

# Unit - III 3.2 Problems in Electromagnetics

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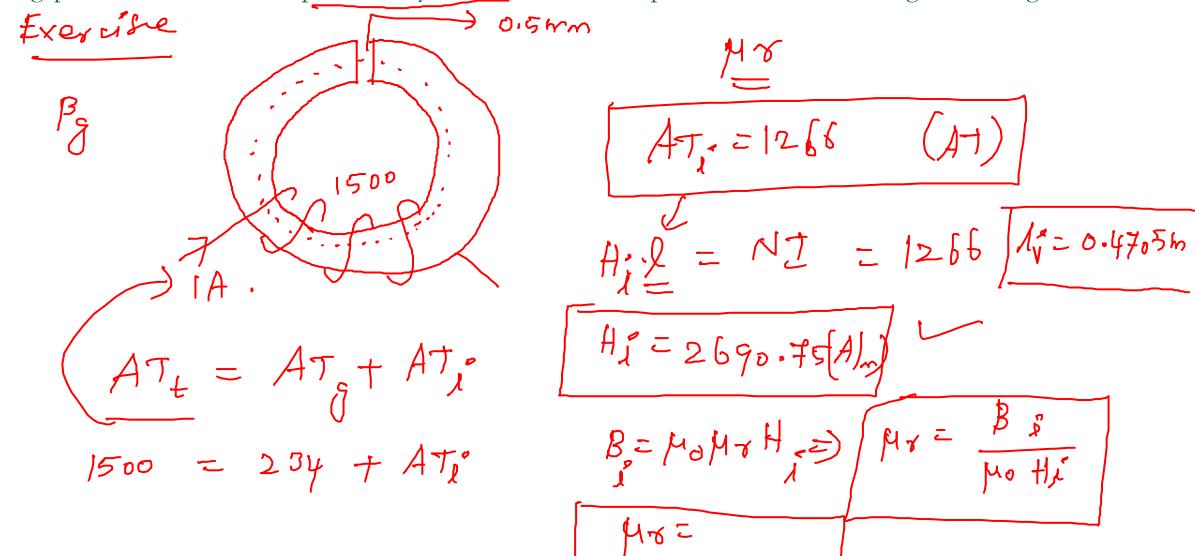


#### **Syllabus**

UNIT – III 10 Periods

**Principles of Electro Magnetics and Electro-mechanics:** Electricity and Magnetism - magnetic field and faraday's law - self and mutual inductance - Ampere's law - Magnetic circuit - Magnetic material and B-H Curve – Single phase transformer - principle of operation - EMF equation - voltage ratio - current ratio – KVA rating - Electromechanical energy conversion – Elementary generator and motors.

A ring has mean diameter of 15 cm, a cross section of 1.7 cm<sup>2</sup> and has a radial gap of 0.5 mm in it. It is uniformly wound with 1500 turns of insulated wire and a current of 1 A produces a flux of 0.1 mwb across the gap. Calculate the relative permeability of iron on the assumption that there is no magnetic leakage.



A series magnetic circuit has an iron path of length 50 cm and an air gap of length 1 mm. The cross-sectional area of the iron is 6.66 cm^2 and the exciting coil has 400 turns. Determine the current required to produce a flux of 0.9 mwb in the circuit. The following points are taken from the magnetization curve for iron. 1'MAN 50CM 1.55 Flux density (wb/m<sup>2</sup>) 1.2 1.35 1.45 Magnetizing force (A/m): **5**00 4000 1000 2000 -) Imm a = 6.66 x 10 4 % = 0.9x103 Wb. ATI = NT 1.351(T) = 0107x107/A/

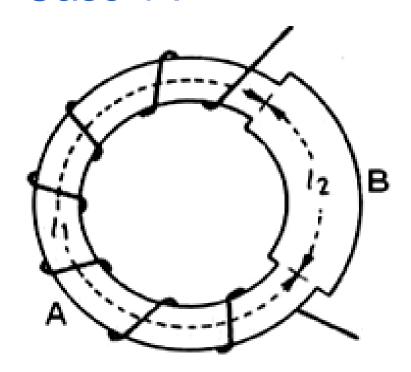
For iron path
$$Bi^2 = \frac{4}{a} = Bg = 1.35T$$

ATt= Atg
+Atg

ATt = 1570

## Composite Magnetic Circuit

#### Case 1:



$$\mathcal{R}_1 = \frac{l_1}{\mu_1 A_1}$$

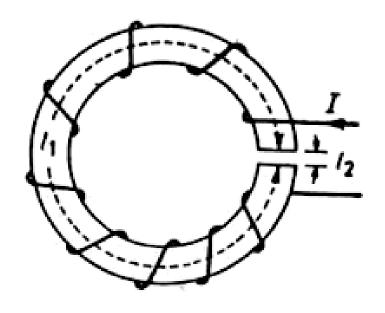
$$\mathcal{R}_2 = \frac{l_2}{\mu_2 A_2}$$

$$\therefore \text{ Total Reluctance, } \mathcal{R} = \mathcal{R}_1 + \mathcal{R}_2 = \frac{l_1}{\mu_1 A_1} + \frac{l_2}{\mu_2 A_2}$$

 $\therefore \text{ Total flux, } \Phi = \frac{\text{mmf of coil}}{\text{total reluctance}}$ 

$$= \frac{F}{R} = \frac{NI}{\frac{l_1}{\mu_1 A_1} + \frac{l_2}{\mu_2 A_2}}$$

#### Case 2: (with air gap)



#### Total reluctance,

$$\mathcal{R} = \frac{l_1}{\mu_1 A} + \frac{l_2}{\mu_0 A}$$

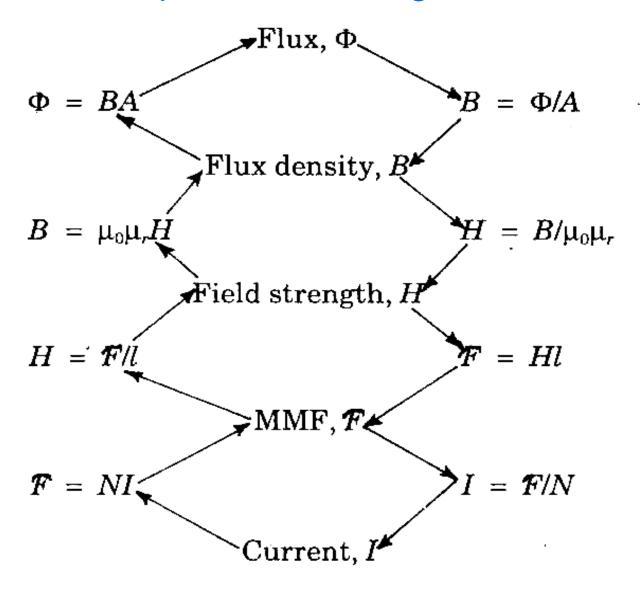
$$= \frac{1}{\mu_0 A} \left( \frac{l_1}{(\mu_1 / \mu_0)} + l_2 \right)$$

$$= \frac{1}{\mu_0 A} \left( \frac{l_1}{\mu_r} + l_2 \right)$$

#### Kirchhoff's Laws

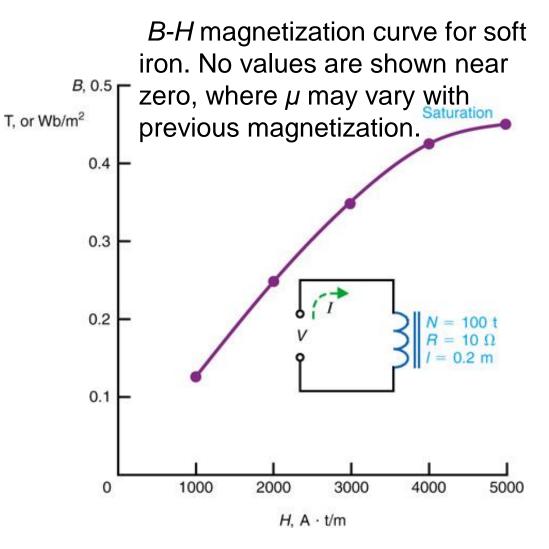
- Kirchhoff's Flux Law (KFL): The total magnetic flux towards a junction is equal to the total magnetic flux away from that junction.
- Kirchhoff's Magnetomotive Force Law (KML): In a closed magnetic circuit, the algebraic sum of the product of the magnetic field strength and the length of each part of the circuit is equal to the resultant magnetomotive force.

#### Steps to solve a problem on magnetic circuit



# B-H Magnetization Curve

- The B-H magnetization curve shows how much flux density B results from increasing field intensity H.
- Saturation is the effect of little change in flux density when the field intensity increases.



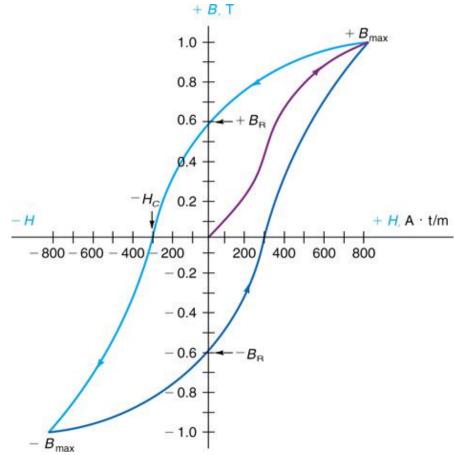
## Magnetic Hysteresis

- Hysteresis refers to a situation where the magnetic flux lags the increases or decreases in magnetizing force.
- Hysteresis loss is energy wasted in the form of heat when alternating current reverses rapidly and molecular dipoles lag the magnetizing force.
- For steel and other hard magnetic materials, hysteresis losses are much higher than in soft magnetic materials like iron.

## Magnetic Hysteresis

- Hysteresis Loop
  - B<sub>R</sub> is due to **retentivity**,
     which is the flux density
     remaining after the
     magnetizing force is
     reduced to zero.
  - □ Note that H = 0 but B > 0.
  - $\Box$   $H_C$  is the coercive force (needed to make B=0)

Fig. 14-4: Hysteresis loop for magnetic materials. This graph is a *B-H* curve , but *H* alternates in polarity with alternating current.

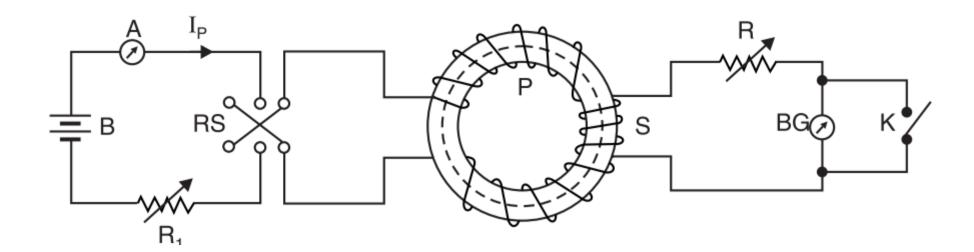


## Magnetic Hysteresis

- Demagnetization (Also Called Degaussing)
  - This method of demagnetization is called degaussing.
  - Applications of degaussing include:
    - Metal electrodes in a color picture tube
    - Erasing the recorded signal on magnetic tape.

#### Determination of B/H or Magnetisation Curve

- ballistic galvanometer
- fluxmeter





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# Joseph Henry

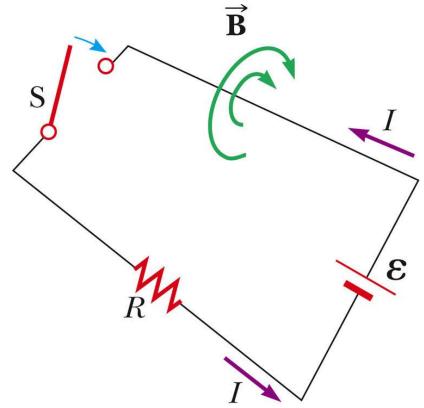
- 1797 1878
- American physicist
- First director of the Smithsonian
- Improved design of electromagnet
- Constructed one of the first motors
- Discovered self-inductance
- Unit of inductance is named in his honor



# Some Terminology

- Use emf and current when they are caused by batteries or other sources
- Use induced emf and induced current when they are caused by changing magnetic fields
- When dealing with problems in electromagnetism, it is important to distinguish between the two situations

- When the switch is closed, the current does not immediately reach its maximum value
- Faraday's law can be used to describe the effect/R



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 As the current increases with time, the magnetic flux through the circuit loop due to this current also increases with time

 This increasing flux creates an induced emf in the circuit

 $\frac{\vec{B}}{R}$ 

- This effect is called self-inductance
  - Because the changing flux through the circuit and the resultant induced emf arise from the circuit itself
- The emf ε<sub>ι</sub> is called a self-induced emf

- An induced emf is always proportional to the time rate of change of the current
  - The emf is proportional to the flux, which is proportional to the field and the field is proportional to the current

$$\varepsilon_L = -L \frac{dI}{dt}$$

 L is a constant of proportionality called the inductance of the coil and it depends on the geometry of the coil and other physical characteristics

### Inductance of a Coil

A closely spaced coil of N turns carrying current / has an inductance of

$$L = \frac{N\Phi_B}{I} = -\frac{\varepsilon_L}{dI/dt}$$

 The inductance is a measure of the opposition to a change in current

#### Inductance Units

The SI unit of inductance is the henry (H)

$$1H = 1\frac{V \cdot s}{A}$$

Named for Joseph Henry

#### Inductance of a Solenoid

- Assume a uniformly wound solenoid having N turns and length e
  - Assume € is much greater than the radius of the solenoid
- The flux through each turn of area A is

$$\Phi_B = BA = \mu_o nIA = \mu_o \frac{N}{\ell}IA$$

#### Inductance of a Solenoid

The inductance is

$$L = \frac{N\Phi_B}{I} = \frac{\mu_o N^2 A}{\ell}$$

This shows that L depends on the geometry of the object

An inductor in the form of a solenoid contains 420 turns, is 16.0 cm in length, and has a cross-sectional area of 3.00 cm<sup>2</sup>. What uniform rate of decrease of current through the inductor induces an emf of 175  $\mu$ V?

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$$L = \frac{\mu_0 N^2 A}{\ell} = \frac{\mu_0 (420)^2 (3.00 \times 10^{-4})}{0.160} = 4.16 \times 10^{-4} \text{ H}$$

$$\varepsilon = -L\frac{dI}{dt} \rightarrow \frac{dI}{dt} = \frac{-\varepsilon}{L} = \frac{-175 \times 10^{-6} \text{ V}}{4.16 \times 10^{-4} \text{ H}} = \boxed{-0.421 \text{ A/s}}$$

The current in a 90.0-mH inductor changes with time as  $I = 1.00t^2 - 6.00t$  (in SI units). Find the magnitude of the induced emf at (a) t = 1.00 s and (b) t = 4.00 s. (c) At what time is the emf zero?

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$$|\varepsilon| = L \frac{dI}{dt} = (90.0 \times 10^{-3}) \frac{d}{dt} (t^2 - 6t) \text{ V}$$

(a) At , t=1s 
$$\varepsilon = 360 \text{ m V}$$

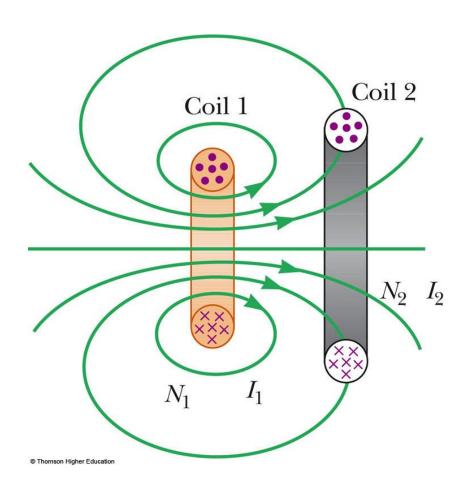
(b) At , t= 4s 
$$\varepsilon = \boxed{180 \text{ m V}}$$

when 
$$t = 3 sec$$
.

$$\varepsilon = (90.0 \times 10^{-3})(2t - 6) = 0$$

- The magnetic flux through the area enclosed by a circuit often varies with time because of time-varying currents in nearby circuits
- This process is known as mutual induction because it depends on the interaction of two circuits

- The current in coil 1 sets up a magnetic field
- Some of the magnetic field lines pass through coil 2
- Coil 1 has a current I<sub>1</sub> and N<sub>1</sub> turns
- Coil 2 has N<sub>2</sub> turns



The mutual inductance M<sub>12</sub> of coil 2 with respect to coil
 1 is

$$M_{12} \equiv \frac{N_2 \Phi_{12}}{I_1}$$

 Mutual inductance depends on the geometry of both circuits and on their orientation with respect to each other

#### Induced emf in Mutual Inductance

 If current 4 varies with time, the emf induced by coil 1 in coil 2 is

$$\varepsilon_2 = -N_2 \frac{d\Phi_{12}}{dt} = -M_{12} \frac{dI_1}{dt}$$

- If the current is in *coil* 2, there is a mutual inductance  $M_{21}$
- If current 2 varies with time, the emf induced by coil 2 in coil 1 is

$$\varepsilon_1 = -M_{21} \frac{dI_2}{dt}$$

- In mutual induction, the emf induced in one coil is always proportional to the rate at which the current in the other coil is changing
- The mutual inductance in one coil is equal to the mutual inductance in the other coil

$$- M_{12} = M_{21} = M$$

The induced emf's can be expressed as

$$\varepsilon_1 = -M \frac{dI_2}{dt}$$
 and  $\varepsilon_2 = -M \frac{dI_1}{dt}$ 

Two coils are close to each other. The first coil carries a time-varying current given by  $I(t) = (5.00 \text{ A}) e^{-0.0250} t \sin(377t)$ . At t = 0.800 s, the emf measured across the second coil is -3.20 V. What is the mutual inductance of the coils?

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$$I_{1}(t) = I_{max}e^{-\alpha t}\sin \omega t \qquad I_{max} = 5.00 \text{ A} \qquad \alpha = 0.0250 \text{ s}^{-1}$$

$$\omega = 377 \text{ rad/s} \qquad \frac{dI_{1}}{dt} = I_{max}e^{-\alpha t}(-\alpha \sin \omega t + \omega \cos \omega t)$$

$$At \quad t = 0.800 \text{ s}$$

$$\frac{dI_{1}}{dt} = (5.00 \text{ A/s})e^{-0.0200} \left[ -(0.0250)\sin(0.800(377)) + 377\cos(0.800(377)) \right]$$

$$\frac{dI_{1}}{dt} = 1.85 \times 10^{3} \text{ A/s}$$

$$\varepsilon_{2} = -M \frac{dI_{1}}{dt} \qquad M = \frac{-\varepsilon_{2}}{dI_{1}/dt} = \frac{+3.20 \text{ V}}{1.85 \times 10^{3} \text{ A/s}} = \boxed{1.73 \text{ m H}}$$

# Relationship between self and mutual inductance

$$k = \frac{M}{\sqrt{L_1 L_2}} = \frac{\text{Actual mutual inductance}}{\text{Max. possible mutual inductance}}$$

• The coefficient of coupling (k) between two coils is defined as the fraction of magnetic flux produced by the current in one coil that links the other.

# Thank you