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The current version is QGIS 2.18.4 'Las Palmas' and was released on 24.02.2017.

QGIS is available on Windows, MacOS X, Linux and Android.

Binary packages (installers) for current stable version 2.18 can be downloaded here.

INSTALLATION DOWNLOADS ALL RELEASES SOURCES

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Latest release (eg. for New Users):

-  QGIS Standalone Installer Version 2.18 (32 bit)
-  QGIS Standalone Installer Version 2.18 (64 bit)

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SEARCH FOR A CITY OR REGION

Mumbai, India SEARCH

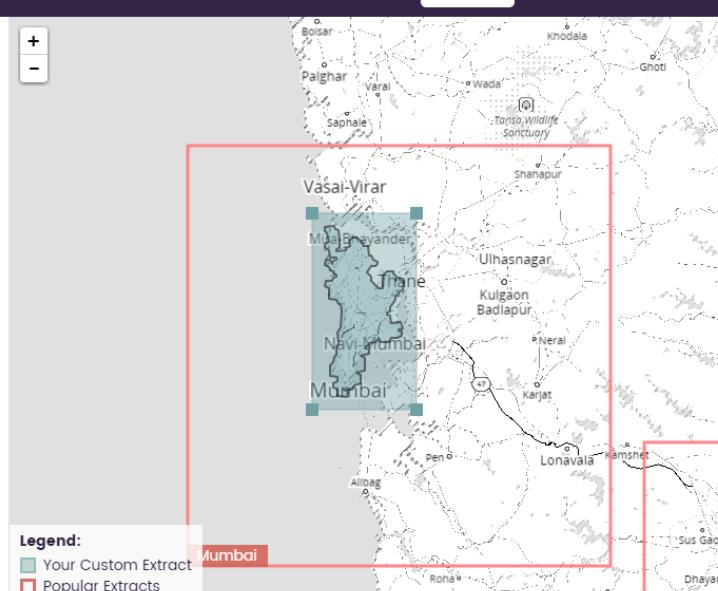
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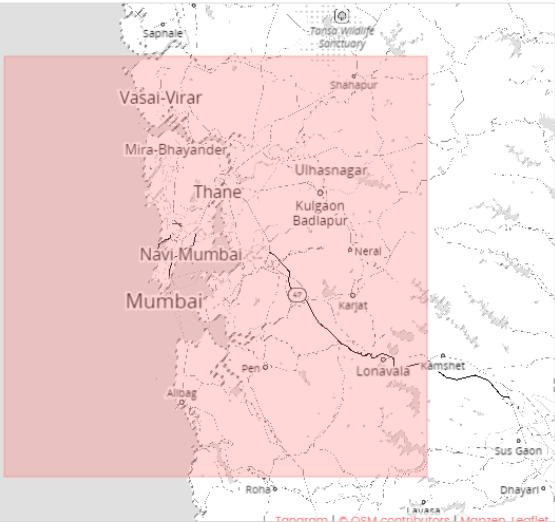
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Metro Extracts > Mumbai



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Datasets split by geometry type: lines, points, or polygons ([OSM2PGSQL](#))

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B. Franklin

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[PRACTICAL 1]

VECTOR DATA MODEL

AIM: To create a map of your surrounding area using vector data model (points, lines and polygons)

THEORY:

The **Vector data model** prepares the data in two basic steps so that the computer can process it –

- It uses points and their (x,y) coordinates to represent spatial features as points, lines and areas
- It organizes the geometric objects and their spatial relationships into a digital data files that the computer can access, interpret and process.

Representation of simple features –

Vector data model uses geometric objects like points, lines, and areas to represent simple spatial features. It is ideal for representing discrete features (features that are individually distinguishable features that do not exist between observations).

Dimensionality and property distinguishes the 3 types of geometric objects as well as the features they represent.

POINT

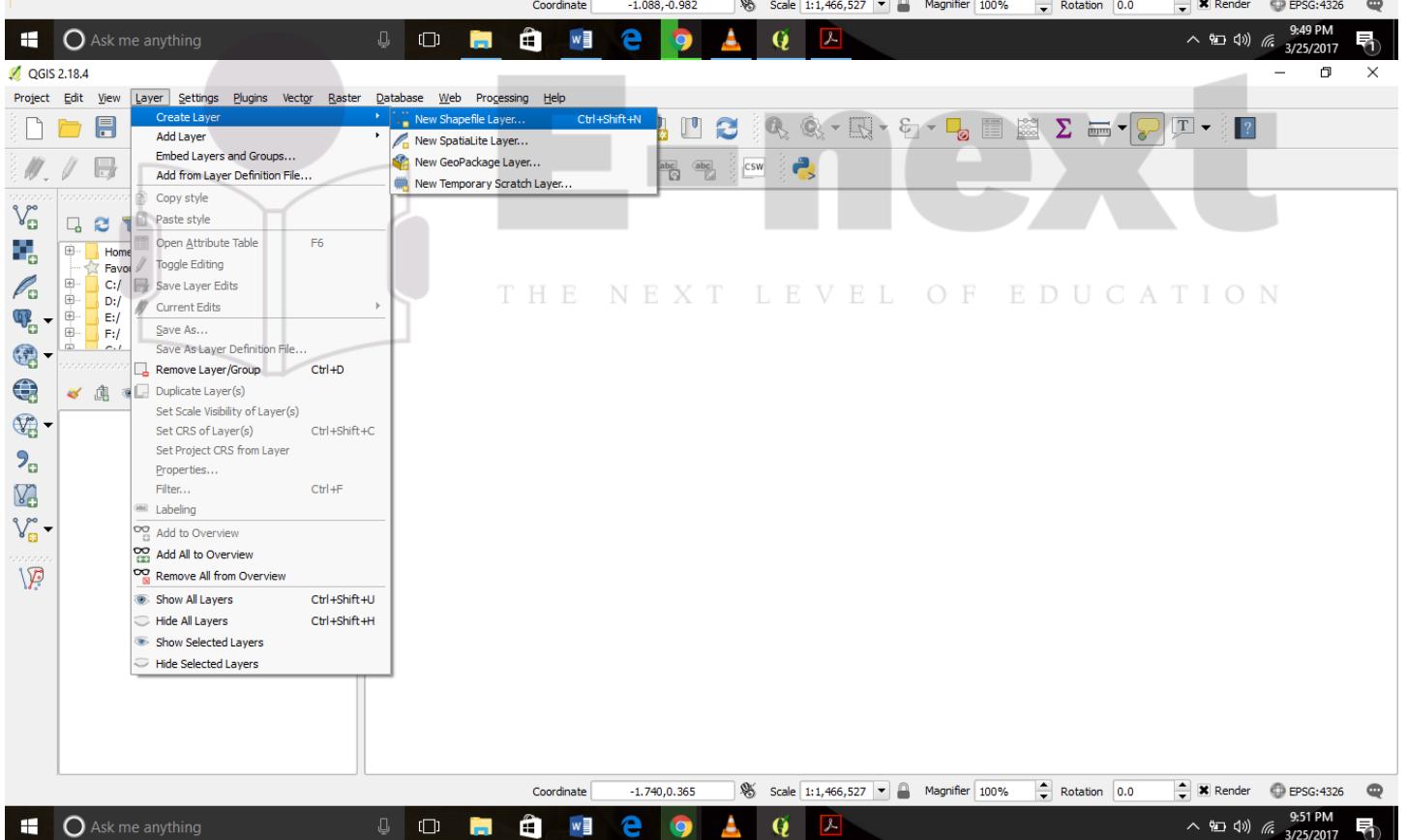
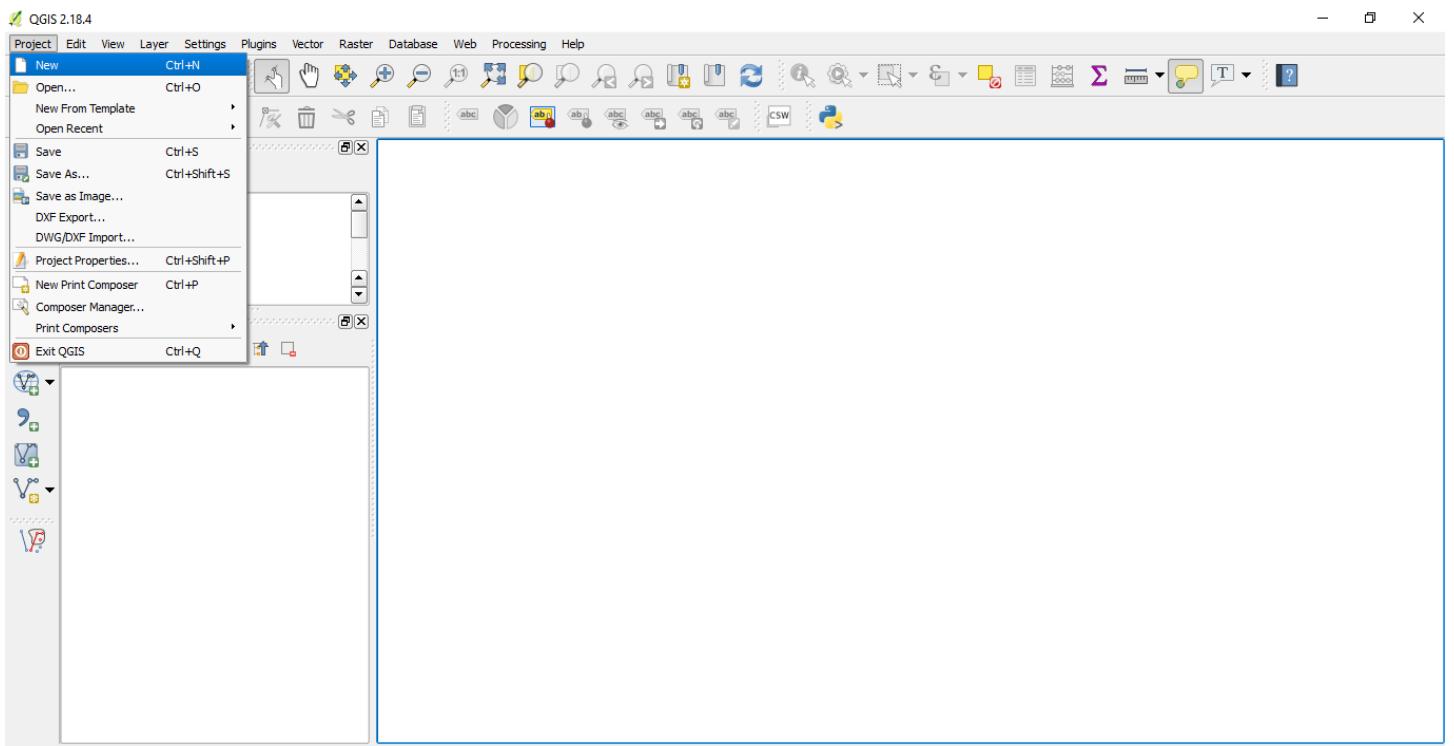
A point has 0 dimensions and has only the property of location. A point may also be called a node, vertex or 0-cell. A point feature is made up of a point or a set of separate points. Example: wells in a particular area, cities in India.

LINE

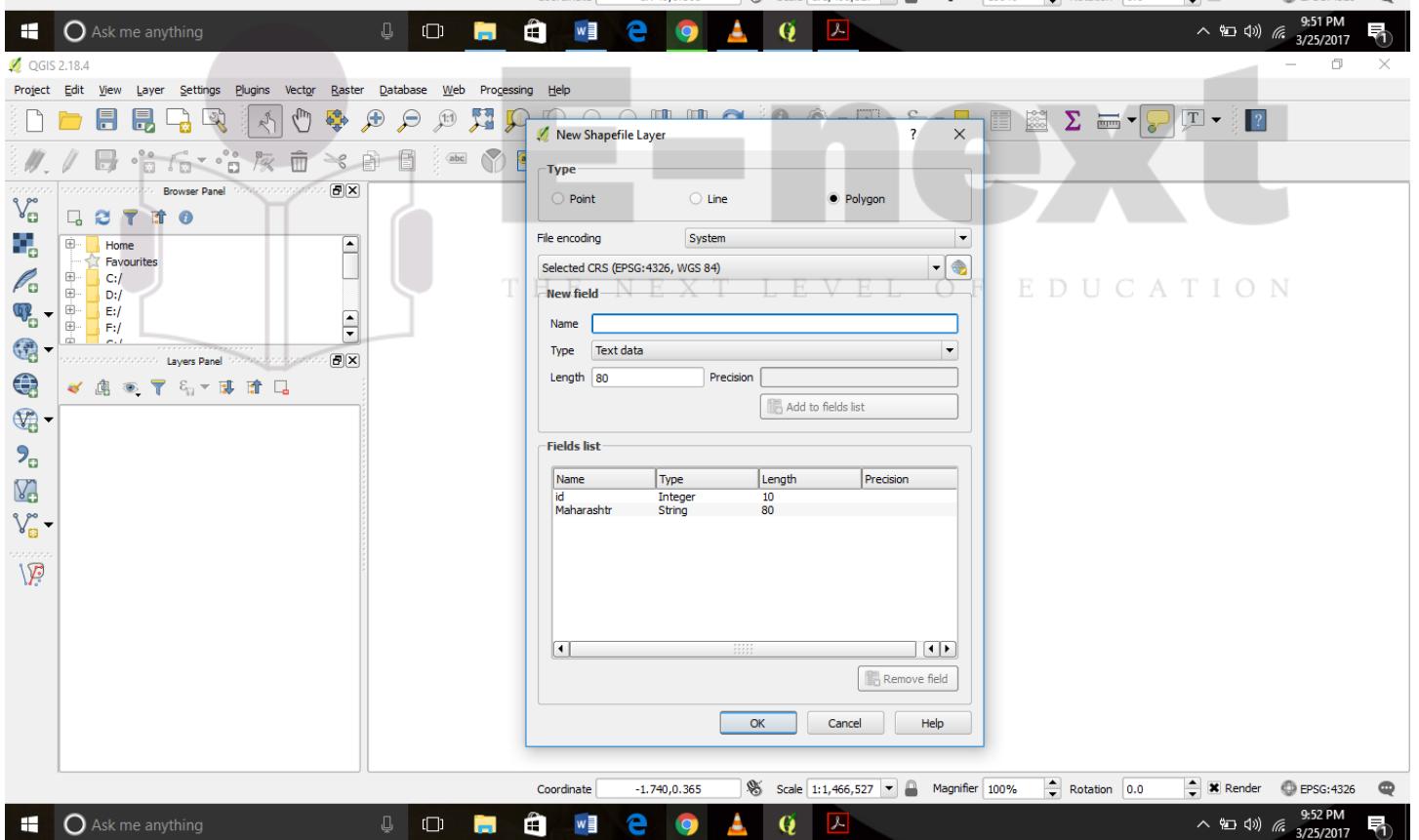
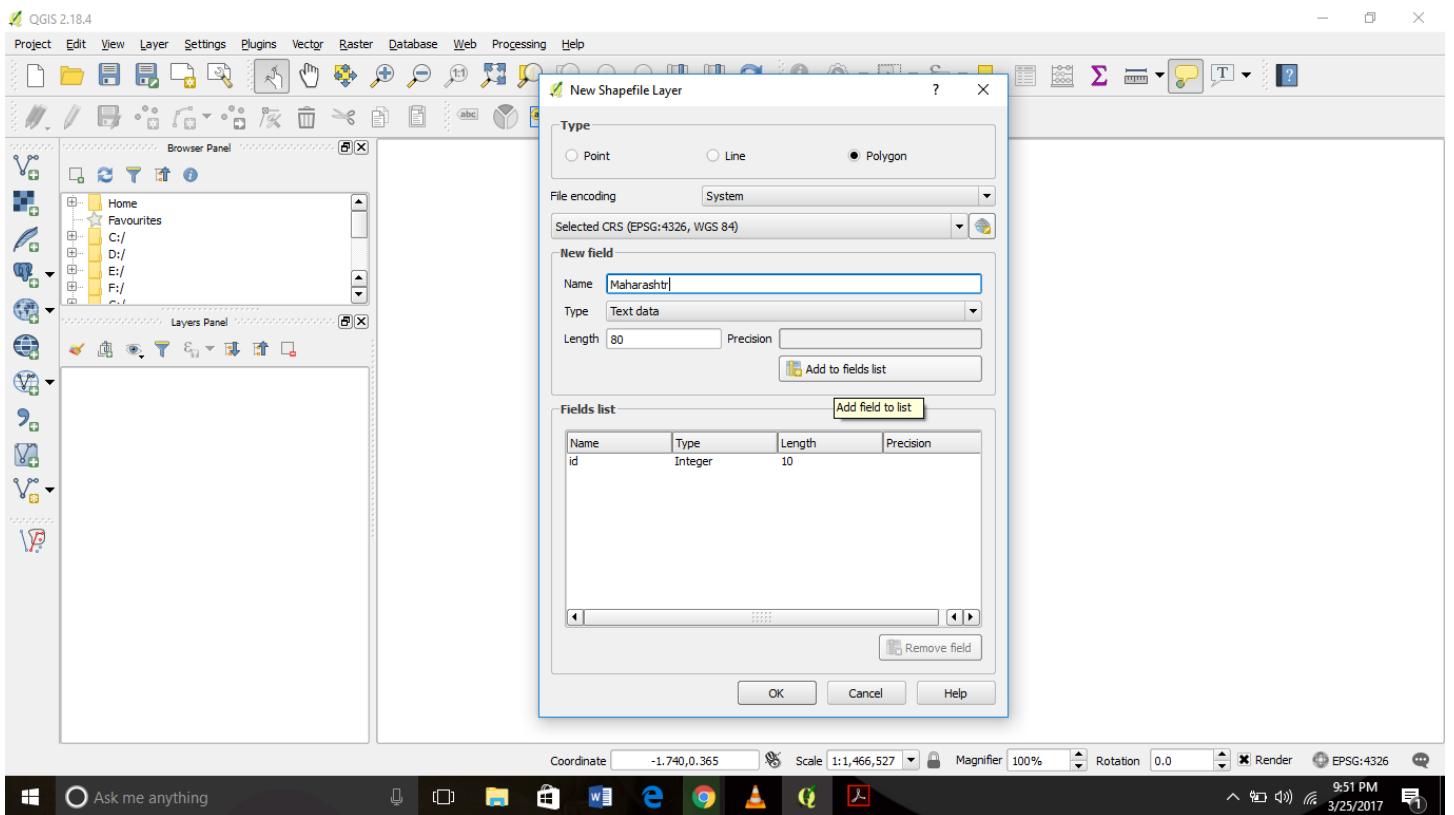
A line is one-dimensional and has the property of location. Line is also called edge, chain, link or 1-cell. A line has 2 end points and points in between to make the shape of the line. The shape of a line may be a smooth curve or a connection of straight line segments. B-Spline curves are used for representing contour lines/smooth lines for rivers and such. Straight line segments are used for representing human made features like streets, canals.

AREA

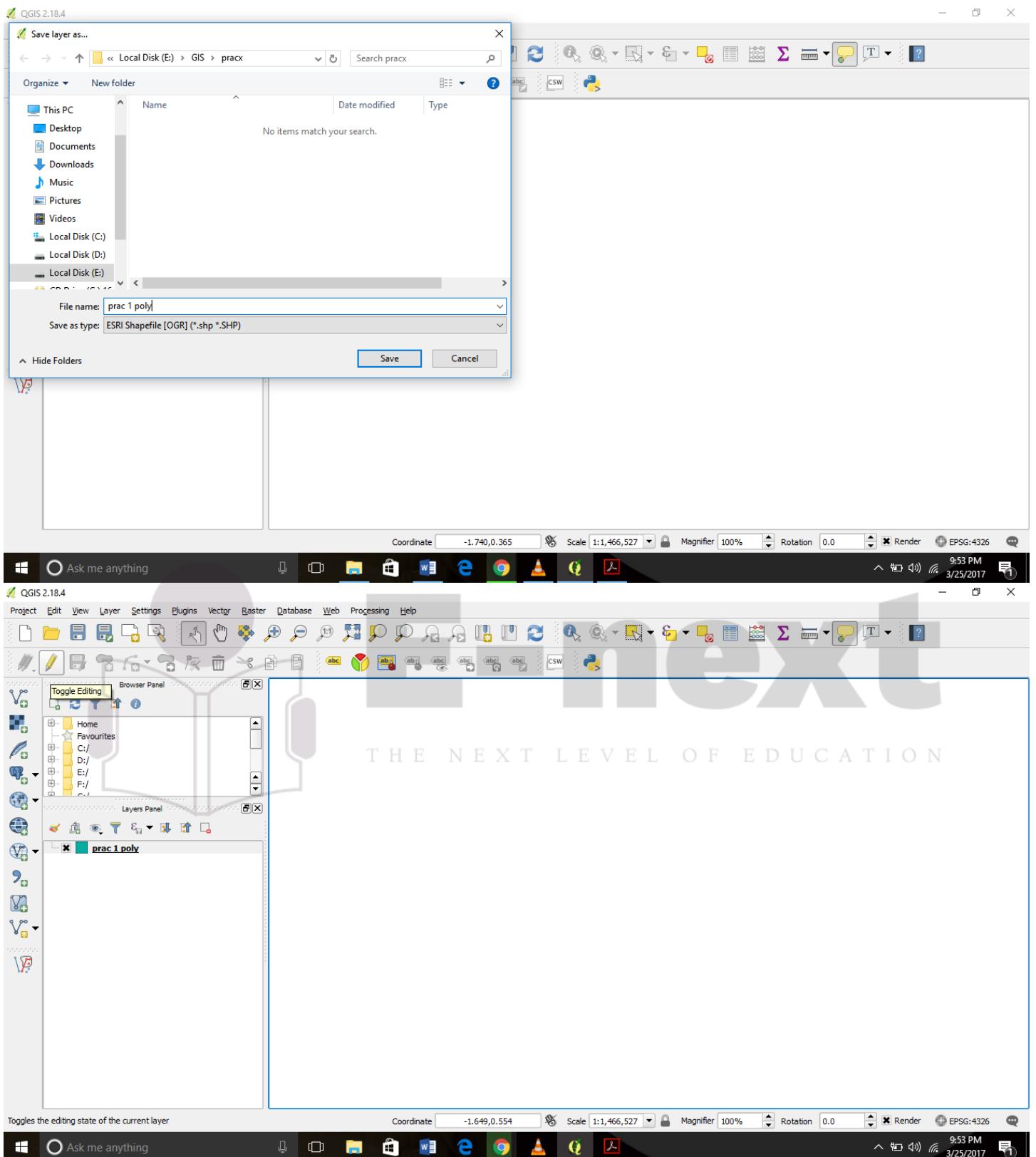
An area is two-dimensional and has the property of area (size) and perimeter. Area is also called polygon, face, zone or 2-cell. Area is made up of connected lines. An area may be alone or share boundaries with other areas. An area may contain holes (such as national forest containing private land parcels). The existence of holes means that the area has both external and internal boundaries. Examples of area features include timber stands, land parcels and water bodies. If the scale is large, the cities are represented as polygons; for a small scale map, the city is represented as a point.



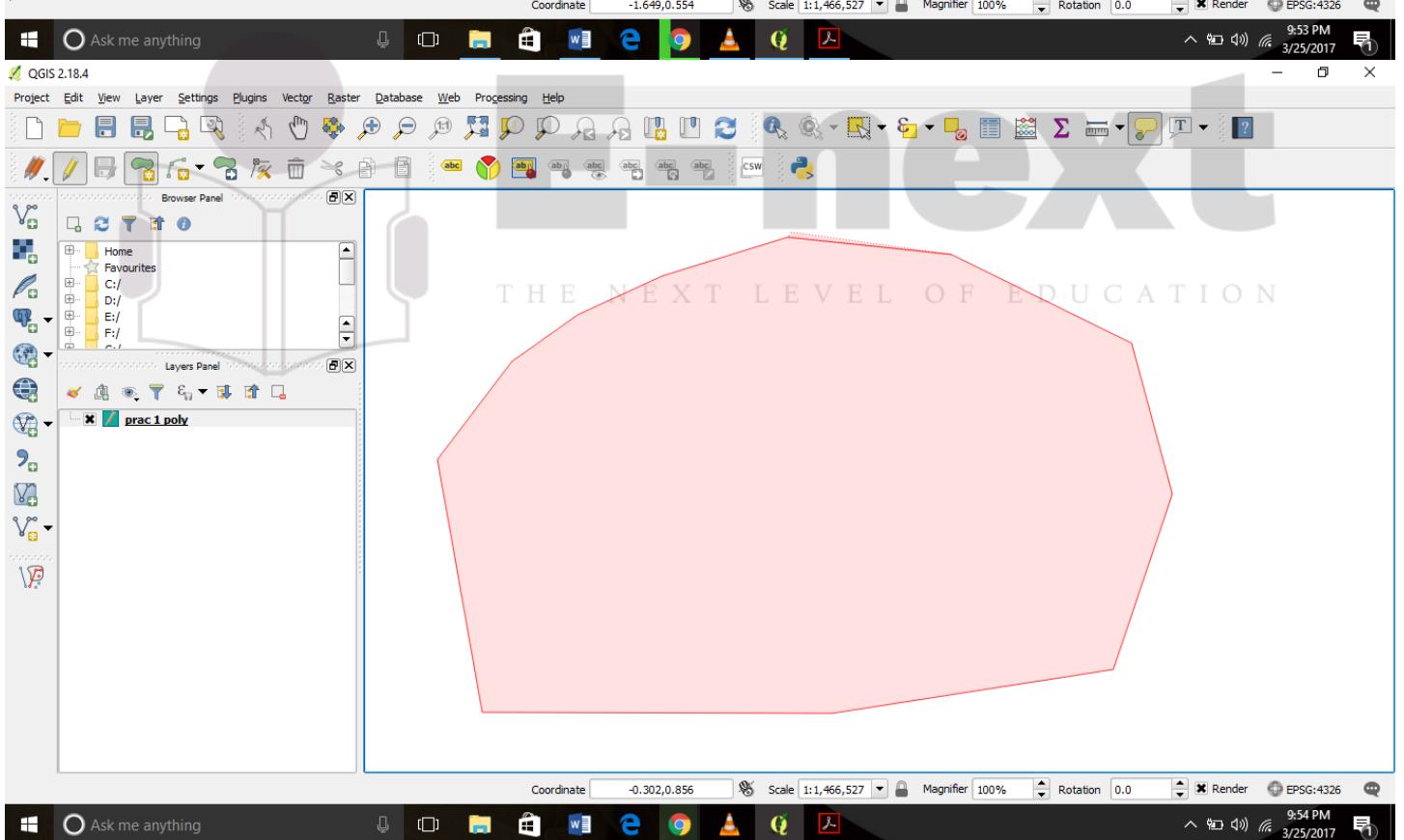
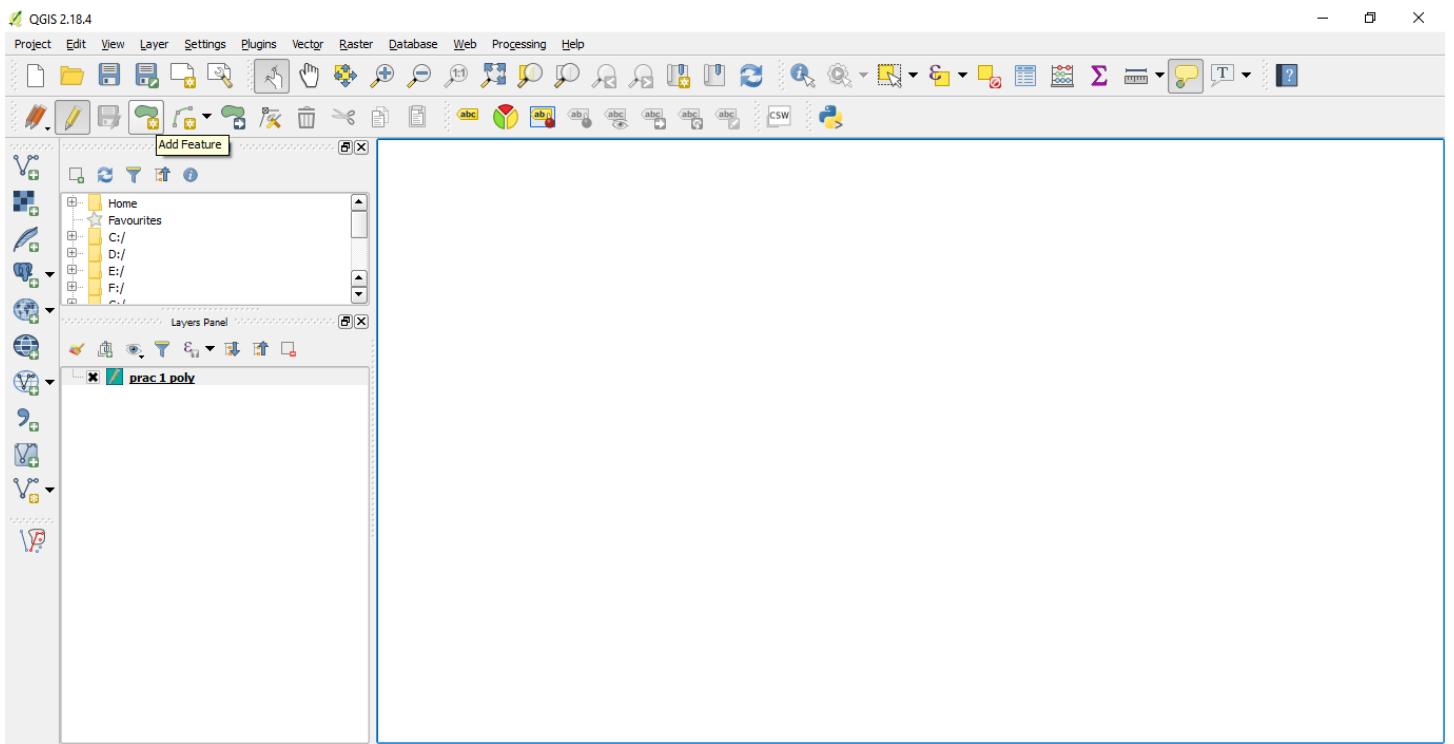
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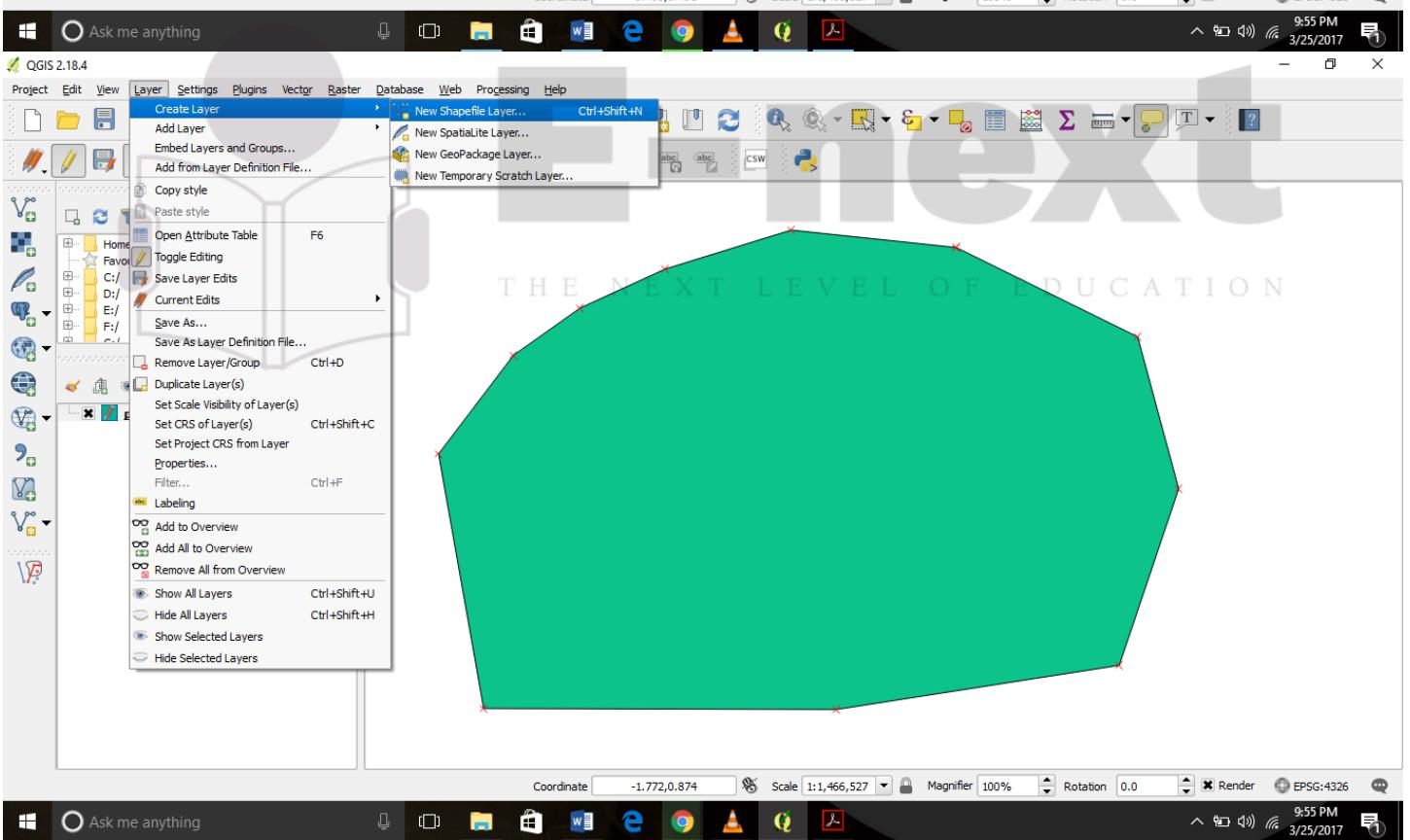
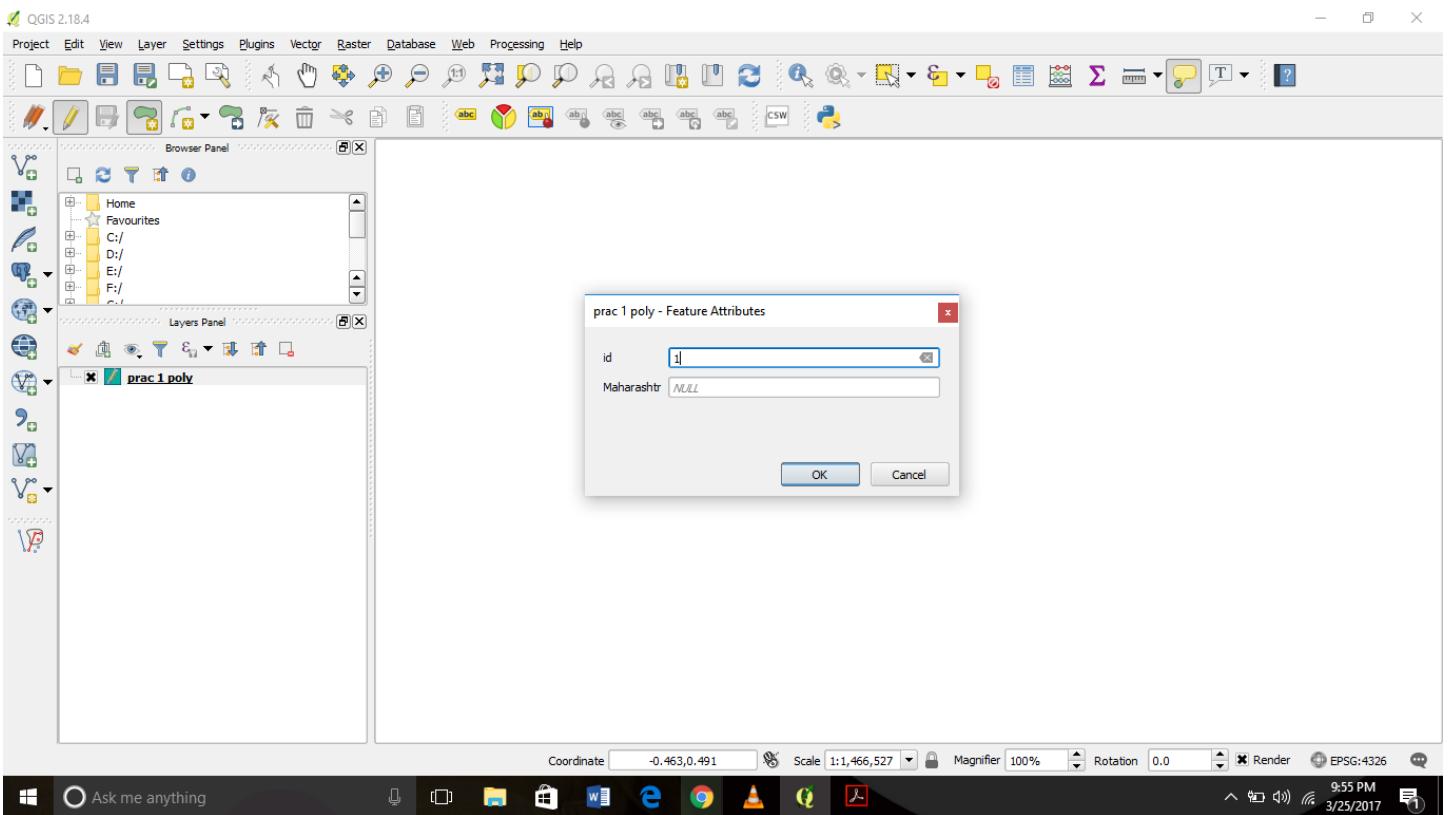
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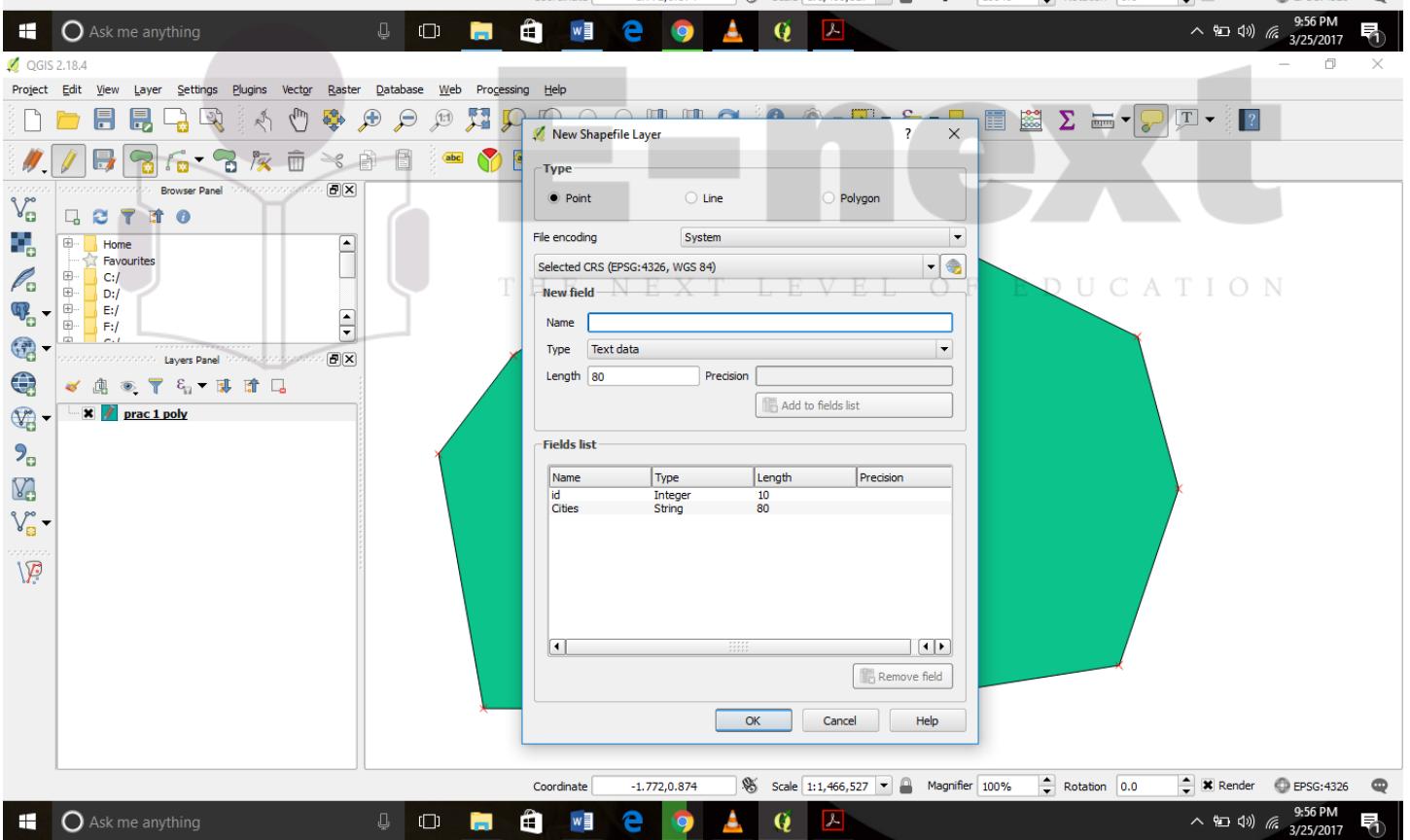
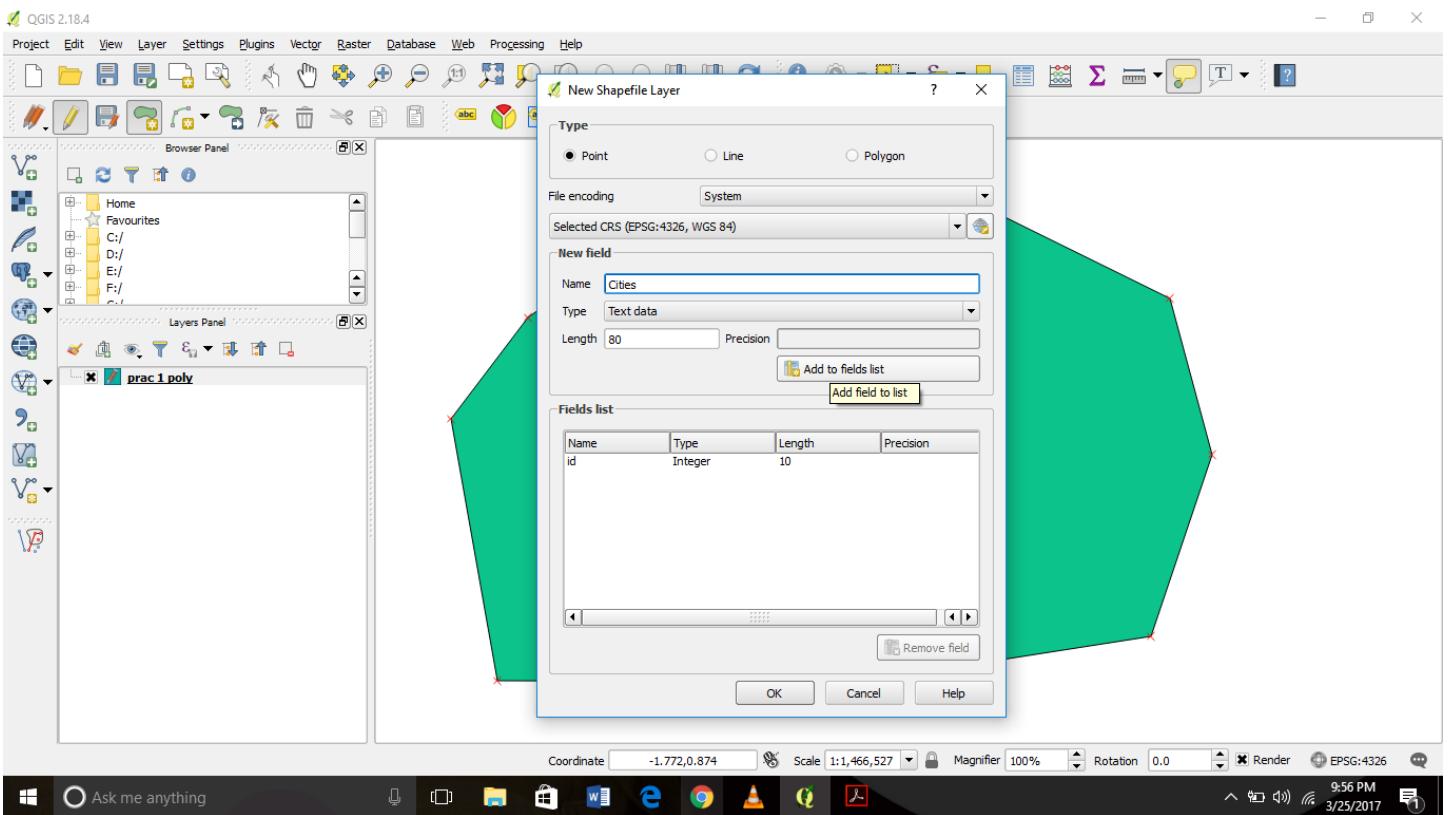
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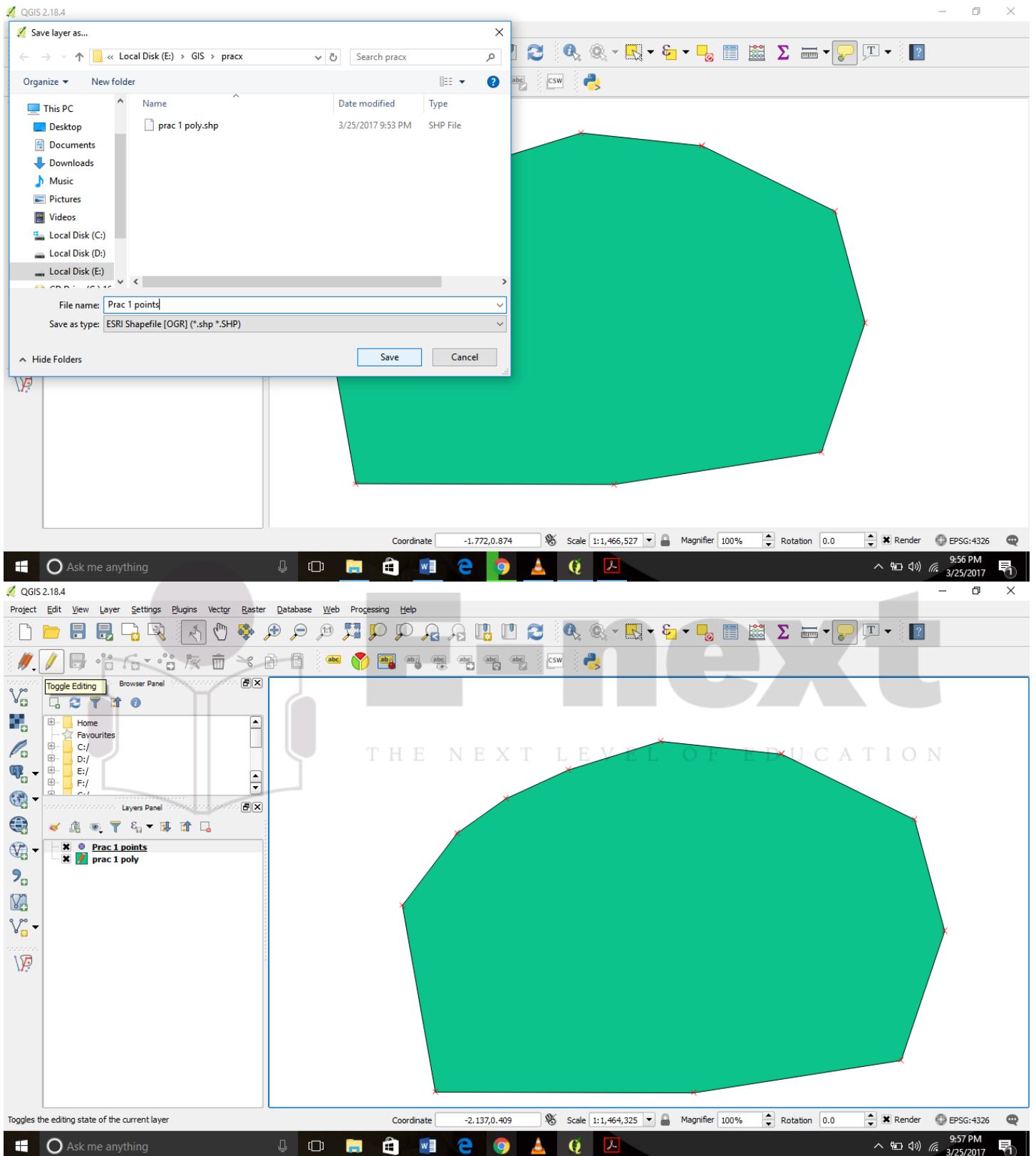


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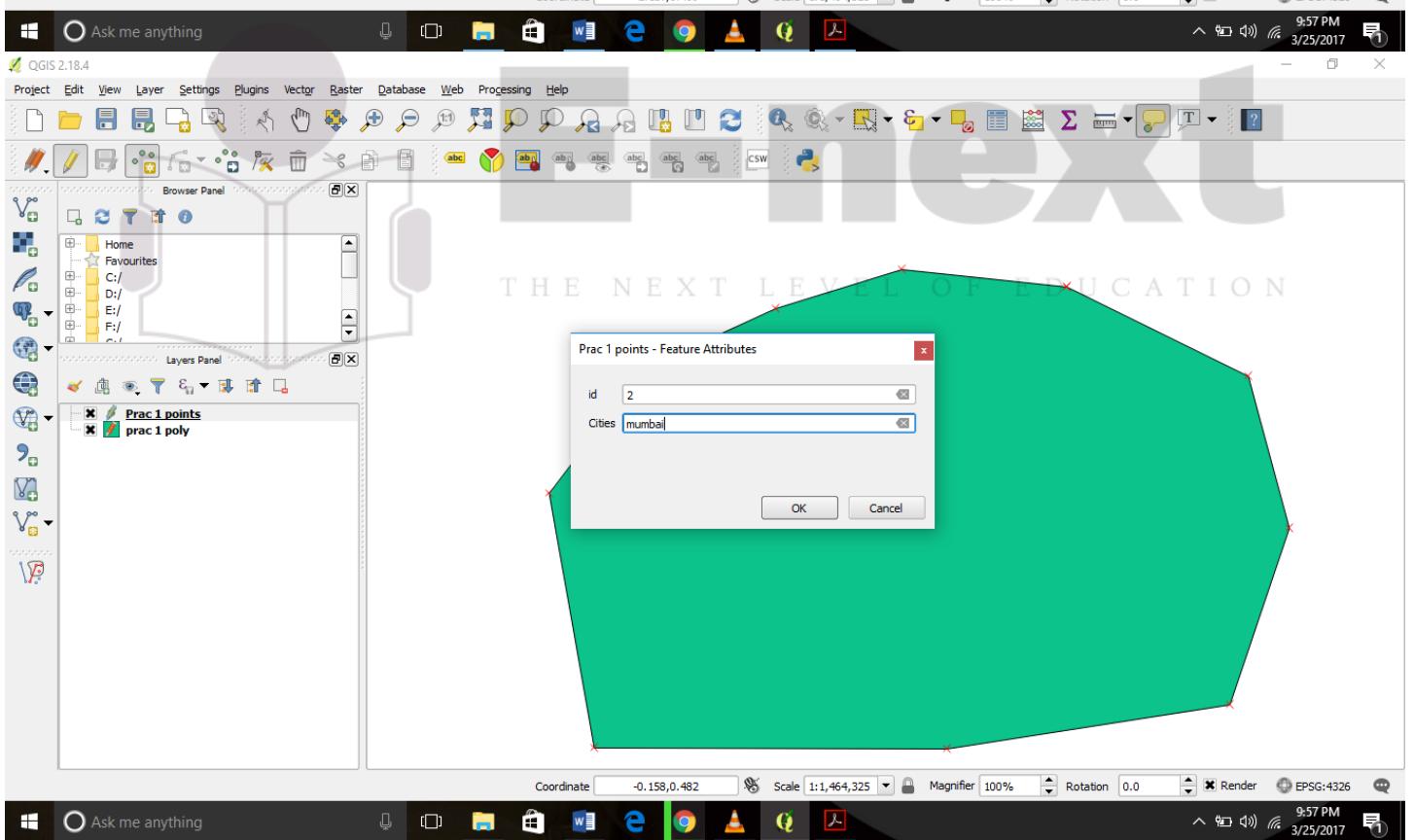
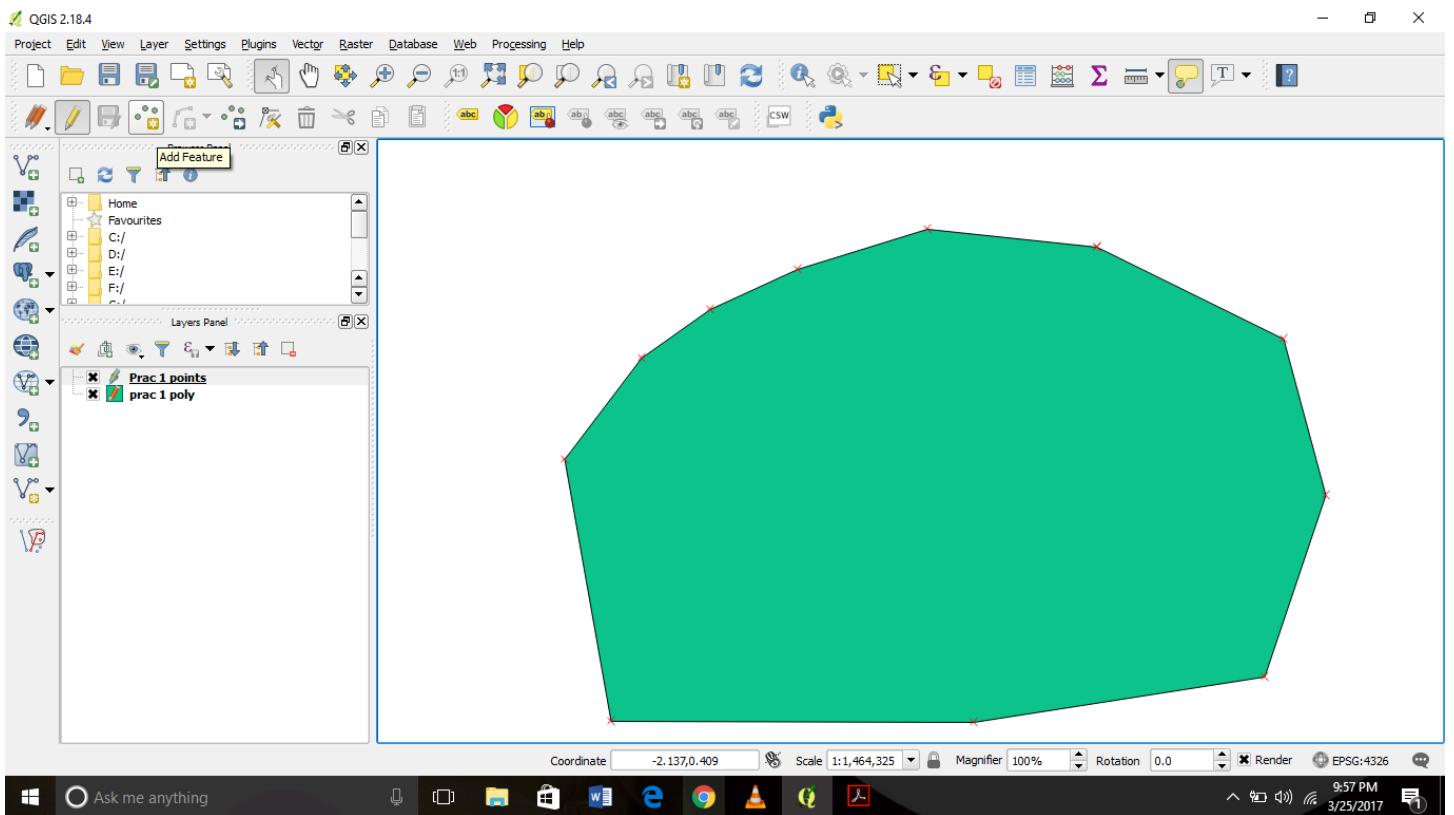


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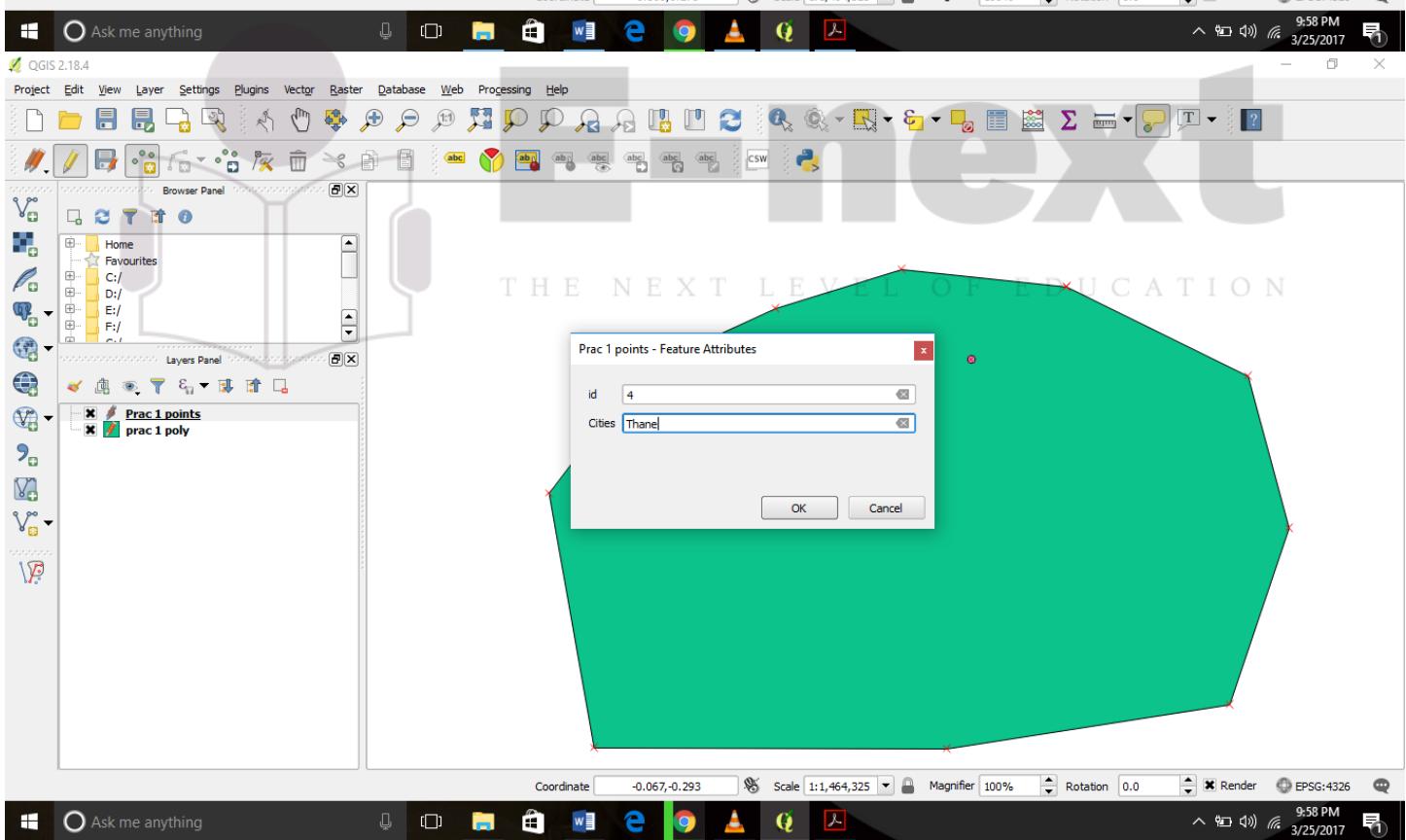
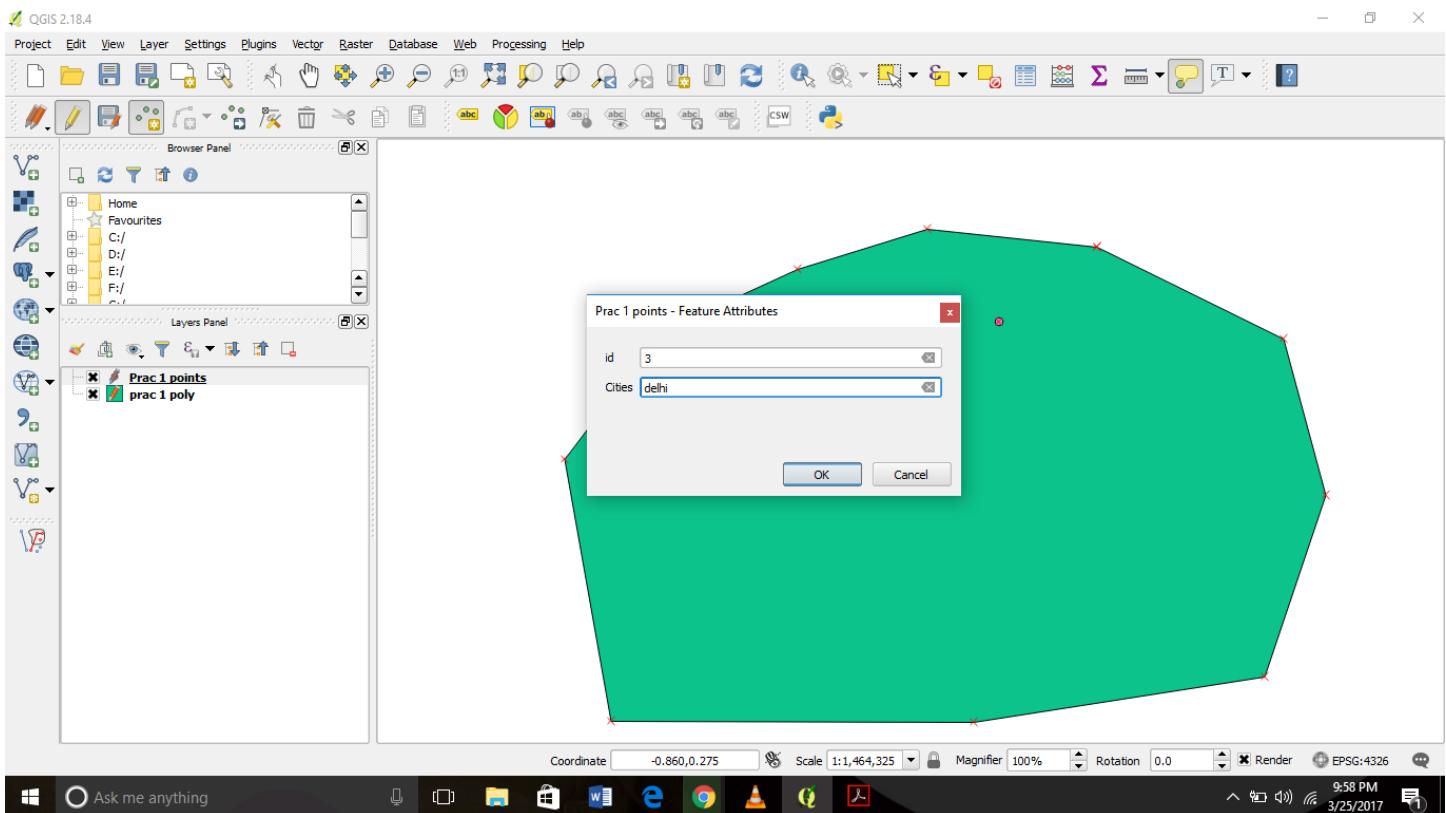




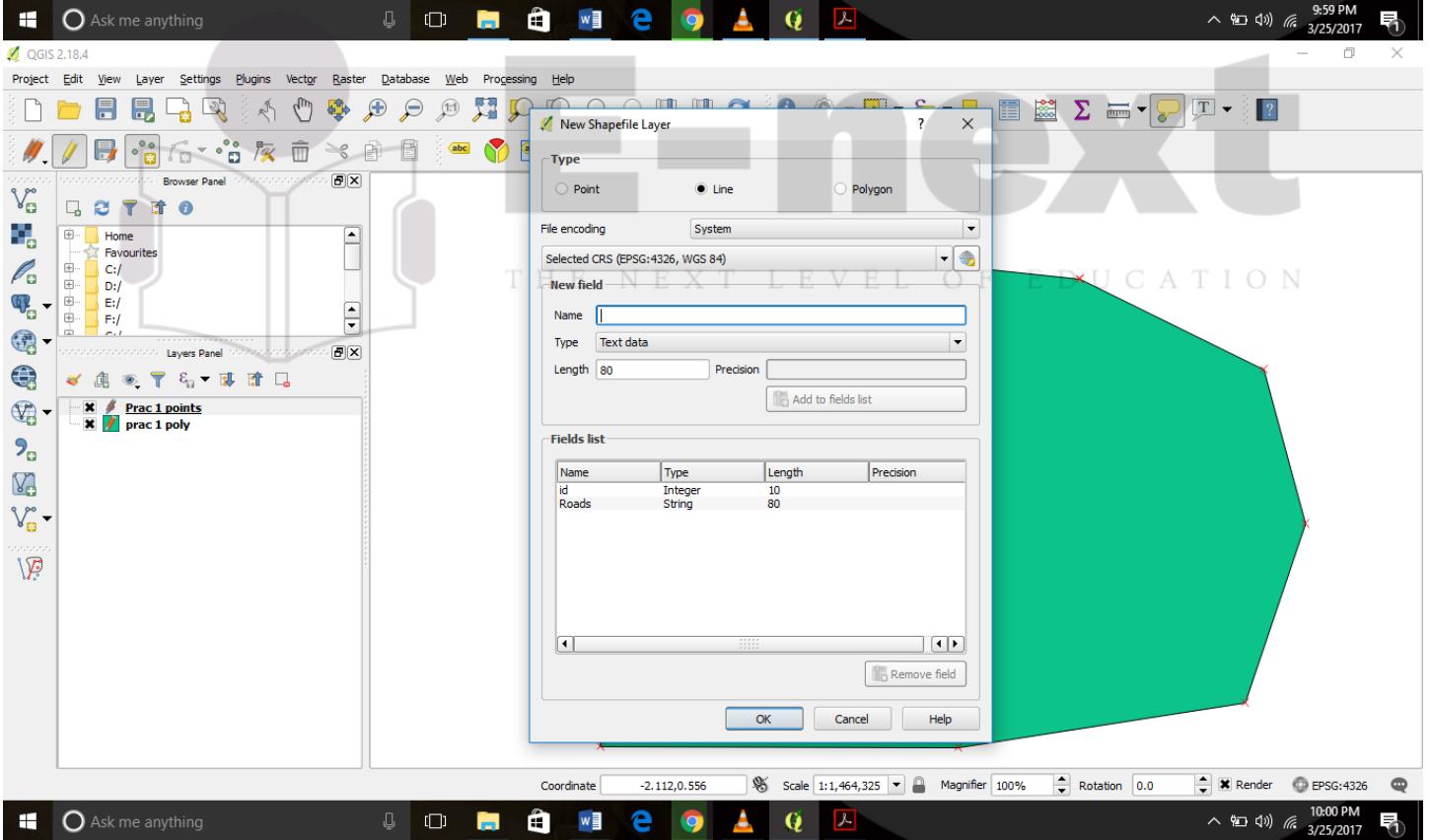
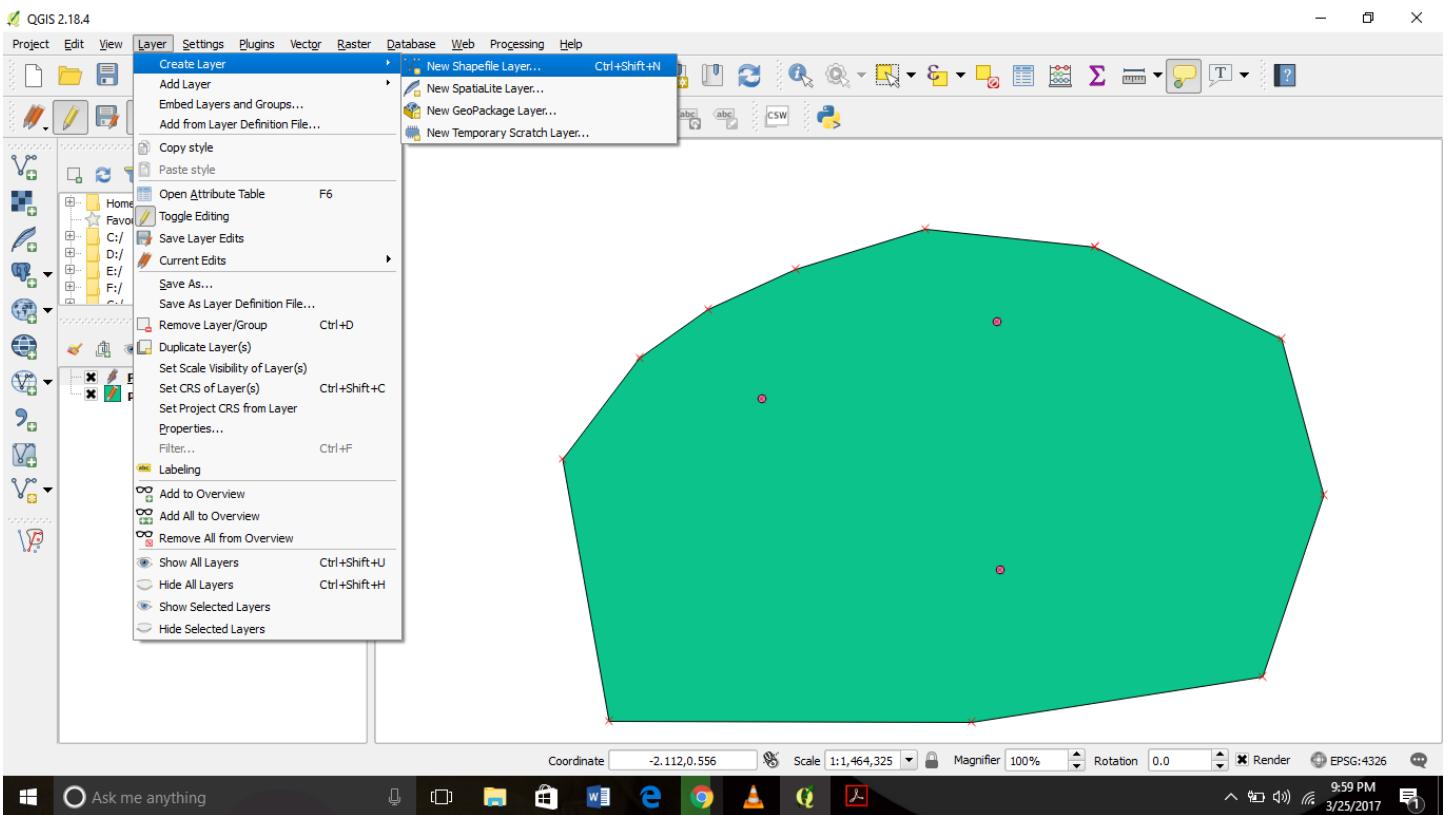
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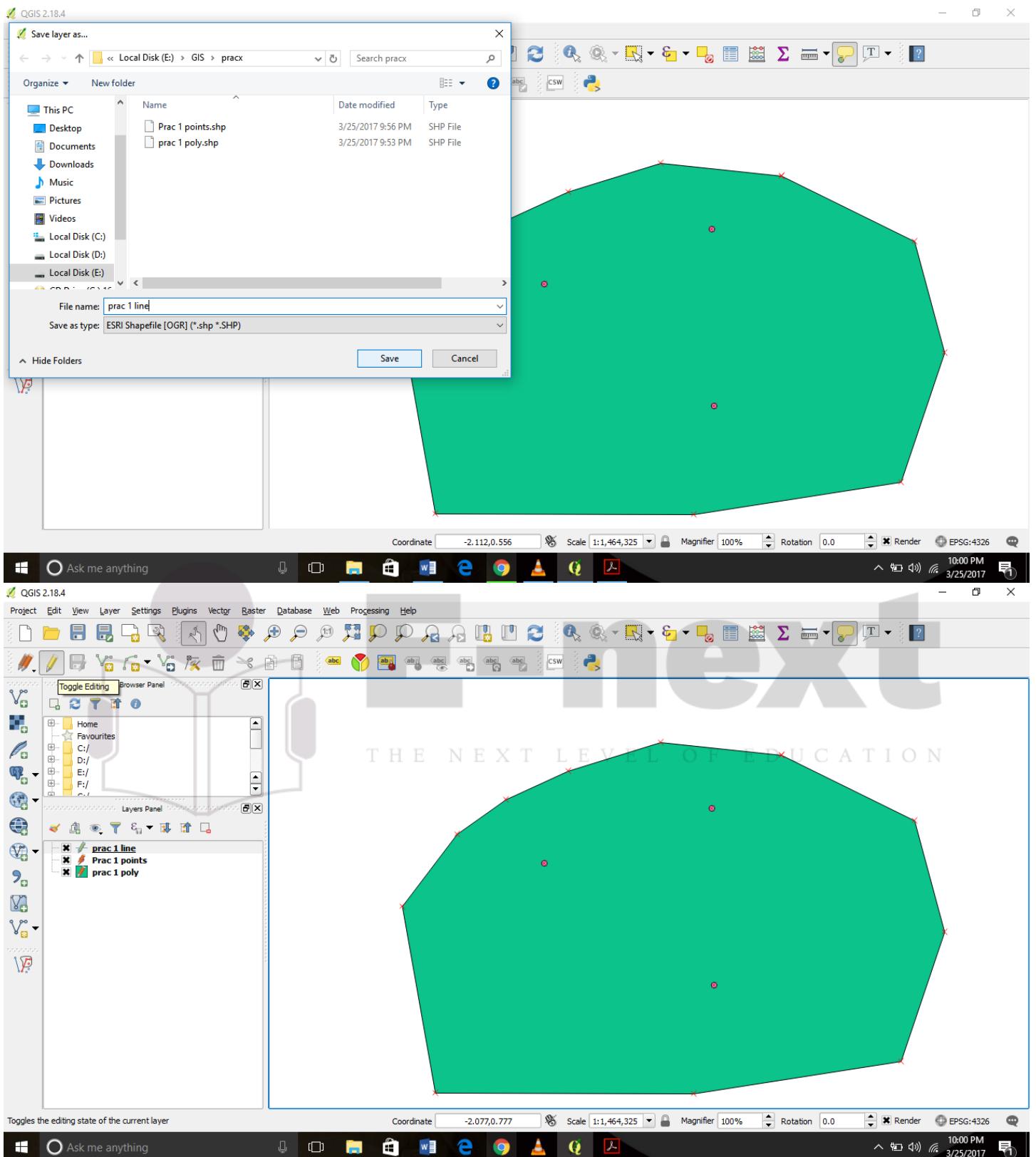
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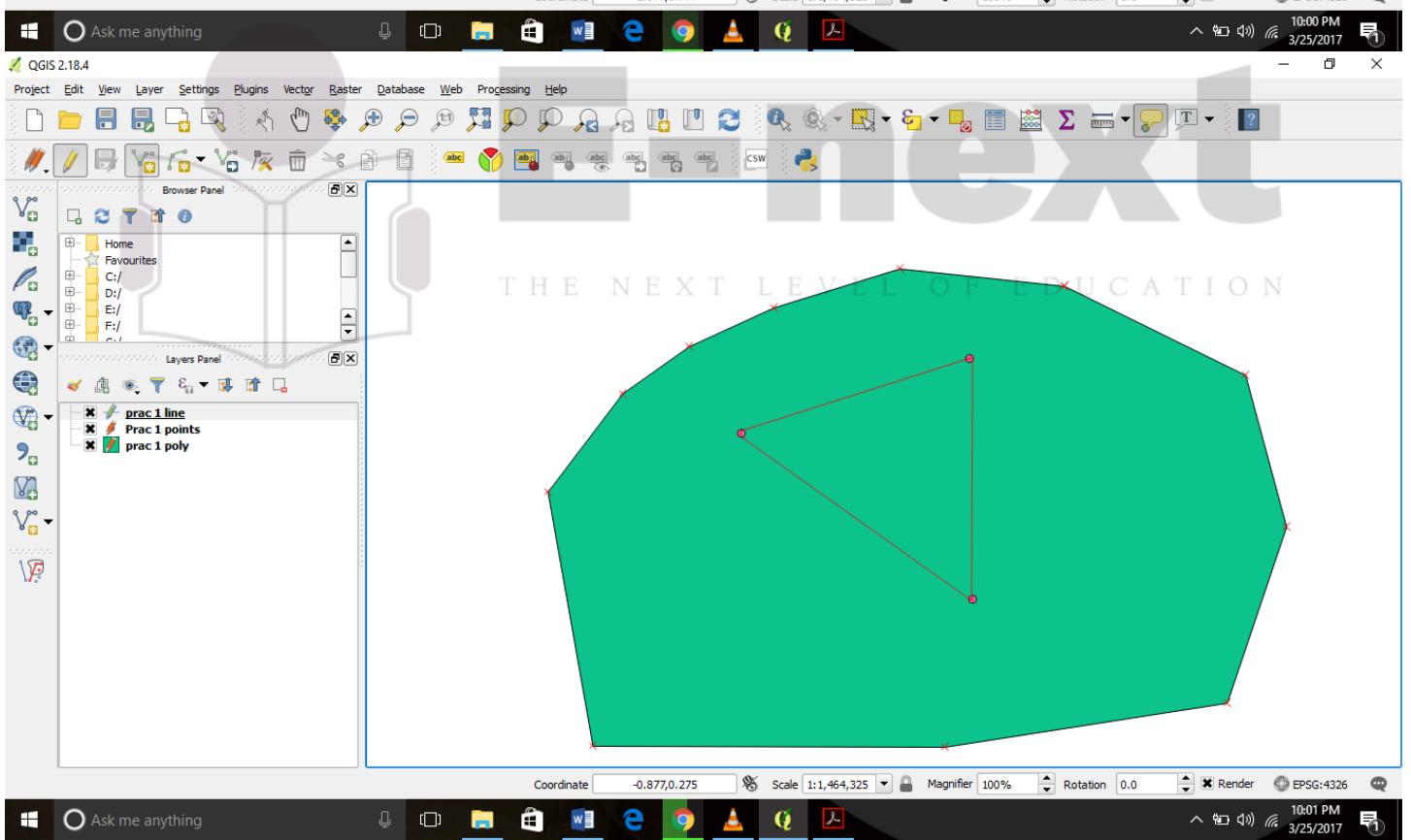
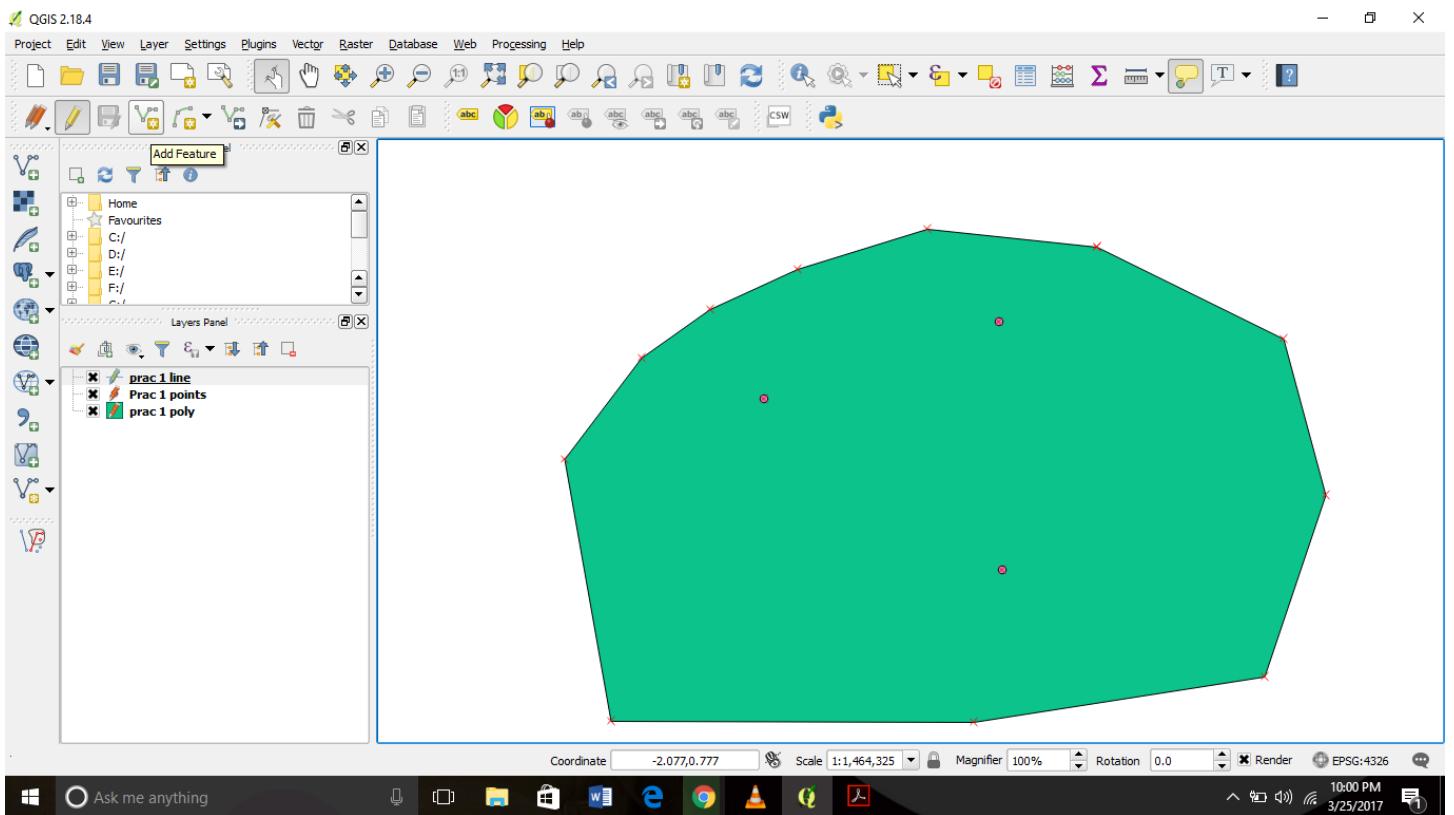
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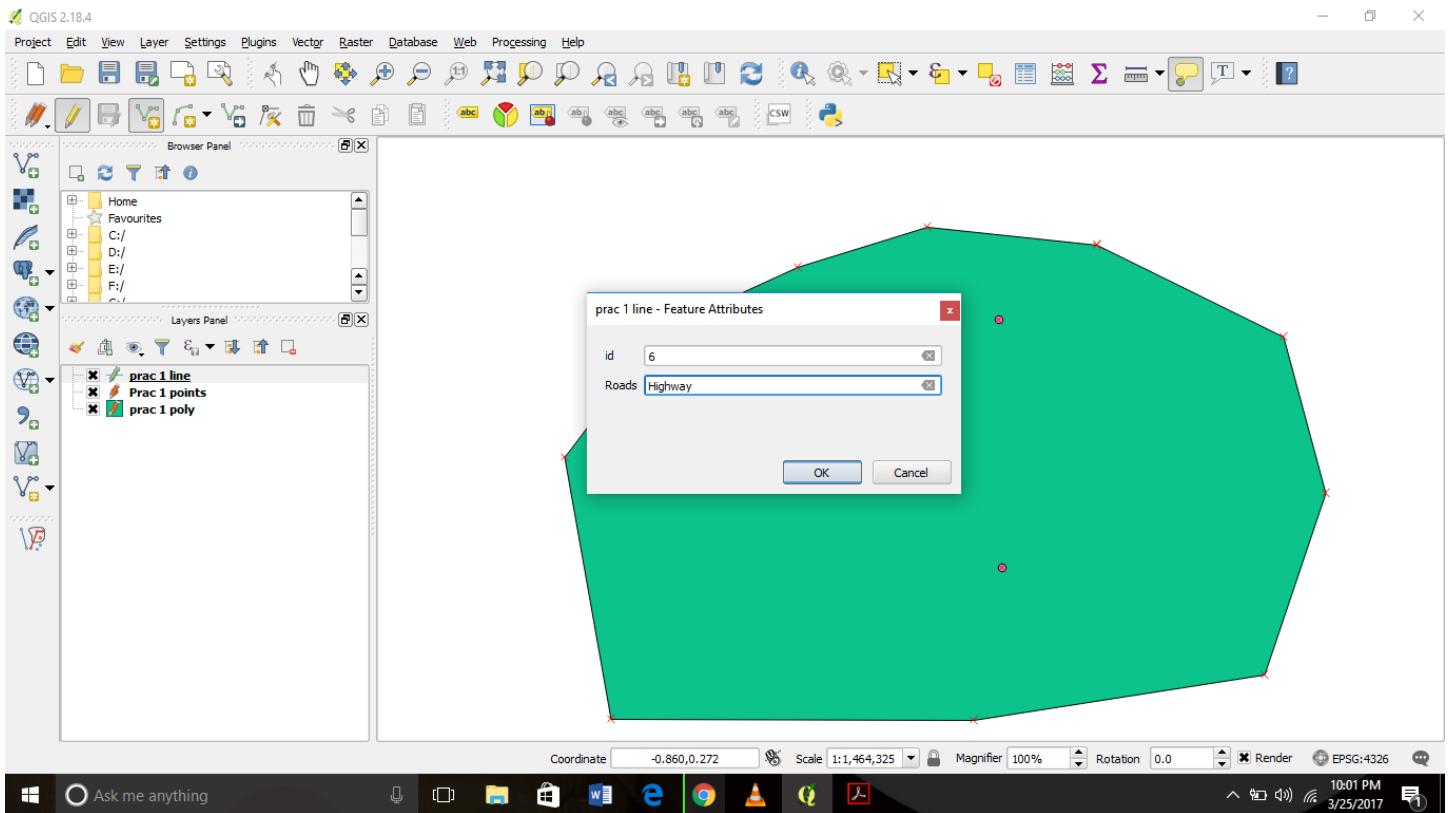
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[PRACTICAL 2]

GEO-RELATIONAL DATA MODEL

AIM: Creation of Geo-relational data model for Abhinav

Nagar

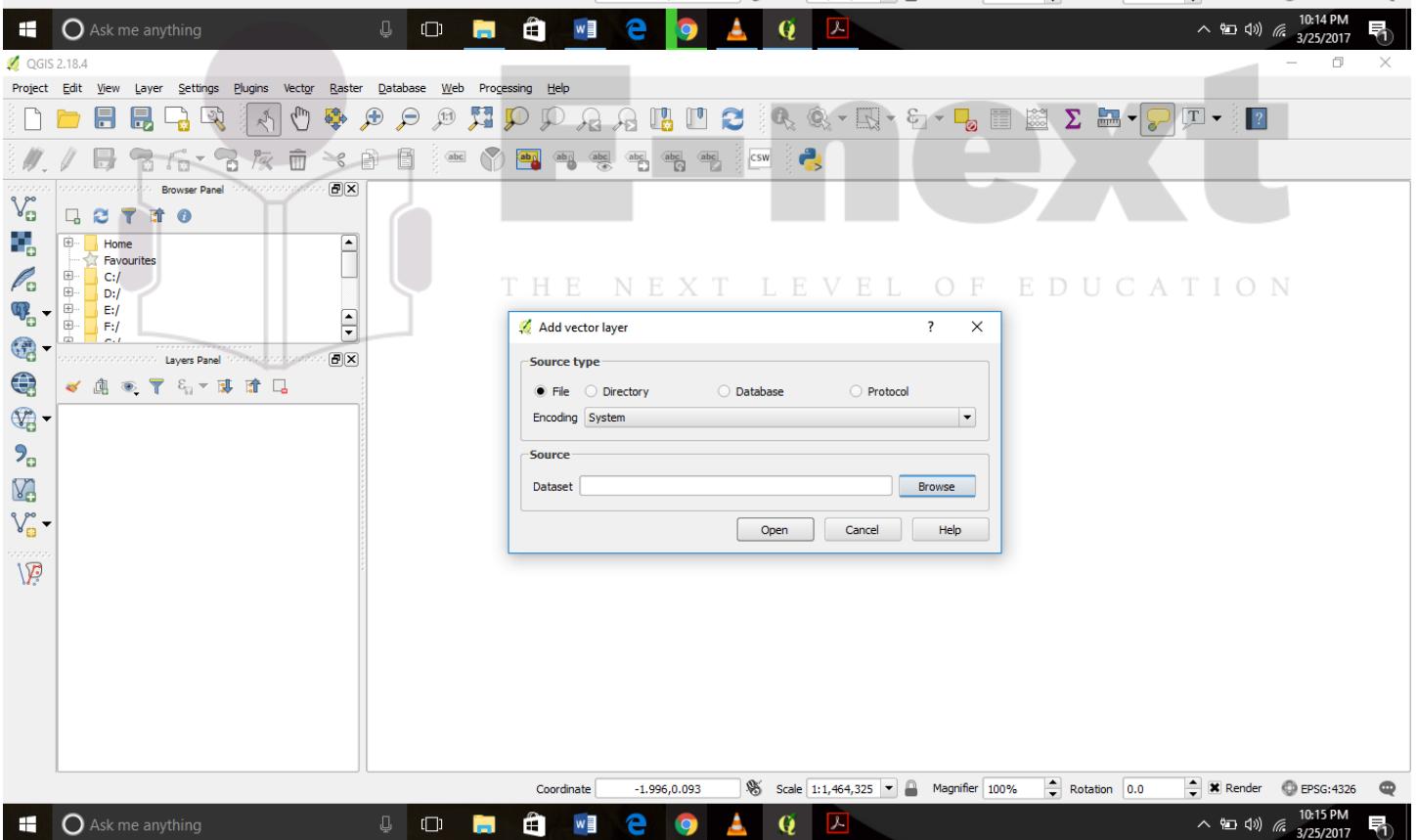
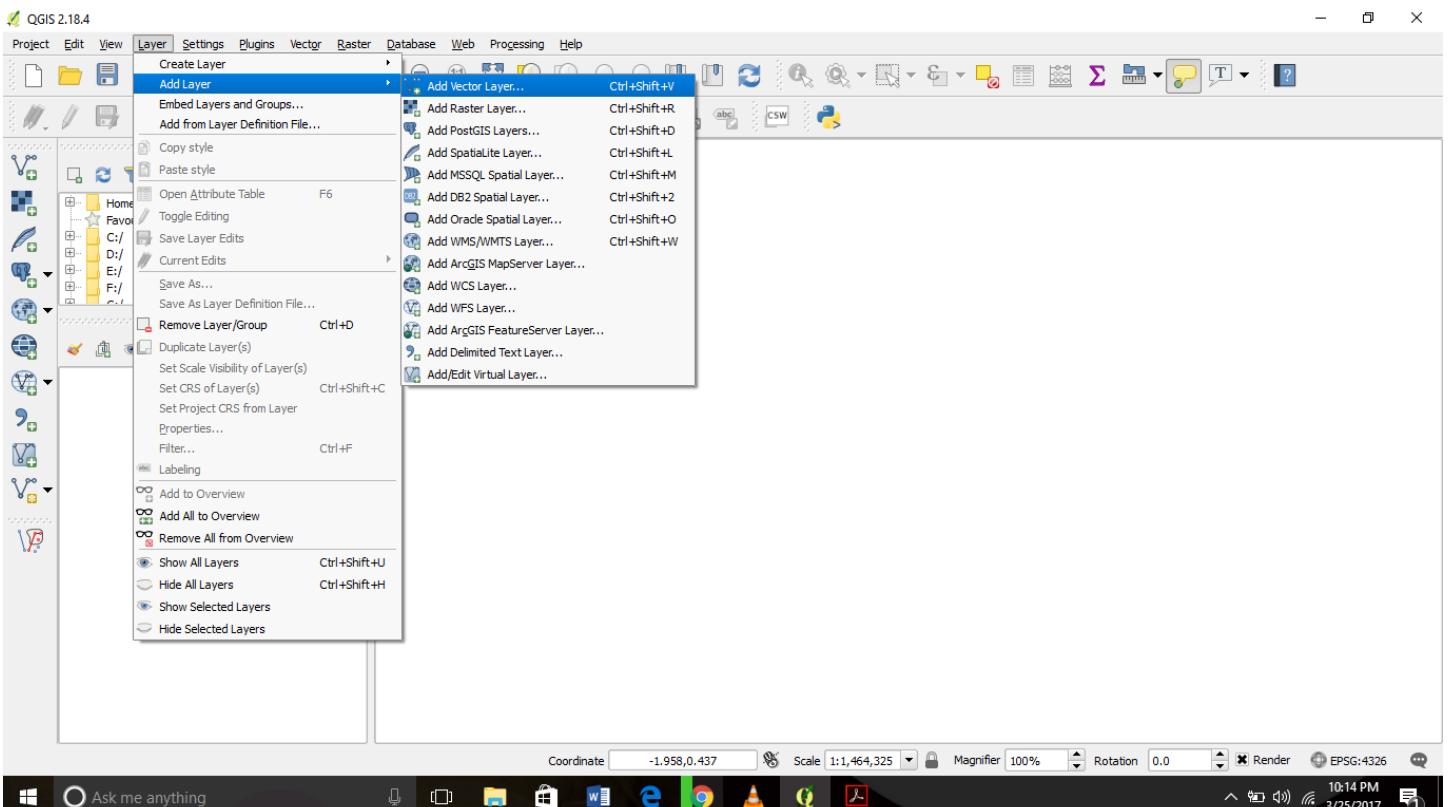
Data Model –

Data Models describe how the spatial features are represented in a GIS. There are various types of data models – Vector Data Model, Raster Data Model, Geo-relational Data Model, and Object-based Data Model.

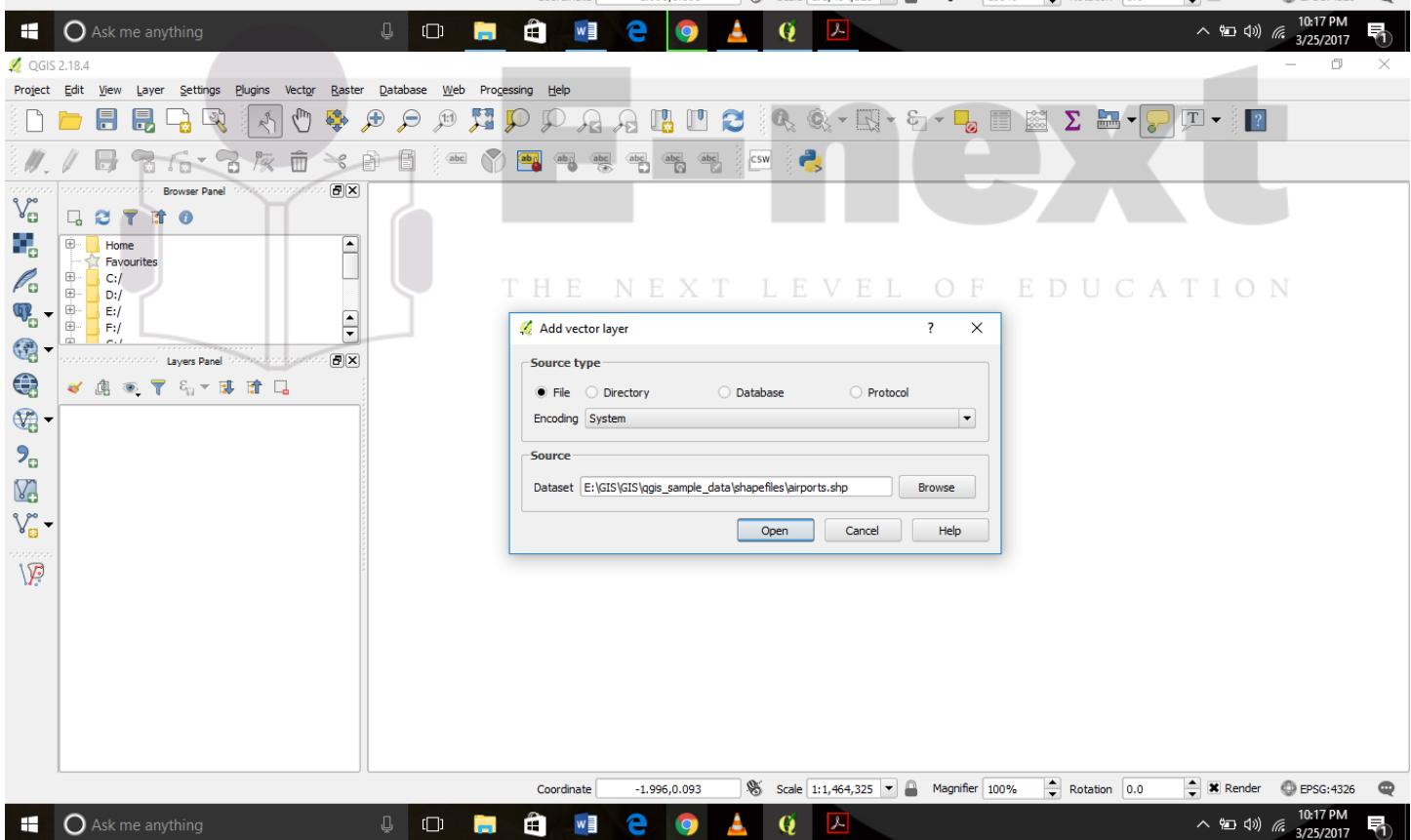
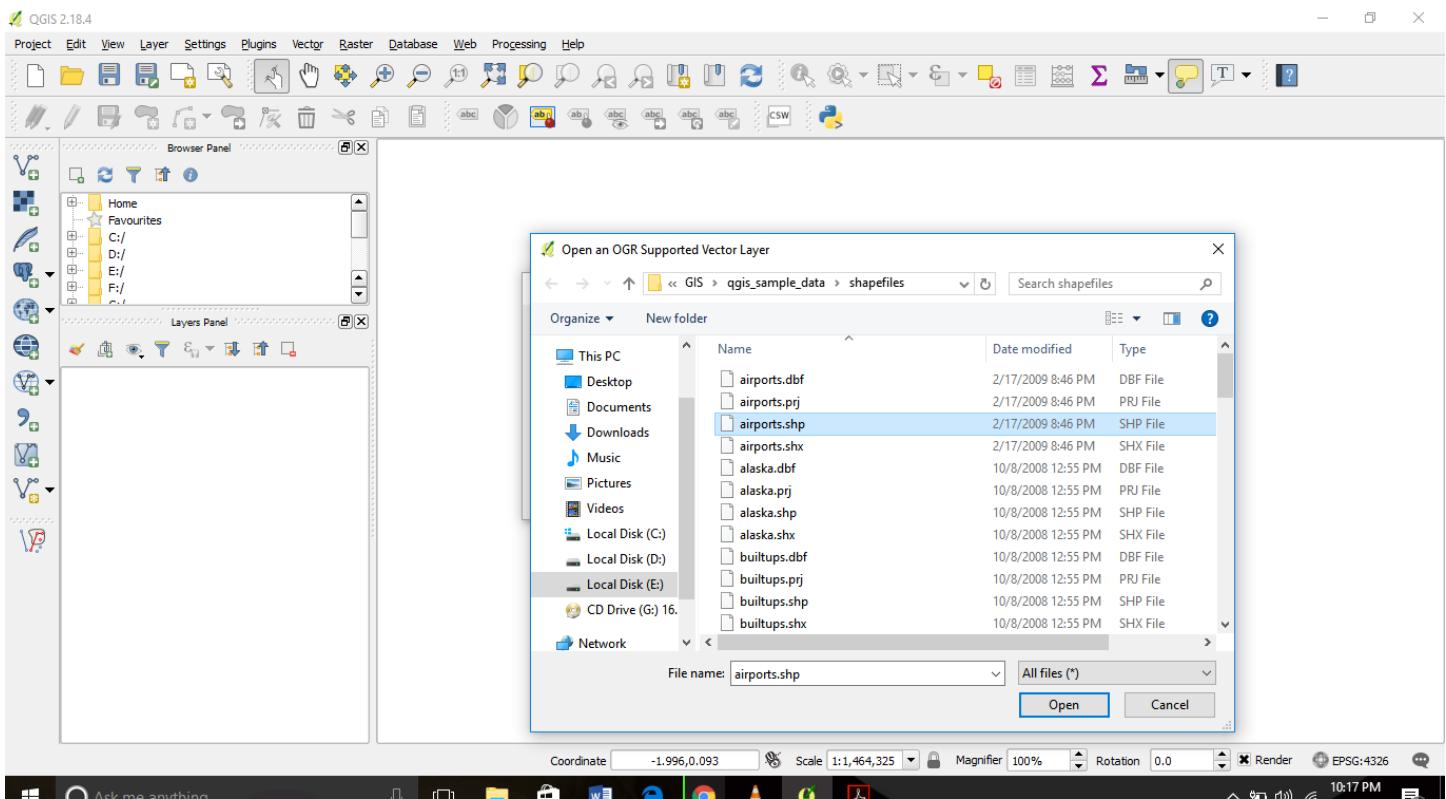
Geo-relational data model –

It stores the spatial and attributes data separately in a split system. Spatial data (also known as geo data) is stored in graphic files. Attribute data (info files) is stored in relational database. ID/ feature label is used to link the 2 components.

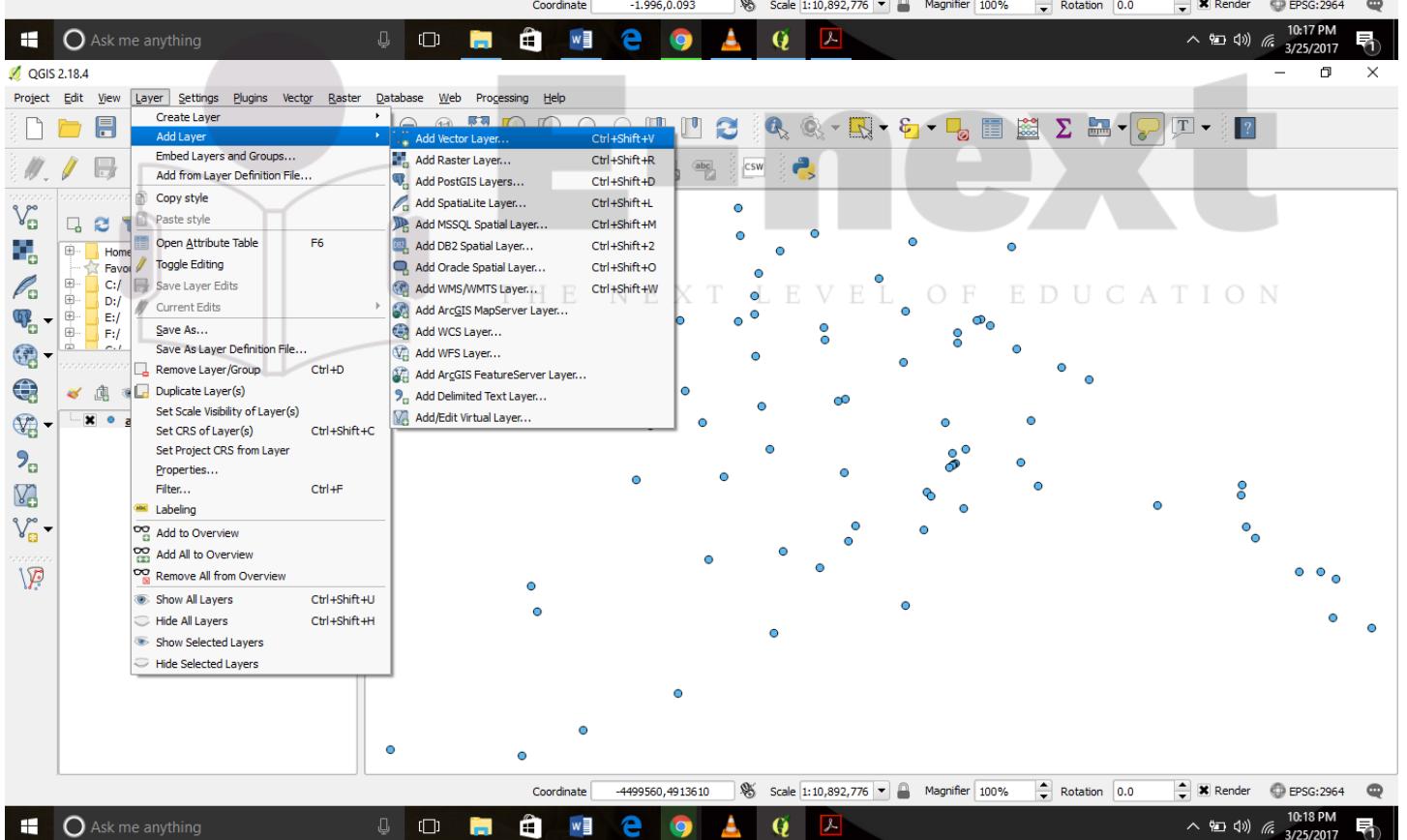
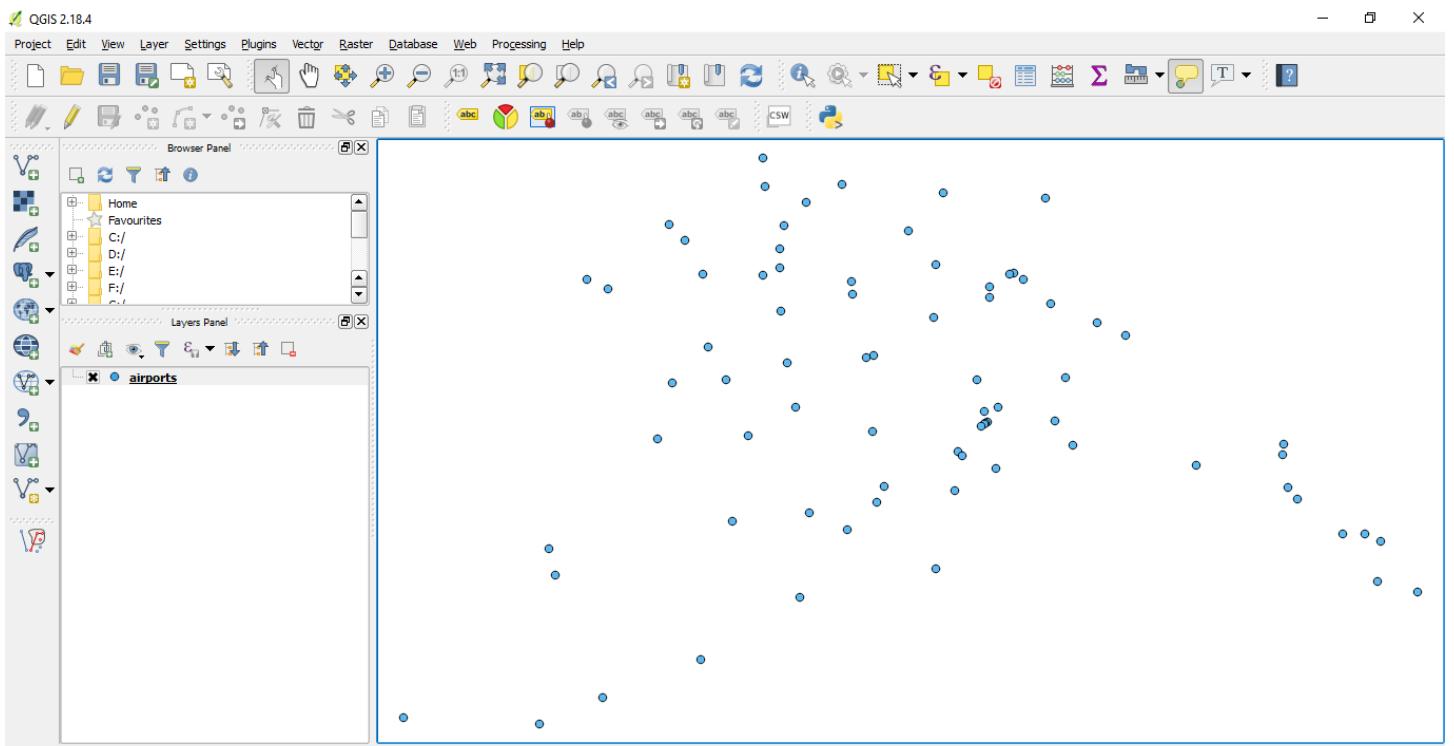
Attribute Tables –



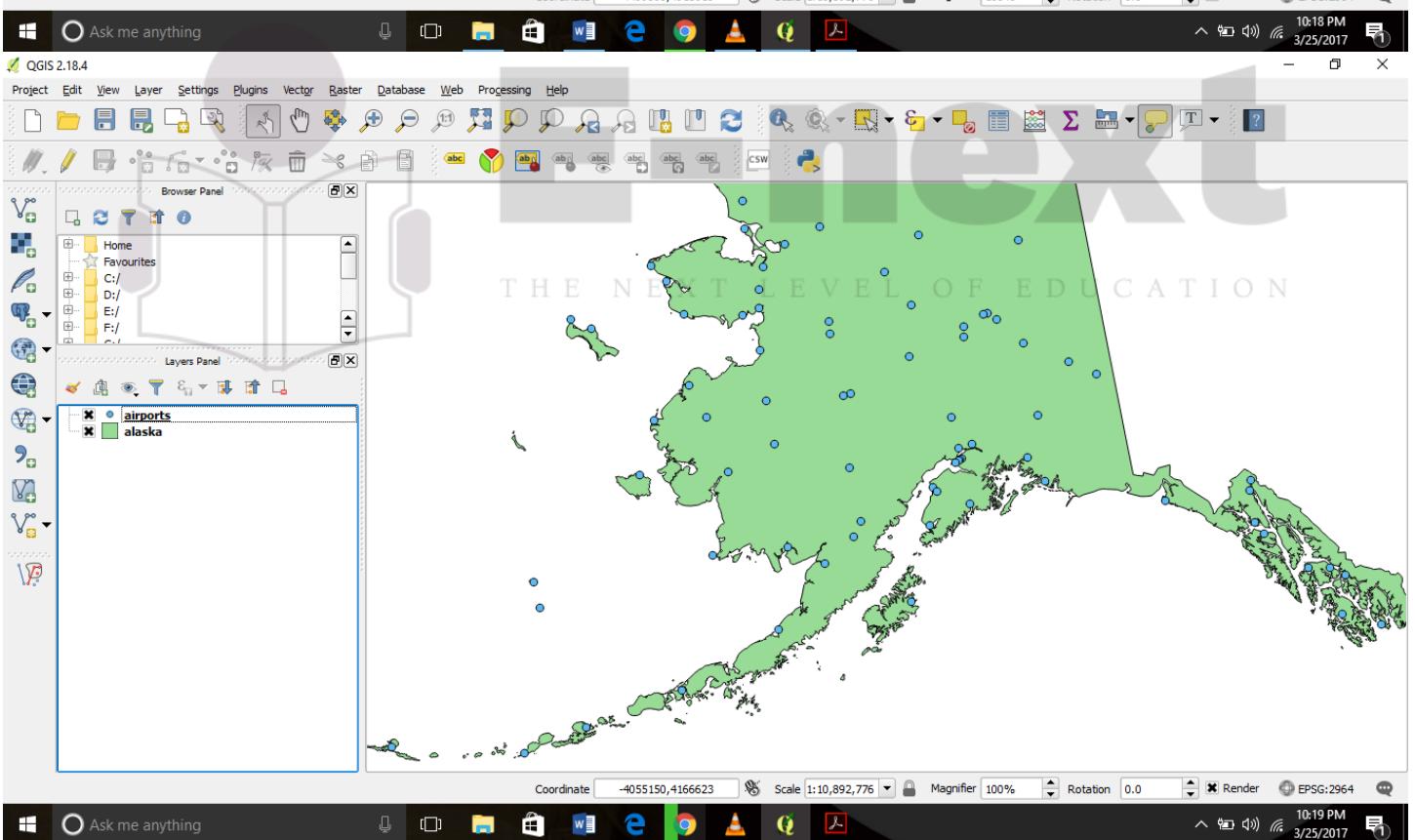
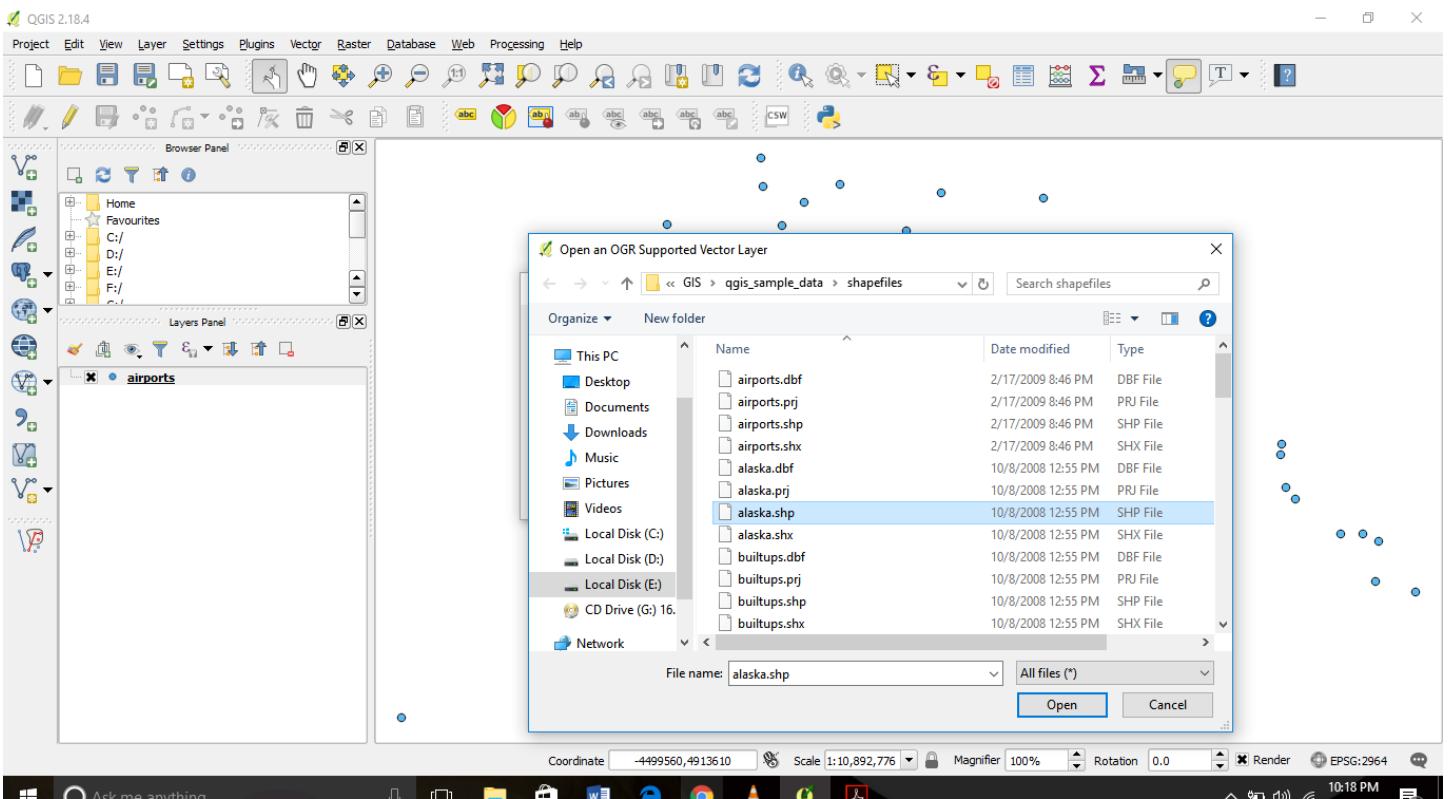
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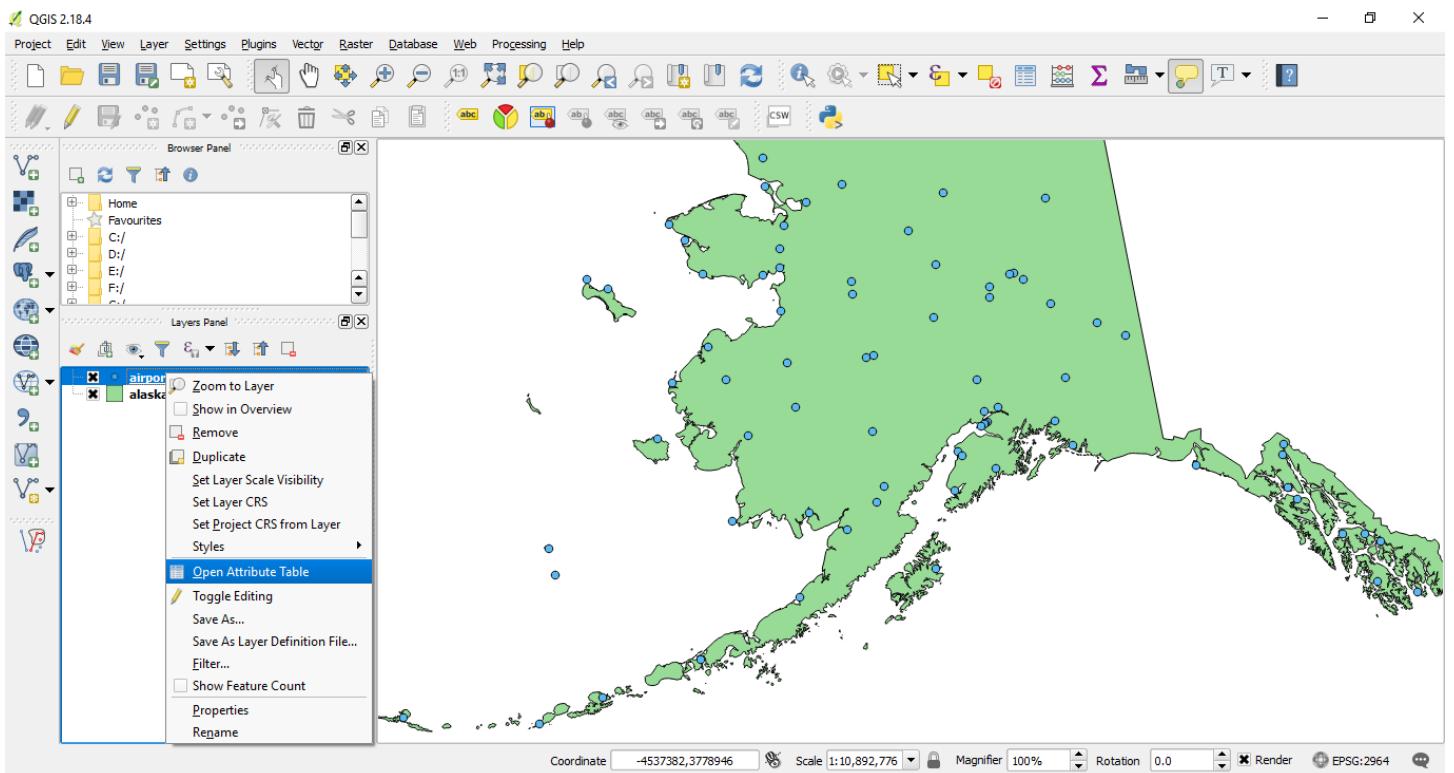
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A screenshot of QGIS 2.8.7-Wien. The main window shows the 'airports' attribute table with 76 features. The table has columns: cat, NA3, ELEV, F_CODE, IKO, NAME, and USE. The first few rows are listed below:

cat	NA3	ELEV	F_CODE	IKO	NAME	USE
1	US00157	78.000	Airport/Airfield	PA	NOATAK	Other
2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other
3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other
4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public
5	US00173	21.000	Airport/Airfield	PA	SELAWIK	Other
6	US00193	1113.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other
7	US00177	21.000	Airport/Airfield	PA	BUCKLAND	Other
8	US00146	243.000	Airport/Airfield	PATC	TIN CITY LRRS	Other
9	US00150	1329.000	Airport/Airfield	PA	GRANITE MOUNT...	Other
10	US003057	9.000	Airport/Airfield	PA	PORT CLARENCE...	Other
11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other
12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other
13	US75867	138.000	Airport/Airfield	PAGA	EDWARD G PITK...	Joint Military/Civil...
14	US60244	12.000	Airport/Airfield	PA	MOSES POINT	Other
15	US42171	33.000	Airport/Airfield	PAOM	NOME	Civilian/Public
16	US00211	1461.000	Airport/Airfield	PA	KALAKAKEET C...	Military

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airports :: Features total: 76, filtered: 76, selected: 0

123 cat E Update All Update Selected

cat	NA3	ELEV	F_CODE	IKO	NAME	USE
1	US00157	78.000	Airport/Airfield	PA	NOATAK	Other
2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other
3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other
4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public
5	US00173	21.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other
6	US00193	1113.000	Airport/Airfield	PA	EDWARD G PITK...	Joint Military/Civil...
7	US00177	21.000	Airport/Airfield	PA	MOSES POINT	Other
8	US00146	243.000	Airport/Airfield	PATC	NOME	Civilian/Public
9	US00150	1329.000	Airport/Airfield	PA	KALAKAKE...	Military
10	US03057	9.000	Airport/Airfield	PA		
11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other
12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other
13	US75867	138.000	Airport/Airfield	PAGA	BUCKLAND	Other
14	US60244	12.000	Airport/Airfield	PA	TIN CITY LRRS	Other
15	US42171	33.000	Airport/Airfield	PAOM	GRANITE MOUNT...	Other
16	US00211	1461.000	Airport/Airfield	PA	PORT CLARENCE...	Other

Add field ? OK Cancel

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Comment: For prac testing
Type: Whole number (integer)
Provider type: integer
Length: 0

Show All Features

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airports :: Features total: 76, filtered: 76, selected: 0

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2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other	NULL
3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other	NULL
4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public	NULL
5	US00173	21.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other	NULL
6	US00193	1113.000	Airport/Airfield	PA	EDWARD G PITK...	Joint Military/Civil...	NULL
7	US00177	21.000	Airport/Airfield	PA	MOSES POINT	Other	NULL
8	US00146	243.000	Airport/Airfield	PATC	NOME	Civilian/Public	NULL
9	US00150	1329.000	Airport/Airfield	PA	KALAKAKE...	Military	NULL
10	US03057	9.000	Airport/Airfield	PA	RALPH M CALHO...	Other	NULL
11	US00188	207.000	Airport/Airfield	PATA	KOYUK	Other	NULL
12	US00155	108.000	Airport/Airfield	PA	TIN CITY LRRS	Other	NULL
13	US75867	138.000	Airport/Airfield	PAGA	GRANITE MOUNT...	Other	NULL
14	US60244	12.000	Airport/Airfield	PA	PORT CLARENCE...	Other	NULL
15	US42171	33.000	Airport/Airfield	PAOM	KOYUK	Other	NULL
16	US00211	1461.000	Airport/Airfield	PA	TIN CITY LRRS	Other	NULL

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airports :: Features total: 76, filtered: 76, selected: 0

123 cat Delete field (Ctrl+L) Update All Update Selected

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1	1	US00157	78.000	Airport/Airfield	PA	NOATAK	Other	NULL
2	2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other	NULL
3	3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other	NULL
4	4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public	NULL
5	5	US00173	21.000	Airport/Airfield	PA	SELAWIK	Other	NULL
6	6	US00193	1113.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other	NULL
7	7	US00177	21.000	Airport/Airfield	PA	BUCKLAND	Other	NULL
8	8	US00146	243.000	Airport/Airfield	PATC	TIN CITY LRRS	Other	NULL
9	9	US00150	1329.000	Airport/Airfield	PA	GRANITE MOUNT...	Other	NULL
10	10	US03057	9.000	Airport/Airfield	PA	PORT CLARENCE...	Other	NULL
11	11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other	NULL
12	12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other	NULL
13	13	US75867	138.000	Airport/Airfield	PAGA	EDWARD G PITK...	Joint Military/Civil...	NULL
14	14	US60244	12.000	Airport/Airfield	PA	MOSES POINT	Other	NULL
15	15	US42171	33.000	Airport/Airfield	PAOM	NOME	Civilian/Public	NULL
16	US00211	1461.000	Airport/Airfield	PA	KAIAKAKET COE	Military	NULL	NULL

Show All Features

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airports :: Features total: 76, filtered: 76, selected: 0

123 cat Delete fields ? X

- cat
- NA3
- ELEV
- F_CODE
- IKO
- NAME
- USE
- Test

OK Cancel

	cat	NA3	ELEV	F_CODE	IKO	NAME	USE	Test
1	1	US00157	78.000	Airport/Airfield	PA	NOATAK	Other	NULL
2	2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other	NULL
3	3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other	NULL
4	4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public	NULL
5	5	US00173	21.000	Airport/Airfield	PA	SELAWIK	Other	NULL
6	6	US00193	1113.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other	NULL
7	7	US00177	21.000	Airport/Airfield	PA	BUCKLAND	Other	NULL
8	8	US00146	243.000	Airport/Airfield	PATC	TIN CITY LRRS	Other	NULL
9	9	US00150	1329.000	Airport/Airfield	PA	GRANITE MOUNT...	Other	NULL
10	10	US03057	9.000	Airport/Airfield	PA	PORT CLARENCE...	Other	NULL
11	11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other	NULL
12	12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other	NULL
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14	14	US60244	12.000	Airport/Airfield	PA	MOSES POINT	Other	NULL
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16	US00211	1461.000	Airport/Airfield	PA	KAIAKAKET COE	Military	NULL	NULL

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QGIS 2.18.4

Project Edit View Layer Settings Plugins Vector Raster Database Web Processing Help

airports :: Features total: 76, filtered: 76, selected: 0

123 cat

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2	US00229	264.000	Airport/Airfield	PA	AMBLER	Other
3	US00186	585.000	Airport/Airfield	PABT	BETTLES	Other
4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public
5	US00173	21.000	Airport/Airfield	PA	SELAWIK	Other
6	US00193	1113.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other
7	US00177	21.000	Airport/Airfield	PA	BUCKLAND	Other
8	US00146	243.000	Airport/Airfield	PATC	TIN CITY LRRS	Other
9	US00150	1329.000	Airport/Airfield	PA	GRANITE MOUNT...	Other
10	US03057	9.000	Airport/Airfield	PA	PORT CLARENCE...	Other
11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other
12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other
13	US75867	138.000	Airport/Airfield	PAGA	EDWARD G PITK...	Joint Military/Civil...
14	US60244	12.000	Airport/Airfield	PA	MOSES POINT	Other
15	US42171	33.000	Airport/Airfield	PAOM	NOME	Civilian/Public
16	US00211	1461.000	Airport/Airfield	PA	KALAKAKEET COE	Military

Show All Features

Coordinate -1152301,1320507 Scale 1:10,892,776 Magnifier 100% Rotation 0.0 Render EPSG:2964 10:22 PM 3/25/2017

QGIS 2.18.4

Project Edit View Layer Settings Plugins Vector Raster Database Web Processing Help

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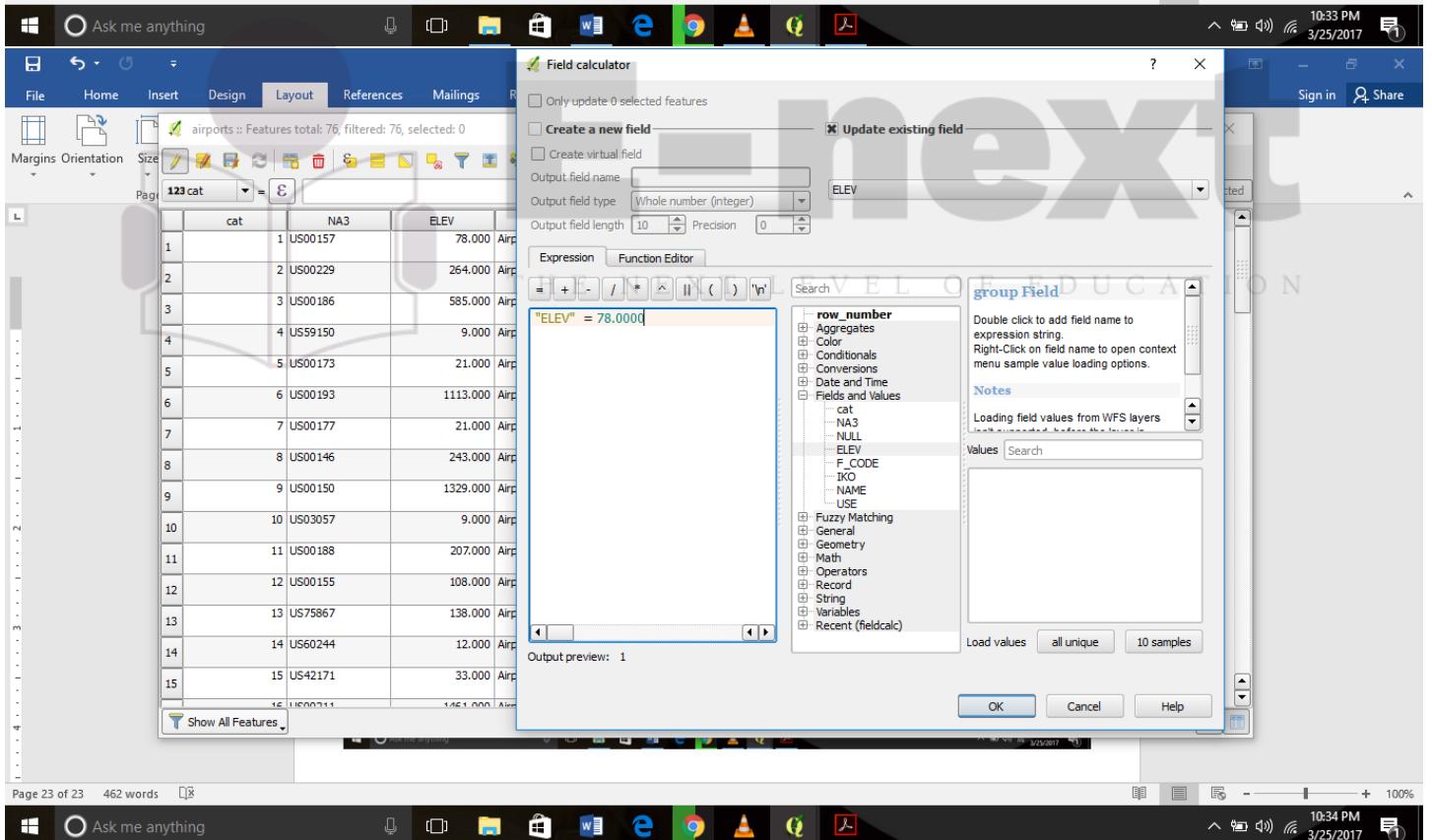
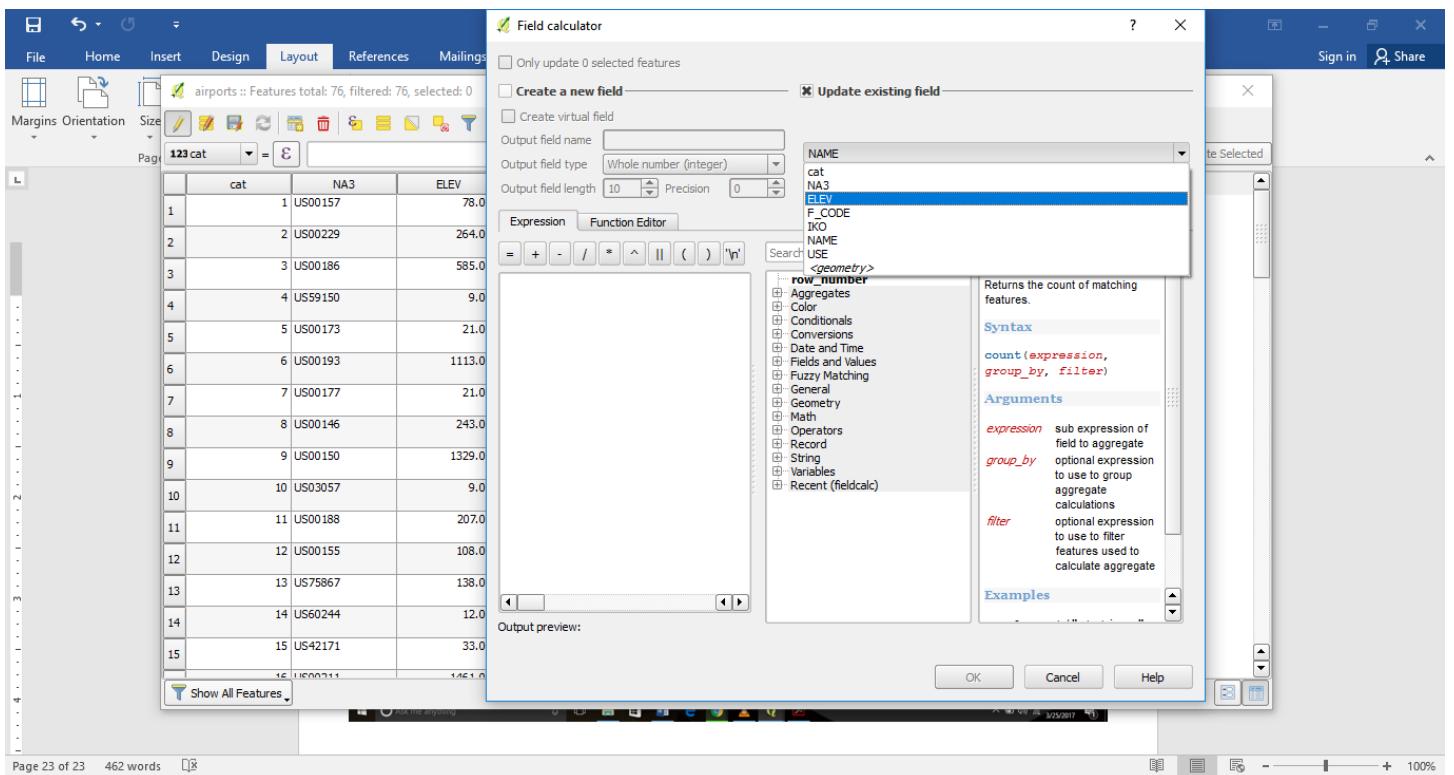
Open field calculator (Ctrl+I)

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4	US59150	9.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public
5	US00173	21.000	Airport/Airfield	PA	SELAWIK	Other
6	US00193	1113.000	Airport/Airfield	PA	INDIAN MOUNTA...	Other
7	US00177	21.000	Airport/Airfield	PA	BUCKLAND	Other
8	US00146	243.000	Airport/Airfield	PATC	TIN CITY LRRS	Other
9	US00150	1329.000	Airport/Airfield	PA	GRANITE MOUNT...	Other
10	US03057	9.000	Airport/Airfield	PA	PORT CLARENCE...	Other
11	US00188	207.000	Airport/Airfield	PATA	RALPH M CALHO...	Other
12	US00155	108.000	Airport/Airfield	PA	KOYUK	Other
13	US75867	138.000	Airport/Airfield	PAGA	EDWARD G PITK...	Joint Military/Civil...
14	US60244	12.000	Airport/Airfield	PA	MOSES POINT	Other
15	US42171	33.000	Airport/Airfield	PAOM	NOME	Civilian/Public
16	US00211	1461.000	Airport/Airfield	PA	KALAKAKEET COE	Military

Show All Features

Coordinate -1350867,1339418 Scale 1:10,892,776 Magnifier 100% Rotation 0.0 Render EPSG:2964 10:24 PM 3/25/2017

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GIS Final prax for Pioneer - Word

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airports :: Features total: 76, filtered: 76, selected: 0

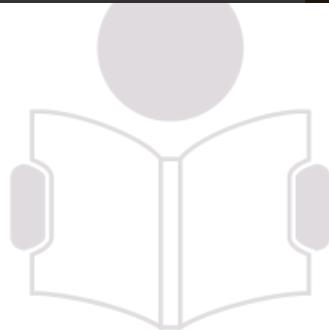
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4	US59150	0.000	Airport/Airfield	PAOT	RALPH WIEN MEM	Civilian/Public
5	US00173	0.000	Airport/Airfield	PA	SELAWIK	Other
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7	US00177	0.000	Airport/Airfield	PA	BUCKLAND	Other
8	US00146	0.000	Airport/Airfield	PATC	TIN CITY LRRS	Other
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12	US00155	0.000	Airport/Airfield	PA	KOYUK	Other
13	US75867	0.000	Airport/Airfield	PAGA	EDWARD G PITK...	Joint Military/Civil...
14	US60244	0.000	Airport/Airfield	PA	MOSES POINT	Other
15	US42171	0.000	Airport/Airfield	PAOM	NOME	Civilian/Public
16	US00711	0.000	Airport/Airfield	PA	KALAKAET COE	Military

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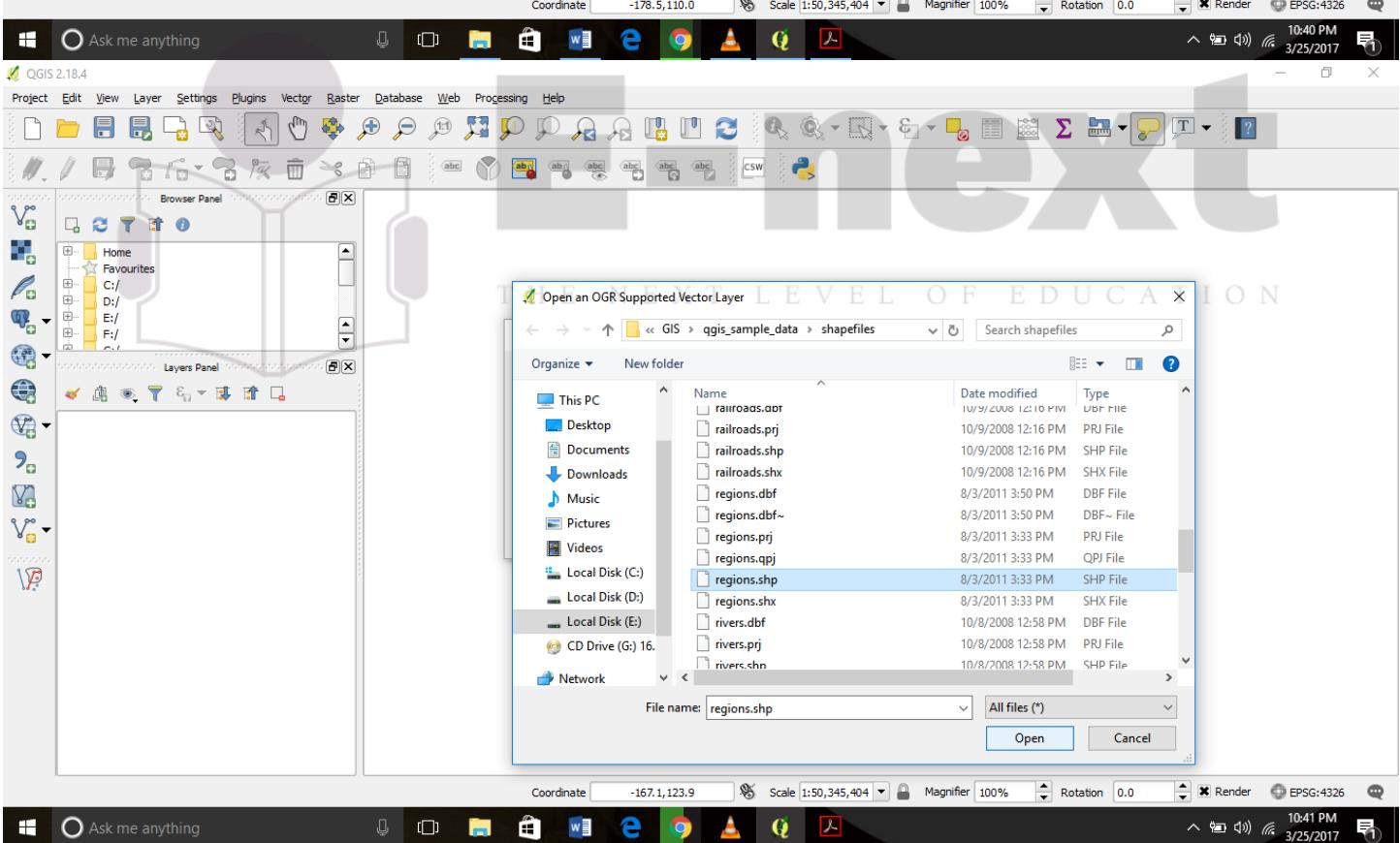
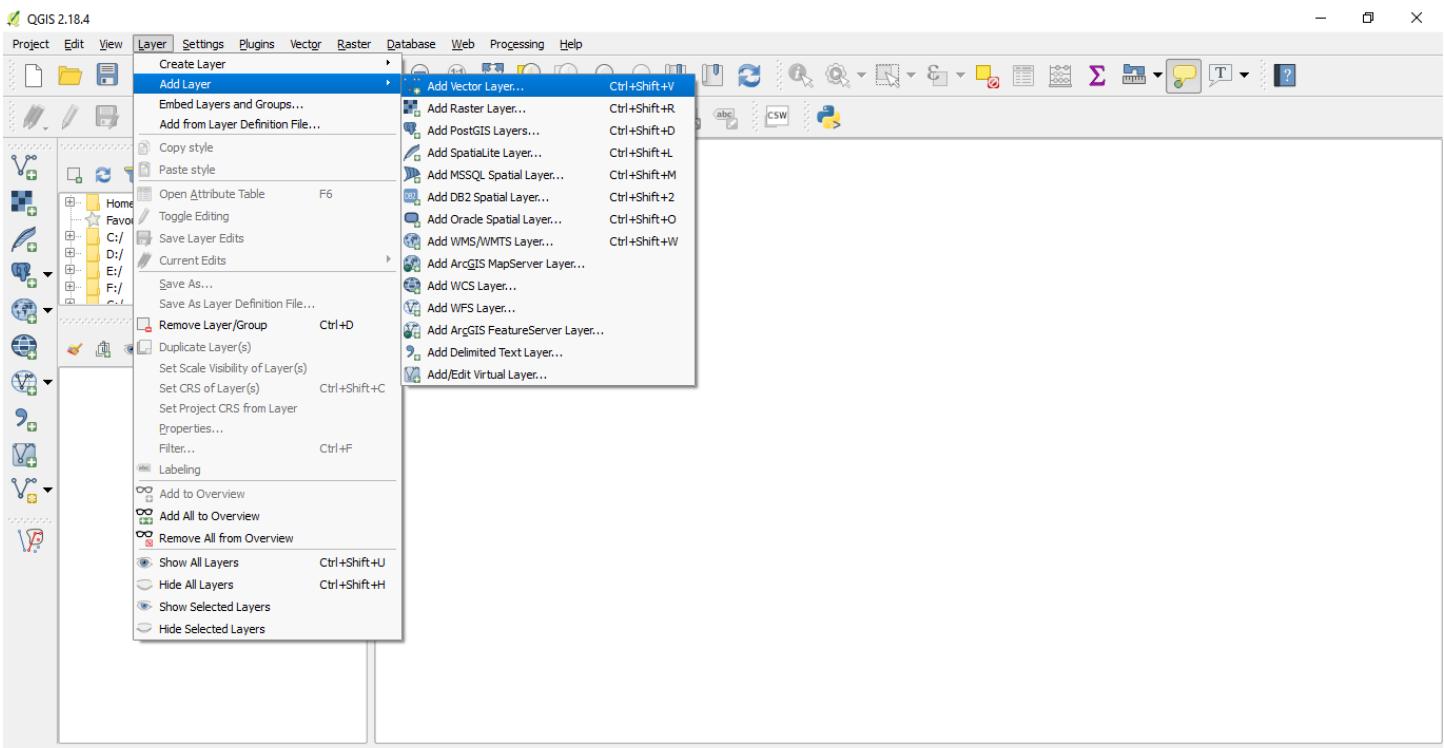
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3/25/2017



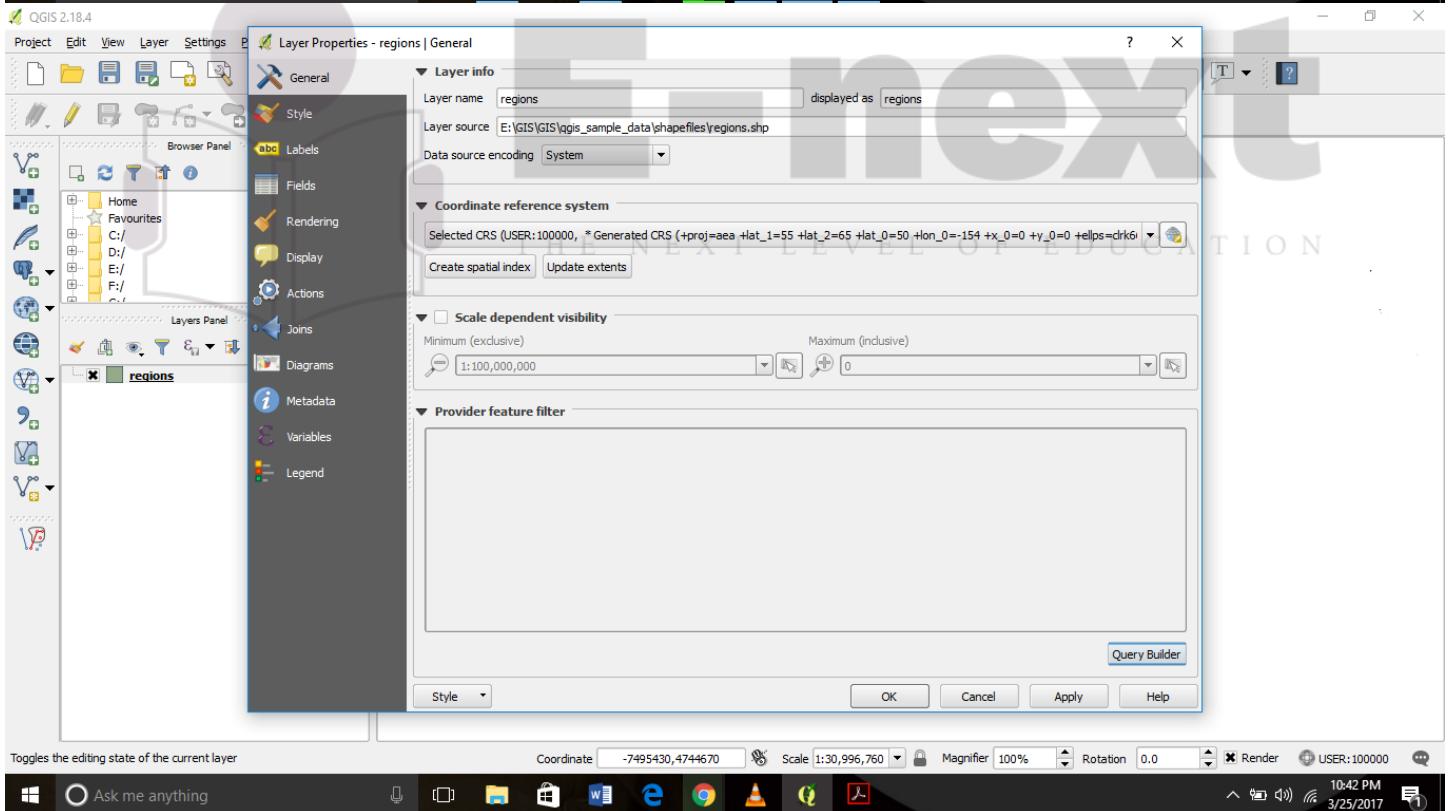
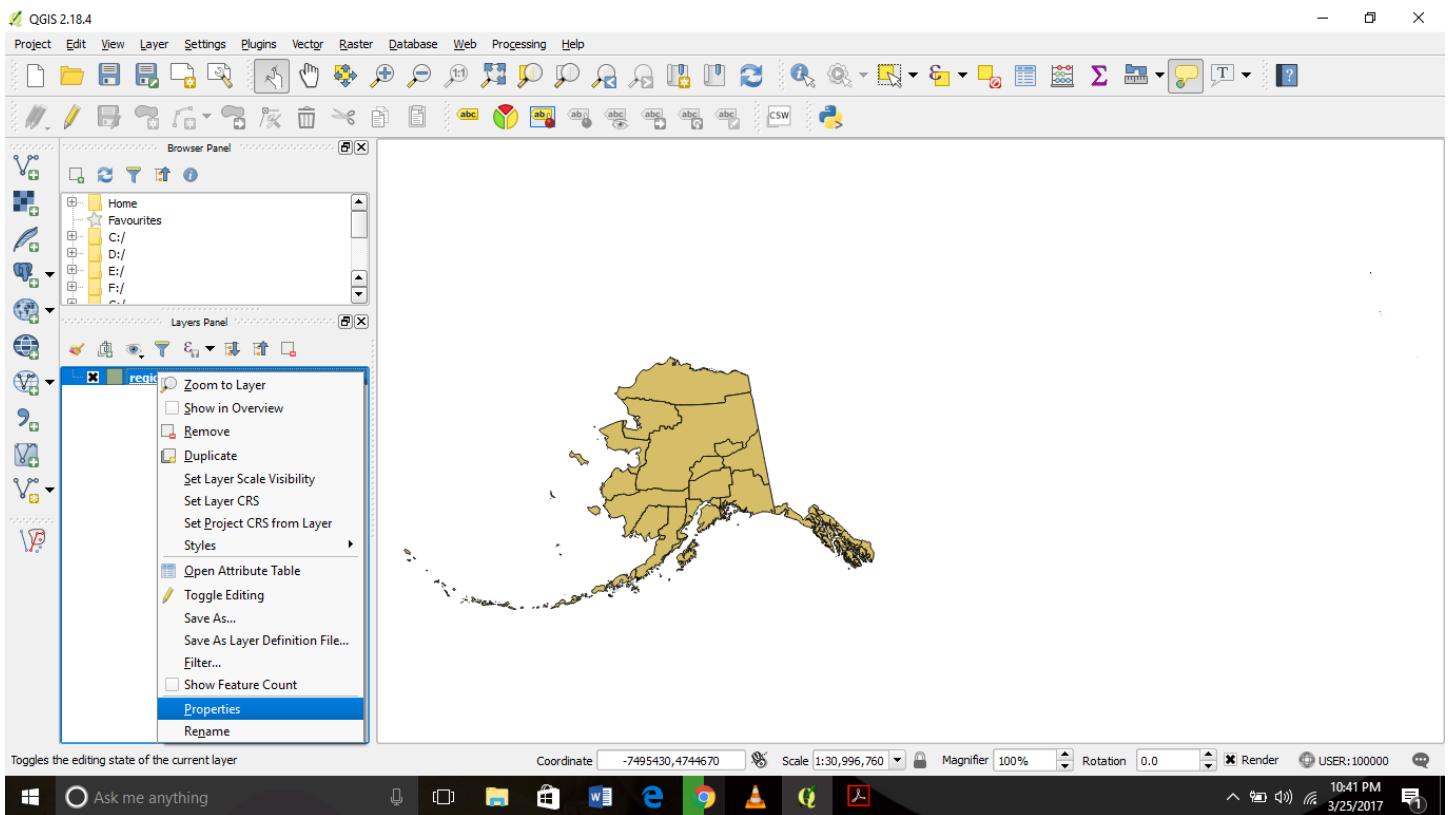
E-next

THE NEXT LEVEL OF EDUCATION

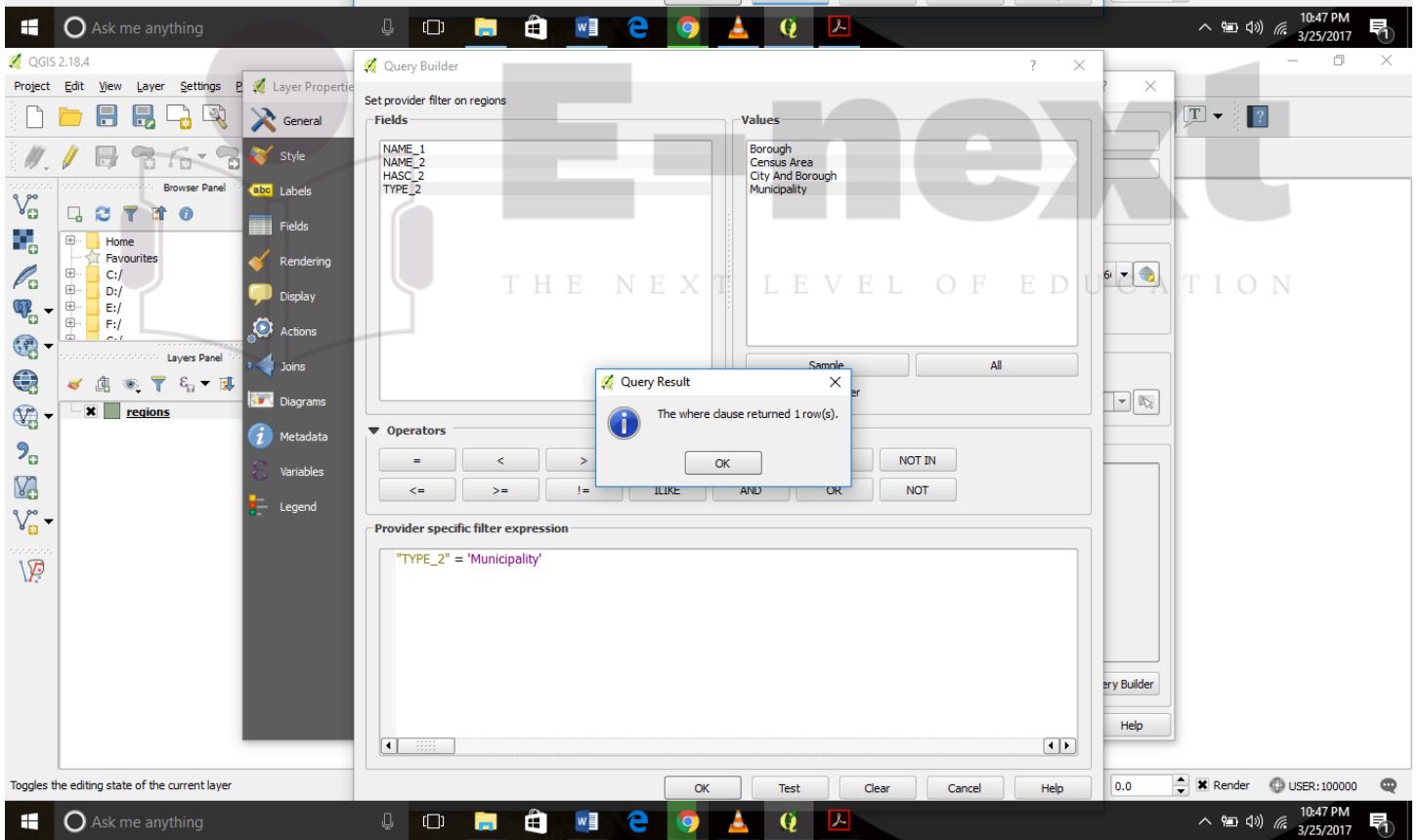
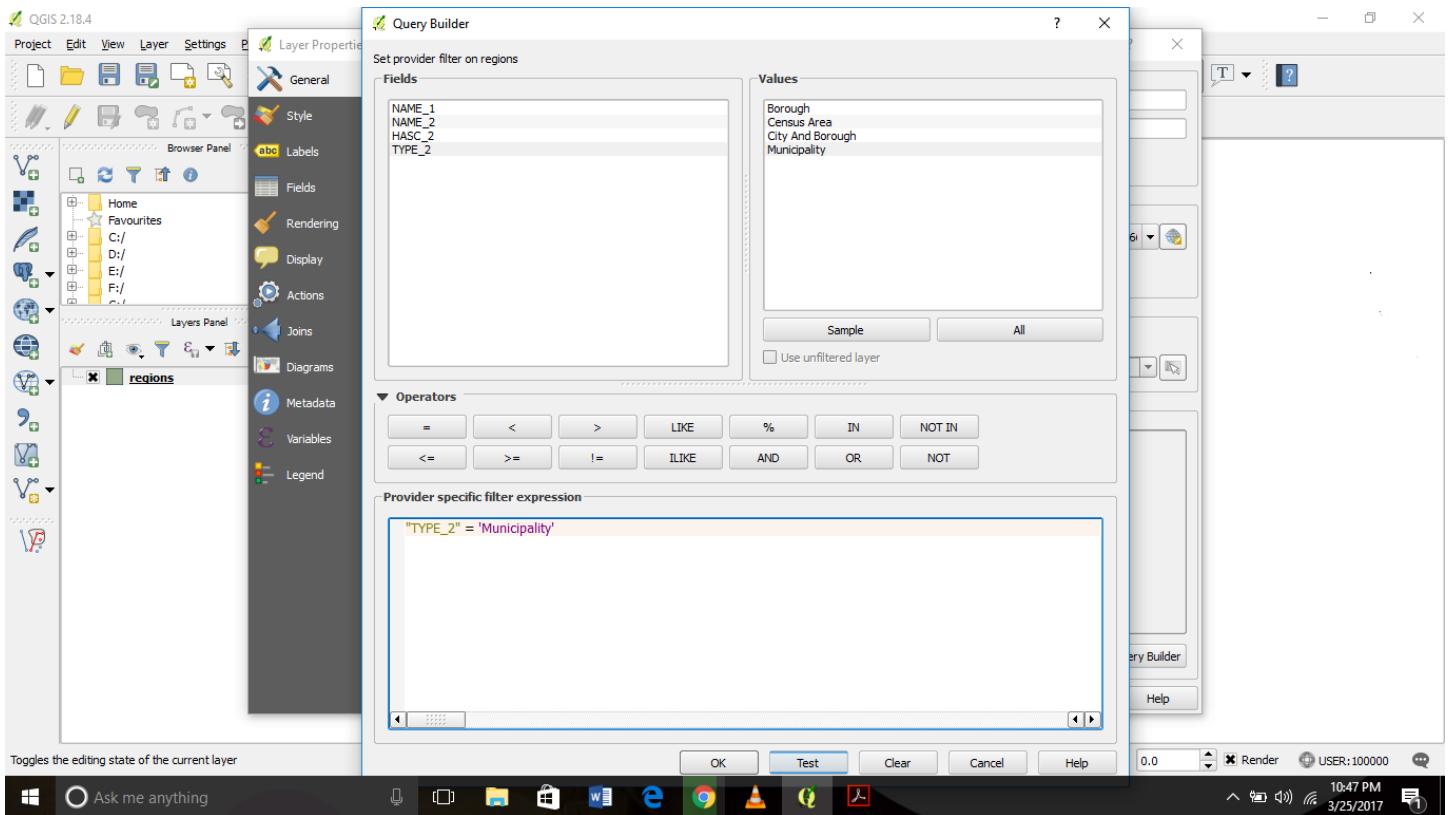
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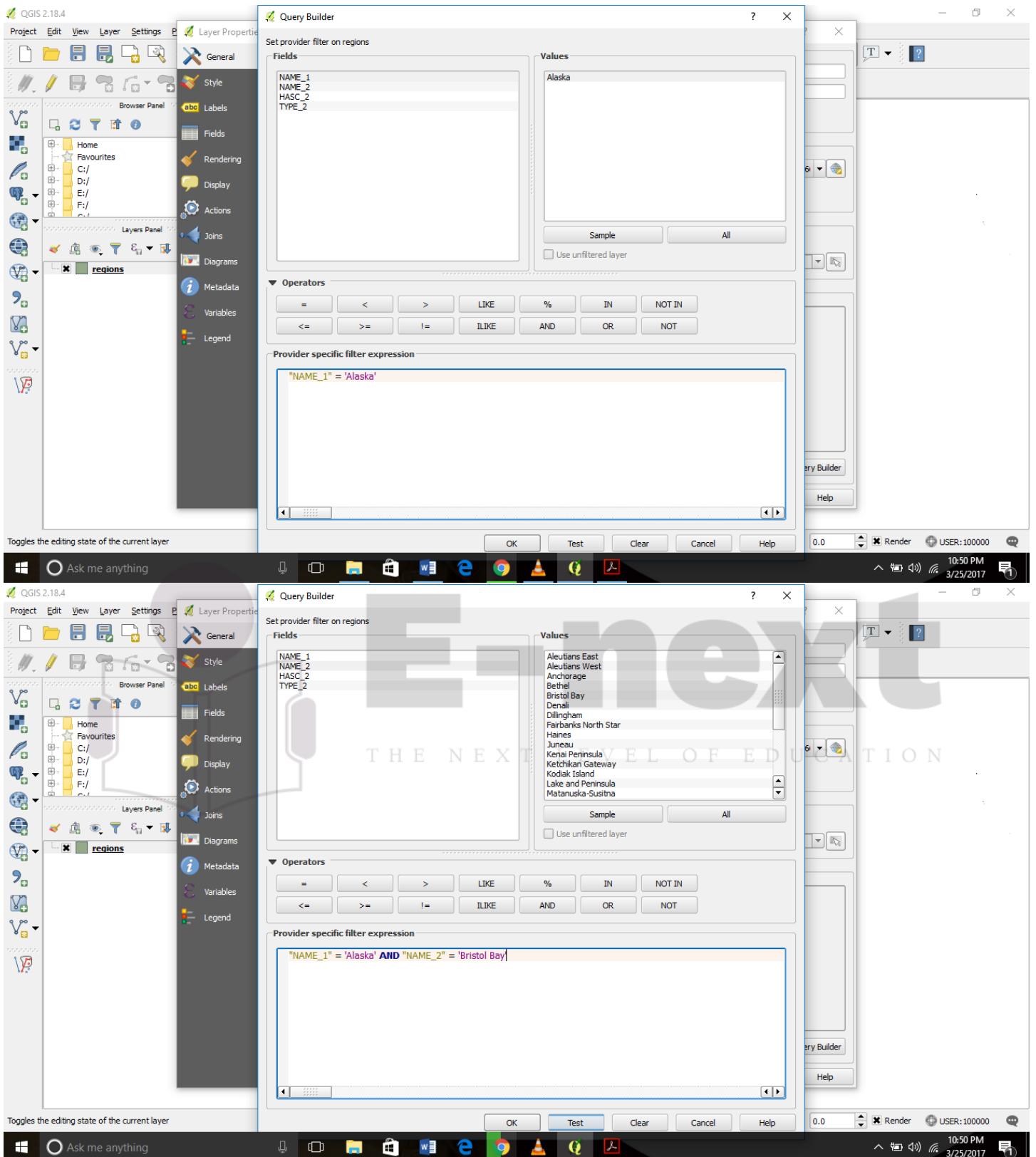
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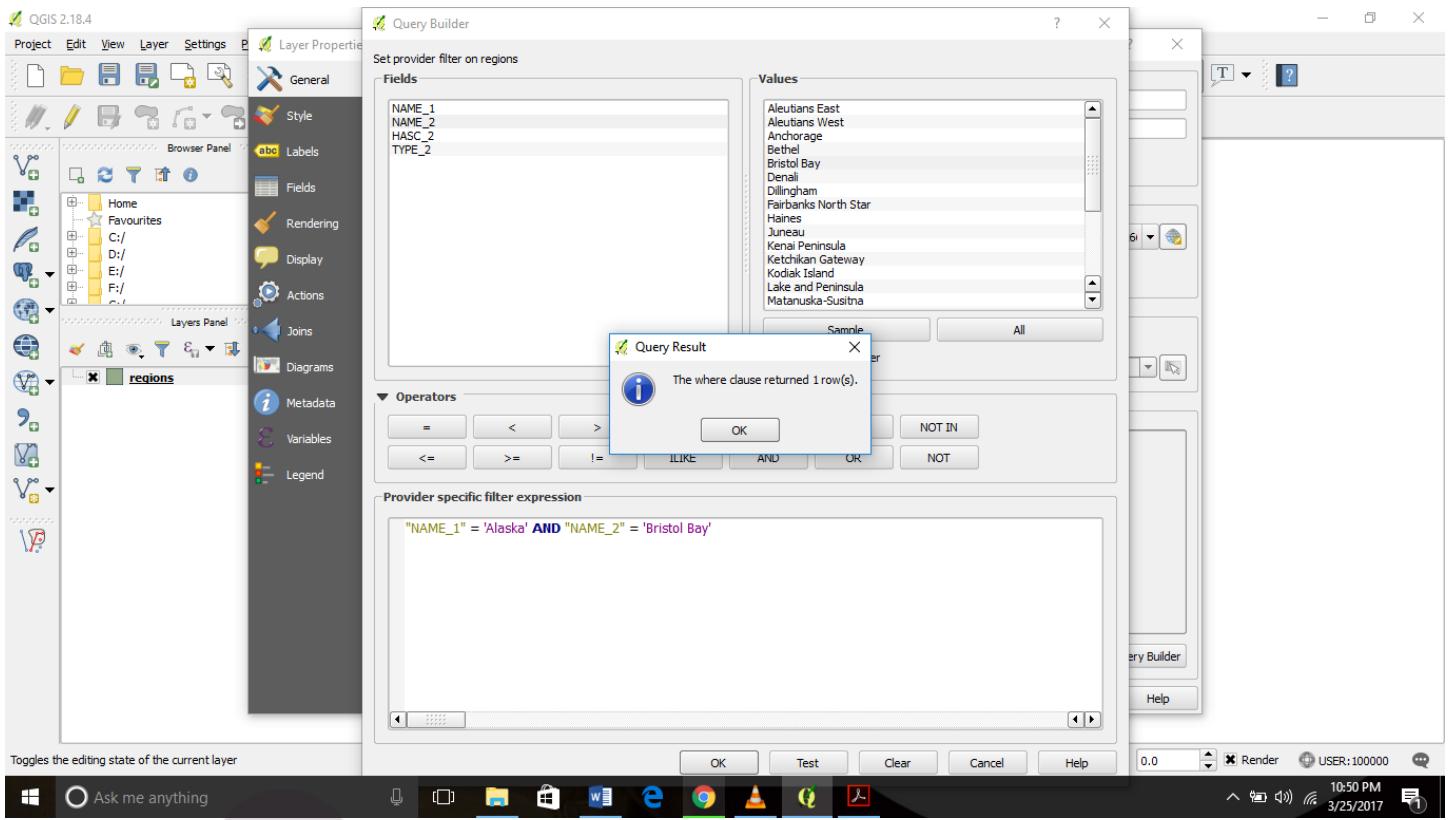
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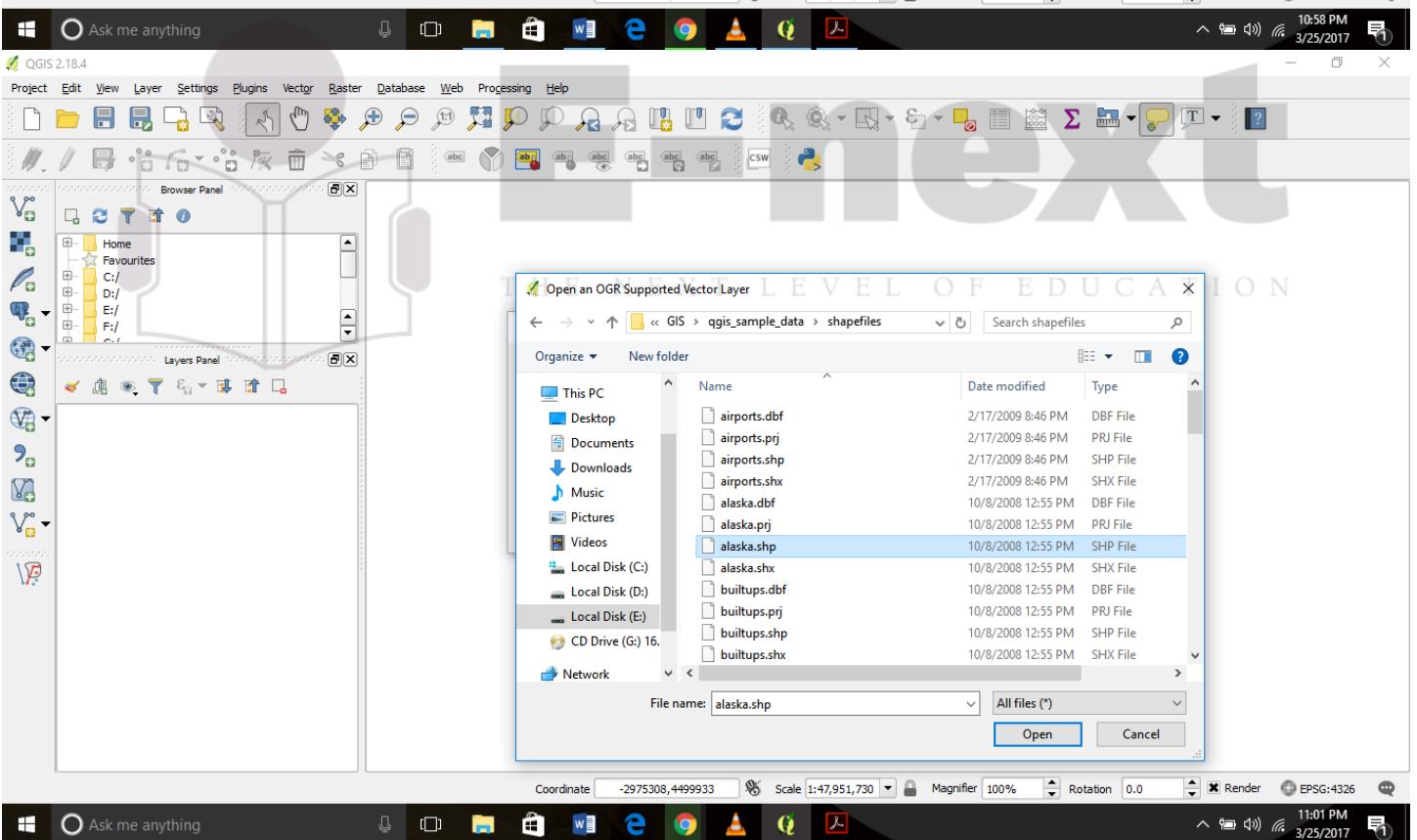
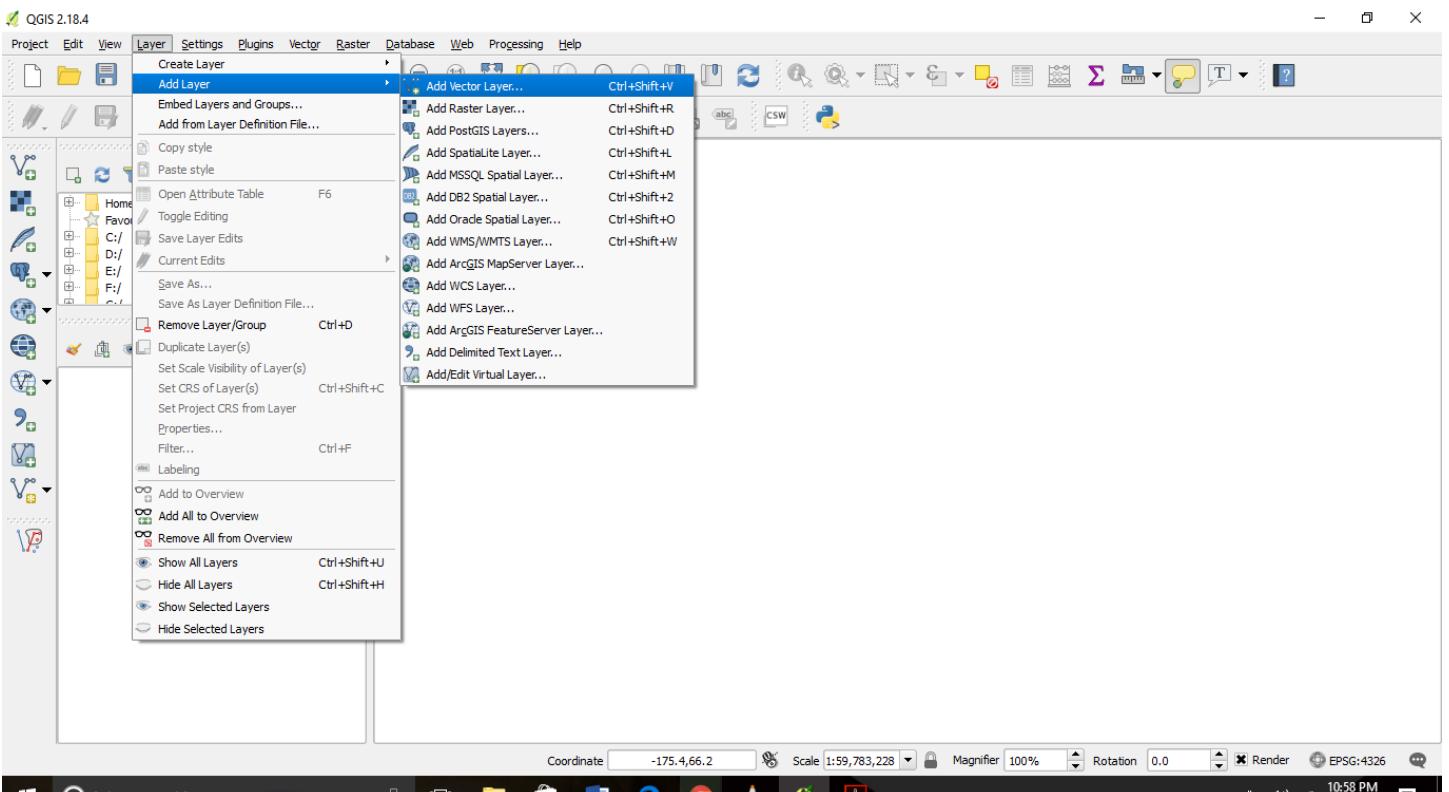
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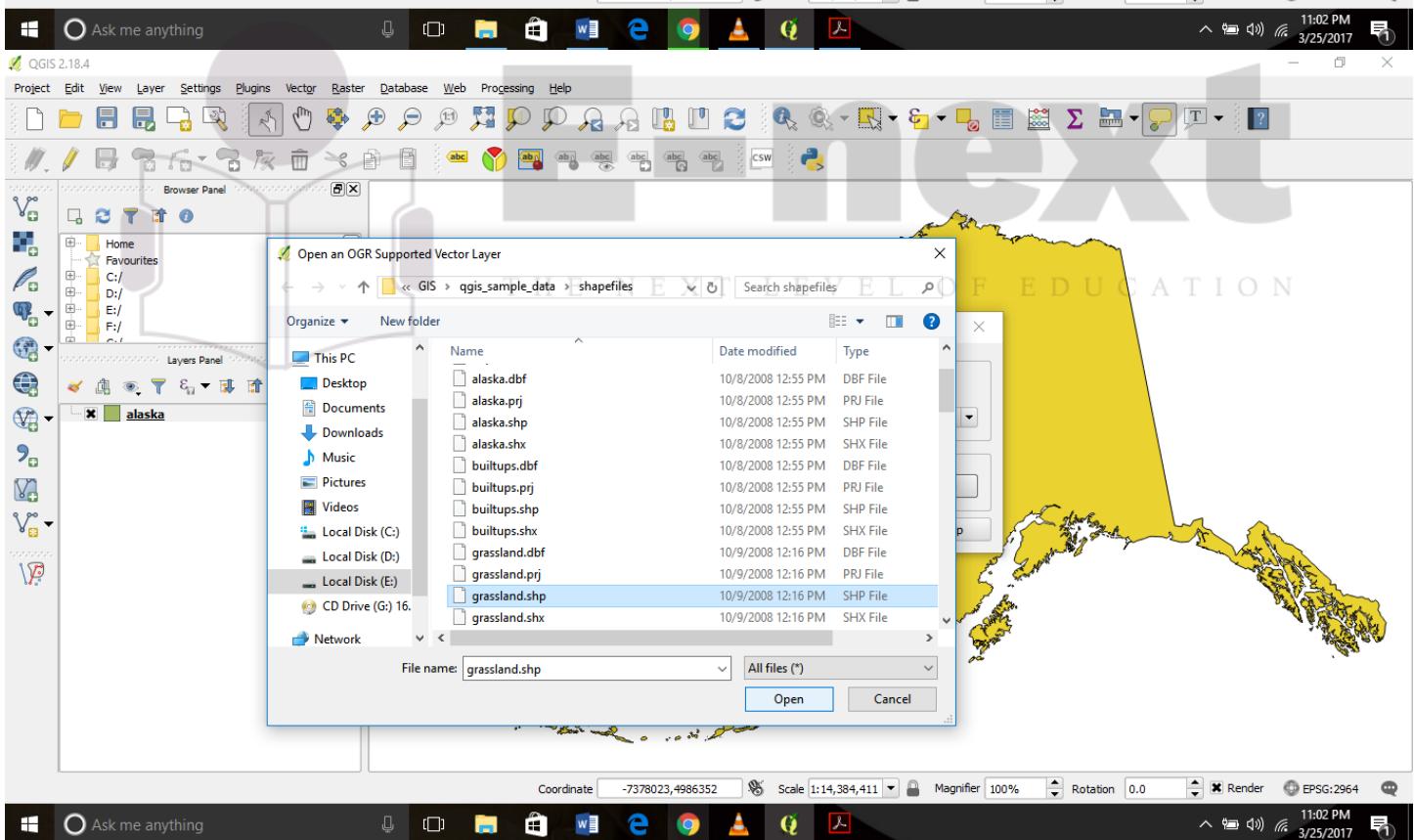
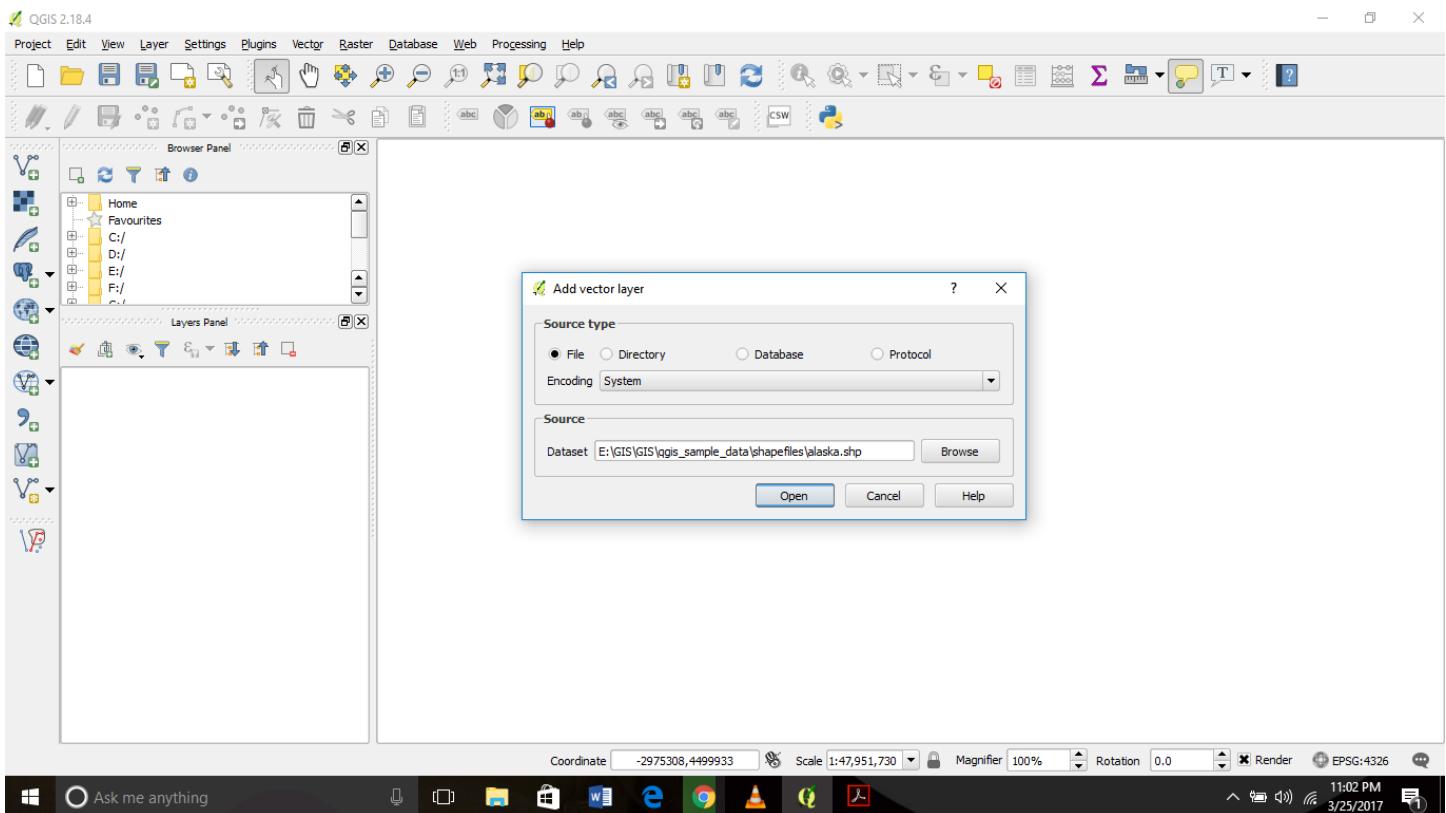
E-next

THE NEXT LEVEL OF EDUCATION

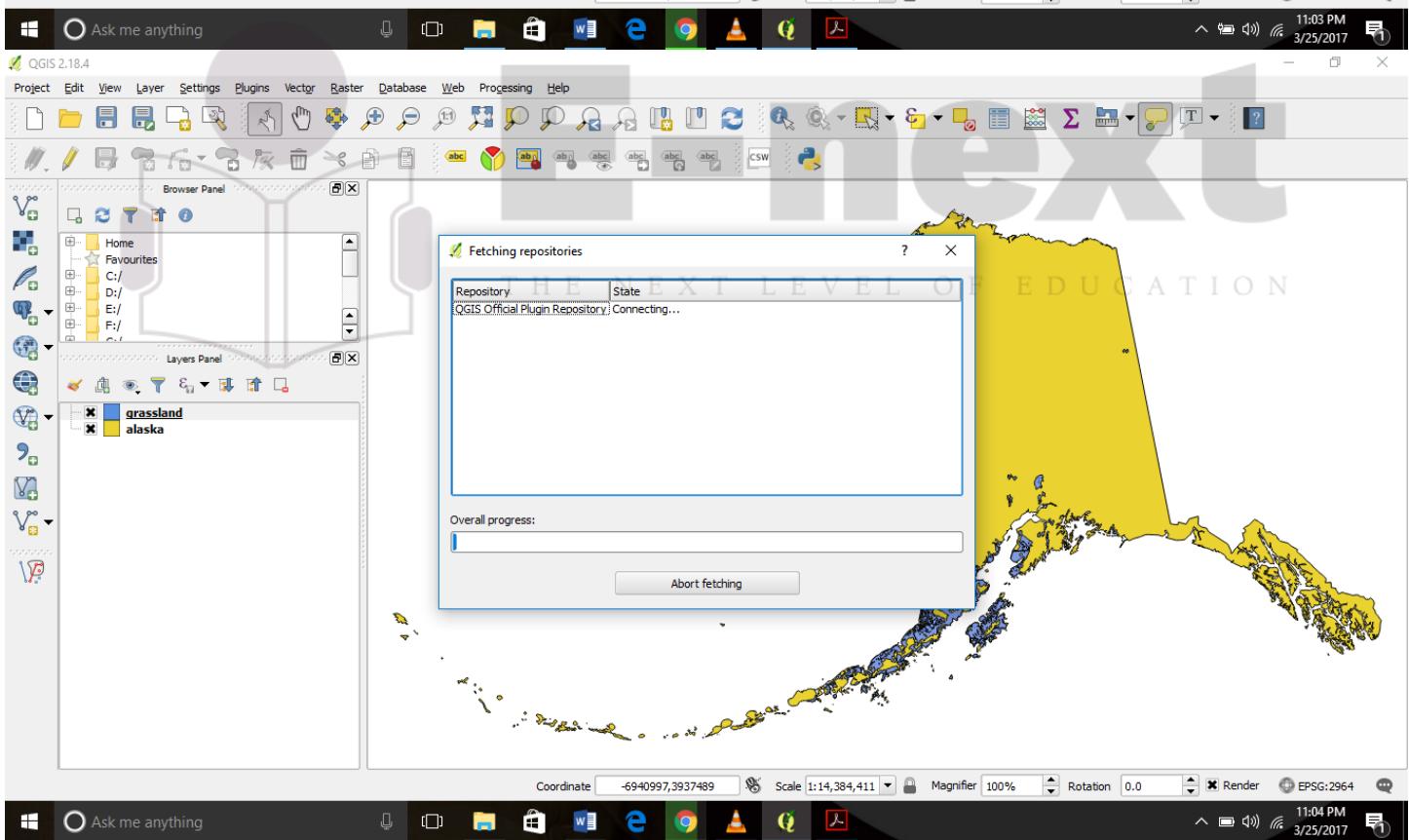
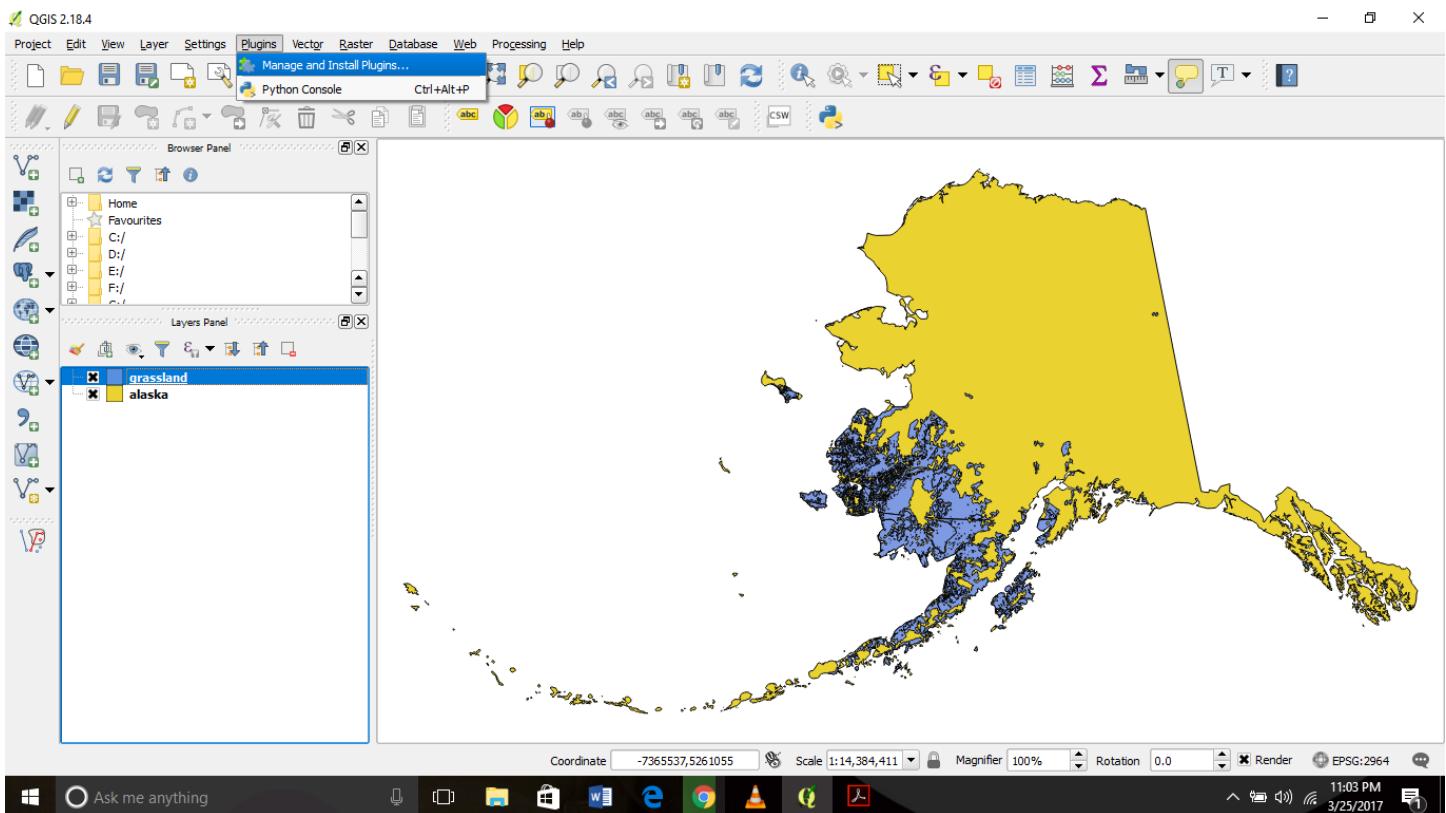
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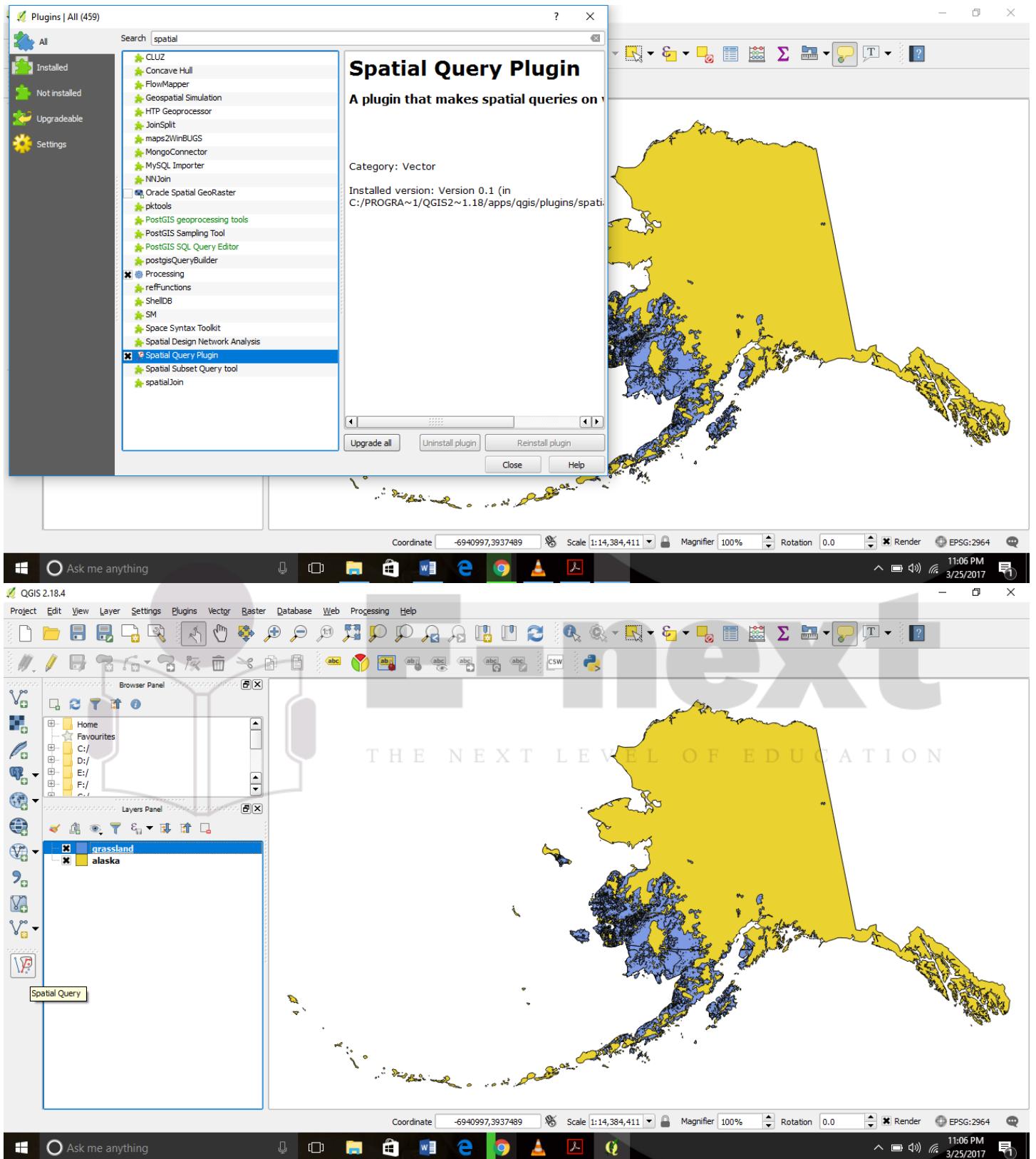
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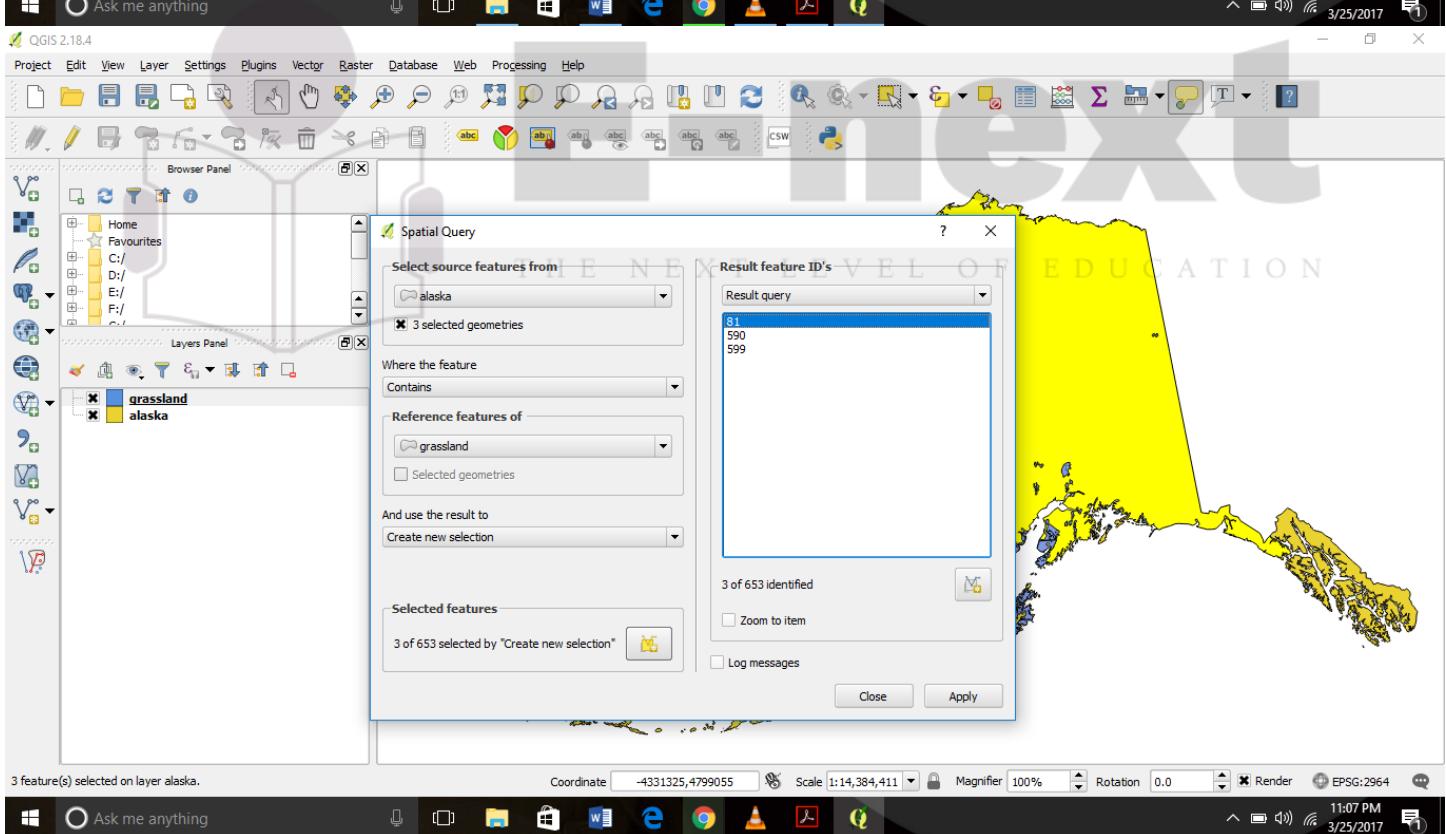
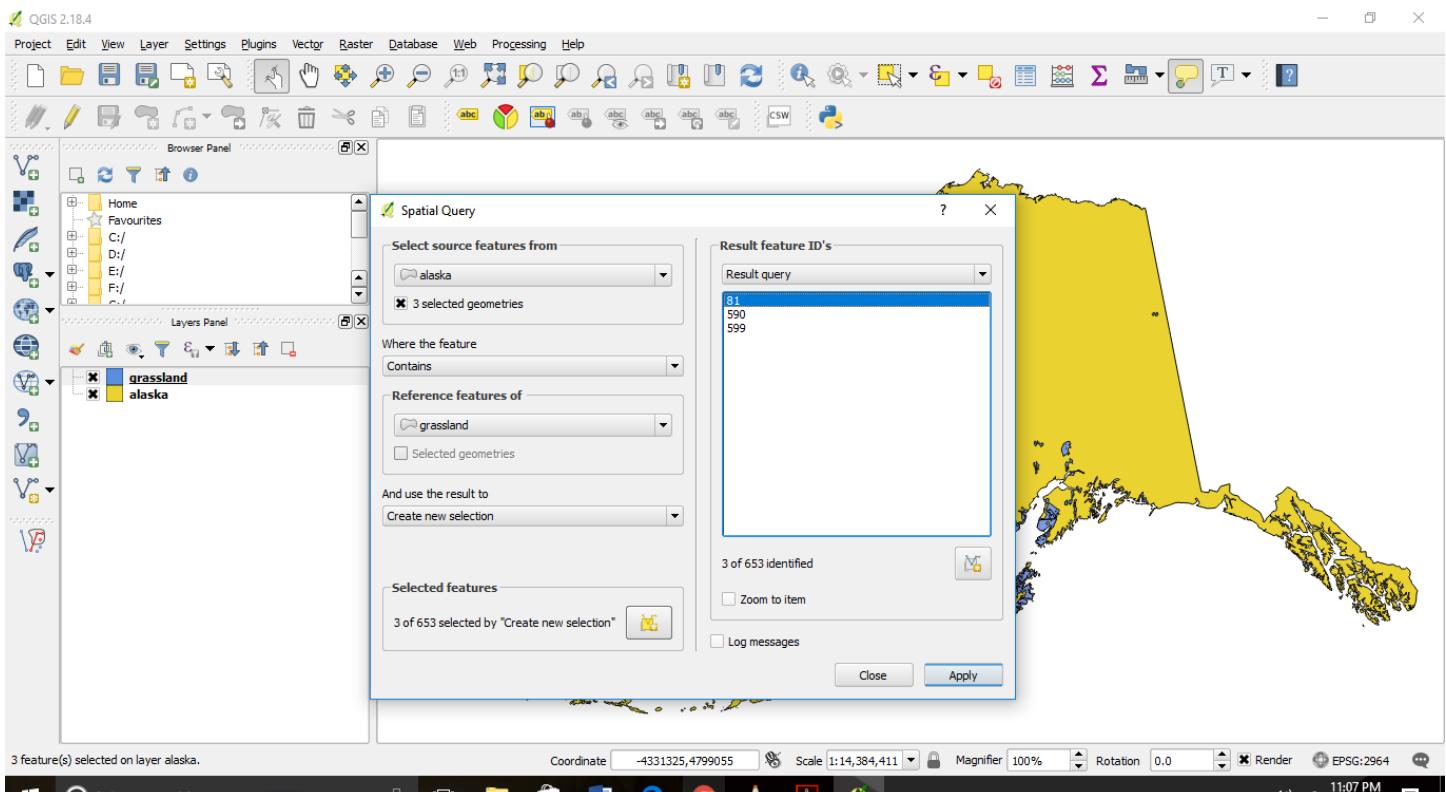
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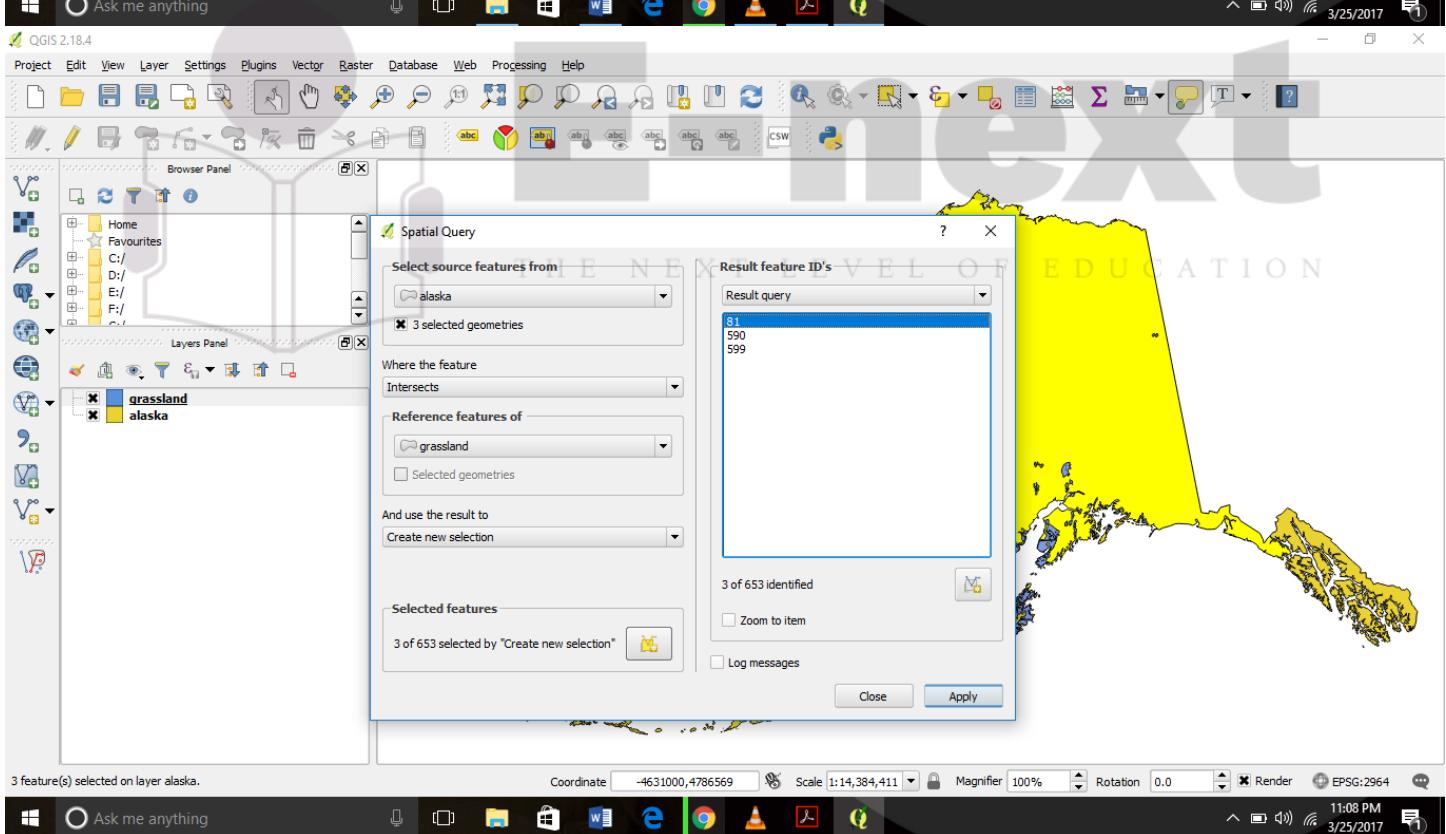
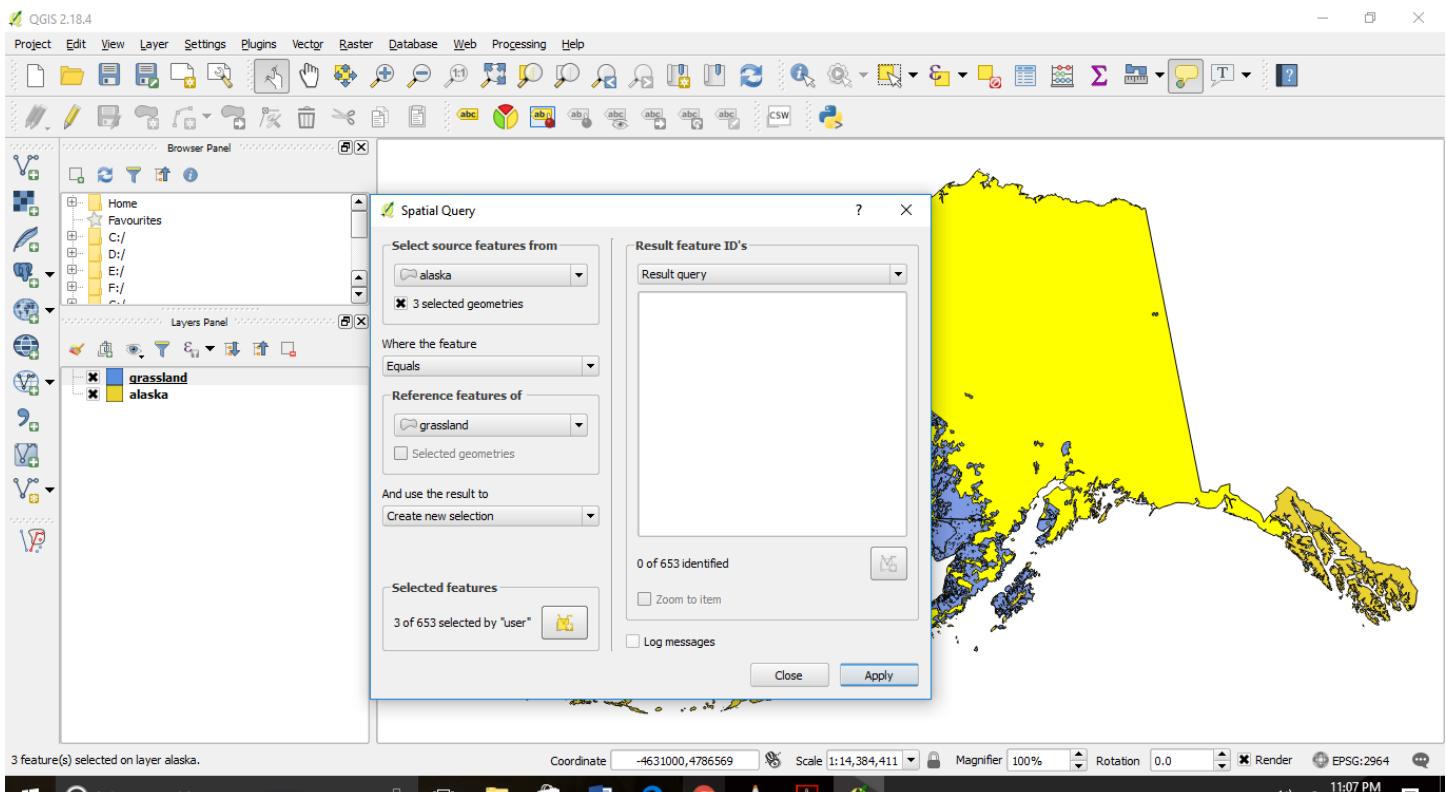
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IMAGE REGISTRATION

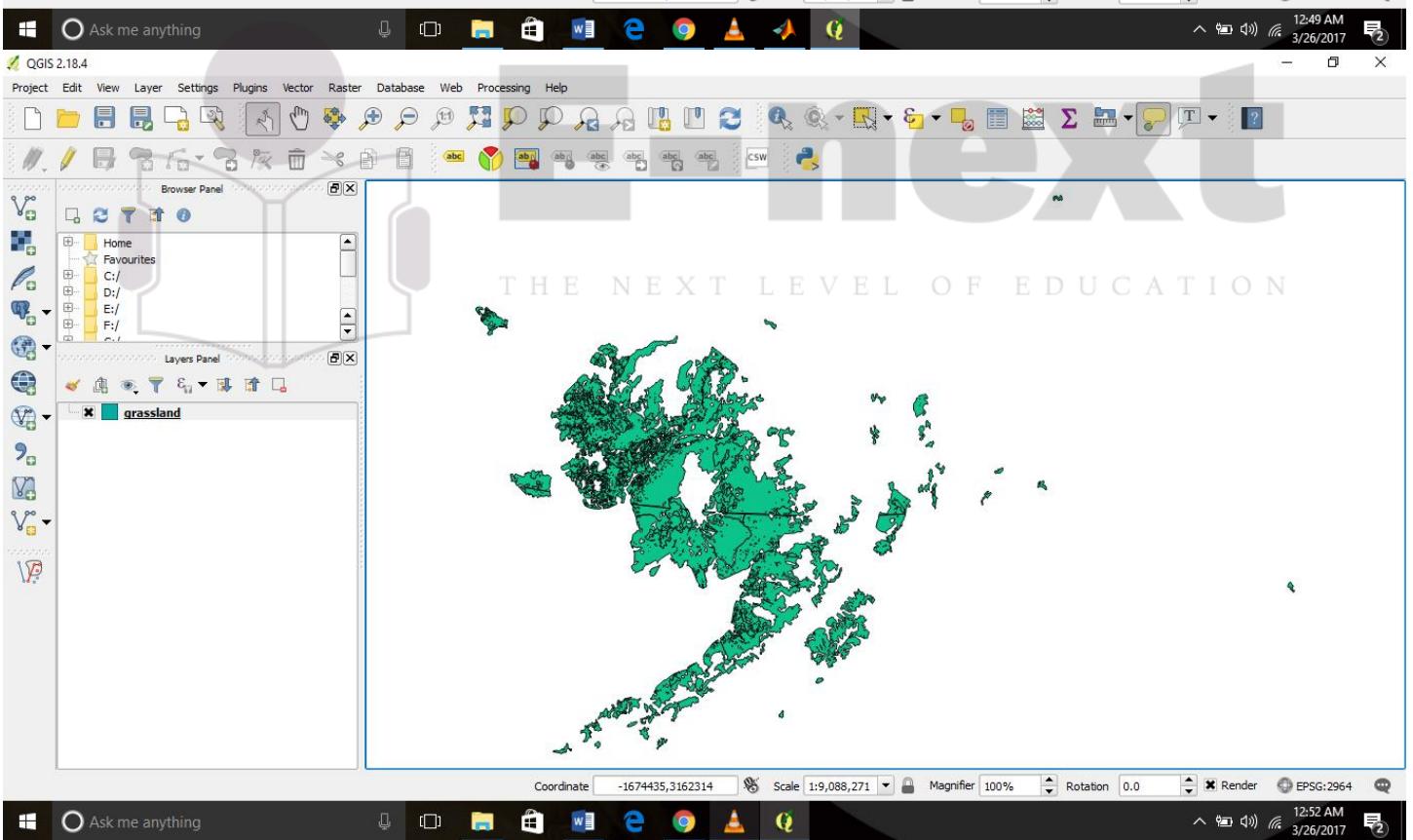
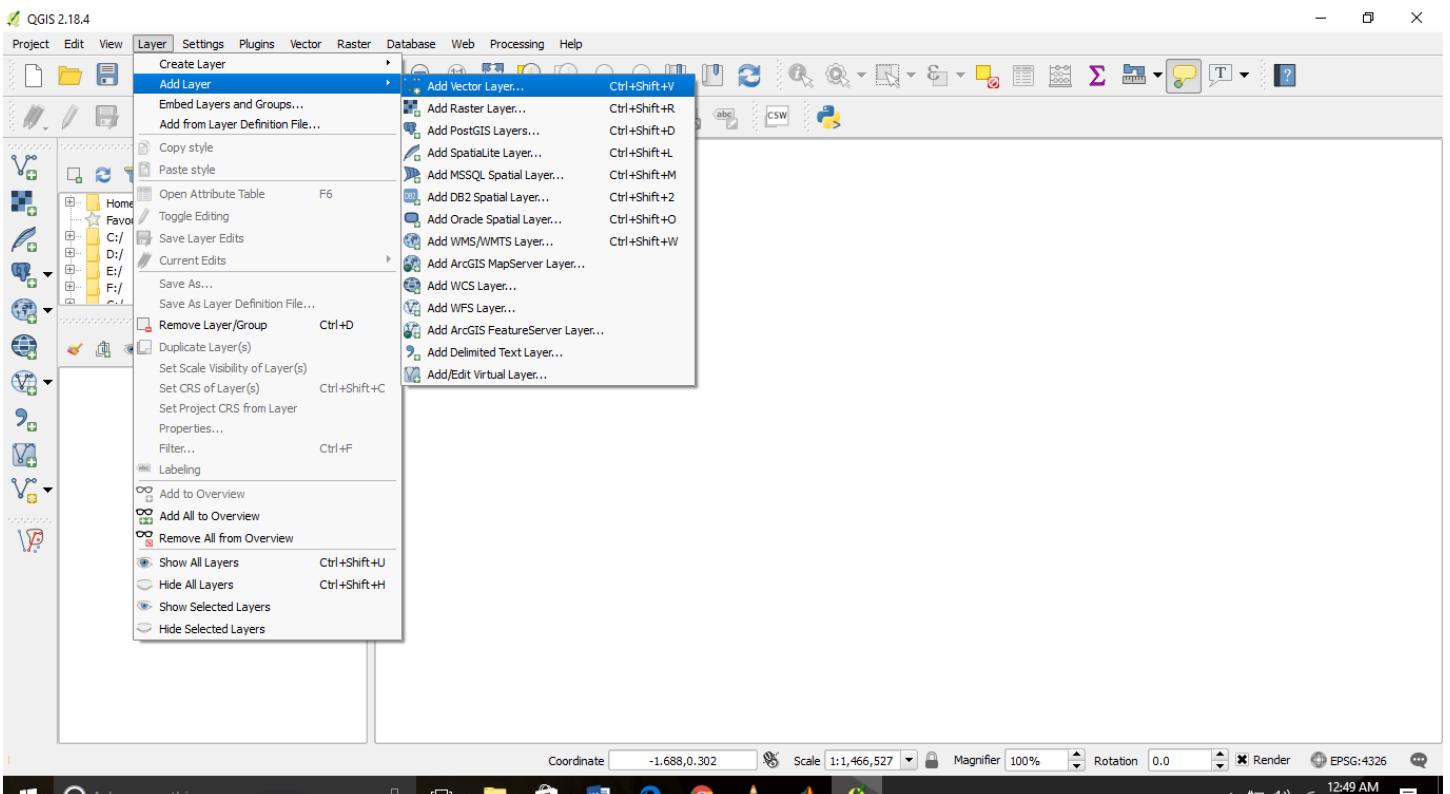
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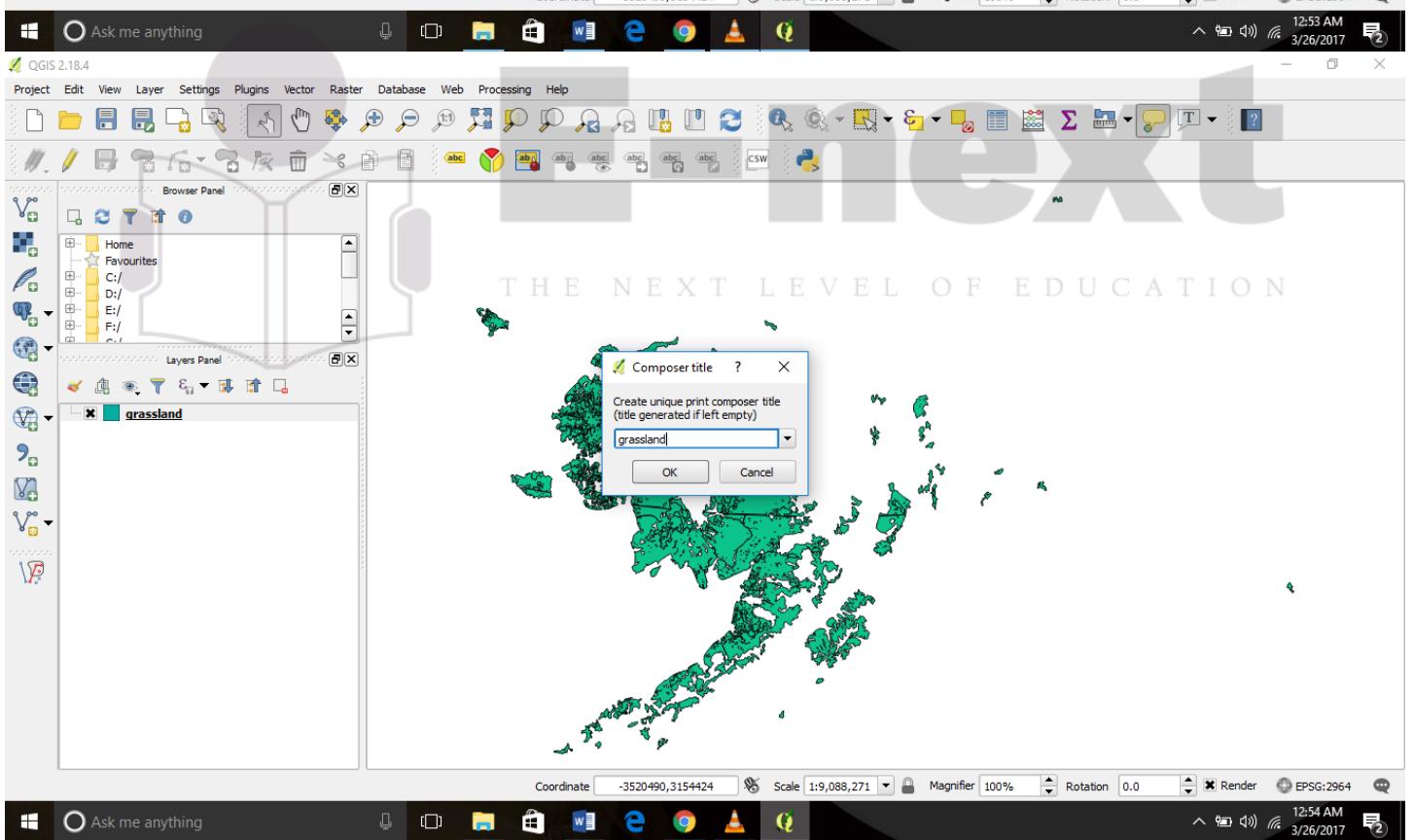
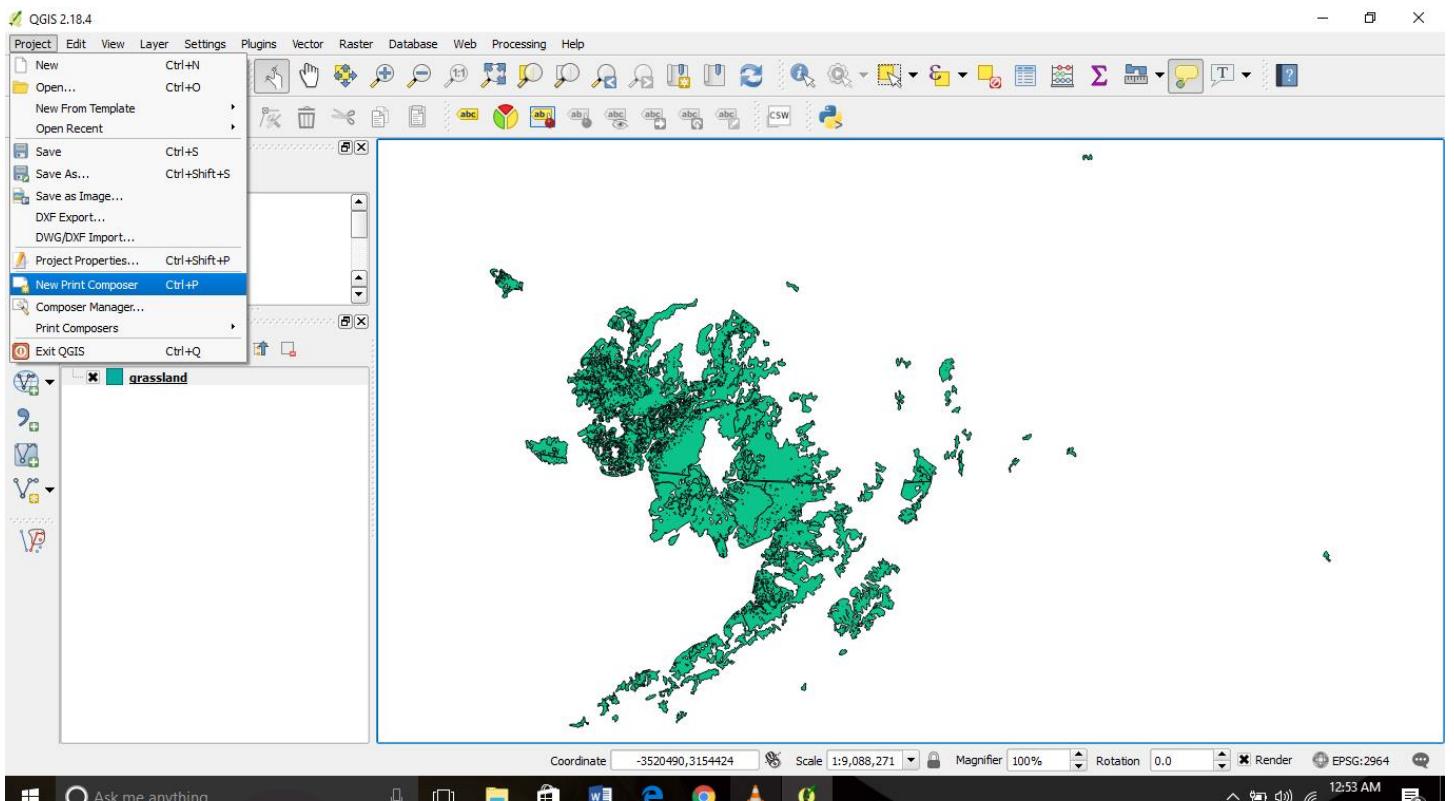
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- 2) About different Matlab functions.



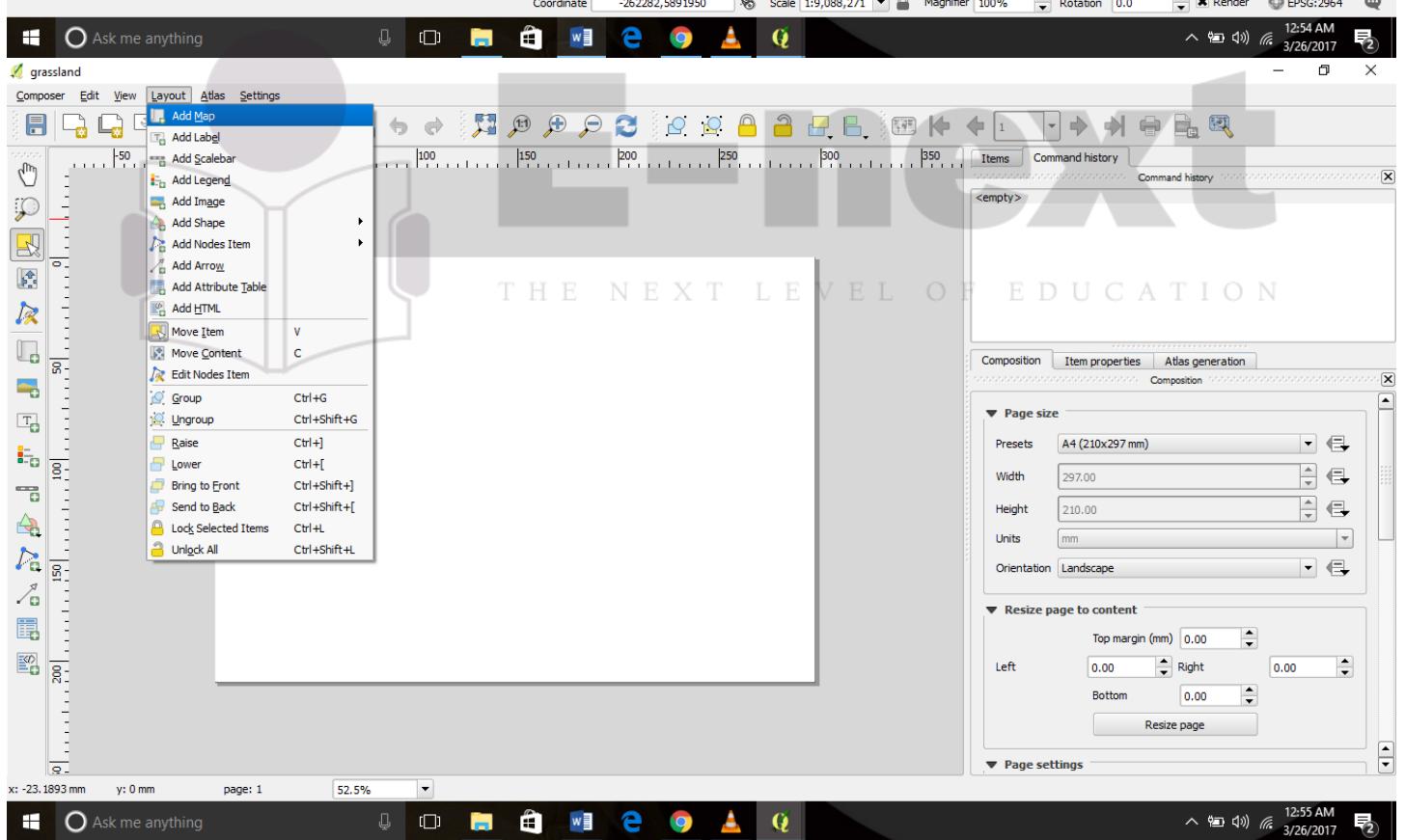
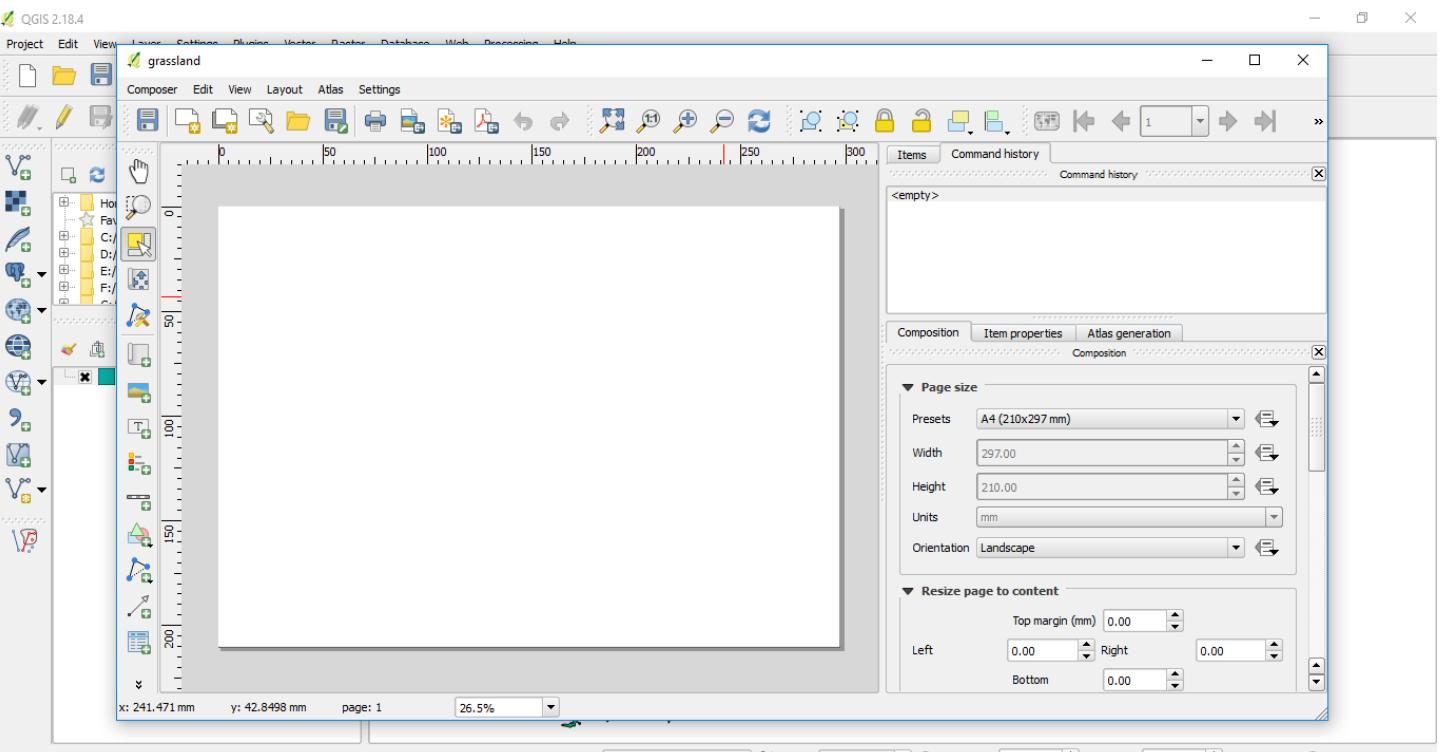
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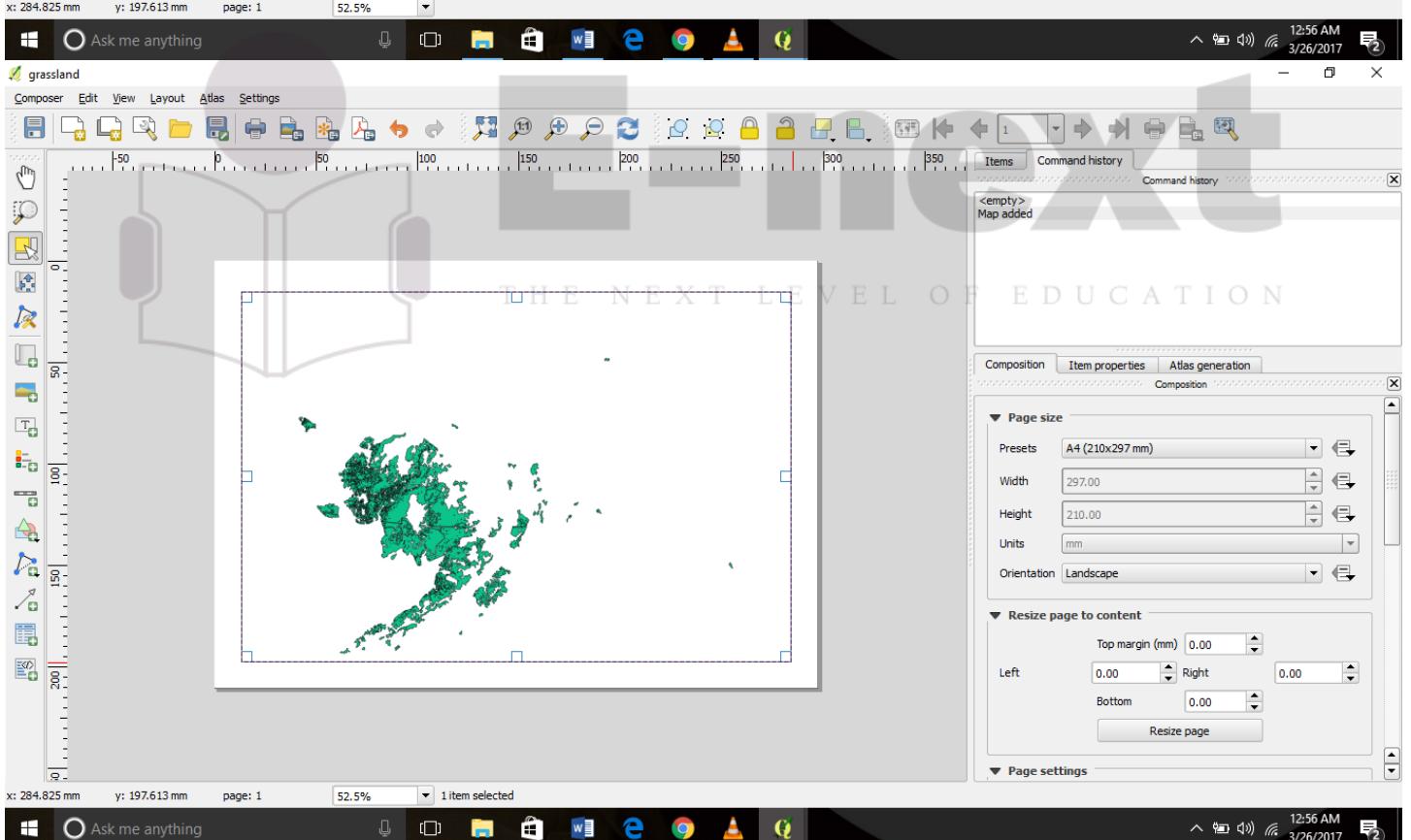
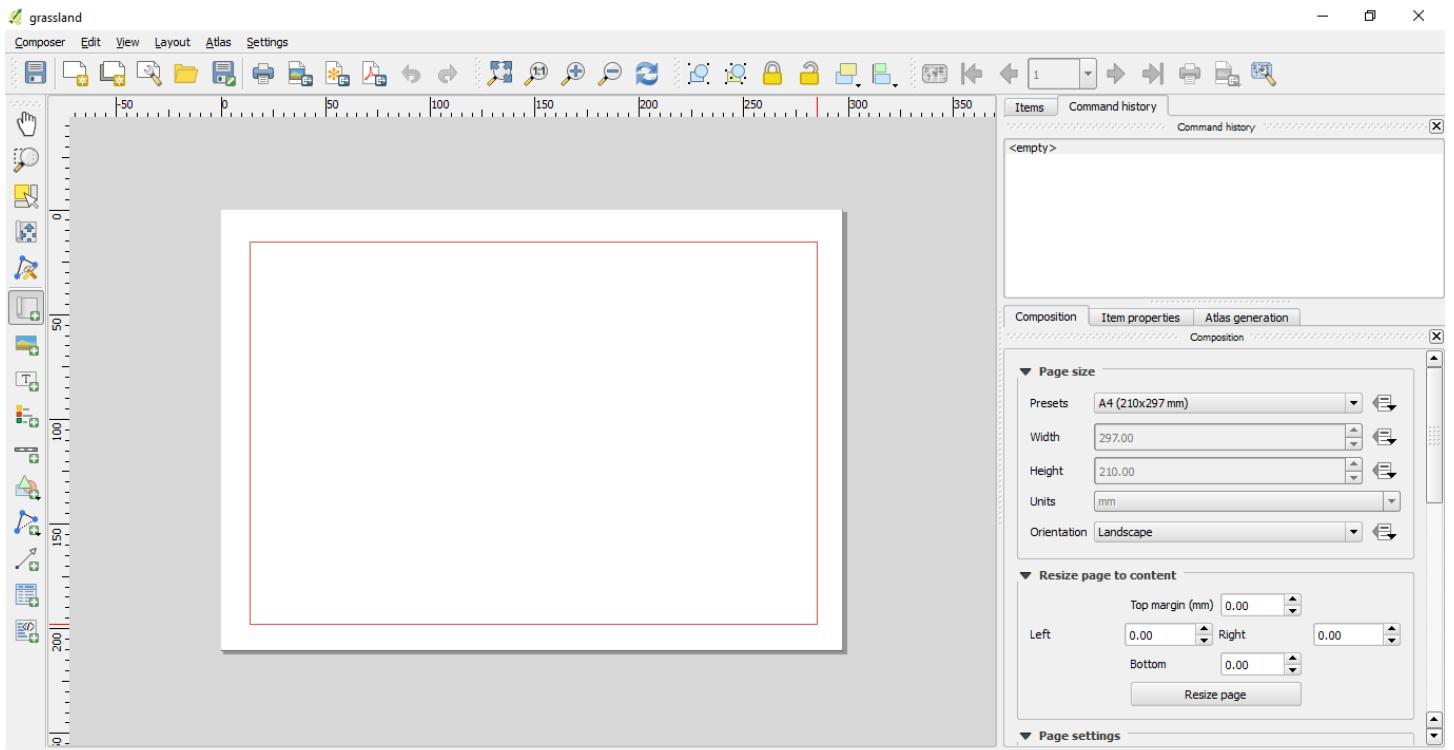
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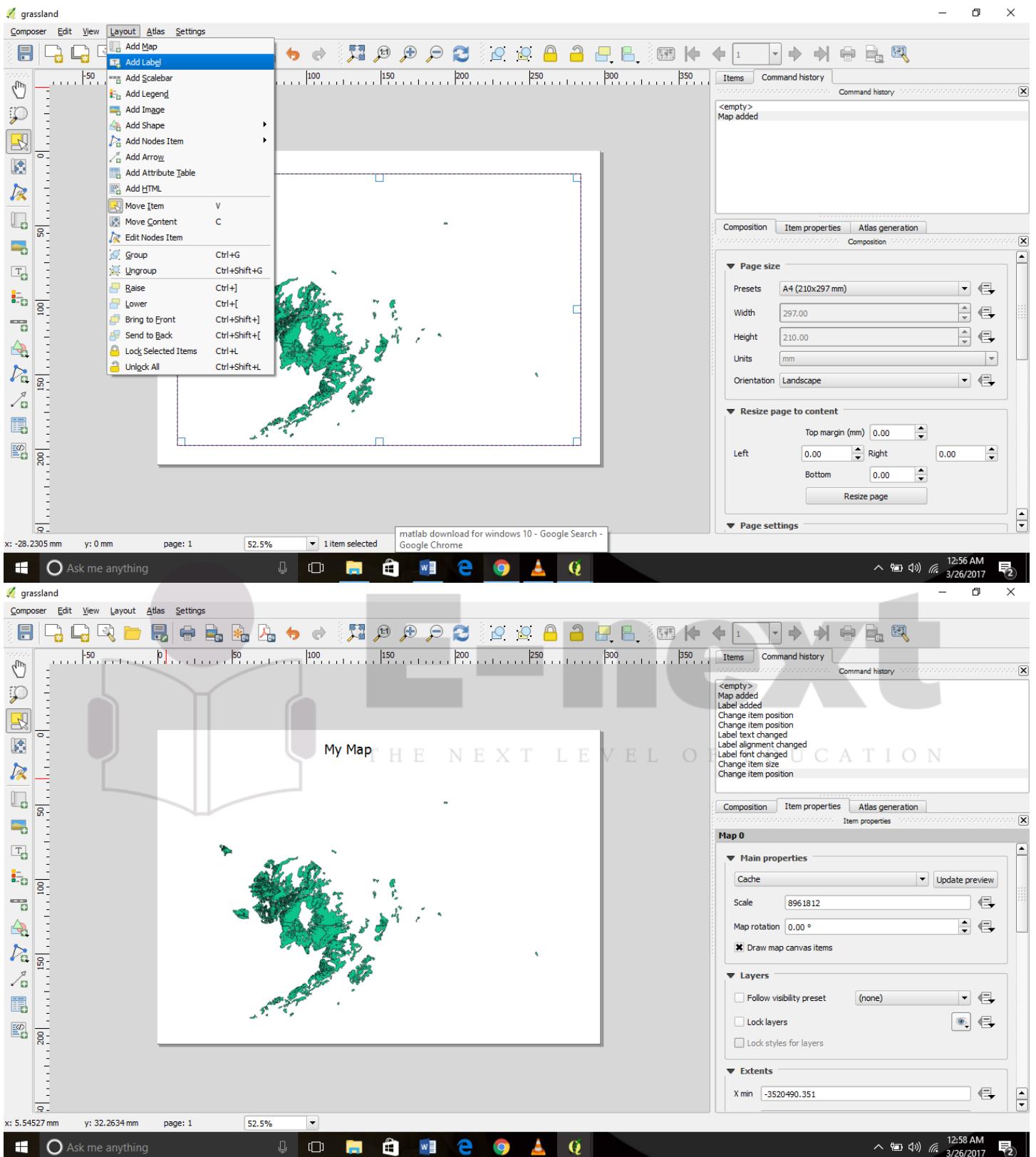
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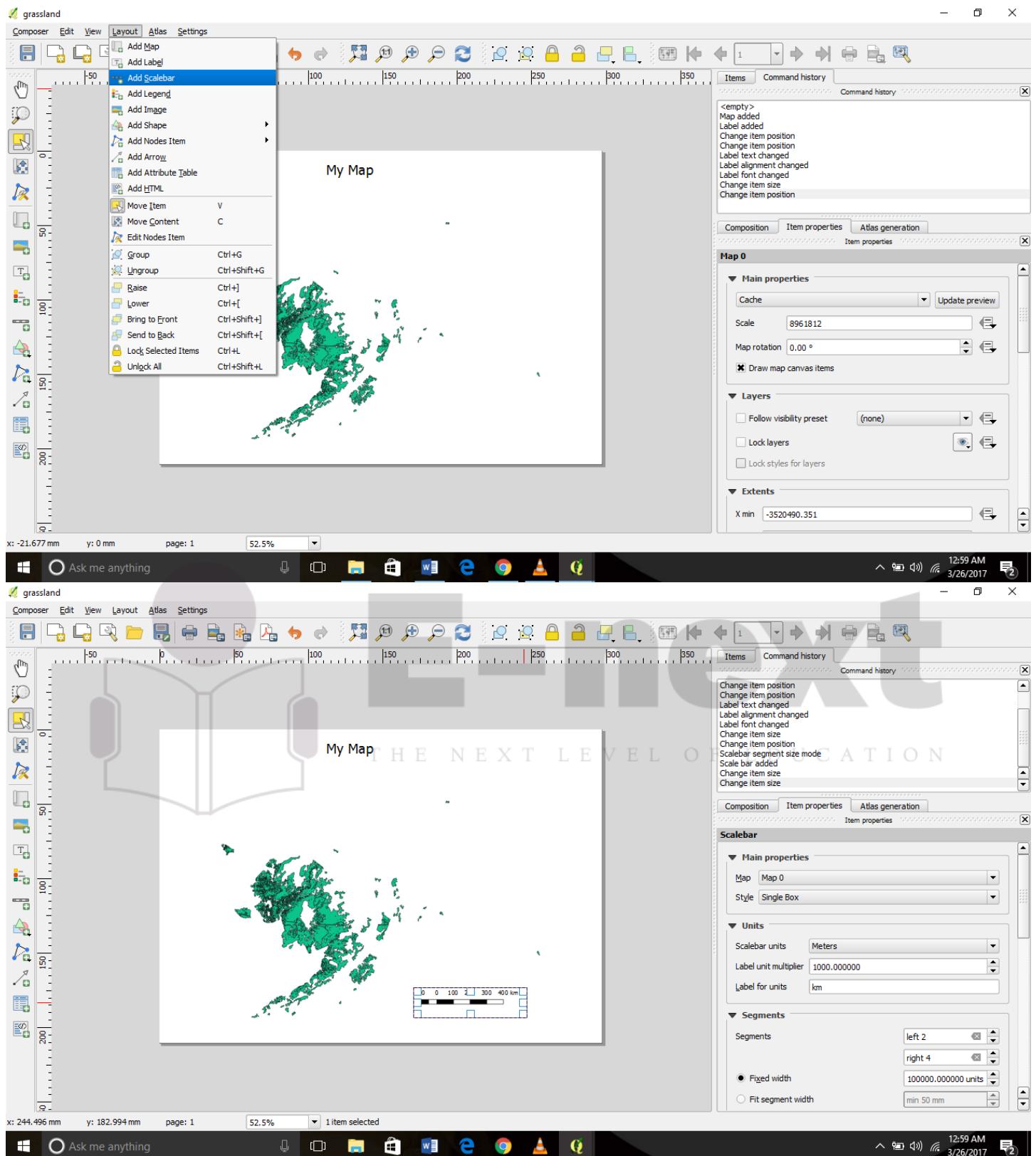
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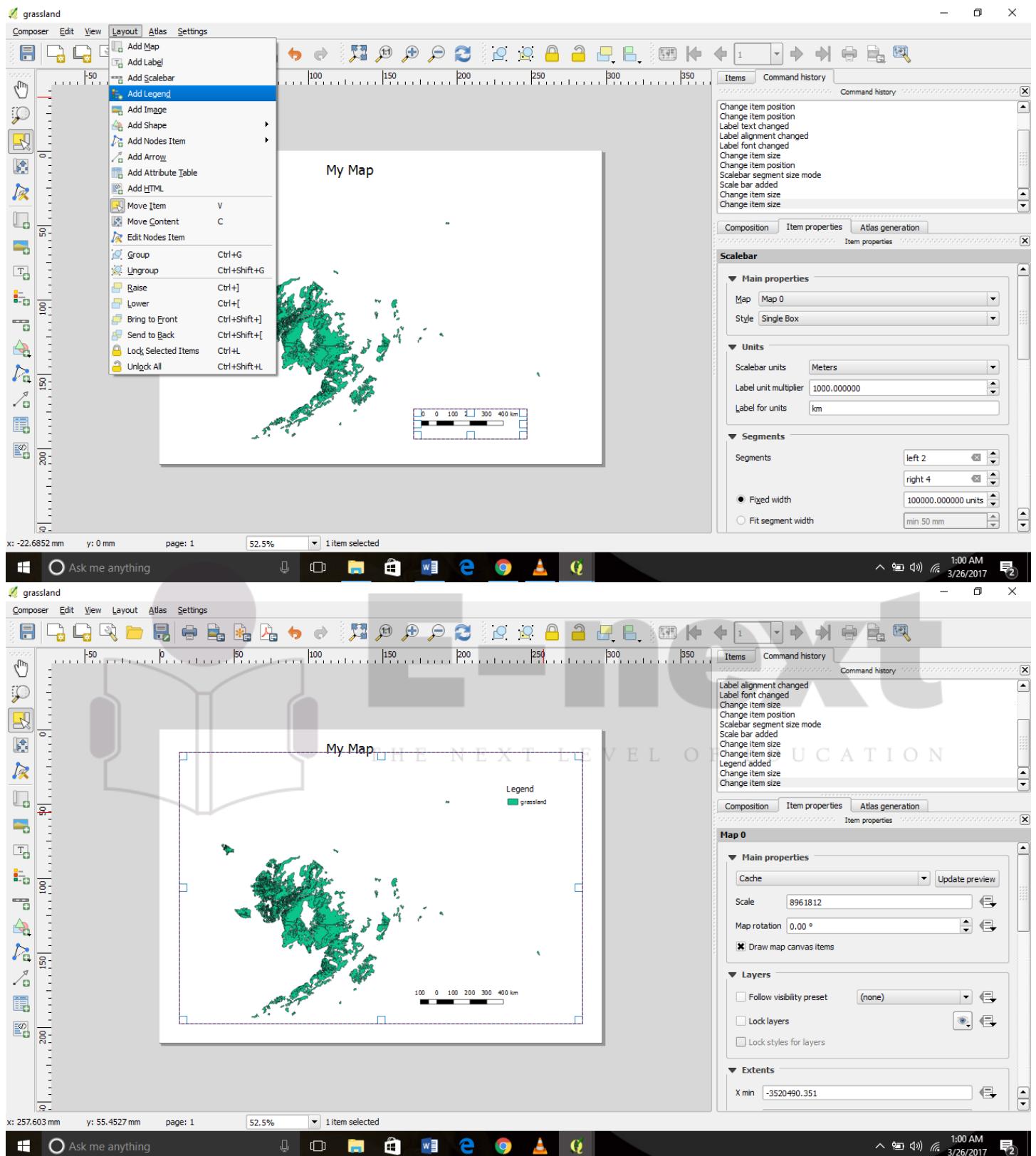
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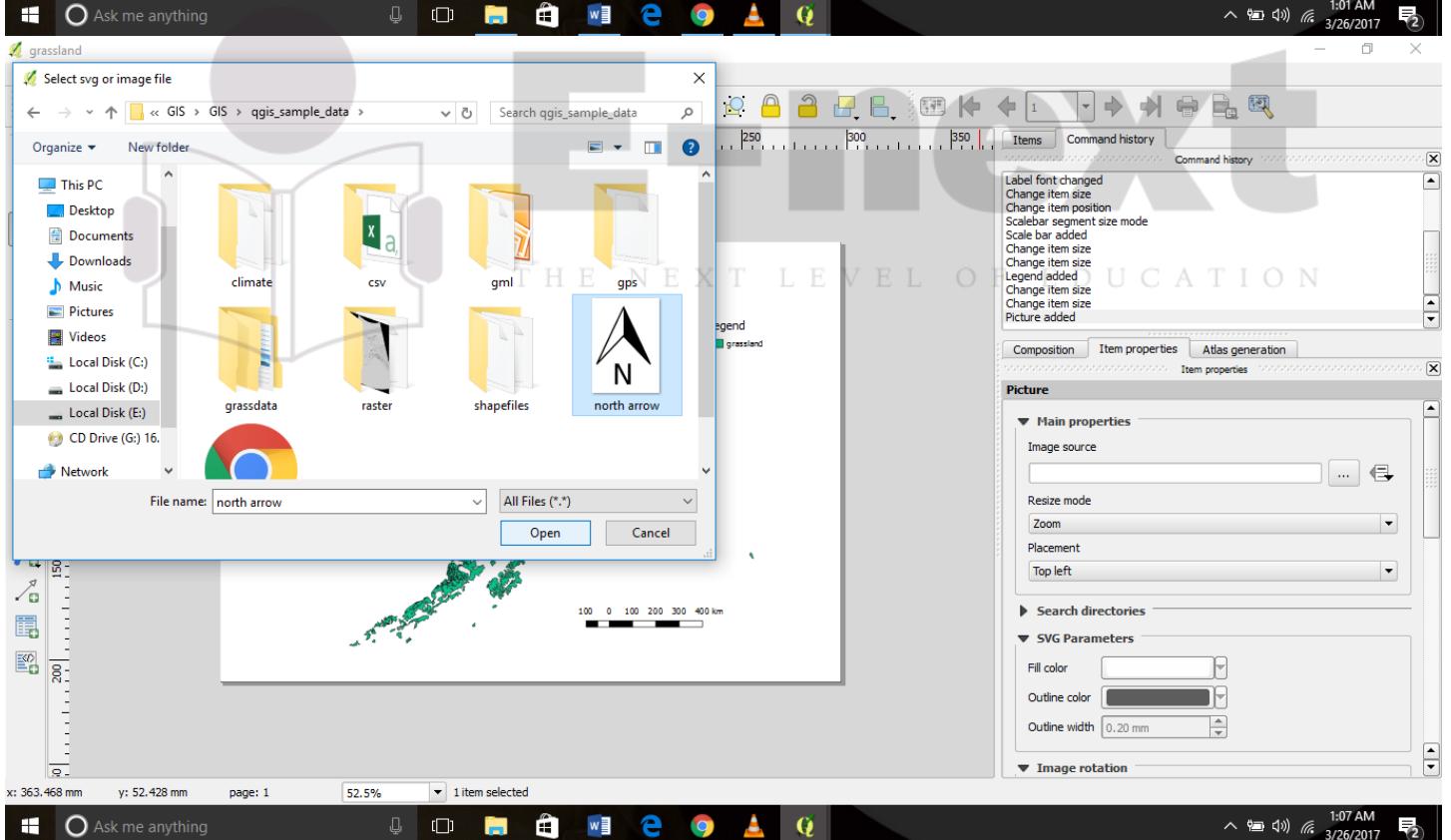
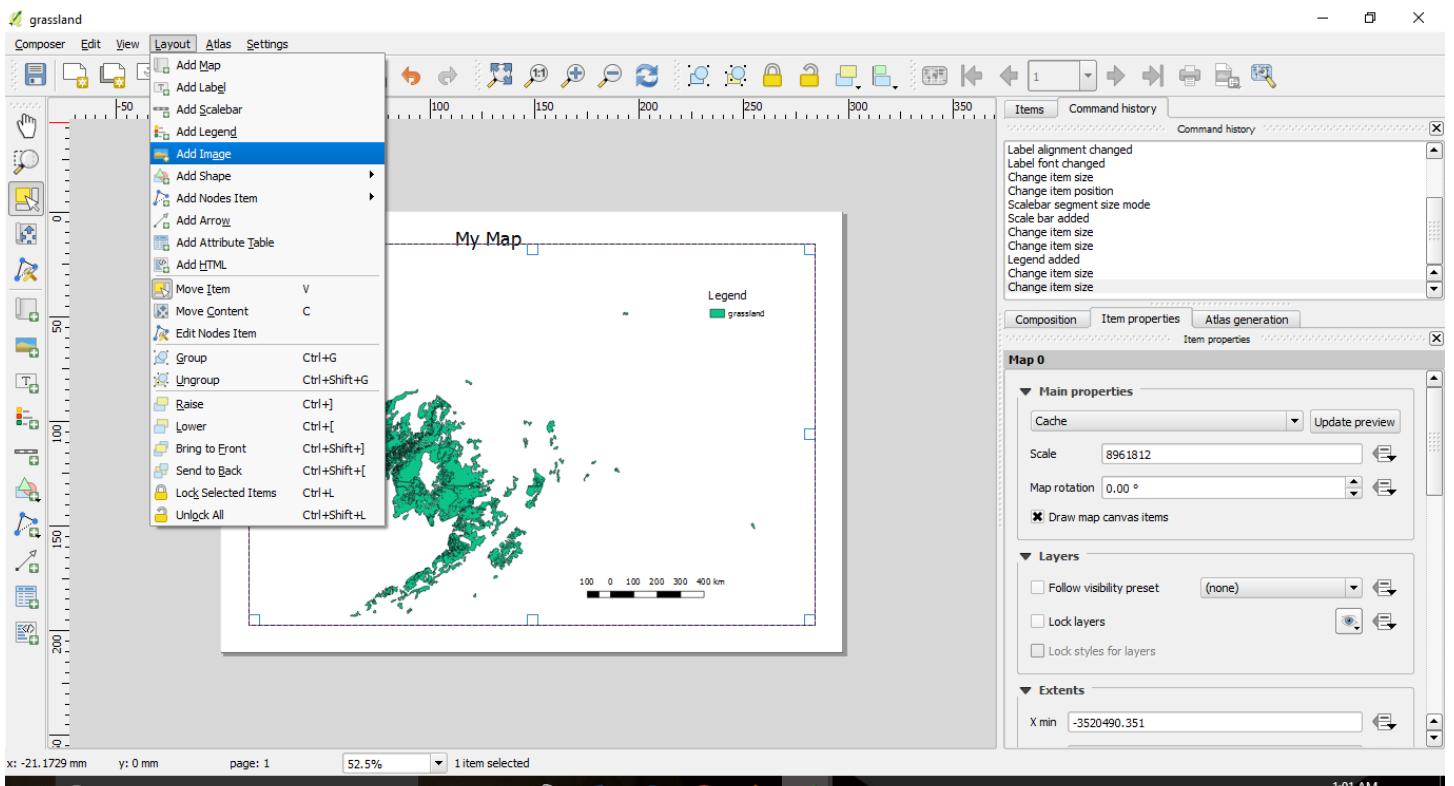
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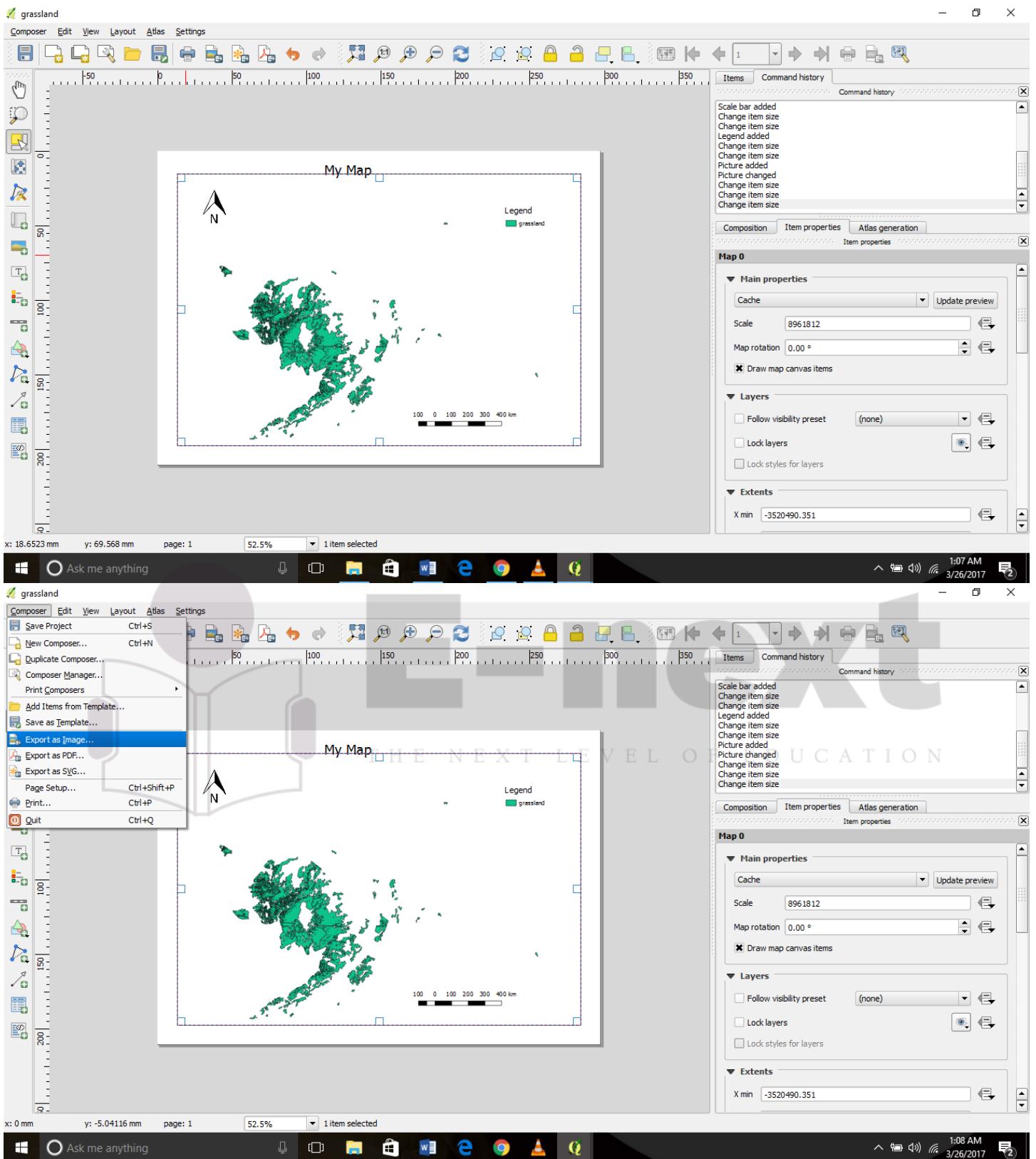
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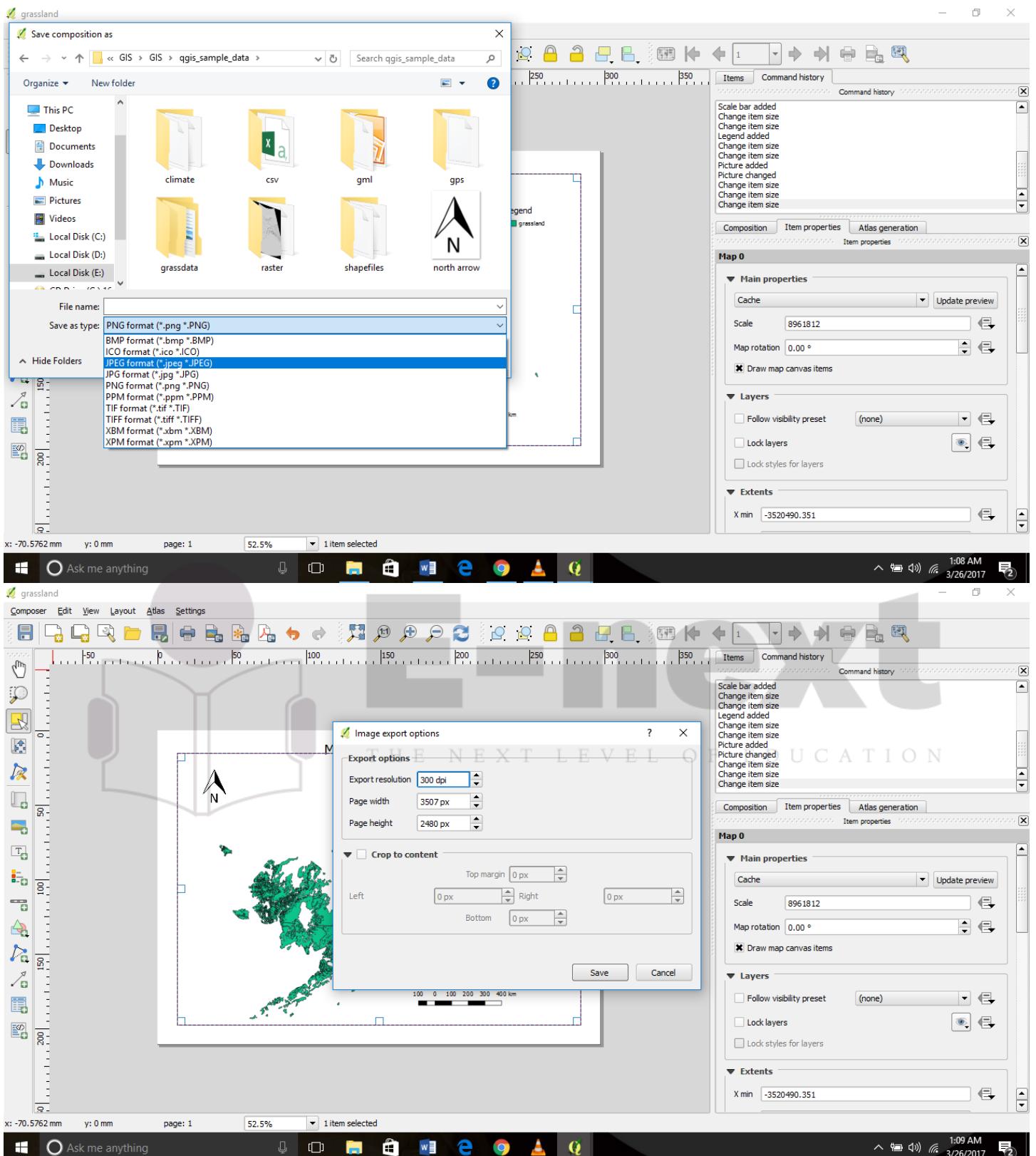
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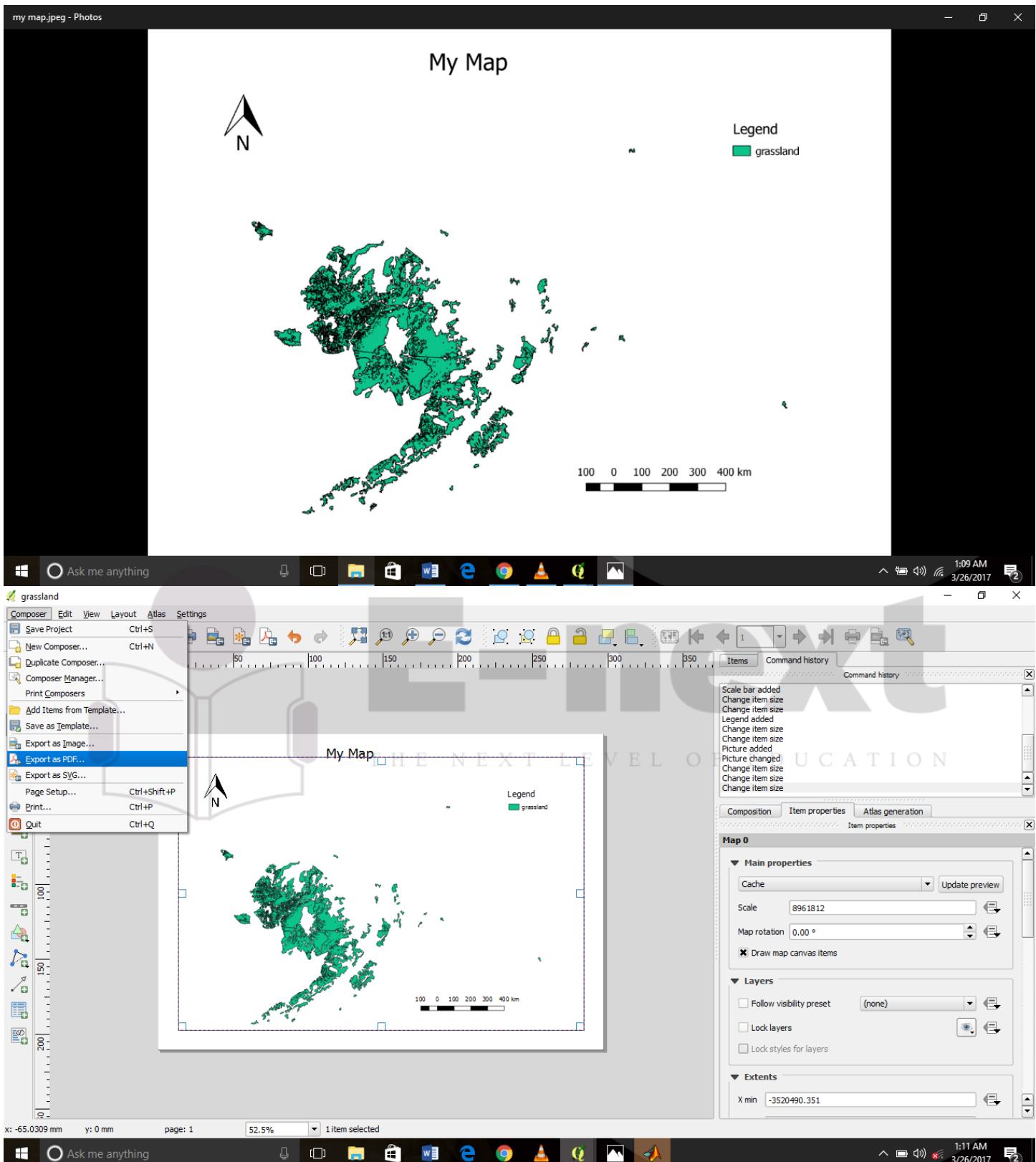
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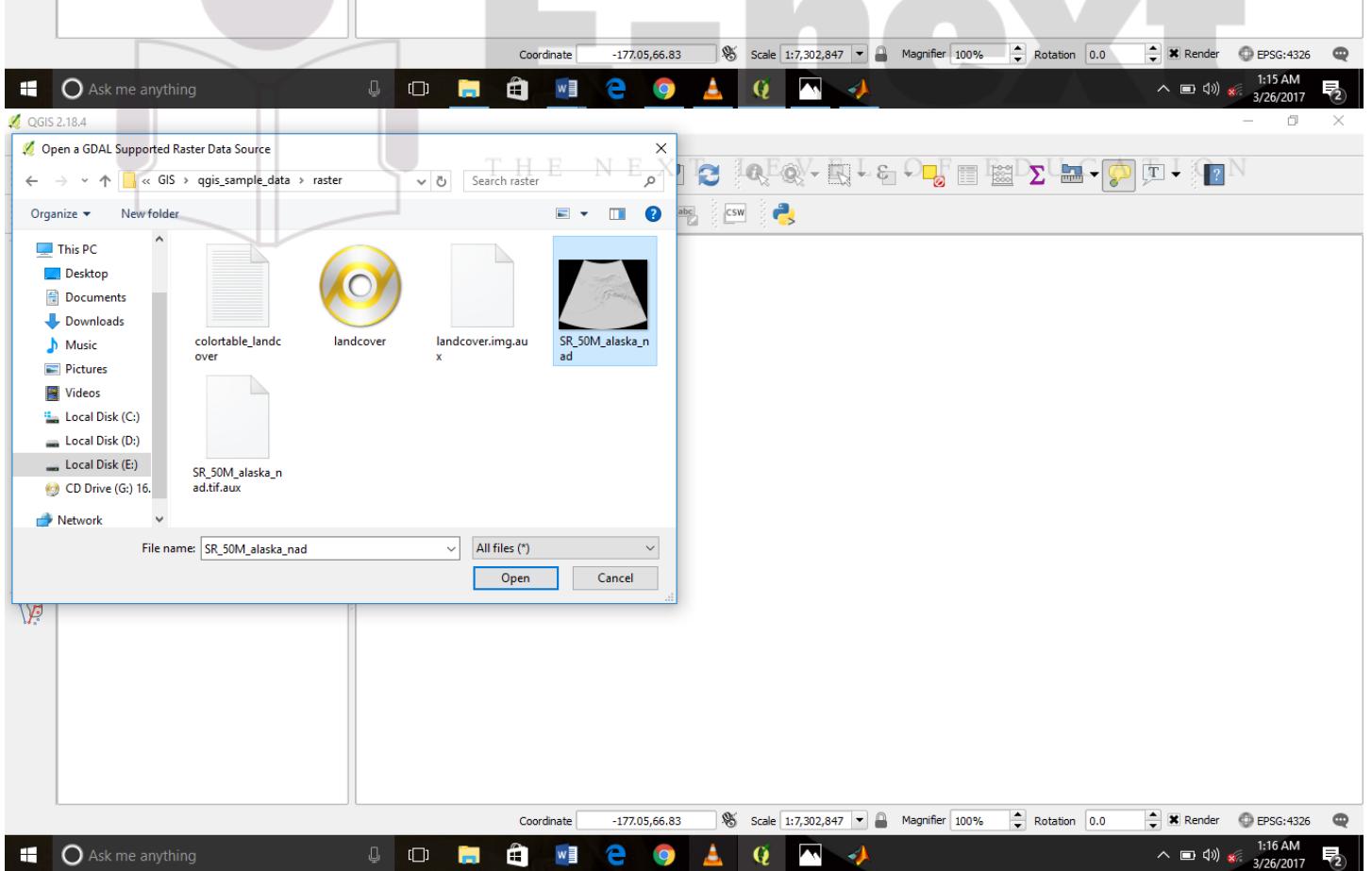
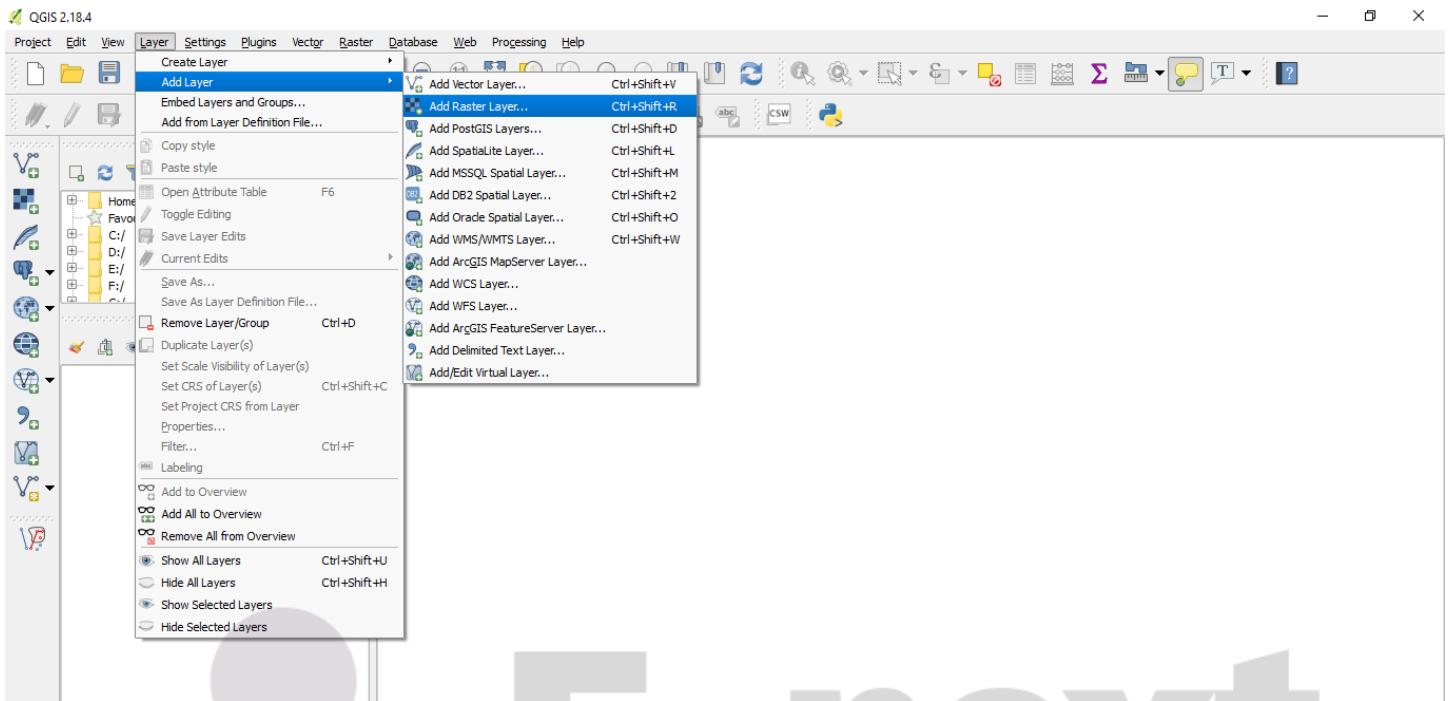
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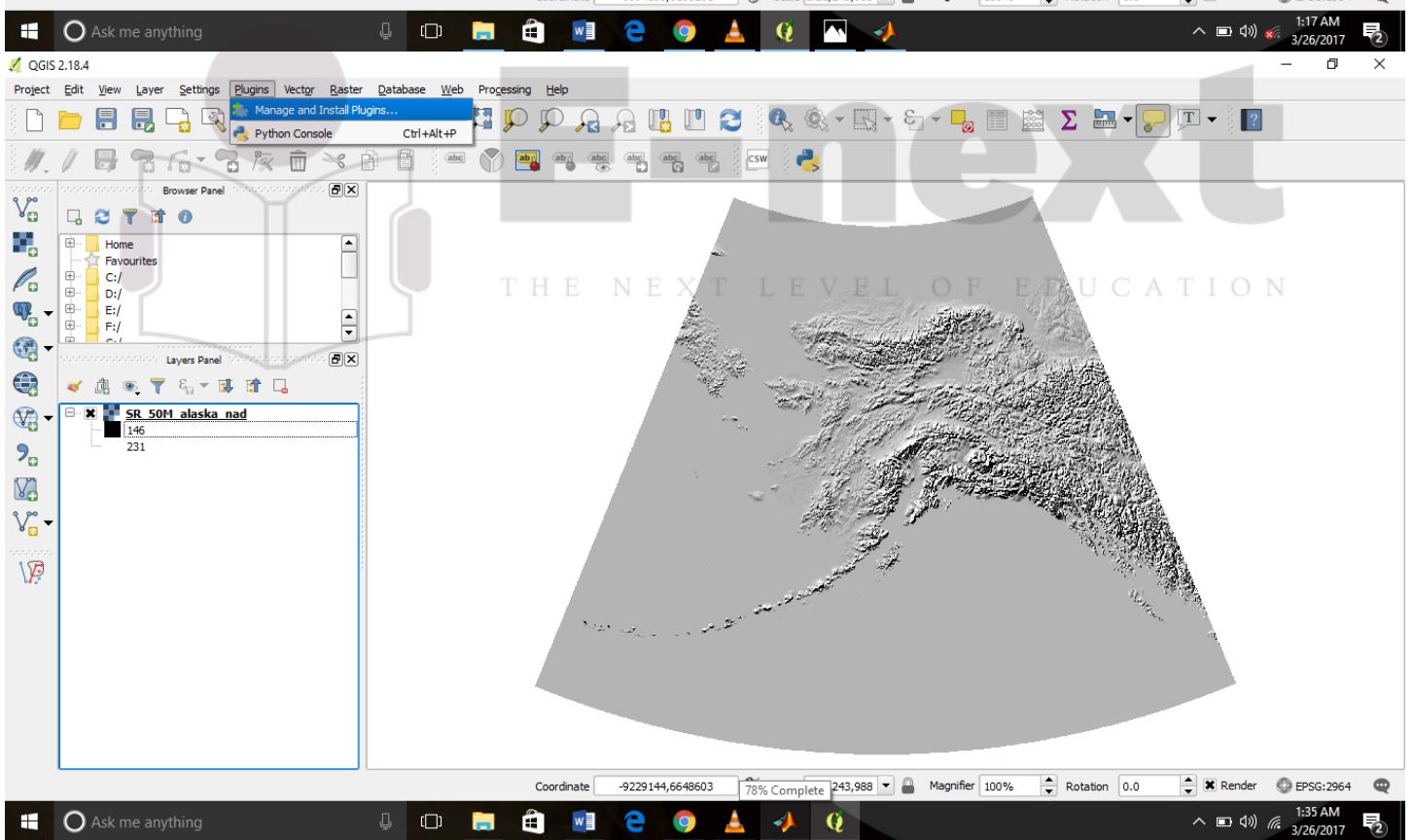
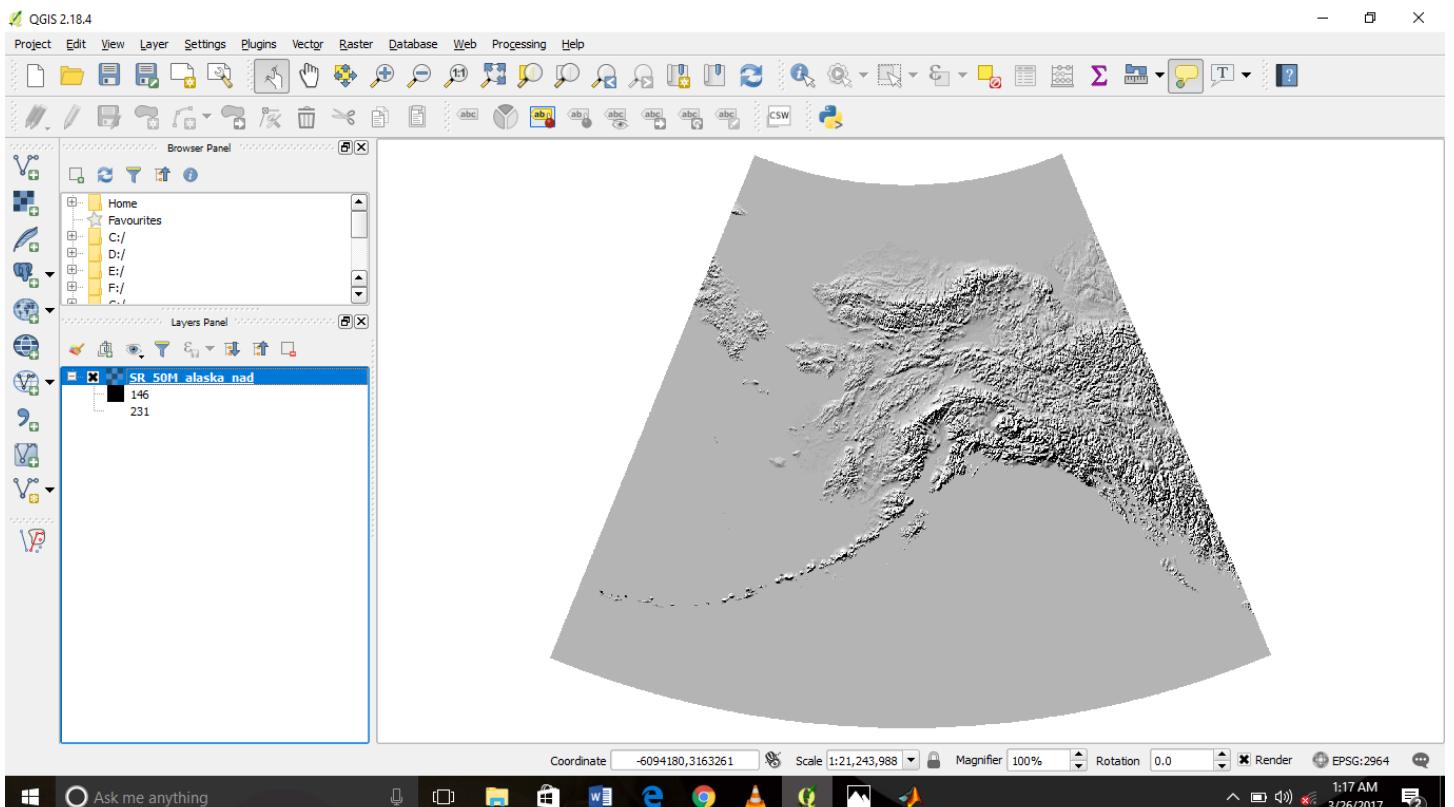
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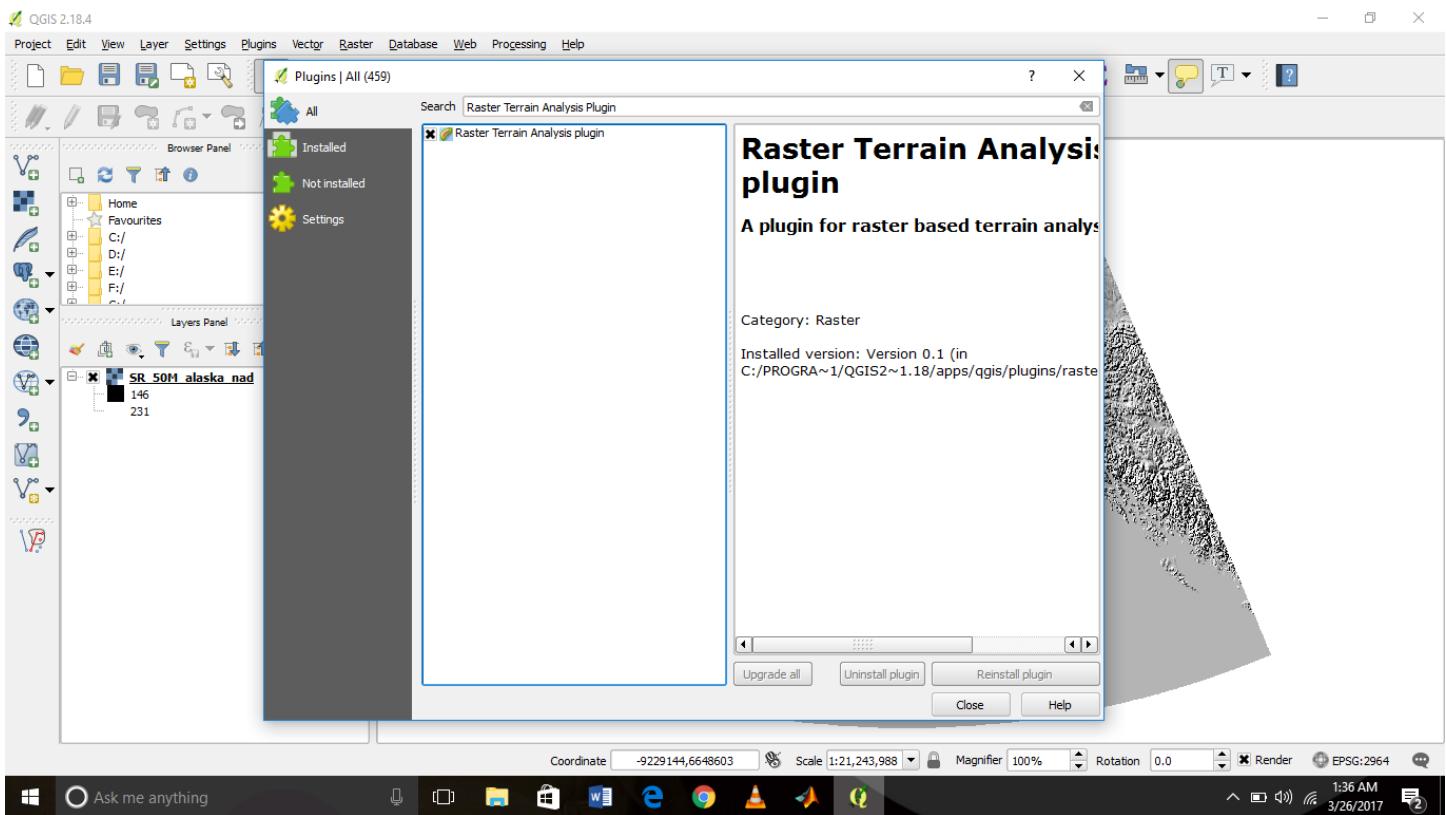
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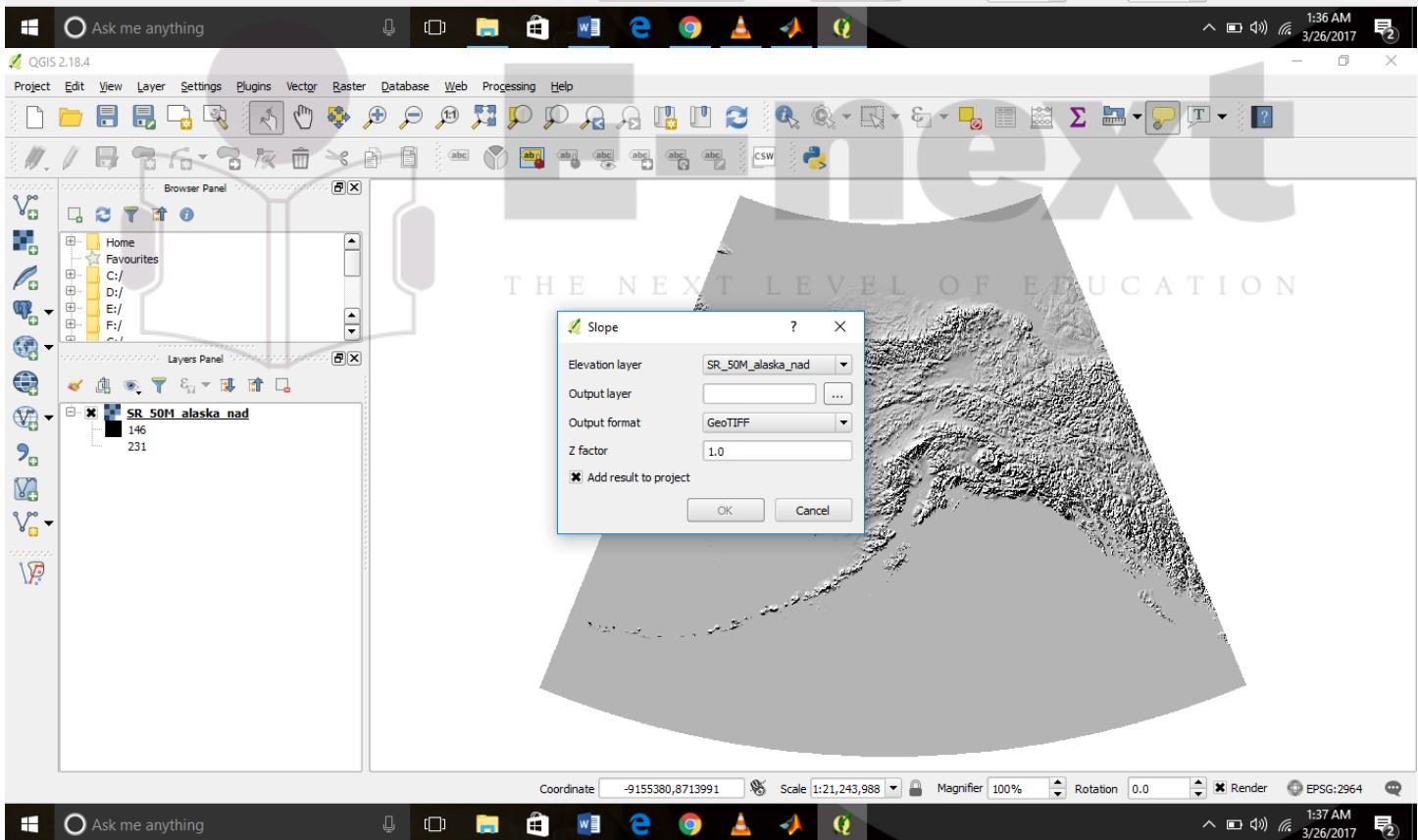
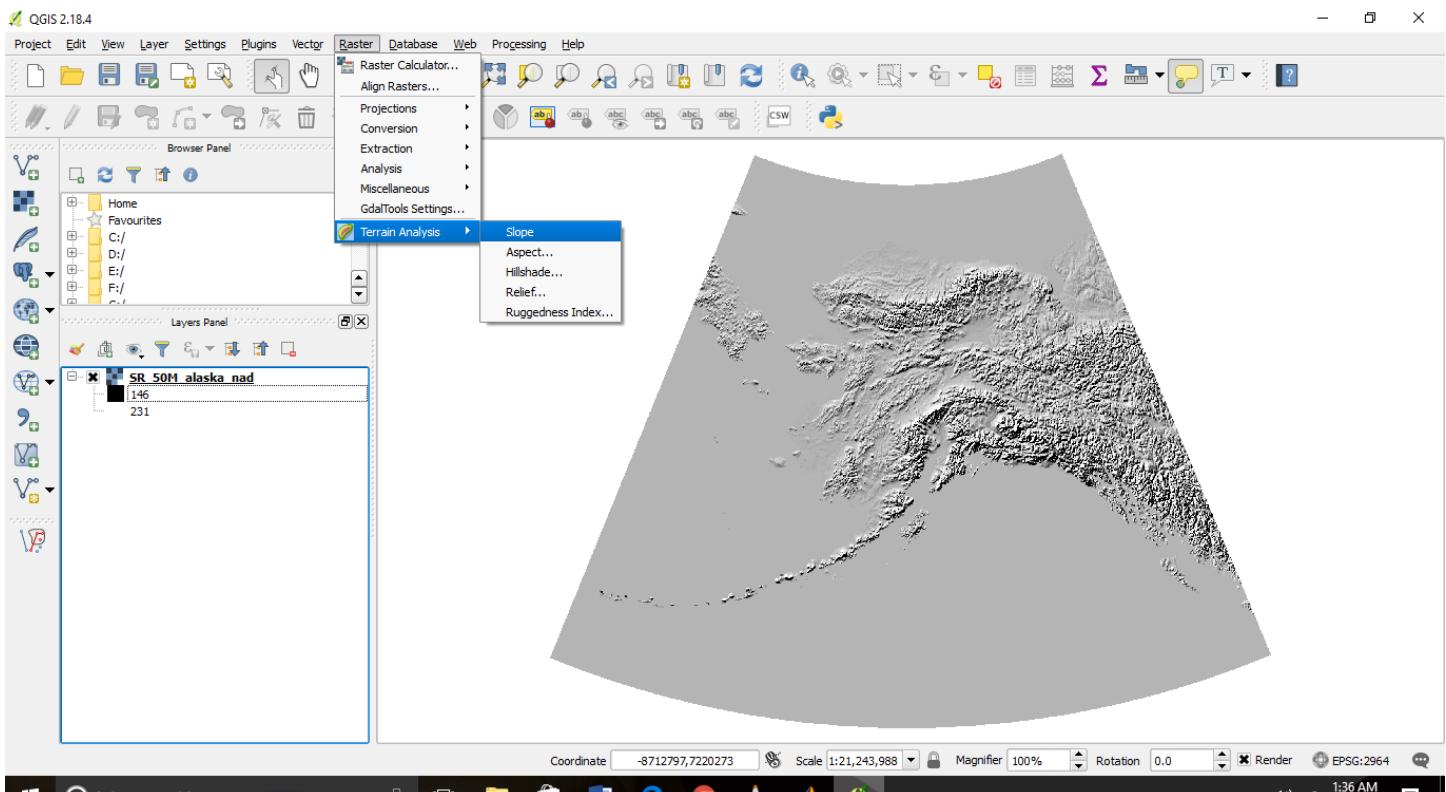


Raster Terrain Analysis Plugin

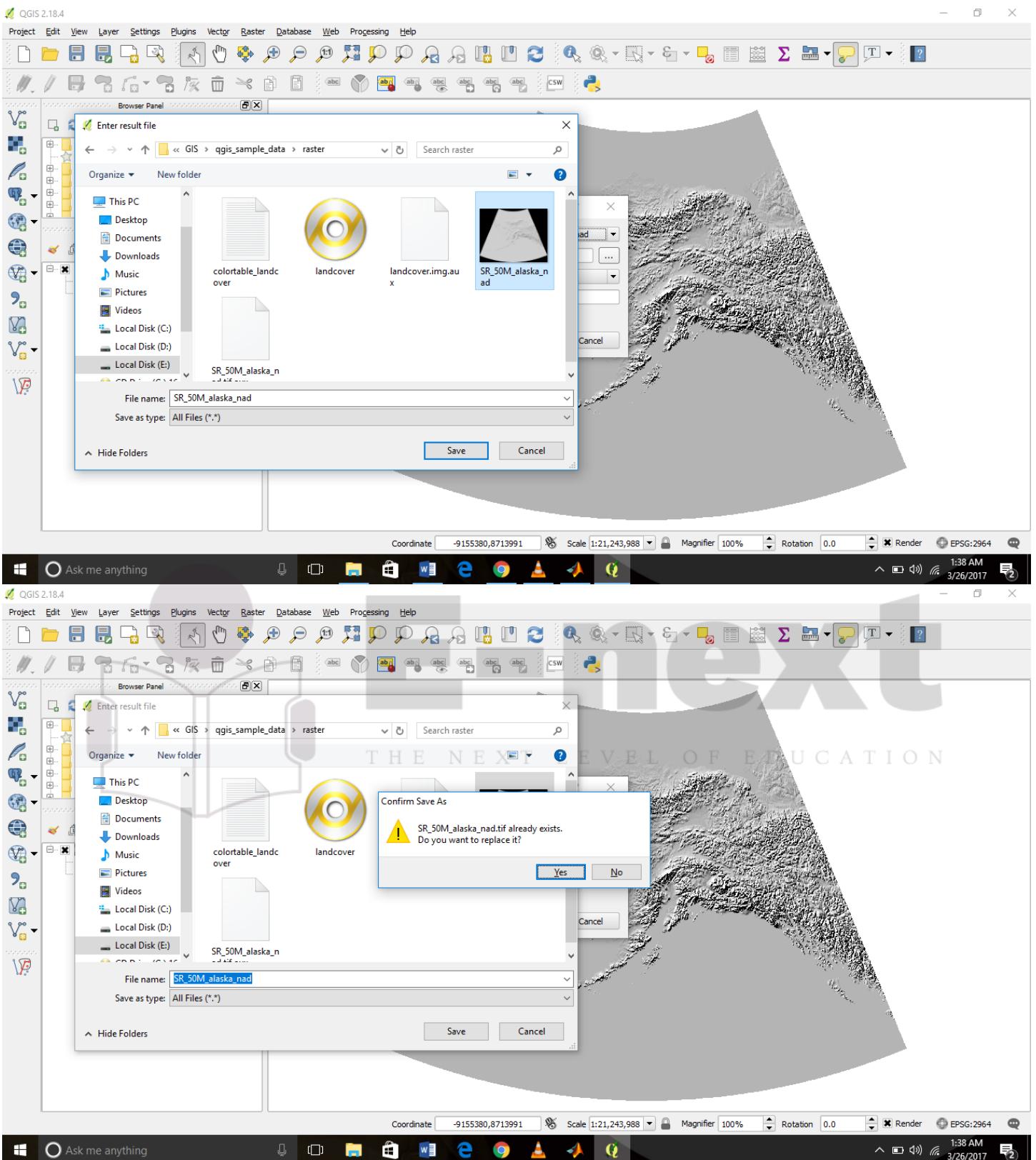
 The Raster Terrain Analysis Plugin can be used to calculate the slope, aspect, hillshade, ruggedness index and relief for digital elevation models (DEM). It is very simple to handle and provides an intuitive graphical user interface for creating new raster layers (See [Figure raster_terrain_1](#)).

Description of the analysis:

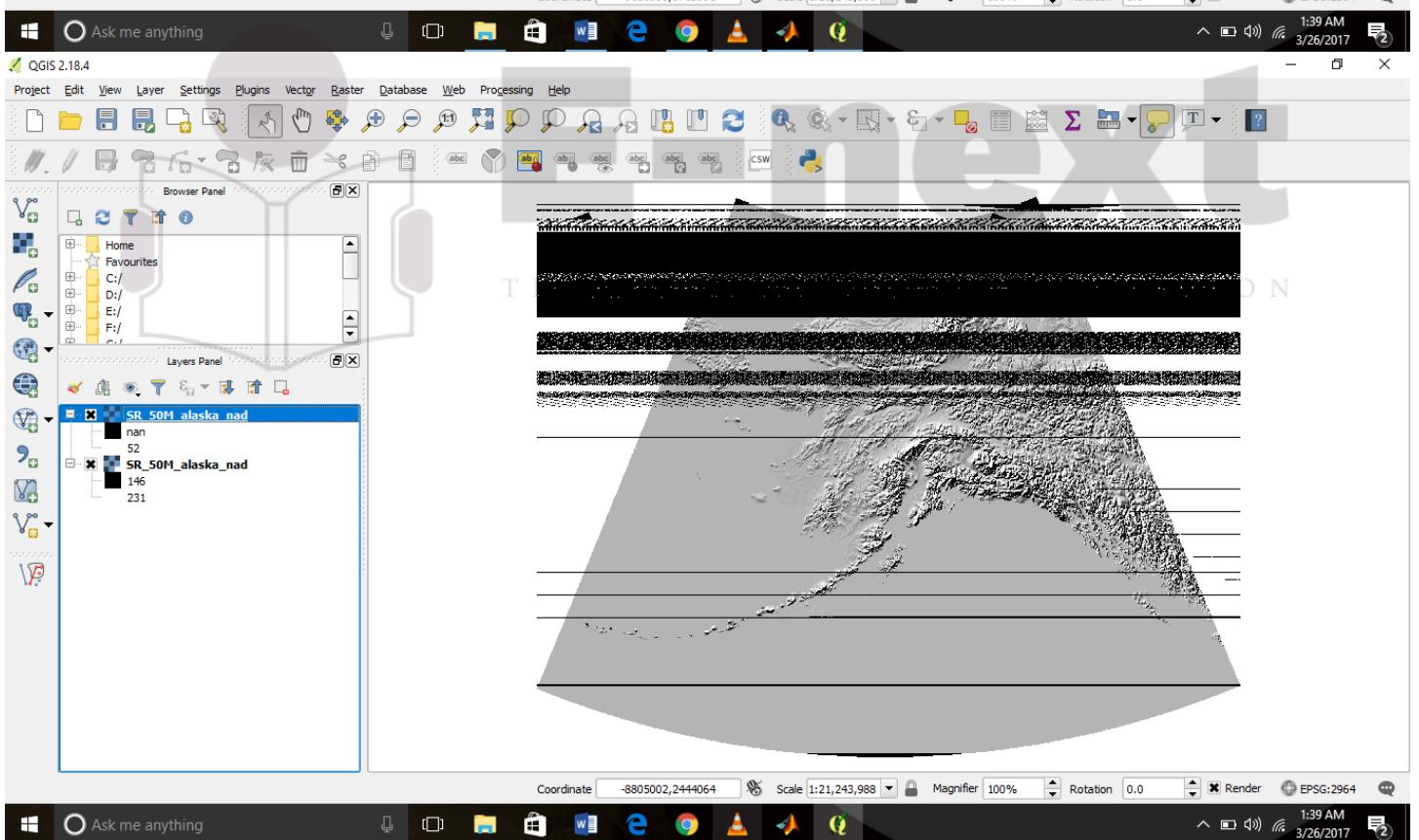
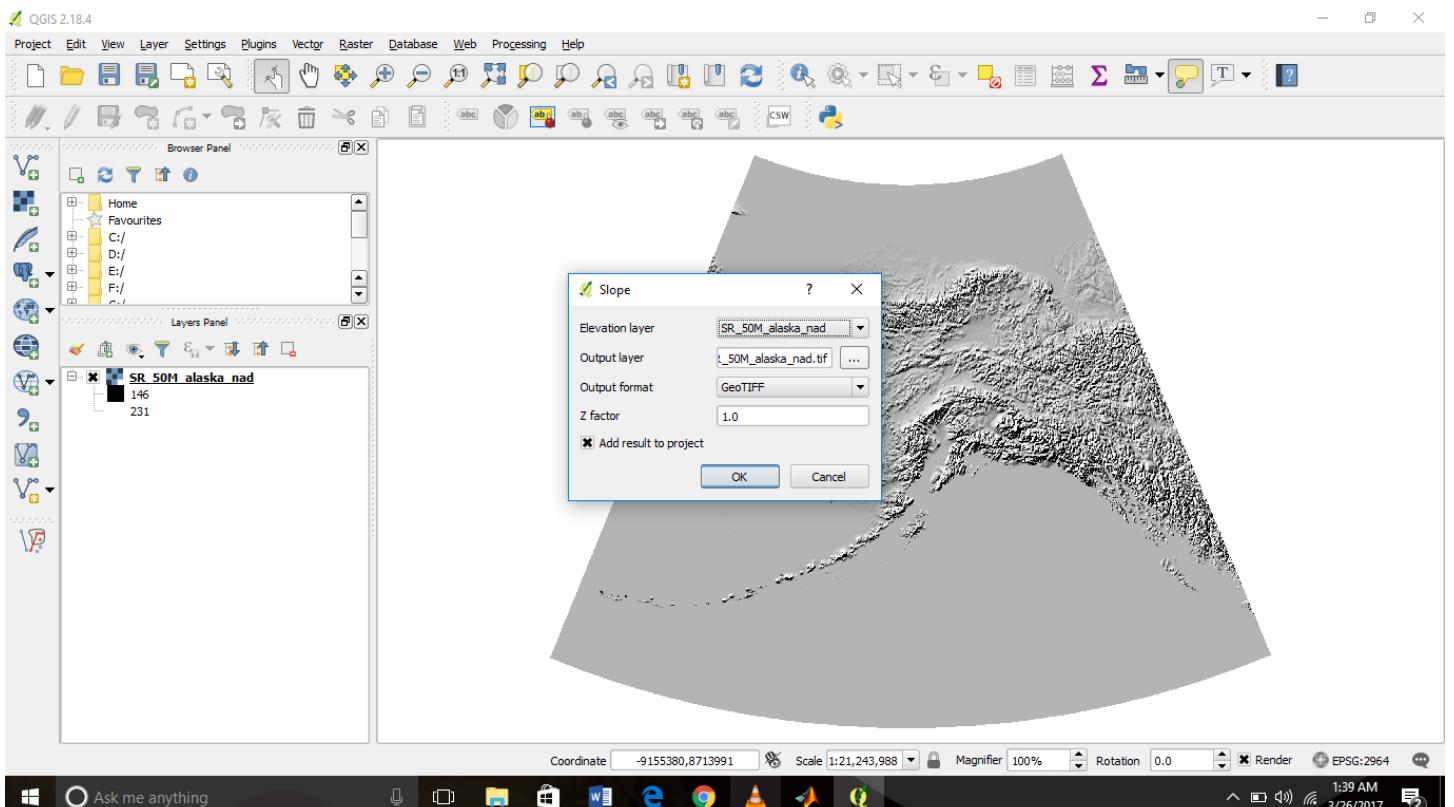
- **Slope:** Calculates slope angle for each cell in degrees (based on first order derivative estimation).
- **Aspect:** Exposition (starting with 0 for north direction, in degrees counterclockwise).
- **Hillshade:** Create shaded map using light and shadow to provide a more three-dimensional appearance for a shaded relief map.
- **Ruggedness Index:** A quantitative measurement of terrain heterogeneity as described by Riley et al. (1999). It is calculated for every location, by summarizing the change in elevation within the 3x3 pixel grid.
- **Relief:** Creating a shaded relief map from digital elevation data. Implemented is a method to choose the elevation colors analysing the frequency distribution.



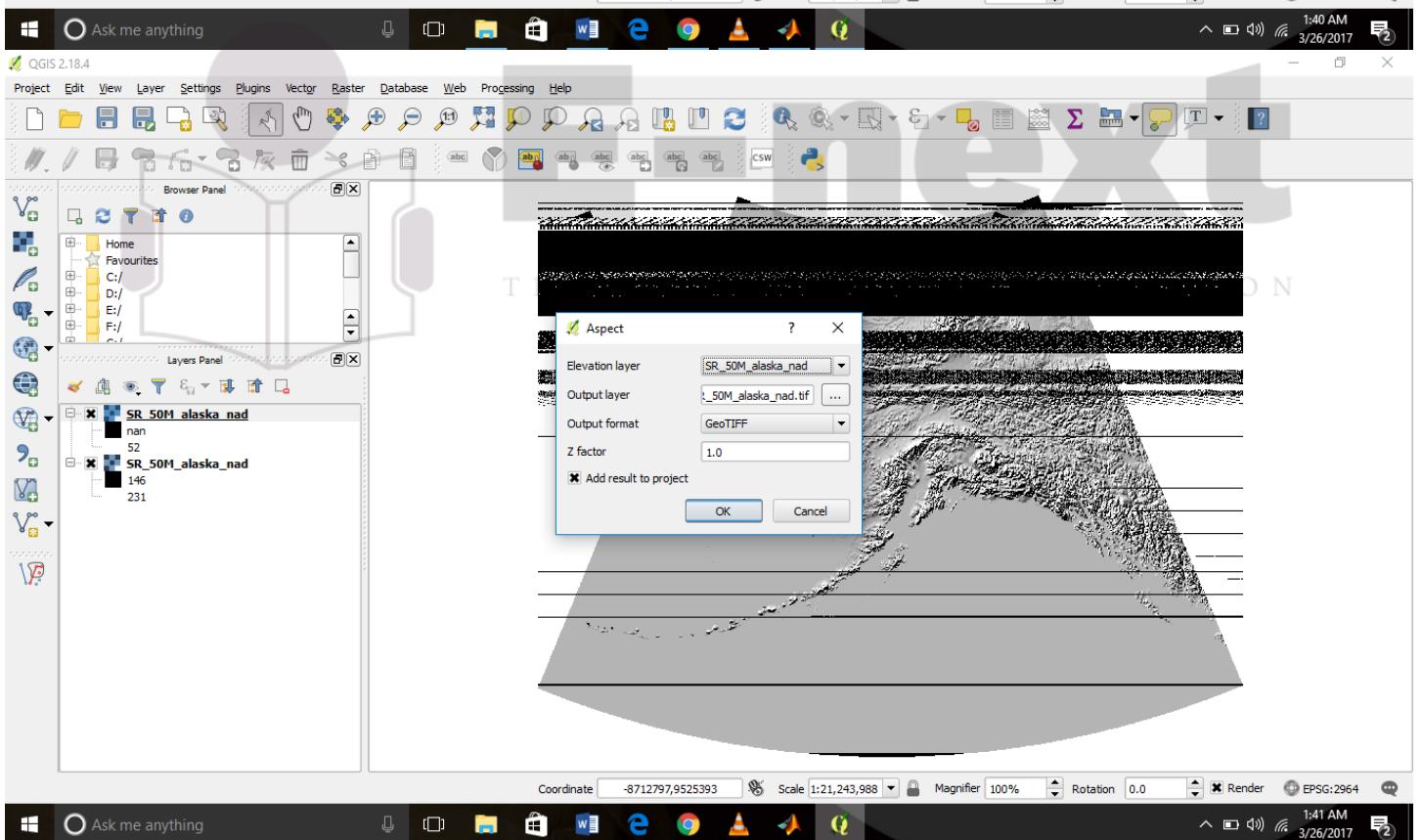
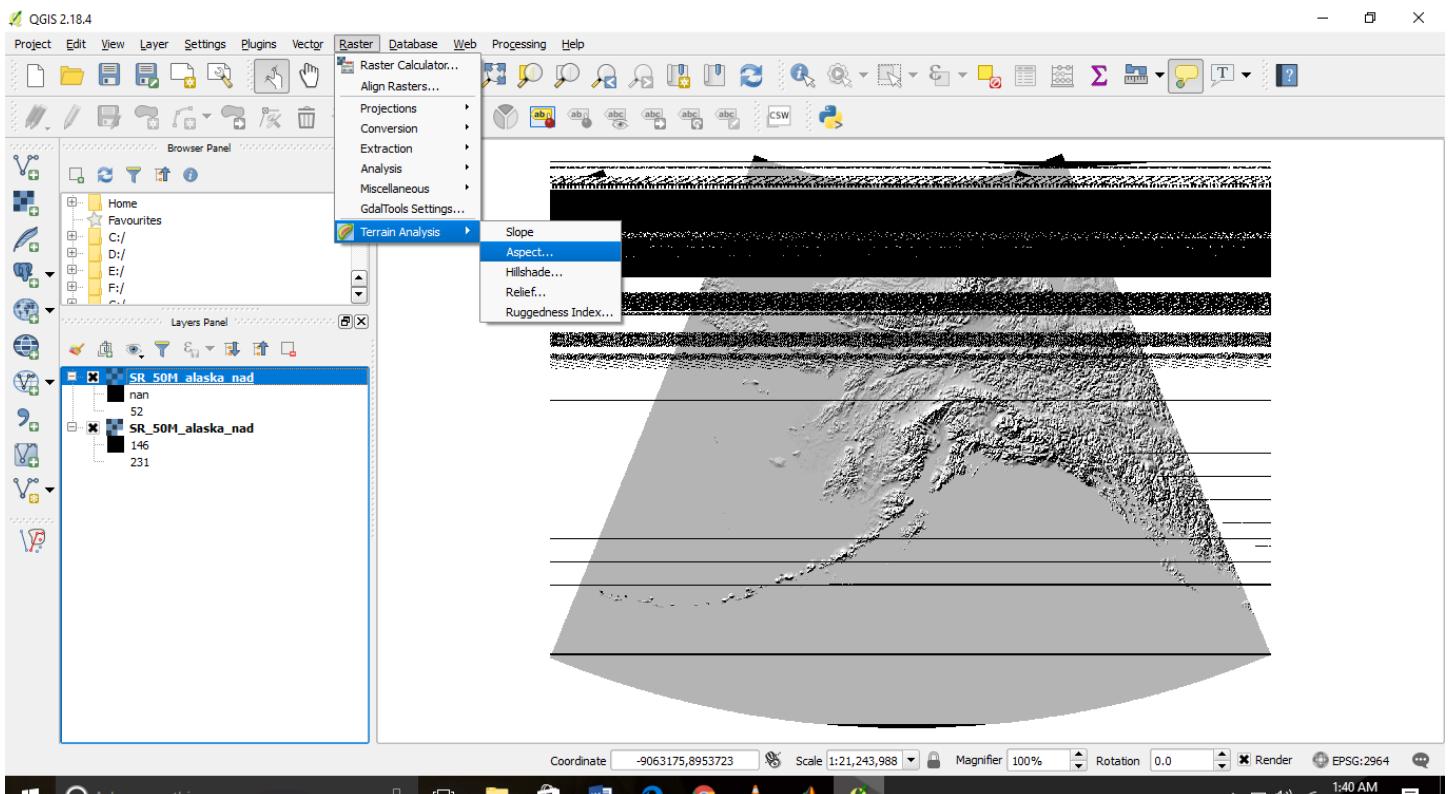
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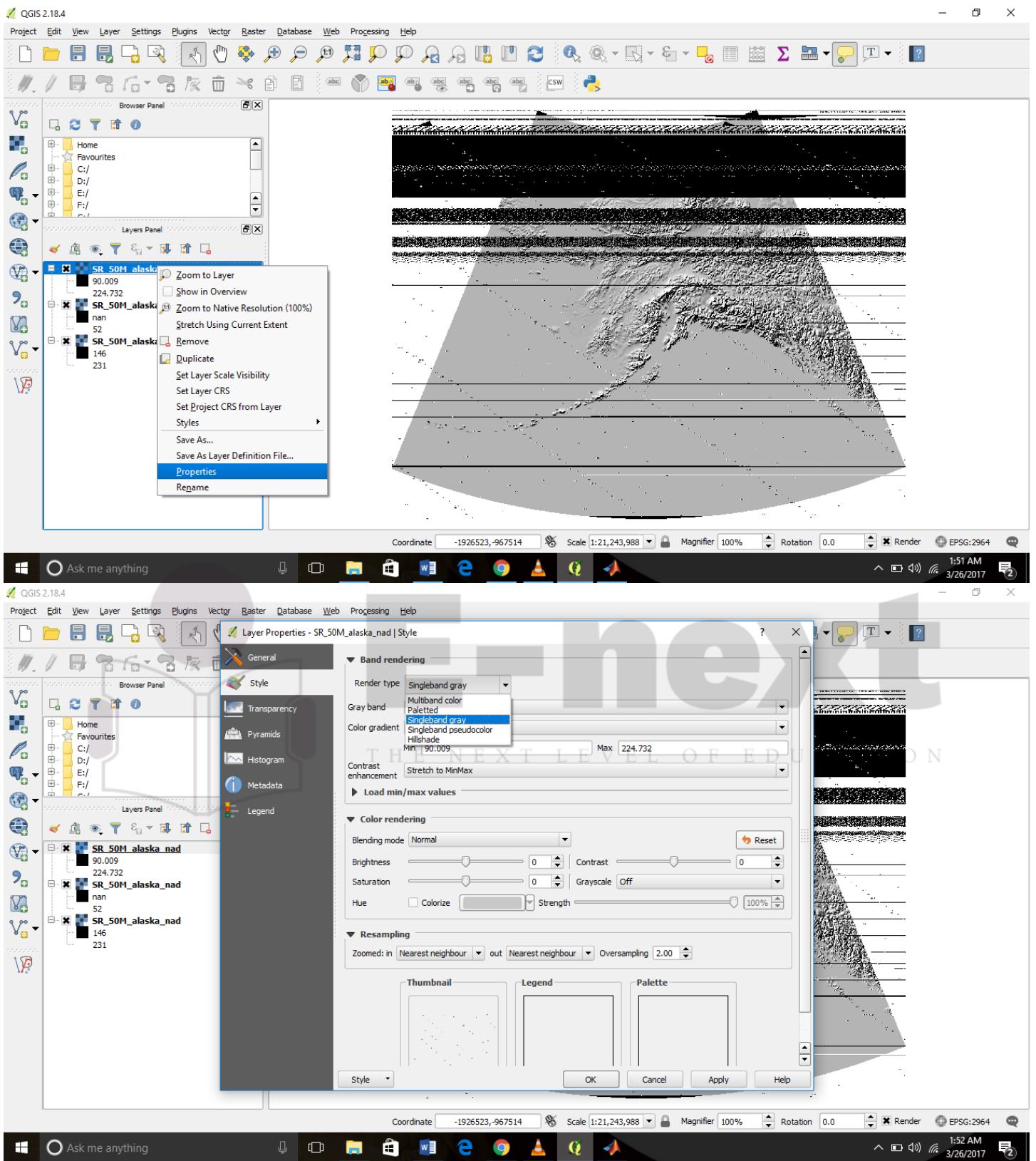
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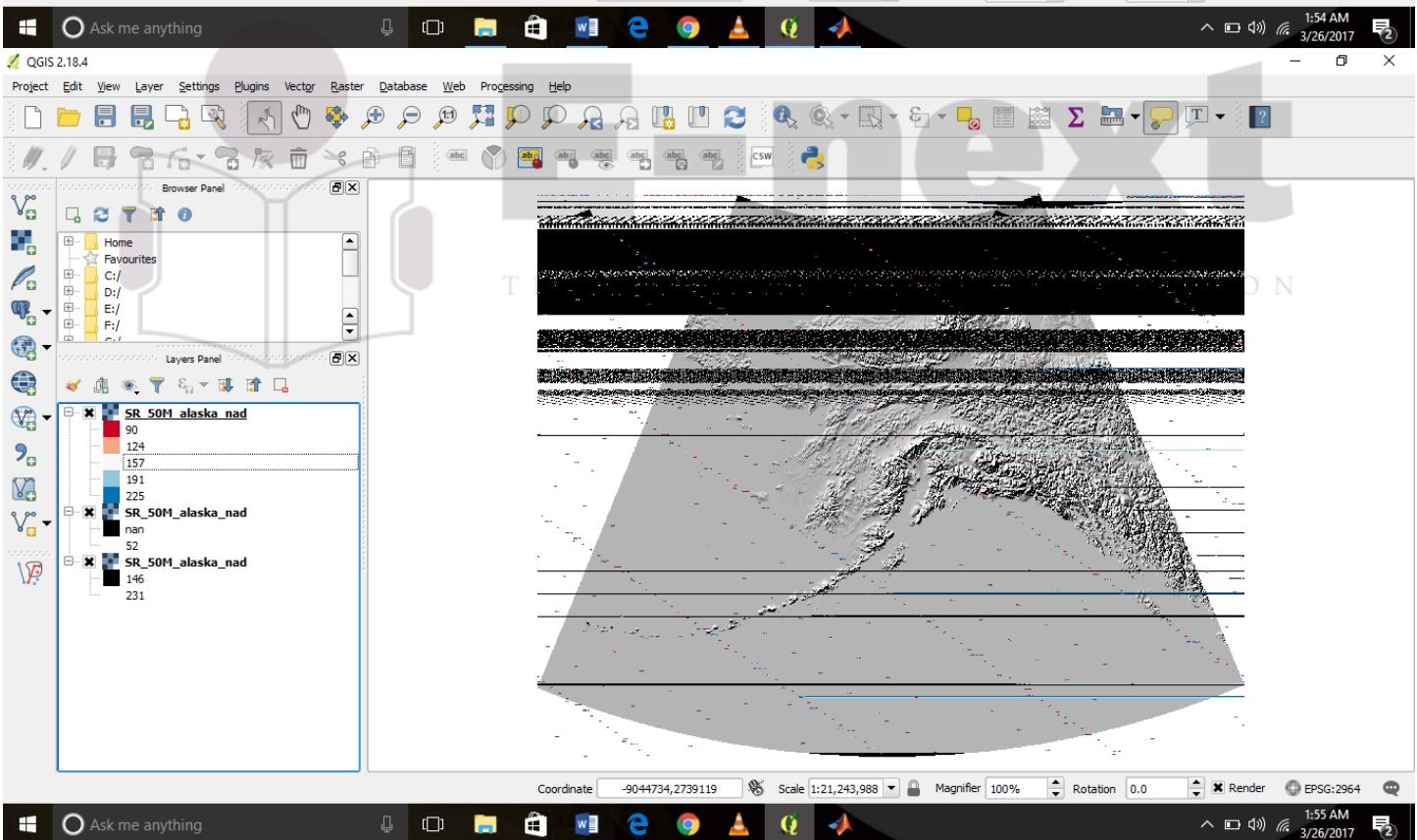
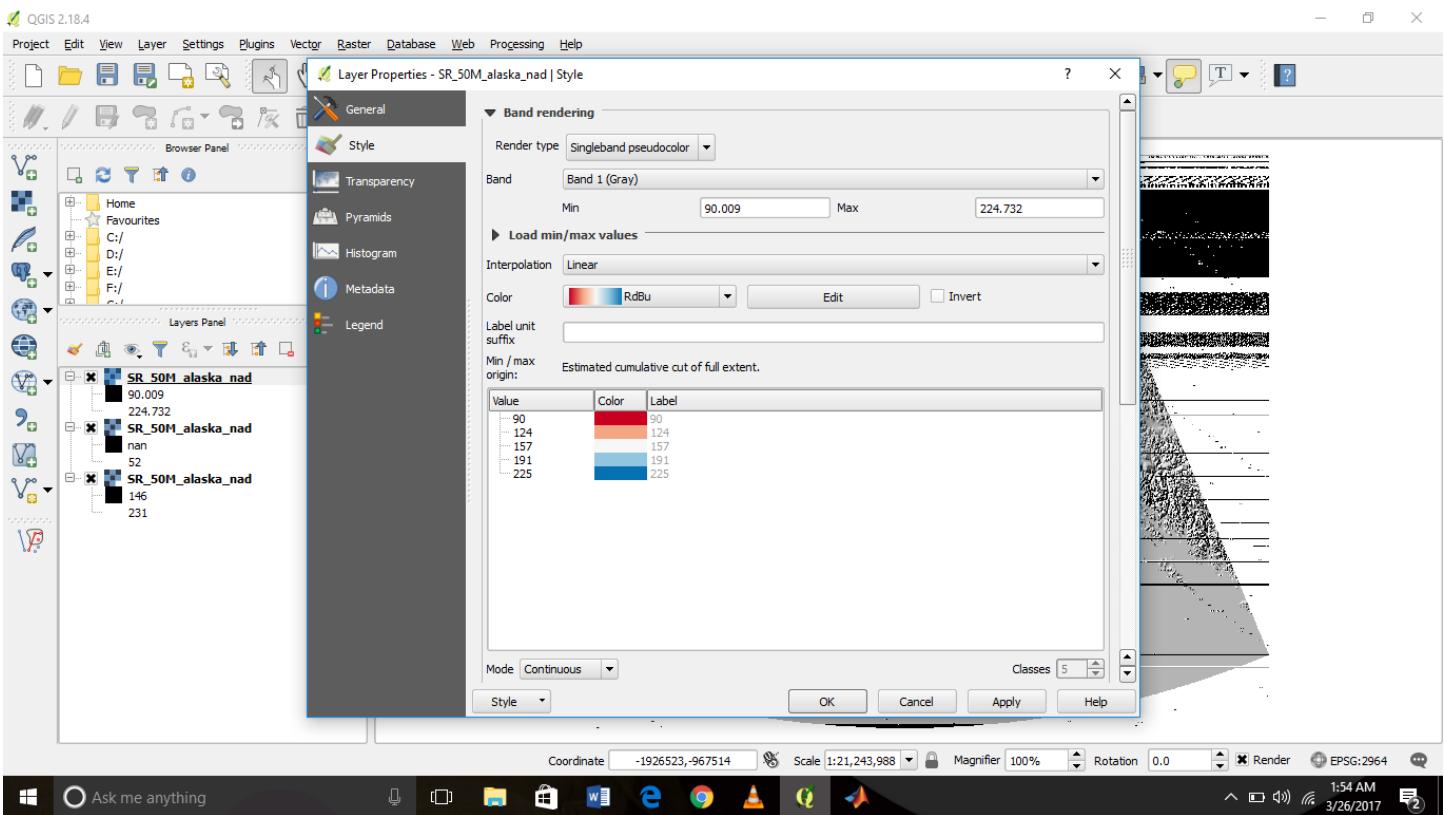
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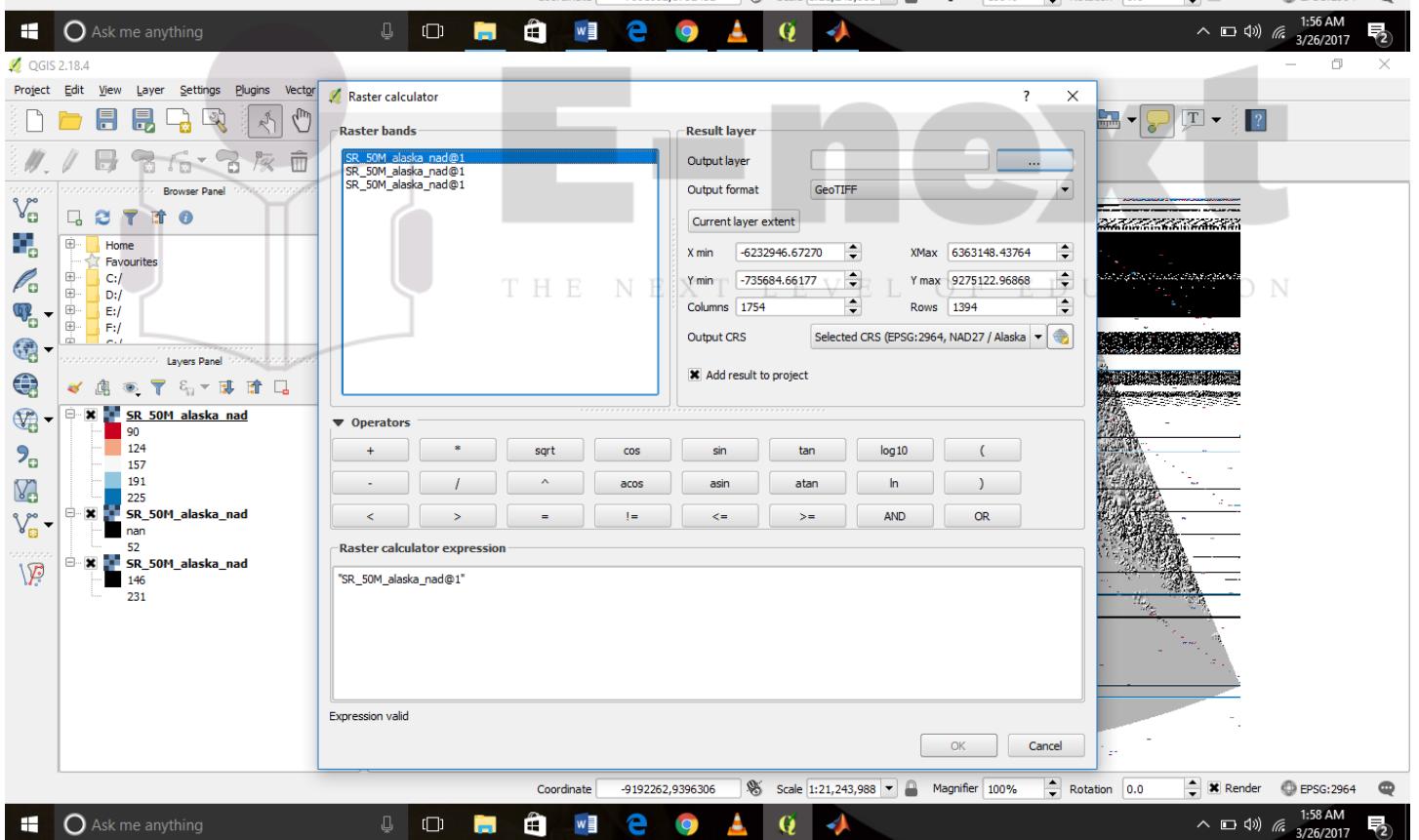
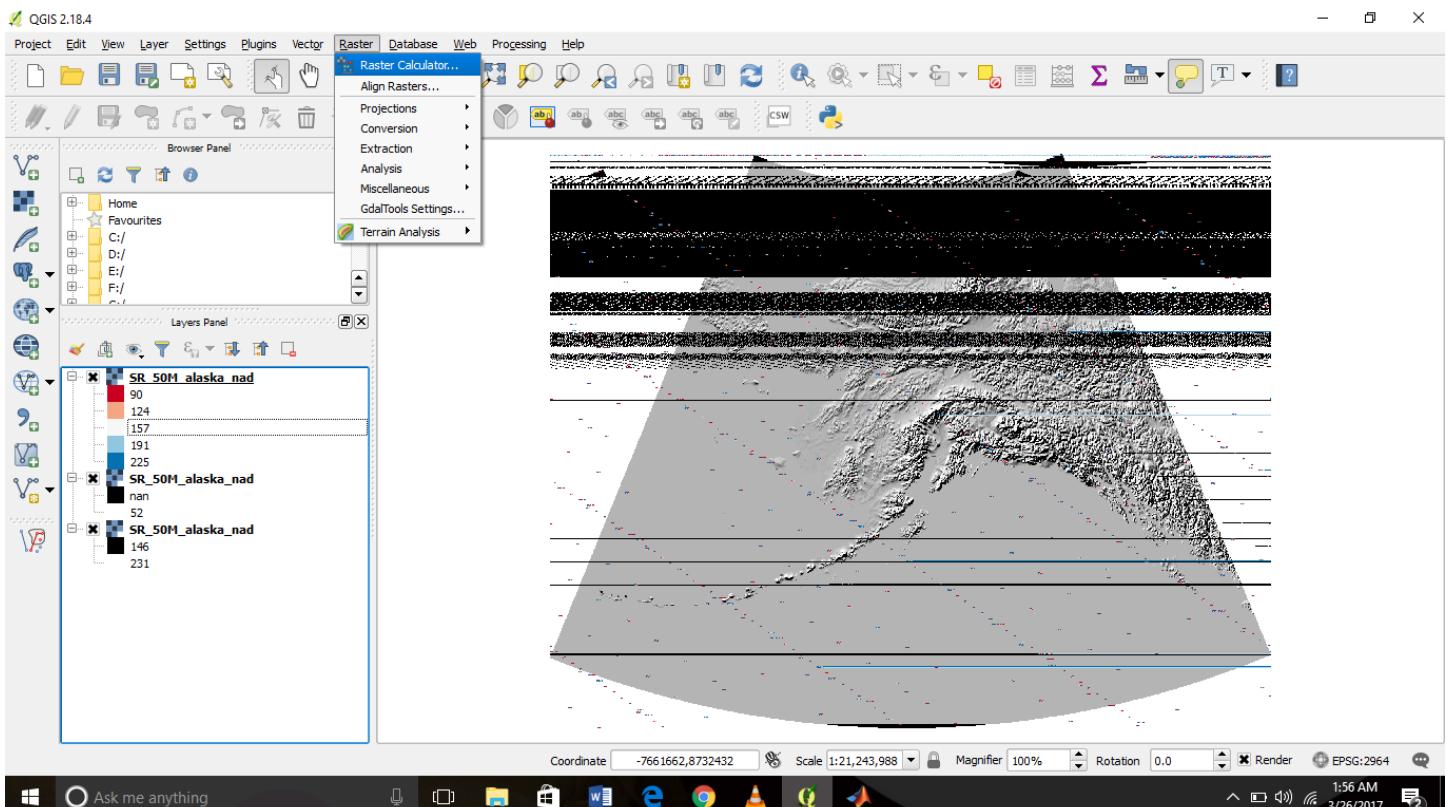
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



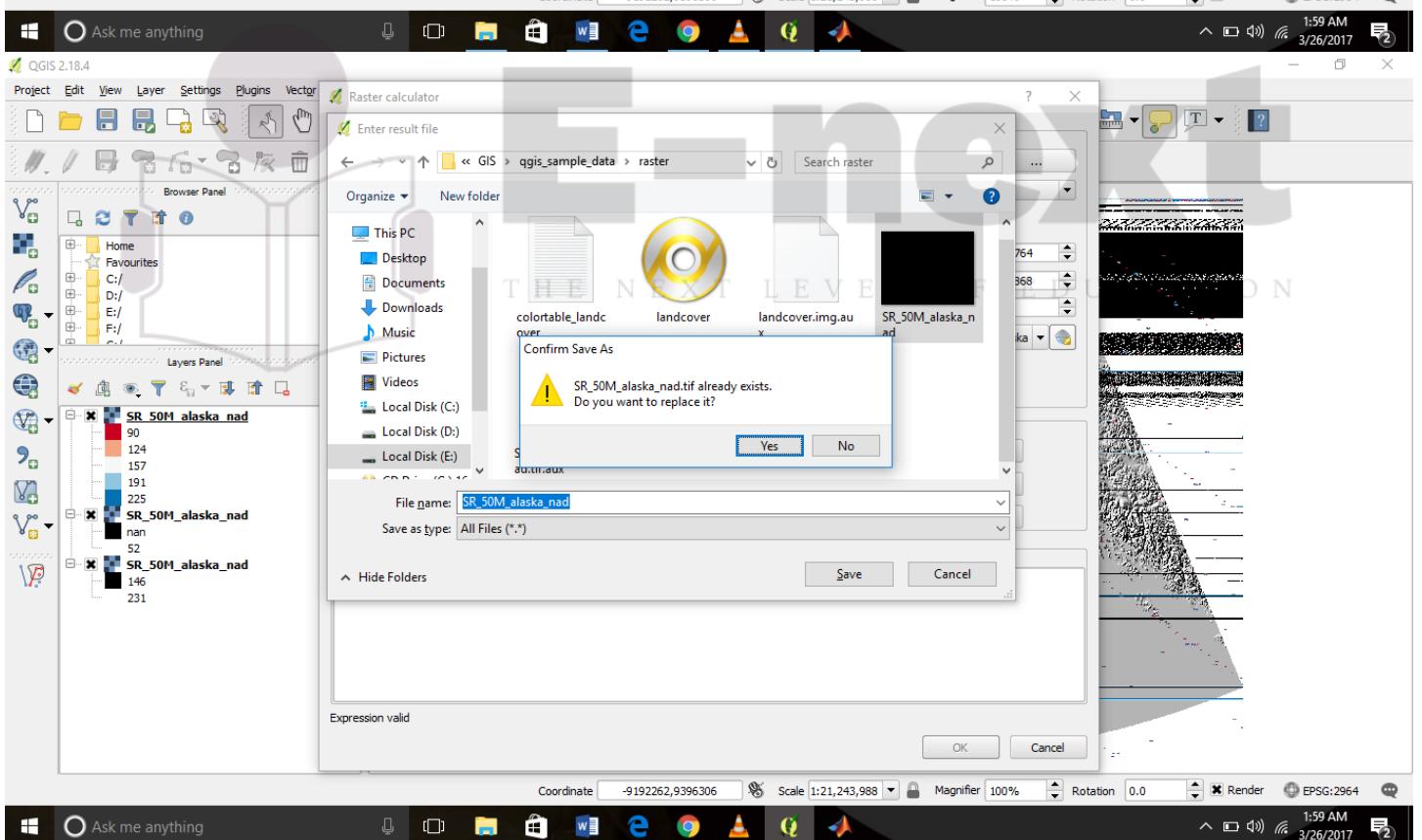
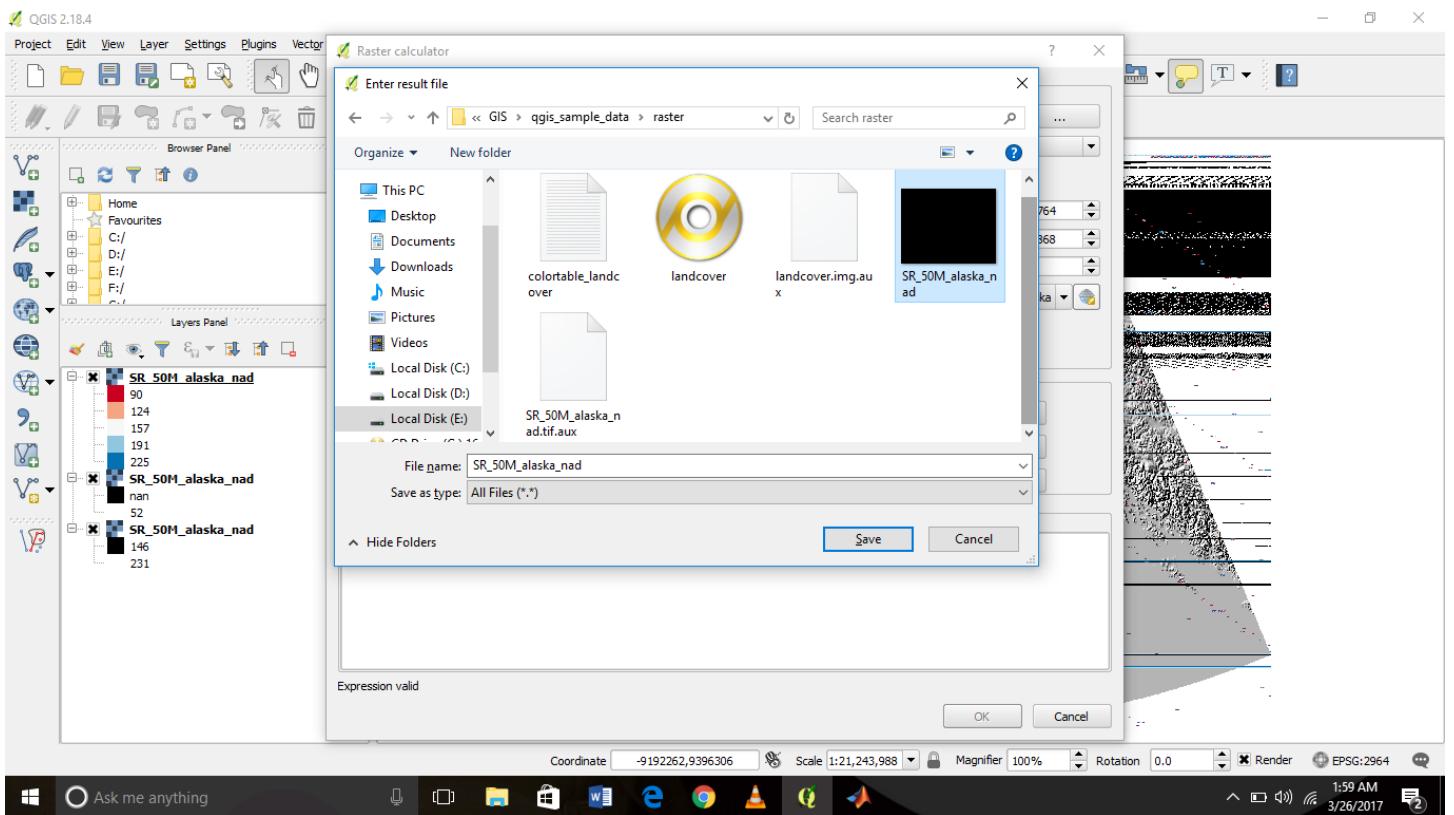
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



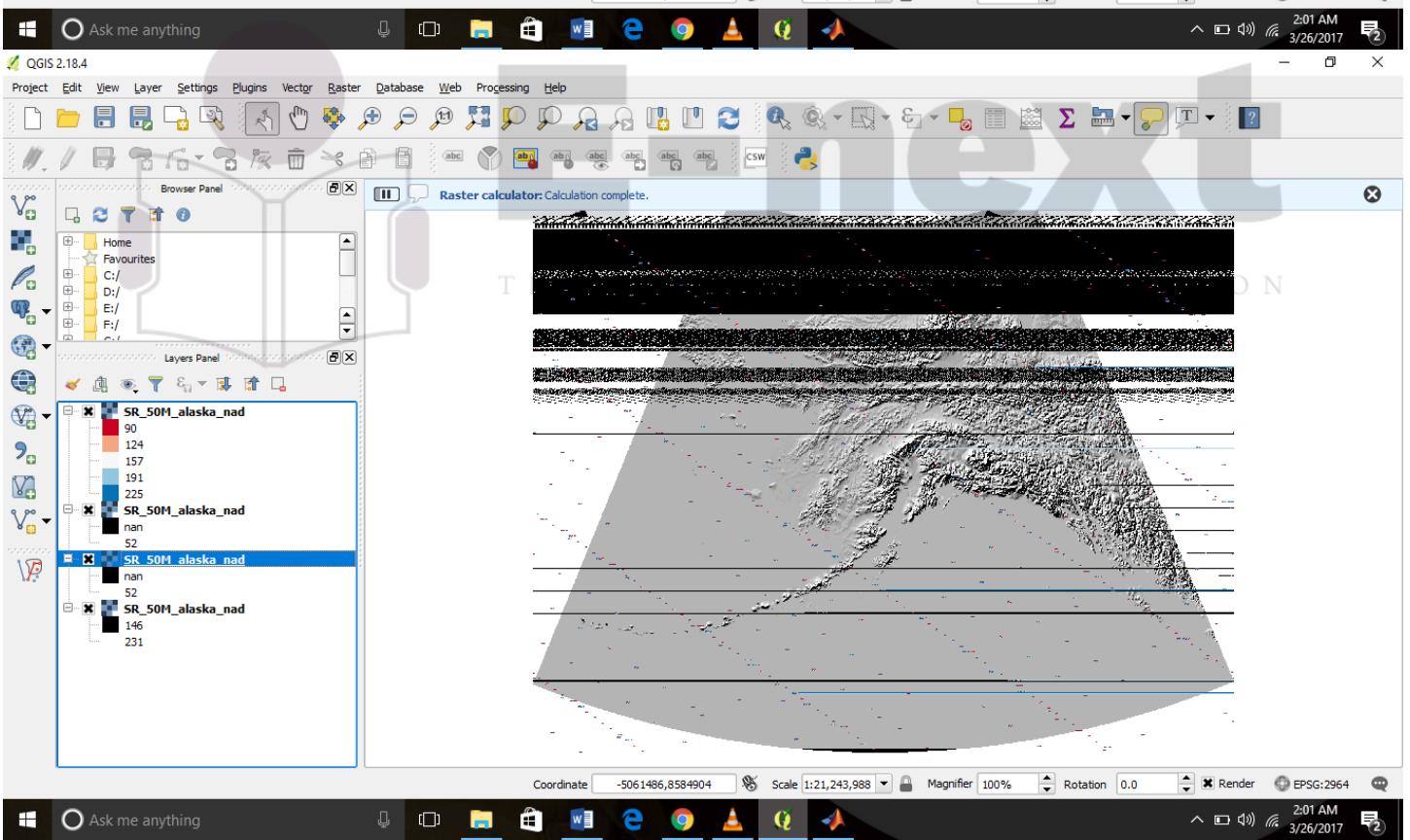
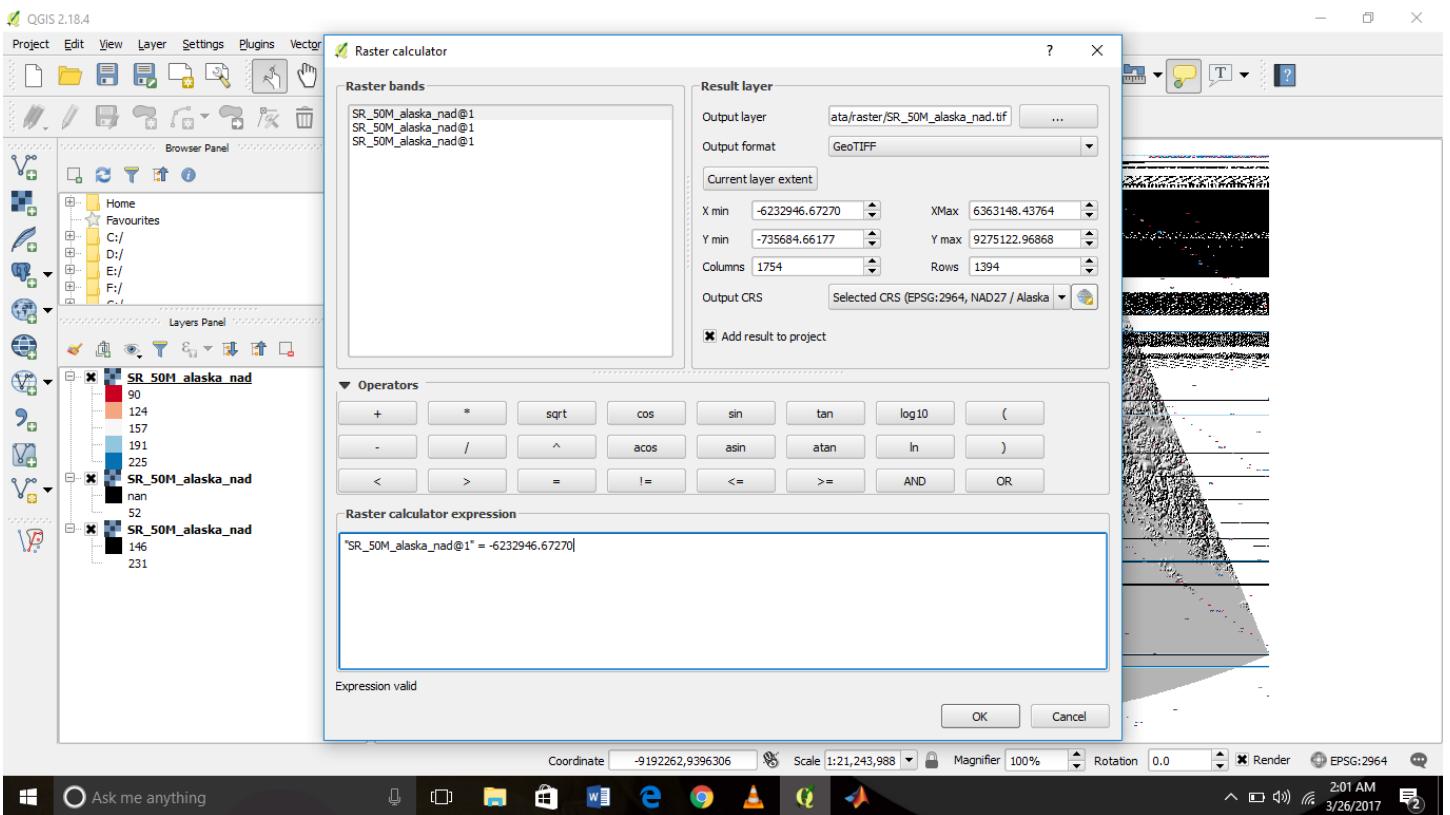
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



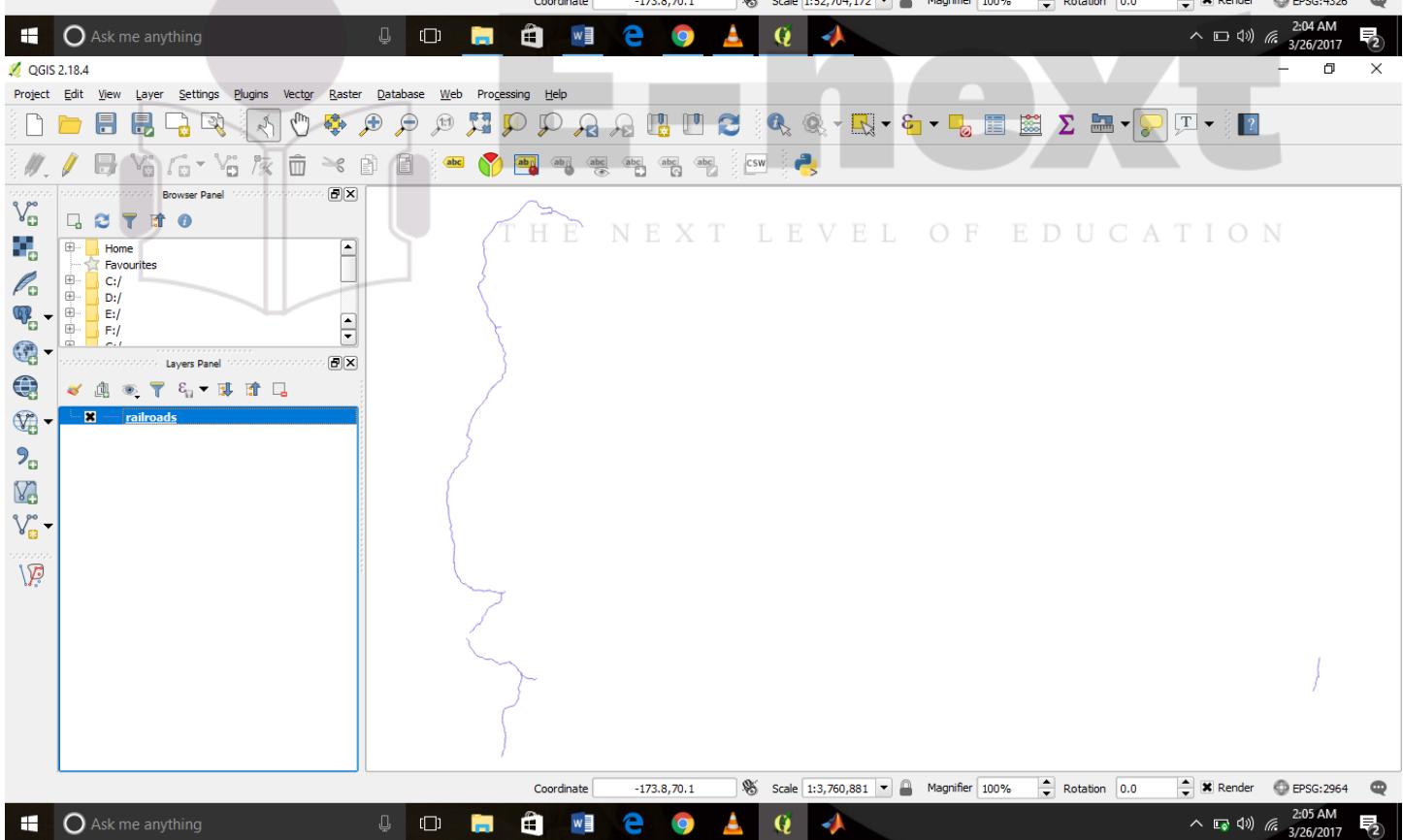
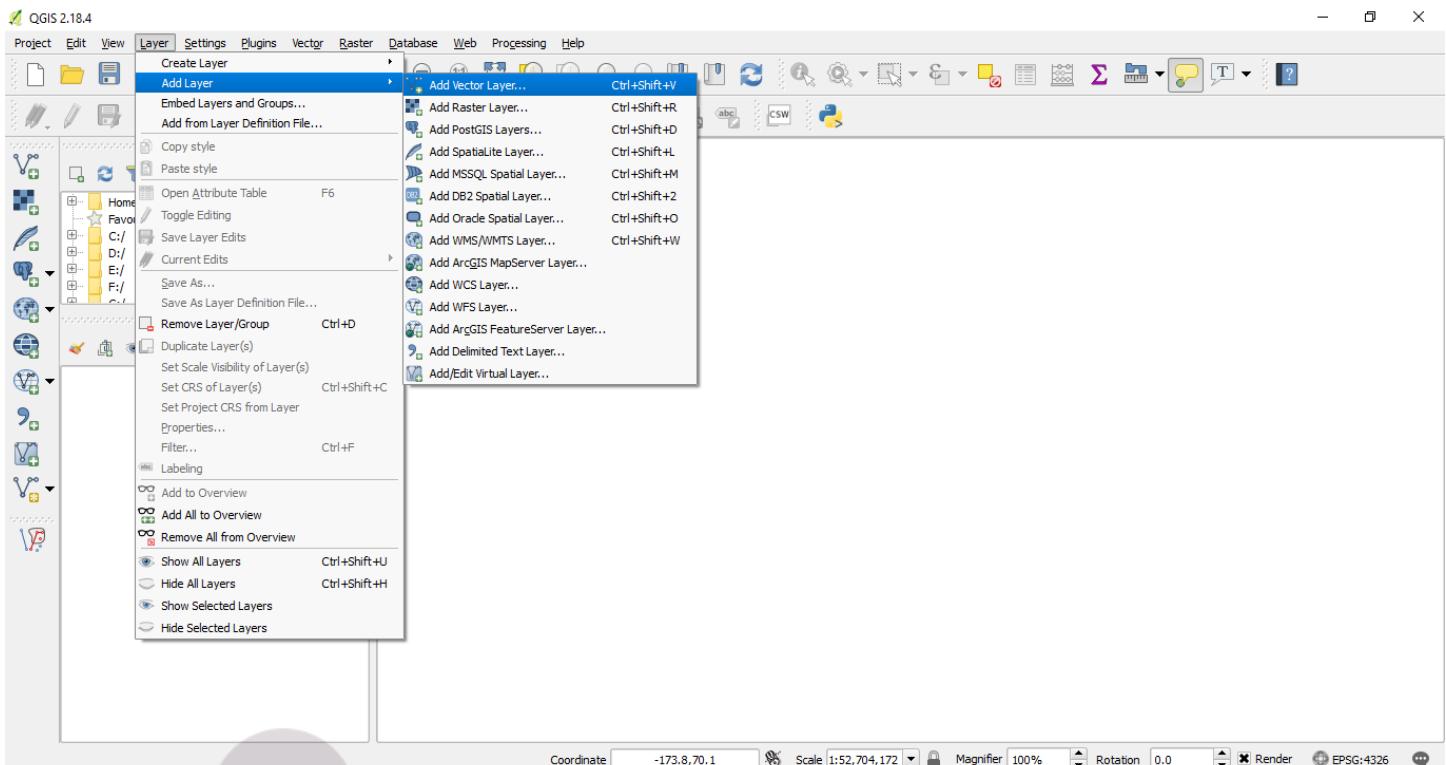
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



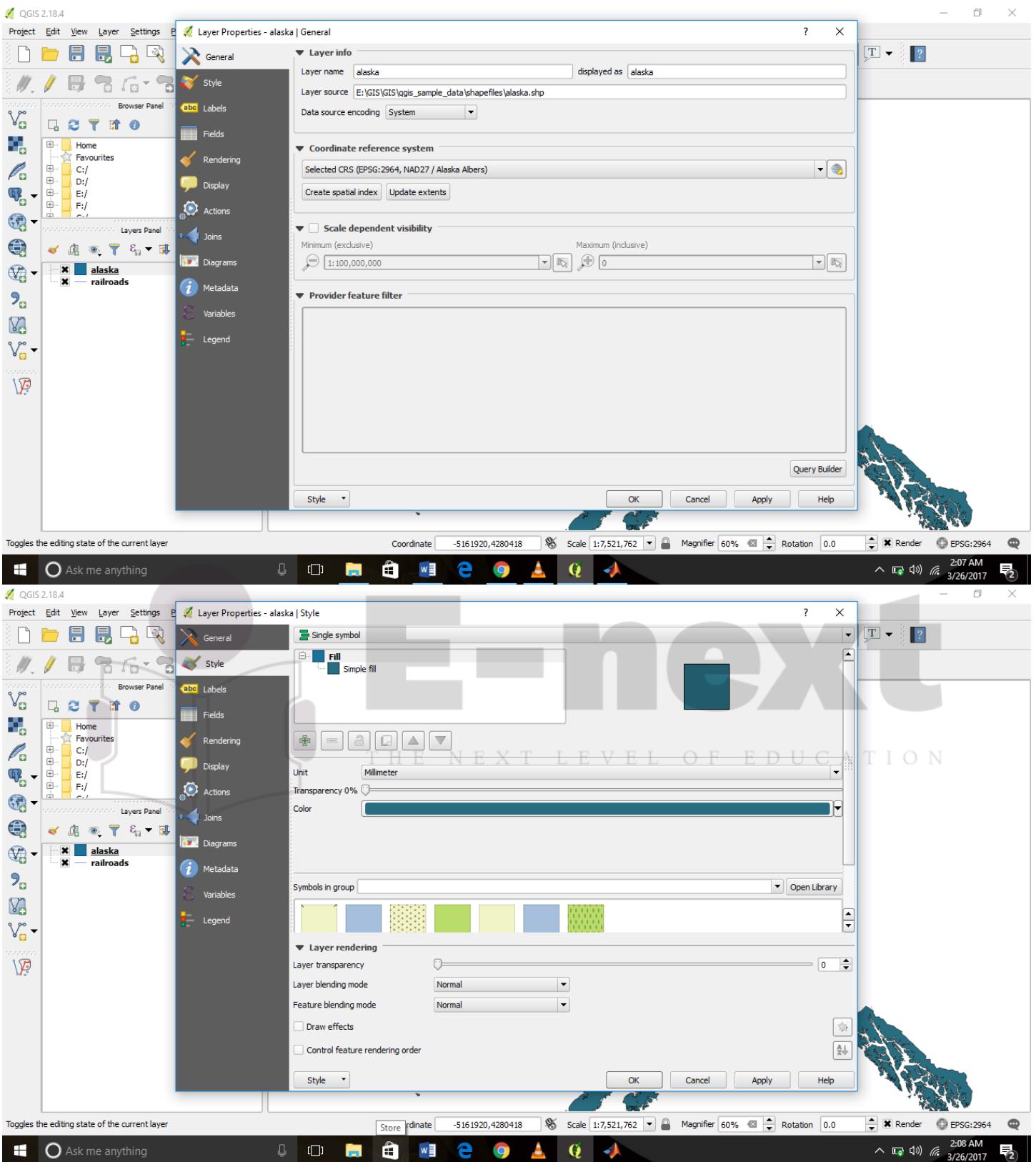
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



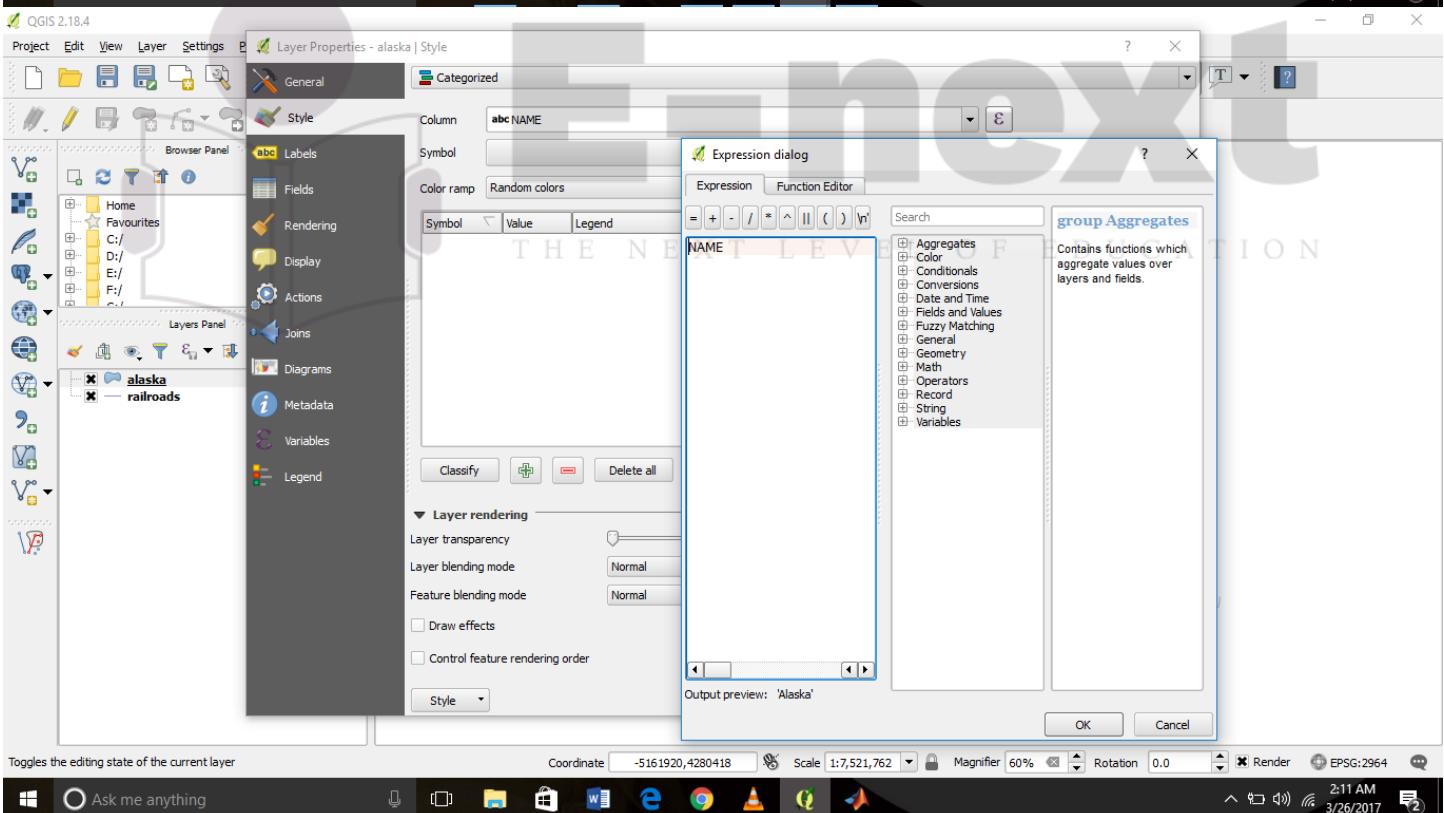
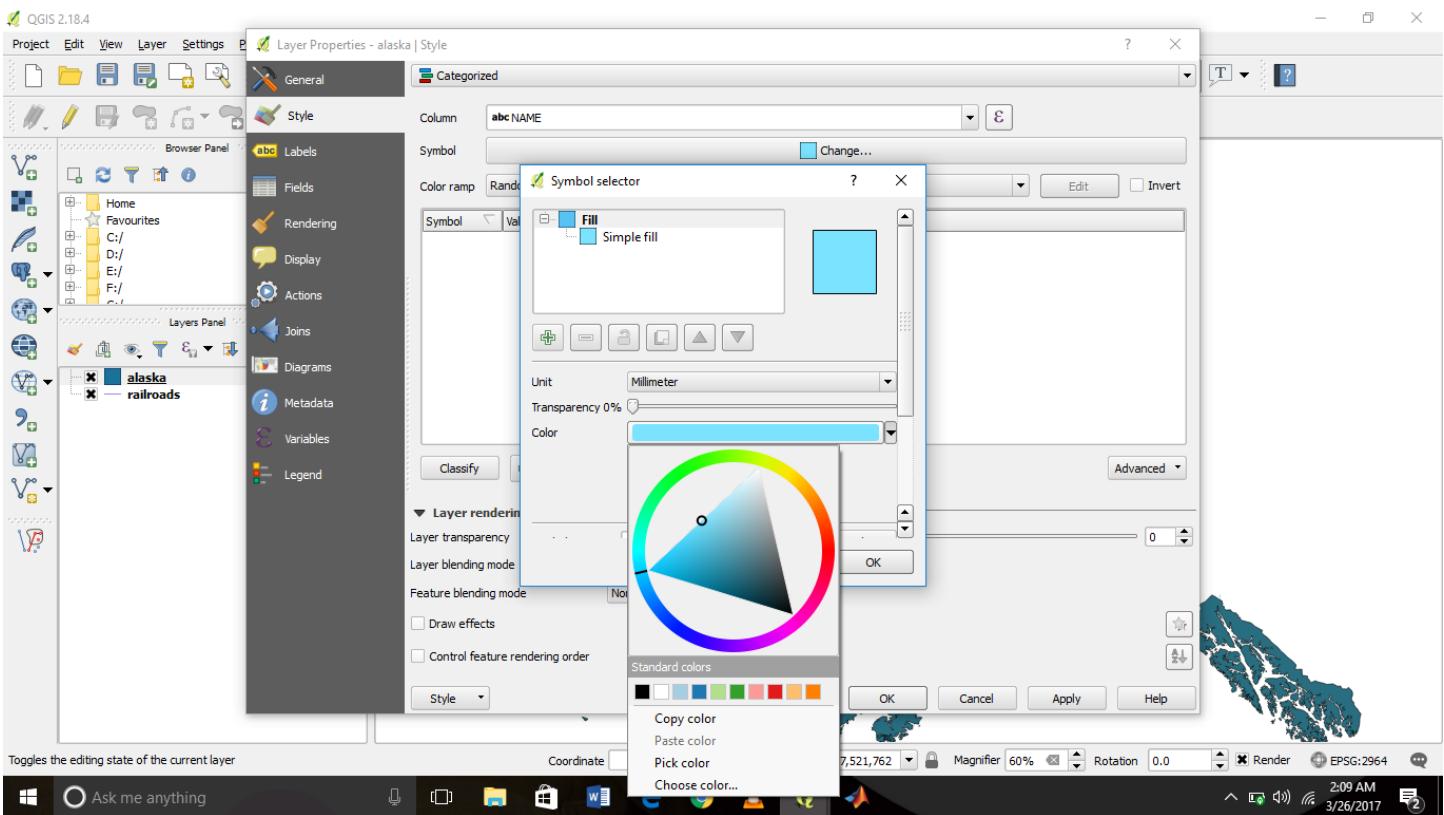
Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>



Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>

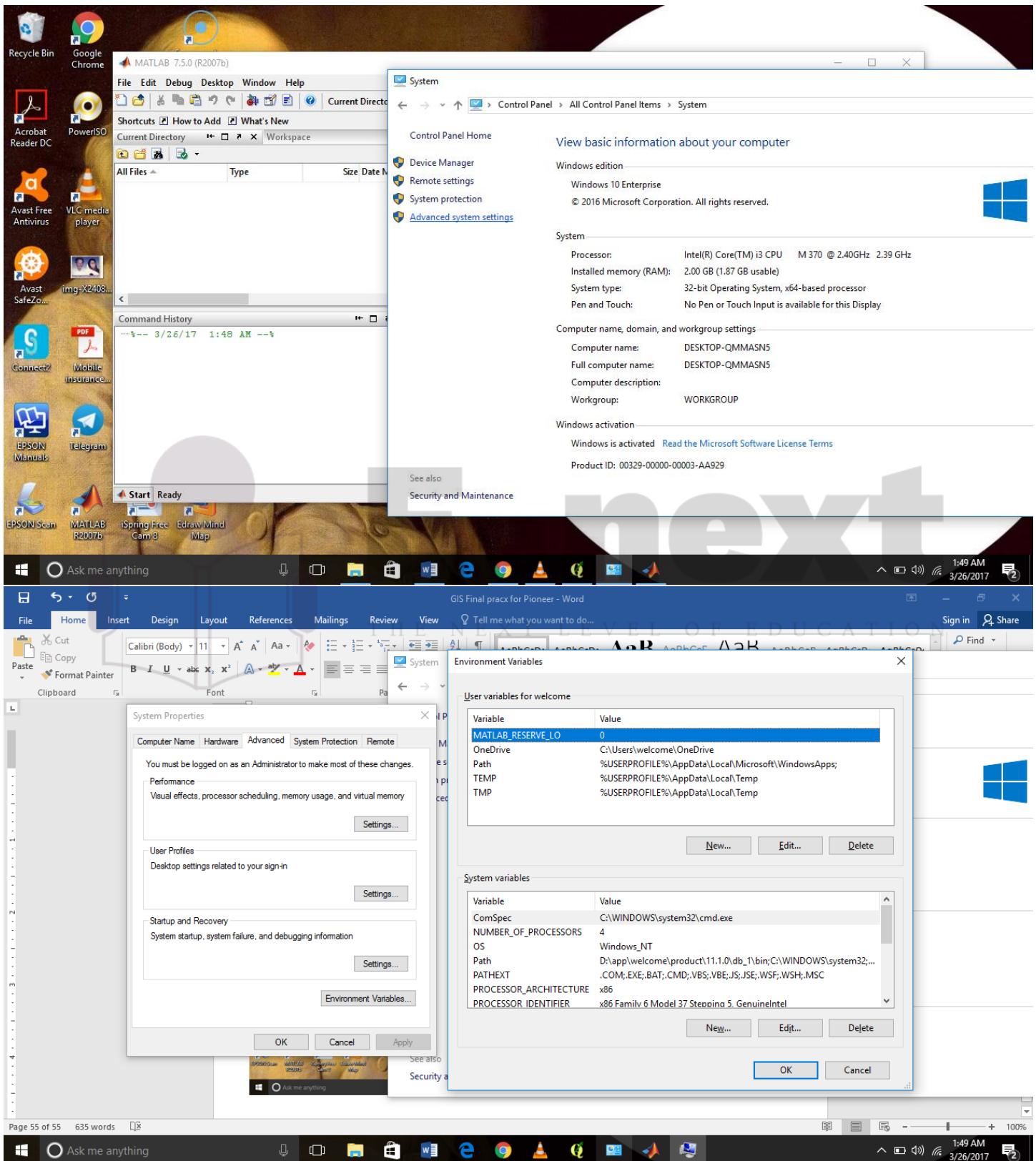


Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>

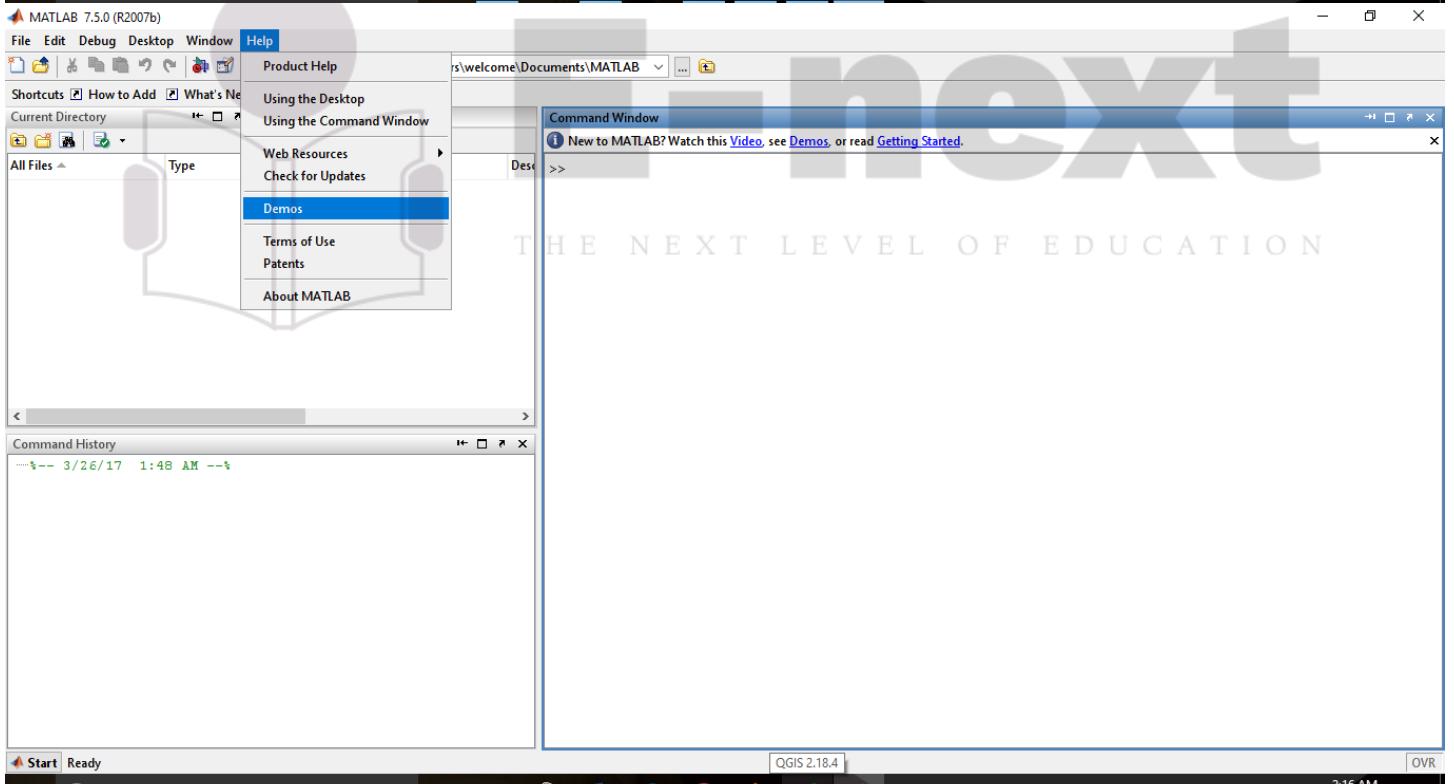
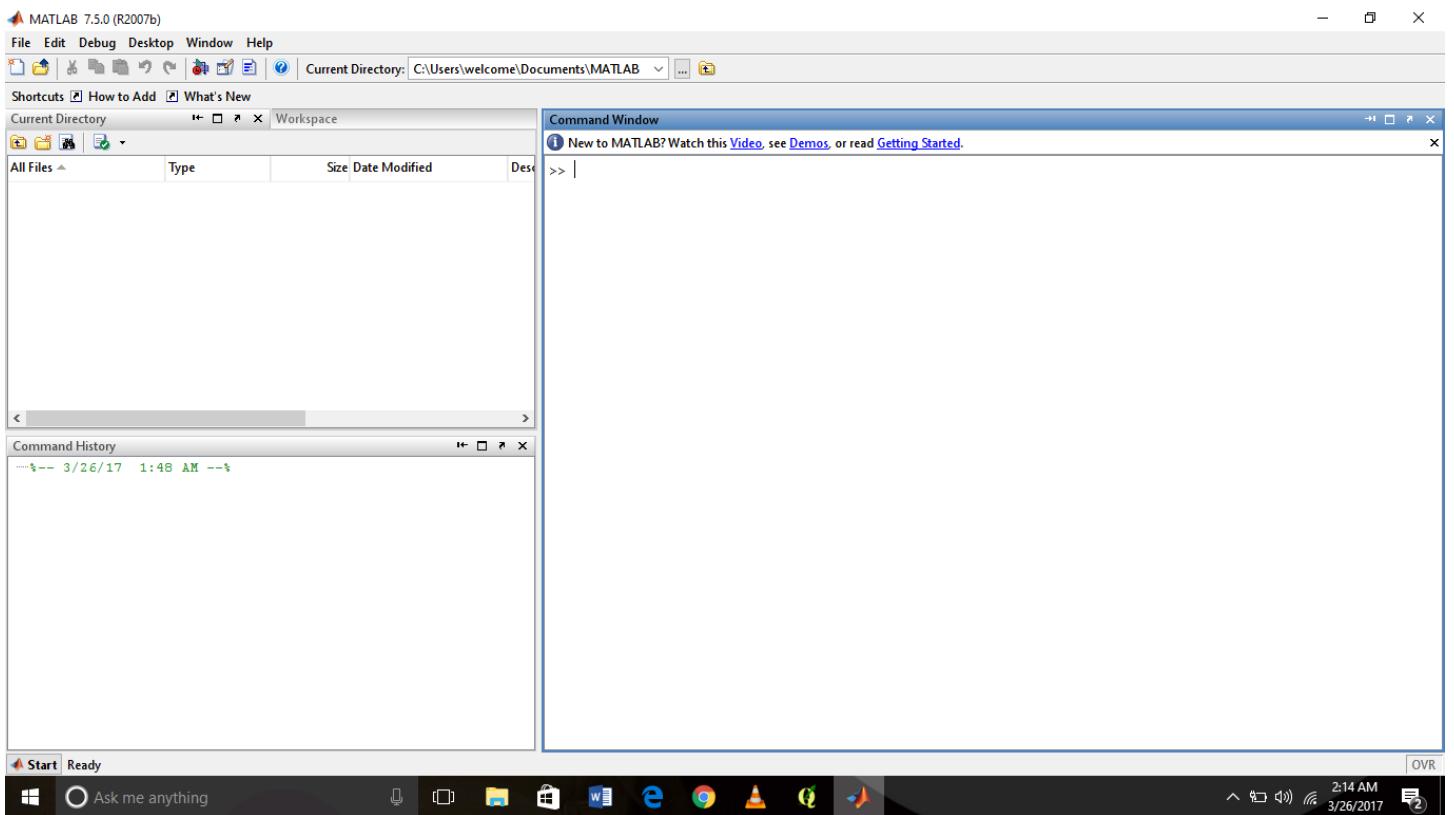


Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>

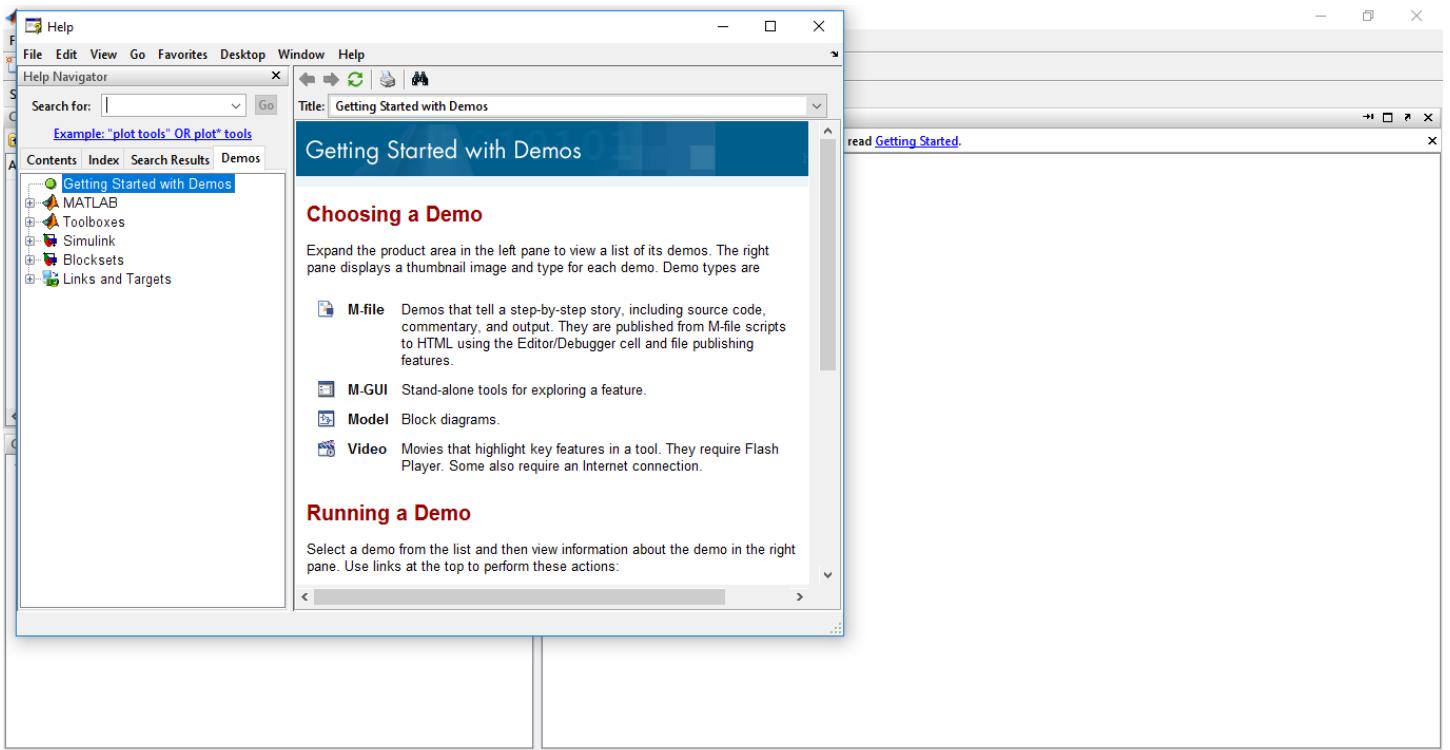
Matlab



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Help Navigator

Search for: image registration Go Example: "plot tools" OR plot* tools

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- Registering an Aerial Photo to a...

Image Registration

This chapter describes the **image registration** capabilities of **Image Processing Toolbox**. **Image registration** is the process of aligning two or more images of the same scene. **Image registration** is often used as a preliminary step in other **image** processing applications.

Registering an Image	Steps you through an example of the image registration process
Transformation Types	Describes the types of supported transformations
Selecting Control Points	Describes how to use the Control Point Selection Tool (<code>cpsel</code>) to select control points in pairs of images
Using Correlation to Improve Control Points	Describes how to use the <code>cpccorr</code> function to fine-tune your control point selections

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Example: Performing **Image Registration** Registering an **Image**

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Search Support Database on Web for **image registration**

24 pages contain the search terms: **image AND registration**

Ask me anything

2:17 AM 3/26/2017

The screenshot shows the MATLAB Help Navigator window. The search bar at the top contains the text "image registration". Below the search bar, a list of documentation search results is displayed under the heading "Documentation Search Results (23)". One result, "Image Registration", is highlighted. To the right of the search results, the main content area displays the "Image Processing Toolbox" help page for "Registering an Image". The page includes sections like "On this page...", "Overview", "Point Mapping", and "Using cselect in a Script". A note at the bottom of the page states: "Note You might need to perform several iterations of this process, experimenting with different types of transformations, before you achieve a satisfactory result. In some cases, you might perform successive registrations, removing gross global distortions first, and then removing smaller local distortions in subsequent passes." The status bar at the bottom of the window shows the date and time as 3/26/2017 2:18 AM.

The screenshot shows the MATLAB desktop interface. The menu bar includes "File", "Edit", "View", "Go", "Favorites", "Desktop", "Window", and "Help". The "Help" menu is open, showing options like "New", "Open...", "Close Help", "Import Data...", "Save Workspace As...", "Set Path...", "Preferences...", "Page Setup...", "Print...", "Print Selection...", and "Exit MATLAB". The "File" menu also lists "M-File Ctrl+N", "Figure", "Variable", "Model", and "GUI". The main workspace area displays the "Image Processing Toolbox" help page for "Registering an Image". The page content is identical to the one in the Help Navigator, including the "On this page..." section and the note about iterative registration. The status bar at the bottom shows the date and time as 3/26/2017 2:19 AM.

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Screenshot of the MATLAB Help Navigator showing the "Image Registration" topic.

Title: Registering an Image :: Image Registration (Image Processing Toolbox)

Contents

- Step 1: Read the Images into MATLAB
- Step 2: Select Control Points
- Step 3: Compute the Transformation
- Step 4: Fine-Tune the Control Point Pair Placement (Optional)
- Step 5: Specify the Type of Transformation and Infer Its Parameters
- Step 6: Transform the Unregistered Image

Text:

The base image or reference image, is considered the reference to input image into alignment with the base image by applying a spatial transformation. This occurred as a result of terrain relief and other changes in perspectives between sensors and sensor types, can also cause distortion. See [Spatial Transformations](#) Determining the parameters of the spatial transformation.

You can use image registration to align satellite images of the earth's surface, or you can compare features in the images to see how a river has migrated, how an area is flooded, or to see if a tumor is visible in an MRI or SPECT image.

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Point Mapping

Image Processing Toolbox provides tools to support point mapping to determine the parameters of the transformation required to bring an image into alignment with another image. In point mapping, you pick points in a pair of images that identify the same feature or landmark in the images. Then, a spatial mapping is inferred from the positions of these control points.

Note: You might need to perform several iterations of this process, experimenting with different types of transformations, before you achieve a satisfactory result. In some cases, you might perform successive registrations, removing gross global distortions first, and then removing smaller local distortions in subsequent passes.

Screenshot of the MATLAB Help Navigator showing the "Image Registration" topic.

Title: Registering an Image :: Image Registration (Image Processing Toolbox)

Contents

- Step 1: Read the Images into MATLAB
- Step 2: Select Control Points
- Step 3: Compute the Transformation
- Step 4: Fine-Tune the Control Point Pair Placement (Optional)
- Step 5: Specify the Type of Transformation and Infer Its Parameters
- Step 6: Transform the Unregistered Image

Text:

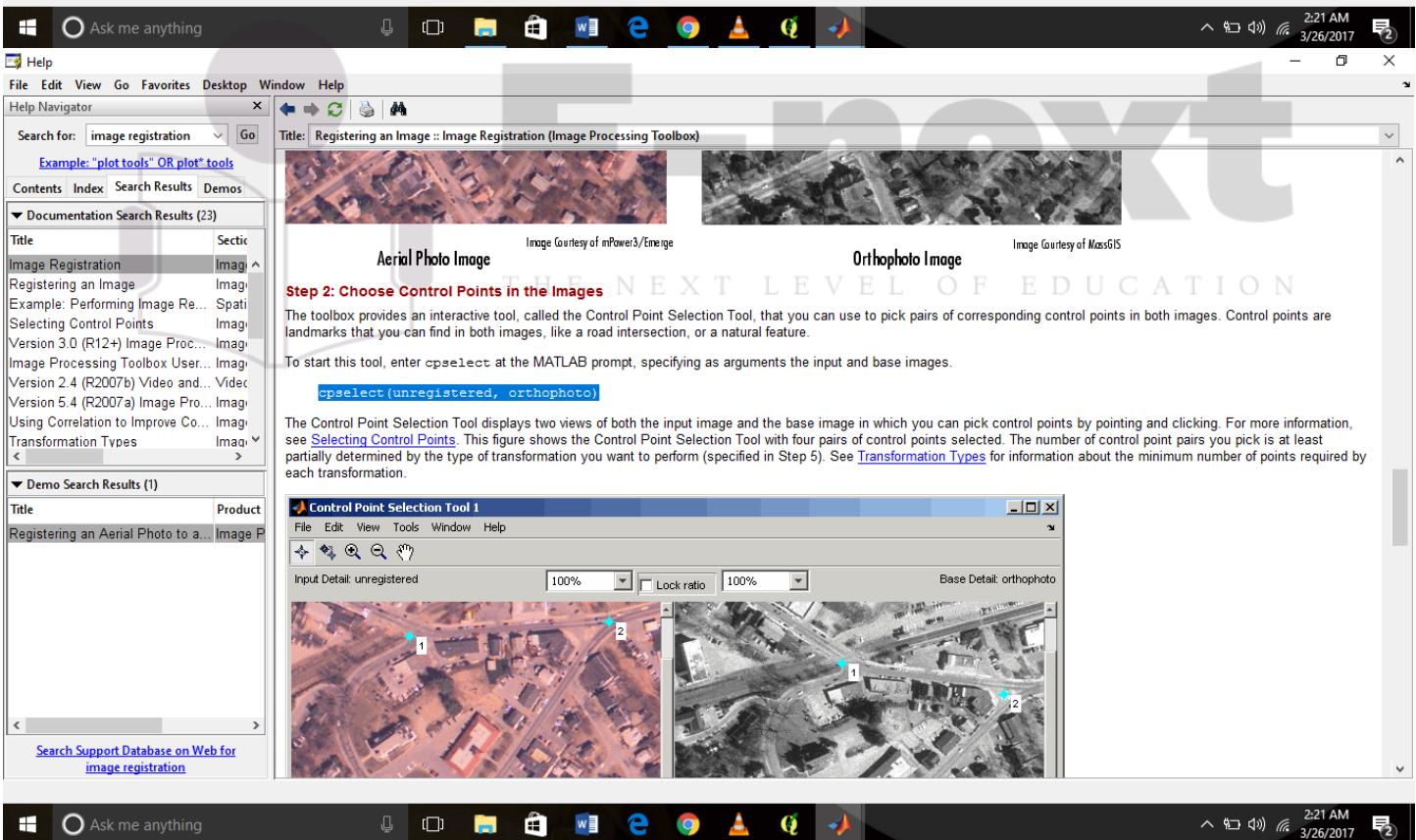
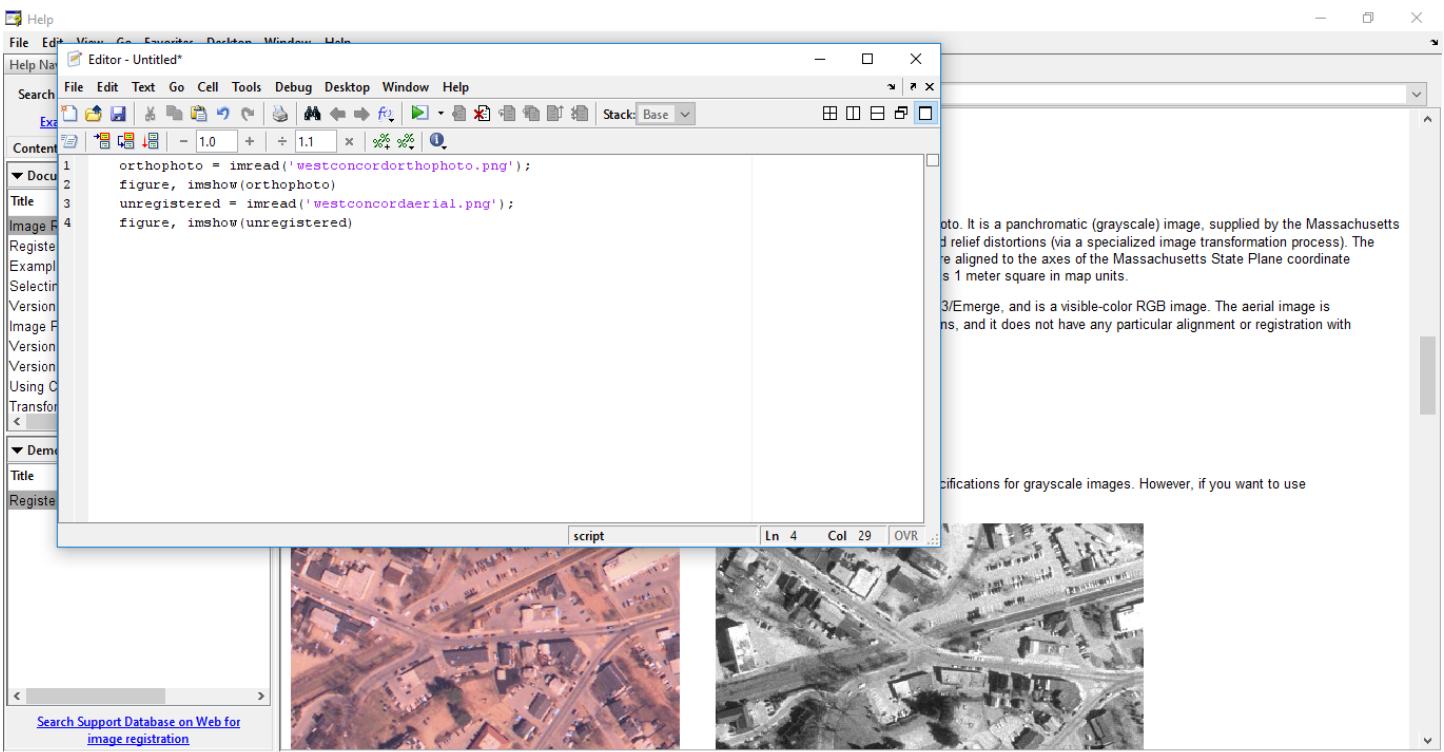
In this example, the base image is `'westconcordorthophoto.png'`, the MassGIS georegistered orthophoto. It is a panchromatic (grayscale) image, supplied by the Massachusetts Geographic Information System (MassGIS), that has been orthorectified to remove camera, perspective, and relief distortions (via a specialized image transformation process). The orthophoto is also georegistered (and geocoded) — the columns and rows of the digital orthophoto image are aligned to the axes of the Massachusetts State Plane coordinate system. In the orthophoto, each pixel center corresponds to a definite geographic location, and every pixel is 1 meter square in map units.

The image to be registered is `'westconcordaerial.png'`, a digital aerial photograph supplied by mPower3/Emerge, and is a visible-color RGB image. The aerial image is geometrically uncorrected: it includes camera perspective, terrain and building relief, internal (lens) distortions, and it does not have any particular alignment or registration with respect to the earth.

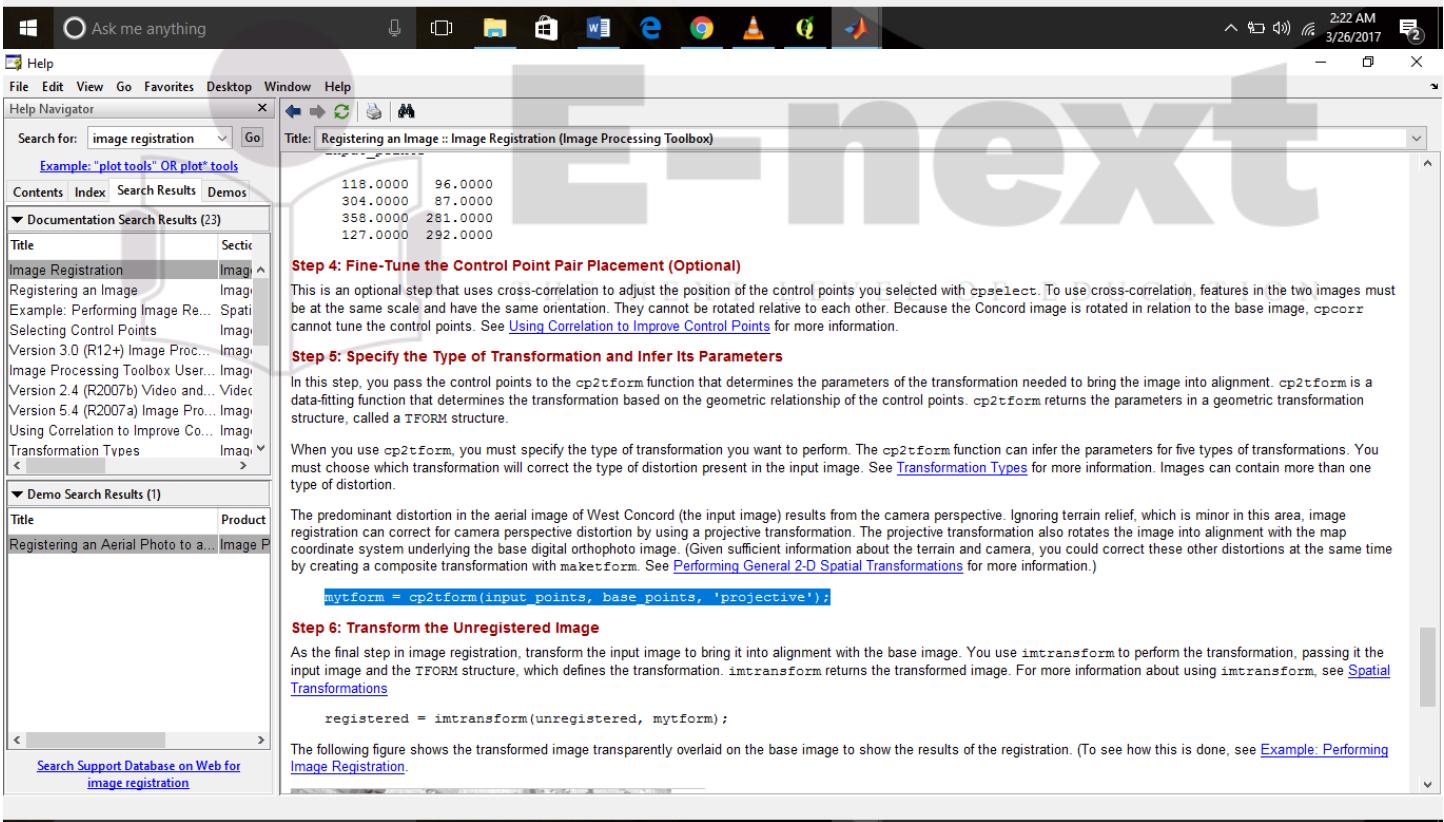
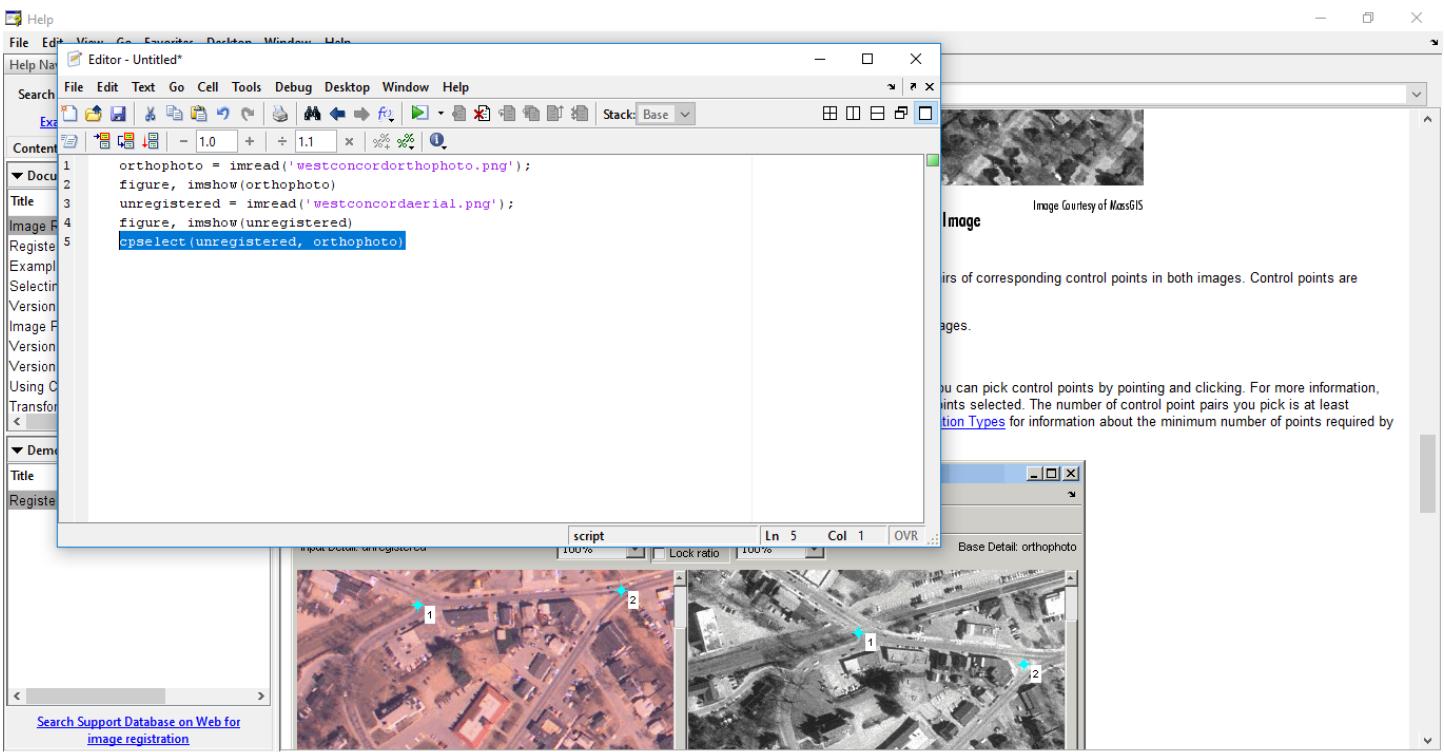
The following example reads both images into the MATLAB workspace and displays them using

```
orthophoto = imread('westconcordorthophoto.png');
figure, imshow(orthophoto)
unregistered = imread('westconcordaerial.png');
figure, imshow(unregistered);
```

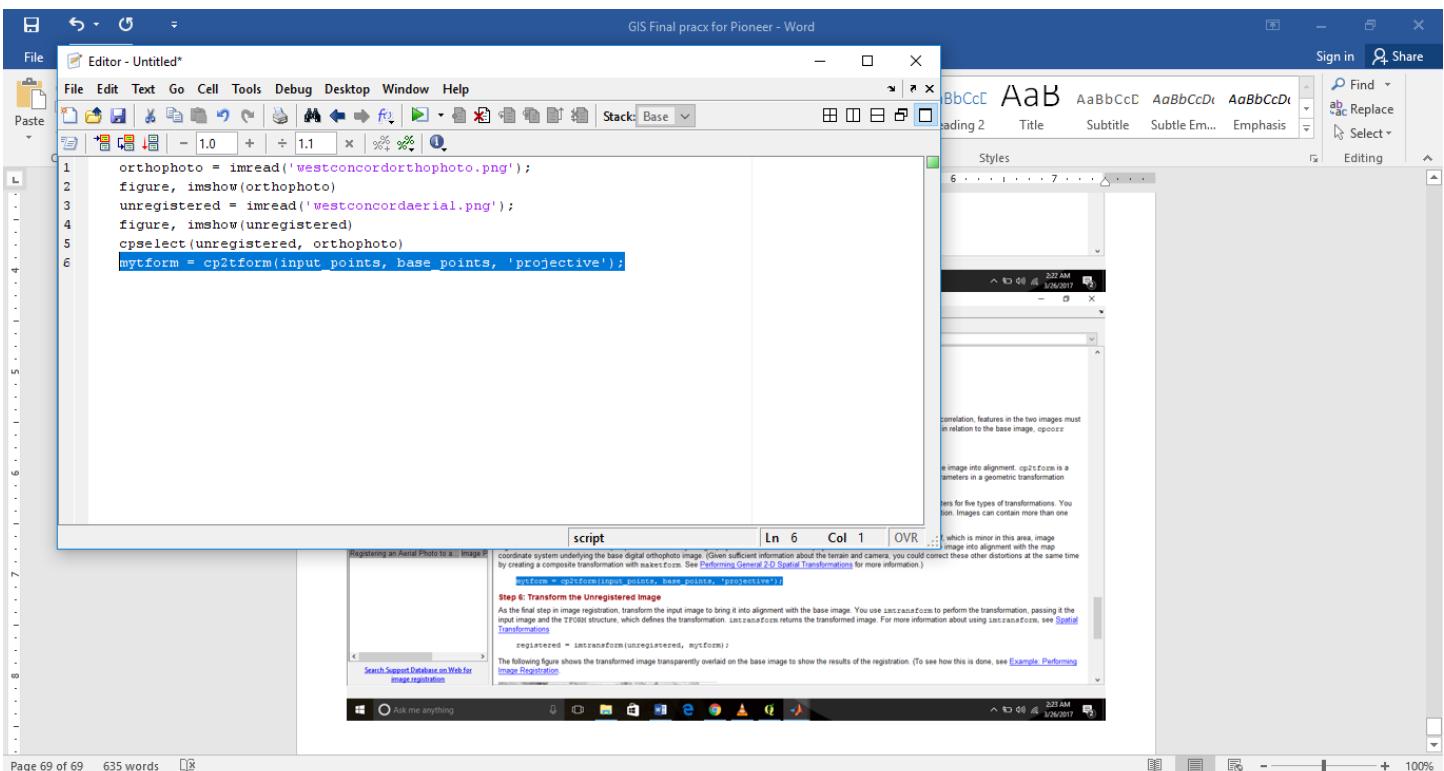
You do not have to read the images into the MATLAB workspace. The `cpselect` function accepts file specifications for grayscale images. However, if you want to use cross-correlation to tune your control point positioning, the images must be in the workspace.



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The screenshot shows the MATLAB Help browser. The title is "Registering an Image :: Image Registration (Image Processing Toolbox)". The content page discusses the optional step of cross-correlation to adjust control points and specifies the type of transformation (projective) using the `cp2tform` function. It also covers transforming the unregistered image using `imtransform`.

Step 5: Specify the Type of Transformation and Infer Its Parameters

In this step, you pass the control points to the `cp2tform` function that determines the parameters of the transformation needed to bring the image into alignment. `cp2tform` is a data-fitting function that determines the transformation based on the geometric relationship of the control points. `cp2tform` returns the parameters in a geometric transformation structure, called a TFORM structure.

When you use `cp2tform`, you must specify the type of transformation you want to perform. The `cp2tform` function can infer the parameters for five types of transformations. You must choose which transformation will correct the type of distortion present in the input image. See [Transformation Types](#) for more information. Images can contain more than one type of distortion.

The predominant distortion in the aerial image of West Concord (the input image) results from the camera perspective. Ignoring terrain relief, which is minor in this area, image registration can correct for camera perspective distortion by using a projective transformation. The projective transformation also rotates the image into alignment with the map coordinate system underlying the base digital orthophoto image. (Given sufficient information about the terrain and camera, you could correct these other distortions at the same time by creating a composite transformation with `maketform`. See [Performing General 2-D Spatial Transformations](#) for more information.)

```

mytfm = cp2tform(input_points, base_points, 'projective');

```

Step 6: Transform the Unregistered Image

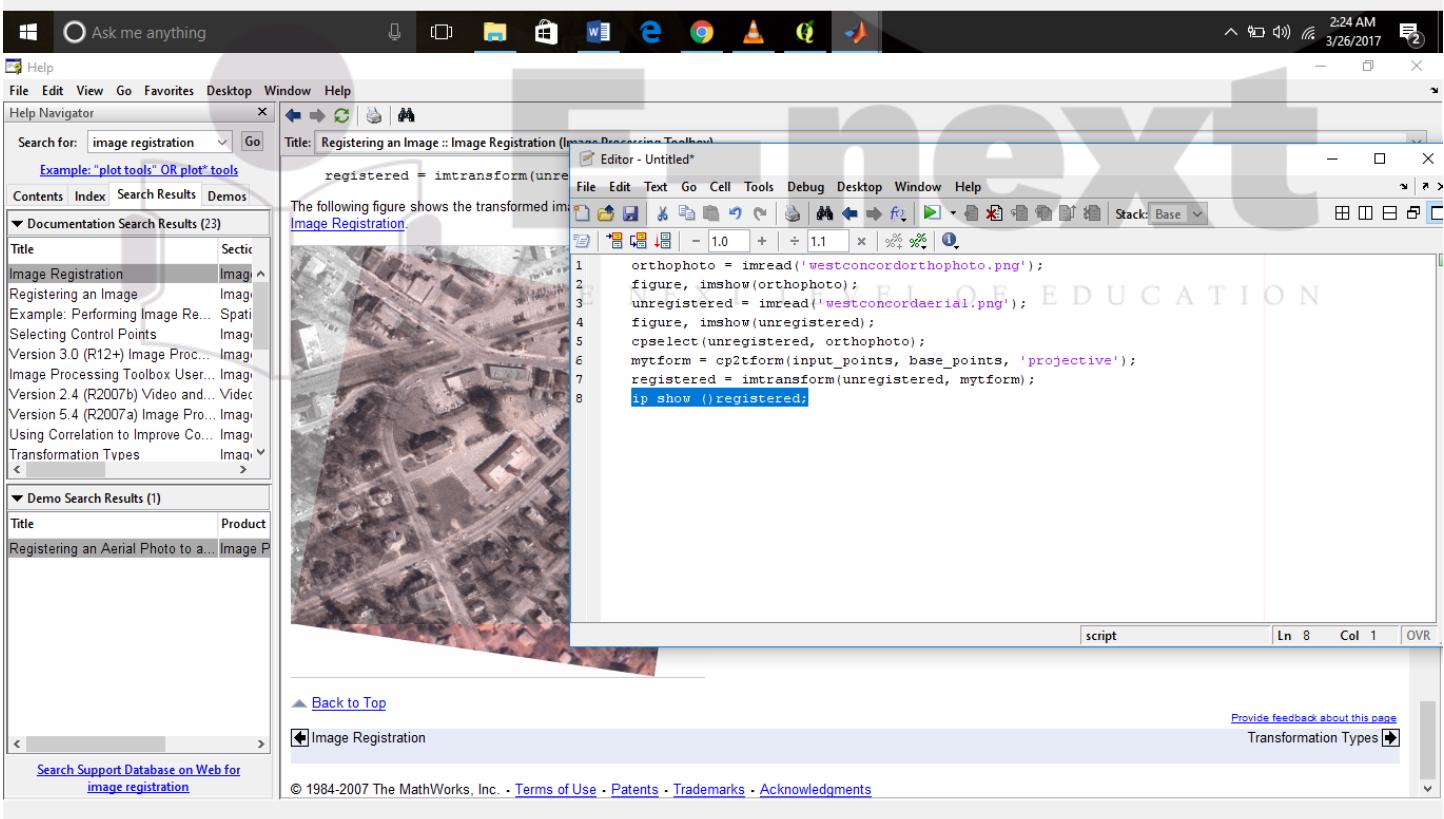
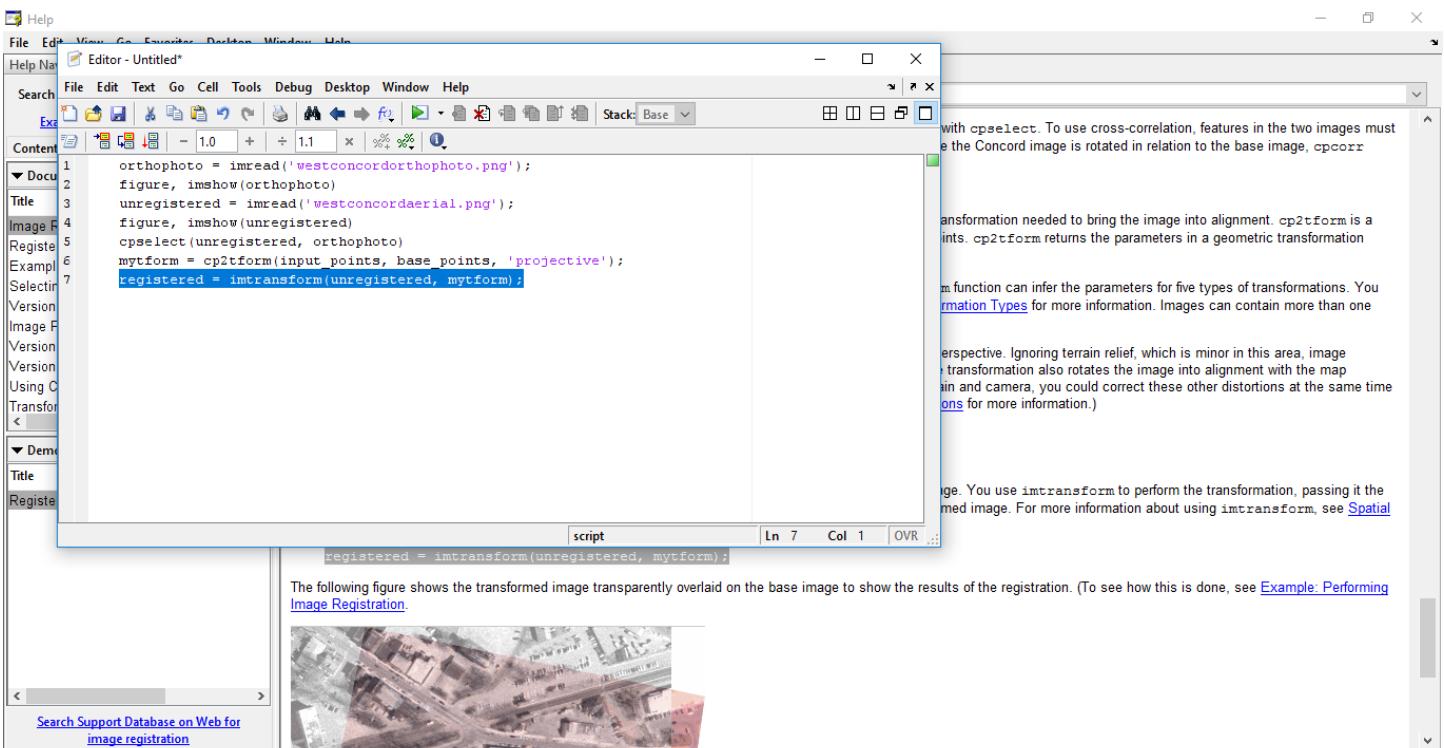
As the final step in image registration, transform the input image to bring it into alignment with the base image. You use `imtransform` to perform the transformation, passing it the input image and the TFORM structure, which defines the transformation. `imtransform` returns the transformed image. For more information about using `imtransform`, see [Spatial Transformations](#)

```

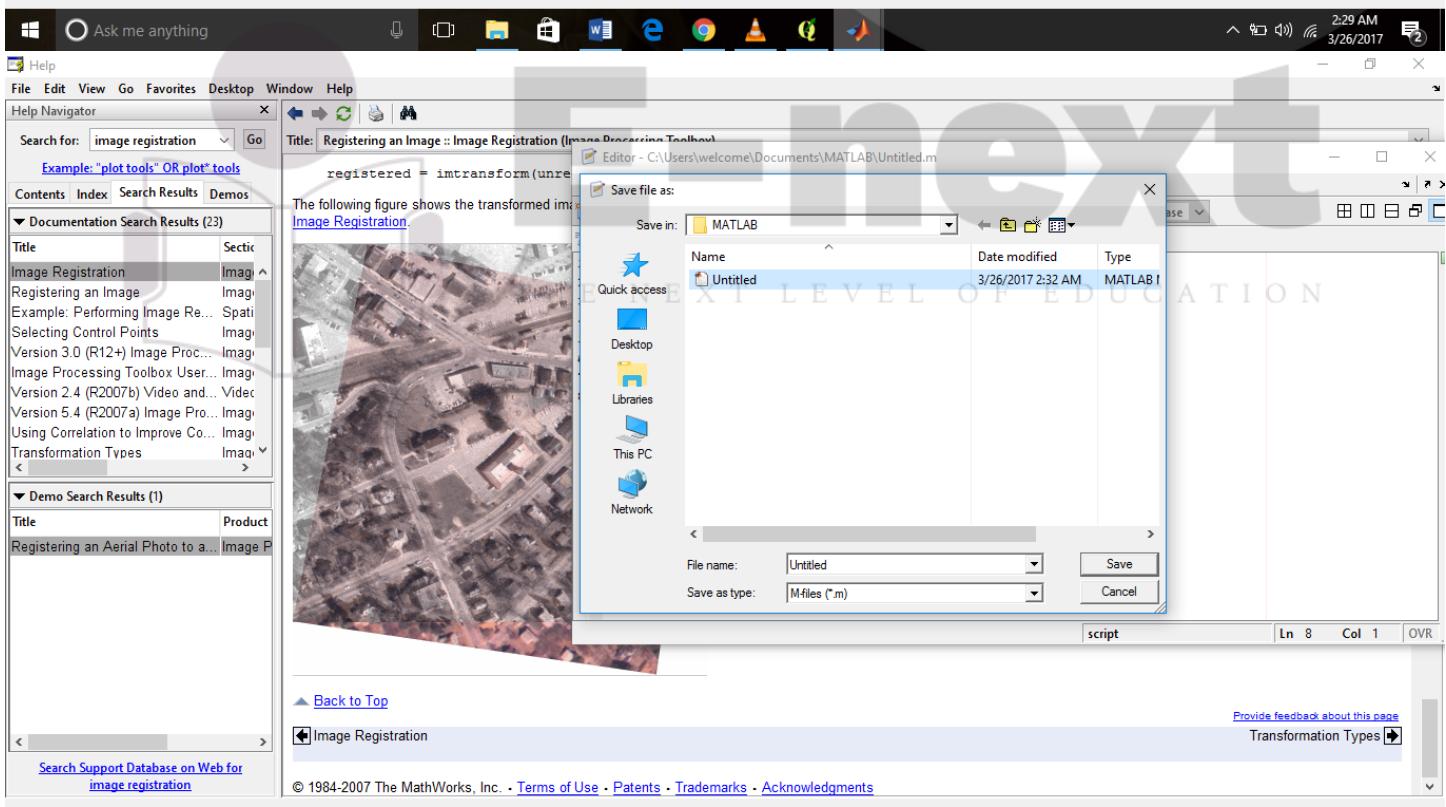
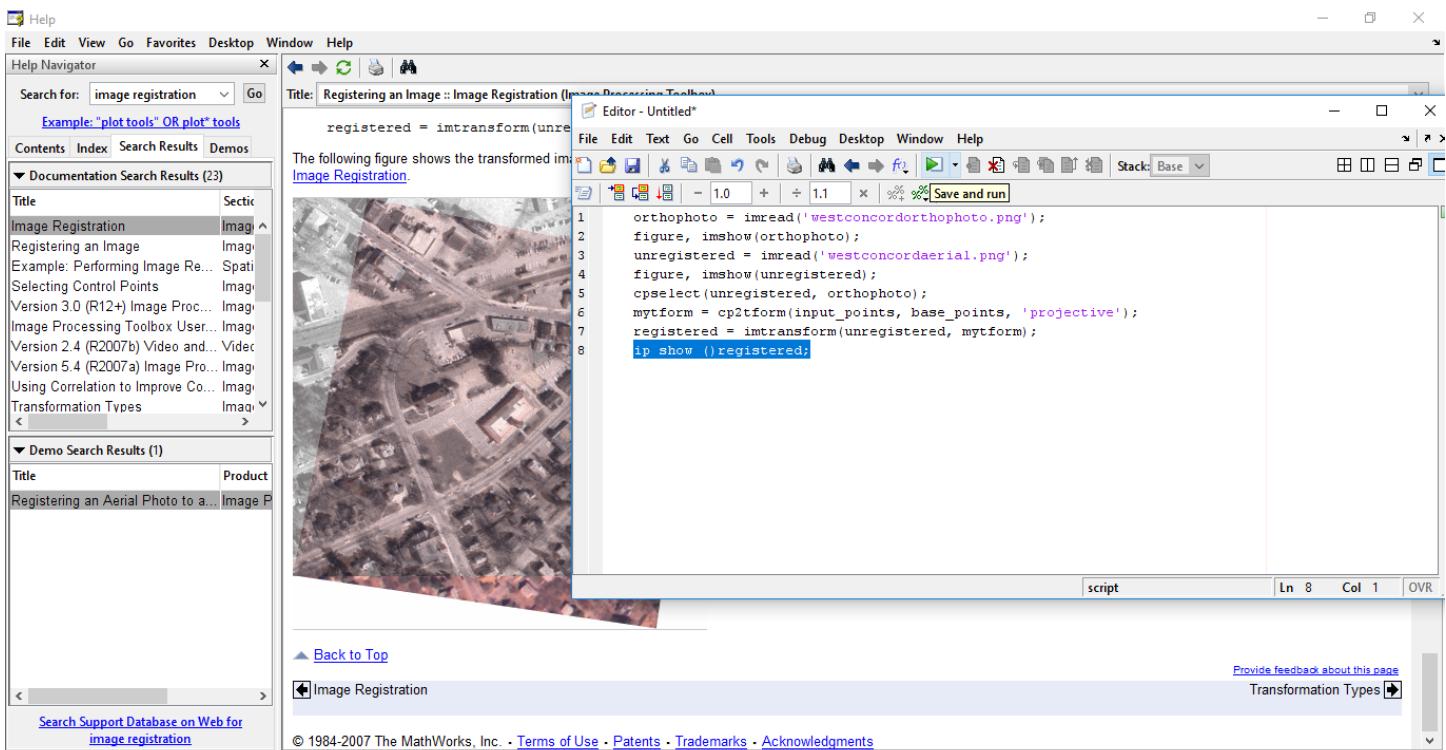
registered = imtransform(unregistered, mytfm);

```

The following figure shows the transformed image transparently overlaid on the base image to show the results of the registration. (To see how this is done, see [Example: Performing Image Registration](#).)



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Search for: image registration Go Example: "plot tools" OR plot* tools

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Demo Search Results (1)

Title Product

Registering an Aerial Photo to a... Image Processing

Search Support Database on Web for image registration

Editor - C:\Users\welcome\Documents\MATLAB\Untitled.m

Title: Registering an Image :: Image Registration (Image Processing Toolbox)

The following figure shows the transformed image.

[Image Registration](#)

```

1 - orthophoto = imread('westconcordorthophoto.png');
2 - figure, imshow(orthophoto);
3 - unregistered = imread('westconcordaerial.png');
4 - figure, imshow(unregistered);
5 - cpselect(unregistered, orthophoto);
6 - mytfm = cp2tform(input_points, base_points, 'projective');
7 - registered = imtransform(unregistered, mytfm);
8 - ip show ()registered;

```

script Ln 8 Col 1 OVR

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Provide feedback about this page Transformation Types

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File Edit View Insert Tools Desktop Window Help

Figure 1

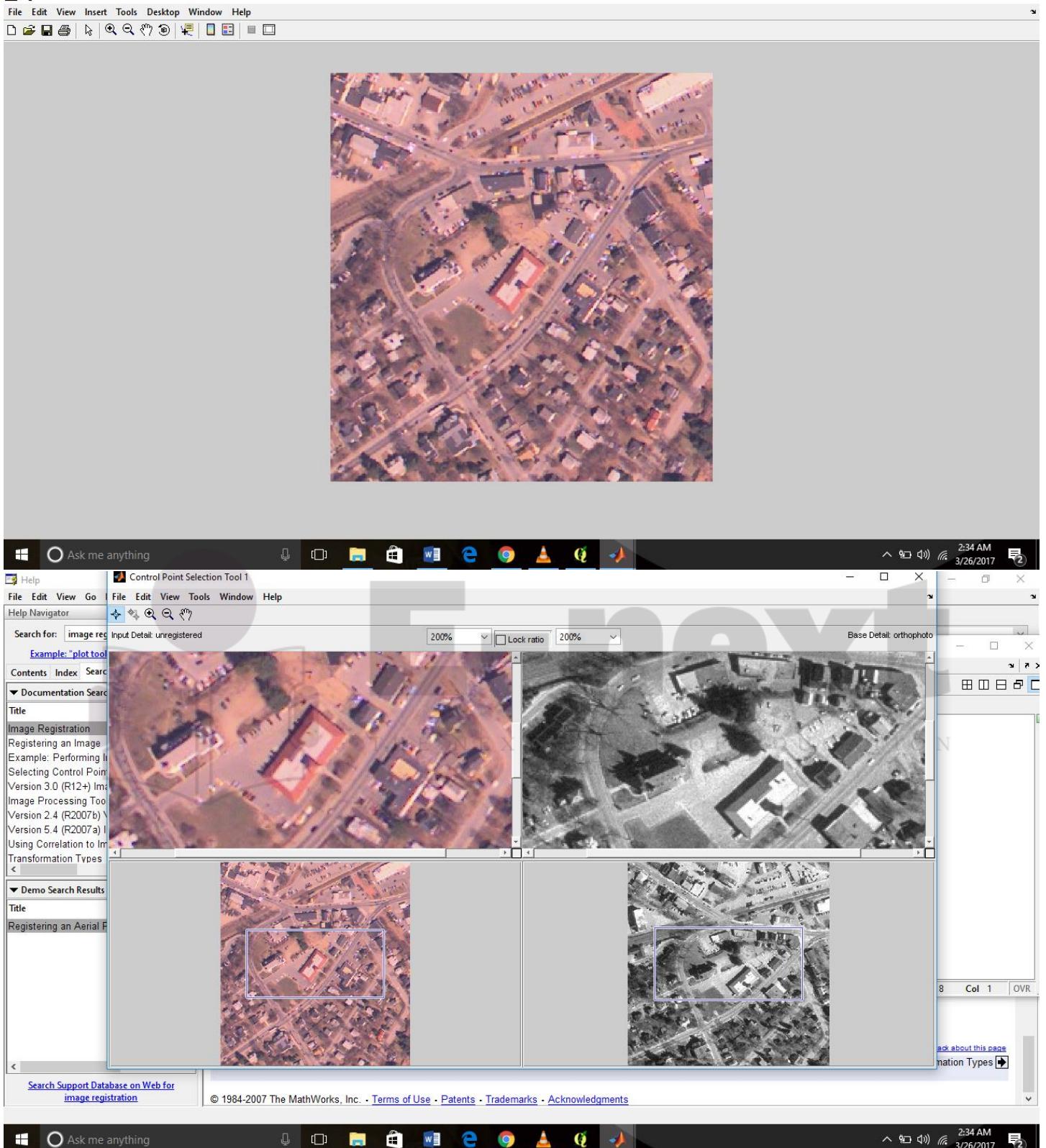
EDUCATION

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2:33 AM 3/26/2017

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Figure 2



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Nearest Neighbor Analysis

GIS is very useful in analyzing spatial relationship between features. One such analysis is finding out which features are closest to a given feature. QGIS has a tool called **Distance Matrix** which helps with such analysis. In this tutorial, we will use 2 datasets and find out which points from one layer are closest to which point from the second layer.

Overview of the task

Given the locations of all known significant earthquakes, find out the nearest populated place for each location where the earthquake happened.

Other skills you will learn

- How to do table joins in QGIS. (See [Performing Table Joins](#) for detailed instructions.)
- Using Query Builder to show a subset of features from a layer.
- Using MMQGIS plugin to create hub lines to visualize the nearest neighbors.

Get the data

We will use NOAA's National Geophysical Data Center's [Significant Earthquake Database](#) as our layer representing all major earthquakes. Download the [tab-delimited earthquake data](#).

Natural Earth has a nice [Populated Places](#) dataset. Download the [simple \(less columns\) dataset](#)

For convenience, you may directly download a copy of both the datasets from the links below:

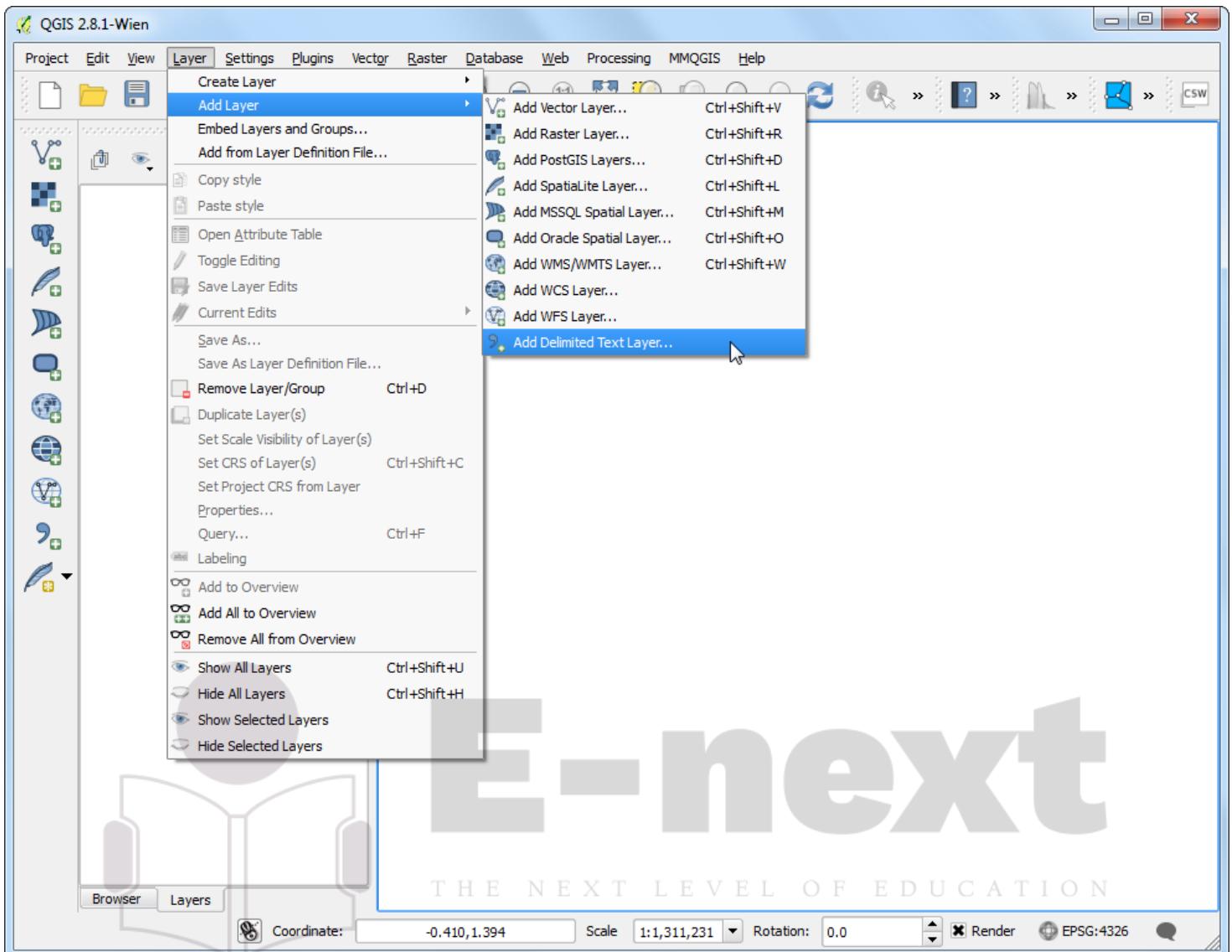
[signif.txt](#)

[ne_10m_populated_places_simple.zip](#)

Data Sources: [\[NGDC\]](#) [\[NATURALEARTH\]](#)

Procedure

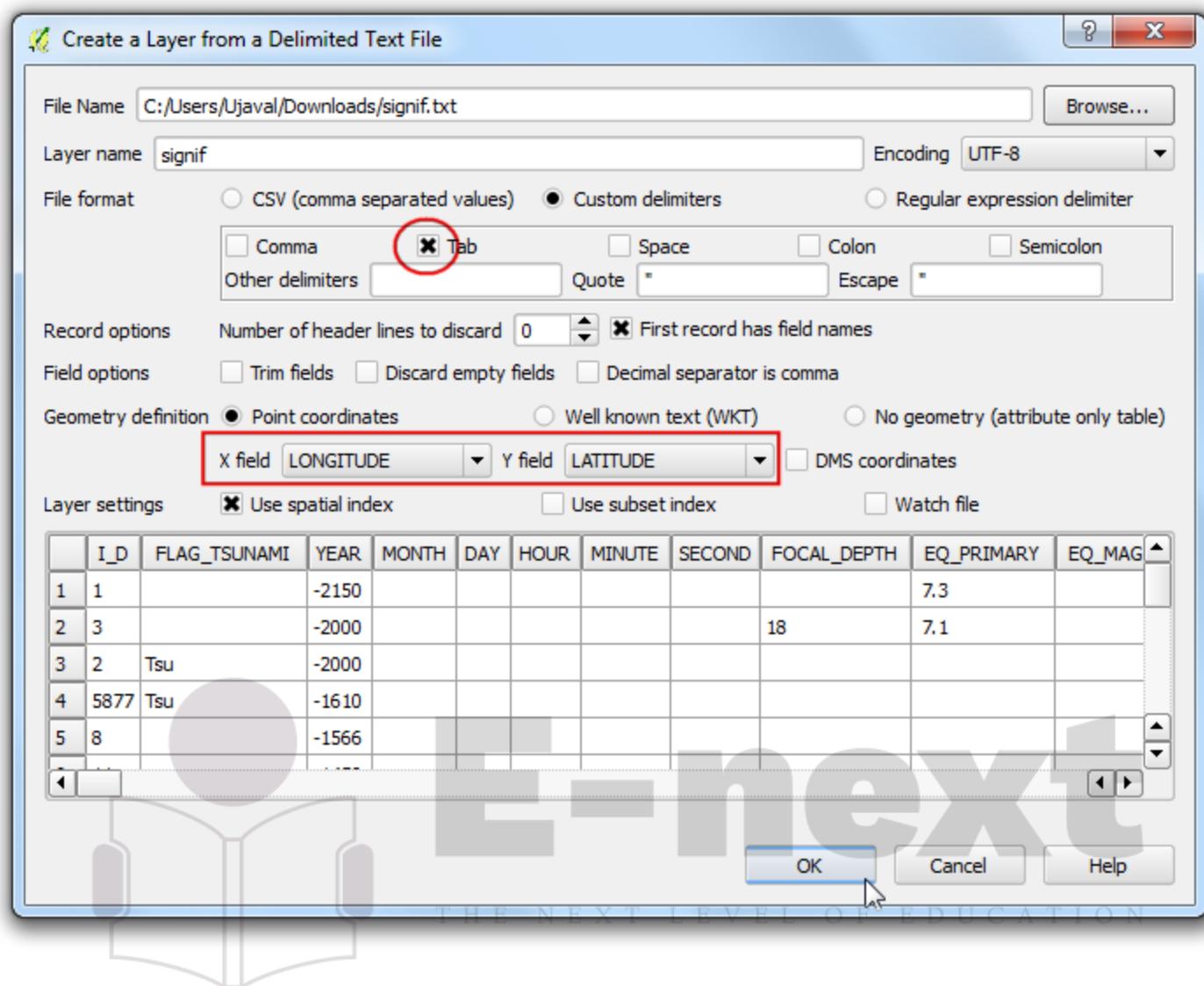
1. Open Layer ▶ Add Layer ▶ Add Delimited Text Layer and browse to the downloaded [signif.txt](#) file.



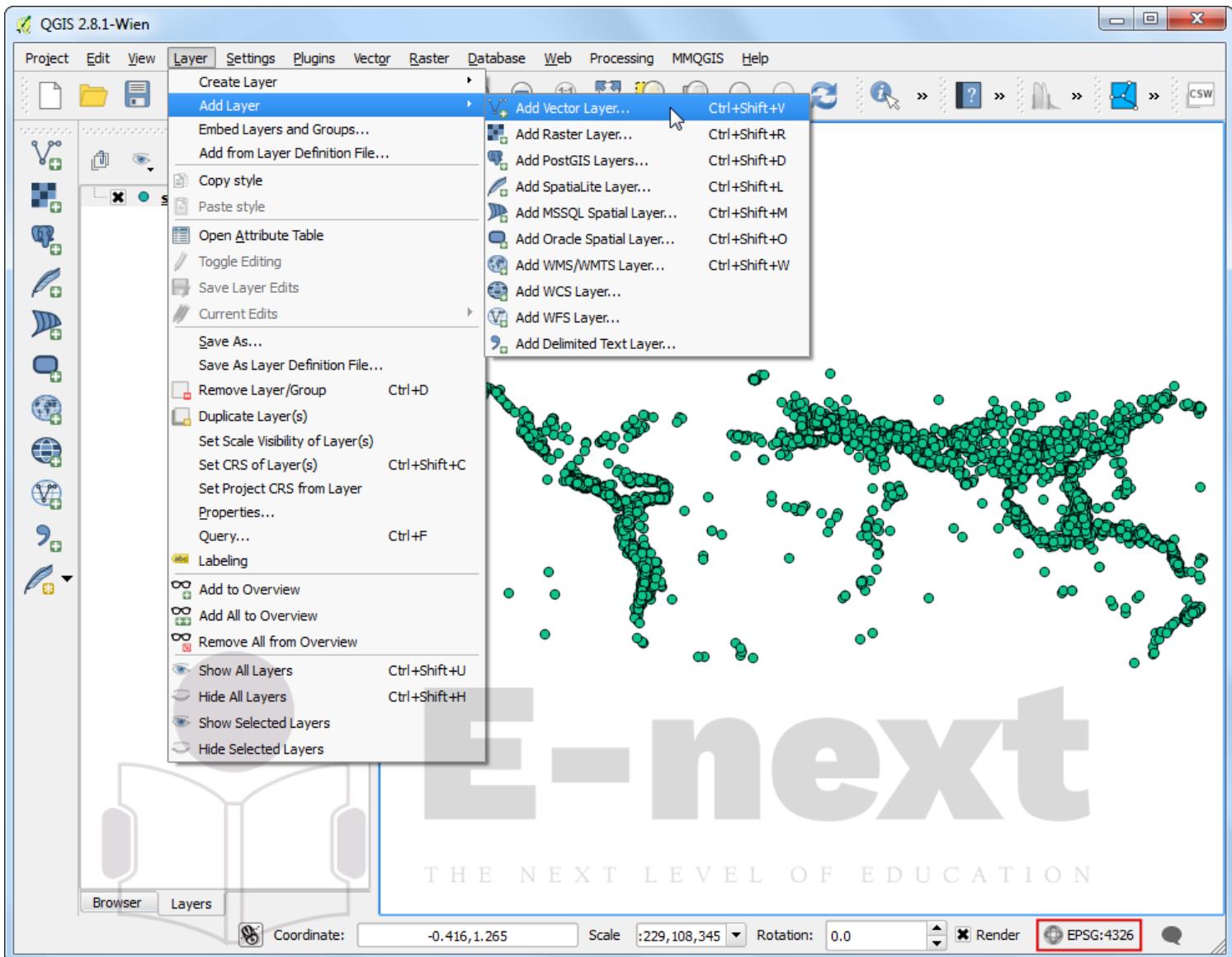
- Since this is a *tab-delimited file*, choose Tab as the File format. The X field and Y field would be auto-populated. Click OK.

Note

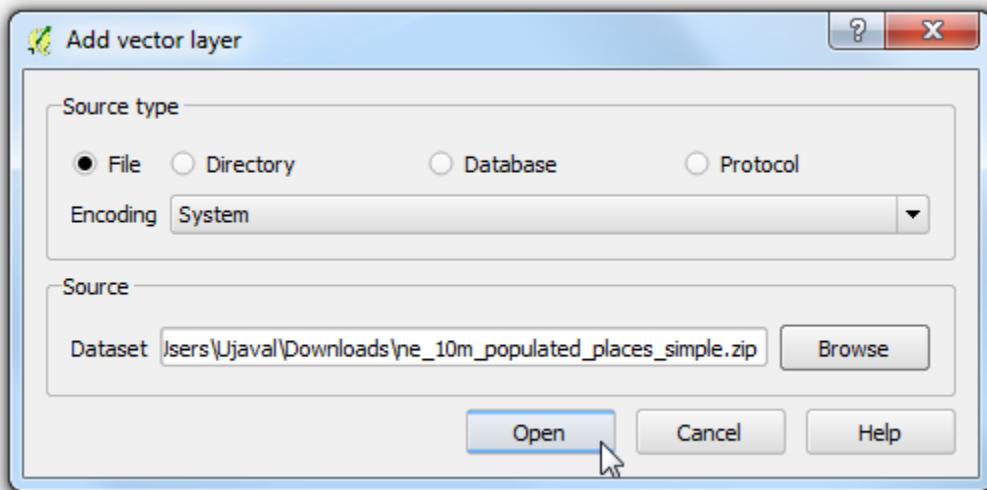
You may see some error messages as QGIS tries to import the file. These are valid errors and some rows from the file will not be imported. You can ignore the errors for the purpose of this tutorial.



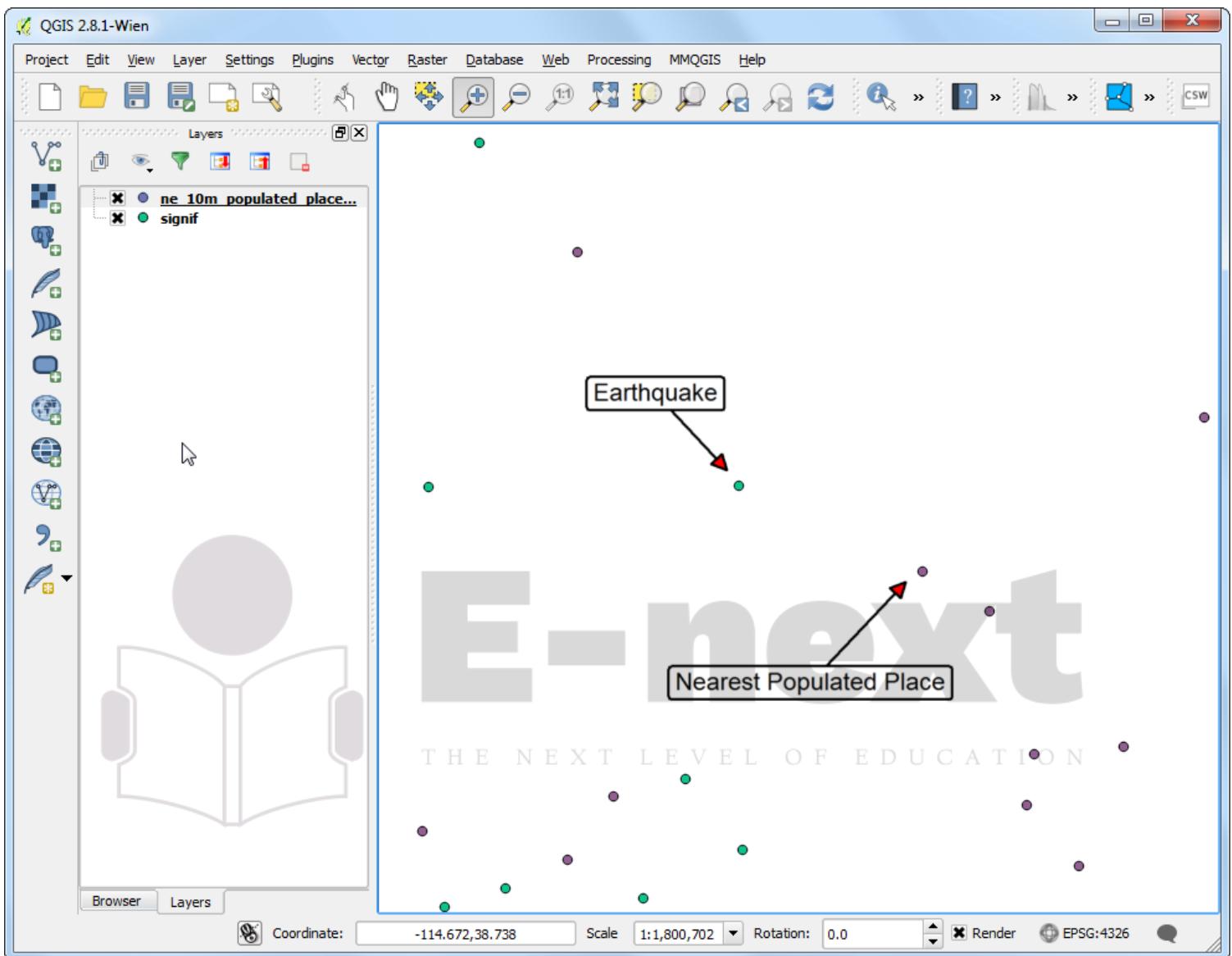
- As the earthquake dataset has Latitude/Longitude coordinates, it will be imported with the default CRS of **EPSG: 4326**. Verify that is the case in the bottom-right corner. Let's also open the Populated Places layer. Go to Layer > Add Layer > Add Vector Layer.



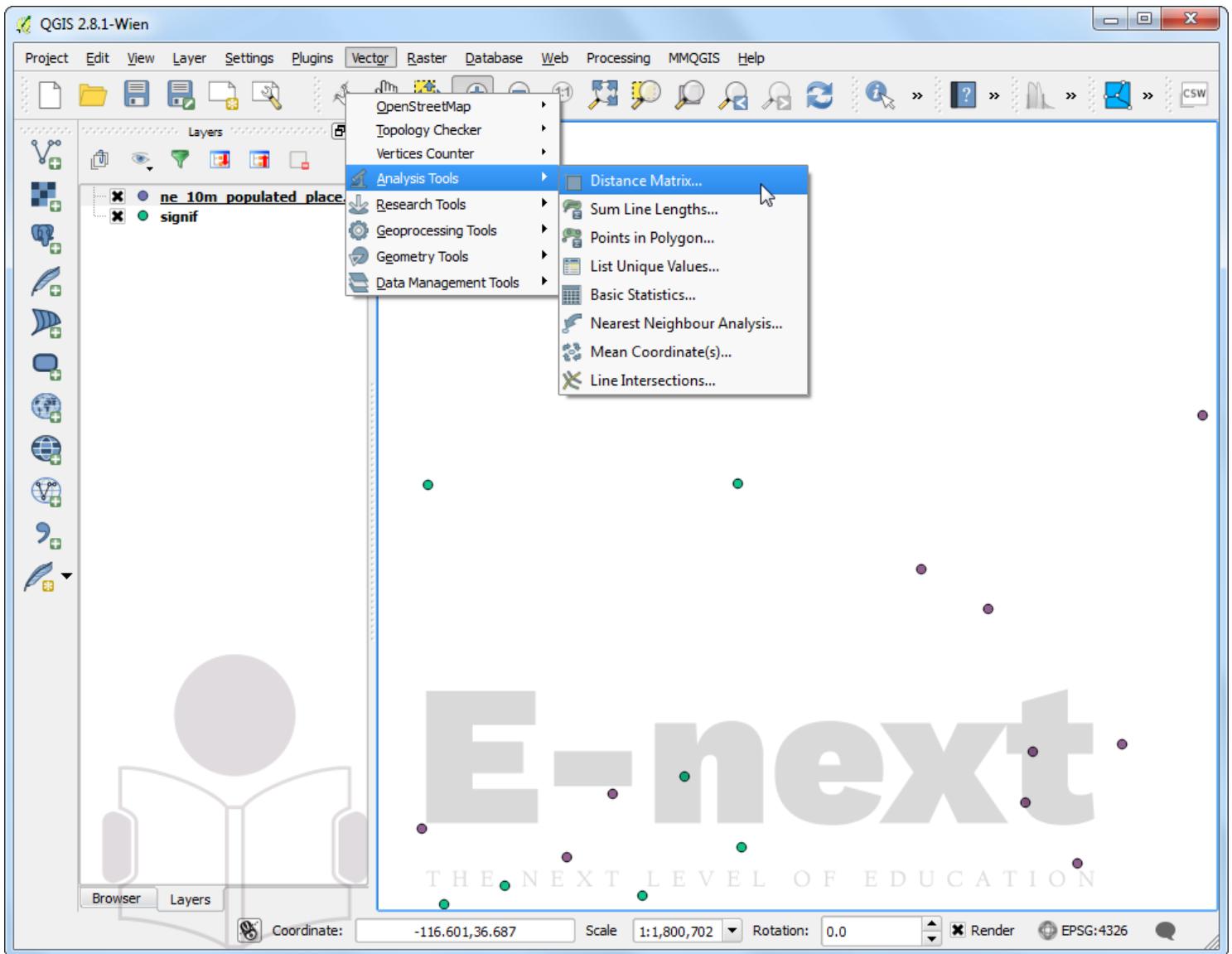
4. Browse to the downloaded `ne_10m_populated_places_simple.zip` file and click Open.



5. Zoom around and explore both the datasets. Each purple point represents the location of a significant earthquake and each blue point represents the location of a populated place. We need a way to find out the nearest point from the populated places layer for each of the points in the earthquake layer.



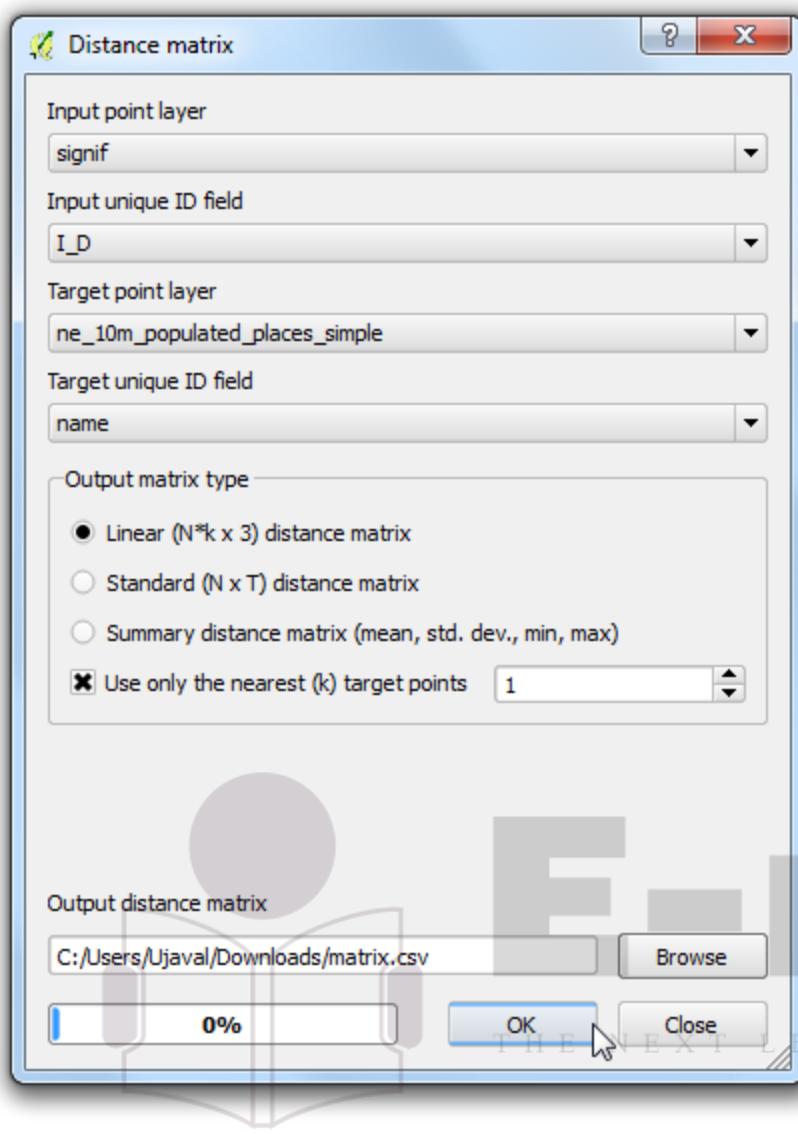
6. Go to Vector > Analysis Tools > Distance Matrix.



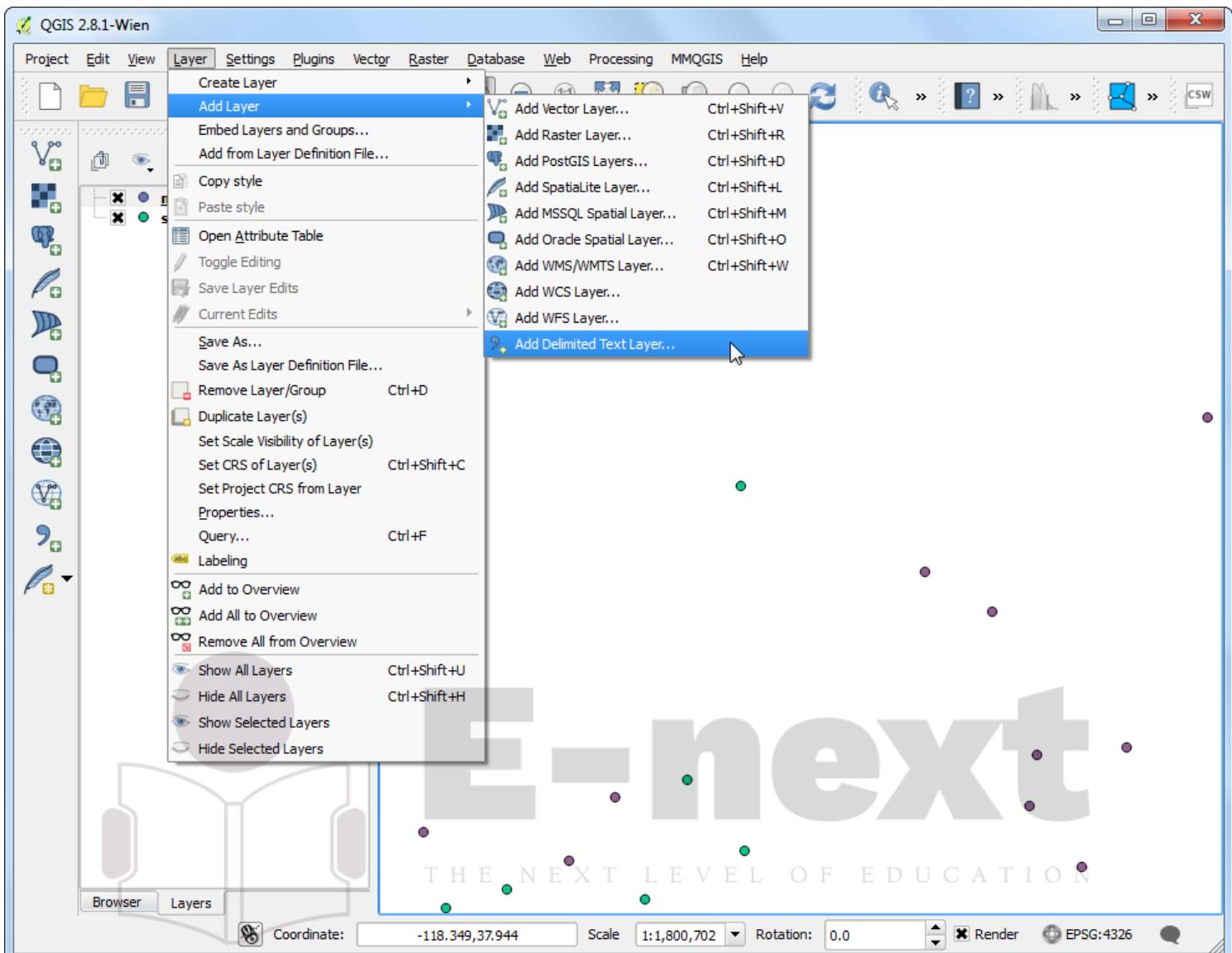
7. Here select the earthquake layer `signif` as the Input point layer and the populated places `ne_10m_populated_places_simple` as the target layer. You also need to select a unique field from each of these layers which is how your results will be displayed. In this analysis, we are looking to get only 1 nearest point, so check the Use only the nearest(k) target points, and enter 1. Name your output file `matrix.csv`, and click OK. Once the processing finishes, click Close.

Note

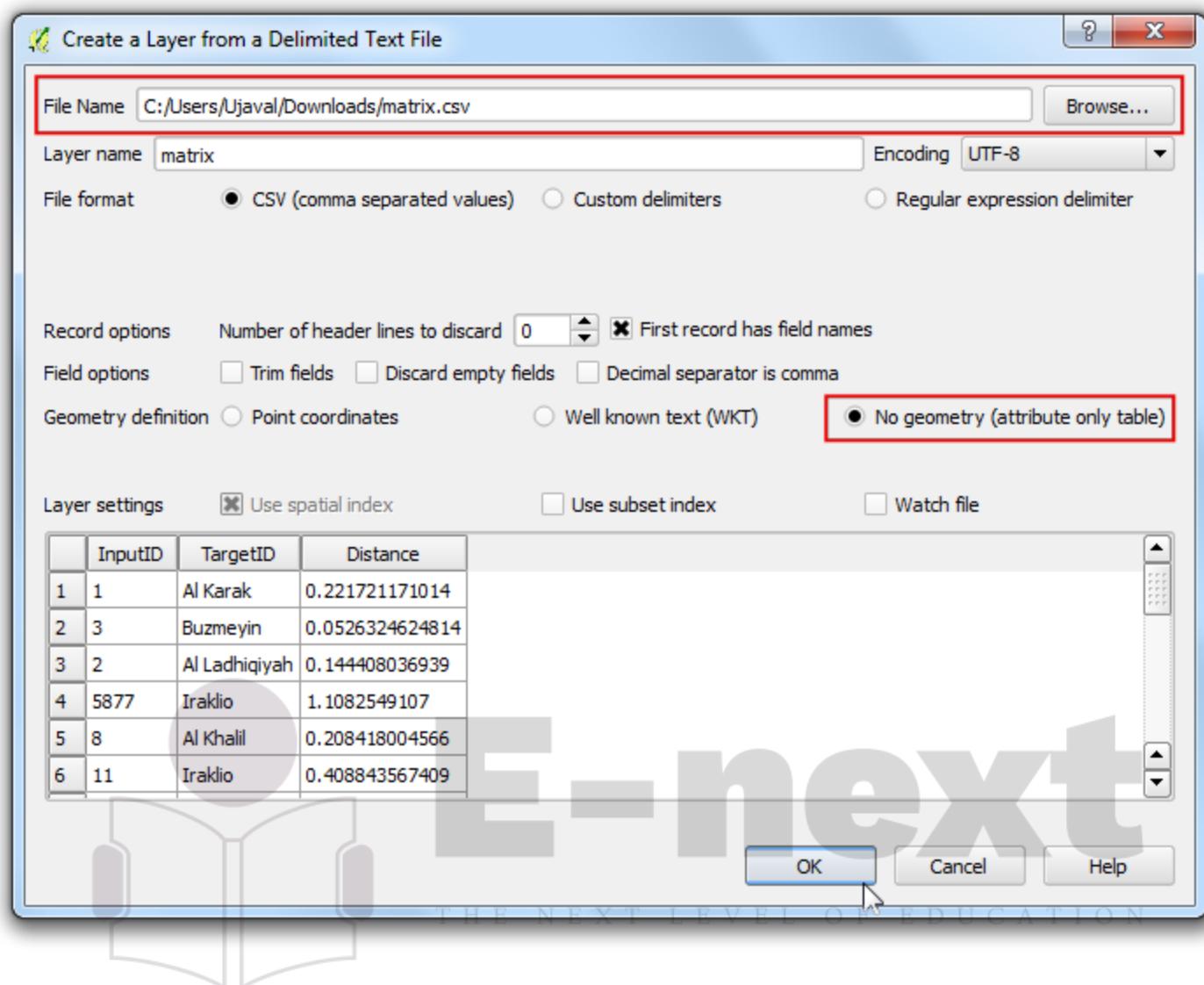
A useful thing to note is that you can even perform the analysis with only 1 layer. Select the same layer as both Input and Target. The result would be a nearest neighbor from the same layer instead of a different layer as we have used here.



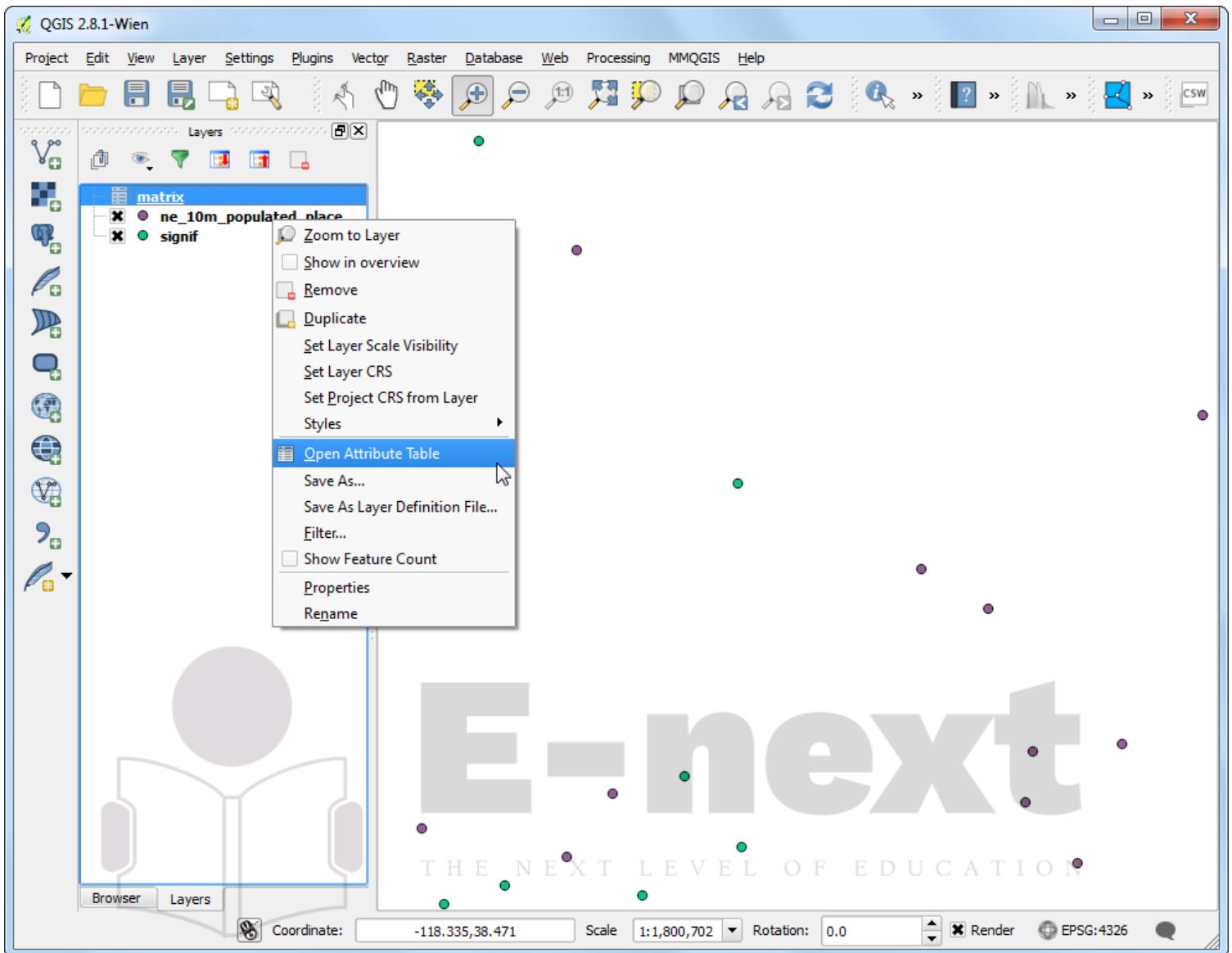
- Once the processing finishes, click the Close button in the Distance Matrix dialog. You can now view the **matrix.csv** file in Notepad or any text editor. QGIS can import CSV files as well, so we will add it to QGIS and view it there. Go to Layer > Add Layer > Add Delimited Text Layer....



9. Browse to the newly created **matrix.csv** file. Since this file is just text columns, select No geometry (attribute only table) as theGeometry definition. Click OK.



10. You will see the CSV file loaded as a table. Right-click on the table layer and select Open Attribute Table.



11. Now you will be able to see the content of our results. The InputID field contains the field name from the Earthquake layer. The TargetID field contains the name of the feature from the Populated Places layer that was the closest to the earthquake point. The Distance field is the distance between the 2 points.

Note

Remember that the *distance* calculation will be done using the layers' Coordinate Reference System. Here the distance will be in *decimal degrees* units because our source layer coordinates are in degrees. If you want distance in meters, reproject the layers before running the tool.

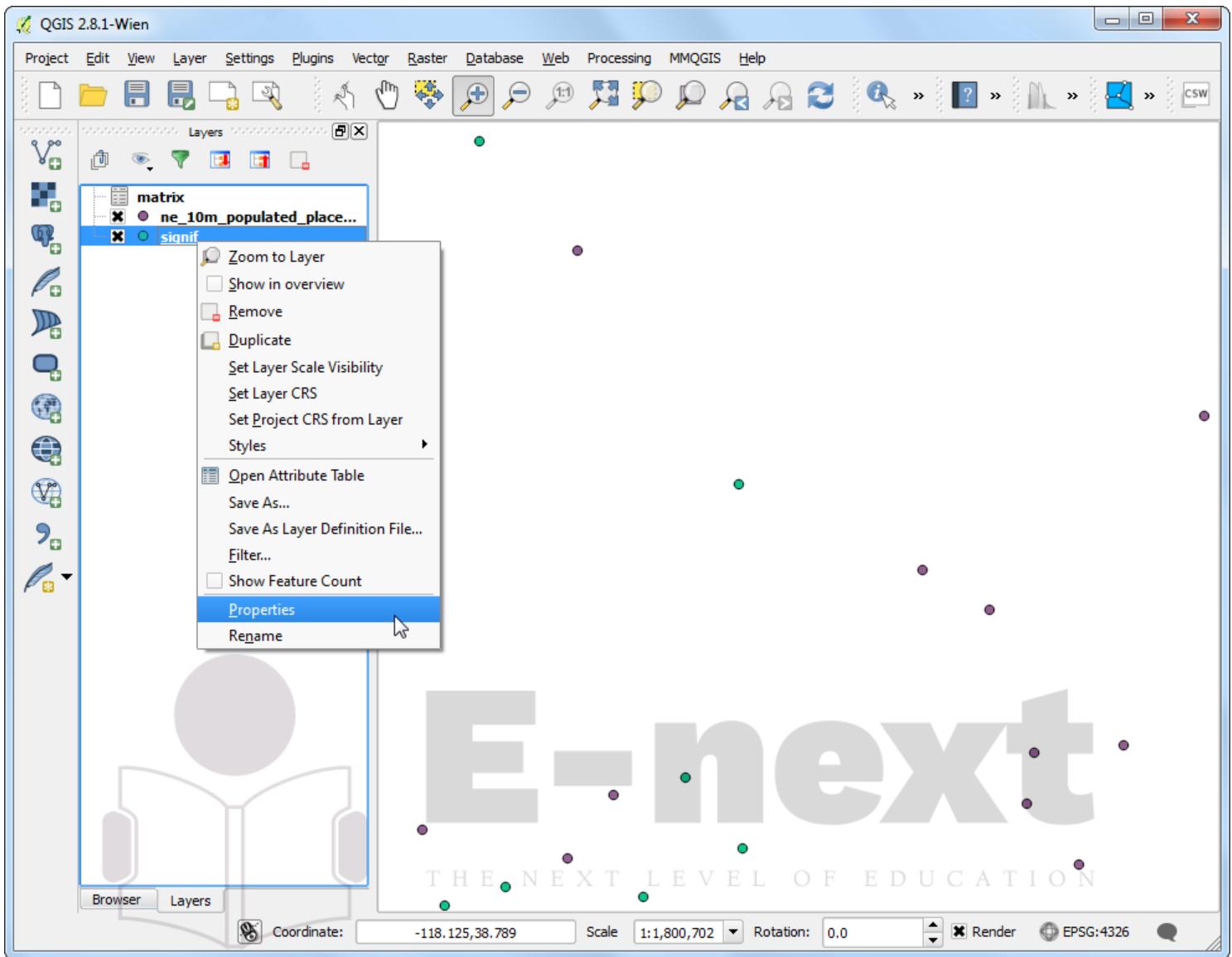
Attribute table - matrix :: Features total: 5789, filtered: 5789, selected: 0

	InputID	TargetID	Distance
0		1 Al Karak	0.221721171014
1		3 Buzmeyin	0.0526324624814
2		2 Al Ladhiqiyah	0.144408036939
3	5877	Iraklio	1.1082549107
4		8 Al Khalil	0.208418004566
5		11 Iraklio	0.408843567409
6		9712 Al Ladhiqiyah	0.144408036939
7		12 As Salt	0.230569794451
8		13 Al Aqabah	0.10661139997
9		14 Al Qunaytirah	0.34713470868
10	7793	Nabatiye et Tahta	0.256395311798
11		16 Sparti	0.101878534504
12	7794	Saida	0.003261678933...
13	9713	Piraiévs	0.206150410754
14		17 Volos	0.4810609473
15		18 Sparti	0.101878534504
16	5878	Lamia	0.265998307404
17		19 Varamin	0.239101501046
18		20 Patra	0.520403483984
19		21 Traklio	0.350232618278

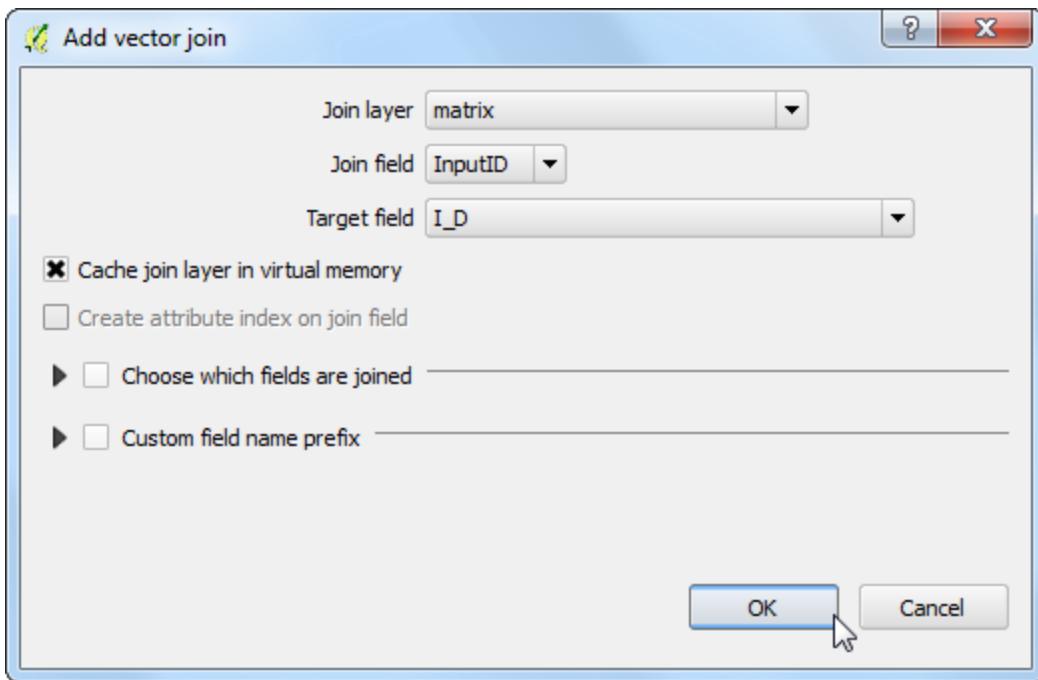
Show All Features

THE NEXT LEVEL OF EDUCATION

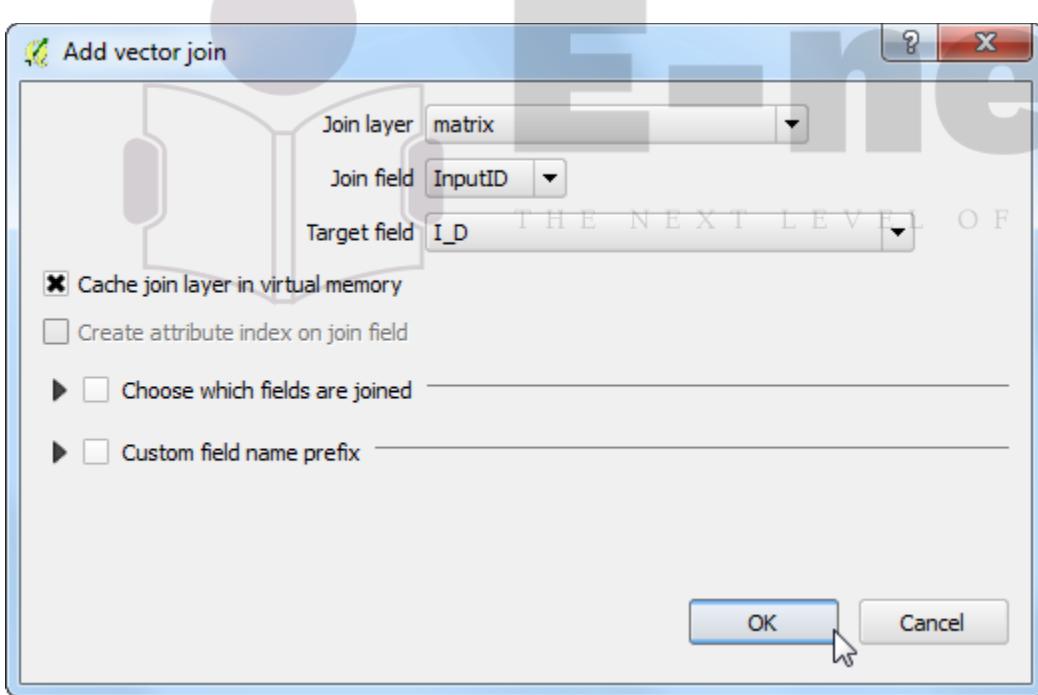
12. This is very close to the result we were looking for. For some users, this table would be sufficient. However, we can also integrate this results in our original Earthquake layer using a **Table Join**. Right-click on the Earthquake layer, and select Properties.



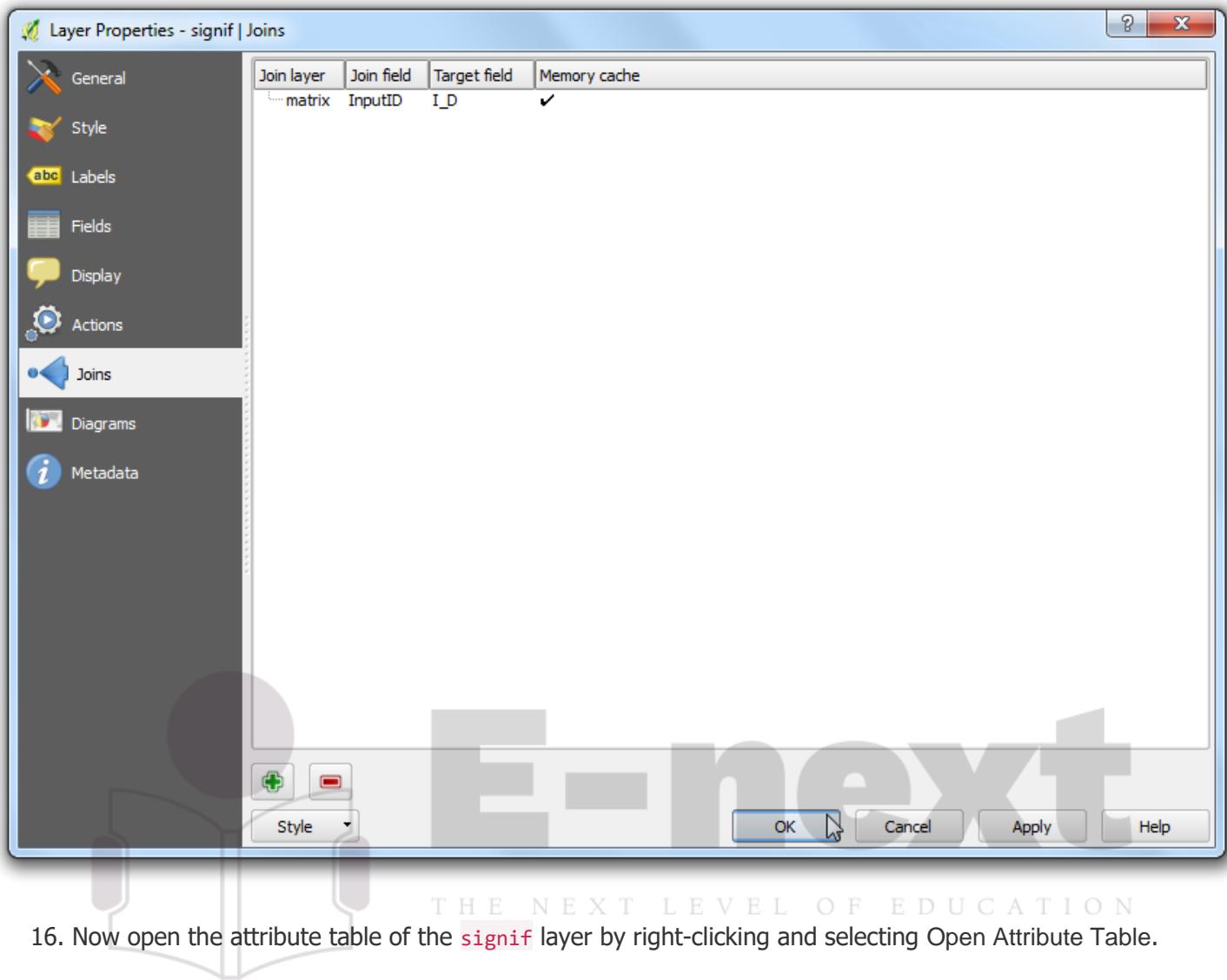
13. Go to the Joins tab and click on the + button.



14. We want to join the data from our analysis result to this layer. We need to select a field from each of the layers that has the same values. Select **matrix** as the Join layer` and **InputID** as the Join field. The Target field would be **I_D**. Leave other options to their default values and click OK.

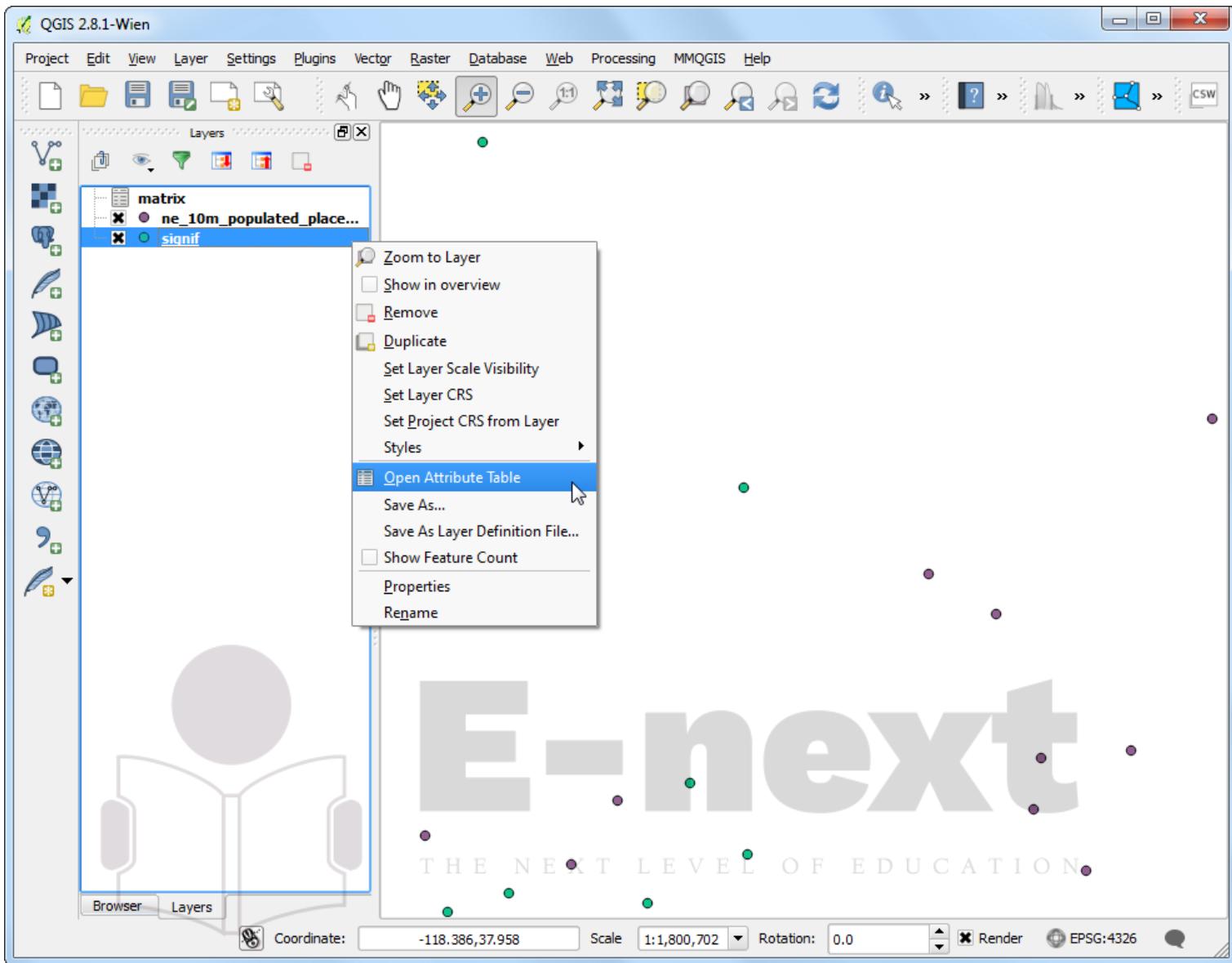


15. You will see the join appear in the Joins tab. Click OK.



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16. Now open the attribute table of the **signif** layer by right-clicking and selecting Open Attribute Table.



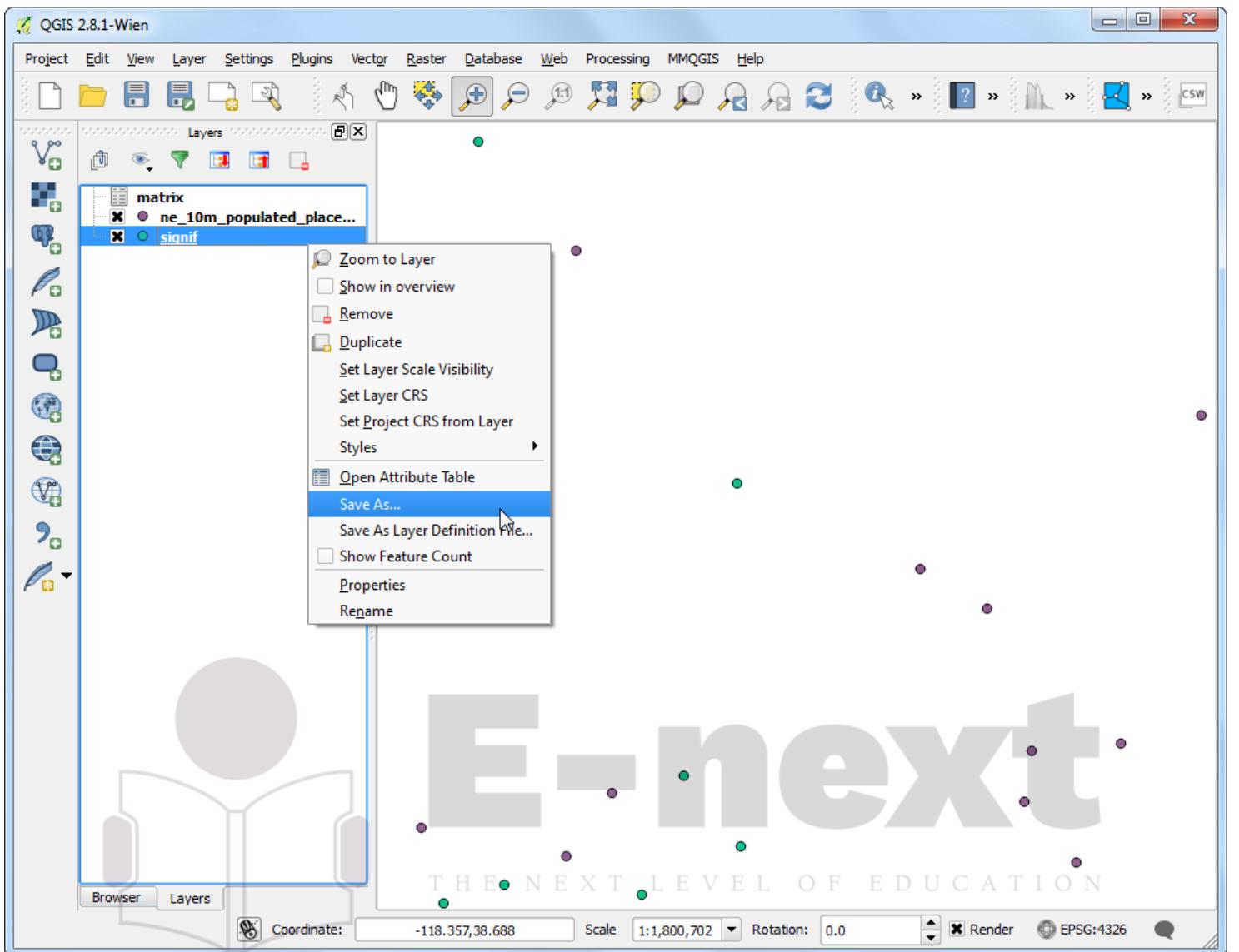
17. You will see that for every Earthquake feature, we now have an attribute which is the nearest neighbor (closest populated place) and the distance to the nearest neighbor.

Attribute table - signif :: Features total: 5789, filtered: 5789, selected: 0

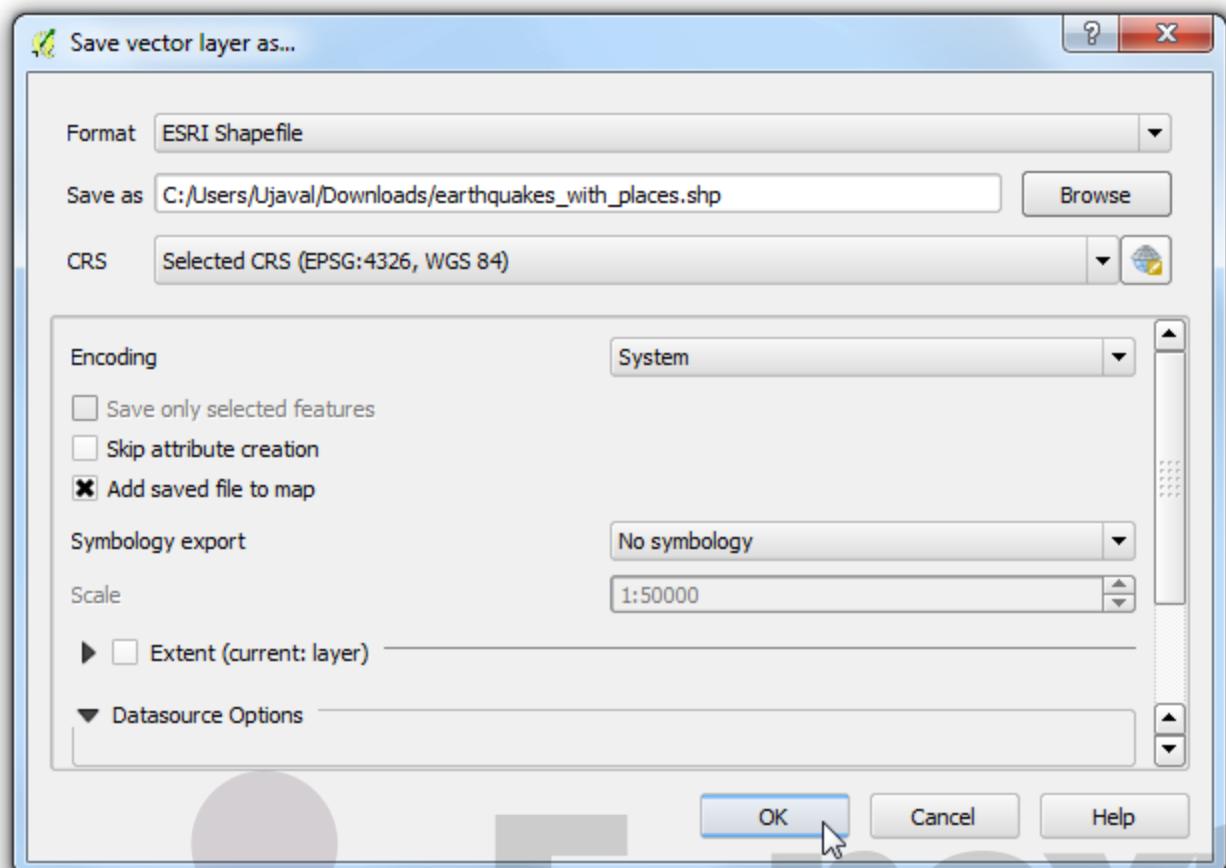
	_HOMES_DESTROYED	ES_DESTROYED_D	AL_HOMES_DAMAGE	ES_DAMAGED_I	matrix_TargetID	matrix_Distance
5139	NULL	NULL	3100	4	Dulan	2.01739872078
3345	NULL	NULL	2800	4	Yogyakarta	1.76045290364
5721	600	3	55000	4	Lijiang	1.68697672541
5464	331	3	5613	4	Aksu	1.63416691989
3225	326	3	2200	4	Yogyakarta	1.62947269236
5668	NULL	NULL	30000	4	Shihezi	1.58756245594
3924	500	3	1951	4	Hios	1.5457604489
5590	127511	4	273796	4	Sendai	1.35225172867
4877	3600	4	18771	4	Shache	1.23735810418
3897	2000	4	5000	4	Jember	1.18334084967
4647	NULL	3	2000	4	Feyzabad	1.14744856695
4841	100	2	5000	4	Birjand	1.08829070683
5575	NULL	3	1800	4	Bam	1.07386335966
1798	20000	4	15000	4	Tokushima	1.06587936484
4919	NULL	NULL	2800	4	Serang	0.945435509316
5042	650	3	1350	4	Bandar-e Bushehr	0.929327026627
3369	29205	4	46950	4	Tsu	0.924368786383
5454	30	1	5400	4	Namtu	0.902227067915
5455	30	1	5400	4	Namtu	0.902227067915

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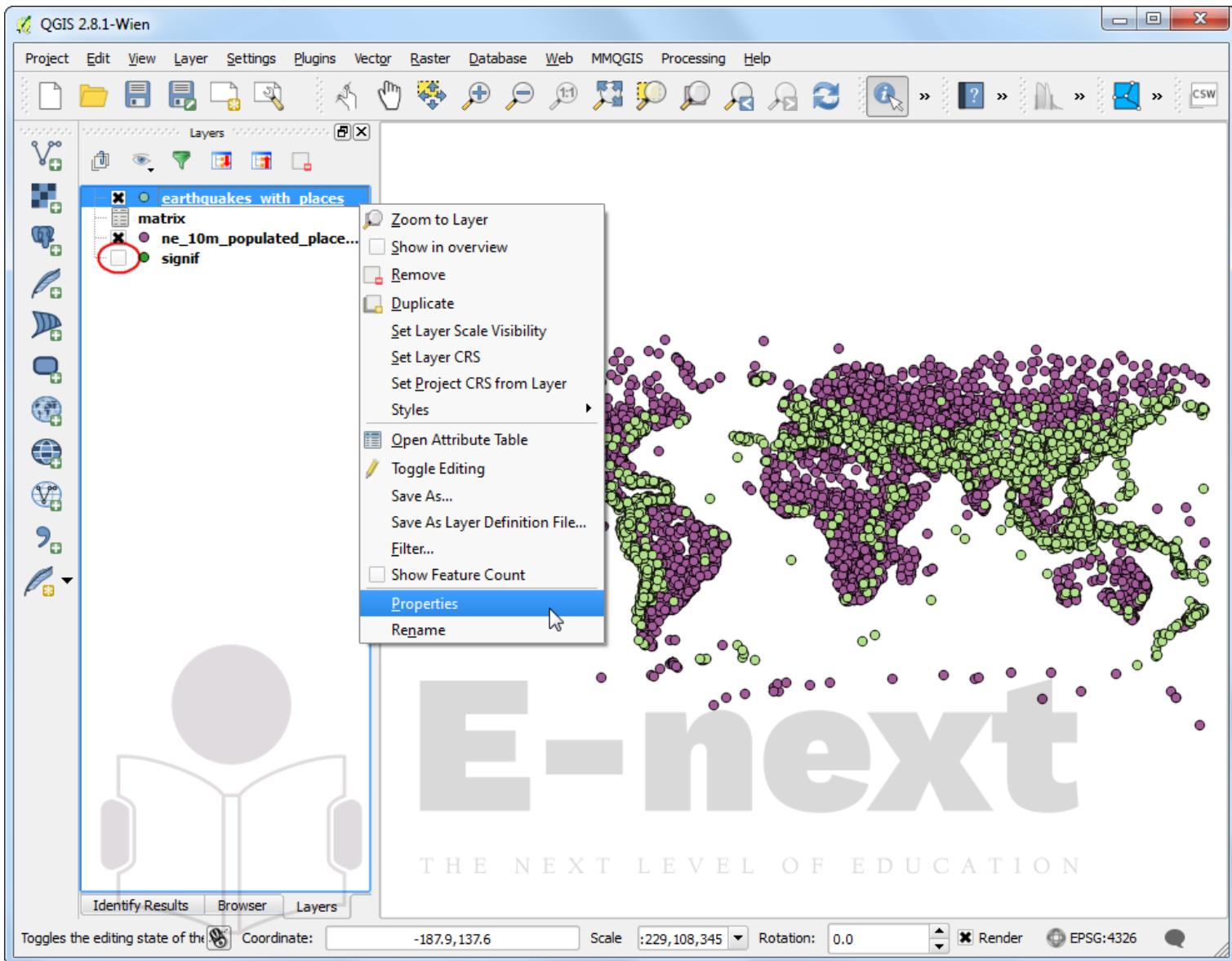
18. We will now explore a way to visualize these results. First, we need to make the table join permanent by saving it to a new layer. Right-click the **signif** layer and select Save As....



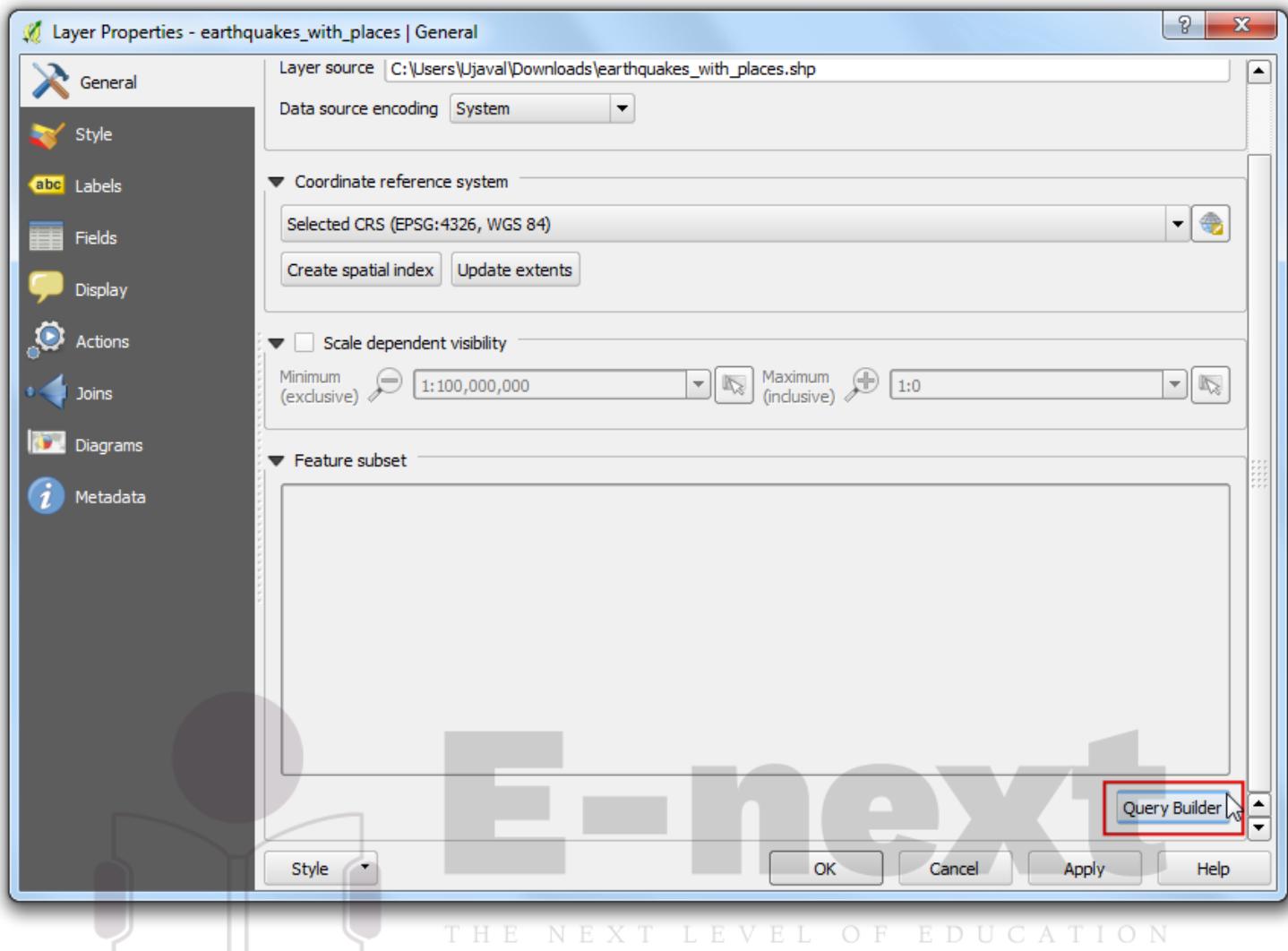
19. Click the Browse button next to Save as label and name the output layer as `earthquake_with_places.shp`. Make sure the Add saved file to map box is checked and click OK.



20. Once the new layer is loaded, you can turn off the visibility of the **signif** layer. As our dataset is quite large, we can run our visualization analysis on a subset of the data. QGIS has a neat feature where you can load a subset of features from a layer without having to export it to a new layer. Right-click the **earthquake_with_places** layer and select Properties.

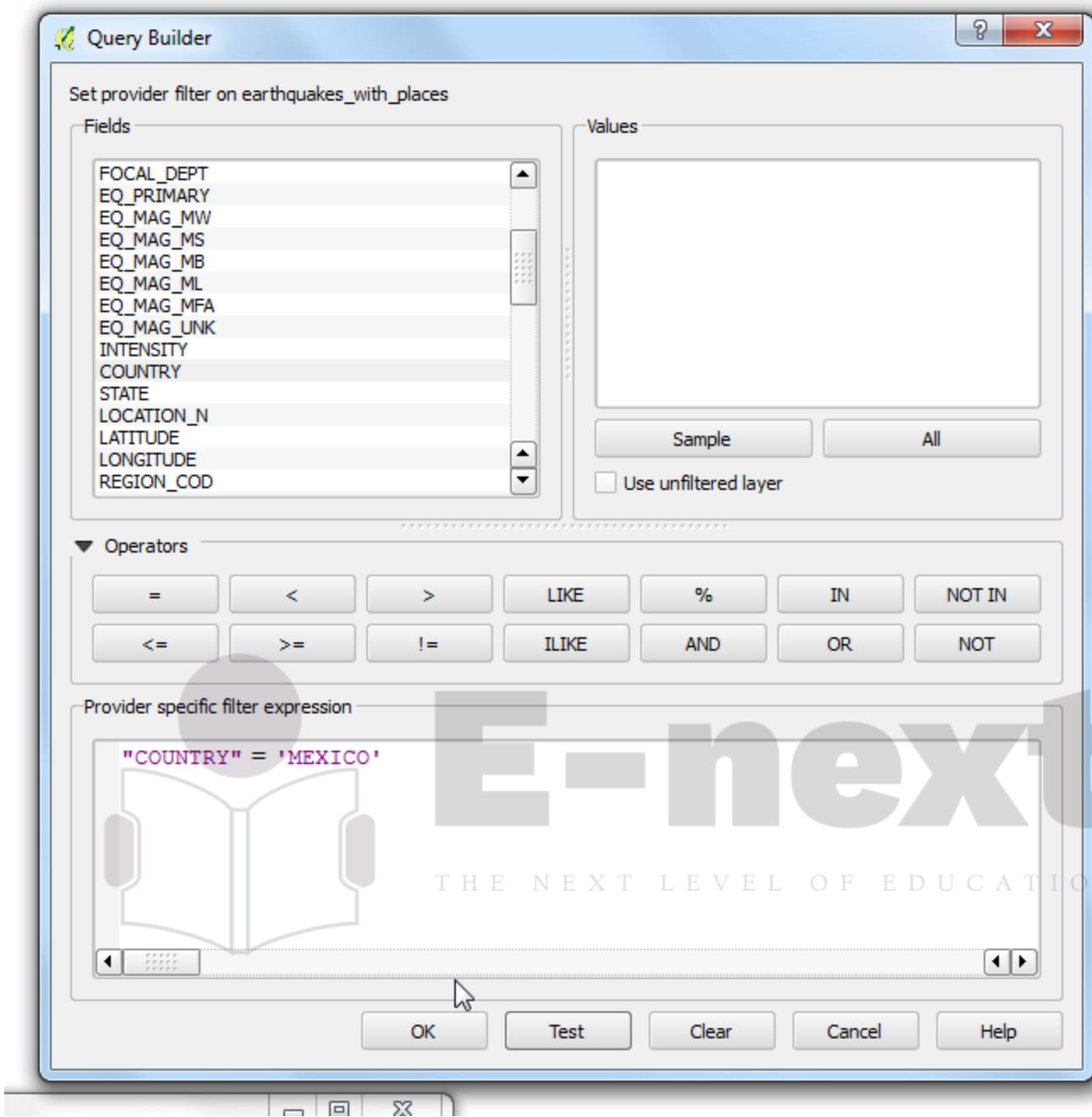


21. In the General tab, scroll down to the Feature subset section. Click Query Builder.

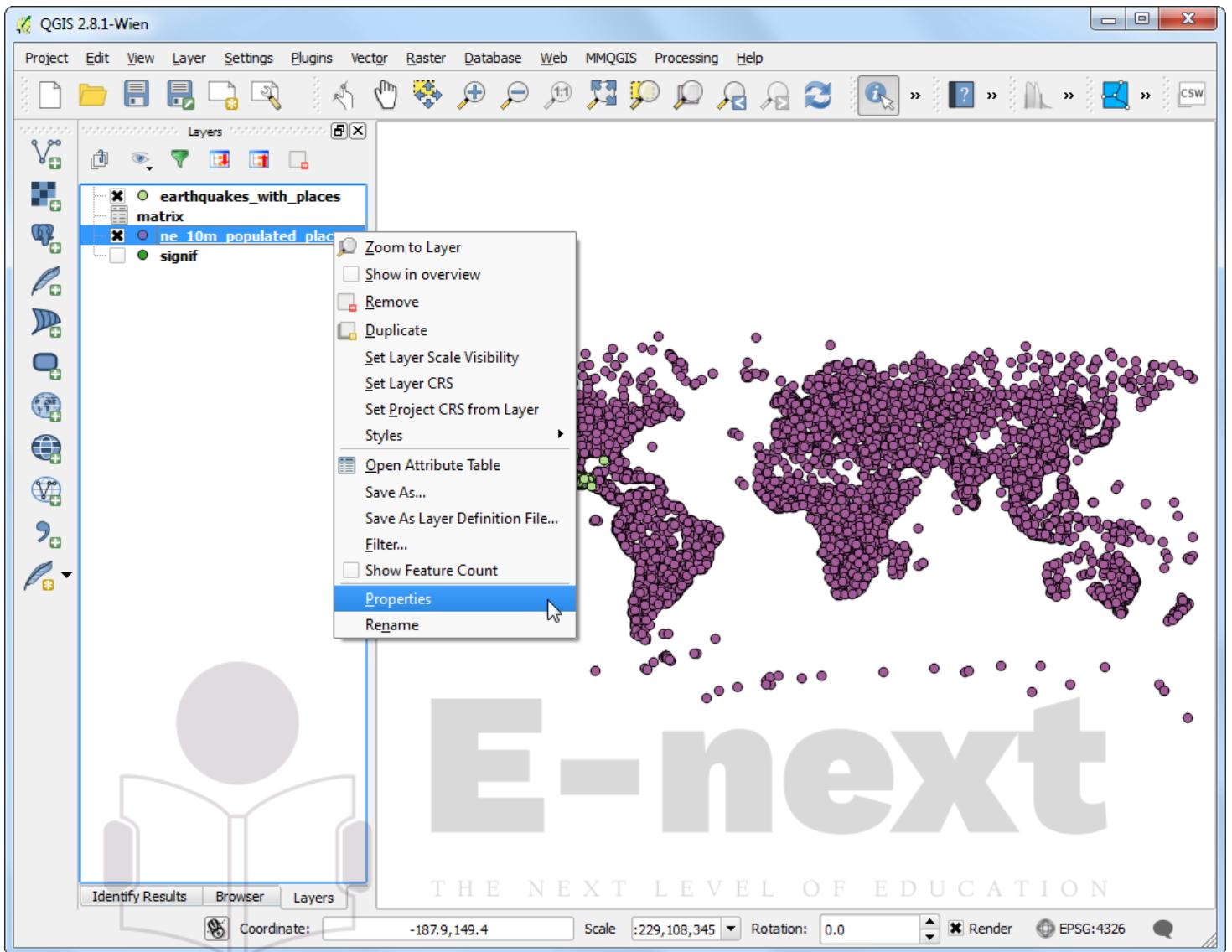


22. For this tutorial, we will visualize the earthquakes and their nearest populated places for Mexico. Enter the following expression in the Query Builder dialog.

```
"COUNTRY" = 'MEXICO'
```

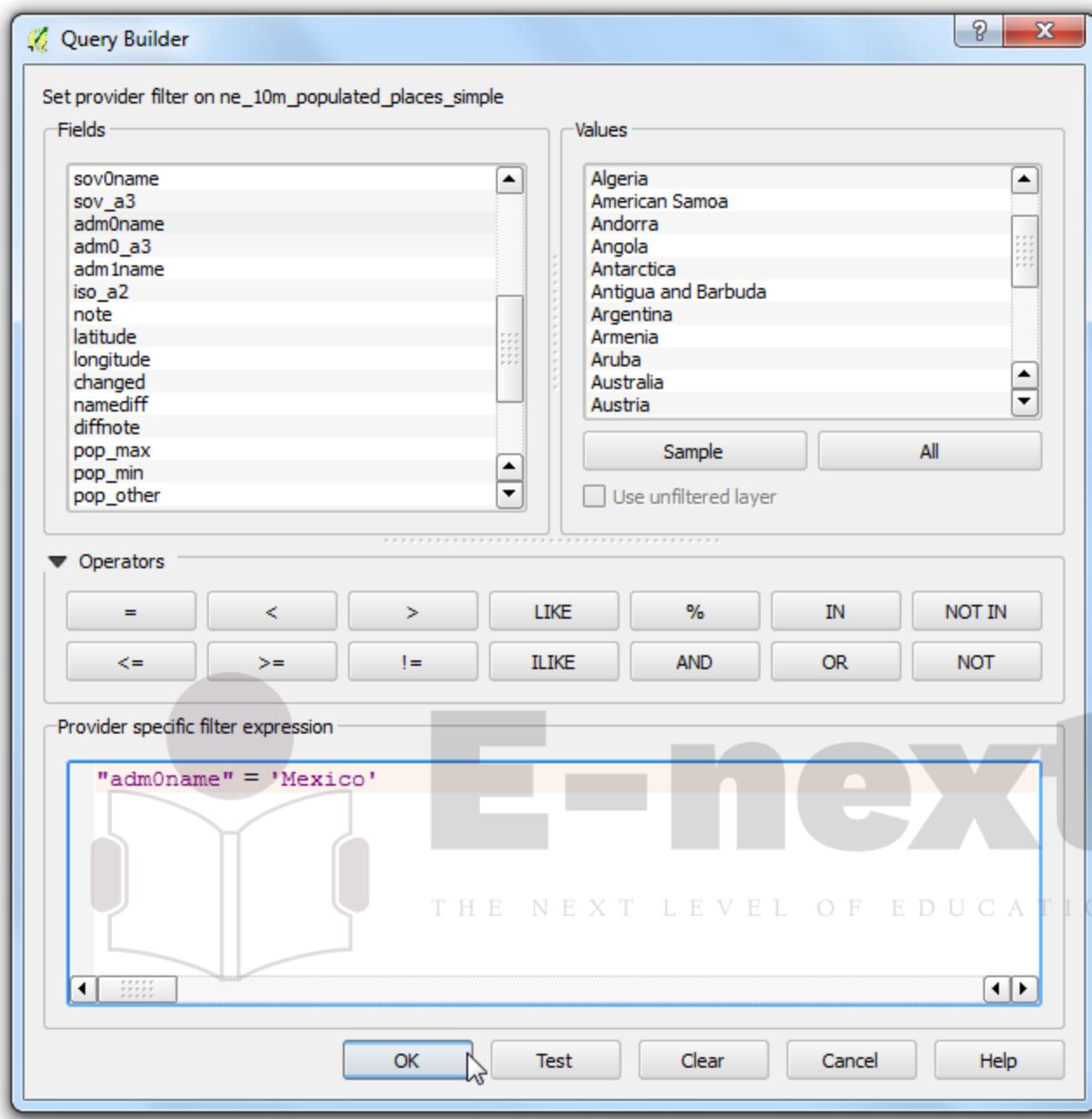


23. You will see that only the points falling within Mexico will be visible in the canvas. Let's do the same for the populated places layer. Right-click on the `ne_10m_populated_places_simple` layer and select Properties.

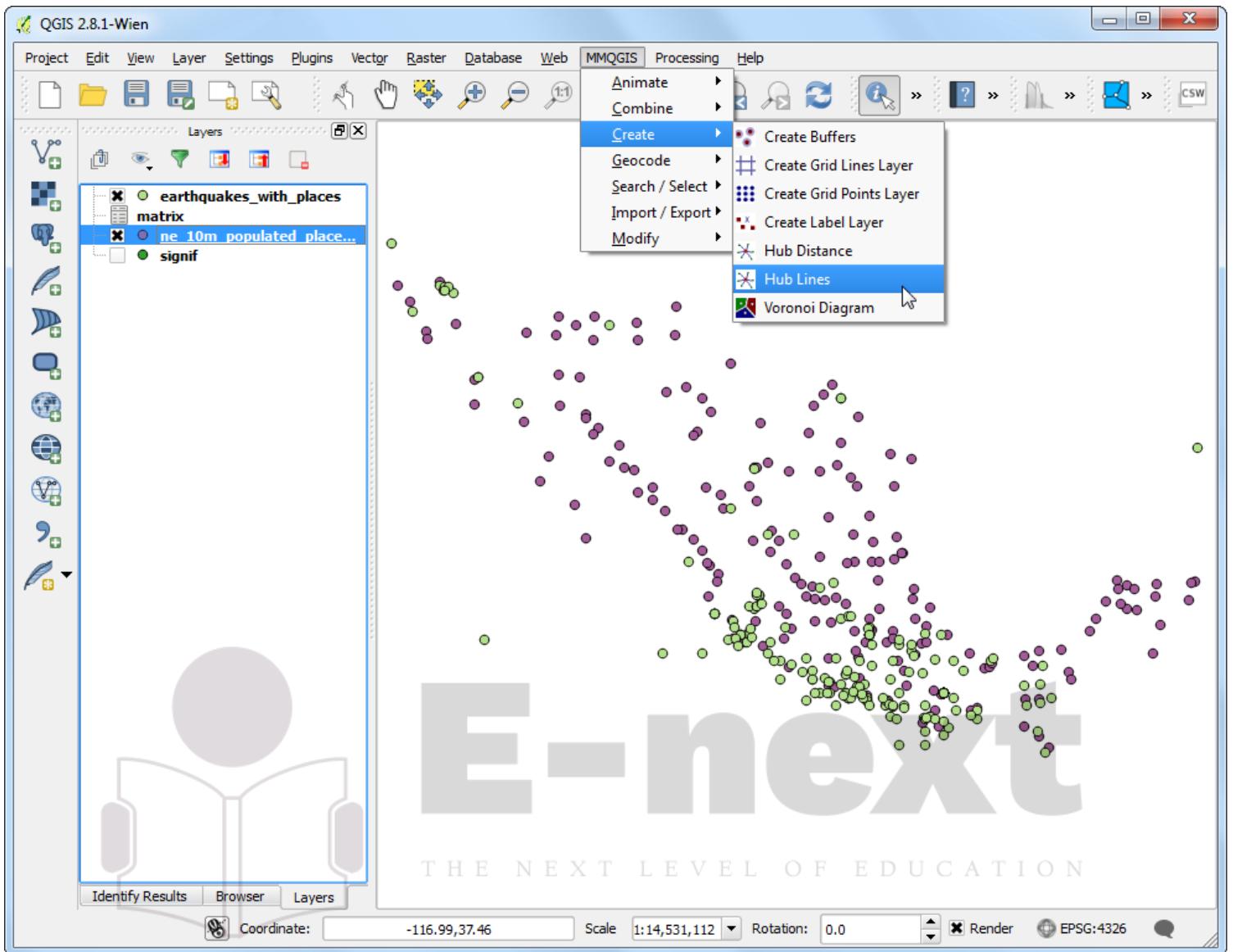


24. Open the Query Builder dialog from the General tab. Enter the following expression.

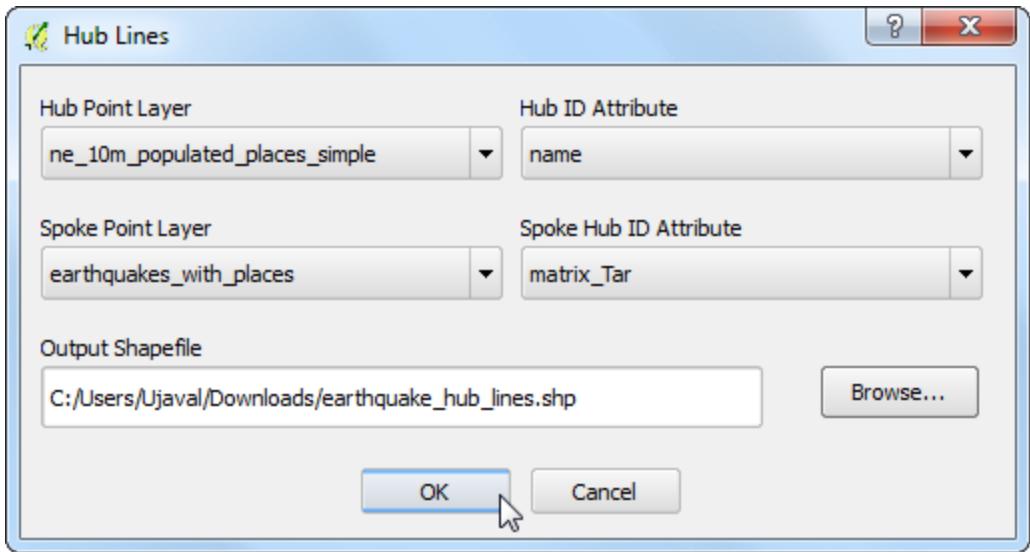
```
"adm0name" = 'Mexico'
```



25. Now we are ready to create our visualization. We will use a plugin named **MMQGIS**. Find and install the plugin. See [Using Plugins](#) for more details on how to work with plugins. Once you have the plugin installed, go to **MMQGIS** → **Create** → **Hub Lines**.



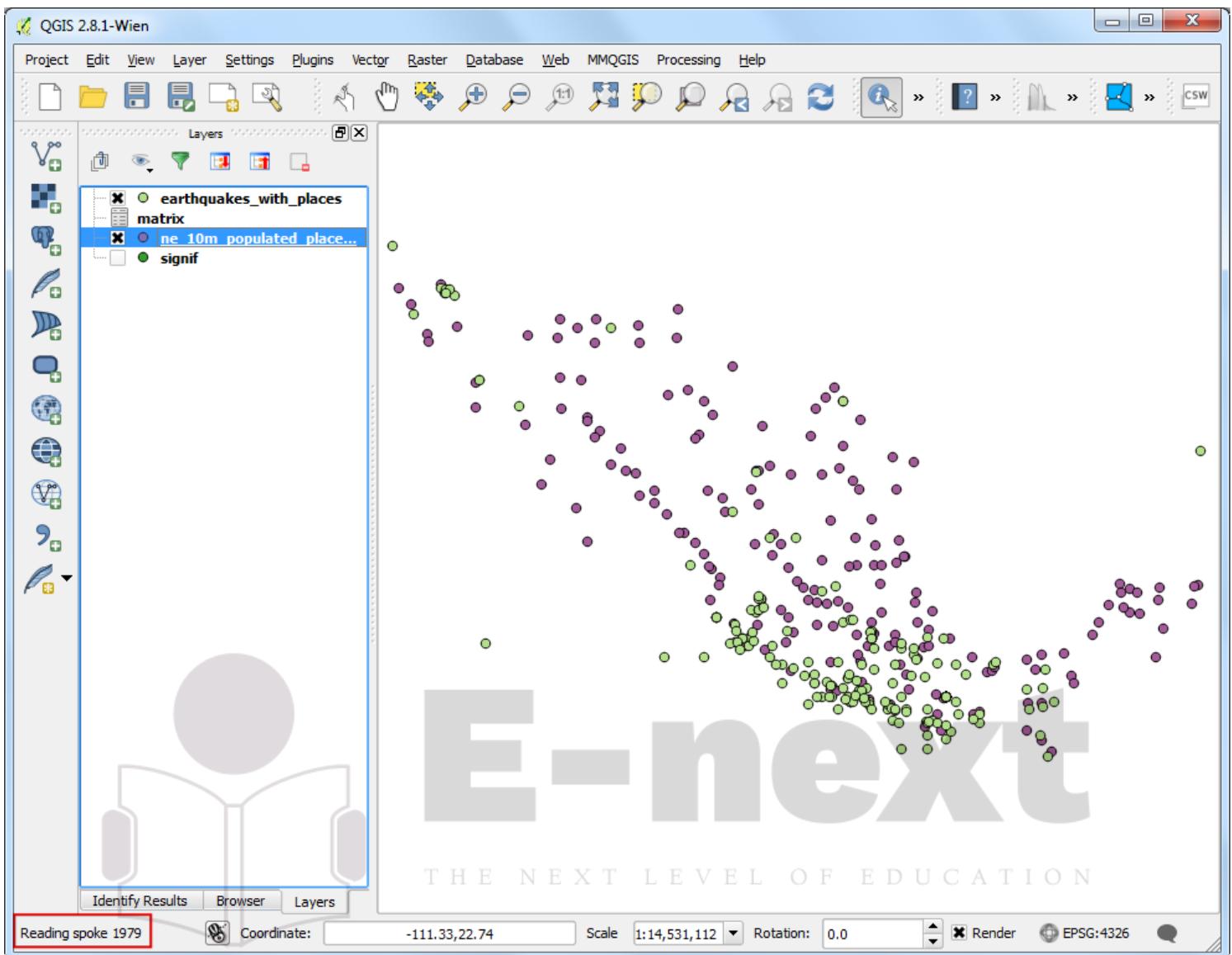
26. Select `ne_10m_populated_places_simple` as the Hub Point Layer and `name` as the Hub ID Attribute. Similarly, select `earthquake_with_places` as the Spoke Point Layer and `matrix_Tar` as the Spoke Hub ID Attribute. The hub lines algorithm will go through each of earthquake points and create a line that will join it to the populated place which matches the attribute we specified. Click Browse and name the Output Shapefile as `earthquake_hub_lines.shp`. Click OK to start the processing.



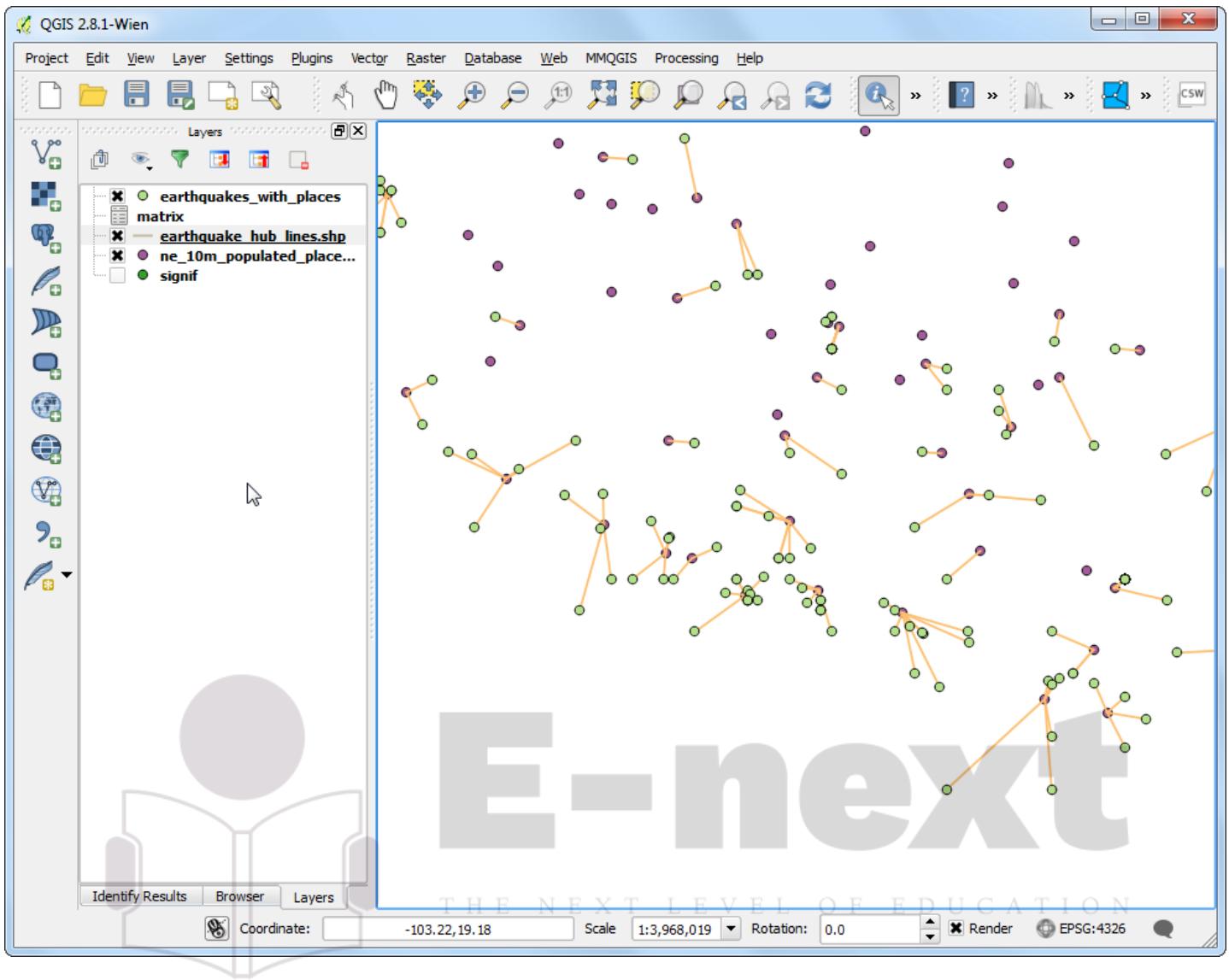
27. The processing may take a few minutes. You can see the progress on the bottom-left corner of the QGIS window.



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28. Once the processing is done, you will see the `earthquake_hub_lines` layer loaded in QGIS. You can see that each earthquake point now has a line that connects it to the nearest populated place.



Video lectures @ <https://www.youtube.com/c/TirupParmar> and Notes & material @ <https://t.me/bscit>