

# Gray code

The **reflected binary code** (**RBC**), also known just as **reflected binary** (**RB**) or **Gray code** after [Frank Gray](#), is an ordering of the [binary numeral system](#) such that two successive values differ in only one [bit](#) (binary digit).

For example, the representation of the decimal value "1" in binary would normally be "001" and "2" would be "010". In Gray code, these values are represented as "001" and "011". That way, incrementing a value from 1 to 2 requires only one bit to change, instead of two.

Gray codes are widely used to prevent spurious output from [electromechanical switches](#) and to facilitate [error correction](#) in digital communications such as [digital terrestrial television](#) and some [cable TV](#) systems.

	Lucal code <sup>[1][2]</sup>				
	5	4	3	2	1
	Gray code				
	4	3	2	1	
0	0	0	0	0	0
1	0	0	0	1	1
2	0	0	1	1	0
3	0	0	1	0	1
4	0	1	1	0	0
5	0	1	1	1	1
6	0	1	0	1	0
7	0	1	0	0	1
8	1	1	0	0	0
9	1	1	0	1	1
10	1	1	1	1	0
11	1	1	1	0	1
12	1	0	1	0	0
13	1	0	1	1	1
14	1	0	0	1	0
15	1	0	0	0	1

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## Motivation and name

Many devices indicate position by closing and opening switches. If that device uses [natural binary codes](#), positions 3 and 4 are next to each other but all three bits of the binary representation differ:

Decimal	Binary
...	...
3	011
4	100
...	...

The problem with natural binary codes is that physical switches are not ideal: it is very unlikely that physical switches will change states exactly in synchrony. In the transition between the two states shown above, all three switches change state. In the brief period while all are changing, the switches will read some spurious position. Even without keybounce, the transition might look like 011 — 001 — 101 — 100. When the switches appear to be in position 001, the observer cannot tell if that is the "real" position 001, or a transitional state between two other positions. If the output feeds into a sequential system, possibly via combinational logic, then the sequential system may store a false value.

This problem can be solved by changing only one switch at a time, so there is never any ambiguity of position, resulting in codes assigning to each of a contiguous set of integers, or to each member of a circular list, a word of symbols such that no two code words are identical and each two adjacent code words differ by exactly one symbol. These codes are also known as *unit-distance*,<sup>[3][4][5][6][7]</sup> *single-distance*, *single-step*, *monostrophic*<sup>[8][9][6][7]</sup> or *synoptic codes*,<sup>[8]</sup> in reference to the Hamming distance of 1 between adjacent codes.

In principle, there can be more than one such code for a given word length, but the term Gray code was first applied to a particular binary code for non-negative integers, the *binary-reflected Gray code*, or **BRGC**. Bell Labs researcher George R. Stibitz described such a code in a 1941 patent application, granted in 1943.<sup>[10][11][12]</sup> Frank Gray introduced the term *reflected binary code* in his 1947 patent application, remarking that the code had "as yet no recognized name".<sup>[13]</sup> He derived the name from the fact that it "may be built up from the conventional binary code by a sort of reflection process".

In the standard encoding the least significant bit follows a repetitive pattern of 2 on, 2 off ( ... 11001100 ... ); the next digit a pattern of 4 on, 4 off; the n-th least significant bit a pattern of **2<sup>n</sup>** on **2<sup>n</sup>** off. The four-bit version of this is shown below:

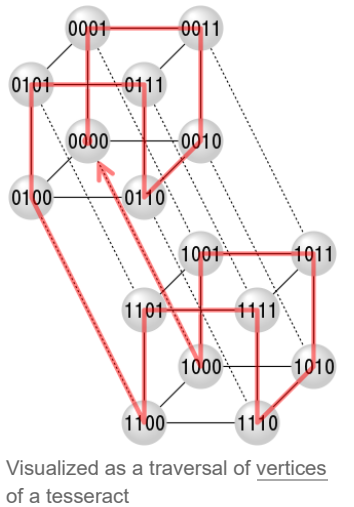
Decimal	Binary	Gray	Gray Decimal
0	0000	0000	0
1	0001	0001	1
2	0010	0011	3
3	0011	0010	2
4	0100	0110	6
5	0101	0111	7
6	0110	0101	5
7	0111	0100	4
8	1000	1100	12
9	1001	1101	13
10	1010	1111	15
11	1011	1110	14
12	1100	1010	10
13	1101	1011	11
14	1110	1001	9
15	1111	1000	8

For decimal 15 the code rolls over to decimal 0 with only one switch change. This is called the cyclic or adjacency property of the code.<sup>[14]</sup>

In modern digital communications, Gray codes play an important role in error correction. For example, in a digital modulation scheme such as QAM where data is typically transmitted in symbols of 4 bits or more, the signal's constellation diagram is arranged so that the bit patterns conveyed by adjacent constellation points differ by only one bit. By combining this with forward error correction capable of correcting single-bit errors, it is possible for a receiver to correct any transmission errors that cause a constellation point to deviate into the area of an adjacent point. This makes the transmission system less susceptible to noise.

Despite the fact that Stibitz described this code<sup>[10][11][12]</sup> before Gray, the reflected binary code was later named after Gray by others who used it. Two different 1953 patent applications use "Gray code" as an alternative name for the "reflected binary code";<sup>[15][16]</sup> one of those also lists "minimum error code" and "cyclic permutation code" among the names.<sup>[16]</sup> A 1954 patent application refers to "the Bell Telephone Gray code".<sup>[17]</sup> Other names include "cyclic binary code",<sup>[11]</sup> "cyclic progression code",<sup>[18][11]</sup> "cyclic permuting binary"<sup>[19]</sup> or "cyclic permuted binary" (CPB).<sup>[20][21]</sup>

received signal.  
The binary code with which the present invention deals may take various forms, all of which have the property that the symbol (or pulse group) representing each number (or signal amplitude) differs from the ones representing the next lower and the next higher number (or signal amplitude) in only one digit (or pulse position). Because this code in its primary form may be built up from the conventional binary code by a sort of reflection process and because other forms may in turn be built up from the primary form in similar fashion, the code in question, which has as yet no recognized name, is designated in this specification and in the claims as the "reflected binary code."  
If, at a receiver station, reflected binary code  
Gray's patent introduces the term "reflected binary code"



The Gray code was sometimes attributed, incorrectly,<sup>[12]</sup> to Elisha Gray.<sup>[22][23][24]</sup>

## History and practical application

### Mathematical puzzles

Reflected binary codes were applied to mathematical puzzles before they became known to engineers.

The binary-reflected Gray code represents the underlying scheme of the classical Chinese rings puzzle, a sequential mechanical puzzle mechanism described by the French Louis Gros in 1872.<sup>[25][12]</sup>

It can serve as a solution guide for the Towers of Hanoi problem, based on a game by the French Édouard Lucas in 1883.<sup>[26][27][28][29]</sup> Similarly, the so called Towers of Bucharest and Towers of Klagenfurt game configurations yield ternary and pentary Gray codes.<sup>[30]</sup>

Martin Gardner wrote a popular account of the Gray code in his August 1972 Mathematical Games column in Scientific American.<sup>[31]</sup>

The code also forms a Hamiltonian cycle on a hypercube, where each bit is seen as one dimension.

### Telegraphy codes

When the French engineer Émile Baudot changed from using a 6-unit (6-bit) code to 5-unit code for his printing telegraph system, in 1875<sup>[32]</sup> or 1876,<sup>[33][34]</sup> he ordered the alphabetic characters on his print wheel using a reflected binary code, and assigned the codes using only three of the bits to vowels. With vowels and consonants sorted in their alphabetical order,<sup>[35][36][37]</sup> and other symbols appropriately placed, the 5-bit character code has been recognized as a reflected binary code.<sup>[12]</sup> This code became known as Baudot code<sup>[38]</sup> and, with minor changes, was eventually adopted as International Telegraph Alphabet No. 1 (ITA1, CCITT-1) in 1932.<sup>[39][40][37]</sup>

About the same time, the German-Austrian Otto Schöffler<sup>[41]</sup> demonstrated another printing telegraph in Vienna using a 5-bit reflected binary code for the same purpose, in 1874.<sup>[42][12]</sup>

### Analog-to-digital signal conversion

Frank Gray, who became famous for inventing the signaling method that came to be used for compatible color television, invented a method to convert analog signals to reflected binary code groups using vacuum tube-based apparatus. Filed in 1947, the method and apparatus were granted a patent in 1953,<sup>[13]</sup> and the name of Gray stuck to the codes. The "PCM tube" apparatus that Gray patented was made by Raymond W. Sears of Bell Labs, working with Gray and William M. Goodall, who credited Gray for the idea of the reflected binary code.<sup>[43]</sup>

**March 17, 1953**

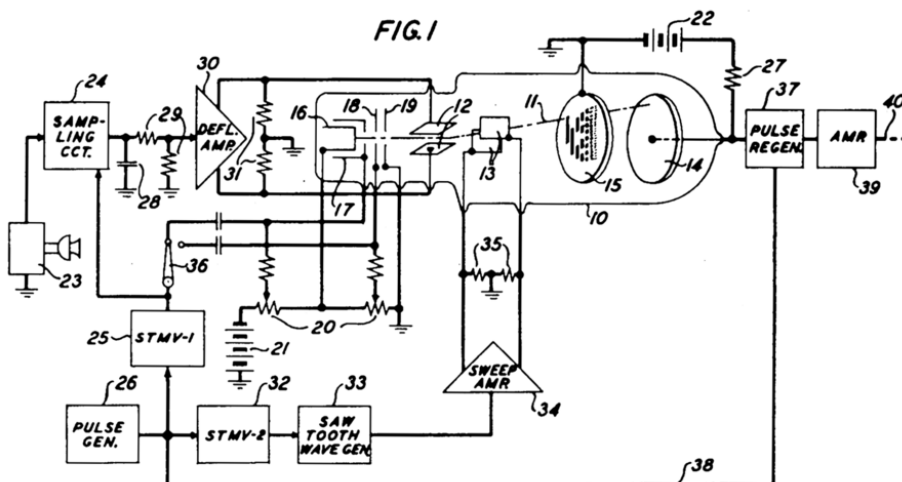
**F. GRAY**

**2,632,058**

PULSE CODE COMMUNICATION

Filed Nov. 13, 1947

4 Sheets-Sheet 1



Part of front page of Gray's patent, showing PCM tube (10) with reflected binary code in plate (15)

Gray was most interested in using the codes to minimize errors in converting analog signals to digital; his codes are still used today for this purpose.

## Position encoders

Gray codes are used in linear and rotary position encoders (absolute encoders and quadrature encoders) in preference to weighted binary encoding. This avoids the possibility that, when multiple bits change in the binary representation of a position, a misread will result from some of the bits changing before others.

For example, some rotary encoders provide a disk which has an electrically conductive Gray code pattern on concentric rings (tracks). Each track has a stationary metal spring contact that provides electrical contact to the conductive code pattern. Together, these contacts produce output signals in the form of a Gray code. Other encoders employ non-contact mechanisms based on optical or magnetic sensors to produce the Gray code output signals.

Regardless of the mechanism or precision of a moving encoder, position measurement error can occur at specific positions (at code boundaries) because the code may be changing at the exact moment it is read (sampled). A binary output code could cause significant position measurement errors because it is impossible to make all bits change at exactly the same time. If, at the moment the position is sampled, some bits have changed and others have not, the sampled position will be incorrect. In the case of absolute encoders, the indicated position may be far away from the actual position and, in the case of incremental encoders, this can corrupt position tracking.

In contrast, the Gray code used by position encoders ensures that the codes for any two consecutive positions will differ by only one bit and, consequently, only one bit can change at a time. In this case, the maximum position error will be small, indicating a position adjacent to the actual position.

## Genetic algorithms

Due to the Hamming distance properties of Gray codes, they are sometimes used in genetic algorithms.<sup>[14]</sup> They are very useful in this field, since mutations in the code allow for mostly incremental changes, but occasionally a single bit-change can cause a big leap and lead to new properties.

## Boolean circuit minimization

Gray codes are also used in labelling the axes of Karnaugh maps since 1953<sup>[44][45][46]</sup> as well as in Händler circle graphs since 1958,<sup>[47][48][49][50]</sup> both graphical methods for logic circuit minimization.

## Error correction

In modern digital communications, Gray codes play an important role in error correction. For example, in a digital modulation scheme such as QAM where data is typically transmitted in symbols of 4 bits or more, the signal's constellation diagram is arranged so that the bit patterns conveyed by adjacent constellation points differ by only one bit. By combining this with forward error correction capable of correcting single-bit errors, it is possible for a receiver to correct any transmission errors that cause a constellation point to deviate into the area of an adjacent point. This makes the transmission system less susceptible to noise.

## Communication between clock domains

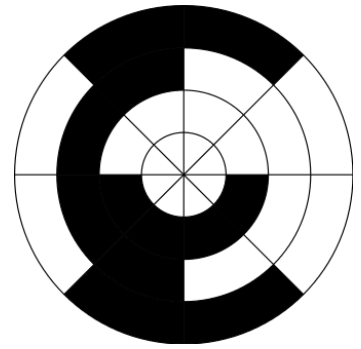
Digital logic designers use Gray codes extensively for passing multi-bit count information between synchronous logic that operates at different clock frequencies. The logic is considered operating in different "clock domains". It is fundamental to the design of large chips that operate with many different clocking frequencies.

## Cycling through states with minimal effort

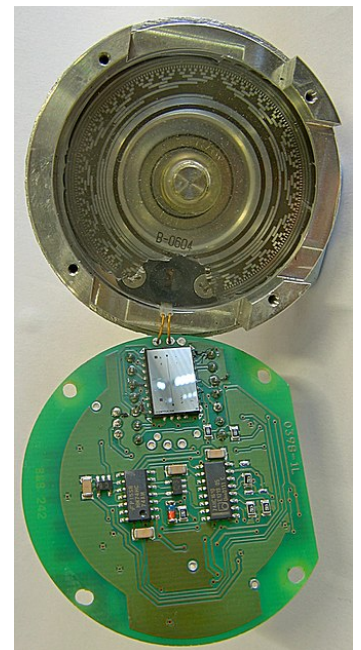
If a system has to cycle through all possible combinations of on-off states of some set of controls, and the changes of the controls require non-trivial expense (e.g. time, wear, human work), a Gray code minimizes the number of setting changes to just one change for each combination of states. An example would be testing a piping system for all combinations of settings of its manually operated valves.

A balanced Gray code can be constructed,<sup>[51]</sup> that flips every bit equally often. Since bit-flips are evenly distributed, this is optimal in the following way: balanced Gray codes minimize the maximal count of bit-flips for each digit.

## Gray code counters and arithmetic



Rotary encoder for angle-measuring devices marked in 3-bit binary-reflected Gray code (BRGC)



A Gray code absolute rotary encoder with 13 tracks. Housing, interrupter disk, and light source are in the top; sensing element and support components are in the bottom.

George R. Stibitz utilized a reflected binary code in a binary pulse counting device in 1941 already.<sup>[10][11][12]</sup>

A typical use of Gray code counters is building a FIFO (first-in, first-out) data buffer that has read and write ports that exist in different clock domains. The input and output counters inside such a dual-port FIFO are often stored using Gray code to prevent invalid transient states from being captured when the count crosses clock domains.<sup>[52]</sup> The updated read and write pointers need to be passed between clock domains when they change, to be able to track FIFO empty and full status in each domain. Each bit of the pointers is sampled non-deterministically for this clock domain transfer. So for each bit, either the old value or the new value is propagated. Therefore, if more than one bit in the multi-bit pointer is changing at the sampling point, a "wrong" binary value (neither new nor old) can be propagated. By guaranteeing only one bit can be changing, Gray codes guarantee that the only possible sampled values are the new or old multi-bit value. Typically Gray codes of power-of-two length are used.

Sometimes digital buses in electronic systems are used to convey quantities that can only increase or decrease by one at a time, for example the output of an event counter which is being passed between clock domains or to a digital-to-analog converter. The advantage of Gray codes in these applications is that differences in the propagation delays of the many wires that represent the bits of the code cannot cause the received value to go through states that are out of the Gray code sequence. This is similar to the advantage of Gray codes in the construction of mechanical encoders, however the source of the Gray code is an electronic counter in this case. The counter itself must count in Gray code, or if the counter runs in binary then the output value from the counter must be reclocked after it has been converted to Gray code, because when a value is converted from binary to Gray code,<sup>[nb 1]</sup> it is possible that differences in the arrival times of the binary data bits into the binary-to-Gray conversion circuit will mean that the code could go briefly through states that are wildly out of sequence. Adding a clocked register after the circuit that converts the count value to Gray code may introduce a clock cycle of latency, so counting directly in Gray code may be advantageous.<sup>[53]</sup>

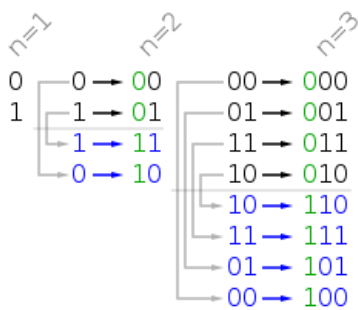
To produce the next count value in a Gray-code counter, it is necessary to have some combinational logic that will increment the current count value that is stored. One way to increment a Gray code number is to convert it into ordinary binary code,<sup>[54]</sup> add one to it with a standard binary adder, and then convert the result back to Gray code.<sup>[55]</sup> Other methods of counting in Gray code are discussed in a report by Robert W. Doran, including taking the output from the first latches of the master-slave flip flops in a binary ripple counter.<sup>[56]</sup>

Gray code addressing

As the execution of program code typically causes an instruction memory access pattern of locally consecutive addresses, bus encodings using Gray code addressing instead of binary addressing can reduce the number of state changes of the address bits significantly, thereby reducing the CPU power consumption in some low-power designs.<sup>[57][58]</sup>

Constructing an *n*-bit Gray code

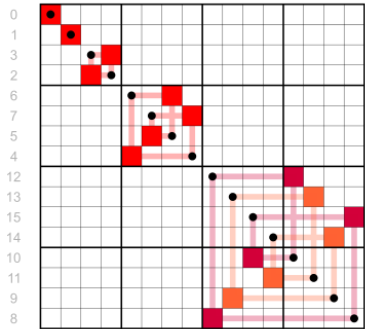
The binary-reflected Gray code list for *n* bits can be generated recursively from the list for *n* − 1 bits by reflecting the list (i.e. listing the entries in reverse order), prefixing the entries in the original list with a binary 0, prefixing the entries in the reflected list with a binary 1, and then concatenating the original list with the reversed list.<sup>[12]</sup> For example, generating the *n* = 3 list from the *n* = 2 list:



The first few steps of the reflect-and-prefix method.

2-bit list: 00, 01, 11, 10  
Reflected: 10, 11, 01, 00  
Prefix old entries with 0: 000, 001, 011, 010,  
Prefix new entries with 1: 110, 111, 101, 100  
Concatenated: 000, 001, 011, 010, 110, 111, 101, 100

The one-bit Gray code is  $G_1 = (0, 1)$ . This can be thought of as built recursively as above from a zero-bit Gray code  $G_0 = (\underline{\hspace{1cm}})$  consisting of a single entry of zero length. This iterative process of generating  $G_{n+1}$  from  $G_n$  makes the following properties of the standard reflecting code clear:



4-bit Gray code permutation

- $G_n$  is a permutation of the numbers 0, ...,  $2^n - 1$ . (Each number appears exactly once in the list.)
- $G_n$  is embedded as the first half of  $G_{n+1}$ .
- Therefore, the coding is *stable*, in the sense that once a binary number appears in  $G_n$  it appears in the same position in all longer lists; so it makes sense to talk about *the* reflective Gray code value of a number:  $G(m)$  = the *m*-th reflecting Gray code, counting from 0.
- Each entry in  $G_n$  differs by only one bit from the previous entry. (The Hamming distance is 1.)
- The last entry in  $G_n$  differs by only one bit from the first entry. (The code is cyclic.)

These characteristics suggest a simple and fast method of translating a binary value into the corresponding Gray code. Each bit is inverted if the next higher bit of the input value is set to one. This can be performed in parallel by a bit-shift and exclusive-or operation if they are available: the  $n$ th Gray code is obtained by computing  $n \oplus \lfloor n/2 \rfloor$ . Prepending a 0 leaves the order of the code words unchanged, prepending a 1 reverses the order of the code words. If the bits at position  $i$  of codewords are inverted, the order of neighbouring blocks of  $2^i$  codewords is reversed. E.g. if bit 0 is inverted in a 3 bit codeword sequence, the order of two neighbouring codewords is reversed

{000,001,010,011,100,101,110,111} → {001,000,011,010,101,100,111,110} (invert bit 0)

If bit 1 is inverted, blocks of 2 codewords change order:

{000,001,010,011,100,101,110,111} → {010,011,000,001,110,111,100,101} (invert bit 1)

If bit 2 is inverted, blocks of 4 codewords reverse order:

{000,001,010,011,100,101,110,111} → {100,101,110,111,000,001,010,011} (invert bit 2)

Thus, ex-oring a bit  $b_i$  at position  $i$  with the bit  $b_{i+1}$  at position  $i + 1$  leaves the order of codewords intact if  $b_{i+1} = 0$ , and reverses the order of blocks of  $2^{i+1}$  codewords if  $b_{i+1} = 1$ . Now, this is exactly the same operation as the reflect-and-prefix method to generate the Gray code.

A similar method can be used to perform the reverse translation, but the computation of each bit depends on the computed value of the next higher bit so it cannot be performed in parallel. Assuming  $g_i$  is the  $i$ th Gray-coded bit ( $g_0$  being the most significant bit), and  $b_i$  is the  $i$ th binary-coded bit ( $b_0$  being the most-significant bit), the reverse translation can be given recursively:  $b_0 = g_0$ , and  $b_i = g_i \oplus b_{i-1}$ . Alternatively, decoding a Gray code into a binary number can be described as a prefix sum of the bits in the Gray code, where each individual summation operation in the prefix sum is performed modulo two.

To construct the binary-reflected Gray code iteratively, at step 0 start with the **code**<sub>0</sub> = 0, and at step  $i > 0$  find the bit position of the least significant 1 in the binary representation of  $i$  and flip the bit at that position in the previous code **code** <sub>$i-1$</sub>  to get the next code **code** <sub>$i$</sub> . The bit positions start 0, 1, 0, 2, 0, 1, 0, 3, ....<sup>[nb 2]</sup> See find first set for efficient algorithms to compute these values.

## Converting to and from Gray code

The following functions in C convert between binary numbers and their associated Gray codes. While it may seem that Gray-to-binary conversion requires each bit to be handled one at a time, faster algorithms exist.<sup>[59][54][nb 1]</sup>

```
typedef unsigned int uint;

// This function converts an unsigned binary number to reflected binary Gray code.
uint BinaryToGray(uint num)
{
    return num ^ (num >> 1); // The operator >> is shift right. The operator ^ is exclusive or.
}

// This function converts a reflected binary Gray code number to a binary number.
uint GrayToBinary(uint num)
{
    uint mask = num;
    while (mask) {
        mask >>= 1; // Each Gray code bit is exclusive-ored with all more significant bits.
        num ^= mask;
    }
    return num;
}

// A more efficient version for Gray codes 32 bits or fewer through the use of SWAR (SIMD within a register) techniques.
// It implements a parallel prefix XOR function. The assignment statements can be in any order.
// This function can be adapted for longer Gray codes by adding steps.

uint GrayToBinary32(uint num)
{
    num ^= num >> 16;
    num ^= num >> 8;
    num ^= num >> 4;
    num ^= num >> 2;
    num ^= num >> 1;
    return num;
}

// A Four-bit-at-once variant changes a binary number (abcd)2 to (abcd)2 ^ (00ab)2, then to (abcd)2 ^ (00ab)2 ^ (0abc)2 ^ (000a)2.
```

## Special types of Gray codes

In practice, "Gray code" almost always refers to a binary-reflected Gray code (BRGC). However, mathematicians have discovered other kinds of Gray codes. Like BRGCs, each consists of a list of words, where each word differs from the next in only one digit (each word has a Hamming distance of 1 from the next word).

### n-ary Gray code



There are many specialized types of Gray codes other than the binary-reflected Gray code. One such type of Gray code is the ***n*-ary Gray code**, also known as a **non-Boolean Gray code**. As the name implies, this type of Gray code uses non-Boolean values in its encodings.

For example, a 3-ary (ternary) Gray code would use the values {0, 1, 2}.<sup>[30]</sup> The *(n, k)*-Gray code is the *n*-ary Gray code with *k* digits.<sup>[60]</sup> The sequence of elements in the (3, 2)-Gray code is: {00, 01, 02, 12, 11, 10, 20, 21, 22}. The *(n, k)*-Gray code may be constructed recursively, as the BRGC, or may be constructed iteratively. An algorithm to iteratively generate the *(N, k)*-Gray code is presented (in C):

```
// inputs: base, digits, value
// output: Gray
// Convert a value to a Gray code with the given base and digits.
// Iterating through a sequence of values would result in a sequence
// of Gray codes in which only one digit changes at a time.
void toGray(unsigned base, unsigned digits, unsigned value, unsigned gray[digits])
{
    unsigned baseN[digits]; // Stores the ordinary base-N number, one digit per entry
    unsigned i;             // The loop variable

    // Put the normal baseN number into the baseN array. For base 10, 109
    // would be stored as [9,0,1]
    for (i = 0; i < digits; i++) {
        baseN[i] = value % base;
        value = value / base;
    }

    // Convert the normal baseN number into the Gray code equivalent. Note that
    // the loop starts at the most significant digit and goes down.
    unsigned shift = 0;
    while (i--) {
        // The Gray digit gets shifted down by the sum of the higher
        // digits.
        gray[i] = (baseN[i] + shift) % base;
        shift = shift + base - gray[i]; // Subtract from base so shift is positive
    }
}

// EXAMPLES
// input: value = 1899, base = 10, digits = 4
// output: baseN[] = [9,9,8,1], gray[] = [0,1,7,1]
// input: value = 1900, base = 10, digits = 4
// output: baseN[] = [0,0,9,1], gray[] = [0,1,8,1]
```

*Ternary number → ternary Gray code*

0	→	000
1	→	001
2	→	002
10	→	012
11	→	011
12	→	010
20	→	020
21	→	021
22	→	022
100	→	122
101	→	121
102	→	120
110	→	110
111	→	111
112	→	112
120	→	102
121	→	101
122	→	100
200	→	200
201	→	201
202	→	202
210	→	212
211	→	211
212	→	210
220	→	220
221	→	221
222	→	222

There are other Gray code algorithms for *(n,k)*-Gray codes. The *(n,k)*-Gray code produced by the above algorithm is always cyclical; some algorithms, such as that by Guan,<sup>[60]</sup> lack this property when *k* is odd. On the other hand, while only one digit at a time changes with this method, it can change by wrapping (looping from *n* − 1 to 0). In Guan's algorithm, the count alternately rises and falls, so that the numeric difference between two Gray code digits is always one.

Gray codes are not uniquely defined, because a permutation of the columns of such a code is a Gray code too. The above procedure produces a code in which the lower the significance of a digit, the more often it changes, making it similar to normal counting methods.

See also Skew binary number system, a variant ternary number system where at most 2 digits change on each increment, as each increment can be done with at most one digit carry operation.

### Balanced Gray code

Although the binary reflected Gray code is useful in many scenarios, it is not optimal in certain cases because of a lack of "uniformity".<sup>[51]</sup> In **balanced Gray codes**, the number of changes in different coordinate positions are as close as possible. To make this more precise, let *G* be an *R*-ary complete Gray cycle having transition sequence (*δ<sub>k</sub>*); the *transition counts* (*spectrum*) of *G* are the collection of integers defined by

$$\lambda_k = |\{j \in \mathbb{Z}_{R^n} : \delta_j = k\}|, \text{ for } k \in \mathbb{Z}_n$$

A Gray code is *uniform* or *uniformly balanced* if its transition counts are all equal, in which case we have  $\lambda_k = R^n/n$  for all *k*. Clearly, when ***R* = 2**, such codes exist only if *n* is a power of 2. Otherwise, if *n* does not divide ***R<sup>n</sup>*** evenly, it is possible to construct *well-balanced* codes where every transition count is either  $\lfloor R^n/n \rfloor$  or  $\lceil R^n/n \rceil$ .<sup>[51]</sup> Gray codes can also be *exponentially balanced* if all of their transition counts are adjacent powers of two, and such codes exist for every power of two.<sup>[61]</sup>

For example, a balanced 4-bit Gray code has 16 transitions, which can be evenly distributed among all four positions (four transitions per position), making it uniformly balanced:<sup>[51]</sup>

0	1	1	1	1	1	0	0	0	0	0	1	1	0
0	0	1	1	1	1	0	0	1	1	1	0	0	0
0	0	0	0	1	1	1	1	0	0	1	1	0	0
0	0	0	1	1	0	0	0	0	1	1	1	1	1

whereas a balanced 5-bit Gray code has a total of 32 transitions, which cannot be evenly distributed among the positions. In this example, four positions have six transitions each, and one has eight:<sup>[51]</sup>

```

1 1 1 1 1 0 0 0 0 1 1 1 1 1 1 0 0 1 1 1 1 1 0 0 0 0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 1 1 1 1 1 1 0 0 0 1 1 0 0 0
1 1 0 0 1 1 1 0 0 0 0 0 0 1 1 1 0 0 0 1 1 1 1 1 1 0 0 0 0 0 1 1
1 0 0 0 0 0 0 0 1 1 1 1 1 1 0 0 0 0 0 0 1 1 1 1 1 1 1 0 0 0 1
1 1 1 1 1 1 0 0 0 0 1 1 0 0 0 0 0 0 0 0 1 1 0 0 0 1 1 1 1 1 1

```

We will now show a construction<sup>[62]</sup> and implementation<sup>[63]</sup> for well-balanced binary Gray codes which allows us to generate an  $n$ -digit balanced Gray code for every  $n$ . The main principle is to inductively construct an  $(n + 2)$ -digit Gray code  $G'$  given an  $n$ -digit Gray code  $G$  in such a way that the balanced property is preserved. To do this, we consider partitions of  $G = g_0, \dots, g_{2^n-1}$  into an even number  $L$  of non-empty blocks of the form

$$\{g_0\}, \{g_1, \dots, g_{k_2}\}, \{g_{k_2+1}, \dots, g_{k_3}\}, \dots, \{g_{k_{L-2}+1}, \dots, g_{-2}\}, \{g_{-1}\}$$

where  $k_1 = 0$ ,  $k_{L-1} = -2$ , and  $k_L = -1 \pmod{2^n}$ . This partition induces an  $(n + 2)$ -digit Gray code given by

$$\begin{aligned}
&00g_0, \\
&00g_1, \dots, 00g_{k_2}, 01g_{k_2}, \dots, 01g_1, 11g_1, \dots, 11g_{k_2}, \\
&11g_{k_2+1}, \dots, 11g_{k_3}, 01g_{k_3}, \dots, 01g_{k_2+1}, 00g_{k_2+1}, \dots, 00g_{k_3}, \dots, \\
&00g_{-2}, 00g_{-1}, 10g_{-1}, 10g_{-2}, \dots, 10g_0, 11g_0, 11g_{-1}, 01g_{-1}, 01g_0
\end{aligned}$$

If we define the *transition multiplicities*  $m_i = |\{j : \delta_{k_j} = i, 1 \leq j \leq L\}|$  to be the number of times the digit in position  $i$  changes between consecutive blocks in a partition, then for the  $(n + 2)$ -digit Gray code induced by this partition the transition spectrum  $\lambda'_i$  is

$$\lambda'_i = \begin{cases} 4\lambda_i - 2m_i, & \text{if } 0 \leq i < n \\ L, & \text{otherwise} \end{cases}$$

The delicate part of this construction is to find an adequate partitioning of a balanced  $n$ -digit Gray code such that the code induced by it remains balanced, but for this only the transition multiplicities matter; joining two consecutive blocks over a digit  $i$  transition and splitting another block at another digit  $i$  transition produces a different Gray code with exactly the same transition spectrum  $\lambda'_i$ , so one may for example<sup>[61]</sup> designate the first  $m_i$  transitions at digit  $i$  as those that fall between two blocks. Uniform codes can be found when  $R \equiv 0 \pmod{4}$  and  $R^n \equiv 0 \pmod{n}$ , and this construction can be extended to the  $R$ -ary case as well.<sup>[62]</sup>

## Long Run Gray codes

Long Run Gray codes maximize the distance between consecutive changes of digits in the same position. That is, the minimum run-length of any bit remains unchanged for as long as possible.

## Monotonic Gray codes

Monotonic codes are useful in the theory of interconnection networks, especially for minimizing dilation for linear arrays of processors.<sup>[64]</sup> If we define the *weight* of a binary string to be the number of 1s in the string, then although we clearly cannot have a Gray code with strictly increasing weight, we may want to approximate this by having the code run through two adjacent weights before reaching the next one.

We can formalize the concept of monotone Gray codes as follows: consider the partition of the hypercube  $Q_n = (V_n, E_n)$  into *levels* of vertices that have equal weight, i.e.

$$V_n(i) = \{v \in V_n : v \text{ has weight } i\}$$

for  $0 \leq i \leq n$ . These levels satisfy  $|V_n(i)| = \binom{n}{i}$ . Let  $Q_n(i)$  be the subgraph of  $Q_n$  induced by  $V_n(i) \cup V_n(i + 1)$ , and let  $E_n(i)$  be the edges in  $Q_n(i)$ . A monotonic Gray code is then a Hamiltonian path in  $Q_n$  such that whenever  $\delta_1 \in E_n(i)$  comes before  $\delta_2 \in E_n(j)$  in the path, then  $i \leq j$ .

An elegant construction of monotonic  $n$ -digit Gray codes for any  $n$  is based on the idea of recursively building subpaths  $P_{n,j}$  of length  $2^{\binom{n}{j}}$  having edges in  $E_n(j)$ .<sup>[64]</sup> We define  $P_{1,0} = (0, 1)$ ,  $P_{n,j} = \emptyset$  whenever  $j < 0$  or  $j \geq n$ , and

$$P_{n+1,j} = 1P_{n,j-1}^{\pi_n}, 0P_{n,j}$$

otherwise. Here,  $\pi_n$  is a suitably defined permutation and  $P^\pi$  refers to the path  $P$  with its coordinates permuted by  $\pi$ . These paths give rise to two monotonic  $n$ -digit Gray codes  $G_n^{(1)}$  and  $G_n^{(2)}$  given by

$$G_n^{(1)} = P_{n,0} P_{n,1}^R P_{n,2} P_{n,3}^R \dots \text{ and } G_n^{(2)} = P_{n,0}^R P_{n,1} P_{n,2}^R P_{n,3} \dots$$



The choice of  $\pi_n$  which ensures that these codes are indeed Gray codes turns out to be  $\pi_n = E^{-1}(\pi_{n-1}^2)$ . The first few values of  $P_{n,j}$  are shown in the table below.

These monotonic Gray codes can be efficiently implemented in such a way that each subsequent element can be generated in  $O(n)$  time. The algorithm is most easily described using [coroutines](#).

Monotonic codes have an interesting connection to the [Lovász conjecture](#), which states that every connected [vertex-transitive graph](#) contains a Hamiltonian path. The "middle-level" subgraph  $Q_{2n+1}(n)$  is [vertex-transitive](#) (that is, its automorphism group is transitive, so that each vertex has the same "local environment" and cannot be differentiated from the others, since we can relabel the coordinates as well as the binary digits to obtain an automorphism) and the problem of finding a Hamiltonian path in this subgraph is called the "middle-levels problem", which can provide insights into the more general conjecture. The question has been answered affirmatively for  $n \leq 15$ , and the preceding construction for monotonic codes ensures a Hamiltonian path of length at least  $0.839N$  where  $N$  is the number of vertices in the middle-level subgraph.<sup>[65]</sup>

### Beckett–Gray code

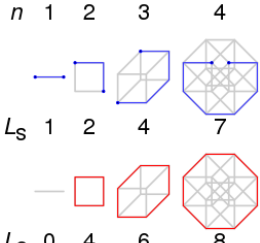
Another type of Gray code, the **Beckett–Gray code**, is named for Irish playwright [Samuel Beckett](#), who was interested in symmetry. His play "Quad" features four actors and is divided into sixteen time periods. Each period ends with one of the four actors entering or leaving the stage. The play begins with an empty stage, and Beckett wanted each subset of actors to appear on stage exactly once.<sup>[66]</sup> Clearly the set of actors currently on stage can be represented by a 4-bit binary Gray code. Beckett, however, placed an additional restriction on the script: he wished the actors to enter and exit so that the actor who had been on stage the longest would always be the one to exit. The actors could then be represented by a first in, first out queue, so that (of the actors onstage) the actor being dequeued is always the one who was enqueued first.<sup>[66]</sup> Beckett was unable to find a Beckett–Gray code for his play, and indeed, an exhaustive listing of all possible sequences reveals that no such code exists for  $n = 4$ . It is known today that such codes do exist for  $n = 2, 5, 6, 7$ , and 8, and do not exist for  $n = 3$  or 4. An example of an 8-bit Beckett–Gray code can be found in [Donald Knuth's Art of Computer Programming](#).<sup>[12]</sup> According to [Sawada and Wong](#), the search space for  $n = 6$  can be explored in 15 hours, and more than 9,500 solutions for the case  $n = 7$  have been found.<sup>[67]</sup>

Subpaths in the Savage–Winkler algorithm

$P_{n,j}$	$j = 0$	$j = 1$	$j = 2$	$j = 3$
$n = 1$	0, 1			
$n = 2$	00, 01	10, 11		
$n = 3$	000, 001	100, 110, 010, 011	101, 111	
$n = 4$	0000, 0001	1000, 1100, 0100, 0110, 0010, 0011	1010, 1011, 1001, 1101, 0101, 0111	1110, 1111

### Snake-in-the-box codes

Snake-in-the-box codes, or *snakes*, are the sequences of nodes of induced paths in an  $n$ -dimensional hypercube graph, and coil-in-the-box codes,<sup>[68]</sup> or *coils*, are the sequences of nodes of induced cycles in a hypercube. Viewed as Gray codes, these sequences have the property of being able to detect any single-bit coding error. Codes of this type were first described by [William H. Kautz](#) in the late 1950s;<sup>[4]</sup> since then, there has been much research on finding the code with the largest possible number of codewords for a given hypercube dimension.



Maximum lengths of snakes ( $L_s$ ) and coils ( $L_c$ ) in the snakes-in-the-box problem for dimensions  $n$  from 1 to 4

### Single-track Gray code

Yet another kind of Gray code is the **single-track Gray code** (STGC) developed by [Norman B. Spedding](#)<sup>[69][70]</sup> and refined by [Hiltgen](#), [Paterson](#) and [Brandestini](#) in "Single-track Gray codes" (1996).<sup>[71][72]</sup> The STGC is a cyclical list of  $P$  unique binary encodings of length  $n$  such that two consecutive words differ in exactly one position, and when the list is examined as a  $P \times n$  matrix, each column is a cyclic shift of the first column.<sup>[73]</sup>

The name comes from their use with [rotary encoders](#), where a number of tracks are being sensed by contacts, resulting for each in an output of 0 or 1. To reduce noise due to different contacts not switching at exactly the same moment in time, one preferably sets up the tracks so that the data output by the contacts are in Gray code. To get high angular accuracy, one needs lots of contacts; in order to achieve at least 1 degree accuracy, one needs at least 360 distinct positions per revolution, which requires a minimum of 9 bits of data, and thus the same number of contacts.

If all contacts are placed at the same angular position, then 9 tracks are needed to get a standard BRGC with at least 1 degree accuracy. However, if the manufacturer moves a contact to a different angular position (but at the same distance from the center shaft), then the corresponding "ring pattern" needs to be rotated the same angle to give the same output. If the most significant bit (the inner ring in [Figure 1](#)) is rotated enough, it exactly matches the next ring out. Since both rings are then identical, the inner ring can be cut out, and the sensor for that ring moved to the remaining, identical ring (but offset at that angle from the other sensor on that ring). Those two sensors on a single ring make a quadrature encoder. That reduces the number of tracks for a "1 degree resolution" angular encoder to 8 tracks. Reducing the number of tracks still further can't be done with BRGC.



Single-track Gray code with 5 sensors.

For many years, Torsten Sillke<sup>[74]</sup> and other mathematicians believed that it was impossible to encode position on a single track such that consecutive positions differed at only a single sensor, except for the 2-sensor, 1-track quadrature encoder. So for applications where 8 tracks were too bulky, people used single-track incremental encoders (quadrature encoders) or 2-track "quadrature encoder + reference notch" encoders.

Norman B. Spedding, however, registered a patent in 1994 with several examples showing that it was possible.<sup>[69]</sup> Although it is not possible to distinguish  $2^n$  positions with  $n$  sensors on a single track, it is possible to distinguish close to that many. Etzion and Paterson conjecture that when  $n$  is itself a power of 2,  $n$  sensors can distinguish at most  $2^n - 2n$  positions and that for prime  $n$  the limit is  $2^n - 2$  positions.<sup>[75]</sup> The authors went on to generate a 504 position single track code of length 9 which they believe is optimal. Since this number is larger than  $2^8 = 256$ , more than 8 sensors are required by any code, although a BRGC could distinguish 512 positions with 9 sensors.

An STGC for  $P = 30$  and  $n = 5$  is reproduced here:

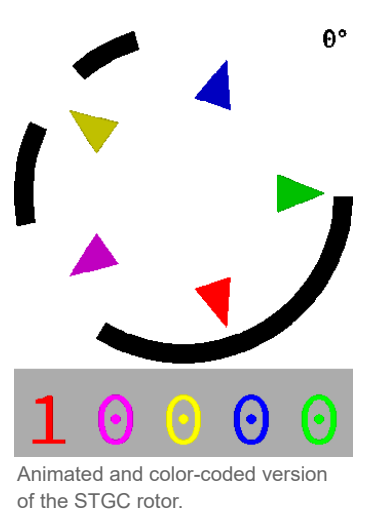
Single-track Gray code for 30 positions									
Angle	Code	Angle	Code	Angle	Code	Angle	Code	Angle	Code
0°	10000	72°	01000	144°	00100	216°	00010	288°	00001
12°	10100	84°	01010	156°	00101	228°	10010	300°	01001
24°	11100	96°	01110	168°	00111	240°	10011	312°	11001
36°	11110	108°	01111	180°	10111	252°	11011	324°	11101
48°	11010	120°	01101	192°	10110	264°	01011	336°	10101
60°	11000	132°	01100	204°	00110	276°	00011	348°	10001

Each column is a cyclic shift of the first column, and from any row to the next row only one bit changes.<sup>[76]</sup> The single-track nature (like a code chain) is useful in the fabrication of these wheels (compared to BRGC), as only one track is needed, thus reducing their cost and size. The Gray code nature is useful (compared to chain codes, also called De Bruijn sequences), as only one sensor will change at any one time, so the uncertainty during a transition between two discrete states will only be plus or minus one unit of angular measurement the device is capable of resolving.<sup>[77]</sup>

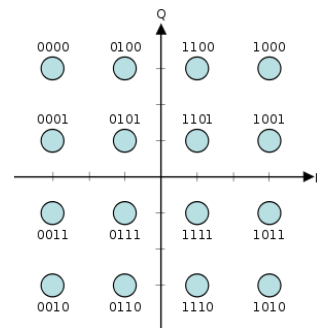
## Two-dimensional Gray code

Two-dimensional Gray codes are used in communication to minimize the number of bit errors in quadrature amplitude modulation (QAM) adjacent points in the constellation. In a typical encoding the horizontal and vertical adjacent constellation points differ by a single bit, and diagonal adjacent points differ by 2 bits.<sup>[78]</sup>

Two-dimensional Gray codes also have uses in location identifications schemes, where the code would be applied to area maps such as a Mercator projection of the earth's surface and an appropriate cyclic two-dimensional distance function such as the Mannheim metric be used to calculate the distance between two encoded locations, thereby combining the characteristics of the Hamming distance with the cyclic continuation of a Mercator projection.<sup>[79]</sup>



Animated and color-coded version of the STGC rotor.



A Gray-coded constellation diagram for rectangular 16-QAM

## Gray isometry

The bijective mapping  $\{ 0 \leftrightarrow 00, 1 \leftrightarrow 01, 2 \leftrightarrow 11, 3 \leftrightarrow 10 \}$  establishes an isometry between the metric space over the finite field  $\mathbb{Z}_2^2$  with the metric given by the Hamming distance and the metric space over the finite ring  $\mathbb{Z}_4$  (the usual modular arithmetic) with the metric given by the Lee distance. The mapping is suitably extended to an isometry of the Hamming spaces  $\mathbb{Z}_2^{2m}$  and  $\mathbb{Z}_4^m$ . Its importance lies in establishing a correspondence between various "good" but not necessarily linear codes as Gray-map images in  $\mathbb{Z}_2^2$  of ring-linear codes from  $\mathbb{Z}_4$ .<sup>[80][81]</sup>

## Related codes

There are a number of binary codes similar to Gray codes, including:

- Datex codes aka Giannini codes (1954), as described by Carl P. Spaulding,<sup>[8][82][83][84][85][7]</sup> use a variant of O'Brien code II.
- Codes used by Varec (ca. 1954),<sup>[86][87][88][89]</sup> use a variant of O'Brien code I as well as base-12 and base-16 Gray code variants.
- Lucal code (1959)<sup>[1][2][56]</sup> aka modified reflected binary code (MRB)<sup>[1][2][nb 3]</sup>
- Gillham code (1961/1962),<sup>[83][90][7][91][92]</sup> uses a variant of Datex code and O'Brien code II.
- Leslie and Russell code (1964)<sup>[93][9][94][90]</sup>
- Royal Radar Establishment code<sup>[90]</sup>

- Hoklas code (1988)<sup>[95][96][97]</sup>

The following binary-coded decimal (BCD) codes are Gray code variants as well:

- Petherick code (1953),<sup>[18][98][99][100][54][96][nb 4]</sup> also known as Royal Aircraft Establishment (RAE) code.<sup>[101]</sup>
- O'Brien codes I and II (1955)<sup>[102][103][104][84][85][96]</sup> (An O'Brien type-I code<sup>[nb 5]</sup> was already described by Frederic A. Foss of IBM<sup>[105][106]</sup> and used by Varec in 1954. Later, it was also known as Watts code or Watts reflected decimal (WRD) code and is sometimes ambiguously referred to as reflected binary modified Gray code.<sup>[107][19][20][108][109][110][111][112][113][nb 1][nb 3]</sup> An O'Brien type-II code was already used by Datex in 1954.<sup>[nb 4]</sup>)
- Excess-3 Gray code (1956)<sup>[114]</sup> (aka Gray excess-3 code,<sup>[84][85][7]</sup> Gray 3-excess code, reflex excess-3 code, excess Gray code,<sup>[96]</sup> Gray excess code, 10-excess-3 Gray code or Gray–Stibitz code), described by Frank P. Turvey Jr. of ITT.<sup>[114]</sup>
- Tompkins codes I and II (1956)<sup>[3][103][104][84][85][96]</sup>
- Glixon code (1957), sometimes ambiguously also called modified Gray code<sup>[115][54][116][117][103][104][84][85][96][nb 3][nb 5]</sup>

5/20/2021

Gray code - Wikipedia

4-bit unit-distance BCD codes<sup>[nb 6]</sup>

Name	Bit	0	1	2	3	4	5	6	7	8	9	Weights <sup>[nb 7]</sup>	Tracks	Compl.	Cyclic	5s	Comment
Gray BCD	4	0	0	0	0	0	0	0	0	1	1	0..3	4 (3 <sup>[nb 8]</sup> )	-	(2, 4, 8, 16)	-	[103][104]
	3	0	0	0	0	1	1	1	1	1	1						
	2	0	0	1	1	1	1	0	0	0	0						
	1	0	1	1	0	0	1	1	0	0	1						
Paul	4	1	0	0	0	0	0	0	0	1	1	1..3	4 (3 <sup>[nb 8]</sup> )	-	2, 10	-	[118]
	3	0	0	0	0	1	1	1	1	1	1						
	2	0	0	1	1	1	1	0	0	0	0						
	1	1	1	1	0	0	1	1	0	0	1						
Glixon	4	0	0	0	0	0	0	0	0	1	1	0..3	4	-	2, 4, 8, 10	(shifted +1)	[115][103][104][116][117][nb 5]
	3	0	0	0	0	1	1	1	1	1	0						
	2	0	0	1	1	1	1	0	0	0	0						
	1	0	1	1	0	0	1	1	0	0	0						
Tompkins I	4	0	0	0	0	0	1	1	1	1	1	0..4	2	-	2, 4, 10	+	[3][103][104]
	3	0	0	0	0	1	1	1	1	1	0						
	2	0	0	1	1	1	1	1	0	0	0						
	1	0	1	1	0	0	0	1	1	0	0						
O'Brien I (Watts)	4	0	0	0	0	0	1	1	1	1	1	0..3	4	g <sup>[96]</sup> [97][nb 9]	2, 4, 10	+	[102][103][104][nb 5]
	3	0	0	0	0	1	1	0	0	0	0						
	2	0	0	1	1	1	1	1	1	0	0						
	1	0	1	1	0	0	0	0	1	1	0						
Petherick (RAE)	4	0	0	0	0	0	1	1	1	1	1	1..3	3	g <sup>[96]</sup> [97][nb 9]	2, 10	+	[18][100][nb 4]
	3	1	0	0	0	1	1	0	0	0	1						
	2	0	0	1	1	1	1	1	1	0	0						
	1	1	1	1	0	0	0	0	1	1	1						
O'Brien II	4	0	0	0	0	0	1	1	1	1	1	1..3	3	g <sup>[84]</sup> [96][97][nb 9]	2, 10	+	[102][103][104][nb 4]
	3	0	0	0	1	1	1	1	0	0	0						
	2	0	1	1	1	0	0	1	1	1	0						
	1	1	1	0	0	0	0	0	0	1	1						
Susskind	4	0	0	0	0	0	1	1	1	1	1	1..4	3	g <sup>[nb 9]</sup>	2, 10	+	[5]
	3	0	0	1	1	1	1	1	1	0	0						
	2	0	1	1	1	0	0	1	1	1	0						
	1	1	1	1	0	0	0	0	1	1	1						
Klar	4	0	0	0	0	0	1	1	1	1	1	0..4	4 (3 <sup>[nb 8]</sup> )	g <sup>[nb 9]</sup>	2, 10	+	[119][120]
	3	0	0	0	1	1	1	1	0	0	0						
	2	0	0	1	1	1	1	1	1	0	0						
	1	0	1	1	1	0	0	1	1	1	0						
Tompkins II	4	0	0	0	0	0	1	1	1	1	1	1..3	2	g <sup>[nb 10]</sup>	2, 10	+	[3][103][104]
	3	0	0	1	1	1	1	1	0	0	0						
	2	1	1	1	0	0	0	0	0	1	1						
	1	0	1	1	1	0	0	1	1	1	0						
Excess-3 Gray	4	0	0	0	0	0	1	1	1	1	1	1..4	4	g <sup>[96]</sup> [97][nb 9]	2, 10	+	[7][96]
	3	0	1	1	1	1	1	1	1	1	0						
	2	1	1	1	0	0	0	0	1	1	1						
	1	0	0	1	1	0	0	1	1	0	0						

## See also

- Linear feedback shift register
- De Bruijn sequence – a Gray code on a larger alphabet than  $\{0,1\}$ .
- Steinhaus–Johnson–Trotter algorithm – an algorithm that generates Gray codes for the factorial number system
- Minimum distance code
- Prouhet–Thue–Morse sequence – related to inverse Gray code
- Ryser formula
- Hilbert curve

## Notes

- By applying a simple *inversion rule*, the Gray code and the O'Brien code I can be translated into the 8421 pure binary code and the 2421 Aiken code, respectively, to ease arithmetic operations.<sup>[C]</sup>
- Sequence 0, 1, 0, 2, 0, 1, 0, 3, ... (sequence A007814 in the OEIS).
- There are several Gray code variants which are called "modified" of some sort: The Glixon code is sometimes called modified Gray code.<sup>[D]</sup> The Lucal code is also called modified reflected binary code (MRB).<sup>[E]</sup> The O'Brien code I or Watts code is sometimes referred to as reflected binary modified Gray code.<sup>[F]</sup>
- By interchanging and inverting three bit rows, the O'Brien code II and the Petherick code can be transferred into each other.
- By swapping two pairs of bit rows, individually shifting four bit rows and inverting one of them, the Glixon code and the O'Brien code I can be transferred into each other.
- Other unit-distance BCD codes include the non-Gray code related 5-bit Libaw–Craig and the 1-2-1 code.
- Depending on a code's target application, the Hamming weights of a code can be important properties beyond coding-theoretical considerations also for physical reasons. Under some circumstances the all-cleared and/or all-set states must be omitted (f.e. to avoid non-conductive or short-circuit conditions), it may be desirable to keep the highest used weight as low as possible (f.e. to reduce power consumption of the reader circuit) or to keep the variance of used weights small (f.e. to reduce acoustic noise or current fluctuations).
- For Gray BCD, Paul and Klar codes, the number of necessary reading tracks can be reduced from 4 to 3 if inversion of one of the middle tracks is acceptable.
- For O'Brien codes I and II and Petherick, Susskind, Klar as well as Excess-3 Gray codes, a 9s complement can be derived by inverting the most-significant (fourth) binary digit.
- For Tompkins code II, a 9s complement can be derived by inverting the first three digits and swapping the two middle binary digits.

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7. *Military Handbook: Encoders – Shaft Angle To Digital* ([http://everyspec.com/MIL-HDBK/MIL-HDBK-0200-0299/download.php?spec=MIL\\_HDBK\\_231A.1809.pdf](http://everyspec.com/MIL-HDBK/MIL-HDBK-0200-0299/download.php?spec=MIL_HDBK_231A.1809.pdf)) (PDF). United States Department of Defense. 1991-09-30. MIL-HDBK-231A. Archived ([https://web.archive.org/web/20200725051128/http://everyspec.com/MIL-HDBK/MIL-HDBK-0200-0299/download.php?spec=MIL\\_HDBK\\_231A.1809.pdf](https://web.archive.org/web/20200725051128/http://everyspec.com/MIL-HDBK/MIL-HDBK-0200-0299/download.php?spec=MIL_HDBK_231A.1809.pdf)) (PDF) from the original on 2020-07-25. Retrieved 2020-07-25. (NB. Supersedes MIL-HDBK-231(AS) (1970-07-01).)
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10. Stibitz, George Robert (1943-01-12) [1941-11-26]. "Binary counter" (<https://patents.google.com/patent/US2307868?q=US2307868>). New York, USA: Bell Telephone Laboratories, Incorporated. U.S. Patent 2,307,868 (<https://patents.google.com/patent/US2307868>). Serial No. 420537. Retrieved 2020-05-24. p. 2, right column, rows 43–73: "[...] A clearer idea of the position of the balls after each pulse will be obtained if the set of balls is represented by a number having a similar number of digits, each of which may have one of two arbitrary values, for example 0 and 1. If the upper position is called 0 and the lower position [...] 1, then the setting of the counter [...] may be read from left to right as 0,100,000. [...] Following is a translation of the number of pulses received into this form of binary notation for the first sixteen pulses as received on the first five balls [...] Pulse number [...] Binary notation [...] [1] (<https://web.archive.org/web/20201217181617/https://patentimages.storage.googleapis.com/51/a5/54/f2f6faf23da3fb/US2307868.pdf>) (4 pages)
11. Winder, C. Farrell (October 1959). "Shaft Angle Encoders Afford High Accuracy" (<https://web.archive.org/web/20200928132232/https://worldradiohistory.com/Archive-Tele-Tech/50s/Electronic-Industries-1959-10.pdf>) (PDF). *Electronic Industries*. Chilton Company. 18 (10): 76–80. Archived from the original (<https://worldradiohistory.com/Archive-Tele-Tech/50s/Electronic-Industries-1959-10.pdf>) (PDF) on 2020-09-28. Retrieved 2018-01-14. p. 78: "[...] The type of code wheel most popular in optical encoders contains a cyclic binary code pattern designed to give a cyclic sequence of "on-off" outputs. The cyclic binary code is also known as the cyclic progression code, the reflected binary code, and the Gray code. This code was originated by G. R. Stibitz, of Bell Telephone Laboratories, and was first proposed for pulse-code modulation systems by Frank Gray, also of BTL. Thus the name Gray code. The Gray or cyclic code is used mainly to eliminate the possibility of errors at code transition which could result in gross ambiguities. [...]"
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17. Domeshek, Sol; Reiner, Stewart (1958-06-24) [1954-01-08]. *Automatic Rectification System* (<https://patentimages.storage.googleapis.com/9d/bf/65/e676a661e1217e/US2839974.pdf>) (PDF). US Secretary of the Navy. U.S. Patent 2,839,974 (<https://patents.google.com/patent/US2839974>). Serial No. 403085. Archived (<https://web.archive.org/web/20200805100327/https://patentimages.storage.googleapis.com/9d/bf/65/e676a661e1217e/US2839974.pdf>) (PDF) from the original on 2020-08-05. Retrieved 2020-08-05. (8 pages)
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24. Edwards, Anthony William Fairbank (2004). *Cogwheels of the Mind: The Story of Venn Diagrams* ([https://books.google.com/books?id=7\\_0Thy4V3JIC&pg=PA65](https://books.google.com/books?id=7_0Thy4V3JIC&pg=PA65)). Baltimore, Maryland, USA: Johns Hopkins University Press. pp. 48, 50. ISBN 0-8018-7434-3. ISBN 978-0-8018-7434-5.
25. Gros, Luc-Agathon-Louis (1872). *Théorie du baguénodier par un clerc de notaire lyonnais* (<https://books.google.com/books?id=EcoBJRekd-sC&pg=PP1>) (in French) (1 ed.). Lyon, France: Aimé Vingtrinier. Archived (<http://archive.wikiwix.com/cache/?url=http%3A%2F%2Fbooks.google.fr%2Fbooks%3Fid%3DEcoBJRekd-sC%26pg%3DPP1>) from the original on 2020-12-17. Retrieved 2020-12-17. [2] ([https://web.archive.org/web/20201217202507/https://books.googleusercontent.com/books/content?req=AKW5Qacg5gq7SW9L1sUUqK7LQ0yJLqCu90GFZZYzch7dsoifr-n9hxiB30SJ1mXq3FhDejHQ7fXY2ZdzlhFywe8pQGNTgMHjX0ANYxRohedbG1FmoPTuKibswKOO7qS2X4MUwQP0dBn-vt3dfTIBFRvTBOVoZZA1ROBXTGTMybnA4gGndl8v0qlAeKsRNUuEddqabMqMngisr8fp-iNt7NMFfwq\\_tPk0we0yXNJWj74AFsFr1JGOIAmdQ6B\\_OJVTOj33lhoYybhf8LMzfpaHusXsY2BWT2ZwVQuIW0mgBaem9xvRZ58TSw](https://web.archive.org/web/20201217202507/https://books.googleusercontent.com/books/content?req=AKW5Qacg5gq7SW9L1sUUqK7LQ0yJLqCu90GFZZYzch7dsoifr-n9hxiB30SJ1mXq3FhDejHQ7fXY2ZdzlhFywe8pQGNTgMHjX0ANYxRohedbG1FmoPTuKibswKOO7qS2X4MUwQP0dBn-vt3dfTIBFRvTBOVoZZA1ROBXTGTMybnA4gGndl8v0qlAeKsRNUuEddqabMqMngisr8fp-iNt7NMFfwq_tPk0we0yXNJWj74AFsFr1JGOIAmdQ6B_OJVTOj33lhoYybhf8LMzfpaHusXsY2BWT2ZwVQuIW0mgBaem9xvRZ58TSw)) (2+16+4 pages and 4 pages foldout) (NB. This booklet was published anonymously, but is known to have been authored by Louis Gros.)
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33. Butrica, Andrew J. (1991-06-21). "Baudot, Jean Maurice Emile". In Froehlich, Fritz E.; Kent, Allen; Hall, Carolyn M. (eds.). *The Froehlich/Kent Encyclopedia of Telecommunications: Volume 2 - Batteries to Codes-Telecommunications* ([https://books.google.com/books?id=I3Rn\\_VefKaoC&pg=PA31&lpg=PA32](https://books.google.com/books?id=I3Rn_VefKaoC&pg=PA31&lpg=PA32)). 2. Marcel Dekker Inc. / CRC Press. pp. 31–34. ISBN 0-8247-2901-3. LCCN 90-3966 (<https://lcn.loc.gov/90-3966>). ISBN 978-0-8247-2901-1. Retrieved 2020-12-20. p. 31: "[...] A Baudot prototype (4 years in the making) was built in 1876. The transmitter had 5 keys similar to those of a piano. Messages were sent in a special 5-element code devised by Baudot [...]"
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## External links

- "Gray Code" demonstration (<http://demonstrations.wolfram.com/BinaryGrayCode/>) by Michael Schreiber, Wolfram Demonstrations Project (with Mathematica implementation). 2007.
- NIST Dictionary of Algorithms and Data Structures: Gray code (<https://xlinux.nist.gov/dads/HTML/graycode.html>).
- Hitch Hiker's Guide to Evolutionary Computation, Q21: What are Gray codes, and why are they used? (<https://web.archive.org/web/20151026021510/http://www.aip.de/~ast/EvolCompFAQ/Q21.htm>), including C code to convert between binary and BRGC.
- Dragos A. Harabor uses Gray codes in a 3D digitizer (<https://web.archive.org/web/20151122120754/http://www.ugcs.caltech.edu/~dragos/3DP/coord.html>).
- Single-track gray codes, binary chain codes (Lancaster 1994 (<http://tinaja.com/text/chain01.html>)), and linear feedback shift registers are all useful in finding one's absolute position on a single-track rotary encoder (or other position sensor).
- AMS Column: Gray codes (<https://www.ams.org/featurecolumn/archive/gray.html>)
- Optical Encoder Wheel Generator (<http://www.bushytails.net/~randyg/encoder/encoderwheel.html>)

- [ProtoTalk.net – Understanding Quadrature Encoding \(https://web.archive.org/web/20110724021700/http://prototalk.net/forums/s/howthread.php?t=78\)](https://web.archive.org/web/20110724021700/http://prototalk.net/forums/s/howthread.php?t=78) – Covers quadrature encoding in more detail with a focus on robotic applications

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