

DESIGN AND IMPLEMENTATION OF INTELLIGENT MANHOLE COVER MONITORING SYSTEM BASED ON NARROW BAND (NB-IOT)

A PROJECT REPORT

Submitted by

SANJANA S	211419104231
SHAKTHI SRI S	211419104243
SARAH JACI J	211419104237

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(An Autonomous Institution, Affiliated to Anna University, Chennai)

BONAFIDE CERTIFICATE

Certified that this project report “**DESIGN AND IMPLEMENTATION OF INTELLIGENT MANHOLE COVER MONITORING SYSTEM BASED ON NARROW BAND (NB-IOT)**” is the bonafide work of “**SANJANA S(211419104231), SHAKTHI SRI S(211419104243) & SARAH JACI J(211419104237)**” who carried out the project work under my supervision.

SIGNATURE

**Dr.L.JABASHEELA,M.E.,Ph.D.,
HEAD OF THE DEPARTMENT**

DEPARTMENT OF CSE,
PANIMALAR ENGINEERING COLLEGE,
NASARATHPETTAI,
POONAMALLEE,
CHENNAI-600 123.

SIGNATURE

**M.MAHESWARI,M.E.,
SUPERVISOR
ASSISTANT PROFESSOR**

DEPARTMENT OF CSE,
PANIMALAR ENGINEERING COLLEGE,
NASARATHPETTAI,
POONAMALLEE,
CHENNAI-600 123.

Certified that the above candidate(s) was/ were examined in the **End Semester**
Project Viva-Voce Examination held on **11.04.23**

INTERNAL EXAMINER

EXTERNAL EXAMINER

DECLARATION BY THE STUDENT

We SANJANA S (211419104231), SHAKTHI SRI S (211419104243) & SARAH JACI J (211419104237) hereby declare that this project report titled “DESIGN AND IMPLEMENTATION OF INTELLIGENT MANHOLE COVER MONITORING SYSTEM BASED NARROW BAND (NB-IOT)” , under the guidance of M.MAHESWARI, M.E., is the original work done by us and we have not plagiarized or submitted to any other degree in any university by us.

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SANJANA S

SHAKTHI SRI S

SARAH JACI J

ABSTRACT

Recently, (Radio Frequency Identification) RFID based frameworks move beyond security to turn into tracking systems that integrate security with more proficient materials tracking inside the library, involving easier and quicker charging & discharging, materials handling and inventorying. In this study, a book tracking RFID-based system has been designed and developed to replace the existing library barcoding system. This system enables the librarians to minimize the spent time that is required for scanning barcodes during charging and discharging process. Further, this technology has been enhanced by robot features to identify the book. A smart city is the future goal to have cleaner and better amenities for the society. Smart underground infrastructure is an important feature to be considered while implementing a smart city. Drainage system monitoring plays a vital role in keeping the city clean and healthy. Since manual monitoring is incompetent, this leads to slow handling of problems in drainage and consumes more time to solve. To mitigate all these issues, the system using a wireless sensor network, consisting of sensor nodes is designed. The proposed system is low cost, low maintenance, ZIGBEE based real time which alerts transmit the managing station when any manhole crosses its threshold values. This system reduces the death risk of manual scavengers who clean the underground drainage and also benefits the public.

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LIST OF ABBREVIATIONS

SHORT FORM	ABBREVIATIONS
IOT	Internet of Things
LCD	Liquid Crystal Display
ISP	In System Programming
IDE	Integrated Development Environment
MCU	Microcontroller Unit
UART	Universal Asynchronous Receiver-Transmitter
GPIO	General Purpose Input Output
DHT	Digital Temperature and Humidity Sensor
SPL	Sound Pressure Level meter
GSM	Global System for Mobile communication
GPS	Global Positioning System

CHAPTER 1

INTRODUCTION

1.1 PROBLEM DEFINITION

Now a days manhole problems in the populated cities is the major issues. Opening of manholes due to breakage of manhole cover, manhole explosions are major threat in recent days. Manhole cover opening leads to accidental fall of vehicles, pedestrians leading to accidents or loss of life. Manhole opening detection and alerting is mainly based on detecting the manholes which are opened due to overflow of sewage rain water during heavy rainfall and alerting. When a manhole opening is detected either due to overflow of sewage water, increase in pressure or temperature, it leads to the breakage of the manhole lids. To avoid such incidents even before it could affect the public, an alerting system is built wherein the buzzer alerts the surrounding and sends the sensed data to the managing authorities using GSM techniques. So, they can take precautionary action to close the manhole considering public safety.

1.2 SCOPE OF THE PROJECT

The aim of our project is to clean the drainage and make a smart city in all over India.

CHAPTER 2

LITERATURE SURVEY

Title 1: Secure Manhole Monitoring System Employing Sensors and GSM Techniques

Author: Nataraja N, Amruthavarshini R, Chaitra N L, Jyothi K, Krupaa N, S S M Saqquaf.

Year : 2021

Description:

Manhole opening detection and alerting is mainly based on detecting the manholes which are opened due to overflow of sewage / rain water during heavy rainfall and alerting when a manhole opening is detected.

Advantages:

To avoid such incidents even before it could affect the public, an alerting system is built wherein the buzzer alerts the surrounding and sends the sensed data to the managing authorities using GSM techniques.

Disadvantages:

Overflow of sewage water, increase in pressure or temperature, it leads to the breakage of the manhole lids.

Title 2: Design and Implementation of Intelligent Manhole Cover Monitoring System Based on NB-IoT

Author: Guo Xiucan, Liu Bingbing, Wang Lili.

Year :2019

Description:

This paper designs an intelligent manhole cover monitoring system based on narrow band Internet of things (NB-IoT) technology.

Advantages:

The sensing layer is based on the embedded ARM microprocessor and combines sensor technology to collect the manhole cover data.

Disadvantages:

Immature technology and insufficient comprehensive analysis.

Title 3: On a Working Monitoring System of Manhole Wells Based on Technology of Internet of Things.

Author: Yunhong Xie, Hong Wang, Jiong Liu, Renpeng Zhang, Yong Guo

Year : 2018

Description:

This system researches and develops the intelligent monitoring system of manhole well, and realizes the monitoring of manhole well status based on the Internet of things technology.

Advantages:

The lock well cover and the alarm terminal perceive the change of the well cover state, send information to the application layer through the network and notify the user, and the user will process it accordingly.

Disadvantages:

The ground cable is usually laid in the underground pipeline, and the manhole is used as the entrance and exit of the pipeline for maintenance of pipeline and ground cable.

Title 4: An IoT Based Proposed System for Monitoring Manhole in Context of Bangladesh

Author: Saadnoor Salehin, Syeda Sabrina Akter, Anika Ibnat, Tasmiah Tamzid Anannya, Nurun Nahar Liya, Manisha Paramita, Md Mahboob Karim

Year : 2018

Description:

This paper presents an manhole monitoring system which detects harmful chemicals and toxic gases inside the manhole, generates an alarm to the passersby in that situation, alerts the authority about the system state.

Advantages:

The system has been implemented in an academic environment to carry out the automated monitoring of a manhole to evaluate the proposed features.

Disadvantages:

The concerned authorities can take proper measures to maintain the manhole.

Title 5: Research on an intelligent monitoring device for cable manhole covers

Author: ZHANG Chongbiao, QIN Mingbo, CHENG Long, GE Qi, SONG Jiajia , ZHANG Jinbo,

Year : 2018

Description:

This paper proposed an monitoring device which uses six axis sensors to monitor the attitude of the cable well covers. Once the attitude changes, it is sent to the supervisors' mobile phones through wireless network.

Advantages:

Timely monitor whether the cable manhole cover is moved artificially, which is of great significance to improve the safety of road driving.

Disadvantages:

The criminals are given the opportunity to steal covers and cables.

CHAPTER 3

SYSTEM ANALYSIS

3.1 EXISTING SYSTEM

- In Existing method, there is no alert for manhole cover and real-time data.
- The manhole cover opening doesn't have the proper maintenance.

3.1.1 EXISTING SYSTEM DISADVANTAGES

- Peoples fall down in the hole. And smell pollution in the opening areas.
- Manual monitoring leads to high human resource.

3.2 PROPOSED SYSTEM

- In proposed method, the narrow band technology used to connect all nodes into the single master to update the information.
- To prevent manhole accidents using sensor provide the proper data.

3.2.1 PROPOSED SYSTEM ADVANTAGES

- Reduce the human deaths in the drainage system.
- The monitoring system easy to handle.

CHAPTER 4

HARDWARE AND SOFTWARE DESCRIPTION

4.1 HARDWARE DESCRIPTION

4.1.1 ARDUINO

Arduino is an open-source electronics platform based on easy-to-use hardware and software. Arduino boards are able to read inputs – light on a sensor, a finger on a button, or a Twitter message – and turn it into an output – activating a motor, turning on an LED, publishing something online. You can tell your board what to do by sending a set of instructions to the microcontroller on the board.

4.1.1.1 ARDUINO MEGA

The MEGA 2560 is designed for more complex projects. With 54 digital I/O pins, 16 analog inputs and a larger space for your sketch it is the recommended board for 3D printers and robotics projects. This gives your projects plenty of room and opportunities.



TECHNICAL SPECIFICATIONS:

Microcontroller	<u>Atmega2560</u>
Operating Voltage	5V
Input Voltage (recommended)	7-12V
Input Voltage (limit)	6-20V
Digital I/O Pins	54 (of which 15 provide PWM output)
Analog Input Pins	16
DC Current per I/O Pin	20 Ma
DC Current for 3.3V Pin	50 Ma
Flash Memory	256 KB of which 8 KB used by boot loader
SRAM	8 KB
EEPROM	4 KB
Clock Speed	16 MHz
LED_BUILTIN	13
Length	101.52 mm
Width	53.3 mm
Weight	37 g

Table 4.1 Technical specification of ARDUINO MEGA

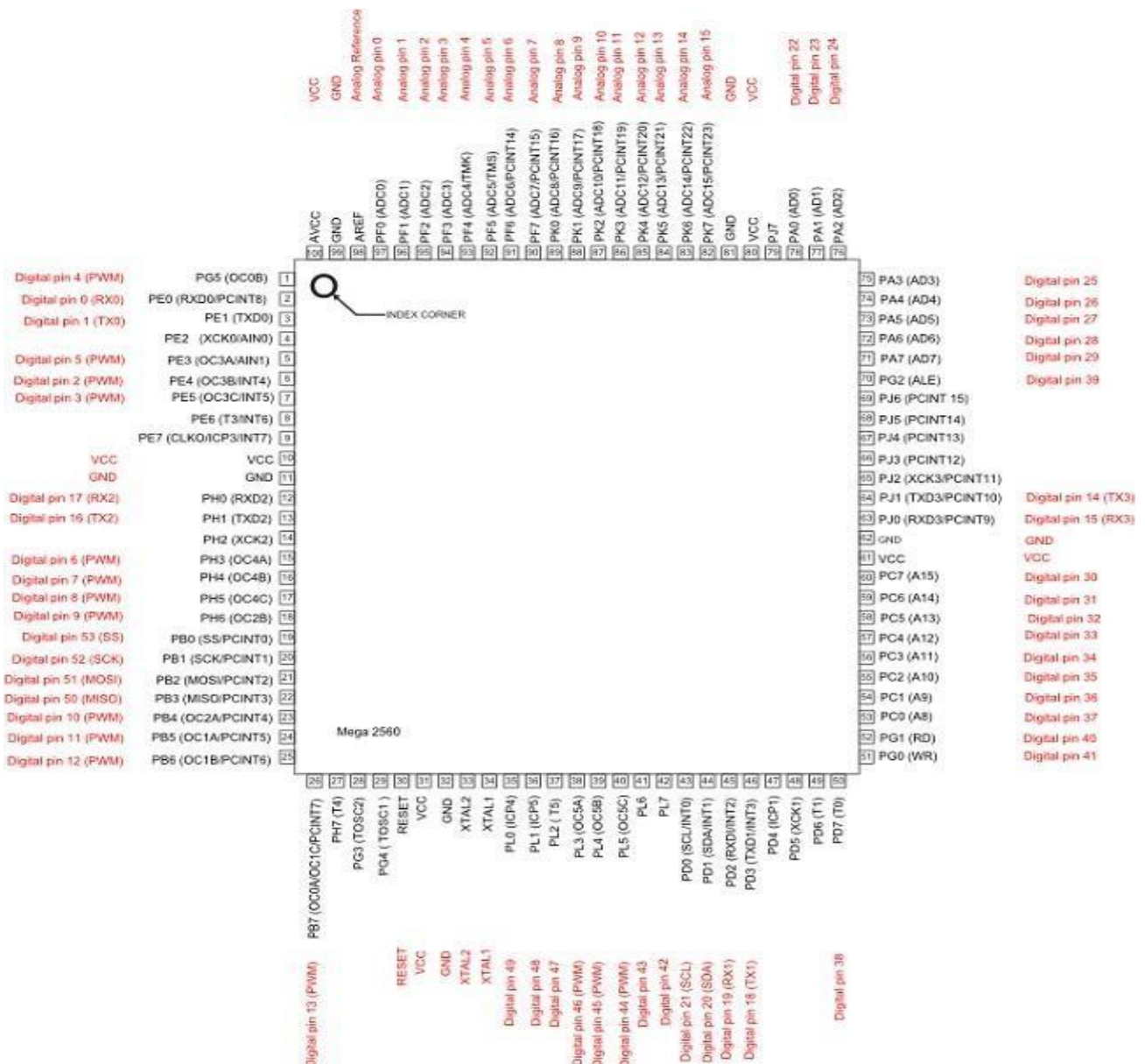


FIG 4.1 Arduino Mega 2560 PIN mapping

Pin Number	Pin Name	Mapped Pin Name
1	PG5 (OC0B)	Digital pin 4 (PWM)
2	PE0 (RXD0/PCINT8)	Digital pin 0 (RX0)
3	PE1 (TXD0)	Digital pin 1 (TX0)
4	PE2 (XCK0/AIN0)	

5	PE3 (OC3A/AIN1)	Digital pin 5 (PWM)
6	PE4 (OC3B/INT4)	Digital pin 2 (PWM)
7	PE5 (OC3C/INT5)	Digital pin 3 (PWM)
8	PE6 (T3/INT6)	
9	PE7 (CLKO/ICP3/INT7)	
10	VCC	VCC
11	GND	GND
12	PH0 (RXD2)	Digital pin 17 (RX2)
13	PH1 (TXD2)	Digital pin 16 (TX2)
14	PH2 (XCK2)	
15	PH3 (OC4A)	Digital pin 6 (PWM)
16	PH4 (OC4B)	Digital pin 7 (PWM)
17	PH5 (OC4C)	Digital pin 8 (PWM)
18	PH6 (OC2B)	Digital pin 9 (PWM)
19	PB0 (SS/PCINT0)	Digital pin 53 (SS)
20	PB1 (SCK/PCINT1)	Digital pin 52 (SCK)
21	PB2 (MOSI/PCINT2)	Digital pin 51 (MOSI)
22	PB3 (MISO/PCINT3)	Digital pin 50 (MISO)
23	PB4 (OC2A/PCINT4)	Digital pin 10 (PWM)
24	PB5 (OC1A/PCINT5)	Digital pin 11 (PWM)
25	PB6 (OC1B/PCINT6)	Digital pin 12 (PWM)

26	PB7 (OC0A/OC1C/PCINT7)	Digital pin 13 (PWM)
27	PH7 (T4)	
28	PG3 (TOSC2)	
29	PG4 (TOSC1)	
30	RESET	RESET
31	VCC	VCC
32	GND	GND
33	XTAL2	XTAL2
34	XTAL1	XTAL1
35	PL0 (ICP4)	Digital pin 49
36	PL1 (ICP5)	Digital pin 48
37	PL2 (T5)	Digital pin 47
38	PL3 (OC5A)	Digital pin 46 (PWM)
39	PL4 (OC5B)	Digital pin 45 (PWM)
40	PL5 (OC5C)	Digital pin 44 (PWM)
41	PL6	Digital pin 43
42	PL7	Digital pin 42
43	PD0 (SCL/INT0)	Digital pin 21 (SCL)
44	PD1 (SDA/INT1)	Digital pin 20 (SDA)
45	PD2 (RXDI/INT2)	Digital pin 19 (RX1)
46	PD3 (TXD1/INT3)	Digital pin 18 (TX1)

47	PD4 (ICP1)	
48	PD5 (XCK1)	
49	PD6 (T1)	
50	PD7 (T0)	Digital pin 38
51	PG0 (WR)	Digital pin 41
52	PG1 (RD)	Digital pin 40
53	PC0 (A8)	Digital pin 37
54	PC1 (A9)	Digital pin 36
55	PC2 (A10)	Digital pin 35
56	PC3 (A11)	Digital pin 34
57	PC4 (A12)	Digital pin 33
58	PC5 (A13)	Digital pin 32
59	PC6 (A14)	Digital pin 31
60	PC7 (A15)	Digital pin 30
61	VCC	VCC
62	GND	GND
63	PJ0 (RXD3/PCINT9)	Digital pin 15 (RX3)
64	PJ1 (TXD3/PCINT10)	Digital pin 14 (TX3)
65	PJ2 (XCK3/PCINT11)	
66	PJ3 (PCINT12)	
67	PJ4 (PCINT13)	

68	PJ5 (PCINT14)	
69	PJ6 (PCINT 15)	
70	PG2 (ALE)	Digital pin 39
71	PA7 (AD7)	Digital pin 29
72	PA6 (AD6)	Digital pin 28
73	PA5 (AD5)	Digital pin 27
74	PA4 (AD4)	Digital pin 26
75	PA3 (AD3)	Digital pin 25
76	PA2 (AD2)	Digital pin 24
77	PA1 (AD1)	Digital pin 23
78	PA0 (AD0)	Digital pin 22
79	PJ7	
80	VCC	VCC
81	GND	GND
82	PK7 (ADC15/PCINT23)	Analog pin 15
83	PK6 (ADC14/PCINT22)	Analog pin 14
84	PK5 (ADC13/PCINT21)	Analog pin 13
85	PK4 (ADC12/PCINT20)	Analog pin 12
86	PK3 (ADC11/PCINT19)	Analog pin 11
87	PK2 (ADC10/PCINT18)	Analog pin 10
88	PK1 (ADC9/PCINT17)	Analog pin 9

89	PK0 (ADC8/PCINT16)	Analog pin 8
90	PF7 (ADC7)	Analog pin 7
91	PF6 (ADC6)	Analog pin 6
92	PF5 (ADC5/TMS)	Analog pin 5
93	PF4 (ADC4/TMK)	Analog pin 4
94	PF3 (ADC3)	Analog pin 3
95	PF2 (ADC2)	Analog pin 2
96	PF1 (ADC1)	Analog pin 1
97	PF0 (ADC0)	Analog pin 0
98	AREF	Analog Reference
99	GND	GND
100	AVCC	VCC

Table 4.2 Arduino Mega 2560 PIN mapping table

Each of the 54 digital pins on the Mega can be used as an input or output, using **pinMode()**, **digitalWrite()**, and **digitalRead()** functions. They operate at 5 volts. Each pin can provide or receive 20 Ma as recommended operating condition and has an internal pull-up resistor (disconnected by default) of 20-50 k ohm. A maximum of 40Ma is the value that must not be exceeded to avoid permanent damage to the microcontroller.

APPLICATIONS:

- Arduboy, a handheld game console based on Arduino.
- Arduinome, a MIDI controller device that mimics the Monome.
- Ardupilot, drone software and hardware.
- ArduSat, a cubesat based on Arduino.
- C-STEM Studio, a platform for hands-on integrated learning of computing, science, technology, engineering, and mathematics (C-STEM) with robotics.
- Data loggers for scientific research.
- OBDuino, a trip computer that uses the on-board diagnostics interface found in most modern cars.

4.1.2 POWER SUPPLY

This section describes how to generate +5V DC power supply

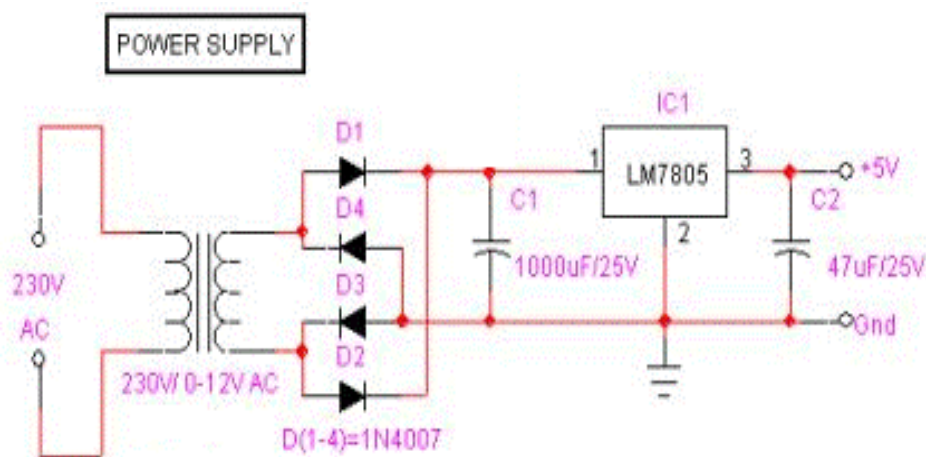


FIG 4.2 Power Supply

The power supply section is the important one. It should deliver constant output regulated power supply for successful working of the project. A 0-12V/1 Ma transformer is used for this purpose. The primary of this transformer is connected in to main supply through on/off switch& fuse for protecting from overload and short circuit protection. The secondary is connected to the diodes to

convert 12V AC to 12V DC voltage. And filtered by the capacitors, which is further regulated to +5v, by using IC 7805.

4.1.3 LCD

LCD screen is an electronic display module and find a wide range of applications. A 16x2 LCD display is very basic module and is very commonly used in various devices and circuits. These modules are preferred over seven segments and other multi segment LEDs. The reasons being: LCDs are economical; easily programmable; have no limitation of displaying special & even custom characters (unlike in seven segments), animations and so on.

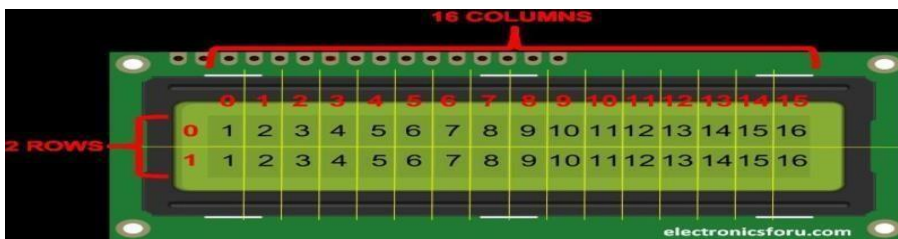


FIG 4.3 16X2 LCD Diagram

4.1.4 ULTRASONICSENSOR



HC-SR04

The HC-SR04 ultrasonic sensor uses sonar to determine distance to an object like bats do. It offers excellent non-contact range detection with high accuracy and stable readings in an easy-to-use package. It comes complete with ultrasonic transmitter and receiver modules. as the name indicates measure distance by using ultrasonic waves .the sensor head emits ultrasonic wave and receives the

wave reflected back from the target .Ultrasonic measures the distance through the target by measuring time between emission and reception

Electric Parameter

Working Voltage	DC 5 V
Working Current	15Ma
Working Frequency	40Hz
Max Range	4m
Min Range	2 cm
MeasuringAngle	15 degree
Trigger Input Signal	10Us TTL pulse
Echo Output Signal	Input TTL lever signal and the range in proportion
Dimension	45*20*15mm
Main parts	Transmitter &receiver
Technology used	Non-contact technology
Resolution	3mm

Table 4.3 Electric Parameters

4.1.5 INTERNET OF THINGS

The **internet of things (IoT)** is the network of physical devices, vehicles, buildings and other items embedded with electronics, software, sensors, actuators, and network connectivity that enable these objects to collect and exchange data. In 2013 the Global Standards Initiative on Internet of Things (IoT-GSI) defined the IoT as “the infrastructure of the information society. The IoT allows objects to be sensed and controlled remotely across existing network infrastructure, creating opportunities for more direct integration of the physical world into computer-based systems, and resulting in improved efficiency, accuracy and economic benefit.

When IoT is augmented with sensors and actuators, the technology becomes an instance of the more general class of cyber-physical systems, which also encompasses technologies such as smart grids, smart homes, intelligent transportation and smart cities.

4.1.6 ESP-12E BASED NODEMCU

The ESP8266 is the name of a micro controller designed by Espressif Systems. The ESP8266 itself is a self-contained Wi-Fi networking solution offering as a bridge from existing micro controller to Wi-Fi and is also capable of running self-contained applications. This module comes with a built in USB connector and a rich assortment of pin-outs. With a micro USB cable, you can connect NodeMCU devkit to your laptop and flash it without any trouble, just like Arduino. It is also immediately breadboard friendly.

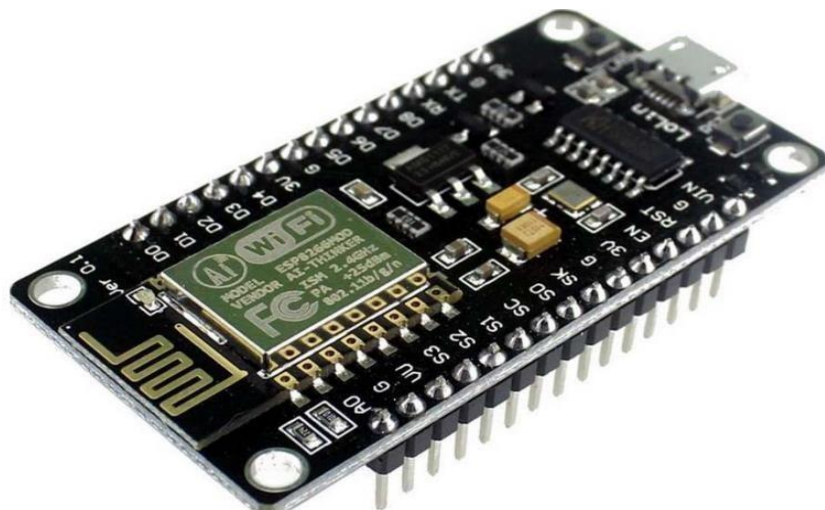
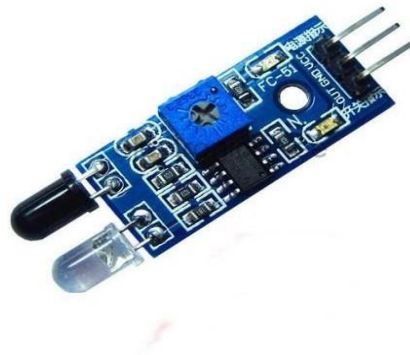


FIG 4.4 ESP-12E Based NODEMCU

4.1.7 IR SENSOR

An [infrared sensor](#) is an electronic device, that emits in order to sense some aspects of the surroundings. An IR sensor can measure the heat of an object as well as detects the motion. These types of sensors measures only infrared radiation, rather than emitting it that is called as a [passive IR sensor](#). Usually in the infrared spectrum, all the objects radiate some form of thermal radiations. These types of radiations are invisible to our eyes, that can be detected by an infrared

sensor. The emitter is simply an IR LED ([Light Emitting Diode](#)) and the detector is simply an IR photodiode which is sensitive to IR light of the same wavelength as that emitted by the IR LED. When IR light falls on the photodiode, The resistances and these output voltages, change in proportion to the magnitude of the IR light received.



4.1.8 GAS SENSOR



The sensors contain two in contact with an electrolyte. The electrodes are typically fabricated by fixing a high surface area precious metal on to the porous hydrophobic membrane. The working electrode contacts both the electrolyte and the ambient air to be monitored usually via a porous membrane. The electrolyte most commonly used is a mineral acid the electrodes and housing are usually in a plastic housing which contains a gas entry hole for the gas and electrical contacts.

4.1.9 DHT 11 HUMIDITY & TEMPERATURE SENSOR

DHT11 Temperature & Humidity Sensor features a temperature & humidity sensor complex with a calibrated digital signal output. By using the exclusive digital-signal-acquisition technique and temperature & humidity sensing technology, it ensures high reliability and excellent long-term stability. This sensor includes a resistive-type humidity measurement component and an NTC temperature measurement component, and connects to a high performance 8-bit microcontroller, offering excellent quality, fast response, anti-interference ability and cost-effectiveness.

4.1.10 FLOW SENSOR

Water flow sensor consists of a plastic valve body, a water rotor, and a hall-effect sensor. When water flows through the rotor, rotor rolls. Its speed changes with different rate of flow. The hall-effect sensor outputs the corresponding pulse signal. The provided sensors are well-manufactured from the topmost grade components and the latest technology under the supervision of our dexterous professionals.

4.1.11 BUZZER

A buzzer or beeper is an [audio](#) signaling device, which may be [mechanical](#), [electromechanical](#), or [piezoelectric](#) (piezo for short). Typical uses of buzzers and beepers include [alarm devices](#), [timers](#), and confirmation of user input such as a mouse click or keystroke.



4.1.12 GLOBAL POSITIONING SYSTEM

GPS or Global Positioning System is a satellite navigation system that furnishes location and time information in all climate conditions to the user. GPS is used for navigation in planes, ships, cars and trucks also. The system gives critical abilities to military and civilian users around the globe. GPS provides continuous real time, 3-dimensional positioning, navigation and timing worldwide.

The Global Positioning System (GPS) is a satellite-based navigation system made up of at least 24 satellites. GPS works in any weather conditions, anywhere in the world, 24 hours a day, with no subscription fees or setup charges. The U.S. Department of Defense (USDOD) originally put the satellites into orbit for military use, but they were made available for civilian use in the 1980s.



APPLICATION OF GPS:

GLOBAL POSITIONING SYSTEM (GPS) Application is considered a dual-use technology, meaning it has significant military and civilian applications

4.1.13 GSM

A GSM modem is a wireless modem that works with a GSM wireless network. A wireless modem behaves like a dial-up modem. The main difference between them is that a dial-up modem sends and receives data through a fixed telephone line while a wireless modem sends and receives data through radio waves. The working of GSM modem is based on commands, the commands

always start with AT (which means ATtention) and finish with a <CR> character.



4.1.14 ZIGBEE PROTOCOL

NRF24L01:

The nRF24L01+ is a single chip 2.4GHz transceiver with an embedded baseband protocol engine (Enhanced ShockBurst™), suitable for ultra-low power wireless applications. The nRF24L01+ is designed for operation in the world wide ISM frequency band at 2.400 - 2.4835GHz.

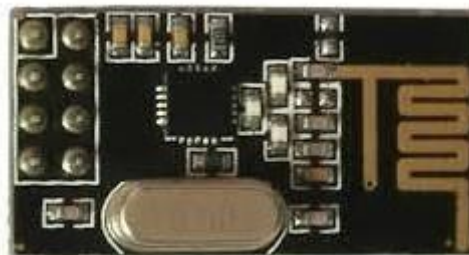


FIG 4.5 NRF24L01

4.2 SOFTWARE REQUIREMENTS

4.2.1 EMBEDDED C

Embedded C is most popular programming language in software field for developing electronic gadgets. Each processor used in electronic system is associated with embedded software.

Embedded C programming plays a key role in performing specific function by the processor. In day-to-day life we used many electronic devices such as mobile phone, washing machine, digital camera, etc.

Let's see the block diagram representation of embedded system programming:

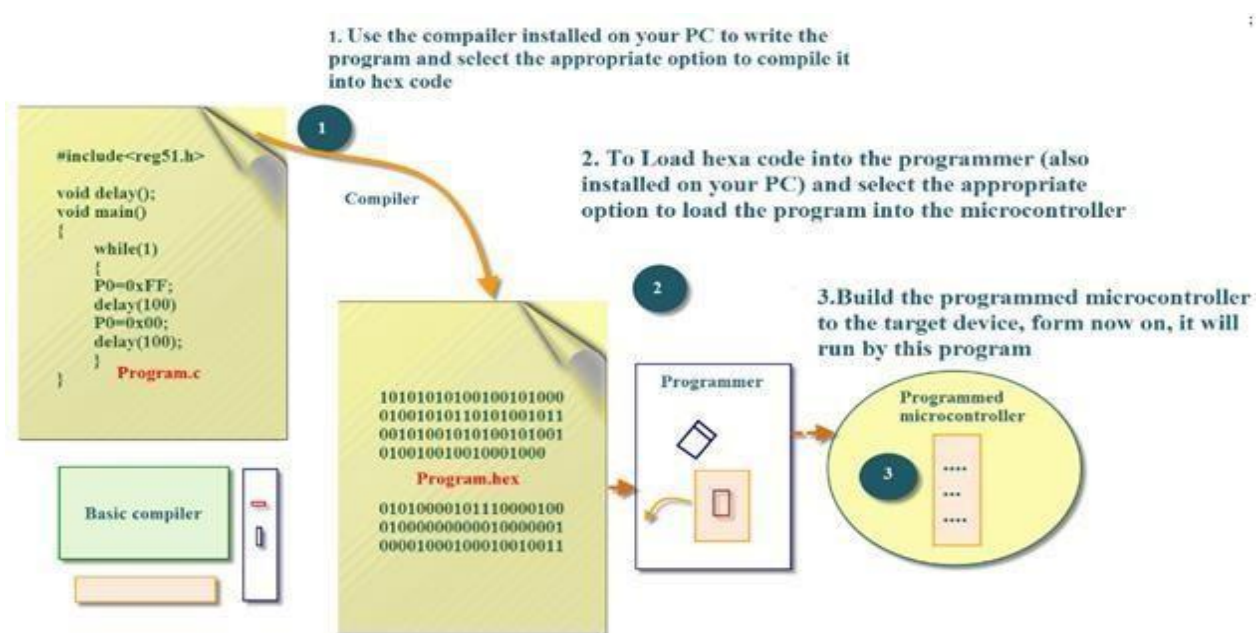


FIG 4.6 Block Diagram Representation Of Embedded System Programming

The Embedded C code written in above block diagram is used for blinking the LED connected with Port0 of microcontroller.

4.2.2 EMBEDDED SYSTEM PROGRAMMING

Function is a collection of statements that is used for performing a specific task and a collection of one or more functions is called a programming language. Every language is consisting of basic elements and grammatical rules. The C language programming is designed for function with variables, character set, data types, keywords, expression and so on are used for writing a C program.

The extension in C language is known as embedded C programming language. As compared to above the embedded programming in C is also have some additional features like data types, keywords and header file etc is represented by `#include<microcontroller name.h>`.

4.2.3 EMBEDDED SYSTEM

Let's see the block diagram shows the basic structure of an embedded system.

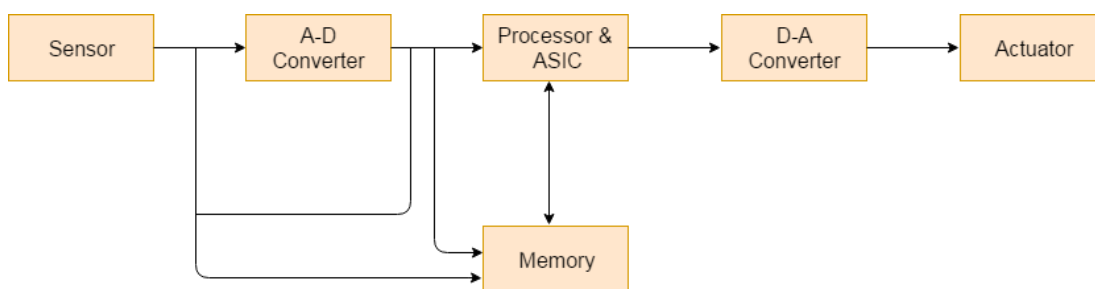






FIG 4.7 The Basic Structure Of An Embedded System



- **Sensor:** Sensor used for sensing the change in environment condition and it generate the electric signal on the basis of change in environment condition. Therefore it is also called as transducers for providing electric input signal on the basis of change in environment condition.
- **A-D Converter:** An analog-to-digital converter is a device that converts analog electric input signal into its equivalent digital signal for further processing in an embedded system.

- **Processor & ASICs:** Processor used for processing the signal and data to execute desired set of instructions with high-speed of operation. Application specific integrated circuit (ASIC) is an integrated circuit designed to perform task specific operation inside an embedded system.
- **D-A Converter:** A digital-to-analog converter is a device that converts digital electric input signal into its equivalent analog signal for further processing in an embedded system.
- **Actuators:** Actuators is a comparator used for comparing the analog input signal level to desired output signal level for providing the error free output from the system.

4.2.4 ARDUINO SOFTWARE IDE

The Arduino Integrated Development Environment - or Arduino Software (IDE) - contains a text editor for writing code, a message area, a text console, a toolbar with buttons for common functions and a series of menus.

	<p><i>Verify</i></p> <p>Checks your code for errors compiling it.</p>
	<p><i>Upload</i></p> <p>Compiles your code and uploads it to the configured board. See <u>uploading</u> below for details.</p> <p>Note: If you are using an external programmer with your board, you can hold down the "shift" key on your computer when using this icon. The text will change to "Upload using Programmer"</p>
	<p><i>New</i></p> <p>Creates a new sketch.</p>
	<p><i>Open</i></p>

	<p>Presents a menu of all the sketches in your sketchbook. Clicking one will open it within the current window overwriting its content.</p> <p>Note: due to a bug in Java, this menu doesn't scroll; if you need to open a sketch late in the list, use the File Sketchbook menu instead.</p>
	<p><i>Save</i></p> <p>Saves your sketch.</p>
	<p><i>Serial</i></p> <p>Opens the serial monitor.</p>

CHAPTER 5

SYSTEM DESIGN

5.1 DATAFLOW DIAGRAM

5.1.1 LEVEL-0 DFD DIAGRAM

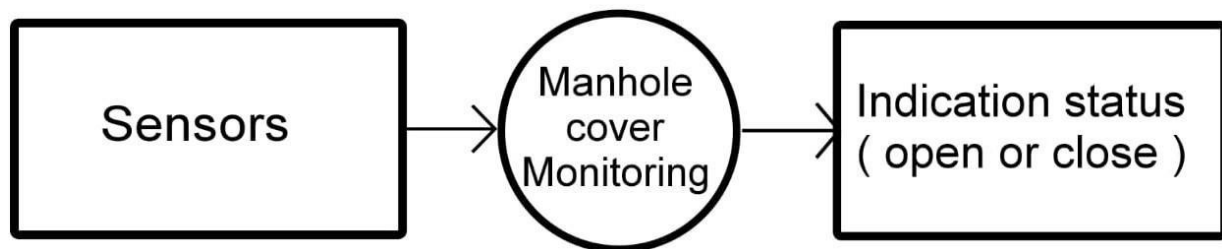


FIG 5.1 Level-0 DFD diagram

It is also known as a context diagram. It shows the entire abstraction of the process. Here ,the process of manhole monitoring is done with the help of sensors based on the concept of IoT which indicates whether the manhole is open or close.

5.1.2 LEVEL-1 DFD DIAGRAM

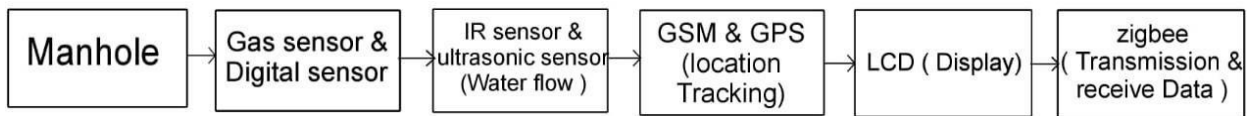


FIG 5.2 Level-1 DFD diagram

In 1-level DFD, we highlight the main functions of the system and breakdown the high-level process of 0-level DFD into subprocesses. Here, we use various types of sensors to measure the temperature, gas and water flow. Also we use LCD & zigbee for display and data transmission purposes.

5.1.3 LEVEL-2 DFD DIAGRAM

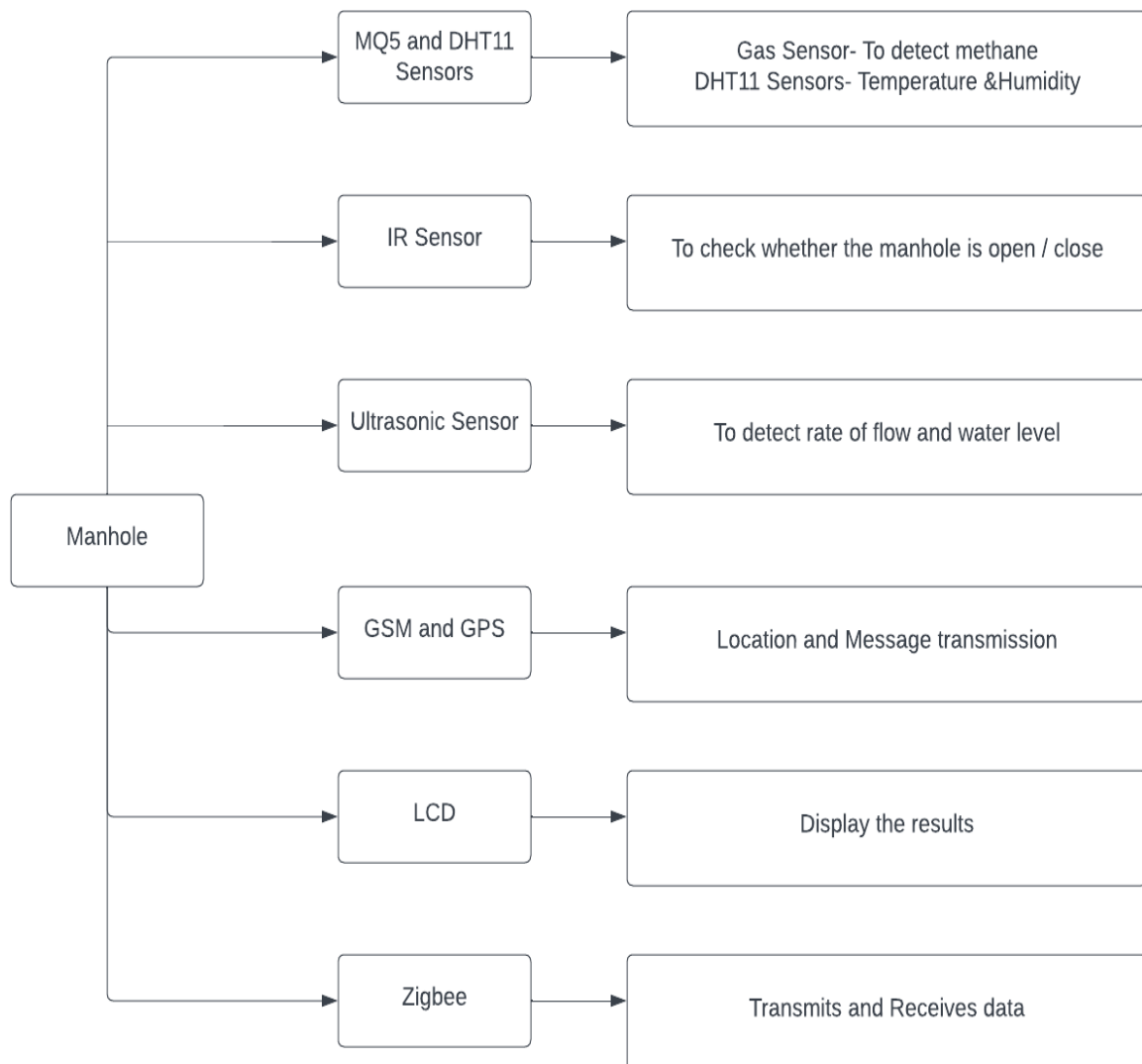


FIG 5.3 Level-2 DFD diagram

2-level DFD goes one step deeper into parts of 1-level DFD. It can be used to plan or record the specific detail about the system's functioning.

5.2 UML DIAGRAMS

5.2.1 USECASE DIAGRAMS

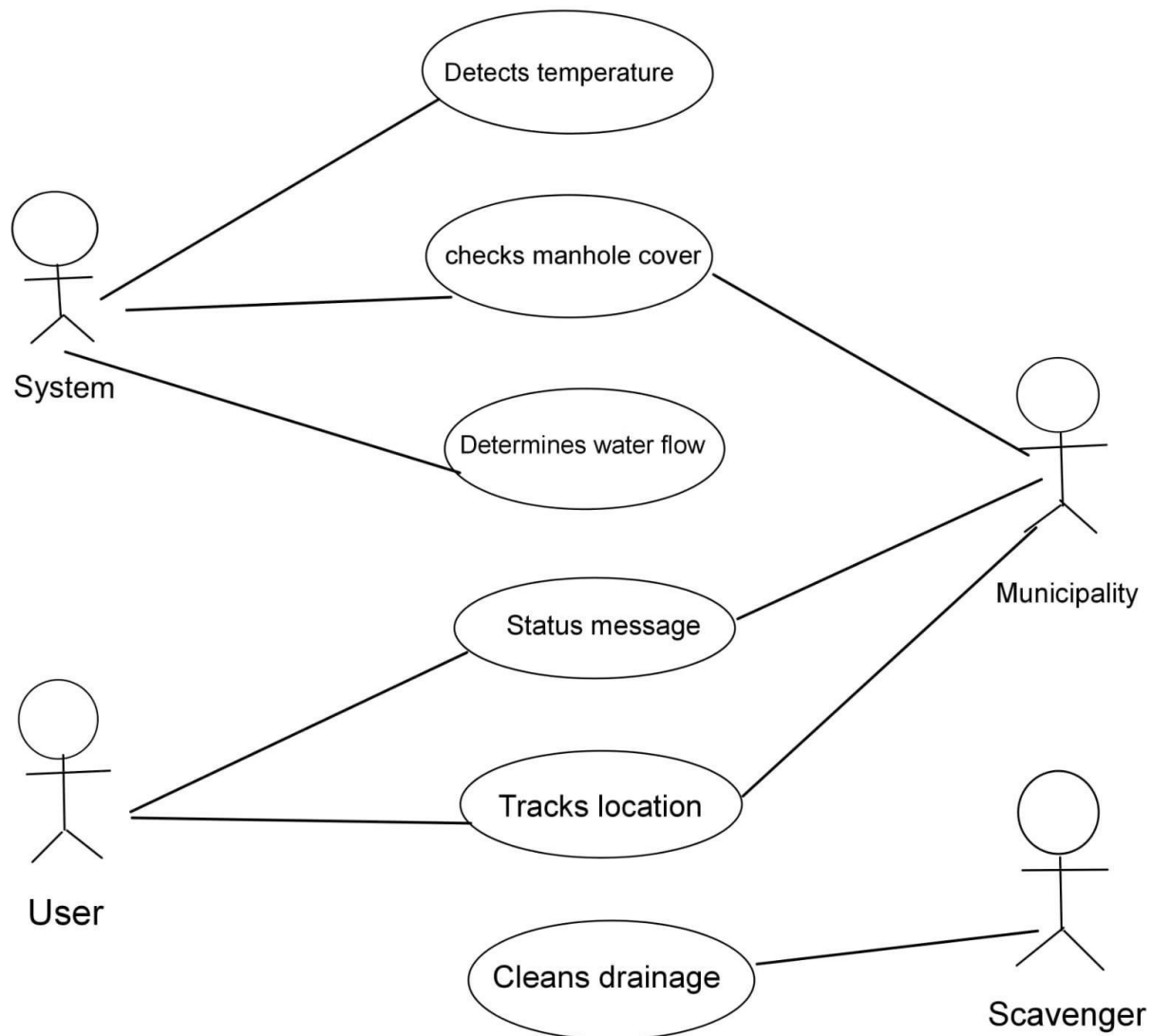


FIG 5.4 Usecase diagram

The main purpose of a use case diagram is to portray the dynamic aspect of a system. It accumulates the system's requirement, which includes both internal as well as external influences. It invokes persons, use cases, and several things that invoke the actors and elements accountable for the implementation of use case diagrams. It represents how an entity from the external environment can interact with a part of the system.

5.3 ARCHITECTURE DIAGRAM

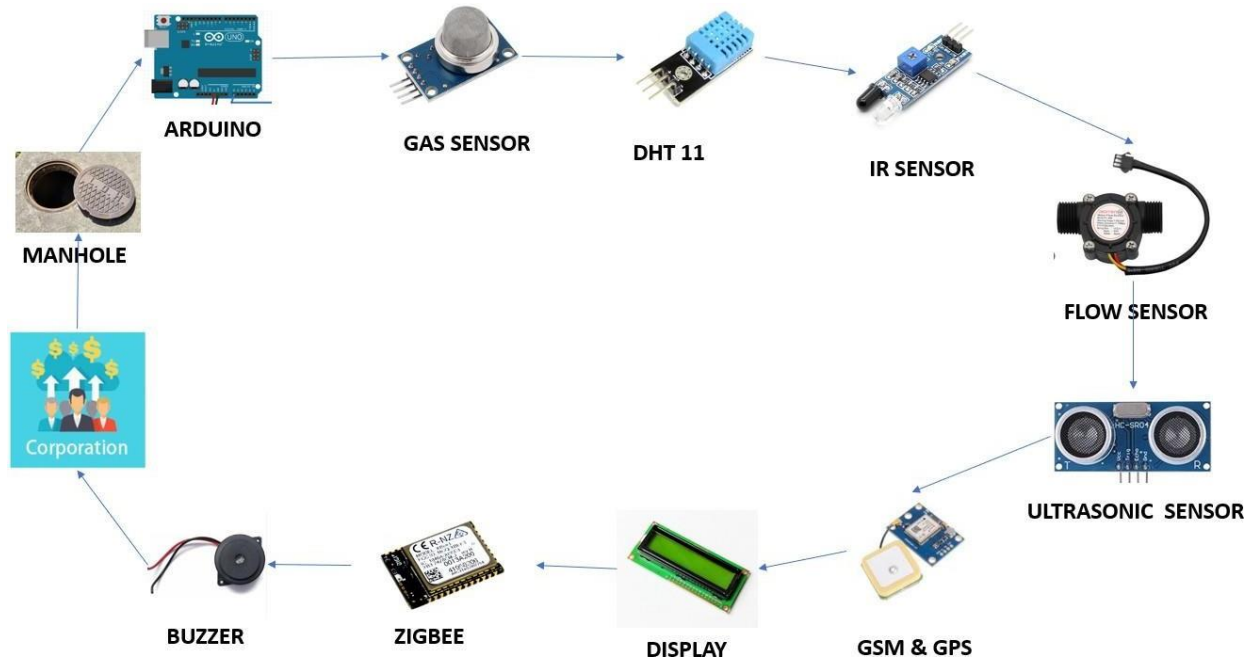


FIG 5.5 Architecture diagram

The above architecture diagram shows the work flow of the project. The devices such as Arduino, gas sensor, DHT11, IR sensor, flow sensor, ultrasonic sensor, GSM & GPS has been attached to the manhole cover to sense the requirements and to collect data. The data collected has sent to the corporation and a buzzer alert has been made to alert the corporation.

CHAPTER 6

SYSTEM ARCHITECTURE

6.1 BLOCK DIAGRAM

TRANSMITTER: DRAINAGE SECTION

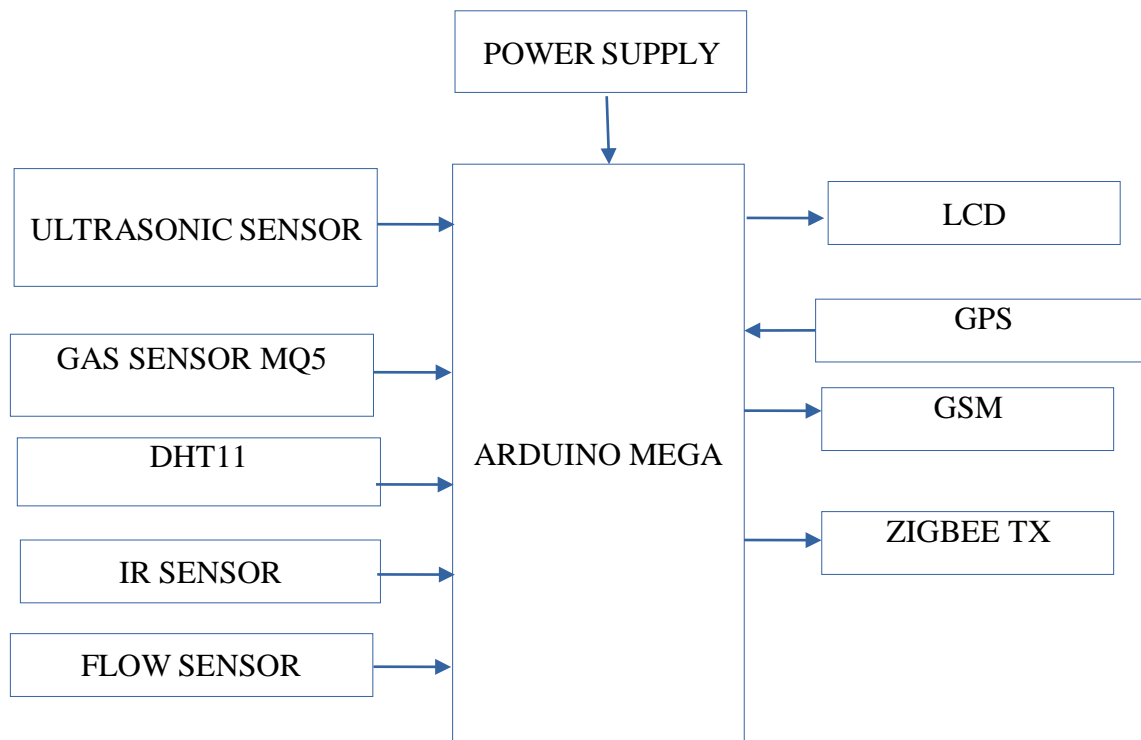


FIG 6.1 Transmitter: Drainage Section

RECEIVER SECTION: MASTER (CONTROL ROOM)

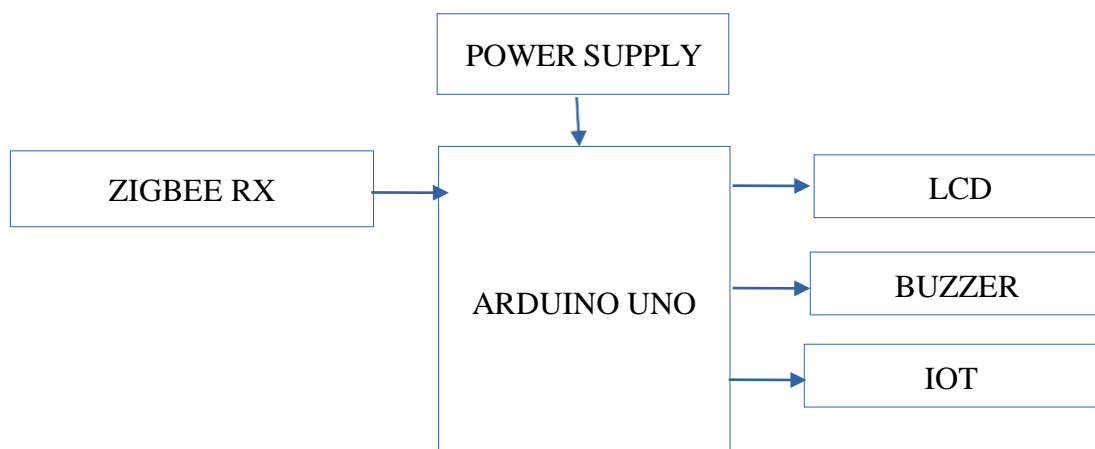


FIG 6.2 Receiver Section: Master (Control Room)

6.2 WORKING PRINCIPLE

In this proposed method, ARDUINO MEGA & ARDUINO UNO microcontroller is used to interface with the sensors and to the communication devices. The MQ 5 – The MQ5 Gas Sensor module is useful for methane gas leakage detecting. The dht11 –low-cost digital sensor for sensing temperature and humidity. An infrared (IR) sensor is a device to confirm whether the cover is open or close. Flow sensors are mainly used to measure the quantity or the rate of flow of liquids. We are using it to detect overflow the ultrasonic sensor provides the water levels of the sewage tanks. GSM and GPS used to send location with SMS, particular area where problem is occurred. The LCD is used to display the updated value from the sensors. The Zigbee used for to transmit and receive the data in the sensor.

6.3 MODULE DESCRIPTION

6.3.1. TRANSMISSION SIDE WORKING

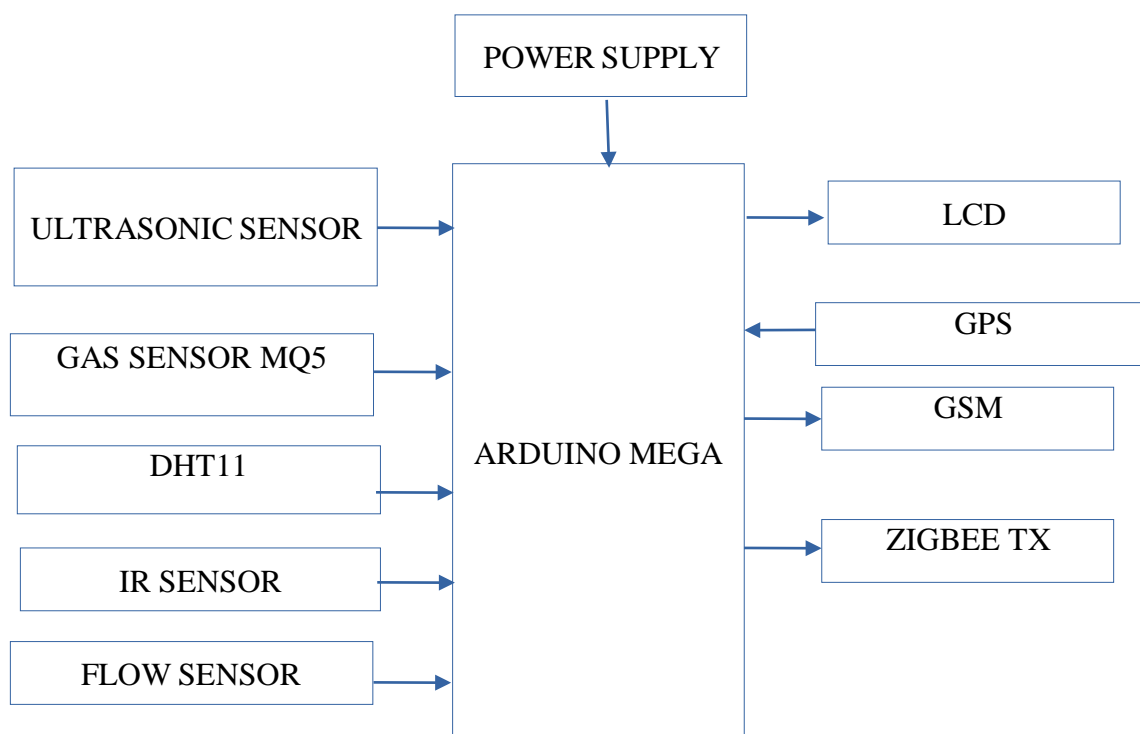


FIG 6.3 Transmission Side Working

In this transmitter side ARDUINO MEGA microcontroller is used to interface with the sensors and to the communication devices. The MQ 5 – The MQ5 Gas Sensor module is useful for methane gas leakage detecting. The dht11 – low-cost digital sensor for sensing temperature and humidity. An infrared (IR) sensor is a device to confirm whether the cover is open or close. Flow sensors are mainly used to measure the quantity or the rate of flow of liquids. We are using it to detect overflow the ultrasonic sensor provides the water levels of the sewage tanks. The GPS and GSM is used for track the location and send SMS where problem is occurred and ZIGBEE transmitter is used to transmit signal to the receiver side.

6.3.2 RECEIVER SIDE WORKING

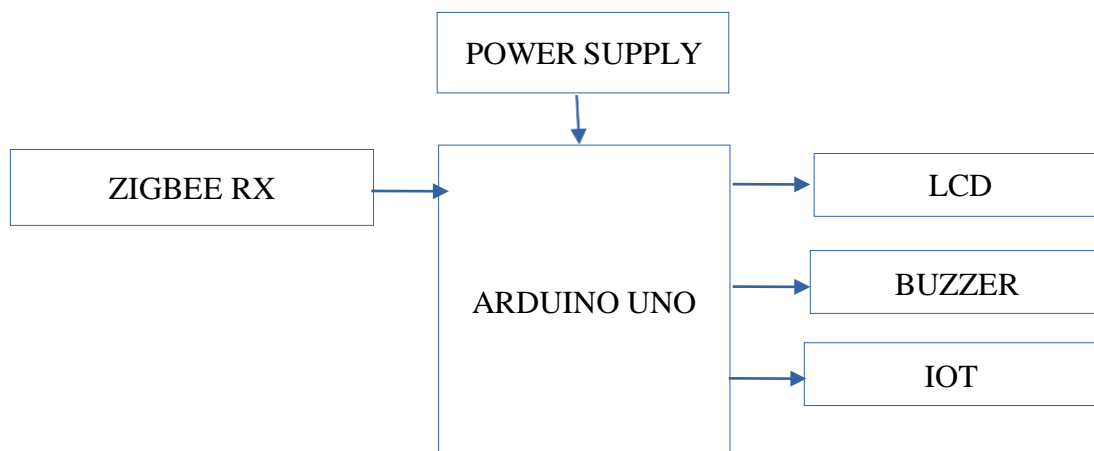


FIG 6.4 Receiver Side Working

In receiving side when data receive from transmitting side the receive side ZIGBEE get that data and transmit to Arduino. If any problem occurred in drainage buzzer gives the alert to receiver LCD also display the problem condition. We store and see the data in cloud by using IOT module.

CHAPTER 7

SYSTEM IMLEMENTATION

7.1 TRANSMITTER SIDE CODING:

```
#include "lcd.h"

#include "gps.h"

#include "gsm.h"

#include <ultrasonic.h>

#include<SoftwareSerial.h>

SoftwareSerial Serial(6, 7);

#include"dht11.h"

DHT dht;

bool leakage_flag = false;

int sensorInterrupt = 0; // interrupt 0

int sensorPin      = 2; //Digital Pin 2

unsigned int SetPoint = 400; //400 milileter

/*The hall-effect flow sensor outputs pulses per second per litre/minute of flow.*/

float calibrationFactor = 90; //You can change according to your datasheet

volatile byte pulseCount = 0;

float flowRate = 0.0;

unsigned int flowMilliLitres = 0;
```

```
unsigned long totalMilliLitres = 0;

unsigned long oldTime = 0;

ULTRASONIC U1;

#define D_temp A0

#define ir_pin 3

#define gas_pin 4

bool refill_flag = false;

bool gas_flag = false;

void ultrasonic(void);

void setup()

{

    Serial.begin(9600);

    Serial.begin(9600);

    lcd.begin(16, 2);

    U1.begin(A1, A2);

    pinMode(sensorPin, INPUT);

    digitalWrite(sensorPin, HIGH);

    pinMode(ir_pin, INPUT);

    dht.dht_read(D_temp);

    lcd.clear();
```

```

lcd.setCursor(1, 0);

lcd.print("DRAINAGE_BLOCK");

lcd.setCursor(3, 1);

lcd.print("MONITORING");

delay(2000);

lcd.clear();

attachInterrupt(sensorInterrupt, pulseCounter, FALLING); //you can use Rising or
Falling

//gps();

}

void loop()

{

if ((millis() - oldTime) > 1000) // Only process counters once per second

{

temperature();

lcd_update();

ultrasonic();

lcd.setCursor(9, 0);

lcd.print("D:");

lcd.setCursor(11, 0);

int pin = digitalRead(ir_pin);

```



```

lcd.print(pin);

if (pin == 0)

{

    Serial.print('D');

    gsm("1234567890", "DRAINAGE OPEN");

}

lcd.setCursor(13, 0);

lcd.print("G:");

lcd.setCursor(15, 0);

lcd.print(digitalRead(gas_pin));

lcd.setCursor(0, 1);

if (digitalRead(gas_pin) == 0)

{

    Serial.print('B');

    gsm("1234567890", "METHANE DETECTED");

}

lcd.print("F:");

detachInterrupt(sensorInterrupt);

```

//We also apply the calibrationFactor to scale the output based on the number of pulses per second per units of measure (litres/minute in this case) coming from the sensor.

```

flowRate = ((1000.0 / (millis() - oldTime)) * pulseCount) / calibrationFactor;

oldTime = millis();

flowMilliLitres = (flowRate / 60) * 1000;

totalMilliLitres += flowMilliLitres;

unsigned int frac;

lcd.setCursor(2, 1);

lcd.print(flowMilliLitres, DEC);

if (flowMilliLitres > 5)
{
    Serial.print('E');

    lcd.setCursor(4, 1);

    lcd.print("flow blocked");

    gsm("1234567890", "FLOW BLOCKED ");
}

}

pulseCount = 0;

attachInterrupt(sensorInterrupt, pulseCounter, FALLING);

}

//Interrupt Service Routine

```

```

void pulseCounter()

{

    // Increment the pulse counter

    pulseCount++;

}

void temperature(void)

{

    dht.dht_read(D_temp);

    if (dht.temperature > 33)

    {

        Serial.print('A');

        gsm("1234567890", "HIGH TEMPERATURE");

    }

}

void lcd_update(void)

{

    lcd.setCursor(0, 0);

    lcd.print("T:");

    lcd.setCursor(2, 0);

    lcd.print(dht.temperature);

```

```

    delay(1000);

}

void ultrasonic(void)

{

    lcd.setCursor(5, 0);

    lcd.print("U:");

    int cm = U1.ultra();

    if (cm < 10)

    {

        Serial.print('C');

        lcd.print("F");

        gsm("1234567890", "DRAINAGE FULL");

    }

    else if (cm > 10 && cm < 30)

    {

        lcd.print("M");

    }

    else if (cm > 30)

    {

        lcd.print("E"); } }

```

7.2 RECIEVER SIDE CODING:

```
#include<SoftwareSerial.h>

SoftwareSerial Serial(2, 3); //RX TX

void iot_send(String text);

char inchar;

# define D_buzzer 7

void setup() {

  Serial.begin(9600);

  Serial.begin(9600);

  digitalWrite(D_buzzer, LOW);

  pinMode(D_buzzer, OUTPUT);

}

void loop() {

  while (Serial.available() > 0)

  {

    inchar = (char)Serial.read();

    Serial.println(inchar);

    switch (inchar)

    {

      case'A':
```

```

digitalWrite(D_buzzer, !digitalRead(D_buzzer));

digitalWrite(D_buzzer, HIGH);

delay(2000);

digitalWrite(D_buzzer, LOW);

iot_send("*HIGH TEMPERATURE#");

break;

case'B':

digitalWrite(D_buzzer, !digitalRead(D_buzzer));

digitalWrite(D_buzzer, HIGH);

delay(2000);

digitalWrite(D_buzzer, LOW);

iot_send("*METHANE DETECTED#");

break;

case'C':

digitalWrite(D_buzzer, !digitalRead(D_buzzer));

digitalWrite(D_buzzer, HIGH);

delay(2000);

digitalWrite(D_buzzer, LOW);

iot_send("*DRAINAGE FULL#");

break;

```

```

case'D':

    digitalWrite(D_buzzer, !digitalRead(D_buzzer));

    digitalWrite(D_buzzer, HIGH);

    delay(2000);

    digitalWrite(D_buzzer, LOW);

    iot_send("*DRAINAGE OPEN#");

    break;

case'E':

    digitalWrite(D_buzzer, HIGH);

    delay(2000);

    digitalWrite(D_buzzer, LOW);

    iot_send("*DRAINAGE BLOCKED#");

    break; } }

delay(1000); }

void iot_send(String text){

    for (int i = 0; i < text.length(); i++){

        Serial.write(text[i]);

    }

    delay(3000);

}

```

CHAPTER 8

CONCLUSION

8.1 CONCLUSION

This article presented the development and validation of an IoT system to monitor the trash level and geolocation of trash bins efficiently. All aspects of an IoT system including the design of a TBLMU, long-range data transmission, long-time data storage, and visualization of the trash bin level were developed. Finally, the developed system was validated by evaluating the accuracy of the sensor employed, maximum transmission distance between a TBLMU and a gateway, life expectancy of a TBLMU, battery charging time, and cost. Based on the results obtained, the proposed IoT system was suitable for the municipality or municipal solid waste management companies to manage the MSW efficiently.

8.2 APPLICATIONS

This method is used in drainage monitoring system to collect the information from all node to the master device using narrow band internet of things.

8.3 FUTURE ENHANCEMENT

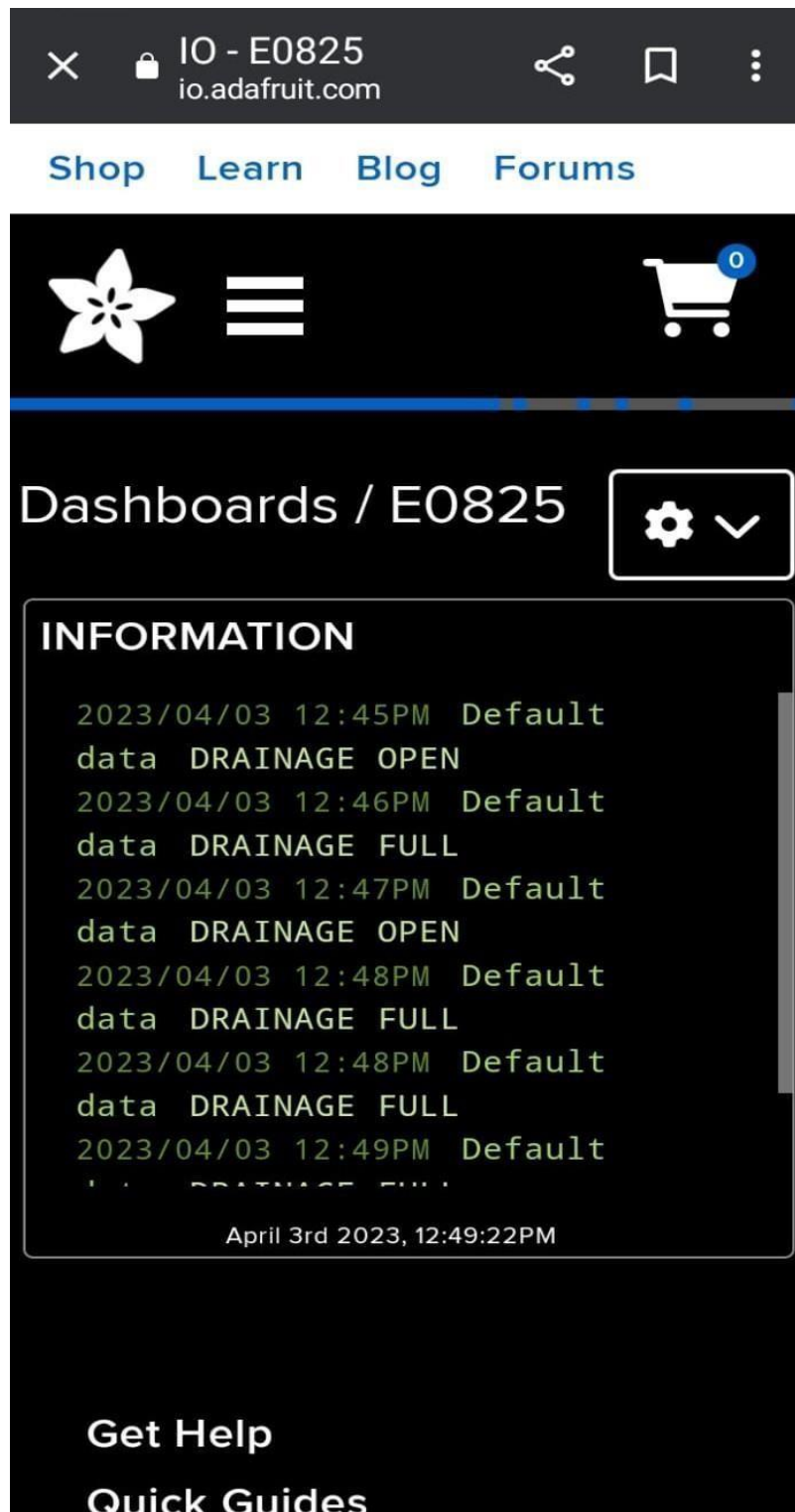
In future we can include AI in drainage places in that system and explore more things in future.

8.4 ADVANTAGES

- Reduce the human deaths in the drainage system.
- The monitoring system easy to handle.

APPENDICES

A.1 SAMPLE SCREENS





Dashboards / E0825



INFORMATION

```
2023/04/03 12:51PM Default  
data DRAINAGE FULL  
2023/04/03 12:52PM Default  
data DRAINAGE FULL  
2023/04/03 12:53PM Default  
data DRAINAGE FULL  
2023/04/03 12:53PM Default  
data DRAINAGE OPEN  
2023/04/03 12:55PM Default  
data DRAINAGE FULL  
2023/04/03 12:56PM Default  
data DRAINAGE BLOCKED
```

April 3rd 2023, 12:55:40PM

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DRAINAGE FULL

<https://www.google.com/maps/place/Panimalar+Engineering+College/@13.0489049,80.0732755,17z/data=!3m1!4b1!4m6!3m5!1s0x3a5261c68a9f3031:0xab41c8bdcf32ad47!8m2!3d13.0489049!4d80.0754642!16s%2Fm%2F03d0n7q0.00000,0.00000>



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<https://www.google.com/maps/place/Panimalar+Engineering+College/@13.0489049,80.0732755,17z/data=!3m1!4b1!4m6!3m5!1s0x3a5261c68a9f3031:0xab41c8bdcf32ad47!8m2!3d13.0489049!4d80.0754642!16s%2Fm%2F03d0n7q0.00000,0.00000>



Chat message



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