## **HumanActivityRecognition**

This project is to build a model that predicts the human activities such as Walking\_Upstairs, Walking\_Downstairs, Sitting, Standing or Laying.

This dataset is collected from 30 persons(referred as subjects in this dataset), performing different activities with a smartphone to their waists. The data is recorded with the help of sensors (accelerometer and Gyroscope) in that smartphone. This experiment was video recorded to label the data manually.

## How data was recorded

By using the sensors(Gyroscope and accelerometer) in a smartphone, they have captured '3-axial linear acceleration'(*tAcc-XYZ*) from accelerometer and '3-axial angular velocity' (*tGyro-XYZ*) from Gyroscope with several variations.

prefix 't' in those metrics denotes time.

suffix 'XYZ' represents 3-axial signals in X, Y, and Z directions.

#### **Feature names**

- 1. These sensor signals are preprocessed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.
- 2. From Each window, a feature vector was obtianed by calculating variables from the time and frequency domain.

In our dataset, each datapoint represents a window with different readings

- 3. The acceleration signal was saperated into Body and Gravity acceleration signals(*tBodyAcc-XYZ* and *tGravityAcc-XYZ*) using some low pass filter with corner frequecy of 0.3Hz.
- After that, the body linear acceleration and angular velocity were derived in time to obtian jerk signals (tBodyAccJerk-XYZ and tBodyGyroJerk-XYZ).
- 5. The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. This magnitudes are represented as features with names like tBodyAccMag, tGravityAccMag, tBodyAccJerkMag, tBodyGyroMag and tBodyGyroJerkMag.
- Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform).
   These signals obtained were labeled with prefix 'f' just like original signals with prefix 't'. These signals are labeled as fBodyAcc-XYZ, fBodyGyroMag etc.,.
- 7. These are the signals that we got so far.
  - tBodyAcc-XYZ
  - tGravityAcc-XYZ
  - tBodyAccJerk-XYZ
  - tBodyGyro-XYZ
  - tBodyGyroJerk-XYZ
  - tBodyAccMag
  - tGravityAccMag
  - tBodyAccJerkMag
  - tBodyGyroMag
  - tBodyGyroJerkMag
  - fBodyAcc-XYZ
  - fBodyAccJerk-XYZ
  - fBodyGyro-XYZ
  - fBodyAccMag
  - fBodyAccJerkMag
  - fBodyGyroMag
  - fBodyGyroJerkMag
- 8. We can esitmate some set of variables from the above signals. ie., We will estimate the following properties on each and every signal that we recoreded so far.
  - mean(): Mean value
  - std(): Standard deviation
  - mad(): Median absolute deviation
  - may/h I areast value in array

- max(): Largest value in array
- min(): Smallest value in array
- sma(): Signal magnitude area
- energy(): Energy measure. Sum of the squares divided by the number of values.
- iqr(): Interquartile range
- entropy(): Signal entropy
- arCoeff(): Autorregresion coefficients with Burg order equal to 4
- correlation(): correlation coefficient between two signals
- maxinds(): index of the frequency component with largest magnitude
- meanFreq(): Weighted average of the frequency components to obtain a mean frequency
- skewness(): skewness of the frequency domain signal
- kurtosis(): kurtosis of the frequency domain signal
- bandsEnergy(): Energy of a frequency interval within the 64 bins of the FFT of each window.
- angle(): Angle between to vectors.
- 9. We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the angle() variable'
  - gravityMean
  - tBodyAccMean
  - tBodyAccJerkMean
  - tBodyGyroMean
  - tBodyGyroJerkMean

## Y\_Labels(Encoded)

- In the dataset, Y labels are represented as numbers from 1 to 6 as their identifiers.
  - WALKING as 1
  - WALKING UPSTAIRS as 2
  - WALKING DOWNSTAIRS as 3
  - SITTING as 4
  - STANDING as 5
  - LAYING as 6

## Train and test data were saperated

 The readings from 70% of the volunteers were taken as trianing data and remaining 30% subjects recordings were taken for test data

#### Data

- All the data is present in 'UCI HAR dataset/' folder in present working directory.
  - Feature names are present in 'UCI HAR dataset/features.txt'
  - Train Data
    - 'UCI\_HAR\_dataset/train/X\_train.txt'
    - 'UCI HAR dataset/train/subject train.txt'
    - 'UCI\_HAR\_dataset/train/y\_train.txt'
  - Test Data
    - 'UCI HAR dataset/test/X test.txt'
    - 'UCI\_HAR\_dataset/test/subject\_test.txt'
    - 'UCI\_HAR\_dataset/test/y\_test.txt'

#### Data Size:

27 MB

## Quick overview of the dataset :

Accelerometer and Gyroscope readings are taken from 30 volunteers(referred as subjects) while performing the following 6
Activities.

. ....

- 1. Walking
- 2. WalkingUpstairs
- 3. WalkingDownstairs
- 4. Standing
- 5. Sitting
- Lying.
- Readings are divided into a window of 2.56 seconds with 50% overlapping.
- Accelerometer readings are divided into gravity acceleration and body acceleration readings, which has x,y and z components
  each
- Gyroscope readings are the measure of angular velocities which has x,y and z components.
- · Jerk signals are calculated for BodyAcceleration readings.
- Fourier Transforms are made on the above time readings to obtain frequency readings.
- Now, on all the base signal readings., mean, max, mad, sma, arcoefficient, engerybands, entropy etc., are calculated for each window.
- We get a feature vector of 561 features and these features are given in the dataset.
- · Each window of readings is a datapoint of 561 features.

## **Problem Framework**

- 30 subjects(volunteers) data is randomly split to 70%(21) test and 30%(7) train data.
- · Each datapoint corresponds one of the 6 Activities.

## **Problem Statement**

· Given a new datapoint we have to predict the Activity

```
In [1]:
```

```
import numpy as np
import pandas as pd

# get the features from the file features.txt
features = list()
with open('features.txt') as f:
    features = [line.split()[1] for line in f.readlines()]
print('No of Features: {}'.format(len(features)))
```

No of Features: 561

## Obtain the train data

```
In [2]:
```

```
import os
if not os.path.exists('train.csv'):
    # get the data from txt files to pandas dataffame
   X_train = pd.read_csv('X_train.txt', delim_whitespace=True, header=None, names=features)
    # add subject column to the dataframe
    X_train['subject'] = pd.read_csv('subject_train.txt', header=None, squeeze=True)
    y train = pd.read csv('y train.txt', names=['Activity'], squeeze=True)
    y_train_labels = y_train.map({1: 'WALKING', 2:'WALKING_UPSTAIRS',3:'WALKING_DOWNSTAIRS',\
                           4:'SITTING', 5:'STANDING', 6:'LAYING'})
    # put all columns in a single dataframe
    train = X train
    train['Activity'] = y_train
    train['ActivityName'] = y_train_labels
    train.sample()
    train.to_csv('train.csv', index=False, header=True)
   print('File has created.')
```

```
train = pd.read_csv('train.csv')
    print('Data is loaded.')
Data is loaded.
In [3]:
train.shape
Out[3]:
(7352, 564)
In [4]:
train.head()
Out[4]:
   tBodyAccmeanX tBodyAccmeanY tBodyAccmeanZ tBodyAccstdX tBodyAccstdY tBodyAccstdZ tBodyAccmadX tBodyAccmadY t
         0.288585
                        -0.020294
                                      -0.132905
                                                   -0.995279
                                                                -0.983111
                                                                             -0.913526
                                                                                           -0.995112
                                                                                                         -0.983185
```

5 rows × 564 columns

-0.998245

-0.995380

-0.996091

-0.998139

-0.975300

-0.967187

-0.983403

-0.980817

-0.123520

-0.113462

-0.123283

-0.115362

-0.998807

-0.996520

-0.997099

-0.998321

-0.974914

-0.963668

-0.982750

-0.979672

-0.960322

-0.978944

-0.990675

-0.990482

## Obtain the test data

0.278419

0.279653

0.279174

0.276629

-0.016411

-0.019467

-0.026201

-0.016570

```
In [5]:
```

1

2

3

```
import os
if not os.path.exists('test.csv'):
    # get the data from txt files to pandas dataffame
   X test = pd.read csv('X test.txt', delim whitespace=True, header=None, names=features)
    # add subject column to the dataframe
   X test['subject'] = pd.read csv('subject test.txt', header=None, squeeze=True)
    # get y labels from the txt file
    y_test = pd.read_csv('y_test.txt', names=['Activity'], squeeze=True)
    y_test_labels = y_test.map({1: 'WALKING', 2:'WALKING_UPSTAIRS',3:'WALKING_DOWNSTAIRS',\
                          4:'SITTING', 5:'STANDING', 6:'LAYING'})
    # put all columns in a single dataframe
    test = X_test
    test['Activity'] = y_test
    test['ActivityName'] = y_test_labels
    test.to_csv('test.csv',index=False,header=True)
   test = pd.read csv('test.csv')
print('Done.')
```

Done.

```
In [6]:
```

```
test.shape
Out[6]:
(2947, 564)
```

## **Data Cleaning**

## 1. Check for Duplicates

```
In [7]:

print('No of duplicates in train: {}'.format(sum(train.duplicated())))
print('No of duplicates in test : {}'.format(sum(test.duplicated())))

No of duplicates in train: 0
No of duplicates in test : 0
```

## 2. Checking for NaN/null values

```
In [8]:

print('We have {} NaN/Null values in train'.format(train.isnull().values.sum()))
print('We have {} NaN/Null values in test'.format(test.isnull().values.sum()))

We have 0 NaN/Null values in train
We have 0 NaN/Null values in test

In []:
```

## 3. Check for data imbalance

```
In [9]:
```

```
import matplotlib.pyplot as plt
import seaborn as sns

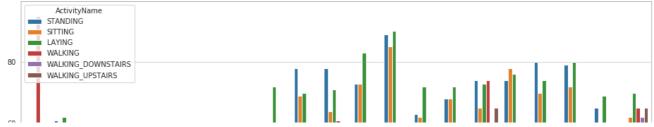
sns.set_style('whitegrid')
plt.rcParams['font.family'] = 'Dejavu Sans'

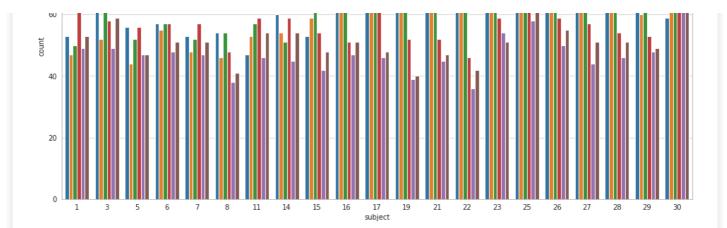
C:\Users\sanjeev\Anaconda3\lib\site-packages\statsmodels\tools\_testing.py:19: FutureWarning:
pandas.util.testing is deprecated. Use the functions in the public API at pandas.testing instead.
   import pandas.util.testing as tm
```

```
In [10]:
```

```
plt.figure(figsize=(16,8))
plt.title('Data provided by each user', fontsize=20)
sns.countplot(x='subject',hue='ActivityName', data = train)
plt.show()
```

Data provided by each user

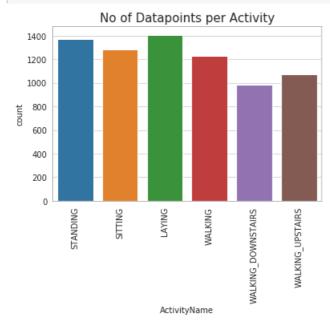




We have got almost same number of reading from all the subjects

#### In [11]:

```
plt.title('No of Datapoints per Activity', fontsize=15)
sns.countplot(train.ActivityName)
plt.xticks(rotation=90)
plt.show()
```



## Observation

Our data is well balanced (almost)

## 4. Changing feature names

## In [12]:

```
columns = train.columns

# Removing '()' from column names
columns = columns.str.replace('[()]','')
columns = columns.str.replace('[-]', '')
columns = columns.str.replace('[,]','')

train.columns = columns
test.columns = columns
```

## 5. Save this dataframe in a csy files

```
In [13]:
```

```
train.to_csv('train.csv', index=False)
test.to_csv('test.csv', index=False)
```

## **Exploratory Data Analysis**

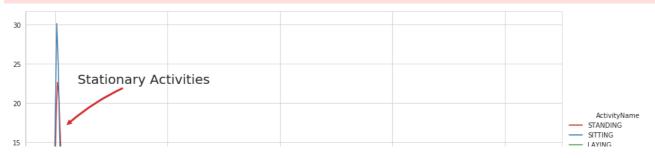
"Without domain knowledge EDA has no meaning, without EDA a problem has no soul."

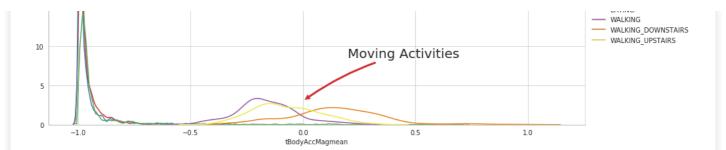
## 1. Featuring Engineering from Domain Knowledge

- Static and Dynamic Activities
  - In static activities (sit, stand, lie down) motion information will not be very useful.
  - In the dynamic activities (Walking, WalkingUpstairs, WalkingDownstairs) motion info will be significant.

## 2. Stationary and Moving activities are completely different

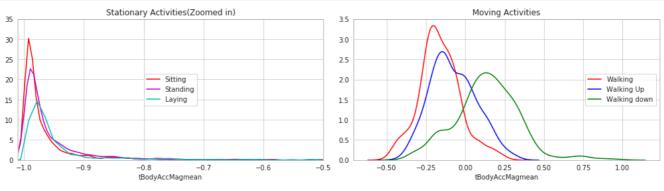
#### In [14]:





#### In [15]:

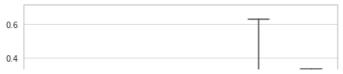
```
# for plotting purposes taking datapoints of each activity to a different dataframe
df1 = train[train['Activity']==1]
df2 = train[train['Activity']==2]
df3 = train[train['Activity']==3]
df4 = train[train['Activity']==4]
df5 = train[train['Activity']==5]
df6 = train[train['Activity']==6]
plt.figure(figsize=(14,7))
plt.subplot(2,2,1)
plt.title('Stationary Activities(Zoomed in)')
sns.distplot(df4['tBodyAccMagmean'],color = 'r',hist = False, label = 'Sitting')
sns.distplot(df5['tBodyAccMagmean'],color = 'm',hist = False,label = 'Standing')
sns.distplot(df6['tBodyAccMagmean'],color = 'c',hist = False, label = 'Laying')
plt.axis([-1.01, -0.5, 0, 35])
plt.legend(loc='center')
plt.subplot(2,2,2)
plt.title('Moving Activities')
sns.distplot(df1['tBodyAccMagmean'],color = 'red',hist = False, label = 'Walking')
sns.distplot(df2['tBodyAccMagmean'],color = 'blue',hist = False,label = 'Walking Up')
sns.distplot(df3['tBodyAccMagmean'],color = 'green',hist = False, label = 'Walking down')
plt.legend(loc='center right')
plt.tight layout()
plt.show()
```

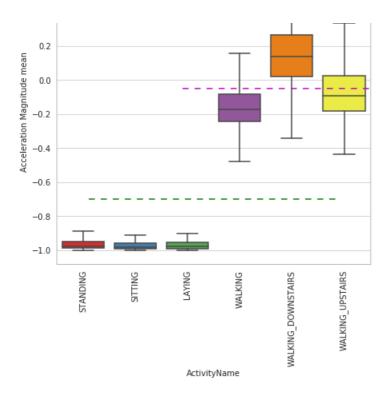


## 3. Magnitude of an acceleration can saperate it well

#### In [16]:

```
plt.figure(figsize=(7,7))
sns.boxplot(x='ActivityName', y='tBodyAccMagmean',data=train, showfliers=False, saturation=1)
plt.ylabel('Acceleration Magnitude mean')
plt.axhline(y=-0.7, xmin=0.1, xmax=0.9,dashes=(5,5), c='g')
plt.axhline(y=-0.05, xmin=0.4, dashes=(5,5), c='m')
plt.xticks(rotation=90)
plt.show()
```





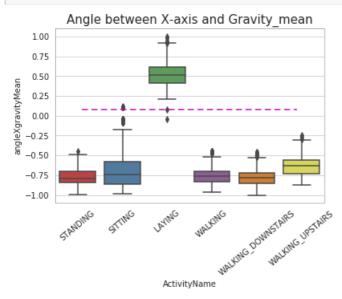
### Observations:

- If tAccMean is < -0.8 then the Activities are either Standing or Sitting or Laying.
- If tAccMean is > -0.6 then the Activities are either Walking or WalkingDownstairs or WalkingUpstairs.
- If tAccMean > 0.0 then the Activity is WalkingDownstairs.
- We can classify 75% the Acitivity labels with some errors.

## 4. Position of GravityAccelerationComponants also matters

## In [17]:

```
sns.boxplot(x='ActivityName', y='angleXgravityMean', data=train)
plt.axhline(y=0.08, xmin=0.1, xmax=0.9,c='m',dashes=(5,3))
plt.title('Angle between X-axis and Gravity_mean', fontsize=15)
plt.xticks(rotation = 40)
plt.show()
```

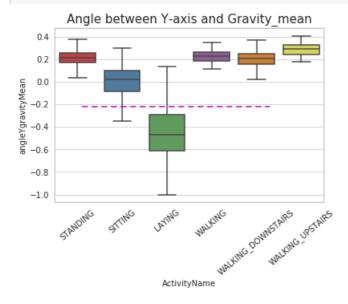


## Observations:

- If angleX,gravityMean > 0 then Activity is Laying.
- · We can classify all datapoints belonging to Laying activity with just a single if else statement.

#### In [18]:

```
sns.boxplot(x='ActivityName', y='angleYgravityMean', data = train, showfliers=False)
plt.title('Angle between Y-axis and Gravity_mean', fontsize=15)
plt.xticks(rotation = 40)
plt.axhline(y=-0.22, xmin=0.1, xmax=0.8, dashes=(5,3), c='m')
plt.show()
```



## Apply t-sne on the data

## In [19]:

```
import numpy as np
from sklearn.manifold import TSNE
import matplotlib.pyplot as plt
import seaborn as sns
```

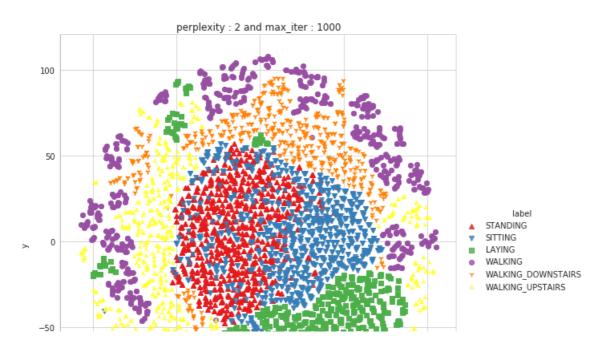
#### In [20]:

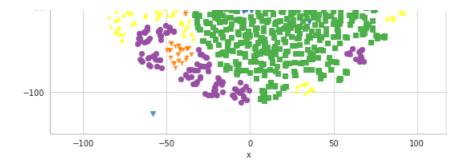
```
# performs t-sne with different perplexity values and their repective plots..
def perform tsne(X data, y data, perplexities, n iter=1000, img name prefix='t-sne'):
    for index,perplexity in enumerate(perplexities):
       # perform t-sne
        print('\nperforming tsne with perplexity {} and with {} iterations at max'.format(perplexit
y, n_iter))
       X_reduced = TSNE(verbose=2, perplexity=perplexity).fit_transform(X_data)
        print('Done..')
        # prepare the data for seaborn
        print('Creating plot for this t-sne visualization..')
        df = pd.DataFrame(('x':X reduced[:,0], 'y':X reduced[:,1] ,'label':y data})
        # draw the plot in appropriate place in the grid
        sns.lmplot(data=df, x='x', y='y', hue='label', fit_reg=False, size=8,\
                  palette="Set1", markers=['^','v','s','o', '1','2'])
        plt.title("perplexity : {} and max iter : {}".format(perplexity, n iter))
        img_name = img_name_prefix + '_perp_{}_iter_{}.png'.format(perplexity, n_iter)
        print('saving this plot as image in present working directory...')
        plt.savefig(img_name)
        plt.show()
        print('Done')
```

```
X pre tsne = train.drop(['subject', 'Activity', 'ActivityName'], axis=1)
y_pre_tsne = train['ActivityName']
perform_tsne(X_data = X_pre_tsne,y_data=y_pre_tsne, perplexities =[2,5,10,20,50])
performing tsne with perplexity 2 and with 1000 iterations at max
[t-SNE] Computing 7 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.486s...
[t-SNE] Computed neighbors for 7352 samples in 50.150s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.635855
[t-SNE] Computed conditional probabilities in 0.125s
[t-SNE] Iteration 50: error = 124.7682190, gradient norm = 0.0257704 (50 iterations in 6.676s)
[t-SNE] Iteration 100: error = 106.7810440, gradient norm = 0.0283834 (50 iterations in 4.605s)
[t-SNE] Iteration 150: error = 100.6281281, gradient norm = 0.0191540 (50 iterations in 3.739s)
[t-SNE] Iteration 200: error = 97.2982483, gradient norm = 0.0169978 (50 iterations in 3.673s)
[t-SNE] Iteration 250: error = 95.0379333, gradient norm = 0.0142829 (50 iterations in 3.780s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 95.037933
[t-SNE] Iteration 300: error = 4.1139207, gradient norm = 0.0015608 (50 iterations in 3.263s)
[t-SNE] Iteration 350: error = 3.2067728, gradient norm = 0.0010018 (50 iterations in 3.223s)
[t-SNE] Iteration 400: error = 2.7781920, gradient norm = 0.0007167 (50 iterations in 4.415s)
[t-SNE] Iteration 450: error = 2.5144770, gradient norm = 0.0005642 (50 iterations in 3.376s)
[t-SNE] Iteration 500: error = 2.3311925, gradient norm = 0.0004784 (50 iterations in 3.117s)
[t-SNE] Iteration 550: error = 2.1932833, gradient norm = 0.0004137 (50 iterations in 2.778s)
[t-SNE] Iteration 600: error = 2.0841417, gradient norm = 0.0003660 (50 iterations in 2.717s)
[t-SNE] Iteration 650: error = 1.9945242, gradient norm = 0.0003307 (50 iterations in 2.708s)
[t-SNE] Iteration 700: error = 1.9192704, gradient norm = 0.0003048 (50 iterations in 2.701s)
[t-SNE] Iteration 750: error = 1.8545545, gradient norm = 0.0002771 (50 iterations in 2.962s)
[t-SNE] Iteration 800: error = 1.7978274, gradient norm = 0.0002596 (50 iterations in 2.992s)
[t-SNE] Iteration 850: error = 1.7478549, gradient norm = 0.0002398 (50 iterations in 2.923s)
[t-SNE] Iteration 900: error = 1.7033331, gradient norm = 0.0002259 (50 iterations in 2.985s)
[t-SNE] Iteration 950: error = 1.6635573, gradient norm = 0.0002107 (50 iterations in 2.827s)
[t-SNE] Iteration 1000: error = 1.6273080, gradient norm = 0.0001986 (50 iterations in 2.984s)
[t-SNE] KL divergence after 1000 iterations: 1.627308
Done..
Creating plot for this t-sne visualization..
```

C:\Users\sanjeev\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWarning: The `size` pa
ramter has been renamed to `height`; please update your code.
 warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...

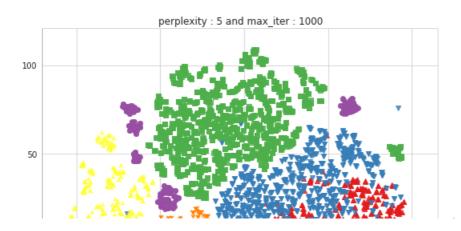


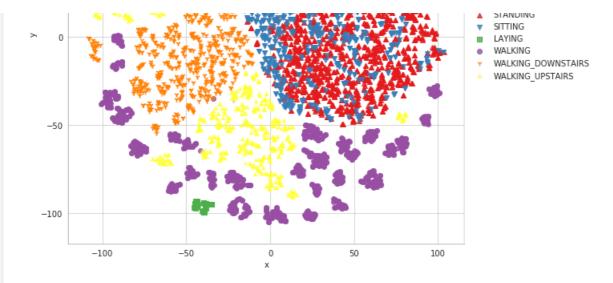


```
performing tsne with perplexity 5 and with 1000 iterations at max
[t-SNE] Computing 16 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.312s...
[t-SNE] Computed neighbors for 7352 samples in 47.514s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.961265
[t-SNE] Computed conditional probabilities in 0.187s
[t-SNE] Iteration 50: error = 114.0555573, gradient norm = 0.0234660 (50 iterations in 11.069s)
[t-SNE] \ \ Iteration \ 100: \ error = 97.8461609, \ gradient \ norm = 0.0152510 \ (50 \ iterations \ in \ 3.155s)
[t-SNE] Iteration 150: error = 93.1312790, gradient norm = 0.0089201 (50 iterations in 2.668s)
[t-SNE] Iteration 200: error = 91.1070709, gradient norm = 0.0067680 (50 iterations in 2.569s)
[t-SNE] Iteration 250: error = 89.9217148, gradient norm = 0.0053157 (50 iterations in 2.544s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 89.921715
[t-SNE] Iteration 300: error = 3.5675917, gradient norm = 0.0014618 (50 iterations in 2.594s)
[t-SNE] Iteration 350: error = 2.8087602, gradient norm = 0.0007490 (50 iterations in 2.582s)
       Iteration 400: error = 2.4282768, gradient norm = 0.0005215 (50 iterations in 2.866s)
[t-SNE]
[t-SNE] Iteration 450: error = 2.2109582, gradient norm = 0.0004047 (50 iterations in 2.757s)
[t-SNE] Iteration 500: error = 2.0662291, gradient norm = 0.0003309 (50 iterations in 2.678s)
[t-SNE] Iteration 550: error = 1.9611422, gradient norm = 0.0002805 (50 iterations in 2.672s)
[t-SNE] Iteration 600: error = 1.8802474, gradient norm = 0.0002452 (50 iterations in 2.647s)
[t-SNE] Iteration 650: error = 1.8152393, gradient norm = 0.0002195 (50 iterations in 2.686s)
[t-SNE] Iteration 700: error = 1.7617742, gradient norm = 0.0002005 (50 iterations in 2.685s)
[t-SNE] Iteration 750: error = 1.7167171, gradient norm = 0.0001777 (50 iterations in 2.681s)
[t-SNE] Iteration 800: error = 1.6778905, gradient norm = 0.0001652 (50 iterations in 2.740s)
[t-SNE] Iteration 850: error = 1.6442558, gradient norm = 0.0001543 (50 iterations in 2.688s)
[t-SNE] Iteration 900: error = 1.6144943, gradient norm = 0.0001440 (50 iterations in 2.708s)
[t-SNE] Iteration 950: error = 1.5878861, gradient norm = 0.0001344 (50 iterations in 2.689s)
[t-SNE] Iteration 1000: error = 1.5640718, gradient norm = 0.0001269 (50 iterations in 2.759s)
[t-SNE] KL divergence after 1000 iterations: 1.564072
Creating plot for this t-sne visualization..
```

C:\Users\sanjeev\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWarning: The `size` pa
ramter has been renamed to `height`; please update your code.
warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...

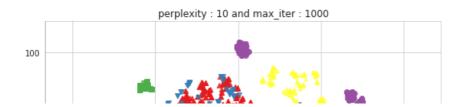


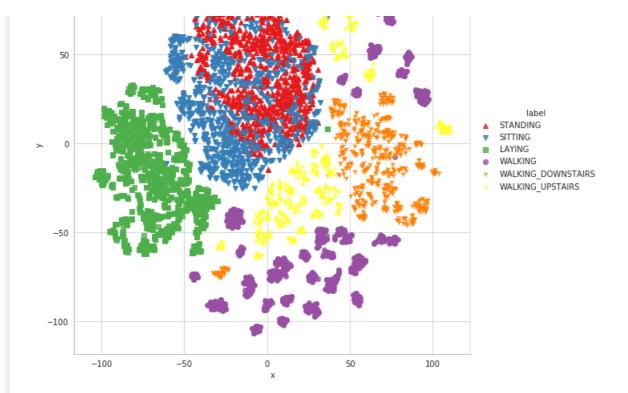


```
performing tsne with perplexity 10 and with 1000 iterations at max
[t-SNE] Computing 31 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.293s...
[t-SNE] Computed neighbors for 7352 samples in 47.773s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.133828
[t-SNE] Computed conditional probabilities in 0.125s
[t-SNE] Iteration 50: error = 105.8732071, gradient norm = 0.0164976 (50 iterations in 4.858s)
[t-SNE] Iteration 100: error = 90.5844574, gradient norm = 0.0112697 (50 iterations in 3.465s)
[t-SNE] Iteration 150: error = 87.5589371, gradient norm = 0.0062893 (50 iterations in 3.095s)
[t-SNE] Iteration 200: error = 86.2989120, gradient norm = 0.0065243 (50 iterations in 3.175s)
[t-SNE] Iteration 250: error = 85.5826340, gradient norm = 0.0029128 (50 iterations in 3.116s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 85.582634
[t-SNE] Iteration 300: error = 3.1351471, gradient norm = 0.0013860 (50 iterations in 2.987s)
[t-SNE] Iteration 350: error = 2.4937270, gradient norm = 0.0006509 (50 iterations in 2.771s)
[t-SNE] Iteration 400: error = 2.1737823, gradient norm = 0.0004212 (50 iterations in 2.774s)
[t-SNE] Iteration 450: error = 1.9893734, gradient norm = 0.0003163 (50 iterations in 2.786s)
[t-SNE] Iteration 500: error = 1.8710037, gradient norm = 0.0002546 (50 iterations in 2.808s)
[t-SNE] Iteration 550: error = 1.7874155, gradient norm = 0.0002133 (50 iterations in 2.807s)
[t-SNE] Iteration 600: error = 1.7246299, gradient norm = 0.0001839 (50 iterations in 2.817s)
[t-SNE] Iteration 650: error = 1.6753068, gradient norm = 0.0001621 (50 iterations in 2.833s)
[t-SNE] Iteration 700: error = 1.6357390, gradient norm = 0.0001437 (50 iterations in 2.832s)
[t-SNE] Iteration 750: error = 1.6034117, gradient norm = 0.0001309 (50 iterations in 2.871s)
[t-SNE] Iteration 800: error = 1.5759659, gradient norm = 0.0001212 (50 iterations in 2.855s)
[t-SNE] Iteration 850: error = 1.5530144, gradient norm = 0.0001120 (50 iterations in 2.849s)
[t-SNE] Iteration 900: error = 1.5330607, gradient norm = 0.0001051 (50 iterations in 2.846s)
[t-SNE] Iteration 950: error = 1.5159706, gradient norm = 0.0000987 (50 iterations in 2.836s)
[t-SNE] Iteration 1000: error = 1.5010815, gradient norm = 0.0000945 (50 iterations in 2.844s)
[t-SNE] KL divergence after 1000 iterations: 1.501081
Done
Creating plot for this t-sne visualization..
```

C:\Users\sanjeev\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWarning: The `size` pa
ramter has been renamed to `height`; please update your code.
warnings.warn(msg, UserWarning)

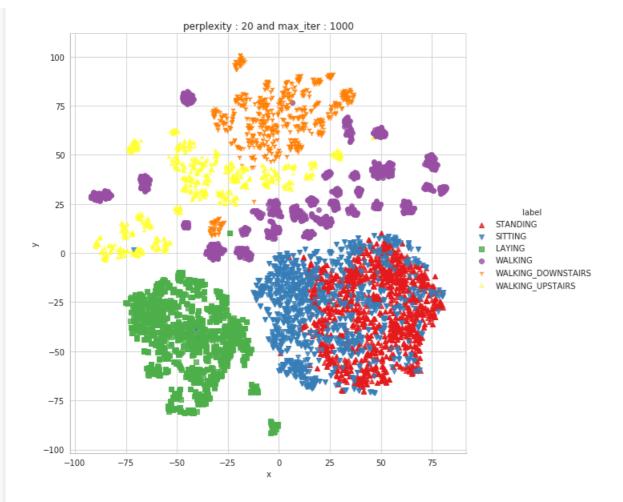
saving this plot as image in present working directory...





```
performing tsne with perplexity 20 and with 1000 iterations at max
[t-SNE] Computing 61 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.291s...
[t-SNE] Computed neighbors for 7352 samples in 48.704s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.274335
[t-SNE] Computed conditional probabilities in 0.232s
[t-SNE] Iteration 50: error = 98.0124283, gradient norm = 0.0108954 (50 iterations in 6.863s)
[t-SNE] Iteration 100: error = 84.0378571, gradient norm = 0.0076726 (50 iterations in 4.252s)
[t-SNE] Iteration 150: error = 81.9204407, gradient norm = 0.0040294 (50 iterations in 3.682s)
[t-SNE] Iteration 200: error = 81.1675034, gradient norm = 0.0026958 (50 iterations in 3.630s)
[t-SNE] Iteration 250: error = 80.7760849, gradient norm = 0.0018361 (50 iterations in 3.480s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 80.776085
[t-SNE] Iteration 300: error = 2.6949992, gradient norm = 0.0013013 (50 iterations in 3.298s)
[t-SNE] Iteration 350: error = 2.1627953, gradient norm = 0.0005764 (50 iterations in 3.126s)
[t-SNE] Iteration 400: error = 1.9131525, gradient norm = 0.0003471 (50 iterations in 3.110s)
[t-SNE] Iteration 450: error = 1.7670326, gradient norm = 0.0002475 (50 iterations in 3.125s)
[t-SNE] Iteration 500: error = 1.6731824, gradient norm = 0.0001917 (50 iterations in 3.142s)
[t-SNE] Iteration 550: error = 1.6089791, gradient norm = 0.0001578 (50 iterations in 3.1388) [t-SNE] Iteration 600: error = 1.5624276, gradient norm = 0.0001320 (50 iterations in 3.1318)
[t-SNE] Iteration 650: error = 1.5270309, gradient norm = 0.0001165 (50 iterations in 3.165s)
[t-SNE] Iteration 700: error = 1.4993186, gradient norm = 0.0001042 (50 iterations in 3.198s)
[t-SNE] Iteration 750: error = 1.4771080, gradient norm = 0.0000953 (50 iterations in 3.230s)
[t-SNE] Iteration 800: error = 1.4592550, gradient norm = 0.0000859 (50 iterations in 3.201s)
        Iteration 850: error = 1.4442073, gradient norm = 0.0000859 (50 iterations in 3.218s)
[t-SNE] Iteration 900: error = 1.4327312, gradient norm = 0.0000769 (50 iterations in 3.213s)
[t-SNE] Iteration 950: error = 1.4231975, gradient norm = 0.0000739 (50 iterations in 3.210s)
[t-SNE] Iteration 1000: error = 1.4148101, gradient norm = 0.0000704 (50 iterations in 3.216s)
[t-SNE] KL divergence after 1000 iterations: 1.414810
Creating plot for this t-sne visualization..
```

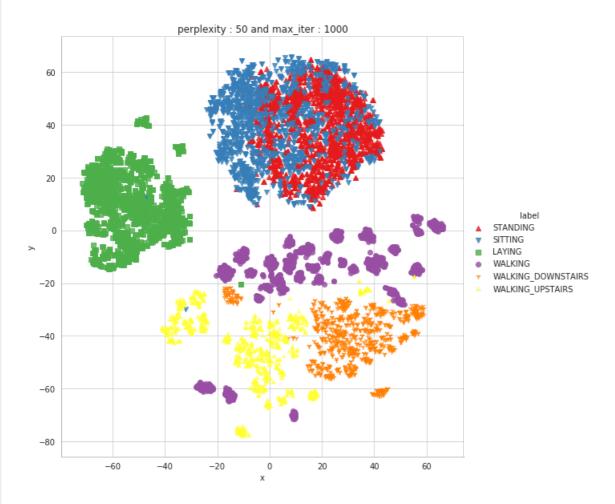
C:\Users\sanjeev\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWarning: The `size` pa
ramter has been renamed to `height`; please update your code.
warnings.warn(msg, UserWarning)



```
performing tsne with perplexity 50 and with 1000 iterations at max
[t-SNE] Computing 151 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.310s...
[t-SNE] Computed neighbors for 7352 samples in 50.319s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352 \,
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.437672
[t-SNE] Computed conditional probabilities in 0.564s
[t-SNE] Iteration 50: error = 84.6528091, gradient norm = 0.0364481 (50 iterations in 5.905s)
[t-SNE] Iteration 100: error = 75.5724411, gradient norm = 0.0039807 (50 iterations in 4.684s)
[t-SNE] Iteration 150: error = 74.6383209, gradient norm = 0.0020514 (50 iterations in 4.1498)
[t-SNE] Iteration 200: error = 74.2526474, gradient norm = 0.0015941 (50 iterations in 4.158s)
[t-SNE] Iteration 250: error = 74.0653610, gradient norm = 0.0012683 (50 iterations in 4.334s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 74.065361
[t-SNE] Iteration 300: error = 2.1436260, gradient norm = 0.0011739 (50 iterations in 4.055s)
[t-SNE] Iteration 350: error = 1.7512568, gradient norm = 0.0004792 (50 iterations in 5.218s)
[t-SNE] Iteration 400: error = 1.5849240, gradient norm = 0.0002780 (50 iterations in 4.103s)
[t-SNE] Iteration 450: error = 1.4920912, gradient norm = 0.0001872 (50 iterations in 3.921s)
[t-SNE] Iteration 500: error = 1.4325999, gradient norm = 0.0001390 (50 iterations in 3.939s)
[t-SNE] Iteration 550: error = 1.3918090, gradient norm = 0.0001100 (50 iterations in 4.017s)
[t-SNE] Iteration 600: error = 1.3629713, gradient norm = 0.0000935 (50 iterations in 3.992s)
[t-SNE] Iteration 650: error = 1.3419070, gradient norm = 0.0000830 (50 iterations in 3.955s)
[t-SNE] Iteration 700: error = 1.3265507, gradient norm = 0.0000743 (50 iterations in 3.937s)
[t-SNE] Iteration 750: error = 1.3150469, gradient norm = 0.0000684 (50 iterations in 3.960s)
[t-SNE] Iteration 800: error = 1.3062477, gradient norm = 0.0000644 (50 iterations in 3.961s)
[t-SNE] Iteration 850: error = 1.2991018, gradient norm = 0.0000616 (50 iterations in 3.948s)
[t-SNE] Iteration 900: error = 1.2936642, gradient norm = 0.0000620 (50 iterations in 3.975s)
       Iteration 950: error = 1.2894293, gradient norm = 0.0000592 (50 iterations in 4.081s)
[t-SNE] Iteration 1000: error = 1.2861389, gradient norm = 0.0000545 (50 iterations in 3.997s)
[t-SNE] KL divergence after 1000 iterations: 1.286139
Creating plot for this t-sne visualization..
```

C:\Users\sanjeev\Anaconda3\lib\site-packages\seaborn\regression.py:546: UserWarning: The `size` pa
ramter has been renamed to `height`; please update your code.
 warnings.warn(msg, UserWarning)

saving this plot as image in present working directory...



Done

## Obtain the train and test data

```
In [22]:
```

```
train = pd.read_csv('train.csv')
test = pd.read_csv('test.csv')
print(train.shape, test.shape)
```

(7352, 564) (2947, 564)

## In [23]:

```
train.head()
```

## Out[23]:

	tBodyAccmeanX	tBodyAccmeanY	tBodyAccmeanZ	tBodyAccstdX	tBodyAccstdY	tBodyAccstdZ	tBodyAccmadX	tBodyAccmadY	t
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.913526	-0.995112	-0.983185	
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.960322	-0.998807	-0.974914	
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.978944	-0.996520	-0.963668	
3	0.279174	-0.026201	-0.123283	-0.996091	-0.983403	-0.990675	-0.997099	-0.982750	
4	0.276629	-0.016570	-0.115362	-0.998139	-0.980817	-0.990482	-0.998321	-0.979672	

```
In [24]:

# get X_train and y_train from csv files
X_train = train.drop(['subject', 'Activity', 'ActivityName'], axis=1)
y_train = train.ActivityName

In [25]:

# get X_test and y_test from test csv file
X_test = test.drop(['subject', 'Activity', 'ActivityName'], axis=1)
y_test = test.ActivityName

In [26]:

print('X_train and y_train : ({},{})'.format(X_train.shape, y_train.shape))
print('X_test and y_test : ({},{})'.format(X_test.shape, y_test.shape))

X_train and y_train : ((7352, 561), (7352,))
X_test and y_test : ((2947, 561), (2947,))
```

## Let's model with our data

## Labels that are useful in plotting confusion matrix

```
In [32]:
labels=['LAYING', 'SITTING','STANDING','WALKING','WALKING_DOWNSTAIRS','WALKING_UPSTAIRS']
```

## Function to plot the confusion matrix

```
In [27]:
```

```
import itertools
import numpy as np
import matplotlib.pyplot as plt
from sklearn.metrics import confusion matrix
plt.rcParams["font.family"] = 'DejaVu Sans'
def plot confusion matrix(cm, classes,
                        normalize=False,
                        title='Confusion matrix',
                        cmap=plt.cm.Blues):
   if normalize:
       cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]
   plt.imshow(cm, interpolation='nearest', cmap=cmap)
   plt.title(title)
   plt.colorbar()
   tick marks = np.arange(len(classes))
   plt.xticks(tick marks, classes, rotation=90)
   plt.yticks(tick marks, classes)
   fmt = '.2f' if normalize else 'd'
   thresh = cm.max() / 2.
   plt.text(j, i, format(cm[i, j], fmt),
               horizontalalignment="center",
               color="white" if cm[i, j] > thresh else "black")
   plt.tight layout()
   plt.ylabel('True label')
   plt.xlabel('Predicted label')
```

## Generic function to run any model specified

```
In [28]:
```

```
from datetime import datetime
def perform model(model, X train, y train, X test, y test, class labels, cm normalize=True, \
               print cm=True, cm cmap=plt.cm.Greens):
   # to store results at various phases
   results = dict()
   # time at which model starts training
   train start time = datetime.now()
   print('training the model..')
   model.fit(X_train, y_train)
   print('Done \n \n')
   train end time = datetime.now()
   results['training_time'] = train_end_time - train_start_time
   print('training time(HH:MM:SS.ms) - {}\n\n'.format(results['training time']))
   # predict test data
   print('Predicting test data')
   test start time = datetime.now()
   y pred = model.predict(X test)
   test end time = datetime.now()
   print('Done \n \n')
   results['testing_time'] = test_end_time - test_start_time
   print('testing time(HH:MM:SS:ms) - {}\n\n'.format(results['testing time']))
   results['predicted'] = y pred
   # calculate overall accuracty of the model
   accuracy = metrics.accuracy_score(y_true=y_test, y_pred=y_pred)
   # store accuracy in results
   results['accuracy'] = accuracy
   print('----')
   print('| Accuracy |')
   print('----')
   print('\n {}\n\n'.format(accuracy))
   # confusion matrix
   cm = metrics.confusion_matrix(y_test, y_pred)
   results['confusion_matrix'] = cm
   if print cm:
       print('----')
       print('| Confusion Matrix |')
      print('----')
      print('\n {}'.format(cm))
   # plot confusin matrix
   plt.figure(figsize=(8,8))
   plt.grid(b=False)
   plot confusion matrix(cm, classes=class labels, normalize=True, title='Normalized confusion
matrix', cmap = cm_cmap)
   plt.show()
   # get classification report
   print('----')
   print('| Classifiction Report |')
   print('----')
   classification report = metrics.classification report(y test, y pred)
   # store report in results
   results['classification report'] = classification report
   print(classification_report)
   # add the trained model to the results
   results['model'] = model
   return results
```

## Method to print the gridsearch Attributes

```
In [29]:
```

```
def print grid search attributes(model):
  # Estimator that gave highest score among all the estimators formed in GridSearch
   print('----')
  print('| Best Estimator |')
  print('----')
  print('\n\t{}\n'.format(model.best_estimator_))
   # parameters that gave best results while performing grid search
   print('----')
   print('| Best parameters |')
   print('----')
   print('\tParameters of best estimator : \n\n\t{}\n'.format(model.best params ))
   # number of cross validation splits
   print('----')
   print('| No of CrossValidation sets |')
   print('----')
   print('\n\tTotal numbre of cross validation sets: {}\n'.format(model.n_splits_))
   # Average cross validated score of the best estimator, from the Grid Search
   print('----')
   print('| Best Score |')
   print('----')
  print('\n\tAverage Cross Validate scores of best estimator :
\n\n\t{}\n'.format(model.best score ))
```

## 1. Logistic Regression with Grid Search

```
In [30]:
```

```
from sklearn import linear_model
from sklearn import metrics

from sklearn.model_selection import GridSearchCV
```

```
In [33]:
```

```
# start Grid search
parameters = {'C':[0.01, 0.1, 1, 10, 20, 30], 'penalty':['12','11']}
log_reg = linear_model.LogisticRegression()
log_reg_grid = GridSearchCV(log_reg, param_grid=parameters, cv=3, verbose=1, n_jobs=-1)
log_reg_grid_results = perform_model(log_reg_grid, X_train, y_train, X_test, y_test, class_labels=
labels)
```

training the model.. Fitting 3 folds for each of 12 candidates, totalling 36 fits

```
[Parallel(n_jobs=-1)]: Using backend LokyBackend with 4 concurrent workers.
[Parallel(n_jobs=-1)]: Done 36 out of 36 | elapsed: 1.2min finished
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\linear_model\logistic.py:432: FutureWarning:
Default solver will be changed to 'lbfgs' in 0.22. Specify a solver to silence this warning.
FutureWarning)
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\linear_model\logistic.py:469: FutureWarning:
Default multi_class will be changed to 'auto' in 0.22. Specify the multi_class option to silence this warning.

"this warning.", FutureWarning)
```

Done

```
training_time(HH:MM:SS.ms) - 0:01:22.522831
```

```
Predicting test data
```

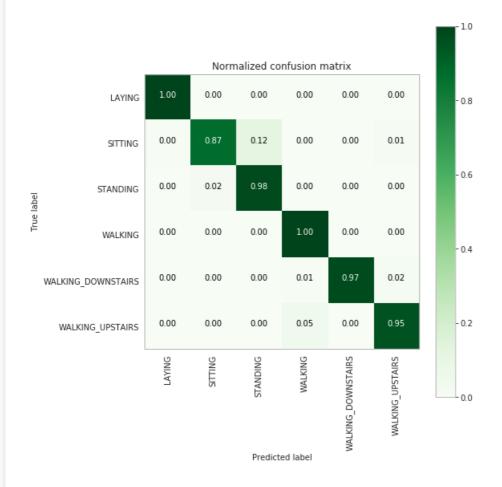
testing time(HH:MM:SS:ms) - 0:00:00.477929

| Accuracy |

0.9630132337970818

## | Confusion Matrix |

[ [	537	7 (	) (	) (	) (	0]
[	2	428	57	0	0	4]
[	0	11	520	1	0	0]
[	0	0	0	495	1	0]
[	0	0	0	3	409	8]
[	0	0	0	22	0	449]]

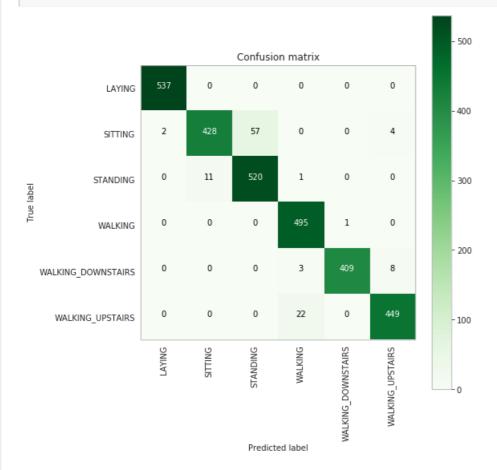


## | Classifiction Report |

	precision	recall	f1-score	support
LAYING SITTING	1.00 0.97	1.00	1.00	537 491
STANDING	0.90	0.98	0.94	532
WALKING	0.95	1.00	0.97	496
WALKING_DOWNSTAIRS	1.00	0.97	0.99	420
WALKING_UPSTAIRS	0.97	0.95	0.96	471
accuracy			0.96	2947
macro avg	0.97	0.96	0.96	2947
weighted avg	0.96	0.96	0.96	2947

#### In [34]:

```
plt.figure(figsize=(8,8))
plt.grid(b=False)
plot_confusion_matrix(log_reg_grid_results['confusion_matrix'], classes=labels, cmap=plt.cm.Greens
, )
plt.show()
```

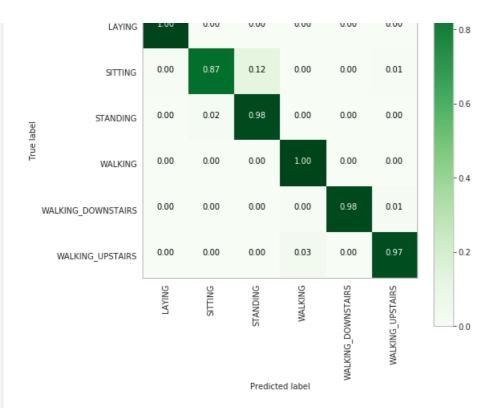


#### In [35]:

```
# observe the attributes of the model
print_grid_search_attributes(log_reg_grid_results['model'])
    Best Estimator |
LogisticRegression(C=30, class_weight=None, dual=False, fit_intercept=True,
                 intercept_scaling=1, l1_ratio=None, max_iter=100,
                 multi_class='warn', n_jobs=None, penalty='12',
                 random state=None, solver='warn', tol=0.0001, verbose=0,
                 warm start=False)
| Best parameters |
Parameters of best estimator :
{'C': 30, 'penalty': '12'}
| No of CrossValidation sets |
______
Total numbre of cross validation sets: 3
| Best Score |
Average Cross Validate scores of best estimator :
```

## 2. Linear SVC with GridSearch

```
In [36]:
from sklearn.svm import LinearSVC
In [37]:
parameters = {'C':[0.125, 0.5, 1, 2, 8, 16]}
lr svc = LinearSVC(tol=0.00005)
lr_svc_grid = GridSearchCV(lr_svc, param_grid=parameters, n_jobs=-1, verbose=1)
lr_svc_grid_results = perform_model(lr_svc_grid, X_train, y_train, X_test, y_test, class_labels=lab
training the model..
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\model selection\ split.py:1978:
FutureWarning: The default value of cv will change from 3 to 5 in version 0.22. Specify it
explicitly to silence this warning.
 warnings.warn(CV WARNING, FutureWarning)
[Parallel(n jobs=-1)]: Using backend LokyBackend with 4 concurrent workers.
Fitting 3 folds for each of 6 candidates, totalling 18 fits
[Parallel(n jobs=-1)]: Done 18 out of 18 | elapsed:
                                                        30.4s finished
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\svm\base.py:929: ConvergenceWarning:
Liblinear failed to converge, increase the number of iterations.
 "the number of iterations.", ConvergenceWarning)
Done
training time(HH:MM:SS.ms) - 0:00:37.065340
Predicting test data
Done
testing time(HH:MM:SS:ms) - 0:00:00.015620
    Accuracy |
   0.9657278588394977
| Confusion Matrix |
 [[537 0 0 0 0
 [ 2 425 61 0 0 3]
 [ 0 10 521 1 0 0]
 [ 0 0 0 496 0 0]
[ 0 0 0 2 412 6]
[ 0 0 0 16 0 455]]
```



-----

| Classifiction Report |

	precision	recall	f1-score	support			
LAYING	1.00	1.00	1.00	537			
SITTING	0.98	0.87	0.92	491			
STANDING	0.90	0.98	0.94	532			
WALKING	0.96	1.00	0.98	496			
WALKING DOWNSTAIRS	1.00	0.98	0.99	420			
WALKING UPSTAIRS	0.98	0.97	0.97	471			
_							
accuracy			0.97	2947			
macro avg	0.97	0.97	0.97	2947			
weighted avg	0.97	0.97	0.97	2947			

#### In [38]:

```
Average Cross Validate scores of best estimator :
```

## 3. Kernel SVM with GridSearch

```
In [39]:
```

training the model..

0.9464091403699674

```
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\model_selection\_split.py:1978:
FutureWarning: The default value of cv will change from 3 to 5 in version 0.22. Specify it explicitly to silence this warning.
  warnings.warn(CV_WARNING, FutureWarning)
```

Done

```
training_time(HH:MM:SS.ms) - 0:03:52.367101
```

Predicting test data Done

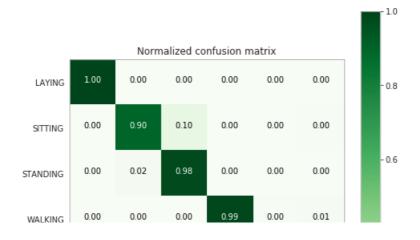
testing time(HH:MM:SS:ms) - 0:00:03.194097

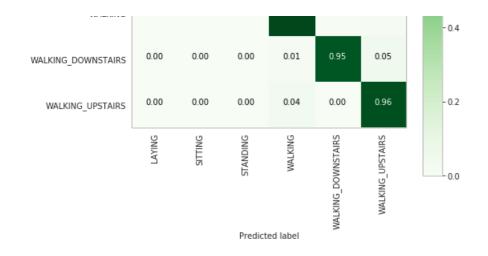
```
| Accuracy |
```

0.9626739056667798

```
| Confusion Matrix |
```

```
[[537 0 0 0 0 0 0]
[ 0 441 48 0 0 2]
[ 0 12 520 0 0 0]
[ 0 0 0 489 2 5]
[ 0 0 0 0 4 397 19]
[ 0 0 0 17 1 453]]
```





| Classifiction Report |

	precision	recall	f1-score	support			
LAYING SITTING STANDING	1.00 0.97 0.92	1.00 0.90 0.98	1.00 0.93 0.95	537 491 532			
WALKING	0.96	0.99	0.97	496			
WALKING_DOWNSTAIRS	0.99	0.95	0.97	420			
WALKING_UPSTAIRS	0.95	0.96	0.95	471			
accuracy			0.96	2947			
macro avg	0.96	0.96	0.96	2947			
weighted avg	0.96	0.96	0.96	2947			

#### In [40]:

```
print_grid_search_attributes(rbf_svm_grid_results['model'])

Best Estimator |

SVC(C=16, cache_size=200, class_weight=None, coef0=0.0, decision_function_shape='ovr', degree=3, gamma=0.0078125, kernel='rbf', max_iter=-1, probability=False, random_state=None, shrinking=True, tol=0.001, verbose=False)

Best parameters |

Parameters of best estimator :
{'C': 16, 'gamma': 0.0078125}

Total numbre of cross validation sets: 3

Best Score |

Average Cross Validate scores of best estimator :
0.9440968443960827
```

## 4. Decision Trees with GridSearchCV

```
In [41]:
```

```
from sklearn.tree import DecisionTreeClassifier
parameters = {'max_depth':np.arange(3,10,2)}
dt = DecisionTreeClassifier()
dt_grid = GridSearchCV(dt,param_grid=parameters, n_jobs=-1)
dt_grid_results = perform_model(dt_grid, X_train, y_train, X_test, y_test, class_labels=labels)
```

training the model..

C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\model\_selection\\_split.py:1978:
FutureWarning: The default value of cv will change from 3 to 5 in version 0.22. Specify it explicitly to silence this warning.
warnings.warn(CV\_WARNING, FutureWarning)

Done

```
training_time(HH:MM:SS.ms) - 0:00:11.826707
```

Predicting test data Done

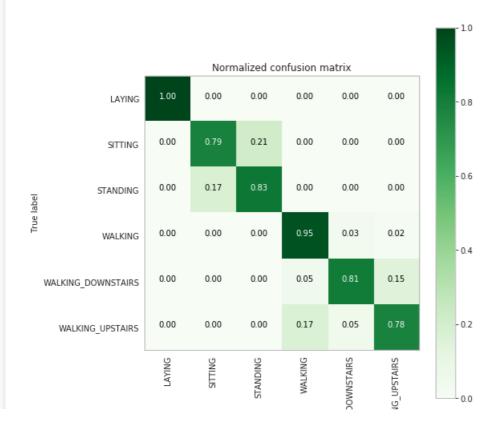
testing time(HH:MM:SS:ms) - 0:00:00

| Accuracy

0.8625721072276892

## | Confusion Matrix |

[[537 0 0 0 0 0 0] [ 0 386 105 0 0 0] [ 0 93 439 0 0 0] [ 0 0 0 471 17 8] [ 0 0 0 19 340 61] [ 0 0 0 78 24 369]]



#### Predicted label

```
| Classifiction Report |
                                            recall f1-score support
                         precision
                                                                            537
491
                LAYING
                                   1.00
                                                1.00
                                                              1.00
                                 0.81 0.79 0.80
               SITTING
                                                         0.82
0.89
0.85
0.81
              STANDING
                                 0.81
                                               0.83
                                                                             532
                           0.83 0.95
0.89 0.81
0.84 0.78
              WALKING
                                                                             496
WALKING DOWNSTAIRS
                                                                               420
  WALKING UPSTAIRS
                                                                               471

        accuracy
        0.86
        2947

        macro avg
        0.86
        0.86
        0.86
        2947

        weighted avg
        0.86
        0.86
        0.86
        2947
```

#### In [42]:

```
print grid search attributes(dt grid results['model'])
     Best Estimator
______
DecisionTreeClassifier(class_weight=None, criterion='gini', max_depth=7,
                     max features=None, max leaf nodes=None,
                     min_impurity_decrease=0.0, min_impurity_split=None,
                     min_samples_leaf=1, min_samples_split=2,
                     min weight fraction leaf=0.0, presort=False,
                     random_state=None, splitter='best')
   Best parameters |
Parameters of best estimator :
{'max depth': 7}
| No of CrossValidation sets |
Total numbre of cross validation sets: 3
| Best Score |
Average Cross Validate scores of best estimator :
0.8351468988030468
```

## 5. Random Forest Classifier with GridSearch

```
In [43]:
```

```
from sklearn.ensemble import RandomForestClassifier
params = \{ "n_estimators": np.arange(10,201,20), "max_depth": np.arange(3,15,2) \} 
rfc = RandomForestClassifier()
rfc_grid = GridSearchCV(rfc, param_grid=params, n_jobs=-1)
rfc_grid_results = perform_model(rfc_grid, X_train, y_train, X_test, y_test, class_labels=labels)
training the model..
```

C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\model\_selection\\_split.py:1978: FutureWarning: The default value of cv will change from 3 to 5 in version 0.22. Specify it explicitly to silence this warning.

warnings.warn(CV\_WARNING, FutureWarning)

Done

training time (HH:MM:SS.ms) - 0:06:42.946082

Predicting test data Done

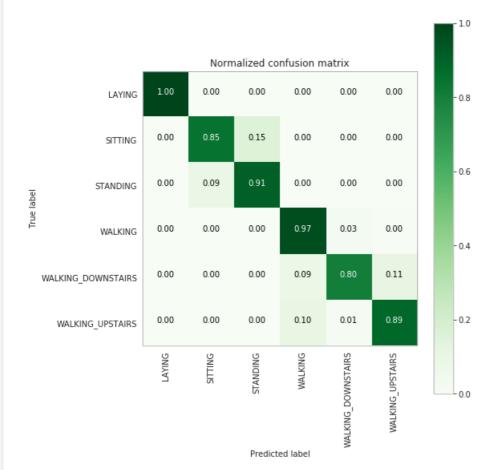
testing time(HH:MM:SS:ms) - 0:00:00.075798

| Accuracy |

0.9073634204275535

| Confusion Matrix |

[[537 0 0 0 0 0 0] [ 0 416 75 0 0 0] [ 0 46 486 0 0 0] [ 0 0 0 481 13 2] [ 0 0 0 36 337 47] [ 0 0 0 48 6 417]]



| Classifiction Report |

```
LAYING 1.00 1.00 1.00 537
SITTING 0.90 0.85 0.87 491
STANDING 0.87 0.91 0.89 532
WALKING 0.85 0.97 0.91 496
WALKING_DOWNSTAIRS 0.95 0.80 0.87 420
WALKING_UPSTAIRS 0.89 0.89 0.89 471

accuracy 0.91 0.90 0.90 2947
weighted avg 0.91 0.91 0.91 0.91
```

```
In [44]:
```

```
print grid search attributes(rfc grid results['model'])
| Best Estimator |
RandomForestClassifier(bootstrap=True, class weight=None, criterion='gini',
                   max depth=7, max features='auto', max leaf nodes=None,
                   min_impurity_decrease=0.0, min_impurity_split=None,
                   min samples leaf=1, min samples split=2,
                   min_weight_fraction_leaf=0.0, n_estimators=150,
                   n_jobs=None, oob_score=False, random_state=None,
                    verbose=0, warm start=False)
| Best parameters |
Parameters of best estimator :
{'max depth': 7, 'n estimators': 150}
_____
| No of CrossValidation sets |
_____
Total numbre of cross validation sets: 3
 Best Score |
______
Average Cross Validate scores of best estimator :
0.9156692056583242
```

## 6. Gradient Boosted Decision Trees With GridSearch

```
In [45]:
```

training the model..

```
C:\Users\sanjeev\Anaconda3\lib\site-packages\sklearn\model_selection\_split.py:1978:
FutureWarning: The default value of cv will change from 3 to 5 in version 0.22. Specify it explicitly to silence this warning.
  warnings.warn(CV_WARNING, FutureWarning)
```

# Predicting test data Done

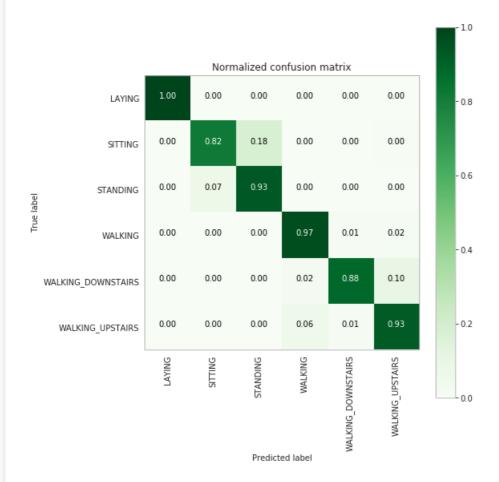
testing time(HH:MM:SS:ms) - 0:00:00.109350

| Accuracy |

0.9239904988123515

| Confusion Matrix |

[[537 0 0 0 0 0 0] [ 0 402 87 0 0 2] [ 0 37 495 0 0 0] [ 0 0 0 481 7 8] [ 0 0 0 9 371 40] [ 0 1 0 28 5 437]]



| Classifiction Report |

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537
SITTING	0.91	0.82	0.86	491
STANDING	0.85	0.93	0.89	532
WALKING	0.93	0.97	0.95	496
WALKING DOWNSTAIRS	0.97	0.88	0.92	420
WALKING_UPSTAIRS	0.90	0.93	0.91	471
accuracy			0.92	2947

```
In [46]:
print grid search attributes(gbdt grid results['model'])
| Best Estimator |
______
GradientBoostingClassifier(criterion='friedman mse', init=None,
                         learning rate=0.1, loss='deviance', max depth=5,
                         max_features=None, max_leaf_nodes=None,
                         min impurity decrease=0.0, min impurity split=None,
                         min_samples_leaf=1, min_samples_split=2,
                         min_weight_fraction_leaf=0.0, n_estimators=150,
                         n iter no change=None, presort='auto',
                         random_state=None, subsample=1.0, tol=0.0001,
                         validation fraction=0.1, verbose=0,
                         warm start=False)
| Best parameters |
Parameters of best estimator :
{'max depth': 5, 'n estimators': 150}
_____
| No of CrossValidation sets |
  _____
Total numbre of cross validation sets: 3
| Best Score |
Average Cross Validate scores of best estimator :
0.9045157780195865
LSTM
In [1]:
import pandas as pd
import numpy as np
In [2]:
# Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
   0: 'WALKING',
   1: 'WALKING UPSTAIRS',
   2: 'WALKING_DOWNSTAIRS',
   3: 'SITTING',
   4: 'STANDING',
   5: 'LAYING',
# Utility function to print the confusion matrix
def confusion matrix(Y true, Y pred):
   Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)])
   Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)])
   return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

macro avg 0.93 0.92 0.92 2947 weighted avg 0.93 0.92 0.92 2947

```
In [3]:
```

```
# Raw data signals
# Signals are from Accelerometer and Gyroscope
\# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
   "body acc x",
   "body_acc_y",
   "body acc z",
   "body_gyro_x",
   "body_gyro_y",
   "body_gyro_z",
   "total_acc_x",
   "total acc y",
   "total_acc_z"
]
```

#### In [4]:

```
# Utility function to read the data from csv file
def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

# Utility function to load the load
def load_signals(subset):
    signals_data = []

for signal in SIGNALS:
    filename = f'UCI_HAR_Dataset/{subset}/Inertial Signals/{signal}_{subset}.txt'
    signals_data.append(
        _read_csv(filename).to_numpy()
    )

# Transpose is used to change the dimensionality of the output,
# aggregating the signals by combination of sample/timestep.
# Resultant shape is (7352 train/2947 test samples, 128 timesteps, 9 signals)
    return np.transpose(signals_data, (1, 2, 0))
```

#### In [5]:

```
def load_y(subset):
    """
    The objective that we are trying to predict is a integer, from 1 to 6,
    that represents a human activity. We return a binary representation of
    every sample objective as a 6 bits vector using One Hot Encoding
    (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get_dummies.html)
    """
    filename = f'UCI_HAR_Dataset/{subset}/y_{subset}.txt'
    y = _read_csv(filename)[0]
    return pd.get_dummies(y).to_numpy()
```

#### In [6]:

```
def load_data():
    """
    Obtain the dataset from multiple files.
    Returns: X_train, X_test, y_train, y_test
    """

X_train, X_test = load_signals('train'), load_signals('test')
    y_train, y_test = load_y('train'), load_y('test')

return X_train, X_test, y_train, y_test
```

#### In [7]:

```
# Importing tensorflow
np.random.seed(42)
import tensorflow as tf
```

```
IMPOIL CENSUITION as CI
tf.set_random_seed(42)
In [8]:
# Configuring a session
session conf = tf.ConfigProto(
    intra op parallelism threads=1,
    inter_op_parallelism_threads=1
In [9]:
# Import Keras
from keras import backend as K
sess = tf.Session(graph=tf.get_default_graph(), config=session_conf)
K.set_session(sess)
Using TensorFlow backend.
In [10]:
# Importing libraries
from keras.models import Sequential
\textbf{from keras.layers import} \ \texttt{LSTM}
from keras.layers.core import Dense, Dropout
In [11]:
# Initializing parameters
epochs = 50
batch size = 32
n hidden = 32
In [12]:
# Utility function to count the number of classes
def count classes(y):
    return len(set([tuple(category) for category in y]))
In [13]:
# Loading the train and test data
X_train, X_test, Y_train, Y_test = load_data()
In [14]:
timesteps = len(X_train[0])
input_dim = len(X_train[0][0])
n_classes = _count_classes(Y_train)
print(timesteps)
print(input_dim)
print(len(X_train))
128
7352
```

## Model 1

## LSTM - Dropout(0.5) - Dense

In [20]:

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(n_hidden, input_shape=(timesteps, input_dim)))
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()
```

#### Model: "sequential 1"

Layer (type)	Output Shape	Param #
lstm_1 (LSTM)	(None, 32)	5376
dropout_1 (Dropout)	(None, 32)	0
dense_1 (Dense)	(None, 6)	198
Total params: 5,574 Trainable params: 5,574 Non-trainable params: 0		

#### In [21]:

#### In [22]:

```
WARNING:tensorflow:From C:\Users\sanjeev\Anaconda3\lib\site-
packages\tensorflow\python\ops\math_grad.py:1250: add_dispatch_support.<locals>.wrapper (from
tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where
WARNING:tensorflow:From C:\Users\sanjeev\Anaconda3\lib\site-
packages\keras\backend\tensorflow backend.py:422: The name tf.global variables is deprecated. Plea
se use tf.compat.v1.global variables instead.
Train on 7352 samples, validate on 2947 samples
Epoch 1/30
loss: 1.0891 - val accuracy: 0.5565
Epoch 2/30
7352/7352 [============== ] - 26s 4ms/step - loss: 0.9056 - accuracy: 0.6171 - val
loss: 0.8277 - val accuracy: 0.5942
Epoch 3/30
loss: 0.7569 - val_accuracy: 0.6230
Epoch 4/30
7352/7352 [============== ] - 27s 4ms/step - loss: 0.6725 - accuracy: 0.6800 - val
loss: 0.6941 - val accuracy: 0.6651
Epoch 5/30
loss: 0.6568 - val_accuracy: 0.7326
Epoch 6/30
7352/7352 [=============== ] - 27s 4ms/step - loss: 0.5866 - accuracy: 0.7333 - val_
loss: 0.7696 - val accuracy: 0.6763
Epoch 7/30
7352/7352 [============== ] - 27s 4ms/step - loss: 0.5055 - accuracy: 0.7748 - val_
loss: 0.6162 - val_accuracy: 0.7272
Epoch 8/30
```

```
loss: 0.5323 - val accuracy: 0.7465
Epoch 9/30
loss: 0.6893 - val accuracy: 0.7167
Epoch 10/30
loss: 0.5631 - val accuracy: 0.7326
Epoch 11/30
loss: 0.5226 - val_accuracy: 0.7937
Epoch 12/30
loss: 0.5721 - val accuracy: 0.8694
Epoch 13/30
loss: 0.4536 - val accuracy: 0.8812
Epoch 14/30
loss: 0.5414 - val accuracy: 0.8748
Epoch 15/30
loss: 0.4205 - val_accuracy: 0.8968
Epoch 16/30
loss: 0.4868 - val_accuracy: 0.8785
Epoch 17/30
loss: 0.5625 - val_accuracy: 0.8833
Epoch 18/30
loss: 0.6079 - val_accuracy: 0.8738
Epoch 19/30
loss: 0.4497 - val_accuracy: 0.8999
Epoch 20/30
loss: 0.5215 - val accuracy: 0.8795
Epoch 21/30
loss: 0.4698 - val accuracy: 0.8887
Epoch 22/30
loss: 0.4783 - val accuracy: 0.8795
Epoch 23/30
loss: 0.4126 - val accuracy: 0.8968
Epoch 24/30
loss: 0.3679 - val accuracy: 0.9111
Epoch 25/30
loss: 0.9810 - val_accuracy: 0.8426
Epoch 26/30
loss: 0.3639 - val_accuracy: 0.9043
Epoch 27/30
loss: 0.3858 - val_accuracy: 0.8996
Epoch 28/30
loss: 0.4374 - val_accuracy: 0.9013
Epoch 29/30
loss: 0.3596 - val_accuracy: 0.9043
Epoch 30/30
loss: 0.4166 - val accuracy: 0.8955
```

#### Out[22]:

<keras.callbacks.callbacks.History at 0x2e063805ba8>

## In [23]:

```
# Confusion Matrix
print(confusion matrix(Y test. model.predict(X test)))
```

```
princ(contactor_macrin(r_cooc, moder.prodicc(n_cooc, , ,
                 LAYING SITTING STANDING WALKING WALKING DOWNSTAIRS
Pred
True
                            0
                    510
                                     27
                                              0
                                                                 0
LAYING
                                   105
                                             1
                           381
                    2
SITTING
                                                                 1
                           86
STANDING
                      0
                                     446
                                                                 0
                                     0
0
                     0
                             0
                                            454
                                                                1.5
WALKING
                                      0 0
0 4
WALKING DOWNSTAIRS
                                                                419
WALKING_UPSTAIRS
                     0
                             7
                                                                 31
Pred
                 WALKING UPSTAIRS
True
                               0
LAYING
SITTING
                               Ω
STANDING
WALKING
                              27
WALKING DOWNSTAIRS
WALKING UPSTAIRS
                             429
In [24]:
score = model.evaluate(X test, Y test)
2947/2947 [============== ] - 1s 463us/step
In [25]:
score
Out[25]:
[0.41655886096877154, 0.8954869508743286]
```

## Model 2

## LSTM(32) - Dropout - LSTM(64) - Dropout - Dense

In [15]:

```
from keras.layers.normalization import BatchNormalization
```

In [37]:

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(n_hidden,return_sequences=True,input_shape=(timesteps, input_dim)))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(64))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n classes, activation='sigmoid'))
model.summary()
```

Model: "sequential\_7"

Layer (type)	Output	Shape	e	Param #
lstm_11 (LSTM)	(None,	128,	32)	5376
hotah namalization 7 (Datah	/None	1 2 0	221	120

```
Datch_Hormatization_/ (Batch (None, 120, 32)
                                                         140
                              (None, 128, 32)
dropout 8 (Dropout)
                                                         0
1stm 12 (LSTM)
                                                         24832
                              (None, 64)
batch normalization 8 (Batch (None, 64)
                                                         256
dropout 9 (Dropout)
                              (None, 64)
dense 4 (Dense)
                              (None, 6)
                                                         390
Total params: 30,982
Trainable params: 30,790
Non-trainable params: 192
```

#### In [38]:

#### In [39]:

```
# Training the model
model.fit(X train,
      Y train,
     batch size=batch size,
     validation data=(X test, Y test),
      epochs=epochs)
Train on 7352 samples, validate on 2947 samples
Epoch 1/30
7352/7352 [============= ] - 67s 9ms/step - loss: 0.9396 - accuracy: 0.6396 - val
loss: 0.9047 - val accuracy: 0.6040
Epoch 2/30
loss: 0.6003 - val accuracy: 0.7791
Epoch 3/30
7352/7352 [==========] - 65s 9ms/step - loss: 0.4637 - accuracy: 0.8509 - val
loss: 0.4141 - val accuracy: 0.8785
Epoch 4/30
loss: 0.3885 - val accuracy: 0.8996
Epoch 5/30
loss: 0.4202 - val_accuracy: 0.8890
Epoch 6/30
loss: 0.4281 - val accuracy: 0.8992
Epoch 7/30
7352/7352 [============= ] - 62s 8ms/step - loss: 0.1949 - accuracy: 0.9348 - val_
loss: 0.4892 - val accuracy: 0.8924
Epoch 8/30
loss: 0.3084 - val_accuracy: 0.9175
Epoch 9/30
loss: 0.4832 - val accuracy: 0.9070
Epoch 10/30
7352/7352 [============= ] - 65s 9ms/step - loss: 0.1737 - accuracy: 0.9388 - val
loss: 0.3536 - val accuracy: 0.9162
Epoch 11/30
loss: 0.3456 - val accuracy: 0.9057
Epoch 12/30
7352/7352 [============= ] - 66s 9ms/step - loss: 0.1620 - accuracy: 0.9441 - val
loss: 0.2723 - val_accuracy: 0.9233
Epoch 13/30
loss: 0.4087 - val_accuracy: 0.9141
Epoch 14/30
7352/7352 [============= ] - 65s 9ms/step - loss: 0.1666 - accuracy: 0.9445 - val
```

```
_____
                        loss: 0.4055 - val_accuracy: 0.9158
Epoch 15/30
loss: 0.3386 - val accuracy: 0.9148
Epoch 16/30
loss: 0.4195 - val accuracy: 0.9206
Epoch 17/30
loss: 0.4564 - val accuracy: 0.9152
Epoch 18/30
loss: 0.3679 - val_accuracy: 0.9237
Epoch 19/30
loss: 0.4656 - val_accuracy: 0.9074
Epoch 20/30
loss: 0.3913 - val_accuracy: 0.8334
Epoch 21/30
loss: 0.5133 - val_accuracy: 0.9070
Epoch 22/30
loss: 0.5740 - val accuracy: 0.9097
Epoch 23/30
loss: 0.4876 - val accuracy: 0.9135
Epoch 24/30
loss: 0.3887 - val accuracy: 0.9230
Epoch 25/30
7352/7352 [============ ] - 65s 9ms/step - loss: 0.1593 - accuracy: 0.9448 - val
loss: 0.4500 - val accuracy: 0.9108
Epoch 26/30
loss: 0.3703 - val accuracy: 0.9158
Epoch 27/30
loss: 0.4475 - val accuracy: 0.9162
Epoch 28/30
loss: 0.6044 - val_accuracy: 0.9030
Epoch 29/30
7352/7352 [============= ] - 65s 9ms/step - loss: 0.1440 - accuracy: 0.9455 - val
loss: 0.5156 - val_accuracy: 0.9094
Epoch 30/30
loss: 0.4488 - val_accuracy: 0.9101
```

#### Out[39]:

<keras.callbacks.callbacks.History at 0x2e06a8afc50>

#### In [40]:

```
# Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))
```

Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS	١
True						
LAYING	537	0	0	0	0	
SITTING	4	376	111	0	0	
STANDING	0	89	443	0	0	
WALKING	0	1	0	469	10	
WALKING_DOWNSTAIRS	0	0	0	4	408	
WALKING_UPSTAIRS	0	2	0	0	20	

Pred	WALKING_UPSTAIRS
True	
LAYING	0
SITTING	0
STANDING	0
WALKING	16
WALKING DOWNSTAIRS	8

```
WALKING UPSTAIRS
```

```
449
```

```
In [41]:
```

#### In [42]:

```
score
```

#### Out[42]:

[0.44884221508369054, 0.9100780487060547]

## Model 3

LSTM(32) - BatchNorm - Dropout(0.5) - LSTM(100) - BatchNorm - Dropout(0.5) - LSTM(200) - BatchNorm - Dropout(0.5) - LSTM(300) - BatchNorm - Dropout(0.5) - Dense

#### In [43]:

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(n hidden,return sequences=True,input shape=(timesteps, input dim)))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(100, return sequences=True))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
model.add(LSTM(200,return sequences=True))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
model.add(LSTM(300))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()
```

## Model: "sequential\_8"

Layer (type)	Output	Shap	е	Param #
lstm_13 (LSTM)	(None,	128,	32)	5376
batch_normalization_9 (Batch	(None,	128,	32)	128
dropout_10 (Dropout)	(None,	128,	32)	0
lstm_14 (LSTM)	(None,	128,	100)	53200
batch_normalization_10 (Batc	(None,	128,	100)	400
dropout_11 (Dropout)	(None,	128,	100)	0
lstm_15 (LSTM)	(None,	128,	200)	240800

<pre>batch_normalization_11 (Batc</pre>	(None,	128,	200)	800
dropout_12 (Dropout)	(None,	128,	200)	0
lstm_16 (LSTM)	(None,	300)		601200
batch_normalization_12 (Batc	(None,	300)		1200
dropout_13 (Dropout)	(None,	300)		0
dense_5 (Dense)	(None,	6)		1806
Total params: 904,910 Trainable params: 903,646 Non-trainable params: 1,264				

#### In [44]:

#### In [45]:

```
\label{eq:model_fit} \begin{tabular}{ll} history = model.fit(X\_train,Y\_train,batch\_size=batch\_size,validation\_data=(X\_test, Y\_test),epochs=epochs) \end{tabular}
```

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/30
7352/7352 [=========== ] - 515s 70ms/step - loss: 0.8332 - accuracy: 0.6087 - va
l loss: 0.7015 - val accuracy: 0.6098
Epoch 2/30
7352/7352 [============= ] - 498s 68ms/step - loss: 0.7708 - accuracy: 0.6113 - va
1 loss: 0.7959 - val accuracy: 0.6281
Epoch 3/30
1 loss: 0.7227 - val accuracy: 0.6288
Epoch 4/30
7352/7352 [============== ] - 511s 70ms/step - loss: 0.7135 - accuracy: 0.6319 - va
1 loss: 0.7020 - val accuracy: 0.6386
Epoch 5/30
7352/7352 [============== ] - 513s 70ms/step - loss: 0.7044 - accuracy: 0.6332 - va
1 loss: 0.7842 - val accuracy: 0.6135
Epoch 6/30
7352/7352 [============ ] - 509s 69ms/step - loss: 0.7032 - accuracy: 0.6245 - va
1 loss: 0.9970 - val accuracy: 0.5948
Epoch 7/30
7352/7352 [============ ] - 505s 69ms/step - loss: 0.7214 - accuracy: 0.6477 - va
l loss: 0.7416 - val accuracy: 0.6335
Epoch 8/30
7352/7352 [============ ] - 502s 68ms/step - loss: 0.6798 - accuracy: 0.6385 - va
1 loss: 0.8528 - val_accuracy: 0.6186
Epoch 9/30
l loss: 0.7832 - val accuracy: 0.6417
Epoch 10/30
7352/7352 [============= ] - 495s 67ms/step - loss: 0.6746 - accuracy: 0.6382 - va
1_loss: 0.7355 - val_accuracy: 0.5955
Epoch 11/30
7352/7352 [============== ] - 500s 68ms/step - loss: 0.7036 - accuracy: 0.6310 - va
l loss: 0.6798 - val accuracy: 0.6121
Epoch 12/30
7352/7352 [============ ] - 519s 71ms/step - loss: 0.6016 - accuracy: 0.6672 - va
1 loss: 0.7377 - val_accuracy: 0.5843
Epoch 13/30
7352/7352 [============== ] - 507s 69ms/step - loss: 0.4163 - accuracy: 0.8618 - va
l loss: 0.4842 - val accuracy: 0.8476
Epoch 14/30
1 loss: 0.4826 - val accuracy: 0.8829
Epoch 15/30
7352/7352 [============== ] - 556s 76ms/step - loss: 0.2322 - accuracy: 0.9163 - va
1 loce · 0 3081 - wal accuracy · 0 8856
```

```
1 1055. U.JJUI - VAI ACCUIACY. U.UUJU
Epoch 16/30
val loss: 0.3468 - val accuracy: 0.9067
Epoch 17/30
1 loss: 0.2879 - val accuracy: 0.9203
Epoch 18/30
7352/7352 [============= ] - 503s 68ms/step - loss: 0.1901 - accuracy: 0.9279 - va
1 loss: 0.3502 - val accuracy: 0.9175
Epoch 19/30
7352/7352 [============== ] - 498s 68ms/step - loss: 0.1929 - accuracy: 0.9323 - va
1 loss: 0.2692 - val accuracy: 0.9186
Epoch 20/30
1 loss: 0.2513 - val accuracy: 0.9182
Epoch 21/30
7352/7352 [============= ] - 496s 67ms/step - loss: 0.1805 - accuracy: 0.9340 - va
1_loss: 0.2996 - val_accuracy: 0.9206
Epoch 22/30
7352/7352 [============= ] - 495s 67ms/step - loss: 0.1884 - accuracy: 0.9385 - va
1_loss: 0.4036 - val_accuracy: 0.9169
Epoch 23/30
7352/7352 [============ ] - 497s 68ms/step - loss: 0.1819 - accuracy: 0.9312 - va
1_loss: 0.3592 - val_accuracy: 0.9074
Epoch 24/30
1 loss: 0.3478 - val_accuracy: 0.9063
Epoch 25/30
l loss: 0.2414 - val accuracy: 0.9162
Epoch 26/30
1 loss: 0.3426 - val accuracy: 0.9091
Epoch 27/30
l loss: 0.3108 - val accuracy: 0.9145
Epoch 28/30
7352/7352 [=============== ] - 495s 67ms/step - loss: 0.1781 - accuracy: 0.9366 - va
1 loss: 0.3854 - val accuracy: 0.9121
Epoch 29/30
7352/7352 [============= ] - 510s 69ms/step - loss: 0.1730 - accuracy: 0.9388 - va
1 loss: 0.2765 - val accuracy: 0.9250
Epoch 30/30
7352/7352 [============== ] - 497s 68ms/step - loss: 0.1574 - accuracy: 0.9354 - va
l loss: 0.3217 - val accuracy: 0.9172
```

#### In [46]:

```
# Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))
```

Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS	\
True						
LAYING	537	0	0	0	0	
SITTING	5	380	106	0	0	
STANDING	0	93	439	0	0	
WALKING	0	0	0	456	23	
WALKING_DOWNSTAIRS	0	0	0	0	420	
WALKING_UPSTAIRS	0	0	0	0	0	

Pred	WALKING_UPSTAIRS
True	
LAYING	0
SITTING	0
STANDING	0
WALKING	17
WALKING_DOWNSTAIRS	0
WALKING UPSTAIRS	471

#### In [47]:

## Model 4

### **LSTM**

In [16]:

```
from keras.callbacks import EarlyStopping, ModelCheckpoint
```

#### In [17]:

```
# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(n_hidden,return_sequences=True,input_shape=(timesteps, input_dim)))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(64,return sequences=True))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(128,return sequences=True))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(256,return sequences=True))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding LSTM layer
model.add(LSTM(512))
# Adding batch normalization layer
model.add(BatchNormalization())
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()
```

## Model: "sequential\_1"

Layer (type)	Output	Shape	е	Param #
lstm_1 (LSTM)	(None,	128,	32)	5376
batch_normalization_1 (Batch	(None,	128,	32)	128
dropout_1 (Dropout)	(None,	128,	32)	0
lstm_2 (LSTM)	(None,	128,	64)	24832
batch_normalization_2 (Batch	(None,	128,	64)	256

dropout_2 (Dropout)	(None,	128,	64)	0
lstm_3 (LSTM)	(None,	128,	128)	98816
batch_normalization_3 (Batch	(None,	128,	128)	512
dropout_3 (Dropout)	(None,	128,	128)	0
lstm_4 (LSTM)	(None,	128,	256)	394240
batch_normalization_4 (Batch	(None,	128,	256)	1024
dropout_4 (Dropout)	(None,	128,	256)	0
lstm_5 (LSTM)	(None,	512)		1574912
batch_normalization_5 (Batch	(None,	512)		2048
dropout_5 (Dropout)	(None,	512)		0
dense_1 (Dense)	(None,	6)		3078
Total params: 2,105,222 Trainable params: 2,103,238 Non-trainable params: 1,984				

Non-trainable params: 1,984

#### In [18]:

```
# Compiling the model
model.compile(loss='categorical crossentropy',optimizer='adam',metrics=['accuracy'])
```

#### In [19]:

```
es = EarlyStopping(monitor='val loss', mode='min', verbose=1, patience=10, min delta=0.0001,restore
best weights=True)
mc = ModelCheckpoint('best model.hdf5', monitor='val acc', verbose=1, save best only=True, mode='ma
x')
```

## In [20]:

```
history = model.fit(X train,Y train,batch size=batch size,validation data=(X test, Y test),epochs=e
pochs, callbacks=[es, mc])
```

WARNING:tensorflow:From C:\Users\sanjeev\Anaconda3\lib\sitepackages\tensorflow\python\ops\math grad.py:1250: add dispatch support.<locals>.wrapper (from

tensorflow.python.ops.array\_ops) is deprecated and will be removed in a future version.

Instructions for updating: Use tf.where in 2.0, which has the same broadcast rule as np.where

WARNING:tensorflow:From C:\Users\sanjeev\Anaconda3\lib\site-

packages\keras\backend\tensorflow backend.py:422: The name tf.global variables is deprecated. Plea se use tf.compat.vl.global variables instead.

Train on 7352 samples, validate on 2947 samples

Epoch 1/50

al\_loss: 1.7162 - val\_accuracy: 0.4744

Epoch 2/50

C:\Users\sanjeev\Anaconda3\lib\site-packages\keras\callbacks.py:707: RuntimeWarning: Can save best model only with val acc available, skipping. 'skipping.' % (self.monitor), RuntimeWarning)

```
7352/7352 [============ ] - 887s 121ms/step - loss: 0.7458 - accuracy: 0.6745 - v
al loss: 1.1356 - val accuracy: 0.5823
Epoch 3/50
7352/7352 [===========] - 1005s 137ms/step - loss: 0.7271 - accuracy: 0.7232 -
val loss: 0.7087 - val accuracy: 0.7163
Epoch 4/50
7352/7352 [============== ] - 12351s 2s/step - loss: 0.5814 - accuracy: 0.7556 - va
1 loss: 0.8868 - val accuracy: 0.6824
Epoch 5/50
```

```
7352/7352 [============] - 1056s 144ms/step - loss: 0.4730 - accuracy: 0.7780 -
val loss: 0.5698 - val accuracy: 0.7248
Epoch 6/50
7352/7352 [===========] - 1036s 141ms/step - loss: 0.4586 - accuracy: 0.7606 -
val_loss: 0.9700 - val_accuracy: 0.6576
Epoch 7/50
7352/7352 [===========] - 1029s 140ms/step - loss: 0.4553 - accuracy: 0.7722 -
val_loss: 0.4239 - val_accuracy: 0.7560
Epoch 8/50
7352/7352 [===========] - 1043s 142ms/step - loss: 0.4074 - accuracy: 0.7763 -
val_loss: 0.4408 - val_accuracy: 0.7523
Epoch 9/50
7352/7352 [============] - 1046s 142ms/step - loss: 0.4023 - accuracy: 0.7756 -
val loss: 0.6162 - val accuracy: 0.6932
Epoch 10/50
7352/7352 [==========] - 1040s 141ms/step - loss: 0.4209 - accuracy: 0.7666 -
val loss: 0.5086 - val accuracy: 0.7706
Epoch 11/50
7352/7352 [==========] - 1058s 144ms/step - loss: 0.4112 - accuracy: 0.7786 -
val loss: 0.4923 - val accuracy: 0.7621
Epoch 12/50
7352/7352 [===========] - 1020s 139ms/step - loss: 0.3832 - accuracy: 0.7867 -
val loss: 0.5143 - val accuracy: 0.7452
Epoch 13/50
7352/7352 [===========] - 1010s 137ms/step - loss: 0.3892 - accuracy: 0.7760 -
val loss: 0.5402 - val accuracy: 0.7727
Epoch 14/50
7352/7352 [===========] - 1007s 137ms/step - loss: 0.3729 - accuracy: 0.7931 -
val loss: 0.5458 - val accuracy: 0.7421
Epoch 15/50
7352/7352 [============] - 1007s 137ms/step - loss: 0.3883 - accuracy: 0.7905 -
val loss: 0.4959 - val accuracy: 0.7615
Epoch 16/50
7352/7352 [==========] - 1012s 138ms/step - loss: 0.3866 - accuracy: 0.7899 -
val_loss: 0.5622 - val_accuracy: 0.6892
Epoch 17/50
7352/7352 [==========] - 1007s 137ms/step - loss: 0.3369 - accuracy: 0.8694 -
val loss: 0.4182 - val_accuracy: 0.8697
Epoch 18/50
7352/7352 [============== ] - 1011s 138ms/step - loss: 0.2468 - accuracy: 0.9161 -
val loss: 0.2906 - val_accuracy: 0.9128
Epoch 19/50
7352/7352 [===========] - 1020s 139ms/step - loss: 0.1990 - accuracy: 0.9234 -
val loss: 0.2919 - val accuracy: 0.9162
Epoch 20/50
7352/7352 [===========] - 1029s 140ms/step - loss: 0.1864 - accuracy: 0.9278 -
val loss: 0.3058 - val accuracy: 0.9152
Epoch 21/50
7352/7352 [==========] - 1038s 141ms/step - loss: 0.1770 - accuracy: 0.9339 -
val_loss: 0.2002 - val_accuracy: 0.9403
Epoch 22/50
7352/7352 [==========] - 1017s 138ms/step - loss: 0.1723 - accuracy: 0.9362 -
val loss: 0.2493 - val accuracy: 0.9348
Epoch 23/50
7352/7352 [============] - 1015s 138ms/step - loss: 0.1633 - accuracy: 0.9285 -
val loss: 0.4483 - val accuracy: 0.8890
Epoch 24/50
7352/7352 [===========] - 1055s 144ms/step - loss: 0.1517 - accuracy: 0.9397 -
val loss: 0.4098 - val accuracy: 0.9036
Epoch 25/50
7352/7352 [===========] - 1224s 166ms/step - loss: 0.1499 - accuracy: 0.9381 -
val loss: 0.2804 - val accuracy: 0.9104
Epoch 26/50
7352/7352 [============] - 1052s 143ms/step - loss: 0.1937 - accuracy: 0.9348 -
val loss: 0.2311 - val accuracy: 0.9237
Epoch 27/50
7352/7352 [===========] - 1043s 142ms/step - loss: 0.1779 - accuracy: 0.9313 -
val_loss: 0.3720 - val_accuracy: 0.8690
Epoch 28/50
7352/7352 [===========] - 1033s 140ms/step - loss: 0.1602 - accuracy: 0.9372 -
val loss: 0.3132 - val_accuracy: 0.9121
Epoch 29/50
7352/7352 [=============] - 1033s 141ms/step - loss: 0.1646 - accuracy: 0.9388 -
val_loss: 0.2218 - val_accuracy: 0.9203
Epoch 30/50
7352/7352 [===========] - 1023s 139ms/step - loss: 0.1479 - accuracy: 0.9402 -
val loss: 0.2908 - val accuracy: 0.8989
```

```
Epoch 31/50
l loss: 0.3713 - val accuracy: 0.9026
Restoring model weights from the end of the best epoch
Epoch 00031: early stopping
In [21]:
# Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))
Pred
              LAYING SITTING STANDING WALKING WALKING DOWNSTAIRS \
True
                  537
                         0
                                 0
                                        0
LAYING
                                                         0
SITTING
                  19
                        412
                                 59
                                        0
                                                        1
                                        0
                         72
                                                        0
STANDING
                   0
                                460
WALKING
                   1
                         0
                                0
                                      492
                                                        0
                                       0
WALKING DOWNSTAIRS
                         0
                                 0
                                                       413
                                 0
                  0
                         0
                                       4
                                                       10
WALKING_UPSTAIRS
Pred
               WALKING UPSTAIRS
True
LAYING
SITTING
                           0
STANDING
                           0
WALKING
                           3
WALKING DOWNSTAIRS
WALKING UPSTAIRS
                         457
In [22]:
score = model.evaluate(X_test, Y_test)
In [23]:
score
Out[23]:
[0.20017623385080346, 0.9402782320976257]
In [ ]:
Results
```

In [66]:

#### In [24]:

```
from prettytable import PrettyTable

table = PrettyTable()
table.field_names = ["Model","LSTM Layers","Optimizer","Accuracy","Loss"]
table.add_row([1,1,"rmsprop",89.54,0.41])
table.add_row([2,2,"rmsprop",91.01,0.44])
table.add_row([3,4,"rmsprop",91.72,0.32])
table.add_row([4,4,"adam",94.02,0.20])

print(table.get_string(title="LSTM Model Results"))
```

LSTM Model Results							
Model	LSTM Layers	Optimizer	Accuracy	Loss			
1   1   1   2   1   3   1   4   1	1 2 4 4	rmsprop   rmsprop   rmsprop   adam	89.54   91.01   91.72   94.02	0.41   0.44   0.32   0.2			

## Conclusion

LinearSVC has given best accuracy 94.6 in ML models. LSTM with 4 layers has given best accuracy 94.02 and loss 0.2