

SMOOTH DIAGNOSTIC EXPECTATIONS

BIANCHI, ILUT, AND SAIJO

Discussant: Sanjay R. Singh

FRBSF & UC Davis

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INTRODUCTION

- ▶ Growing interest in psychological foundations for belief formation in Economics.
- ▶ Diagnostic Expectations (DE): Overreaction driven by the representativeness heuristic.
- ▶ Smooth DE: A new paradigm linking representativeness and uncertainty in dynamic models.

NOVEL CONTRIBUTIONS

- ▶ High-uncertainty environments amplify overreaction.
- ▶ Smooth DE bridges Diagnostic Expectations and Uncertainty literatures.
- ▶ Comprehensive explanation of survey data patterns.

KEY CONCEPTS

- ▶ Representativeness heuristic: Selective memory recalls events that are representative of current news.
- ▶ Smooth DE:
 - ▶ Overreaction depends on uncertainty.
 - ▶ Joint foundation for survey evidence and business cycle properties.

EMPIRICAL EVIDENCE

- ▶ Survey forecasts show:
 - ▶ Overreaction to news.
 - ▶ Stronger overreaction at longer horizons.
 - ▶ Overconfidence in subjective uncertainty.
- ▶ Novel finding: Overreaction amplifies under high uncertainty.

THEORETICAL FRAMEWORK

- ▶ Smooth DE connects belief distortions with time-series dynamics.
- ▶ Business cycle implications:
 - ▶ Asymmetric cycles: Recessions sharper than expansions.
 - ▶ Countercyclical volatility at micro and macro levels.
- ▶ Policy insights: Reducing idiosyncratic uncertainty stabilizes macroeconomy.

COMPARISON: SMOOTH DE vs. STANDARD DE

- ▶ Standard DE

(Bordalo, Gennaioli, and Shleifer, 2018; Bianchi, Ilut, and Saijo, 2024; L'Huillier, Singh, and Yoo, 2024):

- ▶ Captures overreaction but lacks flexibility.
- ▶ Ignores interaction with uncertainty.

- ▶ Smooth DE:

- ▶ Explains overconfidence.
- ▶ Adapts dynamically to uncertainty levels.

KEY EQUATIONS AND COROLLARY

Key Equations:

$$R_{t+h|t,t-J} = \frac{\sigma_{t+h|t}^2}{\sigma_{t+h|t-J}^2} \quad (11)$$

$$E_t^\theta(x_{t+h}) = \mu_{t+h|t} + \underbrace{\theta \frac{R_{t+h|t,t-J}}{1 + \theta(1 - R_{t+h|t,t-J})}}_{\equiv \tilde{\theta}_t} (\mu_{t+h|t} - \mu_{t+h|t-J}) \quad (12)$$

$$V_t^\theta(x_{t+h}) = \frac{\sigma_{t+h|t}^2}{1 + \theta(1 - R_{t+h|t,t-J})} \quad (13)$$

Corollary 1 (Condensed):

- ▶ Overreaction increases with relative uncertainty: $\frac{\partial \tilde{\theta}_t}{\partial R_{t+h|t,t-J}} > 0$.
- ▶ Overconfidence when $R_{t+h|t,t-J} < 1$.
- ▶ Underconfidence when $R_{t+h|t,t-J} > 1$.

AR(1) PROCESS: KEY INSIGHTS

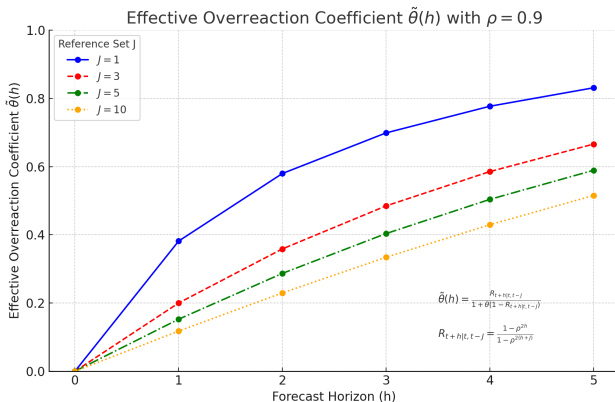
- ▶ Smooth DE applied to an AR(1) process: $x_{t+1} = \rho x_t + \epsilon_{t+1}$.
- ▶ Effective overreaction ($\tilde{\theta}_t$) depends on the ratio of conditional variances:

$$R_{t+h|t,t-J} = \frac{1 - \rho^{2h}}{1 - \rho^{2(h+J)}}.$$

- ▶ Predictions:
 - ▶ Overreaction increases with forecast horizon h .
 - ▶ Subjective overconfidence ($V_t^\theta < V_t$) typical in stationary settings.
 - ▶ Explains survey findings: stronger overreaction for long-term forecasts.

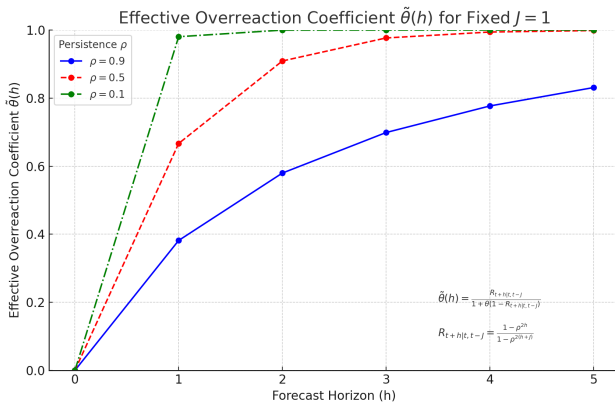
$R_{t+h|t,t-J}$ AS A FUNCTION OF J AND h

- Vary J (e.g., $J = 1, 3, 5, 10$).
- Fix $\rho = 0.9$ and compute $\tilde{\theta}_t^{h,J}$.



$R_{t+h|t,t-J}$ AS A FUNCTION OF ρ AND h

- Fixed $J = 1$.
- Vary ρ across $[0.1, 0.9]$ and compute $\tilde{\theta}_t^{h,J}$.



SIGN OF $\frac{\partial R}{\partial \rho}$ FOR $h = 1$

- ▶ For $J = 1$:
 - ▶ $\frac{\partial R}{\partial \rho} < 0$: R decreases with ρ .
 - ▶ Sensitivity decreases at higher ρ values.
- ▶ For $J = 2$:
 - ▶ $\frac{\partial R}{\partial \rho} < 0$: R continues to decrease with ρ .
 - ▶ Negative derivative becomes more pronounced for small ρ .
- ▶ For $J = 3$ and $J = 4$:
 - ▶ $\frac{\partial R}{\partial \rho} < 0$: Similar trends observed.
 - ▶ Higher J values amplify the rate of decrease.
- ▶ Implication: For small horizons h , R is consistently decreasing in ρ across all J .

effective overreaction is decreasing in ρ

CONCLUSION

- ▶ Smooth DE provides a unified framework for overreaction and overconfidence.
- ▶ Empirical evidence supports uncertainty-dependent overreaction.
- ▶ Implications for macroeconomic modeling and policy design.

Overall:

- ▶ Very rich paper with lot of applications
- ▶ Quibble: I want more on each of the applications.

DERIVATION OF CONDITIONAL VARIANCE

- ▶ Starting from the AR(1) process: $x_{t+1} = \rho x_t + \epsilon_{t+1}$.
- ▶ Conditional variance of x_{t+h} at t :

$$\sigma_{t+h|t}^2 = \sigma_\epsilon^2 \sum_{i=0}^{h-1} \rho^{2i} = \sigma_\epsilon^2 \frac{1 - \rho^{2h}}{1 - \rho^2}.$$

- ▶ Conditional variance at reference set horizon J :

$$\sigma_{t+h|t-J}^2 = \sigma_\epsilon^2 \frac{1 - \rho^{2(h+J)}}{1 - \rho^2}.$$

- ▶ Ratio of conditional variances:

$$R_{t+h|t,t-J} = \frac{\sigma_{t+h|t}^2}{\sigma_{t+h|t-J}^2} = \frac{1 - \rho^{2h}}{1 - \rho^{2(h+J)}}.$$

CONDITIONAL VARIANCE DYNAMICS

- ▶ Why conditional variance changes with horizon:
 - ▶ Persistence of shocks: Influence decays with $|\rho| < 1$.
 - ▶ Cumulative uncertainty: Accumulates over longer horizons.
 - ▶ Stationarity: Variance stabilizes as $h \rightarrow \infty$.
- ▶ $R_{t+h|t,t-J}$ encapsulates how uncertainty varies with horizon and reference set.