Machine Learnign Final Project

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Introduction

Using devices such as Jawbone Up, Nike FuelBand, and Fitbit it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement – a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how much of a particular activity they do, but they rarely quantify how well they do it. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways, exactly according to the specification (Class A), throwing the elbows to the front (Class B), lifting the dumbbell only halfway (Class C), lowering the dumbbell only halfway (Class D) and throwing the hips to the front (Class E). Class A corresponds to the specified execution of the exercise, while the other 4 classes correspond to common mistakes. More details can be found in the paper "Qualitative Activity Recognition of Weight Lifting Exercises" written by Eduardo Velloso et. al., which can be found at this site: http://web.archive.org/web/20170519033209/http://groupware.les.inf.pucrio.br/public/papers/2013.Velloso.QAR-WLE.pdf

Data to conduct this analysis is found in these sites. The training data for this project are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv

The test data are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv

The goal of your project is to predict the manner in which they did the exercise. This is the "classe" variable in the training set. You may use any of the other variables to predict with. You should create a report describing how you built your model, how you used cross validation, what you think the expected out of sample error is, and why you made the choices you did. You will also use your prediction model to predict 20 different test cases.

Methodology

The following steps were followed in order to determine what is the best way to predict "classe" on function of the data acquired through devices located on different parts of the participant bodies.

- 1. Download, and read the data
- 2. Inspect the data
- 3. Clean the data by removing variables (columns) that don't have values/NA, or great majority are zeros)
- 4. Analyze the train set by creating models using different techniques such as "Predicting with Trees", "Random Forest", "Boosting", "Linear Discriminant Analysis", and finally "Combining Predictors" 5 A summary of the results will be provided and a recommendation on what is the most applicable technique to predict "classe"

Downloading, reading and saving data sets

Use the above links to download, read and save the data sets.

```
traindataURL <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
training.csv"
download.file(traindataURL, destfile = "./pml-training.csv")
pmlTrainData <- read.csv("./pml-training.csv")

testdataURL <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-
testing.csv"
download.file(testdataURL, destfile = "./pml-testing.csv")
pmlTestData <- read.csv("./pml-testing.csv")</pre>
```

Data inspection and cleaning

The data set will be inspected and all the variables without values, zeros, and/or NA will be remove. Them the training set will be split in training set and validation set. The test set will be used to confirm the accuracy of the model.

```
dim(pmlTrainData)
## [1] 19622
              160
str(pmlTrainData)
                   19622 obs. of 160 variables:
## 'data.frame':
                             : int 1 2 3 4 5 6 7 8 9 10 ...
## $ X
## $ user_name
                             : chr "carlitos" "carlitos" "carlitos"
"carlitos" ...
## $ raw timestamp part 1 : int 1323084231 1323084231 1323084231
1323084232 1323084232 1323084232 1323084232 1323084232 1323084232 1323084232
                             : int 788290 808298 820366 120339 196328
## $ raw timestamp part 2
304277 368296 440390 484323 484434 ...
                             : chr "05/12/2011 11:23" "05/12/2011 11:23"
## $ cvtd timestamp
"05/12/2011 11:23" "05/12/2011 11:23" ...
## $ new window
                             : chr "no" "no" "no" "no" ...
## $ num_window
                             : int 11 11 11 12 12 12 12 12 12 12 ...
## $ roll belt
                             : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42
```

```
1.43 1.45 ...
                                    8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13
## $ pitch belt
                             : num
8.16 8.17 ...
                                    -94.4 -94.4 -94.4 -94.4 -94.4 -
## $ yaw_belt
                             : num
94.4 - 94.4 - 94.4 ...
   $ total_accel_belt
                                    3 3 3 3 3 3 3 3 3 ...
                             : int
  $ kurtosis roll belt
                             : chr
                                    ... ... ...
##
  $ kurtosis_picth_belt
                             : chr
  $ kurtosis_yaw_belt
                             : chr
## $ skewness roll belt
                             : chr
## $ skewness_roll_belt.1
                             : chr
## $ skewness yaw belt
                             : chr
##
  $ max roll belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
## $ max_picth_belt
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
                                    ... ... ... ...
## $ max_yaw_belt
                             : chr
  $ min roll belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
##
  $ min_pitch_belt
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
## $ min yaw belt
                             : chr
## $ amplitude roll belt
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ amplitude_pitch_belt
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
## $ amplitude yaw belt
                             : chr
## $ var_total_accel_belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
## $ avg_roll_belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
## $ stddev roll belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
##
  $ var_roll_belt
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_belt
                               num
                                    NA NA NA NA NA NA NA NA NA ...
                                    NA NA NA NA NA NA NA NA NA ...
## $ stddev pitch belt
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                             : num
## $ avg_yaw_belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
## $ stddev yaw belt
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt
                             : num
                                    0 0.02 0 0.02 0.02 0.02 0.02 0.02 0.02
## $ gyros_belt_x
                             : num
0.03 ...
                                    0 0 0 0 0.02 0 0 0 0 0 ...
## $ gyros_belt_y
                             : num
                                    -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -
## $ gyros_belt_z
                             : num
0.02 -0.02 -0.02 0 ...
                                    -21 -22 -20 -22 -21 -21 -22 -22 -20 -21
## $ accel_belt_x
                             : int
                                    4 4 5 3 2 4 3 4 2 4 ...
## $ accel_belt_y
                             : int
## $ accel_belt_z
                             : int
                                    22 22 23 21 24 21 21 21 24 22 ...
## $ magnet_belt_x
                             : int
                                    -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
## $ magnet belt y
                             : int
                                    599 608 600 604 600 603 599 603 602 609
                                    -313 -311 -305 -310 -302 -312 -311 -313
## $ magnet_belt_z
                             : int
-312 -308 ...
                                    -128 -128 -128 -128 -128 -128 -128 -128
## $ roll_arm
                             : num
-128 -128 ...
                                    22.5 22.5 22.5 22.1 22.1 22 21.9 21.8
## $ pitch_arm
                             : num
21.7 21.6 ...
## $ yaw_arm
                             : num -161 -161 -161 -161 -161 -161 -161
```

```
-161 -161 ...
                                    34 34 34 34 34 34 34 34 ...
   $ total accel arm
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ var_accel_arm
                             : num
##
   $ avg roll arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
##
   $ stddev_roll_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
   $ var_roll_arm
                                    NA NA NA NA NA NA NA NA NA ...
##
                               num
   $ avg pitch arm
                                    NA NA NA NA NA NA NA NA NA ...
                               num
##
   $ stddev_pitch_arm
                               num
                                    NA NA NA NA NA NA NA NA NA ...
                                    NA NA NA NA NA NA NA NA NA ...
   $ var_pitch_arm
                               num
##
  $ avg yaw arm
                                    NA NA NA NA NA NA NA NA NA ...
                               num
##
  $ stddev_yaw_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ var yaw arm
                             : num
                                    ## $ gyros arm x
                             : num
                                    0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -
## $ gyros_arm_y
                             : num
0.02 -0.03 -0.03 ...
## $ gyros_arm_z
                             : num
                                    -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -
0.02 ...
                                    -288 -290 -289 -289 -289 -289 -289
## $ accel arm x
                             : int
-288 -288 ...
                                    109 110 110 111 111 111 111 111 109 110
## $ accel arm y
                             : int
## $ accel_arm_z
                             : int
                                    -123 -125 -126 -123 -123 -122 -125 -124
-122 -124 ...
                                    -368 -369 -368 -372 -374 -369 -373 -372
## $ magnet arm x
                             : int
-369 -376 ...
                                    337 337 344 344 337 342 336 338 341 334
  $ magnet arm y
                             : int
. . .
##
   $ magnet_arm_z
                                    516 513 513 512 506 513 509 510 518 516
                             : int
   $ kurtosis roll arm
##
                             : chr
##
   $ kurtosis_picth_arm
                             : chr
   $ kurtosis yaw arm
##
                             : chr
   $ skewness roll arm
##
                             : chr
                                    11 11
                                       ....
  $ skewness pitch arm
##
                               chr
##
   $ skewness yaw arm
                             : chr
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ max roll arm
                             : num
##
   $ max_picth_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ max_yaw_arm
                             : int
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ min_roll_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ min_pitch_arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ min yaw arm
                               int
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ amplitude roll arm
                             : num
                                    NA NA NA NA NA NA NA NA NA ...
##
  $ amplitude_pitch_arm
                                    NA NA NA NA NA NA NA NA NA ...
                             : num
##
                                    NA NA NA NA NA NA NA NA NA ...
  $ amplitude_yaw_arm
                             : int
##
  $ roll_dumbbell
                             : num
                                    13.1 13.1 12.9 13.4 13.4 ...
##
   $ pitch_dumbbell
                             : num
                                    -70.5 -70.6 -70.3 -70.4 -70.4 ...
                                    -84.9 -84.7 -85.1 -84.9 -84.9 ...
## $ yaw dumbbell
                             : num
## $ kurtosis_roll_dumbbell : chr
## $ kurtosis_picth_dumbbell : chr
                                    ... ... ... ...
```

```
... ... ... ...
## $ kurtosis yaw dumbbell
                              : chr
                                     ... ... ... ...
## $ skewness roll dumbbell : chr
                                     ## $ skewness_pitch_dumbbell : chr
## $ skewness yaw dumbbell
                              : chr
## $ max_roll_dumbbell
                              : num
                                     NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                              : num
                                     NA NA NA NA NA NA NA NA NA ...
                                     ## $ max yaw dumbbell
                              : chr
## $ min_roll_dumbbell
                              : num
                                     NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_dumbbell
                              : num
                                     NA NA NA NA NA NA NA NA NA ...
                                     ... ... ... ...
## $ min yaw dumbbell
                              : chr
## $ amplitude_roll_dumbbell : num
                                     NA NA NA NA NA NA NA NA NA ...
##
     [list output truncated]
# Remove all the variable with zeros, NA out of the train set
# Here we get the indexes of the columns having at least 90% of NA or blank
indColToRemoveTrain <- which(colSums(is.na(pmlTrainData)</pre>
pmlTrainData=="")>0.9*dim(pmlTrainData)[1])
pmlTrainDataClean <- pmlTrainData[,-indColToRemoveTrain]</pre>
pmlTrainDataClean <- pmlTrainDataClean[,-c(1:7)]</pre>
dim(pmlTrainDataClean)
## [1] 19622
                53
# The same protocol will be done in test data set
indColToRemoveTest <- which(colSums(is.na(pmlTestData)</pre>
pmlTestData=="")>0.9*dim(pmlTestData)[1])
pmlTestDataClean <- pmlTestData[,-indColToRemoveTest]</pre>
pmlTestDataClean <- pmlTestDataClean[,-c(1:7)]</pre>
dim(pmlTestDataClean)
## [1] 20 53
```

Setting up Training, Validation and Test sets

The train data set will be split in training set (75%) and Validation set (25%). The test set will not be changed.

```
set.seed(20210129)
inTrain <- createDataPartition(pmlTrainDataClean$classe, p=3/4)[[1]]
pmlTraining <- pmlTrainDataClean[inTrain, ]
pmlValidation <- pmlTrainDataClean[-inTrain, ]
pmlTesting <- pmlTestDataClean
dim(pmlTraining)
## [1] 14718 53
dim(pmlValidation)</pre>
```

```
## [1] 4904 53

dim(pmlTesting)

## [1] 20 53
```

Modeling

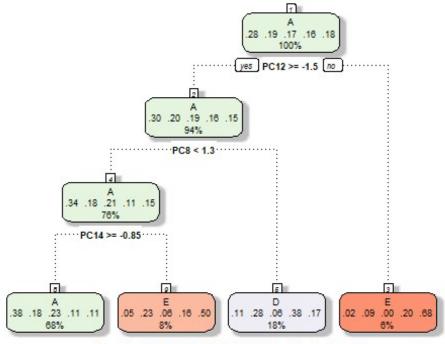
```
Set up processing
```

```
library(doParallel)
cluster <- makeCluster(detectCores() - 1) # convention to leave 1 core for OS
registerDoParallel(cluster)

fitControl <- trainControl(method = "cv", number = 5, allowParallel = TRUE)</pre>
```

Predicting with Recursive Partitioning (Trees)

```
pmlModelrp <- train(classe~., data = pmlTraining, method="rpart", preProcess
= "pca", na.action = na.omit, trControl = fitControl)
pmlValrp <- predict(pmlModelrp, newdata=pmlValidation)
pmllevels <- levels(factor(pmlValidation$classe))
rpAccuracy <- confusionMatrix(factor(pmlValrp, levels =
pmllevels),factor(pmlValidation$classe, levels =
pmllevels))$overall['Accuracy']
fancyRpartPlot(pmlModelrp$finalModel)</pre>
```



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Prediciting with Random Forests

```
pmlModelrf <- train(classe~., data = pmlTraining, method="rf", preProcess =</pre>
"pca", na.action = na.omit, trControl = fitControl)
pmlValrf <- predict(pmlModelrf, newdata=pmlValidation)</pre>
rfAccuracy <- confusionMatrix(factor(pmlValrf, levels =
pmllevels),factor(pmlValidation$classe, levels =
pmllevels))$overall['Accuracy']
```

Prediction with GBM (Gradient Boosting Machine) (Boosting with Trees)

```
pmlModelgbm <- train(classe~., data = pmlTraining, method="gbm", preProcess =</pre>
"pca", na.action = na.omit, trControl = fitControl)
```

##	Iter	TnainDeviance	ValidDeviance	StepSize	Tmnnove	
				•	Improve	
##		1.6094	nan	0.1000	0.1267	
##		1.5315	nan	0.1000	0.0939	
##		1.4752	nan	0.1000	0.0709	
##	4	1.4313	nan	0.1000	0.0595	
##	5	1.3942	nan	0.1000	0.0493	
##	6	1.3617	nan	0.1000	0.0473	
##	7	1.3320	nan	0.1000	0.0372	
##	8	1.3062	nan	0.1000	0.0343	
##	9	1.2844	nan	0.1000	0.0329	
##	10	1.2629	nan	0.1000	0.0327	
##	20	1.1032	nan	0.1000	0.0170	
##	40	0.9288	nan	0.1000	0.0086	
##	60	0.8218	nan	0.1000	0.0055	
##	80	0.7424	nan	0.1000	0.0049	
##	100	0.6803	nan	0.1000	0.0021	
##	120	0.6257	nan	0.1000	0.0019	
##	140	0.5809	nan	0.1000	0.0014	
##	150	0.5615	nan	0.1000	0.0020	
<pre>pmlValgbm <- predict(pmlModelgbm, newdata=pmlValidation)</pre>						
<pre>gbmAccuracy <- confusionMatrix(factor(pmlValgbm, levels =</pre>						
<pre>pmllevels), factor(pmlValidation\$classe, levels =</pre>						

```
pmllevels))$overall['Accuracy']
```

Prediction with Linear Discriminate Analysis

```
pmlModellda <- train(classe~., data = pmlTraining, method="lda", preProcess =</pre>
"pca", na.action = na.omit, trControl = fitControl)
pmlVallda <- predict(pmlModellda, newdata=pmlValidation)</pre>
ldaAccuracy <- confusionMatrix(factor(pmlVallda, levels =</pre>
pmllevels),factor(pmlValidation$classe, levels =
pmllevels))$overall['Accuracy']
```

Prediction with Naive Bayes

```
pmlModelnb <- train(classe~., data = pmlTraining, method="nb", preProcess =</pre>
"pca", na.action = na.omit, trControl = fitControl)
pmlValnb <- predict(pmlModelnb, newdata=pmlValidation)</pre>
nbAccuracy <- confusionMatrix(factor(pmlValnb, levels =</pre>
```

```
pmllevels),factor(pmlValidation$classe, levels =
pmllevels))$overall['Accuracy']
```

Results

The below table summarizes the results of running 5 different techniques to predict "classe". Random Forest and Boosting with Trees offered the highest accuracy; where **0.9771615**, **0.8162724** are their accuracies respectably. Trees has highest accuracy, but it could be over fitting, therefore, it was selected Boosting with Trees to be used with test data set.

```
results <- matrix(c(rpAccuracy, rfAccuracy, gbmAccuracy, ldaAccuracy,</pre>
nbAccuracy), nrow=5, ncol=1)
row.names(results) <- c("Trees", "Random Forests", "Boosting with Trees",</pre>
"Linear Discriminate Analysis", "Naive Bayes")
resultstable <- as.table(results)</pre>
colnames(resultstable)<-c("Accuracy")</pre>
resultstable
##
                                   Accuracy
## Trees
                                  0.4023246
## Random Forests
                                  0.9771615
## Boosting with Trees
                                  0.8162724
## Linear Discriminate Analysis 0.5320147
## Naive Bayes
                                  0.6358075
```

Using Model with Test Dataset

The below table summarizes the predictions for each "problem ID" in the test data set