```
In [0]:
# Importing libraries
import pandas as pd
import numpy as np
from keras.models import Sequential, Model
from keras.layers import LSTM, Conv1D, MaxPooling1D, Flatten, LSTM, BatchNormalization, Input
from keras.layers.core import Dense, Dropout
from keras.callbacks import EarlyStopping, ReduceLROnPlateau, ModelCheckpoint
import keras
from keras.regularizers import 11, 12, 11 12
from sklearn.model selection import train test split
from keras.models import load model
from sklearn.metrics import accuracy score
from prettytable import PrettyTable
In [0]:
pt = PrettyTable()
pt.field names = ['Model', 'Loss', 'Test Accuracy']
In [2]:
from google.colab import drive
drive.mount('/content/drive')
Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client id=947318989803-
6bn6qk8qdgf4n4q3pfee6491hc0brc4i.apps.googleusercontent.com&redirect uri=urn%3Aietf%3Awg%3Aoauth%3A2.0%3Aoob&scope=email%20https%3A%2F%2Fwww.googlea
%2Fauth%2Fdocs.test%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive%20https%3A%2F%2Fwww.googleapis.com%2Fauth%2Fdrive.photos.readonly%20https%3A%2
.googleapis.com%2Fauth%2Fpeopleapi.readonly&response type=code
Enter your authorization code:
. . . . . . . . . .
Mounted at /content/drive
In [0]:
# Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
   0: 'WALKING',
   1: 'WALKING UPSTAIRS',
    2: 'WALKING DOWNSTAIRS',
```

```
3: 'SITTING',
4: 'STANDING',
5: 'LAYING',

# Utility function to print the confusion matrix

def confusion_matrix(Y_true, Y_pred):
    Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)])
    Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)])

return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

### Data

```
In [0]:
```

```
# Data directory
DATADIR = 'drive/My Drive/CoLab/Human Activity Recognition/UCI_HAR_Dataset'
```

## In [0]:

```
# Raw data signals
# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
    "body acc x",
    "body acc y",
   "body acc z",
    "body gyro_x",
    "body gyro y",
    "body_gyro_z",
    "total acc x",
    "total acc y",
    "total acc z"
```

```
# Utility function to read the data from csv file
def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

# Utility function to load the load
def load_signals(subset):
    signals_data = []
```

In [0]:

```
def load_y(subset):
    """

The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get_dummies.html)
    """
    filename = f'/'.join([DATADIR,'{0}/y_{0}.txt'.format(subset)])
    y = _read_csv(filename)[0]

return pd.get_dummies(y).values
```

In [0]:

```
def load_data():
    """

    Obtain the dataset from multiple files.
    Returns: X_train, X_test, y_train, y_test
    """

    X_train, X_test = load_signals('train'), load_signals('test')
    y_train, y_test = load_y('train'), load_y('test')

    return X_train, X_test, y_train, y_test
```

In [0]:

```
# Utility function to count the number of classes
def _count_classes(y):
    return len(set([tuple(category) for category in y]))
```

```
# Loading the train and test data
X_train, X_test, Y_train, Y_test = load_data()
```

```
In [12]:
timesteps = len(X train[0])
input dim = len(X train[0][0])
n classes = count classes(Y train)
n hidden = 32
np.random.seed(23)
print(timesteps)
print(input dim)
print(len(X train))
128
7352
 • Defining the Architecture of LSTM
Model - 1 Using multilayer LSTM

    Splitting the data into Train and Validation data

In [0]:
trainX, valX, trainy, valy = train test split(X train, Y train, test size=.33, random state=23)
In [0]:
# Initiliazing the sequential model
model = Sequential()
```

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(CuDNNLSTM(64, return_sequences=True, input_shape=(timesteps, input_dim)))
model.add(Dropout(rate=0.7))

model.add(CuDNNLSTM(32, input_shape=(timesteps, input_dim)))
model.add(Dropout(rate=0.5))

model.add(Dense(100, activation='relu'))
model.add(BatchNormalization())
# model.add(Dropout(rate=0.7))

model.add(Dense(n_classes, activation='sigmoid'))

# model.summary()
```

```
model.compile(loss='categorical_crossentropy', optimizer=keras.optimizers.Adam(), metrics=['accuracy'])
```

```
In [0]:
# Training the model
model.fit(trainX,
        trainv.
        batch size=8,
        validation data=(valX, valy),
        epochs=50,
        callbacks=[EarlyStopping(monitor='val acc', patience=25), ReduceLROnPlateau(monitor='val acc', factor=0.2, patience=5, min lr=.0001)])
Train on 4925 samples, validate on 2427 samples
Epoch 1/50
4925/4925 [============ ] - 17s 3ms/step - loss: 1.2205 - acc: 0.4721 - val loss: 0.9024 - val acc: 0.4800
Epoch 2/50
Epoch 3/50
4925/4925 [============= ] - 10s 2ms/step - loss: 0.7441 - acc: 0.6311 - val loss: 0.6190 - val acc: 0.6593
Epoch 4/50
4925/4925 [============= ] - 10s 2ms/step - loss: 0.6962 - acc: 0.6499 - val loss: 0.6139 - val acc: 0.6642
Epoch 5/50
4925/4925 [============ ] - 10s 2ms/step - loss: 0.7006 - acc: 0.6493 - val loss: 0.6304 - val acc: 0.6708
Epoch 6/50
4925/4925 [============] - 10s 2ms/step - loss: 0.7043 - acc: 0.6491 - val loss: 0.6064 - val acc: 0.6576
Epoch 7/50
4925/4925 [============] - 10s 2ms/step - loss: 0.6802 - acc: 0.6502 - val loss: 0.6152 - val acc: 0.6716
Epoch 9/50
4925/4925 [=============] - 10s 2ms/step - loss: 0.8927 - acc: 0.5848 - val loss: 0.6260 - val acc: 0.6568
Epoch 10/50
4925/4925 [=============] - 10s 2ms/step - loss: 0.6979 - acc: 0.6445 - val loss: 0.6561 - val acc: 0.6539
Epoch 11/50
4925/4925 [============= ] - 10s 2ms/step - loss: 0.6845 - acc: 0.6475 - val loss: 0.6186 - val acc: 0.6663
Epoch 12/50
4925/4925 [============= ] - 10s 2ms/step - loss: 0.6696 - acc: 0.6589 - val loss: 0.6209 - val acc: 0.6728
Epoch 13/50
4925/4925 [=============] - 10s 2ms/step - loss: 0.6523 - acc: 0.6615 - val loss: 0.6036 - val acc: 0.6782
Epoch 14/50
4925/4925 [============== ] - 10s 2ms/step - loss: 0.6346 - acc: 0.6908 - val loss: 0.5123 - val acc: 0.7553
Epoch 15/50
4925/4925 [============] - 10s 2ms/step - loss: 0.6431 - acc: 0.7232 - val loss: 0.4792 - val acc: 0.7895
Epoch 16/50
4925/4925 [============] - 10s 2ms/step - loss: 0.4728 - acc: 0.7963 - val loss: 0.3330 - val acc: 0.8896
Epoch 17/50
4925/4925 [============ ] - 10s 2ms/step - loss: 0.4983 - acc: 0.8110 - val loss: 0.3650 - val acc: 0.8826
```

4925/4925 [============] - 10s 2ms/step - loss: 0.4729 - acc: 0.8185 - val loss: 0.3075 - val acc: 0.8649

4925/4925 [============= ] - 10s 2ms/step - loss: 0.4875 - acc: 0.8037 - val loss: 0.3148 - val acc: 0.9188

Epoch 18/50

Epoch 19/50

Epoch 20/50 Epoch 21/50 Epoch 22/50 Epoch 23/50 4925/4925 [=============] - 10s 2ms/step - loss: 0.2551 - acc: 0.9127 - val loss: 0.1466 - val acc: 0.9419 Epoch 24/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1867 - acc: 0.9350 - val loss: 0.1181 - val acc: 0.9547 4925/4925 [===========] - 10s 2ms/step - loss: 0.1739 - acc: 0.9340 - val loss: 0.1176 - val acc: 0.9506 Epoch 26/50 4925/4925 [============] - 10s 2ms/step - loss: 0.2980 - acc: 0.9003 - val loss: 0.1437 - val acc: 0.9312 Epoch 27/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1972 - acc: 0.9267 - val loss: 0.1317 - val acc: 0.9547 Epoch 28/50 4925/4925 [============] - 10s 2ms/step - loss: 0.2369 - acc: 0.9198 - val loss: 0.1266 - val acc: 0.9411 Epoch 29/50 Epoch 30/50 4925/4925 [============] - 10s 2ms/step - loss: 0.2227 - acc: 0.9155 - val loss: 0.3197 - val acc: 0.8199 Epoch 31/50 4925/4925 [============] - 10s 2ms/step - loss: 0.2268 - acc: 0.9170 - val loss: 0.1545 - val acc: 0.9444 4925/4925 [===========] - 10s 2ms/step - loss: 0.1865 - acc: 0.9330 - val loss: 0.1287 - val acc: 0.9485 Epoch 33/50 Epoch 34/50 Epoch 35/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1512 - acc: 0.9482 - val loss: 0.1369 - val acc: 0.9477 Epoch 36/50 Epoch 37/50 Epoch 38/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1363 - acc: 0.9488 - val loss: 0.1395 - val acc: 0.9576 4925/4925 [============] - 10s 2ms/step - loss: 0.1361 - acc: 0.9521 - val loss: 0.1105 - val acc: 0.9584 Epoch 40/50 Epoch 41/50 Epoch 42/50 4925/4925 [=============] - 10s 2ms/step - loss: 0.1343 - acc: 0.9519 - val loss: 0.1112 - val acc: 0.9580 Epoch 43/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1272 - acc: 0.9515 - val loss: 0.1103 - val acc: 0.9543 Epoch 44/50 4925/4925 [============] - 10s 2ms/step - loss: 0.1311 - acc: 0.9513 - val loss: 0.1143 - val acc: 0.9555 Epoch 45/50 4925/4925 [============= ] - 10s 2ms/step - loss: 0.1294 - acc: 0.9519 - val loss: 0.1092 - val acc: 0.9584 Enoch 46/50

```
LPUUII 10,00
Epoch 47/50
Epoch 48/50
Epoch 49/50
Epoch 50/50
4925/4925 [============= ] - 10s 2ms/step - loss: 0.1252 - acc: 0.9513 - val loss: 0.1048 - val acc: 0.9613
Out[0]:
<keras.callbacks.History at 0x7fbcf2813240>
In [0]:
model.evaluate(X test, Y test)
Out[0]:
[0.42299219827817475, 0.9002375296912114]
In [0]:
print('Loss: {} | Accuracy: {} %'.format(*np.round([0.42299219827817475, 0.9002375296912114*100.], 3)))
Loss: 0.423 | Accuracy: 90.024 %

    With a simple 2 LSTM layers architecture we got 90.024% test accuracy and a loss of 0.423

In [0]:
pt.add row(['2 Layers LSTM', 0.423, '90.024 %'])
In [0]:
# Confusion Matrix
confusion matrix(Y test, model.predict(X test))
Out[0]:
```

Pred LAYING SITTING STANDING WALKING WALKING\_DOWNSTAIRS WALKING\_UPSTAIRS

Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS	WALKING_UPSTAIRS
LATING	514	0	1	0	0	22
SITTING	0	394	94	0	0	3
STANDING	0	100	430	2	0	0
WALKING	0	0	0	488	0	8
WALKING_DOWNSTAIRS	0	0	0	1	418	1
WALKING_UPSTAIRS	0	0	0	43	19	409

# Model - 2 Using Conv nets

Tried with various hyper parameter values by hit and trail.

```
In [0]:
```

```
model = Sequential()
model.add(Conv1D(filters=32, kernel_size=3, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.001), input_shape=(timesteps, input_dim)))
model.add(Conv1D(filters=32, kernel_size=3, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.0001)))
model.add(MaxPooling1D(pool_size=2))
model.add(Flatten())
model.add(Dropout(0.7))
model.add(Dense(128, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.001)))
model.add(Dense(128, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.001)))
model.add(Dropout(0.7))
model.add(Dense(6, activation='softmax'))
# model.summary()
model.compile(loss='categorical_crossentropy', optimizer=keras.optimizers.Adam(), metrics=['accuracy'])
```

# In [0]:

```
!mkdir ./bestModel
```

### In [0]:

```
!rm ./bestModel/*
```

```
Train on 4925 samples, validate on 2427 samples
Epoch 1/50
4925/4925 [==========] - 5s 926us/step - loss: 0.2105 - acc: 0.9511 - val loss: 0.1696 - val acc: 0.9629
Epoch 2/50
Epoch 3/50
Epoch 4/50
Epoch 5/50
4925/4925 [===========] - 4s 889us/step - loss: 0.2037 - acc: 0.9539 - val loss: 0.1610 - val acc: 0.9633
Epoch 6/50
4925/4925 [============ ] - 4s 903us/step - loss: 0.2063 - acc: 0.9507 - val loss: 0.1590 - val acc: 0.9633
Epoch 7/50
4925/4925 [============ ] - 4s 881us/step - loss: 0.2016 - acc: 0.9521 - val loss: 0.1566 - val acc: 0.9642
Epoch 8/50
4925/4925 [===========] - 4s 879us/step - loss: 0.2067 - acc: 0.9529 - val loss: 0.1575 - val acc: 0.9629
Epoch 9/50
4925/4925 [===========] - 4s 907us/step - loss: 0.2039 - acc: 0.9492 - val loss: 0.1552 - val acc: 0.9646
Epoch 10/50
4925/4925 [============= ] - 4s 904us/step - loss: 0.2042 - acc: 0.9519 - val loss: 0.1564 - val acc: 0.9637
Epoch 11/50
Epoch 12/50
Epoch 13/50
Epoch 15/50
Epoch 16/50
Epoch 17/50
4925/4925 [==========] - 5s 950us/step - loss: 0.1828 - acc: 0.9576 - val loss: 0.1497 - val acc: 0.9621
Epoch 18/50
Epoch 19/50
Epoch 20/50
4925/4925 [============ - 4s 908us/step - loss: 0.1981 - acc: 0.9511 - val loss: 0.1453 - val acc: 0.9658
Epoch 21/50
Epoch 22/50
Epoch 23/50
```

```
4925/4925 [===========] - 4s 888us/step - loss: 0.1927 - acc: 0.9521 - val loss: 0.1439 - val acc: 0.9670
Epoch 24/50
Epoch 25/50
4925/4925 [============ ] - 4s 873us/step - loss: 0.1810 - acc: 0.9576 - val loss: 0.1410 - val acc: 0.9646
Epoch 26/50
4925/4925 [============ ] - 4s 888us/step - loss: 0.1760 - acc: 0.9586 - val loss: 0.1452 - val acc: 0.9658
Epoch 27/50
4925/4925 [===========] - 4s 885us/step - loss: 0.1821 - acc: 0.9543 - val loss: 0.1405 - val acc: 0.9674
4925/4925 [===========] - 4s 901us/step - loss: 0.1873 - acc: 0.9551 - val loss: 0.1370 - val acc: 0.9670
Epoch 30/50
4925/4925 [============ - 4s 891us/step - loss: 0.1858 - acc: 0.9555 - val loss: 0.1378 - val acc: 0.9666
Epoch 31/50
4925/4925 [===========] - 4s 872us/step - loss: 0.1741 - acc: 0.9588 - val loss: 0.1358 - val acc: 0.9650
Epoch 32/50
4925/4925 [============] - 4s 896us/step - loss: 0.1757 - acc: 0.9602 - val loss: 0.1353 - val acc: 0.9658
Epoch 33/50
4925/4925 [===========] - 4s 893us/step - loss: 0.1682 - acc: 0.9630 - val loss: 0.1353 - val acc: 0.9687
Epoch 34/50
4925/4925 [============] - 4s 885us/step - loss: 0.1807 - acc: 0.9537 - val loss: 0.1374 - val acc: 0.9674
Epoch 35/50
4925/4925 [============ ] - 4s 884us/step - loss: 0.1661 - acc: 0.9606 - val loss: 0.1341 - val acc: 0.9691
Epoch 37/50
Epoch 38/50
4925/4925 [============] - 4s 893us/step - loss: 0.1697 - acc: 0.9592 - val loss: 0.1324 - val acc: 0.9679
Epoch 39/50
Epoch 40/50
Epoch 41/50
Epoch 42/50
Epoch 43/50
Epoch 44/50
4925/4925 [============ - 4s 877us/step - loss: 0.1652 - acc: 0.9598 - val loss: 0.1368 - val acc: 0.9716
Epoch 45/50
Epoch 46/50
Epoch 47/50
Epoch 48/50
4925/4925 [===========] - 4s 894us/step - loss: 0.1642 - acc: 0.9614 - val loss: 0.1280 - val acc: 0.9670
Epoch 49/50
```

```
Epoch 50/50
4925/4925 [============] - 4s 900us/step - loss: 0.1690 - acc: 0.9578 - val loss: 0.1332 - val acc: 0.9674
Out[0]:
<keras.callbacks.History at 0x7fbcf7dbc630>
Loading best model so far
In [0]:
#Loading best model at epoch with high val accuracy
model = load model('bestModel/bestmodel.hdf5')
In [0]:
model.evaluate(X test, Y test)
2947/2947 [============ ] - Os 80us/step
[0.343903040034936, 0.9229725144214456]
In [0]:
print('Loss: {} | Accuracy: {} %'.format(*np.round([0.343903040034936, 0.9229725144214456*100.], 2)))
Loss: 0.344 | Accuracy: 92.297 %
 • With a simple 2 convolution layers and 1 max-pooling architecture we got 92.297% test accuracy and a loss of 0.344
In [0]:
pt.add_row(['2 Layers 1D Convolutions', 0.344, '92.297 %'])
In [0]:
# Confusion Matrix
confusion matrix(Y test, model.predict(X test))
Out[0]:
               Pred LAYING SITTING STANDING WALKING WALKING_DOWNSTAIRS WALKING_UPSTAIRS
               True
```

LA <b>'PING</b>	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIR9	WALKING_UPSTAIRS
SITTING	0	399	68	0	0	24
STANDING	0	72	456	0	0	4
WALKING	0	0	0	481	14	1
WALKING_DOWNSTAIRS	0	0	0	0	420	0
WALKING_UPSTAIRS	0	0	0	2	20	449

# Model - 3 Using Divide and conquer Conv nets

### References:

- https://www.ncbi.nlm.nih.gov/pmc/articles/PMC5949027/
- https://github.com/maxpumperla/hyperas

# Data Preparation Basic

```
In [0]:
```

```
from keras.layers import multiply
import keras
import keras.backend as K
```

# In [0]:

```
def load_y_new(subset):
    """
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get_dummies.html)
    """
    filename = f'/'.join([DATADIR,'{0}/y_{0}.txt'.format(subset)])
    y = _read_csv(filename)[0]
    return y.values
```

```
X_train, X_test = load_signals('train'), load_signals('test')
y_train, y_test = load_y_new('train'), load_y_new('test')
```

```
y train bin, y test bin = pd.Series(y train).map(dict(zip(range(1,7), [1]*3+[0]*3))).values,\
                          pd.Series(y test).map(dict(zip(range(1,7), [1]*3+[0]*3))).values
In [0]:
# Dynamic class data
| X train dynamic, X test dynamic = X train[y train bin==1], X test[y test bin==1]
y train dynamic, y test dynamic = y train[y train bin==1], y test[y test bin==1]
# Static class data
X train static, X test static = X train[y train bin==0], X test[y test bin==0]
y train static, y test static = y train[y train bin==0], y test[y test bin==0]
In [0]:
y train bin, y test bin = pd.get dummies(y train bin).values,\
                                     pd.get dummies(y test bin).values
y train dynamic, y test dynamic = pd.get dummies(y train dynamic).values,\
                                                  pd.get dummies (y test dynamic).values
y train static, y test static = pd.get dummies(y train static).values,\
                                              pd.get dummies (y test static).values
```

### Base Binary Model

## In [0]:

**⊥**11 [∪].

```
main_input = Input(shape=(timesteps, input_dim), name='main_input')

# Base Binary Model
x = ConvlD(filters=16, kernel_size=3, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.0001))(main_input)
x = MaxPoolinglD(pool_size=2)(x)
x = Flatten()(x)
x = Dropout(rate=.5)(x)
x = Dense(16, activation='relu', kernel_initializer='he_normal', kernel_regularizer=12(.001))(x)
x = BatchNormalization()(x)
x = Dropout(rate=.65)(x)
out = Dense(2, activation='softmax', name='binary_out')(x)
bin_model = Model(inputs=main_input, outputs=out)
bin_model.compile(loss='binary_crossentropy', optimizer=keras.optimizers.Adam(.01), metrics=['accuracy'])
```

### In [0]:

bin model.fit(X train,

```
y train bin,
        batch size=8,
        validation data=(X test, y test bin),
        epochs=20.
        callbacks=[EarlyStopping(monitor='val acc', patience=10), ReduceLROnPlateau(monitor='val acc', factor=0.2, patience=3, min lr=.0001)])
Train on 7352 samples, validate on 2947 samples
Epoch 1/20
7352/7352 [============= ] - 15s 2ms/step - loss: 0.2863 - acc: 0.9479 - val loss: 0.1700 - val acc: 0.9986
Epoch 2/20
7352/7352 [==========] - 8s 1ms/step - loss: 0.2714 - acc: 0.9686 - val loss: 0.1841 - val acc: 0.9854
Epoch 3/20
Epoch 4/20
7352/7352 [==========] - 8s 1ms/step - loss: 0.2800 - acc: 0.9720 - val loss: 0.1329 - val acc: 0.9986
Epoch 5/20
Epoch 6/20
7352/7352 [============] - 8s 1ms/step - loss: 0.1202 - acc: 0.9839 - val loss: 0.0524 - val acc: 0.9993
Epoch 7/20
7352/7352 [============= ] - 8s lms/step - loss: 0.0806 - acc: 0.9902 - val loss: 0.0423 - val acc: 0.9986
Epoch 8/20
Epoch 9/20
Epoch 10/20
7352/7352 [============== ] - 8s lms/step - loss: 0.1014 - acc: 0.9791 - val loss: 0.0355 - val acc: 0.9993
Epoch 11/20
7352/7352 [==========] - 8s 1ms/step - loss: 0.0702 - acc: 0.9893 - val loss: 0.0330 - val acc: 0.9993
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
7352/7352 [==========] - 8s 1ms/step - loss: 0.0761 - acc: 0.9861 - val loss: 0.0273 - val acc: 0.9990
Epoch 16/20
7352/7352 [============ ] - 8s 1ms/step - loss: 0.0737 - acc: 0.9868 - val loss: 0.0272 - val acc: 0.9990
Out[0]:
```

<keras.callbacks.History at 0x7f98b29eef28>

```
bin loss, bin acc = bin model.evaluate(X test, y test bin)
```

```
In [0]:
print('Loss : {} | Accuracy : {} %'.format(bin loss, bin acc*100.))
Loss: 0.027248992813763112 | Accuracy: 99.8982015609094 %
In [0]:
# Utility function to print the confusion matrix
def confusion matrix bin(Y true, Y pred, ACTIVITIES):
   Y true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y true, axis=1)])
   Y pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y pred, axis=1)])
    return pd.crosstab(Y true, Y pred, rownames=['True'], colnames=['Pred'])
In [0]:
confusion matrix bin(y test bin, bin model.predict(X test), {
   0: 'Static',
   1: 'Dynamic',
})
Out[0]:
   Pred Dynamic Static
   True
Dynamic
          1387
  Static
            3 1557
In [0]:
bin model.save('Base Binary model.hdf5')
Dynamic class Model
```

```
In [0]:
```

```
# Model - 1
dynamic_input = Input(shape=(timesteps, input_dim), name='dynamic_input')
```

```
y = ConvID(Inters=0+, kernel_size=3, activation='relu',) (dynamic_input)
y = ConvID(filters=32, kernel_size=3, activation='relu',) (y)
y = MaxPooling1D(pool_size=2) (y)
y = Flatten() (y)
y = Dropout(rate=.6) (y)
y = Dense(32, activation='relu', kernel_regularizer=12(.001)) (y)
y = BatchNormalization() (y)
y = Dropout(.6) (y)
dynamic_output = Dense(3, activation='softmax', name='dynamic_out') (y)
dynamic_model = Model(inputs=dynamic_input, outputs=dynamic_output)
dynamic_model.compile(loss='categorical_crossentropy', optimizer=keras.optimizers.rmsprop(.01), metrics=['accuracy'])
```

## In [0]:

Epoch 1/50 3285/3285 [==========] - 3s 791us/step - loss: 0.2071 - acc: 0.9482 - val loss: 0.1693 - val acc: 0.9603 Epoch 3/50 Epoch 4/50 3285/3285 [===========] - 3s 782us/step - loss: 0.2026 - acc: 0.9470 - val loss: 0.1143 - val acc: 0.9740 Epoch 5/50 3285/3285 [==========] - 3s 780us/step - loss: 0.2680 - acc: 0.9376 - val loss: 0.1669 - val acc: 0.9625 Epoch 6/50 3285/3285 [==========] - 3s 809us/step - loss: 0.2039 - acc: 0.9528 - val loss: 0.1494 - val acc: 0.9668 Epoch 7/50 3285/3285 [===========] - 3s 789us/step - loss: 0.2005 - acc: 0.9440 - val loss: 0.1628 - val acc: 0.9625 Epoch 8/50 3285/3285 [============] - 3s 783us/step - loss: 0.2084 - acc: 0.9470 - val loss: 0.1412 - val acc: 0.9690 Epoch 9/50 3285/3285 [==========] - 3s 804us/step - loss: 0.2095 - acc: 0.9516 - val loss: 0.1473 - val acc: 0.9697 Epoch 10/50 3285/3285 [==========] - 3s 784us/step - loss: 0.2003 - acc: 0.9513 - val loss: 0.1707 - val acc: 0.9690 Epoch 11/50 3285/3285 [=============] - 3s 798us/step - loss: 0.1752 - acc: 0.9580 - val loss: 0.1792 - val acc: 0.9640 Epoch 12/50 3285/3285 [==========] - 3s 780us/step - loss: 0.1962 - acc: 0.9549 - val loss: 0.1443 - val acc: 0.9690 Epoch 13/50 3285/3285 [==========] - 3s 812us/step - loss: 0.2125 - acc: 0.9537 - val loss: 0.2340 - val acc: 0.9625 Epoch 14/50 

```
Epoch 15/50
3285/3285 [===========] - 3s 783us/step - loss: 0.1709 - acc: 0.9647 - val loss: 0.1951 - val acc: 0.9726
3285/3285 [===========] - 3s 805us/step - loss: 0.1303 - acc: 0.9674 - val loss: 0.2214 - val acc: 0.9654
Epoch 17/50
3285/3285 [===========] - 3s 817us/step - loss: 0.2010 - acc: 0.9528 - val loss: 0.2585 - val acc: 0.9640
Epoch 18/50
3285/3285 [===========] - 3s 818us/step - loss: 0.1694 - acc: 0.9647 - val loss: 0.2897 - val acc: 0.9510
Epoch 19/50
3285/3285 [===========] - 3s 821us/step - loss: 0.1643 - acc: 0.9665 - val loss: 0.4056 - val acc: 0.9286
Epoch 20/50
3285/3285 [==========] - 3s 818us/step - loss: 0.2001 - acc: 0.9543 - val loss: 0.3493 - val acc: 0.9452
Epoch 21/50
Epoch 22/50
3285/3285 [===========] - 3s 798us/step - loss: 0.1520 - acc: 0.9686 - val loss: 0.2686 - val acc: 0.9668
Epoch 23/50
3285/3285 [===========] - 3s 787us/step - loss: 0.1669 - acc: 0.9632 - val loss: 0.2475 - val acc: 0.9683
Epoch 24/50
3285/3285 [==========] - 3s 791us/step - loss: 0.1708 - acc: 0.9616 - val loss: 0.2433 - val acc: 0.9690
Epoch 25/50
3285/3285 [===========] - 3s 796us/step - loss: 0.1600 - acc: 0.9686 - val loss: 0.2373 - val acc: 0.9712
3285/3285 [===========] - 3s 789us/step - loss: 0.1810 - acc: 0.9586 - val loss: 0.3030 - val acc: 0.9510
Epoch 27/50
3285/3285 [===========] - 3s 787us/step - loss: 0.1833 - acc: 0.9623 - val loss: 0.2875 - val acc: 0.9575
Epoch 28/50
3285/3285 [===========] - 3s 793us/step - loss: 0.1666 - acc: 0.9589 - val loss: 0.2197 - val acc: 0.9697
Epoch 29/50
3285/3285 [==========] - 3s 803us/step - loss: 0.1933 - acc: 0.9586 - val loss: 0.2960 - val acc: 0.9640
Out[0]:
<keras.callbacks.History at 0x7f7c353bd978>
In [0]:
dynamic loss, dynamic acc = dynamic model.evaluate(X test dynamic, y test dynamic)
In [0]:
print('Loss : {} | Accuracy : {} %'.format(dynamic loss, dynamic acc*100.))
Loss: 0.2959768250621533 | Accuracy: 96.39509733237203 %
```

- ---

### in [U]:

```
confusion_matrix_bin(y_test_dynamic, dynamic_model.predict(X_test_dynamic), { 0:'WALKING', 1:'WALKING_UPSTAIRS', 2:'WALKING_DOWNSTAIRS'})
```

# Out[0]:

### Pred WALKING WALKING DOWNSTAIRS WALKING UPSTAIRS

True

WALKING	482	5	9
WALKING_DOWNSTAIRS	9	405	6
WALKING_UPSTAIRS	2	24	445

## In [0]:

```
dynamic_model.save('Dynamic_class_model.hdf5')
```

### Static class model

## In [0]:

```
# Model - 2
static_input = Input(shape=(timesteps, input_dim), name='static_input')

z = ConvlD(filters=32, kernel_size=3, activation='relu', kernel_regularizer=12(.001))(static_input)

z = ConvlD(filters=64, kernel_size=3, activation='relu', kernel_regularizer=12(.1))(z)

z = ConvlD(filters=128, kernel_size=3, activation='relu', kernel_regularizer=12(.001))(z)

z = MaxPoolingID(pool_size=2)(z)

z = Flatten()(z)

z = Dropout(rate=.6)(z)

z = Dense(32, activation='relu', kernel_regularizer=12())(z)

z = BatchNormalization()(z)

z = Dropout(.7)(z)

static_output = Dense(3, activation='softmax', name='static_out')(z)

static_model = Model(inputs=static_input, outputs=static_output)

static_model.compile(loss='categorical_crossentropy', optimizer=keras.optimizers.rmsprop(.001), metrics=['accuracy'])
```

```
Train on 4067 samples, validate on 1560 samples
Epoch 1/100
Epoch 2/100
Epoch 3/100
Epoch 4/100
Epoch 5/100
Epoch 6/100
Epoch 7/100
Epoch 8/100
Epoch 9/100
Epoch 11/100
Epoch 12/100
Epoch 13/100
Epoch 14/100
Epoch 15/100
4067/4067 [============] - 3s 851us/step - loss: 0.3586 - acc: 0.8928 - val loss: 0.2868 - val acc: 0.9115
Epoch 16/100
Epoch 17/100
Epoch 18/100
Epoch 19/100
Epoch 20/100
Epoch 21/100
Epoch 22/100
Epoch 23/100
Epoch 24/100
4067/4067 [=============] - 3s 833us/step - loss: 0.3300 - acc: 0.9105 - val loss: 0.2997 - val acc: 0.9096
Epoch 25/100
```

```
Epoch 26/100
Epoch 27/100
Epoch 28/100
4067/4067 [==========] - 3s 859us/step - loss: 0.2788 - acc: 0.9299 - val loss: 0.3297 - val acc: 0.8981
Epoch 29/100
Epoch 30/100
4067/4067 [==========] - 3s 809us/step - loss: 0.2784 - acc: 0.9329 - val loss: 0.2427 - val acc: 0.9244
Epoch 31/100
4067/4067 [===========] - 3s 847us/step - loss: 0.3202 - acc: 0.9225 - val loss: 0.2444 - val acc: 0.9218
Epoch 32/100
4067/4067 [===========] - 3s 821us/step - loss: 0.2459 - acc: 0.9334 - val loss: 0.2705 - val acc: 0.9205
Epoch 33/100
4067/4067 [==========] - 3s 830us/step - loss: 0.3265 - acc: 0.9223 - val loss: 0.2791 - val acc: 0.9250
Epoch 34/100
Epoch 35/100
4067/4067 [===========] - 3s 852us/step - loss: 0.2685 - acc: 0.9243 - val loss: 0.2538 - val acc: 0.9199
Epoch 36/100
4067/4067 [==========] - 3s 835us/step - loss: 0.2763 - acc: 0.9334 - val loss: 0.3314 - val acc: 0.9013
Epoch 37/100
4067/4067 [==========] - 3s 830us/step - loss: 0.2677 - acc: 0.9329 - val loss: 0.2328 - val acc: 0.9237
Out[0]:
<keras.callbacks.History at 0x7f7c3855d240>
In [0]:
static loss, static acc = static model.evaluate(X test static, y test static)
1560/1560 [============ ] - Os 92us/step
In [0]:
print('Loss : {} | Accuracy : {} %'.format(static loss, static acc*100.))
Loss: 0.23280242435061016 | Accuracy: 92.37179487179488 %
In [0]:
confusion matrix bin(y test static, static model.predict(X test static), { 0:'SITTING', 1:'STANDING', 2:'LAYING'})
Out[0]:
```

### Pred LAYING SITTING STANDING

True

LAYING	537	0	0
SITTING	0	402	89
STANDING	0	30	502

```
In [0]:
```

```
static_model.save('Static_class_model.hdf5')
```

## **Final Prediction**

```
In [0]:
```

```
t = np.zeros((10), dtype='int')
t[[2,6,8]] = [23,54,9]
t
```

### Out[0]:

```
array([ 0, 0, 23, 0, 0, 0, 54, 0, 9, 0])
```

```
from keras.models import load_model
from scipy.ndimage import gaussian_filter

class PredictActivity:
    def __init__(self):
        self.binary_model = None
        self.binary_model = None
        self.static_model = None

        self.static_model = None

    def loadModels(self, binModelPath, dynamicModelpath, staticModelPath):
        self.binary_model = load_model(binModelPath)
        self.dynamic_model = load_model(dynamicModelpath)
        self.static_model = load_model(staticModelPath)

def predict(self, X):
        y_bin = np.argmax(self.binary_model.predict(X), axis=1)

        X_dynamic = X[y_bin==1]
        X_static = X[y_bin==0]
```

```
# X dynamic = X dynamic + .007*(X dynamic - gaussian filter(X dynamic, sigma=8))
    # X static = X static + .007*(X static - gaussian filter(X static, sigma=8))
    y dynamic = np.argmax(self.dynamic model.predict(X dynamic), axis=1)
    y static = np.argmax(self.static model.predict(X static), axis=1)
    y dynamic = y dynamic + 1
    y static = y static + 4
    output = np.zeros((X.shape[0]), dtype='int')
    output[np.where(y bin==1)[0]] = y dynamic
    output[np.where(y bin==0)[0]] = y static
    return output
In [0]:
predictactivity = PredictActivity()
predictactivity.loadModels('./Base Binary model.hdf5', './Dynamic class model.hdf5', './Static class model.hdf5')
In [0]:
accuracy score(y test, predictactivity.predict(X test))
Out[0]:
0.9416355615880556
In [0]:
print('Accuracy: {} %'.format(round(accuracy_score(y_test, predictactivity.predict(X_test))*100., 1)))
Accuracy : 94.2 %
In [0]:
pt.add_row(['Divide and Conquer(CNNs)', '-', '94.2 %'])
In [100]:
print(pt)
```

Model		Test Accuracy
	0.423	90.024 %     92.297 %     94.2 %
+	+	++