

**Experiment 9****SPI Protocol**

The objective of this experiment is to get familiar with establishing the serial communication between the STM32 microcontroller board and the Arduino Uno board using SPI Protocol. STM32 has **1 or more SPI bus** in it while Arduino Uno has **one SPI bus** so that it makes the communication possible between them. In this experiment we use STM32F303RE as Master and Arduino Uno as Slave to blink the LED which is connected with Arduino Uno.

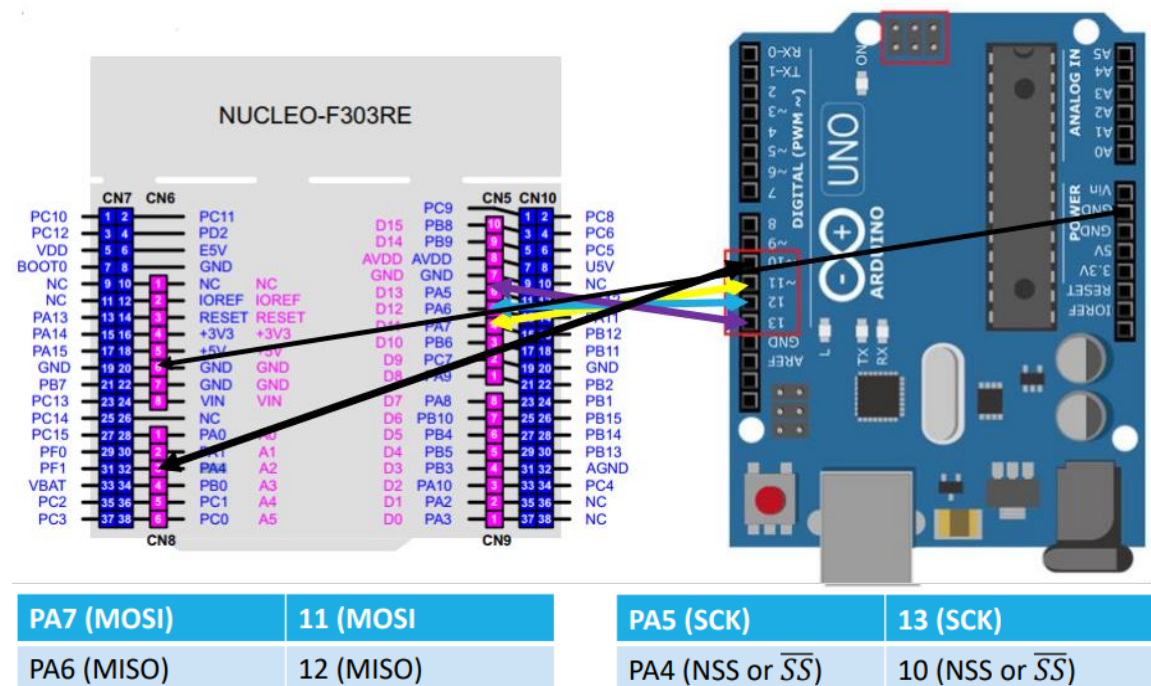
**Working of SPI:**

A SPI has a master/Slave communication by using four lines. A SPI can have only one master and can have multiple slaves. A master is usually a microcontroller and the slaves can be a microcontroller, sensors, ADC, DAC, LCD etc. To start communication between master and slave we need to set the Slave Select (SS) pin to LOW, so that it can communicate with the master. When it's high, it ignores the master. This allows you to have multiple SPI devices sharing the same MISO, MOSI, and CLK lines of master.

**Components and Software applications required:**

**Components:** Arduino Uno board, STM32F303RE board, LED, USB Cables and connecting wires.

**Software applications:** STM32CubeIDE and Arduino IDE.

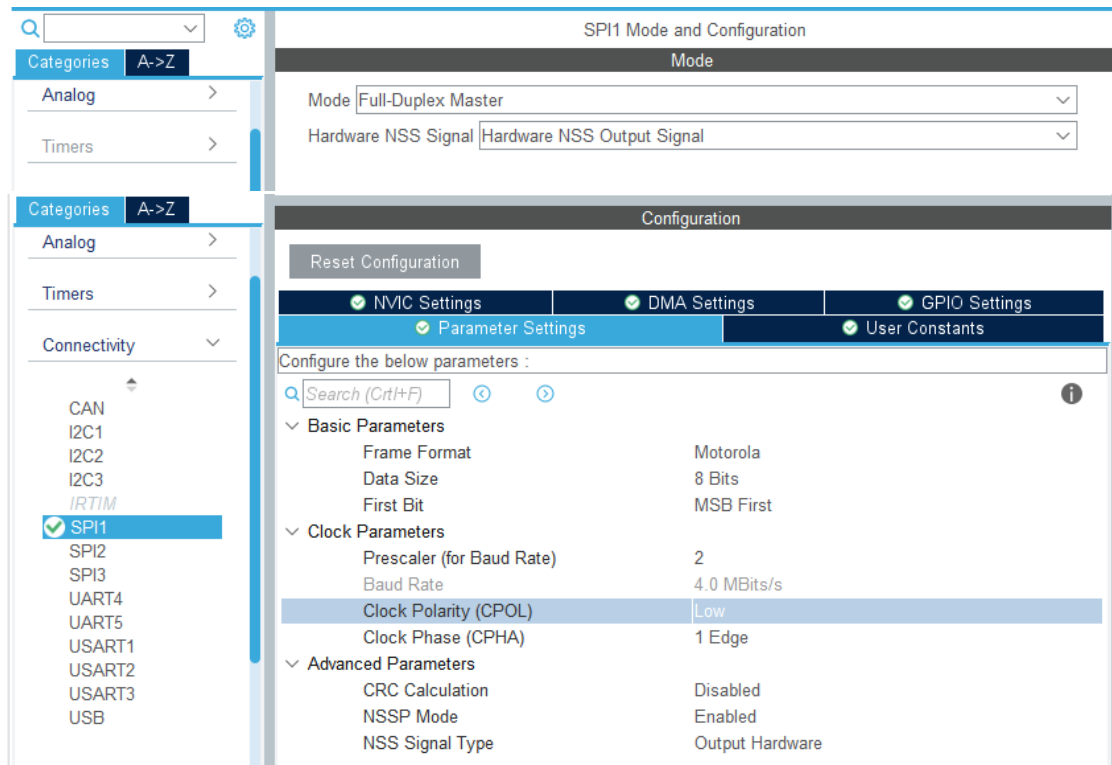
**Circuit Connection Diagram:****Section: 01 Steps to program the Arduino Uno board**

1. Open Arduino IDE and create the new file.
2. Select the serial port by clicking **Tools** → **Port** → **COMx (Arduino Uno)**
3. Write the program for blinking the LED as the program pasted below.
4. Save the file and compile (with no errors) then upload.

## Section: 02 Steps to program the STM32F303RE board

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5. Select **SPI1** from pinout and configuration pane and do the following settings as depicted in below image.




6. After doing the above mentioned settings, generate the code and add the followings in the main.c file. ( Under PV and BEGIN 3)

```

45  /* USER CODE BEGIN PV */
46  uint8_t pTxData = 1;
47  uint16_t Size = 1;
48  int count = 0;
49  /* USER CODE END PV */
98  /* USER CODE BEGIN WHILE */
99  while (1)
100 {
101     /* USER CODE END WHILE */
102
103     /* USER CODE BEGIN 3 */
104     HAL_SPI_Transmit(&hspi1, &pTxData, Size, 100);
105     if(count==0)
106     {
107         pTxData = 0;
108         HAL_Delay(1000);
109         count = 1;
110     }
111     else
112     {
113         count = 0;
114         pTxData = 1;
115         HAL_Delay(1000);
116     }
117 }
118 /* USER CODE END 3 */

```

7. Save and debug the program then click on Run. 
8. Open the Serial Monitor window in the Arduino IDE and observe the LED blinking status.

```
COM6
LED is ON
Master STM32 to Slave Arduino: Data is -> 0
LED id OFF
Master STM32 to Slave Arduino: Data is -> 1
LED is ON
Master STM32 to Slave Arduino: Data is -> 0
LED id OFF
Master STM32 to Slave Arduino: Data is -> 1
LED is ON
Master STM32 to Slave Arduino: Data is -> 0
LED id OFF
Master STM32 to Slave Arduino: Data is -> 1
LED is ON
Master STM32 to Slave Arduino: Data is -> 0
LED id OFF
Master STM32 to Slave Arduino: Data is -> 1
LED is ON
Master STM32 to Slave Arduino: Data is -> 0
LED id OFF
Master STM32 to Slave Arduino: Data is -> 1
LED is ON
```

**NOTE:**

- There should have common ground (GND) connection between mater and slave devices.
- Clock polarity and clock phase of master and slave must be same.
- Frequency of the generated clock by master for SPI communication must be less than or equal to half of the slave's core clock frequency.