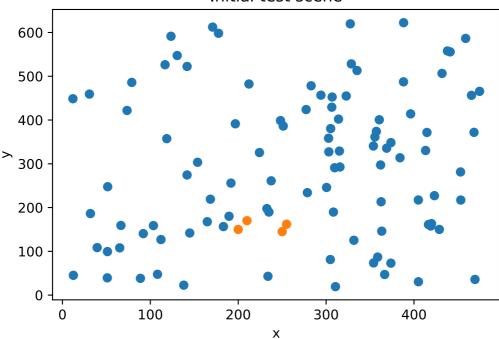
```
import numpy as np
In [1]:
          import matplotlib.pyplot as plt
In [28]:
          class Homography:
              def init (self, src, dst):
                  self.src = src
                  self.dst = dst
                  self.compute coefficents()
                  self.compute homography matrix()
              def get homography matrix(self):
                  return self.H
              def compute coefficents(self):
                  # print(X[:,0])
                  coeffs = []
                  X = self.src
                  Xprime = self.dst
                  for i in range(X.shape[0]):
                      x = X[i]
                      x prime = Xprime[i]
                       upper coeff = np.array([-x[0], -x[1], -1, 0, 0, 0, x \text{ prime}[0] * x[0],
                      lower_coeff = np.array([0, 0, 0, -x[0], -x[1], -1, x prime[1] * x
                       coeffs.append(upper coeff)
                       coeffs.append(lower coeff)
                  self.coeffs = np.array(coeffs)
              def compute homography matrix(self):
                  U, s, VT = np.linalg.svd(self.coeffs)
                  self.H = VT[-1].reshape(3, 3)
              def wrap perspective(self, points):
                  wrapped pts = self.H @ points.T
                  return wrapped pts / wrapped pts[-1:,:] #convert to homogeneous pts
          X = \text{np.array}([[200, 150, 1], [250, 145, 1], [210, 170, 1], [255, 162, 1]]);
In [29]:
          Xprime = np.array([[200, 150, 1], [250, 150, 1], [200, 170, 1], [250, 170, 1])
          x_pts = np.random.rand(100) * 480
          y pts = np.random.rand(100) * 640
          plt.scatter(x_pts, y_pts, label="Random points")
In [40]:
          plt.scatter(X[:,0], X[:,1], label="Source points")
          plt.xlabel('x')
          plt.ylabel('y')
          plt.title('Initial test scene')
          plt.show()
```

6/17/2021 refined\_solution





```
In [41]: homography = Homography(X, Xprime)
H = homography.get_homography_matrix()
print('Est homography matrix:', H)

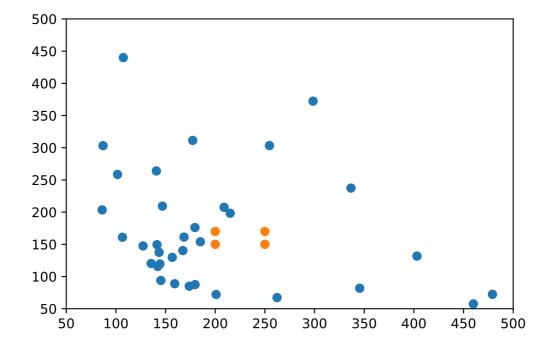
Est homography matrix: [[ 7.26577891e-05 -2.28489626e-03 8.90344723e-01]
```

[-1.34837560e-03 1.57361475e-03 4.55239290e-01] [-1.06309818e-05 -5.92734595e-06 5.82600746e-03]]

In [46]: random\_homogeneous\_pts = np.vstack((x\_pts, y\_pts, np.ones(x\_pts.shape[0]))).1
 wrapped\_pts = homography.wrap\_perspective(random\_homogeneous\_pts)
 wrapped\_src\_pts = homography.wrap\_perspective(X)

In [53]: plt.scatter(wrapped\_pts[0], wrapped\_pts[1], label="Random Points");
 plt.scatter(wrapped\_src\_pts[0], wrapped\_src\_pts[1], label="Homography matrix
 plt.xlim(50, 500)
 plt.ylim(50, 500)

Out[53]: (50.0, 500.0)



refined\_solution In [ ]: