Boxic type of oreating wing lambda layer.

tf.keras.layers.Lambda(lambda x: tf.abs(x))

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```

 $\label{eq:total_label} \textit{tf.keras.layers.Lambda(lambda x: tf.abs(x))} \\ \textit{tf.keras.layers.Lambda(lambda x: tf.abs(x))} \\$

```
model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(input_shape=(28, 28)),
    tf.keras.layers.Dense(128, activation='relu'),
    tf.keras.layers.Dense(10, activation='softmax')
])
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  tf.keras.layers.Dense(10, activation='softmax')
                                          if(x>0):
                                              return x
                                          else:
                                              return 0
```

```
Epoch 1/5
accuracy: 0.9262
Epoch 2/5
accuracy: 0.9662
Epoch 3/5
accuracy: 0.9760
Epoch 4/5
accuracy: 0.9820
Epoch 5/5
accuracy: 0.9862 /
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```

Epoch 1/5

```
Epoch 1/5
accuracy: 0.8984
Epoch 2/5
accuracy: 0.9170
Epoch 3/5
accuracy: 0.9192
Epoch 4/5
accuracy: 0.9205
Epoch 5/5
accuracy: 0.9227
accuracy: 0.9154
```

```
accuracy: 0.8984
Epoch 2/5
accuracy: 0.9170
Epoch 3/5
accuracy: 0.9192
Epoch 4/5
                         ←] - 4s 2ms/step - loss: 0.2821 -
1875/1875 [==========
                     nuived one and see the performance
accuracy: 0.9205
Epoch 5/5
                   -======] - 3s 2ms/step - loss: 0.2<mark>763</mark> -
1875/1875 [==========\pei=====
accuracy: 0.9227
               ========== ] - 0s 1ms/step - loss: 0.3031 -
313/313 [========
accuracy: 0.9154
```

Epoch 1/5

model = tf.keras.models.Sequential([novo, we added the Courbolo contour Danger wind the Courtour and quemorsed the tf.keras.layers.Flatten(input_shape=(28, 28)), tf.keras.layers.Dense(128), tf.keras.layers.Lambda(lambda x: tf.abs(x)), tf.keras.layers.Dense(10, activation='softmax')])



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```

])

```
accuracy: 0.9377
Epoch 2/5
accuracy: 0.9734
Epoch 3/5
accuracy: 0.9807
Epoch 4/5
1875/1875 [=======
accuracy: 0.9875
accuracy: 0.9751
```

Epoch 1/5

```
1875/1875 [=================]
                       4s 2ms/step
                               loss: 0.2229 -
accuracy: 0.9377
Epoch 2/5
                               loss: 0.0908 - Jul
3s 2ms/step
accuracy: 0.9734
Epoch 3/5
                               loss: 0.0636 -
3s 2ms/step
accuracy: 0.9807
Epoch 4/5
loss: 0.0471 -
                       4s 2ms/step
accuracy: 0.9853
Epoch 5/5
loss: 0.0396 -
accuracy: 0.9875
accuracy: 0.9751
```

Epoch 1/5

```
def my_relu(x):
  return K.maximum(0.0, x)
model = tf.keras.models.Sequential()
  tf.keras.layers.Flatten(input_shape=(28, 28)),
  tf.keras.layers.Dense(128),
  tf.keras.layers.Lambda(my_relu),
  tf.keras.layers.Dense(10, activation='softmax')
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Some commonly used layers

Convolutional

Conv1D/Conv2D/Conv3D

SeparableConv2D

DepthwiseConv2D

Merge

Add

Subtract

Multiply

Recurrent

LSTM

GRU

Activations (Advanced)

LeakyReLU

PReLU

ELU

Pooling

MaxPooling2D

AveragePooling2D

GlobalAveragePooling2D

Core

Activation

Lambda

Input

Dense

Dropout

BatchNormalization

Some commonly used layers

Convolutional

Conv1D/Conv2D/Conv3D

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LeakyReLU

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ELU

Pooling

MaxPooling2D

AveragePooling2D

GlobalAveragePooling2D

Core

Activation

Lambda

Input

Dense

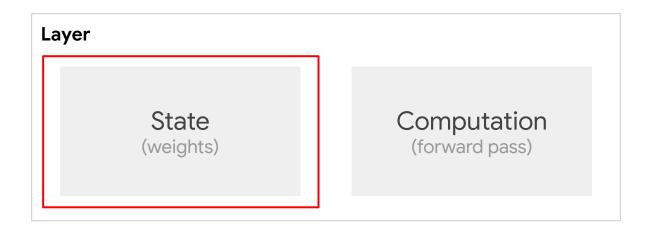
Dropout

BatchNormalization

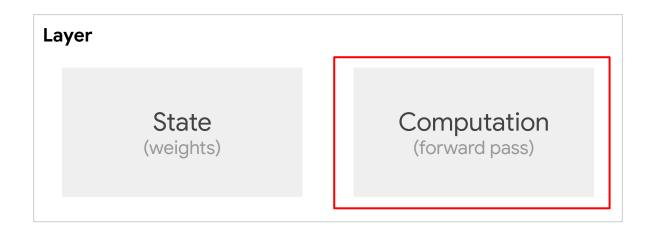
What is a Layer?

Color that the date of the date of the advice for purpose returns the advice purpose returns the advice of the Layer State Computation (weights) (forward pass)

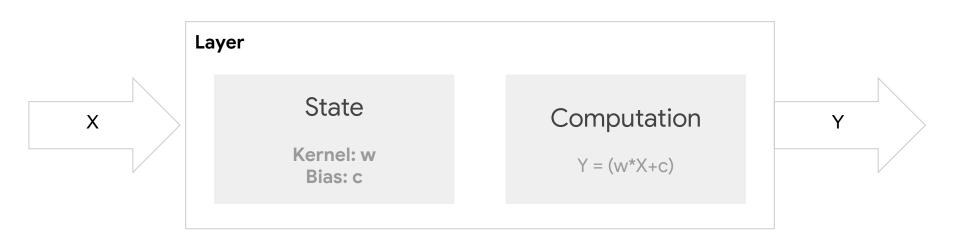
What is a Layer?

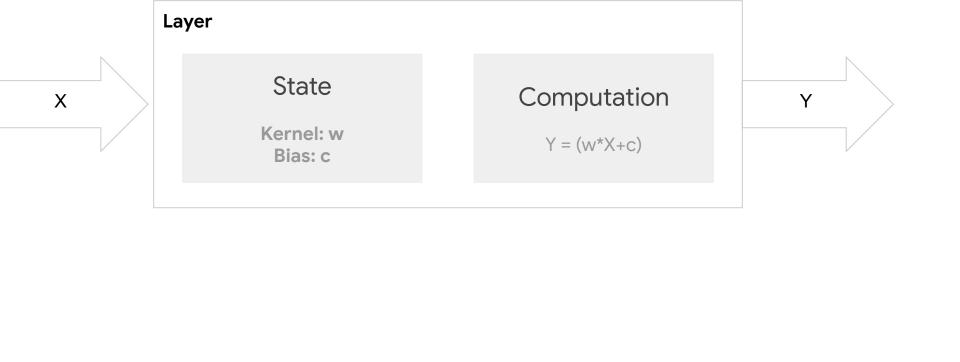


What is a Layer?



Simple Dense Layer





```
def __init__(self, units=32):
    super(SimpleDense, self).__init__()
    self.units = units
def build(self, input_shape): # Create the state of the layer (weights)
 w_init = tf.random_normal_initializer()
  self.w = tf.Variable(name="kernel",
      initial_value=w_init(shape=(input_shape[-1], self.units), dtype='float32'),
      trainable=True)
  b_init = tf.zeros_initializer()
  self.b = tf.Variable(name="bias",
      initial_value=b_init(shape=(self.units,), dtype='float32'),
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def call(self, inputs): # Defines the computation from inputs to outputs
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```

```
def call(self, inputs): # Defines the computation from inputs to outputs
    return tf.matmul(inputs, self.w) + self.b
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initial_value=b_init(shape=(self.units,), dtype='float32'),

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self.b = tf.Variable(name="bias",

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                     Low your gonameters
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      initial_value=b_init(shape=(self.units,), dtype='float32'),
      trainable=True)
def call(self, inputs): # Defines the computation from inputs to outputs
    return tf.matmul(inputs, self.w) + self.b
```

```
my_dense = SimpleDense(units=1)
x = tf.ones((1, 1))
y = my_dense(x)
print(my_dense.variables)
```

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x = tf.ones((1, 1))
y = my_dense(x)
print(my_dense.variables)
  [<tf.Variable 'simple_dense_7/kernel:0' shape=(1, 1)</pre>
```

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```

```
[<tf.Variable 'simple_dense_7/kernel:0' shape=(1, 1)
dtype=float32, numpy=array([[0.03688493]], dtype=float32)>,

<tf.Variable 'simple_dense_7/bias:0' shape=(1,)
dtype=float32, numpy=array([0.], dtype=float32)>]
```

```
my_dense = SimpleDense(units=1)
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y = my_dense(x)
print(my_dense.variables)
  [<tf.Variable 'simple_dense_7/kernel:0' shape=(1, 1)</pre>
```

import numpy as np

```
xs = np.array([-1.0, 0.0, 1.0, 2.0, 3.0, 4.0], dtype=float)
ys = np.array([-3.0, -1.0, 1.0, 3.0, 5.0, 7.0], dtype=float)
model = tf.keras.Sequential([SimpleDense(units=1)])
```

model.compile(optimizer='sgd', loss='mean_squared_error')
model.fit(xs, ys, epochs=500, verbose=0)
print(model.predict([10.0]))

Expected Answer: 19 (y=2x-1) Actual Answer: 0.36

(W = 0.036, B=0 => Y=.036 * 10 + 0 = 0.36)

```
Epoch 1/500
                                       0s 1ms/step - loss: 14.8152
Epoch 2/500
                                        0s 3ms/step - loss: 11.8951
Epoch 3/500
                                       0s 1ms/step - loss: 9.5928
Epoch 498/500
                                    - 0s 2ms/step - loss: 4.1124e-05
```

0s 2ms/step - loss: 4.0279e-05

- 0s 1ms/step - loss: 3.9452e-05

Epoch 499/500

Epoch 500/500

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```
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ys = np.array([-3.0, -1.0, 1.0, 3.0, 5.0, 7.0], dtype=float)
model = tf.keras.Sequential([SimpleDense(units=1)])
model.compile(optimizer='sgd', loss='mean_squared_error')
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```
[[18.981468]]
```

```
[<tf.Variable
'sequential_15/simple_dense_19/kernel:0' shape=(1, 1)
dtype=float32, numpy=array([[1.9972587]],
dtype=float32)>, <tf.Variable</pre>
'sequential_15/simple_dense_19/bias:0' shape=(1,)
dtype=float32, numpy=array([-0.991501],
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```

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                      specifying the activation lanting lanting
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class SimpleDense(Layer): def __init__(self, units=32, activation=None): self.units = units self.activation = tf.keras.activations.get(activation) Pris in spruse get the activation def call(self, inputs): return self.activation(tf.matmul(inputs, self.w) + self.b) that is normal for the printializer reduction feedown the activation activation activation

```
def __init__(self, units=32, activation=None):
    super(SimpleDense, self).__init__()
    self.units = units
    self.activation = tf.keras.activations.get(activation)
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return self.activation(tf.matmul(inputs, self.w) + self.b)

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def call(self, inputs):

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```
model = tf.keras.models.Sequential([
   tf.keras.layers.Flatten(input_shape=(28, 28)),
   SimpleDense(128, activation='relu'),
   tf.keras.layers.Dropout(0.2),
   tf.keras.layers.Dense(10, activation='softmax')
])
```

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