

Q1) Ans :- Fixed points satisfy  $\dot{N} = 0$

$$\sin\left(1 - \frac{N^x}{K}\right) = 0 \rightarrow 1$$

Hence,

$$N^* = 0$$

$$N^* = K^{1/x} \rightarrow \text{These are only fixed points.}$$

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Q2) Ans :- ① Equilibrium States :- Only when  $N(0)$  is exactly a fixed point ( $0 \text{ or } K^{1/x}$ ) is the rate of change exactly zero, meaning the population is at rest and will not change over time.

0.5 Mark  
Six → The population remains constant only when  $\dot{N} = 0$ , occurs only at Equilibrium points.

not a

fixed point. ~~Non-Equilibrium States~~

② Non-Equilibrium States :- Only when  $N(0)$  is exactly a fixed point, then  $f(N) \neq 0$ , so population must change with time.

Because of  $\frac{dN}{dt}$  = Velocity of the population change.  
Population does not remain constant for an arbitrary non-zero initial condition.

## Quiz-1 Marking Scheme: Set I, Question 2

### Question

For a scalar ordinary differential equation  $\dot{x} = f(x)$ , linearize the system about a fixed point  $x^*$  and derive the stability condition in terms of  $f'(x^*)$ .

### Solution

#### 1. Setup and Linearization

Let  $x^*$  be a fixed point such that  $f(x^*) = 0$ . Consider a small perturbation  $\eta(t)$  such that:

$$x(t) = x^* + \eta(t) \quad \text{where } |\eta| \ll 1$$

Differentiating with respect to time (since  $\dot{x}^* = 0$ ):

$$\dot{x} = \dot{\eta} = f(x^* + \eta)$$

Using the Taylor Series expansion about  $x^*$ :

$$\dot{\eta} = f(x^*) + f'(x^*)\eta + O(\eta^2)$$

Since  $f(x^*) = 0$  and we neglect higher-order terms ( $O(\eta^2) \approx 0$ ):

$$\dot{\eta} \approx f'(x^*)\eta$$

#### 2. Derivation of Stability

The linearized equation is  $\dot{\eta} = \lambda\eta$  where  $\lambda = f'(x^*)$ . The general solution is:

$$\eta(t) = \eta(0)e^{f'(x^*)t}$$

For the system to be stable, the perturbation  $\eta(t)$  must decay to 0 as  $t \rightarrow \infty$ . This requires the exponential term to decay.

#### 3. Condition

$$\lim_{t \rightarrow \infty} e^{f'(x^*)t} = 0 \iff f'(x^*) < 0$$

Thus, the fixed point is stable if  $f'(x^*) < 0$ .

### Marking Scheme (Total: 2 Marks)

#### 1. Linearization (1 Mark)

- 0.5 marks: for correctly applying the Taylor Series expansion:  $f(x^* + \eta) \approx f(x^*) + f'(x^*)\eta$ .
- 0.5 marks: for obtaining the correct linearized differential equation:  $\dot{\eta} = f'(x^*)\eta$  (or equivalent  $\dot{x} = f'(x^*)(x - x^*)$ ).
- *Deduction:* If the perturbation term  $\eta$  (or  $x - x^*$ ) is missing (i.e., writing  $\dot{x} = f'(x^*)$ ), award 0 marks for this section.

#### 2. Derivation of Condition (0.5 Marks)

- 0.5 marks: for showing the explicit time-dependent solution  $\eta(t) = \eta_0 e^{\lambda t}$  OR explicitly stating that the solution is exponential in nature, which justifies why the sign of the derivative matters.
- *Note:* Simply stating "slope is negative" without reference to time evolution/decay is insufficient for the Derivation mark.

### 3. Statement of Condition (0.5 Marks)

- 0.5 marks: for clearly stating the final stability criteria:
  - Stable if  $f'(x^*) < 0$ .
  - Unstable if  $f'(x^*) > 0$ .

## Common Errors & Deductions

- *The Second Derivative Error:* Using  $f''(x) < 0$  (concavity test) instead of  $f'(x) < 0$ . This is a fundamental conceptual error confusing optimization with dynamic stability. Score: 0 for the derivation and condition.
- *Missing Variable:* Writing  $\dot{x} = f'(x^*)$  (constant velocity) instead of  $\dot{x} = f'(x^*)(x - x^*)$ . This fails to describe a dynamic system.

## Note on Grading Appeals

The initial marking has been conducted with leniency. Please note the following regarding query submissions:

**Strict Re-evaluation:** If you decide to formally contest a grade or write a query, the question will be forwarded to the Professor's discretion for a final re-check. A formal re-check generally results in a more rigid application of the marking scheme than the initial grading.

**Conceptual Errors:** Fundamental errors, such as confusing the Second Derivative Test (calculus optimization) with Linear Stability Analysis (differential equations), will be marked strictly during a re-check.

**Process:** Submit queries formally through the designated form. Ensure that your query addresses a specific grading error rather than a general request for more marks.

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5.

Initialize  $N = N_0$

Initialize  $t = 0$

Choose time step  $dt$

while  $t < T_{final}$ :

$N = N + dt * r * N * (1 - N^{\alpha} / K)$

$t = t + dt$

0.5m      Identify  
=

State orthogonal transform preserves Euclidean  
norms

0.5m      Property

State and use  $Q^T Q = I$

1m      Proof

$$\|Q\alpha\|^2 = (\alpha^T)(Q^T)(Q\alpha) = \alpha^T Q^T Q\alpha = \alpha^T \alpha = \|\alpha\|^2$$



non-negotiable in proof.

Needs to be there in some

form