# Sanket Shah

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# **EDUCATION**

### **UNIVERSITY OF BONN**

MASTERS IN COMPUTER SCIENCE 2019-2022

#### **MUMBAI UNIVERSITY**

BE IN COMPUTER ENGINEERING 2014-2018

# **SKILLS**

## Development

- C++ CUDA OpenCV PX4
- Thread Programming ROS
- Python Pytorch ONNX

#### Deployment

- TensorRT Quantization and Plugins
- NVIDIA Jetson Snapdragon
- Docker CI/CD Pipelines

#### Concepts

- Deep Learning Lidar, Camera and Radar based 3D Detection, Tracking, Velocity Estimation, Lane Segmentaiton.
- Computer Vision 3D computer vision, Structure from Motion, Optical Flow, Point Cloud Processing
- Robotics Sensor Fusion, SLAM, Motion Planning, Control Systems
- Sensor Setup Lidar, Camera and Radar Calibration and Synchronization

# LINKS

Website:// https://sanket-pixel.github.io/ Github:// sanket-pixel LinkedIn:// sanket-shah-33a3a2135

# COURSEWORK

#### Graduate

Computer Vision(CVI)
Machine Learning(CVII)
Deep Learning
Foundation of Graphics
Cognitive Robotics
Techniques of Self-Driving Cars
Reinforcement Learning

## Undergraduate

Applied Mathematics
Operating Systems
Data Structures and Algorithms
Databases and Distributed Databases
Computer Networks
Computer Architecture
Artificial Intelligence

## RELEVANT EXPERIENCE

## SPLEENLAB GMBH | COMPUTER VISION ENGINEER

November 2023 - Present | Jena, Germany

- Visual Odometry based GNNS Denied Localization Deployed transformer based Keypoint matching model on NVIDIA Jetson Orin used for visual odometry of drones and autonomous ground vehicles.
- *Inference Library* Developed internal tool for inference in C++ and CUDA for generic ONNXRuntime, Tensor RT, SNPE based inference. Used for monocular depth, keypoint matching, object detection, segmentation.
- **Deployment of Computer Vision models on Snapdragon** Deployed Single object tracker, multi-object tracker, keypoint matching, segmentation on VOXL2 drone with Snapdragon's QRB5165 chip using quantization and model pruning.

#### MOTOR AI GMBH | COMPUTER VISION ENGINEER

November 2022 - November 2023 | Berlin, Germany

- Camera-Lidar-Radar Fusion Model Low-Level Latenct Fusion Model for multi-view camera, lidars and radars to solve 3D Detection and Lane segmentation. Implemented TensorRT plugins for unsuported operation. CUDA accelarations for parallelizable operations. Used C++, CUDA, TensorRT, Pytorch.
- Monocular 3D Detection Developed a 3D Object Detection model on monocular images. Developed TensorRT engine and inference in C++/CUDA. Deployed on test vehicle. Achieved 3x inference speedup after quantization. Used C++, TensorRT, Pytorch.
- Lidar based 3D Detection Lidar only model for 3D detection using BEV projection. Developed TensorRT engine and inference in C++/CUDA. Achieved 2x inference speedup after quantization. Used C++, CUDA, PCL, Eigen, OpenCV, TensorRT, Pytorch.
- *German Traffic Sign Detection* at 100FPS. Deployed on test vehicle.Used C++, ROS, CUDA, Pytorch, TensorRT.

## ARTISENSE GMBH | COMPUTER VISION RESEARCHER

April 2022 - August 2022 | Munich, Germany

- *Monocular 3D reconstruction for autonomous vehicles* .Implementation of inhouse research paper.
- Monocular depth estimation model training on internal 4seasons dataset.
- Moving object segmentation mask model.
- Research Project in collaboration with *Technical University of Munich* under guidance of **Dr. Prof. Daniel Cremers**.
- Worked with Python using Pytorch, Numpy, Pandas and Open3D libraries.

## **DINEXT GMBH** | DATA SCIENTIST WERKSTUDENT

Mar 2021 - Mar 2022 | Saarland, Germany

- Lead the data science operations reporting to the CEO.
- Designed, Developed and Deployed(in production) more than 30 Machine Learning powered PowerBI dashboards with over 200 KPIs.

#### **SEPAGO GMBH** | DATA SCIENTIST WERKSTUDENT

Feb 2020 - Feb 2021 | Cologne, Germany

- Worked on machine learning in cybersecurity using unsupervised learning.
- Worked with internal team to develop over 50 KPIs for detecting cyber-attacks.

# **NETMONASTERY LTD** | SOFTWARE DEVELOPMENT | DATA SCIENTIST Sep 2018 – Sep 2019 | Mumbai, India

- Worked directly with CEO on machine learning models for cybersecurity.
- Integrated over 10 real-time ML models within their flagship product.
- Worked on data ingestion architecture with technologies like ElasticSearch.