Unit 5

Probabilistic Methods

Contents

- Introduction to Probabilistic Reasoning
- Bayes and Markov Network, DBN's and HMN's

- One of the most common characteristics of the human information available is its imperfection due to partial observability, non deterministic or combination of both
- An agent may not know what state it is in or will be after certain sequence of actions
- Agent can cope with these defects and make rational judgments and rational decisions to handle such uncertainty and draw valid conclusions

What is uncertainty?

- The lack of the exact knowledge that would enable us to reach a perfectly reliable conclusion
- Classical Logic permits only exact reasoning i.e. perfect knowledge always exists



 In Real world such clear cut knowledge could not be provided to systems

Sources of Uncertain Knowledge

- Weak Implication: Domain experts and knowledge engineer have rather painful or hopeless task of establishing concrete correlation between IF(Condition) and THEN(action) part of rules. Vague Data.
- Imprecise Language: NLP is ambiguous and imprecise. We define facts in terms of often, sometimes, frequently, hardly ever. Such can affect IF-THEN implication
- Unknown Data: incomplete and missing data should be processes to an approx. reasoning with this values
- Combining the views of different experts: Large system uses data from many experts

- The basic Concept of probability plays significant role in our life like we try to determine the probability of rain, prospect of promotion, likely hood of winning in Black Jack
- The probability of an event is the proportion of cases in which the event occurs (Good, 1959)
- Probability, mathematically, is indexed between 0 and 1
- Most events have probability index strictly between 0 and 1, which means that each event has at lease two possible outcomes: favourable outcome or success and unfavourable outcomes or failure

••Iff s is the amune bars of success cards is the fundamental modern of failure then:

$$P(success) = \frac{s}{s+f}$$

$$P(failure) = \frac{f}{s+f}$$

and and

$$p + q = 1$$

- •-Lettus consider calassaic examples within and and a wiethfoweathmy ather probability of getting a head will be equal to the probability of getting a the probability of getting a head will be equal to the probability of getting a fail in a single throw, s=f=1, and therefore the probability of getting a probability of getting a head (or a tail) is 0.5.
- · Consider now a different determine the threbability of the earth from o from a later throweous from the and a successor the section of the asinote the resimicat to merevery jours geotries was an object the care dive much the fre care probability of getting a 6 is $P = \frac{1}{1+5} = 0.1666$ fighet time yes 60 if na outing set till now a. Of hier af or a glad to broke billite reference for a continuous. Of hier af or a glad time a for a glad time a glad time a for a glad time a gl

Likewise, the probability ty for the probability of or the probability of order or the probability or the

$$q = \frac{5}{1+5} = 0.8333$$

- Above instances are for independent events i.e. mutually exclusive events which can not happen simultaneously
- In the dice experiment, the two events of obtaining a 6 and, for example, a 1 are mutually exclusive because we cannot obtain a 6 and a 1 simultaneously in a single throw. However, events that are not independent may affect the likelihood of one or the other occurring. Consider, for instance, the probability of getting a 6 in a single throw, knowing this time that a 1 has not come up. There are still five
 - ways of not getting a 6, but one of them can be eliminated as we know that a 1 has not been obtained. Thus,

- •• Let Aaand Be be two motumy thall sive x cluss, you to we not but acousticound it is to the local trice of other.
- •• Tithe parcobabilitivity extensive mill because if concentrate badecturs is content to the content of the conten

$$p(A|B) = \frac{the number of times A and B can occur}{the number of times B can occur}$$

 $p(A|B) = \frac{the \ number \ of \ times \ A \ and \ B \ can \ occur}{the \ number \ of \ times \ B \ can \ occur}$ The probability of both A and B will occur is called joint probability $(A \cap B)$

B) = $\frac{p(A \cap B)}{P(A \cap B)}$, the probability of A occurring given B has occurred probability of A occurring given B has occurred

, pt(PeA) rebability the probability in probabili

• Joint tyre bability is commutately thus

$$p(A \cap B) = p(B \cap A)$$

Therefore,

$$p(A \cap B) = p(B|A) * p(A)$$

Now the final equation becomes: Now the final equation becomes: $p(A|B) = \frac{p(B)}{p(B)} = \frac{p(B)}{p(B)}$

Where:

(APB) is the conditional probability that event A occurs given event B has occurred p(B|A) is the conditional probability that event B occurs given event A has occurred p(A) is the probability of event A occurring p(B) is the probability of event B occurring

The above equation (a) is known as **Bayesian Rule**

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For n number of mutually exclusive event B we have

$$p(A \cap B_1) = p(A|B_1) \times p(B_1)$$

$$p(A \cap B_2) = p(A|B_2) \times p(B_2)$$

$$\vdots$$

$$p(A \cap B_n) = p(A|B_n) \times p(B_n)$$

or when combined:

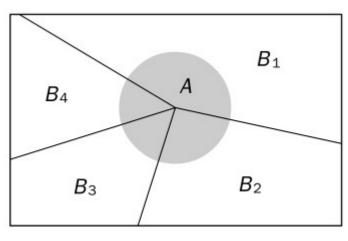
$$\sum_{i=1}^{n} p(A \cap B_i) = \sum_{i=1}^{n} p(A|B_i) \times p(B_i)$$

• Summed over an exhaustive list of events for Bi, we

$$\sum_{i=1}^n p(A \cap B_i) = p(A)$$

• Which radicas to

$$p(A) = \sum_{i=1}^{n} p(A|B_i) \times p(B_i)$$



The joint probability

 If the occurrence of A depends on only two mutually exclusive events, i.e. B and NOT B, then above equation

$$p(A) = p(A|B) \times p(B) + p(A|\neg B) \times p(\neg B)$$

$$p(B) = p(B|A) \times p(A) + p(B|\neg A) \times p(\neg A)$$

• $p(A|B) = \frac{p(B|A) \times p(A)}{p(B|A) \times p(A) + p(B|\neg A) \times p(\neg A)}$ ayesian Equation, We

THANK YOU