

Sankalp Rajeev

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EDUCATION

University of Michigan – Dearborn	Sep 2024 – Dec 2026
<i>M.Sc., Artificial Intelligence & M.S.E., Robotics Engineering; GPA 3.90/4.00</i>	<i>Dearborn, MI</i>
Arizona State University	Aug 2020 – May 2024
<i>B.S., Computer Science; Minor: Mathematical Concepts of Engineering GPA 3.71/4.00</i>	<i>Tempe, AZ</i>

WORK EXPERIENCE

Zoetis	May 2025 – Nov 2025
<i>AI Micro Tools Developer Intern</i>	<i>Kalamazoo, MI</i>
<ul style="list-style-type: none">Engineered Streamlit micro-tools to automate and enhance SDLC documentation for a regulated GxP environment.Developed multi-stage ETL pipelines and integrated corporate LLM APIs for automated classification, trend analysis, and decision support across ServiceNow datasets.Architected and delivered a real-time analytics dashboard, including its custom SQL-backed data pipeline, to track tool adoption, accelerating documentation workflows and saving an estimated ~1,000 engineer-hours annually.	
Mistral Solutions Pvt Ltd	Jun 2024 – Aug 2024
<i>AI/ML Engineer Intern</i>	<i>Bangalore, India</i>
<ul style="list-style-type: none">Deployed and optimized YOLOv8 models on a resource-constrained Mistral EagleKit (Qualcomm QRB5165) to perform real-time object detection, enabling autonomous route monitoring for heavy-payload, high-altitude UAVs.Refactored Lua-based AHRS and obstacle avoidance logic; integrated Qualcomm SNPE SDK with mixed-precision quantization, cutting compute latency 25%.	
Astroseed	Aug 2023 – May 2024
<i>Software Developer</i>	<i>Tempe, AZ</i>
<ul style="list-style-type: none">Led Agile sprints and backlog reprioritization, coordinating cross-functional collaboration across engineering teams.Architected the perception pipeline by integrating a 3D depth camera with a YOLOv5 model in ROS.Implemented SLAM-based autonomous navigation in Gazebo for path planning and obstacle avoidance.	
Machani Robotics	Jun 2022 – Aug 2022
<i>Software Development Engineering Intern</i>	<i>Bangalore, India</i>
<ul style="list-style-type: none">Developed 6-DOF robotic-arm control software via CAN protocol for real-time motion planning.Built autonomous drawing task execution system with TDD, integrated with a ROS vision pipeline (Python/C++) and 3D depth camera for object recognition.	

PROJECTS

MeetingMind AI (Python, FastAPI, React, Docker, GCP)	Dec 2025 – Jan 2026
<ul style="list-style-type: none">Architected a 5-phase ML pipeline orchestrating Whisper (ASR), Pyannote (diarization), YOLOv11 (face detection), and Gemini (LLM) to generate speaker-attributed meeting transcripts with automated summaries and action items.Integrated Gemini Vision (VLM) for multimodal slide/chart extraction, and engineered a speaker-face matching algorithm using IoU-based tracking with cosine similarity on 512-dim ArcFace embeddings.Deployed a RAG system (LangChain, ChromaDB, Vertex AI) with FastAPI backend and React frontend on Google Cloud Run via Docker containers.	
Autonomous Driving Systems in CARLA (Python, PyTorch)	Jan 2025 – Apr 2025
<ul style="list-style-type: none">Developed a real-time 3D trajectory mapping system by engineering a visual SLAM pipeline that fused stereo camera and IMU sensor data for localization and mapping.Implemented a PPO-based RL agent with CNN-encoded semantic features in a custom CARLA Gym environment, integrating YOLOv8 and UFLD for perception-driven lane adherence and obstacle avoidance.	

SKILLS

Languages	Python, C/C++, SQL, JavaScript, Java, Lua, MATLAB
Frameworks & Libraries	PyTorch, TensorFlow, FastAPI, React, LangChain, HuggingFace, ROS, OpenCV, scikit-learn
Cloud/DevOps	Docker, Git, GCP (Cloud Run, Vertex AI), Azure
Domains	Generative AI, NLP, Computer Vision, Reinforcement Learning, Full-Stack Development, MLOps