

Geometric Progression - G

$$S = a + ar + ar^2 + \dots + ar^{n-1}$$

$$r \cdot S = ar + ar^2 + \dots + ar^n$$

$$r \cdot S - S = ar^n - a$$

$$\Rightarrow S(r-1) = ar^n - a$$

$$\Rightarrow S = \frac{a(r^n - 1)}{r - 1}$$

→ Execution Time not a good parameter to compare

→ In fact a machine can run 10^8 iterations.

of iterations → doesn't depend on:

Depends on the algorithm design. ↴ machine ↴ Programming language

→ Asymptotic → How will an algorithm perform for large inputs.

Time Complexity → Rate of growth of # of iterations w.r.t input size.

$$O = O(\# \text{ iterations})$$

Steps to find TC →

1) Calculate # of iterations w.r.t input size.
2) Ignore lower order terms.

3) Ignore constant co-efficient.

$$\text{Ex: } \# \text{ iterations} = 5n \log n + 80n + 3n^2 \\ = O(n^2)$$

Common Time Complexities →

$\log n$ \propto λ for λ \propto n $\log n$ \propto $n \log n$ \propto n^2 \propto n^3 \propto 2^n \propto n^n

- Contribution of lower order terms to time complexity decreases significantly as the input size increases.

↳ Problems with $\Theta(1)$ notation ↳

↳ Lower order term can have large contribution.

Ex $f(n) = n^2 + 10^{18}n$

$$TC = \Theta(n^2)$$

↳ Can't compare two algorithms with similar $\Theta(1)$ value.

Ex $f_1(n) = n^2 + 10^{18}n$ $f_2(n) = n^2 + 50$
- high value of lower order terms.

↳ Importance of constraints ↳ TC of the algorithm to be used can be found from input size constraint.

↳ Space Complexity ↳ Rate of growth of space w.r.t input size.

int & 4 bytes.
long & 8 bytes.
short & 1 byte.