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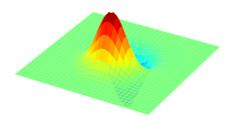
COURSE CODE: EN2550

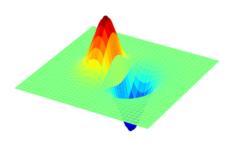
```
In [44]: #Importing Libraries
   import matplotlib.pyplot as plt
   from matplotlib import cm
   import numpy as np
   import cv2 as cv
   from skimage.feature import peak_local_max
In [2]: #q1
stan = 0.1
```

```
step = 0.1
X=np.arange(-5,5+step,step)
Y=np.arange(-5,5+step,step)
sigma=1
XX, YY =np.meshgrid(X,Y)
g=np.exp(-(XX**2+YY**2)/(2*sigma**2))
g=g/np.sum(g)
sobel_v=np.array([[-1,-2,-1],[0,0,0],[1,2,1]],dtype=np.float32)
sobel_h=np.array([[-1,0,1],[-2,0,2],[-1,0,1]],dtype=np.float32)
g_x=cv.filter2D(g,-1,sobel_v)
g_y=cv.filter2D(g,-1,sobel_h)
fig=plt.figure(figsize=(18,8))
ax1 =fig.add_subplot(121,projection='3d')
ax2 =fig.add_subplot(122,projection='3d')
surf = ax1.plot_surface(XX,YY,g_x, cmap=cm.jet,lineWidth=0,antialiased=True)
surf = ax2.plot_surface(XX,YY,g_y, cmap=cm.jet,lineWidth=0,antialiased=True)
ax1.axis('off')
ax1.set_title("$I_x$",fontsize=25,color='blue')
ax2.axis('off')
ax2.set_title("$I_y$",fontsize=25,color='blue')
plt.show()
```

<ipython-input-2-134e8fb36197>:22: MatplotlibDeprecationWarning: Case-insensitive pr
operties were deprecated in 3.3 and support will be removed two minor releases later
 surf = ax1.plot_surface(XX,YY,g_x, cmap=cm.jet,lineWidth=0,antialiased=True)
<ipython-input-2-134e8fb36197>:23: MatplotlibDeprecationWarning: Case-insensitive pr
operties were deprecated in 3.3 and support will be removed two minor releases later
 surf = ax2.plot_surface(XX,YY,g_y, cmap=cm.jet,lineWidth=0,antialiased=True)

 I_X I_Y





```
In [48]:
    f1=cv.imread(r'images/building.tif',cv.IMREAD_GRAYSCALE).astype(np.float32)
    assert f1 is not None
    fig, ax =plt.subplots(figsize=(6,6))
    ax.imshow(f1,cmap='gray',vmin=0,vmax=255)
    plt.axis("off")
    plt.title("ORIGINAL IMAGE")
    plt.show()
```

ORIGINAL IMAGE



```
In [19]: #question 2 : Harris Corner Detector
im=cv.imread('images/building.tif',cv.IMREAD_COLOR)
assert im is not None

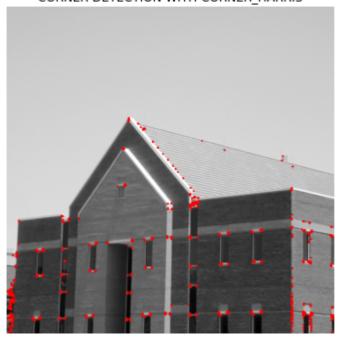
dst=cv.cornerHarris(f1,2,3,0.04)
dst=cv.dilate(dst,None)

im[dst>0.01*dst.max()]=[0,0,255]

fig, ax =plt.subplots(figsize=(6,6))
ax.imshow(cv.cvtColor(im, cv.COLOR_BGR2RGB))
```

```
ax.set_title("CORNER DETECTION WITH CORNER_HARRIS")
ax.axis("off")
plt.show()
```

CORNER DETECTION WITH CORNER HARRIS

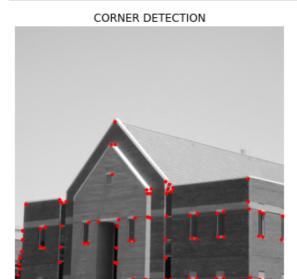


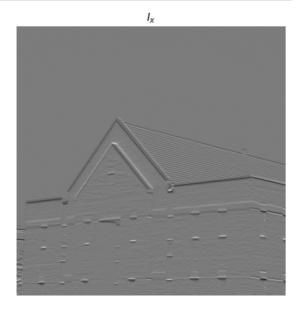
```
In [41]:
          #question 3 : own implementation
          #COMPUTING PARTIAL DERIVATIVE
          sobel_v=np.array([[-1,-2,-1],[0,0,0],[1,2,1]],dtype=np.float32)
          sobel_h=np.array([[-1,0,1],[-2,0,2],[-1,0,1]],dtype=np.float32)
          I_x=cv.filter2D(f1,-1,sobel_v)
          I_y=cv.filter2D(f1,-1,sobel_h)
          #COMPUTING SECOND MOMENT MATRIX
          sigma=3
          k_size=7
          m11=cv.GaussianBlur(I_x*I_x,(k_size,k_size),sigma)
          m12=cv.GaussianBlur(I x*I y,(k size,k size),sigma)
          m21=m12
          m22=cv.GaussianBlur(I_y*I_y,(k_size,k_size),sigma)
          #COMPUTING CORNER RESPONSE
          det=m11*m22-m12*m21
          trace=m11+m22
          alpha=0.04
          R=det-alpha*trace**2
          #THRESHOLDING CORNER RESPONSE
          R[R<1e8]=0
          #FINDING LOCAL MAXIMUM
          coordinates= peak_local_max (R,min_distance=2)
          fig, ax =plt.subplots(2,2,figsize=(12,12))
          ax[0,0].imshow(f1,cmap='gray')
          ax[0,0].plot(coordinates[:,1],coordinates[:,0],'r.')
          ax[0,0].set_title("CORNER DETECTION")
          ax[0,1].imshow(I_x+127,cmap='gray')
          ax[0,1].set_title("$I_x$")
          ax[1,0].imshow(I_y+127,cmap='gray')
```

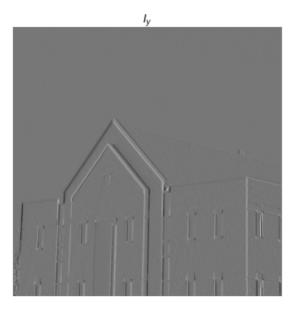
```
ax[1,0].set_title("$I_y$")
ax[1,1].imshow(R+127,cmap=cm.jet,vmin=0,vmax=255)
ax[1,1].set_title("R")

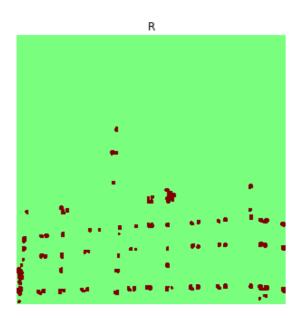
for i in range (4):
    ax[i//2][i%2].axis('off')
plt.show()

coordinates.size
```









Out[41]: 186

```
In [49]: #question 4
  edges=cv.Canny(f1,100,200) # low threshold and high threshold

fig, ax =plt.subplots(figsize=(6,6))
  ax.imshow(edges,cmap='gray',vmin=0,vmax=255)
  plt.axis("off")
  plt.show()
```

