QEEE DSA05 DATA STRUCTURES AND ALGORITHMS

G VENKATESH AND MADHAVAN MUKUND LECTURE 10, 5 SEPTEMBER 2014

Comparing data structures

What is the difference between heap and array, especially if heap is implemented using array?

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Array: Not arranged in any order

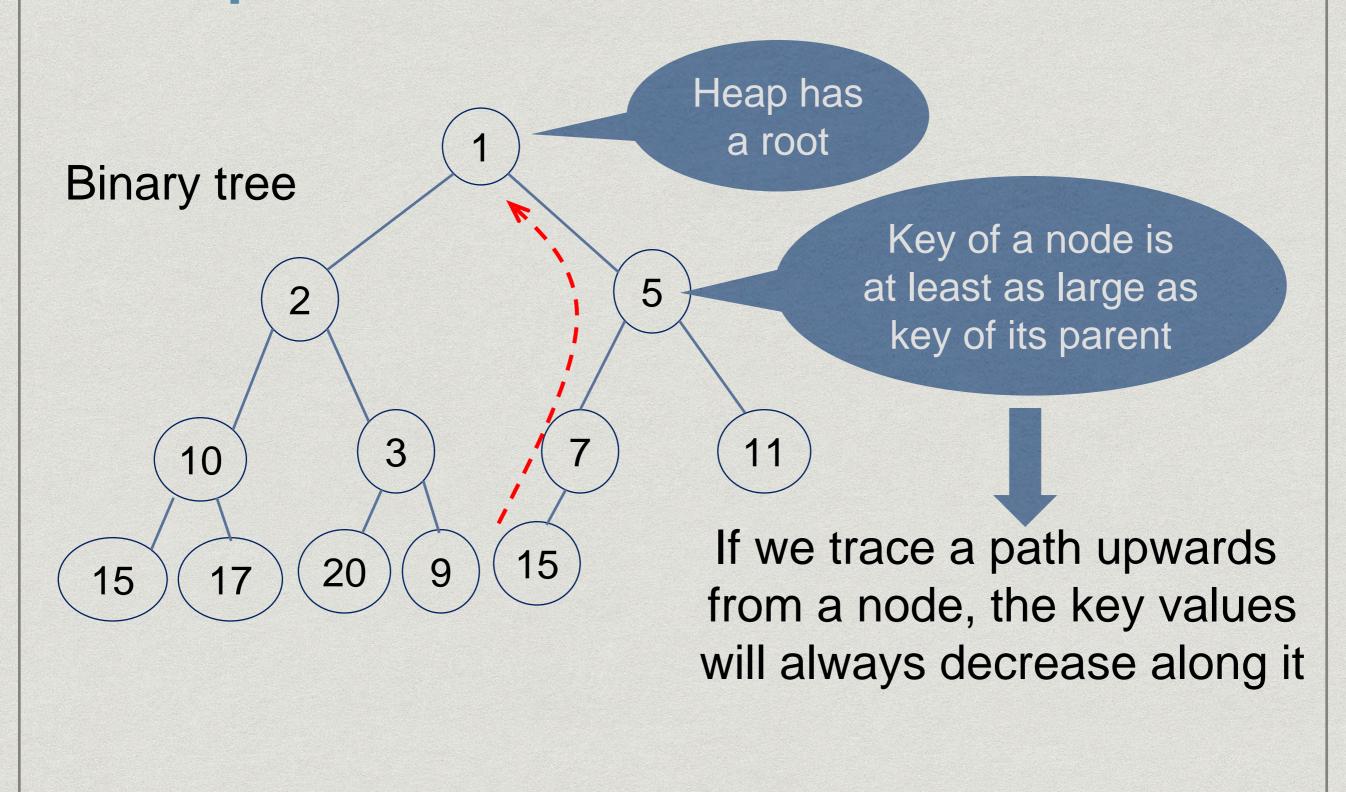
Sorted array: Elements always stored in order

(either ascending or descending)

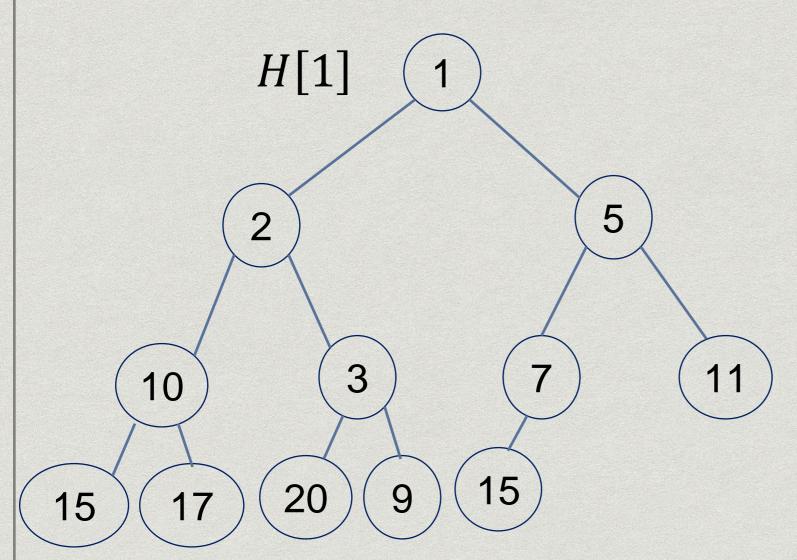
Heap: Elements stored in heap order

(i.e. for each element, parent's key is equal or lower)

Heap data structure



Heap data structure



Use array H[1...12] to store the elements

Start with H[1] for convenience

leftChild(i) = 2i rightChild(i) = 2i + 1 $parent(i) = \lfloor i/2 \rfloor$

1 2 5 10 3 7 11 15 17 20 9 15

n = 12

Comparing data structures

What is the difference between heap and array, especially if heap is implemented using array?

Array: Not arranged in any order

Sorted array: Elements always stored in order

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Heap: Elements stored in heap order

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	Array	Sorted Array	Heap
Select min	O(n)	0(1)	0(1)
Insert	0(1)	O(n)	$O(\log n)$
Delete	O(n)	O(n)	$O(\log n)$

Flights landing at a runway

Flights are arriving at and departing from an airport. The Air traffic controller needs to reserve runway time for each aircraft. Requests for landing time can come anytime during the flight.

Flights nearer to the airport need to be given priority.

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Flight landing/takeoff requests come in at different times

Trivandrum-Chennai Air India 4.23 pm Chennai-Madurai SpiceJet 4.12 pm

Delhi-Chennai Air India 4.55 pm

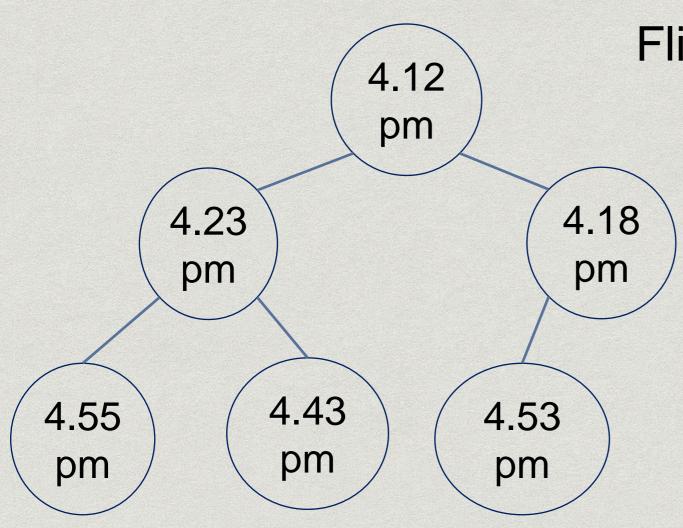
Port Blair-Chennai Jet Airways 4.18 pm

. . .

Flight landing/takeoff requests come in at different times

4.23 pm, 4.12 pm, 4.55 pm, 4.18 pm, 4.43 pm, 4.53 pm

Entered into the heap



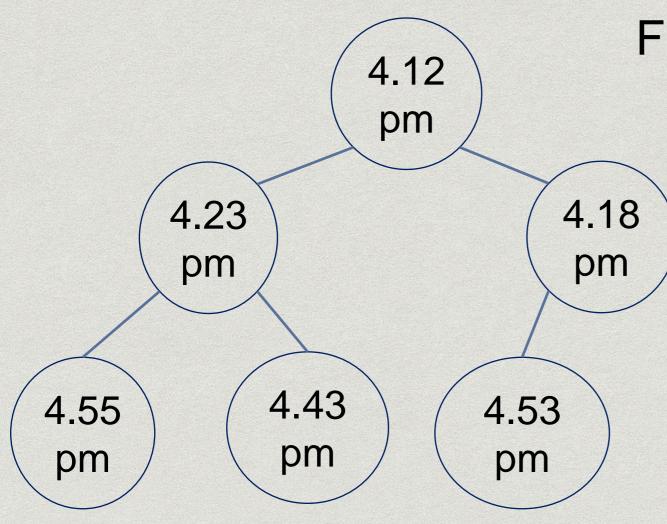
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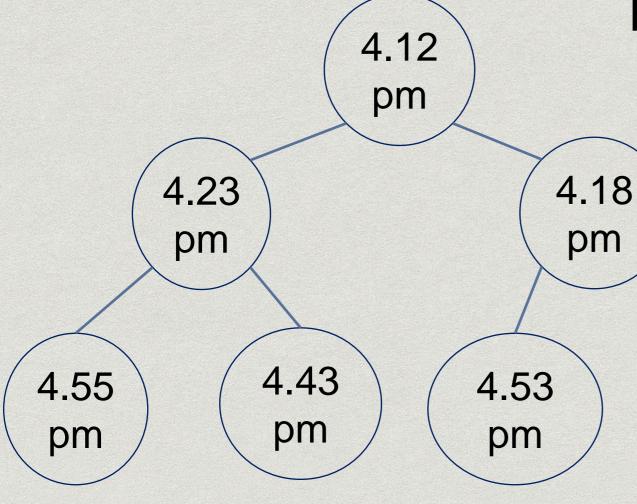
4.55 pm, 4.18 pm,

4.43 pm, 4.53 pm

Entered into the heap

4.12	4.23	4.18	4.55	4.43	4.53	
pm	pm	pm	pm	pm	pm	

$$n = 6$$



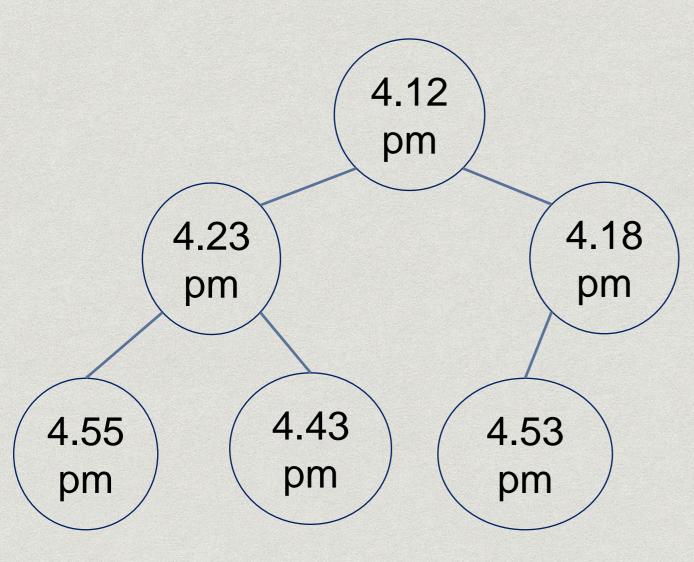
Flight landing/takeoff requests come in at different times

Entered into the heap

A few minutes before the minimum (say 4.10 pm), flight (SG MAA-IXM) is given takeoff permission

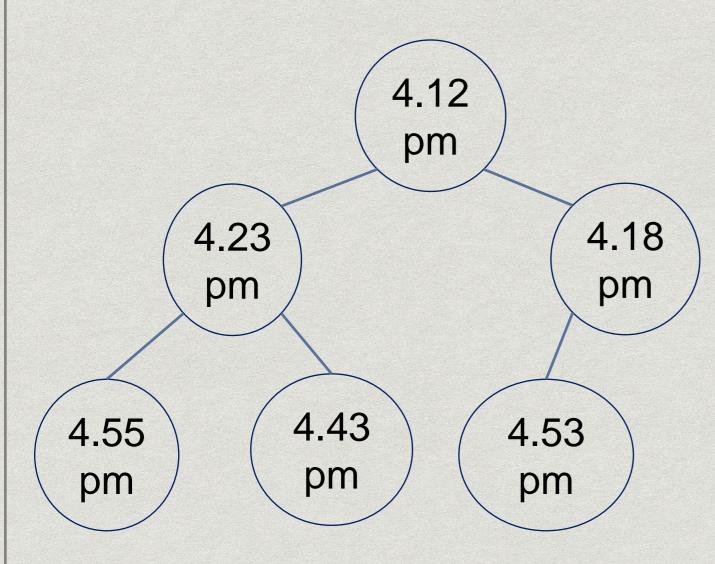
4.12	4.23	4.18	4.55	4.43	4.53	
pm	pm	pm	pm	pm	pm	

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Suppose we want to ensure that the flights are spaced sufficiently apart

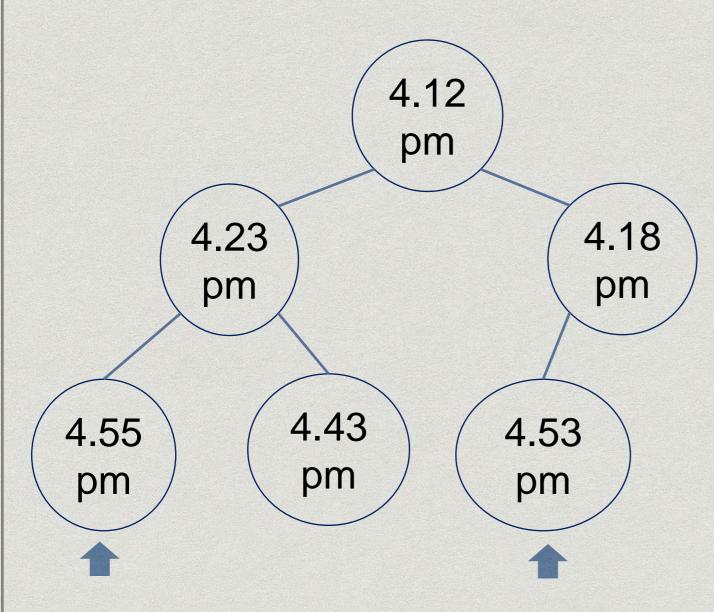
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Suppose we want to ensure that the flights are spaced sufficiently apart

3 min space between two flights

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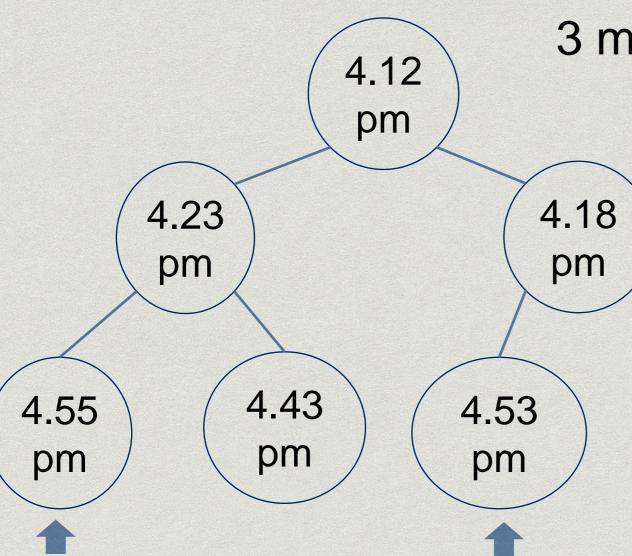


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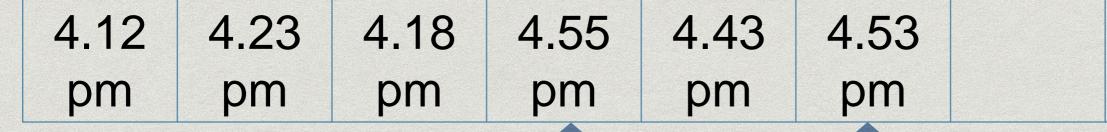
Rule is violated

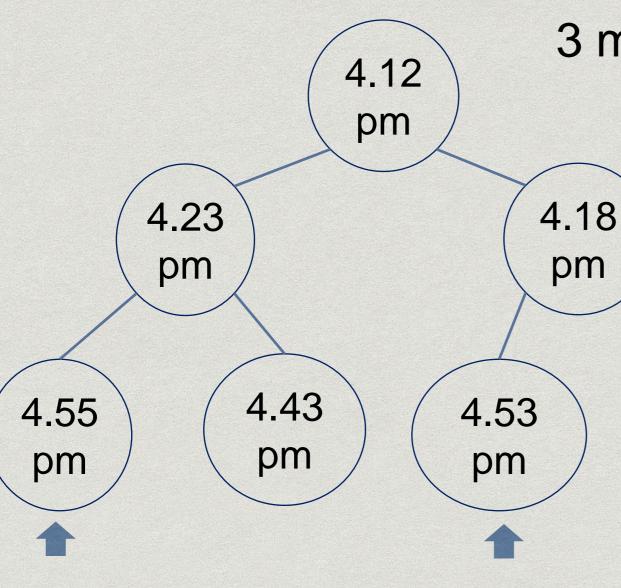
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3 min space between two flights

Not easy to do this check in a heap data structure O(n) time to do this



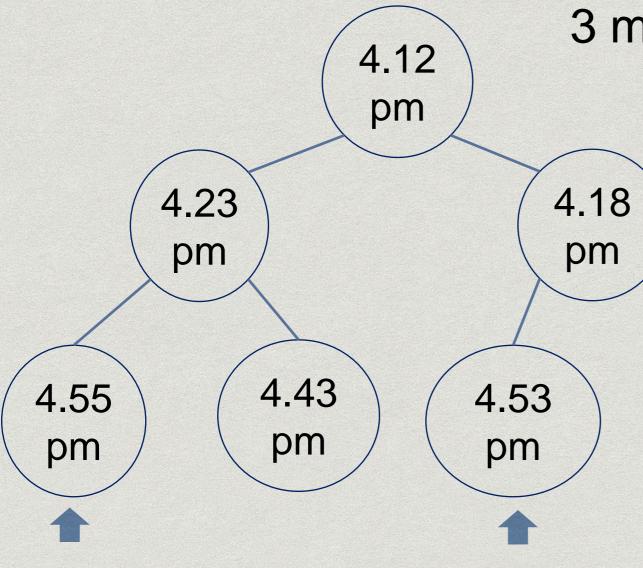


3 min space between two flights

Not easy to do this check in a heap data structure O(n) time to do this

If we could find predecessor and successor easily, that would make the check easier to do

4.12	4.23	4.18	4.55	4.43	4.53	
pm	pm	pm	pm	pm	pm	



3 min space between two flights

4.23 pm, 4.12 pm,

4.55 pm, 4.18 pm,

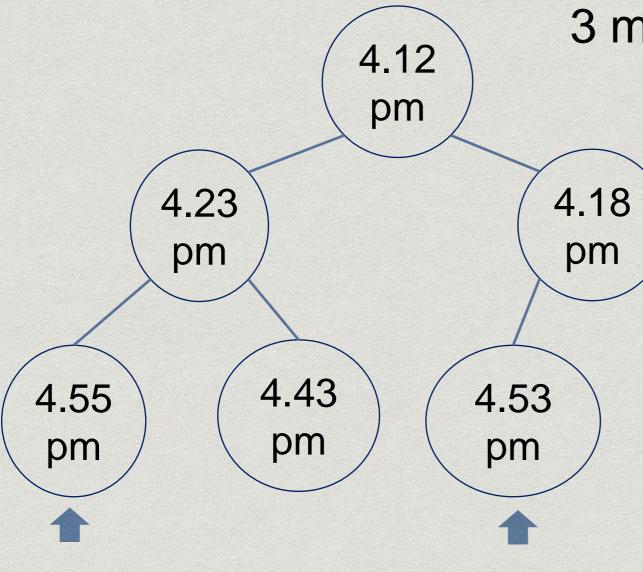
4.43 pm, 4.53 pm

Pred(4.18 pm) = 4.12 pm

Succ(4.18 pm) = 4.23 pm

4.12	4.23	4.18	4.55	4.43	4.53
pm	pm	pm	pm	pm	pm

n =



3 min space between two flights

- 4.23 pm, 4.12 pm,
- 4.55 pm, 4.18 pm,
- 4.43 pm, 4.53 pm

Pred(4.18 pm) = 4.12 pm

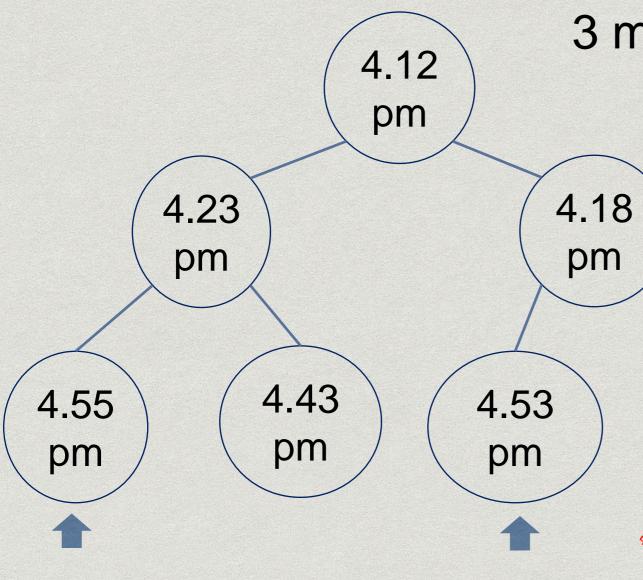
Succ(4.18 pm) = 4.23 pm

Pred(4.53 pm) = 4.43 pm

Succ(4.53 pm) = 4.55 pm

4.12	4.23	4.18	4.55	4.43	4.53	
pm	pm	pm	pm	pm	pm	

 $n = \epsilon$



3 min space between two flights

```
4.23 pm, 4.12 pm, 4.55 pm, 4.18 pm,
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Comparing data structures

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Succ	O(n)	0(1)	O(n)

Sorted array does well with respect to Pred and Succ, but not so well for Insert and Delete. Heap does well for Insert, Delete but not so well for Pred and Succ

Today's class

Example Problems

- Airline routes
- Job scheduling
- Document similarity

Complexity analysis

- O notation asymptotic complexity
- Methods to search and sort
- Needs to be correct!

Data structures

- Arrays, Linked lists
- Queues, Stacks
- Heaps
- Trees

Algorithmic techniques

- Divide and conquer
- Greedy
- Dynamic programming

Need a new data structure

	Heap	Sorted Array	Binary Search Tree
Search	O(n)	$O(\log n)$	$O(\log n)$
Minimum	0(1)	0(1)	$O(\log n)$
Maximum	O(n)	0(1)	$O(\log n)$
Insert	$O(\log n)$	O(n)	$O(\log n)$
Delete	$O(\log n)$	O(n)	$O(\log n)$
Pred	O(n)	0(1)	$O(\log n)$
Succ	O(n)	0(1)	$O(\log n)$

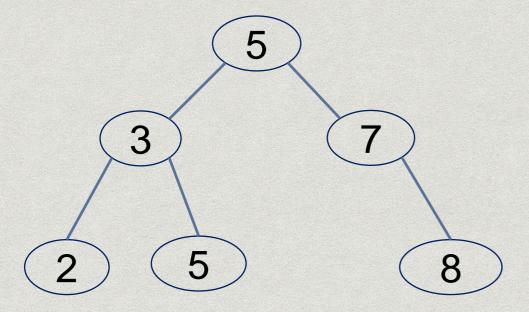
If we need to do search and insert/delete repeatedly, then a new data structure is required – binary search tree

What is a binary tree?

- For each node, we can find the leftchild, the rightchild and the parent.
- Has a ROOT node which does not have a parent (All other nodes in the tree should have a parent)
- Some of the nodes may have left or right child missing
- If both left and right childs are absent, then the node is a LEAF node

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 5

 3
 7

 2
 5

 8

5 is the ROOT

For node 3: parent is 5, children are 2 and 5

7 has no leftchild 2, 5 and 8 are LEAFs

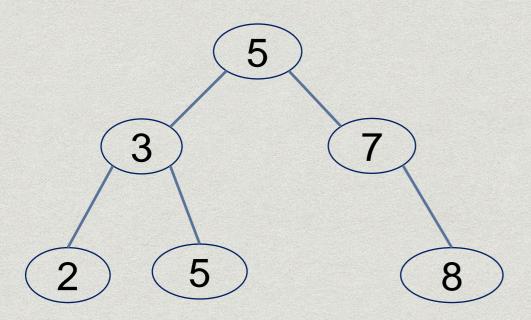
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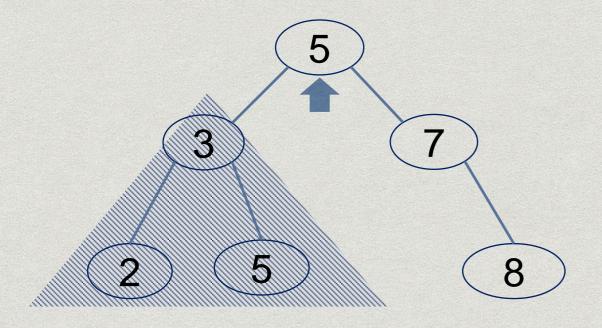
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- Is a binary tree
- Each node x in the tree has a key value key(x)
- Keys are always stored so as to satisfy the property: if node y is in the left subtree of x, then $key(y) \le key(x)$ if node y is in the right subtree of x, then $key(x) \le key(y)$
- Left subtree is the tree rooted at the leftchild of a node
- Right subtree is the tree rooted at the rightchild of a node

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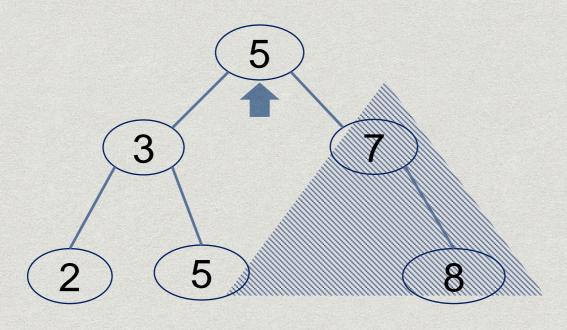
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Left subtree of marked node is shown shaded

All the nodes in the left subtree have key values no greater than 5

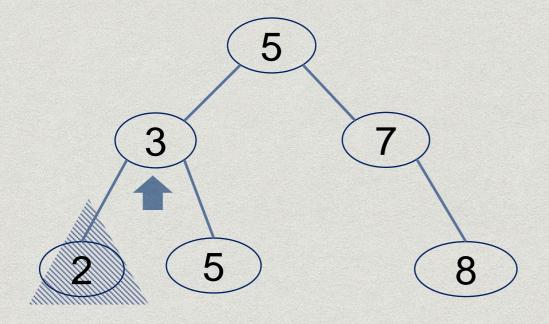
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Right subtree of marked node is shown shaded

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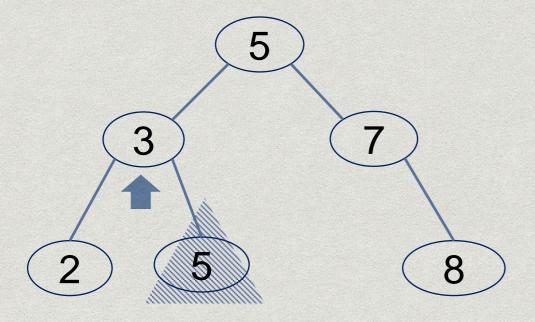
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Left subtree of marked node is shown shaded

All the nodes in the left subtree have key values no greater than 3

- Is a binary tree
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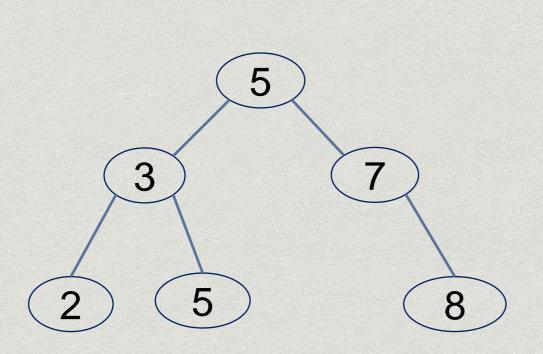


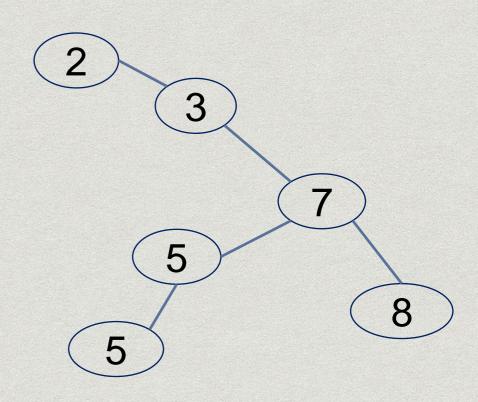
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There could be more than one way to store a set of elements in a binary search tree



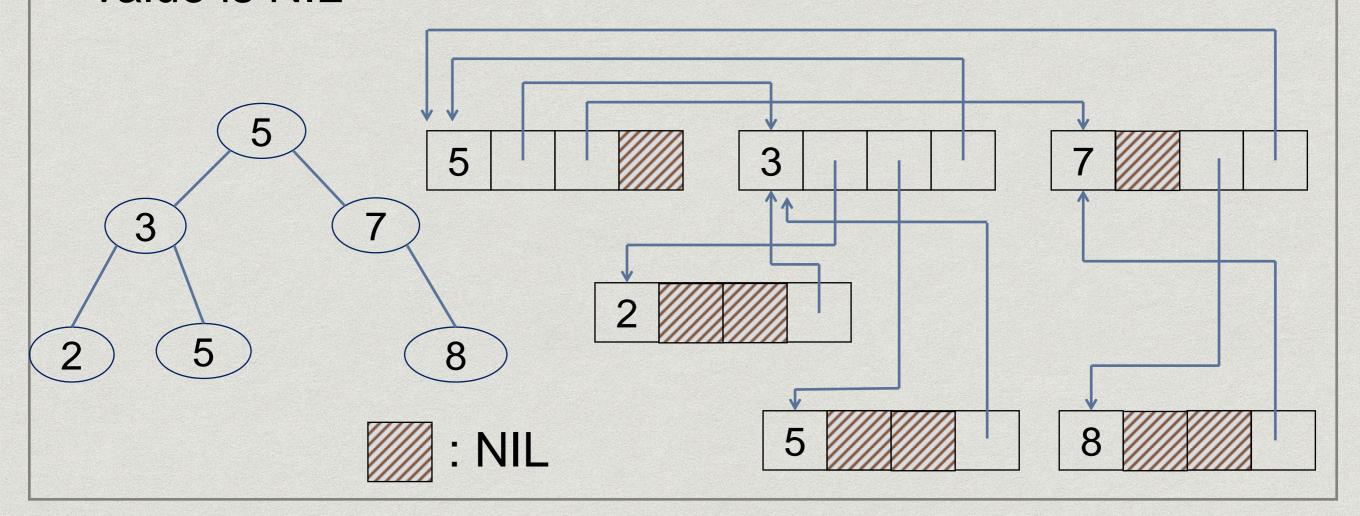


Implementing a binary search tree

- Use pointers to implement a binary search tree
- Each node has a key field and three pointers one each for parent, leftChild and rightChild
- If parent or any child is missing, the corresponding pointer value is NIL

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```
Inorder_Tree_Walk(x) {
    if x ≠ NIL:
        Inorder_Tree_Walk(left_subtree(x))
        Print key(x)
        Inorder_Tree_Walk(right_subtree(x))
        endif
}
```

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  endif
       3
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            5
                               2 3
```

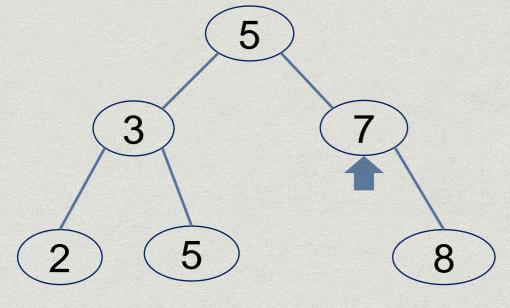
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```

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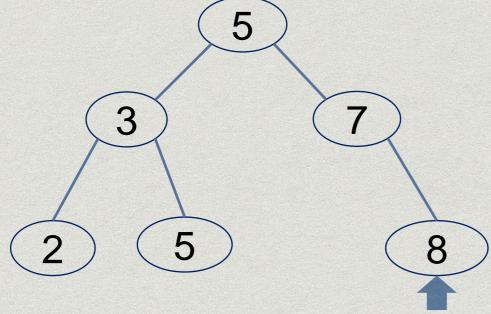
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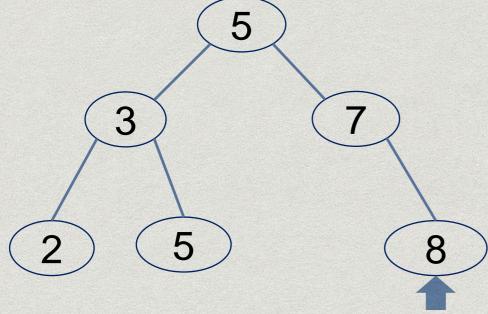
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        endif
}
```



2 3 5 5 7 8

Searching a tree

```
Node Tree_Search(x,k) {
  if x == NIL or k = key(x):
     return (x)
  endif
  if k < key(x):
     return Tree_Search( leftChild(x), k )
  else
     return Tree_Search( rightChild(x), k )
  endif
```

Searching a tree (iterative form)

```
Node Tree_Search(x,k) {
  while x \neq NIL or k \neq key(x):
    if k < key(x):
      x = leftChild(x)
    else
      x = rightChild(x)
    endif
  endwhile
  return x
```

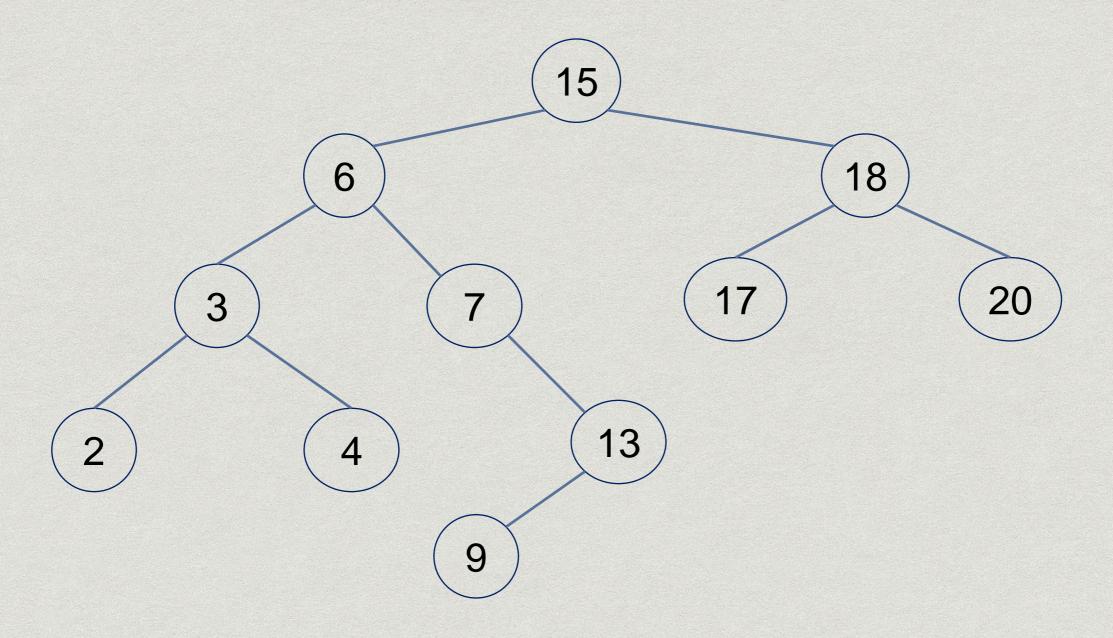
Finding minimum and maximum

```
Node Tree_Min(x) { Node Tree_Max(x) { while leftChild(x) \neq NIL: x = leftChild(x) x = rightChild(x) endwhile return x return x }
```

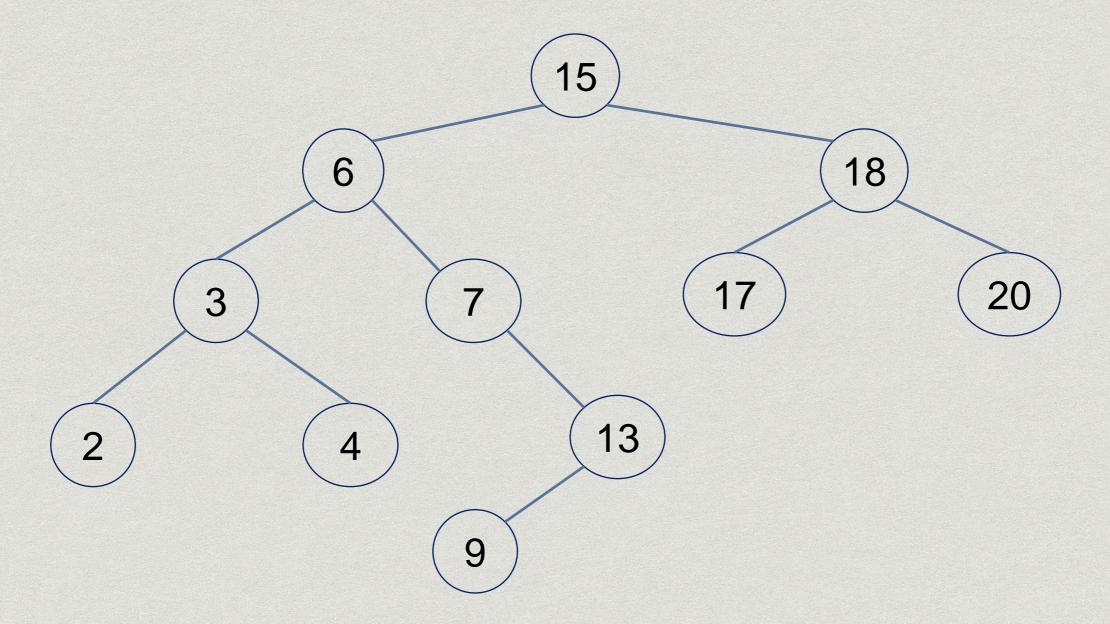
Minimum is found by going down the left side of the tree till a node without a left child

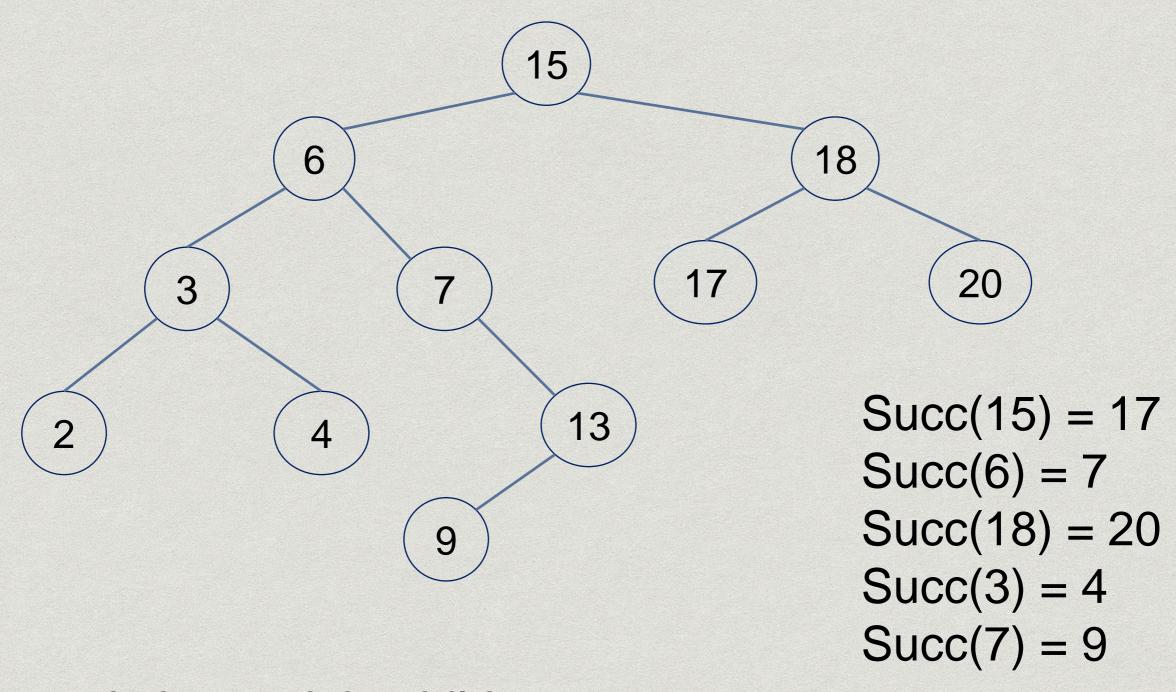
Maximum is found by going down the right side of the tree till a node without a right child

Finding minimum and maximum



Min is 2 and Max is 20

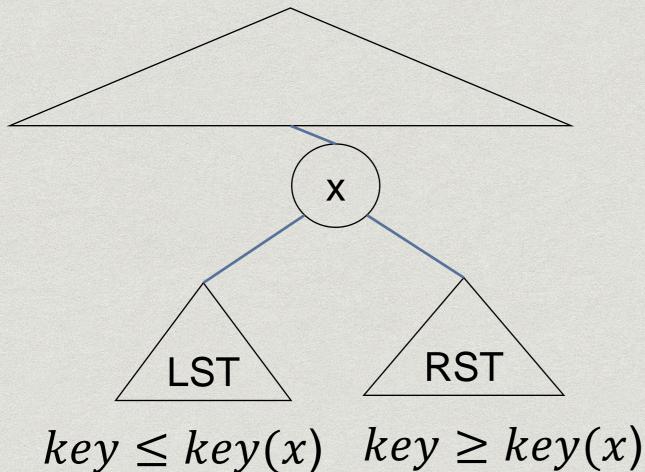




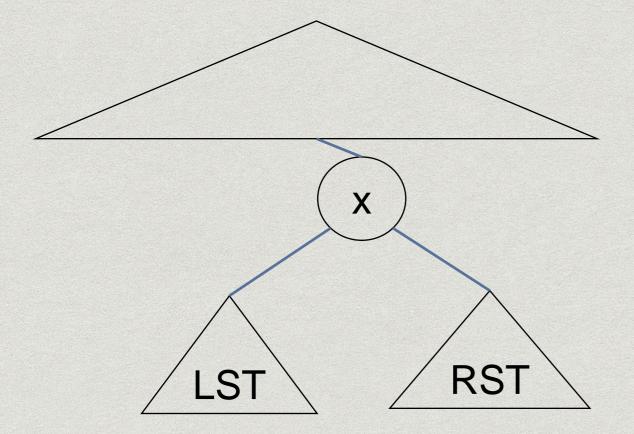
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Consider a node x located somewhere in the tree



Why is this correct?

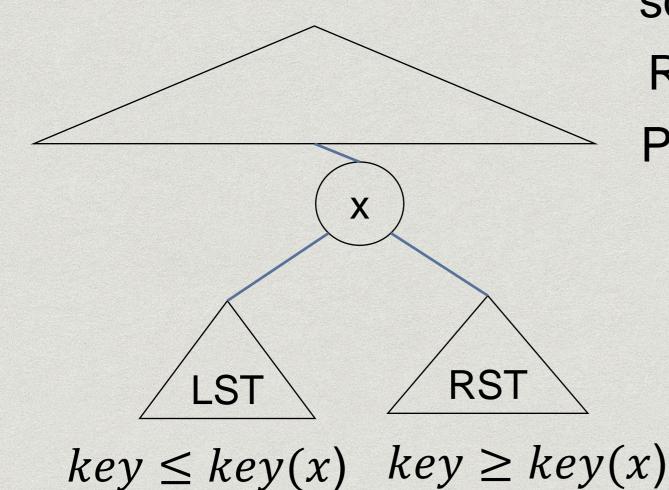


 $key \le key(x)$ $key \ge key(x)$

Consider a node x located somewhere in the tree

Remember inorder tree walk?

Why is this correct?

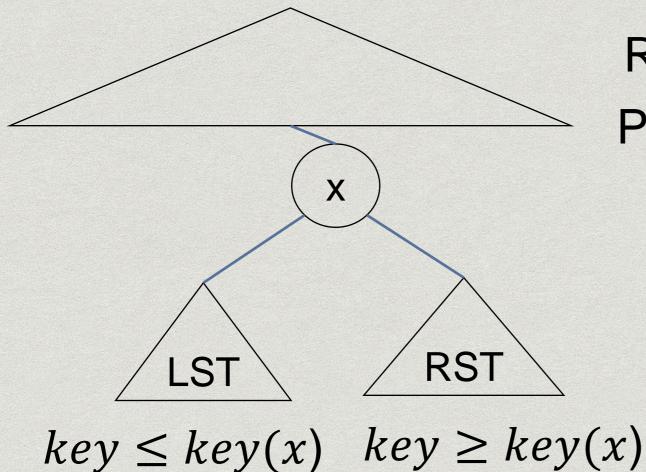


Consider a node x located somewhere in the tree

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Produces keys in sorted order

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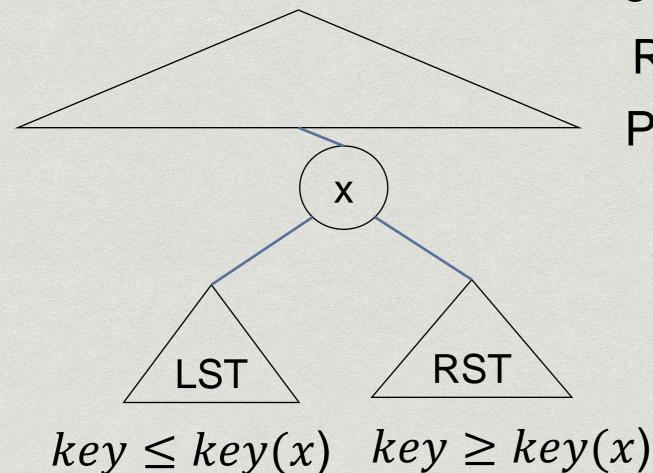
Keys from LST

Key(x)

Keys from RST

. . .

Why is this correct?



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Keys from LST

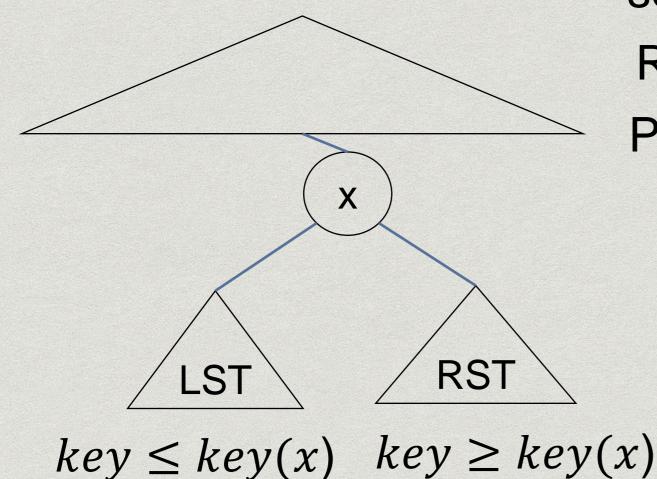
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Min of right subtree has to be Succ

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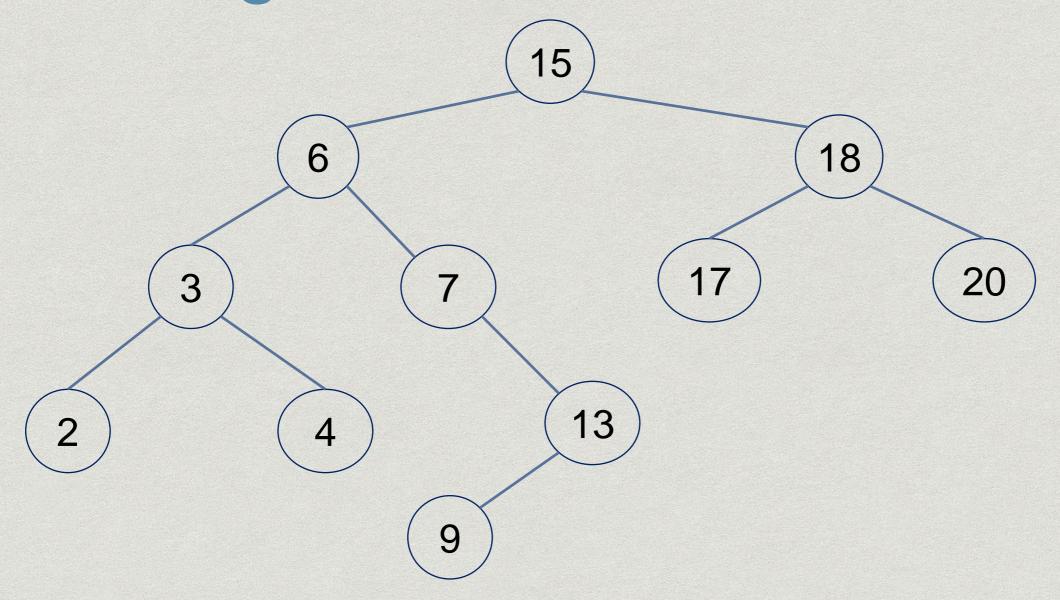
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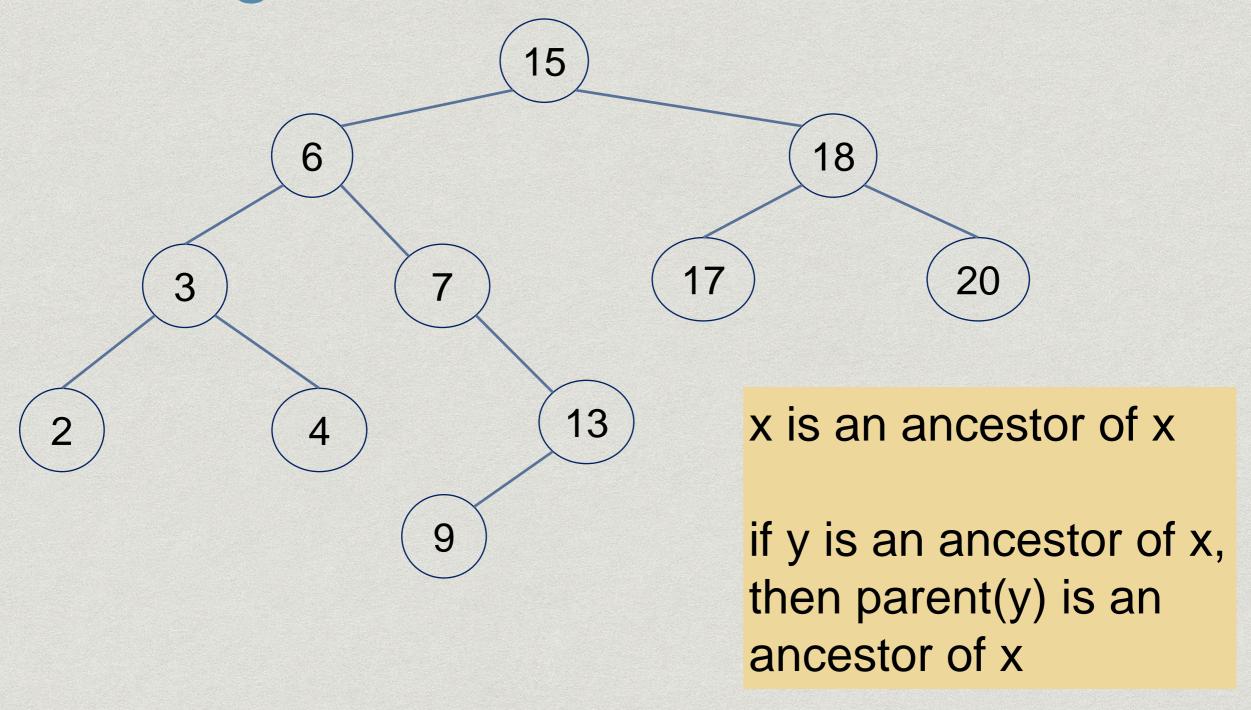
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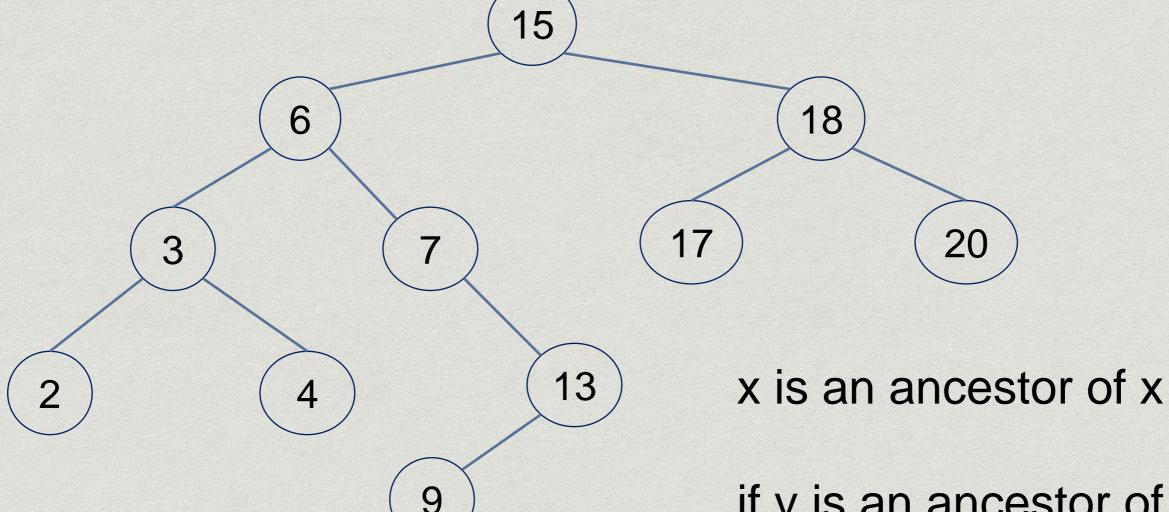
Min of right subtree has to be Succ



If a node does not have a right child, then the succ is earliest ancestor whose leftchild is also an ancestor



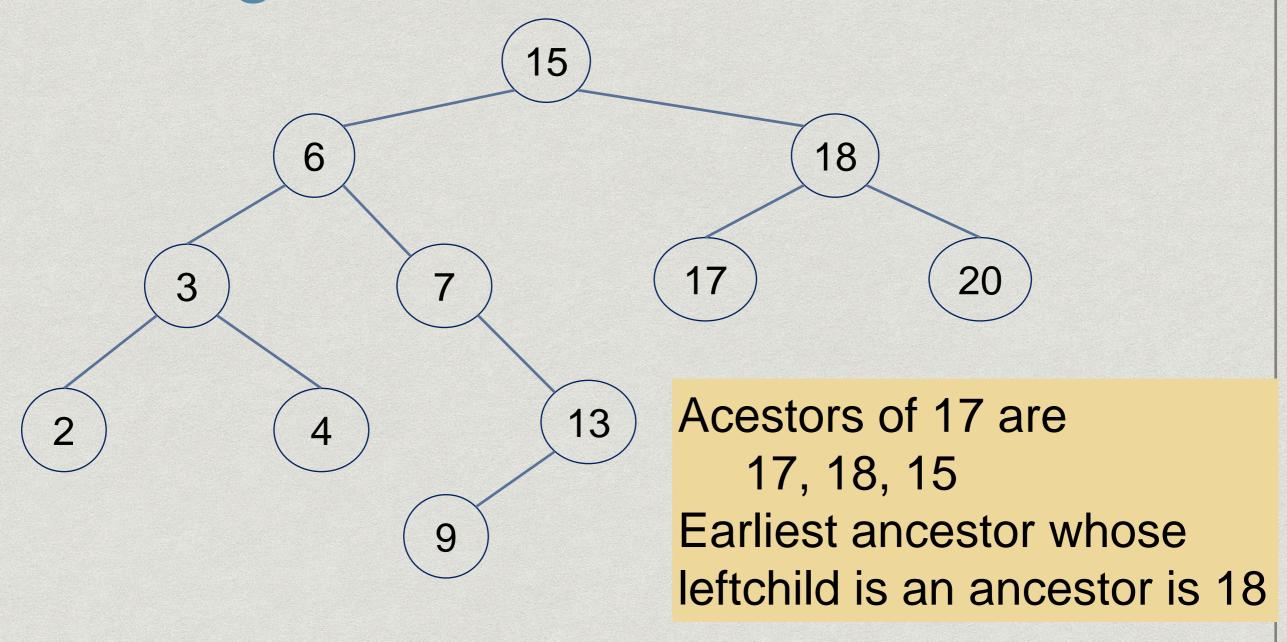
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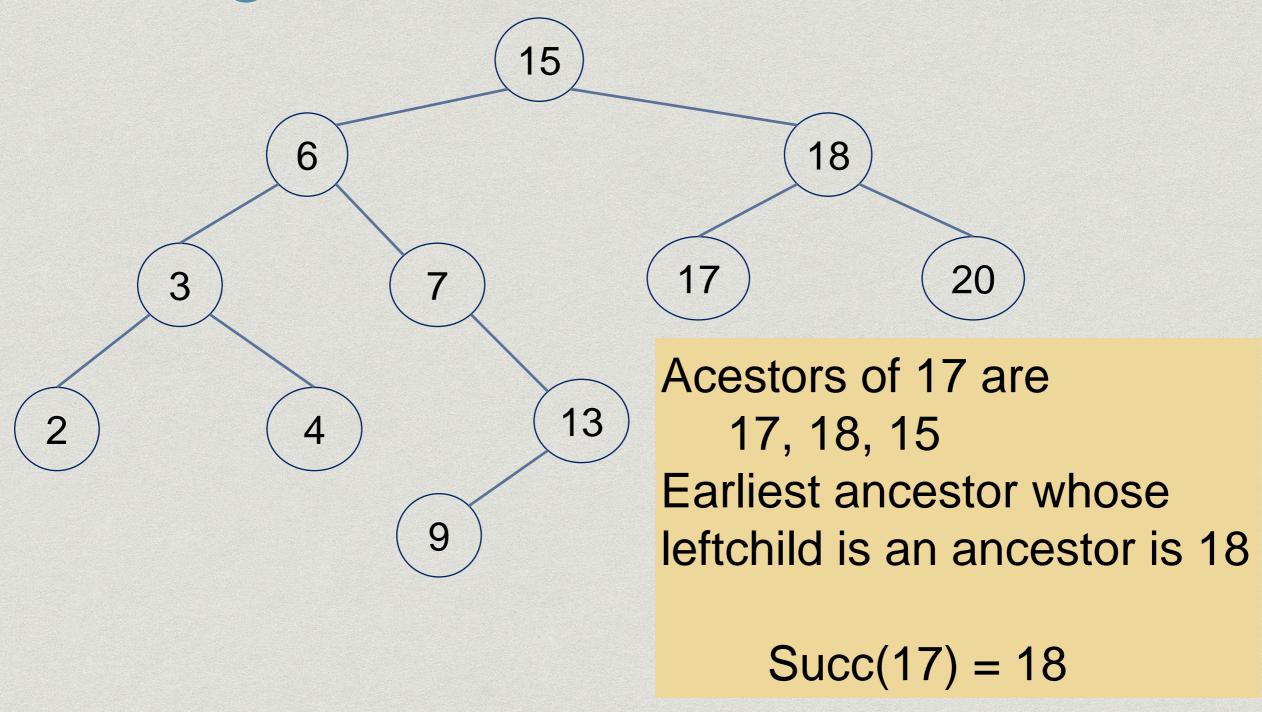
Acestors of 9 are 9, 13, 7, 6, 15

if y is an ancestor of x, then parent(y) is an ancestor of x

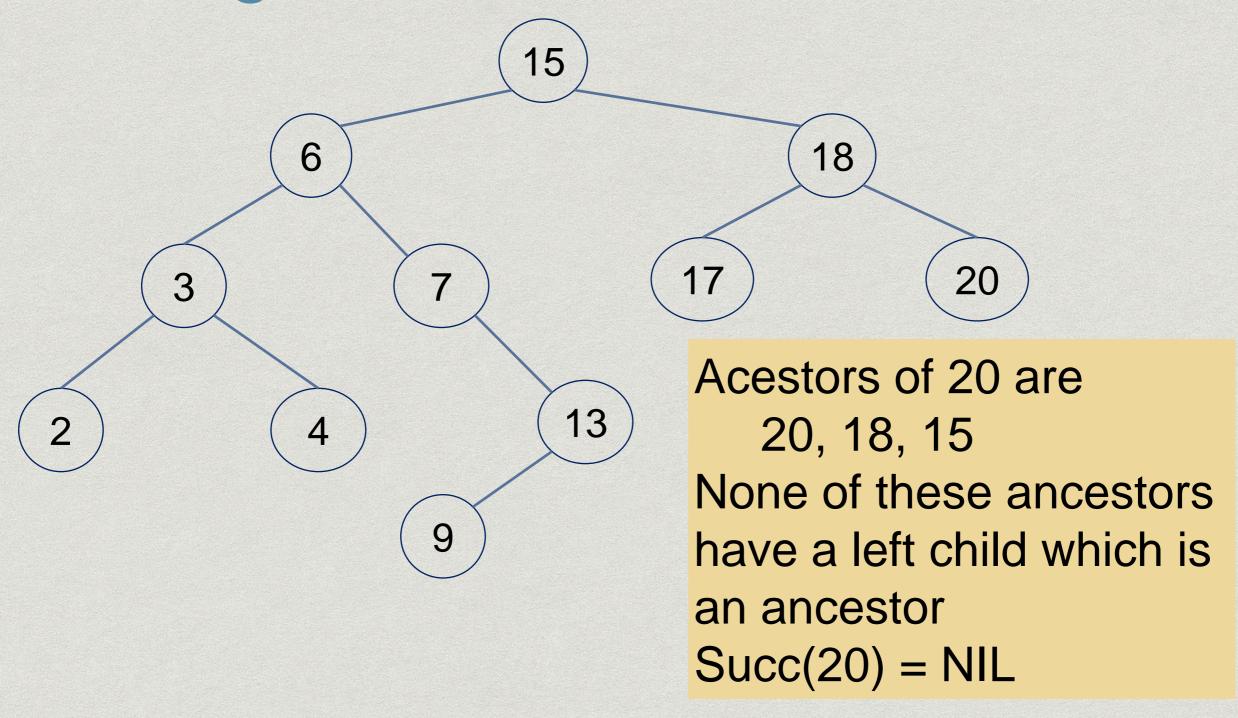
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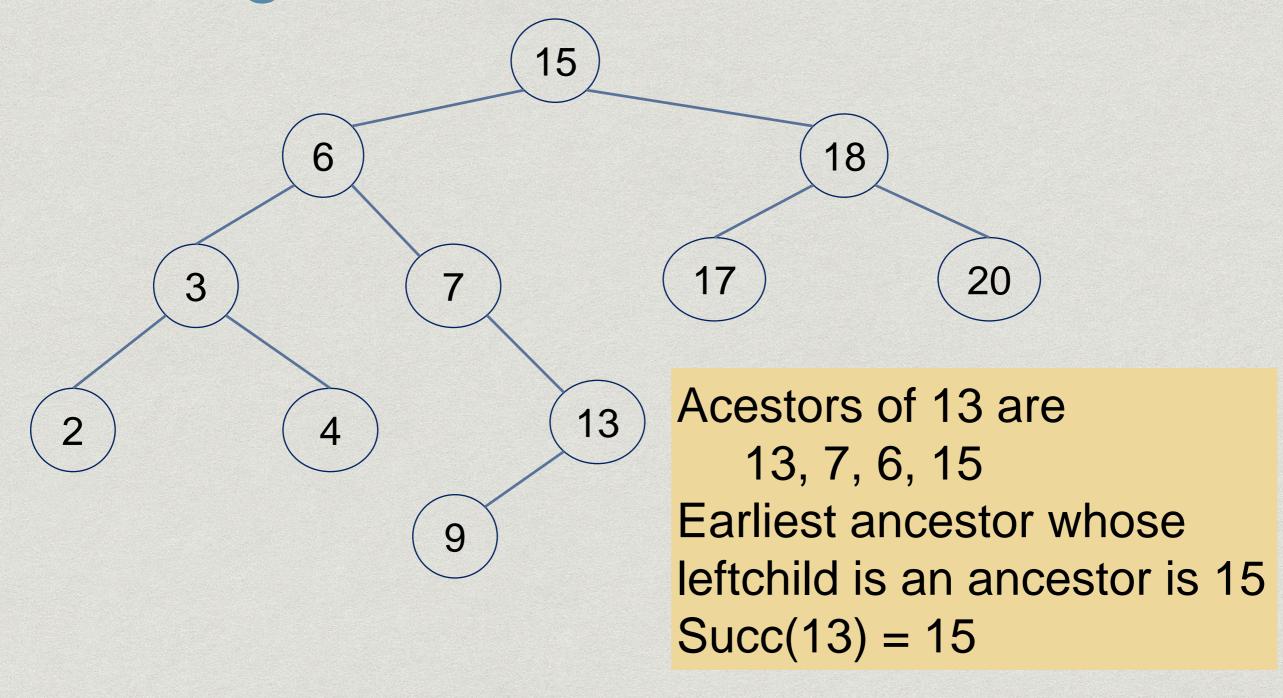
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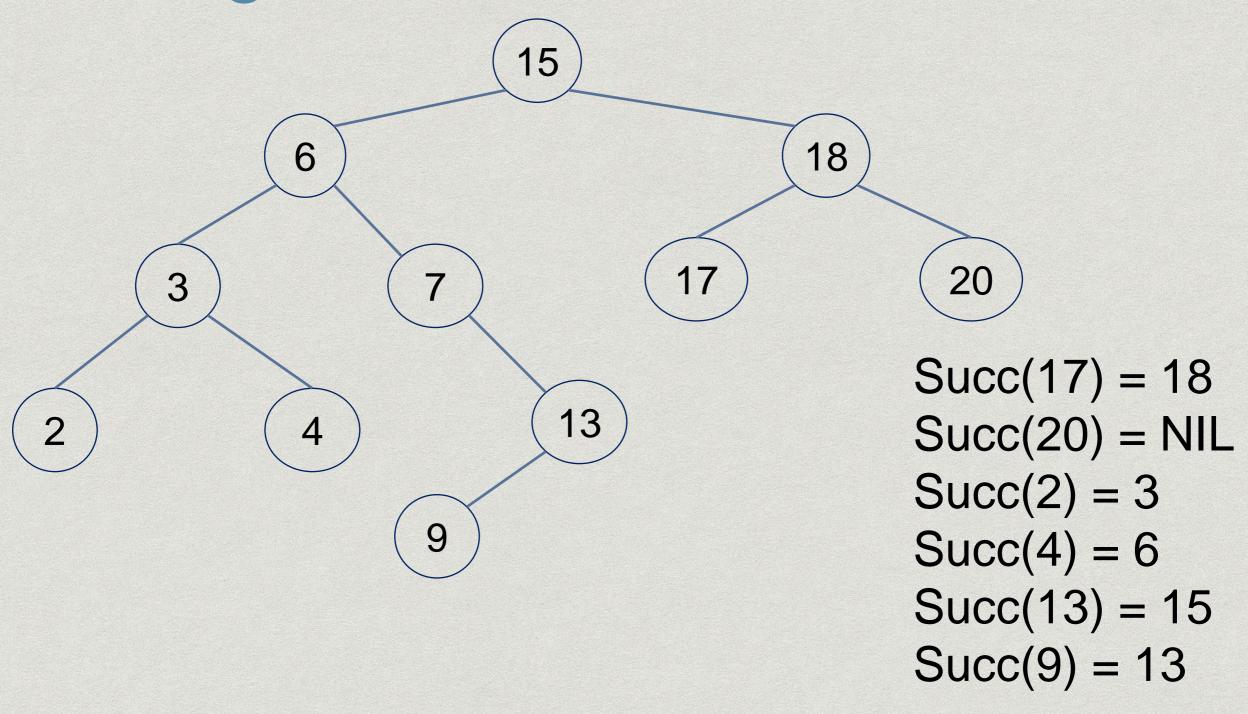
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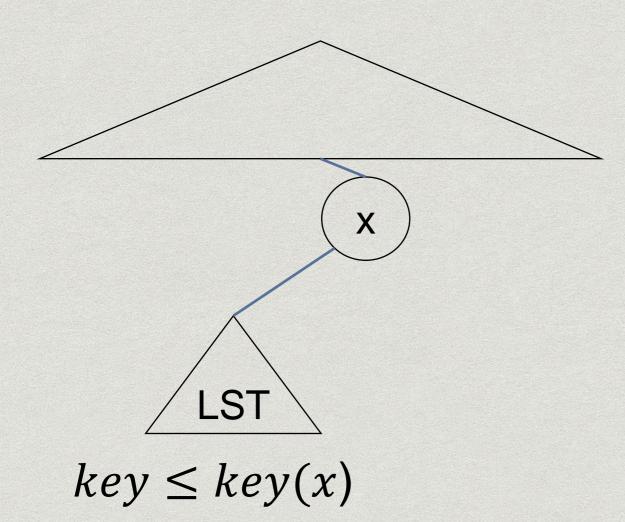
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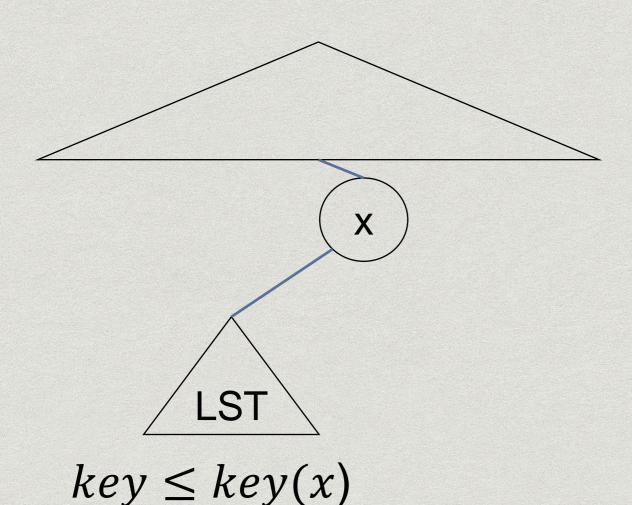
Why is this correct?

Consider a node x located somewhere in the tree



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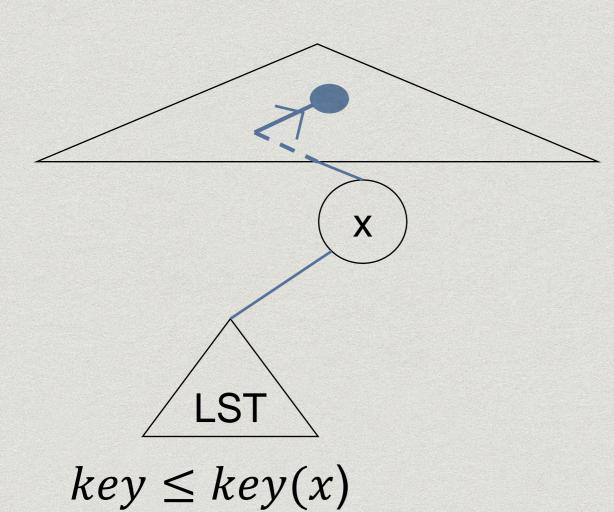


Consider a node x located somewhere in the tree

What is the next key printed by inorder tree walk after x?

If a node does not have a right child, then the succ is earliest ancestor whose leftchild is also an ancestor

Why is this correct?



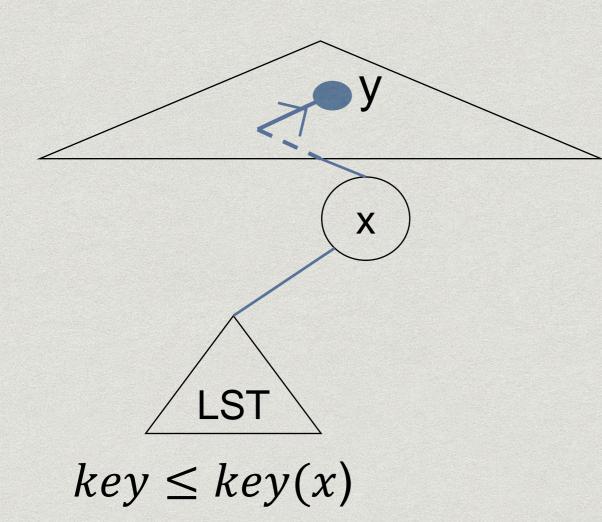
Consider a node x located somewhere in the tree

What is the next key printed by inorder tree walk after x?

Walk up from the tree till you first turn right – that is the node that gets printed next

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Consider a node x located somewhere in the tree

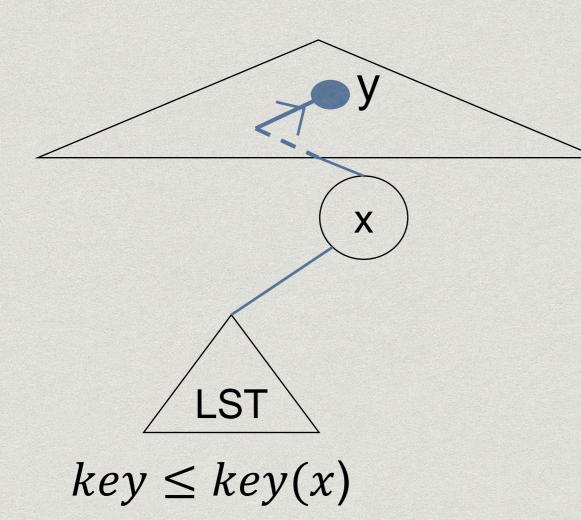
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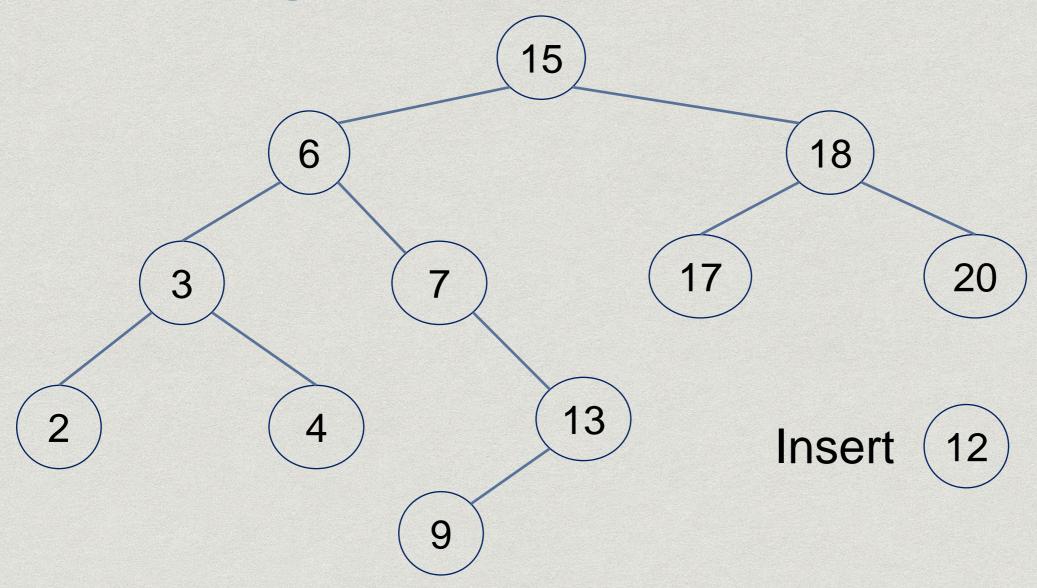
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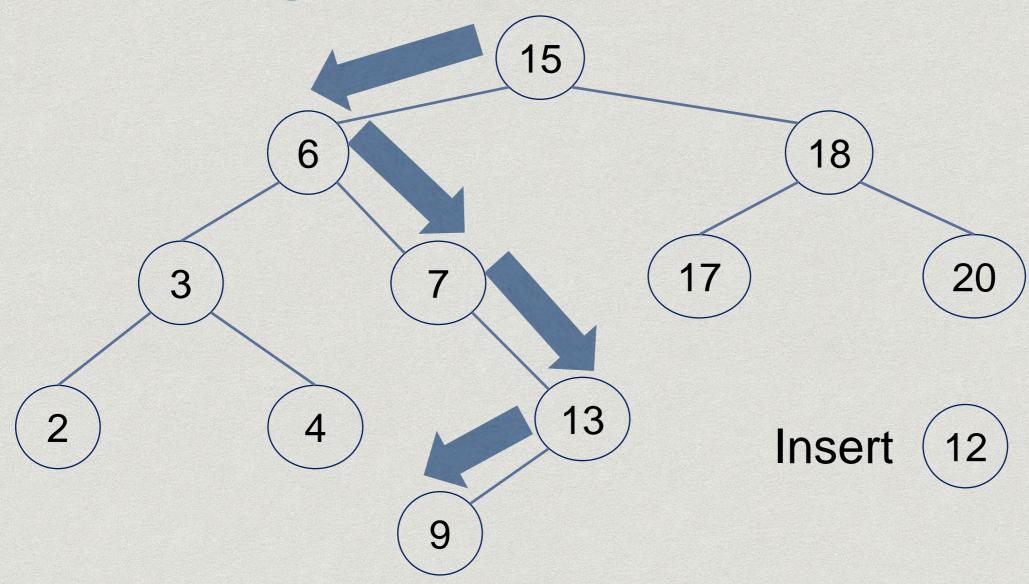
```
Node Tree_Succ(x) {
  if rightChild(x) \neq NIL:
      return Tree_Min(rightChild(x))
  else
      y = parent(x)
      while y \neq NIL and x == rightChild(y)
        X = Y
        y = parent(y)
      endwhile
      return y
  endif
```

Finding the predecessor to a node

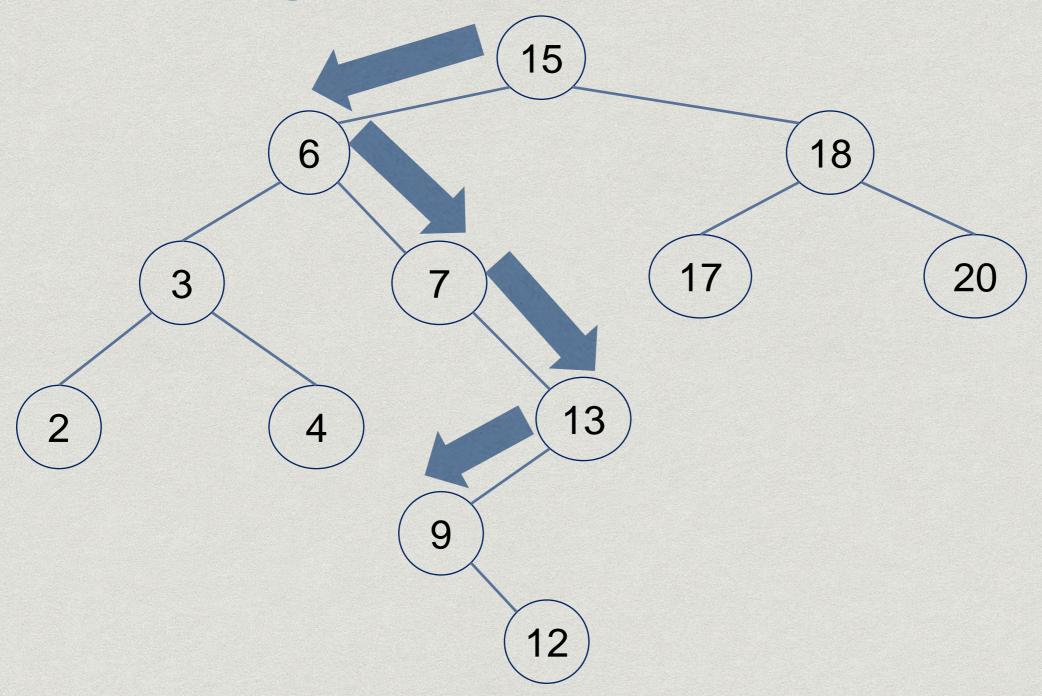
```
Node Tree_Pred(x) {
  if leftChild(x) \neq NIL:
      return Tree_Max( leftChild(x) )
  else
     y = parent(x)
     while y \neq NIL and x == leftChild(y)
        X = Y
        y = parent(y)
     endwhile
     return y
                    Predecessor method is very similar
  endif
                    to successor - take leftChild instead
                    of rightChild
```



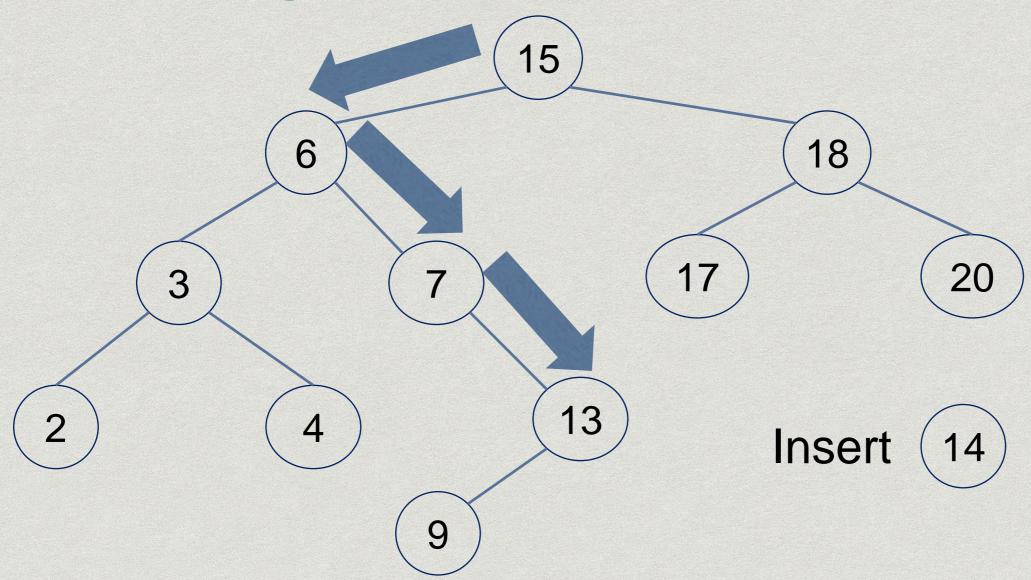
Follow the same method as searching for 12 Then insert it at the right place



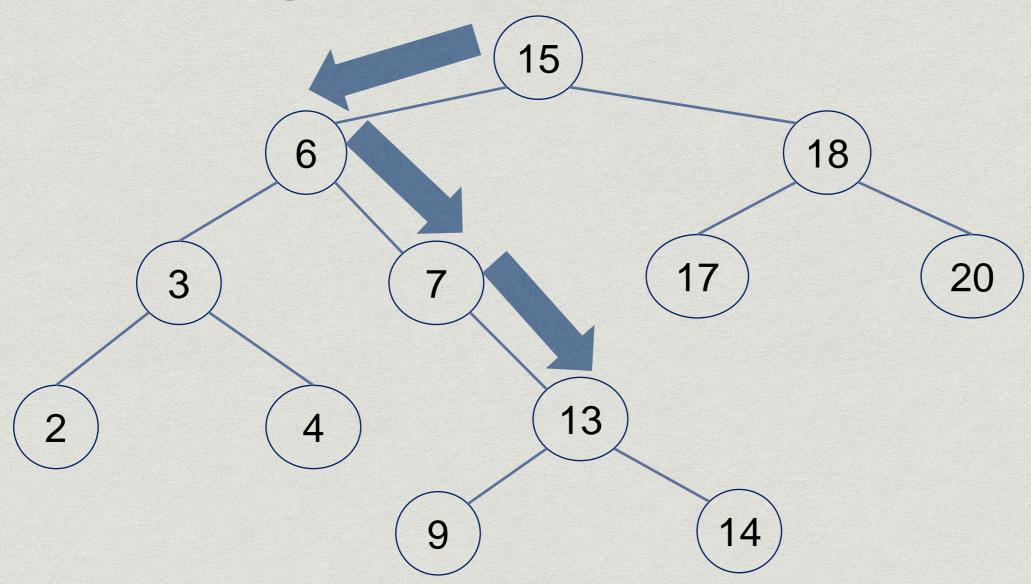
Follow the same method as searching for 12 Then insert it at the right place



Follow the same method as searching for 12 Then insert it at the right place



Follow the same method as searching for 14 Then insert it at the right place

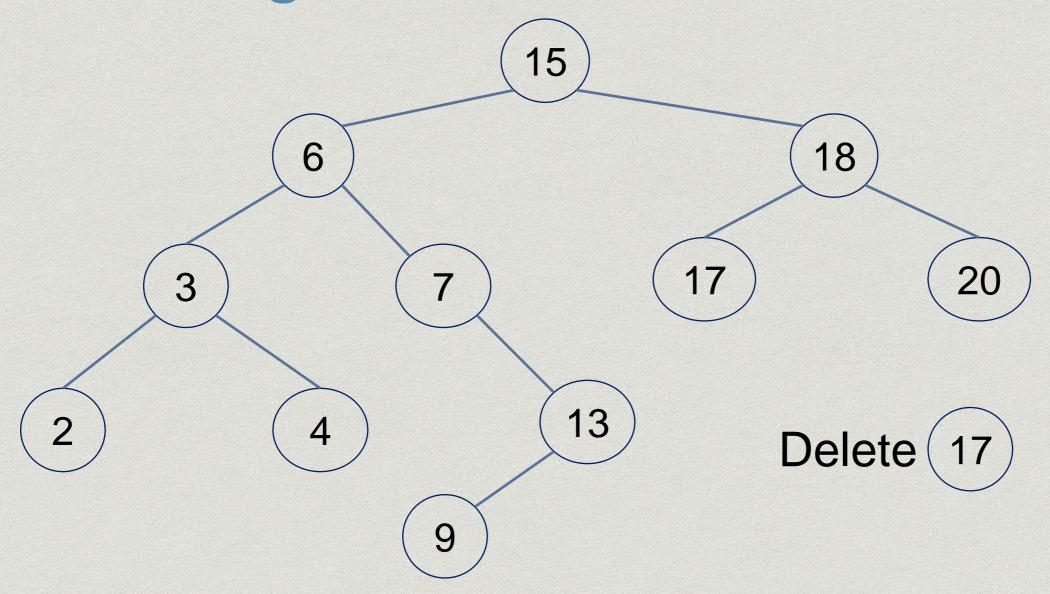


Follow the same method as searching for 14 Then insert it at the right place

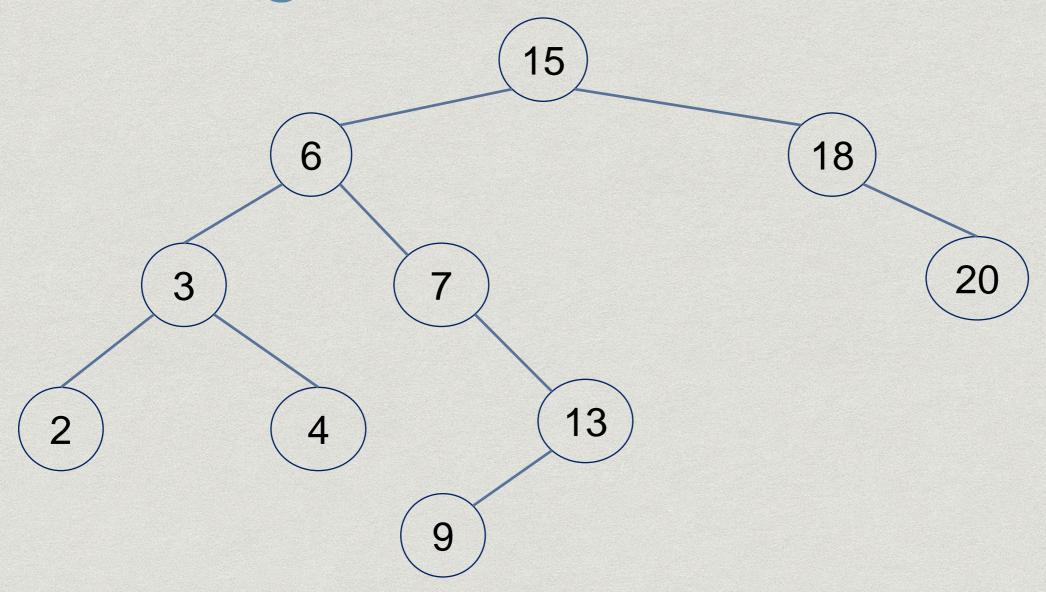
Inserting a node into a tree

```
Tree_Insert(T,z) {
  y = NIL
  x = root(T)
  while x \neq NIL:
    y = x
    if key(z) < key(x):
      x = leftChild(x)
                                        else
    else
      x = rightChild(x)
                                          else
    endif
  endwhile
                                          endif
// we have located
                                        endif
// the right place to insert
```

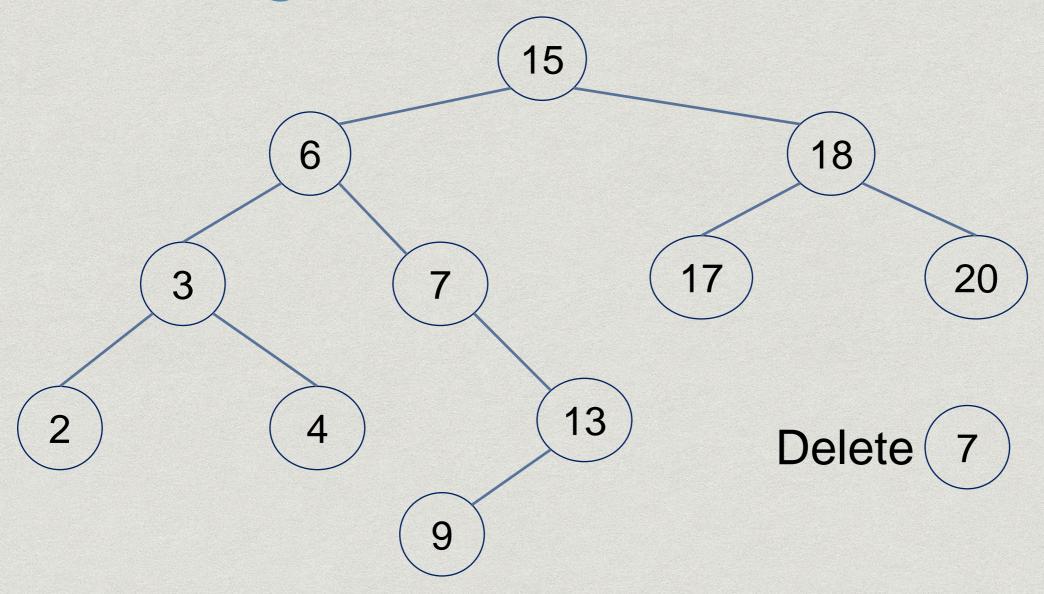
```
// we perform the
// insert now
  parent(z) = y
  if y == NIL:
     root(T) = z
    if key(z) < key(y):
      leftChild(y) = z
      rightChild(y) = z
```



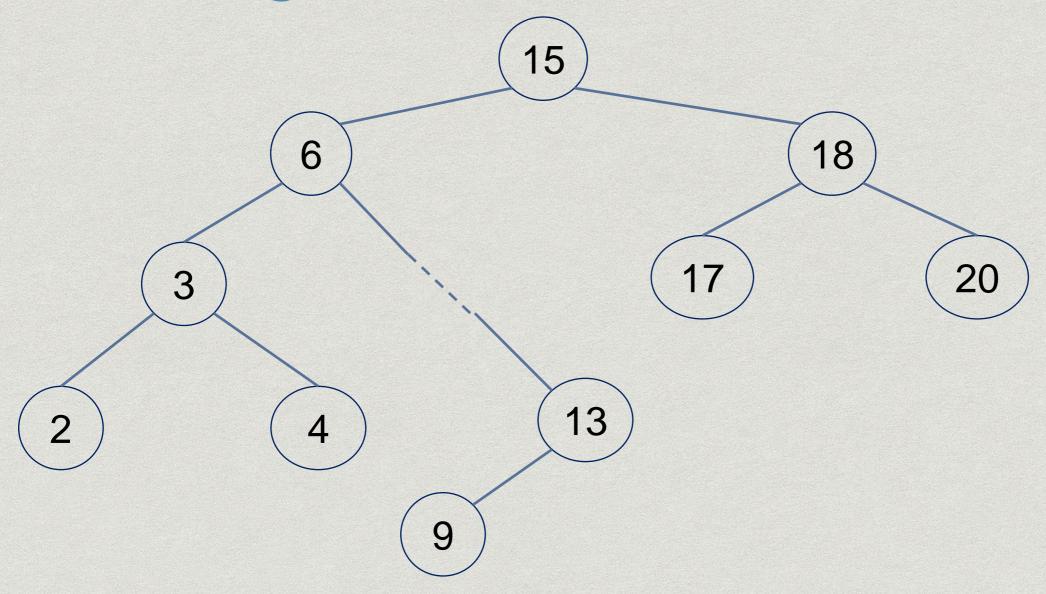
Case 1: Delete a node with no children



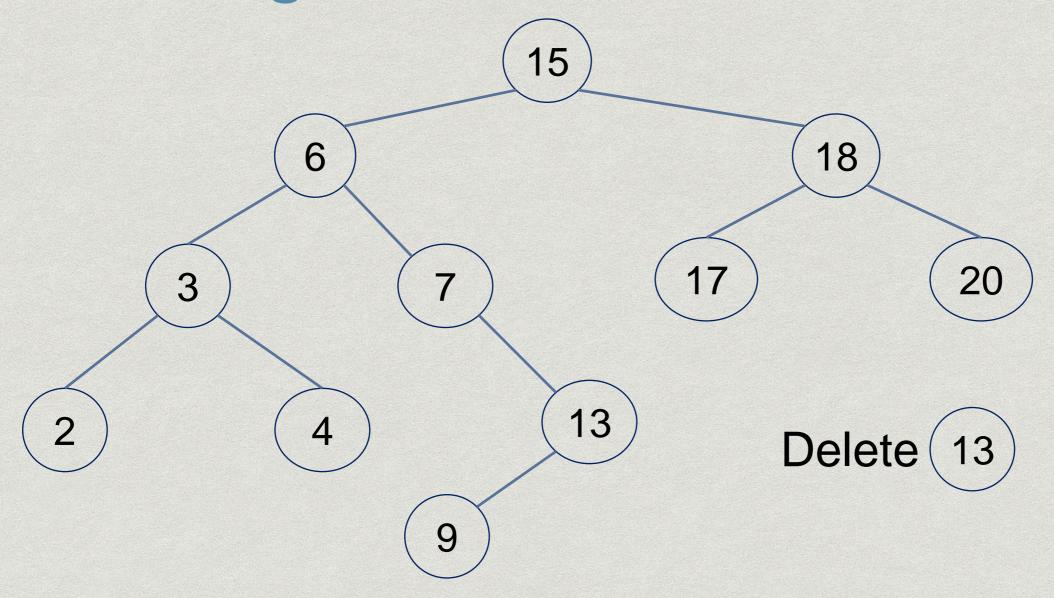
Case 1: Delete a node with no children Easy – Just delete the node!



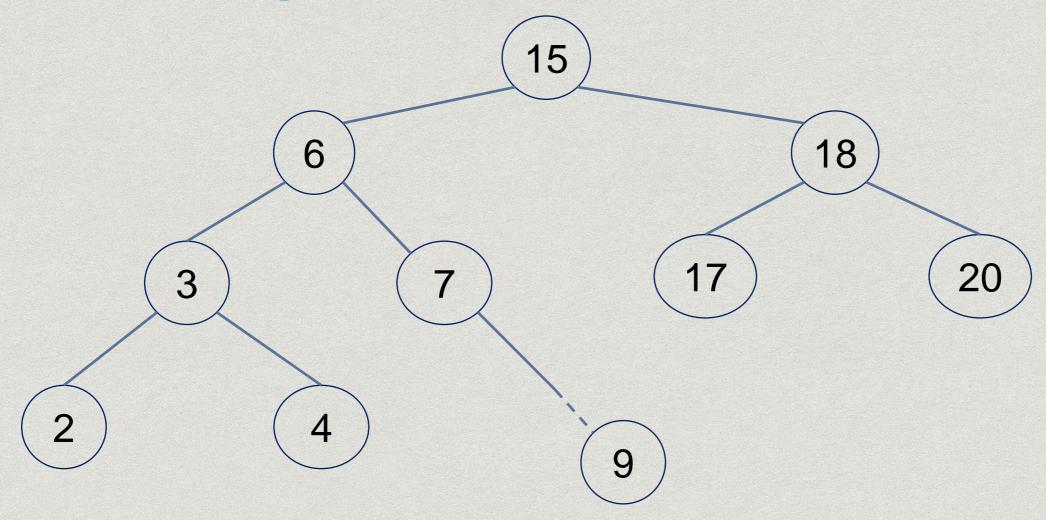
Case 2: Delete a node with one child



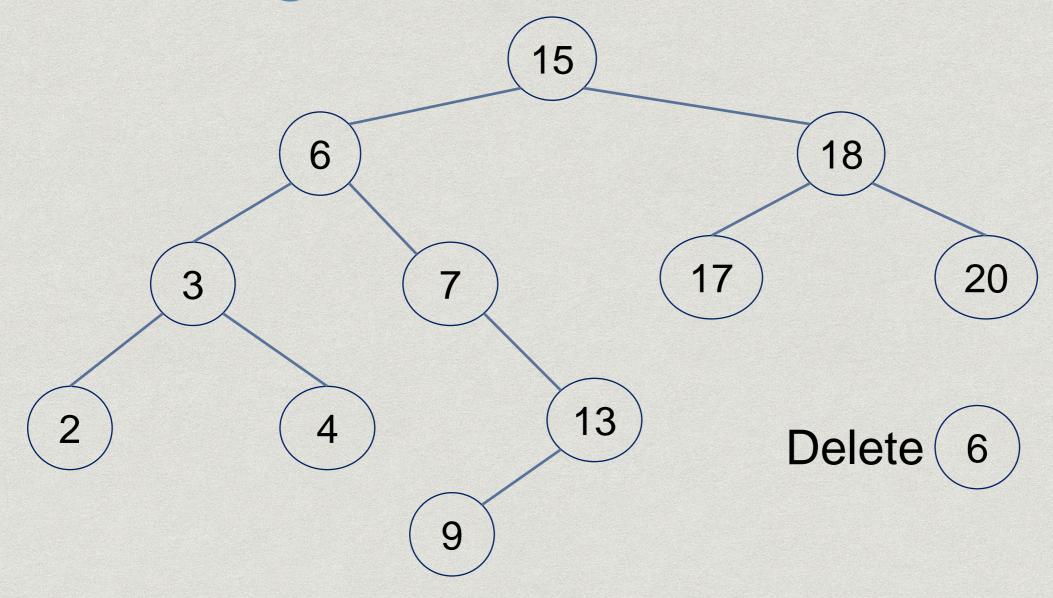
Case 2: Delete a node with one child Splice out the node



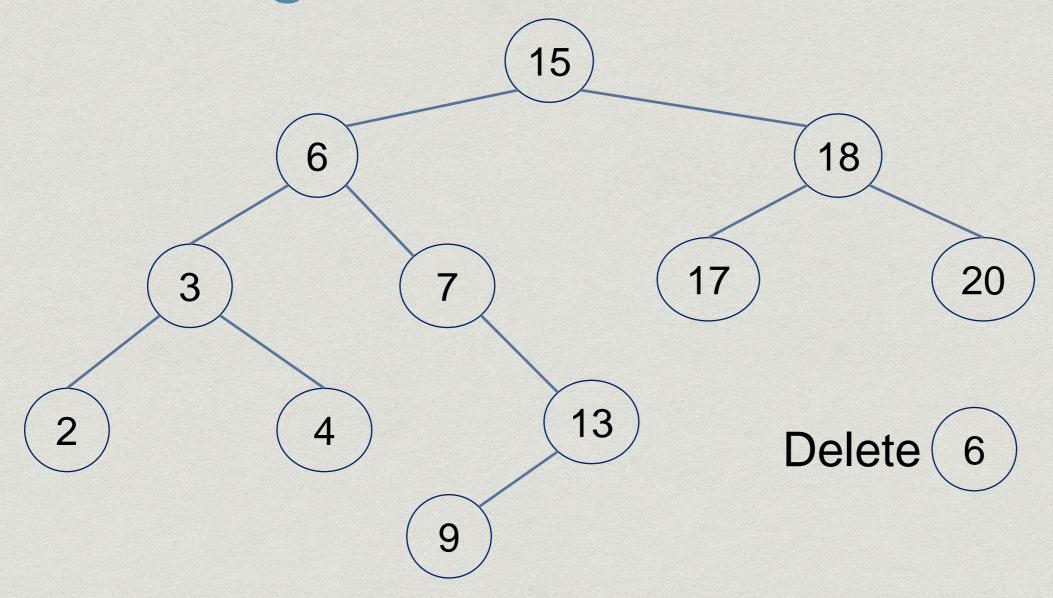
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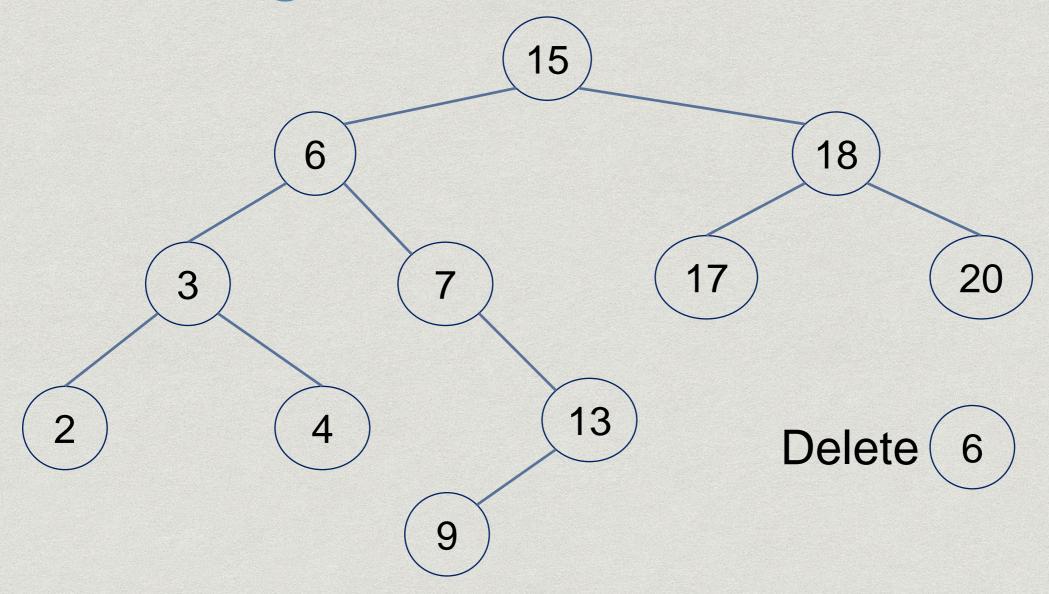
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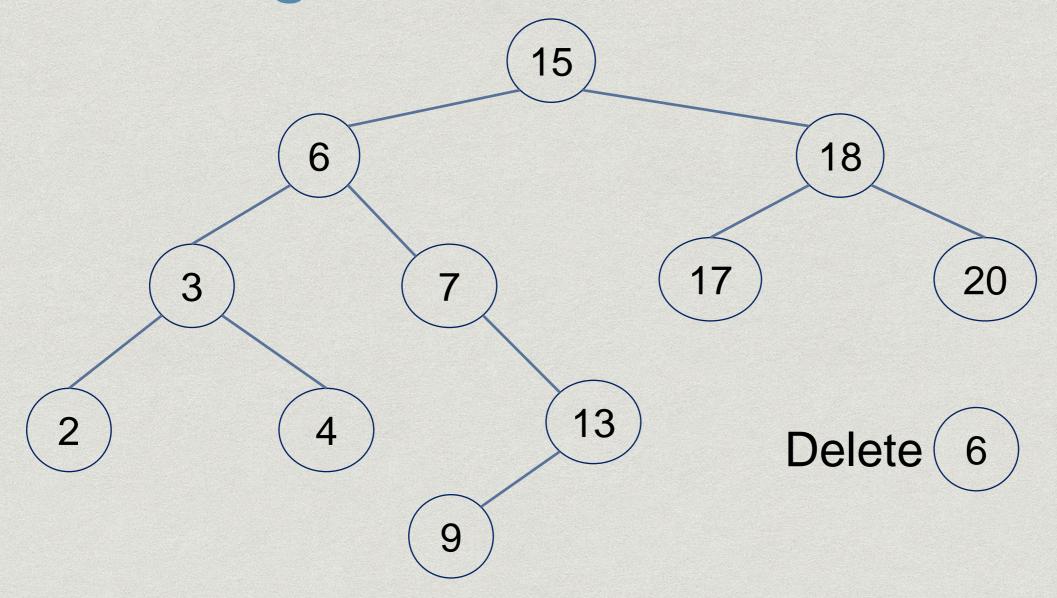
Case 3: Delete a node with two children



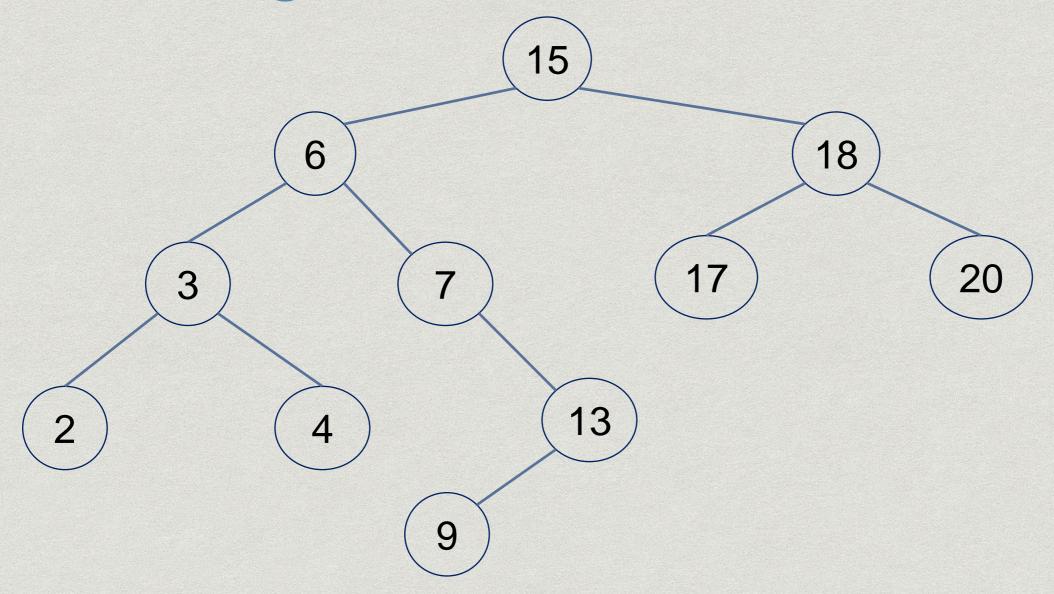
Case 3: Delete a node with two children
First find the successor of 6 ... min of the right sub tree of 6



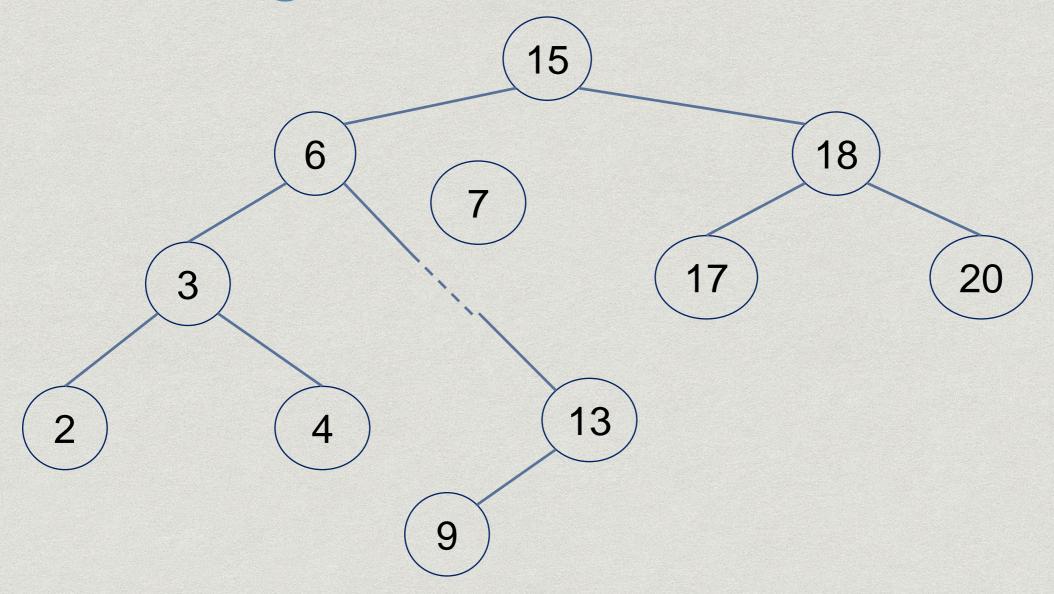
Case 3: Delete a node with two children First find the successor of 6 ... succ is 7



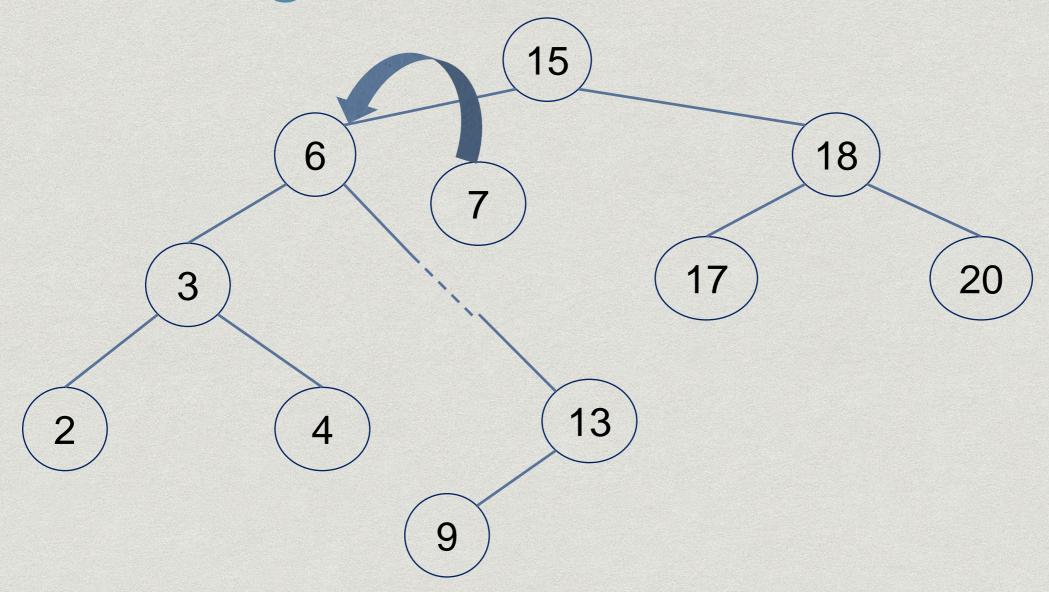
Case 3: Delete a node with two children
First find the successor of 6 ... succ is 7
Note: succ will have only right child ... since min is found
by going down the left of the tree till there is no leftChild



Case 3: Delete a node with two children Find succ ... node 7 Now splice out node 7



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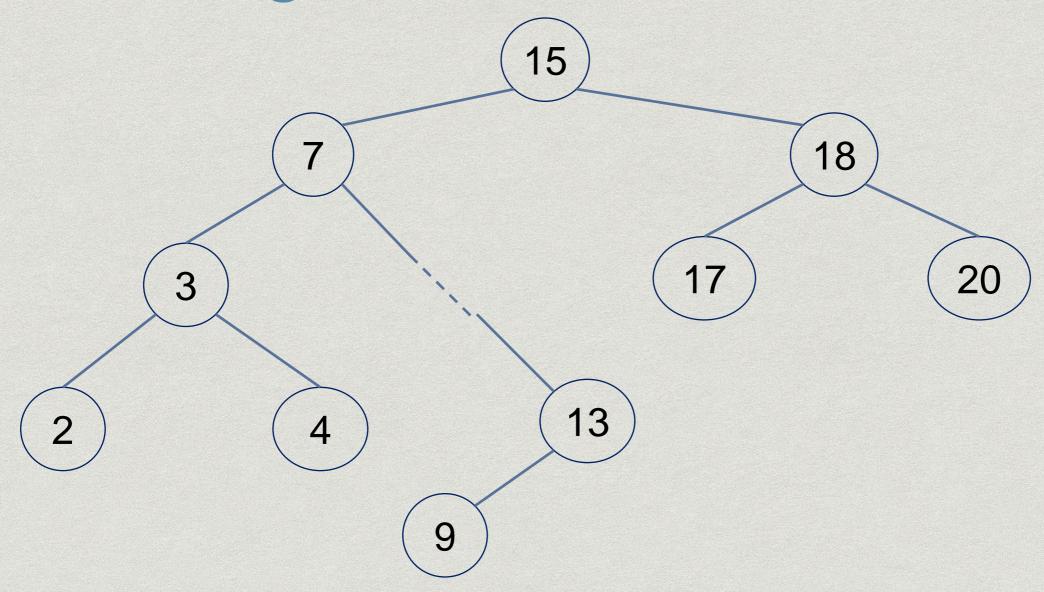


Case 3: Delete a node with two children

Find succ ... node 7

Now splice out node 7

... and replace contents of node 6 with that of node 7



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Find succ ... node 7

Now splice out node 7

... and replace contents of node 6 with that of node 7

Deleting a node from a tree

```
Tree_Delete(T,z) {
   if leftChild(z) == NIL or rightChild(z) == NIL:
     y = z
                                  if x \neq NIL:
   else
                                      parent(x) = parent(y)
     y = Tree_Succ(z)
                                  endif
   endif
                                  if parent(y) == NIL:
// node to splice
                                      root(T) = x
// is z or succ(z)
                                  else
                                    if y == leftChild(parent(y)):
  if leftChild(y) \neq NIL:
                                       leftChild(parent(y)) = x
     x = leftChild(y)
                                   else
   else
                                       rightChild(parent(y)) = x
     x = rightChild(y)
                                   endif
   endif
                                   if y \neq z \dots copy y to z
```

Complexity of algorithms so far

 All operations we saw so far on binary search trees (Search, Min, Max, Succ, Pred, Insert, Delete) can be done in time proportional to the height of the tree (length of longest path from root to a leaf)

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Complexity of algorithms so far

- All operations we saw so far on binary search trees (Search, Min, Max, Succ, Pred, Insert, Delete) can be done in time proportional to the height of the tree (length of longest path from root to a leaf)
- Height of a binary search tree can be properly managed and kept within log n - use rotations to keep the tree balanced - AVL trees or red-black trees
- A randomly generated binary search tree will have an expected height of log n

Summary

- Heaps are not good for determining succ and pred
- A new data structure is required when we have to do search along with insert/delete repeatedly
- Binary search trees are binary trees with elements stored in binary search tree order – i.e. keys of a node are no less than keys in its left subtree and no greater than keys in its right subtree
- All operations on binary search trees can be done in time proportional to the height of the tree
- Height of a binary search tree can be properly managed and kept within log n