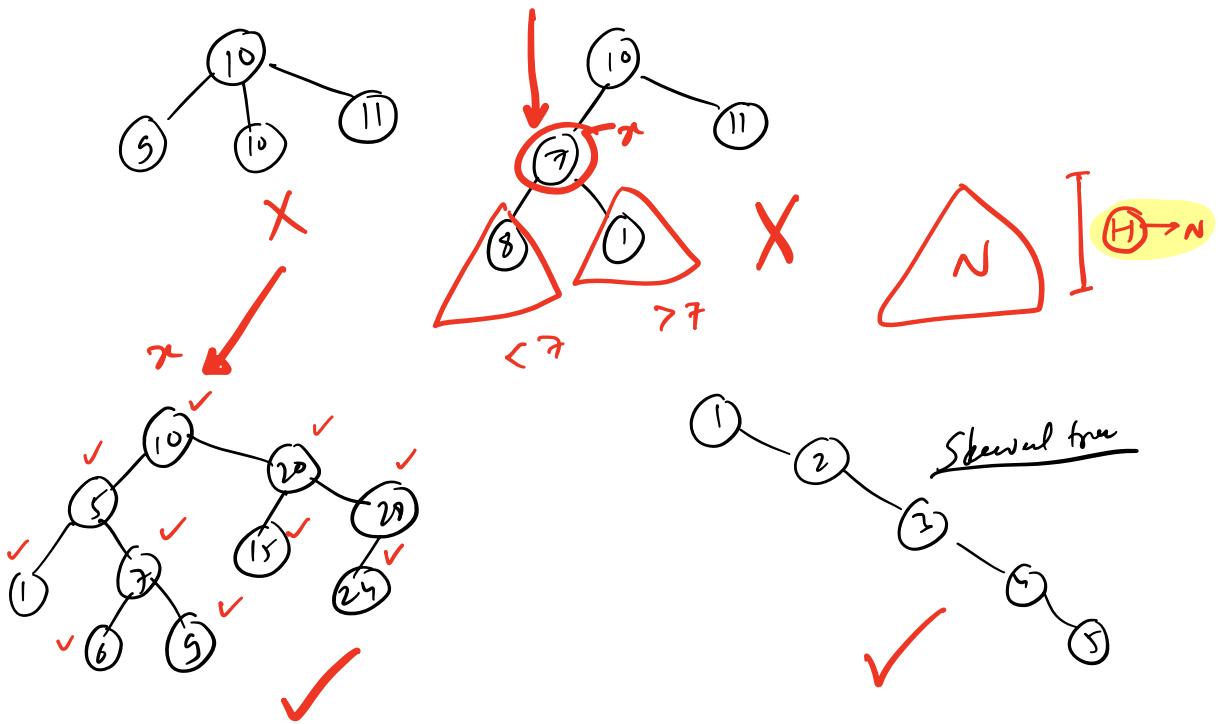
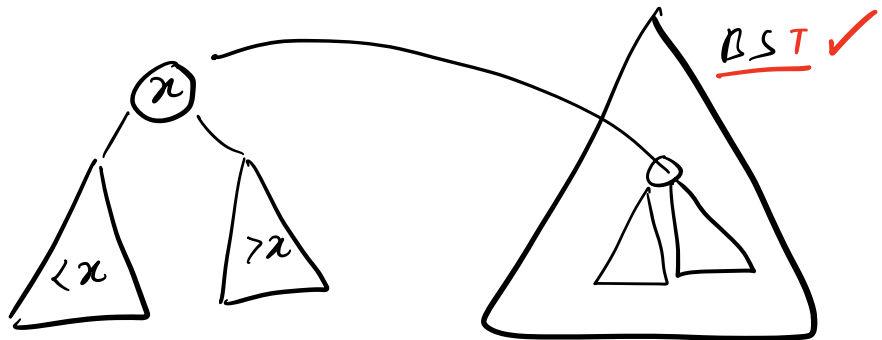


## BST [ Binary Search Tree ]

→ Binary tree

- Binary tree
- All elements in the LST of a node  $<$  node's val

→ RST



All on left < Node.val < All on right

Min on left < Node.val < Max on right

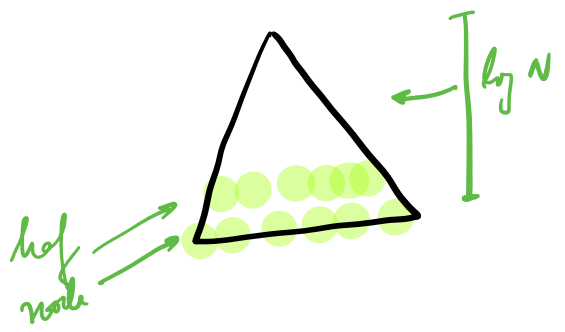
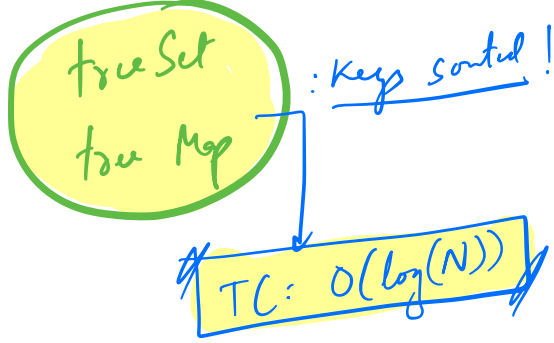
BST

< Balanced BST >

(Abs. diff. b/w the height of LST & RST  $\leq 1$  if nodes)

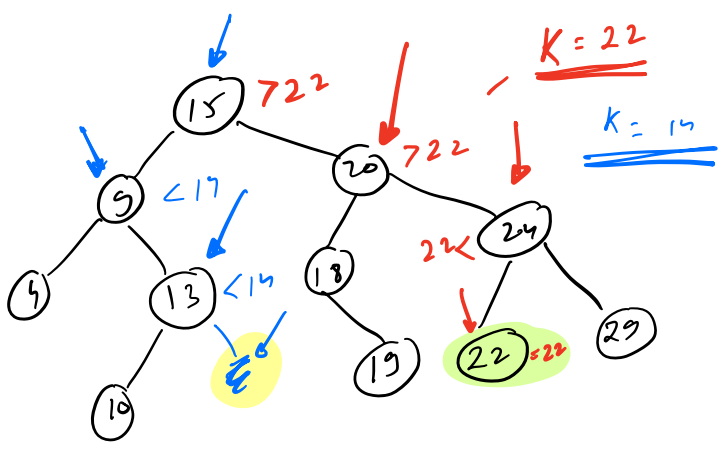
- Red Black tree
- AVL tree

$$H = O(\log N)$$



Normal BST

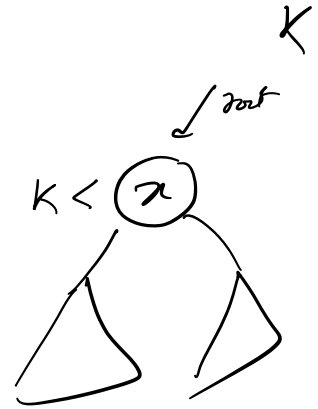
Searching



```

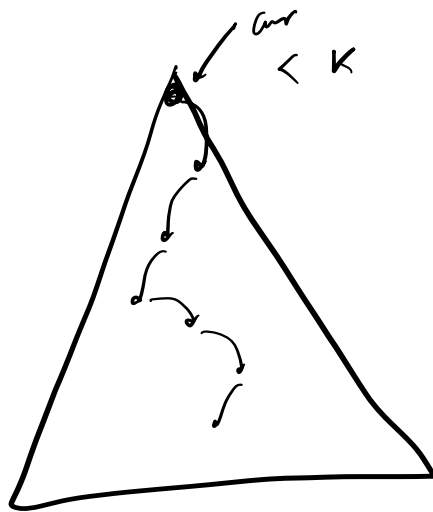
bool search (Node root, int k) {
    if (root == NULL) return false;
    if (root->data == k) return true;
    else if (root->data < k) {
        return search (root->right, k);
    }
    else {
        return search (root->left, k);
    }
}

```



$TC = O(H)$   
 $SC = O(1)$

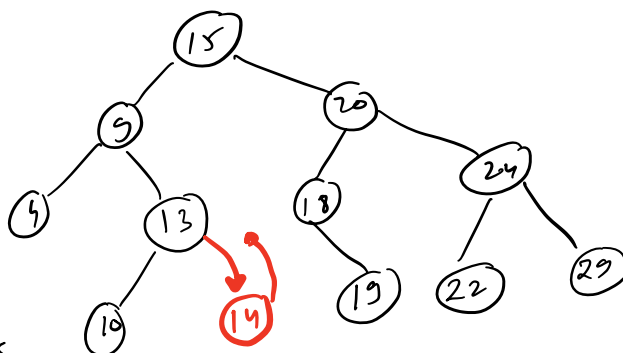
$O(1)$  : iterative code!



Q Given a BST & a val K.  
Insert K in the BST

K=13

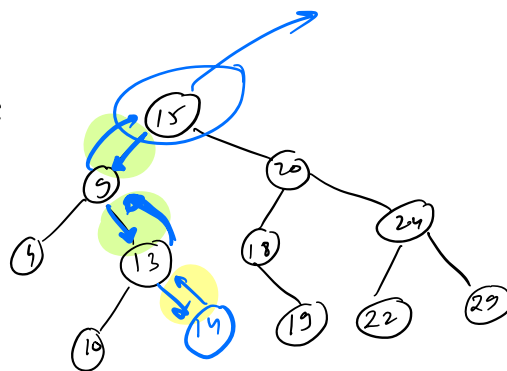
K=14



```
Node insert(Node root, int k) {
    if (root == NULL) {
        Node temp = new Node(k);
        return temp;
    }
```

```
    if (root.data < k) {
        root.right = insert(root.right, k);
    }
    else if (root.data > k) {
        root.left = insert(root.left, k);
    }
    return root;
}
```

K=14



TC = O(H)

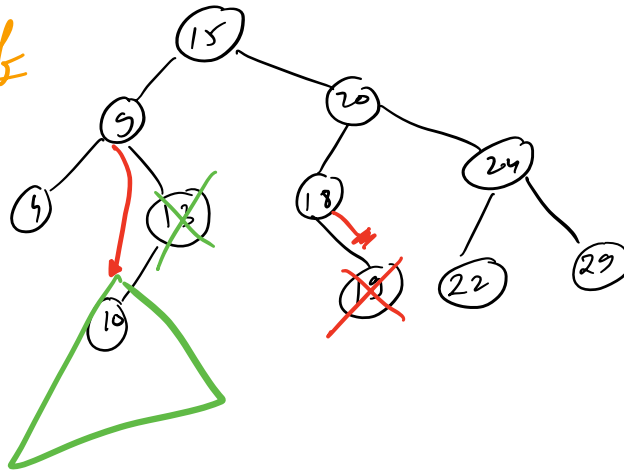
SC = O(H)

O(1)  
iterative

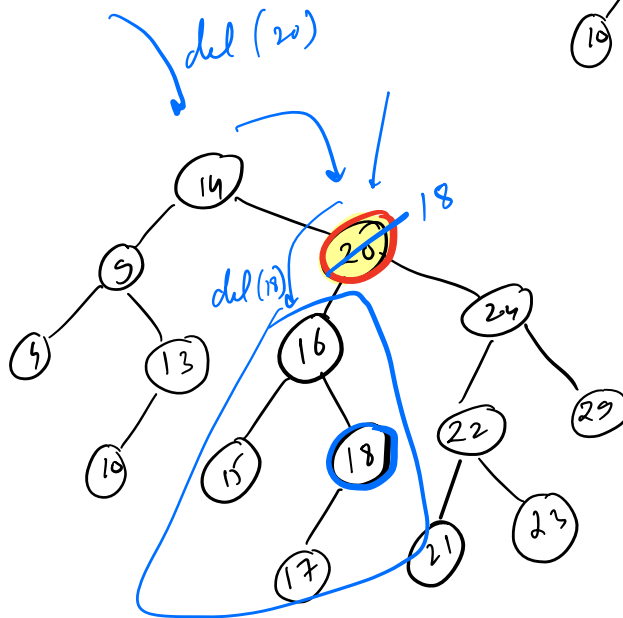
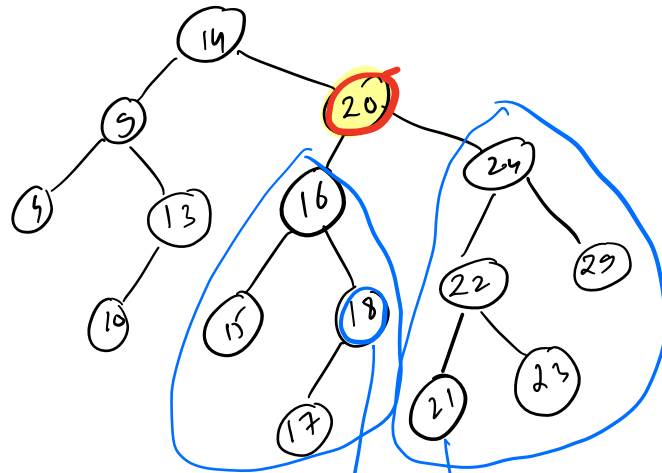
Q Given a BST & K. Del the node with val K

① del(19) | leaf  
18. right = NULL

① del(13) | 1 child



① del(20):



largest of LST  
or  
smallest of RST  
≤ 1 child

```
Node del (Node root, int k) {
```

```
    if (root == NULL) {
        return NULL;
    }
```

```
    if (root->data < k) {
        root->right = del(root->right, k);
    }
```

```
    else if (root->data > k) {
        root->left = del(root->left, k);
    }
```

```
}
```

```
else {
```

```
    if (root->left == NULL && root->right == NULL) {
        return NULL;
    }
```

```
    else if (root->left == NULL) {
        return root->right;
    }
```

```
    else if (root->right == NULL) {
        return root->left;
    }
```

```
}
```

```
else {
```

```
    q = findGreatest(root->left);
```

```
    root->data = q;
```

```
    root->left = del(root->left, q);
}
```

```
}
```

```
}
```

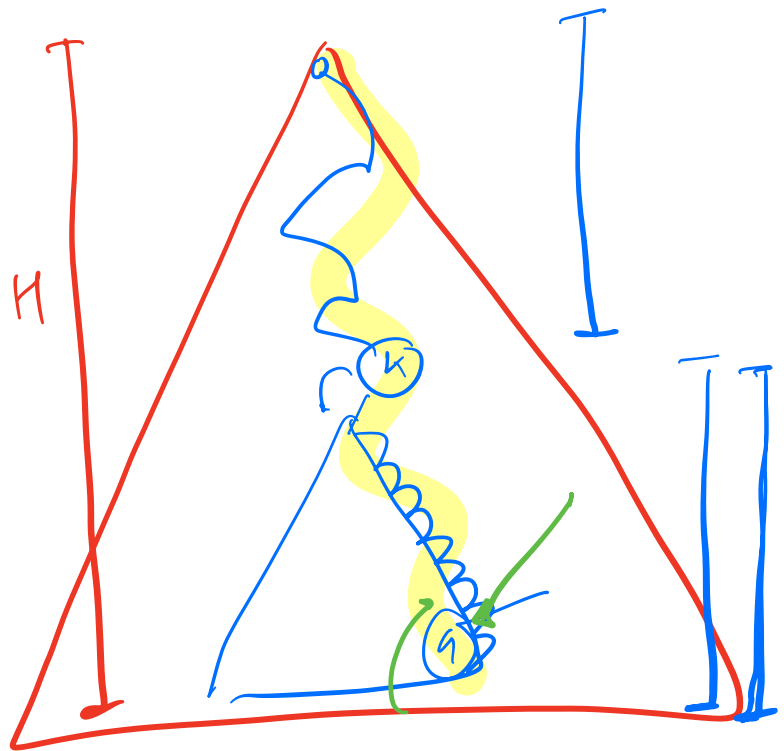


ret root;

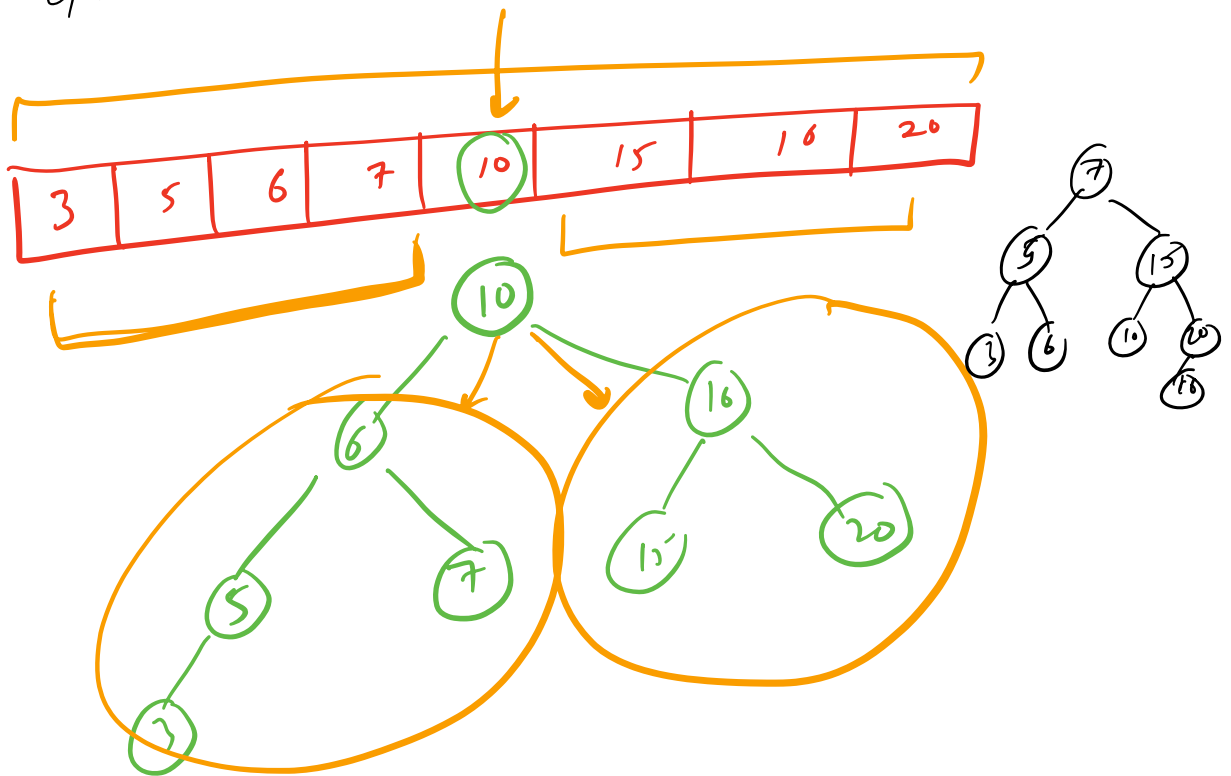
>  
 ~~$TC = O(H)$~~

~~$SC = O(H)$~~

$O(1)$   
iteration



Q Given a sorted array. Construct a BST from it!



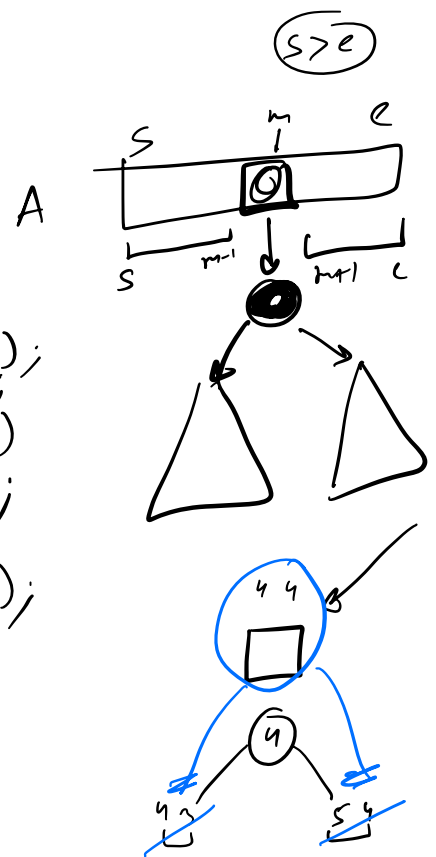
```

Node build ( A[], s, e ) {
    if ( s > e ) return NULL;
    m = (s+e)/2;
    Node root = new Node ( A[m] );
    root->left = build ( A[], s, m-1 );
    root->right = build ( A[], m+1, e );
    return root;
}

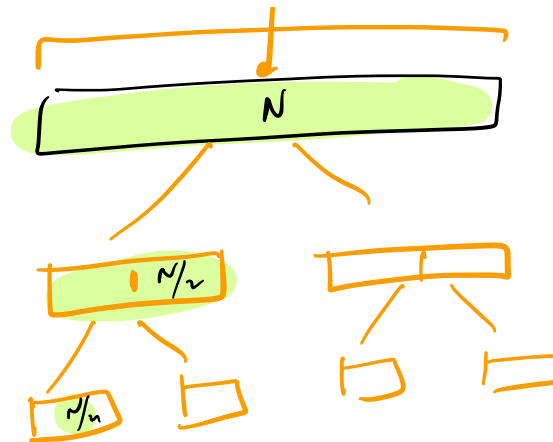
```

**TC =  $O(N)$**

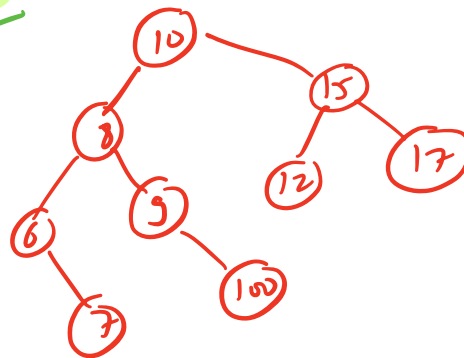
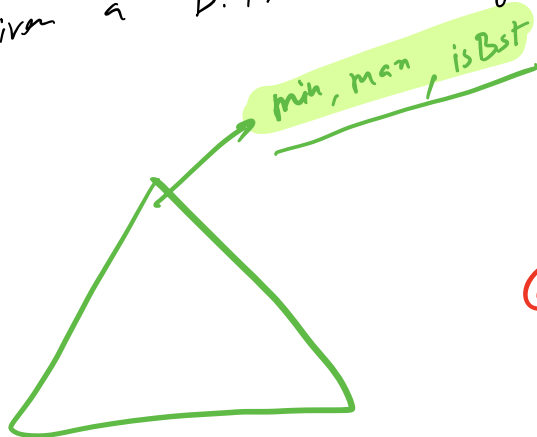
**SC =  $O(\log N)$**







Q Given a B.T. check if it is a BST!



```

In In {
  int maxV;
  int minV;
  int minV;
  bool isBst;
  bool isBst;
}

```

```

Info check (Node root) {
    if (root == NULL) {
        return Info (-∞, +∞, true);
    }
}

```

return check(root).isBst

return early!

```

    Info L = check (root.left);
    Info R = check (root.right);
    curMax = max (L.max, R.max, root.data);
    curMin = min (L.min, R.min, root.data);

```

```

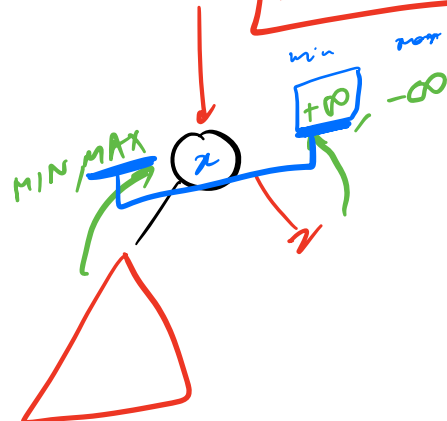
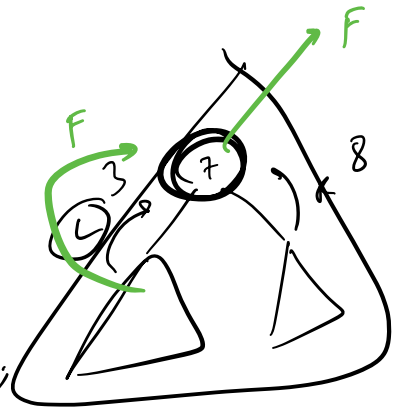
    curIsBst = (L.isBst == true &&
                R.isBst == true &&
                L.max < root.data && root.data < R.min);

```

```

    return Info (curMax, curMin, curIsBst);
}

```



TC = O(N)

SC = O(1)