

# Sanjeev Kumar

Email: [sanjeevksh42@gmail.com](mailto:sanjeevksh42@gmail.com)  
Linkedin: <https://linkedin.com/in/sanjeevk42>

Phone: +49 17631702520  
Address: Peter-Paul-Althaus Str. 15  
Munich 80805

## Education

<b>Munich, Germany</b>	<b>Technical University of Munich</b>	<b>Oct 2015 – March 2018</b>
<ul style="list-style-type: none"><li>• M.Sc. in Informatics (Specialization: Computer Vision and Machine Learning)</li><li>• Inter-disciplinary Project: Cell Detection in Lens-free Microscopy Videos (published in <b>MICCAI'17</b>)</li><li>• Coursework: Machine Learning; Multiple View Geometry; Deep Learning; Vision Based Navigation.</li></ul>		
<b>Hamirpur, India</b>	<b>National Institute of Technology</b>	<b>July 2008 – May 2012</b>
<ul style="list-style-type: none"><li>• B.Tech. in Computer Science and Engineering</li><li>• Coursework: Object Oriented Programming; Data Structure and Algorithms; Theory of Computation; Operating System; Computer Networks.</li></ul>		

## Professional Experience

<b>Machine Learning Engineer</b>	<b>Lyft Level 5, Self-Driving Division, Munich</b>	<b>Aug 2018 – Present</b>
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**Technologies Used:** Python, C++, PyTorch, OpenCV

### Semantic Map Generator

- Primary contributor and owner of the component that generates the HD semantic map required for on car perception, prediction and planning.
- Implemented different geo spatial algorithms and ML pipelines to speed the map creation with human annotators in the loop.

### Traffic Light Placement

- Implemented a 3D placement algorithm for detecting and localizing traffic lights in point clouds.
- Integrated the automatic traffic light placement pipeline with Semantic Map Generator and QC tools for validation/correction by human curators.

### Road Map Element Detection

- Implemented an annotation pipeline for creating ground truth datasets to extract geometries for different types of road elements (lanes, crosswalks, arrows, etc.).
- Led the implementation of semantic segmentation model training and shape extraction pipeline on the top down views created from projected camera images.
- Mentored an intern to integrate different road element models in QC tools and Semantic Map Generator.

### LiDAR Point Cloud Annotation

- Designed and implemented a 3D detector (PointRCNN) and tracker (Kalman filter-based) pipeline to pre-populate object tracks to speed up the annotation of dynamic agents (cars, pedestrians, etc.) in LiDAR point clouds.
- Worked closely with the teams in Palo Alto to integrate the tracker pipeline in the UI tool for point cloud annotation.

<b>Machine Learning Engineer*</b>	<b>Terraloupe GmbH, Munich</b>	<b>Aug 2016 - April 2017</b>
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**Technologies Used:** Python, Keras, OpenCV

- Experimented with various deep convolutional network architectures (PSPNet, UNet etc.) for semantic segmentation of roof objects attributes (solar panel, chimney etc.) from aerial images.
- Implemented geo spatial algorithms that used segmentation output and point clouds to extract the available roof area for installing solar panels across different German cities.

<b>Software Engineer</b>	<b>Amazon, India</b>	<b>Oct 2014 – Oct 2015</b>
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**Technologies Used:** Java, RDS, DynamoDB, Herd (Workflow-orchestration Engine)

- Optimized the seller data ingestion pipeline by detecting duplicate offers in daily XML feed.
- Built a system that automatically sends notifications (SMS, email) to sellers for older offers on jungle.com and implemented the deletion workflow that could be triggered via one-click or a missed call.

<b>Software Engineer</b>	<b>Drishiti Soft Solutions, India</b>	<b>June 2012 – Oct 2014</b>
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**Technologies Used:** Java, JAX-RS, Postgres

- Led the design and implementation of REST API for the core call center functionality (queuing calls, allocating agents etc.). Worked closely with CRM providers for integrating the API.
- Implemented a real-time monitoring system for analyzing the call volume and SLA in a call center.

\*Part-time