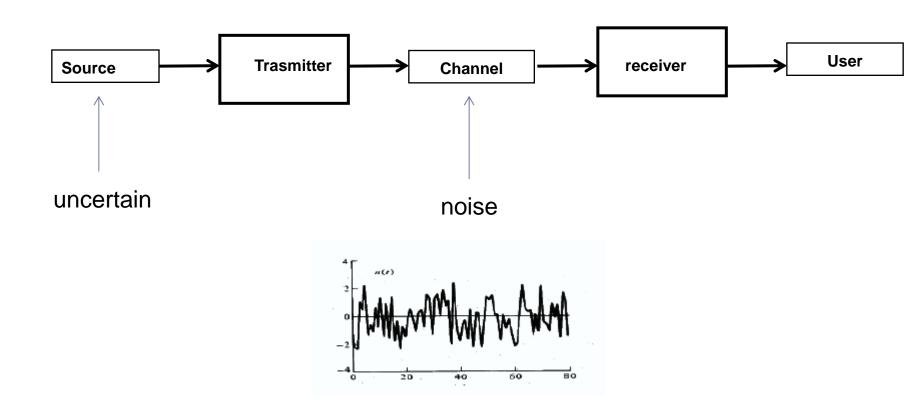
Digital Communications

Signals, Random Processes and Spectral Analisys

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DIGITAL COMUNICATION SYSTEM Signals



- Consider two events A and B
- Conditional probability P(A|B)
- Joint probability $P(AB) = P(A \cap B)$

$$P(AB) = P(B)P(A | B) = P(A)P(B | A)$$

A and B are said statistically independent iff

$$P(AB) = P(A)P(B) \Longrightarrow \begin{cases} P(A|B) = P(A) \\ P(B|A) = P(B) \end{cases}$$



Let A_j , j = 1, 2, ..., n be mutually exclusive events with $A_i \cap A_j = \emptyset$, $\forall i \neq j$

For any event B, we have

$$P(B) = \sum_{j=1}^{n} P(B \cap A_j)$$
$$= \sum_{j=1}^{n} P(B|A_j)P(A_j)$$



DIGITAL COMUNICATION SYSTEM Elements of Statistics Bayes's Theorem

Let A_i , i = 1, 2, ..., n be mutually exclusive events such that $\bigcup_{i=1}^{n} A_i = S$ and B is an arbitrary event with nonzero probability. Then

$$P(A_i|B) = \frac{P(A_i, B)}{P(B)}$$

= $\frac{P(B|A_i)P(A_i)}{\sum_{j=1}^{n} P(B|A_j)P(A_j)}$

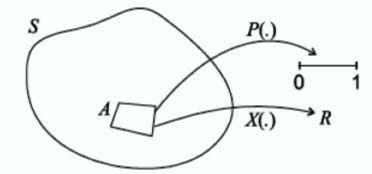


Elements of Statistics

Random Variables

 A r.v. is a mapping from the sample space S to the set of real numbers.

$$X(.): A \subset S \to x \in R \quad X(A) = x$$



- A r.v. may be
 - Discrete-valued: range is finite (e.g. {0,1}), or countable infinite (e.g. {1,2,3 ...})
 - Continuous-valued: range is uncountable infinite (e.g. R)



DIGITAL COMUNICATION SYSTEM Elements of Statistics Random Variables

The Cumulative distribution function (CDF of a r.v. X, is

$$F_X(x) \stackrel{\Delta}{=} P(X \le x)$$

Key properties of CDF

1.
$$0 \le F_X(x) \le 1$$
 with $F_X(-\infty) = 0$ and $F_X(\infty) = 1$

- 2. $F_X(x)$ is a non-decreasing function of x
- 3. $F(x_1 < X \le x_2) = F_X(x_2) F_X(x_1)$

Elements of Statistics

Random Variables

The PDF, of a r.v. X, is defined as

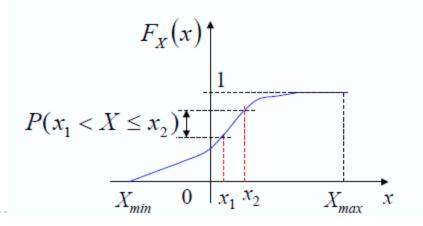
$$f_X(x) \stackrel{\triangle}{=} \frac{d}{dx} F_X(x)$$
 or $F_X(x) = \int_{-\infty}^x f_X(y) dy$

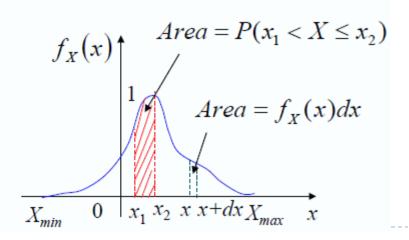
Key properties of PDF

1.
$$p_X(x) \ge 0$$

1.
$$p_X(x) \ge 0$$
 2. $\int_{-\infty}^{\infty} p_X(x) dx = 1$

3.
$$P(x_1 < X \le x_2) = P_X(x_2) - P_X(x_1) = \int_{x_1}^{x_2} p_X(x) dx$$





Bernoulli Distribution

A discrete r.v taking two possible values, X = 1 or X = 0.
 with probability mass function (pmf)

$$p(x) = P(X = x)$$

$$= \begin{cases} 1 - p & x = 0 \\ p & x = 1 \end{cases}$$

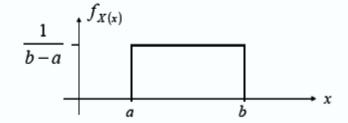
Often used to model binary data



DIGITAL COMUNICATION SYSTEM Elements of Statistics Uniform Distribution

- A continuous r.v. taking values between a and b with equal probabilities
- The probability density function (pdf) is given by

$$f_X(x) = \begin{cases} \frac{1}{b-a} & a \le x \le b \\ 0 & \text{otherwise} \end{cases}$$



• The random phase of a sinusoid is often modeled as a uniform r.v. between 0 and 2π



Elements of Statistics

Statistical Averages

- Consider a <u>discrete</u> r.v. which takes on the possible values x₁, x₂, ..., x_M with respective probabilities P₁, P₂, ..., P_M.
- The mean or expected value of X is

$$m_X = E[X] = \sum_{i=1}^M x_i P_i$$

If X is <u>continuous</u>, then

$$m_X = E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$$

This is the first moment

of X.



DIGITAL COMUNICATION SYSTEM Elements of Statistics Statistical Averages

• The *n*th moment of X

$$E[X^n] = \int_{-\infty}^{\infty} x^n p_X(x) dx$$

Let n = 2, we have the mean-square value

of X

$$E[X^2] = \int_{-\infty}^{\infty} x^2 p_X(x) dx$$



DIGITAL COMUNICATION SYSTEM Elements of Statistics Statistical Averages

n-th Central moment is

$$E[(X-m_X)^n] = \int_{-\infty}^{\infty} (x-m_X)^n f_X(x) dx$$

At n=2, we have the variance

$$\sigma_X^2 = E[(X - m_X)^2]$$

$$= E[X^2 - 2m_X X + m_X^2]$$

$$= E[X^2] - m_X^2$$

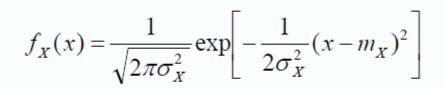
- σ_{X} is called the *standard deviation*
 - It is the average distance from the mean, a measure of the concentration of X around the mean

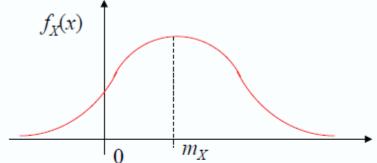


Elements of Statistics

Gaussian Distribution

 Gaussian or normal distribution r.v. with pdf





 A Gaussian r.v. is completely determined by its mean and variance, and hence usually denoted as

$$X \sim N(m_X, \sigma_X^2)$$

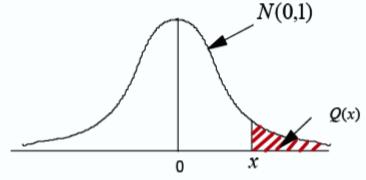
By far the most important distribution in communications

Q-Function

 The Q-function is a standard form to express error probabilities without a closed form

$$Q(x) = \int_{x}^{\infty} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{u^{2}}{2}\right) du$$

 The Q-function is the area under the tail of a Gaussian pdf with mean 0 and variance 1



Extremely important in error probability analysis!!!



Elements of Statistics

Q-Function

- Q-function is monotonically decreasing
- Some features

$$Q(-\infty) = 1$$
 $Q(0) = \frac{1}{2}$ $Q(\infty) = 0$ $Q(-x) = 1 - Q(x)$

- Upper bound $Q(x) \leq \frac{1}{2}e^{-x^2/2}$
- If we have a Gaussian variable $X \sim N(\mu, \sigma^2)$, then

$$\Pr(X > x) = Q\left(\frac{x - \mu}{\sigma}\right)$$

Elements of Statistics

Joint Distributions

 Consider 2 r.v.'s X and Y, joint distribution function is defined as

$$F_{XY}(x, y) = P(X \le x, Y \le y)$$

and joint PDF is
$$f_{XY}(x,y) = \frac{\partial^2 F_{XY}(x,y)}{\partial x \partial y}$$

Key properties of joint distribution

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p_{XY}(x, y) dx dy = 1$$

$$P(x_1 < X \le x_2, y_1 < Y \le y_2) = \int_{y_1}^{y_2} \int_{x_1}^{x_2} p_{XY}(x, y) dx dy$$



DIGITAL COMUNICATION SYSTEM Elements of Statistics Joint Distributions

Marginal distribution

$$P_{X}(x) = P(X \le x, -\infty < Y < \infty) = \int_{-\infty}^{\infty} \int_{-\infty}^{x} p_{XY}(\alpha, \beta) d\alpha d\beta$$

$$P_{Y}(y) = \int_{-\infty}^{y} \int_{-\infty}^{\infty} p_{XY}(\alpha, \beta) d\alpha d\beta$$

Marginal density

$$p_X(x) = \int_{-\infty}^{\infty} p_{XY}(x,\beta) d\beta$$

X and Y are said to be independent iff

$$P_{XY}(x, y) = P_X(x)P_Y(y)$$

$$p_{XY}(x, y) = p_X(x)p_Y(y)$$



DIGITAL COMUNICATION SYSTEM Elements of Statistics Correlation

Correlation of the two r.v. X and Y is defined as

$$R_{XY} = E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{XY}(x, y) dx dy$$

 Correlation of the two centered r.v. X-E[X] and Y-E[Y], is called the <u>covariance</u> of X and Y

$$\sigma_{XY} = E[(X - E[X])(Y - E[Y])]$$
$$= E[XY] - E[X]E[Y]$$

• If $\sigma_{XY} = 0$, i.e. E[XY] = E[X]E[Y], then X and Y are called uncorrelated.



DIGITAL COMUNICATION SYSTEM Elements of Statistics Correlation

• The covariance of X and Y normalized w.r.t. $\sigma_X \sigma_Y$ is referred to the <u>correlation coefficient</u> of X and Y:

$$\rho_{XY} = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}$$

- If X and Y are independent, then they are uncorrelated.
- The converse is not true (except the Gaussian case)



Elements of Statistics

Joint Gaussian Random Variables

X₁, X₂, ..., X_n are jointly Gaussian iff

$$f(x_1, x_2, \dots, x_n) = \frac{1}{(2\pi)^{n/2} (\det(\mathbf{C}))^{1/2}} \exp\left[-\frac{(\mathbf{x} - \mathbf{m})^T \mathbf{C}^{-1} (\mathbf{x} - \mathbf{m})}{2}\right]$$

- x is a column vector $\mathbf{x} = (x_1, \dots, x_n)^T$
- **m** is the vector of the means $\mathbf{m} = (m_1, \dots, m_n)^T$
- C is the n × n covariance matrix

$$\mathbf{C} = \begin{bmatrix} C_{i,j} \end{bmatrix}$$
 $C_{i,j} = E \begin{bmatrix} (X_i - m_i)(X_j - m_j) \end{bmatrix}$



Elements of Statistics Two variate Gaussian PDF

Given two r.v.s: X₁ and X₂ that are joint Gaussian

$$C = \begin{bmatrix} E[(X_1 - m_1)^2] & E[(X_1 - m_1)(X_2 - m_2)] \\ E[(X_1 - m_1)(X_2 - m_2)] & E[(X_2 - m_2)^2] \end{bmatrix}$$
$$= \begin{bmatrix} \sigma_1^2 & \rho \sigma_1 \sigma_2 \\ \rho \sigma_1 \sigma_2 & \sigma_2^2 \end{bmatrix}$$

Then

$$f(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left\{-\frac{1}{2(1-\rho^2)} \left[\frac{(x_1 - m_1)^2}{\sigma_1^2} - \frac{2\rho(x_1 - m_1)(x_2 - m_2)}{\sigma_1\sigma_2} + \frac{(x_2 - m_2)^2}{\sigma_2^2}\right]\right\}$$



• For uncorrelated X and Y, i.e. $\rho = 0$

$$f(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_2} \exp\left\{-\frac{1}{2} \left[\frac{(x_1 - m_1)^2}{\sigma_1^2} + \frac{(x_2 - m_2)^2}{\sigma_2^2} \right] \right\}$$

$$= \frac{1}{\sqrt{2\pi}\sigma_1} e^{-(x_1 - m_1)^2/2\sigma_1^2} \cdot \frac{1}{\sqrt{2\pi}\sigma_2} e^{-(x_2 - m_2)^2/2\sigma_2^2}$$

$$= f(x_1) f(x_2)$$

X1 and X2 are also independent

If X₁ and X₂ are Gaussian and uncorrelated, then they are independent.



Some Properties of Jointly Gaussian r.v.s

- If n random variables (X_1, X_2, \dots, X_n) are jointly Gaussian, any set of them is also jointly Gaussian. In particular, all individual r.v.s are Gaussian
- Jointly Gaussian r.v.s are completely characterized by the mean vector and the covariance matrix, i.e. the secondorder properties
- Any linear combination of (X_1, X_2, \dots, X_n) is a Gaussian r.v.



DIGITAL COMUNICATION SYSTEM Elements of Statistics Law of Large Numbers

- Consider a sequence of r.v. {X₁, X₂,..., X_n}
- Let $Y = \frac{1}{n} \sum_{i=1}^{n} X_i$
- If X_i 's are uncorrelated with the same mean m_X and variance $\sigma_X^2 < \infty$
- Then $\lim_{n\to\infty} P(|Y-m_X| \ge \varepsilon) = 0$ $\forall \varepsilon > 0$

the average converges to the expected value



Elements of Statistics

Central Limit Theorem

- If $\{X_1, X_2, \dots, X_n\}$ are i.i.d random variables with common mean m_X and common variance σ_X^2
- Then, $Y = \frac{1}{n} \sum_{i=1}^n X_i$ converges to a $\mathcal{N}\left(m_X, \frac{\sigma_X^2}{n}\right)$

the sum of many i.i.d random variables converges to a Gaussian random variable

 Thermal noise results from the random movement of many electrons – it is well modeled by a Gaussian distribution.

