

Sanjeew Kanagaraj

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WORK EXPERIENCE

EPropulsion

Robotics Engineer

June 2023 - Present

- Acted as **Product Lead for the Advanced Driver Assistance (ADAS) team**; interfaced directly with end-users to define features and translated needs into technical roadmaps **driving a 2.5x increase in user adoption across 20 countries**.
- Led the design and development of **patented algorithms** for ADAS features - including **virtual anchor, heading hold, and 360° joystick control** - written using **C++** and achieving **operational accuracy of over 90%**
- Redesigned and optimised firmware architecture written using **ROS2, C++ and Python**, boosting **runtime efficiency by 40%** and reducing **improving system latency by 30%**
- Developed a prototype of an **autonomous navigation system for boats with minimal hardware**, using a combination of traditional methods and reinforcement learning techniques and **achieving path accuracy of 85%**

Rice Robotics

Robotics Engineer

April 2021 - March 2023

- Developed multimedia pipelines to enable **teleoperation, 4K video streaming, recording, two-way intercom** and **deep learning inference** using **Gstreamer, AsyncIO, Python** and **TypeScript**, reducing processing and memory requirements **by up to 80%**
- Led the training and optimisation of computer vision models to perform various tasks including **mask, gate** and **intruder detection**, achieving **over 90% accuracy** on edge using **PyTorch, ONNX, OpenVINO** and **Google Cloud**
- Improved self docking success rate** by implementing a 'graceful' controller for parking at firmware level using **C++ and ROS**

Robot Data

Software Engineering Intern

Sept 2020 - April 2021

- Developed computer vision models for real world use cases using **Tensorflow** and **PyTorch**; optimised and deployed inference on edge devices using **Docker, TensorRT** and **Nvidia DeepStream SDK**
- Trained U-Net and PraNet image segmentation models to detect tumors in ultrasound scans, **achieving DICE accuracy of 92%**

Hanson Robotics

Robotics Engineering Intern

June 2020 - Sept 2020

- Co-authored paper titled **A Neuro-Symbolic Humanlike Arm Controller for Sophia the Robot**, researching the use of Convolution Neural Networks coupled with symbolic AI for object grasping (<https://arxiv.org/abs/2010.13983>)
- Implemented AI behaviour tree algorithms and integrated with the Hanson Robotics SDK **reducing interaction delay by 50%**

EDUCATION

University of Hong Kong

Bachelor of Engineering, Computer Engineering

September 2017 - May 2021

Courses: Computer vision, Machine Learning, AI and Robotics, OOP, Operating Systems, Data Structures, Networking, Digital system design

SKILLS

Languages: C++, C, Python, Bash, Java, Go

Frameworks: ROS2, PyTorch, Transformers, HuggingFace, OpenCV2, ONNX, TensorRT, Django, Docker, RayLib

PROJECTS AND RESEARCH

- Times-New-RPG:** 2D RPG with time-loop-based plot built from scratch. Game bosses trained using reinforcement learning algorithms for continuous improvement against players. *Stack: RayLib, C++*
- NewsCrunch:** Summarisation and classification of daily news scraped from reputable outlets, using a combination of extractive summarisation and custom trained LLM based abstractive summarisation *Stack: Django, PyTorch, Transformers, PostgreSQL*
- Federated Learning in Robots:** Continuous improvement of human robot interaction on the NAO robot using a novel Federated Learning framework to retrain a Seq2Seq chatbot and face detection model *Stack: PyTorch, Networks, OpenCV*
- PointpillarsNet:** Research into implementation and optimisation of PointPillars point cloud object detection model on FPGA boards, conducted under the supervision of Dr. Ngai Wong *Stack: PyTorch, VitisAI*

AWARDS

- HKU Foundation Scholarship covering tuition upon admission
- Awarded HKU Engineering Faculty best Final Year Project presentation
- Awarded a grant by the Gallant Ho Experiential Learning Fund to lead an interdisciplinary team researching marine conservation methods in partnership with the University of the Philippines
- Funding to conduct research on marine robotics at the HKU Innovation Wing