

QEEE DSA05

DATA STRUCTURES AND

ALGORITHMS

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LECTURE 7, 26 AUGUST 2014

Recall that ...

- * BFS and DFS are two systematic ways to explore a graph
 - * Both take time linear in the size of the graph with adjacency lists
- * Recover paths by keeping parent information
- * BFS can compute shortest paths, in terms of number of edges
- * DFS numbering can reveal many interesting features

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 - * Distance travelled between two stations
 - * Typical time between two locations during peak hour traffic

Shortest paths

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- ✱ **Weighted graph**

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- * **Shortest path** from v_0 to v_n : minimum cost

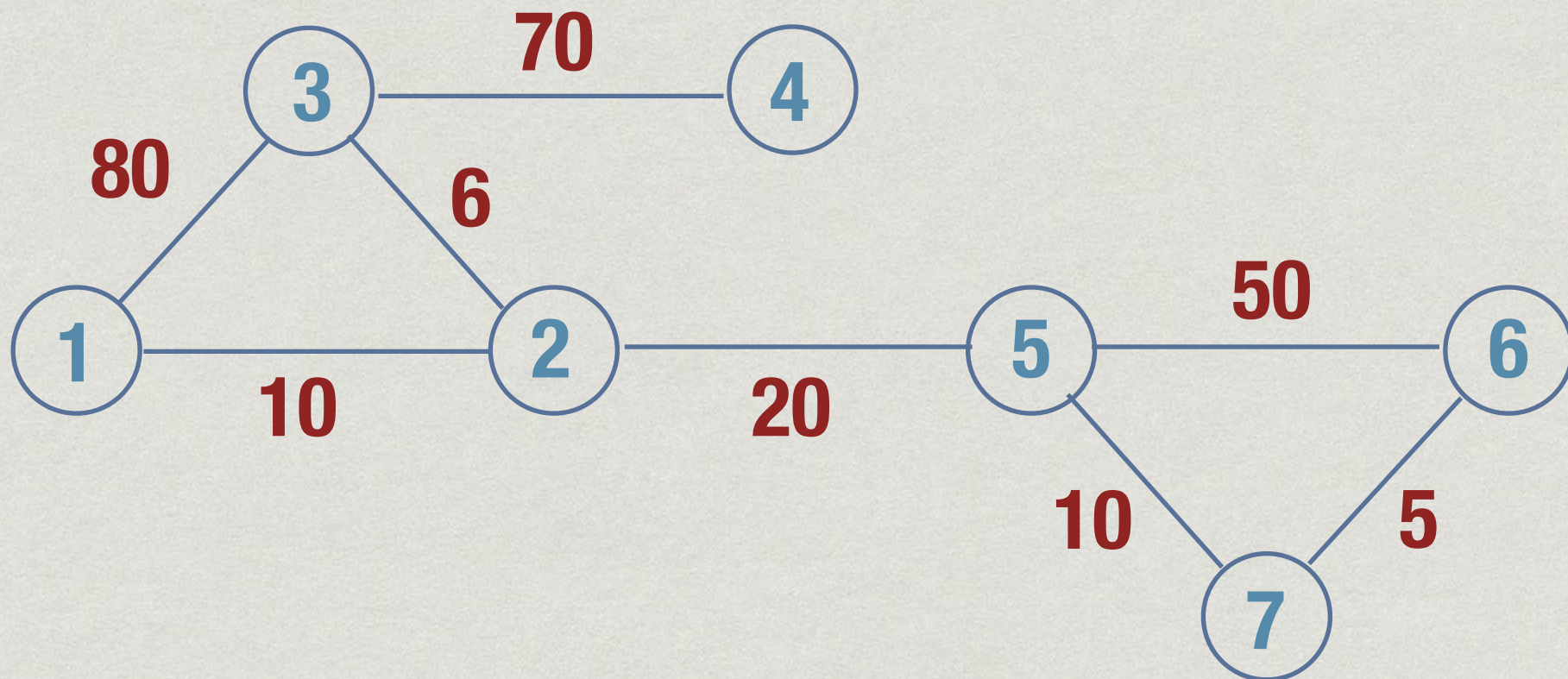
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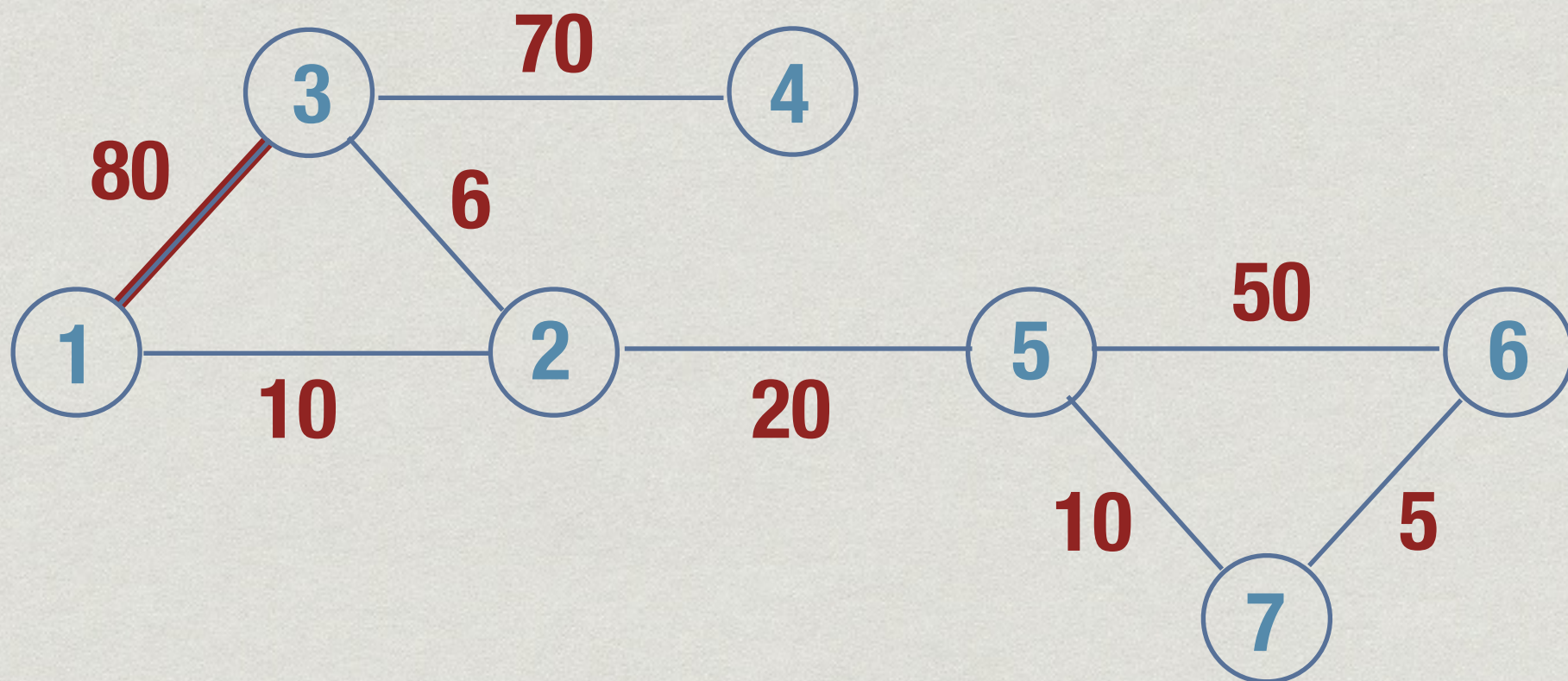
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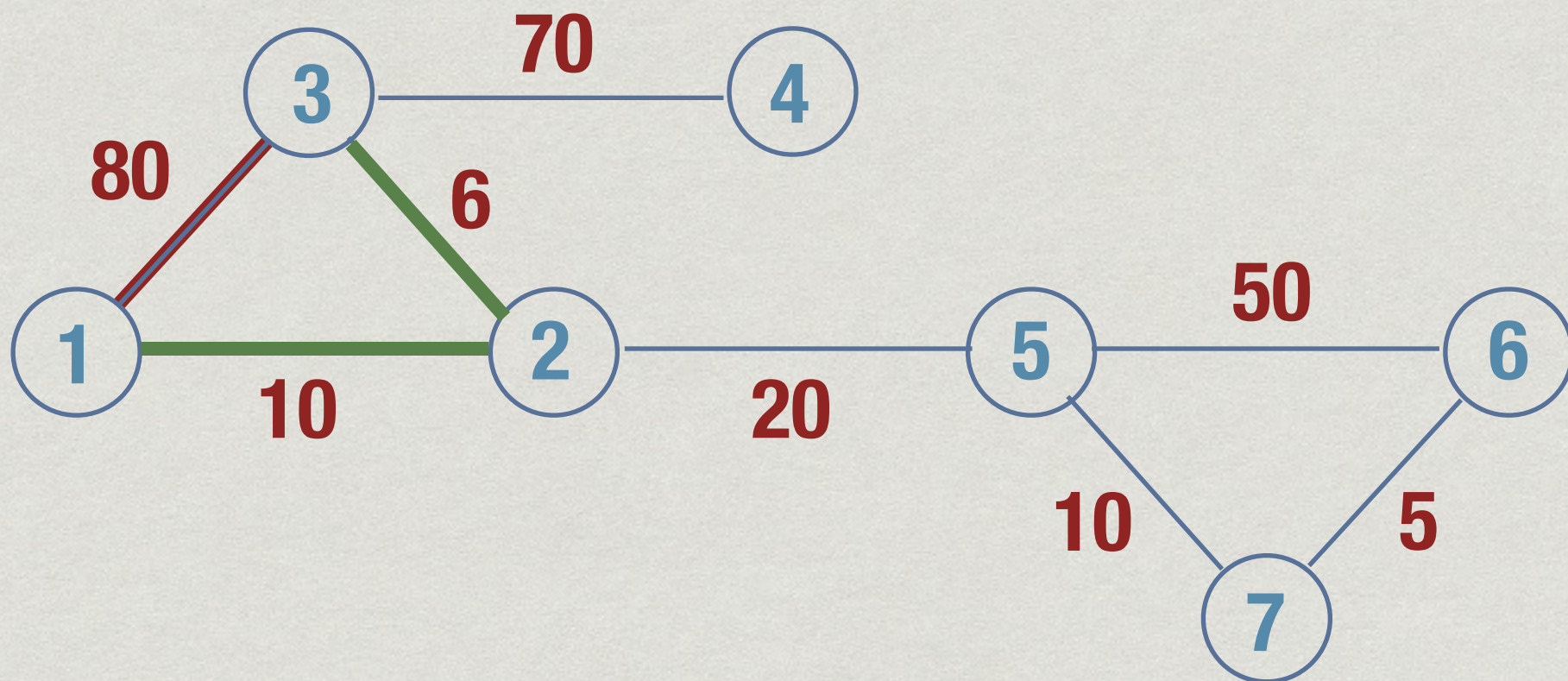
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- ✱ Transport finished product from factory (single source) to all retail outlets
- ✱ Courier company delivers items from distribution centre (single source) to addressees

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- ✱ Find shortest paths between every pair of vertices i and j
- ✱ Railway routes, shortest way to travel between any pair of cities

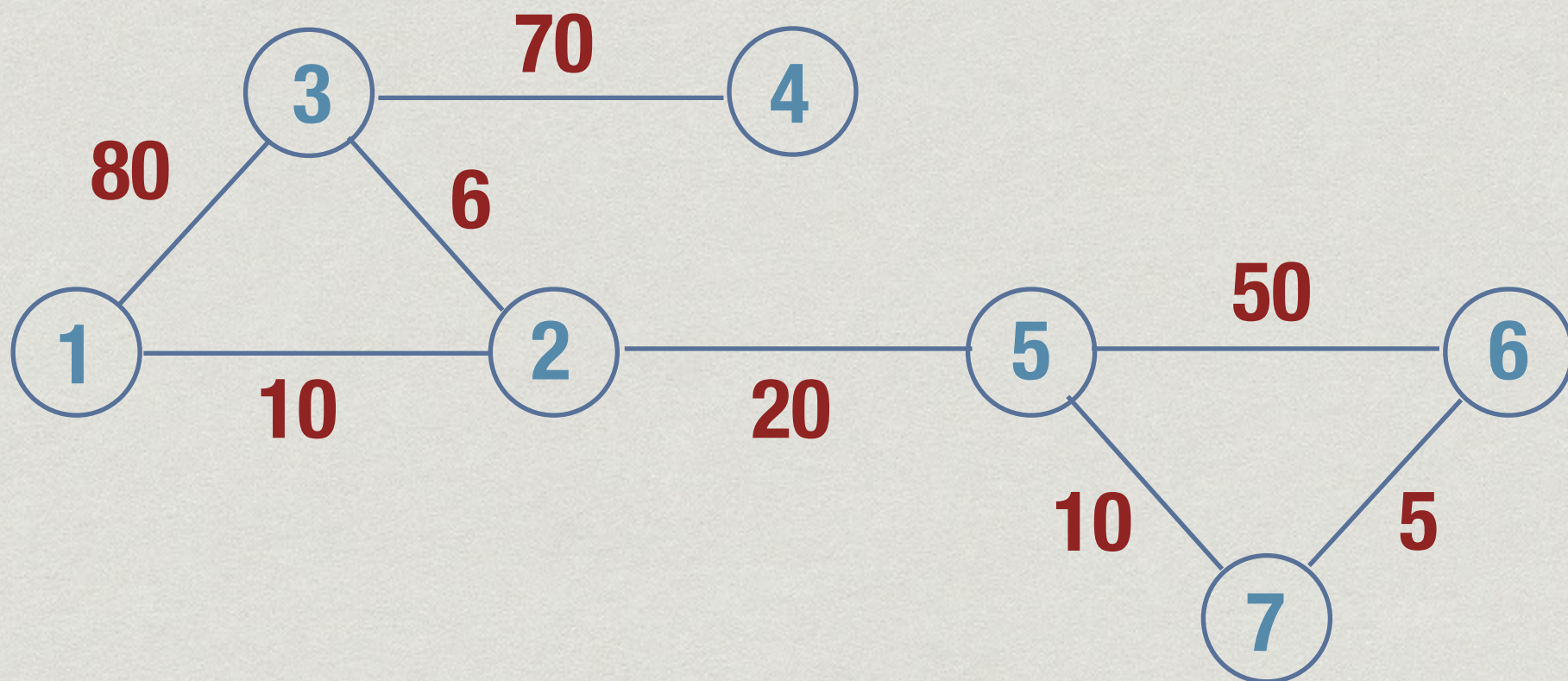
Today...

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- * For instance, shortest paths from 1 to 2,3,...,7



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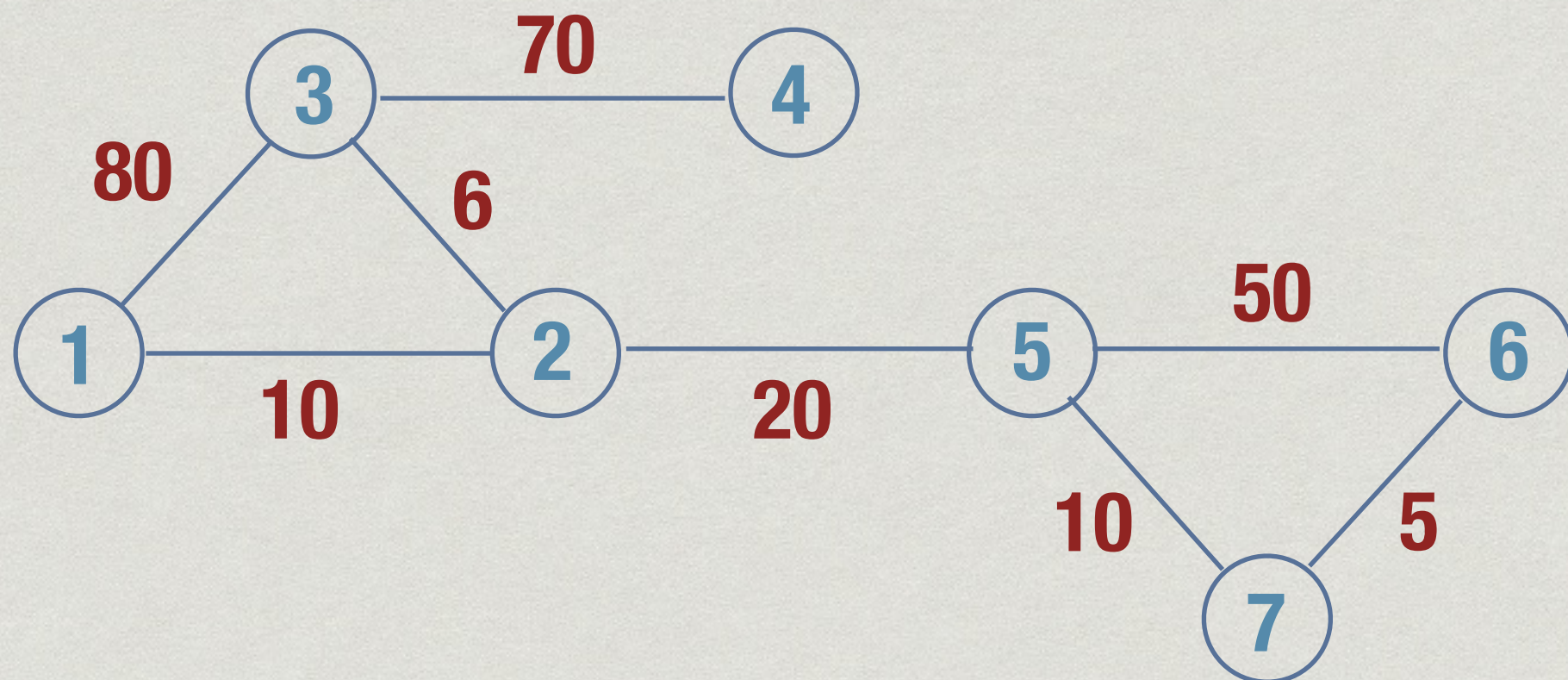
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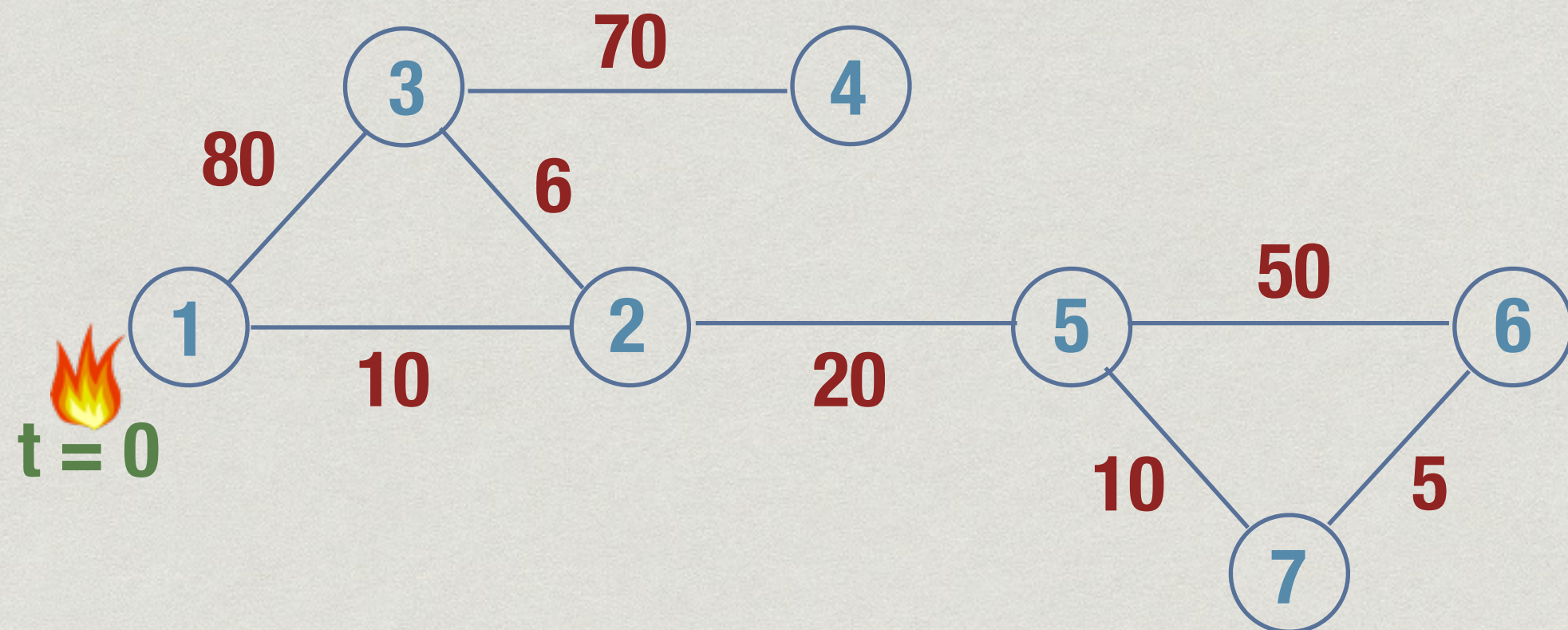
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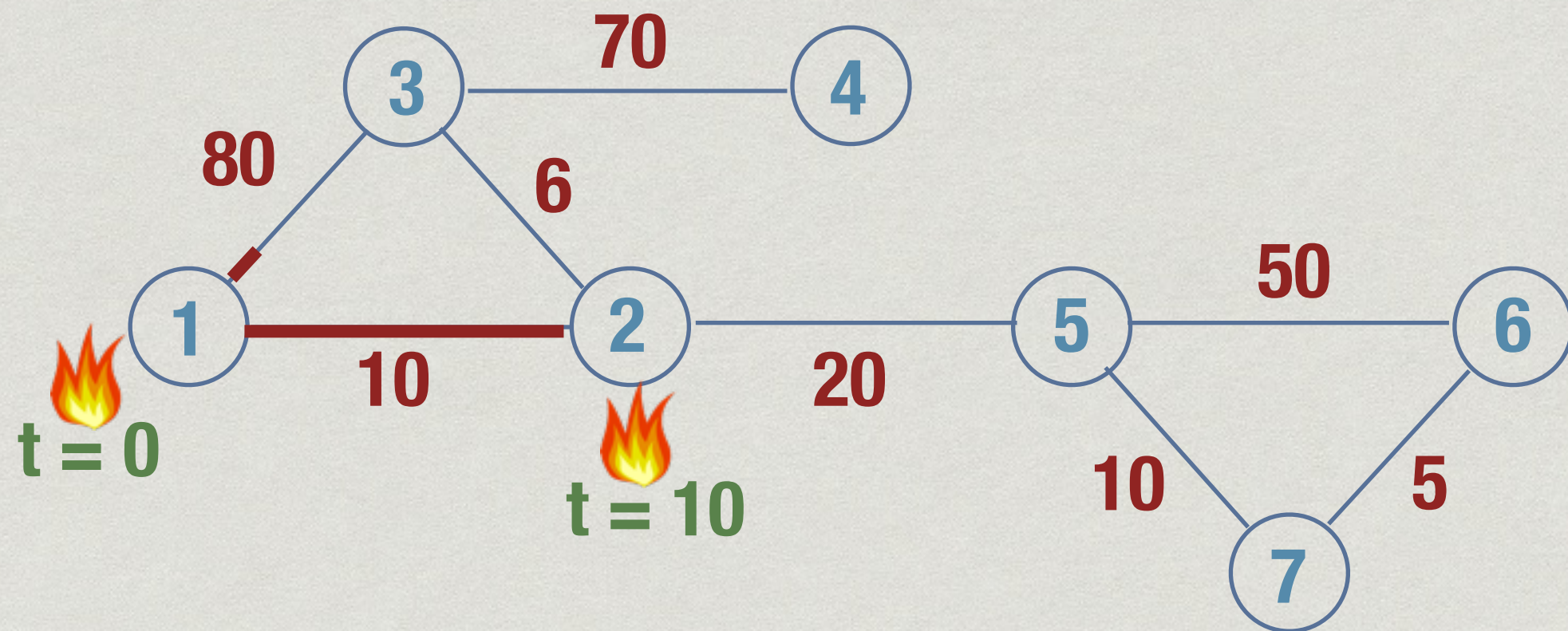
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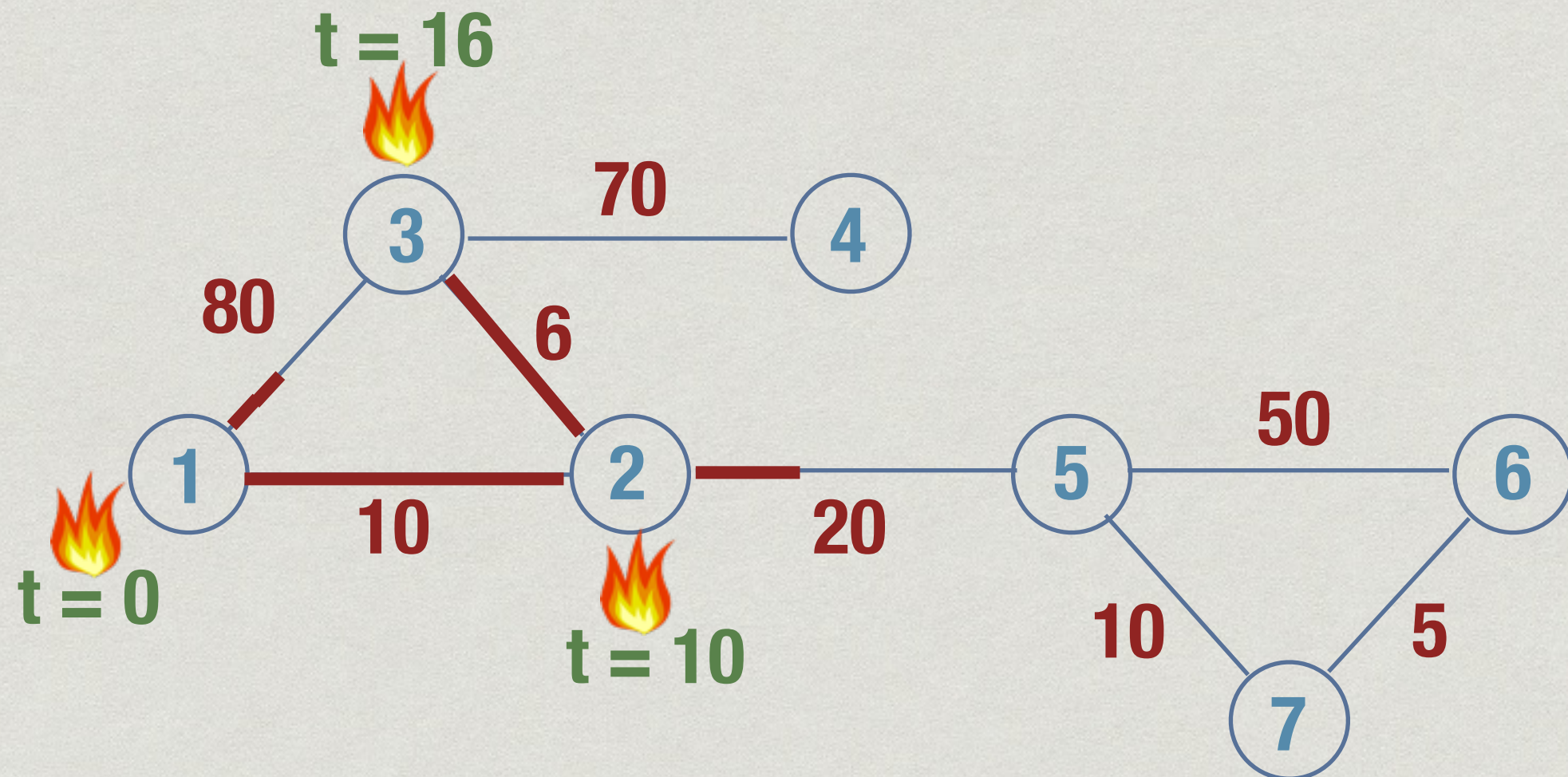
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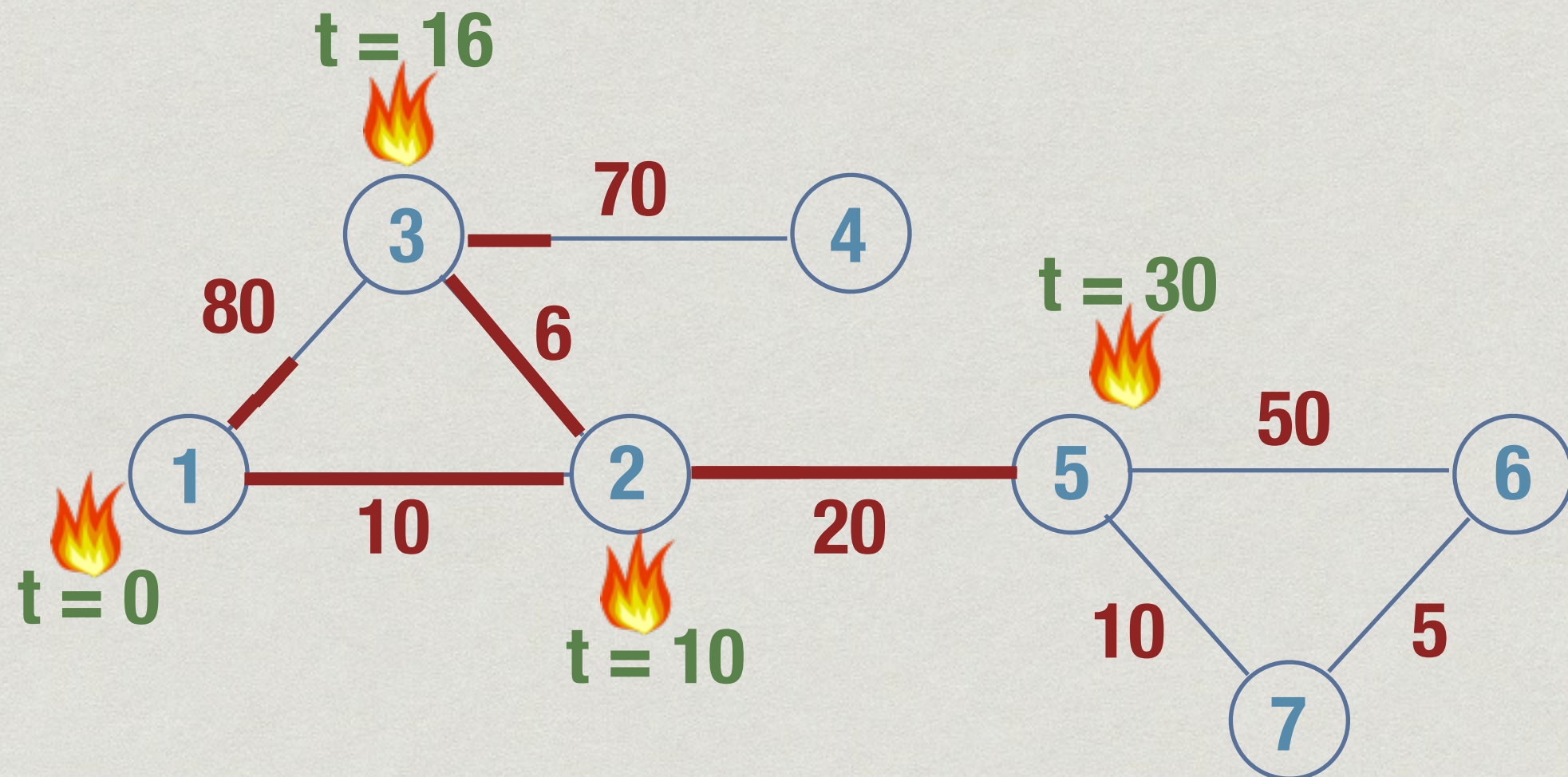
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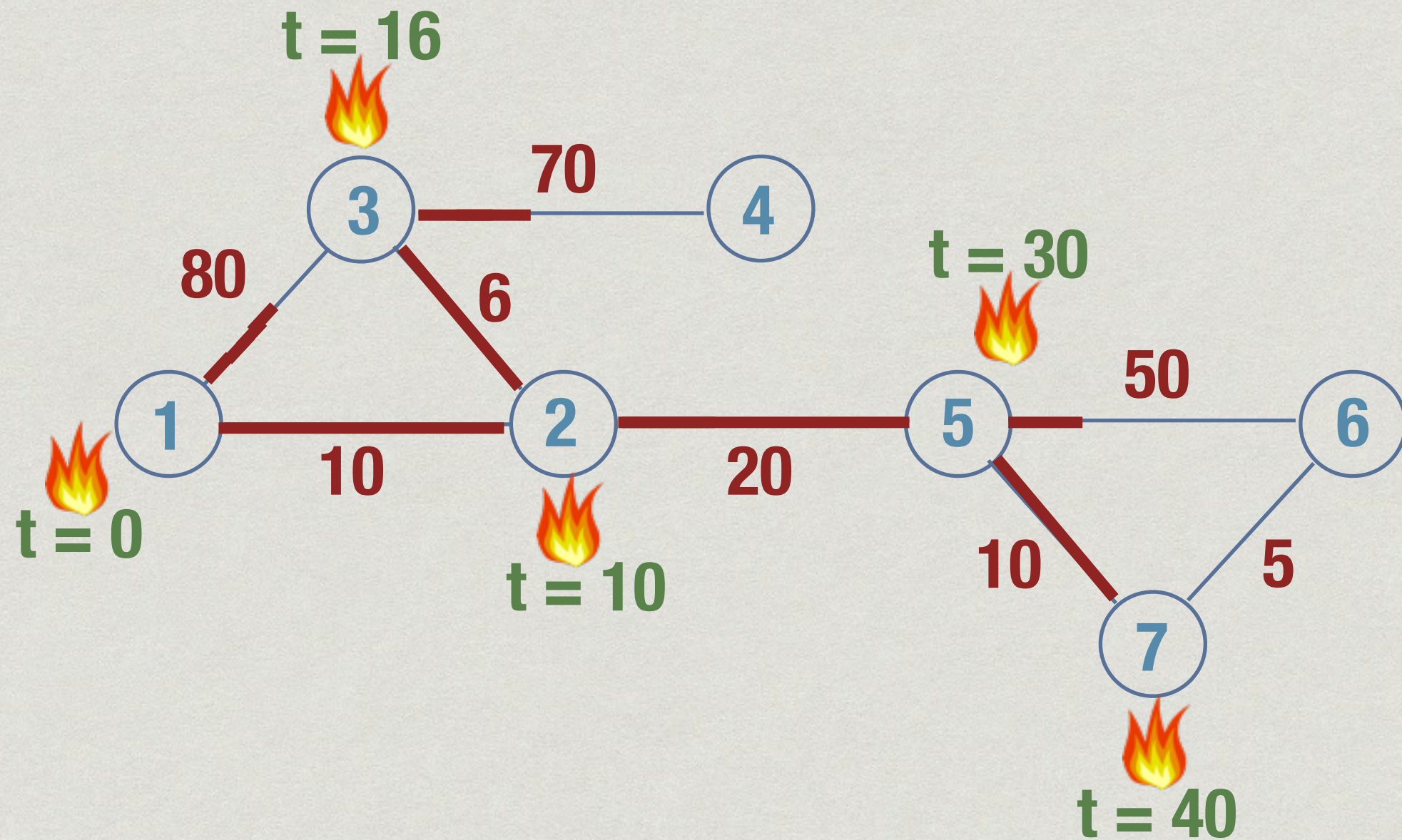
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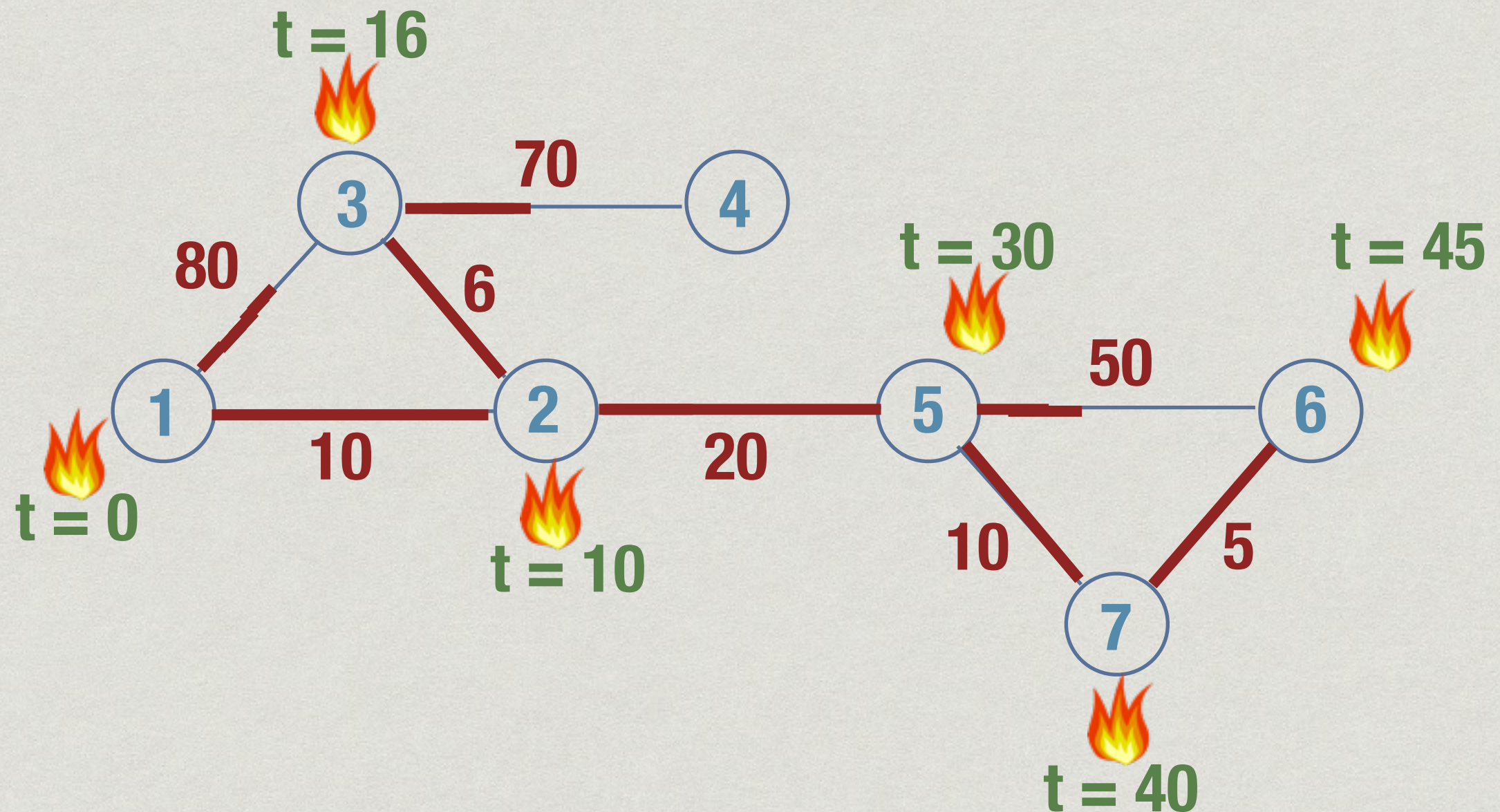
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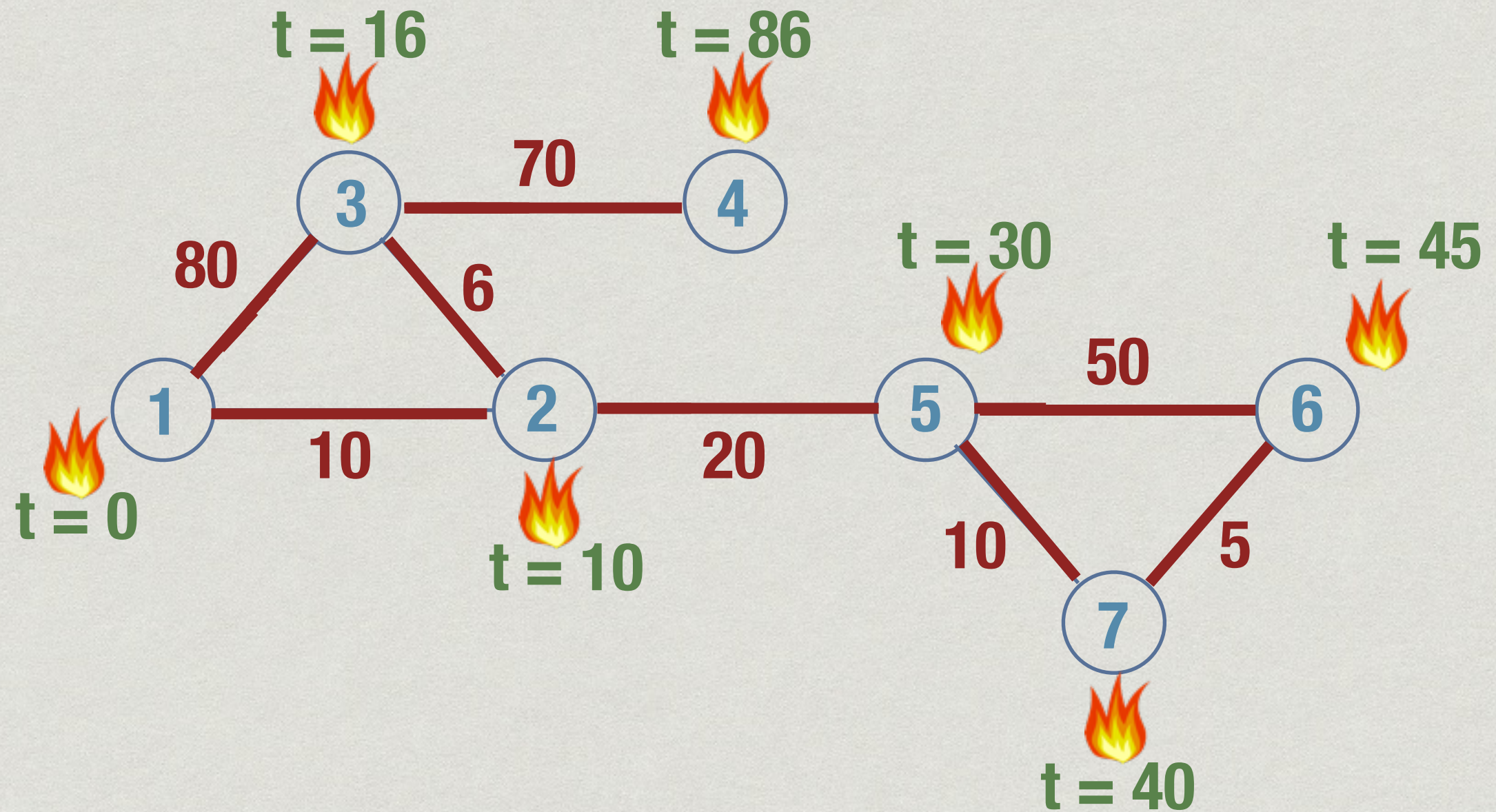
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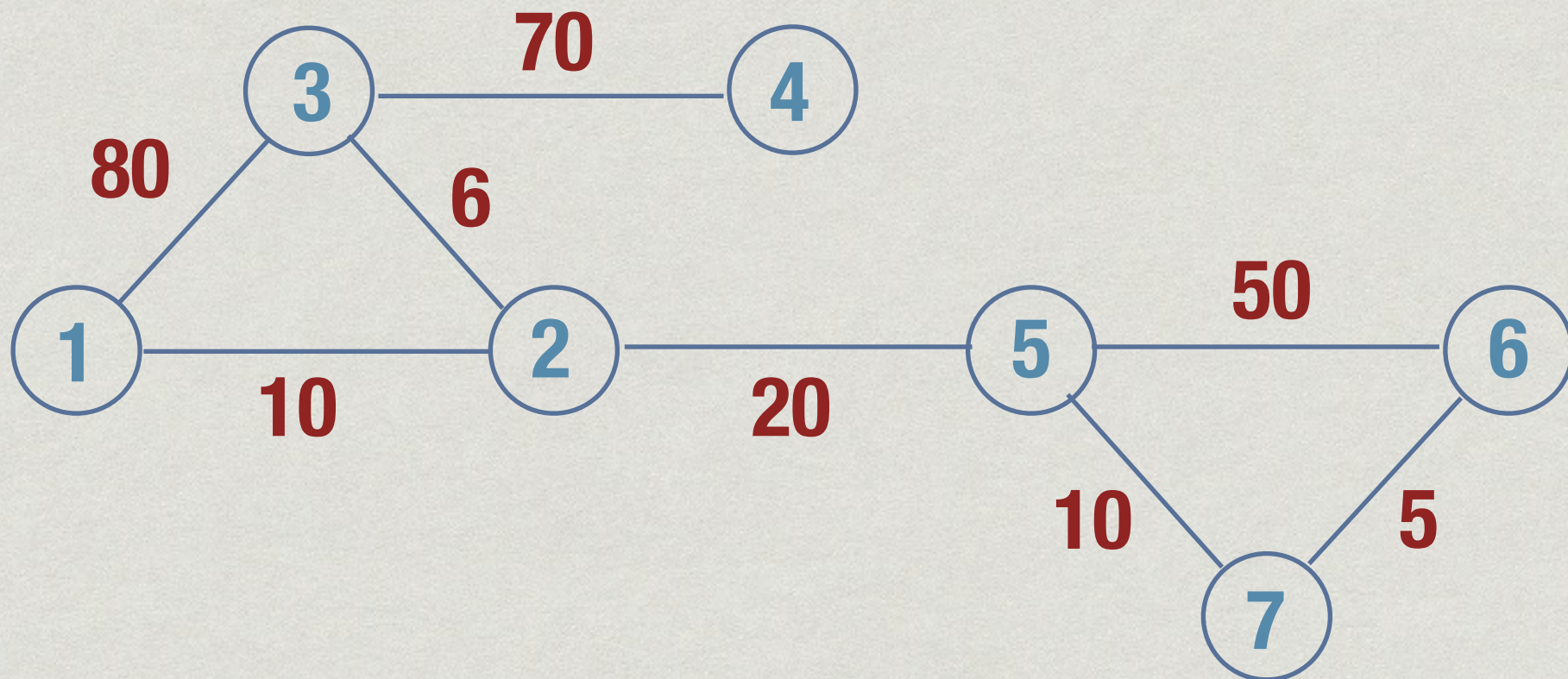


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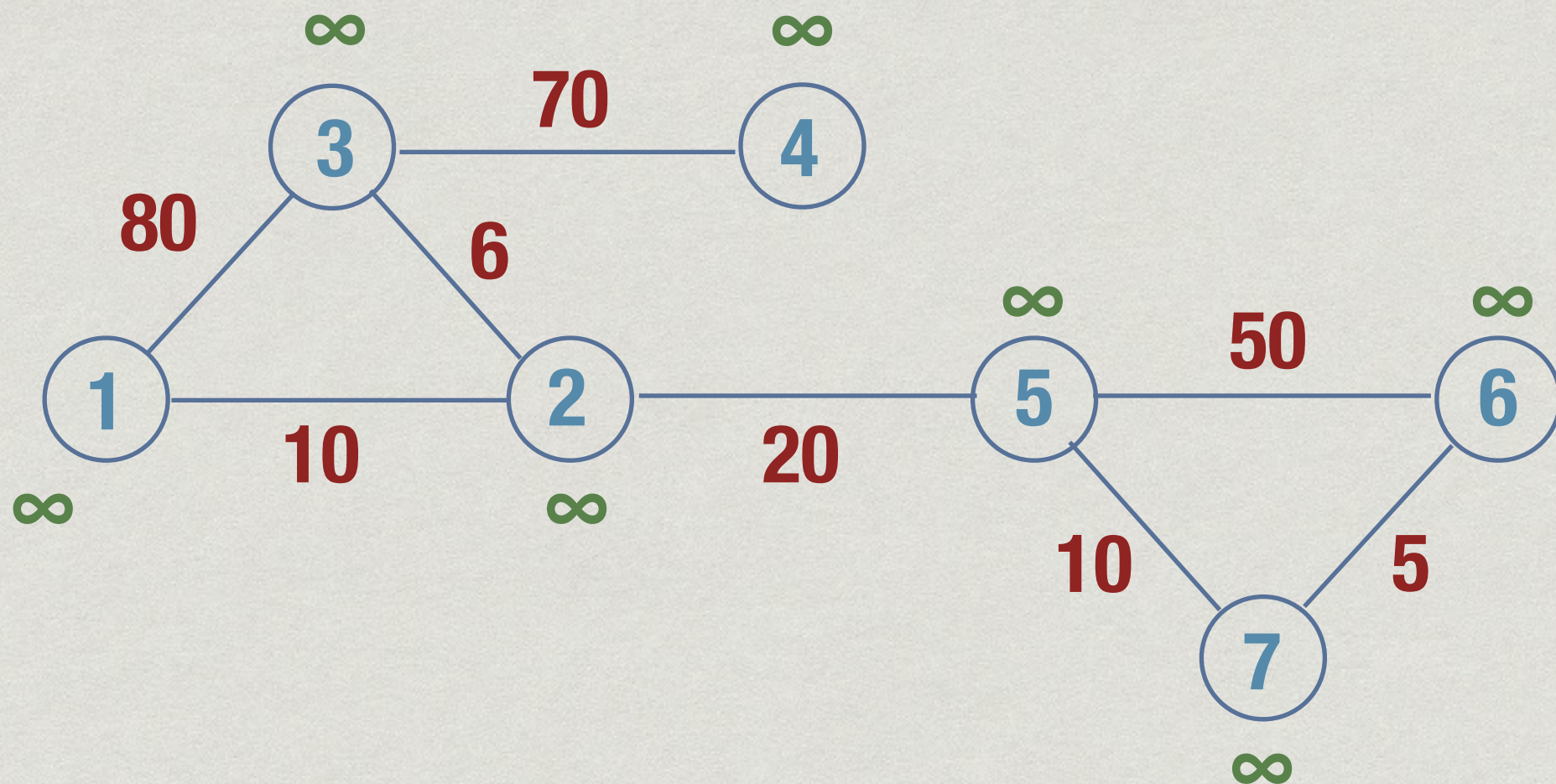
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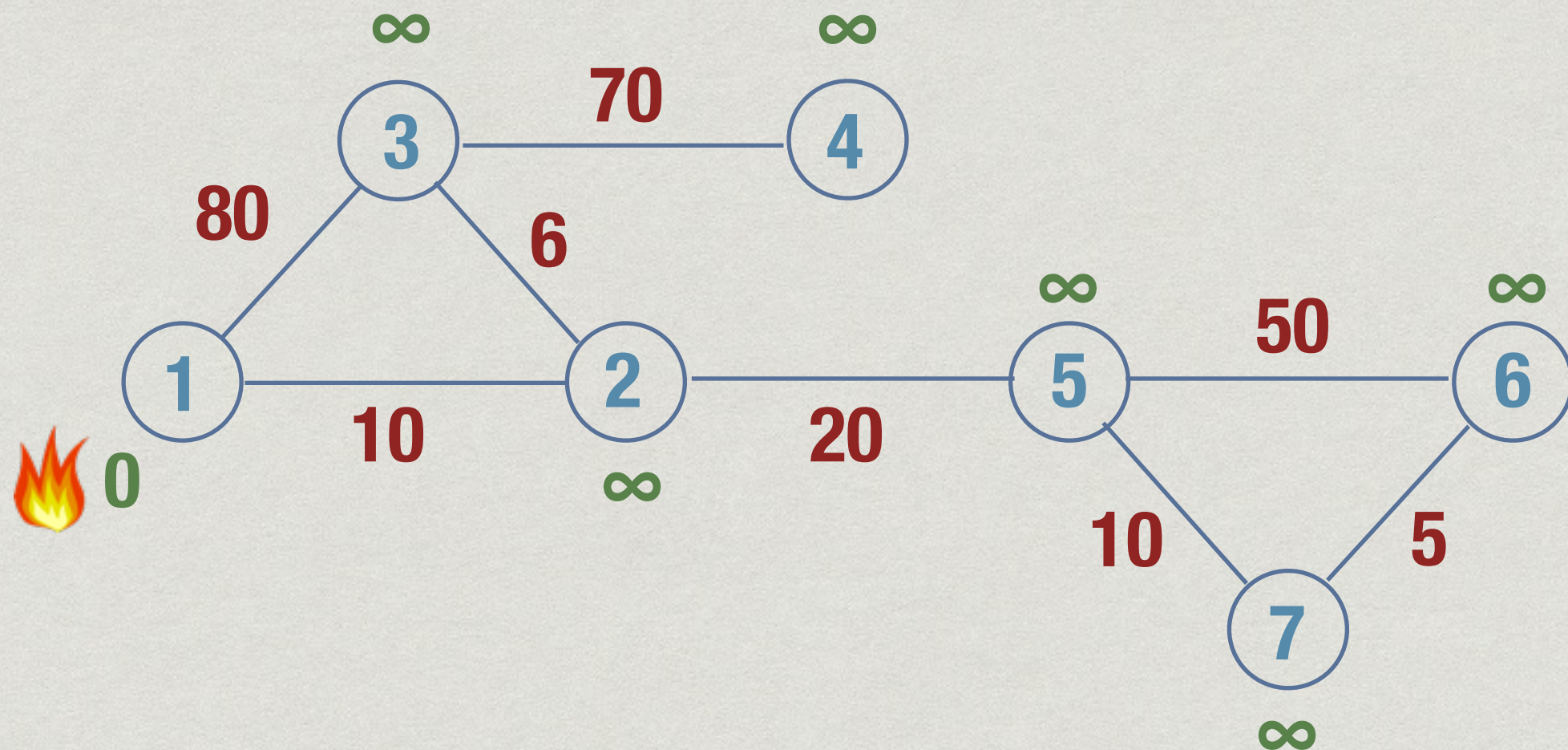
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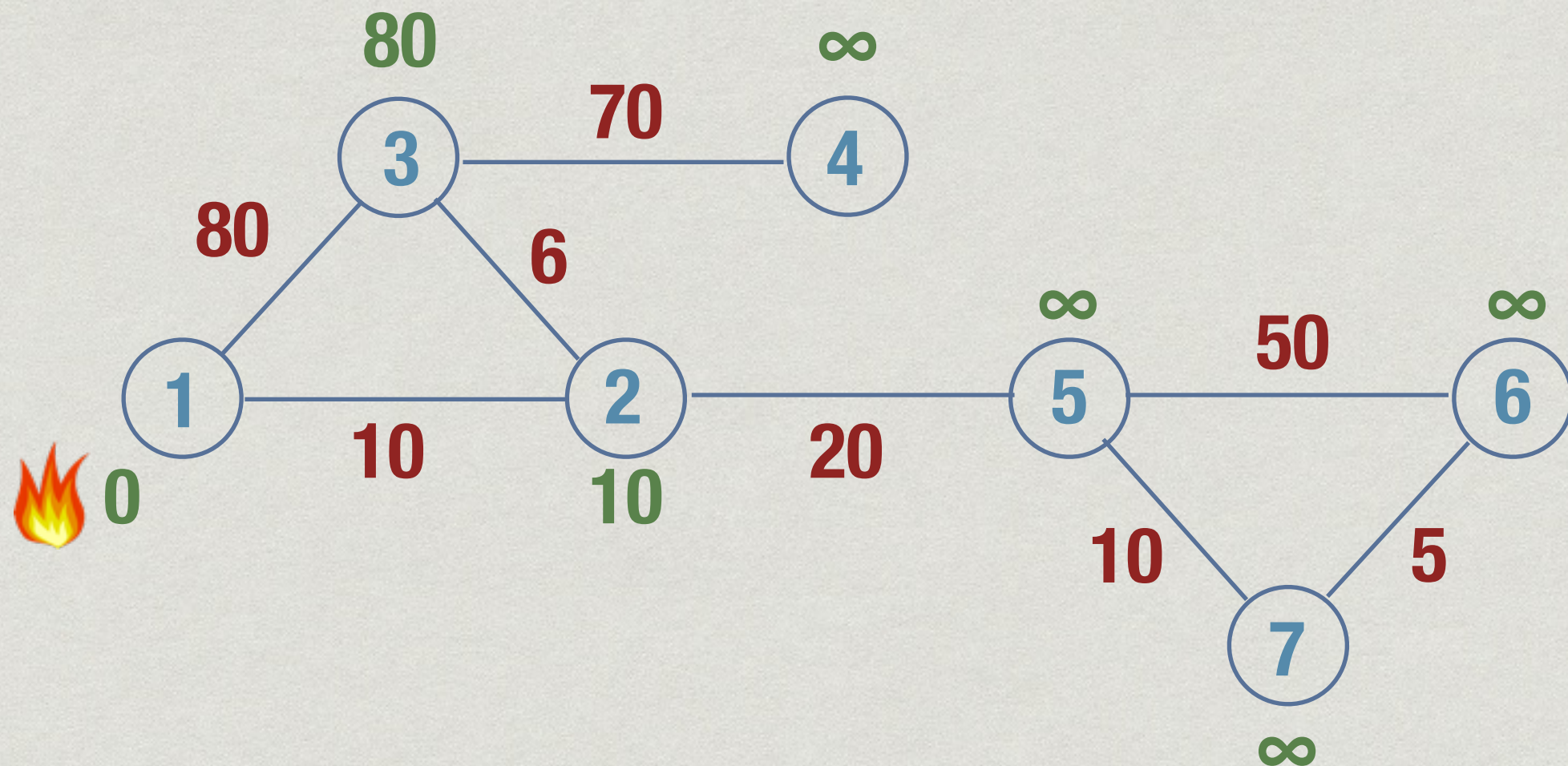
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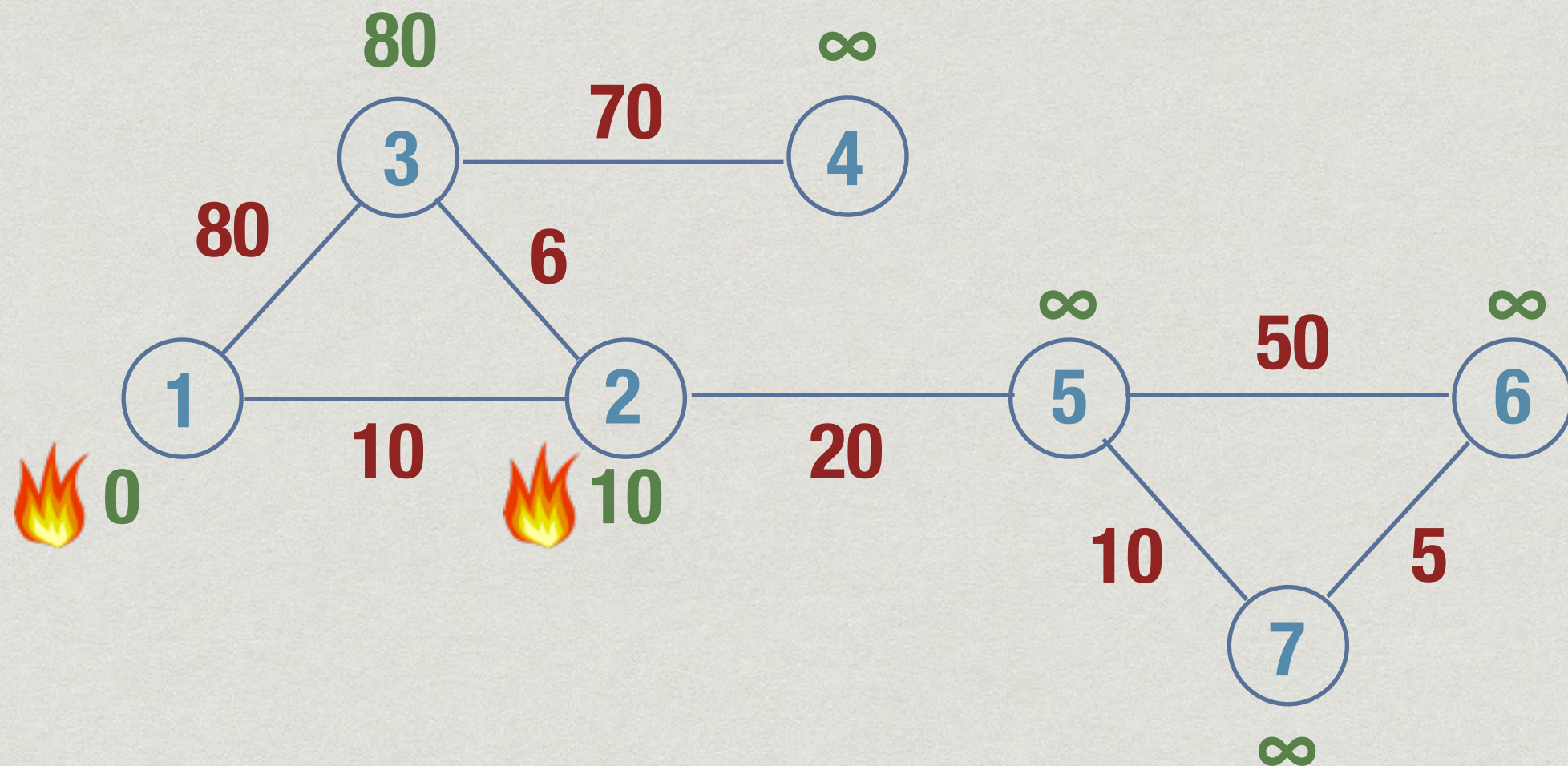
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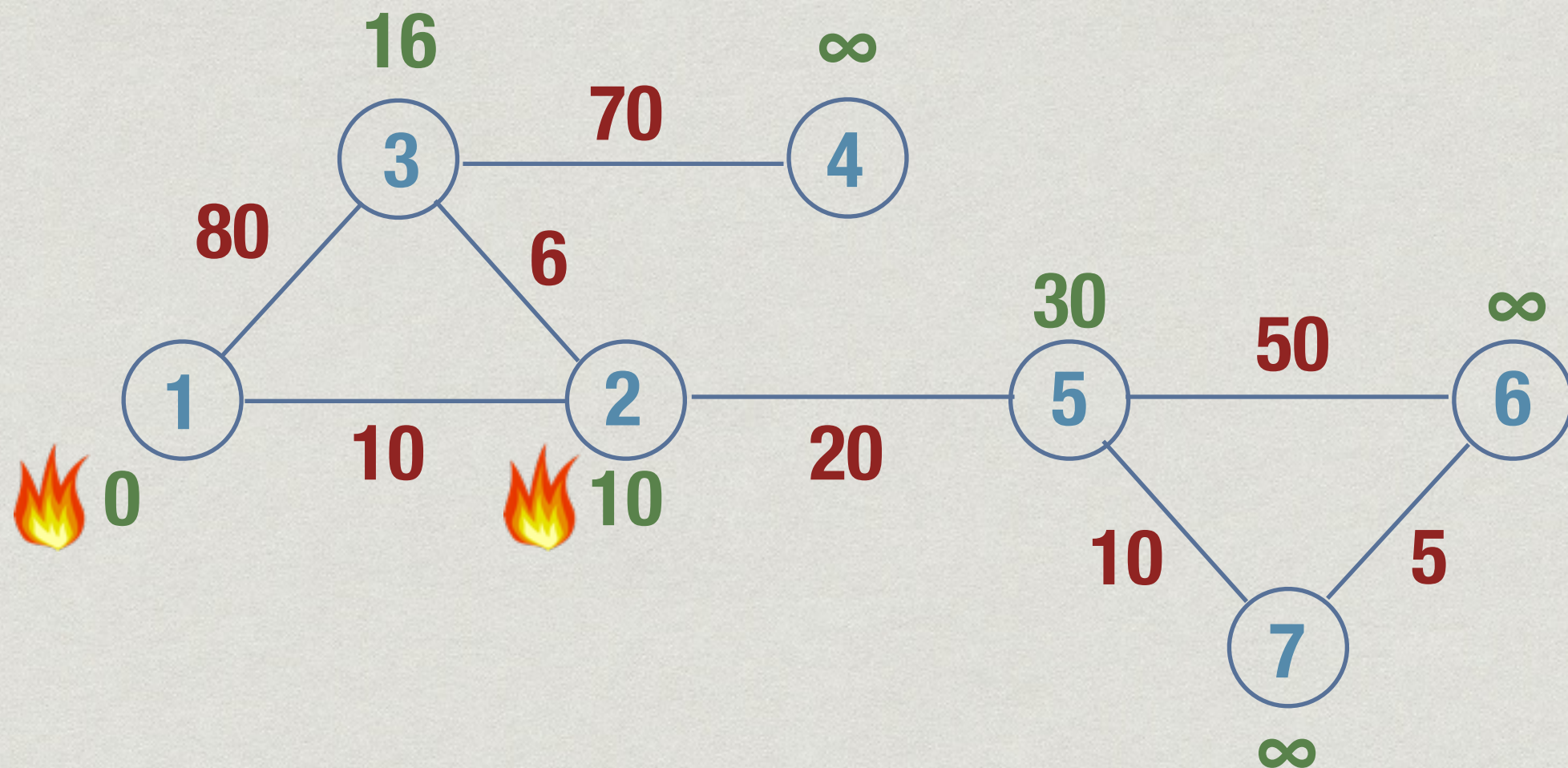
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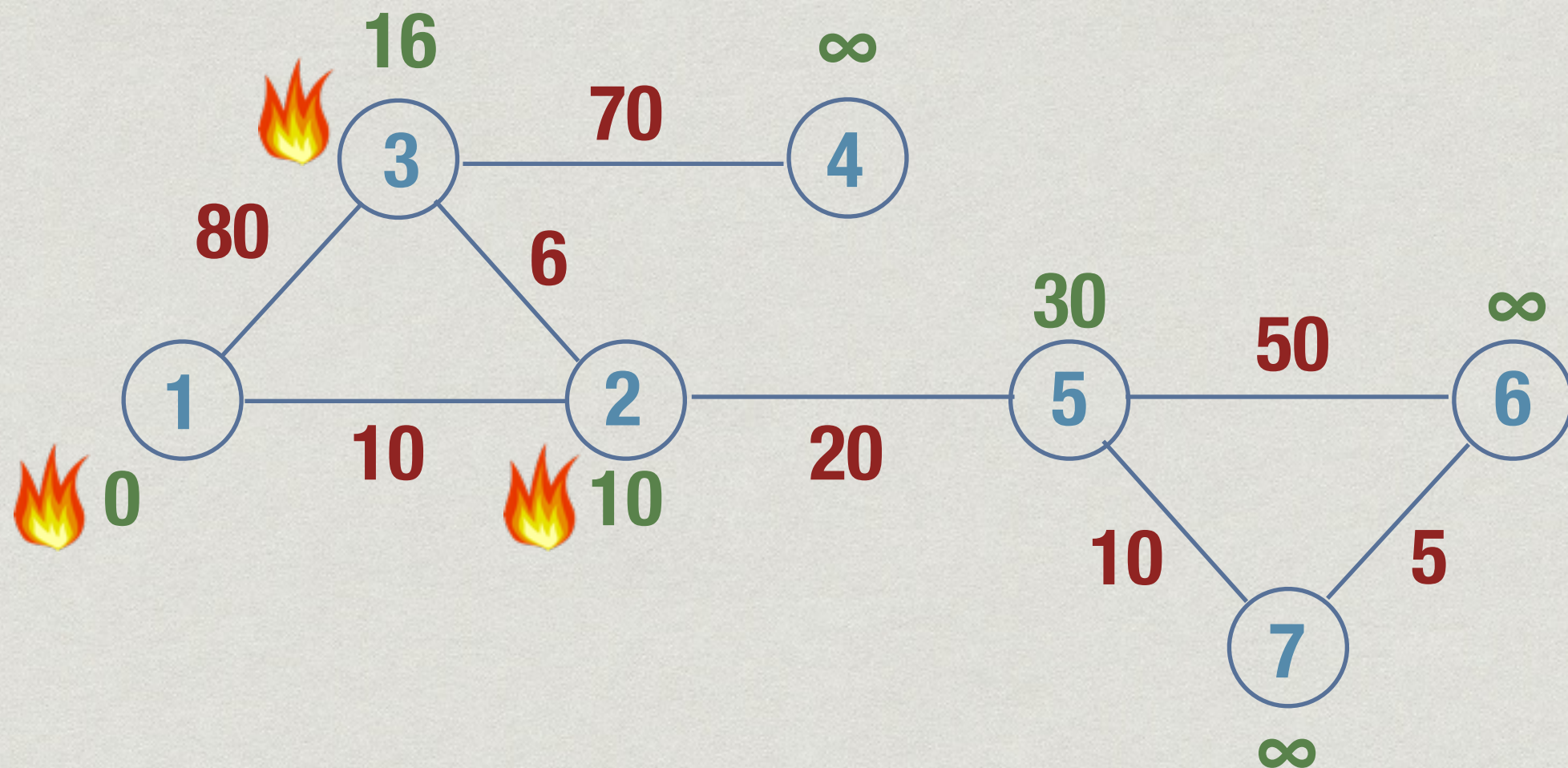
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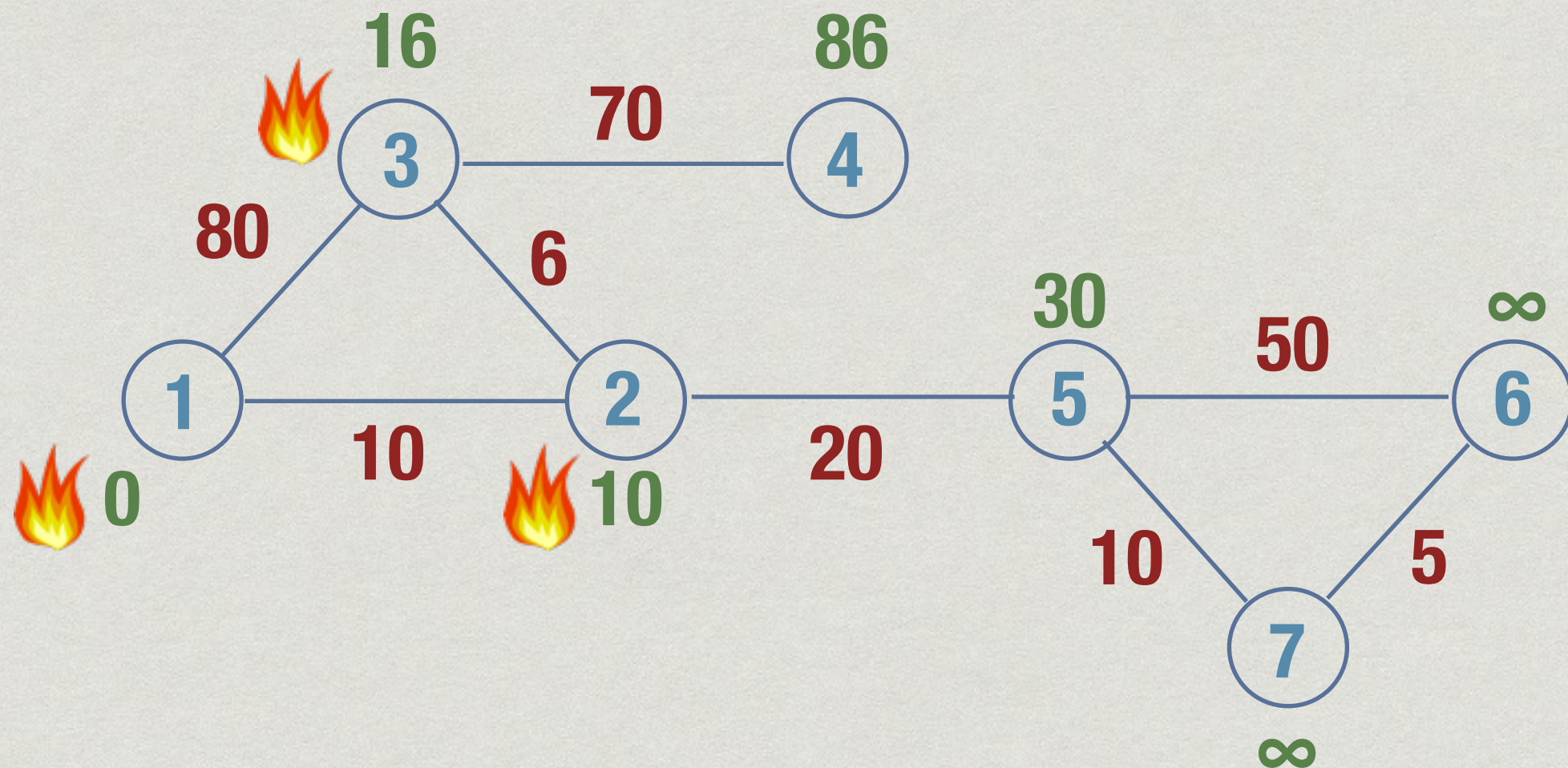
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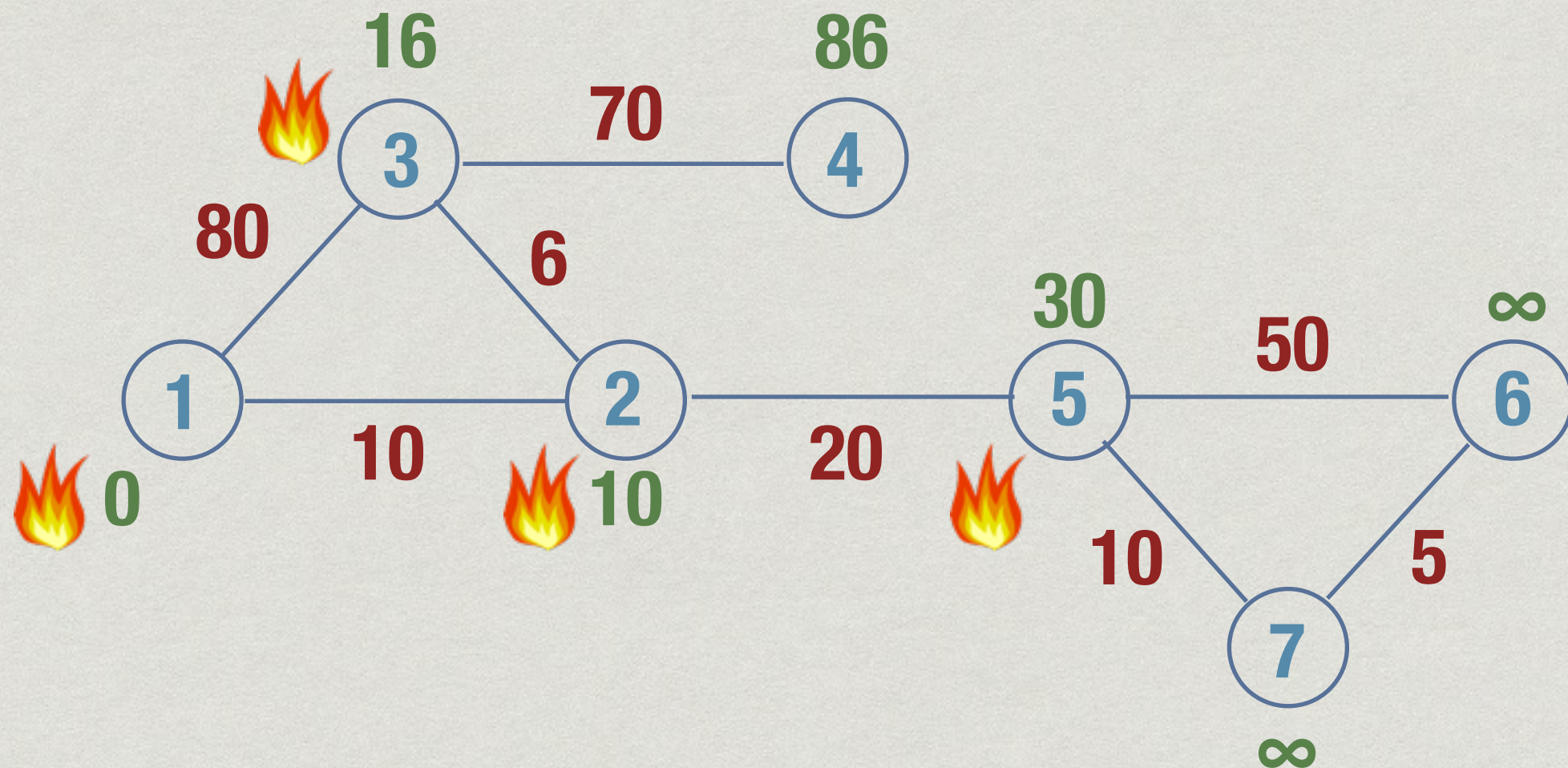
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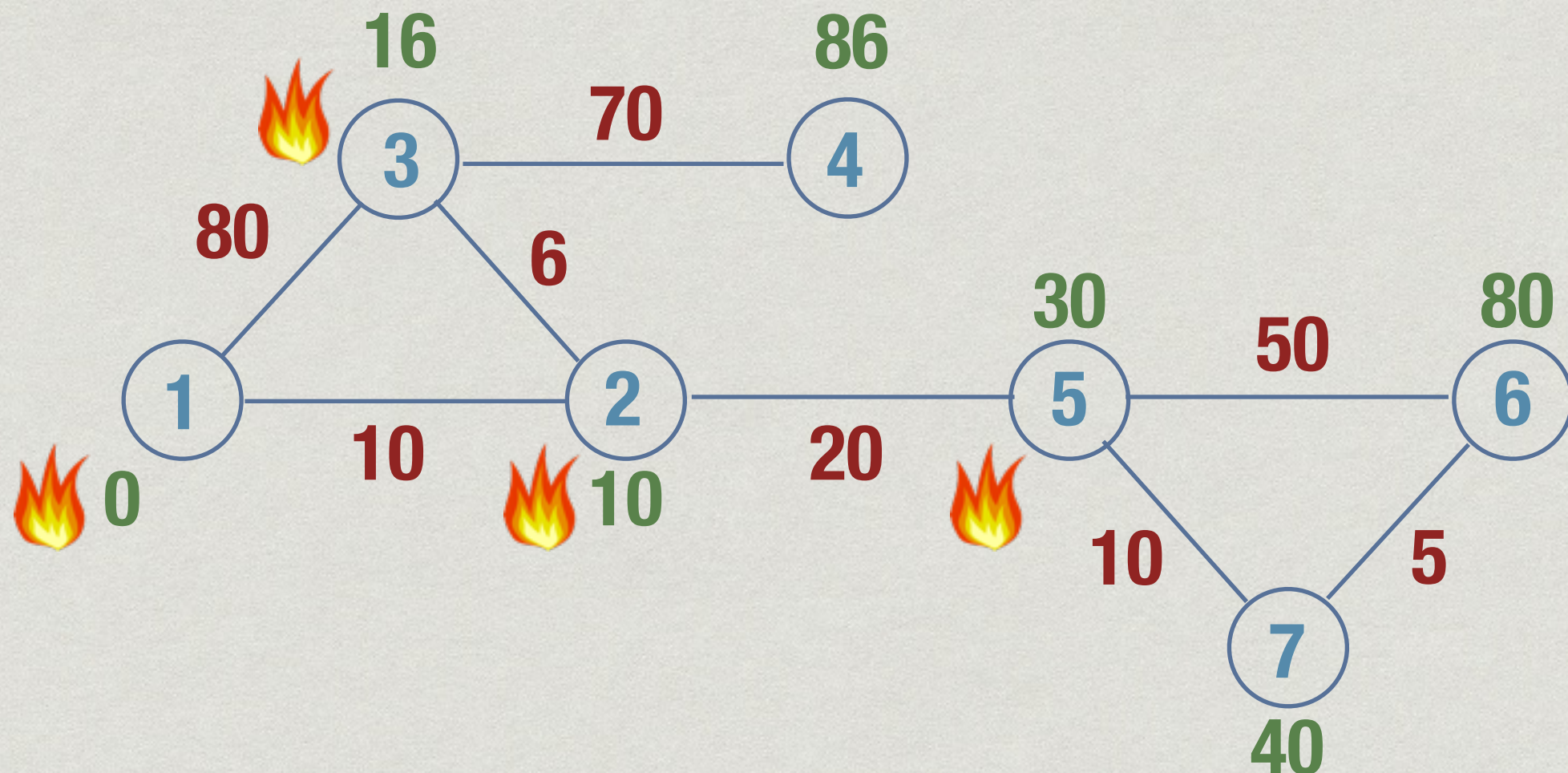
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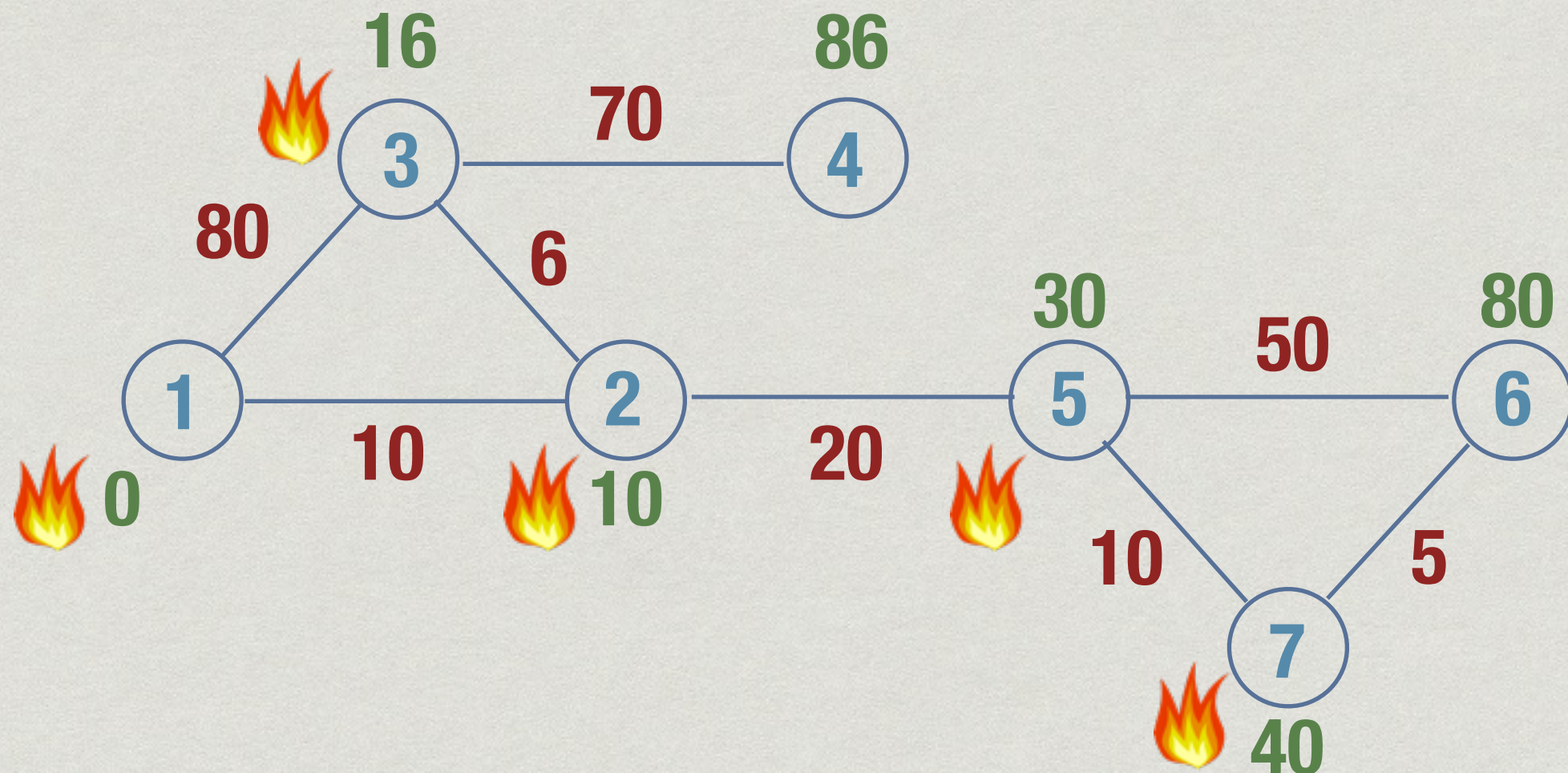
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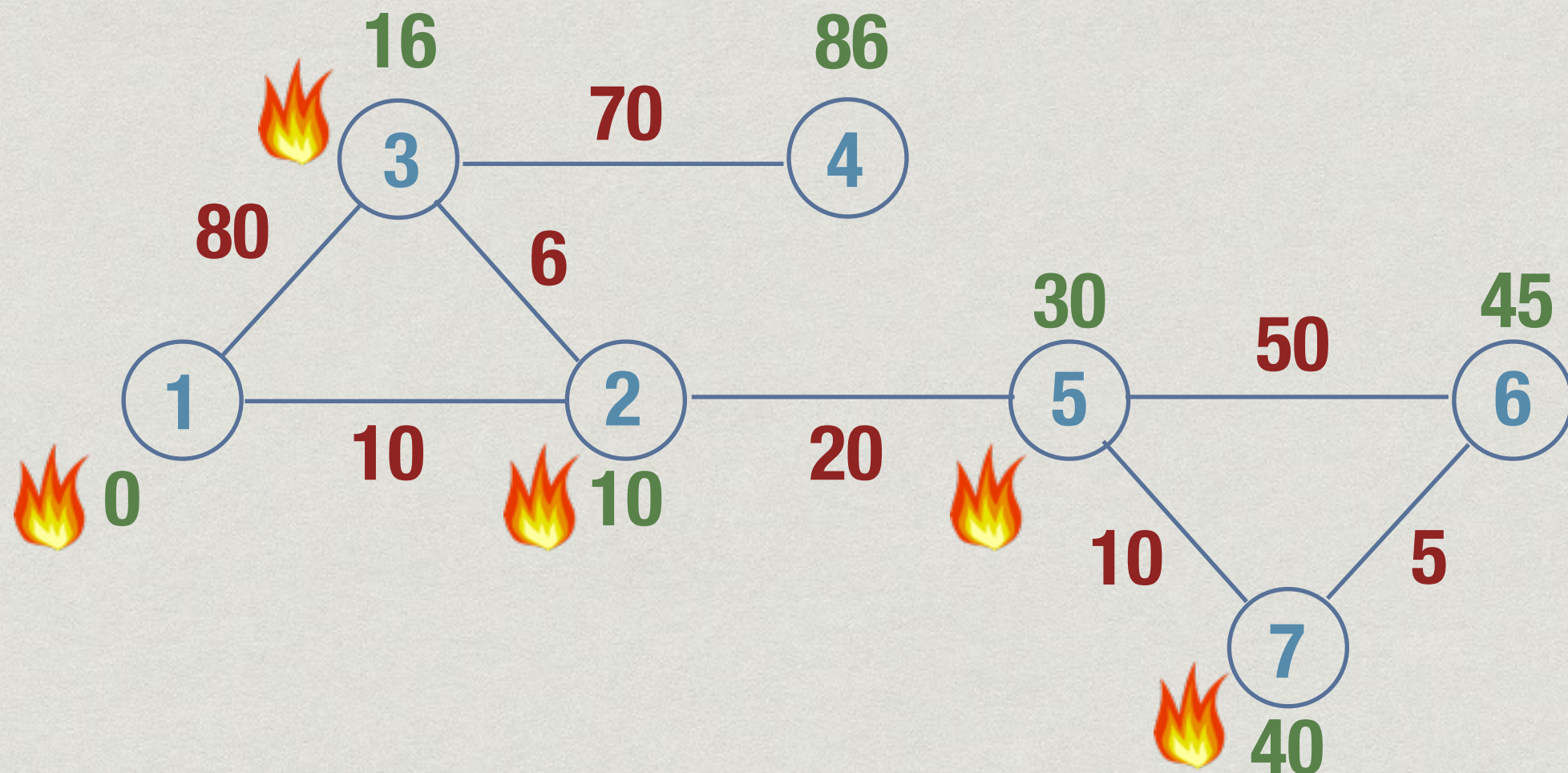
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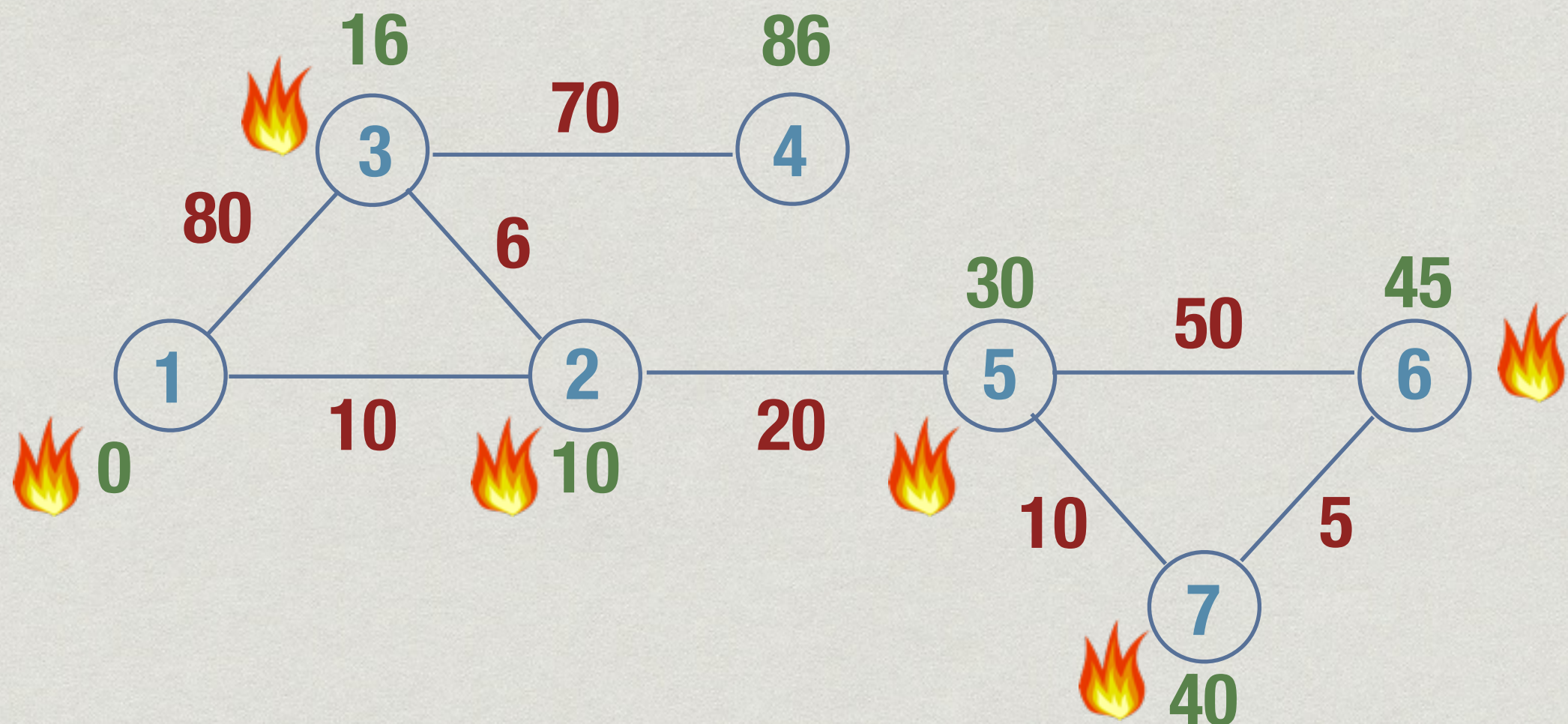
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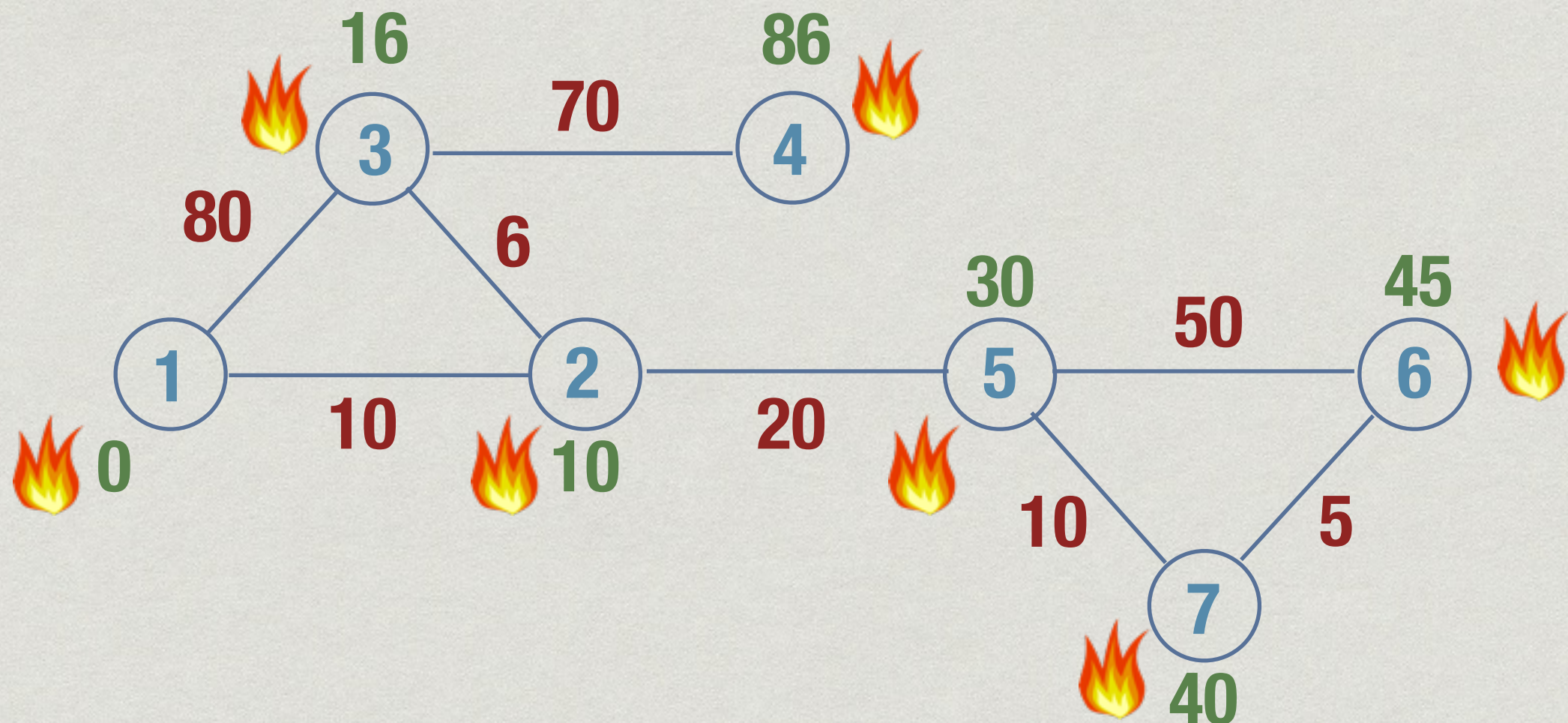
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 - * `BurntVertices[]`, initially `False` for all i
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 - * For ∞ , use sum of all edge weights + 1
- * Set `ExpectedBurnTime[1] = 0`
- * Repeat, until all vertices are burnt
 - * Find j with minimum `ExpectedBurnTime`
 - * Set `BurntVertices[j] = True`
 - * Recompute `ExpectedBurnTime[k]` for each neighbour k of j

Dijkstra's algorithm

```
function ShortestPaths(s){ // assume source is s
    for i = 1 to n
        BV[i] = False; EBT[i] = infinity

    EBT[s] = 0

    for i = 1 to n
        Choose u such that BV[u] == False
                           and EBT[u] is minimum
        BV[u] = True
        for each edge (u,v) with BV[v] == False
            if EBT[v] > EBT[u] + weight(u,v)
                EBT[v] = EBT[u] + weight(u,v)
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Dijkstra's algorithm

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function ShortestPaths(s){ // assume source is s
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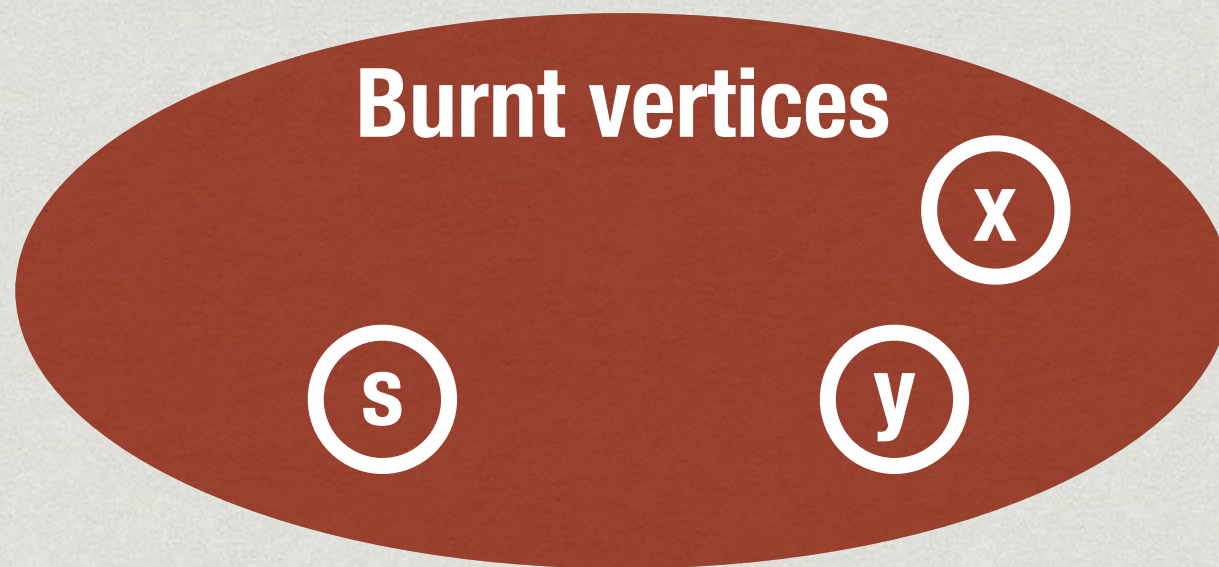
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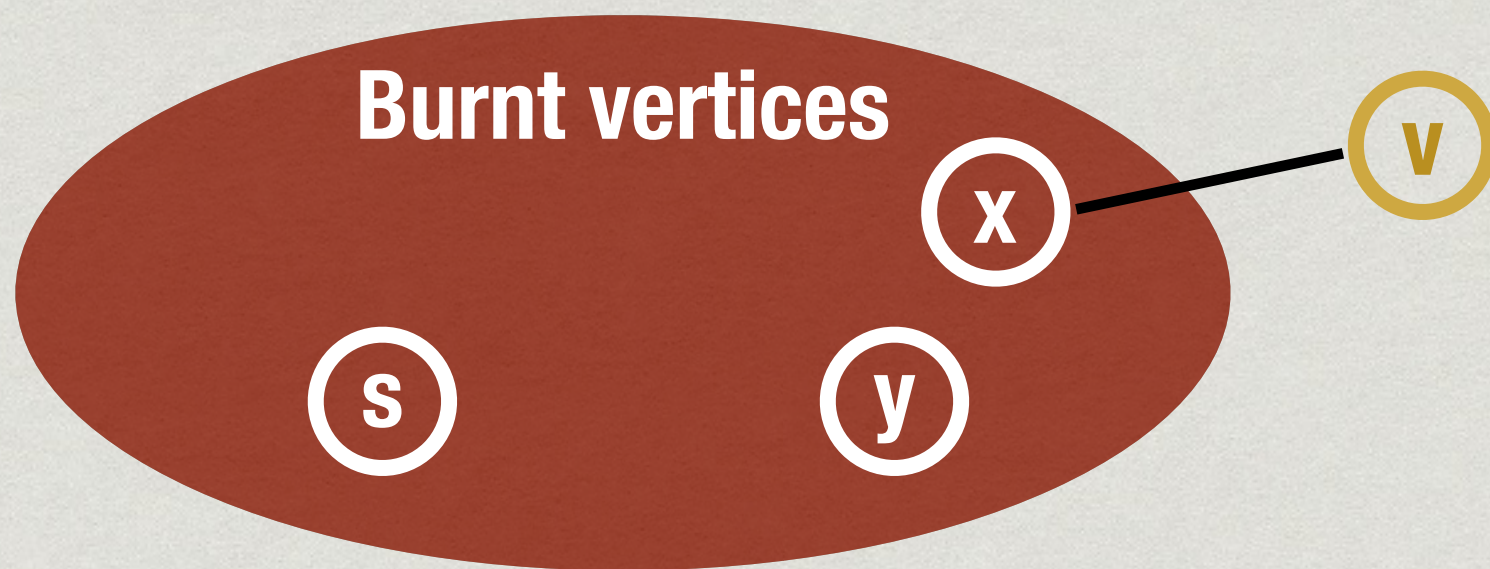
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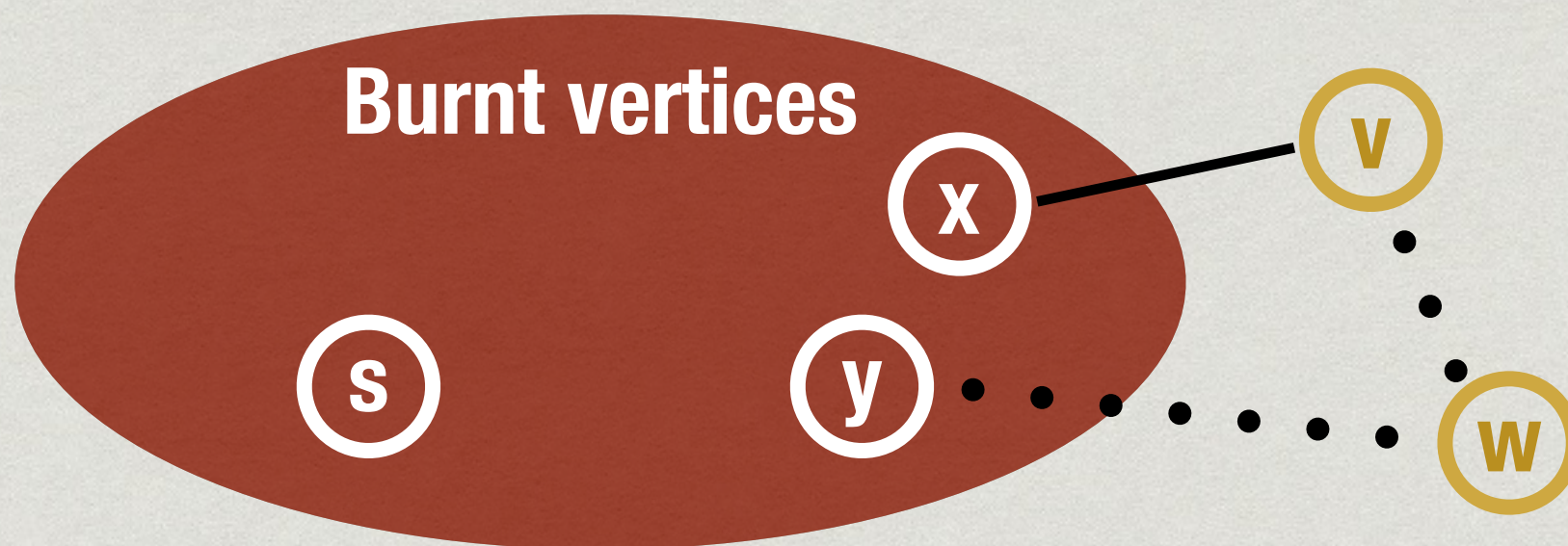
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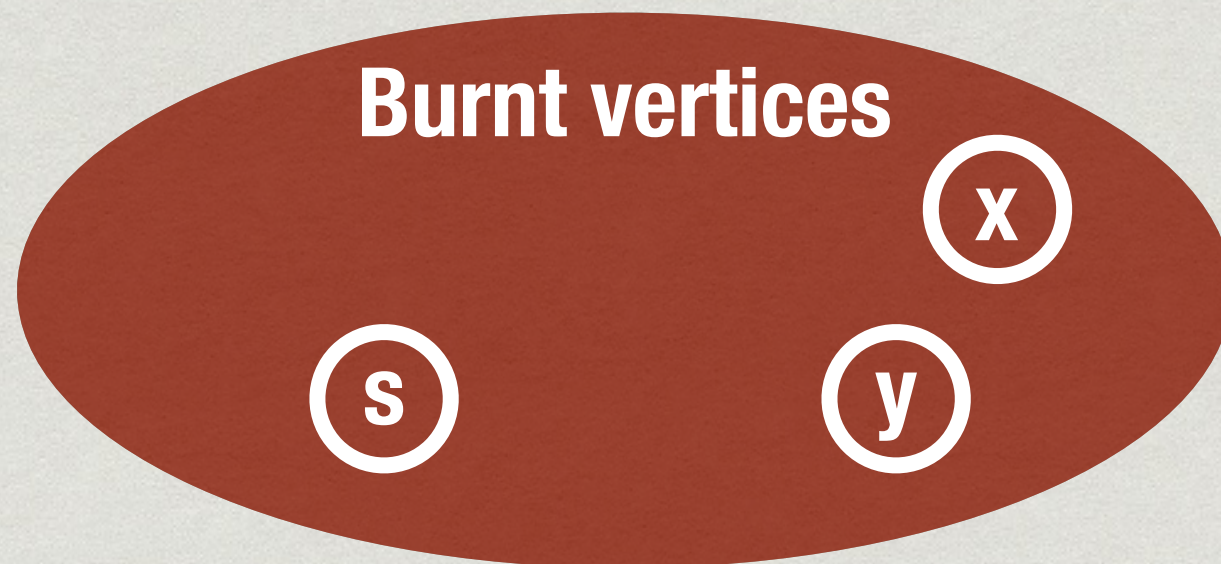
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- * Overall $O(n \log n + m \log n) = O((n+m) \log n)$

Limitations

- * What if edge weights can be negative?
- * Our correctness argument is no longer valid

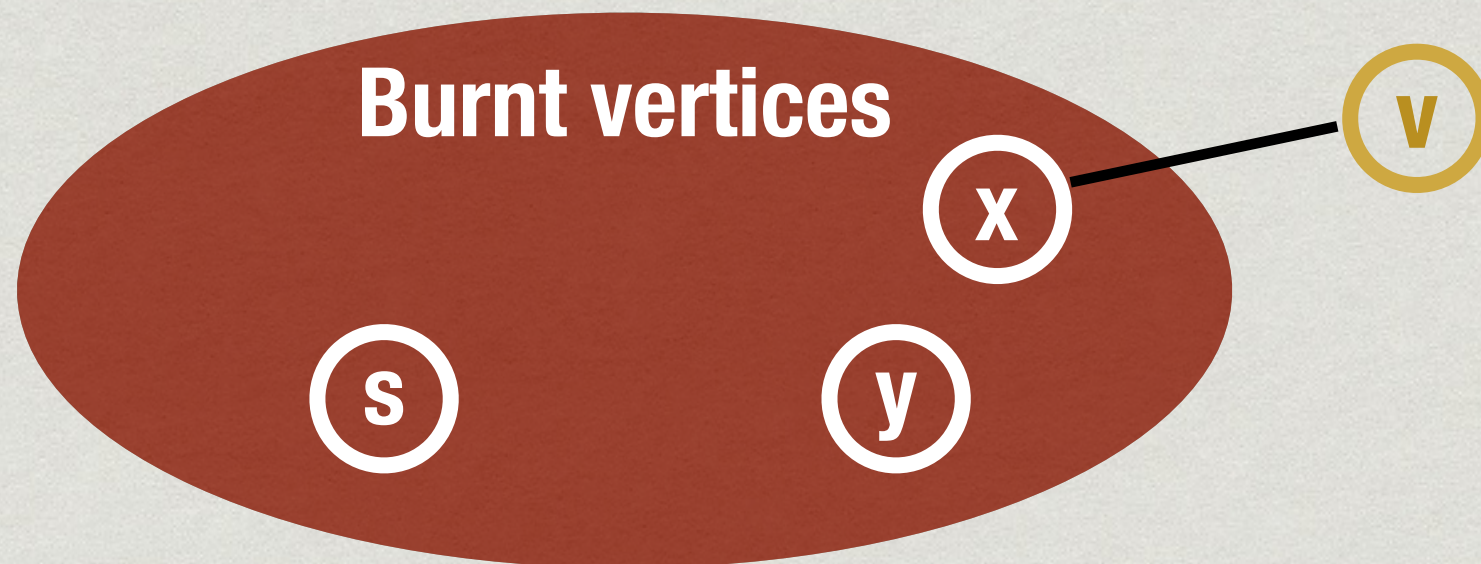
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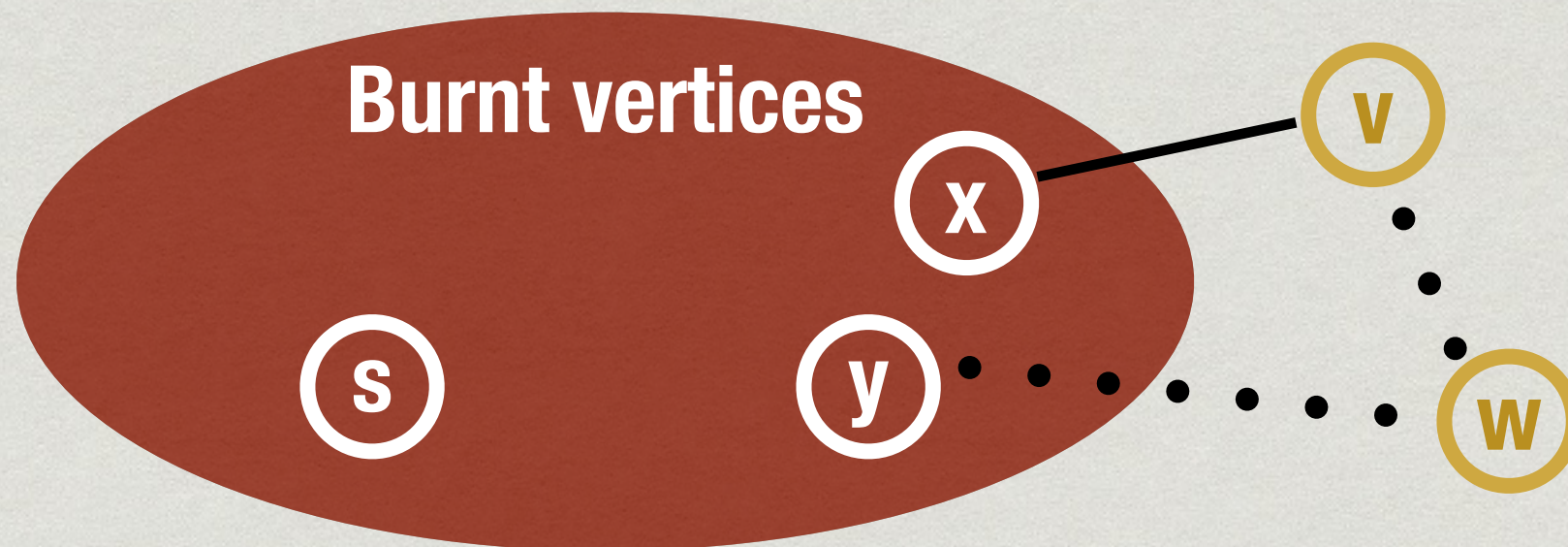
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 - * Bellman-Ford
 - * Floyd-Warshall all pairs shortest path (will see later)

Summary

- * Dijkstra's algorithm solves the single source shortest path problem, assuming no negative weights
 - * Simple implementation is $O(n^2)$
 - * Using clever trees, reduce to $O((n+m) \log n)$
- * With negative edges, but without negative cycles, need to use other strategies

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- * Dijkstra’s algorithm is greedy
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- * Need to prove that greedy strategy is optimal
- * Most times, greedy approach fails
 - * Current best choice may not be globally optimal