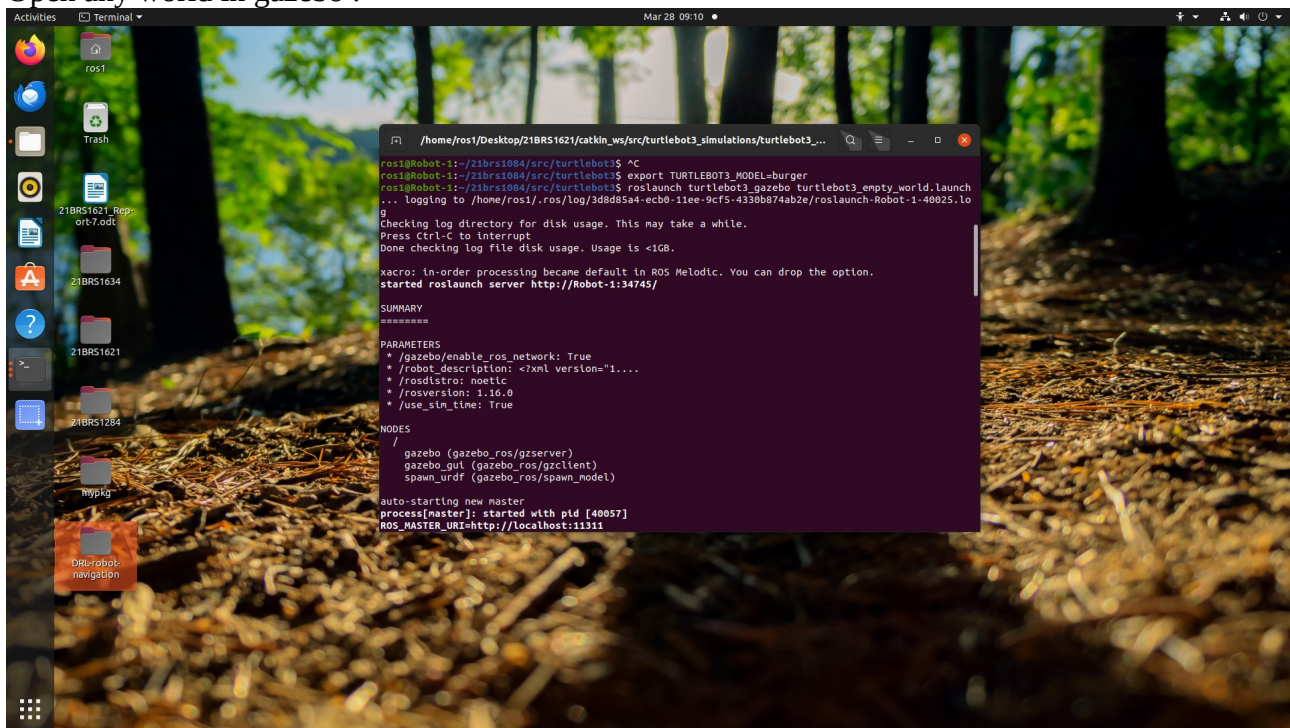


ROS ASSIGNMENT

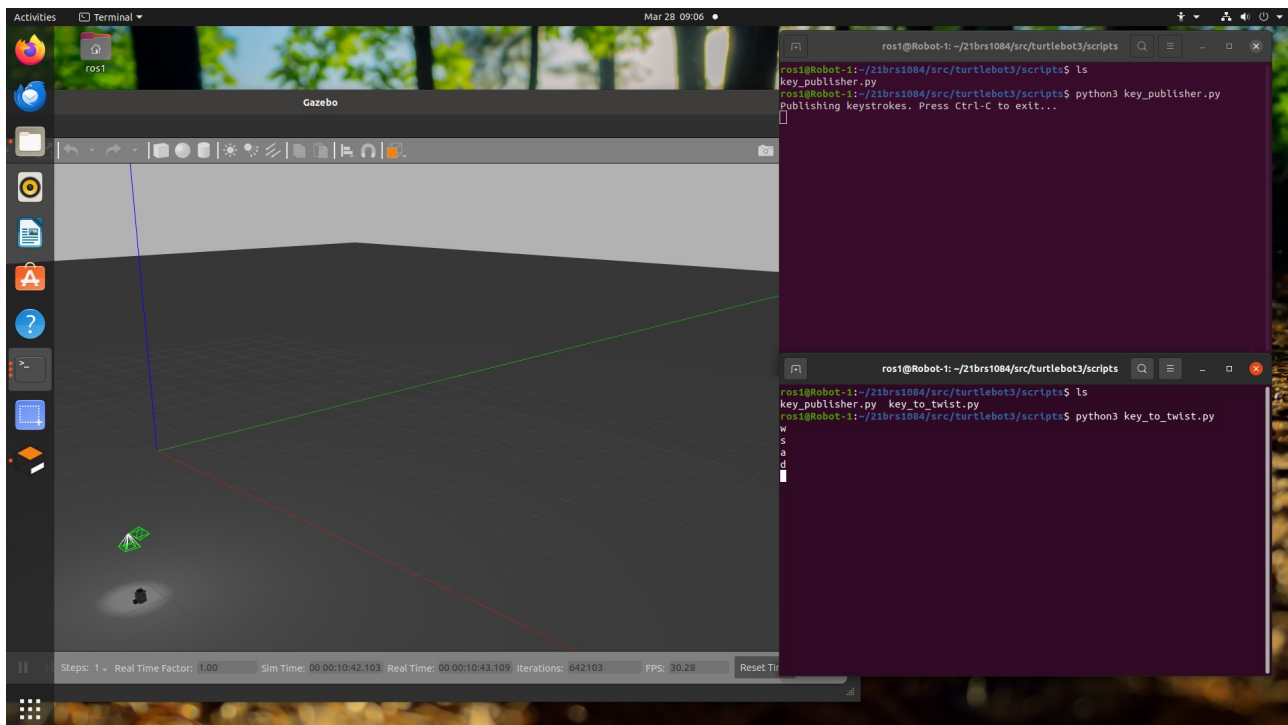
NAME- SANIKA RAHATE

REG.NO-21BRS1084

Open any world in gazebo .



Run the python file key_publisher and key_to_twist.



We moved the robot using a-s-w-d keys .

