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#include "transform.h"
#include "ui transform.h"
#include"QColorDialog"
#include<QMouseEvent>
#include<QtDebug>
#include<QTime>
#include<iostream>
#include<cmath>
using namespace std;
QImage img(500,500,QImage::Format RGB888);
QColor color;
transform::transform(QWidget *parent)
    : QMainWindow(parent)
    , ui(new Ui::transform)
{
   ui->setupUi(this);
    start=true;
    ver = 0;
}
transform::~transform()
{
    delete ui;
}
int ver=0,temp,i,j,a[20],b[20];
float slope [20], dx, dy, x [20];
void transform::dda(float x1, float y1, float x2, float y2)
   int dx,dy,p;
   int x,y;
   int i=0;
   x=x1;
   y=y1;
   dx=abs(x2-x1);
   dy=abs(y2-y1);
    if(dx>=dy)
      p=2*dy-dx;
      while(i<=dx)</pre>
      {img.setPixel(x,y,color.rgb());
          if(p<0)
          {
              p=p+2*dy;
          else{
              p=p+2*(dy-dx);
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y=y+sign(y2-y1);
          }
          x=x+sign(x2-x1);
          <u>i++;</u>
      }
    else{
        p=2*dx-dy;
        while(i<=dy)</pre>
        {img.setPixel(x,y,color.rgb());
             if (p<0)
                 p=p+2*dx;
             }
             else{
                 p=p+2*(dx-dy);
                 x=x+sign(x2-x1);
             y=y+sign(y2-y1);
             i++;
    }
    ui->label->setPixmap(QPixmap::fromImage(img));
}
int transform::sign(float x)
{
    if(x<0)
        return −1;
    else
        return 1;
}
void transform::mousePressEvent(QMouseEvent *ev)
{ if (start)
    {
        int p=ev->pos().x();
        int q=ev->pos().y();
        a[ver]=p;
        b[ver]=q;
        if(ev->button() ==Qt::RightButton)
          dda(a[0],b[0],a[ver-1],b[ver-1]);
          start=false;
        }
        else{
             if(ver>0)
                dda(a[ver],b[ver],a[ver-1],b[ver-1]);
        }
        ver++;
    }
}
```

```
void transform::on pushButton clicked()
    color=QColorDialog::getColor();
    dda (250, 0, 250, 499);
    dda(0,250,499,250);
}
void transform::on_pushButton_2_clicked()
{ int tx, ty, x, y, x1, y1;
    tx=ui->textEdit->toPlainText().toInt();
    ty=ui->textEdit_2->toPlainText().toInt();
    for(int i=0; i<ver-2;i++) {</pre>
        x = a[i];
        y = b[i];
        x1 = a[i+1];
        y1 = b[i+1];
        dda (x+tx, y+ty, x1+tx, y1+ty);
    dda(a[0]+tx,b[0]+ty,x1+tx,y1+ty);
}
void transform::on pushButton 3 clicked()
{
    int cx, cy;
    for (int i=0; i<ver-1;i++) {</pre>
        cx += a[i];
    }
    for (int j=0; j<ver-1; j++) {</pre>
        cy += b[j];
    }
    cx = cx / ver;
    cy = cy / ver;
    float sx, sy;
    float x, y, x1, y1;
    sx = ui->textEdit 3->toPlainText().toInt();
    sy = ui->textEdit 4->toPlainText().toInt();
    for(int i=0; i<ver-2;i++) {</pre>
        x = a[i];
        y = b[i];
        x1 = a[i+1];
        y1 = b[i+1];
        dda ((x-250)*sx +250, (y-250)*sy +250, (x1-250)*sx +250, (y1-
250)*sy+250);
          dda(x+(x1-x)*(sx/2),y+(y1-y)*(sy/2),x1+(x1-x)*(sx/2),y1+(y1-x)*(sx/2)
y) * (sy/2));
    dda((a[0]-250)*sx +250, (b[0]-250)*sy +250, (x1-250)*sx +250, (y1-250)*sy
     dda(a[0] + (x1-a[0])*(sx/2), b[0]+(y1-b[0])*(sy/2), x1+(x1-a[0])*(sx/2), y1
+(y1-b[0])*(sy/2));
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void transform::on pushButton 4 clicked()
               int cx, cy;
                for (int i=0; i<ver-1;i++) {</pre>
                             cx += a[i];
               for (int j=0; j<ver-1; j++) {</pre>
                             cy += b[j];
               }
               cx = cx / ver;
               cy = cy / ver;
               float angle;
               int theta, x, y, x1, y1;
               theta = ui->textEdit 5->toPlainText().toInt();
               angle = (theta * 3.141)/180;
               for(int i=0; i<ver-2;i++) {</pre>
                             x = a[i];
                             y = b[i];
                             x1 = a[i+1];
                              y1 = b[i+1];
                              dda((x-250)*cos(angle) - (y-250)*sin(angle) + 250, (x-250)*sin(angle) +
(y-250)*\cos(\text{angle})+250, (x1-250)*\cos(\text{angle}) - (y1-250)*\sin(\text{angle})+250, (x1-250)*\cos(\text{angle})
250) * sin(angle) + (y1-250) * cos(angle) + 250);
               dda((a[0]-250)*cos(angle) - (b[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin(angle)+250,(a[0]-250)*sin
250) *sin(angle) + (b[0]-250) *cos(angle) + 250, (x1-250) *cos(angle) - (y1-
250) *sin(angle) +250, (x1-250) *sin(angle) + (y1-250) *cos(angle) +250);
```