



# Wind Farm Effects

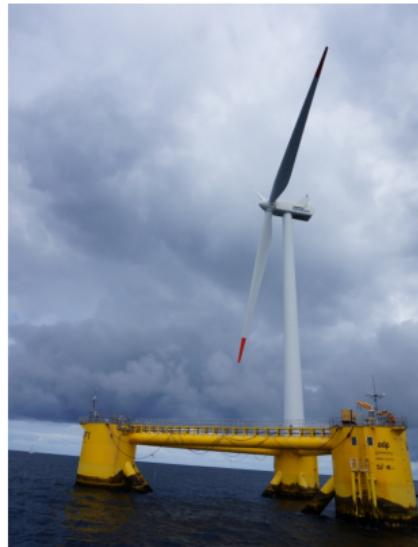
Prof. Dr.-Ing. David Schlipf  
Dr.-Ing. Steffen Raach

17.09.2024

Lecture #12  
Controller Design for  
Wind Turbines and Wind Farms

# Schedule

- 02.09. 1 Controller Design Objectives and Modeling
- 03.09. 2 Baseline Generator Torque Controller
- 04.09. 3 Collective Pitch Controller
- 05.09. 4 Filter Design
- 06.09. 7 Wind Field Generation
- 09.09. 10 Lidar-Assisted Control I
- 10.09. 11 Lidar-Assisted Control II
- 11.09. 5 Tower Damper
- 12.09. 6 Advanced Torque Controller
- 12.09. 8 Steady State Calculations
- 16.09. 9 Individual Pitch Control
- 17.09. 12 Wind Farm Effects**
- 18.09. 13 Wind Farm Control
- 19.09. 14 Floating Wind Control I
- 20.09. 15 Floating Wind Control II



# Wind farms



Horns Rev wind farm.  
Photo by C. Steiness.

"...a humid and warm air mass was advected from the southwest over cold sea and the dew-point temperature was such that cold-water advection fog formed in a shallow layer...The condensation appears to take place primarily in the wake regions with relatively high axial wind speed and high turbulent kinetic energy." [1]

## Motivation wind farms

- ▶ Costs of the grid connection ↘
- ▶ Maintenance costs ↘
- ▶ Land pollution ↘

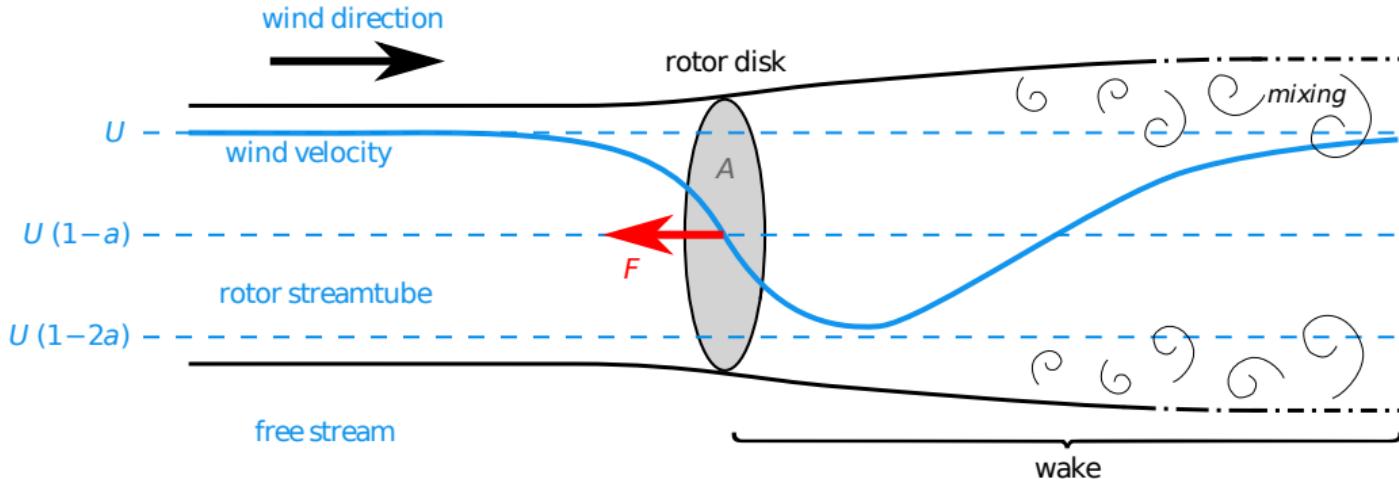
## Motivation wind farm control

- ▶ Energy production ↗
- ▶ Structural loading ↘
- ▶ Energy quality ↗

## Main questions

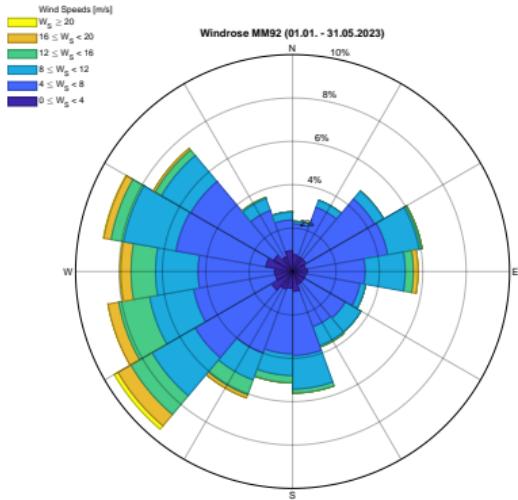
- ▶ How can we optimize wind farm operation?
- ▶ What are current challenges?

# Wind turbine wakes



Simplified representation of a wake [2].

# Yaw control



based on [Daniel Pereira (2022)]

## Motivation yaw control

- ▶ Wind direction is usually not constant
- ▶ Upwind turbines usually better aerodynamics, no tower shadow
- ▶ Active yaw control is necessary

## Main questions

- ▶ How is a yaw controller for wind turbines implemented?
- ▶ Can we improve yaw control with Lidar?

# Learning objectives

After this lectures you should be able to...

- ▶ explain the measurement principle of different sensors for yaw control
- ▶ explain how yaw control works
- ▶ calculate the wake losses using the Jensen wake model
- ▶ name and explain the three main concepts of wind farm control
- ▶ explain the main challenges in wind farm control

# Contents

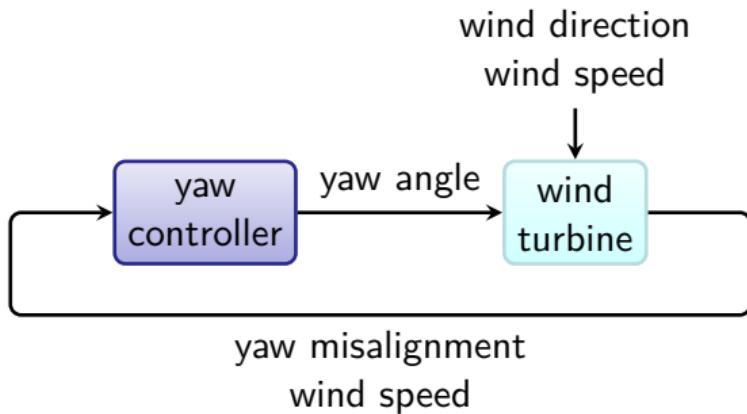
1. Yaw Control

2. Wind Farm Modelling

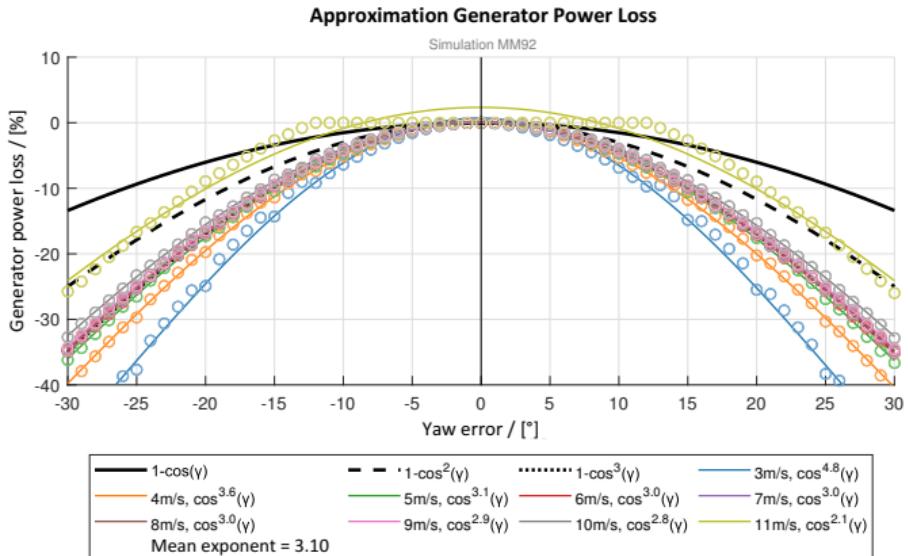
3. Conclusion



# Yaw control loop



## Simplified approximation of losses due to yaw missalignment



[own calculations]

$P(\gamma) = P_{\max} \cos^n(\gamma)$  with BEM  $n = 3$ , from simulations and measurements  $n = 1.88$  to  $5.14$ , mostly around 2 to 3.

# Conventional sensors for yaw control



[Thies]

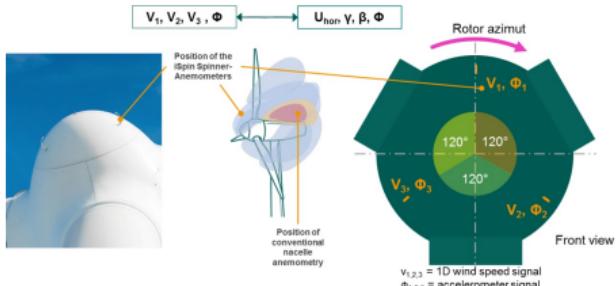
Combined wind vane and cup anemometer



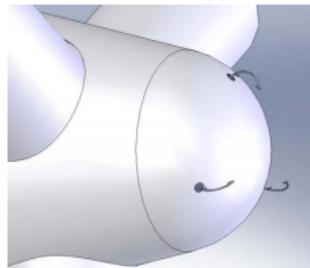
[Lufft]

Heated ultra sonic anemometer

# New sensors for yaw control



[ROMO Wind]



[Pedersen, T.F. (2010)]



[Pedersen, T.F. (2010)]

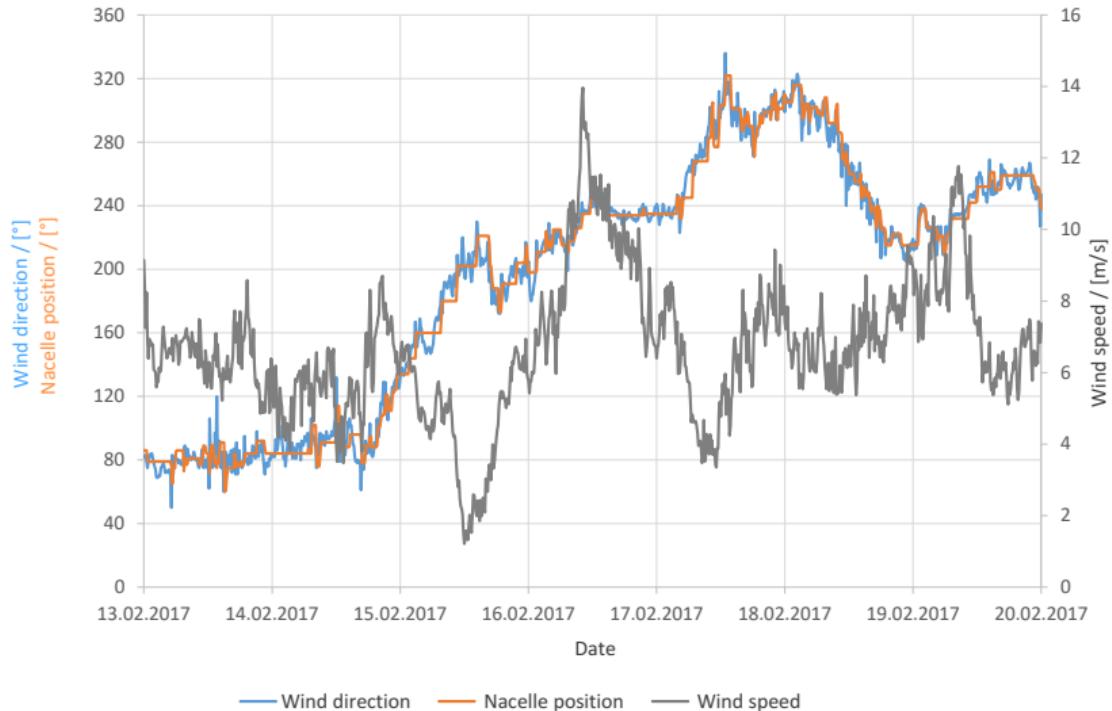
iSpin Spinner Anemometer Technology allows measurement of wind quantities like wind speed and yaw misalignment at the spinner using ultrasonic anemometer

# Actuators for yaw systems

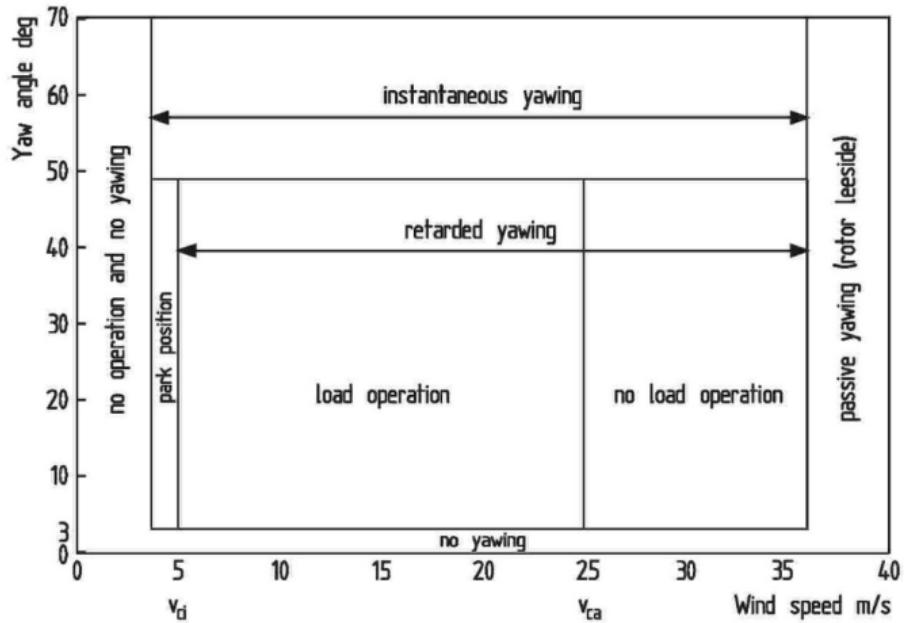


- ▶ Mainly electric motors with flange-mounted gears and pinions on the output side
- ▶ Brake system consists of several hydraulic brake calipers and a brake disc
- ▶ Brake system is always active, adjustment of pressure level depending on operating mode (yawing: low pressure, fixing: higher pressure)
- ▶ Nacelle normally has to be turned back after  $720^\circ$
- ▶ Typical adjustment speed approx.  $0.5^\circ \text{ s}^{-1}$

# Yaw control at a real wind turbine



## **Yaw control strategy**



## Strategy

- ▶ Based on averaged signals
  - ▶ Yaw not activated, if wind speed is too low or high
  - ▶ Yaw does not change below a certain threshold
  - ▶ Reaction depends on misalignment

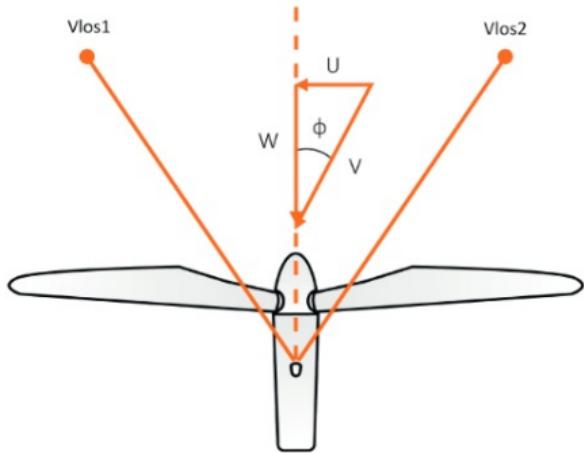
Yaw control example GROWIAN II [3]

## Lidar for yaw control



[Windar]

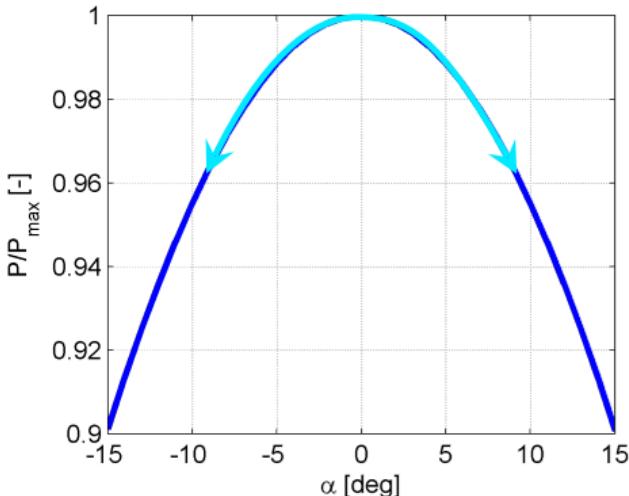
## Nacelle-based lidar



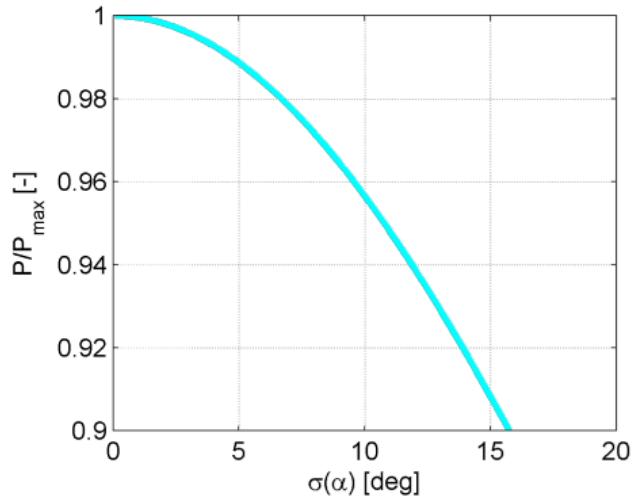
[Windar]

## Reconstruction of wind direction

## Possible improvements with lidar-assisted yaw control [4]

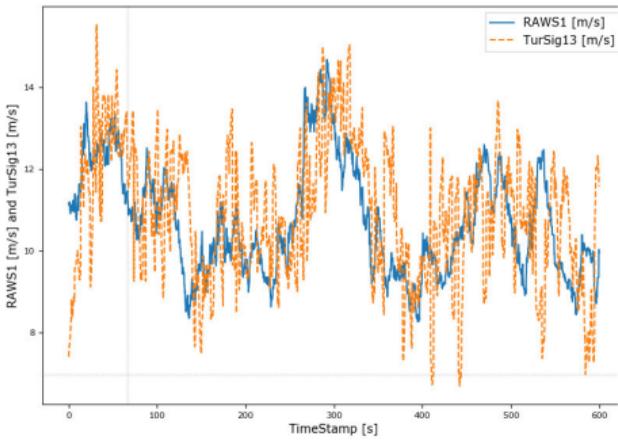


## Static yaw misalignment



## Dynamic yaw misalignment

# Project ABBA (Link to the Project)



Development, evaluation and testing of adaptive operating and control strategies

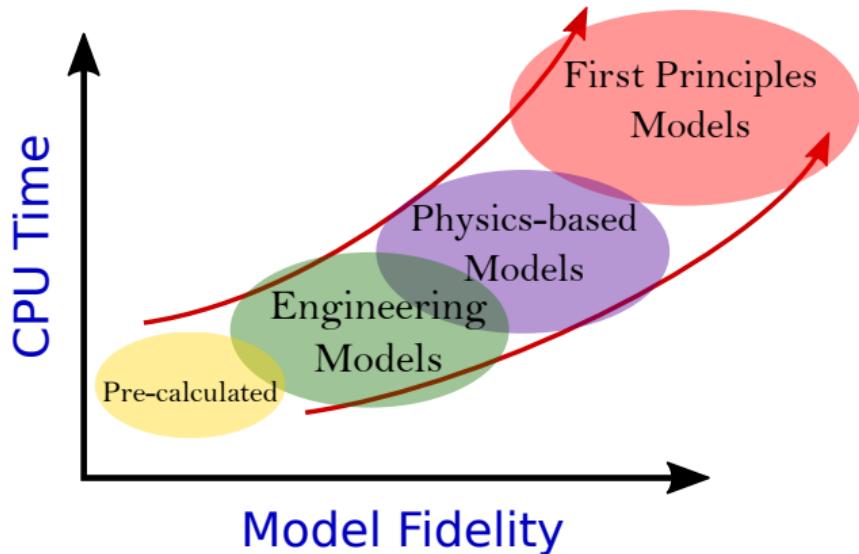
- ▶ Integration of energy price, lidar-based wind forecasting and load monitoring
- ▶ Lifetime extension and increase of energy yield, reduction of noise emissions and grid support through data-based control

# Wind farm models

## Components wind farm model

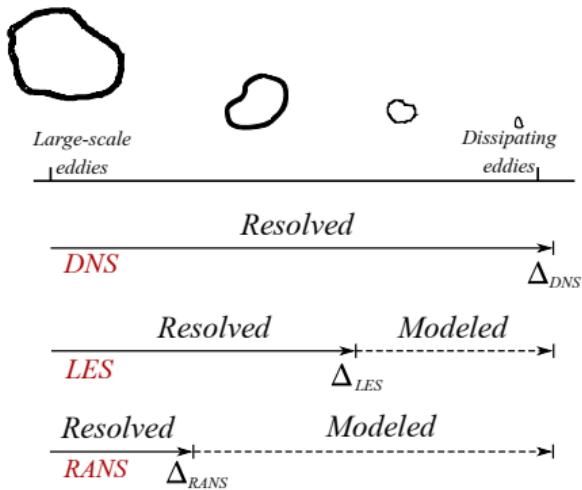
- ▶ Rotor model
  - ▶ ADM: Actuator Disk Model
  - ▶ ADM-R: Rotating Actuator Disk Model
  - ▶ ALM: Actuator Line Model
- ▶ Turbine model (stiff, elastic (e.g. FAST), ...)
- ▶ Flow model (describes wake characteristics)

# Fidelity of wind farm models versus CPU time



[An Analysis of Engagement Algorithms for Real-Time Weapons Effects]

# High and medium fidelity

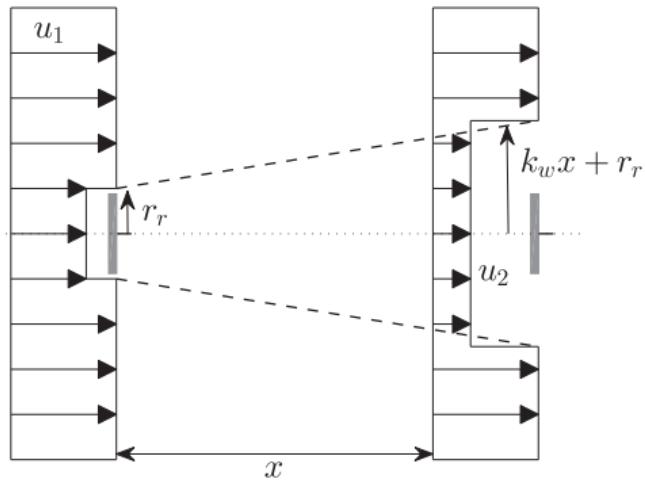


[Lecture slides Dr. A. Bakker]

## Methods to solve Navier-Stokes equations

- ▶ DNS: Direct Numerical Simulation
- ▶ LES: Large Eddies Simulation
- ▶ RANS: Reynolds-Averaged Navier-Stokes

# Jensen wake model 1/3



Reduction of wind speed

$$u_2 = u_1 \left( 1 - \frac{1 - \sqrt{1 - c_T}}{(1 + k_w x / r_r)^2} \right)$$

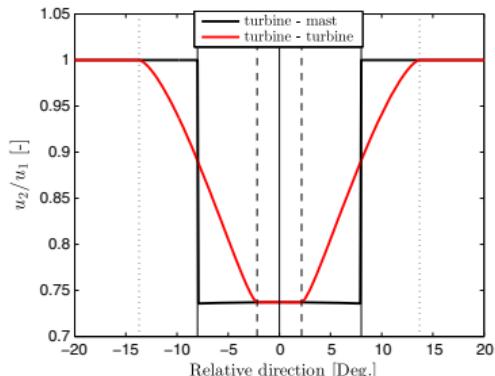
wake decay coefficient

$k_w = 0.075$  onshore

$k_w = 0.040$  offshore

[5]

Jensen wake model 2/3



[5]

## Linear approximation partial wake effect

$$u_{2p} = u_2 \quad \forall |y| \leq k_w x$$

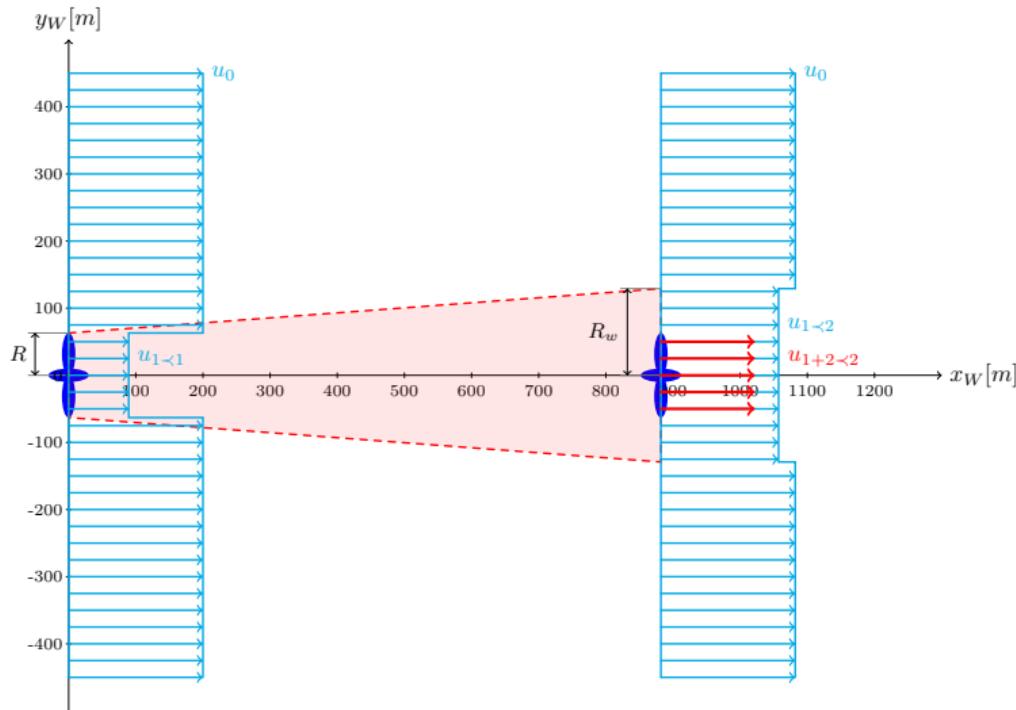
$$u_{2p} = u_1 \quad \forall |y| \leq k_w x + 2r_r$$

$$u_{2p} = f(u_1, u_2, y) \quad \forall k_w x < |y| < k_w x + 2r_r$$

with  $f$  a linear interpolation

$$f = \frac{y - k_w x}{2r_r} u_1 + \frac{k_w x + 2r_r - y}{2r_r} u_2$$

# Jensen wake model 3/3

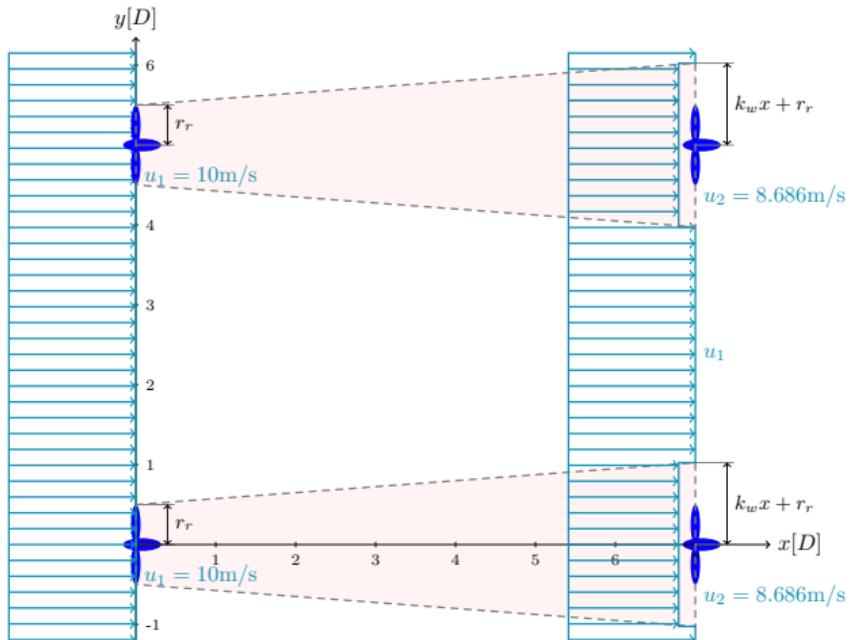


[5]

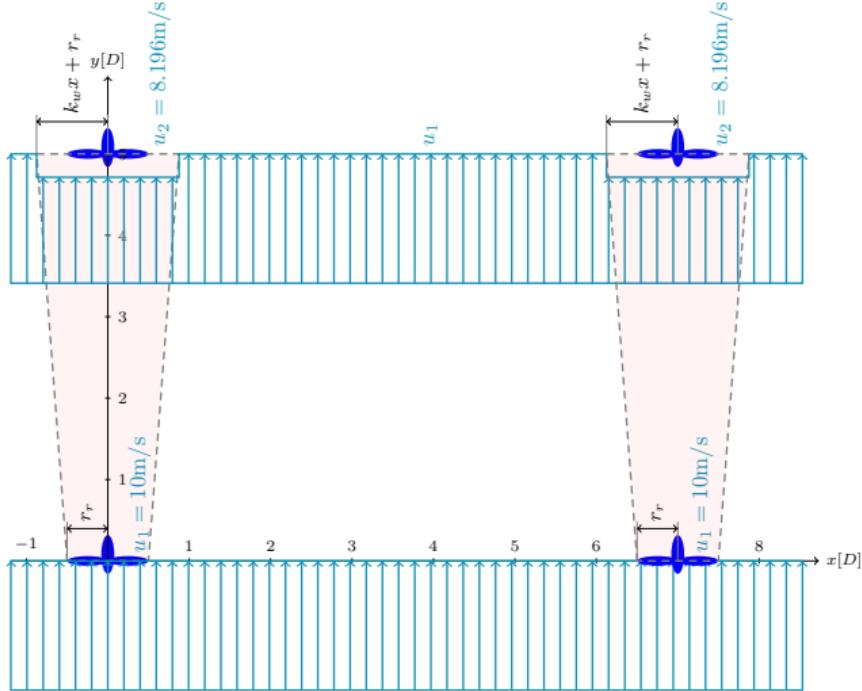
Wake overlap

$$\delta_n = \sqrt{\sum_{i=1}^n \delta_i^2}$$

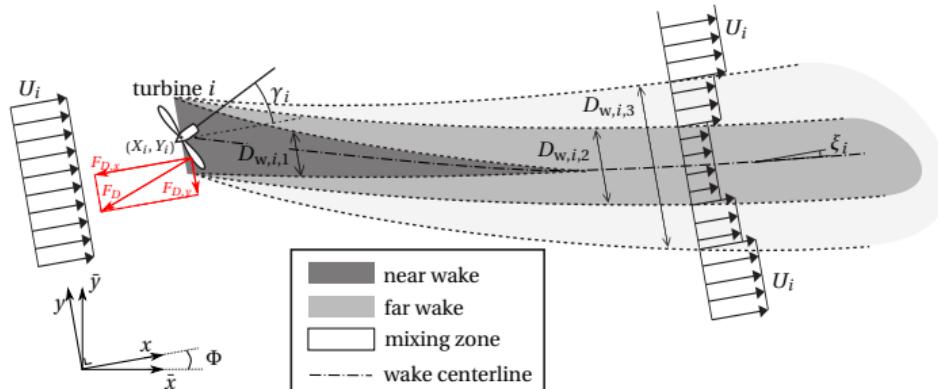
## Jensen wake model - case study



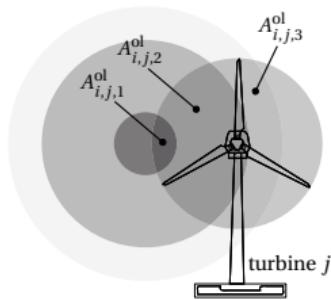
# Jensen wake model - case study



# FLORIS: FLOw Redirection and Induction in Steady State



(a) Top view



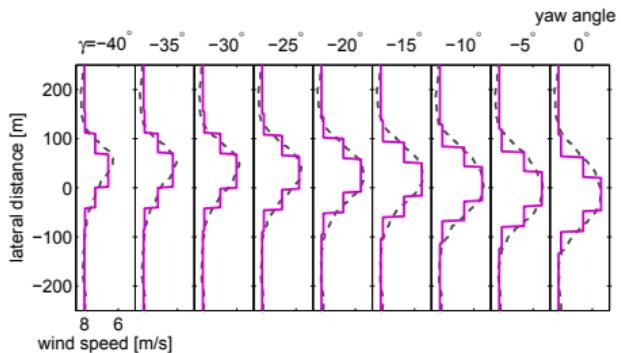
(b) Cut-through at down-stream turbine

[6]

## Ansatz multi zone model

- ▶ Combine effects of yaw control on redirection of wake and velocity in the wake.
- ▶ Separate wake into 3 zones: near wake ( $q = 1$ ), far wake ( $q = 2$ ), mixed zone ( $q = 3$ ).
- ▶ Identify model parameters from data.

# Multi zone model



[6]

## Diameter of wake zones

$$D_{w,q}(x) = \max(D + wk_e m_{e,q} [x - X])$$

with  $D$  turbine diameter,  $x \geq X$  distance in downwind direction and  $m_e$  and  $k_{e,q}$  fitted to simulation data

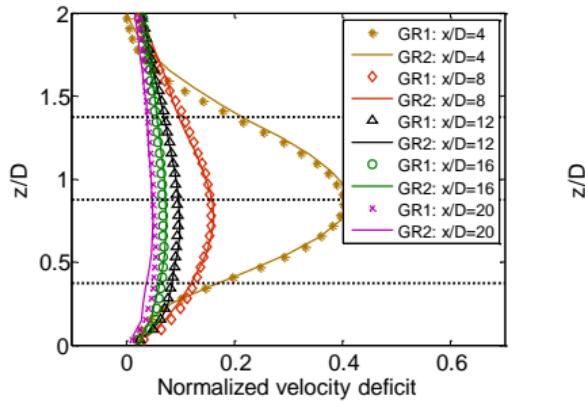
## Decay of velocity deficit

$$U_w(x, y) = U (1 - 2ac_q(x, y))$$

$$c_q = \left( \frac{D}{D + 2k_e m_{U,q}(\gamma)(x - X)} \right)^2$$

with  $\gamma$  yaw angle and  $k_e$  and  $m_{U,q}$  fitted to simulation data

# Gaussian wake model



[7]

## Ansatz Gaussian wake model

- ▶ fit continuous Gaussian normal distributions to the velocity deficit
- ▶ extension for higher order “Super-Gaussians”

# Conclusion

- ▶ How is a yaw controller for wind turbines implemented?
- ▶ Can we improve yaw control with Lidar?
  - ▶ slow control loop independent from pitch and torque control
  - ▶ lidar might help to increase energy, depends on inhomogeneity and control strategy

# References

- [1] C. B. Hasager, N. G. Nygaard, P. J. H. Volker, I. Karagali, S. J. Andersen, and J. Badger. "Wind Farm Wake: The 2016 Horns Rev Photo Case". In: *Energies* 10.3 (2017), p. 317. DOI: 10.3390/en10030317.
- [2] P. M. O. Gebräad. "Data-driven wind plant control". PhD thesis. Delft University of Technology, 2014. DOI: 10.4233/uuid:5c37b2d7-c2da-4457-bff9-f6fd27fe8767.
- [3] E. Hau. *Wind Turbines: Fundamentals, Technologies, Application, Economics*. Springer, 2006. ISBN: 978-3-540-29284-5.
- [4] D. Schlipf et al. "Prospects of optimization of energy production by LIDAR assisted control of wind turbines". In: *European Wind Energy Association Annual Event*. Brussels, Belgium, Mar. 2011. DOI: 10.18419/opus-3916.
- [5] A. Peña, P.-E. Réthoré, and M. P. van der Laan. "On the application of the Jensen wake model using a turbulence-dependent wake decay coefficient: the Sexbierum case". In: *Wind Energy* 19.4 (2016), pp. 763–776. DOI: 10.1002/we.1863.
- [6] P. M. O. Gebräad and J. W. van Wingerden. "A control-oriented dynamic model for wakes in wind plants". In: *Journal of Physics: Conference Series* 524.1 (2014), p. 012186. DOI: 10.1088/1742-6596/524/1/012186.
- [7] M. Abkar and F. Porté-Agel. "Influence of atmospheric stability on wind-turbine wakes: A large-eddy simulation study". In: *Physics of Fluids* 27.3 (Mar. 2015), p. 035104. DOI: 10.1063/1.4913695.

**Please let me know if you have further questions!**

Prof. Dr.-Ing. David Schlipf  
[David.Schlipf@HS-Flensburg.de](mailto:David.Schlipf@HS-Flensburg.de)  
[www.hs-flensburg.de/go/WETI](http://www.hs-flensburg.de/go/WETI)

#### **Disclaimer**

The lecture notes are inspired by the lectures of SWE, University of Stuttgart. They are for educational purposes only and are not allowed to be published, shared or re-used in any form without the express consent of the authors (David Schlipf and colleagues). Copyright belongs to the authors. If not stated otherwise, copyright of photos and figures belongs to the authors. The authors do not assume any responsibility for the content of the material and will not be liable for any losses or damages in connection with the use of the material.