CAR PARKING SYSTEM USING IOT

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DEVELOPMENT PART 2

APP: FIRST STEP CREATE BROKER



Hey there. Welcome!

The app is ready for you! To begin, I would suggest you to add your first broker.

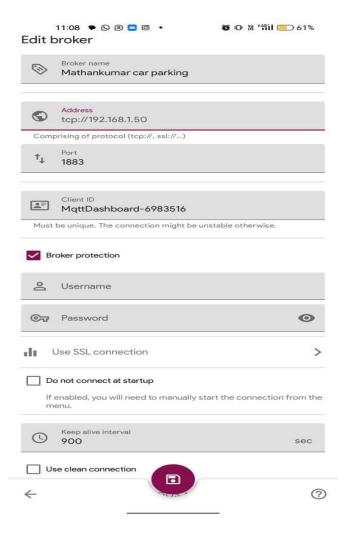
ADD FIRST BROKER

Restore backup

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STEP 2:EDIT BROKER



STEP 3:



PROGRAM:

#!/usr/bin/python

import time

import RPi.GPIO as GPIO

import time

import os,sys

from urllib.parse import urlparse

import paho.mqtt.client as paho

GPIO.setmode(GPIO.BOARD)

GPIO.setwarnings(False)

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define pin for lcd

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Timing constants

E_PULSE = 0.0005

E_DELAY = 0.0005

delay = 1

Define GPIO to LCD mapping

$$LCD_RS = 7$$

LCD_D4 = 12

LCD_D5 = 13

LCD_D6 = 15

LCD_D7 = 16

slot1_Sensor = 29

slot2_Sensor = 31

GPIO.setup(LCD_E, GPIO.OUT) # E

GPIO.setup(LCD_RS, GPIO.OUT) # RS

GPIO.setup(LCD_D4, GPIO.OUT) # DB4

GPIO.setup(LCD_D5, GPIO.OUT) # DB5

GPIO.setup(LCD_D6, GPIO.OUT) # DB6

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GPIO.setup(LCD_D7, GPIO.OUT) # DB7
GPIO.setup(slot1_Sensor, GPIO.IN)
GPIO.setup(slot2_Sensor, GPIO.IN)
# Define some device constants
LCD_WIDTH = 16 # Maximum characters per line
LCD_CHR = True
LCD_CMD = False
LCD_LINE_1 = 0x80 # LCD RAM address for the 1st line
LCD_LINE_2 = 0xC0 # LCD RAM address for the 2nd line
LCD_LINE_3 = 0x90# LCD RAM address for the 3nd line
def on_connect(self, mosq, obj, rc):
    self.subscribe("Fan", 0)
def on_publish(mosq, obj, mid):
  print("mid: " + str(mid))
mqttc = paho.Client()
                                 # object declaration
# Assign event callbacks
mqttc.on_connect = on_connect
mqttc.on_publish = on_publish
url_str = os.environ.get('CLOUDMQTT_URL', 'tcp://broker.emqx.io:1883')
url = urlparse(url_str)
mqttc.connect(url.hostname, url.port)
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Function Name :lcd_init()
Function Description: this function is used to initialized lcd by sending the different
commands
def lcd_init():
# Initialise display
lcd_byte(0x33,LCD_CMD) # 110011 Initialise
lcd_byte(0x32,LCD_CMD) # 110010 Initialise
lcd_byte(0x06,LCD_CMD) # 000110 Cursor move direction
lcd_byte(0x0C,LCD_CMD) # 001100 Display On,Cursor Off, Blink Off
lcd_byte(0x28,LCD_CMD) # 101000 Data length, number of lines, font size
lcd_byte(0x01,LCD_CMD) # 000001 Clear display
time.sleep(E_DELAY)
Function Name :lcd_byte(bits ,mode)
Fuction Name : the main purpose of this function to convert the byte data into bit and send
to lcd port
def lcd_byte(bits, mode):
# Send byte to data pins
# bits = data
# mode = True for character
# False for command
GPIO.output(LCD_RS, mode) # RS
# High bits
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GPIO.output(LCD_D4, False)
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GPIO.output(LCD_D7, False)

if bits&0x10==0x10:

GPIO.output(LCD_D4, True)

if bits&0x20==0x20:

GPIO.output(LCD_D5, True)

if bits&0x40==0x40:

GPIO.output(LCD_D6, True)

if bits&0x80==0x80:

GPIO.output(LCD_D7, True)

Toggle 'Enable' pin

lcd_toggle_enable()

Low bits

GPIO.output(LCD_D4, False)

GPIO.output(LCD_D5, False)

GPIO.output(LCD_D6, False)

GPIO.output(LCD_D7, False)

if bits&0x01==0x01:

GPIO.output(LCD_D4, True)

if bits&0x02==0x02:

GPIO.output(LCD_D5, True)

if bits&0x04==0x04:

GPIO.output(LCD_D6, True)

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if bits&0x08 = 0x08:
  GPIO.output(LCD_D7, True)
# Toggle 'Enable' pin
lcd_toggle_enable()
Function Name : lcd_toggle_enable()
Function Description:basically this is used to toggle Enable pin
def lcd_toggle_enable():
# Toggle enable
time.sleep(E_DELAY)
GPIO.output(LCD_E, True)
time.sleep(E_PULSE)
GPIO.output(LCD_E, False)
time.sleep(E_DELAY)
Function Name :lcd_string(message,line)
Function Description :print the data on lcd
def lcd_string(message,line):
# Send string to display
message = message.ljust(LCD_WIDTH," ")
lcd_byte(line, LCD_CMD)
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for i in range(LCD_WIDTH):
  lcd_byte(ord(message[i]),LCD_CHR)
lcd_init()
lcd_string("welcome ",LCD_LINE_1)
time.sleep(0.5)
lcd_string("Car Parking ",LCD_LINE_1)
lcd_string("System ",LCD_LINE_2)
time.sleep(0.5)
lcd_byte(0x01,LCD_CMD) # 000001 Clear display
# Define delay between readings
delay = 5
while 1:
# Print out results
rc = mqttc.loop()
slot1_status = GPIO.input(slot1_Sensor)
time.sleep(0.2)
slot2_status = GPIO.input(slot2_Sensor)
time.sleep(0.2)
if (slot1_status == False):
 lcd_string("Slot1 Parked ",LCD_LINE_1)
 mqttc.publish("slot1","1")
 time.sleep(0.2)
 else:
  lcd_string("Slot1 Free ",LCD_LINE_1)
  mqttc.publish("slot1","0")
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if (slot2_status == False):
lcd_string("Slot2 Parked ",LCD_LINE_2)
mqttc.publish("slot2","1")
time.sleep(0.2)
else:
lcd_string("Slot2 Free ",LCD_LINE_2)
mqttc.publish("slot2","0")
time.sleep(0.2)
```