PH423 Assignment 2

Parth Sastry 180260026 Sahas Kamat 180260030 Sankalp Gambhir 180260032

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4 Question 1.

- 5 [Sankalp: I got this one.]
- (a) Calculate the expectation values of \hat{J}_x , \hat{J}_y , \hat{J}_x^2 and \hat{J}_y^2 in the angular momentum states $|j, m\rangle$. Explain the result geometrically. (Using symmetry arguments may help).
- We start with the expansion of the operators \hat{J}_x and \hat{J}_y in terms of the ladder operators

$$\hat{\mathbf{J}}_x = \frac{1}{2} \cdot (\hat{\mathbf{J}}_+ + \hat{\mathbf{J}}_-) \tag{1}$$

and

$$\hat{J}_{y} = \frac{1}{2i} \cdot (\hat{J}_{+} - \hat{J}_{-}) . \tag{2}$$

The application of the ladder operators on a state $|j, m\rangle$ changes it to a state of the form $c \cdot |j, m \pm 1\rangle$ for some $c \in \mathbb{C}$. So, given the orthogonality of the $|j, m\rangle$ states, we get that

$$\langle j, m | \hat{\mathbf{J}}_x | j, m \rangle = \langle j, m | \hat{\mathbf{J}}_y | j, m \rangle = 0 \qquad \forall |j, m \rangle .$$
 (3)

Squaring Equation 1 and 2, we get the operators \hat{J}_x^2 and \hat{J}_y^2 in terms of the ladder operators. With the same argument as before, we see that only terms with equal powers of the two ladder operators will contribute, and using

$$\hat{\mathbf{J}}_{+}|j,m\rangle = \hbar\sqrt{(j\mp m)(j\pm m+1)} \quad |j,m\pm 1\rangle , \qquad (4)$$

15 we get

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$$\langle j, m | \hat{\mathbf{J}}_{y}^{2} | j, m \rangle = \langle j, m | \hat{\mathbf{J}}_{x}^{2} | j, m \rangle \tag{5}$$

$$= \langle j, m | \frac{1}{4} \cdot (\hat{\mathbf{J}}_{+}^{2} + \hat{\mathbf{J}}_{+} \hat{\mathbf{J}}_{-} + \hat{\mathbf{J}}_{-} \hat{\mathbf{J}}_{+} + \hat{\mathbf{J}}_{-}^{2}) | j, m \rangle$$
 (6)

$$= \langle j, m | \frac{1}{4} \cdot (\hat{J}_{+} \hat{J}_{-} + \hat{J}_{-} \hat{J}_{+}) | j, m \rangle$$
 (7)

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$$= \langle j, m | \frac{\hbar^2}{4} \cdot \left(\sqrt{(j+m+1)(j-m)} \sqrt{(j-m)(j+m+1)} + \sqrt{(j-m)(j+m+1)} \sqrt{(j+m+1)(j-m)} \right) \cdot |j, m\rangle$$
 (8)

$$=\frac{\hbar^2}{2}(j+m+1)(j-m) \ . \tag{9}$$

The values for x and y are not separately calculated as a trivial calculation shows they're equal. The same is easily argued using symmetry in the x-y plane. This symmetry also serves as an explanation for the expectation value, since there is similarly a reflection symmetry about either axis, the expectation cannot favor either \pm x or \pm y.

- (b) Can the angular momentum \hat{J} be oriented entirely along the z(or x or y) axis? Give reasons in either case.
- No. Kill me now.
- 2. Determine the eigenvalues and eigenvectors of the 2×2 matrix $\sigma.\hat{n}$, where \hat{n} is a unit vector along the (θ, ϕ) direction and σ are the three Pauli matrices. This is basically the projection of the spin 1/2 operator (apart from $\frac{\hbar}{9}$) along the direction of the unit vector \hat{n} . Do this in two ways:
- [Parth: Doing question 2, might have issues with part (b) make sure that it's correct
 - (a) First by explicitly diagonalizing the matrix $\sigma.\hat{\mathbf{n}}$.
 - The vector $\boldsymbol{\sigma} = (\sigma_1, \sigma_2, \sigma_3)$, where the σ_i matrices are -

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \, \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \, \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Now we need to figure out what $\hat{\bf n}$ is. The unit vector points along the (θ, ϕ) direction. This is nothing but the unit vector $\hat{\bf r}$ in Polar co-ordinates.

$$\hat{\mathbf{n}} = \hat{\mathbf{r}} = \cos(\phi)\sin(\theta)\hat{\mathbf{i}} + \sin(\phi)\sin(\theta)\hat{\mathbf{j}} + \cos(\theta)\hat{\mathbf{k}}$$

Thus, $\hat{\mathbf{n}} = (\cos(\phi)\sin(\theta), \sin(\phi)\sin(\theta), \cos(\theta))$. We know that $\mathbf{a}.\mathbf{b} = a_ib_i$ (implicit summation over i) Thus, $\boldsymbol{\sigma}.\hat{\mathbf{n}} = \sigma_i n_i$.

$$\sigma \cdot \hat{\mathbf{n}} = \cos(\phi)\sin(\theta) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \sin(\phi)\sin(\theta) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \cos(\theta) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\therefore \sigma \cdot \hat{\mathbf{n}} = \sin(\theta) \begin{pmatrix} 0 & \cos(\phi) - i * \sin(\phi) \\ \cos(\phi) + i * \sin(\phi) & 0 \end{pmatrix} + \cos(\theta) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$= \sin(\theta) \begin{pmatrix} 0 & e^{-i\phi} \\ e^{i\phi} & 0 \end{pmatrix} + \cos(\theta) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} \cos(\theta) & \sin(\theta)e^{-i\phi} \\ \sin(\theta)e^{i\phi} & -\cos(\theta) \end{pmatrix}$$

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To find the eigenvalues and eigenvectors, we now need to diagonalize this matrix. Let the eigenvalues be represented by λ . The characteristic polynomial takes the following form.

$$(\cos(\theta) - \lambda)(-\cos(\theta) - \lambda) - \sin(\theta)e^{-i\phi} * \sin(\theta)e^{i\phi} = 0$$

$$\therefore -\cos^{2}(\theta) + \lambda^{2} - \sin^{2}(\theta) = 0 \Rightarrow \lambda^{2} - 1 = 0$$

$$\therefore \lambda = \pm 1$$

for $\lambda = 1$, let the eigenvector be $\mathbf{v_1} = (v_{1,1}, v_{1,2})$, thus

$$\begin{pmatrix} \cos(\theta) & \sin(\theta)e^{-i\phi} \\ \sin(\theta)e^{i\phi} & -\cos(\theta) \end{pmatrix} \begin{pmatrix} v_{1,1} \\ v_{1,2} \end{pmatrix} = \begin{pmatrix} v_{1,1} \\ v_{1,2} \end{pmatrix}$$

$$\therefore \cos(\theta) * v_{1,1} + \sin(\theta)e^{-i\phi} * v_{1,2} = v_{1,1} , \sin(\theta)e^{i\phi} * v_{1,1} - \cos(\theta) * v_{1,2} = v_{1,2}$$

$$v_{1,2} = e^{i\phi} \frac{\sin(\theta)}{(\cos(\theta) + 1)} * v_{1,1}$$

- Thus, for eigenvalue $\lambda=1$, the eigenvector $\mathbf{v}_1=(v_{1,1},e^{i\phi}\frac{\sin(\theta)}{(\cos(\theta)+1)}*v_{1,1})$
 - Likewise, for $\lambda = -1$, let the eigenvector be $\mathbf{v_2} = (v_{2,1}, v_{2,2})$, thus

$$\begin{pmatrix} \cos(\theta) & \sin(\theta)e^{-i\phi} \\ \sin(\theta)e^{i\phi} & -\cos(\theta) \end{pmatrix} \begin{pmatrix} v_{2,1} \\ v_{2,2} \end{pmatrix} = \begin{pmatrix} -v_{2,1} \\ -v_{2,2} \end{pmatrix}$$

$$\therefore \cos(\theta) * v_{2,1} + \sin(\theta)e^{-i\phi} * v_{2,2} = -v_{2,1}, \sin(\theta)e^{i\phi} * v_{2,1} - \cos(\theta) * v_{2,2} = -v_{2,2}$$

$$v_{2,2} = e^{i\phi} \frac{\sin(\theta)}{(1 - \cos(\theta))} * v_{2,1}$$

- Thus, for eigenvalue $\lambda = -1$, the eigenvector $\mathbf{v_2} = (v_{2,1}, e^{i\phi} \frac{\sin(\theta)}{(1-\cos(\theta))} * v_{2,1})$. We thus have our two eigenvalues (±1) and our two eigenvectors ($\mathbf{v_1}$ and $\mathbf{v_2}$)
- (b) By rotating the spinor pointing initially along the $+\hat{z}$ axis direction by appropriate angles, using the appropriate rotation operator. Convince yourself that one has to rotate by an angle θ counterclockwise around the *y*-axis and then by ϕ around the *z*-axis. Apart from overall phases, is the resultant spinor the same as the spin up eigenvector obtained in part (a)?
 - Let's start with the spinor pointing in the +z-direction.

$$\left| s_z = +\frac{\hbar}{2} \right\rangle = \begin{bmatrix} 1\\0 \end{bmatrix}, \quad s.t. \quad S_z \left| s_z = +\frac{\hbar}{2} \right\rangle = +\frac{\hbar}{2} \left| s_z = +\frac{\hbar}{2} \right\rangle$$

If we apply consecutive rotation operators, we should be able to rotate this spinor into a general state, pointing in an arbitrary direction $\hat{\mathbf{n}}$, where $\hat{\mathbf{n}}$ points in the (θ, ϕ) direction.

We first rotate this spinor by θ around the y-axis, and then by ϕ around the z-axis. The axis of spin now points in the direction $\hat{\bf n}$. Thus -

$$|\hat{n}+\rangle = U[R(\phi \hat{\mathbf{z}})]U[R(\theta \hat{\mathbf{y}})]\begin{bmatrix}1\\0\end{bmatrix}$$

To find the explicit form of $|\hat{n}+\rangle$, we'll need the forms of the unitary matrices $U[R(\phi \hat{\mathbf{z}})]$ and $U[R(\theta \hat{\mathbf{y}})]$. We'll use the result given in Shankar -

$$U[R(\boldsymbol{\theta}] = \cos\frac{\theta}{2}I - i\sin\frac{\theta}{2}(\hat{\theta}.\boldsymbol{\sigma})$$

Looking at the particular case of rotation around y-axis by amount θ and then subsequently around z-axis by amount ϕ -

$$U[R(\theta \hat{\mathbf{y}})] \begin{bmatrix} 1\\0 \end{bmatrix} = \begin{bmatrix} \cos\frac{\theta}{2}I - i\sin\frac{\theta}{2}\sigma_y \end{bmatrix} \begin{bmatrix} 1\\0 \end{bmatrix}$$
$$= \begin{bmatrix} \cos\frac{\theta}{2}\\0 \end{bmatrix} - i\sin\frac{\theta}{2}\begin{bmatrix} 0 & -i\\i & 0 \end{bmatrix} \begin{bmatrix} 1\\0 \end{bmatrix}$$
$$= \begin{bmatrix} \cos\frac{\theta}{2}\\\sin\frac{\theta}{2} \end{bmatrix}$$

Applying rotation around z-axis by amount ϕ now, we get

$$U[R(\phi \hat{\mathbf{z}})] \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix} = \begin{bmatrix} \cos \frac{\phi}{2} I - i \sin \frac{\phi}{2} \sigma_z \end{bmatrix} \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \cos \frac{\phi}{2} \cos \frac{\theta}{2} \\ \cos \frac{\phi}{2} \sin \frac{\theta}{2} \end{bmatrix} - i \sin \frac{\phi}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \cos \frac{\theta}{2} \left(\cos \frac{\phi}{2} - i \sin \frac{\phi}{2} \right) \\ \sin \frac{\theta}{2} \left(\cos \frac{\phi}{2} + i \sin \frac{\phi}{2} \right) \end{bmatrix}$$

$$= \begin{bmatrix} \cos \frac{\theta}{2} e^{-i \frac{\phi}{2}} \\ \sin \frac{\theta}{2} e^{i \frac{\phi}{2}} \end{bmatrix}$$

This gives us a spinor $s_n = (s_{n1}, s_{n2}) = (\cos \frac{\theta}{2} e^{-i\frac{\phi}{2}}, \sin \frac{\theta}{2} e^{i\frac{\phi}{2}})$. If we recall our $\mathbf{v}_1 = (v_{1,1}, v_{1,2})$ from part (a), we recall the relation we obtained at the end.

$$v_{1,2} = e^{i\phi} \frac{\sin(\theta)}{(\cos(\theta) + 1)} * v_{1,1}$$

Substituting $v_{1,1}=s_{n1}=\cos\frac{\theta}{2}e^{-i\frac{\phi}{2}}$ (as our final spinor seems to suggest), we get -

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$$v_{1,2} = e^{i\phi} \frac{\sin(\theta)}{(\cos(\theta) + 1)} * v_{1,1}$$
$$= e^{i\phi} \frac{\sin(\theta)}{(\cos(\theta) + 1)} * \cos\frac{\theta}{2} e^{-i\frac{\phi}{2}}$$

Recall $1 + \cos(A) = 2 * \cos^2(\frac{A}{2})$ and $\sin(A) = 2 * \sin(\frac{A}{2})\cos(\frac{A}{2})$

$$\begin{split} e^{i\phi} \frac{\sin(\theta)}{(\cos(\theta)+1)} * \cos\frac{\theta}{2} e^{-i\frac{\phi}{2}} &= e^{i\frac{\phi}{2}} \frac{\sin(\theta)}{2\cos^2(\frac{\theta}{2})} * \cos\frac{\theta}{2} \\ &= e^{i\frac{\phi}{2}} \frac{2\sin(\frac{\theta}{2})\cos(\frac{\theta}{2})}{2\cos^2(\frac{\theta}{2})} * \cos\frac{\theta}{2} \\ &= e^{i\frac{\phi}{2}} \sin(\frac{\theta}{2}) = s_{n2} \end{split}$$

Therefore, apart from phase factors, the resultant spinor is the same as the spin up eigenvector we got in part (a).

⁵³ Question 3.

- 4 [Sahas: I got this one.]
 - (a) Construct the matrices \hat{J}_x and \hat{J}_y for a particle with spin one, j=1 (of course \hat{J}_z is already diagonal with eigenvalues \hbar , 0, $-\hbar$).
 - We can write the J_x operator as $\frac{J_++J_-}{2}$. We can write the matrix elements of this matrix in the $\langle j,m|$ basis as $\langle j,m'|\frac{J_++J_-}{2}|j,m\rangle$. Note that this matrix element will vanish if m'=m or |m'-m|>1. This gives us the following matrix for $\frac{J_++J_-}{2}$, when the basis elements are $|-1\rangle$, $|0\rangle$, $|+1\rangle$, in that order.

$$\begin{bmatrix} 0 & a & 0 \\ b & 0 & c \\ 0 & d & 0 \end{bmatrix}$$
 (10)

Now

$$a = \langle -1| J_x | 0 \rangle$$

$$= \langle -1| \frac{J_-}{2} | 0 \rangle$$

$$= \langle -1| \frac{\hbar \sqrt{(1)(1+1) - (0)(0-1)}}{2} | -1 \rangle$$

$$= \hbar \frac{\sqrt{2}}{2}$$

$$= \frac{\hbar}{\sqrt{2}}$$

$$(11)$$

Now, since the matrix is hermitian, we have the following relation between a and b:

$$b = a^*$$

$$\implies b = \frac{\hbar}{\sqrt{2}}$$
(12)

We can perform the same calculation for c:

$$c = \langle 0 | J_x | 1 \rangle$$

$$= \langle 0 | \frac{J_-}{2} | 1 \rangle$$

$$= \langle 0 | \frac{\hbar \sqrt{(1)(1+1) - (1)(1-1)}}{2} | 1 \rangle$$

$$= \hbar \frac{\sqrt{2}}{2}$$

$$= \hbar \frac{1}{\sqrt{2}}$$

$$(13)$$

Again, using the hermiticity argument, we get $d=c=\frac{\hbar}{\sqrt{2}}$. Therefore the final J_x matrix is:

$$\frac{\hbar}{\sqrt{2}} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \tag{14}$$

Now that we have J_x (and J_z is trivial), we can use the commutator relation to get J_y :

$$[J_x, J_z] = -i\hbar J_v \tag{15}$$

We write $[J_x, J_z]$ as

$$\frac{\hbar^2}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$
(16)

With a little algebra we get

$$[J_x, J_z] = -i\hbar J_y = \frac{\hbar^2}{\sqrt{2}} \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$
 (17)

Finally we get

$$J_{y} = \frac{i\hbar}{\sqrt{2}} \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$
 (18)

- (b) An unpolarized beam of spin 1 particles enters a Stern-Gerlach filter that passes only particles with $S_z = \hbar$. After exiting this filter, the beam enters a second filter that passes particles with $S_z = \hbar$ and then finally it encounters a third filter that passes only particles with $S_z = -\hbar$. What fraction of the initial particles make it right through?
- By computing the eigenvectors of the matrix in equation (9) we get the results

$$\left| \langle S_x = i | S_z = j \rangle^2 = 1/3 \right|^2 = \frac{1}{3}$$
 (19)

for i, j = -1, 0, 1.

Since the beam is unpolarised, 1/3 of the particles will pass through the first filter. Again, because of result (10), 1/3 of the particles will pass through filter 2. Similarly, 1/3 of these particles will then pass through filter 3. Finally we find that 1/27 of the particles will pass through the whole set-up.

⁷⁹ 4. Your question here.

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- 81 [Sankalp: I got this one.]
- First, we write down $U(R(\epsilon \hat{\mathbf{n}}))$ in terms of familiar operators assuming $\hat{\mathbf{n}} = n_x \hat{\mathbf{x}} + n_y \hat{\mathbf{y}} + n_z \hat{\mathbf{z}}$ to get

$$U(R(\epsilon \hat{\mathbf{n}})) = \exp\left(-\frac{i\epsilon}{\hbar} \cdot (\hat{\mathbf{J}} \cdot \hat{\mathbf{n}})\right)$$
$$= \exp\left(-\frac{i\epsilon}{\hbar} \cdot (n_x \hat{\mathbf{J}}_x + n_y \hat{\mathbf{J}}_y + n_z \hat{\mathbf{J}}_z)\right)$$
(20)

- 5. Prove that any function of the radial coordinate f(r) where $r = |\mathbf{r}|$ and $\mathbf{X} \cdot \mathbf{P}$, where \mathbf{X} and \mathbf{P} are the position and momentum operators, are both scalar operators.
- [Parth: Doing question 5, I'm not spending as much time on this as question 2]

Under a symmetry operator U, operators change as $\mathfrak{G}' = U^{\dagger} \mathfrak{G} U$. A scalar operator being one which is invariant under rotations, i.e

$$S' = U^{\dagger}[R]SU[R] = S$$

- where $U(R(\alpha) = e^{-\frac{i}{\hbar}\alpha \cdot J})$.
- By considering infinitesimal rotations $\alpha = \epsilon$, we have

$$U[R(\alpha)] = \left(1 - \frac{i}{\hbar}\epsilon_i J_i\right)$$

Thus, our definition for a scalar operator becomes -

$$S' = \left(1 + \frac{i}{\hbar} \epsilon_i J_i\right) S\left(1 - \frac{i}{\hbar} \epsilon_i J_i\right) = S$$

which gives us $\frac{i}{\hbar}\epsilon_i$ [J_i , S] = 0. Since ϵ was an arbitrary choice, we have

$$[J_i, S] = 0$$

- o as our definition of a scalar operator.
- Considering f(r), where $r = |\mathbf{r}|$ as our operator.

$$[J_i, f(r)] = [J_i, r] * f'(r)$$

 $r = \sqrt{\sum_{i=1}^{3} X_i^2}$, Thus

$$[J_i, r] = [J_i, X_1] * \frac{X_1}{r} + [J_i, X_2] * \frac{X_2}{r} + [J_i, X_3] * \frac{X_3}{r}$$

we know that $[J_i, X_j] = i\hbar \epsilon_{ijl} X_l$. Thus

$$[J_i, r] = [J_i, X_j] * \frac{X_j}{r} = \frac{1}{r} (i\hbar \epsilon_{ijl} X_l X_j)$$

$$\epsilon_{ijl}X_lX_j = \left[X_l,X_j\right] = 0 (l \neq j) \Longrightarrow \left[J_i,r\right] = 0$$

- Thus, since $[J_i, r] = 0$, we have $[J_i, f(r)] = [J_i, r] * f'(r) = 0 * f'(r) = 0$.
- Thus, f(r) is a scalar operator.

Now considering $O = \mathbf{X}$. **P** as our operator, we need to show $[J_i, O] = 0$

 $\mathbf{X}.\mathbf{P} = X_i P_i$ implicit summation

$$\therefore [J_i, O] = [J_i, X_j P_j]$$

$$= [J_i, X_j] P_j + X_j [J_i, P_j]$$

$$= i\hbar \epsilon_{ijl} (X_l P_j + X_j P_l)$$

Now, $\epsilon_{iil}X_lP_i=[X_l,P_i]$ for $l\neq j$, but $[X_l,P_i]=0, l\neq j$. Thus

$$i\hbar\epsilon_{ijl}(X_lP_j+X_jP_l)=0\Rightarrow [J_i,O]=0$$

- Since $[J_i, O] = 0$, we can say that the operator O is a scalar operator.
- 100 Thus, X.P is a scalar operator
- Ouestion 6.
- [Sahas: I got this one.]
- We know that the X_i operators can be written in terms of the spherical tensor operators as follows: (notation is the same as that used in Shankar, Principles of Quantum Mechanics, 2ed, page 419)

$$V_1^{+1} = \frac{iX_y - X_x}{\sqrt{2}}$$

$$V_1^0 = X_z$$

$$V_1^{-1} = -\frac{X_x + iX_y}{\sqrt{2}}$$
(21)

Thus in general any linear combination of the X_i s can be written in terms of the V_1^i s. Note that $\epsilon \cdot X$ is exactly such a linear combination. Thus we may write

$$\hat{O} = \epsilon \cdot \mathbf{X} = \alpha_i V_1^i \tag{22}$$

- Where the α_i are scalars, and summation over repeated values is implied.
- Using this form we can write the transition probability for the Hydrogen atom as

$$\left| \langle n', l', m' | \alpha_i V_1^i | n, l, m \rangle \right| \tag{23}$$

- Now since each V_1^i , acting on $|n, l, m\rangle$ can either:
- Increase the value of l by 1
- Decrease the value of l by 1
- Keep the value of *l* unchanged

- Or give a superposition of the above. Since states of different l are orthogonal, $\alpha_i V_1^i | n, l, m \rangle$ and $\langle n', l', m' |$ won't have any common terms unless |l l'| = 1 or l = l'.
- 115 Thus we get the relation

$$\left| \langle n', l', m' | \alpha_i V_1^i | n, l, m \rangle \right| = 0 \tag{24}$$

- 116 Unless |l l'| = 1 or l = l'.
- Since EM theory is invariant under parity inversion, we must require that expectation values of the dipole
- moment be conserved under parity inversion.

$$|\langle n', l, m' | \epsilon \cdot \mathbf{X} | n, l, m \rangle| = |\langle n', l', m' | P^{\dagger} \epsilon \cdot \mathbf{X} P | n, l, m \rangle|$$
(25)

Since $|n, l, m\rangle$ transforms as $|n, l, m\rangle \longrightarrow (-1)^l |n, l, m\rangle$ under parity,

$$(-1)^{l'+l} \langle n', l', m' | \epsilon \cdot \mathbf{X} | n, l, m \rangle = \langle n', l', m' | P^{\dagger} \epsilon \cdot \mathbf{X} P | n, l, m \rangle$$
(26)

Since X transforms as $X \longrightarrow -X$ under parity, we get

$$(-1)^{l'+l} \langle n', l', m' | \epsilon \cdot \mathbf{X} | n, l, m \rangle = -\langle n', l', m' | \epsilon \cdot \mathbf{X} | n, l, m \rangle$$

$$(27)$$

Hence if l + l' is even (i.e. when l = l'), we get

$$\langle n', l', m' | \epsilon \cdot \mathbf{X} | n, l, m \rangle = 0 \tag{28}$$