}{\partial \tau} = \frac{\partial u}{\partial t} \frac{\partial t}{\partial \tau} + \frac{\partial u}{\partial x} \frac{\partial x}{\partial \tau} = u_t(1) + u_x(a) = f(t, x)$$

$$\Rightarrow \frac{\partial \tilde{u}}{\partial \tau} = f(\tau, \xi + a\tau)$$

$$\Rightarrow \int_0^\tau \frac{\partial \tilde{u}}{\partial \sigma} d\sigma = \int_0^\tau f(\sigma, \xi + a\sigma) d\sigma$$

$$\Rightarrow \tilde{u}(\tau, \xi) - \tilde{u}(0, \xi) = \int_0^\tau f(\sigma, \xi + a\sigma) d\sigma$$

$$\circ \circ \tilde{u}(\tau, \xi) = \int_0^\tau f(\sigma, \xi + a\sigma) d\sigma$$

$$\Rightarrow u(t, x) = \int_0^t f(s, x - at + as) ds$$

We know that  $a, s \geq 0$  &  $0 \leq s \leq t$ .

①  $x \leq 0$  :  $f = 0 \Rightarrow u = 0$ .

②  $x \geq 0$  &  $x - at \leq 0$  :

Let  $x^* = x - at + as$ , & assume that  $x^* \leq 0$ . Then

$$x^* \leq 0 \Leftrightarrow 0 \leq s \leq t - \frac{x}{a}. \quad (f(s, x^*) = 0)$$

If  $x^* \geq 0$ , then

$$t - \frac{x}{a} \leq s \leq t. \quad (f(s, x^*) = 1)$$

$$\begin{aligned} u(t, x) &= \int_0^t f(s, x^*) ds = \int_0^{t - \frac{x}{a}} f ds + \int_{t - \frac{x}{a}}^t f ds \\ &= 0 + t - t + \frac{x}{a} = \frac{x}{a}. \end{aligned}$$

③  $x \geq 0$  &  $x - at \geq 0$  :

$$x - at \geq 0 \Rightarrow x - at + as = x^* \geq 0 \quad (\because as \geq 0)$$

$$u(t, x) = \int_0^t f(s, x^*) ds = \int_0^t 1 ds = t.$$

By ①, ②, ③,

$$u(t, x) = \begin{cases} 0 & x \leq 0 \\ x/a & x \geq 0 \text{ \& } x - at \leq 0 \\ t & x \geq 0 \text{ \& } x - at \geq 0 \end{cases}$$



### exercise 1.2.1.

Consider the system  $(*)$  :

$$\begin{bmatrix} u' \\ u^2 \end{bmatrix}_t + \begin{bmatrix} a & b \\ b & a \end{bmatrix} \begin{bmatrix} u' \\ u^2 \end{bmatrix}_x = \vec{0}, \quad a=0 \text{ \& } b=1 \text{ on } [0, 1]$$

with B.C :  $u'(x, 0) = 0$ ,  $u'(x, 1) = 1$

with I.C :  $u'(0, x) = x$ ,  $u^2(0, x) = 1$ .

Then, the solution is  $u'(x, x) = x$  and  $u^2(x, x) = 1 - x$  for all  $(x, x)$  with  $0 \leq x \leq 1$ ,  $0 \leq x$ .

**proof)** Since the system is hyperbolic form,

$A := \begin{bmatrix} a & b \\ b & a \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  is diagonalizable by definition.

$$\det(A - \lambda I) = \lambda^2 - 1 = 0 \Rightarrow \lambda = \pm 1.$$

$$\lambda = 1 \Rightarrow \vec{v}_1 = (1, 1)^T, \quad \lambda = -1 \Rightarrow \vec{v}_2 = (-1, 1)^T.$$

$$\therefore P = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}, \quad P^{-1} = \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} \text{ such that}$$

$$\Lambda := PAP^{-1} : \text{diagonal matrix.}$$

Note that  $\begin{cases} \lambda_i \equiv \text{diagonal elements of } \Lambda \\ \equiv \text{characteristic speed of } u^i \end{cases}$

$$(*) \Rightarrow P \vec{u}_t + PA \vec{u}_x = \vec{0} \Rightarrow P \vec{u}_t + \Lambda P \vec{u}_x = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} u' \\ u^2 \end{bmatrix}_t + \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} u' \\ u^2 \end{bmatrix}_x = \vec{0}$$

$$\Rightarrow \begin{bmatrix} u' - u^2 \\ u' + u^2 \end{bmatrix}_t + \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u' - u^2 \\ u' + u^2 \end{bmatrix}_x = \vec{0}$$

Let  $w^1 = u^1 - u^2$  &  $w^2 = u^1 + u^2$ . Since  $\lambda_i$  are the characteristic speed of  $w^i$ , we can define

$$\xi_1 = x + t \quad \& \quad \xi_2 = x - t.$$

Now, the system is

$$w_t^1 - w_x^2 = 0 \quad \& \quad w_t^1 + w_x^2 = 0$$

with I.C :  $w^1(0, x) = u^1(0, x) - u^2(0, x) = x - 1$

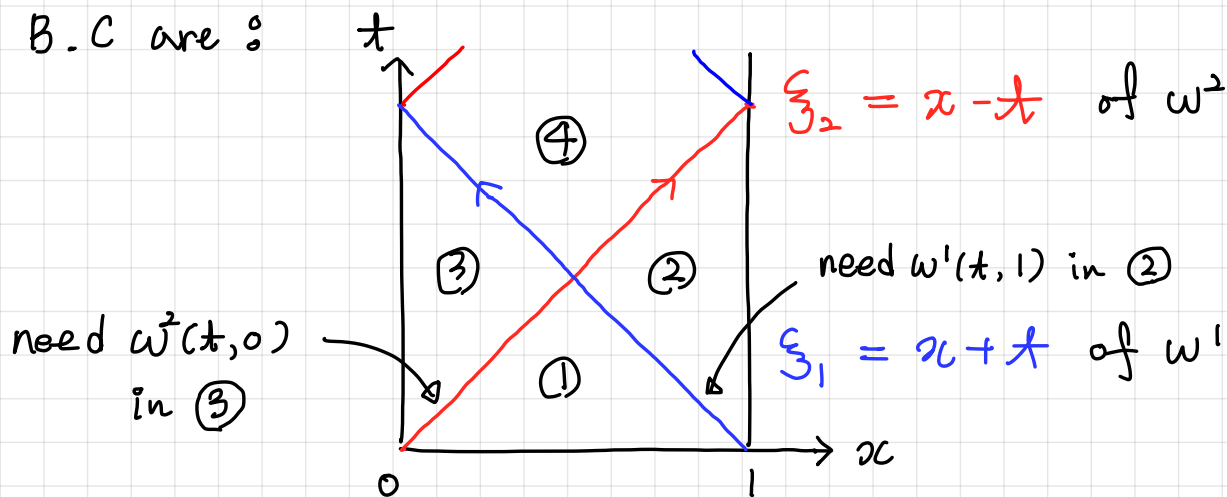
$$w^2(0, x) = u^1(0, x) + u^2(0, x) = x + 1$$

with B.C :  $w^2(t, 0) = u^1 + u^2 = u^1 + u^1 - w^1$   
 $= 2u^1(t, 0) - w^1(t, 0) = -w^1(t, 0)$

$$w^1(t, 1) = u^1 - u^2 = u^1 - w^2 + u^1$$

$$= 2u^1 - w^2 = 2 - w^2(t, 1)$$

( $\therefore$  B.C are :



$$\left\{ \begin{array}{l} \xi_2 \text{ need boundary : } w^1(t, 1) \leftrightarrow w^2(t, 1) \\ \xi_1 \text{ need boundary : } w^2(t, 0) \leftrightarrow w^1(t, 0) \end{array} \right.$$

~ 영역은 먼저 고려한 후 필요한 B.C. 에 대한 계산.

④ : ①, ②, ③ 에서 구한 값으로 일반화 가능하므로 제외. )

① : Both (solutions) are determined I.C.

$$\omega^1(t, x) = \omega^1(0, x+t) = x+t-1$$

$$\omega^2(t, x) = \omega^2(0, x-t) = x-t+1$$

$$\Rightarrow u^1(t, x) = \frac{\omega^1(t, x) + \omega^2(t, x)}{2} = x$$

$$u^2(t, x) = -\frac{\omega^1(t, x) - \omega^2(t, x)}{2} = 1-t$$

} inverse relation.

② :  $\omega^2$  determined by ①. But  $\omega^1$  need B.C at  $x=1$ .

$$\omega^1(t, 1) = 2 - \omega^2(t, 1) = t \quad (\because \omega^2(t, x) = x-t+1 \text{ by ①})$$

$$\therefore \omega^1(t, x) = \omega^1(\overset{(1)}{x+t-1}, 1) = x+t-1$$

$$\Rightarrow u^1(t, x) = \frac{\omega^1(t, x) + \omega^2(t, x)}{2} = x$$

$$u^2(t, x) = -\frac{\omega^1(t, x) - \omega^2(t, x)}{2} = 1-t$$

③ :  $\omega^1$  determined by ①. But  $\omega^2$  need B.C at  $x=0$ .

$$\omega^2(t, 0) = -\omega^1(t, 0) = 1-t \quad (\because \omega^1(t, x) = x+t-1 \text{ by ①})$$

$$\therefore \omega^2(t, x) = \omega^2(\overset{(2)}{x-t}, 0) = 1-t+x$$

$$\Rightarrow u^1(t, x) = \frac{\omega^1(t, x) + \omega^2(t, x)}{2} = x$$

$$u^2(t, x) = -\frac{\omega^1(t, x) - \omega^2(t, x)}{2} = 1-t$$

By ①, ②, ③, we obtain the solution of  $u^1, u^2$  :

$$u^1(t, x) = x, \quad u^2(t, x) = 1-t.$$



### In exercise (1.1.1)

$u_t + au_x + bu = f(t, x)$  : general hyperbolic eq.

with initial condition  $u(0, x) = u_0(x)$ ,  $a, b$  : constant.

→ PDE to ODE using a change of variable.

Let  $\tau = t$ ,  $\xi = x - at \iff t = \tau, x = \xi + a\tau$ .

( $\because$ ) the solution at  $(t, x)$  depends only on the value of  $\xi = x - at$  : "characteristic curve"

Then,  $u(t, x) = \tilde{u}(t, x)$  ( $\because \sim$  : need to distinguish)

$$\begin{aligned}\text{Since } \frac{\partial \tilde{u}}{\partial \tau} &= \frac{\partial u}{\partial t} \frac{\partial t}{\partial \tau} + \frac{\partial u}{\partial x} \frac{\partial x}{\partial \tau} = u_t + au_x \\ &= -bu + f(\tau, \xi + a\tau),\end{aligned}$$

$$\therefore \frac{\partial \tilde{u}}{\partial \tau} = -b\tilde{u} + f(\tau, \xi + a\tau) \iff \tilde{u}' + b\tilde{u} = f$$

integrating factor  $\lambda = e^{\int b \, d\tau} = e^{b\tau}$ .

$$\Rightarrow \frac{\partial \tilde{u}}{\partial \tau} e^{b\tau} + b\tilde{u} e^{b\tau} = f(\tau, \xi + a\tau) e^{b\tau}$$

$$\Rightarrow \frac{\partial}{\partial \tau} \{ e^{b\tau} \tilde{u} \} = f(\tau, \xi + a\tau) e^{b\tau} \quad (\because \text{곱의 미분법})$$

$\tau$ 에 대한  $f$  적분을 하기 위해 정적분  $0 \sim \tau$  을 취하면,

$$\int_0^\tau \frac{\partial}{\partial \sigma} \{ e^{b\sigma} \tilde{u} \} \, d\sigma = e^{b\tau} \tilde{u}(\tau, \xi) - \tilde{u}(0, \xi)$$

$$= e^{b\tau} \tilde{u}(\tau, \xi) - u_0(\xi)$$

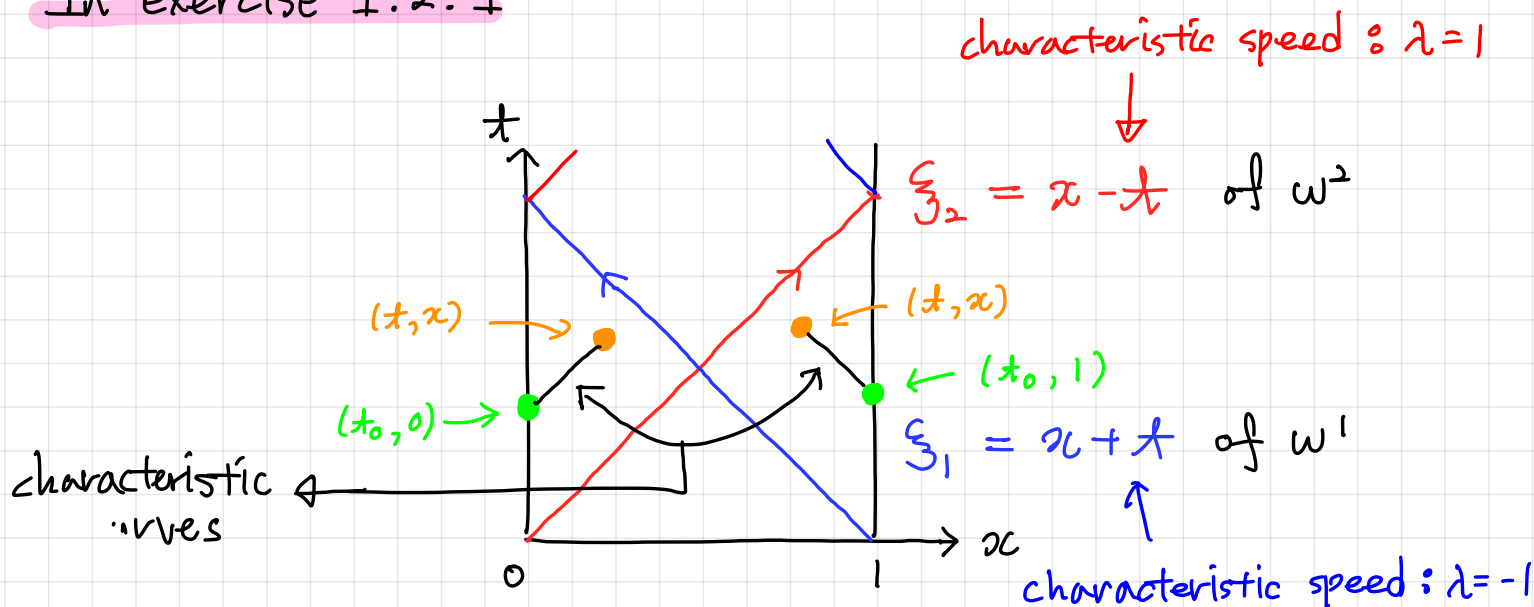
$$= \int_0^\tau f(\sigma, \xi + a\sigma) e^{b\sigma} \, d\sigma$$

$$\Rightarrow \tilde{u}(\tau, \xi) = u_0(\xi) e^{-b\tau} + e^{-b\tau} \int_0^\tau f(\sigma, \xi + a\sigma) e^{b\sigma} \, d\sigma$$

put it

$$\therefore u(t, x) = u_0(x) e^{-bt} + \int_0^t f(s, x - at + as) e^{b(s-t)} \, ds.$$

## In exercise 1.2.1



$$(2) : w^1(t, x) = w^1(\underbrace{x + t - 1}_{(1)}, 1) = x + t - 1$$

$$(3) : w^2(t, x) = w^2(\underbrace{x - t}_{(2)}, 0) = 1 - t + x$$

“Considering extending to the interior along the characteristics.”

(1) in (2), the relationship of  $\lambda = -1$  is :

$$\frac{x - 1}{t - t_0} = -1 \Leftrightarrow t_0 = x + t - 1$$

(2) in (3), the relationship of  $\lambda = 1$  is :

$$\frac{x - 0}{t - t_0} = 1 \Leftrightarrow t_0 = t - x$$

$$* \text{ speed} = \frac{\text{distance}}{\text{time}} = \frac{dx}{dt} = a$$

### exercise 1.4.1.

Show that the FTCS scheme :

$$\frac{v_m^{n+1} - v_m^n}{\kappa} + a \frac{v_{m+1}^n - v_{m-1}^n}{2h} = 0$$

is consistent with equation  $u_t + au_x = 0$ .

**proof)** Let  $P = \frac{\partial}{\partial t} + a \frac{\partial}{\partial x}$ , then  $u_t + au_x = Pu = 0$ .

Define  $\phi(x, t)$  is smooth function such that

$P\phi = \phi_t + a\phi_x$ . Then, the difference operator

$P_{\kappa, h}$  is given as follows.

$$P_{\kappa, h} \phi = \frac{\phi_m^{n+1} - \phi_m^n}{\kappa} + a \frac{\phi_{m+1}^n - \phi_{m-1}^n}{2h}$$

Using the Taylor series, we obtain

$$\phi_m^{n+1} = \phi_m^n + \phi_t \kappa + \frac{\phi_{tt}}{2} \kappa^2 + O(\kappa^3)$$

$$\phi_{m\pm 1}^n = \phi_m^n \pm \phi_x h + \frac{\phi_{xx}}{2} h^2 \pm O(h^3)$$

$$\begin{aligned} P_{\kappa, h} \phi &= \phi_t + \frac{\kappa}{2} \phi_{tt} + O(\kappa^3) + a/2h (2h\phi_x + O(h^3)) \\ &= \phi_t + a\phi_x + \frac{\kappa}{2} \phi_{tt} + O(\kappa^3 + h^3) \end{aligned}$$

$$\Rightarrow P\phi - P_{\kappa, h} \phi = \frac{\kappa}{2} \phi_{tt} + O(\kappa^3 + h^3)$$

$$P\phi - P_{\kappa, h} \phi \rightarrow 0 \text{ as } (\kappa, h) \rightarrow 0$$

$\therefore$  This scheme is consistent. □



### exercise 1.4.2.

Show that the leapfrog scheme :

$$\frac{v_m^{n+1} - v_m^{n-1}}{2\kappa} + a \frac{v_{m+1}^n - v_{m-1}^n}{2h} = 0$$

is consistent with equation  $u_t + au_x = 0$

**proof)**  $u_t + au_x = 0 \iff Pu = 0$ ,  $P = \frac{\partial}{\partial t} + a \frac{\partial}{\partial x}$ .

Define  $\phi$  : smooth fn s.t.  $P\phi = \phi_t + a\phi_x$ .

$$P_{\kappa,h}\phi = \frac{\phi_m^{n+1} - \phi_m^{n-1}}{2\kappa} + a \frac{\phi_{m+1}^n - \phi_{m-1}^n}{2h} = 0$$

Using Taylor series of  $\phi$ , we obtain

$$\phi_m^{n\pm 1} = \phi_m^n \pm \kappa \phi_t + \frac{\kappa^2}{2} \phi_{tt} \pm \frac{\kappa^3}{3!} \phi_{ttt} + O(\kappa^4)$$

$$\phi_{m\pm 1}^n = \phi_m^n \pm h \phi_x + \frac{h^2}{2} \phi_{xx} \pm \frac{h^3}{3!} \phi_{xxx} + O(h^4)$$

$$\begin{aligned} \Rightarrow P_{\kappa,h}\phi &= \phi_t + \frac{\kappa^2}{6} \phi_{ttt} + O(\kappa^4) + \\ &\quad a \phi_x + \frac{h^2}{6} \phi_{xxx} + O(h^4) \\ &= \phi_t + a \phi_x + \frac{1}{6} (\kappa^2 \phi_{ttt} + h^2 \phi_{xxx}) + O(\kappa^4 + h^4) \end{aligned}$$

$$P\phi - P_{\kappa,h}\phi = \frac{1}{6} (\kappa^2 \phi_{ttt} + h^2 \phi_{xxx}) + O(\kappa^4 + h^4)$$

$$P\phi - P_{\kappa,h}\phi \rightarrow 0 \text{ as } (\kappa, h) \rightarrow 0.$$

$\therefore$  This scheme is consistent. □

#### exercise 2.1.4.

show that the initial value problem for the equation  $u_t = u_{xxx}$  is well-posed.

*proof*) Note that Fourier transform of  $u(x)$  is

$$\hat{u}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-i\omega x} u(x) dx \quad (*)$$

Fourier inversion formula of  $\hat{u}(\omega)$  is

$$u(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i\omega x} \hat{u}(\omega) d\omega \quad (**)$$

$$\Rightarrow \frac{\partial u}{\partial x} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i\omega x} i\omega \hat{u}(\omega) d\omega \quad \text{by } (**)$$

$$\Rightarrow \frac{\partial \hat{u}}{\partial x} = i\omega \hat{u}(\omega) \quad \text{by } (*)$$

$$\Rightarrow u_{xxx} = (i\omega)^3 \hat{u}(\omega) = -i\omega^3 \hat{u}(\omega) = \hat{u}_t$$

By Parseval's relation, (PR)

$$\int_{-\infty}^{\infty} |u(t, x)|^2 dx = \int_{-\infty}^{\infty} |\hat{u}(t, \omega)|^2 d\omega \quad \leftarrow \text{PR}$$

$$\hat{u}(t, \omega) = e^{-i\omega^3 t} \hat{u}_0(\omega) \rightarrow \int_{-\infty}^{\infty} |e^{-i\omega^3 t} \hat{u}_0(\omega)|^2 d\omega$$

$$|e^{i\theta}| = 1 \rightarrow \int_{-\infty}^{\infty} |\hat{u}_0(\omega)|^2 d\omega$$

$$= \int_{-\infty}^{\infty} |u_0(x)|^2 dx \quad \leftarrow \text{PR}$$

Let  $G_T = 1$ , then, the equation  $u_t = u_{xxx}$  is well-posed.



### exercise 2.1.5.

show that the initial value problem for the equation  $u_t + u u_x + b u = 0$  is well-posed.

**proof)** Using Fourier transform of  $u$  & its inversion formula, we obtain

$$\frac{\partial \hat{u}}{\partial x} = i\omega \hat{u}(\omega) \Rightarrow \hat{u}_t = -i\omega \hat{u}(\omega) - b \hat{u}(\omega) \\ = -(i\omega + b) \hat{u}(\omega).$$

Then, the solution is,

$$\hat{u}(t, \omega) = e^{-(i\omega + b)t} \hat{u}_0(\omega).$$

By Parseval's relation, then

$$\begin{aligned} \int_{-\infty}^{\infty} |u(t, x)|^2 dx &= \int_{-\infty}^{\infty} |\hat{u}(t, \omega)|^2 d\omega \\ &= e^{-bt} \int_{-\infty}^{\infty} |e^{-i\omega t} \hat{u}_0(\omega)|^2 d\omega \\ &= e^{-bt} \int_{-\infty}^{\infty} |\hat{u}_0(\omega)|^2 d\omega \\ &= e^{-bt} \int_{-\infty}^{\infty} |u_0(x)|^2 dx \end{aligned}$$

Let  $G_T = e^{-bT}$ , then, the equation is well-posed. □

### exercise 2.2.1.

Show that the BTCS scheme

$$\frac{v_m^{n+1} - v_m^n}{\kappa} + a \frac{v_{m+1}^{n+1} - v_{m-1}^{n+1}}{2h} = 0$$

is consistent with  $u_t + a u_x = 0$  & is unconditionally stable.

proof) ① Consistency

Let  $\phi$  be a smooth function that

$P\phi = \phi_t + a\phi_x$  where  $P = \frac{\partial}{\partial t} + a\frac{\partial}{\partial x}$ , and

the difference operator  $P_{\kappa,h}$  that

$$P_{\kappa,h}\phi = \frac{\phi_m^{n+1} - \phi_m^n}{\kappa} + a \frac{\phi_{m+1}^{n+1} - \phi_{m-1}^{n+1}}{2h}.$$

Then, using Taylor series of  $\phi$ ,

$$\phi_m^{n+1} = \phi_m^n + \kappa \phi_t + \frac{\kappa^2}{2} \phi_{tt} + \frac{\kappa^3}{6} \phi_{ttt} + O(\kappa^4)$$

$$\phi_{m\pm 1}^{n+1} = \phi_m^n \pm h \phi_x + \frac{h^2}{2} \phi_{xx} \pm \frac{h^3}{6} \phi_{xxx} + O(h^4)$$

$$\Rightarrow P_{\kappa,h}\phi = \phi_t + \frac{\kappa}{2} \phi_{tt} + \frac{\kappa^2}{6} \phi_{ttt} + O(\kappa^4) \\ + a\phi_x + \frac{h^2}{6} \phi_{xxx} + O(h^4)$$

$$\Rightarrow P\phi - P_{\kappa,h}\phi = \frac{\kappa}{2} \phi_{tt} + \frac{1}{6} (\kappa^2 \phi_{ttt} + h^2 \phi_{xxx}) + O(\kappa^4 + h^4)$$

$$P\phi - P_{\kappa,h}\phi \rightarrow 0 \text{ as } \kappa, h \rightarrow 0$$

$\therefore$  this scheme is consistent.

② unconditionally stable.

Let  $v_m^n = g^n e^{i m \theta}$ , then the scheme is

$$\frac{g^{n+1} e^{i m \theta} - g^n e^{i m \theta}}{\kappa} + \frac{g^{n+1} e^{i(m+1)\theta} - g^{n+1} e^{i(m-1)\theta}}{2h} = 0$$

$$\Rightarrow g^n e^{in\theta} \left\{ \frac{g-1}{\kappa} + a \frac{g e^{i\theta} - g e^{-i\theta}}{2h} \right\} = 0$$

$$\Rightarrow g-1 + \frac{ak}{2h} (g e^{i\theta} - g e^{-i\theta})$$

$$= g-1 + \frac{ak}{2h} g (\cos\theta + i\sin\theta - \cos\theta + i\sin\theta)$$

$$= g \left( \frac{ak}{2h} (2i\sin\theta) + 1 \right) - 1 = 0, \quad \lambda = \frac{k}{h},$$

$$\Rightarrow g(\theta) = \frac{1}{\lambda i \sin\theta}. \Rightarrow |g(\theta)| \leq 1 \text{ clearly.}$$

∴ this scheme is stable. (unconditionally)

Note) Lax-equivalence theorem (linear PDE)

Consistency & Stability  $\Leftrightarrow$  Convergence.

↑  
Taylor expansion

↑  
Property of numerical scheme



## The Lax - Wendroff Scheme

→ second - order accuracy scheme.

For inhomogeneous equation  $u_t + a u_x = f$ ,

using Taylor series in time for  $u(t+k, x)$ , then

$$\left\{ u(t+k, x) = u(t, x) + k u_t(t, x) + \frac{k^2}{2} u_{tt}(t, x) + O(k^3) \right\}$$

Since  $u_t = -a u_x + f$ ,  $u_{tt} = -a u_{xt} + f_t = -a u_{tx} + f_t$ .

$$u_{tx} = (u_t)_x = (-a u_x + f)_x = -a u_{xx} + f_x.$$

$$\Rightarrow u_{tt} = a^2 u_{xx} - a f_x + f_t \quad \leftarrow \text{put in the Taylor series...}$$

replacing  $u_t \rightarrow u_{tx}$  term,  $u_{tt} \rightarrow u_{ttx}$  term

$$u(t+k, x) = u(t, x) + k(-a u_x + f) + \frac{k^2}{2} (a^2 u_{xx} - a f_x + f_t) + O(k^3)$$

$\partial_x$  : 2nd-order difference,  $f_t$  : forward difference

$$\begin{aligned} u(t+k, x) &= u(t, x) - ak \frac{u(t, x+h) - u(t, x-h)}{2h} \\ &\quad + \frac{(ak)^2}{2} \left( \frac{u(t, x+h) - 2u(t, x) + u(t, x-h)}{h^2} \right) \\ &\quad + \frac{k}{2} (f(t+k, x) - f(t, x)) - \frac{ak^2}{2} \left( \frac{f(t, x+h) - f(t, x-h)}{2h} \right) \\ &\quad + O(kh^2) + O(k^3) \dots (*) \end{aligned}$$

Replacing  $(*)$  to difference operator  $\mathcal{L}_m^n$ ,  
we obtain the Lax - Wendroff scheme.



## The Crank - Nicolson Scheme

→ second - order accuracy scheme.

For the point  $(t + \frac{k}{2}, x)$ , use the formula that

$$u_t(t + \frac{1}{2}k, x) = \frac{u(t+k, x) - u(t, x)}{k} + O(k^2), \text{ then}$$

$$\begin{aligned} u_{xx}(t + \frac{1}{2}k, x) &= \frac{u_{xx}(t+k, x) - u_{xx}(t, x)}{2} + O(k^2) \\ &= \frac{1}{2} \left[ \frac{u(t+k, x+h) - u(t+k, x-h)}{2h} \right. \\ &\quad \left. + \frac{u(t, x+h) - u(t, x-h)}{2h} \right] + O(k^2) + O(h^2). \end{aligned}$$

$$(\circ\circ) \Rightarrow \frac{v_m^{n+1} - v_m^n}{k} + a \frac{v_{m+1}^{n+1} - v_{m-1}^{n+1} + v_{m+1}^n - v_{m-1}^n}{4h} = \frac{f_m^{n+1} + f_m^n}{2}$$

□