

A Mini Project Report on

Activity Selection Problem

for the subject

Design and Analysis of Algorithms

By

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STUDENT'S NAME DIKCHA SINGH (RAZO11027010096)	Topics Covered • Rublem Definition • General Technique • Design Technique • Real-life applications
K. SANTHANA LAKSHMI (RA2011027010129)	 Explanation of algorithm Steps of algorithm Code Output
ROSHANA S V (RA2011027010074)	 Puoble m explanation with diagram Complexity Analysis Conclusion Reference

ACTIVITY SELECTION ROBLEM

The Activity Selection Buoblem is an optimization buoblem which deals with the selection of non-conflicting activities that needs to be executed by a single penson on machine in a given time trame.

Each activity is marked by a start and finish time. Greedy technique is used for finding the solution since this is an optimization problem.

PROBLEM DEPINITION:

Given are n activities with their start and finish times, the objective is to find solution set having maximum number of non conflicting activities that can be executed in a single time frame, assuming that only one person or machine is available for execution.

Some points to note here:

It might not be possible to complete all the activities, since their timings can collapse.

Two activities, say i and j, are said to be non-conflicting if si>= fj on sj>= fi where si and sj denote the starting time of activities i and j respectively, and fi and fj refer to the finishing time of the activities i and j respectively.

DESIGN TECHNIQUE :-

Our problem statement uses a greedy algorithm to get the best optimal solution. A greety algorithm is an approach for solving a problem by selecting the best option available at the moment. It doesn't wown whether the current best result will bring the overall optimal result. The algorithm never reserves the earlier decision even if the choice is wrong. It works in a top-down approach. Greedy approach can be used to find the solution since we want to maximize the court of activities that can be executed. This approach will greedily choose an activity with earliest finish time at every step, thus yielding an optimal solution.

REAL-LIFE APPLICATIONS:-

Following are some of the real-life applications of this problem!

- Scheduling multiple competing events in a moon,
 such that each event has its own stant and end time.
- · Scheduling manufacturing of multiple products on the same machine, such that each product has its own production timelines.
 - Activity selection is one of the most well-known geneur bublems used in operations nesearch ton dealing with neal-life buisness publems. In automated programs and the coordination of these programs is done with the activity scheduling publem with in turn helps in snooth completion

of the automated task like in data analysis.

ALGORITHM:-

INPUT DATA

- · act [] Array Containing all the activities.
- · SIJ array Containing the Starting time
- . It I away Containing the finishing time.

OUTPUT DATA

· Solly among referring to the Asolution set Containing the maximum number of non conflicting activities.

ALGORITHM STEPS:

Step 1:- Sort the given activities in ascending Order according to their finishing time.

Step 2: - Select the first activity from sorted array act [] and add it to sol [] array.

Step 3:- Repeat Steps 4 and 5 for the Memoining activities in act [].

Step 4: - If the start time of the Currently Selected activity is greater than or equal to Sinish time of Previously selected activity, then add it to the solt of array.

Step 5: - Select the next activity in act []
array.

Step b :- Parint the sol [] away.

- . Initially anti
- · Bort the an [] ascerding order to finish
 - . Print first activity and make 1-0
 - · Start [i] >= finish [i]

 Make i='s itt
 - · Start [j] < finish [i], '1++
 - · Star [i] >= finish [i]

 Make i= 1, 1++
 - · Make i=i, H+, an []
 - · Start [i] < finish [i], On[]

CODE : the include obits /side+1. hs thing namespace std: define N6 /defines the number of activities Smucture represents an activity having stead time and finish the Struct Nethelby & int Start finish; This function is used for booting activities according to finish time bod Soll- activity (Activity SI, Activity 52) 5 Yeturan (Si. finish < So. finish) Print maximum number of activities done by shingle Person or single machine at a time. oid Annt-Hax_Activities (Activity antz int n) { // Sort activities according to finish time Sort (an, an+n, son_ activity). Court << "Following activities are selected in"):

11 select the first activity int 1:0; Cout << "("<< an [:]. Start <<", "<< an [:]. finish K") \n"; // Consider the Memaining activities from 1 to n-1 3 (+H ; n > L; 1= L + H) rot // Select activity if Istoratione greater than a equal to finish time if (am [i]. Most >= am [i]-finish] } Caut << "(" < can [i]. Start = "; " < can [i]. finish = ") h". Moniver Program int main () { YCHININ ON [N]: for (int i = 0; i<= N-1; i++) { Cast << "Enter the start and end time of "<< i+1<< " activity In"; Cin >> an Eig. Start >> an Eig. finish; 4

```
Parint_Max_Activities (an, N);
Yetum 0;
3
OUTPUT:-
```

Enter the star and end time of 1 activity 5 9 Enter the start and end time of 2 activity Enter the start and end time of 3 activity Enter the start and end time of 4 activity Enter the start and end time of 5 activity Enter the start and end time of 6 activity Following activities are selected (1, 2) (3,4) (5,7)

(8.8)

EXPLANATION OF ALGIORITHM WITH EXAMPLE: Consider the table given, here 6 activities with corresponding start and end time, the objective is to compute an execution schedule having maximum number of nonconflicting activities. Start 3 0 5 8 Time (s) Finish 7 ime (4) 9 Activity al a2 a4 a5 a6 1) sort the given activities in ascending order according to their finishing time. Start

Start
Time (s) 1 3 0 5 5 8

Finish
Time (f) 2 4 6 7 9 9

Activity
Name a2 a3 a4 a5 a1 a6

2) Follow the steps 2,3,4 and 5 given in the algorithm. So, for the data given in the above table,

3 Select activity a3. Since start time of a3 is greater than a2's finish time.

ie, & Ca3) > f(a2)

9

So we add as to the solution set, sal= {a2, a33 - Select a4, s(a4) < f(a3), so it is not added to the solution set. - Select a5, Since here s(a5) > f(a3), it is added to the solution set, sol = {a2, a3, a5} → select a1, as s(a1) < f(a5), a1 is not added to the solution set. > Select a6. a6 is added to the solution set as & C6) > f(a5). Thus, the solution set, sol = {a2, a3, a5, a6 }. At last print the array sol[]. Hence the execution schedule of maximum DUTPUT: 11 02 (1,2) the start and finish (3,4) 11 a 3 time of the activities (5, 4) 11 05 in the solution set (8,9)

1106

is printed.

0 1 2 3 4 5 6 7 8 9 Timeline In the above diagram, selected activity are shaded. TIME COMPLEXITY ANALYSIS: Case 1: When a given set of activities are sorted according to finishing time already, so in such a case no sorting mechanism involved, thence complexity of the algorithm will be OCn). Case 2: When a given set of activities is unsorted, in such a case we will have to include the sort () function defined for sorting activities list Chits/stdc++ header file). So, the time complexity of this method will be OCnlogn), which also defines the complexity of the algorithm.

CONCLUSION: Thus the activity selection problem was explained and executed successfully. REFERENCE : >https://www.studytonight.com/data-structres/ activity-selection-problem. -shttps://youtu.be/trwipswztQr4 -> Activity Selection Problem Cusing Greedy Method) → https://youtu.be/NE5erdkdrck → Grady Algorithm: Activity Selection Problem with example. → Book ALGIORITHMS

Introduction to ALGORITHMS

(Third Edition), Thoms H. Cormen,

Charles E. Leiserson,

Ronald L. Rivest,

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