Computer Vision 2016 Spring HW#5 theory

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Q1.

Input layer: 224 x 224 x 3

- 1. Convolution layer with 11 x 11 size filters, 96 neurons, stride 4 -> 55 x 55 x 96
- 2. Convolution layer with 5 x 5 size filters, 256 neurons, stride 1, pad 2 -> 55 x 55 x 256
- 3. Pooling layer with 2 x 2 -> 27 x 27 x 256
- 4. Convolution layer with 3 x 3 size filters, 384 neurons, stride 1, pad 1 -> 27 x 27 x 384
- 5. Pooling layer with 2 x 2 -> 13 x 13 x 384
- 6. Convolution layer with 3 x 3 size filters, 384 neurons, stride 1, pad 1 -> 13 x 13 x 384
- 7. Convolution layer with 3 x 3 size filters, 256 neurons, stride 1, pad 1 -> 13 x 13 x 256
- 8. Pooling layer with $3 \times 3 \rightarrow 4 \times 4 \times 256 (= 4096)$
 - => 4096 dimension vector connected!

Q2.

During pooling operation, max pooling picks maximum value, mean pooling picks mean value, and min pooling picks minimum value of selected region.

Usually, max pooling shows better performance.